

# TSDT14 Signal Theory

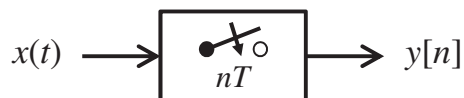
## Lecture 9

### Reconstruction and Reconstruction Errors

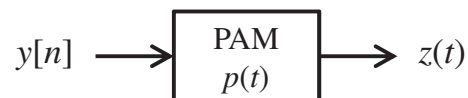
Mikael Olofsson  
Department of EE (ISY)  
Div. of Communication Systems



## Sampling and PAM of Deterministic Signals – Summary



$$y[n] = x(nT)$$

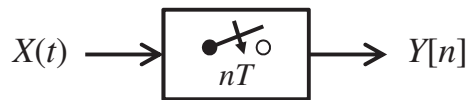


$$z(t) = \sum_n y[n] p(t - kT)$$

$$Y[\theta] = \frac{1}{T} \sum_m X\left(\frac{\theta - m}{T}\right)$$

$$Z(f) = P(f)Y[fT]$$

# Sampling and PAM of WSS Processes – Summary

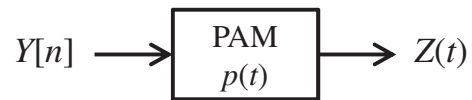


$$Y[n] = X(nT)$$

$$m_Y = m_X$$

$$r_Y[k] = r_X(kT)$$

$$R_Y[\theta] = \frac{1}{T} \sum_m R_X\left(\frac{\theta - m}{T}\right)$$



$$Z(t) = \sum_n Y[n] p(t - nT - \Psi)$$

$$m_Z = \frac{1}{T} P(0) m_Y$$

$\Psi$  unif.  $[0, T]$   
 $\Psi$  &  $Y[n]$  indep.

$$r_Z(\tau) = \frac{1}{T} \sum_k r_Y[k] (p * \tilde{p})(\tau - kT)$$

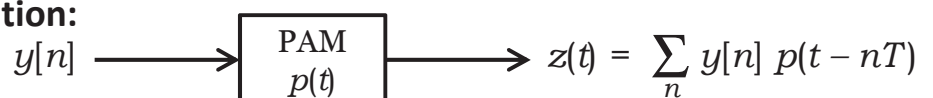
$$R_Z(f) = \frac{1}{T} |P(f)|^2 R_Y[fT]$$

## Linear Mappings

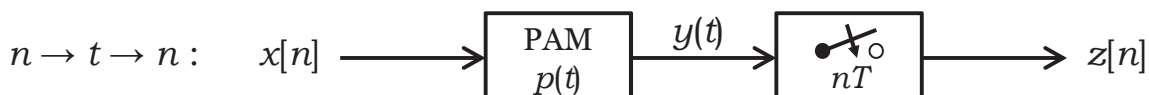
**Sampling:**



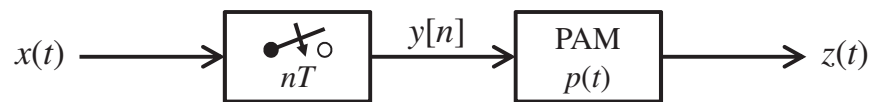
**Pulse-Amplitude Modulation:  
(PAM)**



**Reconstruction:**



# Sampling Theorem for Deterministic Signals



## The Sampling Theorem:

Consider a signal  $x(t)$ , with spectrum  $X(f)$  and  $X(f) = 0$  for  $|f| \geq f_0$ . If  $x(t)$  is sampled with sampling frequency  $f_s$ , then  $x(t)$  can be reconstructed without error from the sampled signal if  $f_s \geq 2f_0$  holds.

## This means:

There exists a pulse shape  $p(t)$ , such that  $x(t)$  can be written as

$$x(t) = \sum_n x(nT) p(t - nT)$$

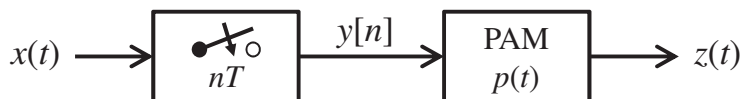
if  $f_s \geq 2f_0$  holds, where  $f_s = 1/T$ .

## Fulfilled for:

Ideal reconstruction:  $p(t) = \text{sinc}(t/T)$

## Reconstruction – Deterministic Case $t \rightarrow n \rightarrow t$ :

$$y[n] = x(nT) \quad Y[\theta] = f_s \sum_m X((\theta - m)f_s)$$



$$z(t) = \sum_n y[n] p(t - nT) \quad Z(f) = P(f) Y[f/f_s]$$

### Total spectrum:

$$Z(f) = f_s P(f) \sum_m X(f - mf_s)$$

### Distorsion:

$$\begin{aligned} \epsilon^2 &= \int_{-\infty}^{\infty} (z(t) - x(t))^2 dt \quad \text{Parseval} \quad = \int_{-\infty}^{\infty} |Z(f) - X(f)|^2 df \\ &= \int_{-\infty}^{\infty} \left| f_s P(f) \sum_m X(f - mf_s) - X(f) \right|^2 df = \int_{-\infty}^{\infty} \left| (f_s P(f) - 1) X(f) + f_s P(f) \sum_{m \neq 0} X(f - mf_s) \right|^2 df \end{aligned}$$

### Ideal reconstruction:

$$p(t) = \text{sinc}(t/T)$$

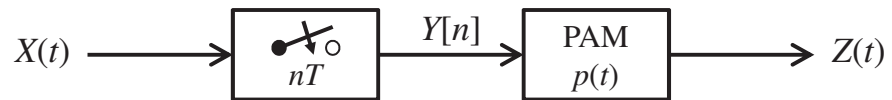
$$P(f) = T \text{rect}(fT)$$

$$\epsilon^2 = 2 \underbrace{\int_{f_s/2}^{\infty} |X(f)|^2 df}_{\text{Bandlimiting distortion}} + 2 \underbrace{\int_0^{f_s/2} \left| \sum_{m \neq 0} X(f - mf_s) \right|^2 df}_{\text{Aliasing distortion}}$$

**Bandlimiting  
distorsion**

**Aliasing  
distorsion**

# The Sampling Theorem for Stochastic Processes



## The Sampling Theorem:

Consider a process  $X(t)$ , with spectrum  $R_X(f)$  and  $R_X(f) = 0$  for  $|f| \geq f_0$ . If  $X(t)$  is sampled with sampling frequency  $f_s$ , then  $X(t)$  can be reconstructed without error from the sampled signal if  $f_s \geq 2f_0$  holds.

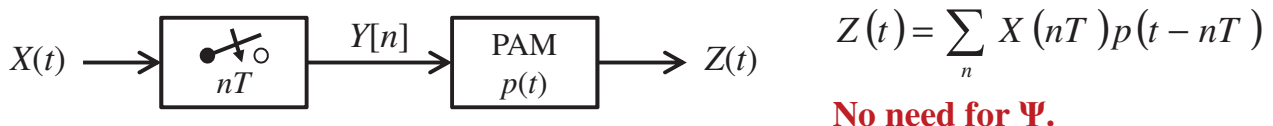
## This means:

There exists a pulse shape  $p(t)$ , such that  $\varepsilon^2 = E\{(Z(t) - X(t))^2\} = 0$  holds.

## Fulfilled for:

Ideal reconstruction:  $p(t) = \text{sinc}(t/T)$

## Proof of Sampling Theorem 1(2)



**Distorsion:**  $\varepsilon^2 = E\{(Z(t) - X(t))^2\} = E\{Z^2(t)\} - 2E\{Z(t)X(t)\} + E\{X^2(t)\}$

$$E\{Z^2(t)\} = E\left\{\left(\sum_n X(nT)p(t - nT)\right)^2\right\} = \sum_m \sum_n E\{X(nT)X(mT)\}p(t - nT)p(t - mT)$$

$$= \sum_m \left(\sum_n r_X(nT - mT)p(t - nT)\right)p(t - mT)$$

$$E\{Z(t)X(t)\} = E\left\{\sum_n X(nT)p(t - nT)X(t)\right\} = \sum_n E\{X(nT)X(t)\}p(t - nT)$$

$$= \sum_n r_X(nT - t)p(t - nT)$$

$$E\{X^2(t)\} = r_X(0)$$

# Proof of Sampling Theorem 2(2)

We had:

$$\begin{aligned} E\{Z^2(t)\} &= \sum_m \left( \sum_n r_X(nT - mT) p(t - nT) \right) p(t - mT) \\ E\{Z(t)X(t)\} &= \sum_n r_X(nT - t) p(t - nT) \end{aligned}$$

Try ideal reconstruction:

$$p(t) = \text{sinc}(t/T)$$

From the deterministic case:

$$r_X(\tau) = \sum_m r_X(mT) p(\tau - mT)$$

$$r_X(\tau - a) = \sum_n r_X(nT) p(\tau - a - nT) = \sum_n r_X(nT - a) p(\tau - nT) \quad (1)$$

With  $\tau = t$  &  $a = mT$  in (1), we get :  $r_X(t - mT) = \sum_n r_X(nT - mT) p(t - nT)$  (2)

With  $\tau = a = t$  in (1), we get :  $r_X(0) = \sum_n r_X(nT - t) p(t - nT)$  (3)

$$(2) \& (3) \Rightarrow E\{Z^2(t)\} = \sum_m r_X(t - mT) p(t - mT) = \sum_m r_X(mT - t) p(t - mT) = r_X(0)$$

$$(3) \Rightarrow E\{Z(t)X(t)\} = r_X(0)$$

**Result:**  $\varepsilon^2 = 0$

Mikael Olofsson  
ISY/CommSys

[www.liu.se](http://www.liu.se)