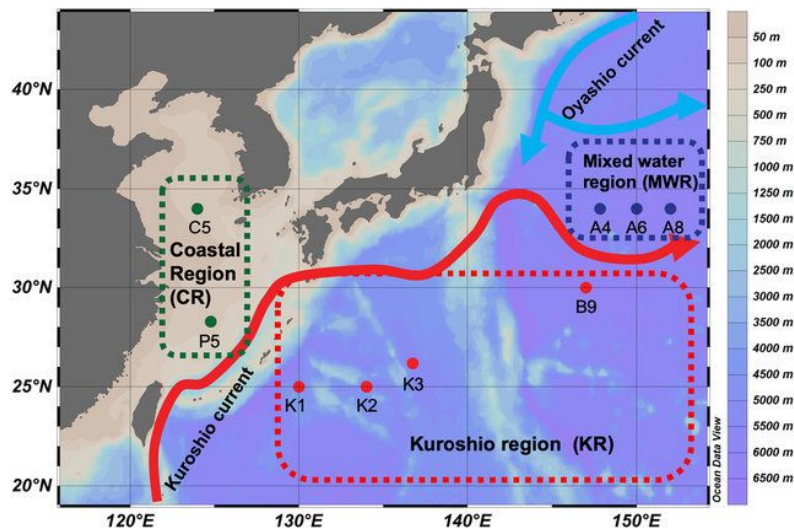


# Climate as a complex system

Project 1: “Toy stochastic models”

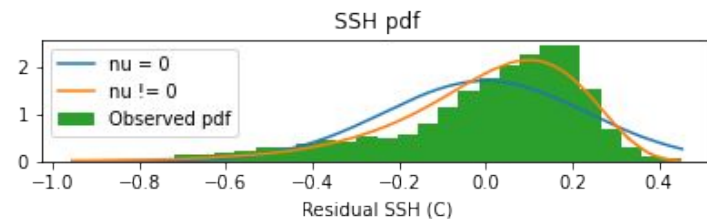
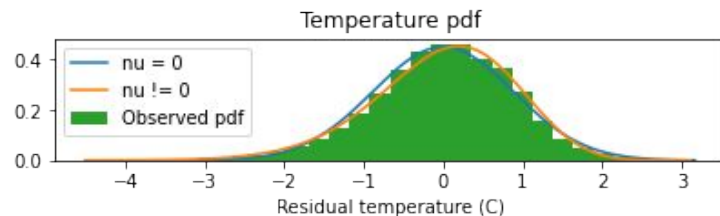
# Talk Summary

- Analysis of SST and SSH data (Julia)
- SDE Model and Stationary Fokker Planck Equation (Calvin)
- Parameter Fitting (Jamie)

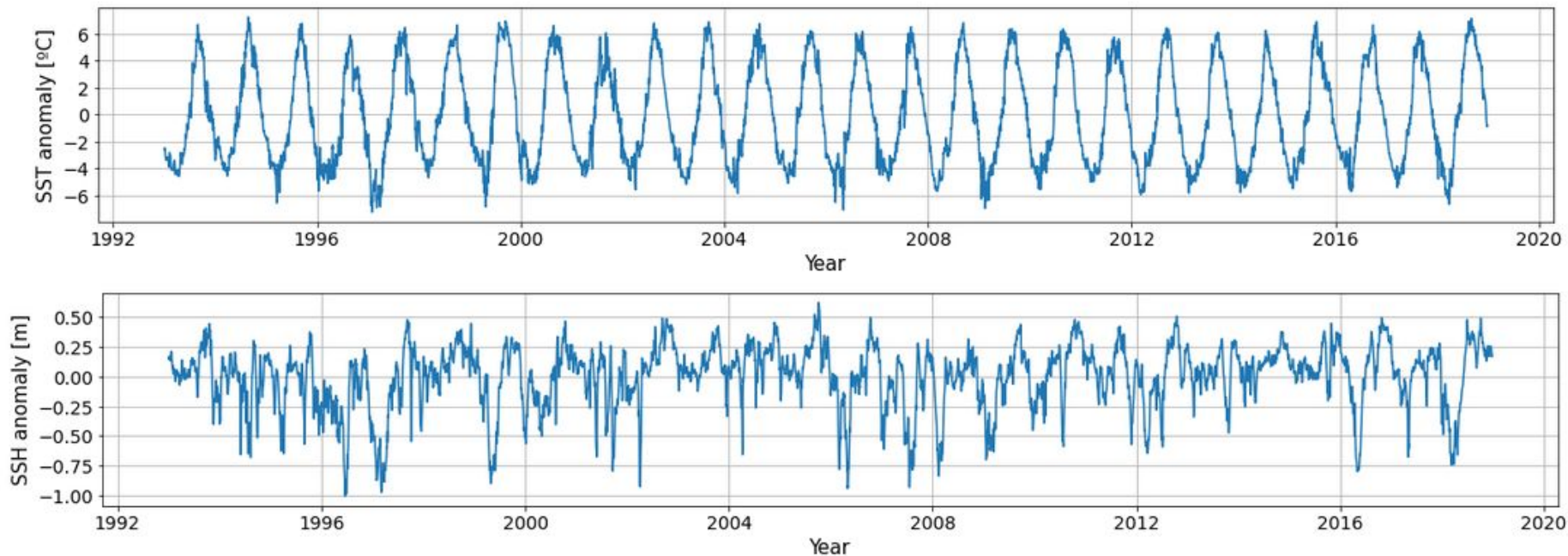


Wu et al.,  
(2019)

$$dX_t = \lambda X_t dt + (\mu + v X_t) dW_t$$

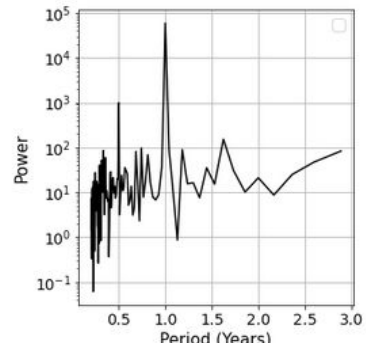
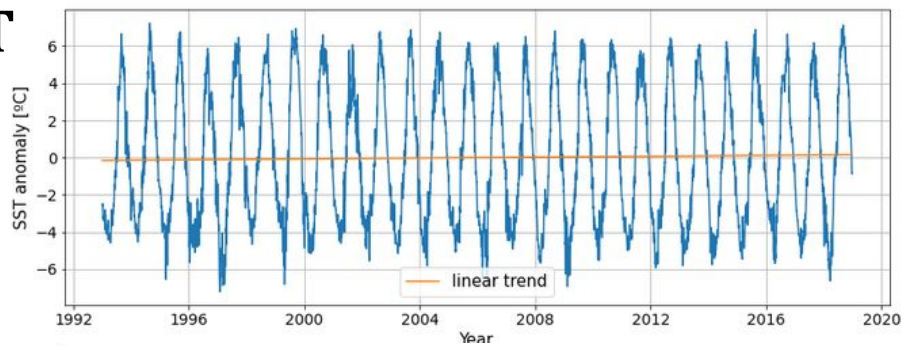


# SST and SSH anomalies

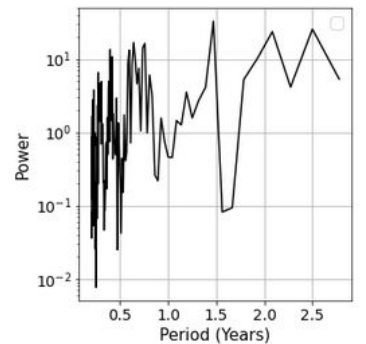
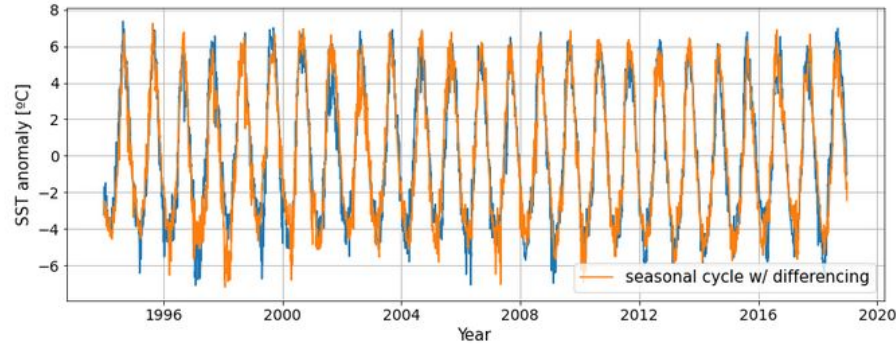


Sea surface temperature and sea surface height at 153°E, 33°N,  
Kuroshio Current

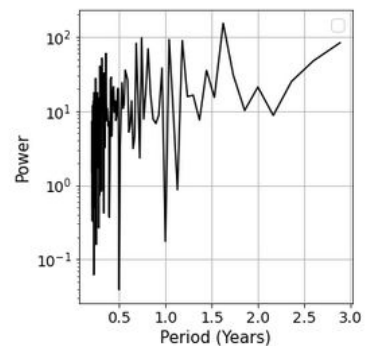
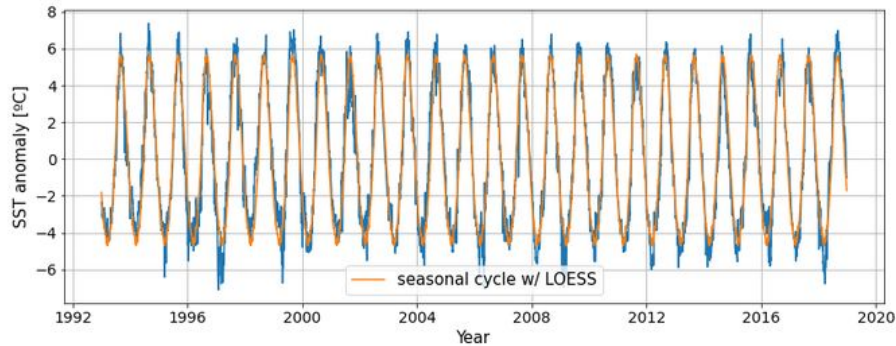
# SST



Linear trend

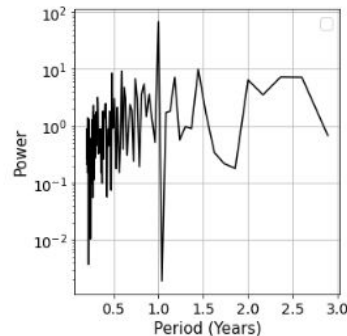
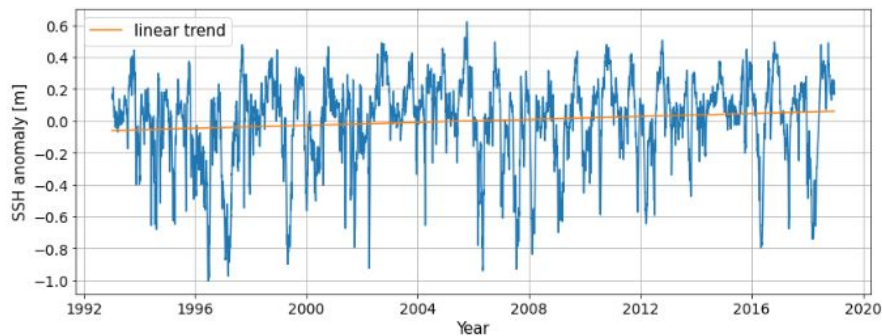


Seasonal cycle removed  
applying differencing

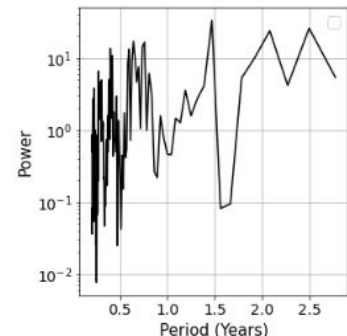
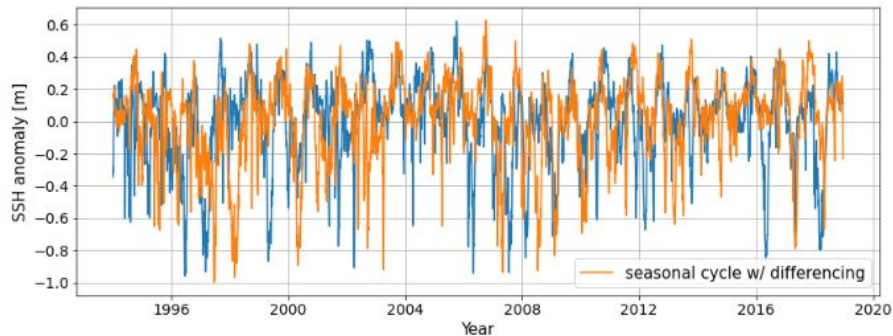


Seasonal cycle removed with  
the “seasonal\_decompose”  
module, which applies  
Locally Weighted Scatterplot  
Smoothing (**LOESS**)

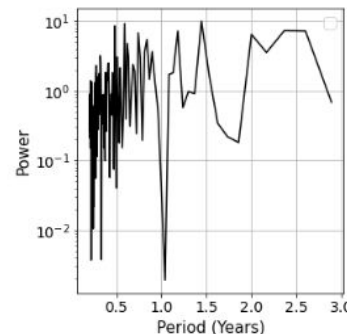
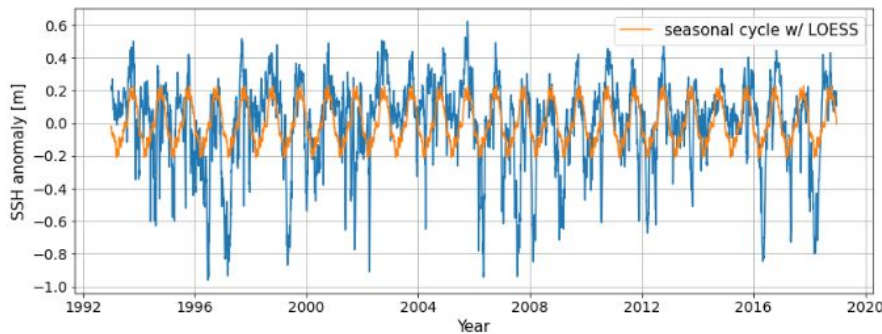
# SSH



Linear trend



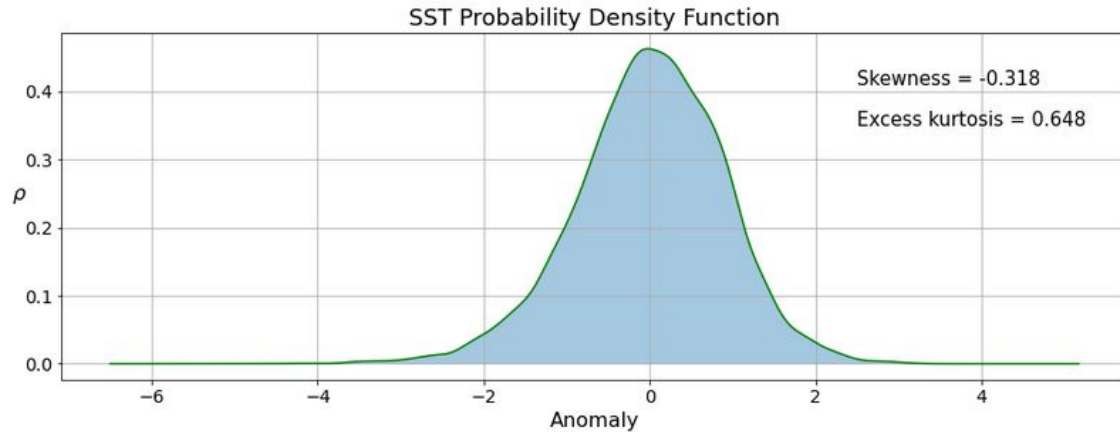
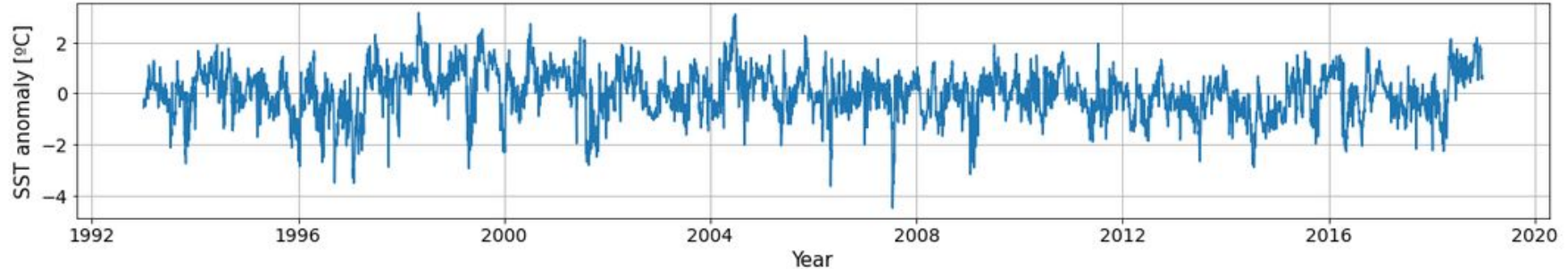
Seasonal cycle removed  
applying differencing



Seasonal cycle removed with  
the “seasonal\_decompose”  
module, which applies  
Locally Weighted Scatterplot  
Smoothing (**LOESS**)



# Sea surface temperature anomalies



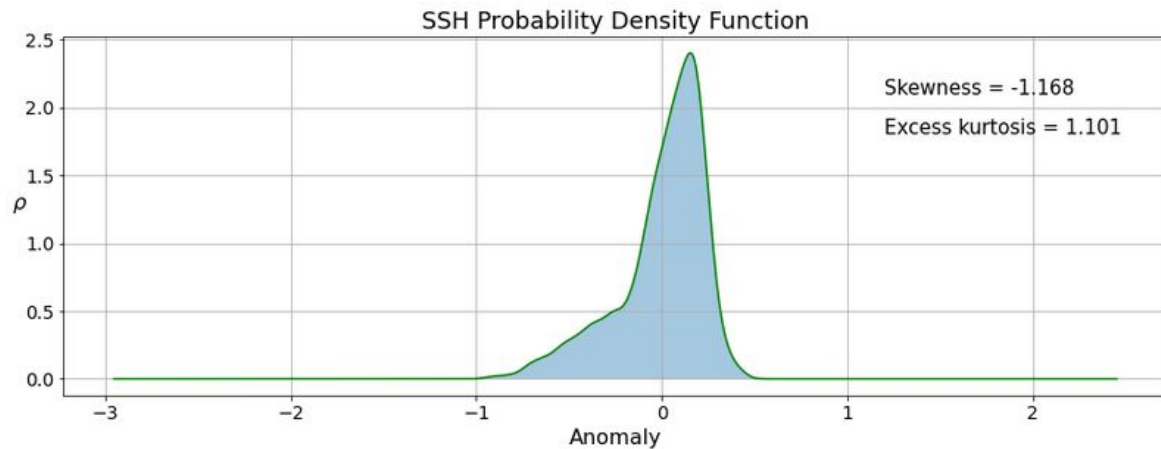
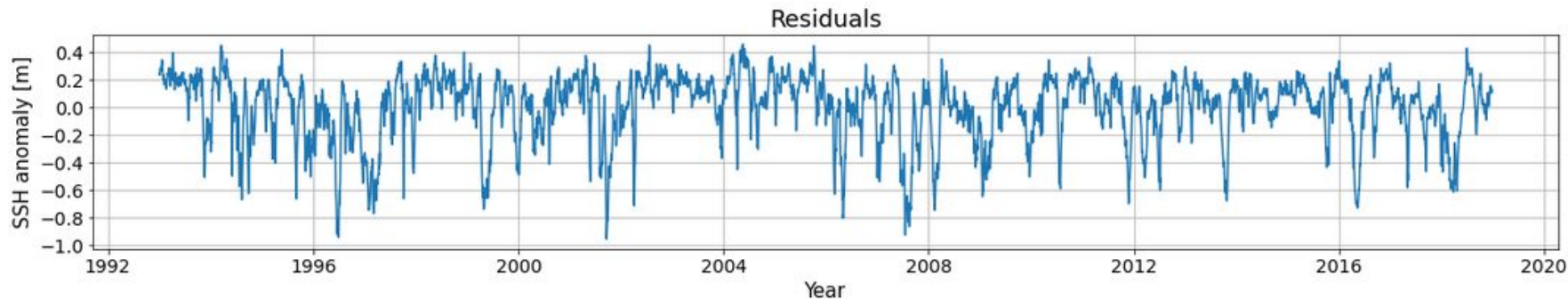
Kernel Density Estimation using the module “Gaussian\_kde” from “scipy.stats”

$$S = \frac{\overline{h'^3}}{\sigma^3}$$
$$K = \frac{\overline{h'^4}}{\sigma^4} - 3$$

Where  $h'$  are the anomalies,  $S$  is skewness,  $K$  is the “excess kurtosis”

$K > 1.5 S^2$  like in Sura et al., 2008

# Sea Surface Height anomalies

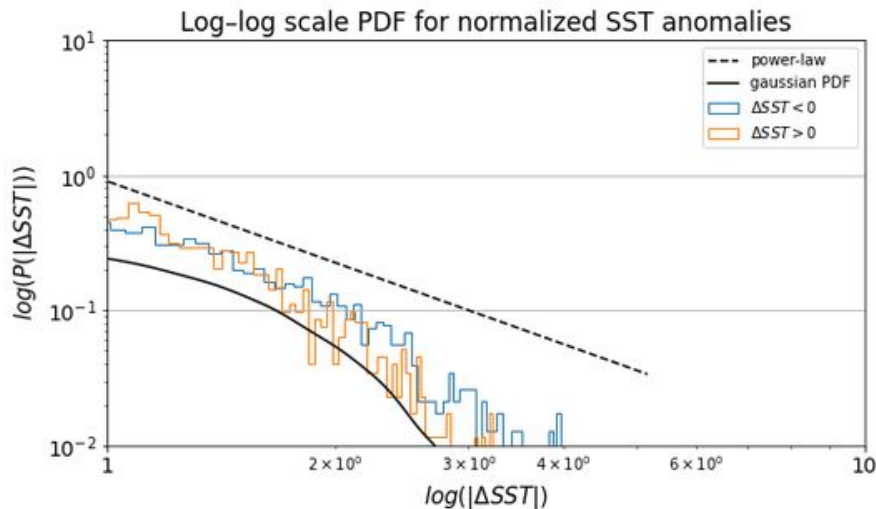
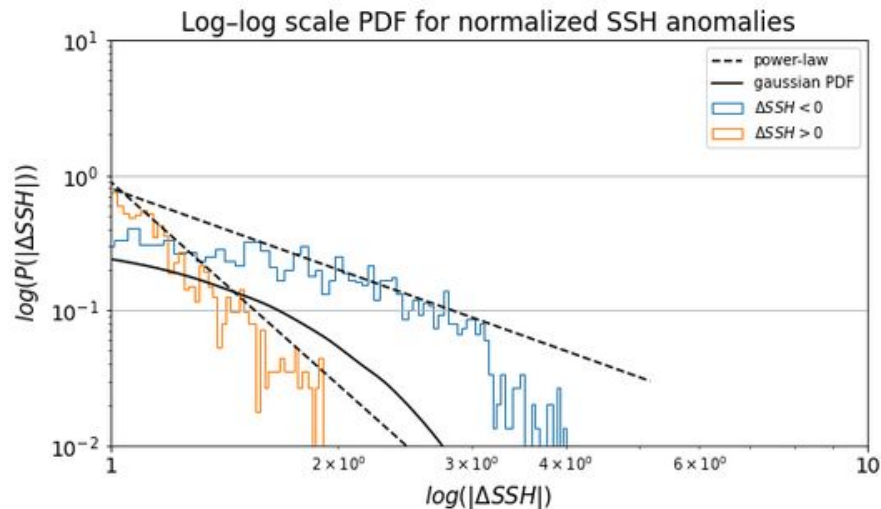


- Skewness represents the asymmetry of the distribution.
- High kurtosis indicates numerous extreme events

Example: 1997 in the Kuroshio Current

$K > 1.5 S^2 - 1.5$ , like in Sura et al. (2010)

# Non-gaussian power-law tails

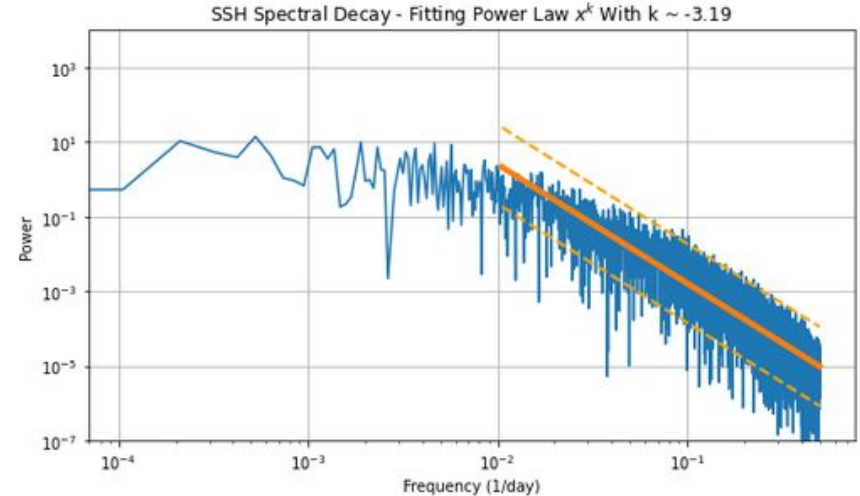
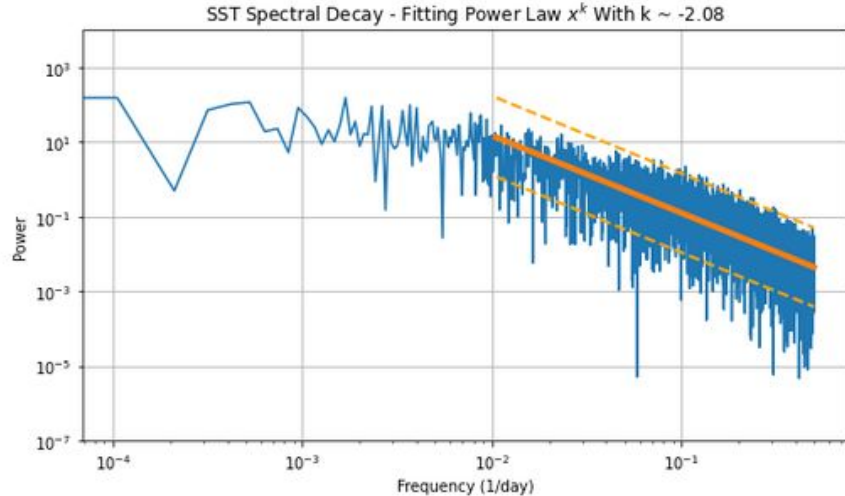


Log-log plot of the PDF tails, we show the PDF of the two normalized tails separately, in absolute value. We can observe deviations from Gaussian behaviour in the SSH data, not too clear for SSTs.

- A highly non-Gaussian power-law tail in this plot will appear as a straight line. ( $P(h') \propto h'^{-\alpha}$ )
- Different decay rate in SSH positive and negative anomalies.
- Scale invariance, indicates self-similarity, this self-similarity is observed in many non-Gaussian natural phenomena



# Decay in Power spectral density



$$\tilde{S}_{xx}(\omega) = \frac{(\Delta t)^2}{T} \left| \sum_{n=1}^N x_n e^{-i\omega n \Delta t} \right|^2.$$

$$x_n = x(n\Delta t)$$

$$T = N\Delta t.$$

# Multiplicative noise in SST and SSH

$$\frac{\partial T'_o}{\partial t} = -\lambda T'_o - \phi F' T'_o + F' + R' + \phi \overline{F' T'},$$

Sura & Sardeshmukh  
(2008)

In this article they conclude that the observed non-Gaussianity of SST anomalies is due to **(weak)** multiplicative noise rather than to nonlinearities in the deterministic part of the SST equation.

$$\frac{dx}{dt} = Ax + (Ex + G)\eta - \frac{1}{2}EG + B\zeta,$$

From a general form for the governing equations, applying a **fast-slow time-scale separation**.

Studying the Fokker-Planck equation for this SDE, they find:

- The property that the (excess) kurtosis  $K$  is always greater than 1.5 times the square of the skewness  $S$ ,  $K \geq 1.5 S^2$
- A PDF with power-law tails,  $P(x) \propto x^{-\alpha}$ .

Sura & Guille (2010)

# SDE Model With Multiplicative Noise

$$dX_t = \lambda X_t dt + (\mu + v X_t) dW_t$$

- Compare with Ornstein Uhlenbeck where there is no  $x$  dependence in the noise
- Similar to well known geometric Brownian motion

# Writing the Stationary Fokker Planck Equation

$$\begin{array}{cc} \text{Drift} & \text{Diffusion} \\ \lambda x & \frac{(\mu + \nu x)^2}{2} \end{array}$$

$$\frac{\partial}{\partial t} p(x, t) = -\frac{\partial}{\partial x} [\mu(x, t)p(x, t)] + \frac{\partial^2}{\partial x^2} [D(x, t)p(x, t)]$$

Thus the stationary Fokker-Planck equation is

$$\lambda \partial_x (px) - \frac{1}{2} \partial_{xx} (p(\nu x + \mu)^2) = 0.$$

# Solving the Stationary Fokker Planck Equation (i)

$$\lambda \partial_x(px) - \frac{1}{2} \partial_{xx}(p(\nu x + \mu)^2) = 0.$$

Integrating with respect to  $x$  and using the boundary conditions on  $p$  (it's a density) we arrive at:

$$\lambda px - \frac{1}{2} \partial_x(p(\nu x + \mu)^2) = 0.$$

## Solving the Stationary Fokker Planck Equation (ii)

$$\lambda p x - \frac{1}{2} \partial_x (p(\nu x + \mu)^2) = 0.$$

This is a separable ODE in  $x$  which has solution

$$p(x) = C_0 (\nu x + \mu)^F \exp \left\{ \frac{-2\lambda x}{\nu(\nu x + \mu)} \right\}$$

where  $F = \frac{2\lambda}{\nu^2} - 2$  and  $C_0$  is a constant of integration.



# Making Sense of the Solution

$$p(x) = C_0(\nu x + \mu)^F \exp\left\{\frac{-2\lambda x}{\nu(\nu x + \mu)}\right\}$$

$$F = \frac{2\lambda}{\nu^2} - 2$$

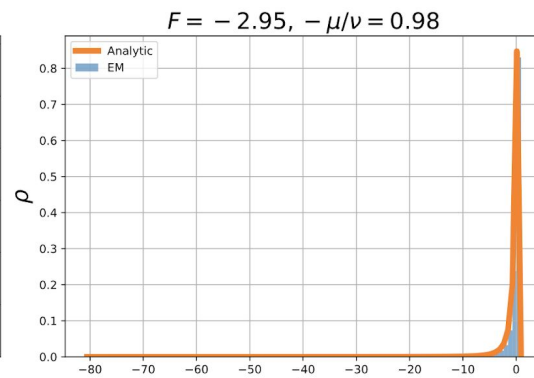
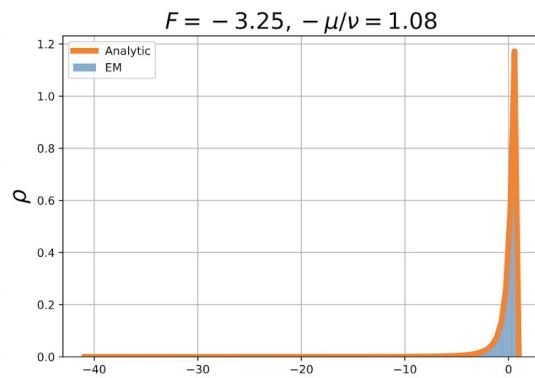
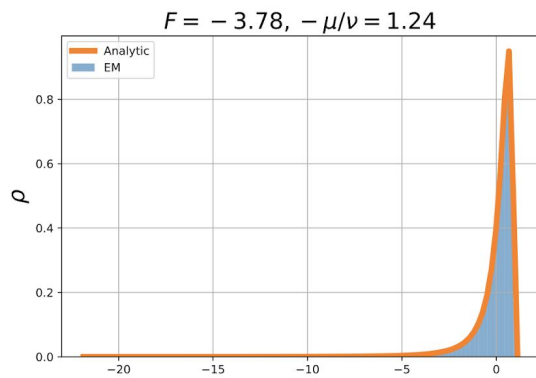
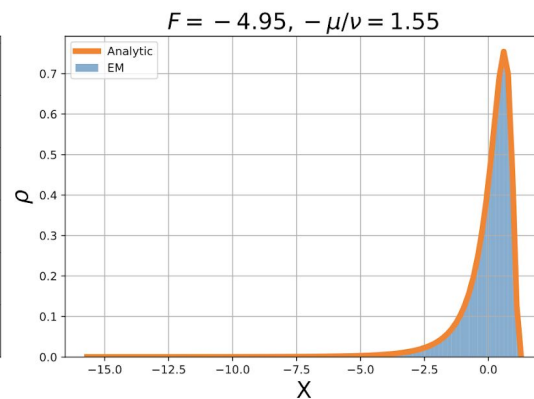
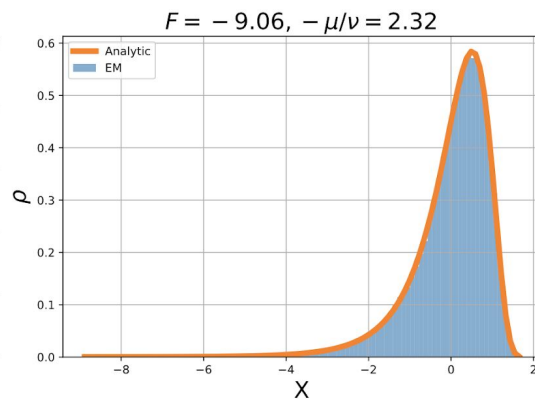
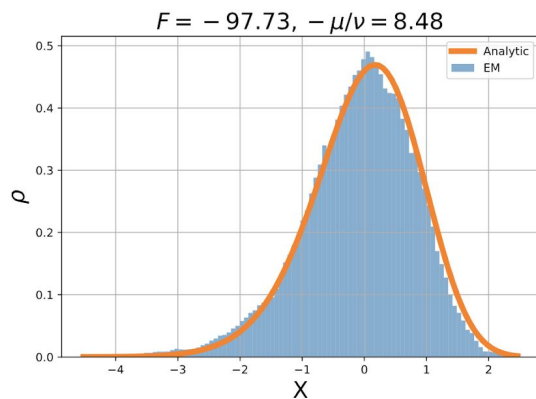
- We want a finite mean  $\langle x \rangle := \int_{\mathbf{R}} x(\nu x + \mu)^F \exp\left\{\frac{-2\lambda x}{\nu(\nu x + \mu)}\right\} dx$
- So would expect integrand to be 0 at the boundaries
- Exponential terms tends to a constant
- Thus we require  $F + 1 < 0$ :

$$\lambda < \frac{\nu^2}{2}$$

- Singularity at  $x = -\frac{\mu}{\nu}$

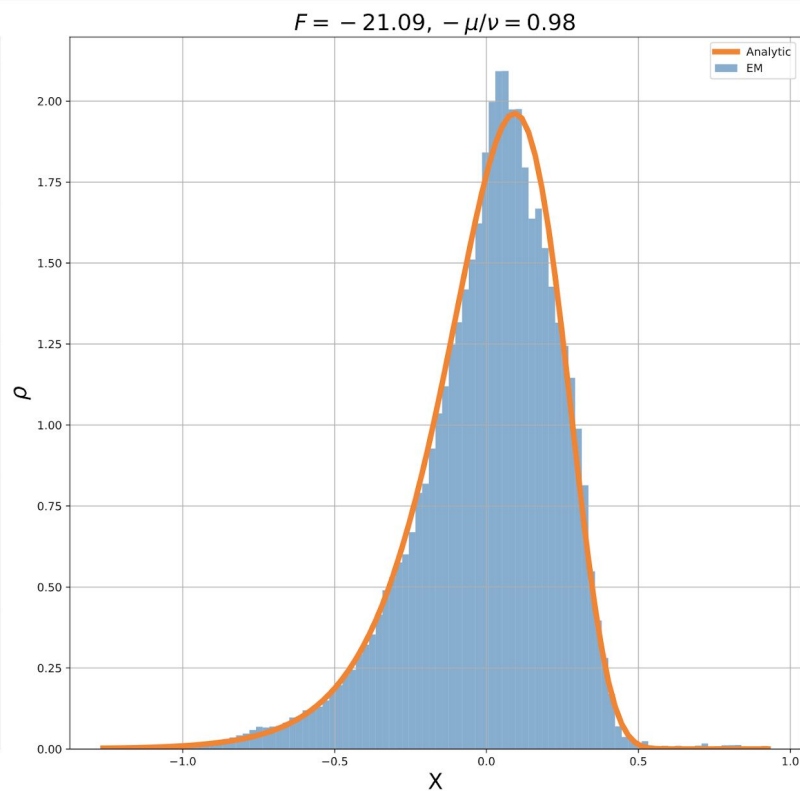
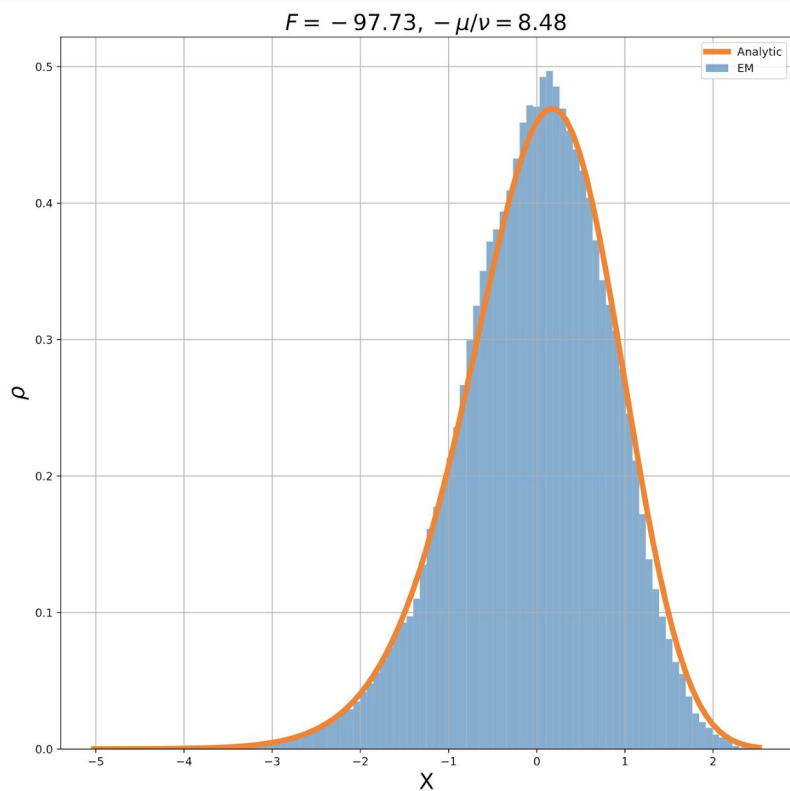
# Characterising Behaviour (i): PDFs

$$p(x) = C_0(\nu x + \mu)^F \exp\left\{\frac{-2\lambda x}{\nu(\nu x + \mu)}\right\}$$



# Characterising Behaviour (i): PDFs

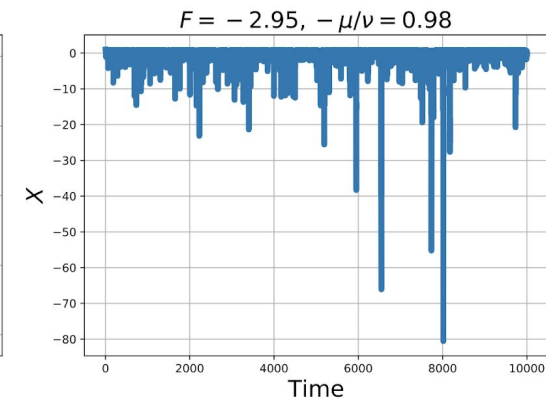
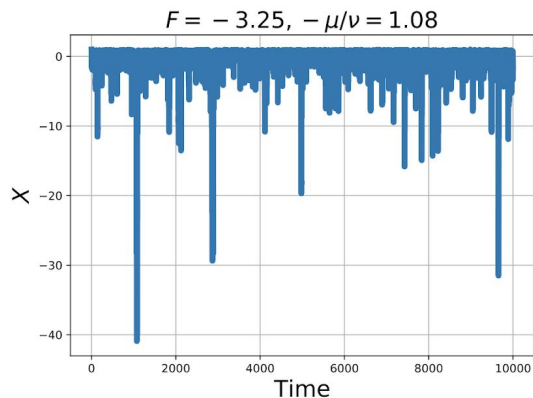
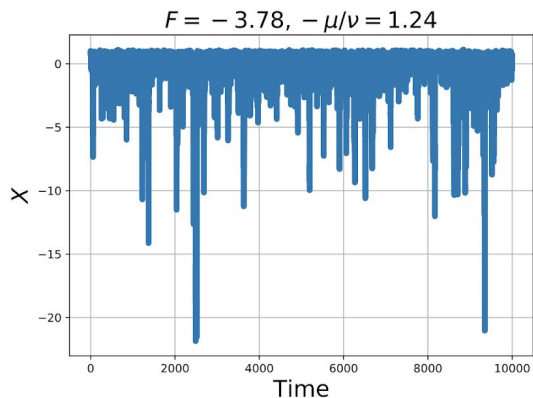
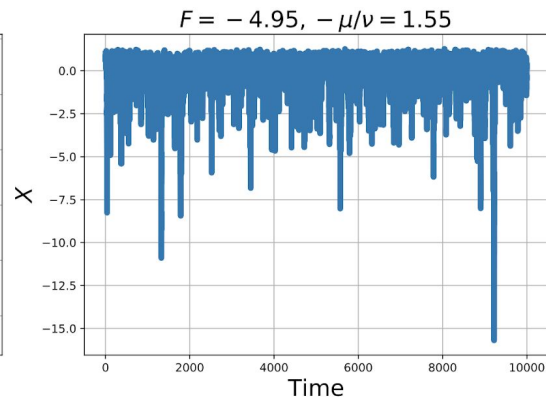
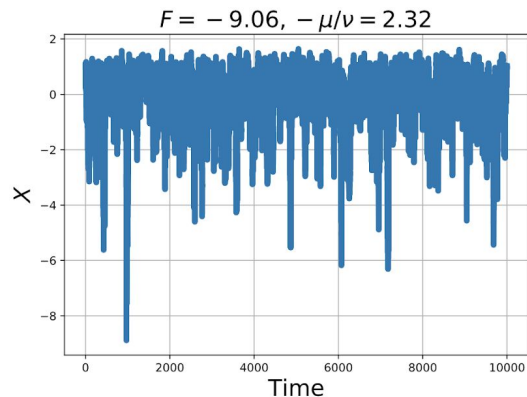
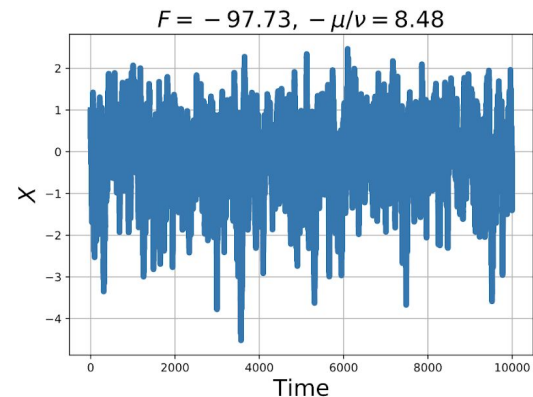
$$p(x) = C_0(\nu x + \mu)^F \exp\left\{\frac{-2\lambda x}{\nu(\nu x + \mu)}\right\}$$



# Characterising Behaviour (ii): Timeseries

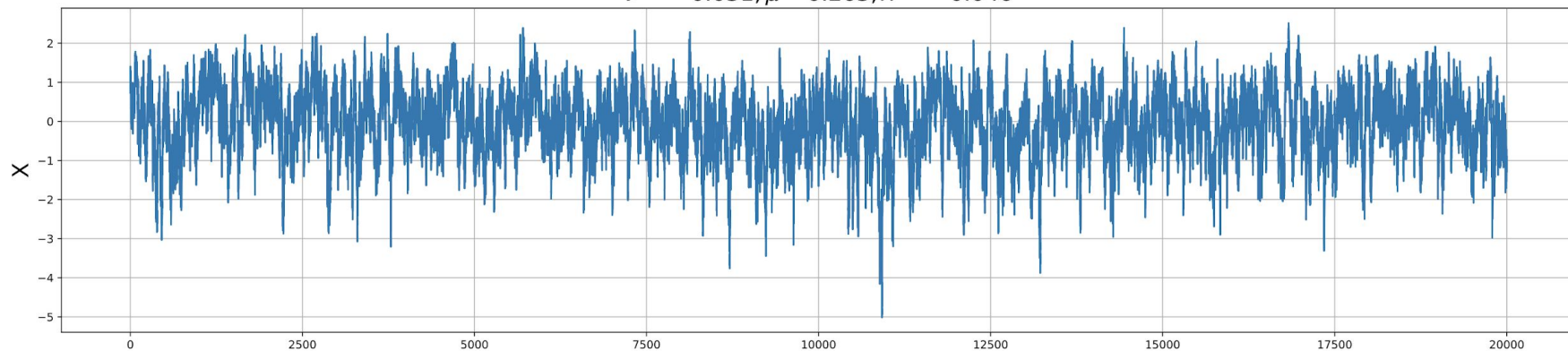
$$dX_t = \lambda X_t dt + (\mu + v X_t) dW_t$$

$$F = \frac{2\lambda}{v^2} - 2$$

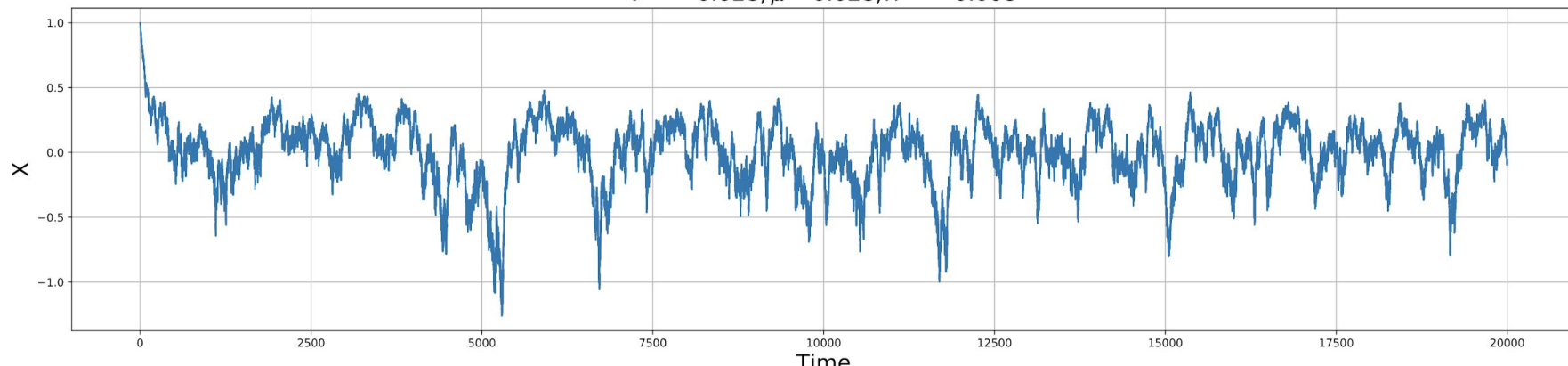


# Characterising Behaviour (ii): Timeseries

$$\nu = -0.031, \mu = 0.263, \lambda = -0.046$$



$$\nu = -0.028, \mu = 0.028, \lambda = -0.008$$



# Parameter Estimation - Maximum Likelihood Estimation

Have state observations,  $x_k$ , at  $N$  times.

Assume model  $dX_t = \lambda X_t dt + (\mu + \nu X) dW_t$

Probability density for observed trajectory  $f_0(X_0|\theta) \prod_{k=0}^{N-1} f(X_{k+1}|X_k; \theta)$

Maximise w.r.t. Parameters  $\theta = \{\lambda, \nu, \mu\}$ .

Minimise negative of log-likelihood function (Jeisman, 2005)  $-\sum_{k=0}^{N-1} \log(f(X_{k+1}|X_k; \theta))$



Estimate transition probability densities using Euler-Maruyama method

$$dt = 1 \text{ day}, \quad X_{k+1} \approx X_k(1 + \lambda) + (\mu + \nu X_k)\xi, \quad \xi \sim N(0, 1)$$

$$\Rightarrow X_{k+1} | X_k \sim N(X_k(1 + \lambda), (\mu + \nu X_k))$$

$$\Rightarrow f(X_{k+1} = x | X_k = y; \theta) \approx \frac{1}{\sqrt{2\pi(\mu + \nu y)}} \exp \left( -\frac{1}{2} \left( \frac{x - y(1 + \lambda)}{\mu + \nu y} \right)^2 \right)$$

Have analytic form of log-likelihood function for given data

# Results

Ornstein-Uhlenbeck ( $\nu=0$ ):

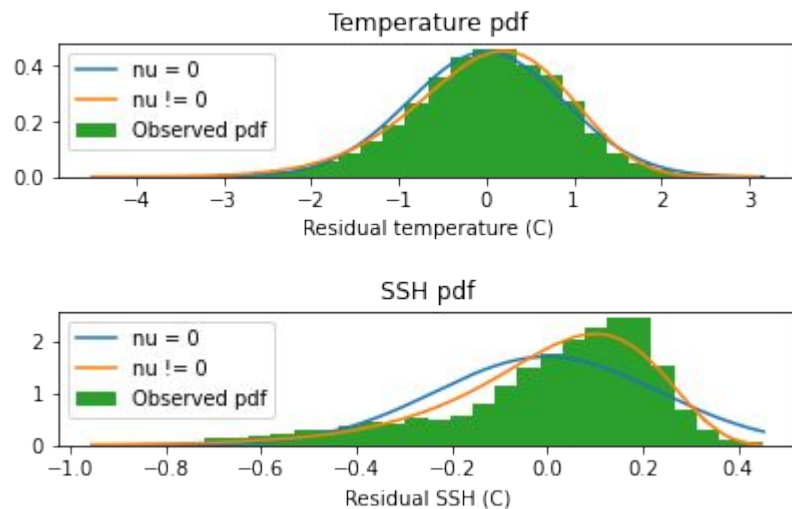
SST:  $\mu = 0.265^\circ \text{C day}^{-1/2}$ ,  $\lambda = -0.044 \text{ day}^{-1}$

SSH:  $\mu = 0.0290 \text{ m day}^{-1/2}$ ,  $\lambda = -0.0076 \text{ day}^{-1}$

Multiplicative Noise ( $\nu \neq 0$ ):

SST:  $\mu = 0.262^\circ \text{C day}^{-1/2}$ ,  $\lambda = -0.042 \text{ day}^{-1}$ ,  $\nu = -0.032 \text{ day}^{-1/2}$

SSH:  $\mu = 0.0276 \text{ m day}^{-1/2}$ ,  $\lambda = -0.0083 \text{ day}^{-1}$ ,  $\nu = -0.0348 \text{ day}^{-1/2}$



# Conclusions / Summary

SSH is significantly skewed compared to SST

Potentially explained by baroclinic instability - affects SSH more than SST

SST is modeled well by red noise whereas SSH requires multiplicative noise

Validated using comparison between spectral powers, parameter estimation for an SDE and comparison between analytic Fokker-Planck and observed PDF

# References

Cleveland, R. B., Cleveland, W. S., McRae, J. E., and Terpenning, I. (1990) STL: A Seasonal-Trend Decomposition Procedure Based on LOESS. *Journal of Official Statistics*, 6, 3-73.

Sura, P., Guille, S. (2010) Stochastic Dynamics of Sea Surface Height Variability, *Journal of Physical Oceanography*, 40(7):1582-1596

Sura, P. and P. D. Sardeshmukh, 2008: A global view of non-Gaussian SST variability. *J. Phys. Oceanogr.*, 38,639–647.

Vaughan, S., (2005) A simple test for periodic signals in red noise, *Astronomy & Astrophysics* 431, 391-403

Wu, P-F. et al., (2019) The diversity and biogeography of microeukaryotes in the euphotic zone of the northwestern Pacific Ocean, *Science of The Total Environment* 698:134289

Joseph Jeisman, (2005) Estimation of the Parameters of Stochastic Differential Equations