



i	a_i	α_i	d_i	θ_i	q_i
1	L_1	0	L_2	θ_1	θ_1
2	0	0	L_3	0	L_3
3	L_4	90	L_5	θ_2	θ_2
4	L_6	-90	0	$\theta_3 - 90$	θ_3
5	0	90	L_7	$\theta_4 + 90$	θ_4
6	L_8	-90	0	$\theta_5 - 90$	θ_5
7	0	90	L_9	$\theta_6 + 90$	θ_6
8	L_{10}	-90	0	$\theta_7 - 90$	θ_7
9	0	0	L_{11}	θ_8	θ_8
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Table 1: Joint Link Parameter Table