

Tercera Práctica Calificada

Solucionario

Resolver las siguientes ecuaciones diferenciales:

1. $y''' - 2y' + 4y = x^2 + \sin x + e^x \cos x \dots (I)$

Solución:

$(D^3 - 2D + 4)y = (D+2)(D^2 - 2D + 2)y = x^2 + \sin x + e^x \cos x \dots (II)$

a) y_H :

$(r+2)(r^2 - 2r + 2) = 0 \Rightarrow r+2=0, (r-1)^2 + 1=0$
 $\Rightarrow r_1 = -2, r_{2,3} = 1 \pm i(1)$

$\Rightarrow y_H = c_1 e^{-2x} + (c_2 \cos x + c_3 \sin x) e^x \dots (1)$

b) y_p : De (II): $y_p = \frac{1}{4 - 2D + D^3} x^2 + \frac{1}{D^2 - 2D + 4} \sin x + \frac{1}{(D-1)^2 + 1} e^x \cos x$

$\Rightarrow y_p = \frac{1}{4} \left(1 + \frac{1}{2}D + \frac{1}{4}D^2 - \frac{1}{8}D^3 - \dots \right) x^2 + \frac{1}{(-1) \cdot D - 2D + 4} \sin x$
 $+ e^x \cdot \frac{1}{(D^2 + 1)(D + 3)} \cos x$

$\Rightarrow y_p = \frac{1}{4} \left(x^2 + \frac{1}{4} D x^2 + \frac{1}{4} D^2 x^2 + 0 \right) - \frac{1}{3D - 4} \sin x + e^x \cdot \frac{1}{D^2 + 1} \left[(D - 3) \cdot \frac{1}{D^2 - 3^2} \cos x \right]$

$\Rightarrow y_p = \frac{1}{4} \left(x^2 + \frac{1}{4} (2x) + \frac{1}{4} (2) \right) - (3D + 4) \cdot \frac{1}{9D^2 - 16} \sin x + e^x \cdot \frac{1}{D^2 + 1} \left[(D - 3) \cdot \frac{1}{-1^2 - 3^2} \cos x \right]$

$\Rightarrow y_p = \frac{1}{4} \left(x^2 + \frac{1}{2}x + \frac{1}{2} \right) - (3D + 4) \cdot \frac{1}{9(-1) - 16} \sin x - \frac{1}{10} e^x \cdot \frac{1}{D^2 + 1} (D - 3) \cos x$

$\Rightarrow y_p = \frac{2x^2 + x + 1}{8} + \frac{1}{25} \left(3D \sin x + 4 \sin x \right) - \frac{1}{10} e^x \cdot \frac{1}{D^2 + 1} (D \cos x - 3 \cos x)$

$\Rightarrow y_p = \frac{2x^2 + x + 1}{8} + \frac{1}{25} (3 \cos x + 4 \sin x) + \frac{1}{10} e^x \left[\frac{1}{D^2 + 1} \sin x + 3 \frac{1}{D^2 + 1} \cos x \right]$

$\Rightarrow y_p = \frac{2x^2 + x + 1}{8} + \frac{3 \cos x + 4 \sin x}{25} + \frac{e^x}{10} \left(-\frac{x \cos x}{2(1)} + 3 \cdot \frac{x \sin x}{2(1)} \right)$

$\Rightarrow y_p = \frac{2x^2 + x + 1}{8} + \frac{3 \cos x + 4 \sin x}{25} + \frac{x e^x}{20} (3 \sin x - \cos x)$

* $1 \div (D^3 - 2D + 4) \Rightarrow$

1		4 - 2D + D ³
-1 + 1/2 D	-1/4 D ³	1/4 + 1/8 D + 1/16 D ² - 1/32 D ³
-1/2 D + 1/4 D ²	-1/8 D ⁴	
-1/4 D ² + 1/8 D ³	-1/16 D ⁵	
-1/8 D ³ - 1/8 D ⁴ - 1/16 D ⁵		
1/8 D ³ - 1/16 D ⁴ + 1/32 D ⁵		

1. b)

i) y_H :

\Rightarrow

ii) y_p :

De (I),

$$y_p = \frac{1}{D^4} \cdot \frac{1}{D^2-1} x^3 + 4 \cdot \frac{1}{(D+1) \cdot \underbrace{D^4(D+1)}_{P(D)}} e^{-x}$$

\Rightarrow

\Rightarrow

\Rightarrow

$$D^4(D^2-1)y = x^3 + 4e^{-x} \dots (I)$$

$$r^4(r+1)(r-1) = 0 \Rightarrow r_{1,2,3,4} = 0, r_5 = -1, r_6 = 1$$

$$y_H = c_1 x^3 + c_2 x^2 + c_3 x + c_4 + c_5 e^{-x} + c_6 e^x \dots (1)$$

$$y_p = \frac{1}{D^4} [(1 + D^2 + D^4 + D^6 + \dots) x^3 + e^{-x} \cdot \frac{x}{1!(-1)^4(-2)}]$$

$$y_p = -\frac{1}{D^4} (x^3 + \underbrace{D^2 x^3}_{6x} + \underbrace{D^4 x^3}_{=0} + \dots) + \frac{x e^{-x}}{2}$$

$$y_p = -\int \int \int \int (x^3 + 6x) dx db da dc - \frac{x e^{-x}}{2}$$

$$y_p = -\frac{x^7}{4 \cdot 5 \cdot 6 \cdot 7} - \frac{x e^{-x}}{2}$$

1. c)

Solución:

a) y_H :

\Rightarrow

b) y_p :

donde:

$$W[y_1, y_2] = \begin{vmatrix} 1 & e^{-x} \\ 0 & -e^{-x} \end{vmatrix} \Rightarrow W[y_1, y_2] = -e^{-x}$$

$$b_1) c_1(x) = -\int \frac{y_2 Q(x)}{a_0(x) W[y_1, y_2]} dx = -\int \frac{e^{-x} \cdot \sec x \tan x}{1 \cdot (-e^{-x})} dx = \int \sec x \tan x dx$$

$$\Rightarrow c_1(x) = \sec x$$

$$b_2) c_2(x) = \int \frac{y_1 Q(x)}{a_0(x) W[y_1, y_2]} dx = \int \frac{1 \cdot \sec x \tan x}{1 \cdot (-e^{-x})} dx = \int \underbrace{e^x}_u \cdot \underbrace{\sec x \tan x}_{dv} dx$$

$$du = e^x dx, v = \sec x$$

$$\Rightarrow c_2(x) = e^x \sec x - \int e^x \sec x dx$$

$$\Rightarrow G_H(x): y_p = \sec x + (e^x \sec x - \int e^x \sec x dx) e^{-x}$$

$$y_p = 2 \sec x - e^{-x} \int e^x \sec x dx$$

2. Resolver la ecuación: $\underbrace{x^4}_{a_0(x)} y'' + \underbrace{x^3}_{a_1(x)} y' - 4x^2 y = 1$ $y_1 = x^2 \dots (I)$

Solución: La ecuación diferencial homogénea asociada a la ecuación propuesta es: $x^4 y'' + x^3 y' - 4x^2 y = 0 \dots (II)$

siendo una de sus soluciones $y_1 = x^2 \dots (1) \Rightarrow y_2 = u(x)x^2 \dots (2)$, también será otra solución, donde:

$$u = u(x) = \int \frac{e^{-\int \frac{a_1(x)}{a_0(x)} dx}}{y_1^2} dx = \int \frac{e^{-\int \frac{x^3}{x^4} dx}}{(x^2)^2} dx = \int \frac{e^{-\int \frac{dx}{x}}}{x^4} dx = \int \frac{e^{-\ln x}}{x^4} dx$$

$$\Rightarrow u = u(x) = \int \frac{x^{-1}}{x^4} dx = \int x^{-5} dx \Rightarrow u = -\frac{1}{4x^4}$$

$$\Rightarrow \text{en (2): } y_2 = \frac{1}{x^2} \dots (3)$$

$$\text{De (1) y (3), } y_H = C_1 x^2 + C_2 \cdot \frac{1}{x^2} \dots (\alpha)$$

$$\Rightarrow y_p: y_p = C_1(x)x^2 + C_2 \cdot \frac{1}{x^2} \dots (\beta)$$

$$\text{donde: } W[y_1, y_2] = \begin{vmatrix} x^2 & \frac{1}{x^2} \\ 2x & -\frac{2}{x^3} \end{vmatrix} = x^2(-\frac{2}{x^3}) - 2x(\frac{1}{x^2}) = -\frac{2}{x} - \frac{2}{x}$$

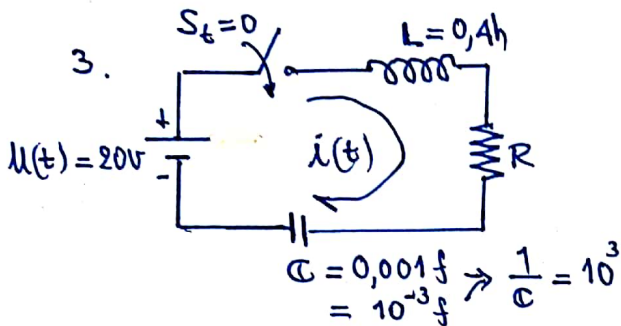
$$\hookrightarrow W[y_1, y_2] = -\frac{4}{x}$$

$$a) C_1(x) = -\int \frac{y_2 Q(x)}{a_0(x) W[y_1, y_2]} dx = -\int \frac{\frac{1}{x^2} \cdot 1}{x^4 \cdot (-\frac{4}{x})} dx = \frac{1}{4} \int x^{-5} dx = -\frac{x^{-4}}{16}$$

$$b) C_2(x) = \int \frac{y_1 Q(x)}{a_0(x) W[y_1, y_2]} dx = \int \frac{x^2 \cdot 1}{x^4 \cdot (-\frac{4}{x})} dx = -\frac{1}{4} \int \frac{dx}{x} \Rightarrow C_2(x) = -\frac{1}{4} \ln x$$

$$C_1(x) \text{ y } C_2(x) \text{ en } (\beta): y_p = \left(-\frac{x^{-4}}{16}\right)x^2 + \left(-\frac{1}{4} \ln x\right) \cdot \frac{1}{x^2}$$

$$y_p = -\frac{x^{-2}}{16} - \frac{\ln x}{4x^2} = -\frac{1 + 4 \ln x}{46x^2}$$



$$V_L + V_C = u(t)$$

$$L Q''(t) + \frac{1}{C} Q(t) = 20V$$

$$0,4 Q''(t) + 10^3 Q(t) = 20$$

$$\rightarrow Q''(t) + 2500 Q(t) = 50 \dots (I)$$

$$(D^2 + 2500) Q(t) = 50 \dots (II)$$

a) $Q_H(t)$:

$$r^2 + 2500 = 0 \Rightarrow r = \pm i50$$

\Rightarrow

$$Q_H(t) = C_1 \cos 50t + C_2 \sin 50t \dots (1)$$

b) $Q_P(t)$:

$$Q_P(t) = 50 \cdot \frac{1}{D^2 + 2500} e^{0t} = 50 \cdot \frac{1}{0^2 + 2500} \dots (1)$$

$$Q_P(t) = \frac{1}{50} \dots (2)$$

$$\Rightarrow Q(1) \text{ y } (2): Q(t) = C_1 \cos 50t + C_2 \sin 50t + \frac{1}{50} \dots (2)$$

$$\rightarrow D_t: i(t) = Q'(t) = -50 C_1 \sin 50t + 50 C_2 \cos 50t \dots (3)$$

Si $t = 0$

$$i) \text{ Gm } (\alpha): Q(0) = C_1(1) + C_2(0) + \frac{1}{50} = 0 \Rightarrow C_1 = -\frac{1}{50}$$

$$ii) \text{ Gm } (\beta): i(0) = -50 C_1(0) + 50 C_2(1) = 0 \Rightarrow C_2 = 0$$

$$\rightarrow \text{Gm } (\alpha) \text{ y } (\beta): Q(t) = -\frac{1}{50} \cos 50t + \frac{1}{50}$$

$$i(t) = \sin 50t$$