

# 1. Observations on 1 pixel kernel

In Line (I), the operation `self.in2out = nn.Conv2d(in_ch, out_ch, 1)` is used to change the number of channels from `in_ch` to `out_ch`. By using a  $1 \times 1$  kernel, this convolution applies a transformation independently to each pixel across channels. Instead of considering neighboring pixels, it performs a per-pixel operation, essentially applying learned linear transformation to each pixel's channel values. This allows for a channel-wise transformation while preserving spatial structure.

In Lines (K) and (L), the operations `self.downsampler1 = nn.Conv2d(in_ch, in_ch, 1, stride=2)` and `self.downsampler2 = nn.Conv2d(out_ch, out_ch, 1, stride=2)` serve as downsamplers. By setting `stride=2`, the convolution layer skips every other pixel in both the width and height dimensions. This results in a reduction of spatial resolution while performing a per-pixel linear transformation across channels. Unlike conventional convolution, which considers spatial neighbors, this method reduces the number of pixels processed while retaining key features.

The reason why Lines (I), (K), and (L) make sense in using a  $1 \times 1$  kernel is that they perform a linear transformation at each pixel location while maintaining spatial information. Line (I) adjusts the number of channels without altering spatial dimensions, whereas Lines (K) and (L) downsample the feature map while preserving channel-wise structure.

# 2. BMENet with maxpool

```
In [1]: import os, sys  
print(os.getcwd())  
sys.path.append("./../DLStudio-2.5.1")  
  
# from DLStudio import *
```

/home/chen4126/ece60146/HW6

```
In [4]: import torch.nn as nn  
from DLStudio import DLStudio  
import torch  
  
# this code is mainly borrowed from DLstudio, the code that i modify has a comment  
class BMENetModifiedForMaxpool(nn.Module):  
    def __init__(self, dl_studio, skip_connections=True, depth=8):  
        super().__init__()  
  
        self.dl_studio = dl_studio  
        self.depth = depth  
        image_size = dl_studio.image_size  
        ## num_ds stands for number of downsampling steps  
        num_ds = 0
```

```

        self.conv = nn.Conv2d(3, 64, 3, padding=1)

        # Layers of skipblock without downsample
        self.skip64_arr = nn.ModuleList()
        for i in range(self.depth):
            self.skip64_arr.append(self.SkipBlock(64, 64, skip_connections=skip_conn))
        # a skipblock with downsample
        self.skip64to128ds = self.SkipBlock(64, 128, downsample=True, skip_connections=skip_conn)
        num_ds += 1

        self.skip128_arr = nn.ModuleList()
        for i in range(self.depth):
            self.skip128_arr.append(self.SkipBlock(128, 128, skip_connections=skip_conn))
        self.skip128to256ds = self.SkipBlock(128, 256, downsample=True, skip_connections=skip_conn)
        num_ds += 1

        self.skip256_arr = nn.ModuleList()
        for i in range(self.depth):
            self.skip256_arr.append(self.SkipBlock(256, 256, skip_connections=skip_conn))

        self.fc1 = nn.Linear( (image_size[0]// (2 ** num_ds)) * (image_size[1]// (2 ** num_ds)), 1000)
        self.fc2 = nn.Linear(1000, 10)

    def forward(self, x):
        x = nn.functional.relu(self.conv(x))
        for skip64 in self.skip64_arr:
            x = skip64(x)
        x = self.skip64to128ds(x)
        for skip128 in self.skip128_arr:
            x = skip128(x)
        x = self.skip128to256ds(x)
        for skip256 in self.skip256_arr:
            x = skip256(x)
        x = x.view( x.shape[0], - 1 )
        x = nn.functional.relu(self.fc1(x))
        x = self.fc2(x)
        return x

    def load_cifar_10_dataset(self):
        self.dl_studio.load_cifar_10_dataset()

    def load_cifar_10_dataset_with_augmentation(self):
        self.dl_studio.load_cifar_10_dataset_with_augmentation()

class SkipBlock(nn.Module):
    def __init__(self, in_ch, out_ch, downsample=False, skip_connections=True):
        super().__init__()
        self.downsample = downsample
        self.skip_connections = skip_connections
        self.in_ch = in_ch

```

```

        self.out_ch = out_ch
        self.convo1 = nn.Conv2d(in_ch, in_ch, 3, stride=1, padding=1)
        self.convo2 = nn.Conv2d(in_ch, out_ch, 3, stride=1, padding=1)
        self.bn1 = nn.BatchNorm2d(in_ch)
        self.bn2 = nn.BatchNorm2d(out_ch)
        self.in2out = nn.Conv2d(in_ch, out_ch, 1)
        if downsample:
            self.maxpool = nn.MaxPool2d(2, 2) # do maxpool

    def forward(self, x):
        # identity holds the original input tensor to the skip block
        identity = x
        out = self.convo1(x)
        out = self.bn1(out)
        out = nn.functional.relu(out)
        out = self.convo2(out)
        out = self.bn2(out)
        out = nn.functional.relu(out)

        # Apply downsampling if needed
        if self.downsample:
            identity = self.maxpool(identity)           # channel still input size
            out = self.maxpool(out)                     # channel still output size

        # Handle skip connections
        if self.skip_connections:
            if (self.in_ch == self.out_ch) and (self.downsample is False):
                out = out + identity
            elif (self.in_ch != self.out_ch) and (self.downsample is False):
                identity = self.in2out( identity )
                out = out + identity
            elif (self.in_ch != self.out_ch) and (self.downsample is True):
                out = out + torch.cat((identity, identity), dim=1)

        return out

    def run_code_for_training(self, net, display_images=False):
        self.dl_studio.run_code_for_training(net, display_images)

    def save_model(self, model):
        '''
        Save the trained model to a disk file
        '''
        torch.save(model.state_dict(), self.dl_studio.path_saved_model)

    def run_code_for_testing(self, model, display_images=False):
        self.dl_studio.run_code_for_testing(model, display_images)

dls = DLStudio(
    #           dataroot = "/home/kak/ImageDatasets/CIFAR-10/",
    dataroot = "./../data/CIFAR-10/",
    image_size = [32,32],

```

```
        path_saved_model = "./saved_model",
        momentum = 0.9,
        learning_rate = 1e-5,
        epochs = 10,
        batch_size = 16,
        classes = ('plane','car','bird','cat','deer','dog','frog','horse',''
        use_gpu = True,
    )

bme_net = BMENetModifiedForMaxpool(dls, skip_connections=True, depth=8)           ##

bme_net.load_cifar_10_dataset()

## display network properties
number_of_learnable_params = sum(p.numel() for p in bme_net.parameters() if p.requires_grad)
print("\n\nThe number of learnable parameters in the model: %d" % number_of_learnable_params)

## training and testing
bme_net.run_code_for_training(bme_net, display_images=False)
bme_net.run_code_for_testing(bme_net, display_images=False)
```

Files already downloaded and verified  
Files already downloaded and verified

The number of learnable parameters in the model: 30092354

Starting training loop...

```
[epoch:1/10  iter=1000  elapsed_time= 25 secs]  Ground Truth:      bird
plane      frog      ship      car      deer      frog      ship      deer
horse      bird      deer      frog      car      dog      ship
[epoch:1/10  iter=1000  elapsed_time= 25 secs]  Predicted Labels:  plane
plane      car      car      car      deer      deer      deer      dog
dog       bird      cat      dog      dog      dog      bird
[epoch:1/10  iter=1000  elapsed_time= 25 secs]  Loss: 2.278
```

```
[epoch:1/10  iter=2000  elapsed_time= 51 secs]  Ground Truth:      frog
plane      dog      truck      cat      horse      car      bird      deer
deer       car      frog      horse     bird      horse      horse
[epoch:1/10  iter=2000  elapsed_time= 51 secs]  Predicted Labels:  frog
ship       bird      car      cat      ship      car      frog      truck
frog       car      frog      horse     frog      dog      truck
[epoch:1/10  iter=2000  elapsed_time= 51 secs]  Loss: 1.803
```

```
[epoch:1/10  iter=3000  elapsed_time= 75 secs]  Ground Truth:      plane
car       frog      cat      bird      horse      truck      car      ship
deer       cat      cat      car      frog      dog      bird
[epoch:1/10  iter=3000  elapsed_time= 75 secs]  Predicted Labels:  plane
horse      dog      cat      bird      plane      truck      car      ship
deer       dog      frog      truck     deer      dog      bird
[epoch:1/10  iter=3000  elapsed_time= 75 secs]  Loss: 1.668
```

```
[epoch:2/10  iter=1000  elapsed_time= 104 secs]  Ground Truth:      truck
deer      plane      bird      cat      dog      ship      bird      deer
bird      frog      truck      car      deer      ship      horse
[epoch:2/10  iter=1000  elapsed_time= 104 secs]  Predicted Labels:  car
deer      ship      plane      cat      dog      car      deer      car
dog       deer      dog      car      deer      ship      horse
[epoch:2/10  iter=1000  elapsed_time= 104 secs]  Loss: 1.578
```

```
[epoch:2/10  iter=2000  elapsed_time= 128 secs]  Ground Truth:      dog
deer      car      horse      deer      horse      frog      cat      ship
plane      plane      car      frog      bird      car      frog
[epoch:2/10  iter=2000  elapsed_time= 128 secs]  Predicted Labels:  dog
ship      car      deer      deer      deer      frog      dog      truck
plane      plane      car      horse     bird      car      frog
[epoch:2/10  iter=2000  elapsed_time= 128 secs]  Loss: 1.526
```

```
[epoch:2/10  iter=3000  elapsed_time= 153 secs]  Ground Truth:      bird
cat      deer      plane      horse      ship      deer      frog      dog
plane     dog      horse      plane      car      dog      frog
[epoch:2/10  iter=3000  elapsed_time= 153 secs]  Predicted Labels:   dog
horse     frog      plane      car      truck      deer      bird
plane     dog      dog      car      car      dog      car
[epoch:2/10  iter=3000  elapsed_time= 153 secs]  Loss: 1.482
```

```
[epoch:3/10  iter=1000  elapsed_time= 183 secs]  Ground Truth:      ship
plane     horse      cat      bird      deer      frog      deer      cat
deer      bird      deer      cat      truck      bird      truck
[epoch:3/10  iter=1000  elapsed_time= 183 secs]  Predicted Labels:   ship
plane     horse      cat      bird      horse      frog      car      truck
horse     bird      deer      dog      car      bird      truck
[epoch:3/10  iter=1000  elapsed_time= 183 secs]  Loss: 1.422
```

```
[epoch:3/10  iter=2000  elapsed_time= 208 secs]  Ground Truth:      deer
horse     dog      truck      ship      bird      frog      bird      ship
truck     frog      plane      horse      frog      car      truck
[epoch:3/10  iter=2000  elapsed_time= 208 secs]  Predicted Labels:   dog
horse     cat      truck      bird      bird      frog      truck      ship
truck     frog      bird      horse      frog      truck      truck
[epoch:3/10  iter=2000  elapsed_time= 208 secs]  Loss: 1.405
```

```
[epoch:3/10  iter=3000  elapsed_time= 232 secs]  Ground Truth:      cat
deer      ship      cat      truck      bird      cat      plane      horse
car       horse      plane      horse      truck      deer      cat
[epoch:3/10  iter=3000  elapsed_time= 232 secs]  Predicted Labels:   dog
deer      car      dog      car      frog      dog      plane      horse
car       frog      plane      horse      plane      plane      dog
[epoch:3/10  iter=3000  elapsed_time= 232 secs]  Loss: 1.361
```

```
[epoch:4/10  iter=1000  elapsed_time= 260 secs]  Ground Truth:      horse
deer      frog      bird      horse      bird      truck      horse      dog
cat       dog      plane      plane      cat      frog      bird
[epoch:4/10  iter=1000  elapsed_time= 260 secs]  Predicted Labels:   cat
deer      deer      deer      deer      ship      truck      horse      cat
cat       cat      plane      plane      cat      frog      ship
[epoch:4/10  iter=1000  elapsed_time= 260 secs]  Loss: 1.339
```

```
[epoch:4/10  iter=2000  elapsed_time= 285 secs]  Ground Truth:      plane
horse     frog      truck      deer      bird      frog      dog      truck
car       car      truck      plane      dog      horse      deer
[epoch:4/10  iter=2000  elapsed_time= 285 secs]  Predicted Labels:   plane
plane     horse      car      deer      ship      frog      cat      cat
car       truck      car      plane      dog      horse      deer
[epoch:4/10  iter=2000  elapsed_time= 285 secs]  Loss: 1.303
```

```
[epoch:4/10 iter=3000 elapsed_time= 308 secs] Ground Truth: ship
deer      ship      dog      car      plane      plane      bird      truck
bird      deer      car      truck     bird       car       car
[epoch:4/10 iter=3000 elapsed_time= 308 secs] Predicted Labels: ship
bird      ship      dog      car      plane      plane      bird      truck
dog      deer      car      plane     bird       car       deer
[epoch:4/10 iter=3000 elapsed_time= 308 secs] Loss: 1.310
```

```
[epoch:5/10 iter=1000 elapsed_time= 338 secs] Ground Truth: dog
horse    truck    dog      ship      bird      ship      frog      frog
car      car      dog      deer      bird      plane      bird
[epoch:5/10 iter=1000 elapsed_time= 338 secs] Predicted Labels: deer
horse    horse    horse    ship      horse     car      deer      cat
car      truck    dog      dog      plane     plane      bird
[epoch:5/10 iter=1000 elapsed_time= 338 secs] Loss: 1.281
```

```
[epoch:5/10 iter=2000 elapsed_time= 363 secs] Ground Truth: dog
car      bird      car      plane     bird      frog      deer      deer
plane    cat      plane    car      dog      dog      dog
[epoch:5/10 iter=2000 elapsed_time= 363 secs] Predicted Labels: cat
car      bird      ship      plane     ship      deer      cat      cat
ship    dog      plane    truck     horse     cat      bird
[epoch:5/10 iter=2000 elapsed_time= 363 secs] Loss: 1.242
```

```
[epoch:5/10 iter=3000 elapsed_time= 387 secs] Ground Truth: dog
car      truck    ship      frog      frog      deer      frog      cat
plane    truck    ship      cat      cat      deer      plane
[epoch:5/10 iter=3000 elapsed_time= 387 secs] Predicted Labels: cat
car      car      ship      frog      cat      cat      frog      cat
plane    car      ship      cat      deer      bird      plane
[epoch:5/10 iter=3000 elapsed_time= 387 secs] Loss: 1.237
```

```
[epoch:6/10 iter=1000 elapsed_time= 416 secs] Ground Truth: deer
truck    bird      deer      car      horse     dog      horse      car
frog      frog      cat      cat      deer      plane      car
[epoch:6/10 iter=1000 elapsed_time= 416 secs] Predicted Labels: deer
truck    bird      cat      car      truck     dog      horse      truck
frog      cat      cat      frog      bird      plane      truck
[epoch:6/10 iter=1000 elapsed_time= 416 secs] Loss: 1.203
```

```
[epoch:6/10 iter=2000 elapsed_time= 439 secs] Ground Truth: truck
ship      bird      truck    plane     plane     ship      dog      frog
truck    truck    horse    horse     cat      plane      horse
[epoch:6/10 iter=2000 elapsed_time= 439 secs] Predicted Labels: ship
ship      horse    ship      truck    plane     bird      cat      cat
truck    truck    horse    bird      deer     plane      horse
[epoch:6/10 iter=2000 elapsed_time= 439 secs] Loss: 1.198
```

```
[epoch:6/10  iter=3000  elapsed_time= 462 secs]  Ground Truth:      horse
horse      bird      ship      bird      cat      dog      cat      ship
horse      plane     plane     bird      dog      ship      dog
[epoch:6/10  iter=3000  elapsed_time= 462 secs]  Predicted Labels:   dog
horse      plane     car      bird      frog     dog      dog      ship
horse      frog     plane     bird      deer     ship      dog
[epoch:6/10  iter=3000  elapsed_time= 462 secs]  Loss: 1.193
```

```
[epoch:7/10  iter=1000  elapsed_time= 491 secs]  Ground Truth:      frog
dog      truck     truck     truck     horse     ship      truck      cat
ship      dog      plane     deer      horse     truck     dog
[epoch:7/10  iter=1000  elapsed_time= 491 secs]  Predicted Labels:   frog
deer      car      cat      car      horse     plane     car      cat
ship      cat      plane     deer      dog      car      cat
[epoch:7/10  iter=1000  elapsed_time= 491 secs]  Loss: 1.158
```

```
[epoch:7/10  iter=2000  elapsed_time= 514 secs]  Ground Truth:      cat
bird      ship     frog      cat      truck     horse     car      car
ship      bird     bird      frog     horse     horse     deer
[epoch:7/10  iter=2000  elapsed_time= 514 secs]  Predicted Labels:   dog
plane     truck     frog     deer      plane     horse     car      car
plane     ship     bird     frog      dog      horse     deer
[epoch:7/10  iter=2000  elapsed_time= 514 secs]  Loss: 1.150
```

```
[epoch:7/10  iter=3000  elapsed_time= 537 secs]  Ground Truth:      plane
dog      bird     dog      cat      truck     deer     car      car
dog      ship     deer     ship     horse     horse     bird
[epoch:7/10  iter=3000  elapsed_time= 537 secs]  Predicted Labels:   deer
dog      deer     dog      dog      truck     deer     car      truck
horse     car     deer     truck     deer     horse     bird
[epoch:7/10  iter=3000  elapsed_time= 537 secs]  Loss: 1.148
```

```
[epoch:8/10  iter=1000  elapsed_time= 565 secs]  Ground Truth:      truck
deer     frog     plane     bird     frog     ship     dog      truck
plane     cat      plane     plane    cat      frog     horse
[epoch:8/10  iter=1000  elapsed_time= 565 secs]  Predicted Labels:   truck
bird     frog     ship     bird     cat      ship     dog      truck
plane     cat      plane     car      dog      frog     horse
[epoch:8/10  iter=1000  elapsed_time= 565 secs]  Loss: 1.104
```

```
[epoch:8/10  iter=2000  elapsed_time= 589 secs]  Ground Truth:      car
truck     plane     cat      car      car      plane     horse      bird
horse     ship     ship     deer     deer     ship     truck
[epoch:8/10  iter=2000  elapsed_time= 589 secs]  Predicted Labels:   car
truck     plane     bird     car      truck     plane     horse      bird
horse     ship     truck     frog     deer     ship     truck
[epoch:8/10  iter=2000  elapsed_time= 589 secs]  Loss: 1.124
```

```
[epoch:8/10  iter=3000  elapsed_time=  613 secs]  Ground Truth:          bird
horse      frog      dog      bird      frog      ship      deer      horse
cat       frog      frog      plane     plane      dog      car
[epoch:8/10  iter=3000  elapsed_time=  613 secs]  Predicted Labels:      bird
horse      frog      dog      bird      frog      ship      frog      horse
cat       frog      frog      plane     cat       cat      car
[epoch:8/10  iter=3000  elapsed_time=  613 secs]  Loss: 1.085
```

```
[epoch:9/10  iter=1000  elapsed_time=  642 secs]  Ground Truth:          dog
car       truck     horse     car       deer      bird      bird      ship
car       dog       truck     bird      truck     frog      plane
[epoch:9/10  iter=1000  elapsed_time=  642 secs]  Predicted Labels:      frog
car       frog     deer     car       deer      bird      dog      ship
truck     dog       truck     bird      truck     cat       horse
[epoch:9/10  iter=1000  elapsed_time=  642 secs]  Loss: 1.060
```

```
[epoch:9/10  iter=2000  elapsed_time=  665 secs]  Ground Truth:          dog
ship     dog       ship     truck     car       ship      deer      bird
truck     car       bird     deer     bird      frog      dog
[epoch:9/10  iter=2000  elapsed_time=  665 secs]  Predicted Labels:      cat
ship     dog       ship     truck     car       ship      cat      bird
truck     car       bird     deer     frog      frog      bird
[epoch:9/10  iter=2000  elapsed_time=  665 secs]  Loss: 1.055
```

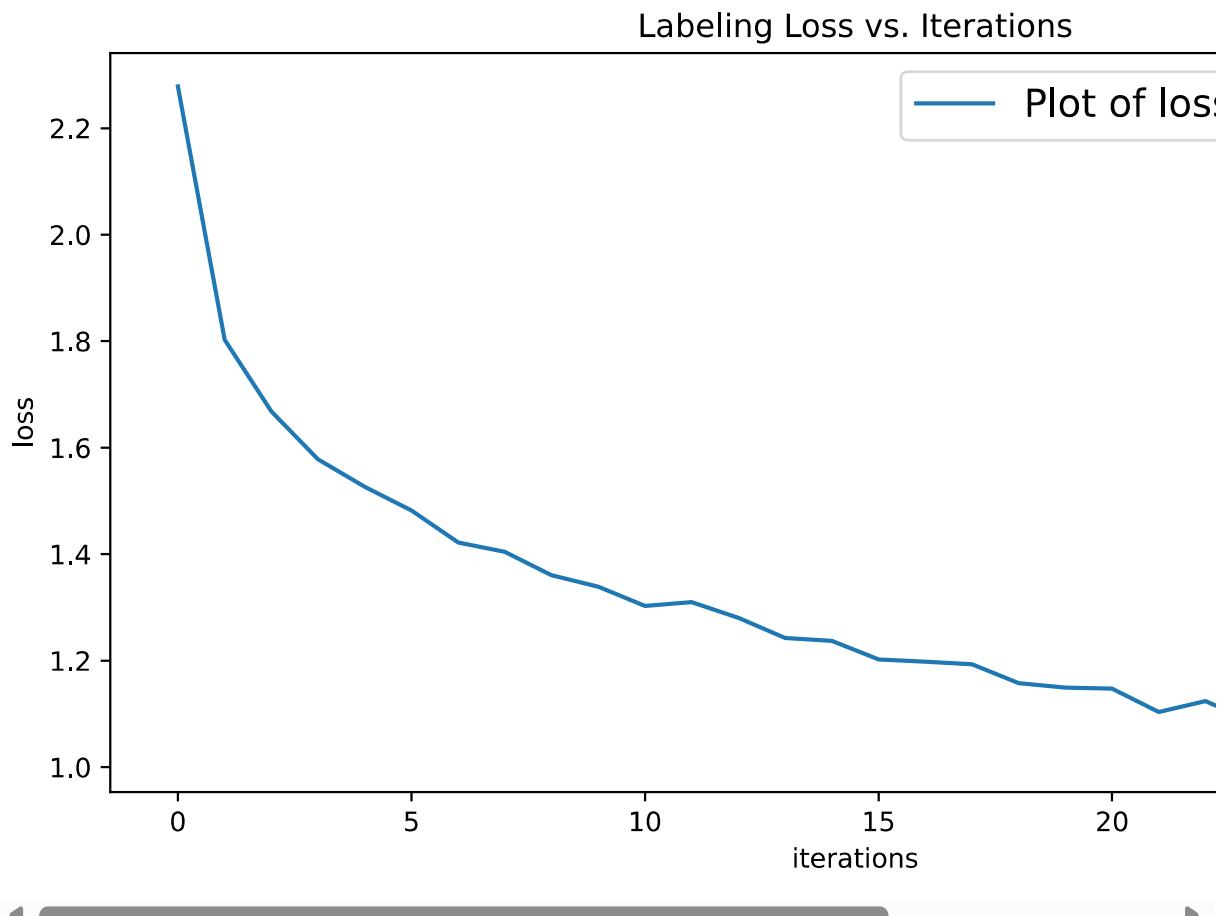
```
[epoch:9/10  iter=3000  elapsed_time=  689 secs]  Ground Truth:          ship
frog      frog      truck     horse     car       plane     frog      car
plane     truck     car       bird     dog       ship      dog
[epoch:9/10  iter=3000  elapsed_time=  689 secs]  Predicted Labels:      ship
deer      frog      truck     horse     truck     plane     deer      ship
horse     truck     truck     bird     dog       ship      dog
[epoch:9/10  iter=3000  elapsed_time=  689 secs]  Loss: 1.054
```

```
[epoch:10/10  iter=1000  elapsed_time=  718 secs]  Ground Truth:         deer
deer      cat       plane     frog     bird      car      horse      bird
dog       car       deer     truck     ship      deer      frog
[epoch:10/10  iter=1000  elapsed_time=  718 secs]  Predicted Labels:      deer
deer      bird      plane     frog     plane     car      horse      deer
deer      car       deer     truck     ship      frog      frog
[epoch:10/10  iter=1000  elapsed_time=  718 secs]  Loss: 1.033
```

```
[epoch:10/10  iter=2000  elapsed_time=  745 secs]  Ground Truth:         car
ship     car       frog     bird     truck     truck     horse      frog
horse     deer     plane     frog     car       deer      horse
[epoch:10/10  iter=2000  elapsed_time=  745 secs]  Predicted Labels:      car
ship     car       dog      horse    truck     plane     cat      frog
horse     cat       plane     frog     car       deer      horse
[epoch:10/10  iter=2000  elapsed_time=  745 secs]  Loss: 1.016
```

```
[epoch:10/10  iter=3000  elapsed_time= 777 secs]  Ground Truth:      cat
horse      deer      cat      car      ship      horse      horse      plane
dog       bird      frog      ship      ship      horse      plane
[epoch:10/10  iter=3000  elapsed_time= 777 secs]  Predicted Labels:   dog
horse      deer      cat      car      ship      horse      horse      plane
dog       bird      frog      ship      ship      horse      ship
[epoch:10/10  iter=3000  elapsed_time= 777 secs]  Loss: 1.019
```

Finished Training



```

Prediction accuracy for plane : 65 %
Prediction accuracy for car : 79 %
Prediction accuracy for bird : 37 %
Prediction accuracy for cat : 52 %
Prediction accuracy for deer : 61 %
Prediction accuracy for dog : 35 %
Prediction accuracy for frog : 68 %
Prediction accuracy for horse : 70 %
Prediction accuracy for ship : 81 %
Prediction accuracy for truck : 77 %

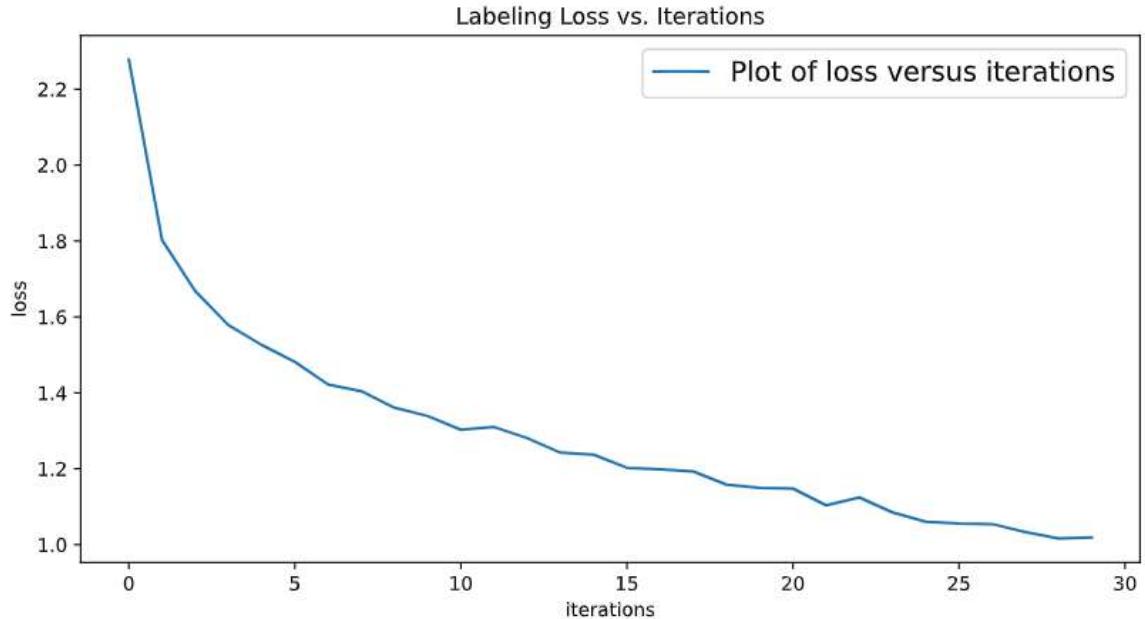
```

Overall accuracy of the network on the 10000 test images: 62 %

Displaying the confusion matrix:

	plane	car	bird	cat	deer	dog	frog	horse	ship	truck
plane:	65.40	4.10	2.70	2.20	2.70	0.30	1.00	1.30	12.20	8.10
car:	1.40	79.10	0.20	0.40	0.50	0.10	0.60	0.10	2.40	15.20
bird:	9.80	2.20	37.30	11.20	17.30	5.20	5.00	4.50	4.30	3.20
cat:	2.90	1.40	5.00	52.40	10.10	7.90	6.70	5.40	2.80	5.40
deer:	2.50	0.80	5.80	7.60	61.60	2.20	5.60	11.00	1.60	1.30
dog:	1.70	0.80	5.10	31.20	8.90	35.50	2.40	8.80	2.70	2.90
frog:	0.60	1.70	4.00	8.50	10.20	0.40	68.20	1.60	1.50	3.30
horse:	1.40	0.60	2.00	7.10	8.10	3.20	1.00	70.00	0.60	6.00
ship:	4.90	5.40	0.20	0.90	0.70	0.00	0.50	0.80	81.90	4.70
truck:	2.30	12.30	0.40	1.60	0.70	0.00	0.80	1.10	3.10	77.70

## 2.1 Train loss curve



## 2.2 Confusion Matrix

	<b>Plane</b>	<b>Car</b>	<b>Bird</b>	<b>Cat</b>	<b>Deer</b>	<b>Dog</b>	<b>Frog</b>	<b>Horse</b>	<b>Ship</b>	<b>Truck</b>
<b>Plane</b>	65.40	4.10	2.70	2.20	2.70	0.30	1.00	1.30	12.20	8.10
<b>Car</b>	1.40	79.10	0.20	0.40	0.50	0.10	0.60	0.10	2.40	15.20
<b>Bird</b>	9.80	2.20	37.30	11.20	17.30	5.20	5.00	4.50	4.30	3.20
<b>Cat</b>	2.90	1.40	5.00	52.40	10.10	7.90	6.70	5.40	2.80	5.40
<b>Deer</b>	2.50	0.80	5.80	7.60	61.60	2.20	5.60	11.00	1.60	1.30
<b>Dog</b>	1.70	0.80	5.10	31.20	8.90	35.50	2.40	8.80	2.70	2.90
<b>Frog</b>	0.60	1.70	4.00	8.50	10.20	0.40	68.20	1.60	1.50	3.30
<b>Horse</b>	1.40	0.60	2.00	7.10	8.10	3.20	1.00	70.00	0.60	6.00
<b>Ship</b>	4.90	5.40	0.20	0.90	0.70	0.00	0.50	0.80	81.90	4.70
<b>Truck</b>	2.30	12.30	0.40	1.60	0.70	0.00	0.80	1.10	3.10	77.70

### 3. BMENet with stride

```
In [3]: # this code is mainly borrowed from DLstudio

dls = DLStudio(
    dataroot = "/home/kak/ImageDatasets/CIFAR-10/",
    dataroot = "./../data/CIFAR-10/",
    image_size = [32,32],
    path_saved_model = "./saved_model",
    momentum = 0.9,
    learning_rate = 1e-4,
    epochs = 6,
    batch_size = 4,
    classes = ('plane','car','bird','cat','deer','dog','frog','horse',''),
    use_gpu = True,
)

bme_net = dls.BMENet(dls, skip_connections=True, depth=8) ## if you want to
bme_net.load_cifar_10_dataset()

## display network properties
number_of_learnable_params = sum(p.numel() for p in bme_net.parameters() if p.requires_grad)
print("\n\nThe number of learnable parameters in the model: %d" % number_of_learnable_params)

## training and testing
bme_net.run_code_for_training(bme_net, display_images=False)
bme_net.run_code_for_testing(bme_net, display_images=False)
```

```
ter=3000  elapsed_time=  93 secs]  Loss: 1.641

[epoch:1/6  iter=4000  elapsed_time= 122 secs]  Ground Truth:      horse
plane      ship       dog
[epoch:1/6  iter=4000  elapsed_time= 122 secs]  Predicted Labels:   ship
plane      ship       frog
[epoch:1/6  iter=4000  elapsed_time= 122 secs]  Loss: 1.556

[epoch:1/6  iter=5000  elapsed_time= 151 secs]  Ground Truth:      plane
bird       plane      car
[epoch:1/6  iter=5000  elapsed_time= 151 secs]  Predicted Labels:   plane
frog       dog        car
[epoch:1/6  iter=5000  elapsed_time= 151 secs]  Loss: 1.478

[epoch:1/6  iter=6000  elapsed_time= 181 secs]  Ground Truth:      plane
ship       deer       cat
[epoch:1/6  iter=6000  elapsed_time= 181 secs]  Predicted Labels:   bird
ship       dog        cat
[epoch:1/6  iter=6000  elapsed_time= 181 secs]  Loss: 1.384

[epoch:1/6  iter=7000  elapsed_time= 210 secs]  Ground Truth:      ship
horse      deer       cat
[epoch:1/6  iter=7000  elapsed_time= 210 secs]  Predicted Labels:   car
horse      bird       dog
[epoch:1/6  iter=7000  elapsed_time= 210 secs]  Loss: 1.332

[epoch:1/6  iter=8000  elapsed_time= 239 secs]  Ground Truth:      horse
plane      frog       bird
[epoch:1/6  iter=8000  elapsed_time= 239 secs]  Predicted Labels:   horse
plane      frog       plane
[epoch:1/6  iter=8000  elapsed_time= 239 secs]  Loss: 1.234

[epoch:1/6  iter=9000  elapsed_time= 268 secs]  Ground Truth:      dog
plane      deer       cat
[epoch:1/6  iter=9000  elapsed_time= 268 secs]  Predicted Labels:   dog
plane      ship       plane
[epoch:1/6  iter=9000  elapsed_time= 268 secs]  Loss: 1.208

[epoch:1/6  iter=10000  elapsed_time= 298 secs]  Ground Truth:     truck
horse      dog        horse
[epoch:1/6  iter=10000  elapsed_time= 298 secs]  Predicted Labels:   truck
truck      dog        frog
[epoch:1/6  iter=10000  elapsed_time= 298 secs]  Loss: 1.151

[epoch:1/6  iter=11000  elapsed_time= 328 secs]  Ground Truth:     frog
dog        dog        car
[epoch:1/6  iter=11000  elapsed_time= 328 secs]  Predicted Labels:   frog
frog      dog        car
```

```
[epoch:1/6  iter=11000  elapsed_time= 328 secs]  Loss: 1.153

[epoch:1/6  iter=12000  elapsed_time= 357 secs]  Ground Truth:      cat
frog      dog      dog
[epoch:1/6  iter=12000  elapsed_time= 357 secs]  Predicted Labels:   cat
frog      cat      horse
[epoch:1/6  iter=12000  elapsed_time= 357 secs]  Loss: 1.069


[epoch:2/6  iter=1000  elapsed_time= 406 secs]  Ground Truth:      car
horse     dog      ship
[epoch:2/6  iter=1000  elapsed_time= 406 secs]  Predicted Labels:   car
horse     dog      ship
[epoch:2/6  iter=1000  elapsed_time= 406 secs]  Loss: 0.895


[epoch:2/6  iter=2000  elapsed_time= 436 secs]  Ground Truth:      cat
dog      dog      frog
[epoch:2/6  iter=2000  elapsed_time= 436 secs]  Predicted Labels:   deer
cat      cat      car
[epoch:2/6  iter=2000  elapsed_time= 436 secs]  Loss: 0.883


[epoch:2/6  iter=3000  elapsed_time= 466 secs]  Ground Truth:      truck
truck    car      deer
[epoch:2/6  iter=3000  elapsed_time= 466 secs]  Predicted Labels:   truck
truck    car      deer
[epoch:2/6  iter=3000  elapsed_time= 466 secs]  Loss: 0.836


[epoch:2/6  iter=4000  elapsed_time= 497 secs]  Ground Truth:      deer
truck    plane    car
[epoch:2/6  iter=4000  elapsed_time= 497 secs]  Predicted Labels:   horse
truck    plane    car
[epoch:2/6  iter=4000  elapsed_time= 497 secs]  Loss: 0.835


[epoch:2/6  iter=5000  elapsed_time= 527 secs]  Ground Truth:      truck
plane    truck    car
[epoch:2/6  iter=5000  elapsed_time= 527 secs]  Predicted Labels:   truck
plane    bird     car
[epoch:2/6  iter=5000  elapsed_time= 527 secs]  Loss: 0.797


[epoch:2/6  iter=6000  elapsed_time= 557 secs]  Ground Truth:      car
plane    deer     horse
[epoch:2/6  iter=6000  elapsed_time= 557 secs]  Predicted Labels:   car
plane    deer     horse
[epoch:2/6  iter=6000  elapsed_time= 557 secs]  Loss: 0.842


[epoch:2/6  iter=7000  elapsed_time= 586 secs]  Ground Truth:      cat
deer      cat     cat
[epoch:2/6  iter=7000  elapsed_time= 586 secs]  Predicted Labels:   frog
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```
deer      deer      cat
[epoch:2/6  iter=7000  elapsed_time= 586 secs]  Loss: 0.794

[epoch:2/6  iter=8000  elapsed_time= 616 secs]  Ground Truth:      truck
dog      ship      frog
[epoch:2/6  iter=8000  elapsed_time= 616 secs]  Predicted Labels:  truck
dog      ship      frog
[epoch:2/6  iter=8000  elapsed_time= 616 secs]  Loss: 0.774

[epoch:2/6  iter=9000  elapsed_time= 646 secs]  Ground Truth:      car
horse    car      frog
[epoch:2/6  iter=9000  elapsed_time= 646 secs]  Predicted Labels:  truck
horse    car      plane
[epoch:2/6  iter=9000  elapsed_time= 646 secs]  Loss: 0.801

[epoch:2/6  iter=10000 elapsed_time= 675 secs]  Ground Truth:      dog
bird     frog      truck
[epoch:2/6  iter=10000 elapsed_time= 675 secs]  Predicted Labels:  cat
cat     frog      truck
[epoch:2/6  iter=10000 elapsed_time= 675 secs]  Loss: 0.760

[epoch:2/6  iter=11000 elapsed_time= 705 secs]  Ground Truth:      horse
frog     dog      car
[epoch:2/6  iter=11000 elapsed_time= 705 secs]  Predicted Labels:  horse
frog     dog      car
[epoch:2/6  iter=11000 elapsed_time= 705 secs]  Loss: 0.732

[epoch:2/6  iter=12000 elapsed_time= 734 secs]  Ground Truth:      deer
truck    cat      horse
[epoch:2/6  iter=12000 elapsed_time= 734 secs]  Predicted Labels:  cat
horse    horse     horse
[epoch:2/6  iter=12000 elapsed_time= 734 secs]  Loss: 0.703

[epoch:3/6  iter=1000  elapsed_time= 781 secs]  Ground Truth:      truck
bird     truck     cat
[epoch:3/6  iter=1000  elapsed_time= 781 secs]  Predicted Labels:  truck
bird     truck     cat
[epoch:3/6  iter=1000  elapsed_time= 781 secs]  Loss: 0.462

[epoch:3/6  iter=2000  elapsed_time= 811 secs]  Ground Truth:      ship
plane    dog      bird
[epoch:3/6  iter=2000  elapsed_time= 811 secs]  Predicted Labels:  ship
plane    dog      bird
[epoch:3/6  iter=2000  elapsed_time= 811 secs]  Loss: 0.471

[epoch:3/6  iter=3000  elapsed_time= 840 secs]  Ground Truth:      ship
ship     ship     plane
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[epoch:3/6  iter=3000  elapsed_time=  840 secs]  Predicted Labels:      ship
ship      ship      plane
[epoch:3/6  iter=3000  elapsed_time=  840 secs]  Loss: 0.459

[epoch:3/6  iter=4000  elapsed_time=  869 secs]  Ground Truth:      deer
ship      frog      bird
[epoch:3/6  iter=4000  elapsed_time=  869 secs]  Predicted Labels:      deer
ship      frog      bird
[epoch:3/6  iter=4000  elapsed_time=  869 secs]  Loss: 0.465

[epoch:3/6  iter=5000  elapsed_time=  899 secs]  Ground Truth:      cat
horse     frog      dog
[epoch:3/6  iter=5000  elapsed_time=  899 secs]  Predicted Labels:      cat
horse     frog      dog
[epoch:3/6  iter=5000  elapsed_time=  899 secs]  Loss: 0.463

[epoch:3/6  iter=6000  elapsed_time=  929 secs]  Ground Truth:      horse
dog       horse     horse
[epoch:3/6  iter=6000  elapsed_time=  929 secs]  Predicted Labels:      deer
dog       dog       horse
[epoch:3/6  iter=6000  elapsed_time=  929 secs]  Loss: 0.474

[epoch:3/6  iter=7000  elapsed_time=  960 secs]  Ground Truth:      frog
horse     deer      bird
[epoch:3/6  iter=7000  elapsed_time=  960 secs]  Predicted Labels:      frog
horse     horse     bird
[epoch:3/6  iter=7000  elapsed_time=  960 secs]  Loss: 0.485

[epoch:3/6  iter=8000  elapsed_time=  990 secs]  Ground Truth:      plane
car       horse     deer
[epoch:3/6  iter=8000  elapsed_time=  990 secs]  Predicted Labels:      plane
car       horse     deer
[epoch:3/6  iter=8000  elapsed_time=  990 secs]  Loss: 0.492

[epoch:3/6  iter=9000  elapsed_time= 1021 secs]  Ground Truth:      ship
horse     dog       plane
[epoch:3/6  iter=9000  elapsed_time= 1021 secs]  Predicted Labels:      ship
horse     plane     plane
[epoch:3/6  iter=9000  elapsed_time= 1021 secs]  Loss: 0.476

[epoch:3/6  iter=10000  elapsed_time= 1052 secs]  Ground Truth:      frog
horse    dog      dog
[epoch:3/6  iter=10000  elapsed_time= 1052 secs]  Predicted Labels:      frog
horse    dog      dog
[epoch:3/6  iter=10000  elapsed_time= 1052 secs]  Loss: 0.499

[epoch:3/6  iter=11000  elapsed_time= 1083 secs]  Ground Truth:      cat
car      ship      cat
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[epoch:3/6  iter=11000  elapsed_time= 1083 secs]  Predicted Labels:      cat
car          ship        cat
[epoch:3/6  iter=11000  elapsed_time= 1083 secs]  Loss: 0.485

[epoch:3/6  iter=12000  elapsed_time= 1113 secs]  Ground Truth:      dog
car          ship        dog
[epoch:3/6  iter=12000  elapsed_time= 1113 secs]  Predicted Labels:      dog
car          ship        dog
[epoch:3/6  iter=12000  elapsed_time= 1113 secs]  Loss: 0.498

[epoch:4/6  iter=1000  elapsed_time= 1162 secs]  Ground Truth:      bird
frog         bird        deer
[epoch:4/6  iter=1000  elapsed_time= 1162 secs]  Predicted Labels:      bird
frog         horse       deer
[epoch:4/6  iter=1000  elapsed_time= 1162 secs]  Loss: 0.221

[epoch:4/6  iter=2000  elapsed_time= 1192 secs]  Ground Truth:      bird
frog         dog         bird
[epoch:4/6  iter=2000  elapsed_time= 1192 secs]  Predicted Labels:      bird
frog         dog         bird
[epoch:4/6  iter=2000  elapsed_time= 1192 secs]  Loss: 0.200

[epoch:4/6  iter=3000  elapsed_time= 1222 secs]  Ground Truth:      cat
truck        car         bird
[epoch:4/6  iter=3000  elapsed_time= 1222 secs]  Predicted Labels:      cat
truck        car         bird
[epoch:4/6  iter=3000  elapsed_time= 1222 secs]  Loss: 0.219

[epoch:4/6  iter=4000  elapsed_time= 1253 secs]  Ground Truth:      cat
cat          ship        ship
[epoch:4/6  iter=4000  elapsed_time= 1253 secs]  Predicted Labels:      cat
cat          ship        ship
[epoch:4/6  iter=4000  elapsed_time= 1253 secs]  Loss: 0.204

[epoch:4/6  iter=5000  elapsed_time= 1283 secs]  Ground Truth:      cat
plane        car         frog
[epoch:4/6  iter=5000  elapsed_time= 1283 secs]  Predicted Labels:      cat
plane        car         frog
[epoch:4/6  iter=5000  elapsed_time= 1283 secs]  Loss: 0.213

[epoch:4/6  iter=6000  elapsed_time= 1313 secs]  Ground Truth:      horse
bird         ship        ship
[epoch:4/6  iter=6000  elapsed_time= 1313 secs]  Predicted Labels:      horse
bird         ship        ship
[epoch:4/6  iter=6000  elapsed_time= 1313 secs]  Loss: 0.244

[epoch:4/6  iter=7000  elapsed_time= 1343 secs]  Ground Truth:      plane
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```
bird      plane      bird
[epoch:4/6  iter=7000  elapsed_time= 1343 secs]  Predicted Labels:      plane
bird      plane      bird
[epoch:4/6  iter=7000  elapsed_time= 1343 secs]  Loss: 0.228

[epoch:4/6  iter=8000  elapsed_time= 1373 secs]  Ground Truth:          bird
car      plane      ship
[epoch:4/6  iter=8000  elapsed_time= 1373 secs]  Predicted Labels:      bird
car      plane      ship
[epoch:4/6  iter=8000  elapsed_time= 1373 secs]  Loss: 0.223

[epoch:4/6  iter=9000  elapsed_time= 1403 secs]  Ground Truth:          car
horse    deer      frog
[epoch:4/6  iter=9000  elapsed_time= 1403 secs]  Predicted Labels:      car
horse    deer      frog
[epoch:4/6  iter=9000  elapsed_time= 1403 secs]  Loss: 0.217

[epoch:4/6  iter=10000  elapsed_time= 1434 secs]  Ground Truth:         dog
deer     bird      dog
[epoch:4/6  iter=10000  elapsed_time= 1434 secs]  Predicted Labels:      dog
deer     bird      dog
[epoch:4/6  iter=10000  elapsed_time= 1434 secs]  Loss: 0.244

[epoch:4/6  iter=11000  elapsed_time= 1463 secs]  Ground Truth:         horse
cat      frog      deer
[epoch:4/6  iter=11000  elapsed_time= 1463 secs]  Predicted Labels:      cat
cat      frog      deer
[epoch:4/6  iter=11000  elapsed_time= 1463 secs]  Loss: 0.247

[epoch:4/6  iter=12000  elapsed_time= 1494 secs]  Ground Truth:         horse
cat      deer      ship
[epoch:4/6  iter=12000  elapsed_time= 1494 secs]  Predicted Labels:      horse
cat      deer      ship
[epoch:4/6  iter=12000  elapsed_time= 1494 secs]  Loss: 0.243

[epoch:5/6  iter=1000  elapsed_time= 1542 secs]  Ground Truth:         deer
bird     frog      dog
[epoch:5/6  iter=1000  elapsed_time= 1542 secs]  Predicted Labels:      deer
bird     frog      dog
[epoch:5/6  iter=1000  elapsed_time= 1542 secs]  Loss: 0.078

[epoch:5/6  iter=2000  elapsed_time= 1571 secs]  Ground Truth:         deer
horse    frog      ship
[epoch:5/6  iter=2000  elapsed_time= 1571 secs]  Predicted Labels:      deer
horse    frog      ship
[epoch:5/6  iter=2000  elapsed_time= 1571 secs]  Loss: 0.085
```

```
[epoch:5/6  iter=3000  elapsed_time= 1600 secs]  Ground Truth:      frog
plane      bird      ship
[epoch:5/6  iter=3000  elapsed_time= 1600 secs]  Predicted Labels:   frog
plane      bird      ship
[epoch:5/6  iter=3000  elapsed_time= 1600 secs]  Loss: 0.080

[epoch:5/6  iter=4000  elapsed_time= 1629 secs]  Ground Truth:      horse
dog        frog      deer
[epoch:5/6  iter=4000  elapsed_time= 1629 secs]  Predicted Labels:   horse
dog        frog      deer
[epoch:5/6  iter=4000  elapsed_time= 1629 secs]  Loss: 0.077

[epoch:5/6  iter=5000  elapsed_time= 1659 secs]  Ground Truth:      frog
ship       dog      ship
[epoch:5/6  iter=5000  elapsed_time= 1659 secs]  Predicted Labels:   frog
ship       dog      ship
[epoch:5/6  iter=5000  elapsed_time= 1659 secs]  Loss: 0.082

[epoch:5/6  iter=6000  elapsed_time= 1689 secs]  Ground Truth:      bird
truck      dog      truck
[epoch:5/6  iter=6000  elapsed_time= 1689 secs]  Predicted Labels:   bird
truck      dog      truck
[epoch:5/6  iter=6000  elapsed_time= 1689 secs]  Loss: 0.085

[epoch:5/6  iter=7000  elapsed_time= 1718 secs]  Ground Truth:      frog
frog       horse     truck
[epoch:5/6  iter=7000  elapsed_time= 1718 secs]  Predicted Labels:   frog
frog       horse     truck
[epoch:5/6  iter=7000  elapsed_time= 1718 secs]  Loss: 0.081

[epoch:5/6  iter=8000  elapsed_time= 1748 secs]  Ground Truth:      ship
truck      ship     bird
[epoch:5/6  iter=8000  elapsed_time= 1748 secs]  Predicted Labels:   ship
truck      ship     bird
[epoch:5/6  iter=8000  elapsed_time= 1748 secs]  Loss: 0.087

[epoch:5/6  iter=9000  elapsed_time= 1778 secs]  Ground Truth:      frog
plane      plane    car
[epoch:5/6  iter=9000  elapsed_time= 1778 secs]  Predicted Labels:   frog
plane      plane    car
[epoch:5/6  iter=9000  elapsed_time= 1778 secs]  Loss: 0.084

[epoch:5/6  iter=10000 elapsed_time= 1807 secs]  Ground Truth:      bird
cat        plane    frog
[epoch:5/6  iter=10000 elapsed_time= 1807 secs]  Predicted Labels:   bird
cat        plane    frog
[epoch:5/6  iter=10000 elapsed_time= 1807 secs]  Loss: 0.081
```

```
[epoch:5/6  iter=11000  elapsed_time= 1836 secs]  Ground Truth:          truck
deer      truck      frog
[epoch:5/6  iter=11000  elapsed_time= 1836 secs]  Predicted Labels:       truck
deer      truck      frog
[epoch:5/6  iter=11000  elapsed_time= 1836 secs]  Loss: 0.088

[epoch:5/6  iter=12000  elapsed_time= 1866 secs]  Ground Truth:          dog
truck     plane      frog
[epoch:5/6  iter=12000  elapsed_time= 1866 secs]  Predicted Labels:       dog
truck     plane      frog
[epoch:5/6  iter=12000  elapsed_time= 1866 secs]  Loss: 0.091

[epoch:6/6  iter=1000  elapsed_time= 1912 secs]  Ground Truth:          cat
frog      car        horse
[epoch:6/6  iter=1000  elapsed_time= 1912 secs]  Predicted Labels:       cat
frog      car        horse
[epoch:6/6  iter=1000  elapsed_time= 1912 secs]  Loss: 0.033

[epoch:6/6  iter=2000  elapsed_time= 1941 secs]  Ground Truth:          truck
ship      deer      plane
[epoch:6/6  iter=2000  elapsed_time= 1941 secs]  Predicted Labels:       truck
ship      deer      plane
[epoch:6/6  iter=2000  elapsed_time= 1941 secs]  Loss: 0.031

[epoch:6/6  iter=3000  elapsed_time= 1970 secs]  Ground Truth:          truck
cat      truck      truck
[epoch:6/6  iter=3000  elapsed_time= 1970 secs]  Predicted Labels:       truck
cat      truck      truck
[epoch:6/6  iter=3000  elapsed_time= 1970 secs]  Loss: 0.029

[epoch:6/6  iter=4000  elapsed_time= 2001 secs]  Ground Truth:          plane
deer      ship      deer
[epoch:6/6  iter=4000  elapsed_time= 2001 secs]  Predicted Labels:       plane
deer      ship      deer
[epoch:6/6  iter=4000  elapsed_time= 2001 secs]  Loss: 0.030

[epoch:6/6  iter=5000  elapsed_time= 2030 secs]  Ground Truth:          horse
cat      horse      frog
[epoch:6/6  iter=5000  elapsed_time= 2030 secs]  Predicted Labels:       horse
cat      horse      frog
[epoch:6/6  iter=5000  elapsed_time= 2030 secs]  Loss: 0.029

[epoch:6/6  iter=6000  elapsed_time= 2061 secs]  Ground Truth:          bird
cat      plane      dog
[epoch:6/6  iter=6000  elapsed_time= 2061 secs]  Predicted Labels:       bird
cat      ship      dog
[epoch:6/6  iter=6000  elapsed_time= 2061 secs]  Loss: 0.029
```

```
[epoch:6/6  iter=7000  elapsed_time= 2090 secs]  Ground Truth:      frog
plane      car      truck
[epoch:6/6  iter=7000  elapsed_time= 2090 secs]  Predicted Labels:   frog
plane      car      truck
[epoch:6/6  iter=7000  elapsed_time= 2090 secs]  Loss: 0.031

[epoch:6/6  iter=8000  elapsed_time= 2118 secs]  Ground Truth:      bird
horse     horse     dog
[epoch:6/6  iter=8000  elapsed_time= 2118 secs]  Predicted Labels:   bird
horse     horse     dog
[epoch:6/6  iter=8000  elapsed_time= 2118 secs]  Loss: 0.028

[epoch:6/6  iter=9000  elapsed_time= 2148 secs]  Ground Truth:      deer
dog       plane     horse
[epoch:6/6  iter=9000  elapsed_time= 2148 secs]  Predicted Labels:   deer
dog       plane     horse
[epoch:6/6  iter=9000  elapsed_time= 2148 secs]  Loss: 0.030

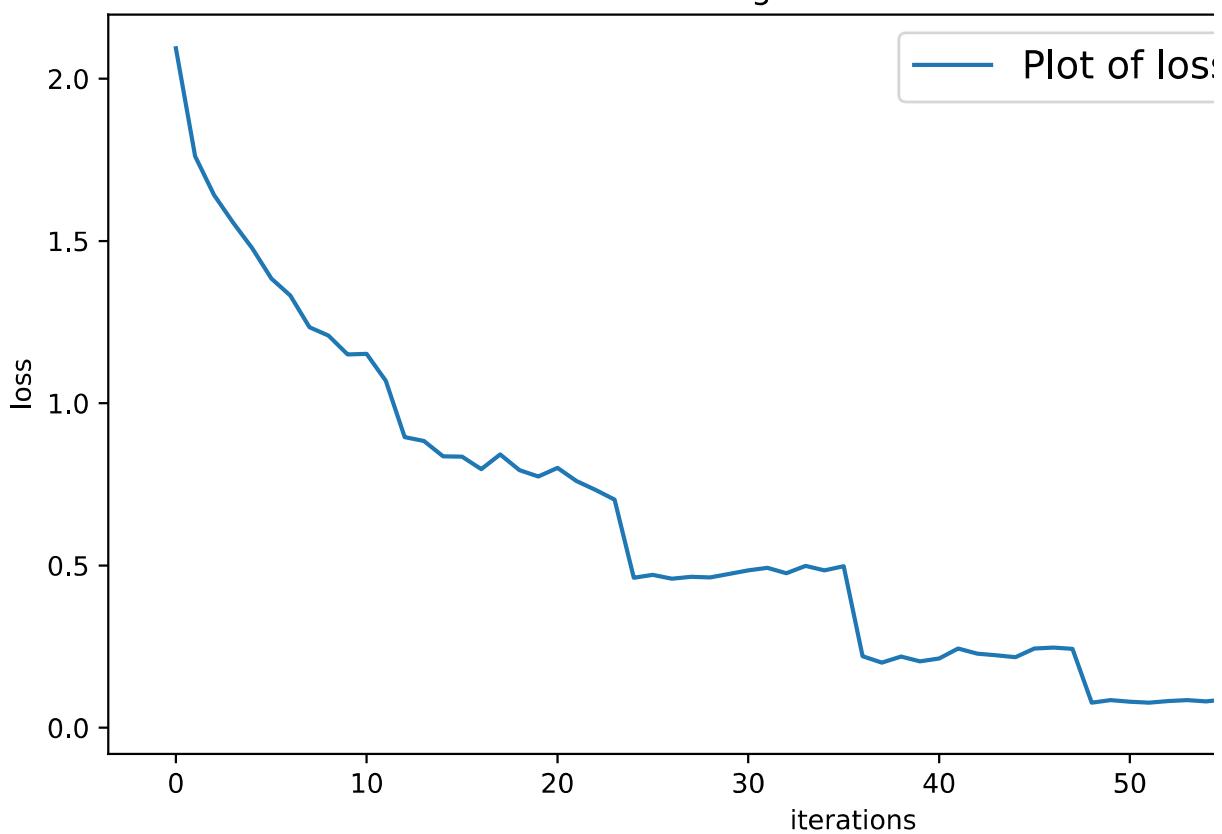
[epoch:6/6  iter=10000 elapsed_time= 2177 secs]  Ground Truth:      plane
frog      dog       ship
[epoch:6/6  iter=10000 elapsed_time= 2177 secs]  Predicted Labels:   plane
frog      dog       ship
[epoch:6/6  iter=10000 elapsed_time= 2177 secs]  Loss: 0.023

[epoch:6/6  iter=11000 elapsed_time= 2206 secs]  Ground Truth:      horse
plane     car       bird
[epoch:6/6  iter=11000 elapsed_time= 2206 secs]  Predicted Labels:   horse
plane     car       bird
[epoch:6/6  iter=11000 elapsed_time= 2206 secs]  Loss: 0.030

[epoch:6/6  iter=12000 elapsed_time= 2236 secs]  Ground Truth:      frog
deer      truck    truck
[epoch:6/6  iter=12000 elapsed_time= 2236 secs]  Predicted Labels:   frog
deer      truck    truck
[epoch:6/6  iter=12000 elapsed_time= 2236 secs]  Loss: 0.026
```

Finished Training

Labeling Loss vs. Iterations



```
/home/chen4126/ece60146/HW6/../../DLStudio-2.5.1/DLStudio/DLStudio.py:2964: FutureWarning: You are using `torch.load` with `weights_only=False` (the current default value), which uses the default pickle module implicitly. It is possible to construct malicious pickle data which will execute arbitrary code during unpickling (See https://github.com/pytorch/pytorch/blob/main/SECURITY.md#untrusted-models for more details). In a future release, the default value for `weights_only` will be flipped to `True`. This limits the functions that could be executed during unpickling. Arbitrary objects will no longer be allowed to be loaded via this mode unless they are explicitly allowed by the user via `torch.serialization.add_safe_globals`. We recommend you start setting `weights_only=True` for any use case where you don't have full control of the loaded file. Please open an issue on GitHub for any issues related to this experimental feature.
```

```
    net.load_state_dict(torch.load(self.path_saved_model))
```

```
[i=1000:] Ground Truth:      frog  bird  bird truck
[i=1000:] Predicted Labels: frog  deer  bird truck
```

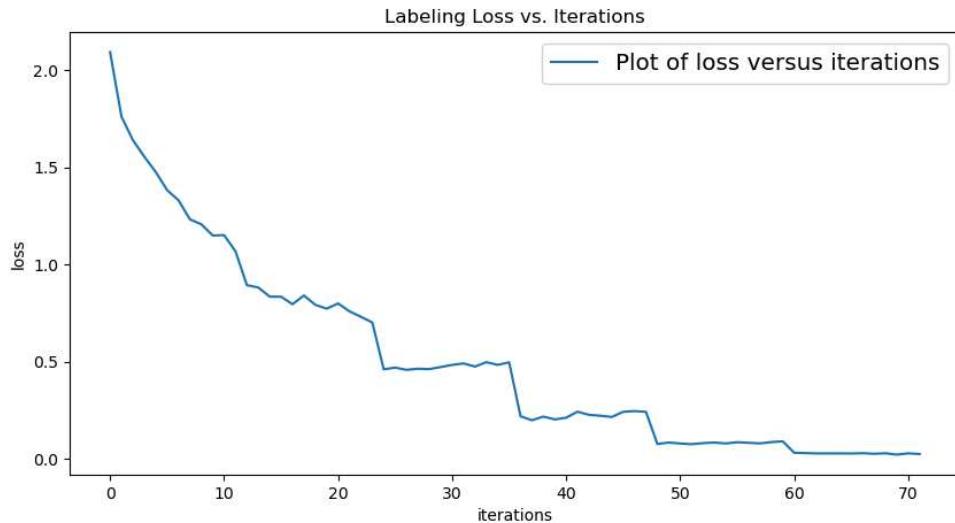
```
[i=2000:] Ground Truth:      horse   car   bird   frog
[i=2000:] Predicted Labels: horse   car   bird   frog
Prediction accuracy for plane : 78 %
Prediction accuracy for car : 93 %
Prediction accuracy for bird : 73 %
Prediction accuracy for cat : 67 %
Prediction accuracy for deer : 71 %
Prediction accuracy for dog : 68 %
Prediction accuracy for frog : 86 %
Prediction accuracy for horse : 82 %
Prediction accuracy for ship : 87 %
Prediction accuracy for truck : 84 %
```

```
Overall accuracy of the network on the 10000 test images: 79 %
```

```
Displaying the confusion matrix:
```

	plane	car	bird	cat	deer	dog	frog	horse	ship	truck
plane:	78.10	1.60	7.50	2.30	0.70	0.50	1.20	0.50	4.60	3.00
car:	0.30	93.20	0.10	0.60	0.00	0.10	1.00	0.10	1.40	3.20
bird:	3.60	0.60	73.90	6.20	4.40	4.20	3.90	1.30	1.00	0.90
cat:	1.00	0.70	6.10	67.60	3.10	12.00	5.40	2.30	1.20	0.60
deer:	1.30	0.60	8.10	6.80	71.30	2.30	4.80	4.40	0.40	0.00
dog:	0.90	0.20	4.00	18.70	1.50	68.20	2.20	3.50	0.40	0.40
frog:	0.40	0.60	3.70	5.70	1.20	1.00	86.70	0.10	0.40	0.20
horse:	1.40	0.10	2.60	5.20	2.80	3.60	0.60	82.60	0.20	0.90
ship:	3.50	3.40	1.30	1.10	0.30	0.50	0.70	0.10	87.50	1.60
truck:	2.00	7.30	0.80	2.10	0.30	0.40	0.60	0.80	1.50	84.20

### 3.1 Train loss curve



### 3.2 Confusion Matrix

	Plane	Car	Bird	Cat	Deer	Dog	Frog	Horse	Ship	Truck
Plane	78.10	1.60	7.50	2.30	0.70	0.50	1.20	0.50	4.60	3.00
Car	0.30	93.20	0.10	0.60	0.00	0.10	1.00	0.10	1.40	3.20
Bird	3.60	0.60	73.90	6.20	4.40	4.20	3.90	1.30	1.00	0.90
Cat	1.00	0.70	6.10	67.60	3.10	12.00	5.40	2.30	1.20	0.60
Deer	1.30	0.60	8.10	6.80	71.30	2.30	4.80	4.40	0.40	0.00
Dog	0.90	0.20	4.00	18.70	1.50	68.20	2.20	3.50	0.40	0.40
Frog	0.40	0.60	3.70	5.70	1.20	1.00	86.70	0.10	0.40	0.20
Horse	1.40	0.10	2.60	5.20	2.80	3.60	0.60	82.60	0.20	0.90
Ship	3.50	3.40	1.30	1.10	0.30	0.50	0.70	0.10	87.50	1.60
Truck	2.00	7.30	0.80	2.10	0.30	0.40	0.60	0.80	1.50	84.20

### 4. Table1: Overall accuracy of 2 models table

	Maxpool	Stride
Accuracy	62%	79%

### 5. Table2: Per class accuracy of 2 models (10x2 table)

	<b>Maxpool</b>	<b>Stride</b>
<b>Plane</b>	65	78
<b>Car</b>	79	93
<b>Bird</b>	37	73
<b>Cat</b>	52	67
<b>Deer</b>	61	71
<b>Dog</b>	35	68
<b>Frog</b>	68	86
<b>Horse</b>	70	82
<b>Ship</b>	81	87
<b>Truck</b>	77	84

## 6. Observations of Maxpool vs Stride

Conclusion first, the stride method significantly outperforms the maxpool method in this experiment.

The likely reason for this difference is that, while both approaches aim to reduce spatial dimensions, the stride method learns how to downsample the image while simultaneously extracting relevant features. In contrast, max pooling is a fixed operation that simply selects the most prominent value in a local region, without learning additional transformations that might preserve more discriminative information.

When using stride-based convolutions, the network jointly optimizes feature extraction and downsampling, ensuring that critical patterns are retained even as resolution decreases. This allows for a more adaptive reduction in spatial dimensions, where the network can learn to emphasize key edges, textures, or shapes based on training data.

On the other hand, MaxPooling is a static operation—it does not learn any parameters, and it simply selects the maximum value from a given region. While this can help with translation invariance, it may also result in information loss, as it discards non-maximum activations that could be useful in later layers. This rigid downsampling process might lead to a degradation in representational power, making it harder for the model to distinguish between similar classes effectively.

Given these findings, stride-based downsampling appears to be a more effective strategy for this particular architecture and dataset.

Furthermore, compared to HW5, where I used max pooling without shortcut connections, the current model shows significant improvement in performance. This suggests that both stride-based downsampling and shortcut connections contribute to better feature retention and overall model efficiency.

## 7. Skip Connections with MSCOCO

```
In [ ]: import torch.nn as nn
# skipblock is borrowed from DLstudio
class SkipBlock(nn.Module):
    """
    Class Path:  DLStudio  ->  BMEnet  ->  SkipBlock
    """

    def __init__(self, in_ch, out_ch, downsample=False, skip_connections=True):
        super().__init__()
        self.downsample = downsample
        self.skip_connections = skip_connections
        self.in_ch = in_ch
        self.out_ch = out_ch
        self.convo1 = nn.Conv2d(in_ch, in_ch, 3, stride=1, padding=1)
        self.convo2 = nn.Conv2d(in_ch, out_ch, 3, stride=1, padding=1)
        self.bn1 = nn.BatchNorm2d(in_ch)
        self.bn2 = nn.BatchNorm2d(out_ch)
        self.in2out = nn.Conv2d(in_ch, out_ch, 1)
        if downsample:
            ## Setting stride to 2 and kernel_size to 1 amounts to retaining every
            ## other pixel in the image --- which halves the size of the image:
            self.downsampler1 = nn.Conv2d(in_ch, in_ch, 1, stride=2)
            self.downsampler2 = nn.Conv2d(out_ch, out_ch, 1, stride=2)

    def forward(self, x):
        identity = x
        out = self.convo1(x)
        out = self.bn1(out)
        out = nn.functional.relu(out)
        out = self.convo2(out)
        out = self.bn2(out)
        out = nn.functional.relu(out)
        if self.downsample:
            identity = self.downsampler1(identity)
            out = self.downsampler2(out)
        if self.skip_connections:
            if (self.in_ch == self.out_ch) and (self.downsample is False):
                out = out + identity
            elif (self.in_ch != self.out_ch) and (self.downsample is False):
                identity = self.in2out(identity)
                out = out + identity
            elif (self.in_ch != self.out_ch) and (self.downsample is True):
                out = out + torch.cat((identity, identity), dim=1)
        return out
```

```

# ----- HW6 NET-----
# some of this code is borrowed from DLstudio, the code that i modify has a comment

class HW6Net(nn.Module): # nn.Module is the base class for all neural network model
    def __init__(self, num_class = 5, skip_connections=True):
        super().__init__()
        num_ds = 0

        self.depth = 6 # Since each SkipBlock uses two instances of nn.Conv2d, your
        self.initial_block = SkipBlock(3, 64, skip_connections=False) # this is ju

        # these for Loop block is mainly borrow from DLstudio, but I added a additi
        self.skip64_arr = nn.ModuleList()
        for i in range(self.depth):
            self.skip64_arr.append(SkipBlock(64, 64, skip_connections=skip_connecti
        self.skip64to128ds = SkipBlock(64, 128, downsample=True, skip_connections=s
        num_ds += 1

        self.skip128_arr = nn.ModuleList()
        for i in range(self.depth):
            self.skip128_arr.append(SkipBlock(128, 128, skip_connections=skip_conne
        self.skip128to256ds = SkipBlock(128, 256, downsample=True, skip_connections=
        num_ds += 1

        self.skip256_arr = nn.ModuleList()
        for i in range(self.depth):
            self.skip256_arr.append(SkipBlock(256, 256, skip_connections=skip_conne

        self.fc1 = nn.Linear( (32//(2 ** num_ds)) * (32//(2 ** num_ds)) *256,
        self.fc2 = nn.Linear(512, num_class) # reduce the size of fc layers

    def forward(self, x):

        x = self.initial_block(x) # initial block 3->64

        for skip64 in self.skip64_arr:
            x = skip64(x)
        x = self.skip64to128ds(x)
        for skip128 in self.skip128_arr:
            x = skip128(x)
        x = self.skip128to256ds(x)
        for skip256 in self.skip256_arr:
            x = skip256(x)

        x = x.view( x.shape[0], - 1 )
        x = nn.functional.relu(self.fc1(x))
        x = self.fc2(x)
        return x

```

## 7.1 5x3 images

```
In [19]: import matplotlib.pyplot as plt
import random

def visualize_dataset(dataset_type, classes, output_dir="output_datasets"):
    fig, axes = plt.subplots(5, 3, figsize=(15, 15)) # 5 rows x 3 columns grid
    fig.suptitle(f"Visualization of {dataset_type} dataset", fontsize=16)

    image_paths = []

    for category in classes:
        category_path = os.path.join(output_dir, dataset_type, 'train', category)
        if os.path.exists(category_path) and os.listdir(category_path):
            category_images = [os.path.join(category_path, img) for img in os.listdir(category_path)]
            random.shuffle(category_images)
            image_paths.extend(category_images[:3]) # Select 3 images per class

    image_paths = image_paths[:15] # Ensure only 15 images for the grid

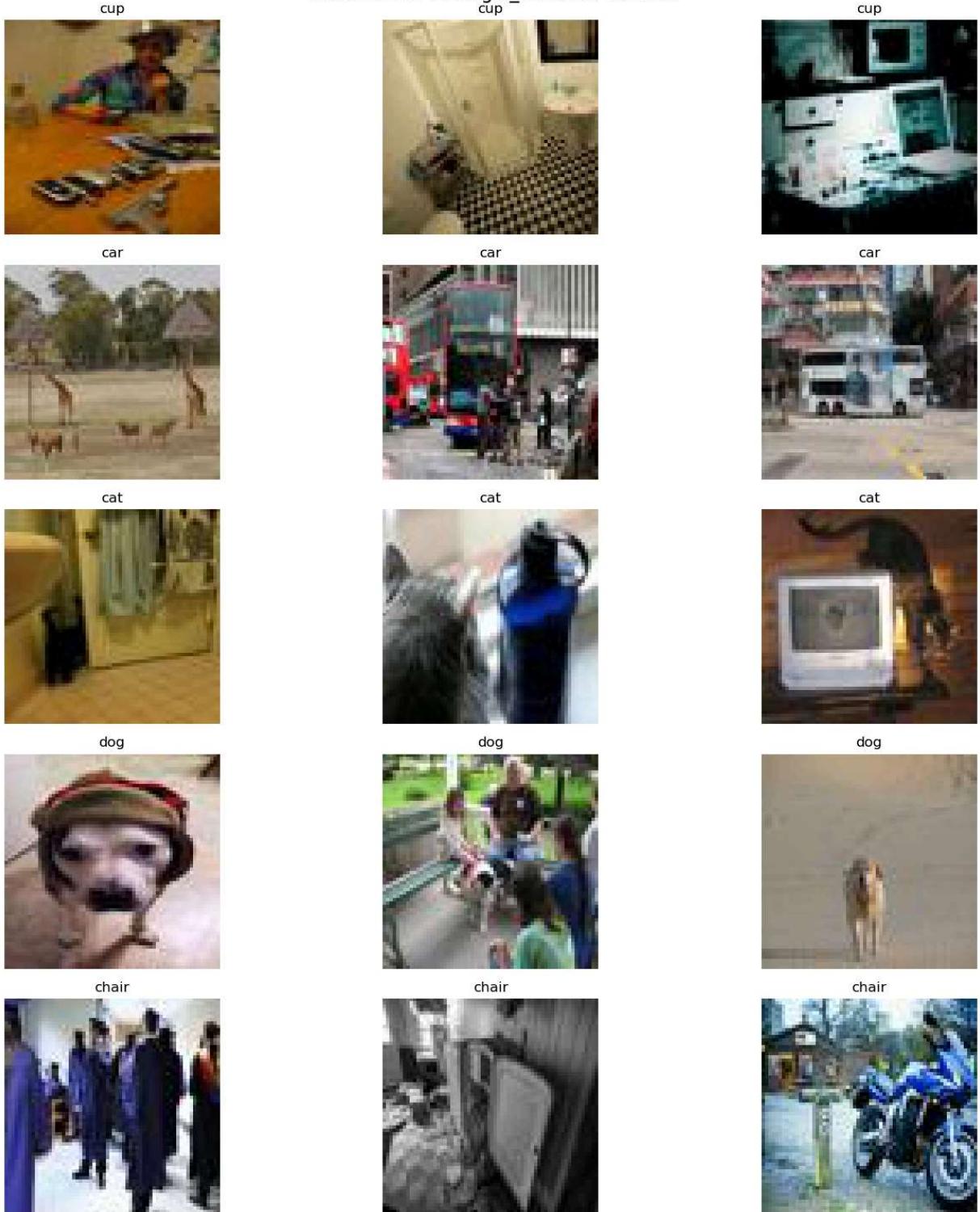
    for ax, img_path in zip(axes.ravel(), image_paths):
        img = Image.open(img_path)
        ax.imshow(img)
        ax.axis("off")
        ax.set_title(os.path.basename(os.path.dirname(img_path))) # Display category name

    plt.tight_layout()
    plt.show()

target_classes = ["cup", "car", "cat", "dog", "chair"]

visualize_dataset("single_instance", target_classes)
```

Visualization of single\_instance dataset



## 7.2 train loss curve

```
In [ ]: import torch
import torchvision
import torchvision.transforms as transforms
from torch.utils.data import DataLoader
import matplotlib.pyplot as plt
import numpy as np
import torch.nn.functional as F
```

```

transform_train = transforms.Compose([
    transforms.RandomHorizontalFlip(p=0.5),
    transforms.RandomRotation(degrees=5),
    transforms.Resize((32, 32)), # Resize images to 32x32 for consistency
    transforms.ToTensor(),
    transforms.Normalize(mean=[0.5, 0.5, 0.5], std=[0.5, 0.5, 0.5])
])

transform_val = transforms.Compose([
    transforms.Resize((32, 32)), # Resize images to 32x32 for consistency
    transforms.ToTensor(),
    transforms.Normalize(mean=[0.5, 0.5, 0.5], std=[0.5, 0.5, 0.5])
])

# Load training dataset
train_dataset = torchvision.datasets.ImageFolder(root="output_datasets/train", transform=transform_train)
train_loader = DataLoader(train_dataset, batch_size=32, shuffle=True)

# Load validation dataset
val_dataset = torchvision.datasets.ImageFolder(root="output_datasets/val", transform=transform_val)
val_loader = DataLoader(val_dataset, batch_size=32, shuffle=False)

# Check if GPU is available
device = torch.device("cuda" if torch.cuda.is_available() else "cpu")
print("Using device:", device)

model = HW6Net().to(device) # move model to gpu

criterion = nn.CrossEntropyLoss() # CrossEntropyLoss for multi-class classification

optimizer = torch.optim.Adam(model.parameters(), lr=0.001, weight_decay=1e-3) # use Adam optimizer

# -----train loop-----
# Modify train function to store training loss
def train_model(model, train_loader, criterion, optimizer, epochs):
    train_losses = [] # Store training losses

    for epoch in range(epochs):
        model.train()
        running_loss = 0.0
        correct, total = 0, 0

        for images, labels in train_loader:
            images, labels = images.to(device), labels.to(device) # move data to gpu

            optimizer.zero_grad() # zero the parameter gradients to prevent accumulation
            outputs = model(images) # forward pass
            loss = criterion(outputs, labels) # calculate loss

```

```

        loss.backward() # backward pass
        optimizer.step() # update weights

        running_loss += loss.item() # accumulate Loss
        _, predicted = torch.max(outputs, 1) # get the class label with the highest probability
        total += labels.size(0) # accumulate total number of labels
        correct += (predicted == labels).sum().item() # accumulate correct predictions

    train_losses.append(running_loss / len(train_loader)) # store average Loss

    train_acc = 100 * correct / total
    print(f"Epoch [{epoch+1}/{epochs}], Loss: {train_losses[-1]:.4f}, Train Acc: {train_acc:.2f}%")

return train_losses

```

train\_losses = train\_model(model, train\_loader, criterion, optimizer, epochs=20) # training loop

# -----end train Loop-----

# ----- train Loss curve -----

```

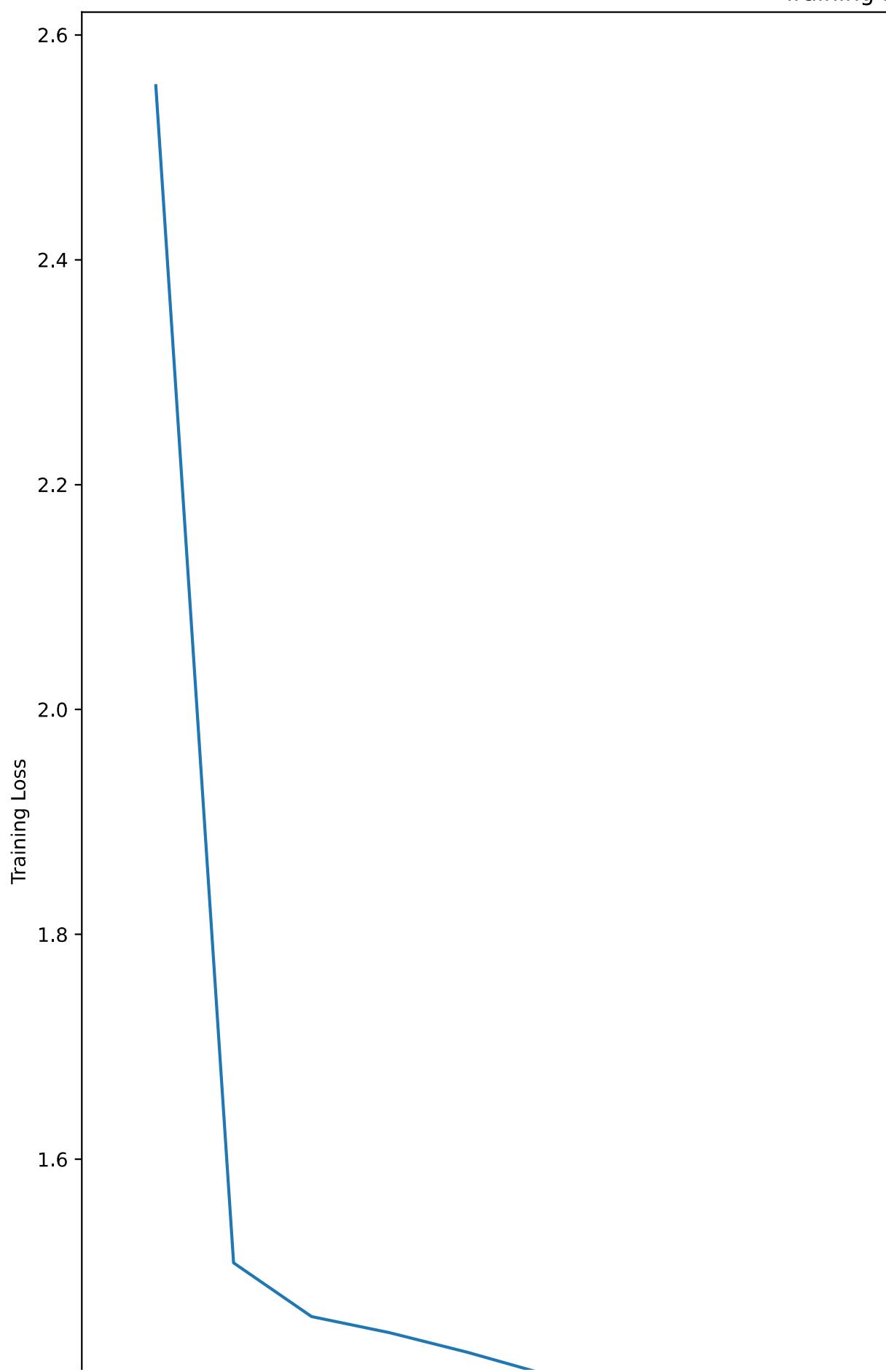
plt.figure(figsize=(15, 15))
plt.plot(range(1, len(train_losses) + 1), train_losses)
plt.xlabel("Epochs")
plt.ylabel("Training Loss")
plt.title("Training Loss Curve")
plt.show()

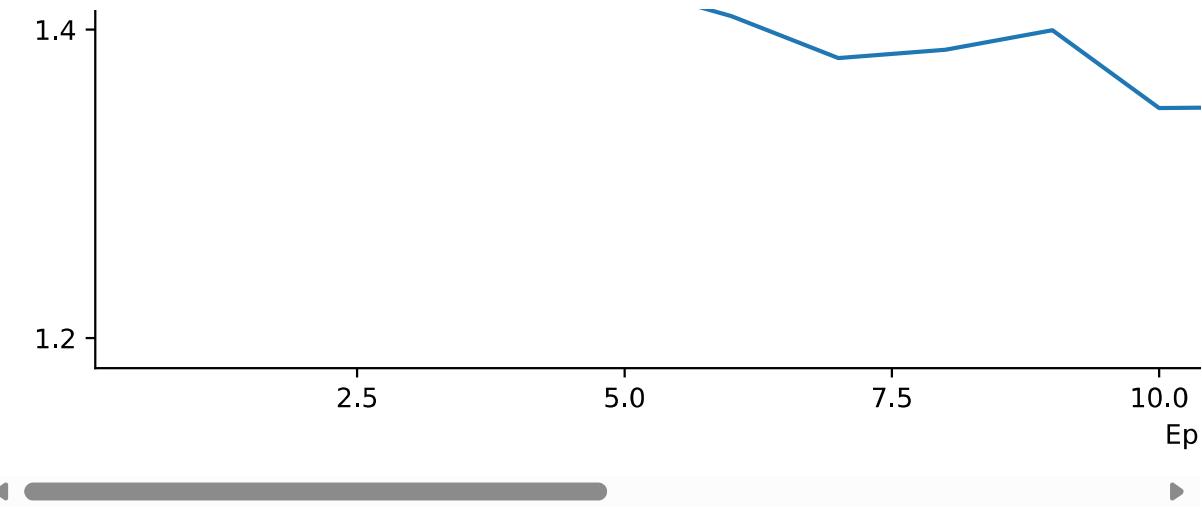
```

Using device: cuda

Epoch [1/20], Loss: 2.5548, Train Acc: 28.43%  
Epoch [2/20], Loss: 1.5079, Train Acc: 35.45%  
Epoch [3/20], Loss: 1.4601, Train Acc: 38.46%  
Epoch [4/20], Loss: 1.4457, Train Acc: 38.84%  
Epoch [5/20], Loss: 1.4284, Train Acc: 39.43%  
Epoch [6/20], Loss: 1.4088, Train Acc: 40.88%  
Epoch [7/20], Loss: 1.3817, Train Acc: 41.74%  
Epoch [8/20], Loss: 1.3870, Train Acc: 42.13%  
Epoch [9/20], Loss: 1.3996, Train Acc: 42.59%  
Epoch [10/20], Loss: 1.3493, Train Acc: 44.06%  
Epoch [11/20], Loss: 1.3498, Train Acc: 44.86%  
Epoch [12/20], Loss: 1.3263, Train Acc: 45.61%  
Epoch [13/20], Loss: 1.3254, Train Acc: 45.49%  
Epoch [14/20], Loss: 1.3353, Train Acc: 45.14%  
Epoch [15/20], Loss: 1.3232, Train Acc: 45.40%  
Epoch [16/20], Loss: 1.3035, Train Acc: 46.54%  
Epoch [17/20], Loss: 1.2842, Train Acc: 47.52%  
Epoch [18/20], Loss: 1.2644, Train Acc: 48.37%  
Epoch [19/20], Loss: 1.2573, Train Acc: 48.90%  
Epoch [20/20], Loss: 1.2459, Train Acc: 49.38%

# Training I





### 7.3 conf matrix 5x5

```
In [ ]: from sklearn.metrics import confusion_matrix, ConfusionMatrixDisplay,accuracy_score

def evaluate_model(model, val_loader):
    model.eval()
    all_preds = []
    all_labels = []

    with torch.no_grad(): # disable gradient calculation to save memory for validation
        for images, labels in val_loader:
            images, labels = images.to(device), labels.to(device)
            outputs = model(images)
            _, predicted = torch.max(outputs, 1)

            all_preds.extend(predicted.cpu().numpy())
            all_labels.extend(labels.cpu().numpy())

    return np.array(all_labels), np.array(all_preds)

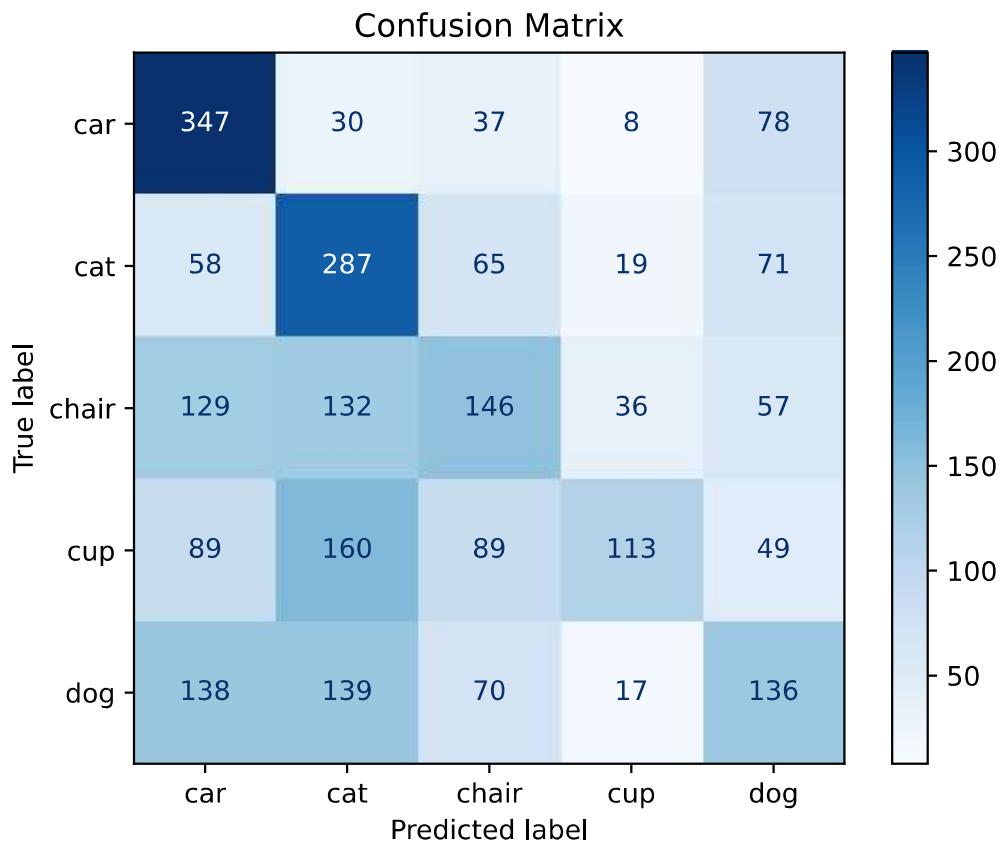
# Get true Labels and predictions
true_labels, predicted_labels = evaluate_model(model, val_loader)

# Compute overall accuracy by using sklearn
overall_acc = accuracy_score(true_labels, predicted_labels)
print(f"Overall Validation Accuracy: {overall_acc * 100:.2f}%")

# Compute confusion matrix
cm = confusion_matrix(true_labels, predicted_labels)
disp = ConfusionMatrixDisplay(confusion_matrix=cm, display_labels=train_dataset.classes)

# Plot confusion matrix
plt.figure(figsize=(6, 6))
disp.plot(cmap="Blues", values_format='d')
plt.title("Confusion Matrix")
plt.show()
```

Overall Validation Accuracy: 41.16%  
<Figure size 600x600 with 0 Axes>



## 7.4 overall accuracy

Overall Validation Accuracy: 41.16%

## 7.5 per class accuracy 5x1 table

Class	Accuracy(%)
Car	69
Cat	57
Chair	29
Cup	22
Dog	27

## 7.6 observations

Initially, I expected that using  $64 \times 64$  images would yield better performance. However, not only did training with  $64 \times 64$  inputs take significantly longer, but the results were also comparable to  $32 \times 32$  images.

One major issue I encountered was severe overfitting—the training accuracy reached 90%, while validation accuracy remained around 40%. I believe the primary reason for this is that

I'm using a 22-layer deep convolutional neural network and 2-layer fully connected layers on a relatively simple dataset, which likely causes the model to memorize training samples rather than generalize effectively.

To address this, I experimented with various hyperparameters, such as reducing the batch size, increasing the weight decay, and increasing learning rate. While these adjustments helped mitigate overfitting, I still struggled to push validation accuracy beyond 50%. (41%)

Since the architecture closely resembles the one used for CIFAR-10 (BMENet), I believe the primary issue is not the model itself. Instead, the COCO dataset poses additional challenges due to its complexity and dense object compositions. A model better suited for object detection, such as YOLO, might yield improved performance. Further investigation is required to pinpoint the underlying factors affecting performance.

## Source Code

Most of the code is included in every sections above, this section will show the code of generating the COCO dataset.

```
In [ ]: # this code is borrow from HW4_spring2025.pdf, my code will be follow by a comment
from PIL import Image
import os
from pycocotools.coco import COCO

# Set COCO dataset paths
data_dir = os.getcwd()
# mac users
# ann_file = os.path.join(data_dir, "annotations/instances_train2014.json")
# image_dir = os.path.join(data_dir, "train2014/train2014")

# windows users
ann_file = os.path.join(data_dir, r"annotations\instances_train2014.json")
image_dir = os.path.join(data_dir, r"train2014\train2014")

output_dir = "output_datasets"

# Load COCO dataset
coco = COCO(ann_file)

# Ensure output directories exist
os.makedirs(output_dir, exist_ok=True)

def save_image(img_info, category_name, dataset_type, split):
    """Saves the extracted image into a structured output directory for training/validation
    img_path = os.path.join(image_dir, img_info['file_name'])
    save_dir = os.path.join(output_dir, dataset_type, split, category_name)
    os.makedirs(save_dir, exist_ok=True)

    # # Check if the file exists before opening
```

```

# if not os.path.exists(img_path):
#     print(f"Skipping {img_info['file_name']} - File not found.")
#     return

# Load and resize image
img = Image.open(img_path).resize((64, 64))
img.save(os.path.join(save_dir, img_info['file_name']))

def extract_images(cat_names, min_instances=1, max_instances=1, multiple_categories=False):
    """
    Extracts images based on object count conditions for single-instance or multi-instance.
    - min_instances: Minimum number of object instances required.
    - max_instances: Maximum number of object instances allowed.
    - multiple_categories: If True, selects images with multiple different object types.
    """
    cat_ids = coco.getCatIds(catNms=cat_names)
    img_ids = coco.getImgIds(catIds=cat_ids)
    # Counter for extracted images
    extracted = 0

    images_to_process = [] # List to store valid images
    target_classes = ["cup", "car", "cat", "dog", "chair"] # remember classes we are interested in
    current_category = cat_names[0] ## e.g. current_category: person
    other_categories = [cat for cat in target_classes if cat != current_category] # categories to ignore

    # Loop through the images
    for img_id in img_ids:
        img_info = coco.loadImgs(img_id)[0]
        # These are annotation IDs for objects detected in a specific image. (we are interested in the first one)
        ann_ids = coco.getAnnIds(imgIds=img_id, iscrowd=False)
        # anns includes bounding box, category ID, and segmentation, area, imageID.
        anns = coco.loadAnns(ann_ids)

        # Count objects per category
        obj_counts = {}

        obj_categories = set() # set to store object categories in the image. e.g.
        # max_area_category = None # variable to store the category with the maximum area
        # max_area = 0

        for ann in anns:

            # return object category name, like obj_category: umbrella, obj_category: chair
            obj_category = coco.loadCats(ann['category_id'])[0]['name']

            # obj count for each category, like obj_counts: {'umbrella': 1}, obj_counts: {'chair': 1}
            obj_counts[obj_category] = obj_counts.get(obj_category, 0) + 1

            obj_categories.add(obj_category) # keep track of all object categories

            # if ann['area'] > max_area: # Track category with largest area
            #     max_area = ann['area']

```

```

#           max_area_category = obj_category

# if max_area_category != current_category: # Skip images with Largest area
#     continue

if dataset_type in ["single_instance", "multi_instance_same"]:
    if any(other_cat in obj_categories for other_cat in other_categories):
        continue

if multiple_categories:
    # Ensure multiple object categories are present(modified)
    if len(obj_counts) >= 2 and current_category in obj_counts and any(other_images_to_process.append(img_info) # instead of saving the image, I extracted += 1
elif dataset_type == "multi_instance_same":
    # Ensure multiple instances of the same object category
    if cat_names[0] in obj_counts and obj_counts[cat_names[0]] >= min_instances:
        images_to_process.append(img_info) # instead of saving the image, I extracted += 1
else:
    # Ensure the number of instances falls within the desired range for single instance
    if all(obj in obj_counts for obj in cat_names) and min_instances <= obj_counts[cat_names[0]]:
        images_to_process.append(img_info) # instead of saving the image, I extracted += 1

# Limit to 500 images per dataset for testing
if extracted >= 2000:
    break

train_images = images_to_process[:1500] # Split the images into training and validation
val_images = images_to_process[1500:2000] # Split the images into training and validation

for img_info in train_images: # Save training and validation images
    save_image(img_info, cat_names[0], dataset_type, 'train')

for img_info in val_images: # Save training and validation images
    save_image(img_info, cat_names[0], dataset_type, 'val')

# Extract Single-instance Dataset
# not enough images for the following requirements
# extract_images(["cup"], min_instances=1, max_instances=1, dataset_type="single_instance")
# extract_images(["car"], min_instances=1, max_instances=1, dataset_type="single_instance")
# extract_images(["cat"], min_instances=1, max_instances=1, dataset_type="single_instance")
# extract_images(["dog"], min_instances=1, max_instances=1, dataset_type="single_instance")
# extract_images(["chair"], min_instances=1, max_instances=1, dataset_type="single_instance")

extract_images(["cup"], min_instances=1, dataset_type="single_instance")
extract_images(["car"], min_instances=1, dataset_type="single_instance")
extract_images(["cat"], min_instances=1, dataset_type="single_instance")
extract_images(["dog"], min_instances=1, dataset_type="single_instance")
extract_images(["chair"], min_instances=1, dataset_type="single_instance")

```