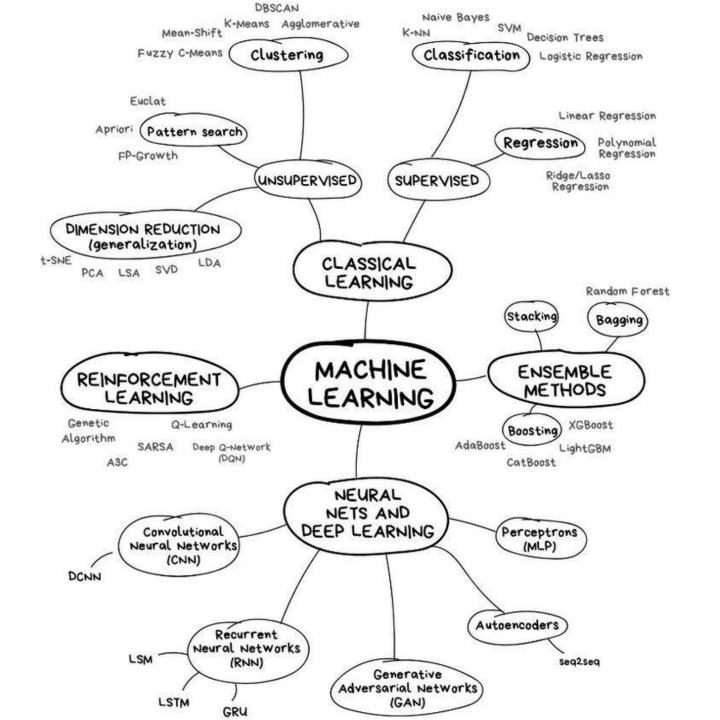
# **Shallow Neural Networks**



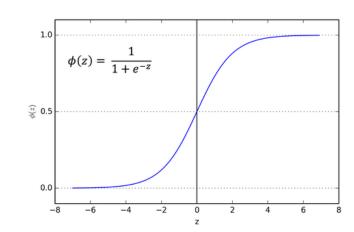
인공지능학과 Department of Artificial Intelligence

정 우 환 (whjung@hanyang.ac.kr) Fall 2021



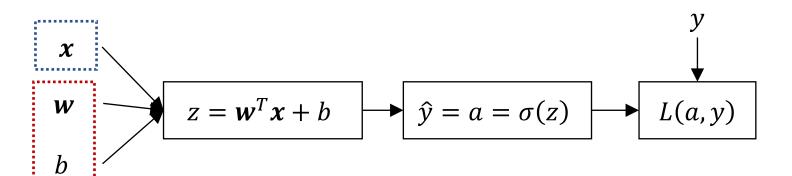
# Logistic Regression

- Output:  $\hat{y} = \sigma(\mathbf{w}^{\mathsf{T}}\mathbf{x} + b)$  where  $\sigma(z) = \frac{1}{1 + e^{-z}}$
- Loss:  $L(\hat{y}, y) = -y \log \hat{y} (1 y) \log(1 \hat{y})$

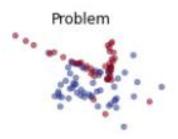


**Features** 

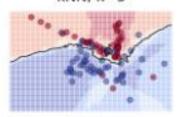
**Parameters** 



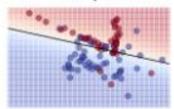
# Decision Boundaries



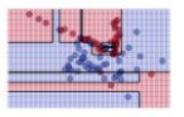
kNN, k=5



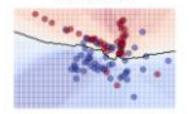
Logistic Regression simple



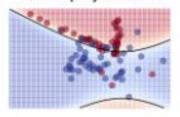
Decision tree



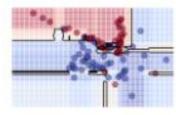
kNN, k=15



Logistic Regression basic polynomials



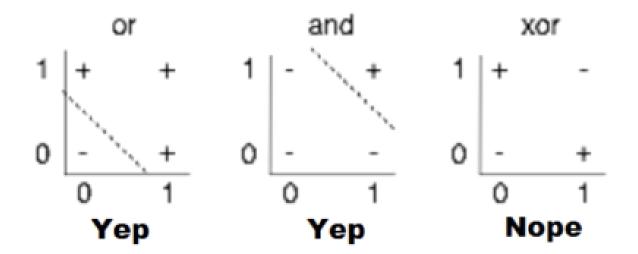
Random forest



SVM

SVM

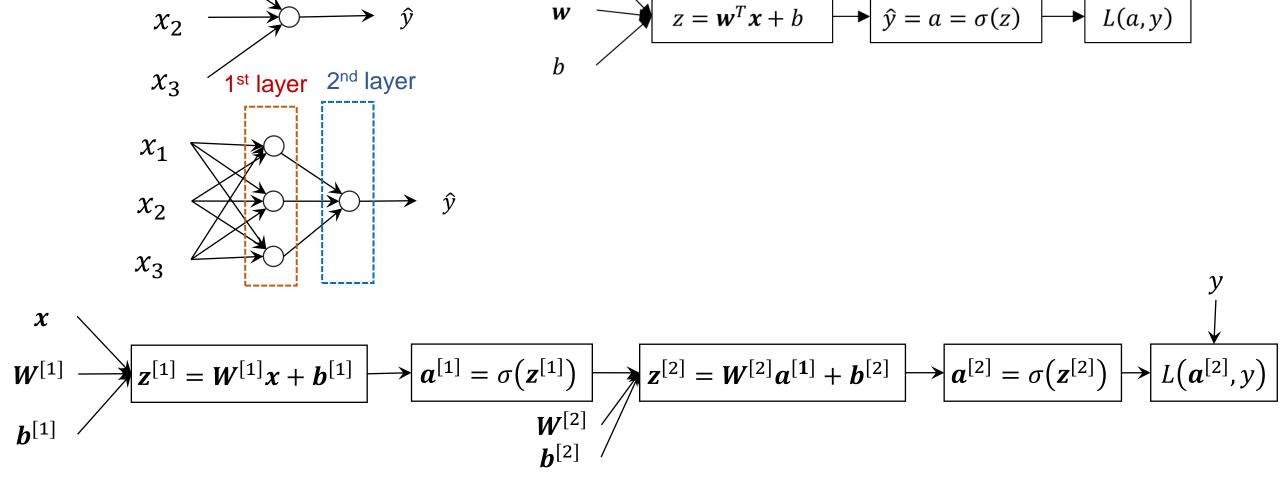
# (Simple) XOR problem: linearly separable?



Solution: make it more complicated

# What is a Neural Network?

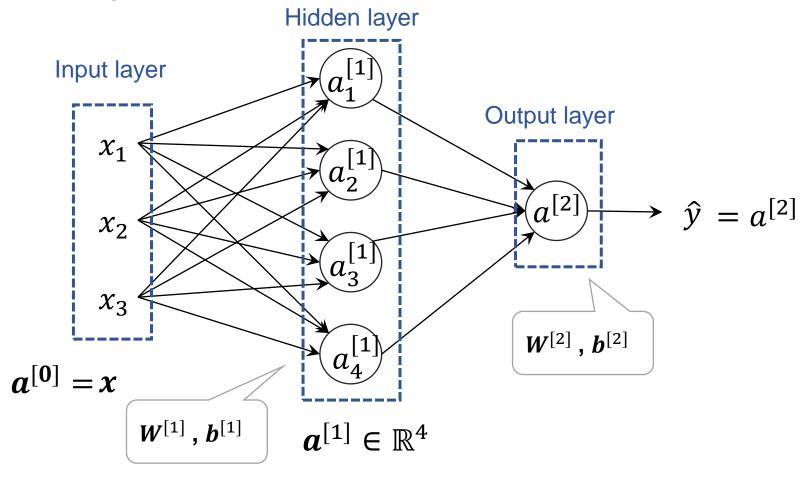
 $x_1$ 



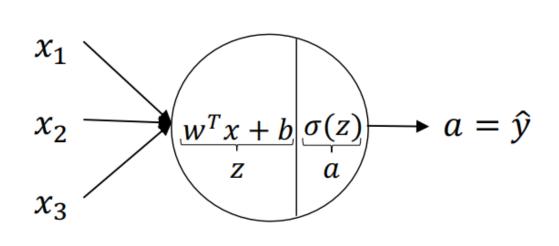
W

# Neural Network Representation

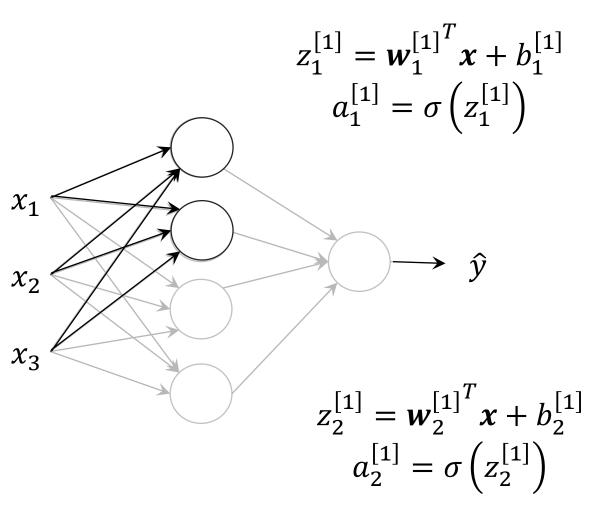
2-layer neural network



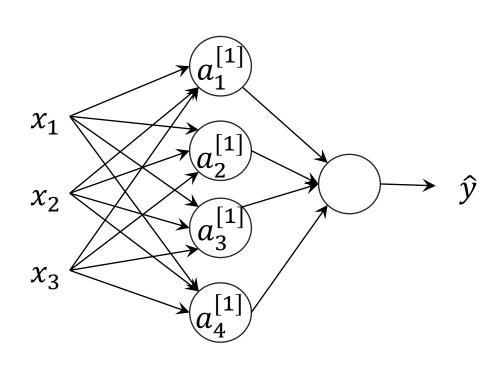
# Neural Network Representation



$$z = w^T x + b$$
$$a = \sigma(z)$$



# Neural Network Representation



$$z_{1}^{[1]} = \boldsymbol{w}_{1}^{[1]^{T}} \boldsymbol{x} + b_{1}^{[1]} \qquad a_{1}^{[1]} = \sigma \left( z_{1}^{[1]} \right)$$

$$z_{2}^{[1]} = \boldsymbol{w}_{2}^{[1]^{T}} \boldsymbol{x} + b_{2}^{[1]} \qquad a_{2}^{[1]} = \sigma \left( z_{2}^{[1]} \right)$$

$$z_{3}^{[1]} = \boldsymbol{w}_{3}^{[1]^{T}} \boldsymbol{x} + b_{3}^{[1]} \qquad a_{3}^{[1]} = \sigma \left( z_{3}^{[1]} \right)$$

$$z_{4}^{[1]} = \boldsymbol{w}_{4}^{[1]^{T}} \boldsymbol{x} + b_{4}^{[1]} \qquad a_{4}^{[1]} = \sigma \left( z_{4}^{[1]} \right)$$

$$z^{[2]} = \mathbf{w}^{[2]^T} \mathbf{a}^{[1]} + b^{[2]} \quad a^{[2]} = \sigma(z^{[2]})$$

# Neural Network Representation: Vectorization

Hidden layer

$$z_i^{[1]} = \boldsymbol{W}_i^{[1]} \boldsymbol{x} + b_i^{[1]}$$

$$a_i^{[1]} = \sigma\left(z_i^{[1]}\right)$$

 $z_i^{[1]} = W_i^{[1]} x + b_i^{[1]}$   $a_i^{[1]} = \sigma(z_i^{[1]})$  For  $1 \le i \le h$  where h: # of hidden nodes

Output layer

$$z^{[2]} = \mathbf{w}^{[2]} \mathbf{a}^{[1]} + b^{[2]} \quad a^{[2]} = \sigma(z^{[2]})$$

$$a^{[2]} = \sigma(z^{[2]})$$

Let 
$$x = \begin{bmatrix} x_1 \\ x_2 \\ \dots \\ x_m \end{bmatrix}$$
  $\mathbf{w}_i^{[1]} \in \mathbb{R}^m$ 

$$\mathbf{w}_i^{[1]} \in \mathbb{R}^m$$

$$oldsymbol{z}^{[1]} = egin{bmatrix} Z_1^{[1]} \ Z_2^{[1]} \ ... \ Z_h^{[1]} \end{bmatrix}$$

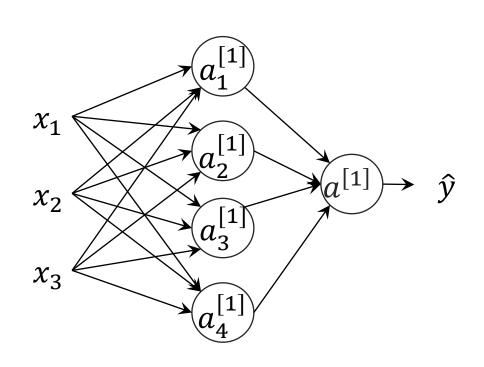
$$m{b}^{[1]} = egin{bmatrix} b_1^{[1]} \ b_2^{[1]} \ ... \ b_h^{[1]} \end{bmatrix}$$

$$\mathbf{z}^{[1]} = \begin{bmatrix} z_1^{[1]} \\ z_2^{[1]} \\ \vdots \\ z_h^{[1]} \end{bmatrix} \qquad \boldsymbol{b}^{[1]} = \begin{bmatrix} b_1^{[1]} \\ b_2^{[1]} \\ \vdots \\ b_h^{[1]} \end{bmatrix} \qquad \boldsymbol{w}^{[1]} = \begin{bmatrix} \boldsymbol{w}_1^{[1]}^T \\ \boldsymbol{w}_2^{[1]}^T \\ \vdots \\ \boldsymbol{w}_{h,1}^{[1]} & \cdots & \boldsymbol{w}_{h,m}^{[1]} \end{bmatrix} \qquad \boldsymbol{a}^{[1]} = \begin{bmatrix} a_1^{[1]} \\ a_2^{[1]} \\ \vdots \\ a_h^{[1]} \end{bmatrix} \qquad \boldsymbol{w}^{[2]} = \begin{bmatrix} w_1^{[2]} \\ w_2^{[2]} \\ \vdots \\ w_{h,1}^{[2]} \end{bmatrix}$$

$$m{a}^{[1]} = egin{bmatrix} a_1^{[1]} \\ a_2^{[1]} \\ ... \\ a_h^{[1]} \end{bmatrix}$$

$$\boldsymbol{w}^{[2]} = \begin{vmatrix} w_1 \\ w_2^{[2]} \\ \dots \\ w_h^{[2]} \end{vmatrix}$$

# Neural Network with a Hidden Layer: Almost Done!



Input:

$$x \in \mathbb{R}^m$$

Parameters:

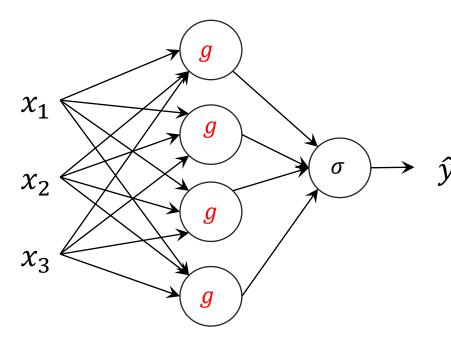
$$m{w}^{[1]} \in \mathbb{R}^{h imes m} \qquad m{w}^{[2]} \in \mathbb{R}^h$$
 $m{b}^{[1]} \in \mathbb{R}^h \qquad b^{[2]} \in \mathbb{R}$ 

Forward pass:

$$z^{[1]} = W^{[1]}x + b^{[1]}$$
 $a^{[1]} = \sigma(z^{[1]})$ 
 $z^{[2]} = w^{[2]}a^{[1]} + b^{[2]}$ 
 $\hat{y} = a^{[2]} = \sigma(z^{[2]})$ 

# **Activation Functions**

# Neural Network with a Hidden Layer: Almost Done!



Input:

$$x \in \mathbb{R}^m$$

Parameters:

$$\mathbf{W}^{[1]} \in \mathbb{R}^{h \times m}$$
  $\mathbf{w}^{[2]} \in \mathbb{R}^{h}$   $\mathbf{b}^{[1]} \in \mathbb{R}^{h}$ 

Forward pass:

$$z^{[1]} = W^{[1]}x + b^{[1]}$$

 $a^{[1]} = g(z^{[1]})$  where g(.) is an activation function

$$z^{[2]} = \mathbf{w}^{[2]^T} \mathbf{a}^{[1]} + b^{[2]}$$
$$\hat{y} = a^{[2]} = \sigma(z^{[2]})$$

# Why we need to use non-linear activation functions?

$$z^{[1]} = W^{[1]}x + b^{[1]}$$
  $z^{[2]} = W^{[2]}z^{[1]} + b^{[2]}$   $z^{[2]}$ 

Composition of linear functions => linear function

# Activation functions

There are so many activation functions ...

We'll cover some important and currently widely used activation functions

Sigmoid

tanh

ReLU

LeakyReLU

Name	♦ Plot	Function, $f(x)$	Derivative of $f$ , $f'(x)$
Identity		x	1
Binary step		$ \begin{cases} 0 & \text{if } x < 0 \\ 1 & \text{if } x \ge 0 \end{cases} $	$\begin{cases} 0 & \text{if } x \neq 0 \\ \text{undefined} & \text{if } x = 0 \end{cases}$
Logistic, sigmoid, or soft step		$\sigma(x)=rac{1}{1+e^{-x}}$	f(x)(1-f(x))
tanh		$ anh(x)=rac{e^x-e^{-x}}{e^x+e^{-x}}$	$1-f(x)^2$
Rectified linear unit (ReLU) <sup>[11]</sup>		$\begin{cases} 0 & \text{if } x \le 0 \\ x & \text{if } x > 0 \end{cases}$ $= \max\{0, x\} = x1_{x > 0}$	$\begin{cases} 0 & \text{if } x < 0 \\ 1 & \text{if } x > 0 \\ \text{undefined} & \text{if } x = 0 \end{cases}$
Gaussian Error Linear Unit (GELU) <sup>[6]</sup>		$rac{1}{2}x\left(1+ ext{erf}\left(rac{x}{\sqrt{2}} ight) ight) \ =x\Phi(x)$	$\Phi(x) + x\phi(x)$
Softplus <sup>[12]</sup>		$\ln(1+e^x)$	$\frac{1}{1+e^{-x}}$
Exponential linear unit (ELU) <sup>[13]</sup>		$\begin{cases} \alpha \left( e^x - 1 \right) & \text{if } x \leq 0 \\ x & \text{if } x > 0 \end{cases}$ with parameter $\alpha$	$\begin{cases} \alpha e^x & \text{if } x < 0 \\ 1 & \text{if } x > 0 \\ 1 & \text{if } x = 0 \text{ and } \alpha = 1 \end{cases}$
Square linear unit (SQLU) <sup>[14]</sup>		$\begin{cases} x & \text{if } x > 0.0\\ \alpha(x+\frac{x^2}{4}) & \text{if } -2.0 \leq x \leq 0\\ -\alpha & \text{if } x < -2.0 \end{cases}$	$\begin{cases} 1 & \text{if } x > 0.0 \\ 1 + \frac{x}{2} & \text{if } -2.0 \le x \le 0 \\ 0 & \text{if } x < -2.0 \end{cases}$
Scaled exponential linear unit (SELU)[15]		$\lambda \begin{cases} \alpha(e^x-1) & \text{if } x<0 \\ x & \text{if } x\geq 0 \end{cases}$ with parameters $\lambda=1.0507$ and $\alpha=1.67326$	$\lambda igg\{ egin{array}{ll} lpha e^x &  ext{if } x < 0 \ 1 &  ext{if } x \geq 0 \end{array}$
Leaky rectified linear unit (Leaky ReLU) <sup>[16]</sup>		$\left\{egin{array}{ll} 0.01x &  ext{if } x < 0 \ x &  ext{if } x \geq 0 \end{array} ight.$	$\left\{egin{array}{ll} 0.01 &  ext{if } x < 0 \ 1 &  ext{if } x \geq 0 \end{array} ight.$
Parameteric rectified linear unit (PReLU) <sup>[17]</sup>		$\begin{cases} \alpha x & \text{if } x < 0 \\ x & \text{if } x \geq 0 \end{cases}$ with parameter $\alpha$	$\begin{cases} \alpha & \text{if } x < 0 \\ 1 & \text{if } x \ge 0 \end{cases}$
ElliotSig, <sup>[18][19]</sup> softsign <sup>[20][21]</sup>		$-\frac{x}{1+ x }$	$\frac{1}{(1+ x )^2}$

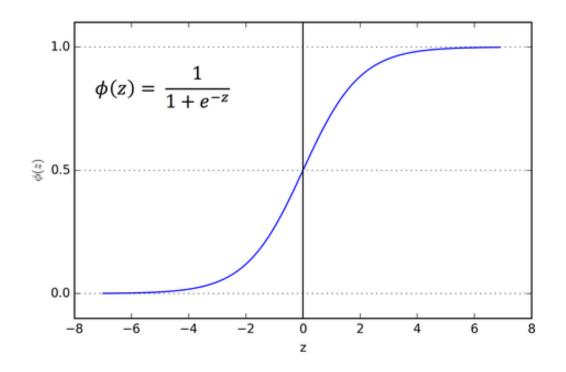
# Sigmoid

$$\bullet \ \sigma(x) = \frac{1}{1 + e^{-x}}$$

- Range: (0,1)
- Derivative

$$\frac{d\sigma(x)}{dx} = \sigma(x) (1 - \sigma(x))$$

• 
$$0 < \frac{d\sigma(x)}{dx} \le 0.25$$



# Hyperbolic tangent: tanh

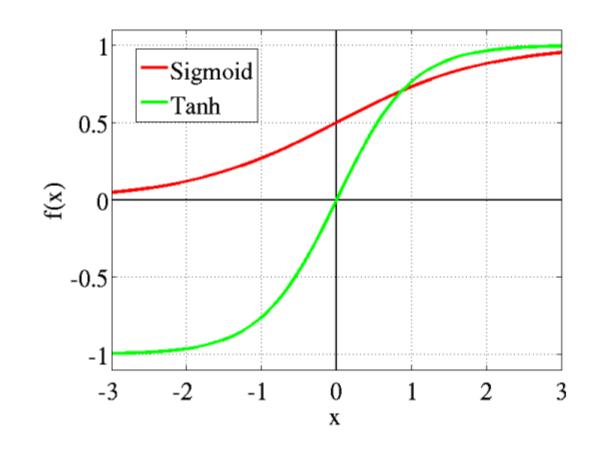
• 
$$tanh x = \frac{e^x - e^{-x}}{e^x + e^{-x}}$$

$$=2\sigma(2x)-1$$

- Range: (-1,1)
- Derivative

$$\frac{d\tanh x}{dx} = 1 - \tanh^2 x$$

• 
$$0 < \frac{d \tanh x}{dx} \le 1$$



# Vanishing gradient

"The term vanishing gradient refers to the fact that in a feedforward network (FFN) the backpropagated error signal typically decreases (or increases) exponentially as a function of the distance from the final layer" by Jason Brownlee

https://machinelearningmastery.com/how-to-fix-vanishing-gradients-using-the-rectified-linear-activation-function/

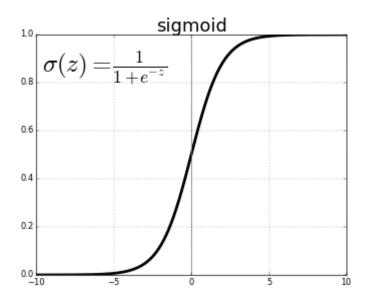
Chain rule (for a Deep NN)

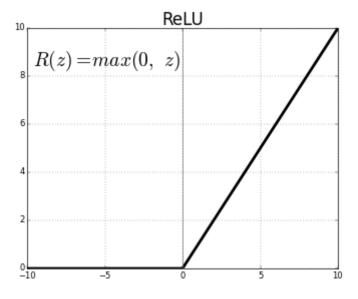
$$\frac{\partial L}{\partial z^{[n]}} \frac{\partial z^{[n]}}{\partial z^{[n-1]}} \dots \frac{\partial z^{[3]}}{\partial z^{[2]}} \frac{\partial z^{[2]}}{\partial z^{[1]}} \frac{\partial z^{[1]}}{\partial w}$$

# Rectified linear unit: ReLU

- $\bullet f(x) = \max\{0, x\}$
- Range: [0, ∞)
- Derivative

$$\frac{df(x)}{dx} = \begin{cases} 0 & if \ x < 0 \\ 1 & if \ x > 0 \\ undefined & if \ x = 0 \end{cases}$$





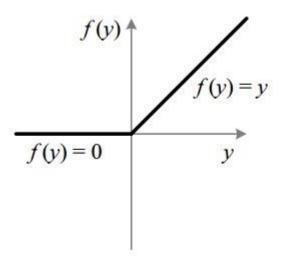
# Leaky ReLU

• 
$$f(x) = \begin{cases} ax & if \ x < 0 \\ x & if \ x \ge 0 \end{cases}$$
• 
$$a \ll 1 \text{ (e.g, } a = 0.01)$$

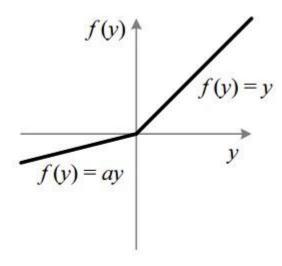
- Range:  $(-\infty, \infty)$
- Derivative

$$\frac{df(x)}{dx} = \begin{cases} a & \text{if } x < 0\\ 1 & \text{if } x > 0\\ undefined & \text{if } x = 0 \end{cases}$$

ReLU



Leaky ReLU

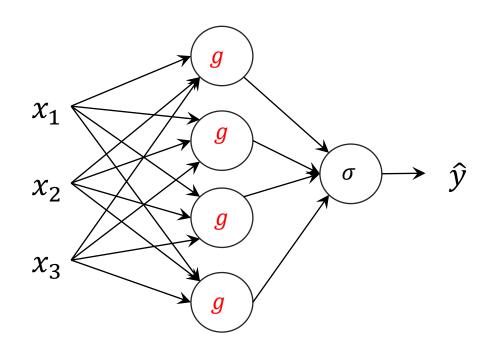


## Activation functions

- There is no rule but ... in many cases
- Output layer
  - Sigmoid
- Hidden layer
  - tanh, ReLU, LeakyReLU

My personal opinion:
If the performance of two things are similar,
Use the simpler one! (Use ReLU!)

# Neural Network with a Hidden Layer: Done!



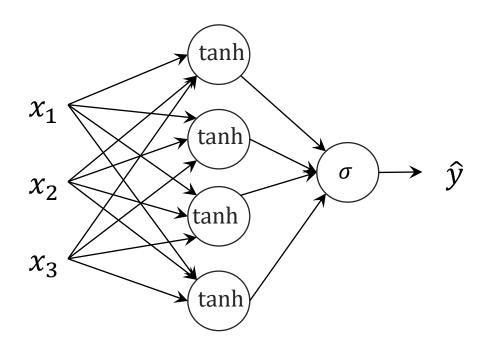
$$egin{aligned} & m{z}^{[1]} = m{W}^{[1]} x + m{b}^{[1]} \ & m{a}^{[1]} = m{g}(m{z}^{[1]}) \text{ where } m{g}(.) \text{ is an activation function} \ & m{z}^{[2]} = m{w}^{[2]}^T m{a}^{[1]} + m{b}^{[2]} \ & \hat{y} = m{a}^{[2]} = \sigma(m{z}^{[2]}) \end{aligned}$$

You may use tanh, ReLU, Leaky ReLU for g

# **Gradient Descent**

Shallow Neural Network with tanh

## **Shallow Neural Network**



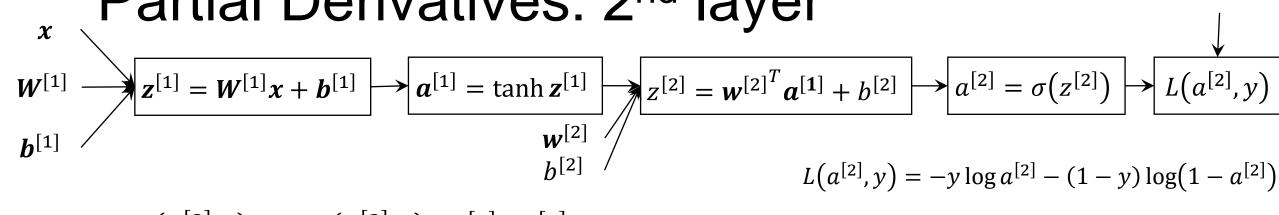
$$\mathbf{z}^{[1]} = \mathbf{W}^{[1]} \mathbf{x} + \mathbf{b}^{[1]}$$
 $\mathbf{a}^{[1]} = \tanh \mathbf{z}^{[1]}$ 
 $\mathbf{z}^{[2]} = \mathbf{w}^{[2]} \mathbf{a}^{[1]} + \mathbf{b}^{[2]}$ 
 $\hat{y} = \mathbf{a}^{[2]} = \sigma(\mathbf{z}^{[2]})$ 

Parameters:  $\boldsymbol{\theta} = \{ \boldsymbol{W}^{[1]}, \, \boldsymbol{b}^{[1]}, \boldsymbol{w}^{[2]}, \, b^{[2]} \}$ Loss  $L(\hat{y}, y)$ Cost  $J(\theta)$ 

Gradient descent

$$\boldsymbol{\theta} \coloneqq \boldsymbol{\theta} - \eta \nabla J = \boldsymbol{\theta} - \eta \frac{\nabla L}{m}$$

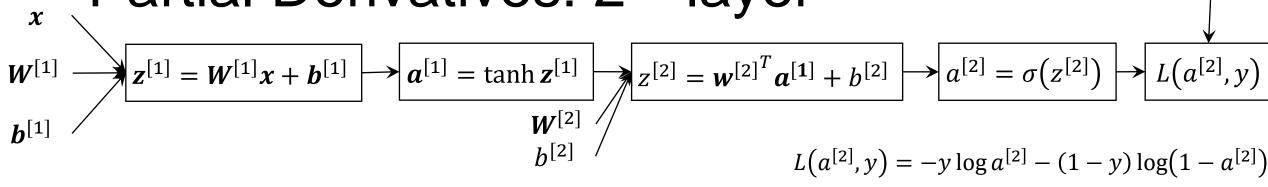
# Partial Derivatives: 2<sup>nd</sup> layer



Do you remember?

 $\frac{d\sigma(x)}{dx} = \sigma(x)(1 - \sigma(x))$ 

# Partial Derivatives: 2<sup>nd</sup> layer

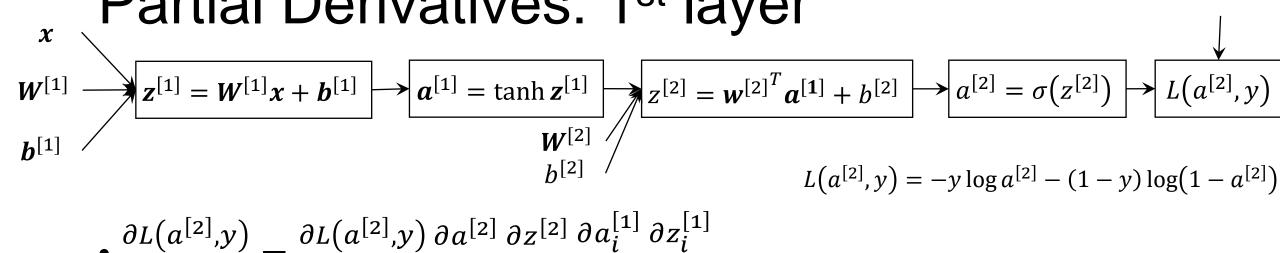


• 
$$\frac{\partial L(a^{[2]}, y)}{\partial w_i^{[2]}} = \frac{\partial L(a^{[2]}, y)}{\partial a^{[2]}} \frac{\partial a^{[2]}}{\partial z^{[2]}} \frac{\partial z^{[2]}}{\partial w_i^{[2]}}$$

$$= (a^{[2]} - y) \frac{\partial z^{[2]}}{\partial w_i^{[2]}}$$

$$= (a^{[2]} - y) a_i^{[1]}$$

# Partial Derivatives: 1<sup>st</sup> layer



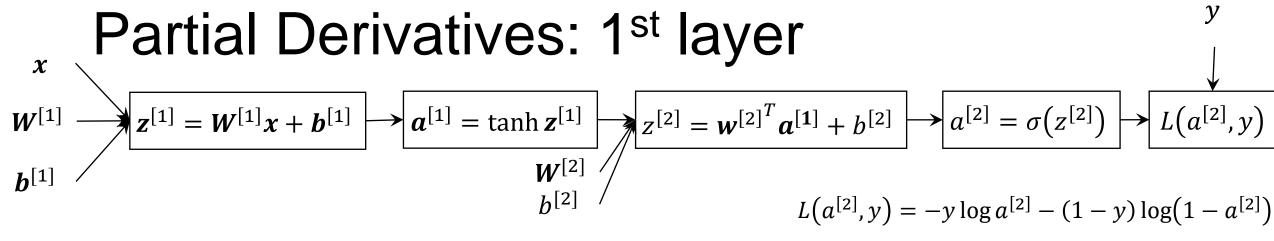
• 
$$\frac{\partial L(a^{[2]}, y)}{\partial b_i^{[1]}} = \frac{\partial L(a^{[2]}, y)}{\partial a^{[2]}} \frac{\partial a^{[2]}}{\partial z^{[2]}} \frac{\partial z^{[2]}}{\partial a_i^{[1]}} \frac{\partial a_i^{[1]}}{\partial z_i^{[1]}} \frac{\partial z_i^{[1]}}{\partial b_i^{[1]}}$$

$$= (a^{[2]} - y) \frac{\partial z^{[2]}}{\partial a_i^{[1]}} \frac{\partial a_i^{[1]}}{\partial z_i^{[1]}} \frac{\partial z_i^{[1]}}{\partial b_i^{[1]}}$$

$$= (a^{[2]} - y) w_i^{[2]} \left(1 - \tanh^2 z_i^{[1]}\right) \cdot 1$$

$$= (a^{[2]} - y) w_i^{[2]} \left(1 - a_i^{[1]^2}\right)$$

$$\frac{d \tanh x}{dx} = 1 - \tanh^2 x$$



$$\bullet \frac{\partial L(a^{[2]}, y)}{\partial W_{ij}^{[1]}} = \frac{\partial L(a^{[2]}, y)}{\partial a^{[2]}} \frac{\partial a^{[2]}}{\partial z^{[2]}} \frac{\partial z^{[2]}}{\partial a_i^{[1]}} \frac{\partial a_i^{[1]}}{\partial z_i^{[1]}} \frac{\partial z_i^{[1]}}{\partial W_{ij}^{[1]}}$$

$$= (a^{[2]} - y) w_i^{[2]} \left(1 - a_i^{[1]^2}\right) \frac{\partial z_i^{[1]}}{\partial W_{ij}^{[1]}}$$

$$= (a^{[2]} - y) w_i^{[2]} \left(1 - a_i^{[1]^2}\right) x_j$$

## Partial derivatives

• 
$$\frac{\partial L(a^{[2]},y)}{\partial b^{[2]}} = a^{[2]} - y$$
  
•  $\frac{\partial L(a^{[2]},y)}{\partial w_i^{[2]}} = (a^{[2]} - y) a_i^{[1]}$   
•  $\frac{\partial L(a^{[2]},y)}{\partial b_i^{[1]}} = (a^{[2]} - y) w_i^{[2]} (1 - a_i^{[1]^2})$   
•  $\frac{\partial L(a^{[2]},y)}{\partial w_{i}^{[1]}} = (a^{[2]} - y) w_i^{[2]} (1 - a_i^{[1]^2}) x_j$ 

# **Gradient Descent**

- Let  $x \in \mathbb{R}^n$
- We have h hidden units
- Randomly initialize the parameters
  - $W^{[1]} \in \mathbb{R}^{h \times n}$
  - $\boldsymbol{b}^{[1]} \in \mathbb{R}^h$
  - $\mathbf{w}^{[2]} \in \mathbb{R}^h$
  - $b^{[2]} \in \mathbb{R}$

## For each epoch

• 
$$dW^{[1]} = 0 \in \mathbb{R}^{h \times n}, db^{[1]} = 0 \in \mathbb{R}^h$$

• 
$$dw^{[2]} = \mathbf{0} \in \mathbb{R}^h$$
,  $db^{[2]} = 0 \in \mathbb{R}$ 

• For 
$$(x, y) \in D$$

• 
$$dw_i^{[2]} += \frac{\partial L(a^{[2]}, y)}{\partial W_i^{[2]}}$$
 for  $1 \le i \le h$ 

• 
$$db^{[2]} += \frac{\partial L(a^{[2]},y)}{\partial b^{[2]}}$$

• 
$$dW_{ij}^{[1]} += \frac{\partial \tilde{L}(a^{[2]}, y)}{\partial W_{ij}^{[1]}}$$
 for  $1 \le i \le n$ ,  $1 \le j \le h$ 

• 
$$db_i^{[1]} += \frac{\partial L(a^{[2]},y)}{\partial b_i^{[1]}}$$
 for  $1 \le i \le h$ ,

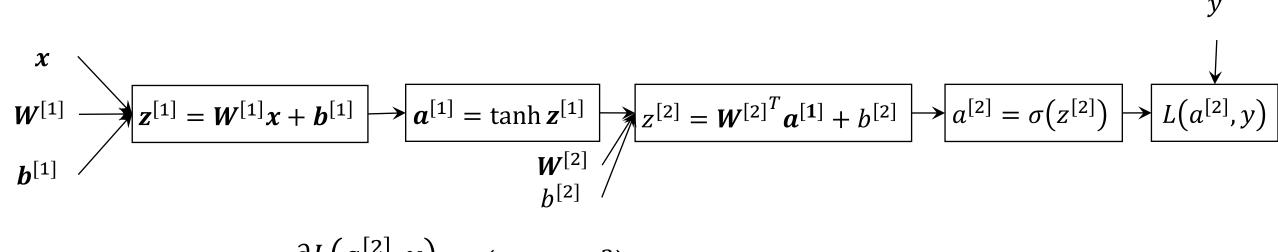
• 
$$W^{[1]} -= \eta \cdot dW^{[1]}/|D|$$

• 
$$b^{[1]} = \eta \cdot db^{[1]}/|D|$$

• 
$$w^{[2]} -= \eta \cdot dw^{[1]}/|D|$$

• 
$$b^{[2]} = \eta \cdot db^{[2]}/|D|$$

# Initialize with the same value?



$$\frac{\partial L(a^{[2]}, y)}{\partial b_i^{[1]}} = \left(1 - a_i^{[1]^2}\right) w_i^{[2]} \left(a^{[2]} - y\right)$$

$$\frac{\partial L(a^{[2]}, y)}{\partial b_1^{[1]}} = \frac{\partial L(a^{[2]}, y)}{\partial b_2^{[1]}} = \frac{\partial L(a^{[2]}, y)}{\partial b_3^{[1]}} = \cdots$$

# Programming Exercise

Shallow neural network for XOR

# Slicing a numpy array

# Slicing In [77]: a = np.array([2,4,6,8,10]) b = np.array([1,3]) In [78]: a[b] Out [78]: array([4, 8])

# NumPy where

- numpy.where(condition[, x, y])
  - Parameters
    - Condition: array\_like, bool
    - x,y: array\_like
  - Returns:
    - Out: ndarray
      - An array with elements from *x* where *condition* is True, and elements from *y* elsewhere.

#### Examples

```
>>> a = np.arange(10)
>>> a
array([0, 1, 2, 3, 4, 5, 6, 7, 8, 9])
>>> np.where(a < 5, a, 10*a)
array([ 0,  1,  2,  3,  4, 50, 60, 70, 80, 90])</pre>
```

# Slicing a numpy array with condition

```
In [84]:    a = np.array([2,4,6,8,10,12])
    b = np.array([1,3])

In [85]:    a[a>5]

Out [85]:    array([ 6,   8, 10, 12])

In [86]:    a[a*3==0]

Out [86]:    array([ 6, 12])
```

# Data preparation

#### XOR data

```
In [4]: x_seeds = np.array([(0,0),(1,0),(0,1),(1,1)],dtype=np.float)
y_seeds = np.array([0,1,1,0])

In [5]: N = 1000
    idxs = np.random.randint(0,4,N)

In [6]: X = x_seeds[idxs]
Y = y_seeds[idxs]
In [7]: X += np.random.normal(scale = 0.25, size = X.shape)
```

# Data plotting

import matplotlib.pyplot as plt

### Plot data ¶

```
idxs_1 = np.where(Y==1)
In [8]:
         idxs_0 = np.where(Y==0)
In [9]: X_0 = X[idxs_0]
         Y_0 = Y[idxs_0]
n [10]: X_1 = X[idxs_1]
         Y_1 = Y[idxs_1]
n [11]: #p/t,o/f()
         plt.plot(X_0[:,0],X_0[:,1],"r^")
         plt.plot(X_1[:,0],X_1[:,1],"bx")
         plt.show()
           1.5
           1.0
           0.5
           0.0
          -0.5
          -1.0
                   -0.5
                             0.0
                                      0.5
                                                         1.5
                                                1.0
```

# Model

```
class shallow neural network():
    def __init__(self, num_input_features, num_hiddens):
        self.num_input_features = num_input_features
        self.num_hiddens = num_hiddens
        self.W1 = np.random.normal(size = (num_hiddens, num_input_features))
        self.b1 = np.random.normal(size = num_hiddens)
        self.W2 = np.random.normal(size = num_hiddens)
        self.b2 = np.random.normal(size = 1)
    def sigmoid(self,z):
        return 1/(1 + np.exp(-z))
    def predict(self,x):
        z1 = np.matmul(self.W1,x) + self.b1
       a1 = np.tanh(z1)
       z2 = np.matmul(self.W2.a1)+ self.b2
       a2 = self.sigmoid(z2)
        return a2, (z1,a1,z2, a2)
```

```
model = shallow_neural_network(2,3)
```

#### Train

# **Train**

```
]: def train(X, Y, model, Ir = 0.1):
       dW1 = np.zeros_like(model.W1)
       db1 = np.zeros_like(model.b1)
       dW2 = np.zeros_like(model.W2)
       db2 = np.zeros_like(model.b2)
       m = Ien(X)
       cost = 0.0
       for x,y in zip(X,Y):
           a2, (z1,a1,z2, _) = model.predict(x)
           if y == 1:
               cost -= np.log(a2)
           else:
               cost = np.log(1-a2)
           diff = a2-y
           # layer 2
           # db2
           db2 += diff
           # dw2 = todo: remove for-loops
           for i in range(model.num_hiddens):
               dW2[i] += a1[i] *diff
           #layer 1
           # db1 = todo: remove for=loops
           for i in range(model.num_hiddens):
               db1[i] += (1-a1[i] ++2) + model. W2[i] + diff
           # db2 = todo: remove for-loops
           for i in range(model.num hiddens):
               for j in range(model.num_input_features):
                   dW1[i,j] += x[j]*(1-a1[i]**2)*model.W2[i]*diff
       cost /= m
       model.W1 -= lr * dW1/m
       model.b1 -= lr * db1/m
       model.W2 -= Ir * dW2/m
       model.b2 -= Ir * db2/m
       return cost
```

```
for epoch in range(100):
    cost = train(X,Y, model, 1.0)
    if epoch %10 == 0:
        print(epoch, cost)

0 [1.16857084]
```

```
0 [1.16857084]

10 [0.68480409]

20 [0.65975895]

30 [0.60186859]

40 [0.52126503]

50 [0.4437902]

60 [0.3854394]

70 [0.34575853]

80 [0.31936125]

90 [0.30160166]
```

## Test Test

```
model.predict((1,1))[0].item()
In [73]:
Out [73]: 0.07201455939561928
In [74]: model.predict((1,0))[0].item()
Out [74]: 0,8872553390238738
         model.predict((0,1))[0].item()
In [75]:
Out [75]: 0.858854303287919
In [76]:
         model.predict((0,0))[0].item()
Out [76]: 0.07550823533589167
```

# 숙제

- Train code에서 for-loops 없이 동 작하도록 수정
- Hint
  - Layer 2 (Logistic regression참고)
  - Layer 1

```
numpy.outer(a, b, out=None)

Compute the outer product of two vectors.

Given two vectors, a = [a0, a1, ..., aM] and b = [b0, b1, ..., bN], the outer product [1] is:

[[a0*b0 a0*b1 ... a0*bN]
[a1*b0 .
[... .
[aM*b0 aM*bN]]
```

#### Train

```
]: def train(X, Y, model, Ir = 0.1):
       dW1 = np.zeros_like(model.W1)
       db1 = np.zeros_like(model.b1)
       dW2 = np.zeros_like(model.W2)
       db2 = np.zeros_like(model.b2)
       m = Ien(X)
       cost = 0.0
       for x,y in zip(X,Y):
           a2, (z1,a1,z2, _) = model.predict(x)
           if v == 1:
               cost -= np.log(a2)
           el se:
               cost = np.log(1-a2)
           diff = a2-y
           # layer 2
           # db2
           db2 += diff
           # dw2 - todo: remove for-loops
           for i in range(model.num_hiddens):
               dW2[i] += a1[i]+diff
           #layer 1
           # db1 = todo: remove for=loops
           for i in range(model.num_hiddens):
               db1[i] += (1-a1[i]**2)*model.\\2[i]*diff
           # db2 = todo: remove for-loops
           for i in range(model.num hiddens):
                for j in range(model.num_input_features):
                   dW1[i,j] += x[j]*(1-a1[i]**2)*model.W2[i]*diff
       cost /= m
       model.W1 -= lr * dW1/m
       model.b1 -= lr * db1/m
       model.W2 -= lr * dW2/m
       model.b2 -= Ir * db2/m
       return cost
```