

32-Bit

Microcontroller

TC270 / TC275 / TC277

32-Bit Single-Chip Micocontroller DC-Step

32-Bit Single-Chip Micocontroller

Data Sheet

V 1.0, 2017-01

Microcontrollers

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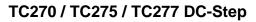
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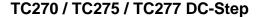


1 Summary of Features

The TC27x product family has the following features:

- High Performance Microcontroller with three CPU cores
- Two 32-bit super-scalar TriCore CPUs (TC1.6P), each having the following features:
 - Superior real-time performance
 - Strong bit handling
 - Fully integrated DSP capabilities
 - Multiply-accumulate unit able to sustain 2 MAC operations per cycle
 - Fully pipelined Floating point unit (FPU)
 - up to 200 MHz operation at full temperature range
 - up to 120 Kbyte Data Scratch-Pad RAM (DSPR)
 - up to 32 Kbyte Instruction Scratch-Pad RAM (PSPR)
 - 16 Kbyte Instruction Cache (ICACHE)
 - 8 Kbyte Data Cache (DCACHE)
- · Power Efficient scalar TriCore CPU (TC1.6E), having the following features:
 - Binary code compatibility with TC1.6P
 - up to 200 MHz operation at full temperature range
 - up to 112 Kbyte Data Scratch-Pad RAM (DSPR)
 - up to 24 Kbyte Instruction Scratch-Pad RAM (PSPR)
 - 8 Kbyte Instruction Cache (ICACHE)
 - 0.125Kbyte Data Read Buffer (DRB)
- Lockstepped shadow cores for one TC1.6P and for TC1.6E
- Multiple on-chip memories
 - All embedded NVM and SRAM are ECC protected
 - up to 4 Mbyte Program Flash Memory (PFLASH)
 - up to 384 Kbyte Data Flash Memory (DFLASH) usable for EEPROM emulation
 - 32 Kbyte Memory (LMU)
 - BootROM (BROM)
- · 64-Channel DMA Controller with safe data transfer
- Sophisticated interrupt system (ECC protected)
- · High performance on-chip bus structure
 - 64-bit Cross Bar Interconnect (SRI) giving fast parallel access between bus masters, CPUs and memories
 - 32-bit System Peripheral Bus (SPB) for on-chip peripheral and functional units
 - One bus bridge (SFI Bridge)
- · Optional Hardware Security Module (HSM) on some variants
- Safety Management Unit (SMU) handling safety monitor alarms
- Memory Test Unit with ECC, Memory Initialization and MBIST functions (MTU)
- Hardware I/O Monitor (IOM) for checking of digital I/O
- · Versatile On-chip Peripheral Units
 - Four Asynchronous/Synchronous Serial Channels (ASCLIN) with hardware LIN support (V1.3, V2.0, V2.1 and J2602) up to 50 MBaud

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- Four Queued SPI Interface Channels (QSPI) with master and slave capability up to 50 Mbit/s
- High Speed Serial Link (HSSL) for serial inter-processor communication up to 320 Mbit/s
- Two serial Micro Second Bus interfaces (MSC) for serial port expansion to external power devices
- One MultiCAN+ Module with 4 CAN nodes and 256 free assignable message objects for high efficiency data handling via FIFO buffering and gateway data transfer
- 10 Single Edge Nibble Transmission (SENT) channels for connection to sensors
- One FlexRay[™] module with 2 channels (E-Ray) supporting V2.1
- One Generic Timer Module (GTM) providing a powerful set of digital signal filtering and timer functionality to realize autonomous and complex Input/Output management
- One Capture / Compare 6 module (Two kernels CCU60 and CCU61)
- One General Purpose 12 Timer Unit (GPT120)
- Three channel Peripheral Sensor Interface conforming to V1.3 (PSI5)
- Peripheral Sensor Interface with Serial PHY (PSI5-S)
- Optional Inter-Integrated Circuit Bus Interface (I2C) conforming to V2.1
- Optional IEEE802.3 Ethernet MAC with RMII and MII interfaces (ETH)
- Versatile Successive Approximation ADC (VADC)
 - Cluster of 8 independent ADC kernels
 - Input voltage range from 0 V to 5.5V (ADC supply)
- Delta-Sigma ADC (DSADC)
 - Six channels
- Digital programmable I/O ports
- On-chip debug support for OCDS Level 1 (CPUs, DMA, On Chip Buses)
- multi-core debugging, real time tracing, and calibration
- four/five wire JTAG (IEEE 1149.1) or DAP (Device Access Port) interface
- · Power Management System and on-chip regulators
- · Clock Generation Unit with System PLL and Flexray PLL
- Embedded Voltage Regulator



Ordering Information

The ordering code for Infineon microcontrollers provides an exact reference to the required product. This ordering code identifies:

- The derivative itself, i.e. its function set, the temperature range, and the supply voltage
- The package and the type of delivery.

For the available ordering codes for the TC270 / TC275 / TC277 please refer to the "AURIX TC27x Microcontrollers Variant Overview", which summarizes all available variants.

Table 1-1 Overview of TC27x Functions

Feature		
CPU Core	Туре	TC1.6P / TC1.6E
	P Cores / Checker Cores /	2/1/
	E Cores / Checker Cores	1/1
	Max. Freq.	200 MHz
	FPU	yes
Program Flash	Size	4 Mbyte
Data Flash	Size	384 Kbyte
Cache	Instruction (P / E)	16 Kbyte / 8 Kbyte
	Data (P / E)	8 Kbyte / -
SRAM	Size TC1.6P (DSPR/PSPR)	120 Kbyte / 32 Kbyte ²⁾
	Size TC1.6E (DSPR/PSPR)	112 Kbyte / 24 Kbyte ^{1) 2)}
	Size LMU	32 Kbyte
DMA	Channels	64
ADC	Channels	48 + 12
	Converter	8
DSADC	Channels	6
GTM	TIM	4
	ТОМ	3
	ATOM / MCS	5 / 4
	CMU / ICM	1/1
	PSM	1
	ТВИ	1
	SPE	2
	CMP / MON	1/1
	BRC / DPLL	1/1
Timer	GPT12	2
	CCU6	2
STM	Modules	3
FlexRay	Modules	1
-	Channels	2



Table 1-1 Overview of TC27x Functions (cont'd)

Feature		
CAN	Nodes	4
	Message Objects	256
QSPI	Channels	4
ASCLIN	Interfaces	4
I2C	Interfaces	1
SENT	Channels	10
PSI5	Modules	3
PSI5-S	Modules	1
HSSL	Channels	1
MSC	Channels	2
Ethernet	Channels	1
ASIL	Level	up to ASIL-D
FCE	Modules	1
Safety support	SMU	1
	IOM	1
Security	HSM	1
Embedded Voltage Regulator	DCDC from 5 V / 3.3 V to 1.3 V	Yes
Embedded Voltage Regulator	LDO from 5 V / 3.3 V to 1.3 V	Yes
Embedded Voltage Regulator	LDO from 5 V to 3.3 V	Yes
Low Power Feature	Standby RAM	Yes
Packages	Туре	LF-BGA-292-6 / PG-LQFP-176-22
I/O	Туре	5 V CMOS / 3.3 V CMOS / LVDS
T _{ambient}	Range	−40 +125°C

¹⁾ Address range starts at lowest address defined in the User's Manual. For reference see the Memory Maps chapter of the User's Manual.

It is therefore recommended that the upper 64 bytes of any memory be unused for instruction storage.

²⁾ To ensure the processor cores are provided with a constant stream of instructions the Instruction Fetch Units will speculatively fetch instructions from the up to 64 bytes ahead of the current PC. If the current PC is within 64 bytes of the top of an instruction memory the Instruction Fetch Unit may attempt to speculatively fetch instruction from beyond the physical range. This may then lead to error conditions and alarms being triggered by the bus and memory systems.



Package and Pinning Definitions

2 Package and Pinning Definitions

This chapter gives a pinning of the different packages of the TC270 / TC275 / TC277.



2.1 TC275x Pin Definition and Functions: LQFP176

Figure 2-1 is showing the TC275x Logic Symbol for the package variant: QFP176.

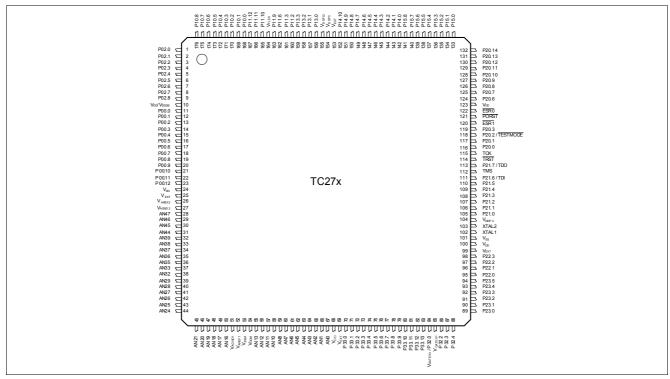


Figure 2-1 TC275x Logic Symbol for the package variant LQFP176.



2.1.1 TC275x LQFP176 Package Variant Pin Configuration'

Table 2-1 Port 00 Functions

Pin	Symbol	Ctrl	Type	Function
11	P00.0	1	MP/	General-purpose input
	TIN9		PU1/	GTM input
	CTRAPA		VEXT	CCU61 input
	T12HRE			CCU60 input
	INJ00			MSC0 input
	CIFD9			CIF input
	P00.0	00		General-purpose output
	TOUT9	O1		GTM output
	ASCLK3	O2		ASCLIN3 output
	ATX3	O3		ASCLIN3 output
	_	O4		Reserved
	TXDCAN1	O5		CAN node 1 output
	_	O6	-	Reserved
	COUT63	O7		CCU60 output
	ETHMDIOA	HWOU T		ETH input/output
2	P00.1	1	LP/	General-purpose input
	TIN10		PU1/	GTM input
	ARX3E		VEXT	ASCLIN3 input
	RXDCAN1D			CAN node 1 input
	PSIRX0A			PSI5 input
	SENT0B			SENT input
	CC60INB			CCU60 input
	CC60INA			CCU61 input
	DSCIN5A			DSADC channel 5 input A
	DS5NA			DSADC negative analog input of channel 5, pin A
	VADCG7.5			VADC analog input channel 5 of group 7
	CIFD10			CIF input
	P00.1	00		General-purpose output
	TOUT10	O1		GTM output
	ATX3	O2		ASCLIN3 output
	_	O3	†	Reserved
	DSCOUT5	O4	1	DSADC channel 5 output
	_	O5	1	Reserved
	SPC0	O6	1	SENT output
	CC60	07	1	CCU61 output

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Table 2-1 Port 00 Functions (cont'd)

Pin	Symbol	Ctrl	Type	Function
13	P00.2	I	LP/	General-purpose input
	TIN11		PU1/	GTM input
	SENT1B		VEXT	SENT input
	DSDIN5A			DSADC channel 5 input A
	DS5PA			DSADC positive analog input of channel 5, pin A
	VADCG7.4			VADC analog input channel 4 of group 7
	CIFD11			CIF input
	P00.2	00		General-purpose output
	TOUT11	01		GTM output
	ASCLK3	O2		ASCLIN3 output
	_	O3		Reserved
	PSITX0	04		PSI5 output
	TXDCAN3	O5		CAN node 3 output
	_	O6		Reserved
	COUT60	07		CCU61 output
14	P00.3	1	LP/	General-purpose input
	TIN12		PU1 /	GTM input
	RXDCAN3A		VEXT	CAN node 3 input
	PSIRX1A			PSI5 input
	PSISRXA			PSI5-S input
	SENT2B			SENT input
	CC61INB			CCU60 input
	CC61INA			CCU61 input
	DSCIN3A			DSADC channel 3 input A
	VADCG7.3			VADC analog input channel 3 of group 7
	DSITR5F			DSADC channel 5 input F
	CIFD12			CIF input
	P00.3	00		General-purpose output
	TOUT12	01		GTM output
	ASLSO3	O2		ASCLIN3 output
		O3		Reserved
	DSCOUT3	O4		DSADC channel 3 output
		O5		Reserved
	SPC2	O6		SENT output
	CC61	O7		CCU61 output

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Table 2-1 Port 00 Functions (cont'd)

Pin	Symbol	Ctrl	Type	Function
15	P00.4	I	LP/	General-purpose input
	TIN13		PU1 /	GTM input
	REQ7		VEXT	SCU input
	SENT3B			SENT input
	DSDIN3A			DSADC channel 3 input A
	DSSGNA			DSADC input
	VADCG7.2			VADC analog input channel 2 of group 7 (MD)
	CIFD13			CIF input
	P00.4	00		General-purpose output
	TOUT13	01		GTM output
	PSISTX	O2		PSI5-S output
	_	О3		Reserved
	PSITX1	04		PSI5 output
	VADCG4BFL0	O5		VADC output
	SPC3	O6		SENT output
	COUT61	07		CCU61 output
16	P00.5	I	LP / PU1 /	General-purpose input
	TIN14			GTM input
	PSIRX2A		VEXT	PSI5 input
	SENT4B			SENT input
	CC62INB			CCU60 input
	CC62INA			CCU61 input
	DSCIN2A			DSADC channel 2 input A
	VADCG7.1			VADC analog input channel 1 of group 7 (MD)
	CIFD14			CIF input
	P00.5	00		General-purpose output
	TOUT14	01		GTM output
	DSCGPWMN	O2		DSADC output
	_	О3		Reserved
	DSCOUT2	04		DSADC channel 2 output
	VADCG4BFL1	O5		VADC output
	SPC4	O6		SENT output
	CC62	07		CCU61 output

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Table 2-1 Port 00 Functions (cont'd)

Pin	Symbol	Ctrl	Type	Function
17	P00.6	I	LP/	General-purpose input
	TIN15		PU1 /	GTM input
	SENT5B		VEXT	SENT input
	DSDIN2A			DSADC channel 2 input A
	VADCG7.0			VADC analog input channel 0 of group 7
	DSITR4F			DSADC channel 4 input F
	CIFD15			CIF input
	P00.6	00		General-purpose output
	TOUT15	01		GTM output
	DSCGPWMP	O2		DSADC output
	VADCG4BFL2	O3		VADC output
	PSITX2	04		PSI5 output
	VADCEMUX10	O5		VADC output
	SPC5	O6		SENT output
	COUT62	07		CCU61 output
18	P00.7	I	LP / PU1 /	General-purpose input
	TIN16			GTM input
	SENT6B		VEXT	SENT input
	CC60INC			CCU61 input
	CCPOS0A			CCU61 input
	T12HRB			CCU60 input
	T2INA			GPT120 input
	DSCIN4A			DSADC channel 4 input A
	DS4NA			DSADC negative analog input of channel 4, pin A
	VADCG6.5			VADC analog input channel 5 of group 6
	CIFCLK			CIF input
	P00.7	00		General-purpose output
	TOUT16	01		GTM output
		O2		Reserved
	VADCG4BFL3	O3		VADC output
	DSCOUT4	04		DSADC channel 4 output
	VADCEMUX11	O5		VADC output
	SPC6	O6		SENT output
	CC60	07		CCU61 output



Table 2-1 Port 00 Functions (cont'd)

Pin	Symbol	Ctrl	Туре	Function
19	P00.8	I	LP/	General-purpose input
	TIN17		PU1/	GTM input
	SENT7B		VEXT	SENT input
	CC61INC			CCU61 input
	CCPOS1A			CCU61 input
	T13HRB			CCU60 input
	T2EUDA			GPT120 input
	DSDIN4A			DSADC channel 4 input A
	DS4PA			DSADC channel 4 input A
	VADCG6.4			VADC analog input channel 4 of group 6
	CIFVSNC			CIF input
	P00.8	00		General-purpose output
	TOUT17	01		GTM output
	SLSO36	O2		QSPI3 output
	_	О3		Reserved
	-	04		Reserved
	VADCEMUX12	O5		VADC output
	SPC7	O6		SENT output
	CC61	07		CCU61 output



Table 2-1 Port 00 Functions (cont'd)

Pin	Symbol	Ctrl	Type	Function
20	P00.9	I	LP/	General-purpose input
	TIN18		PU1/	GTM input
	SENT8B		VEXT	SENT input
	CC62INC			CCU61 input
	CCPOS2A			CCU61 input
	T13HRC			CCU60 input
	T12HRC			CCU60 input
	T4EUDA			GPT120 input
	DSCIN1A			DSADC channel 1 input A
	VADCG6.3			VADC analog input channel 3 of group 6
	DSITR3F			DSADC channel 3 input F
	CIFHSNC			CIF input
	P00.9	00		General-purpose output
	TOUT18	O1		GTM output
	SLSO37	O2		QSPI3 output
	ARTS3	O3		ASCLIN3 output
	DSCOUT1	04		DSADC channel 1 output
		O5		Reserved
	SPC8	O6		SENT output
	CC62	07		CCU61 output
21	P00.10	I	LP/	General-purpose input
	TIN19		PU1/	GTM input
	SENT9B		VEXT	SENT input
	DSDIN1A			DSADC channel 1 input A
	VADCG6.2			VADC analog input channel 2 of group 6 (MD)
	P00.10	00		General-purpose output
	TOUT19	01		GTM output
		O2		Reserved
		O3		Reserved
	_	O4		Reserved
	_	O5		Reserved
	SPC9	06		SENT output
	COUT63	07		CCU61 output

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Table 2-1 Port 00 Functions (cont'd)

Pin	Symbol	Ctrl	Type	Function
22	P00.11	I	LP/	General-purpose input
	TIN20		PU1 /	GTM input
	CTRAPA		VEXT	CCU60 input
	T12HRE			CCU61 input
	DSCIN0A			DSADC channel 0 input A
	VADCG6.1			VADC analog input channel 1 of group 6 (MD)
	P00.11	00		General-purpose output
	TOUT20	O1		GTM output
	_	O2		Reserved
	_	О3		Reserved
	DSCOUT0	O4		DSADC channel 0 output
	_	O5		Reserved
	_	O6		Reserved
	_	07		Reserved
23	P00.12	1	LP / PU1 / VEXT	General-purpose input
	TIN21			GTM input
	ACTS3A			ASCLIN3 input
	DSDIN0A			DSADC channel 0 input A
	VADCG6.0			VADC analog input channel 0 of group 6
	P00.12	00		General-purpose output
	TOUT21	01		GTM output
	_	O2		Reserved
	_	O3		Reserved
	_	O4		Reserved
	_	O5		Reserved
	_	O6		Reserved
	COUT63	O7		CCU61 output

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Table 2-2 Port 02 Functions

Pin	Symbol	Ctrl	Туре	Function
1	P02.0	I	MP+/	General-purpose input
	TIN0		PU1 /	GTM input
	ARX2G		VEXT	ASCLIN2 input
	REQ6			SCU input
	CC60INA			CCU60 input
	CC60INB			CCU61 input
	CIFD0			CIF input
	P02.0	00		General-purpose output
	TOUT0	01		GTM output
	ATX2	O2		ASCLIN2 output
	SLSO31	O3		QSPI3 output
	DSCGPWMN	04		DSADC output
	TXDCAN0	O5		CAN node 0 output
	TXDA	O6		ERAY output
	CC60	07		CCU60 output
2	P02.1	I	LP/PU1	General-purpose input
	TIN1		/ VEXT	GTM input
	REQ14			SCU input
	ARX2B			ASCLIN2 input
	RXDCAN0A			CAN node 0 input
	RXDA2			ERAY input
	CIFD1			CIF input
	P02.1	00		General-purpose output
	TOUT1	01		GTM output
		O2		Reserved
	SLSO32	O3		QSPI3 output
	DSCGPWMP	04		DSADC output
	_	O5		Reserved
	_	O6		Reserved
	COUT60	07		CCU60 output

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Table 2-2 Port 02 Functions (cont'd)

Pin	Symbol	Ctrl	Туре	Function
3	P02.2	I	MP+/	General-purpose input
	TIN2		PU1/	GTM input
	CC61INA		VEXT	CCU60 input
	CC61INB			CCU61 input
	CIFD2			CIF input
	P02.2	00		General-purpose output
	TOUT2	01		GTM output
	ATX1	O2		ASCLIN1 output
	SLSO33	О3		QSPI3 output
	PSITX0	04		PSI5 output
	TXDCAN2	O5		CAN node 2 output
	TXDB	O6		ERAY output
	CC61	07		CCU60 output
4	P02.3	I	LP/	General-purpose input
	TIN3		PU1 / VEXT	GTM input
	ARX1G			ASCLIN1 input
	RXDCAN2B			CAN node 2 input
	RXDB2			ERAY input
	PSIRX0B			PSI5 input
	DSCIN5B			DSADC channel 5 input B
	SDI11			MSC1 input
	CIFD3			CIF input
	P02.3	00		General-purpose output
	TOUT3	01		GTM output
	ASLSO2	O2		ASCLIN2 output
	SLSO34	О3		QSPI3 output
	DSCOUT5	04		DSADC channel 5 output
	_	O5		Reserved
	_	O6		Reserved
	COUT61	07		CCU60 output

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Table 2-2 Port 02 Functions (cont'd)

Pin	Symbol	Ctrl	Туре	Function
5	P02.4	I	MP+/	General-purpose input
	TIN4		PU1 / VEXT	GTM input
	SLSI3A			QSPI3 input
	ECTT1			TTCAN input
	RXDCAN0D			CAN node 0 input
	CC62INA			CCU60 input
	CC62INB			CCU61 input
	DSDIN5B			DSADC channel 5 input B
	SDA0A			I2C0 input
	CIFD4			CIF input
	P02.4	00		General-purpose output
	TOUT4	01		GTM output
	ASCLK2	O2		ASCLIN2 output
	SLSO30	O3		QSPI3 output
	PSISCLK	04		PSI5-S output
	SDA0	O5		I2C0 output
	TXENA	O6		ERAY output
	CC62	07		CCU60 output
6	P02.5	1	MP+/ PU1/ VEXT	General-purpose input
	TIN5			GTM input
	MRST3A			QSPI3 input
	ECTT2			TTCAN input
	PSIRX1B			PSI5 input
	PSISRXB			PSI5-S input
	SENT3C			SENT input
	DSCIN4B			DSADC channel 4 input B
	SCL0A			I2C0 input
	CIFD5			CIF input
	P02.5	00		General-purpose output
	TOUT5	01		GTM output
	TXDCAN0	O2		CAN node 0 output
	MRST3	O3		QSPI3 output
	DSCOUT4	O4		DSADC channel 4 output
	SCL0	O5		I2C0 output
	TXENB	O6		ERAY output
	COUT62	07		CCU60 output

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Table 2-2 Port 02 Functions (cont'd)

Pin	Symbol	Ctrl	Туре	Function
7	P02.6	I	MP/	General-purpose input
	TIN6		PU1/	GTM input
	MTSR3A		VEXT	QSPI3 input
	SENT2C			SENT input
	CC60INC			CCU60 input
	CCPOS0A			CCU60 input
	T12HRB			CCU61 input
	T3INA			GPT120 input
	CIFD6			CIF input
	DSDIN4B			DSADC channel 4 input B
	DSITR5E			DSADC channel 5 input E
	P02.6	00		General-purpose output
	TOUT6	01		GTM output
	PSISTX	O2		PSI5-S output
	MTSR3	О3		QSPI3 output
	PSITX1	O4		PSI5 output
	VADCEMUX00	O5		VADC output
	_	O6		Reserved
	CC60	07		CCU60 output



Table 2-2 Port 02 Functions (cont'd)

Pin	Symbol	Ctrl	Type	Function
8	P02.7	I	MP/	General-purpose input
	TIN7		PU1/	GTM input
	SCLK3A		VEXT	QSPI3 input
	PSIRX2B			PSI5 input
	SENT1C			SENT input
	CC61INC			CCU60 input
	CCPOS1A			CCU60 input
	T13HRB			CCU61 input
	T3EUDA			GPT120 input
	CIFD7			CIF input
	DSCIN3B			DSADC channel 3 input B
	DSITR4E			DSADC channel 4 input E
	P02.7	00		General-purpose output
	TOUT7	01		GTM output
	_	O2		Reserved
	SCLK3	O3		QSPI3 output
	DSCOUT3	04		DSADC channel 3 output
	VADCEMUX01	O5		VADC output
	SPC1	O6		SENT output
	CC61	07		CCU60 output



Table 2-2 Port 02 Functions (cont'd)

Pin	Symbol	Ctrl	Type	Function
9	P02.8	I	LP/PU1	General-purpose input
	TIN8			GTM input
	SENT0C		VEXT	SENT input
	CC62INC			CCU60 input
	CCPOS2A			CCU60 input
	T12HRC			CCU61 input
	T13HRC			CCU61 input
	T4INA			GPT120 input
	CIFD8			CIF input
	DSDIN3B			DSADC channel 3 input B
	DSITR3E			DSADC channel 3 input E
	P02.8	00		General-purpose output
	TOUT8	01		GTM output
	SLSO35	O2		QSPI3 output
		O3		Reserved
	PSITX2	O4		PSI5 output
	VADCEMUX02	O5		VADC output
	ETHMDC	O6		ETH output
	CC62	07		CCU60 output

Table 2-3 Port 10 Functions

Pin	Symbol	Ctrl	Туре	Function
168	P10.0	I	LP/	General-purpose input
	TIN102		PU1/	GTM input
	T6EUDB		VEXT	GPT120 input
	P10.0	00		General-purpose output
	TOUT102	01		GTM output
	_	O2		Reserved
	SLSO110	O3		QSPI1 output
	_	04		Reserved
	VADCG6BFL0	O5		VADC output
	_	O6		Reserved
	_	07		Reserved

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Table 2-3 Port 10 Functions (cont'd)

Pin	Symbol	Ctrl	Type	Function
169	P10.1	I	MP+/	General-purpose input
	TIN103		PU1/	GTM input
	MRST1A		VEXT	QSPI1 input
	T5EUDB			GPT120 input
	P10.1	00		General-purpose output
	TOUT103	01		GTM output
	MTSR1	O2		QSPI1 output
	MRST1	О3		QSPI1 output
	EN01	04		MSC0 output
	VADCG6BFL1	O5		VADC output
	END03	O6		MSC0 output
	_	07		Reserved
170	P10.2	1	MP / PU1 /	General-purpose input
	TIN104			GTM input
	SCLK1A		VEXT	QSPI1 input
	T6INB			GPT120 input
	REQ2			SCU input
	RXDCAN2E			CAN node 2 input
	SDI01			MSC0 input
	P10.2	00		General-purpose output
	TOUT104	01		GTM output
	_	O2		Reserved
	SCLK1	O3		QSPI1 output
	EN00	04		MSC0 output
	VADCG6BFL2	O5		VADC output
	END02	O6		MSC0 output
		07		Reserved



Table 2-3 Port 10 Functions (cont'd)

Pin	Symbol	Ctrl	Type	Function
171	P10.3	I	MP/	General-purpose input
	TIN105		PU1/	GTM input
	MTSR1A		VEXT	QSPI1 input
	REQ3			SCU input
	T5INB			GPT120 input
	P10.3	00		General-purpose output
	TOUT105	01		GTM output
	VADCG6BFL3	O2		VADC output
	MTSR1	О3		QSPI1 output
	EN00	04		MSC0 output
	END02	O5		MSC0 output
	TXDCAN2	O6		CAN node 2 output
		07		Reserved
172	P10.4	I	MP+/	General-purpose input
	TIN106		PU1 /	GTM input
	MTSR1C		VEXT	QSPI1 input
	CCPOS0C			CCU60 input
	T3INB			GPT120 input
	P10.4	00		General-purpose output
	TOUT106	01		GTM output
	_	O2		Reserved
	SLSO18	O3		QSPI1 output
	MTSR1	04		QSPI1 output
	EN00	O5		MSC0 output
	END02	06		MSC0 output
	_	07		Reserved
173	P10.5	I	LP/	General-purpose input
	TIN107		PU1 /	GTM input
	HWCFG4		VEXT	SCU input
	INJ01			MSC0 input
	P10.5	00		General-purpose output
	TOUT107	01		GTM output
	ATX2	O2		ASCLIN2 output
	SLSO38	О3		QSPI3 output
	SLSO19	04		QSPI1 output
	T6OUT	O5		GPT120 output
	ASLSO2	O6		ASCLIN2 output
	_	07		Reserved



Table 2-3 Port 10 Functions (cont'd)

Pin	Symbol	Ctrl	Type	Function
174	P10.6	I	LP/	General-purpose input
	TIN108		PU1/	GTM input
	ARX2D		VEXT	ASCLIN2 input
	MTSR3B			QSPI3 input
	HWCFG5			SCU input
	P10.6	00		General-purpose output
	TOUT108	01		GTM output
	ASCLK2	O2		ASCLIN2 output
	MTSR3	О3		QSPI3 output
	T3OUT	04		GPT120 output
	-	O5		Reserved
	MRST1	O6		QSPI1 output
	VADCG7BFL0	07		VADC output
175	P10.7	I	LP/	General-purpose input
	TIN109		PU1/	GTM input
	ACTS2A		VEXT	ASCLIN2 input
	MRST3B			QSPI3 input
	REQ4			SCU input
	CCPOS1C			CCU60 input
	T3EUDB			GPT120 input
	P10.7	00		General-purpose output
	TOUT109	01		GTM output
	_	O2		Reserved
	MRST3	О3		QSPI3 output
	VADCG7BFL1	04		VADC output
	_	O5		Reserved
	_	O6		Reserved
		07		Reserved

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Table 2-3 Port 10 Functions (cont'd)

Pin	Symbol	Ctrl	Туре	Function
176	P10.8	1	LP/	General-purpose input
	TIN110		PU1/	GTM input
	SCLK3B		VEXT	QSPI3 input
	REQ5			SCU input
	CCPOS2C			CCU60 input
	T4INB			GPT120 input
	P10.8	00		General-purpose output
	TOUT110	O1		GTM output
	ARTS2	O2		ASCLIN2 output
	SCLK3	О3		QSPI3 output
		O4		Reserved
		O5		Reserved
		O6		Reserved
		07		Reserved

Table 2-4 Port 11 Functions

Pin	Symbol	Ctrl	Type	Function
160	P11.2	1	MPR/	General-purpose input
	TIN95		PU1/	GTM input
	P11.2	00	VFLEX	General-purpose output
	TOUT95	01		GTM output
	END03	O2		MSC0 output
	SLSO05	О3		QSPI0 output
	SLSO15	04		QSPI1 output
	EN01	O5		MSC0 output
	ETHTXD1	O6		ETH output
	COUT63	07		CCU60 output

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Table 2-4 Port 11 Functions (cont'd)

Pin	Symbol	Ctrl	Type	Function
161	P11.3	I	MPR/	General-purpose input
	TIN96		PU1 /	GTM input
	MRST1B		VFLEX	QSPI1 input
	SDI03			MSC0 input
	P11.3	00		General-purpose output
	TOUT96	01		GTM output
		O2		Reserved
	MRST1	O3		QSPI1 output
	TXDA	04		ERAY output
		O5		Reserved
	ETHTXD0	O6		ETH output
	COUT62	07		CCU60 output
162	P11.6	I	MPR/	General-purpose input
	TIN97		PU1 /	GTM input
	SCLK1B		VFLEX	QSPI1 input
	P11.6	00		General-purpose output
	TOUT97	01		GTM output
	TXENB	O2		ERAY output
	SCLK1	O3		QSPI1 output
	TXENA	O4		ERAY output
	FCLP0	O5		MSC0 output
	ETHTXEN	O6		ETH output
	COUT61	07		CCU60 output
163	P11.9 I MP+/	General-purpose input		
	TIN98		PU1 /	GTM input
	MTSR1B		VFLEX	QSPI1 input
	RXDA1			ERAY input
	ETHRXD1			ETH input
	P11.9	00		General-purpose output
	TOUT98	01		GTM output
	_	O2		Reserved
	MTSR1	O3		QSPI1 output
	_	O4		Reserved
	SOP0	O5		MSC0 output
		O6		Reserved
	COUT60	07		CCU60 output



Table 2-4 Port 11 Functions (cont'd)

Pin	Symbol	Ctrl	Type	Function
165	P11.10	I	LP/	General-purpose input
	TIN99		PU1 /	GTM input
	REQ12		VFLEX	SCU input
	ARX1E			ASCLIN1 input
	SLSI1A			QSPI1 input
	RXDCAN3D			CAN node 3 input
	RXDB1			ERAY input
	ETHRXD0			ETH input
	SDI00			MSC0 input
	P11.10	00		General-purpose output
	TOUT99	01		GTM output
	_	O2		Reserved
	SLSO03	О3		QSPI0 output
	SLSO13	04		QSPI1 output
	_	O5		Reserved
	_	O6		Reserved
	CC62	07		CCU60 output
166	P11.11	I	MP+/	General-purpose input
	TIN100		PU1 /	GTM input
	ETHCRSDVA		VFLEX	ETH input
	ETHRXDVA			ETH input
	ETHCRSB			ETH input
	P11.11	00		General-purpose output
	TOUT100	01		GTM output
	END02	O2		MSC0 output
	SLSO04	О3		QSPI0 output
	SLSO14	04		QSPI1 output
	EN00	O5		MSC0 output
	TXENB	O6		ERAY output
	CC61	07		CCU60 output



Table 2-4 Port 11 Functions (cont'd)

Pin	Symbol	Ctrl	Туре	Function	_
167	P11.12	I	MPR/	General-purpose input	_
	* * * * * * * * * * * * * * * * * * * *	GTM input	_		
	ETHREFCLK		VFLEX	ETH input	_
	ETHTXCLKB			ETH input (Not for productive purposes)	_
	ETHRXCLKA			ETH input (Not for productive purposes)	_
	P11.12	00		General-purpose output	
	TOUT101	01		GTM output	
	ATX1	O2		ASCLIN1 output	
	GTMCLK2	О3		GTM output	
	TXDB	04		ERAY output	_
	TXDCAN3	O5		CAN node 3 output	_
	EXTCLK1	O6		SCU output	_
	CC60	07		CCU60 output	_

Table 2-5 Port 13 Functions

Pin	Symbol	Ctrl	Type	Function
156	P13.0	I	LVDSM_N /	General-purpose input
	TIN91			GTM input
	P13.0	00	VEXT	General-purpose output
	TOUT91	01		GTM output
	END03	O2		MSC0 output
	SCLK2N	O3		QSPI2 output (LVDS)
	EN01	04		MSC0 output
	FCLN0	O5		MSC0 output (LVDS)
	FCLND0	O6		MSC0 output (LVDS)
	_	07		Reserved
157	P13.1	I	LVDSM_P / PU1 / VEXT	General-purpose input
	TIN92			GTM input
	SCL0B		PU1 /	I2C0 input
	P13.1	00		General-purpose output
	TOUT92	O1		GTM output
		O2		Reserved
	SCLK2P	O3		QSPI2 output (LVDS)
	_	O4		Reserved
	FCLP0	O5		MSC0 output (LVDS)
	SCL0	O6		I2C0 output
	_	07		Reserved

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Table 2-5 Port 13 Functions (cont'd)

Pin	Symbol	Ctrl	Туре	Function	
158	P13.2	I	LVDSM_N /	General-purpose input	
	P13.2	GTM input			
	CAPINA		VEXT	GPT120 input	
	SDA0B			I2C0 input	
	P13.2	00		General-purpose output	
	TOUT93	01		GTM output	
	_	O2		Reserved	
	MTSR2N	O3		QSPI2 output (LVDS)	
	FCLP0	04		MSC0 output	
	SON0	O5		MSC0 output (LVDS)	
	SDA0	O6		I2C0 output	
	SOND0 O7	MSC0 output (LVDS)			
159	P13.3	I	PU1 / VEXT	General-purpose input	
	TIN94			GTM input	
	P13.3	00		General-purpose output	
	TOUT94	01		GTM output	
	_	O2		Reserved	
	MTSR2P	O3		QSPI2 output (LVDS)	
	_	04		Reserved	
	SOP0	O5		MSC0 output (LVDS)	
	_	O6		Reserved	
	_	07		Reserved	

Table 2-6 Port 14 Functions

Pin	Symbol	Ctrl	Type	Function
142	P14.0	I	MP+/	General-purpose input
	TIN80		PU1 /	GTM input
	P14.0	00	VEXT	General-purpose output
	TOUT80	01		GTM output
	ATX0	O2		ASCLIN0 output
				Recommended as Boot loader pin.
	TXDA	O3		ERAY output
	TXDB	O4		ERAY output
	TXDCAN1	O5		CAN node 1 output
				Used for single pin DAP (SPD) function.
	ASCLK0	O6		ASCLIN0 output
	COUT62	O7		CCU60 output

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Table 2-6 Port 14 Functions (cont'd)

Pin	Symbol	Ctrl	Type	Function
143	P14.1	I	MP/	General-purpose input
	TIN81		PU1/	GTM input
	REQ15		VEXT	SCU input
	ARX0A			ASCLIN0 input
				Recommended as Boot loader pin.
	RXDCAN1B			CAN node 1 input Used for single pin DAP (SPD) function.
	RXDA3			ERAY input
	RXDB3			ERAY input
	EVRWUPA			SCU input
	P14.1	00		General-purpose output
	TOUT81	01		GTM output
	ATX0	O2		ASCLIN0 output
		O3		Reserved
	_	04		Reserved
	_	O5		Reserved
	_	O6		Reserved
	COUT63	07		CCU60 output
144	P14.2	I	LP/	General-purpose input
	TIN82		PU1 /	GTM input
	HWCFG2 EVR13		VEXT	SCU input Latched at cold power on reset to decide EVR13 activation.
	P14.2	00		General-purpose output
	TOUT82	01		GTM output
	ATX2	O2		ASCLIN2 output
	SLSO21	O3		QSPI2 output
	_	04		Reserved
	_	O5		Reserved
	ASCLK2	O6		ASCLIN2 output
	_	07		Reserved

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Table 2-6 Port 14 Functions (cont'd)

Pin	Symbol	Ctrl	Type	Function
145	P14.3	I	LP/	General-purpose input
	TIN83		PU1 /	GTM input
	ARX2A		VEXT	ASCLIN2 input
	REQ10			SCU input
	HWCFG3_BMI			SCU input
	SDI02			MSC0 input
	P14.3	00		General-purpose output
	TOUT83	01		GTM output
	ATX2	O2		ASCLIN2 output
	SLSO23	О3		QSPI2 output
	ASLSO1	04		ASCLIN1 output
	ASLSO3	O5		ASCLIN3 output
	_	O6		Reserved
	_	07		Reserved
146	P14.4	I	LP/	General-purpose input
	TIN84		PU1 /	GTM input
	HWCFG6		VEXT	SCU input Latched at cold power on reset to decide default pad reset state (PU or HighZ).
	P14.4	00		General-purpose output
	TOUT84	01		GTM output
	_	O2		Reserved
	_	O3		Reserved
	_	O4		Reserved
	_	O5		Reserved
		O6		Reserved
		07		Reserved



Table 2-6 Port 14 Functions (cont'd)

Pin	Symbol	Ctrl	Туре	Function
147	P14.5	I	MP+/	General-purpose input
	TIN85		PU1 /	GTM input
	HWCFG1		VEXT	SCU input
	EVR33			Latched at cold power on reset to decide EVR33
				activation.
	P14.5	00		General-purpose output
	TOUT85	01		GTM output
	_	O2		Reserved
	_	O3		Reserved
	_	04		Reserved
	_	O5		Reserved
	TXDB	O6		ERAY output
	_	07		Reserved
148	P14.6	1	MP+/	General-purpose input
	TIN86		PU1 / VEXT	GTM input
	HWCFG0			SCU input
	DCLDO			If EVR13 active, latched at cold power on reset to
	244.0			decide between LDO and SMPS mode.
	P14.6	00		General-purpose output
	TOUT86	01		GTM output
	_	O2		Reserved
	SLSO22	O3		QSPI2 output
	_	04		Reserved
	_	O5		Reserved
	TXENB	O6		ERAY output
	_	07		Reserved
149	P14.7	1	LP /	General-purpose input
	TIN87		PU1 /	GTM input
	RXDB0		VEXT	ERAY input
	P14.7	00		General-purpose output
	TOUT87	01		GTM output
	ARTS0	O2		ASCLIN0 output
	SLSO24	O3		QSPI2 output
	_	04		Reserved
	_	O5		Reserved
	_	O6		Reserved
	_	07		Reserved



Table 2-6 Port 14 Functions (cont'd)

Pin	Symbol	Ctrl	Type	Function
150	P14.8	I	LP/	General-purpose input
	TIN88		PU1/	GTM input
	ARX1D		VEXT	ASCLIN1 input
	RXDCAN2D			CAN node 2 input
	RXDA0			ERAY input
	P14.8	00		General-purpose output
	TOUT88	01		GTM output
	_	O2		Reserved
	_	O3		Reserved
	_	04		Reserved
	_	O5		Reserved
	_	O6		Reserved
	_	07		Reserved
151	P14.9	I	MP+/	General-purpose input
	TIN89		PU1/	GTM input
	ACTS0A		VEXT	ASCLIN0 input
	P14.9	00		General-purpose output
	TOUT89	01		GTM output
	END03	O2		MSC0 output
	EN01	O3		MSC0 output
	_	04		Reserved
	TXENB	O5		ERAY output
	TXENA	O6		ERAY output
	_	07		Reserved
152	P14.10	I	MP+/	General-purpose input
	TIN90		PU1 /	GTM input
	P14.10	00	VEXT	General-purpose output
	TOUT90	01		GTM output
	END02	O2		MSC0 output
	EN00	O3		MSC0 output
	ATX1	04		ASCLIN1 output
	TXDCAN2	O5		CAN node 2 output
	TXDA	O6		ERAY output
	_	07		Reserved



Table 2-7 Port 15 Functions

Pin	Symbol	Ctrl	Type	Function
133	P15.0	I	LP/	General-purpose input
	TIN71		PU1/	GTM input
	P15.0	00	VEXT	General-purpose output
	TOUT71	01		GTM output
	ATX1	O2		ASCLIN1 output
	SLSO013	O3		QSPI0 output
		O4		Reserved
	TXDCAN2	O5		CAN node 2 output
	ASCLK1	O6		ASCLIN1 output
		07		Reserved
134	P15.1	I	LP/	General-purpose input
	TIN72		PU1/	GTM input
	REQ16		VEXT	SCU input
	ARX1A			ASCLIN1 input
	RXDCAN2A			CAN node 2 input
	SLSI2B			QSPI2 input
	EVRWUPB			SCU input
	P15.1	00		General-purpose output
	TOUT72	01		GTM output
	ATX1	O2		ASCLIN1 output
	SLSO25	O3		QSPI2 output
		04		Reserved
		O5		Reserved
		O6		Reserved
		07		Reserved
135	P15.2	I	MP/	General-purpose input
	TIN73		PU1/	GTM input
	SLSI2A		VEXT	QSPI2 input
	MRST2E			QSPI2 input
	P15.2	00		General-purpose output
	TOUT73	01		GTM output
	ATX0	O2		ASCLIN0 output
	SLSO20	O3		QSPI2 output
		04		Reserved
	TXDCAN1	O5		CAN node 1 output
	ASCLK0	O6		ASCLIN0 output
		07		Reserved



Table 2-7 Port 15 Functions (cont'd)

Pin	Symbol	Ctrl	Type	Function
136	P15.3	I	MP/	General-purpose input
	TIN74		PU1 /	GTM input
	ARX0B		VEXT	ASCLIN0 input
	SCLK2A			QSPI2 input
	RXDCAN1A			CAN node 1 input
	P15.3	00		General-purpose output
	TOUT74	01		GTM output
	ATX0	O2		ASCLIN0 output
	SCLK2	O3		QSPI2 output
	END03	04		MSC0 output
	EN01	O5		MSC0 output
		O6		Reserved
	_	07		Reserved
137	P15.4	I	MP/	General-purpose input
	TIN75		PU1/	GTM input
	MRST2A		VEXT	QSPI2 input
	REQ0			SCU input
	SCL0C			I2C0 input
	P15.4	00		General-purpose output
	TOUT75	01		GTM output
	ATX1	02		ASCLIN1 output
	MRST2	O3		QSPI2 output
		04		Reserved
		O5		Reserved
	SCL0	O6		I2C0 output
	CC62	O7		CCU60 output

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Table 2-7 Port 15 Functions (cont'd)

Pin	Symbol	Ctrl	Type	Function
138	P15.5	1	MP/	General-purpose input
	TIN76		PU1 /	GTM input
	ARX1B		VEXT	ASCLIN1 input
	MTSR2A			QSPI2 input
	REQ13			SCU input
	SDA0C			I2C0 input
	P15.5	O0		General-purpose output
	TOUT76	O1		GTM output
	ATX1	O2		ASCLIN1 output
	MTSR2	O3		QSPI2 output
	END02	O4		MSC0 output
	EN00	O5		MSC0 output
	SDA0	O6		I2C0 output
	CC61	O7		CCU60 output
139	P15.6	I	MP/	General-purpose input
	TIN77		PU1/	GTM input
	MTSR2B		VEXT	QSPI2 input
	P15.6	O0		General-purpose output
	TOUT77	O1		GTM output
	ATX3	O2		ASCLIN3 output
	MTSR2	O3		QSPI2 output
	_	O4		Reserved
	SCLK2	O5		QSPI2 output
	ASCLK3	O6		ASCLIN3 output
	CC60	O7		CCU60 output
140	P15.7	I	MP/	General-purpose input
	TIN78		PU1 /	GTM input
	ARX3A		VEXT	ASCLIN3 input
	MRST2B			QSPI2 input
	P15.7	00		General-purpose output
	TOUT78	O1		GTM output
	ATX3	O2		ASCLIN3 output
	MRST2	O3		QSPI2 output
	_	04		Reserved
	_	O5		Reserved
	_	O6		Reserved
	COUT60	07		CCU60 output



Table 2-7 Port 15 Functions (cont'd)

Pin	Symbol	Ctrl	Туре	Function
141	P15.8	1	MP/	General-purpose input
	TIN79		PU1 /	GTM input
	SCLK2B		VEXT	QSPI2 input
	REQ1			SCU input
	P15.8	00		General-purpose output
	TOUT79	01		GTM output
	_	O2		Reserved
	SCLK2	O3		QSPI2 output
	_	O4		Reserved
	_	O5		Reserved
	ASCLK3	O6		ASCLIN3 output
	COUT61	O7		CCU60 output

Table 2-8 Port 20 Functions

Pin	Symbol	Ctrl	Type	Function
116	P20.0	1	MP/	General-purpose input
	TIN59		PU1/	GTM input
	RXDCAN3C		VEXT	CAN node 3 input
	T6EUDA			GPT120 input
	REQ9			SCU input
	SYSCLK			HSCT input
	TGI0			OCDS input
	P20.0	00		General-purpose output
	TOUT59	O1		GTM output
	ATX3	O2		ASCLIN3 output
	ASCLK3	O3		ASCLIN3 output
	_	O4		Reserved
	SYSCLK	O5		HSCT output
	_	O6		Reserved
	_	O7		Reserved
	TGO0	HWOU T		OCDS; ENx

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Table 2-8 Port 20 Functions (cont'd)

Pin	Symbol	Ctrl	Type	Function
117	P20.1	I	LP/	General-purpose input
	TIN60		PU1/	GTM input
	TGI1		VEXT	OCDS input
	P20.1	00		General-purpose output
	TOUT60	O1		GTM output
	_	O2	1	Reserved
	_	О3		Reserved
	_	O4		Reserved
	_	O5		Reserved
	_	O6		Reserved
	_	07		Reserved
	TGO1	HWOU T		OCDS; ENx
118	P20.2	I	LP / PU / VEXT	General-purpose input This pin is latched at power on reset release to enter test mode.
	TESTMODE			OCDS input
	P20.2	00		Output function not available
	_	01		Output function not available
	_	O2		Output function not available
	_	O3		Output function not available
		O4		Output function not available
		O5		Output function not available
		O6		Output function not available
	_	O7		Output function not available
119	P20.3	I	LP/	General-purpose input
	TIN61		PU1/	GTM input
	T6INA		VEXT	GPT120 input
	ARX3C			ASCLIN3 input
	P20.3	00		General-purpose output
	TOUT61	O1		GTM output
	ATX3	O2		ASCLIN3 output
	SLSO09	О3		QSPI0 output
	SLSO29	04		QSPI2 output
	TXDCAN3	O5		CAN node 3 output
	_	O6		Reserved
	_	07		Reserved



Table 2-8 Port 20 Functions (cont'd)

Pin	Symbol	Ctrl	Type	Function
124	P20.6	I	LP/	General-purpose input
	TIN62		PU1 /	GTM input
	P20.6	00	VEXT	General-purpose output
	TOUT62	01		GTM output
	ARTS1	O2		ASCLIN1 output
	SLSO08	O3		QSPI0 output
	SLSO28	O4		QSPI2 output
	_	O5		Reserved
	WDT2LCK	O6		SCU output
	_	07		Reserved
25	P20.7 I LP /	General-purpose input		
	TIN63		PU1 /	GTM input
	ACTS1A		VEXT	ASCLIN1 input
	RXDCAN0B			CAN node 0 input
	P20.7	00		General-purpose output
	TOUT63	01		GTM output
	_	O2		Reserved
	_	O3		Reserved
	_	O4		Reserved
	_	O5		Reserved
	WDT1LCK	O6		SCU output
	COUT63	07		CCU61 output
26	P20.8	I	MP/	General-purpose input
	TIN64		PU1 /	GTM input
	P20.8	00	VEXT	General-purpose output
	TOUT64	01		GTM output
	ASLSO1	O2		ASCLIN1 output
	SLSO00	O3		QSPI0 output
	SLSO10	O4		QSPI1 output
	TXDCAN0	O5		CAN node 0 output
	WDT0LCK	O6		SCU output
	CC60	07		CCU61 output



Table 2-8 Port 20 Functions (cont'd)

Pin	Symbol	Ctrl	Type	Function
127	P20.9	I	LP/	General-purpose input
	TIN65		PU1 /	GTM input
	ARX1C		VEXT	ASCLIN1 input
	RXDCAN3E			CAN node 3 input
	REQ11			SCU input
	SLSI0B			QSPI0 input
	P20.9	00		General-purpose output
	TOUT65	01		GTM output
	_	O2		Reserved
	SLSO01	O3		QSPI0 output
	SLSO11	04		QSPI1 output
	_	O5		Reserved
	WDTSLCK	O6		SCU output
	CC61	07		CCU61 output
128	P20.10 I	I	MP / PU1 / VEXT	General-purpose input
	TIN66			GTM input
	P20.10	00		General-purpose output
	TOUT66	01		GTM output
	ATX1	O2		ASCLIN1 output
	SLSO06	O3		QSPI0 output
	SLSO27	04		QSPI2 output
	TXDCAN3	O5		CAN node 3 output
	ASCLK1	O6		ASCLIN1 output
	CC62	07		CCU61 output
129	P20.11	I	MP/	General-purpose input
	TIN67		PU1/	GTM input
	SCLK0A		VEXT	QSPI0 input
	P20.11	00		General-purpose output
	TOUT67	01		GTM output
	_	O2		Reserved
	SCLK0	O3		QSPI0 output
	_	04		Reserved
	_	O5		Reserved
	_	O6		Reserved
	COUT60	07		CCU61 output



Table 2-8 Port 20 Functions (cont'd)

Pin	Symbol	Ctrl	Type	Function
130	P20.12	1	MP/	General-purpose input
	TIN68		PU1 /	GTM input
	MRST0A		VEXT	QSPI0 input
	P20.12	00		General-purpose output
	TOUT68	O1		GTM output
		O2		Reserved
	MRST0	O3		QSPI0 output
	MTSR0	O4		QSPI0 output
		O5		Reserved
		O6		Reserved
	COUT61	07		CCU61 output
131	P20.13	I	MP/	General-purpose input
	TIN69		PU1 / VEXT	GTM input
	SLSI0A			QSPI0 input
	P20.13	00		General-purpose output
	TOUT69	01		GTM output
		O2		Reserved
	SLSO02	O3		QSPI0 output
	SLSO12	04		QSPI1 output
	SCLK0	O5		QSPI0 output
	_	O6		Reserved
	COUT62	07		CCU61 output
132	P20.14	I	MP/	General-purpose input
	TIN70		PU1 /	GTM input
	MTSR0A		VEXT	QSPI0 input
	P20.14	00		General-purpose output
	TOUT70	O1		GTM output
		O2		Reserved
	MTSR0	O3		QSPI0 output
		O4		Reserved
		O5		Reserved
		O6		Reserved
	_	07		Reserved

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Table 2-9 Port 21 Functions

Pin	Symbol	Ctrl	Туре	Function
105	P21.0	I	A2 /	General-purpose input
	TIN51		PU1 /	GTM input
	P21.0	00	VDDP3	General-purpose output
	TOUT51	01		GTM output
	_	O2		Reserved
	_	O3		Reserved
	_	O4		Reserved
	_	O5		Reserved
	ETHMDC	O6		ETH output
	_	O7		Reserved
	HSM1	HWOU T		HSM output 1
106	P21.1	I	A2 / PU1 / VDDP3	General-purpose input
	TIN52			GTM input
	ETHMDIOB			ETH input (Not for production purposes)
	P21.1	00		General-purpose output
	TOUT52	01		GTM output
	_	O2		Reserved
	_	O3		Reserved
	_	O4		Reserved
	_	O5		Reserved
	ETHMDIO	O6		ETH output (Not for production purposes)
	_	07		Reserved
	HSM2	HWOU T		HSM output 2



Table 2-9 Port 21 Functions (cont'd)

Pin	Symbol	Ctrl	Туре	Function
107	P21.2	I	LVDSH_N/	General-purpose input
	TIN53		PU1 /	GTM input
	MRST2CN		VDDP3	QSPI2 input (LVDS)
	MRST3FN			QSPI3 input (LVDS)
	ARX3GN			ASCLIN3 input (LVDS)
	EMGSTOPB			SCU input
	RXDN			HSCT input (LVDS)
	P21.2	00		General-purpose output
	TOUT53	O1		GTM output
	ASLSO3	O2		ASCLIN3 output
	_	О3		Reserved
	_	O4		Reserved
	ETHMDC	O5		ETH output
	_	O6		Reserved
	_	O7		Reserved
08	P21.3	I	LVDSH_P/ PU1 / VDDP3	General-purpose input
	TIN54			GTM input
	MRST2CP			QSPI2 input (LVDS)
	MRST3FP			QSPI3 input (LVDS)
	ARX3GP			ASCLIN3 input (LVDS)
	RXDP			HSCT input (LVDS)
	P21.3	00		General-purpose output
	TOUT54	O1		GTM output
	_	O2		Reserved
	_	О3		Reserved
	_	O4		Reserved
	_	O5		Reserved
	_	O6		Reserved
	_	07		Reserved
	ETHMDIOD	HWOU T		ETH input/output

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Table 2-9 Port 21 Functions (cont'd)

Pin	Symbol	Ctrl	Туре	Function
109	P21.4	I	LVDSH_N/	General-purpose input
	TIN55		PU1 /	GTM input
	P21.4	00	VDDP3	General-purpose output
	TOUT55	01		GTM output
	_	O2		Reserved
	_	O3		Reserved
	_	O4		Reserved
		O5		Reserved
	_	O6		Reserved
		07		Reserved
	TXDN	HSCT		HSCT output (LVDS)
110	P21.5	I	LVDSH_P/	General-purpose input
	TIN56		PU1 /	GTM input
	P21.5	00	VDDP3	General-purpose output
	TOUT56	01		GTM output
	ASCLK3	O2		ASCLIN3 output
	_	O3		Reserved
		O4		Reserved
		O5		Reserved
		O6		Reserved
	_	07		Reserved
	TXDP	HSCT		HSCT output (LVDS)
111 ¹⁾	P21.6	I	A2 /	General-purpose input
	TIN57		PU/	GTM input
	ARX3F		VDDP3	ASCLIN3 input
	TGI2			OCDS input
	TDI			OCDS (JTAG) input
	T5EUDA			GPT120 input
	P21.6	00		General-purpose output
	TOUT57	01		GTM output
	ASLSO3	O2		ASCLIN3 output
		О3		Reserved
		04	_	Reserved
	SYSCLK	O5		HSCT output
		O6		Reserved
	T3OUT	07		GPT120 output
	TGO2	HWOU		OCDS; ENx
		Т		

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Table 2-9 Port 21 Functions (cont'd)

Pin	Symbol	Ctrl	Type	Function
113	P21.7	1	A2 /	General-purpose input
	TIN58		PU / VDDP3	GTM input
	DAP2			OCDS input
	TGI3			OCDS input
	TDO			OCDS (JTAG) input The JTAG TDO function is overlayed with P21.7 via a double bond. In JTAG mode this pin is used as TDO, after power-on reset it is HighZ. In DAP mode this pin is used as P21.7 and controlled by the related port control logic
	ETHRXERB			ETH input
	T5INA			GPT120 input
	P21.7	00		General-purpose output
	TOUT58	O1		GTM output
	ATX3	O2		ASCLIN3 output
	ASCLK3	О3		ASCLIN3 output
	_	O4		Reserved
	_	O5		Reserved
	_	O6		Reserved
	T6OUT	O7		GPT120 output
	TGO3	HWOU		OCDS; ENx
	TDO	T		OCDS (JTAG); ENx The JTAG TDO function is overlayed with P21.7 via a double bond. In JTAG mode this pin is used as TDO, after power-on reset it is HighZ. In DAP mode this pin is used as P21.7 and controlled by the related port control logic

¹⁾ For an Emulation Device in a non Fusion Quad package this pin is used as VDDPSB (3.3V)

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Table 2-10 Port 22 Functions

Pin	Symbol	Ctrl	Туре	Function	
95	P22.0	I	LVDSM_N /	General-purpose input	
	TIN47		PU1 /	GTM input	
	MTSR3E		VEXT	QSPI3 input	
	P22.0	00		General-purpose output	
	TOUT47	01		GTM output	
	ATX3N	O2		ASCLIN3 output (LVDS)	
	MTSR3	O3		QSPI3 output	
	SCLK3N	04		QSPI3 output (LVDS)	
	FCLN1	O5		MSC1 output (LVDS)	
	FCLND1	O6		MSC1 output (LVDS)	
	_	07		Reserved	
96	P22.1	I	LVDSM_P/	General-purpose input	
	TIN48		PU1 / VEXT	GTM input	
	MRST3E			QSPI3 input	
	P22.1	00		General-purpose output	
	TOUT48	01		GTM output	
	ATX3P	O2		ASCLIN3 output (LVDS)	
	MRST3	О3		QSPI3 output	
	SCLK3P	04		QSPI3 output (LVDS)	
	FCLP1	O5		MSC1 output (LVDS)	
	_	O6		Reserved	
		07		Reserved	
7	P22.2	I	LVDSM_N /	General-purpose input	
	TIN49		PU1 /	GTM input	
	SLSI3D		VEXT	QSPI3 input	
	P22.2	00		General-purpose output	
	TOUT49	01		GTM output	
	_	02		Reserved	
	SLSO312	O3		QSPI3 output	
	MTSR3N	04		QSPI3 output (LVDS)	
	SON1	O5		MSC1 output (LVDS)	
	SOND1	O6		MSC1 output (LVDS)	
		07		Reserved	



Table 2-10 Port 22 Functions (cont'd)

Pin	Symbol	Ctrl	Туре	Function	
98	P22.3	I	LVDSM_P/	General-purpose input	
	TIN50		PU1 /	GTM input	
	SCLK3E		VEXT	QSPI3 input	
	P22.3	00		General-purpose output	
	TOUT50	O1		GTM output	
	_	O2		Reserved	
	SCLK3	О3		QSPI3 output	
	MTSR3P	O4		QSPI3 output (LVDS)	
	SOP1	O5		MSC1 output (LVDS)	
	_	O6		Reserved	
	_	07		Reserved	

Table 2-11 Port 23 Functions

Pin	Symbol	Ctrl	Type	Function
89	P23.0	I	LP/	General-purpose input
	TIN41		PU1/	GTM input
	P23.0	00	VEXT	General-purpose output
	TOUT41	01		GTM output
	_	O2		Reserved
	_	O3		Reserved
	_	04		Reserved
	_	O5		Reserved
	_	O6		Reserved
	_	07		Reserved
90	P23.1	I	MP+/ PU1/	General-purpose input
	TIN42			GTM input
	SDI10		VEXT	MSC1 input
	P23.1	00		General-purpose output
	TOUT42	01		GTM output
	ARTS1	O2		ASCLIN1 output
	SLSO313	О3		QSPI3 output
	GTMCLK0	04		GTM output
		O5		Reserved
	EXTCLK0	O6		SCU output
	_	07		Reserved

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Table 2-11 Port 23 Functions (cont'd)

Pin	Symbol	Ctrl	Type	Function
91	P23.2	I	LP/	General-purpose input
	TIN43		PU1/	GTM input
	P23.2	00	VEXT	General-purpose output
	TOUT43	O1		GTM output
		O2		Reserved
		О3		Reserved
	_	04		Reserved
		O5		Reserved
	_	O6		Reserved
	_	07		Reserved
92	P23.3	I	LP/	General-purpose input
	TIN44		PU1/	GTM input
	INJ10		VEXT	MSC1 input
	P23.3	00		General-purpose output
	TOUT44	01		GTM output
		O2		Reserved
		O3		Reserved
		04		Reserved
		O5		Reserved
	_	O6		Reserved
		07		Reserved
93	P23.4	I	MP+/	General-purpose input
	TIN45		PU1/	GTM input
	P23.4	00	VEXT	General-purpose output
	TOUT45	01		GTM output
		O2		Reserved
	SLSO35	O3		QSPI3 output
	END12	04		MSC1 output
	EN10	O5		MSC1 output
		O6		Reserved
	_	07		Reserved

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Table 2-11 Port 23 Functions (cont'd)

Pin	Symbol	Ctrl	Type	Function
94	P23.5	I	MP+/	General-purpose input
	TIN46		PU1/	GTM input
	P23.5	00	VEXT	General-purpose output
	TOUT46	O1		GTM output
		O2		Reserved
	SLSO34	O3		QSPI3 output
	END13	O4		MSC1 output
EN11	O5		MSC1 output	
		O6		Reserved
	_	07		Reserved

Table 2-12 Port 32 Functions

Pin	Symbol	Ctrl	Туре	Function
84	P32.0	I		General-purpose input
	TIN36		EVR13 SMPS	GTM input
	FDEST		-> PD, GPIO - > PU	PMU input
	VGATE1N		/ VEXT	SMPS mode: analog output. External Pass Device gate control for EVR13
	P32.0	00		General-purpose output
	TOUT36	01		GTM output
	_	O2		Reserved
	_	О3		Reserved
	_	04		Reserved
	_	O5		Reserved
	_	O6		Reserved
	_	07		Reserved
86	P32.2	I	LP/	General-purpose input
	TIN38		PU1 /	GTM input
	ARX3D		VEXT	ASCLIN3 input
	RXDCAN3B			CAN node 3 input
	P32.2	00		General-purpose output
	TOUT38	01		GTM output
	ATX3	O2		ASCLIN3 output
	_	О3		Reserved
		04		Reserved
	_	O5		Reserved
	DCDCSYNC	O6		SCU output
	_	07		Reserved

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Table 2-12 Port 32 Functions (cont'd)

Pin	Symbol	Ctrl	Туре	Function	
87	P32.3	I	LP/	General-purpose input	
	TIN39		PU1 /	GTM input	
	P32.3	00	VEXT	General-purpose output	
	TOUT39	01		GTM output	
	ATX3	O2		ASCLIN3 output	
		О3		Reserved	
	ASCLK3	O4		ASCLIN3 output	
	TXDCAN3	O5		CAN node 3 output	
		O6		Reserved	
		07		Reserved	
88	P32.4	I	MP+ / PU1 / VEXT	General-purpose input	
	TIN40			GTM input	
	ACTS1B			ASCLIN1 input	
	SDI12			MSC1 input	
	P32.4	00		General-purpose output	
	TOUT40	01		GTM output	
		02		Reserved	
	END12	О3		MSC1 output	
	GTMCLK1	04		GTM output	
	EN10	O5		MSC1 output	
	EXTCLK1	O6		SCU output	
	COUT63	07		CCU60 output	

Table 2-13 Port 33 Functions

Pin	Symbol	Ctrl	Туре	Function
70	P33.0	I	LP/	General-purpose input
	TIN22		PU1 /	GTM input
	DSITR0E		VEXT	DSADC channel 0 input E
	P33.0	00		General-purpose output
	TOUT22	01		GTM output
	_	O2		Reserved
	_	О3		Reserved
	_	O4		Reserved
	_	O5		Reserved
	VADCG2BFL0	O6		VADC output
	_	07		Reserved

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Table 2-13 Port 33 Functions (cont'd)

Pin	Symbol	Ctrl	Type	Function
71	P33.1	I	LP/	General-purpose input
	TIN23		PU1 / VEXT	GTM input
	PSIRX0C			PSI5 input
	SENT9C			SENT input
	DSCIN2B			DSADC channel 2 input B
	DSITR1E			DSADC channel 1 input E
	P33.1	00		General-purpose output
	TOUT23	01		GTM output
	ASLSO3	O2		ASCLIN3 output
	_	О3		Reserved
	DSCOUT2	04		DSADC channel 2 output
	VADCEMUX02	O5		VADC output
	VADCG2BFL1	O6		VADC output
	_	07		Reserved
72	P33.2	I	LP/	General-purpose input
	TIN24		PU1/	GTM input
	SENT8C		VEXT	SENT input
	DSDIN2B			DSADC channel 2 input B
	DSITR2E			DSADC channel 2 input E
	P33.2	00		General-purpose output
	TOUT24	01		GTM output
	ASCLK3	O2		ASCLIN3 output
	_	О3		Reserved
	PSITX0	O4		PSI5 output
	VADCEMUX01	O5		VADC output
	VADCG2BFL2	O6		VADC output
	_	07		Reserved

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Table 2-13 Port 33 Functions (cont'd)

Pin	Symbol	Ctrl	Type	Function
73	P33.3	I	LP/	General-purpose input
	TIN25		PU1 /	GTM input
	PSIRX1C		VEXT	PSI5 input
	SENT7C			SENT input
	DSCIN1B			DSADC channel 1 input B
	P33.3	00		General-purpose output
	TOUT25	01		GTM output
	_	O2		Reserved
	_	О3		Reserved
	DSCOUT1	04		DSADC channel 1 output
	VADCEMUX00	O5		VADC output
	VADCG2BFL3	O6		VADC output
	_	07		Reserved
74	P33.4	I	LP/	General-purpose input
	TIN26		PU1 / VEXT	GTM input
	SENT6C			SENT input
	CTRAPC			CCU61 input
	DSDIN1B			DSADC channel 1 input B
	DSITR0F			DSADC channel 0 input F
	P33.4	00		General-purpose output
	TOUT26	01		GTM output
	ARTS2	O2		ASCLIN2 output
	_	О3		Reserved
	PSITX1	04		PSI5 output
	VADCEMUX12	O5		VADC output
	VADCG0BFL0	O6		VADC output
	_	07		Reserved



Table 2-13 Port 33 Functions (cont'd)

Pin	Symbol	Ctrl	Type	Function
75	P33.5	I	LP/	General-purpose input
	TIN27		PU1/	GTM input
	ACTS2B		VEXT	ASCLIN2 input
	PSIRX2C			PSI5 input
	PSISRXC			PSI5-S input
	SENT5C			SENT input
	CCPOS2C			CCU61 input
	T4EUDB			GPT120 input
	DSCIN0B			DSADC channel 0 input B
	DSITR1F			DSADC channel 1 input F
	P33.5	00		General-purpose output
	TOUT27	01		GTM output
	SLSO07	O2		QSPI0 output
	SLSO17	О3		QSPI1 output
	DSCOUT0	04		DSADC channel 0 output
	VADCEMUX11	O5		VADC output
	VADCG0BFL1	O6		VADC output
	_	07		Reserved
76	P33.6	I	LP/	General-purpose input
	TIN28		PU1/	GTM input
	SENT4C		VEXT	SENT input
	CCPOS1C			CCU61 input
	T2EUDB			GPT120 input
	DSDIN0B			DSADC channel 0 input B
	DSITR2F			DSADC channel 2 input F
	P33.6	00		General-purpose output
	TOUT28	01		GTM output
	ASLSO2	O2		ASCLIN2 output
	-	О3		Reserved
	PSITX2	04		PSI5 output
	VADCEMUX10	O5		VADC output
	VADCG1BFL0	O6		VADC output
	PSISTX	07		PSI5-S output



Table 2-13 Port 33 Functions (cont'd)

Pin	Symbol	Ctrl	Туре	Function
77	P33.7	I	LP/	General-purpose input
	TIN29		PU1/	GTM input
	RXDCAN0E		VEXT	CAN node 0 input
	REQ8			SCU input
	CCPOS0C			CCU61 input
	T2INB			GPT120 input
	P33.7	00		General-purpose output
	TOUT29	01	=	GTM output
	ASCLK2	O2	=	ASCLIN2 output
	SLSO37	О3	=	QSPI3 output
		04	=	Reserved
		O5		Reserved
	VADCG1BFL1	O6		VADC output
		07		Reserved
78	P33.8	I	MP / HighZ/ VEXT	General-purpose input
	TIN30			GTM input
	ARX2E			ASCLIN2 input
	EMGSTOPA			SCU input
	P33.8	00		General-purpose output
	TOUT30	01		GTM output
	ATX2	O2		ASCLIN2 output
	SLSO32	О3		QSPI3 output
		04		Reserved
	TXDCAN0	O5		CAN node 0 output
		O6	-	Reserved
	COUT62	07		CCU61 output
	SMUFSP	HWOU T		SMU
79	P33.9	I	LP/	General-purpose input
	TIN31		PU1/	GTM input
	P33.9	00	VEXT	General-purpose output
	TOUT31	01		GTM output
	ATX2	O2		ASCLIN2 output
	SLSO31	О3		QSPI3 output
	ASCLK2	04	1	ASCLIN2 output
		O5	1	Reserved
		O6	1	Reserved
	CC62	07	1	CCU61 output



Table 2-13 Port 33 Functions (cont'd)

Pin	Symbol	Ctrl	Type	Function
80	P33.10	I	MP/	General-purpose input
	TIN32		PU1 /	GTM input
	SLSI3C		VEXT	QSPI3 input
	P33.10	00		General-purpose output
	TOUT32	01		GTM output
	SLSO16	O2		QSPI1 output
	SLSO311	О3		QSPI3 output
	ASLSO1	04		ASCLIN1 output
	PSISCLK	O5		PSI5-S output
	_	O6		Reserved
	COUT61	07		CCU61 output
81	P33.11	I	MP/	General-purpose input
	TIN33		PU1 /	GTM input
	SCLK3D		VEXT	QSPI3 input
	P33.11	00		General-purpose output
	TOUT33	01		GTM output
	ASCLK1	O2		ASCLIN1 output
	SCLK3	О3		QSPI3 output
	_	04		Reserved
	_	O5		Reserved
	DSCGPWMN	O6		DSADC output
	CC61	07		CCU61 output
32	P33.12	I	MP/	General-purpose input
	TIN34		PU1/	GTM input
	MTSR3D		VEXT	QSPI3 input
	P33.12	00		General-purpose output
	TOUT34	01		GTM output
	ATX1	O2		ASCLIN1 output
	MTSR3	О3		QSPI3 output
	ASCLK1	04		ASCLIN1 output
	_	O5		Reserved
	DSCGPWMP	O6		DSADC output
	COUT60	07		CCU61 output



Table 2-13 Port 33 Functions (cont'd)

Pin	Symbol	Ctrl	Туре	Function
83	P33.13	I	MP/	General-purpose input
	TIN35		PU1 /	GTM input
	ARX1F		VEXT	ASCLIN1 input
	MRST3D			QSPI3 input
	DSSGNB			DSADC input
	INJ11			MSC1 input
	P33.13	00		General-purpose output
	TOUT35	01		GTM output
	ATX1	O2		ASCLIN1 output
	MRST3	O3		QSPI3 output
	SLSO26	O4		QSPI2 output
	_	O5		Reserved
	DCDCSYNC	O6		SCU output
	CC60	07		CCU61 output

Table 2-14 Port 40 Functions

Pin	Symbol	Ctrl	Type	Function
44	P40.0	I	S/	General-purpose input
	VADCG3.0		HighZ /	VADC analog input channel 0 of group 3
	DS2PB		VDDM	DSADC: positive analog input channe of DSADC 2, pin B
	CCPOS0D			CCU60 input
	SENT0A			SENT input
43	P40.1	I	S/	General-purpose inpu.t
	VADCG3.1		HighZ / VDDM	VADC analog input channel 1 of group 3 (MD)
	DS2NB			DSADC: negative analog of input channel 2, pin B
	CCPOS1B			CCU60 input
	SENT1A			SENT input
42	P40.2	I	S / HighZ / VDDM	General-purpose inpu.t
	VADCG3.2			VADC analog input channel 2 of group 3 (MD)
	CCPOS1D			CCU60 input
	SENT2A			SENT input
41	P40.3	I	S/	General-purpose input
	VADCG3.3		HighZ /	VADC analog input channel 3 of group 3
	CCPOS2B		VDDM	CCU60 input
	SENT3A			SENT input

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Table 2-14 Port 40 Functions (cont'd)

Pin	Symbol	Ctrl	Туре	Function
38	P40.4	I	S/	General-purpose input
	VADCG4.0		HighZ /	VADC analog input channel 0 of group 4
	CCPOS2D		VDDM	CCU60 input
	SENT4A			SENT input
37	P40.5	I	S/	General-purpose input
	VADCG4.1		HighZ /	VADC analog input channel 1 of group 4 (MD)
	CCPOS0D		VDDM	CCU61 input
	SENT5A			SENT input
35	P40.6	I	S/	General-purpose input
	VADCG4.4		HighZ /	VADC analog input channel 4 of group 4
	DS3PA		VDDM	DSADC: positive analog input of channel 3, pin A
	CCPOS1B			CCU61 input
	SENT6A			SENT input
34	P40.7	I	S / HighZ / VDDM	General-purpose input
	VADCG4.5			VADC analog input channel 5 of group 4
	DS3NA			DSADC: negative analog input of channel 3, pin A
	CCPOS1D			CCU61 input
	SENT7A			SENT input
33	P40.8	I	S/	General-purpose input
	VADCG4.6		HighZ /	VADC analog input channel 6 of group 4
	DS3PB		VDDM	DSADC: positive analog input of channel 3, pin B
	CCPOS2B			CCU61 input
	SENT8A			SENT input
32	P40.9	I	S/	General-purpose input
	VADCG4.7		HighZ /	VADC analog input channel 7 of group 4
	DS3NB		VDDM	DSADC: negative analog input of channel 3, pin B
	CCPOS2D			CCU61 input
	SENT9A			SENT input

Table 2-15 Analog Inputs

Pin	Symbol	Ctrl	Туре	Function
67	AN0	I	D/	Analog input 0
	VADCG0.0		HighZ / VDDM	VADC analog input channel 0 of group 0
	DS1PA			DSADC: positive analog of input channel 1, pin A
66	AN1	I	D / HighZ / VDDM	Analog input 1
	VADCG0.1			VADC analog input channel 1 of group 0 (MD)
	DS1NA			DSADC: negative analog input of channel 1, pin A

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Table 2-15 Analog Inputs (cont'd)

Pin	Symbol	Ctrl	Type	Function
65	AN2	I	D/	Analog input 2
	VADCG0.2		HighZ /	VADC analog input channel 2 of group 0 (MD)
	DS0PA		VDDM	DSADC: positive analog input of channel 0, pin A
64	AN3	I	D/	Analog input 3
	VADCG0.3		HighZ /	VADC analog input channel 3 of group 0
	DS0NA		VDDM	DSADC: negative analog input of channel 0, pin A
63	AN4	1	D/	Analog input 4
	VADCG0.4		HighZ / VDDM	VADC analog input channel 4 of group 0
62	AN5	1	D/	Analog input 5
	VADCG0.5		HighZ / VDDM	VADC analog input channel 5 of group 0
61	AN6	1	D/	Analog input 6
	VADCG0.6		HighZ / VDDM	VADC analog input channel 6 of group 0
60	AN7	I	D/	Analog input 7
	VADCG0.7		HighZ / VDDM	VADC analog input channel 7 of group 0 (with pull down diagnostics)
59	AN8	1	D / HighZ / VDDM	Analog input 8
	VADCG1.0			VADC analog input channel 0 of group 1
58	AN10	1	D/	Analog input 10
	VADCG1.2		HighZ / VDDM	VADC analog input channel 2 of group 1 (MD)
57	AN11	1	D/	Analog input 11
	VADCG1.3		HighZ / VDDM	VADC analog input channel 3 of group 1 (with pull down diagnostics)
56	AN12	I	D/	Analog input 12
	VADCG1.4		HighZ / VDDM	VADC analog input channel 4 of group 1
55	AN13	1	D/	Analog input 13
	VADCG1.5		HighZ / VDDM	VADC analog input channel 5 of group 1
50	AN16	1	D/	Analog input 16
	VADCG2.0		HighZ / VDDM	VADC analog input channel 0 of group 2
1 9	AN17	1	D/	Analog input 17
	VADCG2.1		HighZ / VDDM	VADC analog input channel 1 of group 2 (MD)
48	AN18	I	D/	Analog input 18
	VADCG2.2		HighZ / VDDM	VADC analog input channel 2 of group 2 (MD)



Table 2-15 Analog Inputs (cont'd)

Pin	Symbol	Ctrl	Туре	Function
47	AN19	I	D/	Analog input 19
	VADCG2.3		HighZ / VDDM	VADC analog input channel 3 of group 2 (with pull down diagnostics)
46	AN20	I	D/	Analog input 20
	VADCG2.4	I	HighZ /	VADC analog input channel 4 of group 2
	DS2PA	I	VDDM	DSADC: positive analog input of channel 2, pin A
45	AN21	I	D/	Analog input 21
	VADCG2.5	I	HighZ /	VADC analog input channel 5 of group 2
	DS2NA	I	VDDM	DSADC: negative analog input of channel of DSADC 2, pin A
14	AN24	1	S/	Analog input 24
	VADCG3.0		HighZ /	VADC analog input channel 0 of group 3
	DS2PB		VDDM	DSADC: positive analog input of channel 2, pin B
	SENT0A			SENT input channel 0, pin A
43	AN25	I	S/	Analog input 24
	VADCG3.1		HighZ / VDDM	VADC analog input channel 1 of group 3 (MD)
	DS2NB			DSADC: negative analog input of channel 2, pin B
	SENT1A			SENT input channel 1, pin A
42	AN26	4	S / HighZ / VDDM	Analog input 26
	VADCG3.2			VADC analog input channel 2 of group 3 (MD)
	SENT2A			SENT input channel 2, pin A
41	AN27	1	S / HighZ / VDDM	Analog input 27
	VADCG3.3			VADC analog input channel 3 of group 3 (with pull down diagnostics)
	SENT3A			SENT input channel 3, pin A
40	AN28	1	D/	Analog input 28
	VADCG3.4		HighZ / VDDM	VADC analog input channel 4 of group 3
39	AN29	I	D/	Analog input 29
	VADCG3.5		HighZ / VDDM	VADC analog input channel 5 of group 3
38	AN32	I	S/	Analog input 32
	VADCG4.0		HighZ /	VADC analog input channel 0 of group 4
	SENT4A		VDDM	SENT input channel 4, pin A
37	AN33	I	S/	Analog input 33
	VADCG4.1		HighZ /	VADC analog input channel 1 of group 4 (MD)
	SENT5A		VDDM	SENT input channel 5, pin A
36	AN35	I	D/	Analog input 35
	VADCG4.3		HighZ / VDDM	VADC analog input channel 3 of group 4 (with pull down diagnostics)



Table 2-15 Analog Inputs (cont'd)

Pin	Symbol	Ctrl	Туре	Function
35	AN36	I	S/	Analog input 34
	VADCG4.4		HighZ /	VADC analog input channel 4 of group 4
	DS3PA		VDDM	DSADC: positive analog input of channel
				of DSADC 3, pin A
	SENT6A			SENT input channel 6, pin A
34	AN37	I	S/	Analog input 37
	VADCG4.5		HighZ / VDDM	VADC analog input channel 5 of group 4
	DS3NA		V DDIVI	DSADC: negative analog input of channel of DSADC 3, pin A
	SENT7A			SENT input channel 7, pin A
3	AN38	I	S/	Analog input 38
	VADCG4.6		HighZ /	VADC analog input channel 6 of group 4
	DS3PB		VDDM	DSADC: positive analog input of channel of DSADC 3, pin B
	SENT8A			SENT input channel 8, pin A
32	AN39	I	S/	Analog input 39
	VADCG4.7		HighZ /	VADC analog input channel 7 of group 4
	DS3NB		VDDM	DSADC: negative analog input of channel of DSADC 3, pin B
	SENT9A			SENT input channel 9, pin A
1	AN44	I	D/	Analog input 44
	VADCG5.4		HighZ /	VADC analog input channel 4 of group 5
	DS3PC		VDDM	DSADC: positive analog input of channel of DSADC 3, pin C
0	AN45	I	D/	Analog input 45
	VADCG5.5		HighZ /	VADC analog input channel 5 of group 5
	DS3NC		VDDM	DSADC: negative analog input of channel of DSADC 3, pin C
9	AN46	I	D/	Analog input 46
	VADCG5.6		HighZ /	VADC analog input channel 6 of group 5
	DS3PD		VDDM	DSADC: positive analog input of channel of DSADC 3, pin D
8	AN47	I	D/	Analog input 47
	VADCG5.7		HighZ /	VADC analog input channel 7 of group 5
	DS3ND		VDDM	DSADC: negative analog input of channel of DSADC 3, pin D



Table 2-16 System I/O

Pin	Symbol	Ctrl	Type	Function
121	PORST	I	I / PD / VEXT	Power On Reset Input Additional strong PD in case of power fail.
122	ESR0	I/O	MP / OD / VEXT	External System Request Reset 0 Default configuration during and after reset is opendrain driver. The driver drives low during power-on reset. This is valid additionally after deactivation of PORST until the internal reset phase has finished. See also SCU chapter for details. Default after power-on can be different. See also SCU chapter 'Reset Control Unit' and SCU_IOCR register description.
	EVRWUP	I		EVR Wakeup Pin
120	ESR1	I/O MP/PU1 VEXT	MP/PU1/ VEXT	External System Request Reset 1 Default NMI function. See also SCU chapter 'Reset Control Unit' and SCU_IOCR register description.
	EVRWUP	I		EVR Wakeup Pin
85	VGATE1P	0	VGATE1P / -/ VEXT	External Pass Device gate control for EVR13
112	TMS	I	A2/	JTAG Module State Machine Control Input
	DAP1	I/O	PD / VDDP3	Device Access Port Line 1
114	TRST	I	A2 / PD / VDDP3	JTAG Module Reset/Enable Input
115	TCK	I	A2 /	JTAG Module Clock Input
	DAP0	I	PD / VDDP3	Device Access Port Line 0
102	XTAL1	I	XTAL1 / - / VDDP3	Main Oscillator/PLL/Clock Generator Input
103	XTAL2	0	XTAL2 / - / VDDP3	Main Oscillator/PLL/Clock Generator Output

Table 2-17 Supply

Pin	Symbol	Ctrl	Туре	Function
52	VAREF1	I	Vx	Positive Analog Reference Voltage 1
51	VAGND1	I	Vx	Negative Analog Reference Voltage 1

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Table 2-17 Supply (cont'd)

Pin	Symbol	Ctrl	Type	Function
26	VAREF2	I	Vx	Positive Analog Reference Voltage 2
27	VAGND2	I	Vx	Negative Analog Reference Voltage 2
54	VDDM	I	Vx	ADC Analog Power Supply (3.3V / 5V)
101	VSS	I	Vx	Digital Ground
10	VDD / VDDSB	I	Vx	Emulation Device: Emulation SRAM Standby Power Supply (1.3V) (Emulation Device only). Production Device: VDD (1.3V).
123, 68, 24	VDD	I	Vx	Digital Core Power Supply (1.3V)
100	VDD	I	Vx	Digital Core Power Supply (1.3V). The supply pin inturn supplies the main XTAL Oscillator/PLL (1.3V). A higher decoupling capacitor is therefore recommended to the VSS pin for better noise immunity.
153, 99, 69, 25	VEXT	I	Vx	External Power Supply (5V / 3.3V)
154	VDDP3	I	Vx	Digital Power Supply for Flash (3.3V). Can be also used as external 3.3V Power Supply for VFLEX.
104	VDDP3	I	Vx	Digital Power Supply for Oscillator, LVDSH and A2 pads (3.3V). The supply pin inturn supplies the main XTAL Oscillator/PLL (3.3V). A higher decoupling capacitor is therefore recommended to the VSS pin for better noise immunity.
155	VDDFL3	I	Vx	Flash Power Supply (3.3V)
164	VFLEX	I	Vx	Digital Power Supply for Flex Port Pads (5V / 3.3V)
53	VSSM	I	Vx	Analog Ground for VDDM

Legend:

Column "Ctrl.":

I = Input (for GPIO port Lines with IOCR bit field Selection PCx = 0XXX_B)

O = Output

O0 = Output with IOCR bit field selection $PCx = 1X000_B$

O1 = Output with IOCR bit field selection PCx = 1X001_B (ALT1)

O2 = Output with IOCR bit field selection PCx = $1X010_B$ (ALT2)

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```
O3 = Output with IOCR bit field selection PCx = 1X011_B (ALT3)
O4 = Output with IOCR bit field selection PCx = 1X100_B (ALT4)
O5 = Output with IOCR bit field selection PCx = 1X101_{R} (ALT5)
```

O6 = Output with IOCR bit field selection PCx = 1X110_B (ALT6)

O7 = Output with IOCR bit field selection PCx = 1X111_B (ALT7)

Column "Type":

LP = Pad class LP (5V/3.3V, LVTTL)

MP = Pad class MP (5V/3.3V, LVTTL)

MP+ = Pad class MP+ (5V/3.3V, LVTTL)

MPR = Pad class MPR (5V/3.3V, LVTTL)

A2 = Pad class A2 (3.3V, LVTTL)

LVDSM = Pad class LVDSM (LVDS/CMOS 5V/3.3V)

LVDSH = Pad class LVDSH (LVDS/CMOS 3.3V)

S = Pad class S (ADC overlayed with General Purpose Input)

D = Pad class D (ADC)

PU = with pull-up device connected during reset (PORST = 0)

PU1 = with pull-up device connected during reset ($\overline{PORST} = 0$)^{1) 2) 3)}

PD = with pull-down device connected during reset ($\overline{PORST} = 0$)

PD1 = with pull-down device connected during reset ($\overline{PORST} = 0$)^{1) 2) 3)}

PX = Behavior depends on usage: PD in EVR13 SMPS Mode and PU1 in GPIO Mode

OD = open drain during reset (PORST = 0)

HighZ = tri-state during reset (PORST = 0)

PORST = PORST input pad

XTAL1 = XTAL1 input pad

XTAL2 = XTAL2 input pad

VGATE1P = VGATE1P

VGATE3P = VGATE3P

Vx = Supply (the Exposed Pad is also considered as VSS and shall be connected to ground)

NC = These pins are reserved for future extensions and shall not be connected externally

NC1 = These pins are not connected on package level and will not be used for future extensions

NCVDDPSB = This pin has a different functionality in an Production Device and an Emulation Device. For details pls. see Pin/Ball description of this pin.

NCVDDSB = This pin has a different functionality in an Production Device and an Emulation Device. For details pls. see Pin/Ball description of this pin.

2.1.2 **Emergency Stop Function**

The Emergency Stop function can be used to force GPIOs (General Purpose Inputs/Outputs) via an external input signal (EMGSTOPA or EMGSTOPB) into a defined state:

- Input state and
- PU or High-Z depending on HWCFG[6] level latched during PORST active

Control of the Emergency Stop function:

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¹⁾The default state of GPIOs (Px.y) during and after PORST active is controllled via HWCFG[6] (P14.4). HWCFG[6] has a weak internal pull-up active at start-up if the pin is left unconnected. See also User's Manual, "Introduction Chapter", "General Purpose I/O Ports and Peripheral I/O Lines", Figure: "Default state of port pins during and after reset".

If HWCFG[6] is left unconnected or is externally pulled high, weak internal pull-ups (PU1) / pull-downs (PD1) are active during and after reset.

³⁾ If HWCFG[6] is connected to ground, the PD1 / PU1 pins are predominantly in HighZ during and after reset.



- The Emergency Stop function can be enabled/disabled in the SCU (see chapter "SCU", "Emergency Stop Control")
- The Emergency Stop input signal, EMGSTOPA (P33.8) / EMGSTOPB (P21.2), can selected in the SCU (see chapter "SCU", "Emergency Stop Control")
- On port level, each GPIO can be enabled/disabled for the Emergency Stop function via the Px_ESR (Port x Emergency Stop) registers in the port control logic (see chapter "General Purpose I/O Ports and Peripheral I/O Lines", "Emergency Stop Register").

The Emergency Stop function is available for all GPIO Ports with the following exceptions:

- Not available for P20.2 (General Purpose Input/GPI only, overlayed with Testmode)
- Not available for P40.x (analoge input ANx overlayed with GPI)
- Not available for P32.0 EVR13 SMPS mode.
- Not available for dedicated I/O without General Purpose Output function (e.g ESRx, TMS, TCK)

The Emergency Stop function can be overruled on the following GPIO Ports:

- P00.x: Emergency Stop can be overruled by the VADC. Overruling can be disabled via the control register P00_SCR (see chapter "General Purpose I/O Ports and Peripheral I/O Lines", P00)
- P14.0 and P14.1: Emergency Stop can be overruled in the DXCPL mode (DAP over can physical layer mode).
 No Overruling in the DXCM (Debug over can message) mode
- P21.6: Emergency Stop can be overruled in JTAG mode if this pin is used as TDI
- P21.7: Emergency Stop can be overruled in JTAG or Three Pin DAP mode
- P20.0: Emergency Stop can be overruled in JTAG mode if this GPIO is used as TDI

2.1.3 Pull-Up/Pull-Down Reset Behavior of the Pins

Table 2-18 List of Pull-Up/Pull-Down Reset Behavior of the Pins

Pins	PORST = 0	PORST = 1
all GPIOs	Pull-up if HWCFG[6] = 1 or High-Z	if HWCFG[6] = 0
TDI, TESTMODE	Pull-up	
PORST ¹⁾	Pull-down with I_{PORST} relevant	Pull-down with $I_{\rm PDLI}$ relevant
TRST, TCK, TMS	Pull-down	
ESR0	The open-drain driver is used to drive low. ²⁾	Pull-up ³⁾
ESR1	Pull-up ³⁾	
TDO	Pull-up	High-Z/Pull-up ⁴⁾

¹⁾ Pull-down with I_{PORST} relevant is always activated when a primary supply monitor detects a violation.

In case of leakage test $(\overline{PORST} = 0 \text{ and } \overline{TESTMODE} = 0)$, the pull-down of the \overline{TRST} pin is switched off. In case of an user application $(\overline{TESTMODE} = 1)$, the pull-down of the \overline{TRST} is always switched on.

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²⁾Valid additionally after deactivation of PORST until the internal reset phase has finished. See the SCU chapter for details.

³⁾ See the SCU_IOCR register description.

⁴⁾ Depends on JTAG/DAP selection with TRST.



2.2 TC277x Pin Definition and Functions: BGA292

Figure 2-2 is showing the TC277x Logic Symbol for the package variant: BGA292.

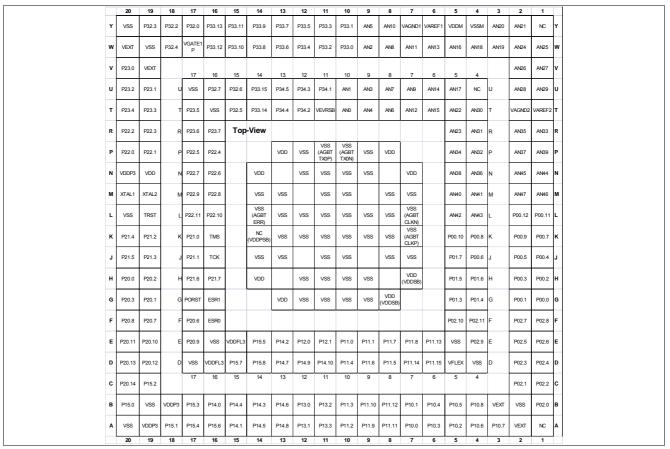


Figure 2-2 TC277x Logic Symbol for the package variant BGA292.

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2.2.1 TC277xBGA292 Package Variant Pin Configuration

Table 2-19 Port 00 Functions

Pin	Symbol	Ctrl	Туре	Function
G1	P00.0	1	MP/	General-purpose input
	TIN9		PU1 / VEXT	GTM input
	CTRAPA			CCU61 input
	T12HRE			CCU60 input
	INJ00			MSC0 input
	CIFD9			CIF input
	P00.0	00		General-purpose output
	TOUT9	O1		GTM output
	ASCLK3	O2		ASCLIN3 output
	ATX3	O3		ASCLIN3 output
		O4		Reserved
	TXDCAN1	O5		CAN node 1 output
	_	O6		Reserved
	COUT63	O7		CCU60 output
	ETHMDIOA	HWOU T		ETH input/output
32	P00.1	1	LP/	General-purpose input
	TIN10		PU1 / VEXT	GTM input
	ARX3E			ASCLIN3 input
	RXDCAN1D			CAN node 1 input
	PSIRX0A			PSI5 input
	SENT0B			SENT input
	CC60INB			CCU60 input
	CC60INA			CCU61 input
	DSCIN5A			DSADC channel 5 input A
	DS5NA			DSADC negative analog input of channel 5, pin A
	VADCG7.5			VADC analog input channel 5 of group 7
	CIFD10			CIF input
	P00.1	00		General-purpose output
	TOUT10	01	GTM out	GTM output
	ATX3	O2		ASCLIN3 output
	_	О3		Reserved
	DSCOUT5	04		DSADC channel 5 output
	_	O5		Reserved
	SPC0	O6		SENT output
	CC60	07		CCU61 output

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Table 2-19 Port 00 Functions (cont'd)

Pin	Symbol	Ctrl	Type	Function
H1	P00.2	I	LP/	General-purpose input
	TIN11		PU1/	GTM input
	SENT1B		VEXT	SENT input
	DSDIN5A			DSADC channel 5 input A
	DS5PA			DSADC positive analog input of channel 5, pin A
	VADCG7.4			VADC analog input channel 4 of group 7
	CIFD11			CIF input
	P00.2	00		General-purpose output
	TOUT11	01		GTM output
	ASCLK3	O2		ASCLIN3 output
	_	O3		Reserved
	PSITX0	04		PSI5 output
	TXDCAN3	O5		CAN node 3 output
	_	O6		Reserved
	COUT60	07		CCU61 output
H2	P00.3	1	LP/	General-purpose input
	TIN12		PU1 /	GTM input
	RXDCAN3A		VEXT	CAN node 3 input
	PSIRX1A			PSI5 input
	PSISRXA			PSI5-S input
	SENT2B			SENT input
	CC61INB			CCU60 input
	CC61INA			CCU61 input
	DSCIN3A			DSADC channel 3 input A
	VADCG7.3			VADC analog input channel 3 of group 7
	DSITR5F			DSADC channel 5 input F
	CIFD12			CIF input
	P00.3	00		General-purpose output
	TOUT12	01		GTM output
	ASLSO3	O2		ASCLIN3 output
	_	O3		Reserved
	DSCOUT3	O4		DSADC channel 3 output
	_	O5		Reserved
	SPC2	O6		SENT output
	CC61	07		CCU61 output



Table 2-19 Port 00 Functions (cont'd)

Pin	Symbol	Ctrl	Type	Function
J1	P00.4	I	LP / PU1 / VEXT	General-purpose input
	TIN13			GTM input
	REQ7			SCU input
	SENT3B			SENT input
	DSDIN3A			DSADC channel 3 input A
	DSSGNA			DSADC input
	VADCG7.2			VADC analog input channel 2 of group 7 (MD)
	CIFD13			CIF input
	P00.4	00		General-purpose output
	TOUT13	01		GTM output
	PSISTX	O2		PSI5-S output
		O3		Reserved
	PSITX1	04		PSI5 output
	VADCG4BFL0	O5		VADC output
	SPC3	O6		SENT output
	COUT61	07		CCU61 output
J2	P00.5	I	LP / PU1 / VEXT	General-purpose input
	TIN14			GTM input
	PSIRX2A			PSI5 input
	SENT4B			SENT input
	CC62INB			CCU60 input
	CC62INA			CCU61 input
	DSCIN2A			DSADC channel 2 input A
	VADCG7.1			VADC analog input channel 1 of group 7 (MD)
	CIFD14			CIF input
	P00.5	00		General-purpose output
	TOUT14	01		GTM output
	DSCGPWMN	O2		DSADC output
	_	О3		Reserved
	DSCOUT2	04		DSADC channel 2 output
	VADCG4BFL1	O5		VADC output
	SPC4	O6		SENT output
	CC62	07		CCU61 output

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Table 2-19 Port 00 Functions (cont'd)

Pin	Symbol	Ctrl	Type	Function
4	P00.6	I	LP/	General-purpose input
	TIN15		PU1 /	GTM input
	SENT5B		VEXT	SENT input
	DSDIN2A			DSADC channel 2 input A
	VADCG7.0			VADC analog input channel 0 of group 7
	DSITR4F			DSADC channel 4 input F
	CIFD15			CIF input
	P00.6	00		General-purpose output
	TOUT15	01		GTM output
	DSCGPWMP	O2		DSADC output
	VADCG4BFL2	О3		VADC output
	PSITX2	04		PSI5 output
	VADCEMUX10	O5		VADC output
	SPC5	O6		SENT output
	COUT62	07		CCU61 output
(1	P00.7	I	LP/	General-purpose input
	TIN16		PU1 / VEXT	GTM input
	SENT6B			SENT input
	CC60INC			CCU61 input
	CCPOS0A			CCU61 input
	T12HRB			CCU60 input
	T2INA			GPT120 input
	DSCIN4A			DSADC channel 4 input A
	DS4NA			DSADC negative analog input of channel 4, pin A
	VADCG6.5			VADC analog input channel 5 of group 6
	CIFCLK			CIF input
	P00.7	00		General-purpose output
	TOUT16	01		GTM output
	-	O2		Reserved
	VADCG4BFL3	O3		VADC output
	DSCOUT4	O4		DSADC channel 4 output
	VADCEMUX11	O5		VADC output
	SPC6	O6		SENT output
	CC60	07		CCU61 output



Table 2-19 Port 00 Functions (cont'd)

Pin	Symbol	Ctrl	Type	Function
K4	P00.8	I	LP/	General-purpose input
	TIN17		PU1/	GTM input
	SENT7B		VEXT	SENT input
	CC61INC			CCU61 input
	CCPOS1A			CCU61 input
	T13HRB			CCU60 input
	T2EUDA			GPT120 input
	DSDIN4A			DSADC channel 4 input A
	DS4PA			DSADC channel 4 input A
	VADCG6.4			VADC analog input channel 4 of group 6
	CIFVSNC			CIF input
	P00.8	00		General-purpose output
	TOUT17	01		GTM output
	SLSO36	O2		QSPI3 output
	_	О3		Reserved
	_	04		Reserved
	VADCEMUX12	O5		VADC output
	SPC7	O6		SENT output
	CC61	07		CCU61 output



Table 2-19 Port 00 Functions (cont'd)

Pin	Symbol	Ctrl	Туре	Function
K2	P00.9	I	LP/	General-purpose input
	TIN18		PU1/	GTM input
	SENT8B		VEXT	SENT input
	CC62INC			CCU61 input
	CCPOS2A			CCU61 input
	T13HRC			CCU60 input
	T12HRC			CCU60 input
	T4EUDA			GPT120 input
	DSCIN1A			DSADC channel 1 input A
	VADCG6.3			VADC analog input channel 3 of group 6
	DSITR3F			DSADC channel 3 input F
	CIFHSNC	O0		CIF input
	P00.9			General-purpose output
	TOUT18	01		GTM output
	SLSO37	O2		QSPI3 output
	ARTS3	О3		ASCLIN3 output
	DSCOUT1	O4		DSADC channel 1 output
	_	O5		Reserved
	SPC8	O6		SENT output
	CC62	07		CCU61 output
K5	P00.10	1	LP/	General-purpose input
	TIN19		PU1/	GTM input
	SENT9B		VEXT	SENT input
	DSDIN1A			DSADC channel 1 input A
	VADCG6.2			VADC analog input channel 2 of group 6 (MD)
	P00.10	00		General-purpose output
	TOUT19	01		GTM output
	_	O2		Reserved
	_	О3		Reserved
	_	O4		Reserved
	_	O5		Reserved
	SPC9	O6		SENT output
	COUT63	07]	CCU61 output



Table 2-19 Port 00 Functions (cont'd)

Pin	Symbol	Ctrl	Type	Function
L1	P00.11	I	LP/	General-purpose input
	TIN20		PU1/	GTM input
	CTRAPA		VEXT	CCU60 input
	T12HRE			CCU61 input
	DSCIN0A			DSADC channel 0 input A
	VADCG6.1			VADC analog input channel 1 of group 6 (MD)
	P00.11	O0		General-purpose output
	TOUT20	01		GTM output
	_	O2		Reserved
	_	О3		Reserved
	DSCOUT0	O4		DSADC channel 0 output
	_	O5		Reserved
	_	O6		Reserved
		O7		Reserved
L2	P00.12	I	LP/	General-purpose input
	TIN21		PU1/	GTM input
	ACTS3A		VEXT	ASCLIN3 input
	DSDIN0A			DSADC channel 0 input A
	VADCG6.0			VADC analog input channel 0 of group 6
	P00.12	O0		General-purpose output
	TOUT21	O1		GTM output
		O2		Reserved
	_	О3		Reserved
	_	04		Reserved
		O5		Reserved
		O6		Reserved
	COUT63	07		CCU61 output



Table 2-20 Port 01 Functions

Pin	Symbol	Ctrl	Туре	Function
G5	P01.3	ı	LP/	General-purpose input
	TIN111		PU1/	GTM input
	SLSI3B		VEXT	QSPI3 input
	P01.3	00		General-purpose output
	TOUT111	01		GTM output
	_	O2		Reserved
	_	O3		Reserved
	SLSO39	O4		QSPI3 output
	TXDCAN1	O5		CAN node 1 output
		O6		Reserved
	_	07		Reserved
3 4	P01.4	I	LP/	General-purpose input
	TIN112		PU1 / VEXT	GTM input
	RXDCAN1C			CAN node 1 input
	P01.4	00		General-purpose output
	TOUT112	O1		GTM output
	_	O2		Reserved
	_	O3		Reserved
	SLSO310	04		QSPI3 output
	_	O5		Reserved
	_	O6		Reserved
		07		Reserved
15	P01.5	I	LP/	General-purpose input
	TIN113		PU1/	GTM input
	MRST3C		VEXT	QSPI3 input
	P01.5	00		General-purpose output
	TOUT113	O1		GTM output
		O2		Reserved
		O3		Reserved
	MRST3	04		QSPI3 output
		O5		Reserved
		O6		Reserved
	_	07		Reserved



Table 2-20 Port 01 Functions (cont'd)

Pin	Symbol	Ctrl	Туре	Function
H4	P01.6	1	LP/	General-purpose input
	TIN114		PU1 /	GTM input
	MTSR3C		VEXT	QSPI3 input
	P01.6	00		General-purpose output
	TOUT114	01		GTM output
	_	O2		Reserved
	_	O3		Reserved
	MTSR3	O4		QSPI3 output
	_	O5		Reserved
	_	O6		Reserved
	_	07		Reserved
J5	P01.7	1	LP/	General-purpose input
	TIN115		PU1 / VEXT	GTM input
	SCLK3C			QSPI3 input
	P01.7	00		General-purpose output
	TOUT115	O1		GTM output
	_	O2		Reserved
	_	O3		Reserved
	SCLK3	O4		QSPI3 output
	_	O5		Reserved
	_	O6		Reserved
	_	07		Reserved



Table 2-21 Port 02 Functions

Pin	Symbol	Ctrl	Туре	Function
B1	P02.0	I	MP+/	General-purpose input
	TIN0		PU1 /	GTM input
	ARX2G		VEXT	ASCLIN2 input
	REQ6			SCU input
	CC60INA			CCU60 input
	CC60INB			CCU61 input
	CIFD0			CIF input
	P02.0	00		General-purpose output
	TOUT0	01		GTM output
	ATX2	O2		ASCLIN2 output
	SLSO31	O3		QSPI3 output
	DSCGPWMN	04		DSADC output
	TXDCAN0	O5		CAN node 0 output
	TXDA	O6		ERAY output
	CC60	07		CCU60 output
C2	P02.1	I	LP/PU1	General-purpose input
	TIN1		/ VEXT	GTM input
	REQ14			SCU input
	ARX2B			ASCLIN2 input
	RXDCAN0A			CAN node 0 input
	RXDA2			ERAY input
	CIFD1			CIF input
	P02.1	00		General-purpose output
	TOUT1	01		GTM output
	_	O2		Reserved
	SLSO32	O3		QSPI3 output
	DSCGPWMP	04		DSADC output
	_	O5		Reserved
	_	O6		Reserved
	COUT60	07		CCU60 output



Table 2-21 Port 02 Functions (cont'd)

Pin	Symbol	Ctrl	Type	Function
C1	P02.2	I	MP+/	General-purpose input
	TIN2		PU1/	GTM input
	CC61INA		VEXT	CCU60 input
	CC61INB			CCU61 input
	CIFD2			CIF input
	P02.2	00		General-purpose output
	TOUT2	01		GTM output
	ATX1	O2		ASCLIN1 output
	SLSO33	O3		QSPI3 output
	PSITX0	04		PSI5 output
	TXDCAN2	O5		CAN node 2 output
	TXDB	O6		ERAY output
	CC61	07		CCU60 output
D2	P02.3	I	LP / PU1 / VEXT	General-purpose input
	TIN3			GTM input
	ARX1G			ASCLIN1 input
	RXDCAN2B			CAN node 2 input
	RXDB2			ERAY input
	PSIRX0B			PSI5 input
	DSCIN5B			DSADC channel 5 input B
	SDI11			MSC1 input
	CIFD3			CIF input
	P02.3	00		General-purpose output
	TOUT3	01		GTM output
	ASLSO2	O2		ASCLIN2 output
	SLSO34	O3		QSPI3 output
	DSCOUT5	04		DSADC channel 5 output
	_	O5		Reserved
	_	O6		Reserved
	COUT61	07		CCU60 output



Table 2-21 Port 02 Functions (cont'd)

Pin	Symbol	Ctrl	Туре	Function
D1	P02.4	I	MP+/	General-purpose input
	TIN4		PU1/	GTM input
	SLSI3A		VEXT	QSPI3 input
	ECTT1			TTCAN input
	RXDCAN0D			CAN node 0 input
	CC62INA			CCU60 input
	CC62INB			CCU61 input
	DSDIN5B			DSADC channel 5 input B
	SDA0A			I2C0 input
	CIFD4			CIF input
	P02.4	00		General-purpose output
	TOUT4	01		GTM output
	ASCLK2	O2		ASCLIN2 output
	SLSO30	O3		QSPI3 output
	PSISCLK	04		PSI5-S output
	SDA0	O5		I2C0 output
	TXENA	O6		ERAY output
	CC62	07		CCU60 output
E2	P02.5	I	MP+/ PU1/ VEXT	General-purpose input
	TIN5			GTM input
	MRST3A			QSPI3 input
	ECTT2			TTCAN input
	PSIRX1B			PSI5 input
	PSISRXB			PSI5-S input
	SENT3C			SENT input
	DSCIN4B			DSADC channel 4 input B
	SCL0A			I2C0 input
	CIFD5			CIF input
	P02.5	00		General-purpose output
	TOUT5	01		GTM output
	TXDCAN0	O2		CAN node 0 output
	MRST3	О3		QSPI3 output
	DSCOUT4	04		DSADC channel 4 output
	SCL0	O5		I2C0 output
	TXENB	O6		ERAY output
	COUT62	07		CCU60 output

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Table 2-21 Port 02 Functions (cont'd)

Pin	Symbol	Ctrl	Туре	Function
E1	P02.6	I	MP / PU1 /	General-purpose input
	TIN6			GTM input
	MTSR3A		VEXT	QSPI3 input
	SENT2C			SENT input
	CC60INC			CCU60 input
	CCPOS0A			CCU60 input
	T12HRB			CCU61 input
	T3INA			GPT120 input
	CIFD6			CIF input
	DSDIN4B			DSADC channel 4 input B
	DSITR5E			DSADC channel 5 input E
	P02.6	00		General-purpose output
	TOUT6	01		GTM output
	PSISTX	O2		PSI5-S output
	MTSR3	O3		QSPI3 output
	PSITX1	O4		PSI5 output
	VADCEMUX00	O5		VADC output
	_	O6		Reserved
	CC60	07		CCU60 output



Table 2-21 Port 02 Functions (cont'd)

Pin	Symbol	Ctrl	Type	Function
F2	P02.7	I	MP/ PU1/	General-purpose input
	TIN7			GTM input
	SCLK3A		VEXT	QSPI3 input
	PSIRX2B			PSI5 input
	SENT1C			SENT input
	CC61INC			CCU60 input
	CCPOS1A			CCU60 input
	T13HRB			CCU61 input
	T3EUDA			GPT120 input
	CIFD7			CIF input
	DSCIN3B			DSADC channel 3 input B
	DSITR4E			DSADC channel 4 input E
	P02.7	00		General-purpose output
	TOUT7	01		GTM output
	_	O2		Reserved
	SCLK3	O3		QSPI3 output
	DSCOUT3	04		DSADC channel 3 output
	VADCEMUX01	O5		VADC output
	SPC1	O6		SENT output
	CC61	07		CCU60 output



Table 2-21 Port 02 Functions (cont'd)

Pin	Symbol	Ctrl	Туре	Function
F1	P02.8	I	LP/PU1	General-purpose input
	TIN8		/	GTM input
	SENT0C		VEXT	SENT input
	CC62INC			CCU60 input
	CCPOS2A			CCU60 input
	T12HRC			CCU61 input
	T13HRC			CCU61 input
	T4INA			GPT120 input
	CIFD8			CIF input
	DSDIN3B			DSADC channel 3 input B
	DSITR3E			DSADC channel 3 input E
	P02.8	00		General-purpose output
	TOUT8	01		GTM output
	SLSO35	O2		QSPI3 output
	_	O3		Reserved
	PSITX2	04		PSI5 output
	VADCEMUX02	O5		VADC output
	ETHMDC	O6		ETH output
	CC62	07		CCU60 output
Ξ4	P02.9	I	LP/	General-purpose input
	TIN116		PU1/	GTM input
	P02.9	00	VEXT	General-purpose output
	TOUT116	01		GTM output
	ATX2	O2		ASCLIN2 output
	_	О3		Reserved
	_	O4		Reserved
	TXDCAN1	O5		CAN node 1 output
	_	O6		Reserved
	_	07		Reserved



Table 2-21 Port 02 Functions (cont'd)

Pin	Symbol	Ctrl	Туре	Function
F5	P02.10	I	LP/	General-purpose input
	TIN117		PU1 /	GTM input
	ARX2C		VEXT	ASCLIN2 input
	RXDCAN1E			CAN node 1 input
	P02.10	00		General-purpose output
	TOUT117	01		GTM output
	_	O2		Reserved
	_	O3		Reserved
	_	04		Reserved
	_	O5		Reserved
		O6		Reserved
		07		Reserved
F4	P02.11	I	LP / PU1 /	General-purpose input
	TIN118			GTM input
	P02.11	00	VEXT	General-purpose output
	TOUT118	01		GTM output
	_	O2		Reserved
	_	O3		Reserved
	_	04		Reserved
		O5		Reserved
	_	O6		Reserved
	_	O7		Reserved

Table 2-22 Port 10 Functions

Pin	Symbol	Ctrl	Type	Function
A7	P10.0	I	LP/	General-purpose input
	TIN102		PU1 /	GTM input
	T6EUDB		VEXT	GPT120 input
	P10.0	00		General-purpose output
	TOUT102	01		GTM output
	_	O2		Reserved
	SLSO110	O3		QSPI1 output
	_	04		Reserved
	VADCG6BFL0	O5		VADC output
	_	O6		Reserved
	_	07		Reserved

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Table 2-22 Port 10 Functions (cont'd)

Pin	Symbol	Ctrl	Type	Function
B7	P10.1	I	MP+/	General-purpose input
	TIN103		PU1/	GTM input
	MRST1A		VEXT	QSPI1 input
	T5EUDB			GPT120 input
	P10.1	00		General-purpose output
	TOUT103	01		GTM output
	MTSR1	O2		QSPI1 output
	MRST1	О3		QSPI1 output
	EN01	04		MSC0 output
	VADCG6BFL1	O5		VADC output
	END03	O6		MSC0 output
	_	07		Reserved
A5	P10.2	I	MP / PU1 / VEXT	General-purpose input
	TIN104			GTM input
	SCLK1A			QSPI1 input
	T6INB			GPT120 input
	REQ2			SCU input
	RXDCAN2E			CAN node 2 input
	SDI01			MSC0 input
	P10.2	00		General-purpose output
	TOUT104	01		GTM output
		O2		Reserved
	SCLK1	O3		QSPI1 output
	EN00	04		MSC0 output
	VADCG6BFL2	O5		VADC output
	END02	O6		MSC0 output
	_	07		Reserved



Table 2-22 Port 10 Functions (cont'd)

Pin	Symbol	Ctrl	Туре	Function
A6	P10.3	I	MP/	General-purpose input
	TIN105		PU1/	GTM input
	MTSR1A		VEXT	QSPI1 input
	REQ3			SCU input
	T5INB			GPT120 input
	P10.3	00		General-purpose output
	TOUT105	01		GTM output
	VADCG6BFL3	02		VADC output
	MTSR1	О3		QSPI1 output
	EN00	04		MSC0 output
	END02	O5		MSC0 output
	TXDCAN2	O6		CAN node 2 output
	_	07		Reserved
B6	P10.4 I MP+ /	MP+/	General-purpose input	
	TIN106		PU1 /	GTM input
	MTSR1C		VEXT	QSPI1 input
	CCPOS0C			CCU60 input
	T3INB			GPT120 input
	P10.4	00		General-purpose output
	TOUT106	01		GTM output
	_	02		Reserved
	SLSO18	O3		QSPI1 output
	MTSR1	04		QSPI1 output
	EN00	O5		MSC0 output
	END02	O6		MSC0 output
	_	07		Reserved
B5	P10.5	I	LP/	General-purpose input
	TIN107		PU1 /	GTM input
	HWCFG4		VEXT	SCU input
	INJ01			MSC0 input
	P10.5	00		General-purpose output
	TOUT107	01		GTM output
	ATX2	O2		ASCLIN2 output
	SLSO38	О3		QSPI3 output
	SLSO19	04		QSPI1 output
	T6OUT	O5		GPT120 output
	ASLSO2	06		ASCLIN2 output
		07		Reserved



Table 2-22 Port 10 Functions (cont'd)

Pin	Symbol	Ctrl	Type	Function
A 4	P10.6	I	LP/	General-purpose input
	TIN108		PU1/	GTM input
	ARX2D		VEXT	ASCLIN2 input
	MTSR3B			QSPI3 input
	HWCFG5			SCU input
	P10.6	00		General-purpose output
	TOUT108	01		GTM output
	ASCLK2	O2		ASCLIN2 output
	MTSR3	О3		QSPI3 output
	T3OUT	04		GPT120 output
	-	O5		Reserved
	MRST1	O6		QSPI1 output
	VADCG7BFL0	07		VADC output
А3	P10.7	I	LP/	General-purpose input
	TIN109		PU1/	GTM input
	ACTS2A		VEXT	ASCLIN2 input
	MRST3B			QSPI3 input
	REQ4			SCU input
	CCPOS1C			CCU60 input
	T3EUDB			GPT120 input
	P10.7	00		General-purpose output
	TOUT109	01		GTM output
		O2		Reserved
	MRST3	О3		QSPI3 output
	VADCG7BFL1	04		VADC output
		O5		Reserved
		06		Reserved
	_	07		Reserved



Table 2-22 Port 10 Functions (cont'd)

Pin	Symbol	Ctrl	Туре	Function
B4	P10.8	I	LP/	General-purpose input
	TIN110		PU1/	GTM input
	SCLK3B		VEXT	QSPI3 input
	REQ5			SCU input
	CCPOS2C			CCU60 input
	T4INB			GPT120 input
	P10.8	00		General-purpose output
	TOUT110	01		GTM output
	ARTS2	O2		ASCLIN2 output
	SCLK3	O3		QSPI3 output
	_	O4		Reserved
	_	O5		Reserved
	_	O6		Reserved
	_	07		Reserved

Table 2-23 Port 11 Functions

Pin	Symbol	Ctrl	Type	Function	
E10	P11.0	I	MP+/	General-purpose input	
	TIN119		PU1 /	GTM input	
	ARX3B		VFLEX	ASCLIN3 input	
	P11.0	00		General-purpose output	
	TOUT119	01		GTM output	
	ATX3	O2		ASCLIN3 output	
	_	O3		Reserved	
	_	04		Reserved	
	_	O5		Reserved	
	ETHTXD3	06		ETH output	
	_	07		Reserved	
E9	P11.1	I	MP+ / PU1 / VFLEX	General-purpose input	
	TIN120			GTM input	
	P11.1	00		General-purpose output	
	TOUT120	01		GTM output	
	ASCLK3	02		ASCLIN3 output	
	ATX3	O3		ASCLIN3 output	
		04		Reserved	
		O5		Reserved	
	ETHTXD2	O6		ETH output	
	_	O7		Reserved	

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Table 2-23 Port 11 Functions (cont'd)

Pin	Symbol	Ctrl	Туре	Function
A10	P11.2	I	MPR/	General-purpose input
	TIN95		PU1 /	GTM input
	P11.2	00	VFLEX	General-purpose output
	TOUT95	01		GTM output
	END03	O2		MSC0 output
	SLSO05	О3		QSPI0 output
	SLSO15	04		QSPI1 output
	EN01	O5		MSC0 output
	ETHTXD1	O6		ETH output
	COUT63	07		CCU60 output
B10	P11.3	I	MPR/	General-purpose input
	TIN96		PU1 /	GTM input
	MRST1B		VFLEX	QSPI1 input
	SDI03			MSC0 input
	P11.3	00		General-purpose output
	TOUT96	01		GTM output
	_	O2		Reserved
	MRST1	O3		QSPI1 output
	TXDA	04		ERAY output
	_	O5		Reserved
	ETHTXD0	O6		ETH output
	COUT62	07		CCU60 output
D10	P11.4	I	MP+/	General-purpose input
	TIN121		PU1/	GTM input
	ETHRXCLKB		VFLEX	ETH input
	P11.4	00		General-purpose output
	TOUT121	01		GTM output
	ASCLK3	O2		ASCLIN3 output
	_	O3		Reserved
	_	04		Reserved
	_	O5		Reserved
	ETHTXER	O6		ETH output
	_	07		Reserved



Table 2-23 Port 11 Functions (cont'd)

Pin	Symbol	Ctrl	Type	Function
D8	P11.5	I	LP/	General-purpose input
	TIN122		PU1 /	GTM input
	ETHTXCLKA		VFLEX	ETH input
	P11.5	00		General-purpose output
	TOUT122	01		GTM output
	_	O2		Reserved
	_	O3		Reserved
	_	04		Reserved
	_	O5		Reserved
	_	O6		Reserved
	_	07		Reserved
D9	P11.6	I	MPR/	General-purpose input
	TIN97		PU1 /	GTM input
	SCLK1B		VFLEX	QSPI1 input
	P11.6	00		General-purpose output
	TOUT97	01		GTM output
	TXENB	O2		ERAY output
	SCLK1	O3		QSPI1 output
	TXENA	04		ERAY output
	FCLP0	O5		MSC0 output
	ETHTXEN	O6		ETH output
	COUT61	07		CCU60 output
E8	P11.7	I	LP/	General-purpose input
	TIN123		PU1 /	GTM input
	ETHRXD3		VFLEX	ETH input
	P11.7	00		General-purpose output
	TOUT123	01		GTM output
		O2		Reserved
		О3		Reserved
		04		Reserved
		O5		Reserved
		O6		Reserved
	_	07		Reserved



Table 2-23 Port 11 Functions (cont'd)

Pin	Symbol	Ctrl	Type	Function	
E7	P11.8	I	LP / PU1 /	General-purpose input	
	TIN124			GTM input	
	ETHRXD2		VFLEX	ETH input	
	P11.8	00		General-purpose output	
	TOUT124	01		GTM output	
	_	O2		Reserved	
	_	O3		Reserved	
	_	04		Reserved	
	_	O5		Reserved	
	_	06		Reserved	
	_	07		Reserved	
A9	P11.9	I	MP+ / PU1 / VFLEX	General-purpose input	
	TIN98			GTM input	
	MTSR1B			QSPI1 input	
	RXDA1			ERAY input	
	ETHRXD1			ETH input	
	P11.9	00		General-purpose output	
	TOUT98	01		GTM output	
	_	O2		Reserved	
	MTSR1	О3		QSPI1 output	
	_	04		Reserved	
	SOP0	O5		MSC0 output	
	_	O6		Reserved	
	COUT60	07		CCU60 output	



Table 2-23 Port 11 Functions (cont'd)

Pin	Symbol	Ctrl	Туре	Function
B9	P11.10	I	LP/	General-purpose input
	TIN99		PU1 / VFLEX	GTM input
	REQ12			SCU input
	ARX1E			ASCLIN1 input
	SLSI1A			QSPI1 input
	RXDCAN3D			CAN node 3 input
	RXDB1			ERAY input
	ETHRXD0			ETH input
	SDI00			MSC0 input
	P11.10	00		General-purpose output
	TOUT99	01		GTM output
		O2		Reserved
	SLSO03	O3		QSPI0 output
	SLSO13	O4		QSPI1 output
		O5		Reserved
		O6		Reserved
	CC62	07		CCU60 output
A8	P11.11	1	MP+/ PU1/	General-purpose input
	TIN100			GTM input
	ETHCRSDVA		VFLEX	ETH input
	ETHRXDVA			ETH input
	ETHCRSB			ETH input
	P11.11	00		General-purpose output
	TOUT100	01		GTM output
	END02	O2		MSC0 output
	SLSO04	О3		QSPI0 output
	SLSO14	04		QSPI1 output
	EN00	O5		MSC0 output
	TXENB	O6		ERAY output
	CC61	07		CCU60 output



Table 2-23 Port 11 Functions (cont'd)

Pin	Symbol	Ctrl	Туре	Function
B8	P11.12	1	MPR/	General-purpose input
	TIN101	00	PU1 /	GTM input
	ETHREFCLK		VFLEX	ETH input
	ETHTXCLKB			ETH input
				(Not for productive purposes)
	P11.12			General-purpose output
	TOUT101	01		GTM output
	ATX1	O2		ASCLIN1 output
	GTMCLK2	O3		GTM output
	TXDB	O4		ERAY output
	TXDCAN3	O5		CAN node 3 output
	EXTCLK1	O6		SCU output
	CC60	O7		CCU60 output
E6	P11.13	I	LP/	General-purpose input
	TIN125		PU1/	GTM input
	ETHRXERA		VFLEX	ETH input
	P11.13	00		General-purpose output
	TOUT125	01		GTM output
	_	O2		Reserved
	_	О3		Reserved
	_	04		Reserved
	_	O5		Reserved
	_	O6		Reserved
	_	07		Reserved
D7	P11.14	1	LP/	General-purpose input
	TIN126		PU1 /	GTM input
	ETHCRSDVB		VFLEX	ETH input
	ETHRXDVB			ETH input
	ETHCRSA			ETH input
	P11.14	00		General-purpose output
	TOUT126	01		GTM output
	_	O2		Reserved
	_	О3		Reserved
	_	O4		Reserved
	_	O5		Reserved
	_	O6		Reserved
	_	07		Reserved



Table 2-23 Port 11 Functions (cont'd)

Pin	Symbol	Ctrl	Туре	Function
D6	P11.15	I	LP/	General-purpose input
	TIN127		PU1/	GTM input
	ETHCOL		VFLEX	ETH input
	P11.15	00		General-purpose output
	TOUT127	01		GTM output
	_	O2		Reserved
	_	О3		Reserved
	_	O4		Reserved
	_	O5		Reserved
	_	O6		Reserved
		O7		Reserved

Table 2-24 Port 12 Functions

Pin	Symbol	Ctrl	Type	Function
E12	P12.0	I	LP/	General-purpose input
	TIN128		PU1/	GTM input
	ETHRXCLKC		VFLEX	ETH input
	RXDCAN0C			CAN node 0 input
	P12.0	00		General-purpose output
	TOUT128	01		GTM output
		O2		Reserved
	_	O3		Reserved
		04		Reserved
	_	O5		Reserved
	ETHMDC	O6		ETH output
		07		Reserved
E11	P12.1	I	LP / PU1 /	General-purpose input
	TIN129			GTM input
	P12.1	00	VFLEX	General-purpose output
	TOUT129	01		GTM output
	ASLSO3	O2		ASCLIN3 output
		О3		Reserved
		O4		Reserved
	TXDCAN0	O5		CAN node 0 output
	_	O6		Reserved
	_	07		Reserved
	ETHMDIOC	HWOU T		ETH input/output

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Table 2-25 Port 13 Functions

Pin	Symbol	Ctrl	Type	Function
B12	P13.0	I	LVDSM_N /	General-purpose input
	TIN91		PU1 /	GTM input
	P13.0	O0	VEXT	General-purpose output
	TOUT91	01		GTM output
	END03	O2		MSC0 output
	SCLK2N	O3		QSPI2 output (LVDS)
	EN01	O4		MSC0 output
	FCLN0	O5		MSC0 output (LVDS)
	FCLND0	O6		MSC0 output (LVDS)
	_	07		Reserved
A12	P13.1	I	LVDSM_P/	General-purpose input
	TIN92		PU1 / VEXT	GTM input
	SCL0B			I2C0 input
	P13.1	00		General-purpose output
	TOUT92	01		GTM output
	_	O2		Reserved
	SCLK2P	O3		QSPI2 output (LVDS)
	_	04		Reserved
	FCLP0	O5		MSC0 output (LVDS)
	SCL0	O6		I2C0 output
	_	07		Reserved
311	P13.2	I	LVDSM_N /	General-purpose input
	TIN93		PU1 /	GTM input
	CAPINA		VEXT	GPT120 input
	SDA0B			I2C0 input
	P13.2	00		General-purpose output
	TOUT93	01		GTM output
	_	O2		Reserved
	MTSR2N	O3		QSPI2 output (LVDS)
	FCLP0	O4		MSC0 output
	SON0	O5		MSC0 output (LVDS)
	SDA0	O6		I2C0 output
	SOND0	07		MSC0 output (LVDS)



Table 2-25 Port 13 Functions (cont'd)

Pin	Symbol	Ctrl	Type	Function
A11	P13.3	I	LVDSM_P/	General-purpose input
	TIN94		PU1/	GTM input
	P13.3	00	VEXT	General-purpose output
	TOUT94	01		GTM output
	_	O2		Reserved
	MTSR2P	О3		QSPI2 output (LVDS)
	_	O4		Reserved
	SOP0	O5		MSC0 output (LVDS)
	_	O6		Reserved
		07		Reserved

Table 2-26 Port 14 Functions

Pin	Symbol	Ctrl	Туре	Function
B16	P14.0	I	MP+/	General-purpose input
	TIN80		PU1 /	GTM input
	P14.0	O0	VEXT	General-purpose output
	TOUT80	01		GTM output
	ATX0	O2		ASCLIN0 output Recommended as Boot loader pin.
	TXDA	O3		ERAY output
	TXDB	O4		ERAY output
	TXDCAN1	O5		CAN node 1 output Used for single pin DAP (SPD) function.
	ASCLK0	O6		ASCLIN0 output
	COUT62	07		CCU60 output

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Table 2-26 Port 14 Functions (cont'd)

Pin	Symbol	Ctrl	Type	Function
A15	P14.1	I	MP/	General-purpose input
	TIN81		PU1 /	GTM input
	REQ15		VEXT	SCU input
	ARX0A			ASCLIN0 input Recommended as Boot loader pin.
	RXDCAN1B			CAN node 1 input Used for single pin DAP (SPD) function.
	RXDA3			ERAY input
	RXDB3			ERAY input
	EVRWUPA			SCU input
	P14.1	00		General-purpose output
	TOUT81	01		GTM output
	ATX0	O2		ASCLIN0 output
		O3		Reserved
		04		Reserved
		O5		Reserved
		O6		Reserved
	COUT63	07		CCU60 output
E13	P14.2	I	LP/	General-purpose input
	TIN82		PU1 /	GTM input
	HWCFG2 EVR13		VEXT	SCU input Latched at cold power on reset to decide EVR13 activation.
	P14.2	00		General-purpose output
	TOUT82	01		GTM output
	ATX2	O2		ASCLIN2 output
	SLSO21	O3		QSPI2 output
		04		Reserved
		O5		Reserved
	ASCLK2	O6		ASCLIN2 output
	_	07		Reserved

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Table 2-26 Port 14 Functions (cont'd)

Pin	Symbol	Ctrl	Type	Function
B14	P14.3	I	LP/	General-purpose input
	TIN83		PU1 /	GTM input
	ARX2A		VEXT	ASCLIN2 input
	REQ10			SCU input
	HWCFG3_BMI			SCU input
	SDI02			MSC0 input
	P14.3	00		General-purpose output
	TOUT83	01		GTM output
	ATX2	O2		ASCLIN2 output
	SLSO23	О3		QSPI2 output
	ASLSO1	04		ASCLIN1 output
	ASLSO3	O5		ASCLIN3 output
	_	O6		Reserved
	_	07		Reserved
B15	P14.4	I	LP / PU1 /	General-purpose input
	TIN84			GTM input
	HWCFG6		VEXT	SCU input Latched at cold power on reset to decide default pad reset state (PU or HighZ).
	P14.4	00		General-purpose output
	TOUT84	01		GTM output
	_	O2		Reserved
	_	O3		Reserved
	_	04		Reserved
	_	O5		Reserved
		O6		Reserved
	_	07		Reserved



Table 2-26 Port 14 Functions (cont'd)

Pin	Symbol	Ctrl	Type	Function
A14	P14.5	I	MP+/	General-purpose input
	TIN85		PU1 /	GTM input
	HWCFG1		VEXT	SCU input
	EVR33			Latched at cold power on reset to decide EVR33
				activation.
	P14.5	00		General-purpose output
	TOUT85	01		GTM output
	_	O2		Reserved
	_	O3		Reserved
	_	O4		Reserved
	_	O5		Reserved
	TXDB	O6		ERAY output
	_	07		Reserved
B13	P14.6	I	MP+/	General-purpose input
	TIN86		PU1 / VEXT	GTM input
	HWCFG0			SCU input
	DCLDO			If EVR13 active, latched at cold power on reset to
	D110			decide between LDO and SMPS mode.
	P14.6	00		General-purpose output
	TOUT86	01		GTM output
	-	02		Reserved
	SLSO22	O3		QSPI2 output
	_	04		Reserved
	_	O5		Reserved
	TXENB	O6		ERAY output
	_	07		Reserved
D13	P14.7	I	LP/	General-purpose input
	TIN87		PU1 / VEXT	GTM input
	RXDB0		VLXI	ERAY input
	P14.7	00		General-purpose output
	TOUT87	01		GTM output
	ARTS0	O2		ASCLIN0 output
	SLSO24	О3		QSPI2 output
	_	O4		Reserved
		O5		Reserved
	_	O6		Reserved
		07		Reserved



Table 2-26 Port 14 Functions (cont'd)

Pin	Symbol	Ctrl	Туре	Function
A13	P14.8	I	LP/	General-purpose input
	TIN88		PU1 /	GTM input
	ARX1D		VEXT	ASCLIN1 input
	RXDCAN2D			CAN node 2 input
	RXDA0			ERAY input
	P14.8	00		General-purpose output
	TOUT88	01		GTM output
		O2		Reserved
		О3		Reserved
		O4		Reserved
		O5		Reserved
		O6		Reserved
		07		Reserved
D12	P14.9	I	MP+/	General-purpose input
	TIN89		PU1 / VEXT	GTM input
	ACTS0A			ASCLIN0 input
	P14.9	00		General-purpose output
	TOUT89	01		GTM output
	END03	O2		MSC0 output
	EN01	O3		MSC0 output
	_	04		Reserved
	TXENB	O5		ERAY output
	TXENA	O6		ERAY output
	_	07		Reserved
D11	P14.10	I	MP+/	General-purpose input
	TIN90		PU1 /	GTM input
	P14.10	00	VEXT	General-purpose output
	TOUT90	01		GTM output
	END02	02		MSC0 output
	EN00	О3		MSC0 output
	ATX1	04		ASCLIN1 output
	TXDCAN2	O5		CAN node 2 output
	TXDA	O6		ERAY output
		07		Reserved



Table 2-27 Port 15 Functions

	Symbol	Ctrl	Туре	Function
B20	P15.0	I	LP/	General-purpose input
	TIN71		PU1 /	GTM input
	P15.0	00	VEXT	General-purpose output
	TOUT71	01		GTM output
	ATX1	O2		ASCLIN1 output
	SLSO013	O3		QSPI0 output
	_	04		Reserved
	TXDCAN2	O5		CAN node 2 output
	ASCLK1	O6		ASCLIN1 output
	_	07		Reserved
A18	P15.1	I	LP/	General-purpose input
	TIN72		PU1 /	GTM input
	REQ16		VEXT	SCU input
	ARX1A			ASCLIN1 input
	RXDCAN2A			CAN node 2 input
	SLSI2B			QSPI2 input
	EVRWUPB			SCU input
	P15.1	00		General-purpose output
	TOUT72	01		GTM output
	ATX1	O2		ASCLIN1 output
	SLSO25	O3		QSPI2 output
	_	04		Reserved
	_	O5		Reserved
	_	O6		Reserved
	_	07		Reserved
C19	P15.2	I	MP/	General-purpose input
	TIN73		PU1/	GTM input
	SLSI2A		VEXT	QSPI2 input
	MRST2E			QSPI2 input
	P15.2	00		General-purpose output
	TOUT73	01		GTM output
	ATX0	O2		ASCLIN0 output
	SLSO20	O3		QSPI2 output
	-	04		Reserved
	TXDCAN1	O5		CAN node 1 output
	ASCLK0	O6		ASCLIN0 output
	-	07		Reserved



Table 2-27 Port 15 Functions (cont'd)

Pin	Symbol	Ctrl	Type	Function
B17	P15.3	I	MP/	General-purpose input
	TIN74		PU1 /	GTM input
	ARX0B		VEXT	ASCLIN0 input
	SCLK2A			QSPI2 input
	RXDCAN1A			CAN node 1 input
	P15.3	00		General-purpose output
	TOUT74	01		GTM output
	ATX0	O2		ASCLIN0 output
	SCLK2	О3		QSPI2 output
	END03	04		MSC0 output
	EN01	O5		MSC0 output
		O6		Reserved
		07		Reserved
A17	P15.4	I	MP/	General-purpose input
	TIN75		PU1 /	GTM input
	MRST2A		VEXT	QSPI2 input
	REQ0			SCU input
	SCL0C			I2C0 input
	P15.4	00		General-purpose output
	TOUT75	01		GTM output
	ATX1	O2		ASCLIN1 output
	MRST2	O3		QSPI2 output
		04		Reserved
		O5		Reserved
	SCL0	O6		I2C0 output
	CC62	07		CCU60 output



Table 2-27 Port 15 Functions (cont'd)

Pin	Symbol	Ctrl	Type	Function
E14	P15.5	I	MP/	General-purpose input
	TIN76		PU1 /	GTM input
	ARX1B		VEXT	ASCLIN1 input
	MTSR2A			QSPI2 input
	REQ13			SCU input
	SDA0C			I2C0 input
	P15.5	O0		General-purpose output
	TOUT76	O1		GTM output
	ATX1	O2		ASCLIN1 output
	MTSR2	O3		QSPI2 output
	END02	O4		MSC0 output
	EN00	O5		MSC0 output
	SDA0	O6		I2C0 output
	CC61	O7		CCU60 output
A16	P15.6	1	MP/	General-purpose input
	TIN77		PU1 /	GTM input
	MTSR2B		VEXT	QSPI2 input
	P15.6	O0		General-purpose output
	TOUT77	O1		GTM output
	ATX3	O2		ASCLIN3 output
	MTSR2	O3		QSPI2 output
	_	O4		Reserved
	SCLK2	O5		QSPI2 output
	ASCLK3	O6		ASCLIN3 output
	CC60	O7		CCU60 output
D15	P15.7	I	MP/	General-purpose input
	TIN78		PU1 /	GTM input
	ARX3A		VEXT	ASCLIN3 input
	MRST2B			QSPI2 input
	P15.7	00		General-purpose output
	TOUT78	O1		GTM output
	ATX3	O2		ASCLIN3 output
	MRST2	O3		QSPI2 output
	_	04		Reserved
	_	O5		Reserved
	_	O6		Reserved
	COUT60	07		CCU60 output



Table 2-27 Port 15 Functions (cont'd)

Pin	Symbol	Ctrl	Туре	Function
D14	P15.8	1	MP / PU1 / VEXT	General-purpose input
	TIN79			GTM input
	SCLK2B			QSPI2 input
	REQ1			SCU input
	P15.8	00		General-purpose output
	TOUT79	O1		GTM output
	_	O2		Reserved
	SCLK2	O3		QSPI2 output
	_	O4		Reserved
	_	O5		Reserved
	ASCLK3	O6		ASCLIN3 output
	COUT61	07		CCU60 output

Table 2-28 Port 20 Functions

Pin	Symbol	Ctrl	Type	Function
H20	P20.0	1	MP / PU1 / VEXT	General-purpose input
	TIN59			GTM input
	RXDCAN3C			CAN node 3 input
	T6EUDA			GPT120 input
	REQ9			SCU input
	SYSCLK			HSCT input
	TGI0			OCDS input
	P20.0	00		General-purpose output
	TOUT59	O1		GTM output
	ATX3	O2		ASCLIN3 output
	ASCLK3	O3		ASCLIN3 output
	_	O4		Reserved
	SYSCLK	O5		HSCT output
	_	O6		Reserved
	_	07		Reserved
	TGO0	HWOU T		OCDS; ENx

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Table 2-28 Port 20 Functions (cont'd)

Pin	Symbol	Ctrl	Type	Function
G19	P20.1	I	LP / PU1 / VEXT	General-purpose input
	TIN60			GTM input
	TGI1			OCDS input
	P20.1	00		General-purpose output
	TOUT60	O1		GTM output
	_	O2		Reserved
	_	О3		Reserved
	_	O4		Reserved
	_	O5		Reserved
	_	O6		Reserved
	_	07		Reserved
	TGO1	HWOU T		OCDS; ENx
H19	P20.2	I	LP / PU / VEXT	General-purpose input This pin is latched at power on reset release to enter test mode.
	TESTMODE			OCDS input
	P20.2	00		Output function not available
	_	O1		Output function not available
	_	O2		Output function not available
	_	О3		Output function not available
	_	O4		Output function not available
	_	O5		Output function not available
	_	O6		Output function not available
	_	07		Output function not available
G20	P20.3	I	LP / PU1 / VEXT	General-purpose input
	TIN61			GTM input
	T6INA			GPT120 input
	ARX3C			ASCLIN3 input
	P20.3	00		General-purpose output
	TOUT61	O1		GTM output
	ATX3	O2		ASCLIN3 output
	SLSO09	О3		QSPI0 output
	SLSO29	04		QSPI2 output
	TXDCAN3	O5		CAN node 3 output
		O6		Reserved
	_	07		Reserved

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Table 2-28 Port 20 Functions (cont'd)

Pin	Symbol	Ctrl	Type	Function
F17	P20.6	I	LP/	General-purpose input
	TIN62		PU1 / VEXT	GTM input
	P20.6	00		General-purpose output
	TOUT62	01		GTM output
	ARTS1	O2		ASCLIN1 output
	SLSO08	O3		QSPI0 output
	SLSO28	O4		QSPI2 output
	_	O5		Reserved
	WDT2LCK	O6		SCU output
	_	07		Reserved
F19	P20.7	I	LP/	General-purpose input
	TIN63		PU1 / VEXT	GTM input
	ACTS1A			ASCLIN1 input
	RXDCAN0B			CAN node 0 input
	P20.7	00		General-purpose output
	TOUT63	01		GTM output
	_	O2		Reserved
	_	O3		Reserved
	_	O4		Reserved
	_	O5		Reserved
	WDT1LCK	O6		SCU output
	COUT63	07		CCU61 output
F20	P20.8	I	MP / PU1 / VEXT	General-purpose input
	TIN64			GTM input
	P20.8	00		General-purpose output
	TOUT64	01		GTM output
	ASLSO1	O2		ASCLIN1 output
	SLSO00	O3		QSPI0 output
	SLSO10	O4		QSPI1 output
	TXDCAN0	O5		CAN node 0 output
	WDT0LCK	O6		SCU output
	CC60	07		CCU61 output

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Table 2-28 Port 20 Functions (cont'd)

Pin	Symbol	Ctrl	Туре	Function
E17	P20.9	I	LP/	General-purpose input
	TIN65		PU1/	GTM input
	ARX1C		VEXT	ASCLIN1 input
	RXDCAN3E			CAN node 3 input
	REQ11			SCU input
	SLSI0B			QSPI0 input
	P20.9	00		General-purpose output
	TOUT65	01		GTM output
	_	O2		Reserved
	SLSO01	O3		QSPI0 output
	SLSO11	04		QSPI1 output
	_	O5		Reserved
	WDTSLCK	O6		SCU output
	CC61	07		CCU61 output
E19	P20.10	I	MP/	General-purpose input
	TIN66		PU1 / VEXT	GTM input
	P20.10	00		General-purpose output
	TOUT66	01		GTM output
	ATX1	O2		ASCLIN1 output
	SLSO06	O3		QSPI0 output
	SLSO27	04		QSPI2 output
	TXDCAN3	O5		CAN node 3 output
	ASCLK1	O6		ASCLIN1 output
	CC62	07		CCU61 output
E20	P20.11	I	MP / PU1 / VEXT	General-purpose input
	TIN67			GTM input
	SCLK0A			QSPI0 input
	P20.11	00		General-purpose output
	TOUT67	01		GTM output
	_	O2		Reserved
	SCLK0	O3		QSPI0 output
	_	04		Reserved
	_	O5		Reserved
	_	O6		Reserved
	COUT60	07		CCU61 output

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Table 2-28 Port 20 Functions (cont'd)

Pin	Symbol	Ctrl	Type	Function
D19	P20.12	I	MP/	General-purpose input
	TIN68		PU1/	GTM input
	MRST0A		VEXT	QSPI0 input
	P20.12	00		General-purpose output
	TOUT68	01		GTM output
	_	O2		Reserved
	MRST0	О3		QSPI0 output
	MTSR0	04		QSPI0 output
		O5		Reserved
		O6		Reserved
	COUT61	07		CCU61 output
D20	P20.13	1	MP/	General-purpose input
	TIN69		PU1/	GTM input
	SLSI0A		VEXT	QSPI0 input
	P20.13	00		General-purpose output
	TOUT69	01		GTM output
	_	O2		Reserved
	SLSO02	О3		QSPI0 output
	SLSO12	04		QSPI1 output
	SCLK0	O5		QSPI0 output
	-	O6		Reserved
	COUT62	07		CCU61 output
C20	P20.14	I	MP/	General-purpose input
	TIN70		PU1 /	GTM input
	MTSR0A		VEXT	QSPI0 input
	P20.14	00		General-purpose output
	TOUT70	01		GTM output
	_	O2		Reserved
	MTSR0	О3		QSPI0 output
	_	O4		Reserved
		O5		Reserved
		O6		Reserved
		07		Reserved



Table 2-29 Port 21 Functions

Pin	Symbol	Ctrl	Type	Function
K17	P21.0	I	A2 /	General-purpose input
	TIN51		PU1 /	GTM input
	P21.0	00	VDDP3	General-purpose output
	TOUT51	01		GTM output
	_	O2		Reserved
	_	O3		Reserved
	_	O4		Reserved
	_	O5		Reserved
	ETHMDC	O6		ETH output
	_	O7		Reserved
	HSM1	HWOU T		HSM output 1
J17	P21.1	I	A2 / PU1 / VDDP3	General-purpose input
	TIN52			GTM input
	ETHMDIOB			ETH input (Not for production purposes)
	P21.1	00		General-purpose output
	TOUT52	01		GTM output
	_	O2		Reserved
	_	O3		Reserved
	_	O4		Reserved
	_	O5		Reserved
	ETHMDIO	O6		ETH output (Not for production purposes)
	_	07		Reserved
	HSM2	HWOU T		HSM output 2



Table 2-29 Port 21 Functions (cont'd)

Pin	Symbol	Ctrl	Туре	Function	
K19	P21.2	1	LVDSH_N/	General-purpose input	
	TIN53		PU1 / VDDP3	GTM input	
	MRST2CN			QSPI2 input (LVDS)	
	MRST3FN			QSPI3 input (LVDS)	
	ARX3GN			ASCLIN3 input (LVDS)	
	EMGSTOPB			SCU input	
	RXDN			HSCT input (LVDS)	
	P21.2	00		General-purpose output	
	TOUT53	O1		GTM output	
	ASLSO3	O2		ASCLIN3 output	
	_	О3		Reserved	
	_	O4		Reserved	
	ETHMDC	O5		ETH output	
	_	O6		Reserved	
	_	O7		Reserved	
J19	P21.3	I	LVDSH_P/ PU1 / VDDP3	General-purpose input	
	TIN54			GTM input	
	MRST2CP			QSPI2 input (LVDS)	
	MRST3FP			QSPI3 input (LVDS)	
	ARX3GP			ASCLIN3 input (LVDS)	
	RXDP			HSCT input (LVDS)	
	P21.3	00		General-purpose output	
	TOUT54	O1		GTM output	
	_	O2		Reserved	
	_	О3		Reserved	
	_	O4		Reserved	
	_	O5		Reserved	
	_	O6		Reserved	
	_	07		Reserved	
	ETHMDIOD	HWOU T		ETH input/output	

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Table 2-29 Port 21 Functions (cont'd)

Pin	Symbol	Ctrl	Туре	Function
K20	P21.4	I	LVDSH_N/	General-purpose input
	TIN55		PU1 /	GTM input
	P21.4	00	VDDP3	General-purpose output
	TOUT55	01		GTM output
	_	O2		Reserved
	_	О3		Reserved
	_	O4		Reserved
	_	O5		Reserved
	_	O6		Reserved
	_	07		Reserved
	TXDN	HSCT		HSCT output (LVDS)
J20	P21.5	I	LVDSH_P/	General-purpose input
	TIN56		PU1 /	GTM input
	P21.5	00	VDDP3	General-purpose output
	TOUT56	01		GTM output
	ASCLK3	O2		ASCLIN3 output
	_	O3		Reserved
	_	O4		Reserved
	_	O5		Reserved
	_	O6		Reserved
	_	O7		Reserved
	TXDP	HSCT		HSCT output (LVDS)
H17	P21.6	1	A2 /	General-purpose input
	TIN57		PU /	GTM input
	ARX3F		VDDP3	ASCLIN3 input
	TGI2			OCDS input
	TDI			OCDS (JTAG) input
	T5EUDA			GPT120 input
	P21.6	00		General-purpose output
	TOUT57	01		GTM output
	ASLSO3	O2		ASCLIN3 output
	_	O3		Reserved
	_	O4		Reserved
	SYSCLK	O5		HSCT output
	_	O6		Reserved
	T3OUT	07		GPT120 output
	TGO2	HWOU		OCDS; ENx
		Т		



Table 2-29 Port 21 Functions (cont'd)

Pin	Symbol	Ctrl	Туре	Function
H16	P21.7	1	A2 /	General-purpose input
	TIN58		PU / VDDP3	GTM input
	DAP2			OCDS input
	TGI3			OCDS input
	TDO			OCDS (JTAG) input The JTAG TDO function is overlayed with P21.7 via a double bond. In JTAG mode this pin is used as TDO, after power-on reset it is HighZ. In DAP mode this pin is used as P21.7 and controlled by the related port control logic
	ETHRXERB			ETH input
	T5INA			GPT120 input
	P21.7	00		General-purpose output
	TOUT58	O1		GTM output
	ATX3	O2		ASCLIN3 output
	ASCLK3	О3		ASCLIN3 output
	_	O4		Reserved
	_	O5		Reserved
	_	O6		Reserved
	T6OUT	07		GPT120 output
	TGO3	HWOU		OCDS; ENx
	TDO	T		OCDS (JTAG); ENx The JTAG TDO function is overlayed with P21.7 via a double bond. In JTAG mode this pin is used as TDO, after power-on reset it is HighZ. In DAP mode this pin is used as P21.7 and controlled by the related port control logic



Table 2-30 Port 22 Functions

Pin	Symbol	Ctrl	Туре	Function	_
P20	P22.0	I	LVDSM_N /	General-purpose input	
	TIN47		PU1 /	GTM input	
	MTSR3E		VEXT	QSPI3 input	
	P22.0	00		General-purpose output	
	TOUT47	01		GTM output	
	ATX3N	O2		ASCLIN3 output (LVDS)	
	MTSR3	О3		QSPI3 output	
	SCLK3N	04		QSPI3 output (LVDS)	
	FCLN1	O5		MSC1 output (LVDS)	
	FCLND1	O6		MSC1 output (LVDS)	
	_	07		Reserved	
P19	P22.1	I	LVDSM_P/	General-purpose input	
	TIN48		PU1 /	GTM input	
	MRST3E		VEXT	QSPI3 input	
	P22.1	00		General-purpose output	
	TOUT48	01		GTM output	
	ATX3P	O2		ASCLIN3 output (LVDS)	
	MRST3	О3		QSPI3 output	
	SCLK3P	04		QSPI3 output (LVDS)	
	FCLP1	O5		MSC1 output (LVDS)	
	_	06		Reserved	
	_	07		Reserved	
R20	P22.2	I	LVDSM_N /	General-purpose input	
	TIN49		PU1 /	GTM input	
	SLSI3D		VEXT	QSPI3 input	
	P22.2	00		General-purpose output	
	TOUT49	01		GTM output	
	_	O2		Reserved	
	SLSO312	О3		QSPI3 output	
	MTSR3N	04		QSPI3 output (LVDS)	
	SON1	O5		MSC1 output (LVDS)	
	SOND1	O6		MSC1 output (LVDS)	
	_	07		Reserved	



Table 2-30 Port 22 Functions (cont'd)

Pin	Symbol	Ctrl	Туре	Function
R19	P22.3	I	LVDSM_P/	General-purpose input
	TIN50		PU1 /	GTM input
	SCLK3E		VEXT	QSPI3 input
	P22.3	00		General-purpose output
	TOUT50	01		GTM output
	_	O2		Reserved
	SCLK3	O3		QSPI3 output
	MTSR3P	04		QSPI3 output (LVDS)
	SOP1	O5		MSC1 output (LVDS)
	_	O6		Reserved
	_	07		Reserved
P16	P22.4	I	LP/	General-purpose input
	TIN130		PU1 /	GTM input
	P22.4	00	VEXT	General-purpose output
	TOUT130	01		GTM output
	_	O2		Reserved
	_	O3		Reserved
	SLSO012	04		QSPI0 output
	_	O5		Reserved
	_	O6		Reserved
	_	07		Reserved
P17	P22.5	I	LP/	General-purpose input
	TIN131		PU1 /	GTM input
	MTSR0C		VEXT	QSPI0 input
	P22.5	00		General-purpose output
	TOUT131	01		GTM output
	_	O2		Reserved
	_	O3		Reserved
	MTSR0	04		QSPI0 output
		O5		Reserved
		O6		Reserved
	_	07		Reserved

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Table 2-30 Port 22 Functions (cont'd)

Pin	Symbol	Ctrl	Туре	Function	
N16	P22.6	I	LP/	General-purpose input	
	TIN132		PU1 /	GTM input	
	MRST0C		VEXT	QSPI0 input	
	P22.6	00		General-purpose output	
	TOUT132	01		GTM output	
	_	O2		Reserved	
		O3		Reserved	
	MRST0	04		QSPI0 output	
		O5		Reserved	
		O6		Reserved	
		07		Reserved	
N17	P22.7	I	LP /	General-purpose input	
	TIN133		PU1 /	GTM input	
	SCLK0C		VEXT	QSPI0 input	
	P22.7	00		General-purpose output	
	TOUT133	01		GTM output	
	_	O2		Reserved	
	_	O3		Reserved	
	SCLK0	04		QSPI0 output	
	_	O5		Reserved	
	_	06		Reserved	
	_	07		Reserved	
M16	P22.8	I	LP/	General-purpose input	
	TIN134		PU1 /	GTM input	
	SCLK0B		VEXT	QSPI0 input	
	P22.8	00		General-purpose output	
	TOUT134	01		GTM output	
	_	O2		Reserved	
	_	O3		Reserved	
	SCLK0	04		QSPI0 output	
		O5		Reserved	
		O6		Reserved	
	_	07		Reserved	

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Table 2-30 Port 22 Functions (cont'd)

Pin	Symbol	Ctrl	Type	Function	
M17	P22.9	I	LP/	General-purpose input	
	TIN135		PU1 /	GTM input	
	MRST0B		VEXT	QSPI0 input	
	P22.9	00		General-purpose output	
	TOUT135	01		GTM output	
	_	O2		Reserved	
	_	O3		Reserved	
	MRST0	04		QSPI0 output	
	_	O5		Reserved	
	_	O6		Reserved	
	_	07		Reserved	
_16	P22.10	I	LP/	General-purpose input	
	TIN136		PU1 / VEXT	GTM input	
	MTSR0B			QSPI0 input	
	P22.10	00		General-purpose output	
	TOUT136	01		GTM output	
	_	O2		Reserved	
	_	O3		Reserved	
	MTSR0	04		QSPI0 output	
	_	O5		Reserved	
	_	O6		Reserved	
	-	07		Reserved	
_17	P22.11	I	LP /	General-purpose input	
	TIN137		PU1 /	GTM input	
	P22.11	00	VEXT	General-purpose output	
	TOUT137	01		GTM output	
		O2		Reserved	
	_	O3		Reserved	
	SLSO010	O4		QSPI0 output	
		O5		Reserved	
		O6		Reserved	
	_	07		Reserved	

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Table 2-31 Port 23 Functions

Pin	Symbol	Ctrl	Type	Function
V20	P23.0	I	LP/	General-purpose input
	TIN41		PU1/	GTM input
	P23.0	O0	VEXT	General-purpose output
	TOUT41	01		GTM output
		O2		Reserved
	_	O3		Reserved
	_	04		Reserved
	_	O5		Reserved
	_	O6		Reserved
	_	07		Reserved
U19	P23.1	I	MP+/	General-purpose input
	TIN42		PU1/	GTM input
	SDI10		VEXT	MSC1 input
	P23.1	00		General-purpose output
	TOUT42	01		GTM output
	ARTS1	O2		ASCLIN1 output
	SLSO313	O3		QSPI3 output
	GTMCLK0	04		GTM output
	_	O5		Reserved
	EXTCLK0	O6		SCU output
	_	07		Reserved
U20	P23.2	I	LP/	General-purpose input
	TIN43		PU1/	GTM input
	P23.2	00	VEXT	General-purpose output
	TOUT43	01		GTM output
	_	O2		Reserved
	_	O3		Reserved
		04		Reserved
		O5		Reserved
		O6		Reserved
	_	07		Reserved

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Table 2-31 Port 23 Functions (cont'd)

Pin	Symbol	Ctrl	Type	Function
T19	P23.3	1	LP/	General-purpose input
	TIN44		PU1/	GTM input
	INJ10		VEXT	MSC1 input
	P23.3	O0		General-purpose output
	TOUT44	O1		GTM output
	_	O2		Reserved
	_	O3		Reserved
		O4		Reserved
		O5		Reserved
		O6		Reserved
	_	07		Reserved
T20	P23.4	1	MP+/	General-purpose input
	TIN45		PU1/	GTM input
	P23.4	O0	VEXT	General-purpose output
	TOUT45	O1		GTM output
		O2		Reserved
	SLSO35	O3		QSPI3 output
	END12	O4		MSC1 output
	EN10	O5		MSC1 output
		O6		Reserved
		07		Reserved
T17	P23.5	I	MP+/	General-purpose input
	TIN46		PU1 / VEXT	GTM input
	P23.5	00	VEXI	General-purpose output
	TOUT46	O1		GTM output
		O2		Reserved
	SLSO34	O3		QSPI3 output
	END13	04		MSC1 output
	EN11	O5		MSC1 output
		O6		Reserved
	_	07		Reserved

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Table 2-31 Port 23 Functions (cont'd)

Pin	Symbol	Ctrl	Туре	Function
R17	P23.6	1	LP/	General-purpose input
	TIN138		PU1/	GTM input
	P23.6	00	VEXT	General-purpose output
	TOUT138	01		GTM output
	_	O2		Reserved
	_	O3		Reserved
	SLSO011	04		QSPI0 output
	_	O5		Reserved
	_	06		Reserved
	_	07		Reserved
R16	P23.7	I	LP/	General-purpose input
	TIN139		PU1/	GTM input
	P23.7	00	VEXT	General-purpose output
	TOUT139	01		GTM output
	_	O2		Reserved
	_	O3		Reserved
	_	04		Reserved
	_	O5		Reserved
	_	O6		Reserved
	_	07		Reserved

Table 2-32 Port 32 Functions

Pin	Symbol	Ctrl	Туре	Function
Y17	P32.0	I	LP/	General-purpose input
	TIN36		EVR13 SMPS	GTM input
	FDEST		-> PD, GPIO - > PU	PMU input
	VGATE1N		/ VEXT	SMPS mode: analog output. External Pass Device gate control for EVR13
	P32.0	00		General-purpose output
	TOUT36	01		GTM output
	_	O2		Reserved
	_	О3		Reserved
	_	04		Reserved
	_	O5		Reserved
	_	O6		Reserved
		07		Reserved

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Table 2-32 Port 32 Functions (cont'd)

Pin	Symbol	Ctrl	Туре	Function
Y18	P32.2	I	LP/	General-purpose input
	TIN38		PU1 /	GTM input
	ARX3D		VEXT	ASCLIN3 input
	RXDCAN3B			CAN node 3 input
	P32.2	00		General-purpose output
	TOUT38	01		GTM output
	ATX3	O2		ASCLIN3 output
	_	О3		Reserved
	_	O4		Reserved
	_	O5		Reserved
	DCDCSYNC	O6		SCU output
	_	07		Reserved
/ 19	P32.3	1	LP/	General-purpose input
	TIN39		PU1 / VEXT	GTM input
	P32.3	00		General-purpose output
	TOUT39	01		GTM output
	ATX3	O2		ASCLIN3 output
		О3		Reserved
	ASCLK3	04		ASCLIN3 output
	TXDCAN3	O5		CAN node 3 output
		O6		Reserved
		07		Reserved
V18	P32.4	I	MP+/	General-purpose input
	TIN40		PU1 /	GTM input
	ACTS1B		VEXT	ASCLIN1 input
	SDI12			MSC1 input
	P32.4	00		General-purpose output
	TOUT40	01		GTM output
		O2		Reserved
	END12	О3		MSC1 output
	GTMCLK1	O4		GTM output
	EN10	O5		MSC1 output
	EXTCLK1	O6		SCU output
	COUT63	07		CCU60 output

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Table 2-32 Port 32 Functions (cont'd)

Pin	Symbol	Ctrl	Туре	Function
T15	P32.5	I	LP/	General-purpose input
	TIN140		PU1 /	GTM input
	P32.5	00	VEXT	General-purpose output
	TOUT140	01		GTM output
	ATX2	O2		ASCLIN2 output
	_	О3		Reserved
	_	04		Reserved
	_	O5		Reserved
	TXDCAN2	O6		CAN node 2 output
	_	07		Reserved
U15	P32.6	I	LP/	General-purpose input
	TGI4		PU1 /	OCDS input
	TIN141		VEXT	GTM input
	RXDCAN2C			CAN node 2 input
	ARX2F			ASCLIN2 input
	P32.6	00		General-purpose output
	TOUT141	01		GTM output
	_	02		Reserved
	_	О3		Reserved
	SLSO212	04		QSPI2 output
	_	O5		Reserved
	_	O6		Reserved
	_	07		Reserved
	TGO4	HWOU T		OCDS; ENx
U16	P32.7	I	LP/	General-purpose input
	TIN142		PU1/	GTM input
	TGI5		VEXT	OCDS input
	P32.7	00		General-purpose output
	TOUT142	01		GTM output
	_	02		Reserved
	_	О3		Reserved
	_	04		Reserved
	_	O5		Reserved
		O6		Reserved
	_	07		Reserved
	TGO5	HWOU		OCDS; ENx

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Table 2-33 Port 33 Functions

Pin	Symbol	Ctrl	Type	Function
W10	P33.0	I	LP/	General-purpose input
	TIN22		PU1/	GTM input
	DSITR0E		VEXT	DSADC channel 0 input E
	P33.0	00		General-purpose output
	TOUT22	01		GTM output
	_	O2		Reserved
	_	O3		Reserved
	_	O4		Reserved
	_	O5		Reserved
	VADCG2BFL0	06		VADC output
	_	07		Reserved
Y10	P33.1	ı	LP/	General-purpose input
	TIN23		PU1 /	GTM input
	PSIRX0C		VEXT	PSI5 input
	SENT9C			SENT input
	DSCIN2B			DSADC channel 2 input B
	DSITR1E			DSADC channel 1 input E
	P33.1	00		General-purpose output
	TOUT23	01		GTM output
	ASLSO3	02		ASCLIN3 output
	_	О3		Reserved
	DSCOUT2	04		DSADC channel 2 output
	VADCEMUX02	O5		VADC output
	VADCG2BFL1	06		VADC output
	_	07		Reserved
W11	P33.2	I	LP/	General-purpose input
	TIN24		PU1 /	GTM input
	SENT8C		VEXT	SENT input
	DSDIN2B			DSADC channel 2 input B
	DSITR2E			DSADC channel 2 input E
	P33.2	00		General-purpose output
	TOUT24	01		GTM output
	ASCLK3	O2		ASCLIN3 output
	_	О3		Reserved
	PSITX0	04		PSI5 output
	VADCEMUX01	O5		VADC output
	VADCG2BFL2	O6		VADC output
		07		Reserved



Table 2-33 Port 33 Functions (cont'd)

Pin	Symbol	Ctrl	Type	Function
Y11	P33.3	I	LP/	General-purpose input
	TIN25		PU1 /	GTM input
	PSIRX1C		VEXT	PSI5 input
	SENT7C			SENT input
	DSCIN1B			DSADC channel 1 input B
	P33.3	00		General-purpose output
	TOUT25	01		GTM output
	_	O2		Reserved
	_	О3		Reserved
	DSCOUT1	04		DSADC channel 1 output
	VADCEMUX00	O5		VADC output
	VADCG2BFL3	O6		VADC output
		07		Reserved
W12	P33.4	I	LP / PU1 / VEXT	General-purpose input
	TIN26			GTM input
	SENT6C			SENT input
	CTRAPC			CCU61 input
	DSDIN1B			DSADC channel 1 input B
	DSITR0F			DSADC channel 0 input F
	P33.4	00		General-purpose output
	TOUT26	01		GTM output
	ARTS2	O2		ASCLIN2 output
		О3		Reserved
	PSITX1	04		PSI5 output
	VADCEMUX12	O5		VADC output
	VADCG0BFL0	O6		VADC output
	_	07		Reserved



Table 2-33 Port 33 Functions (cont'd)

Pin	Symbol	Ctrl	Type	Function
Y12	P33.5	I	LP/	General-purpose input
	TIN27		PU1 /	GTM input
	ACTS2B		VEXT	ASCLIN2 input
	PSIRX2C			PSI5 input
	PSISRXC			PSI5-S input
	SENT5C			SENT input
	CCPOS2C			CCU61 input
	T4EUDB			GPT120 input
	DSCIN0B			DSADC channel 0 input B
	DSITR1F			DSADC channel 1 input F
	P33.5	00		General-purpose output
	TOUT27	01		GTM output
	SLSO07	02		QSPI0 output
	SLSO17	О3		QSPI1 output
	DSCOUT0	04		DSADC channel 0 output
	VADCEMUX11	O5		VADC output
	VADCG0BFL1	06		VADC output
	_	07		Reserved
W13	P33.6	I	LP/	General-purpose input
	TIN28		PU1/	GTM input
	SENT4C		VEXT	SENT input
	CCPOS1C			CCU61 input
	T2EUDB			GPT120 input
	DSDIN0B			DSADC channel 0 input B
	DSITR2F			DSADC channel 2 input F
	P33.6	00		General-purpose output
	TOUT28	01		GTM output
	ASLSO2	O2		ASCLIN2 output
	-	О3		Reserved
	PSITX2	04		PSI5 output
	VADCEMUX10	O5		VADC output
	VADCG1BFL0	O6		VADC output
	PSISTX	07		PSI5-S output

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Table 2-33 Port 33 Functions (cont'd)

Pin	Symbol	Ctrl	Туре	Function
Y13	P33.7	I	LP/	General-purpose input
	TIN29		PU1 /	GTM input
	RXDCAN0E		VEXT	CAN node 0 input
	REQ8			SCU input
	CCPOS0C			CCU61 input
	T2INB			GPT120 input
	P33.7	00	-	General-purpose output
	TOUT29	01	-	GTM output
	ASCLK2	O2	-	ASCLIN2 output
	SLSO37	О3	-	QSPI3 output
	_	04	-	Reserved
	_	O5	-	Reserved
	VADCG1BFL1	O6	-	VADC output
	_	07	-	Reserved
W14	P33.8	I	MP / HighZ/ VEXT	General-purpose input
	TIN30			GTM input
	ARX2E			ASCLIN2 input
	EMGSTOPA			SCU input
	P33.8	00		General-purpose output
	TOUT30	01		GTM output
	ATX2	O2		ASCLIN2 output
	SLSO32	О3		QSPI3 output
	_	04		Reserved
	TXDCAN0	O5		CAN node 0 output
	_	O6		Reserved
	COUT62	07		CCU61 output
	SMUFSP	HWOU T		SMU
Y14	P33.9	I	LP/	General-purpose input
	TIN31		PU1 /	GTM input
	P33.9	00	VEXT	General-purpose output
	TOUT31	01	-	GTM output
	ATX2	O2	-	ASCLIN2 output
	SLSO31	О3	-	QSPI3 output
	ASCLK2	04	1	ASCLIN2 output
	_	O5	-	Reserved
	_	O6	1	Reserved
	CC62	07	1	CCU61 output

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Table 2-33 Port 33 Functions (cont'd)

Pin	Symbol	Ctrl	Туре	Function
W15	P33.10	I	MP/	General-purpose input
	TIN32		PU1 /	GTM input
	SLSI3C		VEXT	QSPI3 input
	P33.10	00		General-purpose output
	TOUT32	01		GTM output
	SLSO16	O2		QSPI1 output
	SLSO311	О3		QSPI3 output
	ASLSO1	04		ASCLIN1 output
	PSISCLK	O5		PSI5-S output
		O6		Reserved
	COUT61	07		CCU61 output
Y15	P33.11	I	MP/	General-purpose input
	TIN33		PU1/	GTM input
	SCLK3D		VEXT	QSPI3 input
	P33.11	00		General-purpose output
	TOUT33	01		GTM output
	ASCLK1	O2		ASCLIN1 output
	SCLK3	О3		QSPI3 output
	_	04		Reserved
	_	O5		Reserved
	DSCGPWMN	O6		DSADC output
	CC61	07		CCU61 output
W16	P33.12	I	MP/	General-purpose input
	TIN34		PU1/	GTM input
	MTSR3D		VEXT	QSPI3 input
	P33.12	00		General-purpose output
	TOUT34	01		GTM output
	ATX1	O2		ASCLIN1 output
	MTSR3	О3		QSPI3 output
	ASCLK1	04		ASCLIN1 output
		O5		Reserved
	DSCGPWMP	O6		DSADC output
	COUT60	07		CCU61 output

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Table 2-33 Port 33 Functions (cont'd)

Pin	Symbol	Ctrl	Туре	Function
Y16	P33.13	I	MP/	General-purpose input
	TIN35		PU1 / VEXT	GTM input
	ARX1F			ASCLIN1 input
	MRST3D			QSPI3 input
	DSSGNB			DSADC input
	INJ11			MSC1 input
	P33.13	00		General-purpose output
	TOUT35	01		GTM output
	ATX1	O2		ASCLIN1 output
	MRST3	О3		QSPI3 output
	SLSO26	04		QSPI2 output
	_	O5		Reserved
	DCDCSYNC	O6		SCU output
	CC60	07		CCU61 output
T14	P33.14	I	LP/	General-purpose input
	TIN143		PU1/	GTM input
	TGI6		VEXT	OCDS input
	SCLK2D			QSPI2 input
	P33.14	00		General-purpose output
	TOUT143	01		GTM output
	_	O2		Reserved
	SCLK2	О3		QSPI2 output
	_	O4		Reserved
	_	O5		Reserved
	_	O6		Reserved
	CC62	07		CCU60 output
	TGO6	HWOU T		OCDS; ENx

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Table 2-33 Port 33 Functions (cont'd)

Pin	Symbol	Ctrl	Туре	Function
U14	P33.15	1	LP/	General-purpose input
	TIN144		PU1/	GTM input
	TGI7		VEXT	OCDS input
	P33.15	00		General-purpose output
	TOUT144	O1		GTM output
	_	O2		Reserved
	SLSO211	O3		QSPI2 output
	_	O4		Reserved
	_	O5		Reserved
	_	O6		Reserved
	COUT62	O7		CCU60 output
	TGO7	HWOU T		OCDS; ENx

Table 2-34 Port 34 Functions

Pin	Symbol	Ctrl	Туре	Function
U11	P34.1	1	LP/	General-purpose input
	TIN146		PU1/	GTM input
	P34.1	00	VEXT	General-purpose output
	TOUT146	01		GTM output
	ATX0	O2		ASCLIN0 output
	_	О3		Reserved
	TXDCAN0	04		CAN node 0 output
	_	O5		Reserved
	_	O6		Reserved
	COUT63	07		CCU60 output
T12	P34.2	1	LP / PU1 /	General-purpose input
	TIN147			GTM input
	ARX0D		VEXT	ASCLIN0 input
	RXDCAN0G			CAN node 0 input
	P34.2	00		General-purpose output
	TOUT147	01		GTM output
	_	O2		Reserved
	_	О3		Reserved
	_	04		Reserved
	_	O5		Reserved
	_	O6		Reserved
	CC60	07		CCU60 output

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Table 2-34 Port 34 Functions (cont'd)

Pin	Symbol	Ctrl	Туре	Function
U12	P34.3	I	LP/	General-purpose input
	TIN148		PU1 /	GTM input
	P34.3	00	VEXT	General-purpose output
	TOUT148	01		GTM output
	_	O2		Reserved
	_	O3		Reserved
	SLSO210	04		QSPI2 output
	_	O5		Reserved
	_	O6		Reserved
	COUT60	07		CCU60 output
T13	P34.4	I	LP/	General-purpose input
	TIN149		PU1 /	GTM input
	MRST2D		VEXT	QSPI2 input
	P34.4	00		General-purpose output
	TOUT149	01		GTM output
	_	O2		Reserved
	_	O3		Reserved
	MRST2	04		QSPI2 output
	_	O5		Reserved
	_	O6		Reserved
	CC61	07		CCU60 output
U13	P34.5	I	LP/	General-purpose input
	TIN150		PU1 /	GTM input
	MTSR2D		VEXT	QSPI2 input
	P34.5	00		General-purpose output
	TOUT150	01		GTM output
	_	O2		Reserved
	_	O3		Reserved
	MTSR2	O4		QSPI2 output
	_	O5		Reserved
	_	O6		Reserved
	COUT61	07		CCU60 output

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Table 2-35 Port 40 Functions

Pin	Symbol	Ctrl	Type	Function
W2	P40.0	I	S/	General-purpose input
	VADCG3.0		HighZ /	VADC analog input channel 0 of group 3
	DS2PB		VDDM	DSADC: positive analog input channe of DSADC 2, pin B
	CCPOS0D			CCU60 input
	SENT0A			SENT input
W1	P40.1	I	S/	General-purpose inpu.t
	VADCG3.1		HighZ /	VADC analog input channel 1 of group 3 (MD)
	DS2NB		VDDM	DSADC: negative analog of input channel 2, pin B
	CCPOS1B			CCU60 input
	SENT1A			SENT input
V2	P40.2	I	S/	General-purpose inpu.t
	VADCG3.2		HighZ /	VADC analog input channel 2 of group 3 (MD)
	CCPOS1D		VDDM	CCU60 input
	SENT2A			SENT input
V1	P40.3	I	S / HighZ / VDDM	General-purpose input
	VADCG3.3			VADC analog input channel 3 of group 3 (with pull down diagnostics)
	CCPOS2B			CCU60 input
	SENT3A			SENT input
P4	P40.4	1	S/	General-purpose input
	VADCG4.0		HighZ /	VADC analog input channel 0 of group 4
	CCPOS2D		VDDM	CCU60 input
	SENT4A			SENT input
R1	P40.5	I	S / HighZ /	General-purpose input
	VADCG4.1			VADC analog input channel 1 of group 4 (MD)
	CCPOS0D		VDDM	CCU61 input
	SENT5A			SENT input
N4	P40.6	I	S/	General-purpose input
	VADCG4.4		HighZ /	VADC analog input channel 4 of group 4
	DS3PA		VDDM	DSADC: positive analog input of channel 3, pin A
	CCPOS1B			CCU61 input
	SENT6A			SENT input
P2	P40.7	1	S/	General-purpose input
	VADCG4.5		HighZ /	VADC analog input channel 5 of group 4
	DS3NA		VDDM	DSADC: negative analog input of channel 3, pin A
	CCPOS1D			CCU61 input
	SENT7A			SENT input

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Table 2-35 Port 40 Functions (cont'd)

Pin	Symbol	Ctrl	Туре	Function
N5	P40.8	I	S/	General-purpose input
	VADCG4.6		HighZ /	VADC analog input channel 6 of group 4
	DS3PB		VDDM	DSADC: positive analog input of channel 3, pin B
	CCPOS2B			CCU61 input
	SENT8A			SENT input
P1	P40.9	I	S / HighZ / VDDM	General-purpose input
	VADCG4.7			VADC analog input channel 7 of group 4
	DS3NB			DSADC: negative analog input of channel 3, pin B
	CCPOS2D			CCU61 input
	SENT9A			SENT input

Table 2-36 Analog Inputs

Pin	Symbol	Ctrl	Туре	Function
T10	AN0	I	D/	Analog input 0
	VADCG0.0		HighZ /	VADC analog input channel 0 of group 0
	DS1PA		VDDM	DSADC: positive analog of input channel 1, pin A
U10	AN1	1	D/	Analog input 1
	VADCG0.1		HighZ /	VADC analog input channel 1 of group 0 (MD)
	DS1NA		VDDM	DSADC: negative analog input of channel 1, pin A
W9	AN2	1	D/	Analog input 2
	VADCG0.2		HighZ /	VADC analog input channel 2 of group 0 (MD)
	DS0PA		VDDM	DSADC: positive analog input of channel 0, pin A
U9	AN3	1	D / HighZ / VDDM	Analog input 3
	VADCG0.3			VADC analog input channel 3 of group 0
	DS0NA			DSADC: negative analog input of channel 0, pin A
Т9	AN4	I	D / HighZ / VDDM	Analog input 4
	VADCG0.4			VADC analog input channel 4 of group 0
Y9	AN5	1	D/	Analog input 5
	VADCG0.5		HighZ / VDDM	VADC analog input channel 5 of group 0
T8	AN6	1	D/	Analog input 6
	VADCG0.6		HighZ / VDDM	VADC analog input channel 6 of group 0
U8	AN7	I	D/	Analog input 7
	VADCG0.7		HighZ / VDDM	VADC analog input channel 7 of group 0 (with pull down diagnostics)
W8	AN8	I	D/	Analog input 8
	VADCG1.0		HighZ / VDDM	VADC analog input channel 0 of group 1

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Table 2-36 Analog Inputs (cont'd)

Pin	Symbol	Ctrl	Туре	Function
U7	AN9	I	D/	Analog input 9
	VADCG1.1		HighZ / VDDM	VADC analog input channel 1 of group 1 (MD)
Y8	AN10	I	D/	Analog input 10
	VADCG1.2		HighZ / VDDM	VADC analog input channel 2 of group 1 (MD)
W7	AN11	I	D/	Analog input 11
	VADCG1.3		HighZ / VDDM	VADC analog input channel 3 of group 1 (with pull down diagnostics)
T7	AN12	1	D/	Analog input 12
	VADCG1.4		HighZ / VDDM	VADC analog input channel 4 of group 1
W6	AN13	1	D/	Analog input 13
	VADCG1.5		HighZ / VDDM	VADC analog input channel 5 of group 1
U6	AN14	I	D/	Analog input 14
	VADCG1.6		HighZ / VDDM	VADC analog input channel 6 of group 1
T6	AN15	I	D / HighZ / VDDM	Analog input 15
	VADCG1.7			VADC analog input channel 7 of group 1
W5	AN16	I	D / HighZ / VDDM	Analog input 16
	VADCG2.0			VADC analog input channel 0 of group 2
U5	AN17	1	D/	Analog input 17
	VADCG2.1		HighZ / VDDM	VADC analog input channel 1 of group 2 (MD)
W4	AN18	1	D/	Analog input 18
	VADCG2.2		HighZ / VDDM	VADC analog input channel 2 of group 2 (MD)
W3	AN19	1	D/	Analog input 19
	VADCG2.3		HighZ / VDDM	VADC analog input channel 3 of group 2 (with pull down diagnostics)
Y3	AN20	i	D/	Analog input 20
	VADCG2.4	1	HighZ /	VADC analog input channel 4 of group 2
	DS2PA	1	VDDM	DSADC: positive analog input of channel 2, pin A
Y2	AN21	1	D/	Analog input 21
	VADCG2.5	1	HighZ /	VADC analog input channel 5 of group 2
	DS2NA	1	VDDM	DSADC: negative analog input of channel of DSADC 2, pin A
T5	AN22	I	D/	Analog input 22
	VADCG2.6		HighZ / VDDM	VADC analog input channel 6 of group 2



Table 2-36 Analog Inputs (cont'd)

Pin	Symbol	Ctrl	Туре	Function
R5	AN23	1	D/	Analog input 23
	VADCG2.7		HighZ / VDDM	VADC analog input channel 7 of group 2
W2	AN24	I	S/	Analog input 24
	VADCG3.0		HighZ /	VADC analog input channel 0 of group 3
	DS2PB		VDDM	DSADC: positive analog input of channel 2, pin B
	SENT0A			SENT input channel 0, pin A
W1	AN25	I	S/	Analog input 24
	VADCG3.1		HighZ /	VADC analog input channel 1 of group 3 (MD)
	DS2NB		VDDM	DSADC: negative analog input of channel 2, pin B
	SENT1A			SENT input channel 1, pin A
V2	AN26	1	S/	Analog input 26
	VADCG3.2		HighZ /	VADC analog input channel 2 of group 3 (MD)
	SENT2A		VDDM	SENT input channel 2, pin A
V1	AN27	I	S / HighZ / VDDM	Analog input 27
	VADCG3.3			VADC analog input channel 3 of group 3 (with pull down diagnostics)
	SENT3A			SENT input channel 3, pin A
U2	AN28	I	D / HighZ / VDDM	Analog input 28
	VADCG3.4			VADC analog input channel 4 of group 3
U1	AN29	I	D/	Analog input 29
	VADCG3.5		HighZ / VDDM	VADC analog input channel 5 of group 3
Т4	AN30	I	D/	Analog input 30
	VADCG3.6		HighZ / VDDM	VADC analog input channel 6 of group 3
R4	AN31	1	D/	Analog input 31
	VADCG3.7		HighZ / VDDM	VADC analog input channel 7 of group 3
P4	AN32	I	S/	Analog input 32
	VADCG4.0		HighZ /	VADC analog input channel 0 of group 4
	SENT4A		VDDM	SENT input channel 4, pin A
R1	AN33	1	S/	Analog input 33
	VADCG4.1		HighZ /	VADC analog input channel 1 of group 4 (MD)
	SENT5A		VDDM	SENT input channel 5, pin A
P5	AN34	I	D/	Analog input 34
	VADCG4.2		HighZ / VDDM	VADC analog input channel 2 of group 4 (MD)



Table 2-36 Analog Inputs (cont'd)

Pin	Symbol	Ctrl	Type	Function
R2	AN35	I	D/	Analog input 35
	VADCG4.3		HighZ / VDDM	VADC analog input channel 3 of group 4 (with pull down diagnostics)
N4	AN36	1	S/	Analog input 34
	VADCG4.4		HighZ /	VADC analog input channel 4 of group 4
	DS3PA		VDDM	DSADC: positive analog input of channel of DSADC 3, pin A
	SENT6A			SENT input channel 6, pin A
P2	AN37	I	S/	Analog input 37
	VADCG4.5		HighZ /	VADC analog input channel 5 of group 4
	DS3NA		VDDM	DSADC: negative analog input of channel of DSADC 3, pin A
	SENT7A			SENT input channel 7, pin A
N5	AN38	1	S/	Analog input 38
	VADCG4.6		HighZ /	VADC analog input channel 6 of group 4
	DS3PB		VDDM	DSADC: positive analog input of channel of DSADC 3, pin B
	SENT8A			SENT input channel 8, pin A
P1	AN39	I	S / HighZ / VDDM	Analog input 39
	VADCG4.7			VADC analog input channel 7 of group 4
	DS3NB			DSADC: negative analog input of channel of DSADC 3, pin B
	SENT9A			SENT input channel 9, pin A
M 5	AN40	1	D/	Analog input 40
	VADCG5.0		HighZ / VDDM	VADC analog input channel 0 of group 5
VI4	AN41	1	D/	Analog input 41
	VADCG5.1		HighZ / VDDM	VADC analog input channel 1 of group 5 (MD)
_5	AN42	I	D/	Analog input 42
	VADCG5.2		HighZ / VDDM	VADC analog input channel 2 of group 5 (MD)
_4	AN43	1	D/	Analog input 43
	VADCG5.3		HighZ / VDDM	VADC analog input channel 3 of group 5 (with pull down diagnostics)
N 1	AN44	1	D/	Analog input 44
	VADCG5.4		HighZ /	VADC analog input channel 4 of group 5
	DS3PC		VDDM	DSADC: positive analog input of channel of DSADC 3, pin C



Table 2-36 Analog Inputs (cont'd)

Pin	Symbol	Ctrl	Туре	Function
N2	AN45	1	D/	Analog input 45
	VADCG5.5		HighZ /	VADC analog input channel 5 of group 5
	DS3NC		VDDM	DSADC: negative analog input of channel of DSADC 3, pin C
M1	AN46	I	D / HighZ / VDDM	Analog input 46
	VADCG5.6			VADC analog input channel 6 of group 5
	DS3PD			DSADC: positive analog input of channel of DSADC 3, pin D
M2	AN47	1	D / HighZ / VDDM	Analog input 47
	VADCG5.7			VADC analog input channel 7 of group 5
	DS3ND			DSADC: negative analog input of channel of DSADC 3, pin D

Table 2-37 System I/O

Pin	Symbol	Ctrl	Туре	Function
G17	PORST	I	I / PD / VEXT	Power On Reset Input Additional strong PD in case of power fail.
F16	ESR0	I/O	MP / OD / VEXT	External System Request Reset 0 Default configuration during and after reset is opendrain driver. The driver drives low during power-on reset. This is valid additionally after deactivation of PORST until the internal reset phase has finished. See also SCU chapter for details. Default after power-on can be different. See also SCU chapter 'Reset Control Unit' and SCU_IOCR register description.
	EVRWUP	1		EVR Wakeup Pin
G16	ESR1	I/O	MP/PU1/ VEXT	External System Request Reset 1 Default NMI function. See also SCU chapter 'Reset Control Unit' and SCU_IOCR register description.
	EVRWUP	1		EVR Wakeup Pin
W17	VGATE1P	0	VGATE1P / -/ VEXT	External Pass Device gate control for EVR13
K16	TMS	1	A2 /	JTAG Module State Machine Control Input
	DAP1	I/O	PD / VDDP3	Device Access Port Line 1
L19	TRST	I	A2 / PD / VDDP3	JTAG Module Reset/Enable Input

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Table 2-37 System I/O (cont'd)

Pin	Symbol	Ctrl	Туре	Function
J16	TCK	I	A2 /	JTAG Module Clock Input
	DAP0	I	PD / VDDP3	Device Access Port Line 0
M20	XTAL1	I	XTAL1 / - / VDDP3	Main Oscillator/PLL/Clock Generator Input
M19	XTAL2	0	XTAL2 / - / VDDP3	Main Oscillator/PLL/Clock Generator Output

Table 2-38 Supply

Pin	Symbol	Ctrl	Type	Function
Y6	VAREF1	I	Vx	Positive Analog Reference Voltage 1
Y7	VAGND1	I	Vx	Negative Analog Reference Voltage 1
T1	VAREF2	I	Vx	Positive Analog Reference Voltage 2
T2	VAGND2	I	Vx	Negative Analog Reference Voltage 2
Y5	VDDM	I	Vx	ADC Analog Power Supply (3.3V / 5V)
G8, H7	VDD / VDDSB	I	Vx	Emulation Device: Emulation SRAM Standby Power Supply (1.3V) (Emulation Device only). Production Device: VDD (1.3V).
P8, P13, N7, N14, H14, G13	VDD	I	Vx	Digital Core Power Supply (1.3V)
N19	VDD	1	Vx	Digital Core Power Supply (1.3V). The supply pin inturn supplies the main XTAL Oscillator/PLL (1.3V). A higher decoupling capacitor is therefore recommended to the VSS pin for better noise immunity.
A2, B3, V19, W20	VEXT	I	Vx	External Power Supply (5V / 3.3V)
B18, A19	VDDP3	I	Vx	Digital Power Supply for Flash (3.3V). Can be also used as external 3.3V Power Supply for VFLEX.
N20	VDDP3	I	Vx	Digital Power Supply for Oscillator, LVDSH and A2 pads (3.3V). The supply pin inturn supplies the main XTAL Oscillator/PLL (3.3V). A higher decoupling capacitor is therefore recommended to the VSS pin for better noise immunity.

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Table 2-38 Supply (cont'd)

Pin	Symbol	Ctrl	Type	Function
E15, D16	VDDFL3	I	Vx	Flash Power Supply (3.3V)
D5	VFLEX	I	Vx	Digital Power Supply for Flex Port Pads (5V / 3.3V)
Y4	VSSM	1	Vx	Analog Ground for VDDM
T11	VEVRSB	I	Vx	Standby Power Supply (3.3V/5V) for the Standby SRAM (CPU0.DSPR). If Standby mode is not used: To be handled like VEXT (3.3V/5V).
B2, D4, E5, L20, T16, U17, W19, Y20	VSS	I	Vx	Digital Ground
E16, D17, B19, A20	VSS	I	Vx	Digital Ground (outer balls)
P9, P12, N9, N10, N11, N12	VSS	I	Vx	Digital Ground (center balls)
M7, M8, M10, M11, M13, M14	VSS	I	Vx	Digital Ground (center balls)
L8, L9, L10, L11, L12, L13	VSS	I	Vx	Digital Ground (center balls)
K8, K9, K10, K11, K12, K13	VSS	I	Vx	Digital Ground (center balls)
J7, J8, J10, J11, J13, J14	VSS	I	Vx	Digital Ground (center balls)
H9, H10, H11, H12, G9, G10, G11, G12	VSS	ı	Vx	Digital Ground (center balls)
P10	VSS	I	Vx	Digital Ground (center balls) This ball is used in the Emulation Device as AGBT TX0N
P11	VSS	1	Vx	Digital Ground (center balls) This ball is used in the Emulation Device as AGBT TX0P
L7	VSS	I	Vx	Digital Ground (center balls) This ball is used in the Emulation Device as AGBT CLKN

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Table 2-38 Supply (cont'd)

Pin	Symbol	Ctrl	Туре	Function
К7	VSS	I	Vx	Digital Ground (center balls) This ball is used in the Emulation Device as AGBT CLKP
L14	VSS	I	Vx	Digital Ground (center balls) This ball is used in the Emulation Device as AGBT ERR
K14	NC / VDDPSB	I	NCVDDP SB	Emulation Device: Power Supply (3.3V) for DAP/JTAG pad group. Can be connected to VDDP or can be left unsupplied (see document 'AurixED' / Aurix Emulation Devices specification). Production Device: This pin is not connected on package level. It can be connected on PCB level to VDDP or Ground or can be left unsupplied.
A1, Y1, U4	NC	I	NC	Not Connected. These pins are not connected on package level and will not be used for future extensions.

Legend:

Column "Ctrl.":

I = Input (for GPIO port Lines with IOCR bit field Selection PCx = 0XXX_B)

O = Output

O0 = Output with IOCR bit field selection $PCx = 1X000_{R}$

O1 = Output with IOCR bit field selection $PCx = 1X001_{R}$ (ALT1)

O2 = Output with IOCR bit field selection PCx = $1X010_{\text{B}}$ (ALT2)

O3 = Output with IOCR bit field selection PCx = $1X011_{R}$ (ALT3)

O4 = Output with IOCR bit field selection $PCx = 1X100_{R}$ (ALT4)

O5 = Output with IOCR bit field selection PCx = $1X101_B$ (ALT5)

O6 = Output with IOCR bit field selection PCx = $1X110_B$ (ALT6)

O7 = Output with IOCR bit field selection PCx = 1X111_B (ALT7)

Column "Type":

LP = Pad class LP (5V/3.3V, LVTTL)

MP = Pad class MP (5V/3.3V, LVTTL)

MP+ = Pad class MP+ (5V/3.3V, LVTTL)

MPR = Pad class MPR (5V/3.3V, LVTTL)

A2 = Pad class A2 (3.3V, LVTTL)

LVDSM = Pad class LVDSM (LVDS/CMOS 5V/3.3V)

LVDSH = Pad class LVDSH (LVDS/CMOS 3.3V)

S = Pad class S (ADC overlayed with General Purpose Input)

D = Pad class D (ADC)

 $PU = with pull-up device connected during reset (<math>\overline{PORST} = 0$)

PU1 = with pull-up device connected during reset ($\overline{PORST} = 0$)^{1) 2) 3)}

¹⁾The default state of GPIOs (Px.y) during and after PORST active is controllled via HWCFG[6] (P14.4). HWCFG[6] has a weak internal pull-up active at start-up if the pin is left unconnected. See also User's Manual, "Introduction Chapter", "General Purpose I/O Ports and Peripheral I/O Lines", Figure: "Default state of port pins during and after reset".



PD = with pull-down device connected during reset ($\overline{PORST} = 0$)

PD1 = with pull-down device connected during reset ($\overline{PORST} = 0$)^{1) 2) 3)}

PX = Behavior depends on usage: PD in EVR13 SMPS Mode and PU1 in GPIO Mode

OD = open drain during reset ($\overline{PORST} = 0$)

HighZ = tri-state during reset ($\overline{PORST} = 0$)

PORST = PORST input pad

XTAL1 = XTAL1 input pad

XTAL2 = XTAL2 input pad

VGATE1P = VGATE1P

VGATE3P = VGATE3P

Vx = Supply

NC = These pins are reserved for future extensions and shall not be connected externally

NC1 = These pins are not connected on package level and will not be used for future extensions

NCVDDPSB = This pin has a different functionality in an Production Device and an Emulation Device. For details pls. see Pin/Ball description of this pin.

NCVDDSB = This pin has a different functionality in an Production Device and an Emulation Device. For details pls. see Pin/Ball description of this pin.

2.2.2 Emergency Stop Function

The Emergency Stop function can be used to force GPIOs (General Purpose Inputs/Outputs) via an external input signal (EMGSTOPA or EMGSTOPB) into a defined state:

- · Input state and
- PU or High-Z depending on HWCFG[6] level latched during PORST active

Control of the Emergency Stop function:

- The Emergency Stop function can be enabled/disabled in the SCU (see chapter "SCU", "Emergency Stop Control")
- The Emergency Stop input signal, EMGSTOPA (P33.8) / EMGSTOPB (P21.2), can selected in the SCU (see chapter "SCU", "Emergency Stop Control")
- On port level, each GPIO can be enabled/disabled for the Emergency Stop function via the Px_ESR (Port x Emergency Stop) registers in the port control logic (see chapter "General Purpose I/O Ports and Peripheral I/O Lines", "Emergency Stop Register").

The Emergency Stop function is available for all GPIO Ports with the following exceptions:

- Not available for P20.2 (General Purpose Input/GPI only, overlayed with Testmode)
- Not available for P40.x (analoge input ANx overlayed with GPI)
- Not available for P32.0 EVR13 SMPS mode.
- Not available for dedicated I/O without General Purpose Output function (e.g ESRx, TMS, TCK)

The Emergency Stop function can be overruled on the following GPIO Ports:

- P00.x: Emergency Stop can be overruled by the VADC. Overruling can be disabled via the control register P00_SCR (see chapter "General Purpose I/O Ports and Peripheral I/O Lines", P00)
- P14.0 and P14.1: Emergency Stop can be overruled in the DXCPL mode (DAP over can physical layer mode).
 No Overruling in the DXCM (Debug over can message) mode
- P21.6: Emergency Stop can be overruled in JTAG mode if this pin is used as TDI
- P21.7: Emergency Stop can be overruled in JTAG or Three Pin DAP mode

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²⁾ If HWCFG[6] is left unconnected or is externally pulled high, weak internal pull-ups (PU1) / pull-downs (PD1) are active during and after reset.

³⁾ If HWCFG[6] is connected to ground, the PD1 / PU1 pins are predominantly in HighZ during and after reset.



• P20.0: Emergency Stop can be overruled in JTAG mode if this GPIO is used as TDI

2.2.3 Pull-Up/Pull-Down Reset Behavior of the Pins

Table 2-39 List of Pull-Up/Pull-Down Reset Behavior of the Pins

Pins	PORST = 0	PORST = 1		
all GPIOs	Pull-up if HWCFG[6] = 1 or High-Z if HWCFG[6] = 0			
TDI, TESTMODE	Pull-up			
PORST ¹⁾	Pull-down with I_{PORST} relevant	Pull-down with $I_{\rm PDLI}$ relevant		
TRST, TCK, TMS	Pull-down			
ESR0	The open-drain driver is used to drive low. ²⁾	Pull-up ³⁾		
ESR1	Pull-up ³⁾			
TDO	Pull-up	High-Z/Pull-up ⁴⁾		

¹⁾ Pull-down with I_{PORST} relevant is always activated when a primary supply monitor detects a violation.

In case of leakage test $(\overline{PORST} = 0 \text{ and } \overline{TESTMODE} = 0)$, the pull-down of the \overline{TRST} pin is switched off. In case of an user application $(\overline{TESTMODE} = 1)$, the pull-down of the \overline{TRST} is always switched on.

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²⁾Valid additionally after deactivation of PORST until the internal reset phase has finished. See the SCU chapter for details.

³⁾ See the SCU_IOCR register description.

⁴⁾ Depends on JTAG/DAP selection with TRST.



Package and Pinning DefinitionsTC270x Bare Die Pad Definition

2.3 TC270x Bare Die Pad Definition

The TC270x Bare Die Logic Symbol is shown in Figure 2-3.

Table 2-40 describes the pads of the TC270x Bare Die. It describes also the mapping of VADC / DS-ADC channels to the analog inputs (ANx) and the mapping of Port functions to the pads.

Note: The detailed description of the port functions (Px.y) can be found in the User's Manual chapter "General Purpose I/O Ports and Peripheral I/O Lines (Ports)".

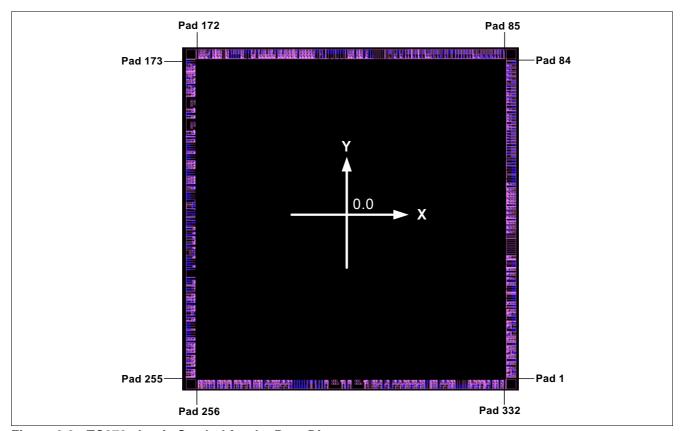


Figure 2-3 TC270x Logic Symbol for the Bare Die.

Table 2-40 List of the TC270x Bare Die Pads

Number	Pad Name	Pad Type	X	Υ	Comment
1	P10.8	LP / PU1 / VEXT	3265500	-3460000	GPIO
2	P02.0	MP+ / PU1 / VEXT	3374000	-3380000	GPIO
3	P02.9	LP / PU1 / VEXT	3265500	-3300000	GPIO
4	P02.1	LP / PU1 / VEXT	3265500	-3200000	GPIO
5	VSS	Vx	3374000	-3125000	Must be bonded to VSS
6	P02.10	LP / PU1 / VEXT	3265500	-3050000	GPIO
7	P02.2	MP+ / PU1 / VEXT	3374000	-2950000	GPIO
8	P02.11	LP / PU1 / VEXT	3265500	-2850000	GPIO
9	VEXT	Vx	3374000	-2775000	Must be bonded to VEXT
10	P02.3	LP / PU1 / VEXT	3265500	-2670000	GPIO



Package and Pinning DefinitionsTC270x Bare Die Pad Definition

Table 2-40 List of the TC270x Bare Die Pads

Number	Pad Name	Pad Type	X	Υ	Comment
11	P02.4	MP+ / PU1 / VEXT	3265500	-2540000	GPIO
12	VSS	Vx	3374000	-2465000	Must be bonded to VSS
13	P02.5	MP+ / PU1 / VEXT	3265500	-2390000	GPIO
14	P02.6	MP/PU1/VEXT	3374000	-2300000	GPIO
15	VEXT	Vx	3374000	-2195000	Must be bonded to VEXT
16	P02.7	MP/PU1/VEXT	3265500	-2110000	GPIO
17	P02.8	LP / PU1 / VEXT	3374000	-2040000	GPIO
18	VSS	Vx	3374000	-1940000	Must be bonded to VSS
19	P01.3	LP / PU1 / VEXT	3265500	-1883500	GPIO
20	VDD	Vx	3374000	-1818500	Must be bonded to VDD
21	VSS	Vx	3374000	-1688500	Must be bonded to VSS
22	VSS	Vx	3374000	-1644500	Must be bonded to VSS. Double Pad (Elephant Pad), shared with Pad Nr 22.
23	VDD	Vx	3374000	-1514500	Must be bonded to VSS. Double Pad (Elephant Pad), shared with Pad Nr 21.
24	P01.4	LP / PU1 / VEXT	3265500	-1449500	GPIO
25	VSS	Vx	3374000	-1394500	Must be bonded to VSS
26	P01.5	LP / PU1 / VEXT	3265500	-1339500	GPIO
27	P01.6	LP / PU1 / VEXT	3265500	-1239500	GPIO
28	P01.7	LP / PU1 / VEXT	3265500	-1139500	GPIO
29	VEXT	Vx	3374000	-1068500	Must be bonded to VEXT
30	VSS	Vx	3374000	-968500	Must be bonded to VSS
31	P00.0	MP/PU1/VEXT	3265500	-868500	GPIO
32	P00.1	LP / PU1 / VEXT	3265500	-241000	GPIO
33	P00.2	LP / PU1 / VEXT	3265500	-141000	GPIO
34	P00.3	LP / PU1 / VEXT	3265500	-41000	GPIO
35	VSS	Vx	3374000	19000	Must be bonded to VSS
36	P00.4	LP / PU1 / VEXT	3265500	79000	GPIO
37	P00.5	LP / PU1 / VEXT	3265500	179000	GPIO
38	P00.6	LP / PU1 / VEXT	3265500	279000	GPIO
39	VEXT	Vx	3374000	339000	Must be bonded to VEXT
40	P00.7	LP / PU1 / VEXT	3265500	399000	GPIO
41	P00.8	LP / PU1 / VEXT	3374000	459000	GPIO
42	P00.9	LP / PU1 / VEXT	3265500	549000	GPIO

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Package and Pinning DefinitionsTC270x Bare Die Pad Definition

Table 2-40 List of the TC270x Bare Die Pads

Number	Pad Name	Pad Type	X	Υ	Comment
43	P00.10	LP / PU1 / VEXT	3374000	609000	GPIO
44	P00.11	LP / PU1 / VEXT	3265500	689000	GPIO
45	VSS	Vx	3374000	749000	Must be bonded to VSS
46	P00.12	LP / PU1 / VEXT	3265500	809000	GPIO
47	VDD	Vx	3374000	864000	Must be bonded to VDD
48	VSS	Vx	3374000	964000	Must be bonded to VSS
49	VSS	Vx	3374000	1064000	Must be bonded to VSS
50	VDD	Vx	3374000	1164000	Must be bonded to VDD
51	VEXT	Vx	3265500	1239000	Must be bonded to VEXT
52	VSS	Vx	3374000	1299000	Must be bonded to VSS
53	VAREF3	Vx	3374000	1419000	Positive Analog Reference Voltage 3
54	VAREF2	Vx	3265500	1479000	Positive Analog Reference Voltage 2
55	VAGND3	Vx	3374000	1539000	Negative Analog Reference Voltage 3
56	VAGND2	Vx	3265500	1599000	Negative Analog Reference Voltage 2
57	VDDM	Vx	3374000	1659000	Must be bonded to VEXT
58	AN47 (VADC5.7/ DS3ND)	D	3265500	1719000	Analog input
59	AN46 (VADC5.6/ DS3PD)	D	3374000	1779000	Analog input
60	AN45 (VADC5.5/ DS3NC)	D	3265500	1839000	Analog input
61	AN44 (VADC5.4 / DS3PC)	D	3374000	1899000	Analog input
62	AN43 (VADC5.3)	D	3265500	1959000	Analog input (with pull down diagnostics)
63	AN42 (VADC5.2)	D	3374000	2019000	Analog input
64	AN41 (VADC5.1)	D	3265500	2079000	Analog input
65	AN40 (VADC5.0)	D	3374000	2139000	Analog input
66	AN39 (VADC4.7/ DS3NB), P40.9 (SENT9A)	S	3265500	2199000	Analog input, GPI (SENT)
67	AN38 (VADC4.6/ DS3PB), P40.8 (SENT8A)	S	3374000	2259000	Analog input, GPI (SENT)
68	AN37 (VADC4.5/ DS3NA), P40.7 (SENT7A)	S	3265500	2319000	Analog input, GPI (SENT)



Table 2-40 List of the TC270x Bare Die Pads

Number	Pad Name	Pad Type	X	Υ	Comment	
69	VDDM	Vx	3374000	2379000	Must be bonded to VEXT	
70	AN36 (VADC4.4/ DS3PA), P40.6 (SENT6A)	S	3265500	2439000	Analog input, GPI (SENT)	
71	VSSM	Vx	3374000	2499000	Must be bonded to VSS	
72	AN35 (VADC4.3)	D	3265500	2559000	Analog input (with pull down diagnostics)	
73	AN34 (VADC4.2)	D	3374000	2619000	Analog input	
74	AN33 (VADC4.1), P40.5 (SENT5A)	S	3265500	2679000	Analog input, GPI (SENT)	
75	AN32 (VADC4.0), P40.4 (SENT4A)	S	3374000	2765000	Analog input, GPI (SENT)	
76	AN31 (VADC3.7)	D	3265500	2825000	Analog input	
77	AN30 (VADC3.6)	D	3374000	2885000	Analog input	
78	AN29 (VADC3.5)	D	3265500	2945000	Analog input	
79	AN28 (VADC3.4)	D	3374000	3045000	GPIO	
80	AN27 (VADC3.3), P40.3 (SENT3A)	S	3265500	3105000	Analog input (with pull down diagnostics), GPI (SENT)	
81	AN26 (VADC3.2), P40.2 (SENT2A)	S	3265500	3205000	Analog input, GPI (SENT)	
82	AN25 (VADC3.1/ DS2NB), P40.1 (SENT1A)	S	3265500	3305000	Analog input, GPI (SENT)	
83	AN24 (VADC3.0 / DS2PB), P40.0 (SENT0A)	S	3265500	3405000	Analog input, GPI (SENT)	
84	VDDM	Vx	3374000	3465000	Must be bonded to VEXT	
85	VSSM	Vx	3134000	3705000	Must be bonded to VSS	
86	AN23 (VADC2.7)	D	3074000	3596500	Analog input	
87	AN22 (VADC2.6)	D	3014000	3705000	Analog input	
88	AN21 (VADC2.5/ DS2NA)	D	2954000	3596500	Analog input	
89	AN20 (VADC2.4/ DS2PA)	D	2854000	3596500	Analog input	
90	AN19 (VADC2.3)	D	2754000	3596500	Analog input (with pull down diagnostics)	
91	AN18 (VADC2.2)	D	2654000	3596500	Analog input	
92	AN17 (VADC2.1)	D	2554000	3596500	Analog input	

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Table 2-40 List of the TC270x Bare Die Pads

Number	Pad Name	Pad Type	X	Υ	Comment	
93	AN16 (VADC2.0)	D	2494000	3705000	Analog input	
94	AN15 (VADC1.7)	D	2434000	3596500	Analog input	
95	VAGND1	Vx	2374000	3705000	Negative Analog Reference Voltage 1	
96	VAGND0	Vx	2314000	3596500	Negative Analog Reference Voltage 0	
97	VAREF1	Vx	2254000	3705000	Positive Analog Reference Voltage 1	
98	VAREF0	Vx	2194000	3596500	Positive Analog Reference Voltage 0	
99	VSSM	Vx	2134000	3705000	Must be bonded to VSS	
100	VSSM	Vx	2074000	3596500	Must be bonded to VSS	
101	VSSMREF	Vx	2014000	3705000	Must be bonded to VSS	
102	AN14 (VADC1.6)	D	1954000	3596500	Analog input	
103	VDDM	Vx	1894000	3705000	Must be bonded to VEXT	
104	VDDM	Vx	1829000	3596500	Must be bonded to VEXT	
105	AN13 (VADC1.5)	D	1724000	3596500	Analog input	
106	AN12 (VADC1.4)	D	1664000	3705000	Analog input	
107	AN11 (VADC1.3)	D	1604000	3596500	Analog input (with pull down diagnostics)	
108	AN10 (VADC1.2)	D	1544000	3705000	Analog input	
109	AN9 (VADC1.1)	D	1484000	3569500	Analog input	
110	AN8 (VADC1.0)	D	1424000	3705000	Analog input	
111	AN7 (VADC0.7)	D	1364000	3596500	Analog input (with pull down diagnostics)	
112	AN6 (VADC0.6)	D	1304000	3705000	Analog input	
113	AN5 (VADC0.5)	D	1244000	3596500	Analog input	
114	AN4 (VADC0.4)	D	1184000	3705000	Analog input	
115	AN3 (VADC0.3 / DS0NA)	D	1124000	3596500	Analog input	
116	VSSM	Vx	1064000	3705000	Must be bonded to VSS	
117	AN2 (VADC0.2 / DS0PA)	D	1004000	3596500	Analog input	
118	VDDM	Vx	944000	3705000	Must be bonded to VEXT	
119	AN1 (VADC0.1 / DS1NA)	D	884000	3596500	Analog input	
120	AN0 (VADC0.0 / DS1PA)	D	807000	3705000	Analog input	
121	VEXT	Vx	427000	3596500	Must be bonded to VEXT	
122	VSS	Vx	377000	3705000	Must be bonded to VSS	



Table 2-40 List of the TC270x Bare Die Pads

Number	Pad Name	Pad Type	X	Y	Comment	
123	P34.1	LP / PU1 / VEXT	322000	3596500	GPIO	
124	VSS	Vx	267000	3705000	Must be bonded to VSS	
125	P34.2	LP / PU1 / VEXT	212000	3596500	GPIO	
126	P34.3	LP / PU1 / VEXT	142000	3705000	GPIO	
127	VEXT	Vx	87000	3596500	Must be bonded to VEXT	
128	P34.4	LP / PU1 / VEXT	22000	3705000	GPIO	
129	P34.5	LP / PU1 / VEXT	-38000	3596500	GPIO	
130	VSS	Vx	-93000	3705000	Must be bonded to VSS	
131	VDD	Vx	-193000	3705000	Must be bonded to VDD	
132	VSS	Vx	-323000	3705000	Must be bonded to VSS. Double Pad (Elephant Pad), shared with Pad Nr 131.	
133	VSS	Vx	x -363000 :		Must be bonded to VSS. Double Pad (Elephant Pad), shared with Pad Nr 130.	
134	VDD	Vx	-493000	3705000	Must be bonded to VDD	
135	VEVRSB	Vx	-560000	3596500	Must be bonded to VEXT	
136	EVR_OFF	Vx	-625000	3705000	Must be bonded to VSS+F178	
137	VEXT	Vx	-725000	3705000	Must be bonded to VEXT	
138	P33.0	LP / PU1 / VEXT	-790000	3596500	GPIO	
139	P33.1	LP / PU1 / VEXT	-855000	3705000	GPIO	
140	P33.2	LP / PU1 / VEXT	-915000	3596500	GPIO	
141	P33.3	LP / PU1 / VEXT	-985000	3705000	GPIO	
142	P33.4	LP / PU1 / VEXT	-1045000	3596500	GPIO	
143	VSS	Vx	-1100000	3705000	Must be bonded to VSS	
144	P33.5	LP / PU1 / VEXT	-1155000	3596500	GPIO	
145	P33.6	LP / PU1 / VEXT	-1250000	3705000	GPIO	
146	P33.7	LP / PU1 / VEXT	-1310000	3596500	GPIO	
147	P33.8	MP / HighZ / VEXT	-1420000	3705000	GPIO	
148	P33.9	LP / PU1 / VEXT	-1490000	3596500	GPIO	
149	VEXT	Vx	-1545000	3705000	Must be bonded to VEXT	
150	P33.10	MP/PU1/VEXT	-1610000	3596500	GPIO	
151	P33.14	LP / PU1 / VEXT	-1680000	3705000	GPIO	
152	P33.11	MP/PU1/VEXT	-1750000	3596500	GPIO	
153	P33.15	LP / PU1 / VEXT	-1820000	3705000	GPIO	
154	P33.12	MP/PU1/VEXT	-1890000	3596500	GPIO	

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Table 2-40 List of the TC270x Bare Die Pads

Number	Pad Name	Pad Type	X	Υ	Comment		
155	VSS	Vx	-1955000	3705000	Must be bonded to VSS		
156	P33.13	MP/PU1/VEXT	-2040000	3596500	GPIO		
157	VSS	Vx	-2105000	3705000	Must be bonded to VSS		
158	VDD	Vx	-2205000	3705000	Must be bonded to VDD		
159	P32.0	LP / EVR13 SMPS -> PD, GPIO -> PU1 / VEXT	-2260000	3596500	GPIO		
160	VGATE1N (SMPS)	VGATE1N	-2315000	3705000	Must be bonded to VSS if EVR13 SMPS is not used. Must be bonded to NMOS gate if EVR13 SMPS used		
161	VGATE1P (SMPS)	VGATE1P	-2365000	3596500	Must be bonded to VEXT if EVR13 SMPS is not used. Must be bonded to PMOS gate if EVR13 SMPS used		
162	VGATE3P (LDO)	VGATE3P	-2415000	3705000	Must be bonded to VSS		
163	VGATE1P (LDO)	VGATE1P	-2465000	3596500	Must be bonded to VSS if no external P channel MOSFET used for EVR13 LDO generation. Must be bonded to external P channnel MOSFET if external LDO pass device used.		
164	VEXT	Vx	-2515000	3705000	Must be bonded to VEXT		
165	P32.2	LP / PU1 / VEXT	-2570000	3596500	GPIO		
166	P32.3	LP / PU1 / VEXT	-2714000	3596500	GPIO		
167	P32.6	LP / PU1 / VEXT	-2774000	3705000	GPIO		
168	P32.5	LP / PU1 / VEXT	-2849000	3596500	GPIO		
169	VSS	Vx	-2904000	3705000	Must be bonded to VSS		
170	P32.4	MP+ / PU1 / VEXT	-2989000	3596500	GPIO		
171	P32.7	LP / PU1 / VEXT	-3069000	3705000	GPIO		
172	P23.0	LP / PU1 / VEXT	-3129000	3596500	GPIO		
173	VSS	Vx	-3374000	3391000	Must be bonded to VSS		
174	P23.1	MP+ / PU1 / VEXT	-3265500	3316000	GPIO		
175	P23.2	LP / PU1 / VEXT	-3374000	3236000	GPIO		
176	P23.3	LP / PU1 / VEXT	-3265500	3125000	GPIO		
177	P23.4	MP+ / PU1 / VEXT	-3374000	3045000	GPIO		

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Table 2-40 List of the TC270x Bare Die Pads

Number	Pad Name	Pad Type	X Y		Comment		
178	P23.6	LP / PU1 / VEXT	-3265500	2965000	GPIO		
179	VEXT	Vx	-3374000	2910000	Must be bonded to VEXT		
180	P23.5 MP+ / PU1 / VEXT		-3265500	2835000	GPIO		
181	P23.7	LP / PU1 / VEXT	-3374000	2755000	GPIO		
182	P22.0	MP/LVDSM_N/ PU1/VEXT	-3265500	2685000	GPIO		
183	P22.1	MP / LVDS_P / PU1 / VEXT	-3265500	2335000	GPIO		
184	VSS	Vx	-3374000	2270000	Must be bonded to VSS		
185	P22.2	MP/LVDSM_N/ PU1/VEXT	-3265500	2205000	GPIO		
186	P22.3	MP / LVDS_P / PU1 / VEXT	-3265500	1855000	GPIO		
187	VEXT	Vx	-3374000	1790000	Must be bonded to VEXT		
188	VEXT	Vx	-3265500	1735000	Must be bonded to VEXT		
189	Reserved	Vx	-3374000	1680000	Must be bonded to VSS		
190	VDD	Vx	-3374000	1580000	Must be bonded to VDD		
191	VSS	Vx	-3374000	1480000	Must be bonded to VSS		
192	P22.4	LP / PU1 / VEXT	-3265500	1425000	GPIO		
193	VSS	Vx	-3374000	1370000	Must be bonded to VSS		
194	VDD	Vx	-3374000	1270000	Must be bonded to VDD		
195	P22.5	LP / PU1 / VEXT	-3265500	1215000	GPIO		
196	P22.6	LP / PU1 / VEXT	-3374000	1155000	GPIO		
197	P22.7	LP / PU1 / VEXT	-3265500	1095000	GPIO		
198	VSS	Vx	-3374000	1040000	Must be bonded to VSS		
199	VDD	Vx	-3374000	940000	Must be bonded to VDD		
200	P22.8	LP / PU1 / VEXT	-3265500	885000	GPIO		
201	P22.9	LP / PU1 / VEXT	-3374000	825000	GPIO		
202	P22.10	LP / PU1 / VEXT	-3265500	765000	GPIO		
203	VSS	Vx	-3374000	710000	Must be bonded to VSS		
204	P22.11	LP / PU1 / VEXT	-3265500	655000	GPIO		
205	VDDOSC	Vx	-3374000	520000	Must be bonded to VDD		
206	VSSOSC	Vx	-3374000	420000	Must be bonded to VSS		
207	XTAL1	XTAL1	-3265500	312500	Main Oscillator/PLL/Clock Generator Input. Must be bonded to external quartz or resonator		



Table 2-40 List of the TC270x Bare Die Pads

Number Pad Name		Pad Type	X	Υ	Comment	
208	XTAL2	XTAL2	-3265500	212500	Main Oscillator/PLL/Clock Generator Input. Must be bonded to external quartz or resonator	
209	VSSOSC3	Vx	-3374000	105000	Must be bonded to VSS	
210	VDDOSC3	Vx	-3265500	55000	Must be bonded to VDDP3	
211	VDDP3	Vx	-3374000	-35000	Must be bonded to VDDP3	
212	VDDP3	Vx	-3265500	-95000	Must be bonded to VDDP3	
213	VSS	Vx	-3374000	-145000	Must be bonded to VSS	
214	P21.0	A2 / PU1 / VDDP3	-3374000	-245000	GPIO	
215	P21.1	A2 / PU1 / VDDP3	-3265500	-345000	GPIO	
216	VSS	Vx	-3374000	-395000	Must be bonded to VSS	
217	P21.2	LVDSH_N/PU1 /VDDP3	-3265500	-457500	GPIO	
218	P21.3	LVDSH_P/PU1 /VDDP3	-3265500	-557500	GPIO	
219	VDDP3	Vx	-3374000	-620000	Must be bonded to VDDP3	
220	P21.4	LVDSH_N/PU1 /VDDP3	-3265500	-694500	GPIO	
221	P21.5	LVDSH_P/PU1 /VDDP3	-3265500	-845500	GPIO	
222	VDD	Vx	-3374000	-920000	Must be bonded to VDD	
223	VSS	Vx	-3374000	-1020000	Must be bonded to VSS	
224	P21.6	A2 / PU / VDDP3	-3265500	-1070000	GPIO, TDI	
225	VDDP3	Vx	-3374000	-1120000	Must be bonded to VDDP3	
226	VSS	Vx	-3374000	-1345000	Must be bonded to VSS	
227	TMS / DAP1	A2 / PD / VDDP3	-3265500	-1395000	JTAG Module State Machine Control Input / Device Access Port Line 1	
228	P21.7	A2 / PU / VDDP3	-3374000	-1445000	GPIO, TDO	
229	TRST (N)	A2 / PU / VDDP3	-3265500	-1535000	JTAG Module Reset/Enable Input	
230	TCK / DAP0	A2 / PU / VDDP3	-3374000	-1585000	JTAG Module Clock Input / Device Access Port Line 0	
231	P20.0	MP/PU1/VEXT	-3265500	-1720000	GPIO	
232	P20.1	LP / PU1 / VEXT	-3374000	-1790000	GPIO	
233	P20.2	LP / PU / VEXT	-3265500	-1845000	Testmode pin must be bonded	
234	VSS	Vx	-3374000	-1895000	Must be bonded to VSS	



Table 2-40 List of the TC270x Bare Die Pads

Number	Pad Name	Pad Type	X	Υ	Comment	
235	P20.3	LP / PU1 / VEXT	-3265500	-1950000	GPIO	
236	ESR1 (N) / EVRWUP	MP/PU1/VEXT	-3374000	-2020000	External System Request Reset 1. Default NMI function. EVR Wakeup Pin.	
237	PORST (N)	I / PD1 / VEXT	-3265500	-2102500	Power On Reset Input. Additional strong PD in case of power fail.	
238	VEXT	Vx	-3374000	-2170000	Must be bonded to VEXT	
239	ESR0 (N) / EVRWUP	MP / OD	-3265500 -2235000 Exter Rese confi after drive durin		External System Request Reset 0. Default configuration during and after reset is open-drain driver. The driver drives low during power-on reset. EVR Wakeup Pin.	
240	VDD	Vx	-3374000	-2310000	Must be bonded to VDD	
241	VSS	Vx	-3374000	-2440000	Must be bonded to VSS. Double Pad (Elephant Pad), shared with Pad Nr 240.	
242	VSS	Vx	-3374000	-2480000	Must be bonded to VSS. Double Pad (Elephant Pad), shared with Pad Nr 239.	
243	VDD	Vx	-3374000	-2610000	Must be bonded to VDD	
244	P20.6	LP / PU1 / VEXT	-3265500	-2665000	GPIO	
245	VSS	Vx	-3374000	-2720000	Must be bonded to VSS	
246	P20.7	LP / PU1 / VEXT	-3265500	-2775000	GPIO	
247	P20.8	MP/PU1/VEXT	-3374000	-2865000	GPIO	
248	P20.9	LP / PU1 / VEXT	-3265500	-2935000	GPIO	
249	VEXT	Vx	-3374000	-2990000	Must be bonded to VEXT	
250	P20.10	MP/PU1/VEXT	-3265500	-3055000	GPIO	
251	P20.11	MP/PU1/VEXT	-3374000	-3155000	GPIO	
252	P20.12	MP/PU1/VEXT	-3265500	-3235000	GPIO	
253	VSS	Vx	-3374000	-3300000	Must be bonded to VSS	
254	P20.13	MP/PU1/VEXT	-3265500	-3365000	GPIO	
255	P20.14	MP/PU1/VEXT	-3265500	-3465000	GPIO	
256	P15.0	LP / PU1 / VEXT	-3134000	-3596500	GPIO	
257	P15.1	LP / PU1 / VEXT	-3034000	-3596500	GPIO	
258	P15.2	MP/PU1/VEXT	-2964000	-3705000	GPIO	
259	P15.3	MP/PU1/VEXT	-2864000	-3705000	GPIO	
260	VEXT	Vx	-2799000	-3596500	Must be bonded to VEXT	

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Table 2-40 List of the TC270x Bare Die Pads

Number	Pad Name	Pad Type	X	Υ	Comment	
261	P15.4	MP/PU1/VEXT	-2734000	-3705000	GPIO	
262	P15.5	MP/PU1/VEXT	-2634000	-3705000	GPIO	
263	P15.6	MP/PU1/VEXT	-2522000	-3596500	GPIO	
264	VSS	Vx	-2457000	-3705000	Must be bonded to VSS	
265	P15.7	MP/PU1/VEXT	-2392000	-3596500	GPIO	
266	P15.8	MP/PU1/VEXT	-2312000	-3705000	GPIO	
267	P14.0	MP+ / PU1 / VEXT	-2222000	-3596500	GPIO	
268	P14.1	MP/PU1/VEXT	-2122000	-3596500	GPIO	
269	VEXT	Vx	-2057000	-3705000	Must be bonded to VEXT	
270	P14.2	LP / PU1 / VEXT	-2002000	-3596500	Must be bonded to VEXT if EVR13 active. Must be bonded to VSS if EVR13 inactive.	
271	P14.3	LP / PU1 / VEXT	-1942000	-3705000	GPIO	
272	P14.4	LP / PU1 / VEXT	-1872000	-3596500	GPIO	
273	VSS	Vx	-1817000	-3705000	Must be bonded to VSS	
274	P14.5	MP+ / PU1 / VEXT	-1742000	-3596500	GPIO	
275	P14.6	MP+ / PU1 / VEXT	-1642000	-3705000	GPIO	
276	P14.7	LP / PU1 / VEXT	-1562000	-3596500	GPIO	
277	P14.8	LP / PU1 / VEXT	-1502000	-3705000	GPIO	
278	P14.9	MP+ / PU1 / VEXT	-1422000	-3596500	GPIO	
279	P14.10	MP+ / PU1 / VEXT	-1322000	-3596500	GPIO	
280	Reserved	Vx	-1247000	-3705000	Must be bonded to VSS	
281	VEXT	Vx	-1197000	-3596500	Must be bonded to VEXT	
282	VSS	Vx	-1147000	-3705000	Must be bonded to VSS	
283	VEXT	Vx	-1097000	-3596500	Must be bonded to VEXT	
284	VSS	Vx	-1017000	-3705000	Must be bonded to VSS. Double Pad (Elephant Pad), shared with Pad Nr 284.	
285	VDDP3	Vx	-994500	-3596500	Must be bonded to VDDP3	
286	VSS	Vx	Double Pad		Must be bonded to VSS. Double Pad (Elephant Pad), shared with Pad Nr 282.	
287	VDDP3	Vx	-877000	-3596500	Must be bonded to VDDP3	



Table 2-40 List of the TC270x Bare Die Pads

Number	Pad Name	Pad Type	X	Υ	Comment		
288	VDDFL3	Vx	-777000	-3596500	Must be bonded to VDDP3		
289	VDDFL3	Vx	-697000	-3705000	Must be bonded to VDDP3		
290	VDDFL3	Vx	-629500	-3596500	Must be bonded to VDDP3		
291	VSS	Vx	-577000	-3705000	Must be bonded to VSS		
292	P13.0	MP/LVDSM_N/ PU1 / VEXT	-512000	-3596500	GPIO		
293	P13.1	MP / LVDS_P / PU1 / VEXT	-162000	-3596500	GPIO		
294	VEXT	Vx	-97000	-3705000	Must be bonded to VEXT		
295	P13.2	MP/LVDSM_N/ PU1 / VEXT	-32000	-3596500	GPIO		
296	P13.3	MP / LVDS_P / PU1 / VEXT	318000	-3596500	GPIO		
297	P12.0	LP / PU1 / VFLEX	458000	-3596500	GPIO		
298	P12.1	LP / PU1 / VFLEX	518000	-3705000	GPIO		
299	P11.0	MP+ / PU1 / VFLEX	598000	-3596500	GPIO		
300	VSSFLEX	Vx	673000	-3705000	Must be bonded to VSS		
301	P11.1	MP+ / PU1 / VFLEX	748000	-3596500	GPIO		
302	VFLEX	Vx	823000	-3705000	Must be bonded to VEXT or VDDP3		
303	P11.2	MPR / PU1 / VFLEX	898000	-3596500	GPIO		
304	P11.3	MPR / PU1 / VFLEX	998000	-3596500	GPIO		
305	P11.4	MP+ / PU1 / VFLEX	1098000	-3705000	GPIO		
306	P11.5	LP / PU1 / VFLEX	1178000	-3596500	GPIO		
307	P11.6	MPR / PU1 / VFLEX	1258000	-3705000	GPIO		
308	P11.7	LP / PU1 / VFLEX	1338000	-3596500	GPIO		
309	P11.9	MP+ / PU1 / VFLEX	1418000	-3705000	GPIO		
310	P11.8	LP / PU1 / VFLEX	1498000	-3596500	GPIO		
311	VSSFLEX	Vx	1553000	-3705000	Must be bonded to VSS		



Table 2-40 List of the TC270x Bare Die Pads

Number	Pad Name	ad Name Pad Type		Y	Comment	
312	VFLEX	Vx	1603000	-3596500	Must be bonded to VEXT or VDDP3	
313	P11.10	LP / PU1 / VFLEX	1698000	-3705000	GPIO	
314	P11.13	LP / PU1 / VFLEX	1758000	-3596500	GPIO	
315	VSSFLEX	Vx	1813000	-3705000	Must be bonded to VSS	
316	P11.11	MP+ / PU1 / VFLEX	1888000	-3596500	GPIO	
317	P11.12	MPR / PU1 / VFLEX	1988000	-3596500	GPIO	
318	P11.14	LP / PU1 / VFLEX	2068000	-3705000	GPIO	
319	P11.15	LP / PU1 / VFLEX	2128000	-3596500	GPIO	
320	VDD	Vx	2183000	-3705000	Must be bonded to VDD	
321	VSS	Vx	2283000	-3705000	Must be bonded to VSS	
322	VSS	Vx	2403000	-3705000	Must be bonded to VSS	
323	P10.0	LP / PU1 / VEXT	2458000	-3596500	GPIO	
324	P10.1	MP+ / PU1 / VEXT	2543000	-3705000	GPIO	
325	P10.2	MP/PU1/VEXT	2643000	-3705000	GPIO	
326	P10.3	MP/PU1/VEXT	2723000	-3596500	GPIO	
327	P10.4	MP+ / PU1 / VEXT	2834000	-3705000	GPIO	
328	VEXT	Vx	2909000	-3596500	Must be bonded to VEXT	
329	P10.5	LP / PU1 / VEXT	2964000 -3705000 GPIO		GPIO	
330	P10.6	LP / PU1 / VEXT	3024000	-3596500	GPIO	
331	VSS	Vx	3079000	-3705000	Must be bonded to VSS	
332	P10.7	LP / PU1 / VEXT	3134000	-3596500	GPIO	

Legend:

Column "Number":

Running number of pads in the pad frame

Column "Name":

Symbolic name of the pad.

The functions mapped on GPIO pads "Px.y" are described in the User's Manual chapter "General Purpose I/O Ports and Peripheral I/O Lines (Ports)"

Column "Type":

LP = Pad class LP (5V/3.3V, LVTTL)

MP = Pad class MP (5V/3.3V, LVTTL)

MP+ = Pad class MP+ (5V/3.3V, LVTTL)

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MPR = Pad class MPR (5V/3.3V, LVTTL)

A2 = Pad class A2 (3.3V, LVTTL)

LVDSM = Pad class LVDSM (LVDS/CMOS 5V/3.3V)

LVDSH = Pad class LVDSH (LVDS/CMOS 3.3V)

S = Pad class S (ADC overlayed with General Purpose Input)

D = Pad class D (ADC)

 $PU = with pull-up device connected during reset (<math>\overline{PORST} = 0$)

PU1 = with pull-up device connected during reset ($\overline{PORST} = 0$)^{1) 2) 3)}

PD = with pull-down device connected during reset ($\overline{PORST} = 0$)

PD1 = with pull-down device connected during reset ($\overline{PORST} = 0$)^{1) 2) 3)}

PX = Behavior depends on usage: PD in EVR13 SMPS Mode and PU1 in GPIO Mode

OD = open drain during reset ($\overline{PORST} = 0$)

HighZ = tri-state during reset ($\overline{PORST} = 0$)

PORST = PORST input pad

XTAL1 = XTAL1 input pad

XTAL2 = XTAL2 input pad

VGATE1P = VGATE1P

VGATE3P = VGATE3P

Vx = Supply

NC = These pins are reserved for future extensions and shall not be connected externally

NC1 = These pins are not connected on package level and will not be used for future extensions

NCVDDPSB = This pin has a different functionality in an Production Device and an Emulation Device. For details pls. see Pin/Ball description of this pin.

NCVDDSB = This pin has a different functionality in an Production Device and an Emulation Device. For details pls. see Pin/Ball description of this pin.

Column "X" / "Y":

Pad opening center coordinates (in nm)

2.3.1 Pad Openings

Two different pad openings are used:

- Standard Pad Opening is 70um x 75um where 70um is the width of the opening (width as seen from the die side) and 75um is the depth of the opening (from the die side into the silicon).
- Double Pad or Elephant Pad Opening is 130um x 75um where 130um is the width of the opening (width as seen from the die side) and 75um is the depth of the opening (from the die side into the silicon). The Double Pad openings are represented with two opening coordinates and two pad numbers. Double Pads are used only for supply and can be identified by the words 'Double Pad' or 'Elephant Pad' in the Comment column.

2.3.2 Emergency Stop Function

The Emergency Stop function can be used to force GPIOs (General Purpose Inputs/Outputs) via an external input signal (EMGSTOPA or EMGSTOPB) into a defined state:

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¹⁾The default state of GPIOs (Px.y) during and after PORST active is controllled via HWCFG[6] (P14.4). HWCFG[6] has a weak internal pull-up active at start-up if the pin is left unconnected. See also User's Manual, "Introduction Chapter", "General Purpose I/O Ports and Peripheral I/O Lines", Figure: "Default state of port pins during and after reset".

²⁾ If HWCFG[6] is left unconnected or is externally pulled high, weak internal pull-ups are active at GPIOs (Px.y) pins during and after reset. Exceptions are P33.8 (HighZ), P40.x (default configuration during and after reset: analog inputs, port input funtion disabled), ESR0, P21.6 / P21.7 (port pins overlayed with JTAG functionality).

³⁾ If HWCFG[6] is connected to ground, port pins are predominantly in HighZ during and after reset. Exceptions are P33.8 (HighZ), P40.x (default configuration during and after reset: analog inputs, port input funtion disabled), ESR0, P21.6 / P21.7 (port pins overlayed with JTAG functionality).



- Input state and
- PU or HighZ depending on HWCFG[6] level latched during PORST active

Control of the Emergency Stop function:

- The Emergency Stop function can be enabled/disabled in the SCU (see chapter "SCU", "Emergency Stop Control")
- The Emergency Stop input signal, EMGSTOPA (P33.8) / EMGSTOPB (P21.2), can selected in the SCU (see chapter "SCU", "Emergency Stop Control")
- On port level, each GPIO can be enabled/disabled for the Emergency Stop function via the Px_ESR (Port x Emergency Stop) registers in the port control logic (see chapter "General Purpose I/O Ports and Peripheral I/O Lines", "Emergency Stop Register").

The Emergency Stop function is available for all GPIO Ports with the following exceptions:

- Not available for P20.2 (General Purpose Input/GPI only, overlayed with Testmode)
- Not available for P40.x (analoge input ANx overlayed with GPI)
- Not available for P32.0 EVR13 SMPS mode.
- Not available for dedicated I/O without General Purpose Output function (e.g ESRx, TMS, TCK)

The Emergency Stop function can be overruled on the following GPIO Ports:

- P00.x: Emergency Stop can be overruled by the VADC. Overruling can be disabled via the control register
 P00 SCR (see chapter "General Purpose I/O Ports and Peripheral I/O Lines", P00)
- P14.0 and P14.1: Emergency Stop can be overruled in the DXCPL mode (DAP over can physical layer mode).
 No Overruling in the DXCM (Debug over can message) mode
- P21.6: Emergency Stop can be overruled in JTAG mode if this pin is used as TDI
- P21.7: Emergency Stop can be overruled in JTAG or Three Pin DAP mode
- P20.0: Emergency Stop can be overruled in JTAG mode if this GPIO is used as TDI

2.3.3 Pull-Up/Pull-Down Reset Behavior of the Pins

Table 2-41 List of Pull-Up/Pull-Down Reset Behavior of the Pins

Pins	PORST = 0	PORST = 1		
all GPIOs	Pull-up if HWCFG[6] = 1 or High-Z if HWCFG[6] = 0			
TDI, TESTMODE	Pull-up			
PORST ¹⁾	Pull-down with I_{PORST} relevant	Pull-down with $I_{\rm PDLI}$ relevant		
TRST, TCK, TMS	Pull-down			
ESR0	The open-drain driver is used to drive low. ²⁾	Pull-up ³⁾		
ESR1	Pull-up ³⁾			
TDO	Pull-up	High-Z/Pull-up ⁴⁾		

- 1) Pull-down with I_{PORST} relevant is always activated when a primary supply monitor detects a violation.
- 2) Valid additionally after deactivation of PORST until the internal reset phase has finished. See the SCU chapter for details.
- 3) See the SCU_IOCR register description.
- 4) Depends on JTAG/DAP selection with TRST.
- In case of leakage test (PORST = 0 and TESTMODE = 0), the pull-down of the TRST pin is switched off. In case of an user application (TESTMODE = 1), the pull-down of the TRST is always switched on.

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Electrical SpecificationParameter Interpretation

3 Electrical Specification

3.1 Parameter Interpretation

The parameters listed in this section partly represent the characteristics of the TC270 / TC275 / TC277 and partly its requirements on the system. To aid interpreting the parameters easily when evaluating them for a design, they are marked with an two-letter abbreviation in column "Symbol":

· cc

Such parameters indicate **C**ontroller **C**haracteristics which are a distinctive feature of the TC270 / TC275 / TC277 and must be regarded for a system design.

SR

Such parameters indicate **S**ystem Requirements which must provided by the microcontroller system in which the TC270 / TC275 / TC277 designed in.



Electrical SpecificationAbsolute Maximum Ratings

3.2 Absolute Maximum Ratings

Stresses above the values listed under "Absolute Maximum Ratings" may cause permanent damage to the device. This is a stress rating only and functional operation of the device at these or any other conditions above those indicated in the Operational Conditions of this specification is not implied. Exposure to absolute maximum rating conditions may affect device reliability.

Table 3-1 Absolute Maximum Ratings

Parameter	Symbol Values			S	Unit	Note / Test Condition
		Min.	Тур.	Max.		
Storage Temperature	$T_{\rm ST}{ m SR}$	-65	-	170	°C	upto 65h @ $T_{\rm J}$ = 150°C; upto 15h @ $T_{\rm J}$ = 170°C
Voltage at $V_{\rm DD}$ power supply pins with respect to $V_{\rm SS}$ 1)	$V_{\mathrm{DD}}\mathrm{SR}$	-	-	1.9	V	
Voltage at $V_{\rm DDP3}$ and $V_{\rm DDFL3}$ power supply pins with respect to $V_{\rm SS}$ 1)	$V_{\mathrm{DDP3}}\mathrm{SR}$	-	-	4.43	V	
Voltage at $V_{\rm DDM}$, $V_{\rm EXT}$ and $V_{\rm FLEX}$ power supply pins with respect to $V_{\rm SS}$ 1)	$V_{DDM}SR$	-	-	7.0	V	
Voltage on any class A2 and LVDSH input pin with respect to $V_{\rm SS}^{-1)2)}$	V _{IN} SR	-0.5	-	$\begin{array}{c} \text{min(} \\ V_{\text{DDP3}} + \\ 0.6 \text{ , 4.23} \\) \end{array}$	V	Whatever is lower
Voltage on all other input pins with respect to $V_{\rm SS}$ ¹⁾²⁾	$V_{IN}SR$	-0.5	-	7.0	V	
Input current on any pin during overload condition ³⁾	I _{IN} SR	-10	-	10	mA	
Absolute maximum sum of all input circuit currents during overload condition ³⁾	ΣI_{IN} SR	-100	-	100	mA	

¹⁾ Valid for cumulated for up to 2.8h and pulse forms following a power supply switch on phase, where the rise and fall times are releated to the system capacities and coils.

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²⁾ Voltages below V_{INmin} have no Impact to the device reliability as Long as the times and currents defined in section Pin Reliability in Overload for the affected pad(s) are not violated.

³⁾ This parameter is an Absolute Maximum Rating. Exposure to Absolute Maximum Ratings for extended periods of time may damage the device.



Electrical SpecificationPin Reliability in Overload

3.3 Pin Reliability in Overload

When receiving signals from higher voltage devices, low-voltage devices experience overload currents and voltages that go beyond their own IO power supplies specification.

The following table defines overload conditions that will not cause any negative reliability impact if all the following conditions are met:

- full operation life-time is not exceeded
- Operating Conditions are met for
 - pad supply levels
 - temperature

If a pin current is out of the **Operating Conditions** but within the overload parameters, then the parameters functionality of this pin as stated in the Operating Conditions can no longer be guaranteed. Operation is still possible in most cases but with relaxed parameters.

Note: An overload condition on one or more pins does not require a reset.

Table 3-2 Overload Parameters

Parameter	Symbol		Values			Note / Test Condition
		Min.	Тур.	Max.		
Input current on any digital pin	I_{IN}	-5	-	5	mA	except LVDS pins
during overload condition		-15 ¹⁾	-	15 ¹⁾	mA	except LVDS pins; limited to max. 20 pulses with 1ms pulse length
Input current on LVDS pin during overload condition	I_{INLVDS}	-3	-	3	mA	
Absolute maximum sum of all input circuit currents during overload condition	I_{ING}	-50	-	50	mA	
Input current on analog input	I_{INANA}	-3	-	3	mA	
pin during overload condition		-5	-	5	mA	limited to 60h over
Absolute sum of all ADC inputs during overload condition	I_{INSCA}	-20	-	20	mA	
Absolute maximum sum of all input circuit currents during overload condition	ΣI_{INS}	-100	-	100	mA	
Signal voltage over/undershoot at GPIOs	V _{OUS}	V _{SS} - 2	-	V _{EXT/FLEX} + 2	V	limited to 60h over lifetime; Valid for LP, MP, MP+, and MPR pads
Inactive device pin current during overload condtion ²⁾	I_{ID}	-1	-	1	mA	All power supply voltages $V_{\rm DDx}$ = 0
Sum of all inactive device pin currents ²⁾	I_{IDS}	-100	-	100	mA	

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Electrical SpecificationPin Reliability in Overload

Table 3-2 Overload Parameters (cont'd)

Parameter	Symbol	Values			Unit	Note / Test Condition
		Min.	Тур.	Max.		
Overload coupling factor for digital inputs, negative ³⁾	K _{OVDN} CC	-	2*10-4	6*10 ⁻⁴		Overload injected on GPIO non LVDS pad and affecting neighbor LP and A2 pads; -2mA < I _{IN} < 0mA
		-	-	1*10 ⁻²		Overload injected on GPIO non LVDS pad and affecting neighbor LP and A2 pads; -5mA < I_{IN} < -2mA
		-	-	1.7*10 ⁻³		Overload injected on GPIO non LVDS pad and affecting neighbor MP, MP+, and MPR pads; -2mA < $I_{\rm IN}$ < 0mA
		-	-	2*10 ⁻²		Overload injected on GPIO non LVDS pad and affecting neighbor MP, MP+, and MPR pads; -5mA < I_{IN} < - 2mA
			-	-	0.3	
		-	-	0.93		coupling between pads 21.2 and 21.3
Overload coupling factor for digital inputs, positive ³⁾	K _{OVDP} CC	-	-	1*10 ⁻⁵		Overload injected on GPIO non LVDS pad and affecting neighbor GPIO non LVDS pads
		-	-	1*10 ⁻⁴		Overload injected on GPIO pad and affecting neighbor P32.0 pad
		-	-	5*10 ⁻⁴		Overload injected on LVDS pad and affecting neighbor LVDS pads



Electrical SpecificationPin Reliability in Overload

Table 3-2 Overload Parameters (cont'd)

Parameter	Symbol		Value	s	Unit	Note / Test Condition
		Min.	Тур.	Max.		
Overload coupling factor for analog inputs, negative	K _{OVAN} CC	-	-	6*10 ^{-4 4)}		Analog Inputs overlaid with class LP pads or pull down diagnostics; $-1mA < I_{IN} < 0mA$
		-	-	1*10 ⁻²		Analog Inputs overlaid with class LP pads or pull down diagnostics; $-5\text{mA} < I_{\text{IN}} < -1\text{mA}$
		-	-	1*10 ⁻⁴		else; -5mA < I_{IN} < 0mA
Overload coupling factor for analog inputs, positive	K _{OVAP} CC	-	-	1*10 ⁻⁵		5mA < I _{IN} < 0mA

- 1) Reduced VADC / DSADC result accuracy and / or GPIO input levels ($V_{\rm IL}$ and $V_{\rm IH}$) can differ from specified parameters.
- 2) Limitations for time and supply levels specified in this section are not valid for this parameter.
- 3) Overload is measured as increase of pad leakage caused by injection on neighbor pad.
- 4) For analogue inputs overlaid with DSADC function the VCM holdbuffer shall be enabled, in case DSADCs are enabled.

Note: DSADC input pins count as analog pins as they are overlaid with VADC pins.

Table 3-3 PN-Junction Characteristics for positive Overload

Pad Type	I_{IN} = 3 mA	I_{IN} = 5 mA
F / A2	U_{IN} = V_{DDP3} + 0.5 V	U_{IN} = V_{DDP3} + 0.6 V
LP / MP / MP+ / MPR	U_{IN} = $V_{\text{EXT/FLEX}}$ + 0.75 V	U_{IN} = $V_{\mathrm{EXT/FLEX}}$ + 0.8 V
LVDSM	U_{IN} = V_{EXT} + 0.75 V	-
LVDSH	U_{IN} = V_{DDP3} + 0.5 V	-
D	$U_{\rm IN}$ = $V_{\rm DDM}$ + 0.75 V	-

Table 3-4 PN-Junction Characteristics for negative Overload

Pad Type	I_{IN} = -3 mA	I_{IN} = -5 mA	
F / A2	U_{IN} = V_{SS} - 0.5 V	U_{IN} = V_{SS} - 0.6 V	
LP / MP / MP+ / MPR	$U_{\rm IN}$ = $V_{\rm SS}$ - 0.75 V	U_{IN} = V_{SS} - 0.8 V	
LVDSM	$U_{\rm IN}$ = $V_{\rm SS}$ - 0.75 V	-	
LVDSH	U_{IN} = V_{SS} - 0.5 V	-	
D	$U_{\rm IN}$ = $V_{\rm SS}$ - 0.75 V	-	

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Electrical SpecificationOperating Conditions

3.4 Operating Conditions

The following operating conditions must not be exceeded in order to ensure correct operation and reliability of the TC270 / TC275 / TC277. All parameters specified in the following tables refer to these operating conditions, unless otherwise noticed.

Digital supply voltages applied to the TC270 / TC275 / TC277 must be static regulated voltages.

All parameters specified in the following tables refer to these operating conditions (see table below), unless otherwise noticed in the Note / Test Condition column.

Table 3-5 Operating Conditions

Parameter	Symbol	Values			Unit	Note / Test Condition
		Min.	Тур.	Max.		
SRI frequency	$f_{\rm SRI}{\rm SR}$	-	-	200	MHz	
Max System Frequency	$f_{MAX}SR$	-	-	200	MHz	
CPU0 Frequency	$f_{\rm CPU0}{\rm SR}$	-	-	200	MHz	
CPU1 Frequency	$f_{\mathrm{CPU1}}\mathrm{SR}$	-	-	200	MHz	
CPU2 Frequency	$f_{\mathrm{CPU2}}\mathrm{SR}$	-	-	200	MHz	
PLL output frequency	$f_{PLL}SR$	20	-	200	MHz	
PLL_ERAY output frequency	$f_{PLLERAY}SR$	20	-	400	MHz	
SPB frequency	$f_{\rm SPB}{\rm SR}$	-	-	100	MHz	
ASCLIN fast frequency	$f_{ASCLINF}SR$	-	-	200	MHz	
ASCLIN slow frequency	$f_{ASCLINS}SR$	-	-	100	MHz	
Baud2 frequency	$f_{\rm BAUD2}{\rm SR}$	-	-	200	MHz	
Baud1 frequency	$f_{\rm BAUD1}{ m SR}$	-	-	100	MHz	
FSI2 frequency	$f_{\rm FSI2}{\rm SR}$	-	-	200	MHz	
FSI frequency	$f_{FSI}SR$	-	-	100	MHz	
GTM frequency	$f_{GTM}SR$	-	-	100	MHz	
STM frequency	$f_{STM}SR$	-	-	100	MHz	
ERAY frequency	$f_{ERAY}SR$	-	-	80	MHz	
BBB frequency	$f_{BBB}SR$	-	-	100	MHz	
MultiCAN frequency	$f_{\sf CAN}{\sf SR}$	-	-	100	MHz	
Absolute sum of short circuit currents of the device	ΣI_{SC_D} SR	-	-	100	mA	
Ambient Temperature	$T_{A}SR$	-40	-	125	°C	valid for all SAK products
		-40	-	150	°C	valid for all SAL products
		-40	-	170	°C	valid for all SAL products without package
Junction Temperature	$T_{J}SR$	-40	-	150	°C	valid for all SAK products
		-40	-	170	°C	valid for all SAL products

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Electrical SpecificationOperating Conditions

Table 3-5 Operating Conditions (cont'd)

Parameter	Symbol		Value	s	Unit	Note / Test Condition
		Min.	Тур.	Max.		
Core Supply Voltage 1)	$V_{\mathrm{DD}}\mathrm{SR}$	1.17	1.3	1.43 ²⁾	V	Only required if externally supplied
ADC analog supply voltage	$V_{DDM}SR$	2.97	5.0	5.5 ³⁾	V	
Digital external supply voltage for LP, MP, MP+ and LVDSM	$V_{EXT}SR$	2.97	-	4.5	V	3.3V pad parameters are valid
pads and EVR 4)		4.5	5.0	5.5 ³⁾	V	5V pad parameters are valid
Digital supply voltage for Flex port	$V_{FLEX}SR$	2.97	-	4.5	V	3.3V pad parameters are valid
		4.5	5.0	5.5 ³⁾	V	5V pad parameters are valid
Digital supply voltage for LVDSH and A2 pads ⁵⁾	$V_{\mathrm{DDP3}}\mathrm{SR}$	2.97	3.3	3.63 ⁶⁾	V	3.3V pad parameters are valid; only required if externally supplied
Flash supply voltage 3.3V ¹⁾	$V_{\mathrm{DDFL3}}\mathrm{SR}$	2.97	3.3	3.63	V	Only required if externally supplied
Digital ground voltage	$V_{\rm SS}$ SR	0	-	-	V	
Analog ground voltage for $V_{\rm DDM}$	V_{SSM} CC	-0.1	0	0.1	V	
Voltage to ensure defined pad	$V_{DDPPA}CC$	0.72	-	-	V	A2 and LVDSH
states ⁷⁾		1.4	-	-	V	LP, MP, MP+, MPR and LVDSM
Digital external supply voltage for EVR and during Standby mode	$V_{EVRSB}SR$	2.97	-	5.5	V	only available in BGA package. $V_{\rm EVRSB}$ is bonded together with $V_{\rm EXT}$ supply pin in LQFP package.

- 1) No external inductive load permissible if EVR is used. All $V_{\rm DD}$ pins shall be connected together externally on the PCB.
- 2) Voltage overshoot to 1.69V is permissible, provided the duration is less than 2h cumulated. Reduced ADC accuracy and leakage is increased.
- 3) Voltage overshoot to 6.5V is permissible, provided the duration is less than 2h cumulated. Reduced ADC accuracy and leakage is increased.
- 4) All $V_{\rm EXT}$ pins shall be connected together externally on the PCB.
- 5) All $V_{\rm DDP3}$ pins shall be connected together externally on the PCB.
- 6) Voltage overshoot to 4.29V is permissible, provided the duration is less than 2h cumulated. Reduced ADC accuracy and leakage is increased.
- 7) This parameter is valid under the assumption the PORST signal is constantly at low level during the power-up/power-down of $V_{\rm DDP3}$.

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3.5 5 V / 3.3 V switchable Pads

Pad classes LP, MP, MP+, and MPR support both Automotive Level (AL) or TTL level (TTL) operation. Parameters are defined for AL operation and degrade in TTL operation.

Table 3-6 Standard_Pads

Parameter	Symbol Values				Unit	Note / Test Condition
		Min.	Тур.	Max.		
Pin capacitance (digital inputs/outputs)	C_{IO} CC	-	6	10	pF	
Spike filter always blocked pulse duration	t _{SF1} CC	-	-	80	ns	PORST only
Spike filter pass-through pulse duration	t _{SF2} CC	220	-	-	ns	PORST only
PORST pad output current 1)	I _{PORST} CC	11	-	-	mA	V_{EXT} = 3.0V; V_{PORST} = 0.9V; T_{J} = 165°C
		13	-	-	mA	V_{EXT} = 4.5V; V_{PORST} = 1.0V

¹⁾ Pull-down with I_{PORST} relevant is always activated when a primary supply monitor detects a violation.

Table 3-7 Class LP 5V

Parameter	Symbol		Value	s	Unit	Note / Test Condition
		Min.	Тур.	Max.		
Input frequency	$f_{IN}SR$	-	-	75	MHz	Hysteresis active
		-	-	150	MHz	Hysteresis inactive
Input Hysteresis for LP pad 1)	HYSLP CC	$0.09 * V_{EXT/FLEX}$	-	-	V	AL
		0.075 * $V_{EXT/FLEX}$	-	-	V	TTL
Input Leakage current for LP pad	I _{OZLP} CC	-150	-	150	nA	$ (0.1*V_{\rm EXT/FLEX}) < V_{\rm IN} < $ $ (0.9*V_{\rm EXT/FLEX}) $
		-350	-	350	nA	else
Input leakage current for P32.0	I _{OZP320} CC	-4900	-	4900	nA	$ (0.1*V_{\rm EXT/FLEX}) < V_{\rm IN} < $ $ (0.9*V_{\rm EXT/FLEX}) $
		-9400	-	9400	nA	$(0.1*V_{\rm EXT/FLEX}) < V_{\rm IN} < (0.9*V_{\rm EXT/FLEX});$ for $T_{\rm J} > 150^{\circ}{\rm C}$
		-5800	-	5800	nA	else
		-12000	-	12000	nA	else; for $T_{\rm J}$ > 150°C
Pull-up current for LP pad	I_{PUHLP} CC	30	-	-	μA	$V_{IHmin};AL$
		43	-	-	μA	$V_{IHmin};TTL$
		-	-	107	μΑ	V_{ILmax} ; AL and TTL



Table 3-7 Class LP 5V (cont'd)

Parameter	Symbol		Value	s	Unit	Note / Test Condition
		Min.	Тур.	Max.		
Pull-down current for LP pad	I_{PDLLP} CC	-	-	[100]	μΑ	V_{IHmin} ; AL and TTL
		46	-	-	μΑ	$V_{ILmax};AL$
		21	-	-	μΑ	$V_{ILmax}; TTL$
On-Resistance for LP pad, weak driver ²⁾	R _{DSONLPW} CC	200	620	1040	Ohm	$\begin{array}{c} {\rm PMOS/NMOS}~;\\ I_{\rm OH} {\rm =}0.5 {\rm mA}~;\\ I_{\rm OL} {\rm =}0.5 {\rm mA} \end{array}$
On-Resistance for LP pad, medium driver ²⁾	R _{DSONLPM} CC	50	155	260	Ohm	$\begin{array}{c} {\rm PMOS/NMOS} \; ; \\ I_{\rm OH} {\rm = 2mA} \; ; \; I_{\rm OL} {\rm = 2mA} \end{array}$
Rise / fall time for LP pad ³⁾	t _{LP} CC	-	-	95+2.1 * C _L	ns	C _L ≤50pF ; pin out driver=weak
		-	-	200+2.9 * (C _L - 50)	ns	$C_{L} \ge 50 \text{pF}$; $C_{L} \le 200 \text{pF}$; pin out driver=weak
		-	-	25+0.5 * C _L	ns	$C_L \le 50 pF$; pin out driver=medium
		-	-	50+0.75 * (C_{L} - 50)	ns	$C_{\rm L} \ge 50 {\rm pF}$; $C_{\rm L} \le 200 {\rm pF}$; pin out driver=medium
Input high voltage for LP pad	$V_{IHLP}SR$	(0.73*V _{EX} _{T/FLEX})- 0.25	-	-	V	Hysteresis active, AL
		2.03 4)	-	-	V	Hysteresis active, TTL
Input low voltage for LP pad	$V_{\rm ILLP}{ m SR}$	-	-	(0.52*V _{EX} _{T/FLEX})- 0.25	V	Hysteresis active, AL
		-	-	0.8 5)	V	Hysteresis active, TTL
Input low / high voltage for LP pad	V_{ILHLP} CC	1.85	-	3.0	V	Hysteresis inactive; not available for P14.2, P14.4, and P15.1
Pad set-up time for LP pad	t _{SET_LP} CC	-	-	100	ns	
Input leakage current for P02.1	I _{OZ021} CC	-150	-	1030	nA	$(0.1*V_{\rm EXT/FLEX}) < V_{\rm IN} < \ (0.9*V_{\rm EXT/FLEX}); T_{\rm J} > \ 150°{\rm C}$
		-150	-	340	nA	$(0.1*V_{\rm EXT/FLEX}) < V_{\rm IN} < (0.9*V_{\rm EXT/FLEX}); T_{\rm J} = 150°{\rm C}$
		-420	-	1100	nA	else; <i>T</i> _J > 150°C
		-350	-	380	nA	else; $T_{\rm J}$ = 150°C
Pull down current for P32_0 pin	I_{PDLP320} CC	-	-	105	μΑ	V_{IHmin} ; AL and TTL
		41	-	-	μΑ	$V_{ILmax};AL$
		16	-	-	μΑ	$V_{ILmax}; TTL$



Table 3-7 Class LP 5V (cont'd)

Parameter	Symbol		Values			Note / Test Condition
		Min.	Тур.	Max.		
Pull Up Current for P32_0 pin	I _{PUHP320} CC	25	-	-	μΑ	$V_{IHmin};AL$
		38	-	-	μΑ	$V_{IHmin};TTL$
		-	-	112	μΑ	V_{ILmax} ; AL and TTL
Short Circuit current for LP pad 6)	$I_{ m SC}$ SR	-10	-	10	mA	absolute max value (PSI5)
Deviation of symmetry for rising and falling edges	SYM CC	-	-	20	%	

¹⁾ Hysteresis is implemented to avoid metastable states and switching due to internal ground bounce. It can't be guaranteed that it suppresses switching due to external system noise.

Table 3-8 Class LP 3.3V

Parameter	Symbol		Value	s	Unit	Note / Test Condition
		Min.	Тур.	Max.		
Input frequency	$f_{IN}SR$	-	-	50	MHz	Hysteresis active
		-	-	100	MHz	Hysteresis inactive
Input Hysteresis for LP pad 1)	HYSLP CC	0.05 * V _{EXT/FLEX}	-	-	V	AL and TTL
Input Leakage current for LP pad	I _{OZLP} CC	-150	-	150	nA	$ (0.1*V_{\rm EXT/FLEX}) < V_{\rm IN} < (0.9*V_{\rm EXT/FLEX}) $
		-350	-	350	nA	else
Input leakage current for P32.0	I _{OZP320} CC	-4900	-	4900	nA	$ (0.1*V_{\rm EXT/FLEX}) < V_{\rm IN} < (0.9*V_{\rm EXT/FLEX}) $
		-9400	-	9400	nA	$\begin{array}{l} (0.1^*V_{\rm EXT/FLEX}) < V_{\rm IN} < \\ (0.9^*V_{\rm EXT/FLEX}); \mbox{for } T_{\rm J} > \\ 150~^{\circ}{\rm C} \end{array}$
		-5800	-	5900	nA	else
		-12000	-	12000	nA	else; for $T_{\rm J}$ > 150°C
Pull-up current for LP pad	I_{PUHLP} CC	17	-	-	μΑ	$V_{IHmin};AL$
		[19]	-	-	μΑ	$V_{IHmin};TTL$
		-	-	75	μΑ	V_{ILmax} ; AL and TTL
Pull-down current for LP pad	I_{PDLLP} CC	-	-	75	μΑ	V_{IHmin} ; AL and TTL
		22	-	-	μΑ	$V_{ILmax};AL$
		11	-	-	μΑ	$V_{ILmax};TTL$
On-Resistance for LP pad, weak driver ²⁾	R _{DSONLPW} CC	250	875	1500	Ohm	; NMOS/PMOS ; $I_{\rm OH}$ =0.25mA ; $I_{\rm OL}$ =0.25mA

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²⁾ For currents smaller than the $I_{\rm OL/OH}$ from the test condition the defined Max. value stays unchanged.

³⁾ Rise / fall times are defined 10% - 90% of $V_{\rm EXT/FLEX}.$

⁴⁾ $V_{\rm IHx}$ = 0.27 * $V_{\rm EXT/FLEX}$ + 0.545V

⁵⁾ $V_{\rm ILx}$ = 0.17 * $V_{\rm EXT/FLEX}$

⁶⁾ The values are only valid if the pad is not used during operation, otherwise $I_{\rm SC}$ defines the limits for operation.



Table 3-8 Class LP 3.3V (cont'd)

Parameter	Symbol		Value	s	Unit	Note / Test Condition
		Min.	Тур.	Max.		
On-Resistance for LP pad, medium driver ²⁾	R _{DSONLPM} CC	70	235	400	Ohm	; NMOS/PMOS ; $I_{\rm OH}$ =1mA ; $I_{\rm OL}$ =1mA
Rise / fall time for LP pad ³⁾	$t_{LP} CC$	-	-	150+3.4 * C_{L}	ns	C _L ≤50pF ; pin out driver=weak
		-	-	320+4.5 * (C _L - 50)	ns	$C_{L} \ge 50 \text{pF}$; $C_{L} \le 200 \text{pF}$; pin out driver=weak
		-	-	30+0.8* <i>C</i>	ns	C_{L} ≤50pF; pin out driver=medium
		-	-	70+1.1 * (C _L - 50)	ns	$C_{\rm L}{\ge}50{\rm pF}$; $C_{\rm L}{\le}200{\rm pF}$; pin out driver=medium
Input high voltage for LP pad	$V_{IHLP}SR$	(0.73*V _{EX} _{T/FLEX})- 0.25	-	-	V	Hysteresis active, AL
		1.6 ⁴⁾	-	-	V	Hysteresis active, TTL
Input low voltage for LP pad	$V_{ILLP}SR$	-	-	(0.52*V _{EX} _{T/FLEX})- 0.25	V	Hysteresis active, AL
		-	-	0.5 5)	V	Hysteresis active, TTL
Input low / high voltage for LP pad	V_{ILHLP} CC	1.1	-	1.9	V	Hysteresis inactive; not available for P14.2, P14.4, and P15.1
Pad set-up time for LP pad	t_{SET_LP} CC	-	-	100	ns	
Input leakage current for P02.1	I _{OZ021} CC	-150	-	920	nA	$(0.1*V_{\rm EXT/FLEX}) < V_{\rm IN} < \ (0.9*V_{\rm EXT/FLEX}); T_{\rm J} > \ 150°{\rm C}$
		-150	-	330	nA	$(0.1*V_{\rm EXT/FLEX}) < V_{\rm IN} < \ (0.9*V_{\rm EXT/FLEX}); \ T_{\rm J} = \ 150^{\circ}{\rm C}$
		-360	-	1000	nA	else; T _J > 150°C
		-350	-	375	nA	else; $T_{\rm J}$ = 150°C
Pull down current for P32_0 pin	I _{PDLP320} CC	-	-	[80]	μΑ	V_{IHmin} ; AL and TTL
		17	-	-	μΑ	$V_{ILmax};AL$
		[6]	-	-	μΑ	$V_{ILmax}; TTL$
Pull Up Current for P32_0 pin	$I_{PUHP320}$ CC	12	-	-	μΑ	V_{IHmin} ; AL
		14	-	-	μΑ	$V_{IHmin};TTL$
		-	-	[80]	μΑ	V_{ILmax} ; AL and TTL
Short Circuit current for LP pad 6)	$I_{ m SC}$ SR	-10	-	10	mA	absolute max value (PSI5)
Deviation of symmetry for rising and falling edges	SYM CC	-	-	20	%	



- 1) Hysteresis is implemented to avoid metastable states and switching due to internal ground bounce. It can't be guaranteed that it suppresses switching due to external system noise.
- 2) For currents smaller than the $I_{\rm OL/OH}$ from the test condition the defined Max. value stays unchanged.
- 3) Rise / fall times are defined 10% 90% of $V_{\rm EXT/FLEX}$.
- 4) V_{IHx} = 0.27 * $V_{\text{EXT/FLEX}}$ + 0.545V
- 5) $V_{\text{ILx}} = 0.17 * V_{\text{EXT/FLEX}}$
- 6) The values are only valid if the pad is not used during operation, otherwise $I_{\rm SC}$ defines the limits for operation.

Table 3-9 Class MP 5V

Parameter	Symbol		Value	s	Unit	Note / Test Condition
		Min.	Тур.	Max.		
Input frequency	$f_{IN}SR$	-	-	75	MHz	Hysteresis active
		-	-	150	MHz	Hysteresis inactive
Input Hysteresis for MP pad 1)	HYSMP CC	0.09 *	-	-	V	AL
		$V_{EXT/FLEX}$				
		0.075 *	-	-	V	TTL
		$V_{EXT/FLEX}$				
Input Leakage current for MP pad	I_{OZMP} CC	-500	-	500	nA	$(0.1*V_{\text{EXT/FLEX}}) < V_{\text{IN}} < (0.9*V_{\text{EXT/FLEX}})$
		-1000	-	1000	nA	else
Pull-up current for MP pad	I_{PUHMP} CC	30	-	-	μA	$V_{IHmin};AL$
		43	-	-	μA	$V_{IHmin};TTL$
		-	-	107	μA	V_{ILmax} ; AL and TTL
Pull-down current for MP pad	I_{PDLMP} CC	-	-	[100]	μA	V_{IHmin} ; AL and TTL
		46	-	-	μA	$V_{ILmax};AL$
		21	-	-	μΑ	$V_{ILmax};TTL$
On-Resistance for MP pad,	$R_{DSONMPW}$	200	620	1040	Ohm	PMOS/NMOS;
weak driver 2)	CC					I_{OH} =0.5mA ;
						$I_{\rm OL}$ =0.5mA
On-Resistance for MP pad,	$R_{DSONMPM}$	50	155	260	Ohm	PMOS/NMOS;
medium driver ²⁾	CC					I_{OH} =2mA ; I_{OL} =2mA
On-Resistance for MP pad,	$R_{DSONMPS}$	20	75	130	Ohm	PMOS/NMOS;
strong driver 2)	CC					I_{OH} =8mA ; I_{OL} =8mA

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Table 3-9 Class MP 5V (cont'd)

Parameter	Symbol		Value	S	Unit	it Note / Test Condition
		Min.	Тур.	Max.		
Rise / fall time for MP pad ³⁾	t _{MP} CC	-	-	95+2.1* <i>C</i>	ns	$C_{\rm L}$ ≤50pF ; pin out driver=weak
		-	-	200+2.9*(C _L -50)	ns	$C_{\rm L} \ge 50 {\rm pF}$; $C_{\rm L} \le 200 {\rm pF}$; pin out driver=weak
		-	-	25+0.5* <i>C</i>	ns	$C_{\rm L}$ ≤50pF ; pin out driver=medium
		-	-	50 + 0.75 * (CL - 50)	ns	$C_{L} \ge 50 \text{pF}$; $C_{L} \le 200 \text{pF}$; pin out driver=medium
		-	-	17.5+0.25 *C _L	ns	C _L ≤50pF; edge=medium; pin out driver=strong
		-	-	30+0.3*(C _L -50)	ns	$C_{\rm L}{\ge}50{\rm pF}$; $C_{\rm L}{\le}200{\rm pF}$; edge=medium ; pin out driver=strong
		-	-	7+0.2* <i>C</i> _L	ns	C _L ≤50pF ; edge=sharp ; pin out driver=strong
		-	-	17+0.3*(C _L -50)	ns	$C_L \ge 50 pF$; $C_L \le 200 pF$; edge=sharp; pin out driver=strong
Input high voltage for MP pad	V _{IHMP} SR	(0.73*V _{EX} _{T/FLEX})- 0.25	-	-	V	Hysteresis active, AL
		2.03 4)	-	-	V	Hysteresis active, TTL
Input low voltage for MP pad	$V_{ILMP}SR$	-	-	(0.52*V _{EX} _{T/FLEX})- 0.25	V	Hysteresis active, AL
		-	-	0.8 5)	V	Hysteresis active, TTL
Input low / high voltage for MP pad	V_{ILHMP} CC	1.85	-	3.0	V	Hysteresis inactive
Pad set-up time for MP pad	t _{SET_MP} CC	-	-	100	ns	
Short Circuit current for MP pad 6)	I _{SC} SR	-10	-	10	mA	absolute max value (PSI5)
Deviation of symmetry for rising and falling edges	SYM CC	-	-	20	%	

¹⁾ Hysteresis is implemented to avoid metastable states and switching due to internal ground bounce. It can't be guaranteed that it suppresses switching due to external system noise.

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²⁾ For currents smaller than the $I_{\rm OL/OH}$ from the test condition the defined Max. value stays unchanged.

³⁾ Rise / fall times are defined 10% - 90% of $V_{\rm EXT/FLEX}.$

⁴⁾ V_{IHx} = 0.27 * $V_{\text{EXT/FLEX}}$ + 0.545V

⁵⁾ $V_{\text{ILx}} = 0.17 * V_{\text{EXT/FLEX}}$

⁶⁾ The values are only valid if the pad is not used during operation, otherwise $I_{\rm SC}$ defines the limits for operation.



Table 3-10 Class MP 3.3V

Parameter	Symbol		Value	s	Unit	Note / Test Condition
		Min.	Тур.	Max.		
Input frequency	$f_{IN}SR$	-	-	50	MHz	Hysteresis active
		-	-	100	MHz	Hysteresis inactive
Input Hysteresis for MP pad 1)	HYSMP CC	$0.05 * V_{EXT/FLEX}$	-	-	V	AL and TTL
Input Leakage current for MP pad	I_{OZMP} CC	-500	-	500	nA	$ (0.1*V_{\rm EXT/FLEX}) < V_{\rm IN} < \\ (0.9*V_{\rm EXT/FLEX}) $
		-1000	-	1000	nA	else
Pull-up current for MP pad	I_{PUHMP} CC	17	-	-	μΑ	V_{IHmin} ; AL
		19	-	-	μΑ	V_{IHmin} ; TTL
		-	-	75	μΑ	V_{ILmax} ; AL and TTL
Pull-down current for MP pad	I_{PDLMP} CC	-	-	75	μΑ	V_{IHmin} ; AL and TTL
		22	-	-	μΑ	$V_{ILmax};AL$
		11	-	-	μA	$V_{ILmax};TTL$
On-Resistance for MP pad, weak driver ²⁾	R _{DSONMPW} CC	250	875	1500	Ohm	; NMOS/PMOS ; $I_{\rm OH}$ =0.25mA ; $I_{\rm OL}$ =0.25mA
On-Resistance for MP pad, medium driver ²⁾	R _{DSONMPM} CC	70	235	400	Ohm	; NMOS/PMOS ; $I_{\rm OH}$ =1mA ; $I_{\rm OL}$ =1mA
On-Resistance for MP pad, strong driver ²⁾	R _{DSONMPS} CC	20	110	200	Ohm	$\begin{array}{c} {\rm PMOS/NMOS} \; ; \\ I_{\rm OH} {\rm = 4mA} \; ; \; I_{\rm OL} {\rm = 4mA} \end{array}$
Rise / fall time for MP pad ³⁾	t _{MP} CC	-	-	150+3.4* <i>C</i> _L	ns	C _L ≤50pF ; pin out driver=weak
		-	-	320+4.5*(C _L -50)	ns	$C_{L} \ge 50 \text{pF}$; $C_{L} \le 200 \text{pF}$; pin out driver=weak
		-	-	30+0.8* <i>C</i>	ns	C _L ≤50pF ; pin out driver=medium
		-	-	70+1.1*(C _L -50)	ns	$C_L \ge 50 pF$; $C_L \le 200 pF$; pin out driver=medium
		-	-	32.5+0.35 *C _L	ns	$C_{\rm L} \le 50 {\rm pF}$; edge=medium; pin out driver=strong
		-	-	50+0.45*(C _L -50)	ns	$C_L \ge 50 pF$; $C_L \le 200 pF$; edge=medium; pin out driver=strong
		-	-	14.5+0.35 *C _L	ns	C _L ≤50pF ; edge=sharp ; pin out driver=strong
		-	-	32+0.5*(C _L -50)	ns	$C_L \ge 50 pF$; $C_L \le 200 pF$; edge=sharp; pin out driver=strong



Table 3-10 Class MP 3.3V (cont'd)

Parameter	Symbol		Value	S	Unit	Note / Test Condition
		Min.	Тур.	Max.		
Input high voltage for MP pad	$V_{IHMP}SR$	(0.73*V _{EX} _{T/FLEX})- 0.25	-	-	V	Hysteresis active, AL
		1.6 ⁴⁾	-	-	V	Hysteresis active, TTL
Input low voltage for MP pad	$V_{ILMP}SR$	-	-	(0.52*V _{EX} _{T/FLEX})- 0.25	V	Hysteresis active, AL
		-	-	0.5 5)	V	Hysteresis active, TTL
Input low / high voltage for MP pad	V_{ILHMP} CC	1.1	-	1.9	V	Hysteresis inactive
Pad set-up time for MP pad	t _{SET_MP} CC	-	-	100	ns	
Short Circuit current for MP pad 6)	I _{SC} SR	-10	-	10	mA	absolute max value (PSI5)
Deviation of symmetry for rising and falling edges	SYM CC	-	-	20	%	

¹⁾ Hysteresis is implemented to avoid metastable states and switching due to internal ground bounce. It can't be guaranteed that it suppresses switching due to external system noise.

- 2) For currents smaller than the $I_{\rm OL/OH}$ from the test condition the defined Max. value stays unchanged.
- 3) Rise / fall times are defined 10% 90% of $V_{\rm EXT/FLEX}$.
- 4) V_{IHx} = 0.27 * $V_{\text{EXT/FLEX}}$ + 0.545V
- 5) $V_{\text{ILx}} = 0.17 * V_{\text{EXT/FLEX}}$
- 6) The values are only valid if the pad is not used during operation, otherwise I_{SC} defines the limits for operation.

Table 3-11 Class MP+ 5V

Parameter	Symbol		Value	s	Unit	Note / Test Condition
		Min.	Тур.	Max.		
Input frequency	$f_{IN}SR$	-	-	75	MHz	Hysteresis active
		-	-	150	MHz	Hysteresis inactive
Input hysteresis for MP+ pad 1)	HYSMPP	0.09 *	-	-	V	AL
	CC	$V_{EXT/FLEX}$				
		0.075 *	-	_	V	TTL
		$V_{EXT/FLEX}$				
Input leakage current for MP+ pad	I_{OZMPP} CC	-750	-	750	nA	$(0.1*V_{\text{EXT/FLEX}}) < V_{\text{IN}} < (0.9*V_{\text{EXT/FLEX}})$
		-1500	-	1500	nA	else
Pull-up current for MP+ pad	I_{PUHMPP} CC	30	-	-	μA	$V_{IHmin};AL$
		43	-	-	μA	$V_{IHmin};TTL$
		-	-	107	μΑ	V_{ILmax} ; AL and TTL
Pull-down current for MP+ pad	I_{PDLMPP} CC	-	-	100	μA	V_{IHmin} ; AL and TTL
		46	-	-	μA	$V_{ILmax};AL$
		21	-	-	μA	$V_{ILmax};TTL$

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Table 3-11 Class MP+ 5V (cont'd)

Parameter	Symbol		Values	S	Unit	Note / Test Condition
		Min.	Тур.	Max.		
On-resistance for MP+ pad, weak driver ²⁾	R _{DSONMPPW} CC	200	620	1040	Ohm	PMOS/NMOS ; $I_{\rm OH}$ =0.5mA ; $I_{\rm OL}$ =0.5mA
On-resistance for MP+ pad, medium driver ²⁾	R _{DSONMPPM} CC	50	155	260	Ohm	$\begin{array}{c} {\rm PMOS/NMOS} \; ; \\ I_{\rm OH} {\rm = 2mA} \; ; \; I_{\rm OL} {\rm = 2mA} \end{array}$
On-resistance for MP+ pad, strong driver ²⁾	R _{DSONMPPS} CC	20	55	90	Ohm	PMOS/NMOS ; $I_{\rm OH}$ =8mA ; $I_{\rm OL}$ =8mA
Rise/fall time for MP+ pad ³⁾	t _{MPP} CC	-	-	95+2.1* <i>C</i>	ns	C_{L} ≤50pF; pin out driver=weak
		-	-	200+2.9*(C _L -50)	ns	$C_L \ge 50 \text{pF}$; $C_L \le 200 \text{pF}$; pin out driver=weak
		-	-	25+0.5* <i>C</i>	ns	C _L ≤50pF ; pin out driver=medium
		-	-	50+0.75*(C _L -50)	ns	$C_{\rm L} \ge 50 {\rm pF}$; $C_{\rm L} \le 200 {\rm pF}$; pin out driver=medium
		-	-	9+0.16* <i>C</i>	ns	C _L ≤50pF; edge=medium; pin out driver=strong
		-	-	17+0.2*(C _L -50)	ns	$C_{\rm L}{\ge}50{\rm pF}$; $C_{\rm L}{\le}200{\rm pF}$; edge=medium; pin out driver=strong
		-	-	4+0.16* <i>C</i>	ns	C _L ≤50pF ; edge=sharp ; pin out driver=strong
		-	-	12+0.21*(C _L -50)	ns	$C_{L} \ge 50 \text{pF}$; $C_{L} \le 200 \text{pF}$; edge=sharp; pin out driver=strong
		-	-	5	ns	from 0.8V to 2.0V (RMII); C_L =25pF; edge=sharp; pin out driver=strong
		-	-	4.5	ns	C_L =15pF; edge=sharp; pin out driver=strong
Input high voltage for MP+ pad	$V_{\mathrm{IHMPP}}\mathrm{SR}$	(0.73*V _{EX}	-	-	V	Hysteresis active, AL
		0.25				
		2.03 4)	-	-	V	Hysteresis active, TTL
Input low voltage for MP+ pad	$V_{ILMPP}SR$	-	-	(0.52*V _{EX} _{T/FLEX})- 0.25	V	Hysteresis active, AL
		-	-	0.8 5)	V	Hysteresis active, TTL
Input low / high voltage for MP+ pad	V_{ILHMPP} CC	1.85	-	3.0	V	Hysteresis inactive



Table 3-11 Class MP+ 5V (cont'd)

Parameter	Symbol		Value	s	Unit	Note / Test Condition
		Min.	Тур.	Max.		
Pad set-up time for MP+ pad	t_{SET_MPP} CC	-	-	100	ns	
Short circuit current for MP+ pad ⁶⁾	I _{SCMPP} SR	-10	-	10	mA	absolute max value (PSI5)
Deviation of symmetry for rising and falling edges	SYM CC	-	-	20	%	

¹⁾ Hysteresis is implemented to avoid metastable states and switching due to internal ground bounce. It can't be guaranteed that it suppresses switching due to external system noise.

- 2) For currents smaller than the $I_{\rm OL/OH}$ from the test condition the defined Max. value stays unchanged.
- 3) Rise / fall times are defined 10% 90% of $V_{\rm EXT/FLEX}$.
- 4) $V_{\text{IHx}} = 0.27 * V_{\text{EXT/FLEX}} + 0.545 \text{V}$
- 5) $V_{\rm ILx}$ = 0.17 * $V_{\rm EXT/FLEX}$
- 6) The values are only valid if the pad is not used during operation, otherwise $I_{\rm SC}$ defines the limits for operation.

Table 3-12 Class MP+ 3.3V

Parameter	Symbol		Value	s	Unit	Note / Test Condition
		Min.	Тур.	Max.		
Input frequency	$f_{IN}SR$	-	-	50	MHz	Hysteresis active
		-	-	100	MHz	Hysteresis inactive
Input hysteresis for MP+ pad 1)	HYSMPP CC	0.05 * V _{EXT/FLEX}	-	-	V	AL and TTL
Input leakage current for MP+ pad	I _{OZMPP} CC	-750	-	750	nA	$(0.1*V_{\rm EXT/FLEX}) < V_{\rm IN} < (0.9*V_{\rm EXT/FLEX})$
		-1500	-	1500	nA	else
Pull-up current for MP+ pad	I _{PUHMPP} CC	17	-	-	μΑ	$V_{IHmin};AL$
		19	-	-	μΑ	$V_{IHmin};TTL$
		-	-	75	μΑ	V_{ILmax} ; AL and TTL
Pull-down current for MP+ pad	I_{PDLMPP} CC	-	-	75	μΑ	V_{IHmin} ; AL and TTL
		22	-	-	μΑ	$V_{ILmax};AL$
		11	-	-	μΑ	$V_{ILmax};TTL$
On-resistance for MP+ pad, weak driver ²⁾	R _{DSONMPPW} CC	250	875	1500	Ohm	; NMOS/PMOS; $I_{\rm OH}$ =0.25mA; $I_{\rm OL}$ =0.25mA
On-resistance for MP+ pad, medium driver ²⁾	R _{DSONMPPM} CC	70	235	400	Ohm	; NMOS/PMOS ; $I_{\rm OH}$ =1mA ; $I_{\rm OL}$ =1mA
On-resistance for MP+ pad, strong driver ²⁾	R _{DSONMPPS} CC	20	75	130	Ohm	$\begin{array}{c} {\rm PMOS/NMOS} \; ; \\ I_{\rm OH}{\rm =}4{\rm mA} \; ; \; I_{\rm OL}{\rm =}4{\rm mA} \end{array}$



Table 3-12 Class MP+ 3.3V (cont'd)

Parameter	Symbol		Value	S	Unit	nit Note / Test Condition
		Min.	Тур.	Max.		
Rise/fall time for MP+ pad 3)	t _{MPP} CC	-	-	150+3.4* C _L	ns	C _L ≤50pF ; pin out driver=weak
		-	-	320+4.5*(C _L -50)	ns	$C_{\rm L} \ge 50 {\rm pF}$; $C_{\rm L} \le 200 {\rm pF}$; pin out driver=weak
		-	-	30+0.8* <i>C</i>	ns	C _L ≤50pF ; pin out driver=medium
		-	-	70+1.1*(C _L -50)	ns	$C_{\rm L} \ge 50 {\rm pF}$; $C_{\rm L} \le 200 {\rm pF}$; pin out driver=medium
		-	-	20+0.2* <i>C</i>	ns	C _L ≤50pF; edge=medium; pin out driver=strong
		-	-	30+0.3*(C _L -50)	ns	$C_{\rm L} \ge 50 {\rm pF}$; $C_{\rm L} \le 200 {\rm pF}$; edge=medium; pin out driver=strong
		-	-	13+0.2* <i>C</i>	ns	C _L ≤50pF ; edge=sharp ; pin out driver=strong
		-	-	23+0.3*(C _L -50)	ns	$C_L \ge 50 \text{pF}$; $C_L \le 200 \text{pF}$; edge=sharp; pin out driver=strong
		-	-	5	ns	from 0.8V to 2.0V (RMII); C_L =25pF; edge=sharp; pin out driver=strong
		-	-	4.5	ns	from 0.2 * $V_{\rm EXT/FLEX}$ to 0.8 * $V_{\rm EXT/FLEX}$; $C_{\rm L}$ =15pF ; edge=sharp ; pin out driver=strong
Input high voltage for MP+ pad	$V_{\mathrm{IHMPP}}\mathrm{SR}$	(0.73*V _{EX} _{T/FLEX})- 0.25	-	-	V	Hysteresis active, AL
		1.6 ⁴⁾	-	-	٧	Hysteresis active, TTL
Input low voltage for MP+ pad	$V_{\rm ILMPP}{ m SR}$	-	-	(0.52*V _{EX} _{T/FLEX})- 0.25	V	Hysteresis active, AL
		-	-	0.5 5)	V	Hysteresis active, TTL
Input low / high voltage for MP+ pad	V_{ILHMPP} CC	1.1	-	1.9	V	Hysteresis inactive
Pad set-up time for MP+ pad	t _{SET MPP} CC	-	-	100	ns	
Short circuit current for MP+ pad ⁶⁾	I _{SCMPP} SR	-10	-	10	mA	absolute max value (PSI5)
Deviation of symmetry for rising and falling edges	SYM CC	-	-	20	%	



- 1) Hysteresis is implemented to avoid metastable states and switching due to internal ground bounce. It can't be guaranteed that it suppresses switching due to external system noise.
- 2) For currents smaller than the $I_{\rm OL/OH}$ from the test condition the defined Max. value stays unchanged.
- 3) Rise / fall times are defined 10% 90% of $V_{\rm EXT/FLEX}$.
- 4) V_{IHx} = 0.27 * $V_{\text{EXT/FLEX}}$ + 0.545V
- 5) $V_{\text{ILx}} = 0.17 * V_{\text{EXT/FLEX}}$
- 6) The values are only valid if the pad is not used during operation, otherwise $I_{\rm SC}$ defines the limits for operation.

Table 3-13 Class MPR 5V

Parameter	Symbol		Value	s	Unit	Note / Test Condition
		Min.	Тур.	Max.		
Input frequency	$f_{IN}SR$	-	-	75	MHz	Hysteresis active
		-	-	150	MHz	Hysteresis inactive
Input Hysteresis for MPR pads	HYSMPR	0.09 *	-	-	V	AL
1)	CC	$V_{EXT/FLEX}$				
		0.075*	_	-	V	TTL
		$V_{EXT/FLEX}$				
Input leakage current class MPR	I_{OZMPR} CC	-750	-	750	nA	$ (0.1*V_{EXT/FLEX}) < V_{IN} < \\ (0.9*V_{EXT/FLEX}) $
		-1500	-	1500	nA	else
Pull-up current	I_{PUHMPR} CC	30	-	-	μA	$V_{IHmin};AL$
		43	-	-	μA	$V_{IHmin};TTL$
		-	_	107	μA	V_{ILmax} ; AL and TTL
Pull-down current	I_{PDLMPR} CC	-	_	[100]	μA	V_{IHmin} ; AL and TTL
		46	-	-	μA	$V_{ILmax};AL$
		21	-	-	μA	$V_{ILmax};TTL$
On-resistance of the MPR pad,	$R_{DSONMPRW}$	200	620	1040	Ohm	PMOS/NMOS;
weak driver 2)	CC					I_{OH} =0.5mA ;
						$I_{\rm OL}$ =0.5mA
On-resistance of the MPR pad,	$R_{DSONMPRM}$	50	155	260	Ohm	PMOS/NMOS;
medium driver ²⁾	CC					I_{OH} =2mA ; I_{OL} =2mA
On-resistance of the MPR pad,	$R_{DSONMPRS}$	20	55	90	Ohm	PMOS/NMOS;
strong driver ²⁾	CC					I_{OH} =8mA ; I_{OL} =8mA

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Table 3-13 Class MPR 5V (cont'd)

Parameter	Symbol	Values			Unit	Note / Test Condition
		Min.	Тур.	Max.		
Rise/fall time 3)	t _{MPR} CC	-	-	95+2.1* <i>C</i>	ns	C _L ≤50pF ; pin out driver=weak
		-	-	200+2.9*(C _L -50)	ns	$C_{L} \ge 50 \text{pF}$; $C_{L} \le 200 \text{pF}$; pin out driver=weak
		-	-	25+0.5* <i>C</i>	ns	C _L ≤50pF ; pin out driver=medium
		-	-	50+0.75*(C _L -50)	ns	$C_{\rm L}{\ge}50{\rm pF}$; $C_{\rm L}{\le}200{\rm pF}$; pin out driver=medium
		-	-	9+0.16* <i>C</i>	ns	$C_{L} \ge 0 \text{pF}$; $C_{L} \le 50 \text{pF}$; edge=medium; pin out driver=strong
		-	-	17+0.2*(C _L -50)	ns	$C_{L} \ge 50 \text{pF}$; $C_{L} \le 200 \text{pF}$; edge=medium; pin out driver=strong
		-	-	4+0.16* <i>C</i>	ns	C _L ≤50pF ; edge=sharp ; pin out driver=strong
		-	-	12+0.21*(C _L -50)	ns	$C_L \ge 50 \text{pF}$; $C_L \le 200 \text{pF}$; edge=sharp; pin out driver=strong
		-	-	5	ns	from 0.8V to 2.0V (RMII); C_L =25pF; edge=sharp; pin out driver=strong
		-	-	4.5	ns	from 0.2 * $V_{\rm EXT/FLEX}$ to 0.8 * $V_{\rm EXT/FLEX}$; $C_{\rm L}$ =15pF; edge=sharp; pin out driver=strong
Input high voltage, class MPR pads	$V_{IHMPR}SR$	(0.73*V _{EX} _{T/FLEX})- 0.25	-	-	V	Hysteresis active, AL
		2.03 4)	-	-	V	Hysteresis active, TTL
Input low voltage, class MPR pads	$V_{ILMPR}SR$	-	-	(0.52*V _{EX} _{T/FLEX})- 0.25	V	Hysteresis active, AL
		-	-	0.8 5)	V	Hysteresis active, TTL
Input low / high voltage, class MPR pads	$V_{ILHMPR}SR$	1.2	-	2.3	V	Hysteresis inactive
Pad set-up time	t _{SET_MPR} CC	-	-	100	ns	
Short circuit current Class MPR	$I_{\rm SC}$ SR	-10	-	10	mA	absolute max value (PSI5)
Deviation of symmetry for rising and falling edges	SYM CC	-	-	20	%	



- 1) Hysteresis is implemented to avoid metastable states and switching due to internal ground bounce. It can't be guaranteed that it suppresses switching due to external system noise.
- 2) For currents smaller than the $I_{\rm OL/OH}$ from the test condition the defined Max. value stays unchanged.
- 3) Rise / fall times are defined 10% 90% of $V_{\rm EXT/FLEX}$.
- 4) V_{IHx} = 0.27 * $V_{\text{EXT/FLEX}}$ + 0.545V
- 5) $V_{\text{ILx}} = 0.17 * V_{\text{EXT/FLEX}}$

Table 3-14 Class MPR 3.3V

Parameter	Symbol		Value	s	Unit	Note / Test Condition
		Min.	Тур.	Max.		
Input frequency	$f_{IN}SR$	-	-	50	MHz	Hysteresis active
		-	-	100	MHz	Hysteresis inactive
Input Hysteresis for MPR pads	HYSMPR CC	0.05 * V _{EXT/FLEX}	-	-	V	AL and TTL
Input leakage current class MPR	I _{OZMPR} CC	-750	-	750	nA	$ (0.1*V_{\rm EXT/FLEX}) < V_{\rm IN} < \\ (0.9*V_{\rm EXT/FLEX}) $
		-1500	-	1500	nA	else
Pull-up current	I_{PUHMPR} CC	17	-	-	μA	$V_{IHmin};AL$
		19	-	-	μA	$V_{IHmin};TTL$
		-	-	75	μA	V_{ILmax} ; AL and TTL
Pull-down current	I _{PDLMPR} CC	-	-	75	μA	V_{IHmin} ; AL and TTL
		22	-	-	μA	$V_{ILmax};AL$
		[11]	-	-	μA	$V_{ILmax};TTL$
On-resistance of the MPR pad, weak driver ²⁾	R _{DSONMPRW} CC	250	875	1500	Ohm	; NMOS/PMOS ; $I_{\rm OH}$ =0.25mA ; $I_{\rm OL}$ =0.25mA
On-resistance of the MPR pad, medium driver ²⁾	R _{DSONMPRM} CC	70	235	400	Ohm	; NMOS/PMOS ; $I_{\rm OH}$ =1mA ; $I_{\rm OL}$ =1mA
On-resistance of the MPR pad, strong driver ²⁾	R _{DSONMPRS} CC	20	75	130	Ohm	$\begin{array}{c} {\rm PMOS/NMOS} \; ; \\ I_{\rm OH}{\rm =}4{\rm mA} \; ; \; I_{\rm OL}{\rm =}4{\rm mA} \end{array}$

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Table 3-14 Class MPR 3.3V (cont'd)

Parameter	Symbol		Value	S	Unit	Note / Test Condition
		Min.	Тур.	Max.		
Rise/fall time ³⁾	t _{MPR} CC	-	-	150+3.4* C _L	ns	C _L ≤50pF ; pin out driver=weak
		-	-	320+4.5*(C _L -50)	ns	$C_{\rm L}{\ge}50{\rm pF}$; $C_{\rm L}{\le}200{\rm pF}$; pin out driver=weak
		-	-	30+0.8* <i>C</i>	ns	$C_{\rm L}{\le}50{\rm pF}$; pin out driver=medium
		-	-	70+1.1*(<i>C</i> _L -50)	ns	$C_{\rm L}{\ge}50{\rm pF}$; $C_{\rm L}{\le}200{\rm pF}$; pin out driver=medium
		-	-	20+0.2* <i>C</i>	ns	$C_{\rm L}{\ge}0{\rm pF}$; $C_{\rm L}{\le}50{\rm pF}$; edge=medium; pin out driver=strong
		-	-	30+0.3*(C _L -50)	ns	$C_{L} \ge 50 \text{pF}$; $C_{L} \le 200 \text{pF}$; edge=medium; pin out driver=strong
		-	-	13+0.2* <i>C</i>	ns	C _L ≤50pF ; edge=sharp ; pin out driver=strong
		-	-	23+0.3*(C _L -50)	ns	$C_{\rm L}{\ge}50{\rm pF}$; $C_{\rm L}{\le}200{\rm pF}$; edge=sharp ; pin out driver=strong
		-	-	5	ns	from 0.8V to 2.0V (RMII); C_L =25pF; edge=sharp; pin out driver=strong
		-	-	4.5	ns	from 0.2 * $V_{\rm EXT/FLEX}$ to 0.8 * $V_{\rm EXT/FLEX}$; $C_{\rm L}$ =15pF; edge=sharp; pin out driver=strong
Input high voltage, class MPR pads	$V_{IHMPR}SR$	(0.73*V _{EX} _{T/FLEX})- 0.25	-	-	V	Hysteresis active, AL
		1.6 ⁴⁾	-	-	V	Hysteresis active, TTL
Input low voltage, class MPR pads	$V_{ILMPR}SR$	-	-	(0.52*V _{EX} _{T/FLEX})- 0.25	V	Hysteresis active, AL
		_	_	0.5 5)	V	Hysteresis active, TTL
Input low / high voltage, class MPR pads	$V_{ILHMPR}SR$	0.8	-	1.7	V	Hysteresis inactive
Pad set-up time	t _{SET_MPR} CC	-	-	100	ns	
Short circuit current Class MPR	I _{SC} SR	-10	-	10	mA	absolute max value (PSI5)

¹⁾ Hysteresis is implemented to avoid metastable states and switching due to internal ground bounce. It can't be guaranteed that it suppresses switching due to external system noise.

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²⁾ For currents smaller than the $I_{\rm OL/OH}$ from the test condition the defined Max. value stays unchanged.



- 3) Rise / fall times are defined 10% 90% of $V_{\rm EXT/FLEX}$.
- 4) V_{IHx} = 0.27 * $V_{\mathrm{EXT/FLEX}}$ + 0.545V
- 5) $V_{\text{ILx}} = 0.17 * V_{\text{EXT/FLEX}}$

Table 3-15 Class S

Parameter	Symbol		Values		Unit	Note / Test Condition
		Min.	Тур.	Max.		
Input frequency	$f_{IN}SR$	-	-	75	MHz	Hysteresis active
		-	-	150	MHz	Hysteresis inactive
Input Hysteresis for S pad 1)	HYSS CC	0.3	-	-	V	
Pull-up current for S pad	I _{PUHS} CC	30	-	-	μΑ	V_{IHmin}
		-	-	107	μΑ	V_{ILmax}
Pull-down current for S pad	I _{PDLS} CC	-	-	100	μΑ	V_{IHmin}
		46	-	-	μΑ	V_{ILmax}
Input Leakage current Class S	I _{OZS} CC	-350	-	350	nA	Analog Inputs with pull down diagnostics
		-150	-	150	nA	else
Input voltage high for S pad	$V_{IHS}SR$	-	-	(0.73*V _{DD} _M)-0.25	V	Hysteresis active
Input voltage low for S pad	$V_{ILS}SR$	$(0.52*V_{\rm DD})$ M)-0.25	-	-	V	Hysteresis active
$\begin{tabular}{ll} \hline \textbf{Input low threshold variation for} \\ \textbf{S pad} \begin{tabular}{ll} \textbf{S} \\ \textbf{pad} \begin{tabular}{ll} \textbf{S} \\ $	$V_{ILSD}SR$	-50	-	50	mV	$\begin{array}{c} \text{max. variation of 1ms;} \\ V_{\text{DDM}} \text{=constant} \end{array}$
Input capacitance for S pad	C_{INS} CC	-	-	10	pF	
Pad set-up time for S pad	t _{SETS} CC	-	-	100	ns	

¹⁾ Hysteresis is implemented to avoid metastable states and switching due to internal ground bounce. It can't be guaranteed that it suppresses switching due to external system noise.

Table 3-16 Class I 5V

Parameter	Symbol		Value	s	Unit	Note / Test Condition
		Min.	Тур.	Max.		
Input frequency	$f_{IN}SR$	-	-	75	MHz	Hysteresis active
		-	-	150	MHz	Hysteresis inactive
Input Hysteresis for I pad 1)	HYSI CC	0.07 * V _{EXT/FLEX}	-	-	V	PORST pad only
		0.09 * V _{EXT/FLEX}	-	-	V	AL
		0.075 * V _{EXT/FLEX}	-	-	V	TTL
Pull-up current for I pad	I _{PUHI} CC	30	-	-	μΑ	$V_{IHmin};AL$
		43	-	-	μΑ	$V_{IHmin};TTL$
		-	-	107	μΑ	$V_{\rm ILmax}$; AL and TTL

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²⁾ VILSD is implemented to ensure J2716 specification. For details of dedicated pins please see AP32286 for details.



Table 3-16 Class I 5V (cont'd)

Parameter	Symbol	Values			Unit	Note / Test Condition
		Min.	Тур.	Max.		
Pull-down current for I pad	$I_{PDLI}CC$	-	-	[100]	μΑ	V_{IHmin} ; AL and TTL
		46	-	-	μΑ	$V_{ILmax};AL$
		21	-	-	μΑ	$V_{ILmax}; TTL$
Input Leakage Current for I pad	I _{OZI} CC	-150	-	150	nA	$(0.1*V_{\rm EXT/FLEX}) < V_{\rm IN} < (0.9*V_{\rm EXT/FLEX})$
		-350	-	350	nA	else
Input high voltage for I pad	$V_{IHI}SR$	2.03 ²⁾	-	-	V	Hysteresis active, TTL
		(0.73*V _{EX} _{T/FLEX})- 0.25	-	-	V	Hysteresis active; AL; not available for the PORST pad
Input low voltage for I pad	$V_{ILI}SR$	-	-	0.8 3)	V	Hysteresis active, TTL
		-	-	(0.52*V _{EX} _{T/FLEX})- 0.25	V	Hysteresis active; AL; not available for the PORST pad
Input low / high voltage for I pad	$V_{ILHI}CC$	1.85	-	3.0	V	Hysteresis inactive
Pad set-up time for I pad	t _{SETI} CC	-	-	100	ns	

¹⁾ Hysteresis is implemented to avoid metastable states and switching due to internal ground bounce. It can't be guaranteed that it suppresses switching due to external system noise.

Table 3-17 Class I 3.3V

Parameter	Symbol		Value	s	Unit	Note / Test Condition
		Min.	Тур.	Max.		
Input frequency	$f_{IN}SR$	-	-	50	MHz	Hysteresis active
		-	-	100	MHz	Hysteresis inactive
Input Hysteresis for I pad 1)	HYSI CC	0.045 * V _{EXT/FLEX}	-	-	V	PORST pad only
		$0.05 * V_{EXT/FLEX}$	-	-	V	AL and TTL
Pull-up current for I pad	I _{PUHI} CC	17	-	-	μΑ	$V_{IHmin};AL$
		19	-	-	μΑ	$V_{IHmin};TTL$
		-	-	75	μΑ	$V_{\rm ILmax}$; AL and TTL
Pull-down current for I pad	$I_{PDLI}CC$	-	-	75	μΑ	V_{IHmin} ; AL and TTL
		22	-	-	μΑ	$V_{ILmax};AL$
		11	-	-	μΑ	$V_{ILmax}; TTL$
Input Leakage Current for I pad	I _{OZI} CC	-150	-	150	nA	$ (0.1*V_{\rm EXT/FLEX}) < V_{\rm IN} < (0.9*V_{\rm EXT/FLEX}) $
		-350	-	350	nA	else

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²⁾ V_{IHx} = 0.27 * $V_{\text{EXT/FLEX}}$ + 0.545V

³⁾ $V_{\text{ILx}} = 0.17 * V_{\text{EXT/FLEX}}$



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Table 3-17 Class I 3.3V (cont'd)

Parameter	Symbol		Value	S	Unit	Note / Test Condition
		Min.	Тур.	Max.		
Input high voltage for I pad	$V_{IHI}SR$	1.6 ²⁾	-	-	V	Hysteresis active, TTL
		(0.73*V _{EX} _{T/FLEX})- 0.25	-	-	V	Hysteresis active; AL; not available for the PORST pad
Input low voltage for I pad	$V_{ILI}SR$	-	-	0.5 3)	V	Hysteresis active, TTL
		-	-	(0.52*V _{EX} _{T/FLEX})- 0.25	V	Hysteresis active; AL; not available for the PORST pad
Input low / high voltage for I pad	$V_{ILHI}CC$	1.1	-	1.9	V	Hysteresis inactive
Pad set-up time for I pad	t _{SETI} CC	-	-	100	ns	

¹⁾ Hysteresis is implemented to avoid metastable states and switching due to internal ground bounce. It can't be guaranteed that it suppresses switching due to external system noise.

Table 3-18 Driver Mode Selection for LP Pads

PDx.2	PDx.1	PDx.0	Port Functionality	Driver Setting	
X	Х	0	Speed grade 1	medium (LPm)	
X	Х	1	Speed grade 2	weak (LPw)	

Table 3-19 Driver Mode Selection for MP / MP+ Pads

PDx.2	PDx.1	PDx.0	Port Functionality	Driver Setting
X	0	0	Speed grade 1	Strong sharp edge (MPss / MP+ss / MPRss)
X	0	1	Speed grade 2	Strong medium edge (MPsm / MP+sm)
X	1	0	Speed grade 3	medium (MPm / MP+m / MPRm)
X	1	1	Speed grade 4	weak (MPw / MP+w / MPRw)

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²⁾ V_{IHx} = 0.27 * $V_{\text{EXT/FLEX}}$ + 0.545V

³⁾ $V_{\text{ILx}} = 0.17 * V_{\text{EXT/FLEX}}$



Electrical Specification3.3 V only Pads

3.6 3.3 V only Pads

Pad classes LP, MP and MP+ support both Automotive Level (AL) or TTL level (TTL) operation. Parameters are defined for AL operation and degrade in TTL operation.

Table 3-20 Class A2

Parameter	Symbol		Value	S	Unit	Note / Test Condition
		Min.	Тур.	Max.		
Input frequency	$f_{IN}SR$	-	-	160	MHz	
Input Hysteresis for A2 pad ¹⁾	HYSA2 CC	0.1 * V _{DDP3}	-	-	V	TTL;else
		0.06 * V _{DDP3}	-	-	V	valid for P21.6 and P21.7
Input Leakage current for A2 pad	I _{OZA2} CC	-300	-	300	nA	$ (0.1*V_{\rm EXT/FLEX}) < V_{\rm IN} < (0.9*V_{\rm EXT/FLEX}) $
		-800	-	500	nA	else
Pull-up current for A2 pad	I _{PUHA2} CC	-	-	[100]	μΑ	V_{IHmin}
		25	-	-	μΑ	V_{ILmax}
Pull-down current for A2 pad	$I_{PDLA2}CC$	23	-	-	μΑ	V_{IHmin}
		-	-	[100]	μΑ	V_{ILmax}
On-Resistance for A2 pad, weak driver ²⁾	R _{DSONA2W} CC	100	200	325	Ohm	$\begin{array}{c} {\rm PMOS/NMOS}~;\\ I_{\rm OH}{\rm =}0.5{\rm mA}~;\\ I_{\rm OL}{\rm =}0.5{\rm mA} \end{array}$
On-Resistance for A2 pad, medium driver ²⁾	R _{DSONA2M} CC	40	70	100	Ohm	$\begin{array}{c} {\rm PMOS/NMOS} \; ; \\ I_{\rm OH} {\rm = 2mA} \; ; \; I_{\rm OL} {\rm = 2mA} \end{array}$
On-Resistance for A2 pad, strong driver ²⁾	R _{DSONA2S} CC	20	35	50	Ohm	PMOS/NMOS ; $I_{\rm OH}$ =8mA ; $I_{\rm OL}$ =8mA
Rise/fall time for A2 pad ³⁾	t _{A2} CC	-	-	20+0.8* <i>C</i>	ns	C _L ≤50pF ; pin out driver=weak
		-	-	17.5+0.85 *C _L	ns	$C_{\rm L} \ge 50 {\rm pF}$; $C_{\rm L} \le 200 {\rm pF}$; pin out driver=weak
		-	-	12+0.16* <i>C</i> _L	ns	$C_{\rm L}$ ≤50pF ; pin out driver=medium
		-	-	11.5+0.17 * <i>C</i> _L	ns	$C_{\rm L}$ \geq 50pF ; $C_{\rm L}$ \leq 200pF ; pin out driver=medium
		-	-	6+0.06* <i>C</i>	ns	$C_{\rm L} \le 50 {\rm pF}$; edge=medium; pin out driver=strong
		-	-	5.5+0.07* <i>C</i> _L	ns	$C_L \ge 50 pF$; $C_L \le 200 pF$; edge=medium; pin out driver=strong
		-	-	0.0+0.12* <i>C</i> _L	ns	C _L ≤50pF; edge=sharp; pin out driver=strong
		-	-	0.0+0.12* <i>C</i> _L	ns	$C_L \ge 50 pF$; $C_L \le 200 pF$; edge=sharp; pin out driver=strong



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Table 3-20 Class A2 (cont'd)

Parameter	Symbol		Value	s	Unit	Note / Test Condition
		Min.	Тур.	Max.		
Input high voltage for A2 pad	$V_{IHA2}SR$	2.04 4)	-	-	V	TTL;valid for all A2 pads except TMS/DAP1, TRST, and TCK/DAP0
		0.7 * V _{DDP3}	-	-	V	valid for TMS/DAP1, TRST, and TCK/DAP0
Input low voltage for A2 pad	$V_{ILA2}SR$	-	-	0.8 5)	V	TTL;valid for all A2 pads except TMS/DAP1, TRST, and TCK/DAP0
		-	-	0.3 * V _{DDP3}	V	valid for TMS/DAP1, TRST, and TCK/DAP0
Pad set-up time for A2 pad	t _{SETA2} CC	-	-	100	ns	
Deviation of symmetry for rising and falling edges	SYM CC	-	-	20	%	

¹⁾ Hysteresis is implemented to avoid metastable states and switching due to internal ground bounce. It can't be guaranteed that it suppresses switching due to external system noise.

- 3) Rise / fall times are defined 10% 90% of $V_{\rm DDP3}.$
- 4) V_{IHx} = 0.57 * V_{DDP3} 0.03V
- 5) $V_{\rm ILx}$ = 0.25 * $V_{\rm DDP3}$ + 0.058V

Table 3-21 Driver Mode Selection for A2 Pads

PDx.2	PDx.1	PDx.0	Port Functionality	Driver Setting
X	0	0	Speed grade 1	Strong sharp edge
X	0	1	Speed grade 2	Strong medium edge
X	1	0	Speed grade 3	medium
X	1	1	Speed grade 4	weak

Table 3-22 Driver Mode Selection for F Pads

PDx.2	PDx.1	PDx.0	Port Functionality	Driver Setting
X	0	0	Speed grade 1	Reduced Strong sharp edge
X	0	1	Speed grade 2	Reduced Strong medium edge
X	1	0	Speed grade 3	medium
X	1	1	Speed grade 4	weak

²⁾ For currents smaller than the $I_{\rm OL/OH}$ from the test condition the defined Max. value stays unchanged.



3.7 High performance LVDS Pads (LVDSH)

This LVDS pad type is used for the high speed chip to chip communication inferface of the new TC270 / TC275 / TC277. It compose out of a LVDSH pad and a Class F pad.

This pad combination is always supplied by the 3.3V supply rail.

Table 3-23 Class F

Parameter	Symbol		Value	s	Unit	Note / Test Condition
		Min.	Тур.	Max.		
Input frequency	$f_{IN}SR$	-	-	75	MHz	
Input Hysteresis for F pad 1)	HYSF CC	0.1 * V _{DDP3}	-	-	V	TTL
Input Leakage Current for F pad	I _{OZF} CC	-1000	-	1000	nA	$(0.1*V_{\rm DDP3}) < V_{\rm IN} < \ (0.9*V_{\rm DDP3});$ valid for P21.2 and P21.3; $T_{\rm J}$ = 150°C
		-1500	-	1500	nA	$(0.1*V_{\rm DDP3}) < V_{\rm IN} < \ (0.9*V_{\rm DDP3});$ valid for P21.2 and P21.3; $T_{\rm J}$ = 170°C
		-300	-	300	nA	$(0.1*V_{\rm DDP3}) < V_{\rm IN} < \ (0.9*V_{\rm DDP3}); \ {\rm valid\ for} \ {\rm P21.4\ and\ P21.5}$
		-2000	-	2000	nA	else; valid for P21.2 and P21.3; $T_{\rm J}$ = 150°C
		-3000	-	3000	nA	else; valid for P21.2 and P21.3; T_J = 170°C
		-600	-	600	nA	else; valid for P21.4 and P21.5
Pull-up current for F pad	I _{PUHF} CC	25	-	-	μΑ	V_{IHmin}
		-	-	[100]	μΑ	V_{ILmax}
Pull-down current for class F	I_{PDLF} CC	-	-	[100]	μΑ	V_{IHmin}
pads		25	_	-	μΑ	V_{ILmax}
On resistance for F pad, weak driver ²⁾	R _{DSONFW} CC	100	200	325	Ohm	PMOS/NMOS ; $I_{\rm OH}$ =0.5mA ; $I_{\rm OL}$ =0.5mA
On resistance for F pad, medium driver ²⁾	R _{DSONFM} CC	40	70	100	Ohm	$\begin{array}{c} {\rm PMOS/NMOS}~;\\ I_{\rm OH} {\rm = 2mA}~;~I_{\rm OL} {\rm = 2mA} \end{array}$
On resistance for F pad, strong driver ²⁾	R _{DSONFS} CC	20	50	80	Ohm	$\begin{array}{c} {\rm PMOS/NMOS} \; ; \\ I_{\rm OH} {\rm = 4mA} \; ; \; I_{\rm OL} {\rm = 4mA} \end{array}$



Table 3-23 Class F (cont'd)

Parameter	Symbol		Value	s	Unit	Note / Test Condition	
		Min.	Тур.	Max.			
Rise/fall time for F pad 3)	$t_{\sf rfF}$ CC	-	-	20+0.8* <i>C</i>	ns	C _L ≤50pF ; pin out driver=weak	
		-	-	17.5+0.85 * <i>C</i> _L	ns	$C_{\rm L}{\ge}50{\rm pF}$; $C_{\rm L}{\le}200{\rm pF}$; pin out driver=weak	
		-	-	12+0.16* <i>C</i> _L	ns	C _L ≤50pF ; pin out driver=medium	
		-	-	11.5+0.17 * <i>C</i> _L	ns	$C_{\rm L}{\ge}50{\rm pF}$; $C_{\rm L}{\le}200{\rm pF}$; pin out driver=medium	
		-	-	7+0.16* <i>C</i>	ns	C _L ≤50pF; edge=medium; pin out driver=reduced strong	
		-	-	6.5+0.17* <i>C</i> _L	ns	$C_{L} \ge 50 \text{pF}$; $C_{L} \le 200 \text{pF}$; edge=meduim; pin out driver>reduced strong	
		-	-	4+0.16* <i>C</i>	ns	C _L ≤50pF ; edge=sharp ; pin out driver=reduced strong	
		-	-	3.5+0.17* <i>C</i> _L	ns	$C_L \ge 50 pF$; $C_L \le 200 pF$; edge=sharp; pin out driver=reduced strong	
Input high voltage for F pad	$V_{IHF}SR$	2.04 4)	-	-	٧	TTL	
Input low voltage for F pad	$V_{ILF}SR$	-	-	0.8 5)	V	TTL	
Pad set-up time for F pad	$t_{SETF}CC$	-	-	100	ns		
Deviation of symmetry for rising and falling edges	SYM CC	-	-	20	%		

¹⁾ Hysteresis is implemented to avoid metastable states and switching due to internal ground bounce. It can't be guaranteed that it suppresses switching due to external system noise.

 C_L = 2.5 pF for all LVDSH parameters.

Table 3-24 LVDSH - IEEE standard LVDS general purpose link (GPL)

Parameter	Symbol		Values			Note / Test Condition
		Min.	Тур.	Max.		
Output impedance	R_0 CC	40	-	140	Ohm	Vcm = 1.0 V and 1.4 V
Rise time 1)	t _{rise20} CC	-	-	0.5	ns	ZL = 100 Ohm ±5% @2 pF
Fall time 1)	t _{fall20} CC	-	-	0.5	ns	ZL = 100 Ohm ±5% @ 2 pF
Output differential voltage	$V_{OD}CC$	250	-	400	mV	RT = 100 Ohm ±5%

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²⁾ For currents smaller than the $I_{\rm OL/OH}$ from the test condition the defined Max. value stays unchanged.

³⁾ Rise / fall times are defined 10% - 90% of $V_{\rm DDP3}$.

⁴⁾ $V_{\text{IHx}} = 0.57 * V_{\text{DDP3}} - 0.03 \text{V}$

⁵⁾ $V_{\rm ILx}$ = 0.25 * $V_{\rm DDP3}$ + 0.058V



Table 3-24 LVDSH - IEEE standard LVDS general purpose link (GPL) (cont'd)

Parameter	Symbol		Value	s	Unit	Note / Test Condition
		Min.	Тур.	Max.		
Output voltage high	$V_{OH}CC$	-	-	1475	mV	RT = 100 Ohm ±5% (400 mV/2) + 1275 mV
Output voltage low	$V_{OL}CC$	925	-	-	mV	RT = 100 Ohm ±5%
Output offset (Common mode) voltage	$V_{\rm OS}$ CC	1125	-	1275	mV	RT = 100 Ohm ±5%
Input voltage range	V _I SR	0	-	1600	mV	Driver ground potential difference < 925 mV; RT = 100 Ohm ±10%
		0	-	2000	mV	Driver ground potential difference < 925 mV; RT = 100 Ohm ±20%
Input differential threshold	$V_{idth}SR$	-100	-	100	mV	Driver ground potential difference < 925 mV
Delta output impedance	dR0 SR	-	-	10	%	Vcm = 1.0 V and 1.4 V (mismatch Pd and Pn)
Change in VOS between 0 and 1	dVOS CC	-	-	25	mV	RT = 100 Ohm ±5%
Change in Vod between 0 and 1	dVod CC	-	-	25	mV	RT = 100 Ohm ±5%
Duty cycle	t _{duty} CC	45	-	55	%	

¹⁾ Rise / fall times are defined for 20% - 80% of $\,V_{\rm OD}$

Table 3-25 LVDSH - IEEE standard LVDS reduced link (REDL)

Parameter	Symbol		Value	s	Unit	Note / Test Condition
		Min.	Тур.	Max.		
Output impedance	R_0 CC	40	-	140	Ohm	Vcm = 1.0 V and 1.4 V
Output differential voltage	$V_{OD}CC$	150	-	250	mV	RT = 100 Ohm ±5%
Output voltage high	$V_{OH}CC$	-	-	1375	mV	RT = 100 Ohm ±5%
Output voltage low	$V_{OL}CC$	1025	-	-	mV	RT = 100 Ohm ±5%
Output offset (Common mode) voltage	V _{OS} CC	1125	-	1275	mV	RT = 100 Ohm ±5%
Input voltage range	V _I SR	825	-	1575	mV	Driver ground potential difference < 50 mV
Input differential threshold	$V_{idth}SR$	-100	-	100	mV	Driver ground potential difference < 50 mV
Change in VOS between 0 and 1	dVOS CC	-	-	25	mV	RT = 100 Ohm ±5%
Change in Vod between 0 and 1	dVod CC	-	-	25	mV	RT = 100 Ohm ±5%
Duty cycle	t _{duty} CC	45	-	55	%	

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Table 3-25 LVDSH - IEEE standard LVDS reduced link (REDL) (cont'd)

Parameter	Symbol		Value	Values		Note / Test Condition
		Min.	Тур.	Max.		
$V_{ m OD}$ Fall time $^{-1)}$	t_{fall10} CC	-	-	0.5	ns	ZL = 100 Ohm ±5% @ 2pF
$V_{ m OD}$ Rise time $^{1)}$	t _{rise10} CC	-	-	0.5	ns	ZL = 100 Ohm ±5% @ 2pF

¹⁾ Rise / fall times are defined for 10% - 90% of $V_{\rm OD}$

default after start-up = CMOS function

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3.8 Medium performance LVDS Pads (LVDSM)

This LVDS pad type is used for the medium speed chip to chip communication inferface of the new TC270 / TC275 / TC277. It compose out of a LVDSM pad and a MP pad.

This pad combination is always supplied by the 5V or 3.3V.

For the parameters of the MP pad please see Chapter 3.5.

Table 3-26 LVDSM

Parameter	Symbol	Symbol Values				Note / Test Condition
		Min.	Тур.	Max.		
Output impedance	$R_{\rm O}$ CC	40	100	140	Ohm	
Fall time	t _F CC	-	-	2.5	ns	Z_{load} = 100 Ohm; termination 100 Ohm ±1%
Rise time	t _R CC	-	-	2.5	ns	Z_{load} = 100 Ohm; termination 100 Ohm ±1%
Pad set-up time	t _{SET_LVDS}	-	10	13	μs	
Output Differential Voltage	$V_{OD}CC$	250	-	400	mV	termination 100 Ohm ±1%
Output voltage high	$V_{OH}CC$	-	-	1475	mV	termination 100 Ohm ±1%
Output voltage low	V _{OL} CC	925	-	-	mV	termination 100 Ohm ±1%
Output Offset Voltage	V _{os} CC	1125	-	1275	mV	termination 100 Ohm ±1%

default after start-up = CMOS function



3.9 VADC Parameters

VADC parameter are valid for $V_{\rm DDM}$ = 4.5 V to 5.5 V.

This tables also covers the parameters for Class D pads.

Table 3-27 VADC

Parameter	Symbol		Values		Unit	Note / Test Condition
		Min.	Тур.	Max.		
Analog reference voltage 1)	$V_{AREF}SR$	<i>V</i> _{AGND} + 1.0	-	V _{DDM} + 0.05	V	
Analog reference ground	$V_{AGND}SR$	V _{SSM} - 0.05	-	V _{SSM} + 0.05	V	
Analog input voltage range	$V_{AIN}SR$	V_{AGND}	-	V_{AREF}	V	
Converter reference clock	$f_{ADCI}SR$	2	-	20	MHz	
Charge consumption per conversion ^{2) 3)}	$Q_{CONV}CC$	-	50	75	pC	$V_{\rm AIN}$ = 5 V, charge consumed from reference pin, precharging disabled
		-	10	22	pC	$V_{\rm AIN}$ = 5 V, charge consumed from reference pin, precharging enabled
Conversion time for 12-bit result	t _{C12} CC	-	$(16 + STC) x$ $t_{ADCI} + 2 x$ t_{VADC}	-		Includes sample time and post calibration
Conversion time for 10-bit result	t _{C10} CC	-	$(14 + STC) x$ $t_{ADCI} + 2 x$ t_{VADC}	-		Includes sample time
Conversion time for 8-bit result	t _{C8} CC	-	$(12 + STC) x$ $t_{ADCI} + 2 x$ t_{VADC}	-		Includes sample time
Conversion time for fast compare mode	t _{CF} CC	-	(4 + STC) x t _{ADCI} + 2 x t _{VADC}	-		Includes sample time
Broken wire detection delay against $V_{AGND}^{-4)}$	t _{BWG} CC	-	-	120	cycles	Result below 10%
Broken wire detection delay against $V_{AREF}^{5)}$	t _{BWR} CC	-	-	60	cycles	Result above 80%
Input leakage at analog inputs	I _{OZ1} CC	-350	-	350	nA	Analog Inputs overlaid with class LP pads or pull down diagnostics
		-150	-	150	nA	else
Total Unadjusted Error 1)	TUE CC	-4 ⁶⁾	-	4 ⁶⁾	LSB	12-bit resolution



Table 3-27 VADC (cont'd)

Parameter	Symbol		Value	s	Unit	Note / Test Condition
		Min.	Тур.	Max.		
INL Error	EA _{INL} CC	-3	-	3	LSB	12-bit resolution
Gain Error 1)	EA _{GAIN} CC	-3.5	-	3.5	LSB	12-bit resolution
DNL error ¹⁾	EA _{DNL} CC	-3	-	3	LSB	12-bit resolution
Offset Error 1)	EA _{OFF} CC	-4	-	4	LSB	12-bit resolution
Total capacitance of an analog input	C_{AINT} CC	-	-	30	pF	
Switched capacitance of an analog input	C_{AINS} CC	2	4	7	pF	
Resistance of the analog input	R _{AIN} CC	-	-	1.5	kOhm	else
path		-	-	1.8	kOhm	valid for analog inputs mapped to GPIOs
Switched capacitance of a reference input	C_{AREFS} CC	-	-	30	pF	
RMS Noise 7)	EN_{RMS} CC	-	0.5	0.8 6)8)	LSB	
Positive reference V_{AREFx} pin leakage	I _{OZ2} CC	-7	-	7	μΑ	$V_{AREFx} = V_{AREF2};$ $V_{AREF} > V_{DDM} \lor;$ $T_{J} > 150 ^{\circ}C$
		-4	-	4	μΑ	$V_{\text{AREFx}} = V_{\text{AREF2}};$ $V_{\text{AREF}} > V_{\text{DDM}} \lor;$ $T_{\text{J}} \le 150 ^{\circ}\text{C}$
		-2	-	3	μΑ	$V_{AREFx} = V_{AREF2};$ $V_{AREF} \leq V_{DDM} V;$ $T_{J} > 150 ^{\circ} C$
		-1	-	1	μΑ	$V_{AREFx} = V_{AREF2};$ $V_{AREF} \leq V_{DDM} V;$ $T_{J} \leq 150^{\circ}C$
Negative reference V_{AGNDx} pin leakage	I _{OZ3} CC	-13	-	13	μΑ	$V_{\rm AGNDx} = V_{\rm AGND2};$ $V_{\rm AGND} < V_{\rm SSM} V;$ $T_{\rm J} > 150 ^{\circ} {\rm C}$
		-7	-	7	μΑ	$V_{\rm AGNDx} = V_{\rm AGND2};$ $V_{\rm AGND} < V_{\rm SSM} V;$ $T_{\rm J} \le 150 ^{\circ} {\rm C}$
		-3.3	-	2.5	μΑ	$V_{\text{AGNDx}} = V_{\text{AGND2}};$ $V_{\text{AREF}} \leq V_{\text{DDM}} V;$ $T_{\text{J}} > 150 ^{\circ} \text{C}$
		-2.85	-	1	μА	$V_{\text{AGNDx}} = V_{\text{AGND2}};$ $V_{\text{AREF}} \leq V_{\text{DDM}} V;$ $T_{\text{J}} \leq 150^{\circ} \text{C}$
Resistance of the reference input path	R _{AREF} CC	-	-	1	kOhm	
CSD resistance 9)	$R_{CSD}CC$	-	-	28	kOhm	



Table 3-27 VADC (cont'd)

Parameter	Symbol	Values			Unit	Note / Test Condition
		Min.	Тур.	Max.	-	
Resistance of the multiplexer	R_{MDD} CC	$25 + 1*V_{IN}$	-	35 - 8*V _{IN}	kOhm	$0 \text{ V} \le V_{IN} \le 2.5 \text{ V}$
diagnostics pull-down device		-5 + 13*V _{IN}	-	15 + 16*V _{IN}	kOhm	$2.5 \text{ V} \le V_{\text{IN}} \le V_{\text{DDM}}$
Resistance of the multiplexer diagnostics pull-up device	R _{MDU} CC	45 - 6*V _{IN}	-	90 - 16*V _{IN}	kOhm	$0 \text{ V} \ge V_{\text{IN}} \le 2.5 \text{ V}$
		40 - 4*V _{IN}	-	65 - 6*V _{IN}	kOhm	$2.5 \text{ V} \le V_{\text{IN}} \le V_{\text{DDM}}$
Resistance of the pull-down test device ¹⁰⁾	R_{PDD} CC	-	-	0.3	kOhm	
CSD voltage accuracy 11) 12)	dVCSD CC	-	-	10	%	
Wakeup time	t _{WU} CC	-	-	12	μs	

- 1) If the reference voltage is reduced by the factor k (k < 1), TUE,DNL,INL,Gain, and Offset errors increase also by the factor 1/k. V_{AREF} must be decoupled with an external capacitor.
- 2) For QCONV = X pC and a conversion time of 1 μ s a rms value of X μ A results for I_{AREFX} .
- 3) For the details of the mapping for a VADC group to pin V_{AREFx} please see the User's Manual.
- 4) The broken wire detection delay against V_{AGND} is measured in numbers of consecutive precharge cycles at a conversion rate higher than 1 conversion per 500 ms.
- 5) The broken wire detection delay against V_{AREF} is measured in numbers of consecutive precharge cycles at a conversion rate higher than 1 conversion per 10 ms. This function is influenced by leakage current, in particular at high temperature.
- 6) Resulting worst case combined error is arithmetic combination of TUE and $EN_{\rm RMS}$.
- 7) This parameter is valid for soldered devices and requires careful analog board design.
- 8) Value is defined for one sigma Gauss distribution.
- 9) In order to avoid an additional error due to incomplete sampling, the sampling time shall be set greater than 5 * R_{CSD} * C_{AINS}.
- 10) The pull-down resistor R_{PDD} is connected between the input pad and the analog multiplexer. The input pad itself adds another 200-Ohm series resistance, when measuring through the pin.
- 11) CSD: Converter Self Diagnostics, for details please consult the User's Manual.
- 12) Note, that in case CSD voltage is chosen to nom. 1/3 or 2/3 of V_{AREF} voltage, the reference voltage is loaded with a current of max. V_{AREF} / 45 kOhm.

The following VADC parameter are valid for $V_{\rm DDM}$ = 2.97 V to 3.63 V.

Table 3-28 VADC_33V

Parameter	Symbol	Values			Unit	Note / Test Condition
		Min.	Тур.	Max.		
Analog reference voltage 1)	$V_{AREF}SR$	V _{AGND} + 1.0	-	V _{DDM} + 0.05	V	
Analog reference ground	$V_{AGND}SR$	V _{SSM} - 0.05	-	V _{SSM} + 0.05	V	
Analog input voltage range	$V_{AIN}SR$	V_{AGND}	-	V_{AREF}	V	
Converter reference clock	$f_{ADCI}SR$	2	-	20	MHz	

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Table 3-28 VADC_33V (cont'd)

Parameter	Symbol		Values		Unit	Note / Test Condition
		Min.	Тур.	Max.		
Charge consumption per conversion ^{2) 3)}	Q_{CONV} CC	-	35	50	pC	$V_{\rm AIN}$ = 3.3 V, charge consumed from reference pin, precharging disabled
		-	8	17	pC	$V_{\rm AIN}$ = 3.3 V, charge consumed from reference pin, precharging enabled
Conversion time for 12-bit result	t _{C12} CC	-	$(16 + STC) x$ $t_{ADCI} + 2 x$ t_{VADC}	-		Includes sample time and post calibration
Conversion time for 10-bit result	t _{C10} CC	-	(14 + STC) x $t_{ADCI} + 2 x$ t_{VADC}	-		Includes sample time
Conversion time for 8-bit result	t _{C8} CC	-	(12 + STC) x $t_{ADCI} + 2 x$ t_{VADC}	_		Includes sample time
Conversion time for fast compare mode	t _{CF} CC	-	$(4 + STC)$ $x t_{ADCI} + 2$ $x t_{VADC}$	-		Includes sample time
Broken wire detection delay against $V_{\rm AGND}^{-4)}$	t _{BWG} CC	-	-	120	cycles	Result below 10%
Broken wire detection delay against $V_{\rm AREF}$ $^{5)}$	t _{BWR} CC	-	-	60	cycles	Result above 80%
Input leakage at analog inputs	I _{OZ1} CC	-350	-	350	nA	Analog Inputs overlaid with class LP pads or pull down diagnostics
		-150	-	150	nA	else
Total Unadjusted Error 1)	TUE CC	-12 ⁶⁾	-	12 ⁶⁾	LSB	12-bit Resolution; $T_{\rm J}$ > 150 °C
		-6 ⁶⁾	-	6 ⁶⁾	LSB	12-bit Resolution; <i>T</i> _J ≤ 150 °C
INL Error	EA _{INL} CC	-12	-	12	LSB	12-bit Resolution; $T_{\rm J}$ > 150 °C
		-5	-	5	LSB	12-bit Resolution; <i>T</i> _J ≤ 150 °C
Gain Error 1)	EA _{GAIN} CC	-6	-	6	LSB	12-bit Resolution; $T_{\rm J}$ > 150 °C
		-5.5	-	5.5	LSB	12-bit Resolution; <i>T</i> _J ≤ 150 °C



Table 3-28 VADC_33V (cont'd)

Parameter	Symbol		Value	s	Unit	Note / Test Condition
		Min.	Тур.	Max.		
DNL error 1)	EA _{DNL} CC	-4	-	4	LSB	12-bit resolution
Offset Error 1)	EA _{OFF} CC	-6	-	6	LSB	12-bit Resolution; $T_{\rm J}$ > 150 °C
		-5	-	5	LSB	12-bit Resolution; <i>T</i> _J ≤ 150 °C
Total capacitance of an analog input	C_{AINT} CC	-	-	30	pF	
Switched capacitance of an analog input	C_{AINS} CC	2	4	7	pF	
Resistance of the analog input path	R _{AIN} CC	-	-	4.5	kOhm	
Switched capacitance of a reference input	C_{AREFS} CC	-	-	30	pF	
RMS Noise 7)	EN _{RMS} CC	-	-	1.7 6)8)	LSB	
Positive reference V_{AREFx} pin leakage	I _{OZ2} CC	-6	-	6	μΑ	$V_{AREFx} = V_{AREF2};$ $V_{AREF} > V_{DDM} V;$ $T_{J} > 150^{\circ}C$
		-3.5	-	3.5	μΑ	$V_{\text{AREFx}} = V_{\text{AREF2}};$ $V_{\text{AREF}} > V_{\text{DDM}} \lor;$ $T_{\text{J}} \le 150 ^{\circ}\text{C}$
		-2	-	2.5	μΑ	$V_{AREFx} = V_{AREF2};$ $V_{AREF} \leq V_{DDM} V;$ $T_{J} > 150 ^{\circ} C$
		-1	-	1	μΑ	$V_{AREFx} = V_{AREF2};$ $V_{AREF} \leq V_{DDM} V;$ $T_{J} \leq 150^{\circ} C$
Negative reference V_{AGNDx} pin leakage	I _{OZ3} CC	-12	-	12	μΑ	$V_{\rm AGNDx}$ = $V_{\rm AGND2}$; $V_{\rm AGND}$ < $V_{\rm SSM}$ V; $T_{\rm J}$ > 150 ° C
		-6.5	-	6.5	μΑ	$V_{\rm AGNDx}$ = $V_{\rm AGND2}$; $V_{\rm AGND}$ < $V_{\rm SSM}$ V; $T_{\rm J}$ \leq 150° C
		-2.2	-	2	μΑ	$V_{\text{AGNDx}} = V_{\text{AGND2}};$ $V_{\text{AREF}} \leq V_{\text{DDM}} V;$ $T_{\text{J}} > 150 ^{\circ} \text{C}$
		-1	-	1	μΑ	$V_{\text{AGNDx}} = V_{\text{AGND2}};$ $V_{\text{AREF}} \leq V_{\text{DDM}} V;$ $T_{\text{J}} \leq 150^{\circ} \text{C}$
Resistance of the reference input path	R _{AREF} CC	-	-	3	kOhm	
CSD resistance 9)	$R_{\rm CSD}$ CC	-	-	28	kOhm	



Table 3-28 VADC_33V (cont'd)

Parameter	Symbol		Values		Unit	Note / Test Condition
		Min.	Тур.	Max.		
Resistance of the multiplexer diagnostics pull-down device	R _{MDD} CC	25 + 3*V _{IN}	-	40 + 12* <i>V</i> _{IN}	kOhm	$0 \text{ V} \le V_{\text{IN}} \le 1.667 \text{ V}$
		$0 + 18*V_{IN}$	-	$0 + 18*V_{IN}$	kOhm	$1.667 \text{ V} \leq V_{\text{IN}} \leq V_{\text{DDM}}$
Resistance of the multiplexer diagnostics pull-up device	R _{MDU} CC	60 - 12* <i>V</i> _{IN}	-	120 - 30*V _{IN}	kOhm	$0 \text{ V} \le V_{\text{IN}} \le 1.667 \text{ V}$
		55 - 9*V _{IN}	-	95 - 15*V _{IN}	kOhm	$1.667 \text{ V} \le V_{\text{IN}} \le V_{\text{DDM}}$
Resistance of the pull-down test device ¹⁰⁾	$R_{PDD}CC$	-	-	0.9	kOhm	
CSD voltage accuracy 11) 12)	dVCSD CC	-	-	10	%	
Wakeup time	t _{WU} CC	-	-	12	μs	

- 1) If the reference voltage is reduced by the factor k (k < 1), TUE,DNL,INL,Gain, and Offset errors increase also by the factor 1/k. V_{AREF} must be decoupled with an external capacitor.
- 2) For QCONV = X pC and a conversion time of 1 μ s a rms value of X μ A results for I_{AREFx} .
- 3) For the details of the mapping for a VADC group to pin V_{AREFx} please see the User's Manual.
- 4) The broken wire detection delay against V_{AGND} is measured in numbers of consecutive precharge cycles at a conversion rate higher than 1 conversion per 500 ms.
- 5) The broken wire detection delay against V_{AREF} is measured in numbers of consecutive precharge cycles at a conversion rate higher than 1 conversion per 10 ms. This function is influenced by leakage current, in particular at high temperature.
- 6) Resulting worst case combined error is arithmetic combination of TUE and $EN_{\rm RMS}$.
- 7) This parameter is valid for soldered devices and requires careful analog board design.
- 8) Value is defined for one sigma Gauss distribution.
- 9) In order to avoid an additional error due to incomplete sampling, the sampling time shall be set greater than 5 * R_{CSD} * C_{AINS} .
- 10) The pull-down resistor R_{PDD} is connected between the input pad and the analog multiplexer. The input pad itself adds another 200-Ohm series resistance, when measuring through the pin.
- 11) CSD: Converter Self Diagnostics, for details please consult the User's Manual.
- 12) Note, that in case CSD voltage is chosen to nom. 1/3 or 2/3 of V_{AREF} voltage, the reference voltage is loaded with a current of max. V_{AREF} / 45 kOhm.

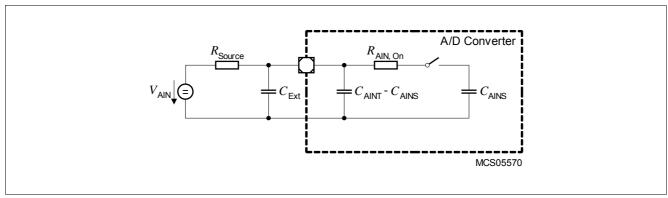


Figure 3-1 Equivalent Circuitry for Analog Inputs

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3.10 DSADC Parameters

The following DSADC parameter are valid for $V_{\rm DDM}$ = 4.5 V to 5.5 V.

Table 3-29 DSADC

Parameter	Symbol		Value	s	Unit	Note / Test Condition
		Min.	Тур.	Max.		
Analog input voltage range 1)	$V_{DSIN}SR$	0	-	5	V	single ended
		0	-	10	V	$\begin{array}{c} \text{differential;} V_{\text{DSxP}} \text{ -} \\ V_{\text{DSxN}} \end{array}$
Reference load current	I _{REF} SR	-	4.5	6.3	μΑ	per twin-modulator (1 or 2 channels)
Modulator clock frequency 2)	$f_{MOD}SR$	10	-	20	MHz	
Gain error	ED_{GAIN} CC	-1	-	1 ³⁾	%	Calibrated once
		-3.5 ⁴⁾	-	3.5 4)	%	Uncalibrated
		-0.2	-	0.2 5)	%	calibrated; GAIN = 1; MODCFG.INCFGx=01
DC offset error	ED_{OFF} CC	-5	-	5 ⁵⁾	mV	calibrated
		-50	-	50	mV	calibrated once
		-100 ⁴⁾	04)	100 ⁴⁾	mV	gain = 1; uncalibrated
Common Mode Rejection Ratio	ED_{CM} CC	200	500	-		
Input impedance 6)	$R_{DAIN}CC$	100	130	170	kOhm	Exact value (±1%) available in UCB
Signal-Noise Ratio ^{7) 8) 9) 10)}	SNR CC	80	-	-	dB	$f_{\rm PB}$ = 30 kHz; $V_{\rm DDM}$ = ±5%; $f_{\rm MOD}$ = 20 MHz; GAIN = 1
		78	-	-	dB	$f_{\rm PB}$ = 50 kHz; $V_{\rm DDM}$ = ±5%; $f_{\rm MOD}$ = 20 MHz; GAIN = 1
		70	-	-	dB	$f_{\rm PB}$ = 100 kHz; $V_{\rm DDM}$ = $\pm 10\%$; $f_{\rm MOD}$ = 20 MHz; GAIN = 1
		74	-	-	dB	$f_{\rm PB}$ = 100 kHz; $V_{\rm DDM}$ = ±5%; $f_{\rm MOD}$ = 20 MHz; GAIN = 1
		76	-	-	dB	$f_{\rm PB}$ = 30 kHz; $V_{\rm DDM}$ = $\pm 10\%$; $f_{\rm MOD}$ = 20 MHz; GAIN = 1
		74	-	-	dB	$f_{\rm PB}$ = 50 kHz; $V_{\rm DDM}$ = $\pm 10\%$; $f_{\rm MOD}$ = 20 MHz; GAIN = 1
Pass band	$f_{\sf PB}$ CC	10 11)	-	100	kHz	Output data rate f_D = f_{PB} * 3
Pass band ripple 8)	$df_{PB}CC$	-1	-	1	%	
Output sampling rate	$f_{D} CC$	30	_	330	kHz	



Table 3-29 DSADC (cont'd)

Parameter	Symbol		Value	s	Unit	Note / Test Condition
		Min.	Тур.	Max.		
DC compensation factor	DCF CC	-3	-	-	dB	$10^{-5} f_{D}$
Positive reference V_{AREF1} pin leakage	I _{OZ5} CC	-2	-	2	μΑ	all ADCs disabled
$\begin{tabular}{ll} \hline & Negative reference $V_{\rm AGND1}$ pin \\ leakage \\ \hline \end{tabular}$	I _{OZ6} CC	-2	-	2	μΑ	all ADCs disabled
Stop band attenuation 8)	SBA CC	40	-	-	dB	0.5 1 f _D
		45	-	-	dB	1 1.5 f _D
		50	-	-	dB	1.5 2 f _D
		55	-	-	dB	2 2.5 f _D
		60	-	-	dB	2.5 OSR/2 f _D
Reference ground voltage	$V_{AGND}SR$	$V_{\rm SSM}$ - 0.05	-	$V_{\rm SSM}$ + 0.05	V	
Positive reference voltage	$V_{AREF}SR$	$V_{ m DDMnom}$ * 0.9	-	V _{DDM} + 0.05	V	
Common mode voltage accuracy	$dV_{CM}CC$	-100	-	100	mV	from selected voltage
Common mode hold voltage deviation ¹²⁾	$dV_{CMH}CC$	-200	-	200	mV	From common mode voltage
Analog filter settling time	t _{AFSET} CC	-	2	4	μs	If enabled
Modulator recovery time	t _{MREC} CC	-	3.5	5.5	μs	After leaving overdrive state
Modulator settling time ¹³⁾	t _{MSET} CC	-	1	-	μs	After switching on, voltage regulator already running
Spurious Free Dynamic Range 7)14)	SFDR CC	60	-	-	dB	$V_{\rm CM}$ = 2.2 V, DC coupled; $V_{\rm DDM}$ = ±10%

- 1) The maximum input range for symmetrical signals (e.g. AC-coupled inputs) depends on the selected internal/external common mode voltage. In this case the Amplitude is limited to $V_{\rm CM}$ * 2.
- 2) All modulators must run on the same frequency.
- 3) The calibration sequence must be executed once after an Application Reset
- 4) The total DC error for the uncalibrated case can be calculated by the geometric addition of ED_{GAIN} and ED_{OFF}
- 5) Recalibration needed in case of a temperature change > 20°C
- 6) The variation of the impedance between different channels is < 1.5%.
- 7) Derating factors:
 - -2 dB in standard-performance mode.
 - -3 dB for CMV = 10_B, i.e. $V_{\rm CM}$ = ($V_{\rm AREF}\pm2\%$) / 2.0.
- 8) CIC3, FIR0, FIR1 filters enabled.
- 9) Single-ended mode reduces the SNR by 6 dB if the unused input is grounded, by 3 dB if the unused input connects to $V_{\rm CM}$ (GAIN = 2).
- 10) The defined limits are only valid if the following condition is not applicable: $T_{\rm J}$ > 150°C and $V_{\rm VAREF}$ > $V_{\rm DDM}$.
- 11) 10 kHz only reachable with 10 MHz modulator clock frequency.
- 12) Voltage $V_{\rm CM}$ is proportional to $V_{\rm AREF}$, voltage $V_{\rm CMH}$ is proportional to $V_{\rm DDM}$.
- 13) The modulator needs to settle after being switched on and after leaving the overdrive state.
- 14) SFDR = 20 * $log(INL / 2^{N})$; N = amount of bits

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The following DSADC parameter are valid for $V_{\rm DDM}$ = 2.97 V to 3.63 V.

Table 3-30 DSADC_33V

Parameter	Symbol		Value	s	Unit	Note / Test Condition
		Min.	Тур.	Max.		
Analog input voltage range 1)	$V_{DSIN}SR$	0	-	3.3	V	single ended
		0	-	6.6	V	$\begin{array}{c} \text{differential;} V_{\text{DSxP}} \text{ -} \\ V_{\text{DSxN}} \end{array}$
Reference load current	I _{REF} SR	-	4.5	5.8	μΑ	per twin-modulator (1 or 2 channels)
Modulator clock frequency 2)	$f_{MOD}SR$	10	-	20	MHz	
Gain error	ED_{GAIN} CC	-1.5	-	1.5 ³⁾	%	Calibrated once
		-10 ⁴⁾	-	10 4)	%	Uncalibrated
		-0.3	-	0.3 5)	%	calibrated; GAIN = 1; MODCFG.INCFGx=01
DC offset error	ED_{OFF} CC	-5	-	5 ⁵⁾	mV	calibrated
		-50	-	50	mV	calibrated once
		-100 ⁴⁾	_	100 ⁴⁾	mV	gain = 1; uncalibrated
		-	04)	-	mV	gain = 1; uncalibrated; uncalibrated
Common Mode Rejection Ratio	ED_{CM} CC	200	500	-		
Input impedance 6)	R _{DAIN} CC	100	130	170	kOhm	Exact value (±1%) available in UCB
Signal-Noise Ratio 7) 8) 9) 10)	SNR CC	45	63	-	dB	$f_{\rm PB}$ = 100kHz; $V_{\rm DDM}$ = ±10%; $f_{\rm MOD}$ = 20 MHz; GAIN = 1
		60	69	-	dB	$f_{\rm PB}$ = 100kHz; $V_{\rm DDM}$ = ±5%; $f_{\rm MOD}$ = 20 MHz; GAIN = 1
		60	68	-	dB	$f_{\rm PB}$ = 30kHz; $V_{\rm DDM}$ = $\pm 10\%$; $f_{\rm MOD}$ = 20 MHz; GAIN = 1
		69	74	-	dB	$\begin{split} f_{\mathrm{PB}} &= 30 \mathrm{kHz}; \ V_{\mathrm{DDM}} = \\ &\pm 5\%; f_{\mathrm{MOD}} = 20 \ \mathrm{MHz}; \\ \mathrm{GAIN} &= 1 \end{split}$
		55	66	-	dB	$f_{\rm PB}$ = 50kHz; $V_{\rm DDM}$ = ±10%; $f_{\rm MOD}$ = 20 MHz; GAIN = 1
		65	72	-	dB	$f_{\rm PB}$ = 50kHz; $V_{\rm DDM}$ = ±5%; $f_{\rm MOD}$ = 20 MHz; GAIN = 1
Pass band	f_{PB} CC	10 11)	-	100	kHz	Output data rate f_D = f_{PB} * 3
Pass band ripple 8)	$df_{PB}CC$	-1	-	1	%	



Table 3-30 DSADC_33V (cont'd)

Parameter	Symbol		Value	s	Unit	Note / Test Condition
		Min.	Тур.	Max.		
Output sampling rate	$f_{D} CC$	30	-	330	kHz	
DC compensation factor	DCF CC	-3	-	-	dB	$10^{-5} f_{D}$
Positive reference V_{AREF1} pin leakage	I _{OZ5} CC	-2	-	2	μA	
$\begin{tabular}{lll} \hline & Negative reference $V_{\rm AGND1}$ pin leakage \\ \hline \end{tabular}$	I _{OZ6} CC	-2	-	2	μA	
Stop band attenuation 8)	SBA CC	40	-	-	dB	0.5 1 f _D
		45	-	-	dB	1 1.5 f _D
		50	-	-	dB	1.5 2 f _D
		55	-	-	dB	2 2.5 f _D
		60	-	-	dB	2.5 OSR/2 f _D
Reference ground voltage	$V_{AGND}SR$	V _{SSM} - 0.05	-	V _{SSM} + 0.05	V	
Positive reference voltage	$V_{AREF}SR$	$V_{ m DDMnom}$ * 0.9	-	V _{DDM} + 0.05	V	
Common mode voltage accuracy	$dV_{CM}CC$	-100	-	100	mV	from selected voltage
Common mode hold voltage deviation ¹²⁾	$dV_{CMH}CC$	-200	-	200	mV	From common mode voltage
Analog filter settling time	t_{AFSET} CC	-	2	4	μs	If enabled
Modulator recovery time	t _{MREC} CC	-	3.5	-	μs	After leaving overdrive state
Modulator settling time ¹³⁾	t _{MSET} CC	-	1	-	μs	After switching on, voltage regulator already running
Spurious Free Dynamic Range 7)14)	SFDR CC	52	-	-	dB	$V_{\rm CM}$ = 2.2 V, DC coupled; $V_{\rm DDM}$ = ±10%
		60	-	-	dB	$V_{\rm CM}$ = 2.2 V, DC coupled; $V_{\rm DDM}$ = ±5%

¹⁾ The maximum input range for symmetrical signals (e.g. AC-coupled inputs) depends on the selected internal/external common mode voltage. In this case the Amplitude is limited to $V_{\rm CM}$ * 2.

- 2) All modulators must run on the same frequency.
- 3) The calibration sequence must be executed once after an Application Reset
- 4) The total DC error for the uncalibrated case can be calculated by the geometric addition of ED_{GAIN} and ED_{OFF}
- 5) Recalibration needed in case of a temperature change > 20°C.
- 6) The variation of the impedance between different channels is < 1.5%.
- 7) Derating factors:
 - -2 dB in standard-performance mode.
 - -3 dB for CMV = $10_{\rm B}$, i.e. $V_{\rm CM}$ = ($V_{\rm AREF}\pm2\%$) / 2.0.
- 8) CIC3, FIR0, FIR1 filters enabled.
- 9) Single-ended mode reduces the SNR by 6 dB if the unused input is grounded, by 3 dB if the unused input connects to $V_{\rm CM}$ (GAIN = 2).
- 10) The defined limits are only valid if the following condition is not applicable: $T_{\rm J}$ > 150°C and $V_{\rm VAREF}$ > $V_{\rm DDM}$.

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- 11) 10 kHz bandwidth only with 10Mhz modulator clock frequency reachable
- 12) Voltage $V_{\rm CM}$ is proportional to $V_{\rm AREF}$, voltage $V_{\rm CMH}$ is proportional to $V_{\rm DDM}$.
- 13) The modulator needs to settle after being switched on and after leaving the overdrive state.
- 14) SFDR = 20 * $log(INL / 2^{N})$; N = amount of bits

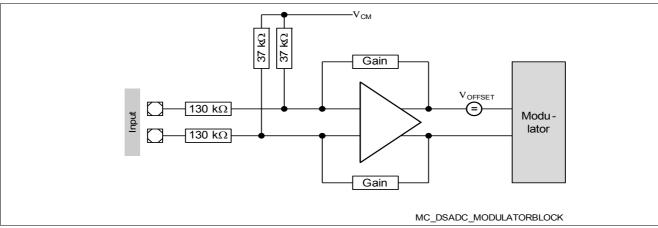


Figure 3-2 DSADC Analog Inputs



Electrical SpecificationMHz Oscillator

3.11 MHz Oscillator

OSC_XTAL is used as accurate and exact clock source. OSC_XTAL supports 8 MHz to 40 MHz crystals external outside of the device. Support of ceramic resonators is also provided.

Table 3-31 OSC_XTAL

Parameter	Symbol		Value	s	Unit	Note / Test Condition
		Min.	Тур.	Max.		
Input current at XTAL1	$I_{\rm IX1}$ CC	-25	-	25	μA	$V_{IN} > 0V$; $V_{IN} < V_{DDP3} V$
Oscillator frequency	$f_{ m OSC}{ m SR}$	4	-	40	MHz	Direct Input Mode selected
		8	-	40	MHz	External Crystal Mode selected
Oscillator start-up time 1)	$t_{ m OSCS}$ CC	-	-	5 ²⁾	ms	
Input high voltage at XTAL1	$V_{IHBX}SR$	0.8	-	V _{DDP3} + 0.5	V	If shaper is bypassed
Input low voltage at XTAL1	$V_{ILBX}SR$	-0.5	-	0.4	V	If shaper is bypassed
Input voltage at XTAL1	$V_{IX}SR$	-0.5	-	V _{DDP3} + 0.5	V	If shaper is not bypassed
Input amplitude (peak to peak) at XTAL1	$V_{PPX}SR$	0.3 * V _{DDP3}	-	V _{DDP3} + 1.0	V	If shaper is not bypassed; $f_{\rm OSC}$ > 25MHz
		0.4 * V _{DDP3}	-	V _{DDP3} + 1.0	V	If shaper is not bypassed; $f_{\rm OSC} \le$ 25MHz
Internal load capacitor	$C_{L0}CC$	2	2.35	2.7	pF	
Internal load capacitor	$C_{L1}CC$	2	2.35	2.7	pF	
Internal load capacitor	$C_{L2}CC$	3	3.5	4	pF	
Internal load capacitor	$C_{L3}CC$	5.1	5.9	6.6	pF	

¹⁾ $t_{\rm OSCS}$ is defined from the moment when $V_{\rm DDP3}$ = 3.13V until the oscillations reach an amplitude at XTAL1 of 0.3 * $V_{\rm DDP3}$. The external oscillator circuitry must be optimized by the customer and checked for negative resistance as recommended and specified by crystal suppliers.

Note: It is strongly recommended to measure the oscillation allowance (negative resistance) in the final target system (layout) to determine the optimal parameters for the oscillator operation. Please refer to the limits specified by the crystal or ceramic resonator supplier.

²⁾ This value depends on the frequency of the used external crystal. For faster crystal frequencies this value decrease.



Electrical SpecificationBack-up Clock

3.12 Back-up Clock

The back-up clock provides an alternative clock source.

Table 3-32 Back-up Clock

Parameter	eter Symbol Values			Unit	Note / Test Condition	
		Min.	Тур.	Max.		
Back-up clock before trimming	f_{BACKUT} CC	75	100	125	MHz	V _{EXT} ≥2.97V
Back-up clock after trimming	f_{BACKT} CC	97.5	100	102.5	MHz	V _{EXT} ≥2.97V



Electrical SpecificationTemperature Sensor

3.13 Temperature Sensor

Table 3-33 DTS

Parameter	Symbol	Values			Unit	Note / Test Condition
		Min.	Тур.	Max.		
Measurement time	t _M CC	-	-	100	μs	
Calibration reference accuracy	T_{CALACC} CC	-1	-	1	°C	calibration points @ T_J =-40°C and T_J =127°C
Non-linearity accuracy over temperature range	$T_{NL}CC$	-2	-	2	°C	
Temperature sensor range	$T_{SR}SR$	-40	-	170	°C	
Start-up time after resets inactive	$t_{TSST}SR$	-	-	20	μs	

The following formula calculates the temperature measured by the DTS in $[^{\circ}C]$ from the RESULT bit field of the DTSSTAT register.

(3.1)

$$Tj = \frac{DTSSTATRESULT - (607)}{2, 13}$$



3.14 Power Supply Current

The total power supply current defined below consists of leakage and switching component.

Application relevant values are typically lower than those given in the following table and depend on the customer's system operating conditions (e.g. thermal connection or used application configurations).

The operating conditions for the parameters in the following table are:

The real (realisic) power pattern defines the following conditions:

- T₁ = 150 °C
- $f_{SRI} = f_{MAX} = f_{CPU0} = 200 \text{ MHz}$
- $f_{\text{SPB}} = f_{\text{STM}} = f_{\text{GTM}} = f_{\text{BAUD1}} = f_{\text{BAUD2}} = f_{\text{ASCLIN}} = 40 \text{ MHz}$
- $V_{\rm DD}$ = 1.326 V
- $V_{\text{DDP3}} = 3.366 \text{ V}$
- $V_{\text{EXT/FLEX}} = V_{\text{DDM}} = 5.1 \text{ V}$
- · all cores are active including one lockstep core
- the following peripherals are inactive: HSM, HSCT, Ethernet, PSI5, I2C, FCE, MTU, and 50% of the DSADC channels

The max power pattern defines the following conditions:

- T_J = 150 °C
- $f_{SRI} = f_{MAX} = f_{CPU0} = 200 \text{ MHz}$
- $f_{\rm SPB}$ = $f_{\rm STM}$ = $f_{\rm GTM}$ = $f_{\rm BAUD1}$ = $f_{\rm BAUD2}$ = $f_{\rm ASCLIN}$ = 100 MHz
- $V_{\rm DD}$ = 1.43 V
- $V_{\rm DDP3} = 3.63 \text{ V}$
- $V_{\text{EXT/FLEX}} = V_{\text{DDM}} = 5.5 \text{ V}$
- · all cores and lockstep cores are active
- · all peripherals are active

Table 3-34 Power Supply

Parameter	Symbol		Value	S	Unit	Note / Test Condition
		Min.	Тур.	Max.		
Σ Sum of I_{DD} 1.3 V core and	I_{DD} CC	-	-	550	mA	max power pattern
peripheral supply currents		-	-	350	mA	real power pattern
$I_{\rm DD}$ core current during active	$I_{DDPORST}$	-	-	80	mA	<i>T</i> _J =125°C
power-on reset (PORST held low)	CC	-	-	160	mA	T _J =150°C
		-	-	215	mA	<i>T</i> _J =165°C
$I_{\rm DD}$ core current of CPU0 lockstep core active	I _{DDC01} CC	-	-	36	mA	real power pattern
$I_{\rm DD}$ core current of CPU1 main core with CPU1 lockstep core inactive	I _{DDC10} CC	-	-	43	mA	real power pattern
$\overline{I_{\rm DD}}$ core current of CPU1 main core with lockstep core active	I _{DDC11} CC	-	-	<i>I</i> _{DDC10} + 36	mA	real power pattern
$\overline{I_{\mathrm{DD}}}$ core current of CPU2 main core	I _{DDC20} CC	-	-	37	mA	real power pattern



Table 3-34 Power Supply (cont'd)

Parameter	Symbol		Value	s	Unit	Note / Test Condition
		Min.	Тур.	Max.		
$\overline{I_{ m DD}}$ core current added by HSM	I _{DDHSM} CC	-	-	20	mA	HSM running at 100MHz.
\sum Sum of 3.3 V supply currents without pad activity	I _{DDx3RAIL} CC	-	-	57	mA	real power pattern
$\overline{I_{\text{DDFL3}}}$ Flash memory current	$I_{DDFL3}CC$	-	-	42 ¹⁾	mA	flash read current
		-	-	42 ²⁾	mA	flash read current while programming Dflash
I _{DDP3} supply current without pad activity	I _{DDP3} CC	-	-	15 ¹⁾	mA	real power pattern; incl. OSC current & flash read current
		-	-	37 ³⁾	mA	incl. OSC current and flash 3.3V programming current when using external 5V supply
		-	-	39 ²⁾	mA	incl. OSC current and flash programming current at 3.3V
$\overline{I_{\mathrm{DDP3}}}$ supply current for LVDSH pads in LVDS mode	I _{DDP3LVDSH} CC	-	-	16	mA	
Σ Sum of external and ADC supply currents (incl. $I_{\text{EXTFLEX}} + I_{\text{DDM}} + I_{\text{EXTLVDSM}}$)	I _{EXTRAIL} CC	-	-	62	mA	real power pattern
Sum of I_{EXT} and I_{FLEX} supply current without pad activity	I _{EXT/FLEX} CC	-	-	4	mA	real power pattern; PORST output inactive.
$\overline{I_{\rm EXT}}$ supply current for LVDSM pads in LVDS mode	I _{EXTLVDSM} CC	-	-	14 4)	mA	real power pattern



Table 3-34 Power Supply (cont'd)

Parameter	Symbol		Value	S	Unit	Note / Test Condition
		Min.	Тур.	Max.		
$\overline{I_{ extsf{DDM}}}$ supply current	I_{DDM} CC	-	-	44	mA	real power pattern; sum of currents of DSADC and VADC modules
		-	-	30	mA	current for DSADC module only; 50% DSADC channels active.
		-	-	14	mA	real pattern; current for VADC only
		-	-	59 ⁵⁾	mA	max power pattern; All DSADC channels active 100% time.
		-	-	17 ⁶⁾	mA	max power pattern; All VADC converters are active 100% time
Σ Sum of all currents (incl. $I_{\rm EXTRAIL} + I_{\rm DDX3RAIL} + I_{\rm DD}$)	I_{DDTOT} CC	-	-	469	mA	real power pattern
Σ Sum of all currents with DC-DC EVR13 regulator active $^{7)}$	I_{DDTOTDC3}	-	-	302	mA	real power pattern; $V_{\text{EXT}} = 3.3V$
Σ Sum of all currents with DC-DC EVR13 regulator active $^{7)}$	I _{DDTOTDC5} CC	-	-	240	mA	real power pattern; $V_{\text{EXT}} = 5V$
Σ Sum of all currents (STANDBY mode)	I_{EVRSB} CC	-	-	150 8)	μА	Standby RAM is active. Power to remaining domains switched off. T_J = 25° C ; V_{EVRSB} = 5 V
Σ Sum of all currents (SLEEP mode)	I _{SLEEP} CC	-	-	15	mA	All CPUs in idle, All peripherals in sleep, $f_{\rm SRI/SPB}$ = 1 MHz via LPDIV divider; $T_{\rm J}$ = 25° C
Maximum power dissipation	PD CC	-	-	1480	mW	max power pattern
		-	-	1014	mW	real power pattern

¹⁾ Realistic Pflash read pattern with 70% Pflash bandwidth utilization and a code mix of 50% 0s and 50% 1s. A common decoupling capacitor of atleast 100nF for $(V_{\rm DDFL3} + V_{\rm DDP3})$ is used. Dflash read current is also included. Flash read current is predominantly drawn from $V_{\rm DDFL3}$ pin and a minor part drawn from the neighbouring $V_{\rm DDP3}$ pin.

²⁾ Continuous Dflash programming in burst mode with 3.3 V supply and realistic Pflash read access in parallel. Erase currents of the corresponding flash modules are less than the respective programming currents at $V_{\rm DDP3}$ pin. Programming and erasing flash may generate transient current spikes of up to x mA for maximum x us which is handled by the decoupling and buffer capacitors. This parameter is relevant for external power supply dimensioning and not for thermal considerations.

³⁾ In addition to the current specified, upto 4 mA is additionally drawn at V_{EXT} supply in burst programming mode with 5V external supply. Erase currents of the corresponding flash modules are less than the respective programming currents at V_{DDP3} supply. This parameter is relevant for external power supply dimensioning and not for thermal considerations.



- 4) The current consumption is for 2 pairs of LVDSM differential pads (8 pins). A single pair of LVDSM differential pads (4 pins) consumes 7 mA.
- 5) The current consumption is for 6 DS channels with standard performance (MCFG=11b). A single DS channel instance consumes 6-8 mA.
- 6) A single converter instance of VADC unit consumes 2 mA.
- 7) The total current drawn from external regulator is estimated with 72% EVR13 SMPS regulator Efficiency. $I_{\rm DDTOTDC}x$ is calculated from $I_{\rm DDTOT}$ using the scaled core current [$(I_{\rm DD} \times V_{\rm DD})/({\rm VinxEfficiency})$] and constitutes all other rail currents and $I_{\rm DDM}$.
- 8) Current at V_{EVRSB} supply pin during normal RUN mode is less than 5 mA at Tj =150 degC. The transition between RUN mode to STANDBY mode has a duration of less than 100us during which the current is higher but is less than 8 mA at Tj =150 degC. Once STANDBY mode is entered with only Standby RAM active the current is less than 5mA at Tj = 150 degC. It is recommended to have atleast 100 nF decoupling capacitor at this pin.

3.14.1 Calculating the 1.3 V Current Consumption

The current consumption of the 1.3 V rail compose out of two parts:

- Static current consumption
- Dynamic current consumption

The static current consumption is related to the device temperature T_J and the dynamic current consumption depends of the configured clocking frequencies and the software application executed. These two parts needs to be added in order to get the rail current consumption.

(3.2)

$$I_0 = 1,135 \left[\frac{\text{mA}}{\text{C}} \right] \times e^{0,02689} \times T_J[\text{C}]$$

(3.3)

$$I_0 = 3,264 \left[\frac{mA}{C} \right] \times e^{0,0259 \times T} J[C]$$

Function 2 defines the typical static current consumption and Function 3 defines the maximum static current consumption. Both functions are valid for V_{DD} = 1.326 V.

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3.15 Power-up and Power-down

3.15.1 External Supply Mode

5 V & 1.3 V supplies are externally supplied. 3.3V is generated internally by EVR33.

- External supplies VEXT and VDD may ramp-up or ramp-down independent of each other with regards to start, rise and fall time(s). Voltage Ramp-up from a residual threshold (Eg: up to 1 V) should also lead to a normal startup of the device.
- The rate at which current is drawn from the external regulator (dIEXT /dt or dIDD /dt) is limited in the Start-up phase to a maximum of 50 mA/100 us.
- PORST is active/asserted when either PORST (input) or PORST (output) is active/asserted.
- PORST (input) active means that the reset is held active by external agents by pulling the PORST pin low. It
 is recommended to keep the PORST (input) asserted until all the external supplies are above their primary
 reset thresholds.
- PORST (output) active means that μC asserts the reset internally and drives the PORST pin low thus
 propagating the reset to external devices. The PORST (output) is asserted by the μC when atleast one among
 the three supply domains (1.3 V, 3.3 V or 5 V) violate their primary under-voltage reset thresholds. The
 PORST (output) is deasserted by the μC when all supplies are above their primary reset thresholds and the
 basic supply and clock infrastructure is available.
- The power sequence as shown in Figure 3-3 is enumerated below
 - T1 refers to the point in time when basic supply and clock infrastructure is available as the external supplies ramp up. The supply mode is evaluated based on the HWCFG [0:2] pins and consequently a soft start of EVR33 regulator is initiated.
 - T2 refers to the point in time when all supplies are above their primary reset thresholds. EVR33 regulator
 has ramped up. PORST (output) is deasserted and HWCFG [0:7] pins are latched on PORST rising edge.
 Firmware execution is initiated.
 - T3 refers to the point in time when Firmware execution is completed. User code execution starts with a default frequency of 100 MHz.
 - T4 refers to the point in time during the Ramp-down phase when atleast one of the externally provided or generated supplies (1.3 V, 3.3 V or 5 V) drop below their respective primary under-voltage reset thresholds.

Please note that there is no special requirements for PORST slew rates.

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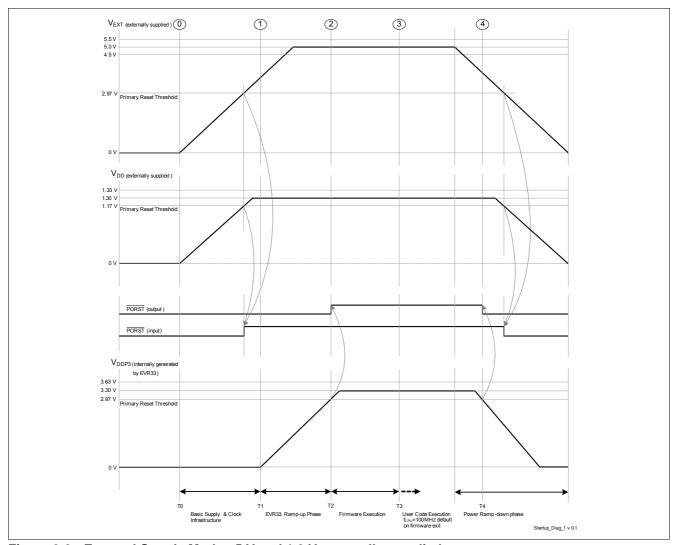


Figure 3-3 External Supply Mode - 5 V and 1.3 V externally supplied

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3.15.2 Single Supply Mode

5 V single supply mode. 1.3 V & 3.3 V are generated internally by EVR13 & EVR33.

- The rate at which current is drawn from the external regulator (dIEXT /dt) is limited in the Start-up phase to a maximum of 50 mA/100 us.
- PORST is active/asserted when either PORST (input) or PORST (output) is active/asserted.
- PORST (input) active means that the reset is held active by external agents by pulling the PORST pin low. It
 is recommended to keep the PORST (input) asserted until the external supply is above the respective primary
 reset threshold.
- PORST (output) active means that μC asserts the reset internally and drives the PORST pin low thus
 propagating the reset to external devices. The PORST (output) is asserted by the μC when atleast one among
 the three supply domains (1.3 V, 3.3 V or 5 V) violate their primary under-voltage reset thresholds. The
 PORST (output) is deasserted by the μC when all supplies are above their primary reset thresholds and the
 basic supply and clock infrastructure is available.
- The power sequence as shown in Figure 3-4 is enumerated below
 - T1 refers to the point in time when basic supply and clock infrastructure is available as the external supply ramps up. The supply mode is evaluated based on the HWCFG [0:2] pins and consequently a soft start of EVR13 and EVR33 regulators are initiated.
 - T2 refers to the point in time when all supplies are above their primary reset thresholds. EVR13 and EVR33 regulators have ramped up. PORST (output) is deasserted and HWCFG [0:7] pins are latched on PORST rising edge. Firmware execution is initiated.
 - T3 refers to the point in time when Firmware execution is completed. User code execution starts with a default frequency of 100 MHz.
 - T4 refers to the point in time during the Ramp-down phase when atleast one of the externally provided or generated supplies (1.3 V, 3.3 V or 5 V) drop below their respective primary under-voltage reset thresholds.

Please note that there is no special requirements for PORST slew rates.

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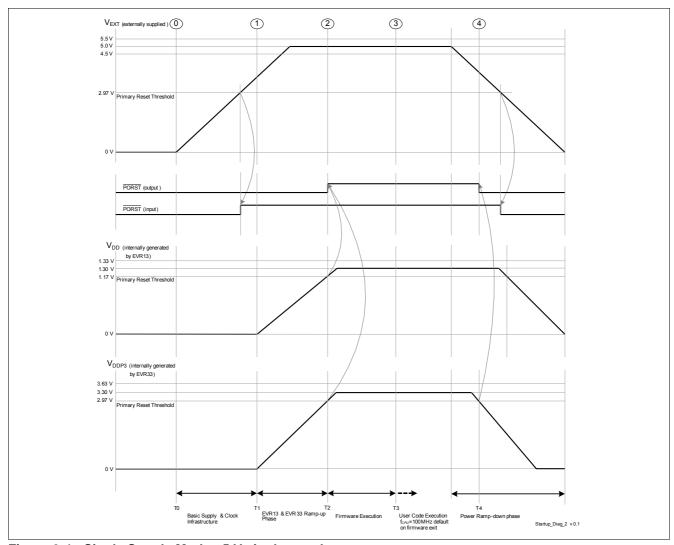


Figure 3-4 Single Supply Mode - 5 V single supply



3.15.3 External Supply Mode

All supplies, namely 5 V, 3.3 V & 1.3 V, are externally supplied.

- External supplies VEXT,, VDDP3 & VDD may ramp-up or ramp-down independent of each other with regards to start, rise and fall time(s).
- The rate at which current is drawn from the external regulator (dIEXT /dt, dIDD /dt or dIDDP3 /dt) is limited in the Start-up phase to a maximum of 50 mA/100 us.
- PORST is active/asserted when either PORST (input) or PORST (output) is active/asserted.
- PORST (input) active means that the reset is held active by external agents by pulling the PORST pin low. It
 is recommended to keep the PORST (input) asserted until all the external supplies are above their primary
 reset thresholds.
- PORST (output) active means that μC asserts the reset internally and drives the PORST pin low thus
 propagating the reset to external devices. The PORST (output) is asserted by the μC when atleast one among
 the three supply domains (1.3 V, 3.3 V or 5 V) violate their primary under-voltage reset thresholds. The
 PORST (output) is deasserted by the μC when all supplies are above their primary reset thresholds and the
 basic supply and clock infrastructure is available.
- The power sequence as shown in Figure 3-5 is enumerated below
 - T1 refers to the point in time when all supplies are above their primary reset thresholds and basic clock infrastructure is available. The supply mode is evaluated based on the HWCFG [0:2] pins. PORST (output) is deasserted and HWCFG [0:7] pins are latched on PORST rising edge. Firmware execution is initiated.
 - T2 refers to the point in time when Firmware execution is completed. User code execution starts with a default frequency of 100 MHz.
 - T3 refers to the point in time during the Ramp-down phase when atleast one of the externally provided supplies (1.3 V, 3.3 V or 5 V) drop below their respective primary under-voltage reset thresholds.

Please note that there is no special requirements for PORST slew rates.



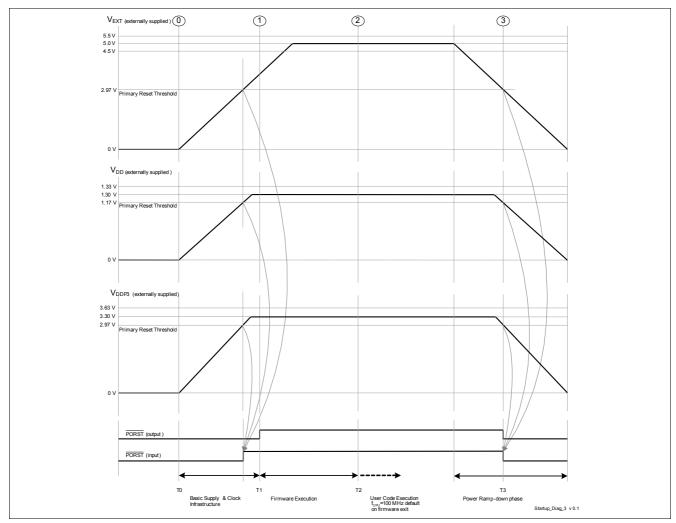


Figure 3-5 External Supply Mode - 5 V, 3.3 V & 1.3 V externally supplied

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3.15.4 Single Supply Mode

3.3 V single supply mode. 1.3 V is generated internally by EVR13.

- The rate at which current is drawn from the external regulator (dIEXT /dt) is limited in the Start-up phase to a maximum of 50 mA/100 us.
- PORST is active/asserted when either PORST (input) or PORST (output) is active/asserted.
- PORST (input) active means that the reset is held active by external agents by pulling the PORST pin low. It
 is recommended to keep the PORST (input) asserted until the external supply is above the respective primary
 reset threshold.
- PORST (output) active means that μC asserts the reset internally and drives the PORST pin low thus
 propagating the reset to external devices. The PORST (output) is asserted by the μC when atleast one among
 the three supply domains (1.3 V or 3.3 V) violate their primary under-voltage reset thresholds. The
 PORST (output) is deasserted by the μC when all supplies are above their primary reset thresholds and the
 basic supply and clock infrastructure is available.
- The power sequence as shown in Figure 3-6 is enumerated below
 - T1 refers to the point in time when basic supply and clock infrastructure is available as the external supply ramps up. The supply mode is evaluated based on the HWCFG [0:2] pins and consequently a soft start of EVR13 regulator is initiated.
 - T2 refers to the point in time when all supplies are above their primary reset thresholds. EVR13 regulator
 has ramped up. PORST (output) is deasserted and HWCFG [0:7] pins are latched on PORST rising edge.
 Firmware execution is initiated.
 - T3 refers to the point in time when Firmware execution is completed. User code execution starts with a default frequency of 100 MHz.
 - T4 refers to the point in time during the Ramp-down phase when atleast one of the externally provided or generated supplies (1.3 V or 3.3 V) drop below their respective primary under-voltage reset thresholds.

Please note that there is no special requirements for PORST slew rates.



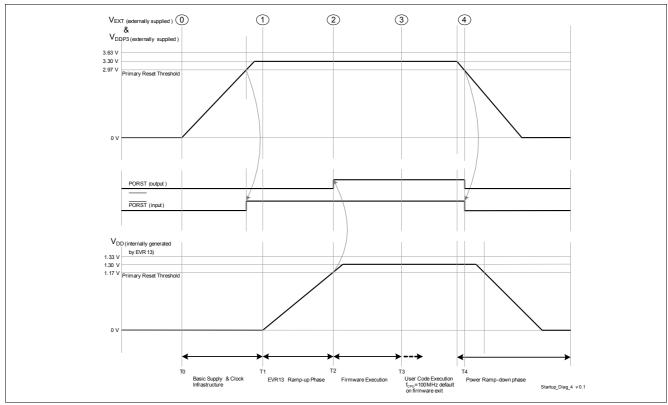


Figure 3-6 Single Supply Mode - 3.3 V single supply



Electrical SpecificationReset Timing

3.16 Reset Timing

Table 3-35 Reset Timings

Parameter	Symbol		Value	s	Unit	Note / Test Condition
		Min.	Тур.	Max.		
Application Reset Boot Time 1)	t _B CC	-	-	350 ²⁾	μs	operating with max. frequencies.
System Reset Boot Time	t_{BS} CC	-	-	1	ms	
Power on Reset Boot Time ³⁾	t _{BP} CC	-	-	2.5 ²⁾	ms	dV/dT=1V/ms. including EVR ramp- up and Firmware execution time
		-	-	1.11 2)	ms	Firmware execution time; without EVR operation (external supply only)
Minimum PORST hold time incase of power fail event issued by EVR primary monitor	t _{EVRPOR} CC	10	-	-	μs	
EVR start-up or ramp-up time	t _{EVRstartup}	-	-	1	ms	dV/dT=1 V/ms . EVR13 and EVR33 active
Minimum PORST active hold time after power supplies are stable at operating levels 4)	t _{POA} CC	1	-	-	ms	
Configurable PORST digital filter delay in addition to analog pad filter delay	t _{PORSTDF} CC	600	-	1200	ns	
HWCFG pins hold time from ESR0 rising edge	t _{HDH} CC	16 / f _{SPB}	-	-	ns	
HWCFG pins setup time to ESR0 rising edge	t _{HDS} CC	0	-	-	ns	
Ports inactive after ESR0 reset active	t _{Pl} CC	-	-	8/f _{SPB}	ns	
Ports inactive after PORST reset active 5)	t _{PIP} CC	-	-	150	ns	
Hold time from PORST rising edge	t _{POH} SR	150	-	-	ns	
Setup time to PORST rising edge	t _{POS} SR	0	-	-	ns	

¹⁾ The duration of the boot time is defined between the rising edge of the internal application reset and the clock cycle when the first user instruction has entered the CPU pipeline and its processing starts.

²⁾ The timing values assumes programmed BMI with ESR0CNT inactive.

³⁾ The duration of the boot time is defined by all external supply voltages are inside there operation condictions and the clock cycle when the first user instruction has entered the CPU pipeline and its processing starts.



Electrical SpecificationReset Timing

- 4) The regulator that supplies $V_{\rm EXT}$ should ensure that $V_{\rm EXT}$ is in the operational region before PORST is externally released by the regulator. Incase of 5V nominal supply, it should be ensured that $V_{\rm EXT} > 4$ V before PORST is released. Incase of 3.3V nominal supply , it should be ensured that $V_{\rm EXT} > 3$ V before PORST is released. The additional minimum PORST hold time is required as an additional mechanism to avoid consecutive PORST toggling owing to slow supply slopes or residual supply ramp-ups. It is also required to activate external PORST atleast 100us before power-fail is recognised to avoid consecutive PORST toggling on a power fail event.
- 5) This parameter includes the delay of the analog spike filter in the PORST pad.

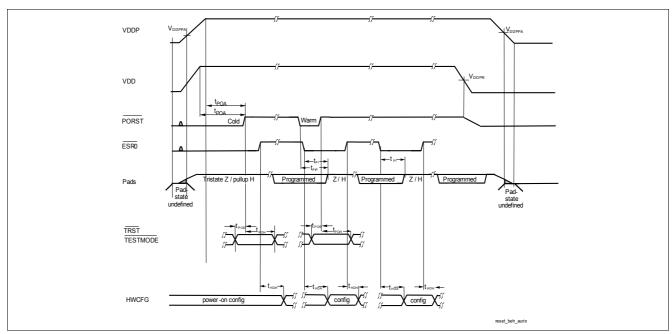


Figure 3-7 Power, Pad and Reset Timing

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3.17 EVR

Table 3-36 3.3V

Parameter	Symbol Values				Unit	Note / Test Condition
		Min.	Тур.	Max.		
Input voltage range 1)	$V_{IN}SR$	4	-	5.50	V	pass device=on chip
Output voltage operational range including load/line regulation and aging incase of LDO regulator	V _{OUT} CC	2.97	3.3	3.63	V	pass device=on chip
Output $V_{\rm DDx3}$ static voltage accuracy after trimming and aging without dynamic load/line Regulation incase of LDO regulator.	$V_{OUTT}CC$	3.225	3.3	3.375	V	pass device=on chip
$\begin{tabular}{lll} \hline Output buffer capacitance on \\ $V_{\rm OUT}$^{2)} \\ \hline \end{tabular}$	$C_{OUT}CC$	-	1	-	μF	pass device=on chip
Primary Undervoltage Reset threshold for $V_{\rm DDx3}^{\ \ 3)}$	$V_{RST33}CC$	-	-	3.0	V	by reset release before EVR trimming on supply ramp-up.
Startup time	t _{STR} CC	-	-	1000	μs	Only EVR33 active. ; pass device=on chip
External V_{IN} supply ramp $^{4)}$	dVin/dT SR	-	1	50	V/ms	pass device=on chip
Load step response	dVout/dIout CC	-	-	240	mV	dI=-70mA/20ns; Tsettle=20us; pass device=on chip
		-240	-	-	mV	dI=50mA/20ns; Tsettle=100us; pass device=on chip
Line step response	dVout/dVin	-20	-	20	mV	dV/dT=1 V/ms ; pass device=on chip

¹⁾ A maximum pass device dropout voltage of 700mV is included in the minimum input voltage to ensure optimal pass device operation.

²⁾ It is recommended to select a capacitor with ESR less than 50 mOhm (0.5MHz - 10 MHz). It is also recommended that the resistance of the supply trace from the pin to the EVR output capacitor is less than 100 mOhm.

³⁾ The reset release on supply ramp-up is delayed by a time duration 20-40 us after reaching undervoltage reset threshold. This serves as a time hysteresis to avoid multiple consecutive cold PORST events during slow supply ramp-ups owing to voltage drop/current jumps when reset is released. The reset limit of 2,97V at pin is for the case with 3.3V generated internally from EVR33. In case the 3.3V supply is provided externally, the bondwire drop will cause a reset at a higher voltage of 3.0V at the $V_{\rm DDP3}$ pin.

⁴⁾ EVR robust against residual voltage ramp-up starting between 0-1 V.



Table 3-37 1.3V

Parameter	Symbol		Value	s	Unit	Note / Test Condition
		Min.	Тур.	Max.		
Input voltage range 1)	$V_{IN}SR$	2.97	-	5.5	V	pass device=off chip
Output voltage operational range including load/line regulation and aging incase of LDO regulator	V _{OUT} CC	1.17	1.3	1.43	V	pass device=off chip
Output $V_{\rm DD}$ static voltage accuracy after trimming without dynamic load/line regulation with aging incase of LDO regulator.	$V_{OUTT}CC$	1.275	1.3	1.325	V	pass device=off chip
$\begin{tabular}{lll} \hline Output buffer capacitance on \\ $V_{\rm OUT}$^{2)} \\ \hline \end{tabular}$	$C_{OUT}CC$	3	4.7	6.3	μF	pass device=off chip
Primary undervoltage reset threshold for $V_{\rm DD}^{\ \ 3)}$	V _{RST13} CC	-	-	1.17	V	by reset release before EVR trimming on supply ramp-up. pass device=off chip
Startup time	t _{STR} CC	-	-	1000	μs	pass device=off chip. Only EVR13 active.
External V_{IN} supply ramp $^{4)}$	dVin/dT SR	-	1	50	V/ms	pass device=off chip
Load step response	dVout/dIout CC	-	-	100	mV	dI=-150 mA ; $Tsettle$ =20 μs ; pass device=off chip
		-100	-	-	mV	dI=100 mA ; $Tsettle$ =20 μs ; pass device=off chip
Line step response	dVout/dVin	-10	-	10	mV	dV/dT=1 V/ms ; pass device=off chip

¹⁾ A maximum pass device dropout voltage of 700mV is included in the minimum input voltage to ensure optimal pass device operation.

²⁾ It is recommended to select a capacitor with ESR less than 50 mOhm (0.5MHz - 10 MHz). It is also recommended that the resistance of the supply trace from the pin to the EVR output capacitor is less than 100 mOhm.

³⁾ The reset release on supply ramp-up is delayed by a time duration 30-60 µs after reaching undervoltage reset threshold. This serves as a time hysteresis to avoid multiple consecutive cold PORST events during slow supply ramp-ups owing to voltage drop/current jumps when reset is released.

⁴⁾ EVR robust against residual voltage ramp-up starting between 0-1 V.



Table 3-38 Supply Monitoring

Parameter	Symbol		Value	s	Unit	Note / Test Condition
		Min.	Тур.	Max.		
$\overline{V_{\rm EXT}}$ primary undervoltage monitor accuracy after trimming $^{1)}$	V _{EXTPRIUV} SR	2.86	2.92	2.97	V	$V_{\rm EXT}$ = Undervoltage Reset Threshold
$\overline{V_{\mathrm{DDP3}}}$ primary undervoltage monitor accuracy after trimming $^{1)}$	$V_{ m DDP3PRIUV}$ SR	2.86	2.90	2.97	V	$V_{\rm DDP3}$ = Undervoltage Reset Threshold
$\overline{V_{\rm DD}}$ primary undervoltage monitor accuracy after trimming $^{1)}$	V _{DDPRIUV} SR	1.13	1.15	1.17	V	V_{DD} = Undervoltage Reset Threshold
$\overline{V_{\rm EXT}}$ secondary supply monitor accuracy	V _{EXTMON} CC	4.9	5.0	5.1	V	SWDxxVAL $V_{\rm EXT}$ monitoring threshold=5V=DBh
$\overline{V_{\mathrm{DDP3}}}$ secondary supply monitor accuracy	V _{DDP3MON} CC	3.23	3.30	3.37	V	EVR33xxVAL $V_{\rm DDP3}$ monitoring threshold=3.3V=91h
$\overline{V_{\mathrm{DD}}}$ secondary supply monitor accuracy	$V_{ m DDMON}$ CC	1.27	1.30	1.33	V	
EVR primary and secondary monitor measurement latency for a new supply value	t _{EVRMON} CC	-	-	1.8	μs	after trimming

¹⁾ The monitor tolerances constitute the inherent variation of the bandgap and ADC over process, voltage and temperature operational ranges. The xxxPRIUV parameters are device individually tested in production with ±1% tolerance about the min and max xxxPRIUV limits.

Table 3-39 EVR13 SMPS External components

Parameter	Symbol		Value	s	Unit	Note / Test Condition
		Min.	Тур.	Max.		
External output capacitor value	$C_{OUTDC}SR$	15.4	22	29.7	μF	I _{DDDC} =1A
1)		6.5	10	13.5	μF	I _{DDDC} =400mA
External output capacitor ESR	$C_{DC_ESR}SR$	-	-	50	mOhm	<i>f</i> ≥0.5MHz ; <i>f</i> ≤10MHz
		-	-	100	Ohm	<i>f</i> =10Hz
External input capacitor value 1)	C _{IN} SR	6.5	10	13.5	μF	I _{DDDC} =1A
		4.42	6.8	9.18	μF	I _{DDDC} =400mA
External input capacitor ESR	$C_{IN_ESR}SR$	-	-	50	mOhm	<i>f</i> ≥0.5MHz ; <i>f</i> ≤10MHz
		-	-	100	Ohm	<i>f</i> =100Hz
External inductor value 2)	$L_{ m DC}{ m SR}$	2.31	3.3	4.29	μH	$f_{\rm DCDC}$ =1.5MHz
		3.29	4.7	6.11	μH	$f_{ m DCDC}$ =1MHz
External inductor ESR	$L_{ m DC_ESR}{ m SR}$	-	-	0.2	Ohm	
P + N-channel MOSFET logic level	V _{LL} SR	-	-	2.5	V	



Table 3-39 EVR13 SMPS External components (cont'd)

Parameter	Symbol		Value	s	Unit	Note / Test Condition
		Min.	Тур.	Max.		
P + N-channel MOSFET drain source breakdown voltage	$/V_{\mathrm{BR}_{\mathrm{DS}}}$ SR	-	-	7	V	
P + N-channel MOSFET drain source ON-state resistance	R _{ON} SR	-	-	150	mOhm	I_{DDDC} =1A; V_{GS} =2.5 V ; T_{A} =25° C
		-	-	200	mOhm	I_{DDDC} =400mA; V_{GS} =2.5 V ; T_{A} =25° C
P + N-channel MOSFET Gate Charge	$Q_{ m ac}{ m SR}$	-	4	-	nC	$I_{ m DDDC}$ =1A; MOS- $V_{ m GS}$ =5V
		-	8	-	nC	$I_{ m DDDC}$ =400mA; MOS- $V_{ m GS}$ =5V
External MOSFET commutation time	t _c SR	10	30	40	ns	configurable
N-channel MOSFET reverse diode forward voltage	$V_{RDN}SR$	-	0.8	-	V	

¹⁾ Capacitor min-max range represent typical ±35% tolerance including DC bias effect. The trace resistance from the capacitor to the supply or ground rail should be limited to 25 mOhm.

Table 3-40 EVR13 SMPS

Parameter	Symbol Values				Unit	Note / Test Condition
		Min.	Тур.	Max.		
Input V_{EXT} Voltage range	$V_{IN}SR$	2.97	-	5.5	V	
SMPS regulator output voltage range including load/line regulation and aging 1)	$V_{ m DDDC}$ CC	1.17	-	1.43	V	$V_{\mathrm{DD}} \ge 2.97 \mathrm{V}$; $V_{\mathrm{DD}} \le 5.5 \mathrm{V}$; $I_{\mathrm{DDDC}} \ge 1 \mathrm{mA}$; $I_{\mathrm{DDDC}} \le 1 \mathrm{A}$
SMPS regulator static voltage output accuracy after trimming without dynamic load/line Regulation with aging. ²⁾	$V_{ m DDDCT}$ CC	1.275	1.3	1.325	V	$V_{\rm DD}$ \geq 2.97V ; $V_{\rm DD}$ \leq 5.5V ; $I_{\rm DDDC}$ \geq 1mA ; $I_{\rm DDDC}$ \leq 1A
Programmable switching frequency	f_{DCDC} CC	0.4	-	2.0	MHz	
Switching frequency modulation spread	Δf_{DCSPR} CC	-	-	2%	MHz	
Maximum ripple at $I_{\rm MAX}$ (peakto-peak) $^{3)}$	$\Delta V_{ exttt{DDDC}}$ CC	-	-	15	mV	$V_{\rm DD} \ge 2.97 \rm V$; $V_{\rm DD} \le 5.5 \rm V$; $I_{\rm DDDC} \ge 300 \rm mA$; $I_{\rm DDDC} \le 1 \rm A$
No load current consumption of SMPS regulator	I _{DCNL} CC	-	5	10	mA	f_{DCDC} =1 MHz

²⁾ External inductor min-max range represent typical ±30% tolerance at a DC bias current of 100mA.



Table 3-40 EVR13 SMPS (cont'd)

Parameter	Symbol		Value	s	Unit	Note / Test Condition
		Min.	Тур.	Max.		
SMPS regulator load transient response	dVout/dIout CC	-25	-	25	mV	dI < 200mA; $f_{\rm DCDC} = 1MHz$; $t_{\rm r} = 0.1 \mu s$; $t_{\rm f} = 0.1 \mu s$; $V_{\rm DDDC} = 1.3 V$
		-65	-	65	mV	dI < 400mA; $f_{DCDC}=1MHz$; $t_r=0.1\mu s$; $t_f=0.1\mu s$; $V_{DDDC}=1.3V$
		-130	-	130	mV	dI < 700mA; $f_{DCDC} = 1MHz$; $t_r = 0.1 \mu s$; $t_f = 0.1 \mu s$; $V_{DDDC} = 1.3 V$
Maximum output current of the regulator	I _{MAX} SR	-	-	1	A	limited by thermal constraints and component choice
SMPS regulator efficiency	n_{DC} CC	-	85	-	%	$V_{\rm IN}$ =3.3 V ; $I_{\rm DDDC}$ =300 mA ; $f_{\rm DCDC}$ =1 MHz
		-	75	-	%	V_{IN} =5 V ; I_{DDDC} =400 mA ; f_{DCDC} =1.5 MHz
		-	80	-	%	V_{IN} =5 V ; I_{DDDC} =400 mA ; f_{DCDC} =1 MHz

¹⁾ Incase of SMPS mode, It shall be ensured that the $V_{\rm DD}$ output pin shall be connected on PCB level to all other $V_{\rm DD}$ Input pins.

²⁾ Incase of $f_{\rm SRI}$ running with max frequency, it shall be ensured that the $V_{\rm DD}$ operating range is limited to 1.235V upto 1.430V. The DCDC may be configured in this case with a nominal voltage of 1.33V±7.5%. The static accuracy and regulation parameter ranges remain also valid for this case.

³⁾ If frequency spreading (SDFREQSPRD = 1) is activated, an additional ripple of 1% need to be considered.



Electrical SpecificationPhase Locked Loop (PLL)

3.18 Phase Locked Loop (PLL)

Table 3-41 PLL

Parameter	Symbol		Value	S	Unit	Note / Test Condition
		Min.	Тур.	Max.		
PLL base frequency	$f_{PLLBASE}$ CC	80	150	360	MHz	
VCO frequency range	$f_{\rm VCO}{\rm SR}$	400	-	800	MHz	
VCO Input frequency range	$f_{REF}CC$	8	-	24	MHz	
Modulation Amplitude	MA CC	0	-	2	%	
Peak Period jitter	DP CC	-200	-	200	ps	
Peak Accumulated Jitter	$D_{PP}CC$	-5	-	5	ns	without modulation
Total long term jitter	$J_{TOT}CC$	-	-	11.5	ns	including modulation; MA ≤ 1%
System frequency deviation	f_{SYSD} CC	-	-	0.01	%	with active modulation
Modulation variation frequency	f_{MV} CC	2	3.6	5.4	MHz	
PLL lock-in time	t_{L} CC	11.5	-	200	μs	

Note: The specified PLL jitter values are valid if the capacitive load per pin does not exceed $C_L = 20$ pF with the maximum driver and sharp edge.

Note: The maximum peak-to-peak noise on the power supply voltage, is limited to a peak-to-peak voltage of $V_{PP} = 100$ mV for noise frequencies below 300 KHz and $V_{PP} = 40$ mV for noise frequencies above 300 KHz. These conditions can be achieved by appropriate blocking of the supply voltage as near as possible to the supply pins and using PCB supply and ground planes.



Electrical SpecificationERAY Phase Locked Loop (ERAY_PLL)

3.19 ERAY Phase Locked Loop (ERAY_PLL)

Table 3-42 PLL_ERAY

Parameter	Symbol Values				Unit	Note / Test Condition
		Min.	Тур.	Max.		
PLL Base Frequency of the ERAY PLL	$f_{ m PLLBASE_ERA}$	50	200	320	MHz	
VCO frequency range of the ERAY PLL	$f_{ m VCO_ERAY}$ SR	400	-	480	MHz	
VCO input frequency of the ERAY PLL	$f_{REF}SR$	16	-	24	MHz	
Accumulated_Jitter	$D_{P}CC$	-0.5	-	0.5	ns	
Accumulated jitter at SYSCLK pin	$D_{PP}CC$	-0.8	-	0.8	ns	
PLL lock-in time	t _L CC	5.6	-	200	μs	

Note: The specified PLL jitter values are valid if the capacitive load per pin does not exceed $C_L = 20$ pF with the maximum driver and sharp edge.

Note: The maximum peak-to-peak noise on the power supply voltage, is limited to a peak-to-peak voltage of $V_{PP} = 100$ mV for noise frequencies below 300 KHz and $V_{PP} = 40$ mV for noise frequencies above 300 KHz. These conditions can be achieved by appropriate blocking of the supply voltage as near as possible to the supply pins and using PCB supply and ground planes.



Electrical SpecificationAC Specifications

3.20 AC Specifications

All AC parameters are specified for the complette operating range defined in **Chapter 3.4** unless otherwise noted in colum Note / test Condition.

Unless otherwise noted in the figures the timings are defined with the following guidelines:

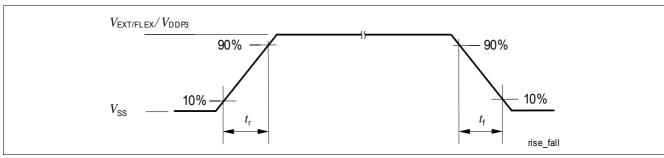


Figure 3-8 Definition of rise / fall times

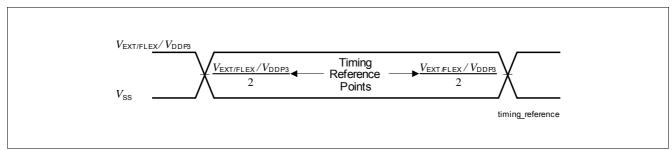


Figure 3-9 Time Reference Point Definition



Electrical SpecificationJTAG Parameters

3.21 JTAG Parameters

The following parameters are applicable for communication through the JTAG debug interface. The JTAG module is fully compliant with IEEE1149.1-2000.

Table 3-43 JTAG

Parameter	Symbol		Value	s	Unit	Note / Test Condition
		Min.	Тур.	Max.		
TCK clock period	t ₁ SR	25	-	-	ns	
TCK high time	t ₂ SR	10	-	-	ns	
TCK low time	t ₃ SR	10	-	-	ns	
TCK clock rise time	t ₄ SR	-	-	4	ns	
TCK clock fall time	t ₅ SR	-	-	4	ns	
TDI/TMS setup to TCK rising edge	t ₆ SR	6.0	-	-	ns	
TDI/TMS hold after TCK rising edge	t ₇ SR	6.0	-	-	ns	
TDO valid after TCK falling	t ₈ CC	3.0	-	-	ns	<i>C</i> _L ≤20pF
edge (propagation delay) 1)		-	-	16	ns	<i>C</i> _L ≤50pF
TDO hold after TCK falling edge ¹⁾	t ₁₈ CC	2	-	-	ns	
TDO high impedance to valid from TCK falling edge ¹⁾²⁾	t ₉ CC	-	-	17.5	ns	C _L ≤50pF
TDO valid output to high impedance from TCK falling edge ¹⁾	t ₁₀ CC	-	-	17	ns	<i>C</i> _L ≤50pF

- 1) The falling edge on TCK is used to generate the TDO timing.
- 2) The setup time for TDO is given implicitly by the TCK cycle time.

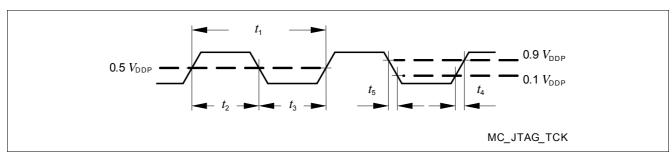


Figure 3-10 Test Clock Timing (TCK)



Electrical SpecificationJTAG Parameters

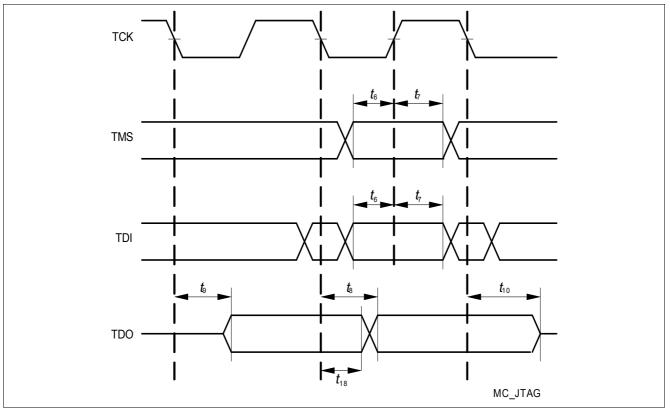


Figure 3-11 JTAG Timing



Electrical SpecificationDAP Parameters

3.22 DAP Parameters

The following parameters are applicable for communication through the DAP debug interface.

Table 3-44 DAP

Parameter	Symbol		Values			Note / Test Condition
		Min.	Тур.	Max.		
DAP0 clock period	t ₁₁ SR	6.25	-	-	ns	
DAP0 high time	t ₁₂ SR	2	-	-	ns	
DAP0 low time	t ₁₃ SR	2	-	-	ns	
DAP0 clock rise time	t ₁₄ SR	-	-	1	ns	<i>f</i> =160MHz
		-	-	2	ns	f=80MHz
DAP0 clock fall time	t ₁₅ SR	-	-	1	ns	<i>f</i> =160MHz
		-	-	2	ns	<i>f</i> =80MHz
DAP1 setup to DAP0 rising edge	t ₁₆ SR	4	-	-	ns	
DAP1 hold after DAP0 rising edge	t ₁₇ SR	2	-	-	ns	
DAP1 valid per DAP0 clock	t ₁₉ CC	3	-	-	ns	C_{L} =20pF; f =160MHz
period ¹⁾		8	-	-	ns	C_{L} =20pF ; f =80MHz
		10	-	-	ns	C_{L} =50pF ; f =40MHz

¹⁾ The Host has to find a suitable sampling point by analyzing the sync telegram response.

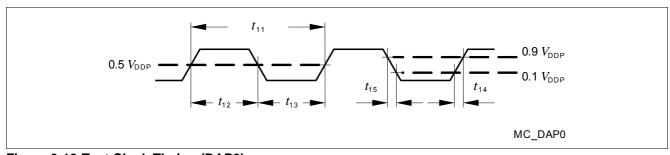


Figure 3-12 Test Clock Timing (DAP0)

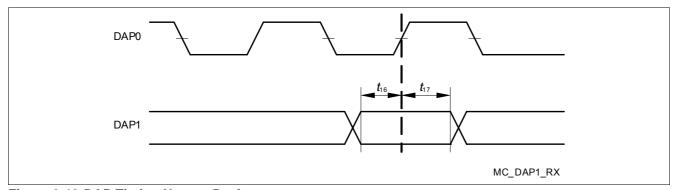


Figure 3-13 DAP Timing Host to Device



Electrical SpecificationDAP Parameters

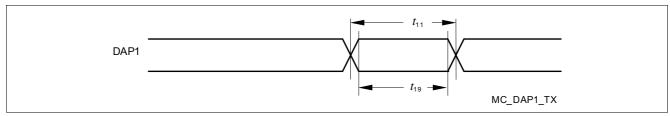


Figure 3-14 DAP Timing Device to Host (DAP1 and DAP2 pins)

Note: The DAP1 and DAP2 device to host timing is individual for both pins. There is no guaranteed max. signal skew

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3.23 ASCLIN SPI Master Timing

This section defines the timings for the ASCLIN in the TC270 / TC275 / TC277, for 5V power supply. *Note: Pad asymmetry is already included in the following timings.*

Table 3-45 Master Mode MP+ss/MPRss output pads

Parameter	Symbol		Value	Unit	Note / Test Condition	
		Min.	Тур.	Max.		
ASCLKO clock period 1)	t ₅₀ CC	20	-	-	ns	C _L =25pF
Deviation from ideal duty cycle 2)	t ₅₀₀ CC	-3	-	3	ns	0 < C _L < 50pF
MTSR delay from ASCLKO shifting edge	t ₅₁ CC	-7	-	6	ns	C _L =25pF
ASLSOn delay from the first ASCLKO edge	t ₅₁₀ CC	5	-	35	ns	C_L =25pF; pad used = LPm
MRST setup to ASCLKO latching edge	<i>t</i> ₅₂ SR	28	-	-	ns	C _L =25pF
MRST hold from ASCLKO latching edge	<i>t</i> ₅₃ SR	-6	-	-	ns	C _L =25pF

¹⁾ PLL Jitter not included. Should be considered additionally, corresponding to the used baudrate. The duty cycle can be adjusted using the BITCON.SAMPLEPOINT bitfield with the finest granularity of T_{MAX} = 1 / f_{MAX} .

Table 3-46 Master Mode MP+sm/MPRsm output pads

Parameter	Symbol Values				Unit	Note / Test Condition
		Min.	Тур.	Max.		
ASCLKO clock period 1)	t ₅₀ CC	50	-	-	ns	C _L =50pF
Deviation from ideal duty cycle 2)	t ₅₀₀ CC	-2	-	3+0.01 * C _L	ns	0 < C _L < 200pF
MTSR delay from ASCLKO shifting edge	t ₅₁ CC	-10	-	10	ns	C _L =50pF
ASLSOn delay from the first ASCLKO edge	t ₅₁₀ CC	5	-	35	ns	C _L =50pF; pad used = LPm
MRST setup to ASCLKO latching edge	t ₅₂ SR	50	-	-	ns	C _L =50pF
MRST hold from ASCLKO latching edge	t ₅₃ SR	-10	-	-	ns	C _L =50pF

¹⁾ PLL Jitter not included. Should be considered additionally, corresponding to the used baudrate. The duty cycle can be adjusted using the BITCON.SAMPLEPOINT bitfield with the finest granularity of $T_{\text{MAX}} = 1 / f_{\text{MAX}}$.

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²⁾ Positive deviation lenghtens the high time and shortens the low time of a clock period. Negative deviation does the opposite.

²⁾ Positive deviation lenghtens the high time and shortens the low time of a clock period. Negative deviation does the opposite.



Table 3-47 Master Mode MPss output pads

Parameter	Symbol Values					Note / Test Condition
		Min.	Тур.	Max.		
ASCLKO clock period 1)	t ₅₀ CC	20	-	-	ns	C _L =25pF
Deviation from ideal duty cycle 2)	t ₅₀₀ CC	-2	-	3.5+0.035 * C _L	ns	0 < C _L < 200pF
MTSR delay from ASCLKO shifting edge	t ₅₁ CC	-7	-	6	ns	C _L =25pF
ASLSOn delay from the first ASCLKO edge	t ₅₁₀ CC	-7	-	6	ns	C _L =25pF
MRST setup to ASCLKO	t ₅₂ SR	30	-	-	ns	$C_{\rm L}$ =25pF, else
latching edge		33 ³⁾	-	-	ns	C _L =25pF, for P14.2, P14.4, and P15.1
MRST hold from ASCLKO latching edge	<i>t</i> ₅₃ SR	-5	-	-	ns	C _L =25pF

¹⁾ PLL Jitter not included. Should be considered additionally, corresponding to the used baudrate. The duty cycle can be adjusted using the BITCON.SAMPLEPOINT bitfield with the finest granularity of $T_{\text{MAX}} = 1 / f_{\text{MAX}}$.

Table 3-48 Master Mode MPsm output pads

Parameter	Symbol		Value	s	Unit	Note / Test Condition
		Min.	Тур.	Max.		
ASCLKO clock period 1)	t ₅₀ CC	100	-	-	ns	C _L =50pF
Deviation from ideal duty cycle 2)	t ₅₀₀ CC	-3	-	4+0.04 * C _L	ns	0 < C _L < 200pF
MTSR delay from ASCLKO shifting edge	t ₅₁ CC	-11	-	10	ns	C _L =50pF
ASLSOn delay from the first ASCLKO edge	t ₅₁₀ CC	-11	-	10	ns	C _L =50pF
MRST setup to ASCLKO latching edge	t ₅₂ SR	60	-	-	ns	C _L =50pF
MRST hold from ASCLKO latching edge	<i>t</i> ₅₃ SR	-10	-	-	ns	C _L =50pF

¹⁾ PLL Jitter not included. Should be considered additionally, corresponding to the used baudrate. The duty cycle can be adjusted using the BITCON.SAMPLEPOINT bitfield with the finest granularity of T_{MAX} = 1 / f_{MAX} .

²⁾ Positive deviation lenghtens the high time and shortens the low time of a clock period. Negative deviation does the opposite.

³⁾ Please note that these pins didn't support the hystereses inactive feature.

²⁾ Positive deviation lenghtens the high time and shortens the low time of a clock period. Negative deviation does the opposite.



Table 3-49 Master Mode medium output pads

Parameter	Symbol Values					Note / Test Condition
		Min.	Тур.	Max.		
ASCLKO clock period 1)	t ₅₀ CC	200	-	-	ns	C _L =50pF
Deviation from ideal duty cycle 2)	t ₅₀₀ CC	-8	-	4+0.04 * C _L	ns	0 < C _L < 200pF
MTSR delay from ASCLKO shifting edge	t ₅₁ CC	-20	-	15	ns	C _L =50pF
ASLSOn delay from the first ASCLKO edge	t ₅₁₀ CC	-20	-	20	ns	C _L =50pF
MRST setup to ASCLKO latching edge	<i>t</i> ₅₂ SR	70	-	-	ns	C _L =50pF
MRST hold from ASCLKO latching edge	<i>t</i> ₅₃ SR	-10	-	-	ns	C _L =50pF

¹⁾ PLL Jitter not included. Should be considered additionally, corresponding to the used baudrate. The duty cycle can be adjusted using the BITCON.SAMPLEPOINT bitfield with the finest granularity of T_{MAX} = 1 / f_{MAX} .

Table 3-50 Master Mode weak output pads

Parameter	Symbol Values				Unit	Note / Test Condition
		Min.	Тур.	Max.		
ASCLKO clock period 1)	t ₅₀ CC	1000	-	-	ns	C _L =50pF
Deviation from ideal duty cycle 2)	t ₅₀₀ CC	-30	-	30+0.15 * C _L	ns	0 < C _L < 200pF
MTSR delay from ASCLKO shifting edge	t ₅₁ CC	-75	-	75	ns	C _L =50pF
ASLSOn delay from the first ASCLKO edge	t ₅₁₀ CC	-65	-	65	ns	C _L =50pF
MRST setup to ASCLKO latching edge	<i>t</i> ₅₂ SR	510	-	-	ns	C _L =50pF
MRST hold from ASCLKO latching edge	<i>t</i> ₅₃ SR	-50	-	-	ns	C _L =50pF

¹⁾ PLL Jitter not included. Should be considered additionally, corresponding to the used baudrate. The duty cycle can be adjusted using the BITCON.SAMPLEPOINT bitfield with the finest granularity of T_{MAX} = 1 / f_{MAX} .

²⁾ Positive deviation lenghtens the high time and shortens the low time of a clock period. Negative deviation does the opposite.

²⁾ Positive deviation lenghtens the high time and shortens the low time of a clock period. Negative deviation does the opposite.



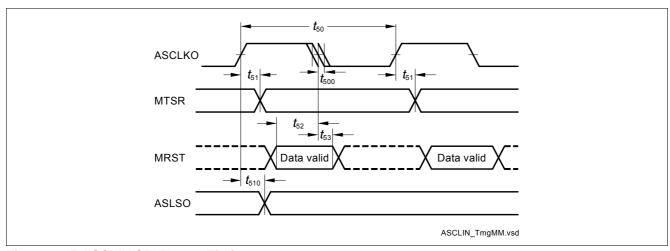


Figure 3-15 ASCLIN SPI Master Timing



3.24 ASCLIN SPI Master Timing

This section defines the timings for the ASCLIN in the TC270 / TC275 / TC277, for 3.3V power supply, Medium Performance pads, strong sharp edge (MPss), C_1 =25pF.

Note: Pad asymmetry is already included in the following timings.

Table 3-51 Master Mode MP+ss/MPRss output pads

Parameter	Symbol		Value	Unit	Note / Test Condition	
		Min.	Тур.	Max.		
ASCLKO clock period 1)	t ₅₀ CC	40	-	-	ns	C _L =25pF
Deviation from ideal duty cycle 2)	t ₅₀₀ CC	-5	-	5	ns	0 < C _L < 50pF
MTSR delay from ASCLKO shifting edge	t ₅₁ CC	-12	-	12	ns	C _L =25pF
ASLSOn delay from the first ASCLKO edge	t ₅₁₀ CC	0	-	60	ns	$C_{\rm L}$ =25pF; pad used = LPm
MRST setup to ASCLKO latching edge	t ₅₂ SR	50	-	-	ns	C _L =25pF
MRST hold from ASCLKO latching edge	<i>t</i> ₅₃ SR	-5	-	-	ns	C _L =25pF

¹⁾ PLL Jitter not included. Should be considered additionally, corresponding to the used baudrate. The duty cycle can be adjusted using the BITCON.SAMPLEPOINT bitfield with the finest granularity of $T_{\text{MAX}} = 1 / f_{\text{MAX}}$.

Table 3-52 Master Mode MP+sm/MPRsm output pads

Parameter	Symbol		Value	s	Unit	Note / Test Condition
		Min.	Тур.	Max.		
ASCLKO clock period 1)	t ₅₀ CC	100	-	-	ns	C _L =50pF
Deviation from ideal duty cycle 2)	t ₅₀₀ CC	-3	-	7	ns	0 < C _L < 200pF
MTSR delay from ASCLKO shifting edge	t ₅₁ CC	-17	-	17	ns	C _L =50pF
ASLSOn delay from the first ASCLKO edge	t ₅₁₀ CC	0	-	60	ns	C_L =50pF; pad used = LPm
MRST setup to ASCLKO latching edge	<i>t</i> ₅₂ SR	85	-	-	ns	C _L =50pF
MRST hold from ASCLKO latching edge	<i>t</i> ₅₃ SR	-5	-	-	ns	C _L =50pF

¹⁾ PLL Jitter not included. Should be considered additionally, corresponding to the used baudrate. The duty cycle can be adjusted using the BITCON.SAMPLEPOINT bitfield with the finest granularity of $T_{\text{MAX}} = 1 / f_{\text{MAX}}$.

²⁾ Positive deviation lenghtens the high time and shortens the low time of a clock period. Negative deviation does the opposite.

²⁾ Positive deviation lenghtens the high time and shortens the low time of a clock period. Negative deviation does the opposite.



Table 3-53 Master Mode MPss output pads

Parameter	Symbol Values					Note / Test Condition
		Min.	Тур.	Max.		
ASCLKO clock period 1)	t ₅₀ CC	40	-	-	ns	C _L =25pF
Deviation from ideal duty cycle 2)	t ₅₀₀ CC	-5	-	7+0.07 * C _L	ns	0 < C _L < 200pF
MTSR delay from ASCLKO shifting edge	t ₅₁ CC	-12	-	12	ns	C _L =25pF
ASLSOn delay from the first ASCLKO edge	t ₅₁₀ CC	-12	-	12	ns	C _L =25pF
MRST setup to ASCLKO latching edge	t ₅₂ SR	50	-	-	ns	C _L =25pF
MRST hold from ASCLKO latching edge	<i>t</i> ₅₃ SR	-5	-	-	ns	C _L =25pF

¹⁾ PLL Jitter not included. Should be considered additionally, corresponding to the used baudrate. The duty cycle can be adjusted using the BITCON.SAMPLEPOINT bitfield with the finest granularity of $T_{\text{MAX}} = 1 / f_{\text{MAX}}$.

Table 3-54 Master Mode MPsm output pads

Parameter	Symbol Values				Unit	Note / Test Condition
		Min.	Тур.	Max.		
ASCLKO clock period 1)	t ₅₀ CC	200	-	-	ns	C _L =50pF
Deviation from ideal duty cycle 2)	t ₅₀₀ CC	-5	-	9+0.06 * C _L	ns	0 < C _L < 200pF
MTSR delay from ASCLKO shifting edge	t ₅₁ CC	-19	-	17	ns	C _L =50pF
ASLSOn delay from the first ASCLKO edge	t ₅₁₀ CC	-19	-	17	ns	C _L =50pF
MRST setup to ASCLKO latching edge	<i>t</i> ₅₂ SR	100	-	-	ns	C _L =50pF
MRST hold from ASCLKO latching edge	t ₅₃ SR	-13	-	-	ns	C _L =50pF

¹⁾ PLL Jitter not included. Should be considered additionally, corresponding to the used baudrate. The duty cycle can be adjusted using the BITCON.SAMPLEPOINT bitfield with the finest granularity of $T_{\text{MAX}} = 1 / f_{\text{MAX}}$.

Table 3-55 Master Mode medium output pads

Parameter	Symbol		Values		Unit	Note / Test Condition
		Min.	Тур.	Max.		
ASCLKO clock period 1)	t ₅₀ CC	400	-	-	ns	C _L =50pF
Deviation from ideal duty cycle 2)	t ₅₀₀ CC	-6-0.07 * C _L	-	6+0.07 * C _L	ns	0 < C _L < 200pF

²⁾ Positive deviation lenghtens the high time and shortens the low time of a clock period. Negative deviation does the opposite.

²⁾ Positive deviation lenghtens the high time and shortens the low time of a clock period. Negative deviation does the opposite.



Table 3-55 Master Mode medium output pads (cont'd)

Parameter	Symbol	Symbol Values				Note / Test Condition
		Min.	Тур.	Max.		
MTSR delay from ASCLKO shifting edge	t ₅₁ CC	-33	-	25	ns	C _L =50pF
ASLSOn delay from the first ASCLKO edge	t ₅₁₀ CC	-35	-	35	ns	C _L =50pF
MRST setup to ASCLKO latching edge	t ₅₂ SR	120	-	-	ns	C _L =50pF
MRST hold from ASCLKO latching edge	t ₅₃ SR	-13	-	-	ns	C _L =50pF

¹⁾ PLL Jitter not included. Should be considered additionally, corresponding to the used baudrate. The duty cycle can be adjusted using the BITCON.SAMPLEPOINT bitfield with the finest granularity of $T_{\text{MAX}} = 1 / f_{\text{MAX}}$.

Table 3-56 Master Mode weak output pads

Parameter	Symbol		Value	Unit	Note / Test Condition	
		Min.	Тур.	Max.		
ASCLKO clock period 1)	t ₅₀ CC	2000	-	-	ns	C _L =50pF
Deviation from ideal duty cycle 2)	t ₅₀₀ CC	-110	-	150	ns	0 < C _L < 200pF
MTSR delay from ASCLKO shifting edge	t ₅₁ CC	-170	-	170	ns	C _L =50pF
ASLSOn delay from the first ASCLKO edge	t ₅₁₀ CC	-170	-	170	ns	C _L =50pF
MRST setup to ASCLKO latching edge	<i>t</i> ₅₂ SR	510	-	-	ns	C _L =50pF
MRST hold from ASCLKO latching edge	<i>t</i> ₅₃ SR	-40	-	-	ns	C _L =50pF

¹⁾ PLL Jitter not included. Should be considered additionally, corresponding to the used baudrate. The duty cycle can be adjusted using the BITCON.SAMPLEPOINT bitfield with the finest granularity of $T_{\text{MAX}} = 1 / f_{\text{MAX}}$.

Table 3-57 Master Mode A2ss output pads

Parameter	Symbol		Value	Values		Note / Test Condition
		Min.	Тур.	Max.		
ASCLKO clock period 1)	t ₅₀ CC	20	-	-	ns	C _L =50pF
Deviation from ideal duty cycle 2)	t ₅₀₀ CC	-3	-	3	ns	C _L =50pF
MTSR delay from ASCLKO shifting edge	t ₅₁ CC	-4	-	4	ns	C _L =50pF
ASLSOn delay from the first ASCLKO edge	t ₅₁₀ CC	-5	-	4	ns	C _L =50pF

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²⁾ Positive deviation lenghtens the high time and shortens the low time of a clock period. Negative deviation does the opposite.

²⁾ Positive deviation lenghtens the high time and shortens the low time of a clock period. Negative deviation does the opposite.



Table 3-57 Master Mode A2ss output pads (cont'd)

Parameter	Symbol	Values			Unit	Note / Test Condition
		Min.	Тур.	Max.		
MRST setup to ASCLKO latching edge	<i>t</i> ₅₂ SR	17	-	-	ns	C _L =50pF
MRST hold from ASCLKO latching edge	<i>t</i> ₅₃ SR	0	-	-	ns	C _L =50pF

¹⁾ PLL Jitter not included. Should be considered additionally, corresponding to the used baudrate. The duty cycle can be adjusted using the BITCON.SAMPLEPOINT bitfield with the finest granularity of $T_{\text{MAX}} = 1 / f_{\text{MAX}}$.

Table 3-58 Master Mode A2sm output pads

Parameter	Symbol		Value	Unit	Note / Test Condition	
		Min.	Тур.	Max.		
ASCLKO clock period 1)	t ₅₀ CC	40	-	-	ns	C _L =50pF
Deviation from ideal duty cycle 2)	t ₅₀₀ CC	-4	-	4	ns	C _L =50pF
MTSR delay from ASCLKO shifting edge	t ₅₁ CC	-8	-	6	ns	C _L =50pF
ASLSOn delay from the first ASCLKO edge	t ₅₁₀ CC	-8	-	9	ns	C _L =50pF
MRST setup to ASCLKO latching edge	t ₅₂ SR	26	-	-	ns	C _L =50pF
MRST hold from ASCLKO latching edge	<i>t</i> ₅₃ SR	0	-	-	ns	C _L =50pF

¹⁾ PLL Jitter not included. Should be considered additionally, corresponding to the used baudrate. The duty cycle can be adjusted using the BITCON.SAMPLEPOINT bitfield with the finest granularity of T_{MAX} = 1 / f_{MAX} .

²⁾ Positive deviation lenghtens the high time and shortens the low time of a clock period. Negative deviation does the opposite.

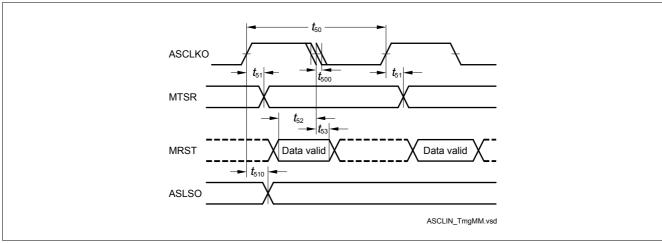


Figure 3-16 ASCLIN SPI Master Timing

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²⁾ Positive deviation lenghtens the high time and shortens the low time of a clock period. Negative deviation does the opposite.



3.25 QSPI Timings, Master and Slave Mode

This section defines the timings for the QSPI in the TC270 / TC275 / TC277, for 5V pad power supply. It is assumed that SCLKO, MTSR, and SLSO pads have the same pad settings:

- LVDSM output pads,LVDSH input pad, master mode, C_L=25pF
- Medium Performance Plus Pads (MP+):
 - strong sharp edge (MP+ss), C₁ =25pF
 - strong medium edge (MP+sm), C_L =50pF
 - medium edge (MP+m), C_L =50pF
 - weak edge (MP+w), C_L =50pF
 - Medium Performance Pads (MP):
 - strong sharp edge (MPss), C_L =25pF
 - strong medium edge (MPsm), C_1 =50pF
- Medium and Low Performance Pads (MP/LP), the identical output strength settings:
 - medium edge (LP/MPm), C_L =50pF
 - weak edge (MPw), C_L =50pF

Note: Pad asymmetry is already included in the following timings.

Table 3-59 Master Mode Timing, LVDSM output pads for data and clock

Parameter	Symbol		Value	s	Unit	Note / Test Condition
		Min.	Тур.	Max.		
SCLKO clock period 1)	t ₅₀ CC	20 ²⁾	-	-	ns	C _L =25pF
Deviation from the ideal duty cycle ^{3) 4)}	t ₅₀₀ CC	-1	-	1	ns	C _L =25pF
MTSR delay from SCLKO shifting edge	t ₅₁ CC	-3	-	3	ns	C _L =25pF
SLSOn deviation from the ideal	t ₅₁₀ CC	0	-	30	ns	$C_{\rm L}$ =25pF; MPsm
programmed position		-5	-	7	ns	$C_{\rm L}$ =25pF; MPss
		-4	-	7	ns	MP+ss; C_L =25pF
		-1	-	15	ns	MP+sm; C_L =25pF
MRST setup to SCLK latching edge ⁵⁾	<i>t</i> ₅₂ SR	19 ⁵⁾	-	-	ns	C_L =25pF; LVDSM 5V output and LVDSH 3.3V input
MRST hold from SCLK latching edge	<i>t</i> ₅₃ SR	-6 ⁵⁾	-	-	ns	C _L =25pF; LVDSM 5V output and LVDSH 3.3V input

¹⁾ Documented value is valid for master transmit or slave receive only. For full duplex the external SPI counterpart timing has to be taken into account.

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²⁾ The capacitive load on the LVDS pins is differential, the capacitive load on the CMOS pins is single ended.

³⁾ The PLL jitter is not included. It should be considered additionally, corresponding to the used baudrate. The duty cycle can be adjusted using the bit fields ECONz.A, B and C with the finest granularity of T_{MAX} = 1 / f_{MAX} .

⁴⁾ Positive deviation lenghtens the high time and shortens the low time of a clock period. Negative deviation does the opposite.

⁵⁾ For compensation of the average on-chip delay the QSPI module provides the bit fields ECONz.A, B and C.



Table 3-60 Master Mode MP+ss/MPRss output pads

Parameter	Symbol		Value	Unit	Note / Test Condition	
		Min.	Тур.	Max.		
SCLKO clock period 1)	t ₅₀ CC	20	-	-	ns	C _L =25pF
Deviation from the ideal duty cycle ^{2) 3)}	t ₅₀₀ CC	-3	-	3	ns	0 < C _L < 50pF
MTSR delay from SCLKO shifting edge	t ₅₁ CC	-7	-	6	ns	C _L =25pF
SLSOn deviation from the ideal programmed position	t ₅₁₀ CC	-7	-	6	ns	C _L =25pF
MRST setup to SCLK latching edge ⁴⁾	<i>t</i> ₅₂ SR	27 ⁴⁾⁵⁾	-	-	ns	C _L =25pF
MRST hold from SCLK latching edge	<i>t</i> ₅₃ SR	-6 ⁴⁾⁵⁾	-	-	ns	C _L =25pF

¹⁾ Documented value is valid for master transmit or slave receive only. For full duplex the external SPI counterpart timing has to be taken into account.

- 2) The PLL jitter is not included. It should be considered additionally, corresponding to the used baudrate. The duty cycle can be adjusted using the bit fields ECONz.A, B and C with the finest granularity of T_{MAX} = 1 / f_{MAX} .
- 3) Positive deviation lenghtens the high time and shortens the low time of a clock period. Negative deviation does the opposite.
- 4) For compensation of the average on-chip delay the QSPI module provides the bit fields ECONz.A, B and C.
- 5) The setup and hold times are valid for both settings of the input pads thresholds: TTL and AL.

Table 3-61 Master Mode MP+sm/MPRsm output pads for data and clock

Parameter	Symbol		Value	ues Unit		Note / Test Condition
		Min.	Тур.	Max.		
SCLKO clock period 1)	t ₅₀ CC	50	-	-	ns	C _L =50pF
Deviation from the ideal duty cycle ^{2) 3)}	t ₅₀₀ CC	-2	-	3+0.01 * C _L	ns	0 < C _L < 200pF
MTSR delay from SCLKO shifting edge	t ₅₁ CC	-10	-	10	ns	C _L =50pF
SLSOn deviation from the ideal	t ₅₁₀ CC	-10	-	10	ns	MP+sm; C_L =50pF
programmed position		-13	-	1	ns	MPss; C_L =50pF
		0	-	40	ns	MP+m, MPm, LPm; C_L =50pF
MRST setup to SCLK latching edge ⁴⁾	<i>t</i> ₅₂ SR	50 ⁴⁾⁵⁾	-	-	ns	C _L =50pF
MRST hold from SCLK latching edge	<i>t</i> ₅₃ SR	-10 ⁴⁾⁵⁾	-	-	ns	C _L =50pF

¹⁾ Documented value is valid for master transmit or slave receive only. For full duplex the external SPI counterpart timing has to be taken into account.

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²⁾ The PLL jitter is not included. It should be considered additionally, corresponding to the used baudrate. The duty cycle can be adjusted using the bit fields ECONz.A, B and C with the finest granularity of T_{MAX} = 1 / f_{MAX} .

Positive deviation lenghtens the high time and shortens the low time of a clock period. Negative deviation does the opposite.



- 4) For compensation of the average on-chip delay the QSPI module provides the bit fields ECONz.A, B and C.
- 5) The setup and hold times are valid for both settings of the input pads thresholds: TTL and AL.

Table 3-62 Master Mode timing MPsm output pads

Parameter	Symbol Values					Note / Test Condition
		Min.	Тур.	Max.		
SCLKO clock period 1)	t ₅₀ CC	100	-	-	ns	C _L =50pF
Deviation from the ideal duty cycle ^{2) 3)}	t ₅₀₀ CC	-3	-	4+0.04 * C _L	ns	0 < C _L < 200pF
MTSR delay from SCLKO shifting edge	t ₅₁ CC	-11	-	10	ns	C _L =50pF
SLSOn deviation from the ideal programmed position	t ₅₁₀ CC	-11	-	10	ns	C _L =50pF
MRST setup to SCLK latching edge ⁴⁾	<i>t</i> ₅₂ SR	60 4)5)	-	-	ns	C _L =50pF
MRST hold from SCLK latching edge	<i>t</i> ₅₃ SR	-10 ⁴⁾⁵⁾	-	-	ns	C _L =50pF

- 1) Documented value is valid for master transmit or slave receive only. For full duplex the external SPI counterpart timing has to be taken into account.
- 2) The PLL jitter is not included. It should be considered additionally, corresponding to the used baudrate. The duty cycle can be adjusted using the bit fields ECONz.A, B and C with the finest granularity of T_{MAX} = 1 / f_{MAX} .
- 3) Positive deviation lenghtens the high time and shortens the low time of a clock period. Negative deviation does the opposite.
- 4) For compensation of the average on-chip delay the QSPI module provides the bit fields ECONz.A, B and C.
- 5) The setup and hold times are valid for both settings of the input pads thresholds: TTL and AL.

Table 3-63 Master Mode timing MPRm/MP+m/MPm/LPm output pads

Parameter	Symbol Values					Note / Test Condition
		Min.	Тур.	Max.		
SCLKO clock period 1)	t ₅₀ CC	200	-	-	ns	C _L =50pF
Deviation from the ideal duty cycle ^{2) 3)}	t ₅₀₀ CC	-10	-	10+0.04 * C _L	ns	0 < C _L < 200pF
MTSR delay from SCLKO shifting edge	t ₅₁ CC	-15	-	19	ns	C _L =50pF
SLSOn deviation from the ideal programmed position	t ₅₁₀ CC	-20	-	20	ns	C _L =50pF
MRST setup to SCLK latching edge ⁴⁾	t ₅₂ SR	70 4)5)	-	-	ns	C _L =50pF
MRST hold from SCLK latching edge	<i>t</i> ₅₃ SR	-10 ⁴⁾⁵⁾	-	-	ns	C _L =50pF

¹⁾ Documented value is valid for master transmit or slave receive only. For full duplex the external SPI counterpart timing has to be taken into account.

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²⁾ The PLL jitter is not included. It should be considered additionally, corresponding to the used baudrate. The duty cycle can be adjusted using the bit fields ECONz.A, B and C with the finest granularity of T_{MAX} = 1 / f_{MAX} .

³⁾ Positive deviation lenghtens the high time and shortens the low time of a clock period. Negative deviation does the opposite.



- 4) For compensation of the average on-chip delay the QSPI module provides the bit fields ECONz.A, B and C.
- 5) The setup and hold times are valid for both settings of the input pads thresholds: TTL and AL.

Table 3-64 Master Mode Weak output pads

Parameter	Symbol Values					Note / Test Condition
		Min.	Тур.	Max.		
SCLKO clock period 1)	t ₅₀ CC	1000	-	-	ns	C _L =50pF
Deviation from the ideal duty cycle ^{2) 3)}	t ₅₀₀ CC	-30	-	30+0.15 * C _L	ns	0 < C _L < 200pF
MTSR delay from SCLKO shifting edge	<i>t</i> ₅₁ CC	-65	-	65	ns	C _L =50pF
SLSOn deviation from the ideal programmed position	t ₅₁₀ CC	-70	-	65	ns	C _L =50pF
MRST setup to SCLK latching edge ⁴⁾	<i>t</i> ₅₂ SR	300 4)5)	-	-	ns	C _L =50pF
MRST hold from SCLK latching edge	<i>t</i> ₅₃ SR	-40 ⁴⁾⁵⁾	-	-	ns	C _L =50pF

- 1) Documented value is valid for master transmit or slave receive only. For full duplex the external SPI counterpart timing has to be taken into account.
- 2) The PLL jitter is not included. It should be considered additionally, corresponding to the used baudrate. The duty cycle can be adjusted using the bit fields ECONz.A, B and C with the finest granularity of T_{MAX} = 1 / f_{MAX} .
- 3) Positive deviation lenghtens the high time and shortens the low time of a clock period. Negative deviation does the opposite.
- 4) For compensation of the average on-chip delay the QSPI module provides the bit fields ECONz.A, B and C.
- 5) The setup and hold times are valid for both settings of the input pads thresholds: TTL and AL.

Table 3-65 Slave mode timing

Parameter	Symbol		Values			Note / Test Condition
		Min.	Тур.	Max.		
SCLK clock period	t ₅₄ SR	$4 \times T_{\text{MAX}}$	-	-	ns	
SCLK duty cycle	t _{55/t54} SR	40	-	60	%	
MTSR setup to SCLK latching	t ₅₆ SR	4 ¹⁾	-	-	ns	Hystheresis Inactive
edge		5 ¹⁾	-	-	ns	Input Level AL
		5 ¹⁾	-	-	ns	Input Level TTL
MTSR hold from SCLK latching	t ₅₇ SR	3 ¹⁾	-	-	ns	Hystheresis Inactive
edge		6 ¹⁾	-	-	ns	Input Level AL
		9 ¹⁾	-	-	ns	Input Level TTL
SLSI setup to first SCLK shift	t ₅₈ SR	5 ¹⁾	-	-	ns	Hystheresis Inactive
edge		4 1)	-	-	ns	Input Level AL
		8 1)	-	-	ns	Input Level TTL
		6	-	-	ns	Only for pin 15.1, AL

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Table 3-65 Slave mode timing (cont'd)

Parameter	Symbol		Value	s	Unit	Note / Test Condition
		Min.	Тур.	Max.		
SLSI hold from last SCLK	t ₅₉ SR	3 1)	-	-	ns	Hystheresis Inactive
latching edge		4 1)	-	-	ns	Input Level AL
		8 ¹⁾	-	-	ns	Input Level TTL
MRST delay from SCLK shift edge	t ₆₀ CC	10	-	70	ns	MP+m/MPRm; C_L =50pF
		10	-	50	ns	MP+sm/MPRsm; C_L =50pF
		5	-	30	ns	MP+ss/MPRss; C_L =25pF
		40	-	300	ns	MP+w/MPRw; C_L =50pF
		10	-	70	ns	MPm/LPm; C_L =50pF
		10	-	55	ns	MPsm; C_L =50pF
		5	-	30	ns	MPss; C_L =25pF
		40	-	300	ns	MPw/LPw; C_L =50pF
SLSI to valid data on MRST	t ₆₁ SR	-	-	5	ns	

¹⁾ Except pin P15.1.

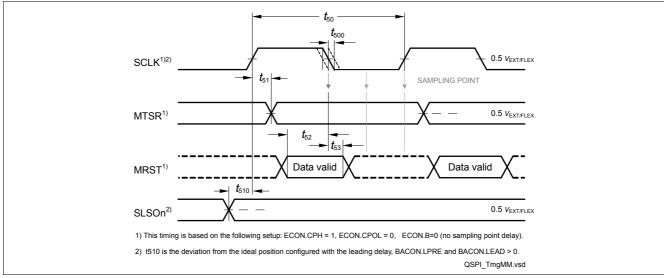


Figure 3-17 Master Mode Timing

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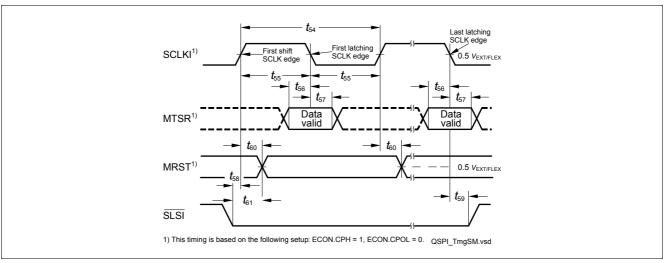


Figure 3-18 Slave Mode Timing

3.26 QSPI Timings, Master and Slave Mode

This section defines the timings for the QSPI in the TC270 / TC275 / TC277, for 3.3V pad power supply. It is assumed that SCLKO, MTSR, and SLSO pads have the same pad settings:

- LVDSM output pads, LVDSH input pad, master mode, C₁ =25pF
- · Medium Performance Plus Pads (MP+):
 - strong sharp edge (MP+ss), C₁=25pF
 - strong medium edge (MP+sm), C_I =50pF
 - medium edge (MP+m), C_L =50pF
 - weak edge (MP+w), C_L =50pF
- Medium Performance Pads (MP):
 - strong sharp edge (MPss), C₁ =25pF
 - strong medium edge (MPsm), C_1 =50pF
- · Medium and Low Performance Pads (MP/LP), the identical output strength settings:
 - medium edge (LP/MPm), C_1 =50pF
 - weak edge (MPw), C_1 =50pF

Note: Pad asymmetry is already included in the following timings.

Table 3-66 Master Mode Timing, LVDSM output pads for data and clock

Parameter	Symbol		Value	s	Unit	Note / Test Condition
		Min.	Тур.	Max.		
SCLKO clock period 1)	t ₅₀ CC	20	-	-	ns	C _L =25pF
Deviation from the ideal duty cycle ^{2) 3)}	t ₅₀₀ CC	-2	-	2	ns	C _L =25pF
MTSR delay from SCLKO shifting edge	t ₅₁ CC	-5	-	5	ns	C _L =25pF



Table 3-66 Master Mode Timing, LVDSM output pads for data and clock (cont'd)

Parameter	Symbol		Value	s	Unit	Note / Test Condition
		Min.	Тур.	Max.		
SLSOn deviation from the ideal	t ₅₁₀ CC	-2	-	55	ns	$C_{\rm L}$ =25pF; MPsm
programmed position		-9	-	12	ns	C _L =25pF; MPss
		-7	-	12	ns	MP+ss; C_L =25pF
		-2	-	26	ns	MP+sm; C_L =25pF
MRST setup to SCLK latching edge ⁴⁾	<i>t</i> ₅₂ SR	20	-	-	ns	C _L =25pF; LVDSM 5V output and LVDSH 3.3V input
MRST hold from SCLK latching edge	<i>t</i> ₅₃ SR	-6	-	-	ns	C _L =25pF; LVDSM 5V output and LVDSH 3.3V input

¹⁾ Documented value is valid for master transmit or slave receive only. For full duplex the external SPI counterpart timing has to be taken into account.

Table 3-67 Master Mode MP+ss/MPRss output pads

Parameter	Symbol Values				Unit	Note / Test Condition
		Min.	Тур.	Max.		
SCLKO clock period 1)	t ₅₀ CC	40	-	-	ns	C _L =25pF
Deviation from the ideal duty cycle ^{2) 3)}	t ₅₀₀ CC	-5	-	5	ns	0 < C _L < 50pF
MTSR delay from SCLKO shifting edge	t ₅₁ CC	-12	-	12	ns	C _L =25pF
SLSOn deviation from the ideal programmed position	t ₅₁₀ CC	-12	-	12	ns	C _L =25pF
MRST setup to SCLK latching edge ⁴⁾	<i>t</i> ₅₂ SR	50 ⁴⁾⁵⁾	-	-	ns	C _L =25pF
MRST hold from SCLK latching edge	<i>t</i> ₅₃ SR	-6 ⁴⁾⁵⁾	-	-	ns	C _L =25pF

¹⁾ Documented value is valid for master transmit or slave receive only. For full duplex the external SPI counterpart timing has to be taken into account.

- 4) For compensation of the average on-chip delay the QSPI module provides the bit fields ECONz.A, B and C.
- 5) The setup and hold times are valid for both settings of the input pads thresholds: TTL and AL.

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²⁾ The PLL jitter is not included. It should be considered additionally, corresponding to the used baudrate. The duty cycle can be adjusted using the bit fields ECONz.A, B and C with the finest granularity of T_{MAX} = 1 / f_{MAX} .

³⁾ Positive deviation lenghtens the high time and shortens the low time of a clock period. Negative deviation does the opposite.

⁴⁾ For compensation of the average on-chip delay the QSPI module provides the bit fields ECONz.A, B and C.

²⁾ The PLL jitter is not included. It should be considered additionally, corresponding to the used baudrate. The duty cycle can be adjusted using the bit fields ECONz.A, B and C with the finest granularity of T_{MAX} = 1 / f_{MAX} .

³⁾ Positive deviation lenghtens the high time and shortens the low time of a clock period. Negative deviation does the opposite.



Table 3-68 Master Mode MP+sm/MPRsm output pads for data and clock

Parameter	Symbol		Value	s	Unit	Note / Test Condition
		Min.	Тур.	Max.		
SCLKO clock period 1)	t ₅₀ CC	100	-	-	ns	C _L =50pF
Deviation from the ideal duty cycle ^{2) 3)}	t ₅₀₀ CC	-3	-	7	ns	0 < C _L < 200pF
MTSR delay from SCLKO shifting edge	t ₅₁ CC	-17	-	17	ns	C _L =50pF
SLSOn deviation from the ideal	t ₅₁₀ CC	-17	-	17	ns	MP+sm; C_L =50pF
programmed position		-22	-	2	ns	MPss; C_L =50pF
		0	-	70	ns	MP+m; MPm; LPm; C_L =50pF
MRST setup to SCLK latching edge ⁴⁾	t ₅₂ SR	85 4)5)	-	-	ns	C _L =50pF
MRST hold from SCLK latching edge	t ₅₃ SR	-10 ⁴⁾⁵⁾	-	-	ns	C _L =50pF

¹⁾ Documented value is valid for master transmit or slave receive only. For full duplex the external SPI counterpart timing has to be taken into account.

- 2) The PLL jitter is not included. It should be considered additionally, corresponding to the used baudrate. The duty cycle can be adjusted using the bit fields ECONz.A, B and C with the finest granularity of T_{MAX} = 1 / f_{MAX} .
- 3) Positive deviation lenghtens the high time and shortens the low time of a clock period. Negative deviation does the opposite.
- 4) For compensation of the average on-chip delay the QSPI module provides the bit fields ECONz.A, B and C.
- 5) The setup and hold times are valid for both settings of the input pads thresholds: TTL and AL.

Table 3-69 Master Mode timing MPss output pads

Parameter	Symbol	Symbol Values				Note / Test Condition
		Min.	Тур.	Max.		
SCLKO clock period 1)	t ₅₀ CC	40	-	-	ns	C _L =25pF
Deviation from the ideal duty cycle ^{2) 3)}	t ₅₀₀ CC	-5	-	7+0.07 * C _L	ns	C _L =25pF
MTSR delay from SCLKO shifting edge	t ₅₁ CC	-10	-	10	ns	C _L =25pF
SLSOn deviation from the ideal programmed position	t ₅₁₀ CC	-10	-	10	ns	C _L =25pF
MRST setup to SCLK latching edge ⁴⁾	<i>t</i> ₅₂ SR	50 ⁴⁾⁵⁾	-	-	ns	C _L =25pF
MRST hold from SCLK latching edge	<i>t</i> ₅₃ SR	-6 ⁴⁾⁵⁾	-	-	ns	C _L =25pF

¹⁾ Documented value is valid for master transmit or slave receive only. For full duplex the external SPI counterpart timing has to be taken into account.

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²⁾ The PLL jitter is not included. It should be considered additionally, corresponding to the used baudrate. The duty cycle can be adjusted using the bit fields ECONz.A, B and C with the finest granularity of T_{MAX} = 1 / f_{MAX} .

Positive deviation lenghtens the high time and shortens the low time of a clock period. Negative deviation does the opposite.



- 4) For compensation of the average on-chip delay the QSPI module provides the bit fields ECONz.A, B and C.
- 5) The setup and hold times are valid for both settings of the input pads thresholds: TTL and AL.

Table 3-70 Master Mode timing MPsm output pads

Parameter	Symbol Values					Note / Test Condition
		Min.	Тур.	Max.		
SCLKO clock period 1)	t ₅₀ CC	200	-	-	ns	C _L =50pF
Deviation from the ideal duty cycle ^{2) 3)}	t ₅₀₀ CC	-5	-	9+0.06 * C _L	ns	0 < C _L < 200pF
MTSR delay from SCLKO shifting edge	t ₅₁ CC	-19	-	19	ns	C _L =50pF
SLSOn deviation from the ideal programmed position	t ₅₁₀ CC	-19	-	17	ns	C _L =50pF
MRST setup to SCLK latching edge ⁴⁾	<i>t</i> ₅₂ SR	100 4)5)	-	-	ns	C _L =50pF
MRST hold from SCLK latching edge	<i>t</i> ₅₃ SR	-13 ⁴⁾⁵⁾	-	-	ns	C _L =50pF

- 1) Documented value is valid for master transmit or slave receive only. For full duplex the external SPI counterpart timing has to be taken into account.
- 2) The PLL jitter is not included. It should be considered additionally, corresponding to the used baudrate. The duty cycle can be adjusted using the bit fields ECONz.A, B and C with the finest granularity of T_{MAX} = 1 / f_{MAX} .
- 3) Positive deviation lenghtens the high time and shortens the low time of a clock period. Negative deviation does the opposite.
- 4) For compensation of the average on-chip delay the QSPI module provides the bit fields ECONz.A, B and C.
- 5) The setup and hold times are valid for both settings of the input pads thresholds: TTL and AL.

Table 3-71 Master Mode timing MPRm/MP+m/MPm/LPm output pads

Parameter	Symbol Values					Note / Test Condition
		Min.	Тур.	Max.		
SCLKO clock period 1)	t ₅₀ CC	400	-	-	ns	C _L =50pF
Deviation from the ideal duty cycle ^{2) 3)}	t ₅₀₀ CC	-6-0.07 * C _L	-	6+0.07 * C _L	ns	0 < C _L < 200pF
MTSR delay from SCLKO shifting edge	t ₅₁ CC	-25	-	33	ns	C _L =50pF
SLSOn deviation from the ideal programmed position	t ₅₁₀ CC	-35	-	35	ns	C _L =50pF
MRST setup to SCLK latching edge ⁴⁾	<i>t</i> ₅₂ SR	120 4)5)	-	-	ns	C _L =50pF
MRST hold from SCLK latching edge	<i>t</i> ₅₃ SR	-13 ⁴⁾⁵⁾	-	-	ns	C _L =50pF

¹⁾ Documented value is valid for master transmit or slave receive only. For full duplex the external SPI counterpart timing has to be taken into account.

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²⁾ The PLL jitter is not included. It should be considered additionally, corresponding to the used baudrate. The duty cycle can be adjusted using the bit fields ECONz.A, B and C with the finest granularity of T_{MAX} = 1 / f_{MAX} .

³⁾ Positive deviation lenghtens the high time and shortens the low time of a clock period. Negative deviation does the opposite.



- 4) For compensation of the average on-chip delay the QSPI module provides the bit fields ECONz.A, B and C.
- 5) The setup and hold times are valid for both settings of the input pads thresholds: TTL and AL.

Table 3-72 Master Mode Weak output pads

Parameter	Symbol		Value	Unit	Note / Test Condition	
		Min.	Тур.	Max.		
SCLKO clock period 1)	t ₅₀ CC	2000	-	-	ns	C _L =50pF
Deviation from the ideal duty cycle ^{2) 3)}	t ₅₀₀ CC	-110	-	110	ns	0 < C _L < 200pF
MTSR delay from SCLKO shifting edge	t ₅₁ CC	-170	-	170	ns	C _L =50pF
SLSOn deviation from the ideal programmed position	t ₅₁₀ CC	-170	-	170	ns	C _L =50pF
MRST setup to SCLK latching edge ⁴⁾	<i>t</i> ₅₂ SR	510 ⁴⁾⁵⁾	-	-	ns	C _L =50pF
MRST hold from SCLK latching edge	t ₅₃ SR	-40 ⁴⁾⁵⁾	-	-	ns	C _L =50pF

- 1) Documented value is valid for master transmit or slave receive only. For full duplex the external SPI counterpart timing has to be taken into account.
- 2) The PLL jitter is not included. It should be considered additionally, corresponding to the used baudrate. The duty cycle can be adjusted using the bit fields ECONz.A, B and C with the finest granularity of T_{MAX} = 1 / f_{MAX} .
- 3) Positive deviation lenghtens the high time and shortens the low time of a clock period. Negative deviation does the opposite.
- 4) For compensation of the average on-chip delay the QSPI module provides the bit fields ECONz.A, B and C.
- 5) The setup and hold times are valid for both settings of the input pads thresholds: TTL and AL.

Table 3-73 Slave mode timing

Parameter	Symbol		Value	s	Unit	Note / Test Condition
		Min.	Тур.	Max.		
SCLK clock period	t ₅₄ SR	$4 \times T_{\text{MAX}}$	-	-	ns	
SCLK duty cycle	t _{55/t54} SR	40	-	60	%	
MTSR setup to SCLK latching	t ₅₆ SR	7 1)	-	-	ns	Hystheresis inactive
edge		9 ¹⁾	-	-	ns	Input Level AL
		7 1)	-	-	ns	Input Level TTL
MTSR hold from SCLK latching	t ₅₇ SR	5 ¹⁾	-	-	ns	Hystheresis inactive
edge		11 ¹⁾	-	-	ns	Input Level AL
		16 ¹⁾	-	-	ns	Input Level TTL
SLSI setup to first SCLK shift	t ₅₈ SR	7 1)	-	-	ns	Hystheresis inactive
edge		7 1)	-	-	ns	Input Level AL
		14 ¹⁾	-	-	ns	Input Level TTL
		11	-	-	ns	Only for pin P15.1, AL

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Table 3-73 Slave mode timing (cont'd)

Parameter	Symbol		Value	s	Unit	Note / Test Condition
		Min.	Тур.	Max.		
SLSI hold from last SCLK	t ₅₉ SR	5 ¹⁾	-	-	ns	Hystheresis inactive
latching edge		7 1)	-	-	ns	Input Level AL
		14 ¹⁾	-	-	ns	Input Level TTL
MRST delay from SCLK shift edge	t ₆₀ CC	13	-	120	ns	MP+m/MPRm; C_L =50pF
		13	-	85	ns	MP+sm/MPRsm; C_L =50pF
		6	-	50	ns	MP+ss/MPRss; C_L =25pF
		70	-	500	ns	MP+w/MPRw; C_L =50pF
		13	-	120	ns	MPm/LPm; C _L =50pF
		13	-	100	ns	MPsm; C_L =50pF
		6	-	52	ns	MPss; C_L =25pF
		70	-	500	ns	MPw/LPw; C_L =50pF
SLSI to valid data on MRST	t ₆₁ SR	-	-	9	ns	

¹⁾ Except pin P15.1

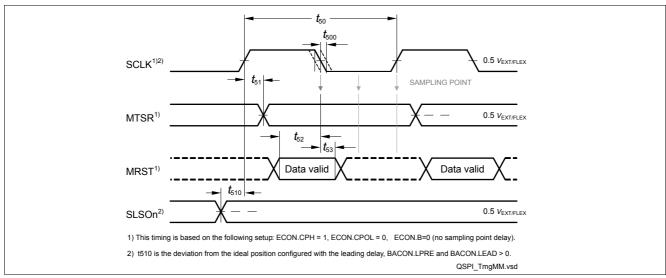


Figure 3-19 Master Mode Timing

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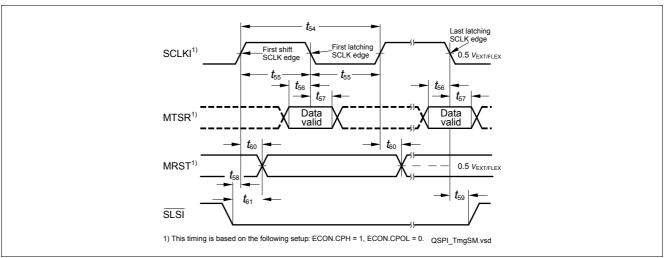


Figure 3-20 Slave Mode Timing

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3.27 MSC Timing 5 V Operation

The following section defines the timings for 5V pad power supply.

Note: Pad asymmetry is already included in the following timings.

Note: Load for LVDS pads are defined as differential loads in the following timings.

Table 3-74 LVDS clock/data (LVDS pads in LVDS mode)

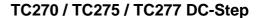
Parameter	Symbol		Value	s	Unit	Note / Test Condition
		Min.	Тур.	Max.		
FCLPx clock period 1)	t ₄₀ CC	2 * T _A ^{2) 3)}	-	-	ns	LVDSM; C_L =50pF
Deviation from ideal duty cycle 4) 5)	t ₄₀₀ CC	-1	-	1	ns	LVDSM; 0 < C _L < 50pF
SOPx output delay ⁶⁾	t ₄₄ CC	-3	-	4	ns	LVDSM; C_L =50pF; option EN01
		-4	-	4.5	ns	LVDSM; C_L =50pF; option EN01D
ENx output delay ⁶⁾	t ₄₅ CC	-4	-	5	ns	MP+ss/MPRss; option EN01; C_L =25pF
		-3	-	7	ns	MP+ss/MPRss; option EN01; C_L =50pF
		-3	-	11	ns	MP+sm/MPRsm; option EN01D; C_L =50pF
		-2	-	9	ns	MP+ss/MPRss; option EN23; C_L =25pF
		-2	-	11	ns	MP+ss/MPRss; option EN23; C_L =50pF
		-3	-	11	ns	MPss; option EN01; C_L =50pF
		-7	-	2	ns	MP+ss/MPRss; option EN01; C_L =0pF
		-5	-	3	ns	MP+sm/MPRsm; option EN01D; C_L =0pF
		-4	-	5	ns	MP+ss/MPRss; option EN23; C_L =0pF
		-7	-	4	ns	MPss; option EN01; C_L =0pF
SDI bit time	t ₄₆ CC	8 * t _{MSC}	-	-	ns	Upstream Timing
SDI rise time 7)	t ₄₈ SR	-	-	200	ns	Upstream Timing
SDI fall time 7)	t ₄₉ SR	-	-	200	ns	Upstream Timing

¹⁾ FCLP signal rise/fall times are the rise/fall times of the LVDSM pads, and the high/low times are min 1 * $T_{\rm A}$.

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²⁾ $T_{\rm A}$ depends on the clock source selected for baud rate generation in the ABRA block of the MSC.

³⁾ The capacitive load on the LVDS pins is differential, the capacitive load on the CMOS pins is single ended.





- 4) The PLL jitter is not included. It should be considered additionally, corresponding to the used baudrate. The duty cycle can be adjusted if the ABRA block is used.
- 5) Positive deviation lenghtens the high time and shortens the low time of a clock period. Negative deviation does the opposite.
- 6) From FCLP rising edge.
- 7) When using slow and asymmetrical edges, like in case of open drain upstream connection, the application must take care that the bit is long enough (the baud rate is low enough) so that under worst case conditions the three sampling points in the middle of the bit are not violated.

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Timing Options for t_{45}

The wiring shown in the **Figure 3-21** provides three useful timing options for t_{45} . depending on the signals selected with the alternate output lines (ALT1 to ALT7) in the ports:

EN01 - FCLN, SON, EN0, EN1 - t₄₅ reference timing

EN01D - FCLND, SOND, EN0, EN1 - t₄₅ window shifted to the left

EN23 - FCLN, SON, EN2, EN3 - t₄₅ window shifted to the right

The timings corresponding to EN01, EN01D, and EN23 are defined in the LVDS. In order to use the EN23 timings, the application should use the EN2 and EN3 outputs of the MSC module.

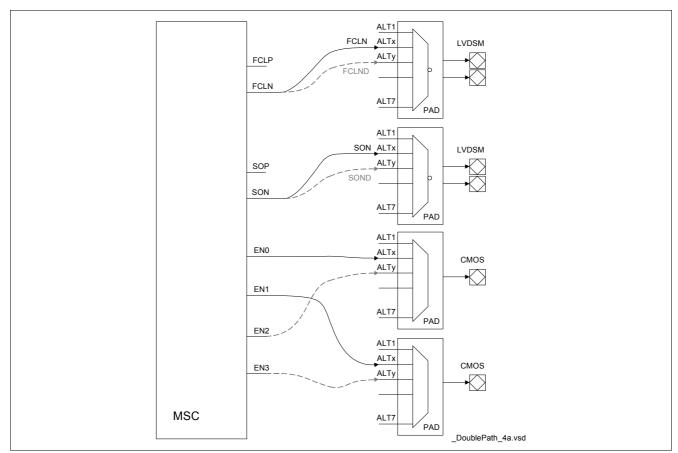


Figure 3-21 Timing Options for t_{45}

Table 3-75 MPss clock/data (LVDS pads in CMOS mode, option EN01)

Parameter	Symbol Values			Unit	Note / Test Condition	
		Min.	Тур.	Max.	=	
FCLPx clock period 1)	t ₄₀ CC	2 * T _A ^{2) 3)}	-	-	ns	MPss; C_L =50pF
Deviation from ideal duty cycle 4) 5)	t ₄₀₀ CC	-2	-	6+0.035 * C _L	ns	MPss; 0 < C _L < 100pF
SOPx output delay 6)	t ₄₄ CC	-4	-	7	ns	MPss; C_L =50pF

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Table 3-75 MPss clock/data (LVDS pads in CMOS mode, option EN01) (cont'd)

Parameter	Symbol		Values			Note / Test Condition
		Min.	Тур.	Max.		
ENx output delay ⁶⁾	t ₄₅ CC	-5	-	7	ns	MP+ss/MPRss; C_L =50pF
		-2	-	15	ns	MP+sm/MPRsm; C_L =50pF
		-4	-	10	ns	MPss; C_L =50pF
		0	-	30	ns	MPsm; C _L =50pF; except pin P13.0
		0	-	31	ns	MPsm; C_L =50pF; pin P13.0
		6	-	45	ns	MPm/MP+m/MPRm; C_L =50pF
		-11	-	2	ns	$\begin{array}{c} \text{MP+ss/MPRss;} \\ C_{\text{L}} \text{=0pF} \end{array}$
		-4	-	7	ns	$\begin{array}{c} \text{MP+sm/MPRsm;} \\ C_{\text{L}} \text{=0pF} \end{array}$
		-10	-	2	ns	MPss; C_L =0pF
		-1	-	16	ns	MPsm; C_L =0pF
		-2	-	18	ns	MP+m/MPm/MPRm; C_L =0pF
SDI bit time	t ₄₆ CC	8 * t _{MSC}	-	-	ns	Upstream Timing
SDI rise time 7)	t ₄₈ SR	-	-	200	ns	Upstream Timing
SDI fall time 7)	t ₄₉ SR	-	-	200	ns	Upstream Timing

- 1) FCLP signal rise/fall times are the rise/fall times of the LVDSM pads, and the high/low times are min 1 * TA.
- 2) $T_{\rm A}$ depends on the clock source selected for baud rate generation in the ABRA block of the MSC.
- 3) FCLP signal high and low can be minimum 1 * $T_{\rm MSC}$.
- 4) The PLL jitter is not included. It should be considered additionally, corresponding to the used baudrate. The duty cycle can be adjusted if the ABRA block is used.
- 5) Positive deviation lenghtens the high time and shortens the low time of a clock period. Negative deviation does the opposite.
- 6) From FCLP rising edge.
- 7) When using slow and asymmetrical edges, like in case of open drain upstream connection, the application must take care that the bit is long enough (the baud rate is low enough) so that under worst case conditions the three sampling points in the middle of the bit are not violated.

Table 3-76 MP+sm/MPRsm clock/data

Parameter	Symbol	Values			Unit	Note / Test Condition
		Min.	Тур.	Max.		
FCLPx clock period 1)	t ₄₀ CC	2 * T _A	-	-	ns	$\begin{array}{c} \text{MP+sm/MPRsm;} \\ C_{\text{L}} = 50 \text{pF} \end{array}$
Deviation from ideal duty cycle 2) 3)	t ₄₀₀ CC	-2	-	3+0.01 * C _L	ns	$\begin{array}{l} \text{MP+sm/MPRsm; 0 <} \\ C_{\text{L}} < \text{200pF} \end{array}$
SOPx output delay 4)	t ₄₄ CC	-5	-	7	ns	MP+sm; C_L =50pF

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Table 3-76 MP+sm/MPRsm clock/data (cont'd)

Parameter	Symbol		Value	s	Unit	Note / Test Condition
		Min.	Тур.	Max.		
ENx output delay 4)	t ₄₅ CC	-13	-	2 ⁵⁾	ns	MPss; C_L =50pF
		-5	-	11	ns	MP+sm/MPRsm; C_L =50pF
		1	-	24	ns	MPsm; C_L =50pF
		4	-	37	ns	MP+m/MPm/MPRm; C_L =50pF
		-19	-	-1	ns	MPss; C _L =0pF
		-13	-	2	ns	MP+sm; C_L =0pF
		-5	-	8	ns	MPsm; C_L =0pF
		-5	-	10	ns	$\begin{array}{c} \text{MPm/MP+m/MPRm;} \\ C_{\text{L}} \text{=0pF} \end{array}$

- 1) FCLP signal rise/fall times are the rise/fall times of the LVDSM pads, and the high/low times are min 1 * $T_{\rm A}$.
- 2) The PLL jitter is not included. It should be considered additionally, corresponding to the used baudrate. The duty cycle can be adjusted if the ABRA block is used.
- 3) Positive deviation lenghtens the high time and shortens the low time of a clock period. Negative deviation does the opposite.
- 4) From FCLP rising edge.
- 5) If EN1 is configured to P13.0 the max limt is increased by 0.5ns to 2.5ns.

Table 3-77 MPm/MP+m/MPRm clock/data

Parameter	Symbol	Values			Unit	Note / Test Condition
		Min.	Тур.	Max.		
FCLPx clock period 1)	t ₄₀ CC	2 * T _A	-	-	ns	MPm/MP+m/MPRm; C_L =50pF
Deviation from ideal duty cycle 2) 3)	t ₄₀₀ CC	-8	-	15+0.04 * C _L	ns	MPm/MP+m; $0 < C_{\rm L} < 200 {\rm pF}$
SOPx output delay 4)	t ₄₄ CC	-11	-	9	ns	MPm/MP+m; C_L =50pF
ENx output delay 4)	t ₄₅ CC	-15	-	11	ns	MPm/MP+m/MPRm; $C_{\rm L}$ =50pF
		-33	-	-4	ns	MPm/MP+m/MPRm; $C_{\rm L}$ =0pF

¹⁾ FCLP signal rise/fall times are the rise/fall times of the LVDSM pads, and the high/low times are min 1 * $T_{\rm A}$.

- 3) Positive deviation lenghtens the high time and shortens the low time of a clock period. Negative deviation does the opposite.
- 4) From FCLP rising edge.

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²⁾ The PLL jitter is not included. It should be considered additionally, corresponding to the used baudrate. The duty cycle can be adjusted if the ABRA block is used.



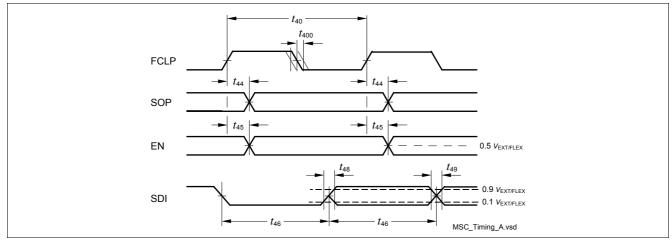


Figure 3-22 MSC Interface Timing

Note: The SOP data signal is sampled with the falling edge of FCLP in the target device.

3.28 MSC Timing 3.3 V Operation

The following section defines the timings for 3.3V pad power supply.

Note: Pad asymmetry is already included in the following timings.

Note: Load for LVDS pads are defined as differential loads in the following timings.

Mapping A, Combo Pads in LVDS Mode or CMOS Mode

The timing applies for the LVDS pads in LVDS operating mode:

- · The LVDSM output pads for clock and data signals set in LVDS mode
- The CMOS MP pads for enable signals, with strong driver sharp edge (MPss) or strong driver medium edge (MPsm).

Table 3-78 LVDS clock/data (LVDS pads in LVDS mode)

Parameter	Symbol		Values			Note / Test Condition
		Min.	Тур.	Max.		
FCLPx clock period 1)	t ₄₀ CC	2 * T _A ^{2) 3)}	-	-	ns	LVDSM; C_L =50pF
Deviation from ideal duty cycle 4) 5)	t ₄₀₀ CC	-2	-	2	ns	LVDSM; 0 < C _L < 50pF
SOPx output delay ⁶⁾	t ₄₄ CC	-5	-	5	ns	LVDSM; C _L =50pF; option EN01
		-7	-	7	ns	LVDSM; C_L =50pF; option EN01D

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Table 3-78 LVDS clock/data (LVDS pads in LVDS mode) (cont'd)

Parameter	Symbol		Value	s	Unit	Note / Test Condition
		Min.	Тур.	Max.		
ENx output delay ⁶⁾	t ₄₅ CC	-7	-	10	ns	MP+ss/MPRss; option EN01; C_L =25pF
		-5	-	13	ns	MP+ss/MPRss; option EN01; C_L =50pF
		-5	-	26	ns	MP+sm/MPRsm; option EN01D; C_L =50pF
		-4	-	16	ns	MP+ss/MPRss; option EN23; C_L =25pF
		-4	-	17	ns	MP+ss/MPRss; option EN23; $C_{\rm L}$ =50pF
		-5	-	19	ns	MPss; option EN01; C_L =50pF
		-12	-	4	ns	MP+ss/MPRss; option EN01; C_L =0pF
		-9	-	11	ns	MP+sm/MPRsm; option EN01D; C_L =0pF
		-7	-	9	ns	MP+ss/MPRss; option EN23; C_L =0pF
		-12	-	7	ns	MPss; option EN01; C_L =0pF
SDI bit time	t ₄₆ CC	8 * t _{MSC}	-	-	ns	Upstream Timing
SDI rise time 7)	t ₄₈ SR	-	-	200	ns	Upstream Timing
SDI fall time 7)	t ₄₉ SR	-	-	200	ns	Upstream Timing

- 1) FCLP signal rise/fall times are the rise/fall times of the LVDSM pads, and the high/low times are min 1 * T_A .
- 2) $T_{\rm Amin}$ = $T_{\rm MAX}$. When $T_{\rm MAX}$ = 100 MHz, $t_{\rm 40}$ = 20 ns
- 3) The capacitive load on the LVDS pins is differential, the capacitive load on the CMOS pins is single ended.
- 4) The PLL jitter is not included. It should be considered additionally, corresponding to the used baudrate. The duty cycle can be adjusted if the ABRA block is used.
- 5) Positive deviation lenghtens the high time and shortens the low time of a clock period. Negative deviation does the opposite.
- 6) From FCLP rising edge.
- 7) When using slow and asymmetrical edges, like in case of open drain upstream connection, the application must take care that the bit is long enough (the baud rate is low enough) so that under worst case conditions the three sampling points in the middle of the bit are not violated.

Table 3-79 MPss clock/data (LVDS pads in CMOS mode, option EN01)

Parameter	Symbol	Values			Unit	Note / Test Condition
		Min.	Тур.	Max.		
FCLPx clock period 1)	t ₄₀ CC	2 * T _A ^{2) 3)}	-	-	ns	MPss; C_L =50pF
Deviation from ideal duty cycle 4) 5)	t ₄₀₀ CC	-5	-	7+0.07 * C _L	ns	MPss; 0 < C _L < 100pF



Table 3-79 MPss clock/data (LVDS pads in CMOS mode, option EN01) (cont'd)

Parameter	Symbol		Values			Note / Test Condition
		Min.	Тур.	Max.		
SOPx output delay 6)	t ₄₄ CC	-7	-	12	ns	MPss; C_L =50pF
ENx output delay 6)	t ₄₅ CC	-9	-	12	ns	MP+ss/MPRss; C_L =50pF
		-4	-	26	ns	MP+sm/MPRsm; C_L =50pF
		-7	-	17	ns	MPss; C_L =50pF
		0	-	54	ns	MPsm; C _L =50pF; except pin P13.0
		0	-	58	ns	MPsm; C_L =50pF; pin P13.0
		4	-	77	ns	MPm/MP+m/MPRm; C_L =50pF
		-19	-	4	ns	$\begin{array}{c} \text{MP+ss/MPRss;} \\ C_{\text{L}} \text{=0pF} \end{array}$
		-7	-	12	ns	$\begin{array}{c} \text{MP+sm/MPRsm;} \\ C_{\text{L}} \text{=0pF} \end{array}$
		-17	-	4	ns	MPss; C_L =0pF
		-2	-	28	ns	MPsm; C_L =0pF
		-4	-	31	ns	MP+m/MPm/MPRm; C_L =0pF
SDI bit time	t ₄₆ CC	8 * t _{MSC}	-	-	ns	Upstream Timing
SDI rise time 7)	t ₄₈ SR	-	-	200	ns	Upstream Timing
SDI fall time 7)	t ₄₉ SR	-	-	200	ns	Upstream Timing

¹⁾ FCLP signal rise/fall times are the rise/fall times of the LVDSM pads, and the high/low times are min 1 * TA.

Mapping B, CMOS MP Pads

This timing applies for the dedicated CMOS pads, pin Mapping B:

- MP strong sharp (MPss) output pads for the clock and the data signals
- · MP strong sharp or strong medium (MPss or MPsm) output pads for enable signals

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²⁾ $T_{\text{Amin}} = T_{\text{MAX}}$. When $T_{\text{MAX}} = 100 \text{ MHz}$, $t_{40} = 20 \text{ ns}$

³⁾ FCLP signal high and low can be minimum 1 * $T_{\rm MSC}$.

⁴⁾ The PLL jitter is not included. It should be considered additionally, corresponding to the used baudrate. The duty cycle can be adjusted if the ABRA block is used.

⁵⁾ Positive deviation lenghtens the high time and shortens the low time of a clock period. Negative deviation does the opposite.

⁶⁾ From FCLP rising edge.

⁷⁾ When using slow and asymmetrical edges, like in case of open drain upstream connection, the application must take care that the bit is long enough (the baud rate is low enough) so that under worst case conditions the three sampling points in the middle of the bit are not violated.



Table 3-80 MP+sm/MPRsm clock/data

Parameter	Symbol		Value	s	Unit	Note / Test Condition
		Min.	Тур.	Max.		
FCLPx clock period 1)	t ₄₀ CC	2 * T _A	-	-	ns	$\begin{array}{c} \text{MP+sm/MPRsm;} \\ C_{\text{L}} = 50 \text{pF} \end{array}$
Deviation from ideal duty cycle 2) 3)	t ₄₀₀ CC	-3	-	7	ns	MP+sm/MPRsm; 0 < $C_{\rm L}$ < 200pF
SOPx output delay 4)	t ₄₄ CC	-9	-	12	ns	MP+sm; C_L =50pF
ENx output delay 4)	t ₄₅ CC	-20	-	4	ns	MPss; C_L =50pF
		-9	-	19	ns	$\begin{array}{c} \text{MP+sm/MPRsm;} \\ C_{\text{L}} = 50 \text{pF} \end{array}$
		0	-	44	ns	MPsm; C_L =50pF
		0	-	63	ns	MP+m/MPm/MPRm; $C_{\rm L}$ =50pF
		-33	-	0	ns	MPss; C_L =0pF
		-23	-	4	ns	$\begin{array}{c} \text{MP+sm/MPRsm;} \\ C_{\text{L}}\text{=0pF} \end{array}$
		-9	-	14	ns	MPsm; C_L =0pF
		-9	-	17	ns	$\begin{array}{c} \text{MPm/MP+m/MPRm;} \\ C_{\text{L}} \text{=0pF} \end{array}$

¹⁾ FCLP signal rise/fall times are the rise/fall times of the LVDSM pads, and the high/low times are min 1 * $T_{\rm A}$.

Table 3-81 MPm/MP+m/MPRm clock/data

Parameter	Symbol	Symbol Values				Note / Test Condition
		Min.	Тур.	Max.		
FCLPx clock period 1)	t ₄₀ CC	2 * T _A	-	-	ns	MPm/MP+m/MPRm; C_L =50pF
Deviation from ideal duty cycle 2) 3)	t ₄₀₀ CC	-6-0.07 * C _L	-	6+0.07 * C _L	ns	MPm/MP+m/MPRm; 0 $< C_L < 200$ pF
SOPx output delay 4)	t ₄₄ CC	-19	-	17	ns	MPm/MP+m; C_L =50pF
ENx output delay 4)	t ₄₅ CC	-19	-	20	ns	MPm/MP+m/MPRm; C_L =50pF
		-57	-	0	ns	$ \begin{array}{c} \text{MPm/MP+m/MPRm;} \\ C_{\text{L}} \text{=0pF} \end{array} $

¹⁾ FCLP signal rise/fall times are the rise/fall times of the LVDSM pads, and the high/low times are min 1 * $T_{\rm A}$.

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²⁾ The PLL jitter is not included. It should be considered additionally, corresponding to the used baudrate. The duty cycle can be adjusted if the ABRA block is used.

³⁾ Positive deviation lenghtens the high time and shortens the low time of a clock period. Negative deviation does the opposite.

⁴⁾ From FCLP rising edge.

²⁾ The PLL jitter is not included. It should be considered additionally, corresponding to the used baudrate. The duty cycle can be adjusted if the ABRA block is used.

³⁾ Positive deviation lenghtens the high time and shortens the low time of a clock period. Negative deviation does the opposite.



4) From FCLP rising edge.

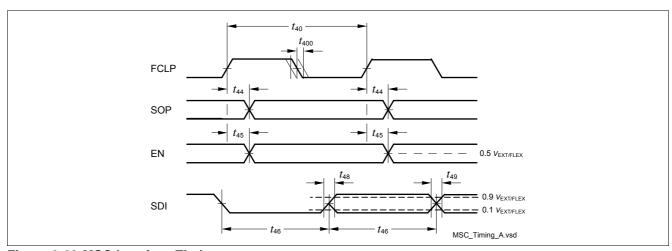


Figure 3-23 MSC Interface Timing

Note: The SOP data signal is sampled with the falling edge of FCLP in the target device.



3.29 Ethernet Interface (ETH) Characteristics

3.29.1 ETH Measurement Reference Points

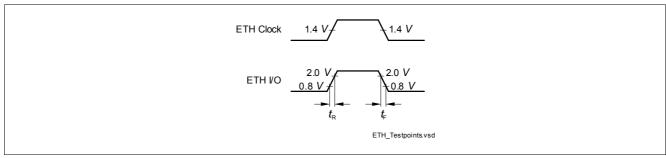


Figure 3-24 ETH Measurement Reference Points



3.29.2 ETH Management Signal Parameters (ETH_MDC, ETH_MDIO)

Table 3-82 ETH Management Signal Parameters

Parameter	Symbol		Value	Unit	Note / Test Condition	
		Min.	Тур.	Max.		
ETH_MDC period	t ₁ CC	400	-	-	ns	C _L =25pF
ETH_MDC high time	t ₂ CC	160	-	-	ns	C _L =25pF
ETH_MDC low time	t ₃ CC	160	-	-	ns	C _L =25pF
ETH_MDIO setup time (output)	t ₄ CC	10	-	-	ns	C _L =25pF
ETH_MDIO hold time (output)	t ₅ CC	10	-	-	ns	C _L =25pF
ETH_MDIO data valid (input)	t ₆ SR	0	-	300	ns	C _L =25pF

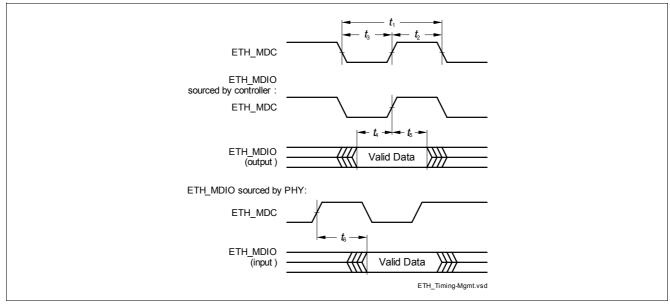


Figure 3-25 ETH Management Signal Timing

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3.29.3 ETH MII Parameters

In the following, the parameters of the MII (Media Independent Interface) are described.

Table 3-83 ETH MII Signal Timing Parameters

Parameter	Symbol		Value	s	Unit	Note / Test Condition
		Min.	Тур.	Max.		
Clock period	t ₇ SR	40	-	-	ns	$C_{\rm L}$ =25pF; baudrate=100Mbps
		400	-	-	ns	C _L =25pF; baudrate=10Mbps
Clock high time	t ₈ SR	14	-	26	ns	C_L =25pF; baudrate=100Mbps
		140 ¹⁾	-	260 ²⁾	ns	C _L =25pF; baudrate=10Mbps
Clock low time	t ₉ SR	14	-	26	ns	C _L =25pF; baudrate=100Mbps
		140 ¹⁾	-	260 ²⁾	ns	C_L =25pF; baudrate=10Mbps
Input setup time	t ₁₀ SR	10	-	-	ns	C _L =25pF
Input hold time	t ₁₁ SR	10	-	-	ns	C _L =25pF
Output valid time	t ₁₂ CC	0	-	25	ns	C _L =25pF

- 1) Defined by 35% of clock period.
- 2) Defined by 65% of clock period.

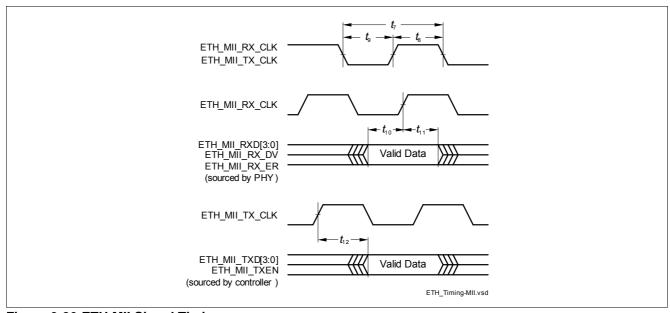


Figure 3-26 ETH MII Signal Timing

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3.29.4 ETH RMII Parameters

In the following, the parameters of the RMII (Reduced Media Independent Interface) are described.

Table 3-84 ETH RMII Signal Timing Parameters

Parameter	Symbol Values				Unit	Note / Test Condition
		Min.	Тур.	Max.		
ETH_RMII_REF_CL clock period	t ₁₃ CC	20	-	-	ns	C _L =25pF; 50ppm
ETH_RMII_REF_CL clock high time	t ₁₄ CC	7 1)	-	13 ²⁾	ns	C _L =25pF
ETH_RMII_REF_CL clock low time	t ₁₅ CC	7 1)	-	13 ²⁾	ns	C _L =25pF
ETHTXEN, ETHTXD[1:0], ETHRXD[1:0], ETHCRSDV, ETHRXER; setup time	t ₁₆ CC	4	-	-	ns	C _L =25pF
ETHTXEN, ETHTXD[1:0], ETHRXD[1:0], ETHCRSDV, ETHRXER; hold time	t ₁₇ CC	2	-	-	ns	C _L =25pF

- 1) Defined by 35% of clock period.
- 2) Defined by 65% of clock period.

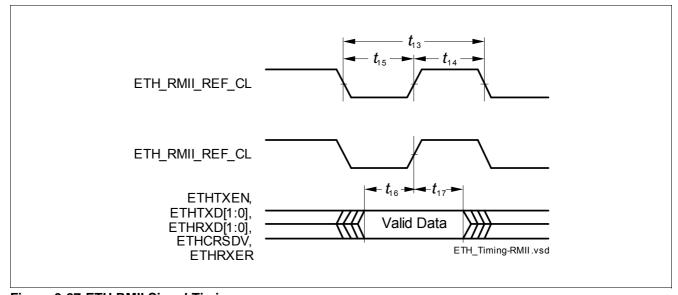


Figure 3-27 ETH RMII Signal Timing

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Electrical SpecificationE-Ray Parameters

3.30 E-Ray Parameters

The timings of this section are valid for the strong driver and either sharp edge settings of the output drivers with $C_{\rm L}$ = 25 pF. For the inputs the hysteresis has to be configured to inactive.

Table 3-85 Transmit Parameters

Parameter	Symbol		Value	s	Unit	Note / Test Condition
		Min.	Тур.	Max.		
Rise time of TxEN	t _{dCCTxENRise2} 5 CC	-	-	9	ns	C _L =25pF
Fall time of TxEN	$t_{ m dCCTxENFall25}$	-	-	9	ns	C _L =25pF
Sum of rise and fall time	$t_{ m dCCTxRise25+}$ dCCTxFall25	-	-	9	ns	20% - 80%; <i>C</i> _L =25pF
Sum of delay between TP1_FF and TP1_CC and delays derived from TP1_FFi, rising edge of TxEN	t _{dCCTxEN01}	-	-	25	ns	
Sum of delay between TP1_FF and TP1_CC and delays derived from TP1_FFi, falling edge of TxEN	t _{dCCTxEN10}	-	-	25	ns	
Asymmetry of sending	t _{tx_asym} CC	-2.45	-	2.45	ns	C_{L} =25pF
Sum of delay between TP1_FF and TP1_CC and delays derived from TP1_FFi, rising edge of TxD	t _{dCCTxD01}	-	-	25	ns	
Sum of delay between TP1_FF and TP1_CC and delays derived from TP1_FFi, falling edge of TxD	t _{dCCTxD10}	-	-	25	ns	
TxD signal sum of rise and fall time at TP1_BD	t _{txd_sum} CC	-	-	9	ns	

Table 3-86 Receive Parameters

Parameter	Symbol		Value	s	Unit	Note / Test Condition
		Min.	Тур.	Max.		
Acceptance of asymmetry at receiving part	$t_{ m dCCTxAsymAcc}$ ept25 SR	-30.5	-	43.0	ns	C _L =25pF
Acceptance of asymmetry at receiving part	$t_{ m dCCTxAsymAcc}$ ept15 SR	-31.5	-	44.0	ns	C _L =15pF
Threshold for detecting logical high	$T_{ m uCCLogic1}$ SR	35	-	70	%	
Threshold for detecting logical low	$T_{ m uCCLogic0}$ SR	30	-	65	%	





Electrical SpecificationE-Ray Parameters

Table 3-86 Receive Parameters (cont'd)

Parameter	Symbol		Values	Values Unit		Note / Test Condition
		Min.	Тур.	Max.		
Sum of delay between TP4_CC and TP4_FF and delays derived from TP4_FFi, rising edge of RxD	t _{dCCRxD01}	-	-	10	ns	
Sum of delay between TP1_CC and TP1_CC and delays derived from TP4_FFi, falling edge of RxD	t _{dCCRxD10}	-	-	10	ns	



Electrical SpecificationHSCT Parameters

3.31 HSCT Parameters

Table 3-87 HSCT - Rx/Tx setup timing

Parameter Sy	Symbol		Value	s	Unit	Note / Test Condition
		Min.	Тур.	Max.		
RX o/p duty cycle	DCrx CC	40	-	60	%	
Bias startup time	t _{bias} CC	-	5	10	μs	Bias distributor waking up from power down and provide stable Bias.
RX startup time	t _{rxi} CC	-	5	-	μs	Wake-up RX from power down.
TX startup time	t _{tx} CC	-	5	-	μs	Wake-up TX from power down.

Table 3-88 HSCT - Rx parasitics and loads

Parameter	Symbol	Values			Unit	Note / Test Condition
		Min.	Тур.	Max.		
Capacitance total budget	C _{total} CC	-	3.5	5	pF	Total Budget for complete receiver including silicon, package, pins and bond wire
Parasitic inductance budget	Htotal CC	-	5	-	nH	

Table 3-89 LVDSH - Reduced TX and RX (RED)

Parameter	Symbol		Value	s	Unit	Note / Test Condition
		Min.	Тур.	Max.		
Output differential voltage	$V_{OD}CC$	150	200	285	mV	Rt = 100 Ohm ±20% @2pF
Output voltage high	$V_{OH}CC$	-	-	1463	mV	Rt = 100 Ohm ±20%
Output voltage low	$V_{OL}CC$	937	-	-	mV	Rt = 100 Ohm ±20%
Output offset (Common mode) voltage	$V_{\rm OS}$ CC	1.08	1.2	1.32	V	Rt = 100 Ohm ±20% @2pF
Input voltage range	$V_{I}SR$	-	-	1.6	V	Absolute max = 1.6 V + (285mV/2) = 1.743
		0.15	-	-	V	Absolute min = 0.15 V - (285 mV /2) = 0 V
Input differential threshold	V_{idth} SR	-100	-	100	mV	100 mV for 55% of bit period; Note Absolute Value (Vidth - Vidthl)
Data frequency	DR CC	5	-	320	Mbps	



Electrical SpecificationHSCT Parameters

Table 3-89 LVDSH - Reduced TX and RX (RED) (cont'd)

Parameter	Symbol		Value	s	Unit	Note / Test Condition
		Min.	Тур.	Max.		
Receiver differential input	R _{in} CC	90	100	110	Ohm	0 V < V _I < 1.6V
impedance		80	100	120	Ohm	1.6 V < V _I < 2.0V
Slew rate	SRtx CC	-	-	2	V/ns	
Change in VOS between 0 and 1	dVOS CC	-	-	50	mV	Peak to peak (including DC transients).
Change in Vod between 0 and 1	dVod CC	-	-	50	mV	Peak to peak (including DC transients)
Fall time 1)	t _{fall} CC	0.26	-	1.2	ns	Rt = 100 Ohm ±20% @2pF
Rise time 1)	t _{rise} CC	0.26	-	1.2	ns	Rt = 100 Ohm ±20% @2pF

¹⁾ Rise / fall times are defined for 10% - 90% of $\,V_{\rm OD}$

Table 3-90 HSCT PLL

Parameter	Symbol		Value	s	Unit	Note / Test Condition
		Min.	Тур.	Max.		
PLL frequency range	f_{PLL} CC	12.5	320	320	MHz	
PLL input frequency	$f_{REF}CC$	10	-	20	MHz	
PLL lock-in time	t_{LOCK} CC	-	-	50	μs	
Bit Error Rate based on 10 MHz reference clock at Slave PLL side	BER ₁₀ CC	-	-	10EXP-9	-	Bit Error Rate based on Slave interface reference clock at 10 MHz
Bit Error Rate based on 20 MHz reference clock at Slave PLL side	BER ₂₀ CC	-	-	10EXP- 12	-	Bit Error Rate based on Slave interface reference clock at 20 MHz
Absolute RMS Jitter (TX out)	$J_{ m ABS10}$ CC	-125	-	125	ps	Measured at link TX out; valid for Reference frequency at 10 MHz
Absolute RMS Jitter (TX out)	J _{ABS20} CC	-85	-	85	ps	Measured at link TX out; valid for Reference frequency at 20 MHz



Electrical SpecificationHSCT Parameters

Table 3-90 HSCT PLL (cont'd)

Parameter	Symbol		Value	S	Unit	Note / Test Condition
		Min.	Тур.	Max.		
Accumulated RMS Jitter (RX side)	J _{ACC10} CC	-	-	145	ps	Measured at link RX input, based on 5000 measures, each 300 clock cycles; valid for Reference frequency at 10 MHz
Accumulated RMS Jitter (link RX side)	$J_{ m ACC20}$ CC	-	-	115	ps	Measured at link RX input, based on 5000 measures, each 300 clock cycles; valid for Reference frequency at 20 MHz
Total Jitter peak to peak	$TJ_{pp}CC$	-	-	2083	ps	Total Jitter as sum of deterministic jitter and random jitter

Table 3-91 HSCT Sysclk

Parameter Sym	Symbol		Value	s	Unit	Note / Test Condition
		Min.	Тур.	Max.		
Frequency	$f_{SYSCLK}CC$	10	-	20	MHz	
Frequency error	dfERR CC	-1	-	1	%	
Duty Cycle	DCsys CC	45	-	55	%	
Load impedance	R_{LOAD} CC	10	-	-	kOhm	
Load capacitance	C_{LOAD} CC	-	-	10	pF	
Integrated phase noise	I _{PN} CC	-	-	-58	dB	single sideband phase noise in 10 kHz to 10 Mhz at 20 MHz SysClk



Electrical SpecificationInter-IC (I2C) Interface Timing

3.32 Inter-IC (I2C) Interface Timing

This section defines the timings for I2C in the TC270 / TC275 / TC277.

All I2C timing parameter are SR for Master Mode and CC for Slave Mode.

Table 3-92 I2C Standard Mode Timing

Parameter	Symbol		Value	s	Unit	Note / Test Condition
		Min.	Тур.	Max.		
Fall time of both SDA and SCL	<i>t</i> ₁	-	-	300	ns	Measured with a pull- up resistor of 4.7 kohms at each of the SCL and SDA line
Capacitive load for each bus line	$C_{\rm b}$ SR	-	-	400	pF	
Bus free time between a STOP and ATART condition	t ₁₀	4.7	-	-	μs	Measured with a pull- up resistor of 4.7 kohms at each of the SCL and SDA line
Rise time of both SDA and SCL	<i>t</i> ₂	-	-	1000	ns	Measured with a pull- up resistor of 4.7 kohms at each of the SCL and SDA line
Data hold time	<i>t</i> ₃	0	-	-	μs	Measured with a pull- up resistor of 4.7 kohms at each of the SCL and SDA line
Data set-up time	<i>t</i> ₄	250	-	-	ns	Measured with a pull- up resistor of 4.7 kohms at each of the SCL and SDA line
Low period of SCL clock	<i>t</i> ₅	4.7	-	-	μs	Measured with a pull- up resistor of 4.7 kohms at each of the SCL and SDA line
High period of SCL clock	<i>t</i> ₆	4	-	-	μs	Measured with a pull- up resistor of 4.7 kohms at each of the SCL and SDA line
Hold time for the (repeated) START condition	<i>t</i> ₇	4	-	-	μs	Measured with a pull- up resistor of 4.7 kohms at each of the SCL and SDA line



Electrical SpecificationInter-IC (I2C) Interface Timing

Table 3-92 I2C Standard Mode Timing (cont'd)

Parameter	Symbol	Values			Unit	Note / Test Condition
		Min.	Тур.	Max.		
Set-up time for (repeated) START condition	<i>t</i> ₈	4.7	-	-	μs	Measured with a pull- up resistor of 4.7 kohms at each of the SCL and SDA line
Set-up time for STOP condition	t ₉	4	-	-	μs	Measured with a pull- up resistor of 4.7 kohms at each of the SCL and SDA line

Table 3-93 I2C Fast Mode Timing

Parameter	Symbol		Value	S	Unit	Note / Test Condition
		Min.	Тур.	Max.		
Fall time of both SDA and SCL	<i>t</i> ₁	20+0.1* <i>C</i>	-	300	ns	Measured with a pull- up resistor of 4.7 kohms at each of the SCL and SDA line
Capacitive load for each bus line	$C_{\rm b}$ SR	-	-	400	pF	
Bus free time between a STOP and ATART condition	t ₁₀	1.3	-	-	μs	Measured with a pull- up resistor of 4.7 kohms at each of the SCL and SDA line
Rise time of both SDA and SCL	t_2	20+0.1* <i>C</i>	-	300	ns	Measured with a pull- up resistor of 4.7 kohms at each of the SCL and SDA line
Data hold time	<i>t</i> ₃	0	-	-	μs	Measured with a pull- up resistor of 4.7 kohms at each of the SCL and SDA line
Data set-up time	<i>t</i> ₄	100	-	-	ns	Measured with a pull- up resistor of 4.7 kohms at each of the SCL and SDA line
Low period of SCL clock	<i>t</i> ₅	1.3	-	-	μs	Measured with a pull- up resistor of 4.7 kohms at each of the SCL and SDA line
High period of SCL clock	<i>t</i> ₆	0.6	-	-	μs	Measured with a pull- up resistor of 4.7 kohms at each of the SCL and SDA line





Electrical SpecificationInter-IC (I2C) Interface Timing

Table 3-93 I2C Fast Mode Timing (cont'd)

Parameter	Symbol	Values			Unit	Note / Test Condition
		Min.	Тур.	Max.		
Hold time for the (repeated) START condition	<i>t</i> ₇	0.6	-	-	μs	Measured with a pull- up resistor of 4.7 kohms at each of the SCL and SDA line
Set-up time for (repeated) START condition	<i>t</i> ₈	0.6	-	-	μs	Measured with a pull- up resistor of 4.7 kohms at each of the SCL and SDA line
Set-up time for STOP condition	<i>t</i> ₉	0.6	-	-	μs	Measured with a pull- up resistor of 4.7 kohms at each of the SCL and SDA line



Electrical SpecificationFlash Target Parameters

3.33 Flash Target Parameters

Program Flash program and erase operation is only allowed up the $T_{\rm J}$ = 150°C.

Table 3-94 FLASH

Parameter	Symbol	Values			Unit	Note / Test Condition
		Min.	Тур.	Max.		
Program Flash Erase Time per	t_{ERP} CC	-	-	1	s	cycle count < 1000
logical sector		-	0.207 + 0.003 * (<i>S</i> [KByte]) / (<i>f</i> _{FSI} [MHz]) ¹⁾	-	S	cycle count < 1000, for sector of size S
Program Flash Erase Time per Multi-Sector Command	t _{MERP} CC	-	-	1	S	For consecutive logical sectors in a physical sector, cycle count < 1000
		-	0.207 + 0.003 * (<i>S</i> [KByte]) / (<i>f</i> _{FSI} [MHz]) ¹⁾	-	S	For consecutive logical sector range of size S in a physical sector, cycle count < 1000
Program Flash program time per page in 5 V mode	t _{PRP5} CC	-	-	50 + 3000/(f _{FSI} [MHz])	μs	32 Byte
Program Flash program time per page in 3.3 V mode	t _{PRP3} CC	-	-	81 + 3400/(<i>f</i> _{FSI} [MHz])	μs	32 Byte
Program Flash program time per burst in 5 V mode	t _{PRPB5} CC	-	-	125 + 9500/(f _{FSI} [MHz])	μs	256 Byte
Program Flash program time per burst in 3.3 V mode	t_{PRPB3} CC	-	-	410 + 12000/($f_{\rm F}$ _{SI} [MHz])	μs	256 Byte
Program Flash program time for 1 MByte with burst programming in 3 V mode excluding communication	t _{PRPB3_1MB}	-	-	2.2	s	Derived value for documentation purpose, valid for $f_{\rm FSI}$ = 100MHz
Program Flash program time for 1 MByte with burst programming in 5 V mode excluding communication	t _{PRPB5_1MB}	-	-	0.9	s	Derived value for documentation purpose, valid for $f_{\rm FSI}$ = 100MHz
Program Flash program time for complete PFlash with burst programming in 5 V mode excluding communication	t _{PRPB5_PF}	-	-	3.6	s	Derived value for documentation purpose, valid for $f_{\rm FSI}$ = 100MHz



Electrical SpecificationFlash Target Parameters

Table 3-94 FLASH (cont'd)

Parameter	Symbol		Values		Unit	Note / Test Condition	
		Min. Typ. Max.		Max.			
Write Page Once adder	t _{ADD} CC	-	-	15 + 500/(f _{FSI} [MHz])	μs	Adder to Program Time when using Write Page Once	
Program Flash suspend to read latency	t _{SPNDP} CC	-	-	12000/(f _F _{SI} [MHz])	μs	For Write Burst, Verify Erased and for multi- (logical) sector erase commands	
Data Flash Erase Time per Sector ²⁾	t _{ERD} CC	-	0.12 + 0.08/ $(f_{\text{FSI}} \text{ [MHz]})^{1)}$	-	s	cycle count < 1000	
		-	$0.57 + 0.15/(f_{FSI} \text{ [MHz]})^{1)}$	0.928 + 0.15/(f_{FSI} [MHz])	s	cycle count < 125000	
Data Flash Erase Time per Multi-Sector Command ²⁾	t_{MERD} CC	-	0.12 + 0.01 * (<i>S</i> [KByte]) / (f_{FSI} [MHz]) ¹⁾	-	S	For consecutive logical sector range of size S, cycle count < 1000	
		-	0.57 + 0.019 * (<i>S</i> [KByte]) / (f_{FSI} [MHz]) ¹⁾	0.928 + 0.019 * (<i>S</i> [KByte]) / (<i>f</i> _{FSI} [MHz])	s	For consecutive logical sector range of size S, cycle count < 125000	
Data Flash erase disturb limit	N_{DFD} CC	-	-	50	cycles		
Program time data flash per page ³⁾	t _{PRD} CC	-	-	50 + 2500/(f _{FSI} [MHz]) ³⁾	μs	8 Byte	
Complete Device Flash Erase Time PFlash and DFlash ⁴⁾	t _{ER_Dev} CC	-	-	9	S	Derived value for documentation purpose (excl. UCBs and HSMs), valid for f_{FSI} = 100MHz	
Data Flash program time per burst ³⁾	t _{PRDB} CC	-	-	96 + 4400/(f _{FSI} [MHz]) ³⁾	μs	32 Bytes	
Data Flash suspend to read latency	t_{SPNDD} CC	-	-	12000/(f _F _{SI} [MHz])	μs		
Wait time after margin change	t _{FL_MarginDel}	-	-	10	μs		
Program Flash Retention Time, Sector	$t_{RET}CC$	20	-	-	years	Max. 1000 erase/program cycles	
Data Flash Endurance per EEPROMx sector ⁵⁾	N _{E_EEP10}	125000	-	-	cycles	Max. data retention time 10 years	



Electrical SpecificationFlash Target Parameters

Table 3-94 FLASH (cont'd)

Parameter	Symbol		Value	s	Unit	Note / Test Condition
		Min.	Тур.	Max.		
Data Flash Endurance per HSMx sector ⁵⁾	$N_{E_HSM}CC$	125000	-	-	cycles	Max. data retention time 10 years
UCB Retention Time	t _{RTU} CC	20	-	-	years	Max. 100 erase/program cycles per UCB, max 400 erase/program cycles in total
Data Flash access delay	t _{DF} CC	-	-	100	ns	see PMU_FCON.WSDFLA SH
Data Flash ECC Delay	t _{DFECC} CC	-	-	20	ns	see PMU_FCON.WSECD F
Program Flash access delay	t _{PF} CC	-	-	30	ns	see PMU_FCON.WSPFLA SH
Program Flash ECC delay	t _{PFECC} CC	-	-	10	ns	see PMU_FCON.WSECP F
Number of erase operations on DF0 over lifetime	N _{ERD0} CC	-	-	750000	cycles	
Number of erase operations on DF1 over lifetime	N _{ERD1} CC	-	-	500000	cycles	
Junction temperature limit for PFlash program/erase operations	T _{JPFlash} SR	-	-	150	°C	

- 1) All typical values were characterised, but are not tested. Typical values are safe median values at room temperature
- 2) Under out-of-spec conditions (e.g. over-cycling) or in case of activation of WL oriented defects, the duration of erase processes may be increased by up to 50%.
- 3) Time is not dependent on program mode (5V or 3.3V).
- 4) Using 512 KByte erase commands.
- 5) Only valid when a robust EEPROM emulation algorithm is used. For more details see the Users Manual.



Electrical SpecificationPackage Outline

3.34 Package Outline

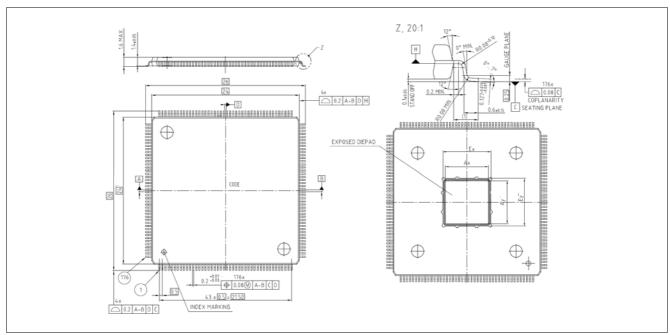


Figure 3-28 Package Outlines PG-LQFP-176-22

Table 3-95 Exposed Pad Dimensions

Ax (nominal EPad size)	7.9 mm ± 50 µm
Ay (nominal EPad size)	7.9 mm ± 50 µm
Ex (solder able EPad size)	8.7 mm ± 50 µm
Ey (solder able EPad size)	8.7 mm ± 50 µm

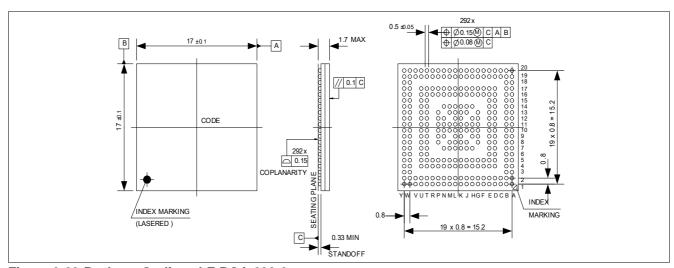


Figure 3-29 Package Outlines LF-BGA-292-6

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Electrical SpecificationPackage Outline

3.34.1 Package Parameters

Table 3-96 Thermal Characteristics of the Package

Device	Package	RQJCT ¹⁾	RQJCB ¹⁾	RQJA	Unit	Note
TC275	PG-LQFP-176-22	9,6	1,25	14,72)	K/W	with soldered exposed pad
TC277	LF-BGA-292-6	5,1	7,2	15,8 ³⁾	K/W	

- 1) The top and bottom thermal resistances between the case and the ambient $(R_{\mathsf{TCAT}}, R_{\mathsf{TCAB}})$ are to be combined with the thermal resistances between the junction and the case given above $(R_{\mathsf{TJCT}}, R_{\mathsf{TJCB}})$, in order to calculate the total thermal resistance between the junction and the ambient (R_{TJA}) . The thermal resistances between the case and the ambient $(R_{\mathsf{TCAT}}, R_{\mathsf{TCAB}})$ depend on the external system (PCB, case) characteristics, and are under user responsibility. The junction temperature can be calculated using the following equation: $T_{\mathsf{J}} = T_{\mathsf{A}} + R_{\mathsf{TJA}} * P_{\mathsf{D}}$, where the R_{TJA} is the total thermal resistance between the junction and the ambient. This total junction ambient resistance R_{TJA} can be obtained from the upper four partial thermal resistances.
 - Thermal resistances as measured by the 'cold plate method' (MIL SPEC-883 Method 1012.1).
- 2) Value is defined in accordance with JEDEC JESD51-3, JESD51-5, and JESD51-7.
- 3) Value is defined in accordance with JEDEC JESD51-1.

3.34.2 TC270 Carrier Tape

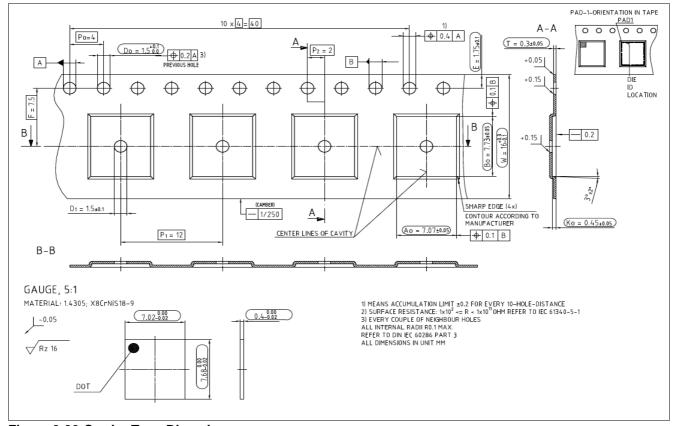


Figure 3-30 Carrier Tape Dimenions





Electrical SpecificationPackage Outline

Table 3-97 TC270 Chip Dimenions

Device	A	В	T
TC270	7,590 mm	6,930 mm	0,3 mm



Electrical SpecificationQuality Declarations

3.35 Quality Declarations

Table 3-98 Quality Parameters

Parameter	Symbol Values			s	Unit	Note / Test Condition
		Min.	Тур.	Max.		
Operation Lifetime	$t_{\sf OP}$	-	-	24500	hour	
ESD susceptibility according to Human Body Model (HBM)	V_{HBM}	-	-	2000	V	Conforming to JESD22-A114-B
ESD susceptibility of the LVDS pins	V_{HBM1}	-	-	500	V	
ESD susceptibility according to Charged Device Model (CDM)	V_{CDM}	-	-	500	V	for all other balls/pins; conforming to JESD22-C101-C
		-	-	750	V	for corner balls/pins; conforming to JESD22-C101-C
Moisture Sensitivity Level	MSL	-	-	3		Conforming to Jedec J-STD020C for 240C



HistoryChanges from TC27xDB_v10 to 1.0

4 History

4.1 Changes from TC27xDB_v10 to 1.0

- Replace PG-LQFP-176-18 with correct package LF-BGA-292-6 in table 1
- VADC
 - Add parameter $t_{\rm WU}$
 - Add parameter R_{MDU}
 - Add parameter R_{MDD}

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