

On Uncertainty Estimation by Tree-based Surrogate Models in Sequential Model-based Optimization



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Introduction

- GP regression is a popular choice as a surrogate model, because of its capability of calculating uncertainties analytically.
- On the other hand, an ensemble of randomized trees is another option and has practical merits over GPs due to its scalability and easiness of handling continuous/discrete mixed variables.
- We revisit various ensembles of randomized trees to investigate their behavior in the perspective of prediction uncertainty estimation.
- Then, we propose our own tree-based model, referred to as *BwO forest*.

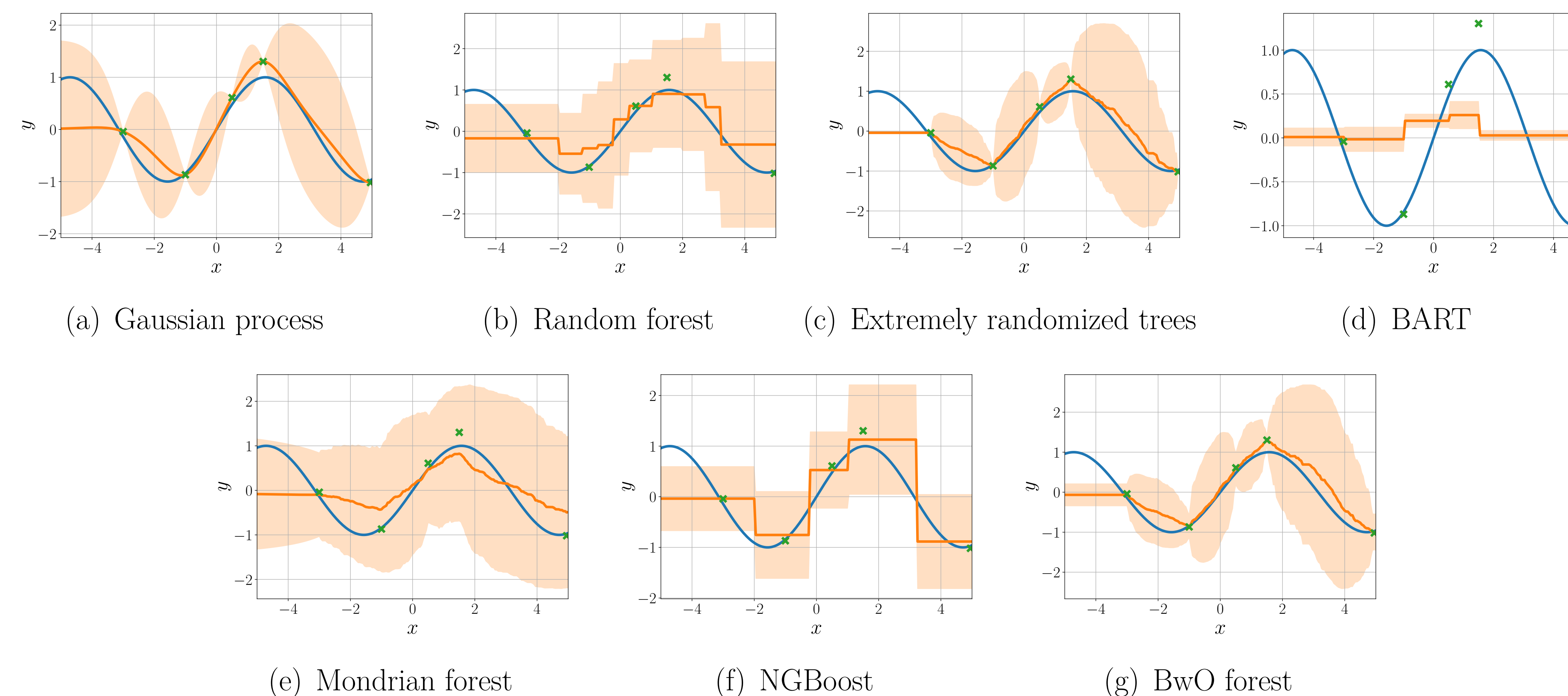


Figure 1: Results with GP regression and tree-based models such as random forest, extremely randomized trees, BART, Mondrian forest, NGBoost, and BwO forest (ours).

Tree Construction

- The uncertainty of an ensemble is derived from the randomness of individual trees:
 - bagging**: it samples a bootstrap sample with replacement and then aggregates base estimators;
 - random feature selection**: this technique randomly selects a feature from a set of dimensions;
 - random split location**: it randomly selects a split location between lower and upper bounds of the selected dimension;
 - random tree sampling**: this strategy randomly samples a tree under the assumption on a prior distribution.

- Random forest employs (i) and (ii), BART employs (i), (ii), and (iv), and Mondrian forest employs (i) and (iii).

Elaborating Uncertainty Estimation

- The expectation and variance of an indicator for the existence of \mathbf{x}_i in a bootstrap sample \mathbf{B} are expressed as

$$\mathbb{E}[1_{\mathbf{x}_i \in \mathbf{B}}] = 1 - \left(1 - \frac{1}{N}\right)^M,$$

$$\text{Var}[1_{\mathbf{x}_i \in \mathbf{B}}] = \left(1 - \frac{1}{N}\right)^M - \left(1 - \frac{1}{N}\right)^{2M},$$
 where N is the size of \mathbf{X} and M is the size of a bootstrap sample.

- The distribution of unique original elements in a bootstrap sample \mathbf{B} is:

$$\mathbb{E}[|\text{unique}(\mathbf{B})|] = N - \frac{(N-1)^M}{N^{M-1}},$$

$$\text{Var}[|\text{unique}(\mathbf{B})|] = (N-1) \frac{(N-2)^M}{N^{M-1}} + \frac{(N-1)^M}{N^{M-1}} - \frac{(N-1)^{2M}}{N^{2M-2}},$$

where $\text{unique}(\mathbf{B})$ filters duplicates.

Algorithm 1 Training BwO Forest

Require: Ensemble size B , training data and evaluations $\mathbf{X} \in \mathbb{R}^{N \times d}$ and $\mathbf{y} \in \mathbb{R}^N$, size of bootstrap sample $M = \alpha N$ for an oversampling rate $\alpha > 1$.
Ensure: Set of decision trees $\{\mathcal{T}_b\}_{b=1}^B$

- 1: Initialize a set of decision trees.
- 2: **for** $b = 1, \dots, B$ **do**
- 3: **Sample a bootstrap sample** $\mathbf{B}_b \in \mathbb{R}^{M \times d}$ **from** \mathbf{X} .
- 4: Set a root node τ_r that contains all the elements in \mathbf{B}_b , and τ_r is set as the current split node.
- 5: Train a decision tree using random feature selection and random split location.
- 6: **end for**
- 7: **return** A set of decision trees $\{\mathcal{T}_b\}_{b=1}^B$

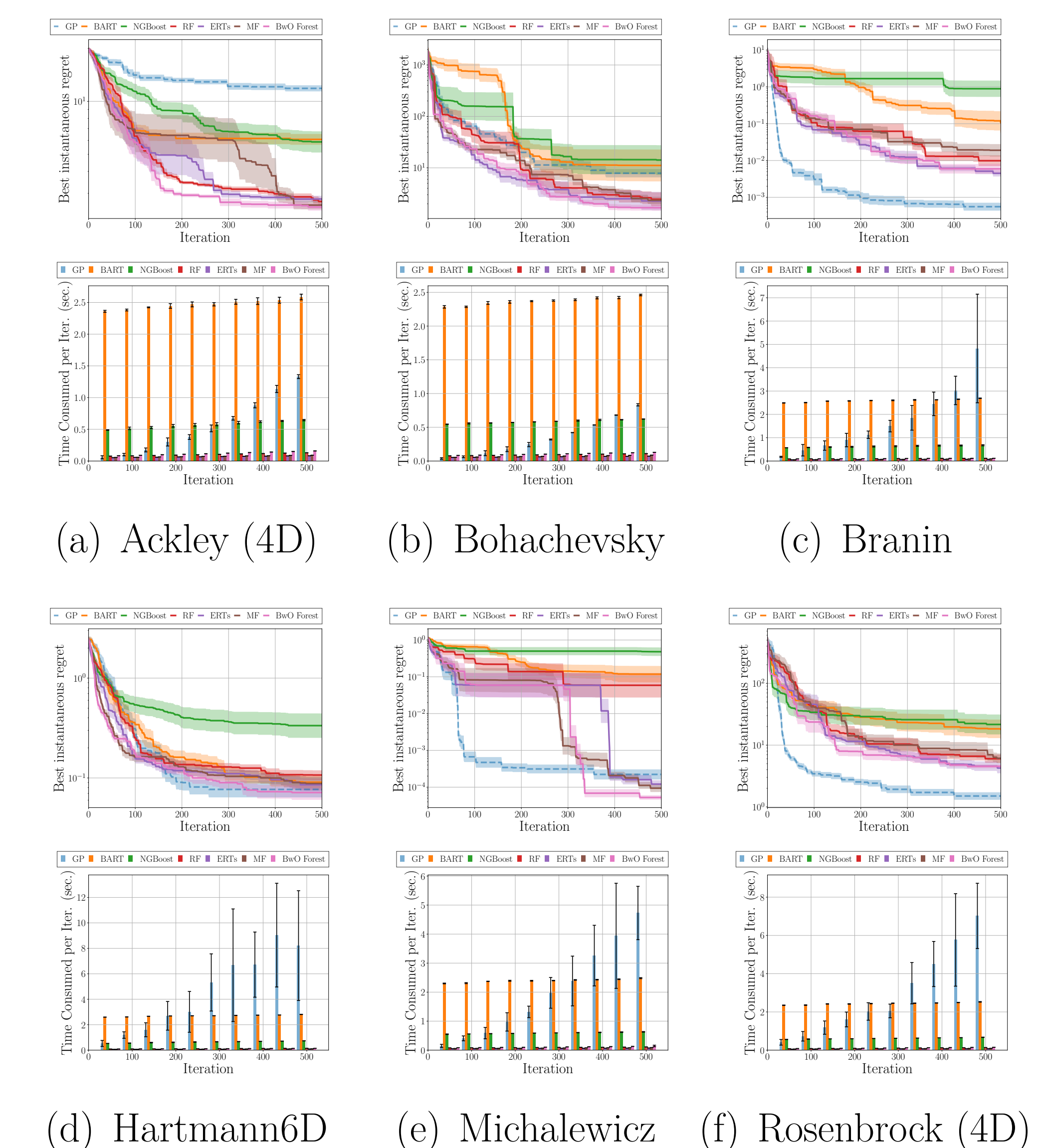


Figure 2: Experimental results on various benchmark functions.

Available on [arXiv](#)/[GitHub](#)



arXiv



GitHub

Uncertainty Estimation by Tree-based Models

- Sum-of-Trees Model:** Posterior mean and variance functions are

$$\mu(\mathbf{x}; \{\mathcal{T}_b\}_{b=1}^B, \mathbf{X}, \mathbf{y}) = \frac{1}{B} \sum_{b=1}^B \sum_{\tau \in \mathcal{T}_{b,l}} \mu_\tau 1_{\mathbf{x} \in \tau},$$

$$\sigma^2(\mathbf{x}; \{\mathcal{T}_b\}_{b=1}^B, \mathbf{X}, \mathbf{y}) = \frac{1}{B} \sum_{b=1}^B \left(\left(\sum_{\tau \in \mathcal{T}_{b,l}} \sigma_\tau 1_{\mathbf{x} \in \tau} \right)^2 + \left(\sum_{\tau \in \mathcal{T}_{b,l}} \mu_\tau 1_{\mathbf{x} \in \tau} \right)^2 - \mu(\mathbf{x}; \{\mathcal{T}_b\}_{b=1}^B, \mathbf{X}, \mathbf{y})^2 \right).$$

- Gradient Boosting Models:** It updates parameters θ using their gradients in terms of the objective of parametric dist., e.g., likelihood function.