Dissecting Urban Noises from Heterogeneous

Geo-Social Media and Sensor Data

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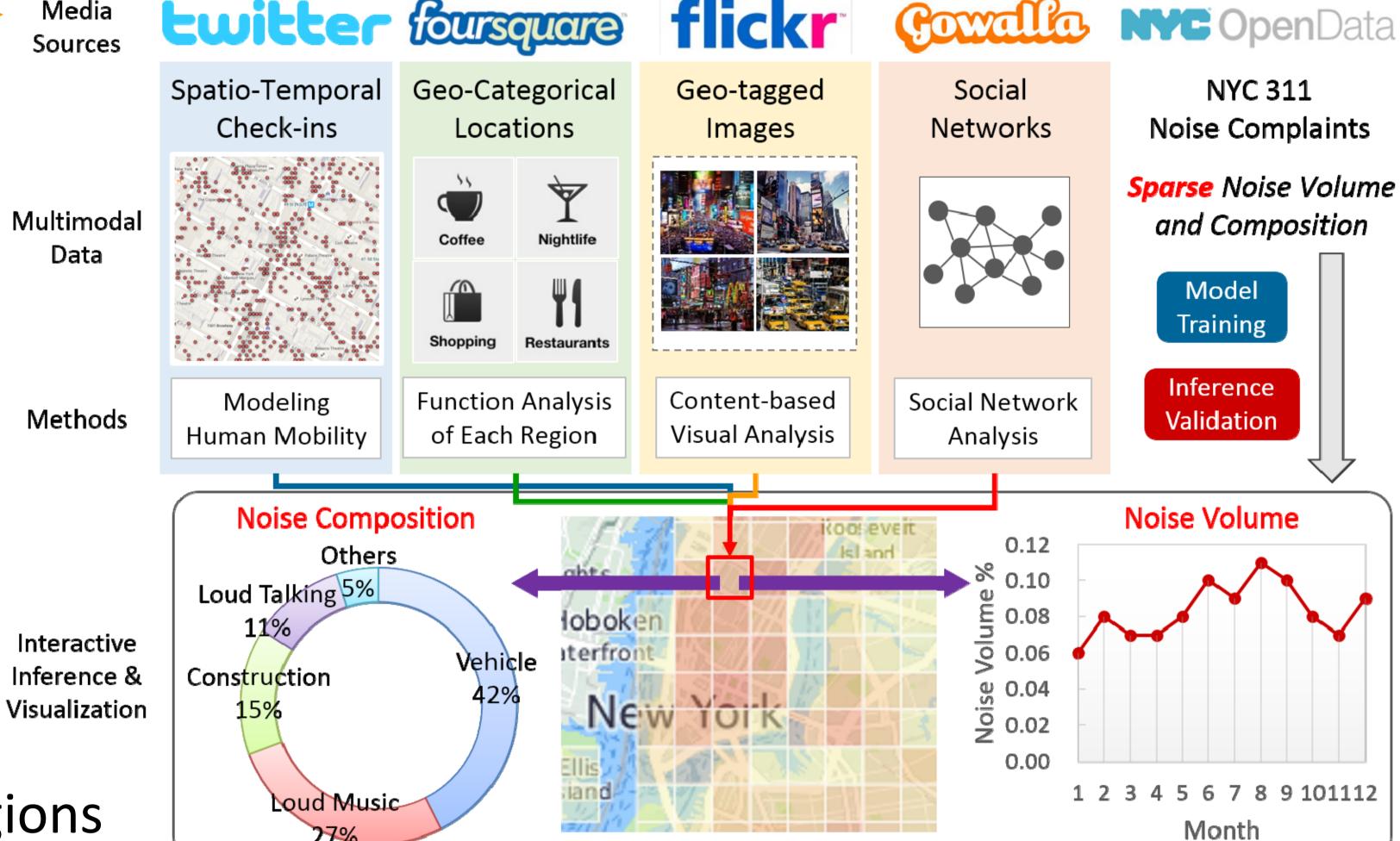
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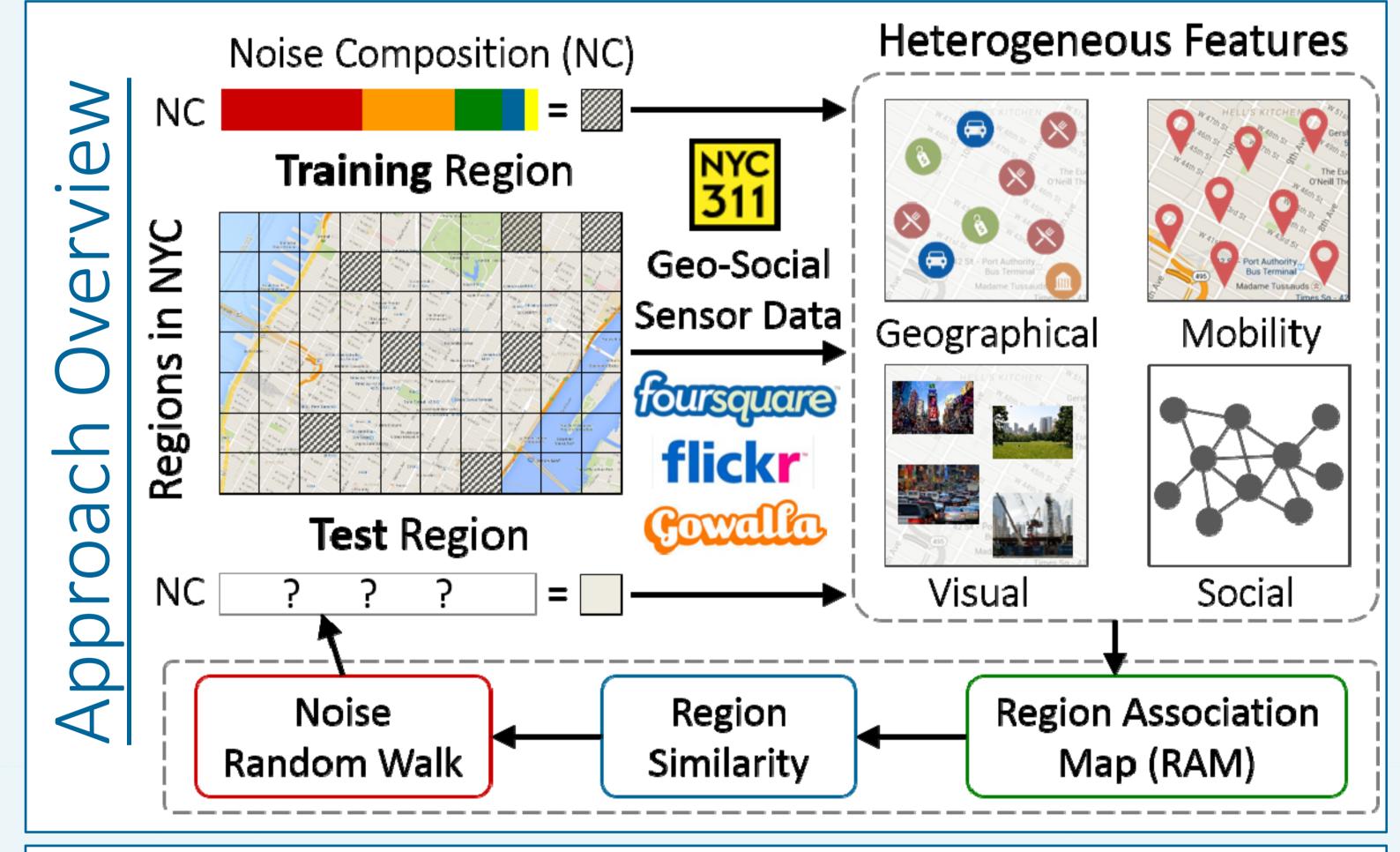
## Motivation

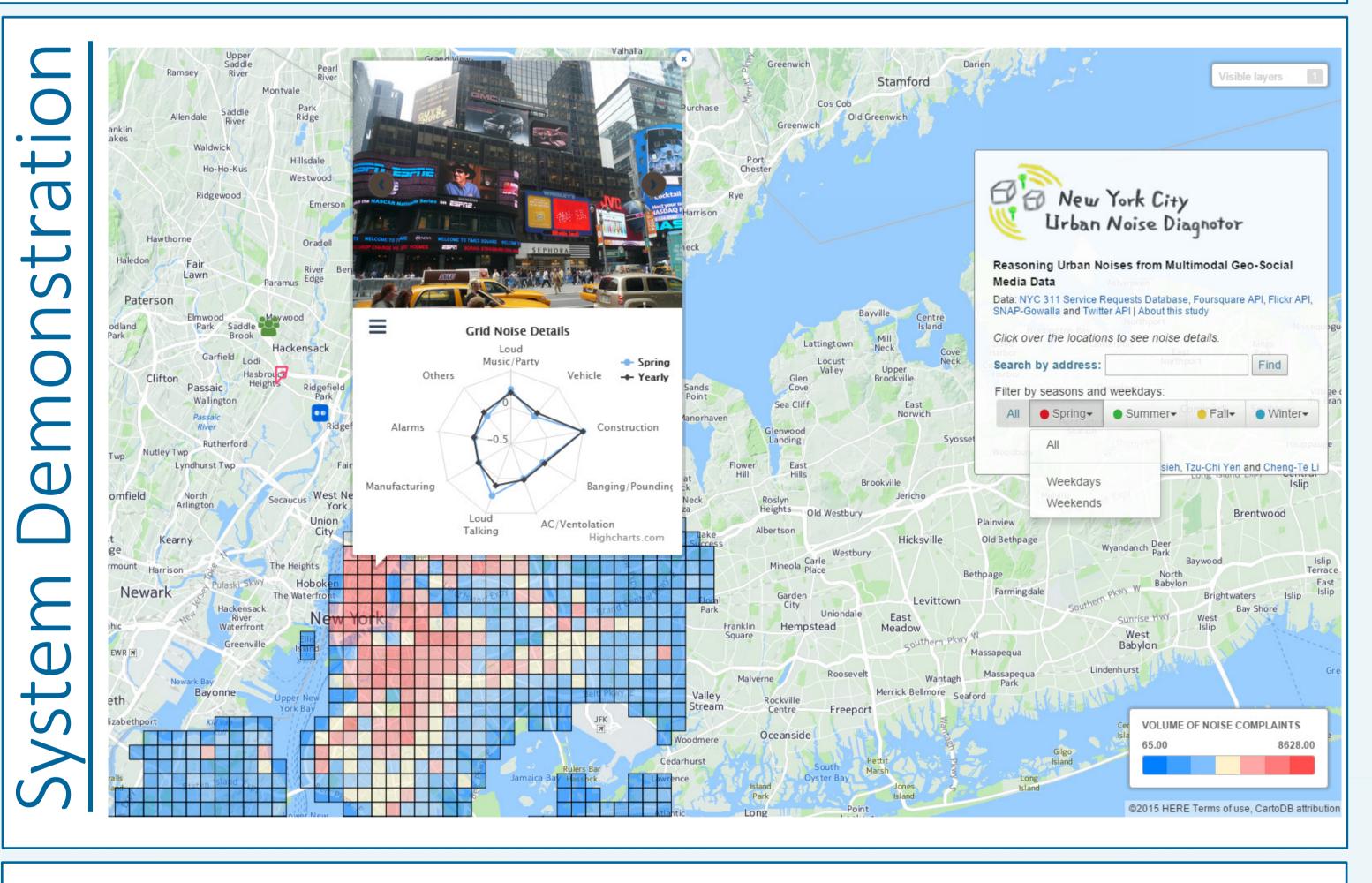
- Geo-social media can be considered as a kind of sensors that monitor urban human activities.
- Urban noise pollution damages the mental health (e.g. work efficiency and sleep quality).
- We need to first understand the elements and causes that produce the noise. E.g. @TimeSquare "in evening rush hour, 60% noise come from vehicle traffic, 30% from loud music of stores, and 10% from people' talking"

## Problem Statement

 Given a few NYC regions whose noise info are known, infer the noise composition of other regions







#### Extracting Geo-Social Features Step 1

Geographical Mobility Visual Social Color Histogram, Region Density, PageRank, SimRank, Region Popularity, Venue Closeness, Color Moments, Spatial Centralities, **Movement Density** #Communities, Gabor Textures, Category Entropy, **Incoming Flow** CC, density Competitiveness SIFT features Step 2 Region Association Map Step 3

#### A region is a node. Edges are constructed based on Region Similarity geo-closeness, time, and labeled data. EdgeWeight(u, v) = RegSim(u, v) = $-\sum_{k} |\mathbf{f_k}(u) - \mathbf{f_k}(v)||$ 1 Feature Vector of Feature Weights feature k for node v Learned from validation set!

 $t_{n+1}$ 

Noise Random Walk in RAM

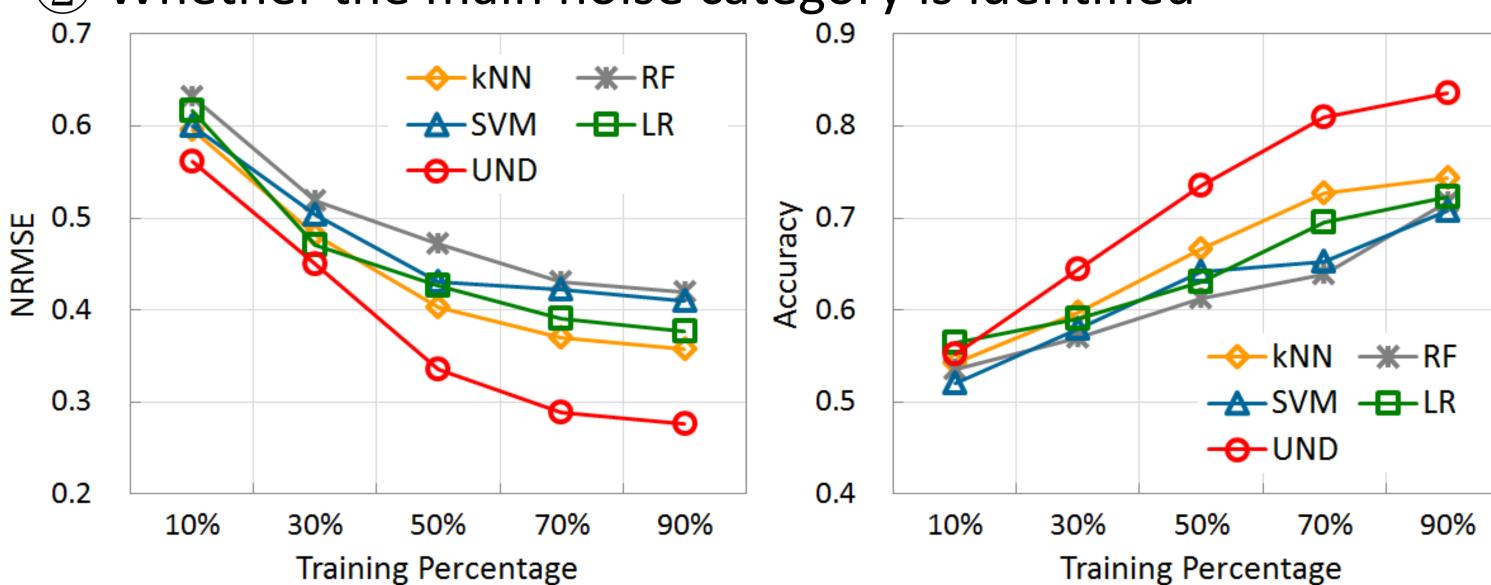
 $t_{n-1}$ 

Iteratively update each unlabeled node based on the noise composition of its neighbors

### Edge weight $n_c(v) \leftarrow$ $u\overline{\in}\Gamma(v)$

Neighbor nodes of v

#### (2) Whether the main noise category is identified <del>-</del>₩-RF



Hour Intervals Days 20 - 23Weekday Weekend 00 - 0304 - 0708 - 1112 - 1516 - 19 $\overline{\mathbf{RMSE}}$ 0.0750.2190.1590.0810.1060.1180.1670.0610.9090.8580.8530.9230.9040.8360.9110.895Accuracy

# Experimental Results

## 560 regions in NYC e.g. Loud Music/Party,

- NYC 311 Noise Compliant Data 14 noise categories Construction, Loud Talking, Vehicle
- 47,581 venues, 196,591 users, 6,442,890 check-ins
- (1) Measure the error between the ground-truth and the inferred noise values

5% data used for tuning parameters