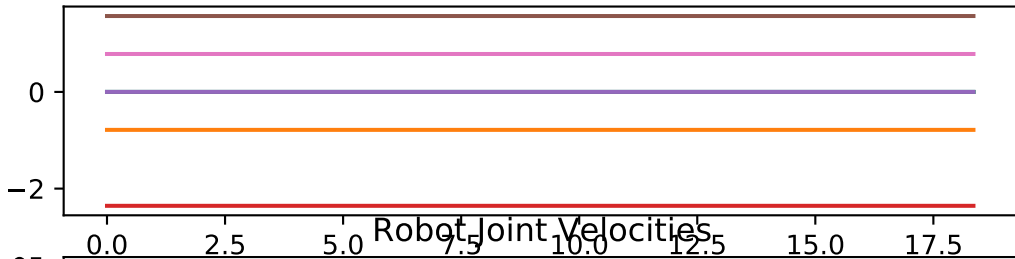
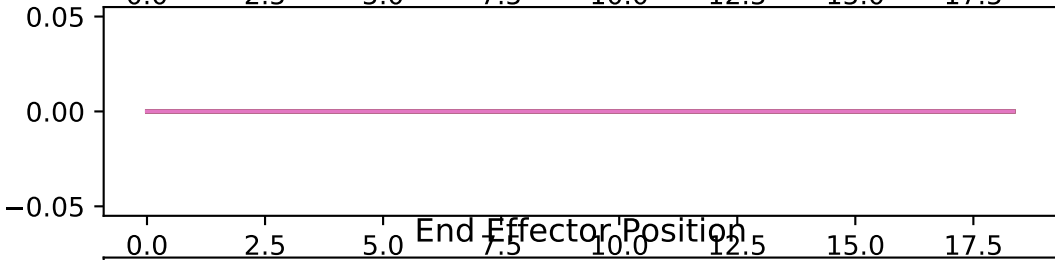


Robot Joint Positions



Robot Joint Velocities



End Effector Position

