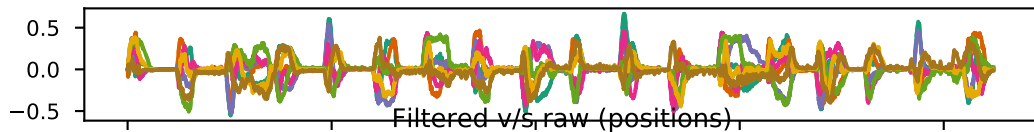


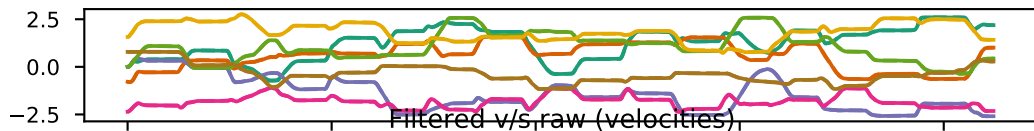
Robot Joint Positions



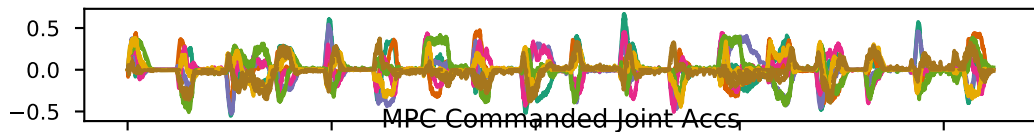
Robot Joint Velocities



Filtered v/s,raw (positions)



Filtered v/s,raw (velocities)



MPC Commanded Joint Accs

