Jun Meng

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Max-Bill-Str. 67, 80807 München (DE)
Chinese | German | English
Born on 20.09.1997, in China
Homepage | LinkedIn | Github

Skills: Python, C/C++, ROS/ROS2, MATLAB/Simulink, Git, Docker, Linux OS, CATIA

Roles: I'm looking for a challenging role as **Software Developer** / **Test Engineer** / **Simulation Engineer** / **AI Engineer** in the fields of AD/ADAS or general Engineering fields.

Education

M.Sc. in Automotive Engineering | **Technical University of Munich** — Munich, DE | 10/2020 – 06/2024
Curricula: DL, CV, SW Development of ADAS, E/E in Automotive (CAN, LIN, FlexRay) — *Grade: 2,3*

B.Eng. in Vehicle Engineering | **South China University of Technology** — Guangzhou, CN | 09/2015 – 06/2019
Curricula: Mechanical Engineering, Control Theory, Vehicle Dynamics — *Grade: 3.78/4.0 (best 5%)*

Work Experiences

Porsche Engineering Group GmbH — Mönsheim, DE
Intern ADAS (Praktikant Fahrerassistenzsysteme) — *03/2023 – 08/2023*
- Task: Pre-development of ML-based collision prediction for Highway-Pilot (HWP) function. (*Certificate*)
- Process sensor data (LRR and camera), determine sovereign zone, develop labeling tool with 2ooX logic, establish dataset.
- Develop and train a model to classify surrounding vehicles as safe / unsafe based on their history behaviors in Frenet coordnate.
- Test through various scenarios, evaluate safety vote and reliability in collision prediction using KPI metrics.

ENSNARE TUM — Munich, DE
HiWi: ROS Developer — *10/2022 – 02/2023*
- Task: UAV localization for automated construction.
- Develop ROS-based AprilTag detection and tracking pipeline with BASLER camera and SONY-SDK. (*GitHub*)
- Validate tracking system's real-time capability with total station. Lag less than 0.1 s under FPS 16.

SCUT-Racing (Formula Student China) — Guangzhou, CN
Leader Aerodynamics — *11/2017 – 06/2019*
- Technical tasks: CAD design and CFD simulation for Aero-Kits; Manufacturing of CFK-parts; Track testing and data analysis.
- Team management; Financial management for the subteam Aerodynamics.

Projects

Mamba-based 3D Object Detection with Object Relation (Slide) — 12/2023 – 06/2024
Master's thesis, School of CIT, TUM — *Python, PyTorch, GNN, 3D Object Detection*
- Design a GNN-based module and integrate into LiDAR-based baseline models to infer object relation explicitly. (*IEEE-ITSC24*)
- Apply newly proposed Mamba-based feature encoder as 2D BEV backbone in baseline models to reduce model complexity.
- Results: Experiments on KITTI and Waymo datasets. FLOPs reduced by 40%, average mAP improved by over 1%.

Autonomous Driving Simulator and Benchmark with ROS2 (GitHub) — 06/2022 – 12/2022
Semester thesis, School of CIT, TUM — *Python, C#, ROS2, OpenCV, Depth Estimation*
- Develop autonomous driving simulator on *Neuro-Robotics Platform* , developed with ROS2, results visualized in Rviz.
- Implement YOLOv5 for 2D object detection and SGBM for stereo depth estimation, distance errors limited in cm-level.

Skills & Hobbies

- **Programming**: Python, C/C++, ROS/ROS2, MATLAB/Simulink, CUDA, Git, Docker, Linux OS
- **CAD & CAE**: AutoCAD, CATIA, SolidWorks, Blender, ANSYS, StarCCM+
- **Languages**: Chinese (Native) | English (Business-fluent) | German (Business-fluent)
- **Hobbies**: Car model handworking, Photography, Hiking, Driving
- **Driver's License**: Klasse B (DE)

Munich, August 19, 2024

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