

CALCULUS FORMULES

DIFFERENTIATIE REGELS

$$\frac{d}{dx}(f(x) + g(x)) = f'(x) + g'(x)$$

$$\frac{d}{dx}(cf(x)) = cf'(x)$$

$$\frac{d}{dx}(f(x)g(x)) = f'(x)g(x) + f(x)g'(x)$$

$$\frac{d}{dx}\left(\frac{1}{f(x)}\right) = -\frac{f'(x)}{(f(x))^2}$$

$$\frac{d}{dx}\left(\frac{f(x)}{g(x)}\right) = \frac{f'(x)g(x) - f(x)g'(x)}{(g(x))^2}$$

$$\frac{d}{dx}f(g(x)) = f'(g(x))g'(x)$$

ELEMENTAIRE AFGELEIDEN

$$\frac{d}{dx}x^r = rx^{r-1}$$

$$\frac{d}{dx}a^x = a^x \ln a \quad (a > 0)$$

$$\frac{d}{dx} \ln x = \frac{1}{x} \quad (x > 0)$$

$$\frac{d}{dx} \sin x = \cos x$$

$$\frac{d}{dx} \cos x = -\sin x$$

$$\frac{d}{dx} \tan x = \sec^2 x$$

$$\frac{d}{dx} \sec x = \sec x \tan x$$

$$\frac{d}{dx} \csc x = -\csc x \cot x$$

$$\frac{d}{dx} \cot x = -\csc^2 x$$

$$\frac{d}{dx} \sin^{-1} x = \frac{1}{\sqrt{1-x^2}}$$

$$\frac{d}{dx} \tan^{-1} x = \frac{1}{1+x^2}$$

$$\frac{d}{dx} |x| = \operatorname{sgn} x = \frac{x}{|x|}$$

TRIGONOMETRISCHE IDENTITEITEN

$$\sin^2 x + \cos^2 x = 1$$

$$\sin(-x) = -\sin x$$

$$\cos(-x) = \cos x$$

$$\sec^2 x = 1 + \tan^2 x$$

$$\sin(\pi - x) = \sin x$$

$$\cos(\pi - x) = -\cos x$$

$$\csc^2 x = 1 + \cot^2 x$$

$$\sin\left(\frac{\pi}{2} - x\right) = \cos x$$

$$\cos\left(\frac{\pi}{2} - x\right) = \sin x$$

$$\sin(x \pm y) = \sin x \cos y \pm \cos x \sin y$$

$$\cos(x \pm y) = \cos x \cos y \mp \sin x \sin y$$

$$\tan(x \pm y) = \frac{\tan x \pm \tan y}{1 \mp \tan x \tan y}$$

$$\sin 2x = 2 \sin x \cos x$$

$$\sin^2 x = \frac{1 - \cos 2x}{2}$$

$$\frac{1 + \cos 2x}{2}$$

$$\cos 2x = 2 \cos^2 x - 1 = 1 - 2 \sin^2 x$$

KWADRATISCHE VERGELIJKING

$$\text{Als } Ax^2 + Bx + C = 0, \text{ dan } x = \frac{-B \pm \sqrt{B^2 - 4AC}}{2A}$$

VECTORIDENTITEITEN

$$\text{Als } u_1 \mathbf{i} + u_2 \mathbf{j} + u_3 \mathbf{k}$$

$$v_1 \mathbf{i} + v_2 \mathbf{j} + v_3 \mathbf{k}$$

$$w_1 \mathbf{i} + w_2 \mathbf{j} + w_3 \mathbf{k}$$

$$(\text{dot product}) \quad \mathbf{u} \cdot \mathbf{v} = u_1 v_1 + u_2 v_2 + u_3 v_3$$

$$(\text{cross product}) \quad \mathbf{u} \times \mathbf{v} = \begin{vmatrix} \mathbf{i} & \mathbf{j} & \mathbf{k} \\ u_1 & u_2 & u_3 \\ v_1 & v_2 & v_3 \end{vmatrix}$$

$$= (u_2 v_3 - u_3 v_2) \mathbf{i} + (u_3 v_1 - u_1 v_3) \mathbf{j} + (u_1 v_2 - u_2 v_1) \mathbf{k}$$

$$\text{lengte van } \mathbf{u} = |\mathbf{u}| = \sqrt{u_1^2 + u_2^2 + u_3^2}$$

$$\text{hoek tussen } \mathbf{u} \text{ en } \mathbf{v} = \cos^{-1} \left(\frac{\mathbf{u} \cdot \mathbf{v}}{|\mathbf{u}| |\mathbf{v}|} \right)$$

$$\text{drievoudig product}$$

$$\mathbf{u} \cdot (\mathbf{v} \times \mathbf{w}) = \mathbf{v} \cdot (\mathbf{w} \times \mathbf{u}) = \mathbf{w} \cdot (\mathbf{u} \times \mathbf{v})$$

$$\mathbf{u} \times (\mathbf{v} \times \mathbf{w}) = \mathbf{u} \times (\mathbf{u} \cdot \mathbf{w}) \mathbf{v} - (\mathbf{u} \cdot \mathbf{v}) \mathbf{w}$$

IDENTITEITEN M.B.T. GRADIENT, DIVERGENTIE, CURL EN LAPLACIAAN

$$\nabla = \mathbf{i} \frac{\partial}{\partial x} + \mathbf{j} \frac{\partial}{\partial y} + \mathbf{k} \frac{\partial}{\partial z} \quad \text{"del" of "nabla" operator}$$

$$F(x, y, z) = F_1(x, y, z) \mathbf{i} + F_2(x, y, z) \mathbf{j} + F_3(x, y, z) \mathbf{k}$$

$$\nabla \phi(x, y, z) = \frac{\partial \phi}{\partial x} \mathbf{i} + \frac{\partial \phi}{\partial y} \mathbf{j} + \frac{\partial \phi}{\partial z} \mathbf{k}$$

$$\nabla \cdot F(x, y, z) = \frac{\partial F_1}{\partial x} + \frac{\partial F_2}{\partial y} + \frac{\partial F_3}{\partial z}$$

$$\nabla \times F(x, y, z) = \operatorname{curl} F(x, y, z) = \begin{vmatrix} \mathbf{i} & \mathbf{j} & \mathbf{k} \\ \frac{\partial}{\partial x} & \frac{\partial}{\partial y} & \frac{\partial}{\partial z} \\ F_1 & F_2 & F_3 \end{vmatrix}$$

$$= \left(\frac{\partial F_3}{\partial y} - \frac{\partial F_2}{\partial z} \right) \mathbf{i} + \left(\frac{\partial F_1}{\partial z} - \frac{\partial F_3}{\partial x} \right) \mathbf{j} + \left(\frac{\partial F_2}{\partial x} - \frac{\partial F_1}{\partial y} \right) \mathbf{k}$$

$$\begin{aligned}\nabla(\phi\psi) &= \phi\nabla\psi + \psi\nabla\phi \\ \nabla \cdot (\phi F) &= (\nabla\phi) \cdot F + \phi(\nabla \cdot F) \\ \nabla \times (\phi F) &= (\nabla\phi) \times F + \phi(\nabla \times F) \\ \nabla \times (\nabla\phi) &= 0\end{aligned}$$

$$\begin{aligned}\nabla \cdot (F \times G) &= (\nabla \times F) \cdot G - F \cdot (\nabla \times G) \\ \nabla \times (F \times G) &= F(\nabla \cdot G) - G(\nabla \cdot F) - (F \cdot \nabla)G + (G \cdot \nabla)F \\ \nabla(F \cdot G) &= F \times (\nabla \times G) + G \times (\nabla \times F) + (F \cdot \nabla)G + (G \cdot \nabla)F \\ \nabla \cdot (\nabla \times F) &= 0\end{aligned}$$

$$\nabla^2 \phi(x, y, z) = \nabla \cdot \nabla \phi(x, y, z) = \frac{\partial^2 \phi}{\partial x^2} + \frac{\partial^2 \phi}{\partial y^2} + \frac{\partial^2 \phi}{\partial z^2}$$

$$\nabla \times (\nabla \times F) = \nabla(\nabla \cdot F) - \nabla^2 F$$

VARIANTEN FUNDAMENTELE STELLING VAN CALCULUS

1 dimensie

$$\int_a^b f'(t) dt = f(b) - f(a)$$

$$\int_C \nabla \phi \cdot d\mathbf{r} = \phi(\mathbf{r}(a)) \text{ als } C \text{ de kromme } \mathbf{r} = \mathbf{r}(t) \text{ is, met } a \leq t \leq b$$

Theorema van Green

$$\begin{aligned}\iint_R \left(\frac{\partial F_2}{\partial x} - \frac{\partial F_1}{\partial y} \right) dA &= \oint_C \mathbf{F} \cdot d\mathbf{r} \\ &= \oint_C F_1(x, y) + F_2(x, y) dy \\ &\text{waarbij } C \text{ de positieve grens is van } R\end{aligned}$$

Theorema van Stokes

$$\begin{aligned}\iint_S \nabla \times \mathbf{F} \cdot \hat{\mathbf{N}} dS &= \oint_C \mathbf{F} \cdot d\mathbf{r} \\ &= \oint_C F_1(x, y, z) dx + F_2(x, y, z) dy + F_3(x, y, z) dz \\ &\text{waarbij } C \text{ de georiënteerde grens is van } S\end{aligned}$$

3D varianten

Divergentie theorema

$$\begin{aligned}\iiint_D \nabla \cdot \mathbf{F} dV &= \oiint_S \mathbf{F} \cdot \hat{\mathbf{N}} dS \\ \iiint_D \nabla \phi dV &= \oiint_S \phi \hat{\mathbf{N}} dS \\ \iiint_D \nabla \times \mathbf{F} dV &= - \oiint_S \mathbf{F} \times \hat{\mathbf{N}} dS\end{aligned}$$

FORMULES OVER KROMMEN IN DRIEDIMENSIONALE RUIMTE

Kromme: $\mathbf{r} = \mathbf{r}(t) = x(t)\mathbf{i} + y(t)\mathbf{j} + z(t)\mathbf{k}$

Velociteit: $\mathbf{v} = \frac{d\mathbf{r}}{dt} = v\hat{\mathbf{T}}$

Snelheid: $v = |\mathbf{v}| = \frac{ds}{dt}$

Booglengte: $s = \int_{t_0}^t v dt$

Versnelling: $\mathbf{a} = \frac{d\mathbf{v}}{dt} = \frac{d^2\mathbf{r}}{dt^2}$

Tangentiele componenten: $\mathbf{a} = \frac{dv}{dt}\hat{\mathbf{T}}$

Unit tangent: $\hat{\mathbf{T}} = \frac{\mathbf{v}}{v}$

Binormaal: $\hat{\mathbf{B}} = \frac{\mathbf{v} \times \mathbf{a}}{|\mathbf{v} \times \mathbf{a}|}$

Normaal: $\hat{\mathbf{N}} = \hat{\mathbf{B}} \times \hat{\mathbf{T}} = \frac{d\hat{\mathbf{T}}/dt}{|d\hat{\mathbf{T}}/dt|}$

Kromming: $\kappa = \frac{|\mathbf{v} \times \mathbf{a}|}{v^3}$

Kromtegraad: $\rho = \frac{1}{\kappa}$

Torsie $\tau = \frac{(\mathbf{v} \times \mathbf{a}) \cdot (d\mathbf{a}/dt)}{|\mathbf{v} \times \mathbf{a}|^2}$

Frenet-Serret formules

$$\frac{d\hat{\mathbf{T}}}{ds} = \kappa\hat{\mathbf{N}}$$

$$\frac{d\hat{\mathbf{N}}}{ds} = -\kappa\hat{\mathbf{T}} + \tau\hat{\mathbf{B}}$$

$$\frac{d\hat{\mathbf{B}}}{ds} = -\tau\hat{\mathbf{N}}$$