

On Subsample Size of Quantile-Based Randomized Kaczmarz

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Outline

- ① Motivation and Setup
- ② Main Results
- ③ Proof Overview
- ④ Numerical Example

Motivation and Setup

Corrupted linear systems.

- Large linear systems arise in scientific computing, ML, imaging.
- In practice, some measurements are **arbitrarily corrupted** (sensor failures, transmission errors, adversarial attacks ...).

Sparse corruption model.

$$\underbrace{\mathbf{A}}_{\substack{\mathbb{R}^{m \times n} \\ \text{(known)}}} \underbrace{\mathbf{x}^*}_{\substack{\text{to be} \\ \text{exactly} \\ \text{recovered}}} + \underbrace{\boldsymbol{\epsilon}}_{\substack{\beta m\text{-sparse} \\ \text{corruption} \\ 0 < \beta < c}} = \underbrace{\mathbf{b}}_{\substack{\text{corrupted} \\ \text{observations}}} .$$

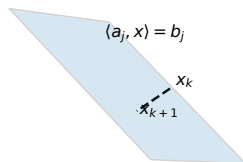
- In highly over-determined case $m \gg n$: we hope to access one or only a few measurements in each iteration

From RK to QuantileRK

Randomized Kaczmarz (RK) for solving $\mathbf{Ax} = \mathbf{b}$

- Uses one row per iteration

$$\mathbf{x}_{k+1} = \mathbf{x}_k - \frac{\langle \mathbf{a}_j, \mathbf{x}_k \rangle - b_j}{\|\mathbf{a}_j\|^2} \mathbf{a}_j \quad \text{for some randomly chosen } j$$



- (Strohmer and Vershynin, 2009): linear convergence for consistent systems.
- Noisy linear system $\mathbf{Ax} + \underbrace{\boldsymbol{\epsilon}}_{\text{noise vector}} = \mathbf{b}$: converges only to an error depending on noise level (Needell, 2010).
- Corrupted linear system: one bad row can destroy convergence

QuantileRK (QRK) for solving $\mathbf{Ax} + \epsilon = \mathbf{b}$ (Haddock et al., 2022)

- Idea: use residual quantiles to avoid corrupted rows.
- The q -quantile of a *multi-set* $\{z_1, z_2, \dots, z_N\}$ is defined as $z_{[qN]}^*$, where we let

$$z_1^* \leq z_2^* \leq \dots \leq z_N^*$$

be the non-decreasing rearrangement of the N elements.

- At iteration k , compute the quantile of $\{|\mathbf{a}_i^\top \mathbf{x}_k - b_i| : i \in [m]\}$.
- Only update if the chosen row has residual below this quantile.

Quantile RK Algorithm

We assume the rows of \mathbf{A} are iid uniformly distributed over S^{n-1}

QuantileRK(q) (Haddock et al., 2022)

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1: Input:  $A, b, x_0, q \in (0, 1)$ , quantile subsample size  $D$ , iteration number  $T$ 
2: for  $k = 0$  to  $T - 1$  do
3:   Sample  $i_1^{(k+1)}, \dots, i_D^{(k+1)} \sim \text{Uniform}(1, \dots, m) \rightarrow$  quantile subsample
4:   Compute  $Q := q\text{-quantile}\left(\left\{\left|\mathbf{a}_{i_j^{(k+1)}}^\top \mathbf{x}_k - b_{i_j^{(k+1)}}\right|\right\}_{j=1}^D\right)$ 
5:   Sample  $r_{k+1} \sim \text{Uniform}(1, \dots, m) \rightarrow$  update sample
6:   Compute  $h_{r_{k+1}} := \mathbf{a}_{r_{k+1}}^\top \mathbf{x}_k - b_{r_{k+1}}$ 
7:   if  $|h_{r_{k+1}}| \leq Q$  then
8:      $\mathbf{x}_{k+1} \leftarrow \mathbf{x}_k - h_{r_{k+1}} \mathbf{a}_{r_{k+1}} \rightarrow$  accept & update
9:   else
10:     $\mathbf{x}_{k+1} \leftarrow \mathbf{x}_k \rightarrow$  reject
11:  end if
12: end for
13: Output:  $\mathbf{x}_T$ 
```

Main Results

Main Question

Gap in the literature:

- **Theory:** quantile computed from all m rows every iteration.
- **Practice:** quantile computed from a small subsample $D \ll m$.

How large the subsample size D need to be to guarantee linear convergence of the first T iterations of QRK?

Main Theorems: Upper and Lower Bounds

Upper bound (sufficiency).

If $D \geq C \frac{\log T}{\log(1/\beta)}$, then with high probability

$$\|\mathbf{x}_T - \mathbf{x}^*\|^2 \leq \left(1 - \frac{c}{n}\right)^T \|\mathbf{x}_0 - \mathbf{x}^*\|^2.$$

Lower bound (necessity).

If $D \leq c \frac{\log T}{\log(1/\beta)}$, then there exists (βm) -sparse corruption such that $\|\mathbf{x}_T - \mathbf{x}^*\|$ is arbitrarily large

Conclusion. $D \asymp \frac{\log T}{\log(1/\beta)}$ is the *minimal* subsample size, up to constant.

Implication (β is a small constant)

$D \asymp \frac{\log T}{\log(1/\beta)}$ is the *minimal* subsample size

Setting 1: β is a small constant

- $D = O(\log T)$ is minimal
- $\|\mathbf{x}_T - \mathbf{x}^*\|^2 \leq (1 - \frac{\epsilon}{n})^T \|\mathbf{x}_0 - \mathbf{x}^*\|^2$
 $\implies T \asymp n \log(1/\epsilon)$ to achieve approximation error $\epsilon \|\mathbf{x}_0 - \mathbf{x}^*\|_2^2$
 \implies
$$D = O(\log n + \log \log \epsilon^{-1}) \stackrel{\epsilon \geq \exp(-n)}{=} O(\log n)$$
- Previous theory:
 - $D = m$ (Haddock et al., 2022; Steinerberger, 2023)
 - $D = \alpha m$ with $\alpha \geq 2\beta$ (Haddock et al., 2023)
- We achieve massive reduction: $\Theta(m) \longrightarrow O(\log n)$

Implication ($\beta = o(1)$)

$D \asymp \frac{\log T}{\log(1/\beta)}$ is the *minimal* subsample size

Setting 2: $\beta = o(1)$

- The subsample size can be further reduced by a factor of $\frac{1}{\log(1/\beta)}!$
- (Sublinear number of corruptions) If

$$\beta = \Theta(m^{-\xi}), \quad \text{for some } \xi \in (0, 1),$$

together with $\varepsilon \geq \exp(-n)$, then we can use

$$D = O\left(\frac{\log n}{\xi \log m}\right) = O\left(\frac{1}{\xi}\right)$$

Proof Overview

Preliminary: Chernoff Bound

- Tight Chernoff bounds for binomial variable

$$\mathbb{P}(\text{Bin}(N, q) \leq k) \leq \exp\left(-N \cdot D_{KL}\left(\frac{k}{N} \| q\right)\right), \quad k \leq Nq$$

$$\mathbb{P}(\text{Bin}(N, q) \geq k) \leq \exp\left(-N \cdot D_{KL}\left(\frac{k}{N} \| q\right)\right), \quad k \geq Nq$$

where $D_{KL}(p \| q) = p \log \frac{p}{q} + (1 - p) \log \frac{1-p}{1-q}$

- We cannot capture $O(\frac{1}{\log(1/\beta)})$ if we stick with the weakened Chernoff bound in Haddock et al. (2022):

$$\mathbb{P}(\text{Bin}(N, q) \geq (1 + \delta)Nq) \leq \exp\left(-\frac{\delta^2 Nq}{3}\right), \quad \forall \delta \in (0, 1)$$

Preliminary: Quantiles

- Runtime quantile:

$$Q_q(\mathbf{x}, S) = q\text{-quantile of } \{|b_i - \langle \mathbf{a}_i, \mathbf{x} \rangle| : i \in S\}.$$

- Ideal quantile: $(b_i \rightarrow \langle \mathbf{a}_i, \mathbf{x}^* \rangle)$

$$\tilde{Q}_q(\mathbf{x}) = q\text{-quantile of } \{|\langle \mathbf{x} - \mathbf{x}^*, \mathbf{a}_i \rangle| : i \in [m]\}.$$

which satisfies

$$\tilde{Q}_q(\mathbf{x}) \leq \frac{\sigma_{\max}(\mathbf{A}) \|\mathbf{x} - \mathbf{x}^*\|}{\sqrt{(1-q)m}}$$

Proof Overview (Upper Bound)

1. By Markov's inequality, for $\mathbb{P}(\Omega) \leq \epsilon$,

$$\mathbb{E}\left(\|\mathbf{x}_T - \mathbf{x}^*\|^2 \mathbf{1}_{\Omega^c}\right) \leq \left(1 - \frac{c}{n}\right)^T \|\mathbf{x}_0 - \mathbf{x}^*\|^2 \quad (3.1)$$

$$\implies \|\mathbf{x}_T - \mathbf{x}^*\|^2 \leq \left(1 - \frac{c'}{n}\right)^T \|\mathbf{x}_0 - \mathbf{x}^*\|^2, \quad \text{w.h.p.} \quad (3.2)$$

Question: How to choose the failure event Ω ?

2. Upper bound on quantile is important to control the worst case, but it does not arbitrarily if $D \ll \beta m$
(possibility of $i_1, \dots, i_D \in B$)

3. Fortunately, we can prove for one step that

$$\mathbb{P}\left(\underbrace{Q_q(\mathbf{x}_k, \{i_j^{(k+1)}\}_{j=1}^D) \leq \tilde{Q}_{q+\beta+\epsilon}(\mathbf{x}_k)}_{\substack{:= S_{k+1} \\ \text{(quantile being upper bounded)}}}\right) \geq 1 - \exp(-D \cdot D_{KL}(q \| q + \epsilon))$$

Proof Overview (Upper Bound)

4. We work with $\Omega := \{\mathcal{S}_{k+1} \text{ fails for some } 0 \leq k \leq T-1\}$ satisfying

$$\mathbb{P}(\Omega) \leq T \exp(-D \cdot D_{KL}(q \| q + \epsilon)) \quad (3.3)$$

$$\leq \epsilon \quad (\text{so long as } D \text{ is suitably large}) \quad (3.4)$$

5. A stopping time argument (Tan and Vershynin, 2019) shows

$$\mathbb{E}[\|\mathbf{x}_{k+1} - \mathbf{x}\|^2 \mathbf{1}_{\mathcal{S}_{k+1}}] \leq (1 - \frac{c}{n}) \|\mathbf{x}_k - \mathbf{x}^*\|^2 \quad (3.5)$$

$$\implies \mathbb{E}(\|\mathbf{x}_T - \mathbf{x}^*\|^2 \mathbf{1}_{\Omega^c}) \leq (1 - \frac{c}{n})^T \|\mathbf{x}_0 - \mathbf{x}^*\|^2$$

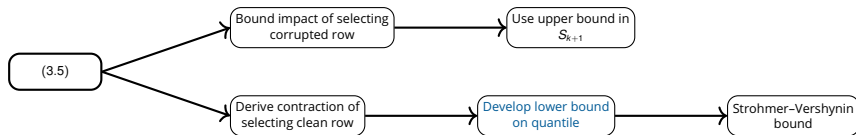
Proof Overview (Upper Bound)

6. We discuss if the update sample r_{k+1} is corrupted or not:

$$\mathbb{E}[\|\mathbf{x}_{k+1} - \mathbf{x}\|^2 1_{S_{k+1}}] = \overbrace{\beta \cdot \mathbb{E}[\|\mathbf{x}_{k+1} - \mathbf{x}\|^2 1_{S_{k+1}} | r_{k+1} \in B]}^{\text{select corrupted row}} \quad (3.6)$$

$$+ \underbrace{(1 - \beta) \mathbb{E}[\|\mathbf{x}_{k+1} - \mathbf{x}\|^2 1_{S_{k+1}} | r_{k+1} \in B^c]}_{\text{select clean row}} \quad (3.7)$$

=



$$\mathbb{P}\left(Q_q(\mathbf{x}_k, \{i_j^{(k+1)}\}_{j=1}^D) \geq \tilde{Q}_{q-\beta-\epsilon}(\mathbf{x}_k)\right) \geq 1 - \exp(-D_{KL}(q||q + \epsilon) \cdot D)$$

Proof Overview (Lower Bound)

1. Key idea: A bad step — which projects the iterate onto a corrupted row — makes the error arbitrarily large. Formally,

$$\|\mathbf{x}_{k,\text{bad}} - \mathbf{x}^*\| \geq \min_{i \in B} |\epsilon_i| \quad (3.8)$$

2. Lower bounding the prob. of a bad step:

$$\mathbb{P}(\text{Bad step}) \geq \mathbb{P}\left(i_1, \dots, i_D \in B^*, \substack{r \in B_*}\right) \geq \left(\frac{\beta}{2}\right)^{D+1} \quad (3.9)$$

(Argument: Equally divide $B = B^* \cup B_*$ such that residuals of B^* are uniformly higher than those of B_*)

3. Brief outline:

Find the last bad step
in first T iterations

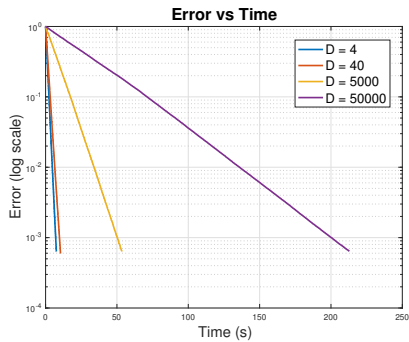
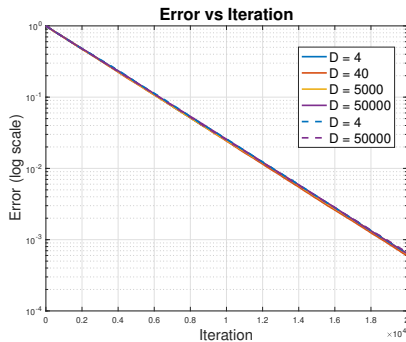
→ Show the remaining steps
cannot reduce error too much

Numerical Example

Effect of Subsample Size D

Experiment. ($m = 50000$, $n = 100$, $T = 20000$, $\beta = 0.01$)

- Compare $D \in \{4, 40, 5000, 50000\}$.



- Similar convergence rate & much faster

“On Subsample Size of Quantile-Based Randomized Kaczmarz”

Available on arXiv: <https://arxiv.org/abs/2507.15185>

Under revision at SIAM Journal on Matrix Analysis and Applications

Thank You!

Questions?

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