

a)

```
function sol =cond_Hil_rand(n)

    R=rand(n);

    H=hilb(n);

    sol=[cond(R), cond(H)];

end
```

```
A=rand(4);
```

```
A=0.276922984960890  0.694828622975817  0.438744359656398  0.186872604554379
    0.046171390631154  0.317099480060861  0.381558457093008  0.489764395788231
    0.097131781235848  0.950222048838355  0.765516788149002  0.445586200710899
    0.823457828327293  0.0344446080502909  0.795199901137063  0.646313010111265
```

| n | Random matrix | Hilbert matrix |
|---|---------------|-------------------|
| 1 | 1 | 1 |
| 2 | 9.1 | 19.3 |
| 3 | 5.2 | $5.24 \cdot 10^2$ |
| 4 | 20.66 | $1.55 \cdot 10^4$ |

We can say that Hilbert matrices are likely to be ill-conditioned matrices as condition number is growing rapidly. However, for a random matrix, the condition number is really random.

b)

```
A=hilb(4);
```

```
[evec,eval]=eig(A**A)
```

```
evec =
```

```
    0.029193323163918    0.179186290535595   -0.582075699497238    0.792608291163764
   -0.328712055759592   -0.741917790630046    0.370502185067095    0.451923120901600
    0.791411145832639    0.100228136951032    0.509578634501801    0.322416398581825
   -0.514552750000250    0.638282528191121    0.514048272222161    0.252161169688242
```

```
norm(A*evec(:,1))/norm(evec(:,1))
```

```
ans = 9.670230402259483e-05
```

```
norm(A*evec(:,2))/norm(evec(:,2))
```

```
ans = 0.006738273605761
```

```
norm(A*evec(:,3))/norm(evec(:,3))
```

```
ans = 0.169141220221450
```

```
norm(A*evec(:,4))/norm(evec(:,4))
```

```
ans = 1.500214280059243
```

```
cond(A) = 1.551373873892814e+04
```

```
%norm(A*evec(:,1))/norm(evec(:,1)) = 9.670230402259483e-05
```

```
A=[1,0,1,2;2,2,3,1;4,3,2,3;7,3,4,1];
```

```
norm(A*evec(:,1))/norm(evec(:,1))
```

```
ans = 1.165044286012182
```

```
norm(A*evec(:,2))/norm(evec(:,2))
```

```
ans = 1.614314212558824
```

```
norm(A*evec(:,3))/norm(evec(:,3))
```

```
ans = 2.602514361419407
```

```
norm(A*evec(:,4))/norm(evec(:,4))
```

```
ans = 11.236706832224760
```

```
cond(A)=9.64
```

```
%norm(A*evec(:,4))/norm(evec(:,4))=11.236706832224760
```

Using eigenvectors of A^*A can be a good approximation of finding condition number for the well-conditioned matrix but not for ill-conditioned matrix.

c)

```
A=hilb(4);
```

```
[Q,R]=qr(A);
```

```
cond(Q)*cond(R)/cond(A)=1.000000000000013
```

```
Q =
```

```
-0.838116354923494  0.522648373955656 -0.153972761515708 -0.026306682088232
```

```
-0.419058177461747 -0.441713323920529  0.727753807365351  0.315680185058791
```

```
-0.279372118307831 -0.528821386246471 -0.139505522178664 -0.789200462646984
```

```
-0.209529088730873 -0.502071666319607 -0.653609205762985  0.526133641764659
```

```
R =
```

```
-1.193151755273030 -0.670493083938795 -0.474932601123313 -0.369835470902748
```

0 -0.118533267487887 -0.125655094630809 -0.117541992762881

0 0 -0.006221774060129 -0.009566092949394

0 0 0 0.000187904872059

A =

1.000000000000000 0.500000000000000 0.333333333333333 0.250000000000000

0.500000000000000 0.333333333333333 0.250000000000000 0.200000000000000

0.333333333333333 0.250000000000000 0.200000000000000 0.166666666666667

0.250000000000000 0.200000000000000 0.166666666666667 0.142857142857143

A=hilb(3);

[Q,R]=qr(A);

cond(Q)*cond(R)/cond(A)=0.999999999999999

A=hilb(2);

[Q,R]=qr(A);

cond(Q)*cond(R)/cond(A)= 1

A=hilb(1);

[Q,R]=qr(A);

cond(Q)*cond(R)/cond(A)= 1

We know that stability is not determined by the condition of A. Since in theory, QR factorization guarantees good stability we can assume that the stability ratio should be close to 1 for all cases above. As we can see, even if we use an ill-conditioned matrix, the above results are close to one.

d)

A =

0.276922984960890 0.694828622975817 0.438744359656398 0.186872604554379

0.046171390631154 0.317099480060861 0.381558457093008 0.489764395788231

0.097131781235848 0.950222048838355 0.765516788149002 0.445586200710899

0.823457828327293 0.0344446080502909 0.795199901137063 0.646313010111265

cond(A)=20.6

[evec,eval]=eig(A'*A)

evec =

```
0.334676075239744 -0.643619658255031 0.599487644869025 0.338171885021787
0.297553923343812 -0.272165609215882 -0.752249872658138 0.521063981626698
-0.758544601226644 0.054355773206988 0.122060286567955 0.637774900973636
0.473353647197038 0.713249652356659 0.244613939051220 0.455384759209411
```

norm(A*evec(:,4))/norm(evec(:,4))= 1.945232608679346

b=A*evec(:,4)

b =

```
0.820616813226491
0.647222632489595
1.219114280226397
1.097898530585030
```

[Q,R]=qr(A);

y=Q\b;

x=R\y

x =

```
0.338171885021787
0.521063981626699
0.637774900973635
0.455384759209412
```

evec(:,4)-x

ans =

```
1.0e-14 *
-0.077715611723761
-0.077715611723761
0.122124532708767
-0.083266726846887
```

The error is very small as A is a well-conditioned matrix.

<ill-condition matrix>

```

A=hilb(4);

b=evec(:,2);

y=Q\b;

x=R\y

x =

    1.0e+02 *

    0.265923144456661

   -1.101050260270333

    0.148744534696545

    0.947249348073386

evec(:,2)-x

ans =

    1.0e+02 *

   -0.264131281551305

    1.093631082364033

   -0.147742253327035

   -0.940866522791474

```

The error is much larger than the well-conditioned matrix case. We found that solving equations using QR factorization is very stable in question c. So the error should really depend on the condition of the matrix. From question a) we know that the first matrix A is well-conditioned so the error should be very small. Second A is ill-conditioned so an error is likely to be large.

