```
function s=Hermite(A,n)
 coefs=zeros(n-1,4);
 for i=1:n-1
    x0=A(1,i);
    x1=A(1,i+1);
    y0=A(2,i);
    y1=A(2,i+1);
    dy0=A(3,i);
    dy1=A(3,i+1);
    coefs(i,:) = Divided\_diff(x0,x1,y0,y1,dy0,dy1);
  end
 s=mkpp(A(1,:),coefs);
end
function coef=Divided_diff(x0,x1,y0,y1,dy0,dy1)
 x=[x0,x0,x1,x1];
 y=[y0,y0,y1,y1];
 ydiff=[dy0,dy1];\\
  n=4;
  table=zeros(n,n);
 table(:,1)=y(:);
  cnt=1;
  for j=2:n
    for i=1:n-j+1
       if(x(i+j-1)==x(i))
          table(i,j) = ydiff(1,cnt);\\
          cnt=cnt+1;
       else
          table(i,j) \hspace{-0.5mm}=\hspace{-0.5mm} (table(i+1,j-1)-table(i,j-1))/(x(i+j-1)-x(i));
```

```
end
```

```
end
```

end

```
coef=[table(1,1),table(1,2),table(1,3),table(1,4)];
 coef = flip(coef);
 coef(1,2) = coef(1,2) - (coef(1,1)*(x1-x0));
end
B)
%settings
f=@(x)exp(x-5);
g=@(x) \sin(x);
h=@(x) log(x-3);
k=@(x)abs(x-5).^(3/2);
a=4; b=6; t=linspace(4,6);
%function f
n=3;
X=linspace(a,b,n);
Y=f(X);
A=[X;Y;Y];
s=Hermite(A,n);
table =
 0.367879441171442 \quad 0.367879441171442 \quad 0.264241117657115 \quad 0.103638323514327
 0.367879441171442  0.632120558828558  0.367879441171442
 1.0000000000000 1.00000000000 0 0
 1.00000000000000 0 0
                                         0
table =
```

 $1.00000000000000 \quad 1.0000000000000 \quad 0.718281828459045 \quad 0.281718171540955$

,

 $\max(abs(ppval(s,t)-f(t))) = 0.004370746538173$

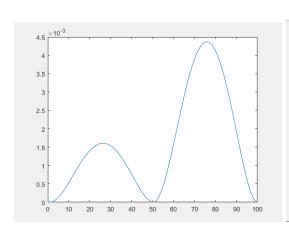
mean(abs(ppval(s,t)-f(t))) = 0.001578365909698

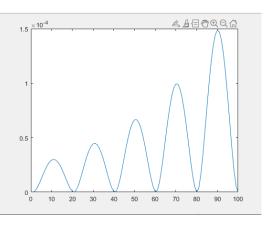
% now n=6 points,5 interval

max(abs(ppval(s,t)-f(t))) = 1.486750864114761e-04

mean(abs(ppval(s,t)-f(t))) = 4.121030630701017e-05

Error functions





Observation: As the number of interval goes from 2 to 5 the error gets smaller.

%function g

n=3;

X=linspace(a,b,n);

Y=g(X);

dY=cos(X);

A=[X;Y;dY];

s=Hermite(A,n);

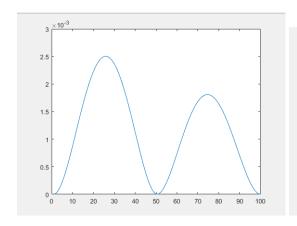
 $\max(abs(ppval(s,t)-g(t))) = 0.002503541715719$

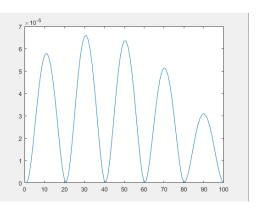
mean(abs(ppval(s,t)-g(t))) = 0.001136591190992

%Now with n=6

max(abs(ppval(s,t)-g(t))) = 6.595726378433309e-05

Error functions





Observation: The error got smaller as n increased.

%function h

n=3;

X=linspace(a,b,n);

Y=h(X);

dY= 1./(X-3);

A=[X;Y;dY];

s=Hermite(A,n);

 $\max(\mathsf{abs}(\mathsf{ppval}(\mathsf{s}, t) \text{-} \mathsf{h}(t))) = 0.003641976248656$

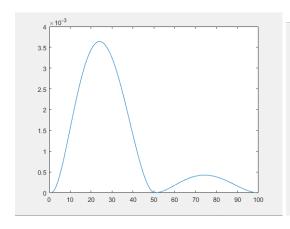
mean(abs(ppval(s,t)-h(t))) = 0.001075147047493

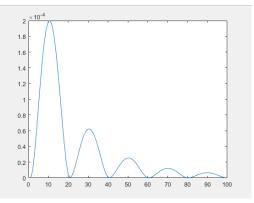
%Now with n=6

 $\max(abs(ppval(s,t)-h(t))) = 1.999649170678075e-04$

mean(abs(ppval(s,t)-h(t))) = 3.245452420306480e-05

Error functions





Observation: The error got smaller as n increased.

% function k

dk = @(t)(3*(t-5))/(2*sqrt(abs(t-5)));

n=3;

X=linspace(a,b,n);

Y=k(X);

dY= [-1.5,0,1.5]; %approx

A=[X;Y;dY];

s=Hermite(A,n);

max(abs(ppval(s,t)-k(t))) = 0.045063155139943

mean(abs(ppval(s,t)-k(t)))=0.024750944910461

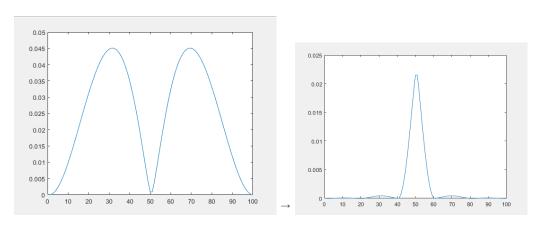
%now n=6

dY= [-1.5, -1.162,-0.671, 0.671,1.162,1.5]; %approx

 $\max(abs(ppval(s,t)-k(t))) = 0.021498685392098$

mean(abs(ppval(s,t)-k(t))) = 0.001872700152697

Error functions



Observation: The error got smaller as n increased.

In theory, when we use cubic Hermite interpolation, regardless of what function we are interpolating, it should converge. It is because the error formula is 5/384*max(f''')[a,b]*h^4 and h always gets smaller when the number of interval increases. As we can see above when n increased the error got smaller for all 4 functions, So **convergence is quite certain.** If we compare with HW5's results, cubic Hermite interpolation has lower errors than cubic spline interpolation. However, since Hermite interpolation requires derivates for each interval, the cost is more expensive.