

Signals and Systems Project 1: Convolution

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About

This Jupyter Notebook details the code used for implementing the convolution specified in project document, and serves as a final submission file with answers to 3 different questions embedded in the sections organized below (each denoted with "Question X" style nomenclature).

It was a nice opportunity to get hands-on with the concept of convolution & learn the pitfalls & challenges of making it computationally effective, and gave me various foods for thought that I am still pondering about!

Signals definition

```
In [ ]: # Unit rect (rect)
def unit_rect(x):
    if abs(x) > 0.5:
        return 0.0
    elif abs(x) == 0.5:
        return 0.5
    else:
        return 1.0

# Half rect (rect(x/2))
def rect_x_2(x):
    return unit_rect(x/2.0)

# Unit step function
def unit_step(x):
    if x > 0.0:
        return 1.0
    else:
        return 0.0

# Unit step with offset 1 (u(x-1))
def unit_step_1(x):
    return unit_step(x-1)
```

Draw the functions (Question 1)

```
In [ ]: # Draw the functions
import matplotlib.pyplot as plt

x_range = [x/100.0 for x in range(-200, 301)]
```

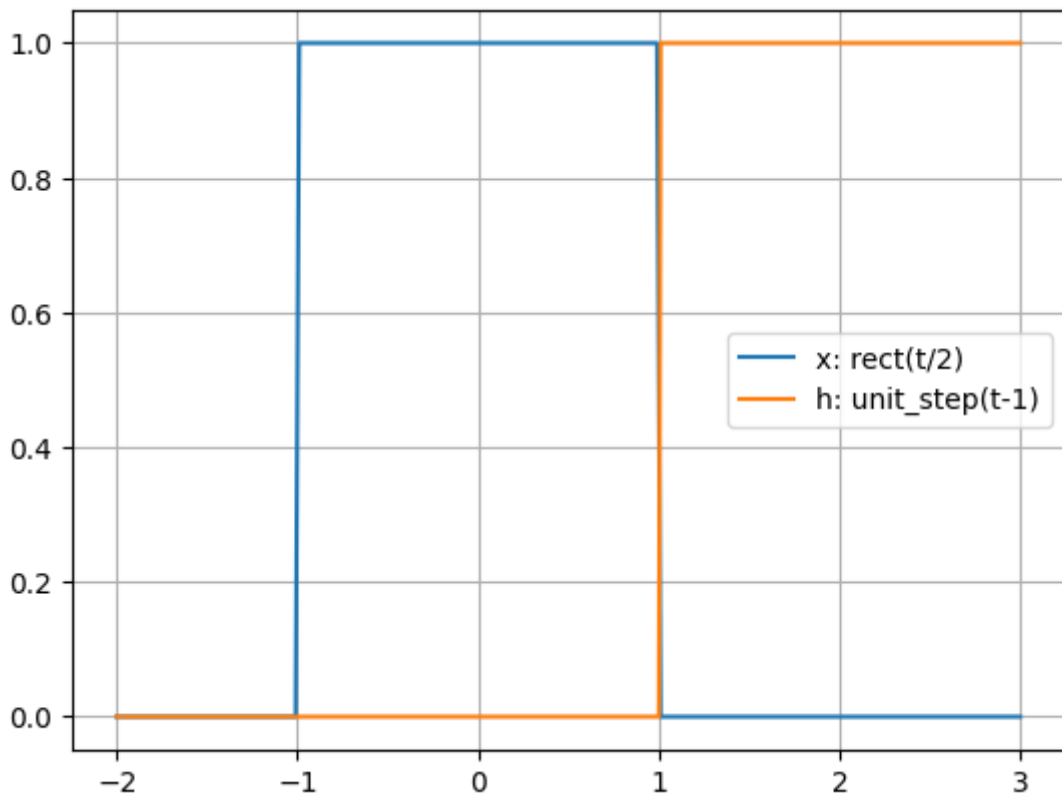
```

# Our x and h functions
x_func = rect_x_2
h_func = unit_step_1

# Draw those functions
x_values = list(map(x_func, x_range))
h_values = list(map(h_func, x_range))

plt.plot(x_range, x_values, label='x: rect(t/2)')
plt.plot(x_range, h_values, label='h: unit_step(t-1)')
plt.legend()
plt.grid()

```



Define Convolution

```

In [ ]: # Default range to include x values that results in non-zero value of the
        RANGE_DEFAULT = [-100.0, 100.0]

def convolve(f, g, x_range, dx = 0.01, f_nonzero_range = RANGE_DEFAULT, g
    ...
    Convolve two functions (f, g) and output the result in specified x_range.
    Result will be a list of numbers the length equal to x_range itself.

    dx = granularity of the variable x for the integration itself. By default
    is in a sane range of 0.01, assuming that functions are mostly rectangular
    unit step, etc, which doesn't change much within the range of dx, except
    at non-continuous boundaries

    NOTE:
    To make computation more efficient, we can optionally supply the nonzero
    functions (f, g) being convoluted. This provides a sensible `tau` range
    since without this limit, it can literally range from -inf to +inf, which
    computation (since it's not symbolic math at this point).

```

```

But to remove the need to integrate -inf to +inf, the arbitrary default
'''

# Uncomment to enable debugging
# DEBUG = True

result = [0] * len(x_range)

for x_idx in range(len(x_range)):
    t = x_range[x_idx]

    # tau range that results in non-zero value of f
    f_range = f_nonzero_range

    # tau range that results in non-zero (significant) value of g
    g_range = [t-g_nonzero_range[1], t-g_nonzero_range[0]]

    # Common tau range that results in both f and g resulting in non-zero
    tau_range = [max(f_range[0], g_range[0]), min(f_range[1], g_range[1])]

    # if DEBUG:
    #     print('x_range[{}]={} | Tau_range={}'.format(x_idx, x_range[x_idx], tau_range))

    if tau_range[0] >= tau_range[1]:
        # No valid tau range available (integral is 0)
        result[x_idx] = 0.0
    else:
        # Integral of f(tau) * g(t - tau). Discretized by unit of `dx`
        result[x_idx] = 0.0
        for tau_idx in range(int(tau_range[0]/dx), int(tau_range[1]/dx) + 1):
            tau = tau_idx * dx
            result[x_idx] += (f(tau) * g(t - tau)) * dx

return result

```

Execute Convolution (Question 2)

```

In [ ]: # Convolution test
import matplotlib.pyplot as plt

x_range = [x/100.0 for x in range(-200, 301)]

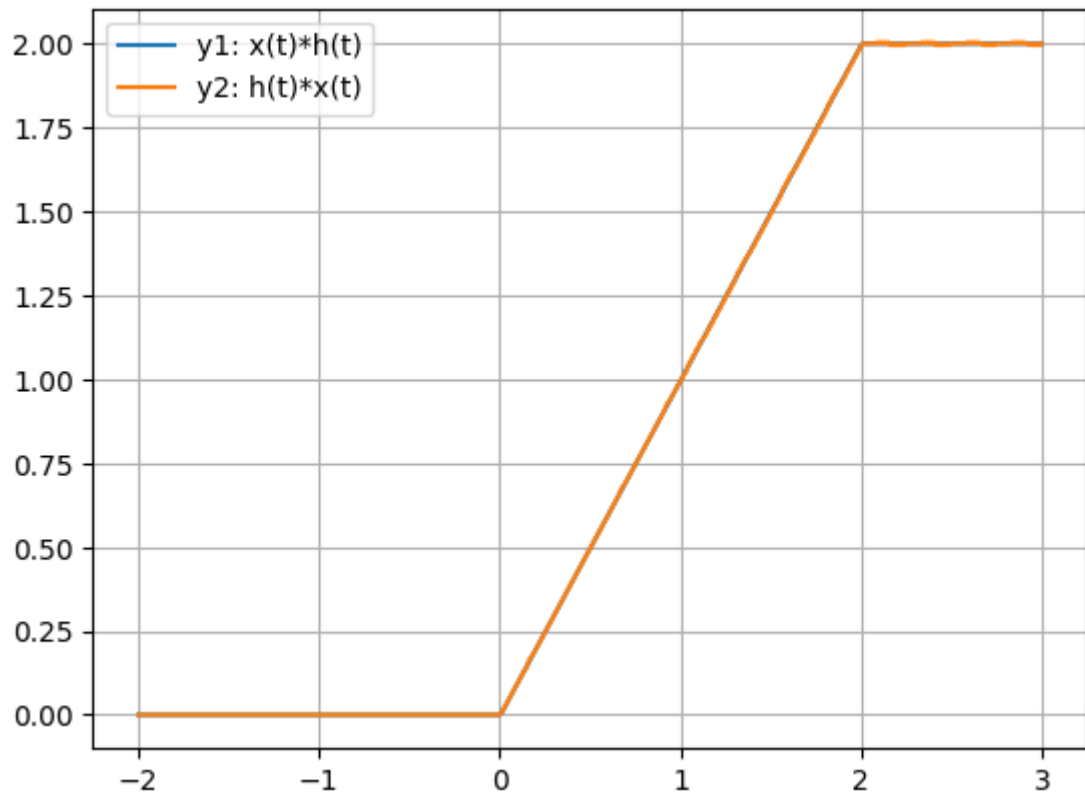
# Our x and h functions
x_func = rect_x_2
h_func = unit_step_1

# Convolve
y_one_values = convolve(x_func, h_func, x_range)
y_two_values = convolve(h_func, x_func, x_range)

# Plot
plt.plot(x_range, y_one_values, label='y1: x(t)*h(t)')
plt.plot(x_range, y_two_values, label='y2: h(t)*x(t)')

plt.legend()
plt.grid()

```



Is $Y_1(t)$ and $Y_2(t)$ the same? (Question 3)

It is. Because convolution by definition is commutative, meaning the order of the functions for the arguments doesn't matter: $\langle f, g \rangle = \langle g, f \rangle$.

Thought Experiment

This can be proven simply with a thought experiment: When we integrate $f(\tau)$ and $g(t-\tau)$, we are essentially integrating every single pair of t that sums up to the specified value t .

And it should be obvious that it doesn't matter whether we have f in the first or the second, as the resulting pair of t would stay the same for both f and g .

Also, put it simply, every single pair of $f(\tau)$ and $g(t-\tau)$ equals to: $f(t-(t-\tau))$ and $g(t-\tau)$, which means that regardless of the order of f and g function, the resulting pair matches 1 to 1 by just modulating the value of τ .

Resources

1. <https://scicoding.com/convolution-in-python-3-essential-packages/>
2. <https://en.wikipedia.org/wiki/Convolution>
3. https://en.wikipedia.org/wiki/Heaviside_step_function
4. https://en.wikipedia.org/wiki/Rectangular_function