## Topology II – Homework 2

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**Theorem 51.2** Give the complete proof of (ii) and (iii) of Theorem 51.2.

*Proof.* First two observations

- Suppose  $f \simeq_p g$  via homotopy  $H, f, g: I \to X$ . Let  $k: X \to Y$ . Then  $k \circ f \simeq_p k \circ g$  using  $k \circ H$ .
- If f \* g (not necessarily path homotopic). Then  $k \circ (f * g) = (k \circ f) * (k \circ g)$ .

Now, the proof

(ii) Take  $e_0: I \to I$  given by  $s \mapsto 0$ . Take  $i: I \to I$  given by  $s \mapsto s$ . Then  $e_0 * i$  is a path from 0 to  $1 \in I$ . The path i is also such a path. Because I is a convex subset,  $e_0 * i$  and i are path homotopic,  $e_0 * \simeq i$ . Using one of our observations, we find that

$$f \circ (e_0 * i) \simeq_p f \circ i$$
$$(f \circ e_0) * (f \circ i) \simeq_p f$$
$$e_{x_0} * f \simeq_p f.$$

Thus,  $[e_{x_0}] * [f] = [f]$ . An entirely similar argument, using  $i * e_1 \simeq_p i$  where  $e_1 : I \to I$  is taken by  $s \mapsto 1$ , shows that  $[f] * [e_{x_1}] = [f]$ .

(iii) Note that  $i * \bar{i} \simeq_p e_0$ . Now, applying the same rules, we get

$$f \circ (i * \overline{i}) \simeq_p f \circ e_0$$
  
 $f * \overline{f} \simeq_p e_{x_0}.$ 

Thus,  $[f] * [\overline{f}] = [e_{x_0}]$ .  $[\overline{f}] * [f] = [e_{x_1}]$  is similar.

**Exercise 51.1.** Show that if  $h, h': X \to Y$  are homotopic and  $k, k': Y \to Z$  are homotopic, then  $k \circ h$  and  $k' \circ h'$  are homotopic.

Proof. Let  $H: X \times I \to Y$  and  $K: Y \times I \to Z$  be homotopies between h, h' and k, k' respectively, i.e. H(x,0) = h(x), H(x,1) = h'(x), K(y,0) = k(y), and K(y,1) = k'(y). Then, define the map  $F: X \times I \to Z$  by F(x,t) = K(H(x,t),t). This is continuous and defines a homotopy between  $F(x,0) = K(H(x,0),0) = K(h(x),0) = k(h(x)) = k \circ h$  and  $F(x,1) = K(H(x,1),1) = K(h'(x),1) = k'(h'(x)) = k' \circ h'$ .

**Exercise 51.2.** Given spaces X and Y, let [X,Y] denote the set of homotopy classes of maps of X into Y.

- (a) Let I = [0, 1]. Show that for any X, the set [X, I] has a single element.
- (b) Show that if Y is path connected, the set [I, Y] has a single element.

*Proof.* To explain more about homotopy class, given two topological spaces X and Y, place an equivalence relation on the continuous maps  $f: X \to Y$  using homotopies, and write  $f_1 \sim f_2$  if  $f_1$  is homotopic to  $f_2$ .

- (a) We need to show that all continuous maps of X into I are homotopic to each other; we do this by showing that every continuous map  $f: X \to I$  is homotopic to the constant map  $f_0: X \to I$  defined by  $f_0(x) = 0$  for all  $x \in X$ . This is indeed the case, and an explicit homotopy is given by  $F: X \times I \to I$  defined by F(x,t) = tf(x), which is clearly continuous, and satisfies  $F(x,0) = 0 = f_0(x)$  and F(x,1) = f(x).
- (b) Assuming Y is path-connected, we need to show that any two continuous maps from I to Y are homotopic. First we show that every continuous map  $f\colon I\to Y$  is homotpic to the constant map  $I\to Y$  which maps every element of I to f(0). Indeed, consider  $F\colon I\times I\to Y$  given by F(s,t)=f(st), which is continuous. This is a homotopy between the constant map F(s,0)=f(0) and F(s,1)=f(s). (In other terms: we have shown that every path in Y can be homotoped (not fixing the end points) to the constant path at its starting point).

Next, given two points  $y, y' \in Y$ , let  $f, f' \colon I \to Y$  be the constant maps taking the values f(s) = y and  $f'(s) = y' \, \forall s \in I$ . Since Y is path-connected, there exists a path  $g \colon I \to Y$  such that g(0) = y and g(1) = y'. We then consider the map  $F \colon I \times I \to Y$  defined by F(s,t) = g(t), which gives a homotopy between F(s,0) = g(0) = y = f(s) and F(s,1) = g(1) = y' = f'(s). Thus, any path is homotopic to a constant path, and any two constant paths are homotopic to each other (again, not fixing the end points); it follows that any two maps  $I \to Y$  are homotopic.

**Exercise 51.3.** A space X is said to be contractible if the identity map  $i_X \colon X \to X$  is null-homotopic.

- (a) Show that I and  $\mathbb{R}$  are contractible.
- (b) Show that a contractible space is path connected.
- (c) Show that if Y is contractible, then for any X, the set [X,Y] has a single element.
- (d) Show that if X is contractible and Y is path connected, then [X,Y] has a single element.
- *Proof.* (a) Let  $F: I \times I \to I$  be defined by F(s,t) = st and  $G: \mathbb{R} \times I \to \mathbb{R}$  by G(s,t) = st. These are homotopies between the constant map at 0 and identity map, so both spaces are contractible.

- (b) Recall that if there is a path between a, b and a path between b, c, then there is a path between a, c. It therefore suffices to show that all points can be connected to a given point by a path. Assuming X is contractible, there is a homotopy  $F \colon X \times I \to X$  between identity map  $\mathrm{id}_X$  and the constant map  $f_0$  mapping every point  $x \in X$  to the same point  $x_0 \in X$  s.t.  $F(x,0) = f_0(x) = x_0$  and  $F(x,1) = \mathrm{id}_X(x) = x$  for all  $x \in X$ . Then, the map  $g \colon I \to X$  defined by g(t) = F(x,t) is continuous and determines a path from  $g(0) = x_0$  to g(1) = x.
- (c) Assume Y is contractible, and let  $F: Y \times I \to Y$  be a homotopy s.t. F(y,1) = y is the identity map and  $F(y,0) = y_0 \in Y$  is a constant map sending every point to some point  $y_0 \in Y$ . Then given any map  $g: X \to Y$ , we consider  $G: X \times I \to Y$  defined by G(x,t) = F(g(x),t). This is continuous, and defines a homotopy between g and the constant map  $g_0$  which maps every point of X to  $y_0$ . Indeed, G(x,1) = F(g(x),1) = g(x), and  $G(x,0) = F(g(x),0) = y_0$ . It follows that every map from X to Y is homotopic to the constant map  $g_0$ , and hence that any two maps from X to Y are homotopic to each other.
- (d) Since X is contractible,  $\mathrm{id}_X$  is homotopic to a constant map  $g(x) = x_0$  by a homotopy  $G \colon X \times I \to X$  s.t.  $G(x,0) = x_0$ , G(x,1) = x for all  $x \in X$ . First we show that every continuous map  $f \colon X \to Y$  is homotopic to the constant map  $X \to Y$  which maps every element of X to  $f(x_0)$ . Indeed, define a continuous map  $F \colon X \times I \to Y$  by F(x,t) = f(G(x,t)). This is a homotopy between the constant map  $F(x,0) = f(G(x,0)) = f(x_0)$  and F(x,1) = f(G(x,1)) = f(x).

Next, we show that if Y is path connected then constant maps (sending every point of X to the same point of Y) are homotopic to each other. Indeed, given two points  $y_0, y_1 \in Y$ , let  $f_0, f_1 \colon X \to Y$  be the constant maps taking the values  $f_0(x) = y_0$  and  $f_1(x) = y_1$  for all  $x \in X$ . Since Y is path-connected, there exists a path  $g \colon I \to Y$  s.t.  $g(0) = y_0$  and  $g(1) = y_1$ . We then consider the map  $F \colon X \times I \to Y$  defined by F(x,t) = g(t), which gives a homotopy between  $F(x,0) = g(0) = y_0 = f_0(x)$  and  $F(x,1) = g(1) = y_1 = f_1(x)$ .

Thus, assuming X contractible and Y path-connected, any continuous map of X into Y is homotopic to a constant map, and any two constant maps are homotopic to each other. It follows that any two continuous maps from X to Y are homotopic to each other.