

## Lecture 4. Moving Average Models

MA model.

### 1. Properties

AR: present value with  $x_t = x_{t-1}, x_{t-2}, \dots$   
 MA: "  $x_t = \varepsilon_t, \varepsilon_{t-1}, \dots$

**Definition 1.1.** An **moving average** (MA) model of order  $q$  is defined by

$$x_t = \mu + \varepsilon_t + \theta_1 \varepsilon_{t-1} + \dots + \theta_q \varepsilon_{t-q} = \mu + \theta(L) \varepsilon_t,$$

where  $\theta(L) = 1 + \theta_1 L + \theta_2 L^2 + \dots + \theta_q L^q$  and  $\varepsilon_t \sim WN(0, \sigma_\varepsilon^2)$ .

- The MA model is “always” stationary because it is a linear combination of white noise errors that are stationary.

- For an MA( $q$ ) model, it shows that

$$\begin{aligned} E[x_t] &= E[\mu + \varepsilon_t + \theta_1 \varepsilon_{t-1} + \dots + \theta_q \varepsilon_{t-q}] \\ &\stackrel{\text{if } \theta_0 = 1}{=} \mu, \\ E[x_t + \theta_1 x_{t-1} + \theta_2 x_{t-2} + \dots + \theta_q x_{t-q}] &= \\ Var[x_t] &= Var[\mu + \varepsilon_t + \theta_1 \varepsilon_{t-1} + \dots + \theta_q \varepsilon_{t-q}] \\ &= Var[\varepsilon_t] + \theta_1^2 Var[\varepsilon_{t-1}] + \dots + \theta_q^2 Var[\varepsilon_{t-q}] \\ &= (1 + \theta_1^2 + \dots + \theta_q^2) \sigma_\varepsilon^2, \quad \text{Var}(\varepsilon_{t-1}) = \sigma_\varepsilon^2 \end{aligned}$$

and

$$\begin{aligned} \gamma_k &= E[(x_t - E[x_t])(x_{t-k} - E[x_{t-k}])] \\ &= E[(\varepsilon_t + \theta_1 \varepsilon_{t-1} + \dots + \theta_q \varepsilon_{t-q})(\varepsilon_{t-k} + \theta_1 \varepsilon_{t-1-k} + \dots + \theta_q \varepsilon_{t-q-k})] \\ &= \begin{cases} (\theta_k + \theta_{k+1}\theta_1 + \theta_{k+2}\theta_2 + \dots + \theta_q \theta_{q-k}) \sigma_\varepsilon^2 & \text{for } k = 1, 2, \dots, q \\ 0 & \text{for } k > q. \end{cases} \end{aligned}$$

**Remark 1.2.** For an MA( $q$ ) model, the  $k$ th order autocorrelation is given by

$$\rho_k = \begin{cases} \frac{\theta_k + \theta_{k+1}\theta_1 + \theta_{k+2}\theta_2 + \dots + \theta_q \theta_{q-k}}{1 + \theta_1^2 + \dots + \theta_q^2} & \text{for } k = 1, 2, \dots, q \\ 0 & \text{for } k > q. \end{cases}$$

Notice that the ACF cuts off at lag  $q$ . *and to collection of correlations*

If MA( $q$ )  $\rho_1, \rho_2, \rho_3 = ?$

$$\rho_4 = 0.4$$

**Example 1.3.** Consider an MA(1) process

$$x_t = \mu + \varepsilon_t + \theta_1 \varepsilon_{t-1},$$

$$\begin{aligned}
 x_t &= \mu + \varepsilon_t + \theta_1 \varepsilon_{t-1} + \dots + \theta_q \varepsilon_{t-q} \\
 &= \mu + \varepsilon_t + \theta_1 L \varepsilon_t + \dots + \theta_q L^q \varepsilon_t \\
 &= \mu + \varepsilon_t (1 + \theta_1 L + \dots + \theta_q L^q) \\
 &\quad \text{θ(L).}
 \end{aligned}$$

MA(1).

$$x_t = \mu + \varepsilon_t + \theta_1 \varepsilon_{t-1}$$

$$\begin{aligned}
 r_k &= E[(x_t - E[x_t])(x_{t-k} - E[x_{t-k}])] \\
 &= E[(\varepsilon_t + \theta_1 \varepsilon_{t-1})(\varepsilon_{t-k} + \theta_1 \varepsilon_{t-k-1})] \\
 &= E[\varepsilon_t \cdot \varepsilon_{t-k} + \theta_1 \varepsilon_t \varepsilon_{t-k-1} + \theta_1 \varepsilon_{t-1} \varepsilon_{t-k} + \theta_1^2 \varepsilon_{t-1} \varepsilon_{t-k-1}]
 \end{aligned}$$

$$k=1 \quad E[\theta_1 \varepsilon_{t-1}^2] = \theta_1 E[\varepsilon_{t-1}^2] = \theta_1 \sigma_e^2$$

$$\text{Var}(\varepsilon_{t-1}) = E[(\varepsilon_{t-1} - E[\varepsilon_{t-1}])^2] = E[\varepsilon_{t-1}^2]$$

$$k=2, k=3 \Rightarrow 0.$$

MA(2) process.

$$x_t = \mu + \epsilon_t + \theta_1 \epsilon_{t-1} + \theta_2 \epsilon_{t-2}$$

ACF : auto correlation Function.

$$E[x_t], \text{Var}[x_t], r_k, p_k$$

$$E[x_t] = E[\mu + \epsilon_t + \theta_1 \epsilon_{t-1} + \theta_2 \epsilon_{t-2}] = \mu$$

$$\begin{aligned}\text{Var}[x_t] &= \text{Var}[\mu + \epsilon_t + \theta_1 \epsilon_{t-1} + \theta_2 \epsilon_{t-2}] \\ &= \text{Var}[\epsilon_t] + \theta_1^2 \text{Var}[\epsilon_{t-1}] + \theta_2^2 \text{Var}[\epsilon_{t-2}] \\ &= (1 + \theta_1^2 + \theta_2^2) \sigma^2\end{aligned}$$

$$\begin{aligned}r_k &= \text{Cov}[x_t, x_{t-k}] \\ &= E[(x_t - \mu)(x_{t-k} - \mu)] \\ &= E[(\epsilon_t + \theta_1 \epsilon_{t-1} + \theta_2 \epsilon_{t-2})(\epsilon_{t-k} + \theta_1 \epsilon_{t-k-1} + \theta_2 \epsilon_{t-k-2})] \\ &= E[\cancel{\epsilon_t \cdot \epsilon_{t+k}} + \cancel{\epsilon_t \cdot \theta_1 \epsilon_{t+k-1}} + \cancel{\epsilon_t \cdot \theta_2 \epsilon_{t+k-2}} \\ &\quad + \cancel{\theta_1 \epsilon_{t-1} \epsilon_{t+k}} + \cancel{\theta_1 \epsilon_{t-1} \cdot \theta_1 \epsilon_{t-k-1}} + \cancel{\theta_1 \epsilon_{t-1} \cdot \theta_2 \epsilon_{t-k-2}} \\ &\quad + \cancel{\theta_2 \epsilon_{t-2} \epsilon_{t+k}} + \cancel{\theta_2 \epsilon_{t-2} \cdot \theta_1 \epsilon_{t-k-1}} + \cancel{\theta_2 \epsilon_{t-2} \cdot \theta_2 \epsilon_{t-k-2}}] \\ &= \theta_1 E[\epsilon_{t-1} \epsilon_{t+k}] + \theta_2 E[\epsilon_{t-2} \epsilon_{t+k}] + \theta_1 \theta_2 E[\epsilon_{t-2} \epsilon_{t+k-1}]\end{aligned}$$

$$r_k \begin{cases} (\theta_1 + \theta_1 \theta_2) \sigma^2 & k = 1, \\ \theta_2 \sigma^2 & k = 2 \\ 0 & k > 2 \end{cases}$$

$$p_k \begin{cases} \frac{\theta_1 + \theta_1 \theta_2}{1 + \theta_1^2 + \theta_2^2} & k = 1 \\ \frac{\theta_2}{1 + \theta_1^2 + \theta_2^2} & k = 2 \\ 0 & k > 2 \end{cases}$$

where  $\varepsilon_t \sim WN(0, \sigma_\varepsilon^2)$ . Then, the  $k$ th-order autocovariance is

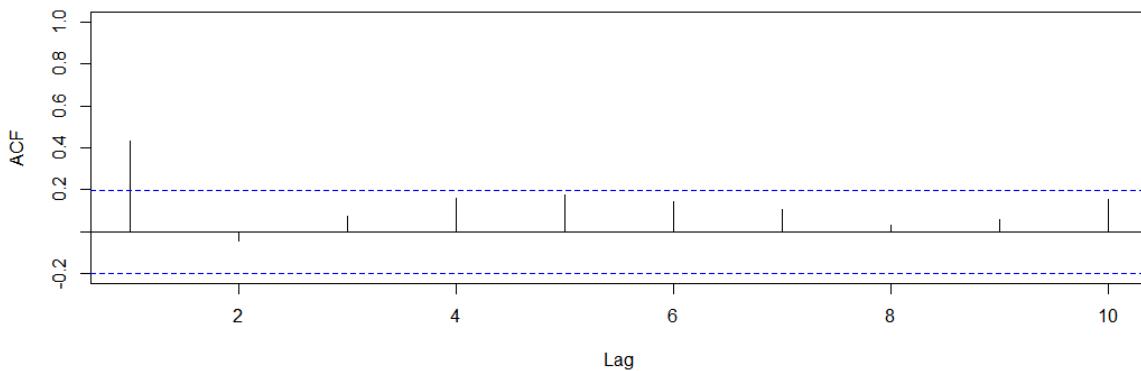
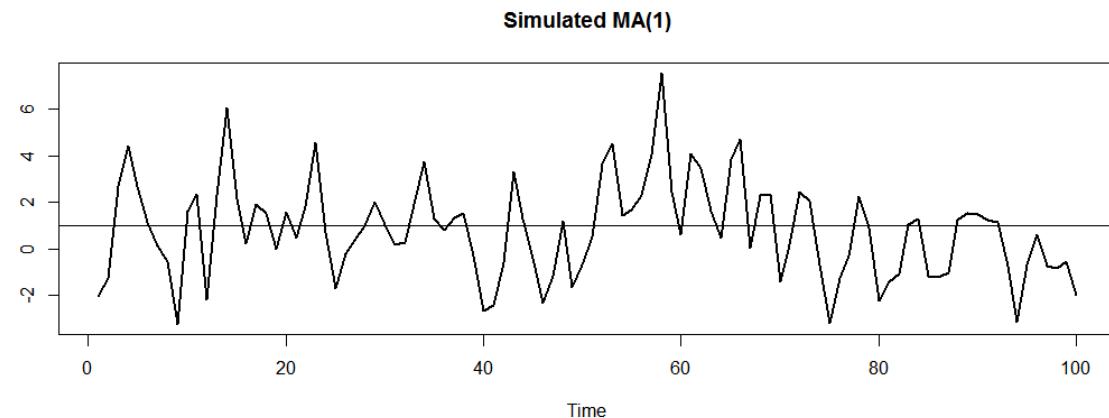
$$\begin{aligned}\gamma_k &= E[(x_t - \mu)(x_{t-k} - \mu)] \\ &= E[(\varepsilon_t + \theta_1 \varepsilon_{t-1})(\varepsilon_{t-k} + \theta_1 \varepsilon_{t-1-k})] \\ &= E[\varepsilon_t \varepsilon_{t-k} + \theta_1 \varepsilon_t \varepsilon_{t-1-k} + \theta_1 \varepsilon_{t-1} \varepsilon_{t-k} + \theta_1^2 \varepsilon_{t-1} \varepsilon_{t-1-k}] \\ &= \begin{cases} \theta_1 \sigma_\varepsilon^2 & \text{for } k = 1 \\ 0 & \text{for } k > 1 \end{cases}\end{aligned}$$

and the  $k$ th-order autocorrelation is

$$\rho_k = \begin{cases} \frac{\theta_1}{1+\theta_1^2} & \text{for } k = 1 \\ 0 & \text{for } k > 1. \end{cases}$$

**Example 1.4.** Simulate an MA(1) process with  $\mu = 1$ ,  $\theta_1 = 0.8$ ,  $\sigma_\varepsilon^2 = 3$ , and  $T = 100$ .

```
> x <- 1 + arima.sim(list(order = c(0, 0, 1), ma = 0.8), sd = sqrt(3), n = 100)
> par(mfrow = c(2, 1))
> plot(x, lwd = 2, xlab = "Time", ylab = "", main = "Simulated MA(1)")
> abline(h = 1)
> acf(x, lag = 10, main = "")
```



**Theorem 1.5.** Consider the infinite series

$$1 + \phi_1 L + \phi_1^2 L^2 + \dots$$

and its  $n$ th partial sum

$$S_n = 1 + \phi_1 L + \phi_1^2 L^2 + \dots + \phi_1^{n-1} L^{n-1}.$$

If  $|\phi_1| < 1$ , then it shows

$$\lim_{n \rightarrow \infty} S_n = \frac{1}{1 - \phi_1 L}.$$

*Proof.* Note

$$\begin{aligned} S_n - \phi_1 L S_n &= (1 + \phi_1 L + \phi_1^2 L^2 + \dots + \phi_1^{n-1} L^{n-1}) - (\phi_1 L + \phi_1^2 L^2 + \phi_1^3 L^3 + \dots + \phi_1^n L^n) \\ &= 1 - \phi_1^n L^n \end{aligned}$$

and hence

$$\underbrace{\phi_1}_{\text{if}} \quad S_n = \frac{1 - \phi_1^n L^n}{1 - \phi_1 L}.$$

If  $|\phi_1| < 1$ , then  $|\phi_1 L| < 1$  and  $\phi_1^n L^n \rightarrow 0$  as  $n \rightarrow \infty$ , and hence

$$\lim_{n \rightarrow \infty} S_n = \frac{1}{1 - \phi_1 L}.$$

□

**Theorem 1.6.** The Wold theorem states that “any stationary” process  $\{x_t\}$  can be represented as a “linear” time series in the form

$$x_t = \mu + \sum_{i=0}^{\infty} \psi_i \varepsilon_{t-i},$$

where  $\varepsilon_t \sim WN(0, \sigma_\varepsilon^2)$ ,  $\mu = E[x_t]$ ,  $\psi_0 = 1$ , and  $\sum_{i=0}^{\infty} \psi_i^2 < \infty$ .

- Importantly, the Wold theorem implies that any stationary AR model has the corresponding MA model.

**Example 1.7.** Consider a stationary AR(1) model

$$x_t - \mu = \phi_1(x_{t-1} - \mu) + \varepsilon_t,$$

where  $\varepsilon_t \sim WN(0, \sigma_\varepsilon^2)$  and  $|\phi_1| < 1$ . Using a lag operator, one obtains

$$(1 - \phi_1 L)(x_t - \mu) = \varepsilon_t. \quad (1.1)$$

Since the stationarity condition  $|\phi_1| < 1$  ensures

$$1 + \phi_1 L + \phi_1^2 L^2 + \dots = \sum_{i=0}^{\infty} \phi_1^i L^i = \frac{1}{1 - \phi_1 L},$$

$$x_t - \mu = \phi_1(x_{t-1} - \mu) + \epsilon_t \quad AR(1)$$

$$|\phi_1| < 1$$

$$\phi_1 L (x_t - \mu)$$

$$\Rightarrow (x_t - \mu)(1 - \phi_1 L) = \epsilon_t$$

$$x_t = \mu + \frac{\epsilon_t}{1 - \phi_1 L}$$

$$= \mu + \epsilon_t (1 + \phi_1 L + \phi_1^2 L^2 + \phi_1^3 L^3 + \dots)$$

$$= \frac{1}{1 - \phi_1 L}$$

$$= \mu + \epsilon_t + \phi_1 \epsilon_{t-1} + \phi_1^2 \epsilon_{t-2} + \phi_1^3 \epsilon_{t-3} + \dots$$

MA( $\infty$ )

AR  $\Rightarrow$  MA.

$\phi(L)$  stationarity

AR  $\Rightarrow$  MA

$\theta(L)$

MA  $\Rightarrow$  AR

invertible.

(solution of characteristic eq  
are greater than 1 in modulus)

AR  $\xrightarrow{\text{stationary}} \text{MA} \xrightarrow{\phi(L)=0}$  all sols  
greater than 1 in modulus

MA  $\xrightarrow{\text{invertible}} \text{AR} \xrightarrow{\theta(L)=0}$  / in modulus

stationary AR(2) model. find corresponding MA model.

$$x_t = \phi_0 + \phi_1 x_{t-1} + \phi_2 x_{t-2} + \varepsilon_t$$
$$|\phi_1| < 1 \quad |\phi_2| < 1$$

$$x_t - \mu = \phi_1(x_{t-1} - \mu) + \phi_2(x_{t-2} - \mu) + \varepsilon_t$$
$$x_t - \mu = \phi_1 L(x_t - \mu) + \phi_2 L^2(x_{t-2} - \mu) + \varepsilon_t$$
$$(x_t - \mu)(1 - \phi_1 L - \phi_2 L^2) = \varepsilon_t.$$

$$x_t = \mu + \frac{\varepsilon_t}{1 - \phi_1 L - \phi_2 L^2} \quad ??$$

one writes (1.1) as

$$x_t = \mu + \frac{\varepsilon_t}{1 - \phi_1 L} = \mu + \sum_{i=0}^{\infty} \phi_1^i \varepsilon_{t-i},$$

which is the Wold representation of the AR(1) model.

**Definition 1.8.** An MA( $q$ ) process is *invertible* if all of the solutions of the characteristic equation

$$\theta(z) = 1 + \theta_1 z + \theta_2 z^2 + \cdots + \theta_q z^q = 0$$

are greater than 1 in modulus.

**Theorem 1.9.** If an MA process is invertible, there exists a corresponding AR process,

**Example 1.10.** Consider an MA(1) model of the form

$$\underline{x_t = \varepsilon_t - \theta_1 \varepsilon_{t-1}}, \quad (1.2)$$

where  $\{\varepsilon_t\}$  is a white noise process. The characteristic equation of the MA(1) model is

$$\theta(z) = 1 - \theta_1 z = 0$$

and, hence, the solution is  $z = \theta_1^{-1}$ . Rewriting (1.2) as  $\varepsilon_t = x_t + \theta_1 \varepsilon_{t-1}$ , one obtains

$$\begin{aligned} \varepsilon_t &= x_t + \theta_1(x_{t-1} + \theta_1 \varepsilon_{t-2}) \\ &= x_t + \theta_1 x_{t-1} + \theta_1^2 \varepsilon_{t-2} \\ &= x_t + \theta_1 x_{t-1} + \theta_1^2 x_{t-2} + \cdots \\ &= (1 + \theta_1 L + \theta_1^2 L^2 + \cdots) x_t. \end{aligned} \quad (1.3)$$

Since  $\varepsilon_t$  is stationary by definition, it must hold that  $1 + \theta_1 L + \theta_1^2 L^2 + \cdots$  converges to  $(1 - \theta_1 L)^{-1}$  in the RHS of (1.3), which requires the condition  $|\theta_1| < 1$ . Therefore, if  $|\theta_1| < 1$  or equivalently  $|z| > 1$ , the MA(1) model in (1.2) has a corresponding AR process of the form

$$\begin{aligned} x_t &= -\theta_1 \varepsilon_{t-1} + \varepsilon_t \\ &= -\theta_1(L + \theta_1 L^2 + \theta_1^2 L^3 + \cdots) x_t + \varepsilon_t \\ &= -\theta_1 x_{t-1} - \theta_1^2 x_{t-2} - \theta_1^3 x_{t-3} - \cdots + \varepsilon_t. \end{aligned}$$

## 2. Order Determination

For a time series  $x_t$  with ACF  $\rho_k$ , if  $\rho_k \neq 0$ , but  $\rho_k = 0$  for  $k > q$ , then  $x_t$  follows an MA( $q$ ) model.

**Example 2.1.** Consider monthly returns of the CRSP equal-weighted index from January 1926 to December 2008.

```
> mydat <- read.table("data1.txt", header = T)
```

```
> head(mydat)
```

date	ibmrtn	vwrtn	ewrtn	sprtn
------	--------	-------	-------	-------

MA(1).

$$x_t = \varepsilon_t - \theta_1 \varepsilon_{t-1}$$

$$\theta(z) = 1 - \theta_1 z = 0.$$

$$z = \theta_1^{-1}$$

$$\varepsilon_t = x_t + \theta_1 \varepsilon_{t-1}$$

$$= x_t + \theta_1 (x_{t-1} + \theta_1 \varepsilon_{t-2})$$

$$= x_t + \theta_1 x_{t-1} + \theta_1^2 \cdot \varepsilon_{t-2}$$

$$= x_t + \theta_1 x_{t-1} + \theta_1^2 x_{t-2} + \theta_1^3 x_{t-3} + \dots$$

$$= x_t (1 + \theta_1 L + \theta_1^2 L^2 + \theta_1^3 L^3 + \dots)$$

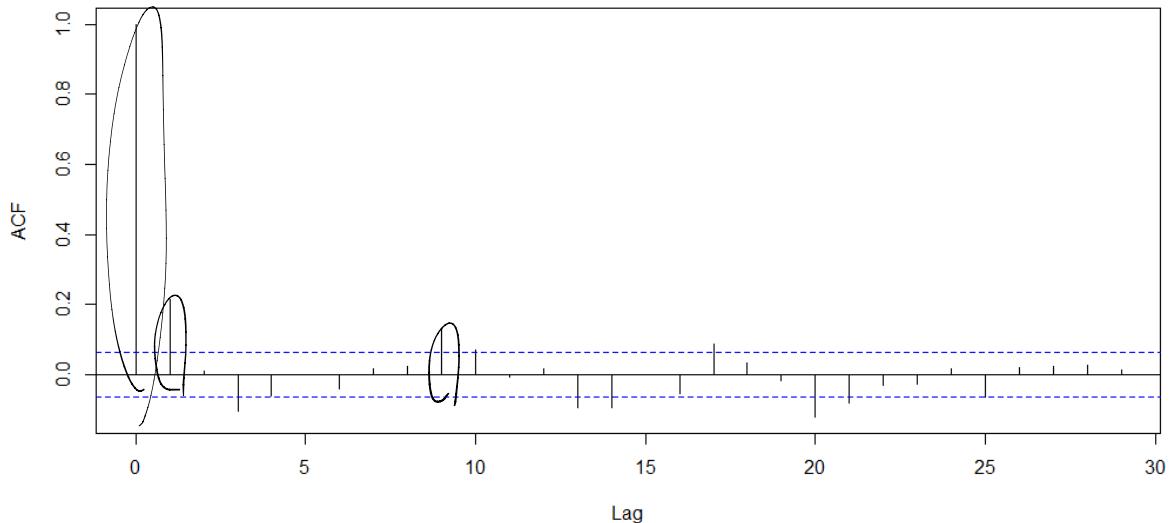
$$x_t = -\theta_1 \varepsilon_{t-1} + \varepsilon_t$$

$$= -\theta_1 (x_{t-1} (1 + \theta_1 L + \theta_1^2 L^2 + \dots)) + \varepsilon_t$$

$$= -\theta_1 x_{t-1} - \theta_1^2 x_{t-2} - \theta_1^3 x_{t-3} - \dots + \varepsilon_t$$

```

1 19260130 -0.010381 0.000724 0.023174 0.022472
...
6 19260630  0.068493 0.056888 0.050487 0.043184
> ewrtn <- mydat$ewrtn
> acf(ewrtn, main = "")
```



- The autocorrelation is significant at lags 1, 3, and 9.

### 3. Parameter Estimation

*order q*

Consider an MA( $q$ ) model of the form

$$x_t = \mu + \varepsilon_t + \theta_1 \varepsilon_{t-1} + \cdots + \theta_q \varepsilon_{t-q},$$

*$\theta_1 \sim \theta_2, \dots$*

where  $\varepsilon_t \sim WN(0, \sigma_\varepsilon^2)$ . Maximum likelihood estimation is used to estimate the parameters of the MA( $q$ ) model.

- In estimating MA( $q$ ) models, one needs to decide how to treat the first  $q$  values of  $\varepsilon_t$ . In the *conditional likelihood* method, the missing lagged shocks are set to zero. In the *exact likelihood* method, the missing lagged shocks are treated as additional parameters of the model and estimated jointly with other parameters. The exact likelihood estimates are often preferred to the conditional likelihood estimates. If the sample size is large enough, both estimates are close to each other.

*Remark 3.1.* In R, the MA( $q$ ) model is treated in the form

$$x_t = \mu + \varepsilon_t + \theta_1 \varepsilon_{t-1} + \cdots + \theta_q \varepsilon_{t-q},$$

where  $\mu = E[x_t]$  is referred to as the *intercept*.



- The fitted model is

$$x_t = 0.0122 + \varepsilon_t + 0.1909\varepsilon_{t-1} - 0.1199\varepsilon_{t-3} + 0.1227\varepsilon_{t-9}.$$

The  $p$ -value is 0.04, so that the fitted model is "only" marginally adequate.

*unit root AR, not apply x.*

## 5. Forecasting

The  $s$ -step ahead forecast of an MA model is the conditional expectation of  $x_{t+s}$  given  $I_t$ ; i.e.,

$$\hat{x}_t[s] = E[x_{t+s}|I_t]$$

for  $s \geq 1$ .

- For an MA(1) model, it shows

$$\begin{aligned} \hat{x}_t[1] &= E[x_{t+1}|I_t] \\ &= E[\mu + \varepsilon_{t+1} + \theta_1\varepsilon_t|I_t] \\ &= (\mu + \theta_1\varepsilon_t) \end{aligned} \quad \begin{matrix} \uparrow \\ AR \\ \text{but } 1 \text{ corresponding} \end{matrix} \quad (5.1)$$

$$\begin{aligned} e_t[1] &= x_{t+1} - \hat{x}_t[1] \\ &= \varepsilon_{t+1} \end{aligned} \quad (5.2)$$

$$\begin{aligned} \hat{x}_t[s] &= E[x_{t+s}|I_t] \\ &= E[\mu + \varepsilon_{t+s} + \theta_1\varepsilon_{t+s-1}|I_t] \\ &= (\mu) \end{aligned} \quad (5.3)$$

$$\begin{aligned} e_t[s] &= x_{t+s} - \hat{x}_t[s] \\ &= \varepsilon_{t+s} + \theta_1\varepsilon_{t+s-1} \end{aligned} \quad (5.4)$$

for  $s > 1$ . Based on (5.1) and (5.3), one sees that it takes one time period for its forecast to go to the mean. From (5.2) and (5.4), it shows

$$Var[e_t[1]] = \sigma_\varepsilon^2 < Var[e_t[s]] = (1 + \theta_1^2)\sigma_\varepsilon^2.$$

- For an MA(2) model, it shows

$$\begin{aligned} \hat{x}_t[1] &= E[\mu + \varepsilon_{t+1} + \theta_1\varepsilon_t + \theta_2\varepsilon_{t-1}|I_t] \\ &= \mu + \theta_1\varepsilon_t + \theta_2\varepsilon_{t-1} \\ \hat{x}_t[2] &= E[\mu + \varepsilon_{t+2} + \theta_1\varepsilon_{t+1} + \theta_2\varepsilon_t|I_t] \\ &= \mu + \theta_2\varepsilon_t \\ \hat{x}_t[s] &= \mu \end{aligned}$$

for  $s > 2$ . Thus, it takes two time periods for its forecast to go to the mean. In general, for an MA( $q$ ) model, the forecasts go to the mean after the first  $q$  periods.

MACID.

$$x_t = \mu + \varepsilon_t + \theta_1 \varepsilon_{t-1}$$

$$\begin{aligned}\hat{x}_t[1] &= E[x_{t+1} | I_t] \\ &= E[\mu + \varepsilon_{t+1} + \theta_1 \varepsilon_t | I_t] \\ &= \mu + \theta_1 \varepsilon_t\end{aligned}$$

$$\begin{aligned}e_t[1] &= x_{t+1} - \hat{x}_t[1] \\ &= \varepsilon_{t+1}\end{aligned}$$

$$\text{Var}[e_t[1]] = 6\varepsilon^2$$

$$\begin{aligned}\hat{x}_t[2] &= E[x_{t+2} | I_t] \\ &= E[\mu + \varepsilon_{t+2} + \theta_1 \varepsilon_{t+1} | I_t] \\ &= \mu\end{aligned}$$

$$\begin{aligned}e_t[2] &= x_{t+2} - \hat{x}_t[2] \\ &= \varepsilon_{t+2} + \theta_1 \varepsilon_{t+1}\end{aligned}$$

$$\begin{aligned}\text{Var}[e_t[2]] &= \text{Var}[\varepsilon_{t+2} + \theta_1 \varepsilon_{t+1}] \\ &= 6\varepsilon^2 + \theta_1^2 6\varepsilon^2 \\ &= 6\varepsilon^2 (1 + \theta_1^2)\end{aligned}$$

$$\begin{aligned}\hat{x}_t[s] &= E[x_{t+s} | I_t] \\ &= E[\mu + \varepsilon_{t+s} + \theta_1 \varepsilon_{t+s-1} | I_t] \\ &= \mu\end{aligned}$$

$$e_t[s] = \varepsilon_{t+s} + \theta_1 \varepsilon_{t+s-1}$$

$$\begin{aligned}\text{Var}[e_t[s]] &= \text{Var}[\varepsilon_{t+s} + \theta_1 \varepsilon_{t+s-1}] \\ &= 6\varepsilon^2 + \theta_1^2 6\varepsilon^2 \\ &= 6\varepsilon^2 (1 + \theta_1^2)\end{aligned}$$

MA(2).

$$x_t = \mu + \varepsilon_t + \theta_1 \varepsilon_{t-1} + \theta_2 \varepsilon_{t-2}$$

$$\begin{aligned}\hat{x}_{t+1} &= E(x_{t+1} | I_t) \\ &= E(\mu + \varepsilon_{t+1} + \theta_1 \varepsilon_t + \theta_2 \varepsilon_{t-1} | I_t) \\ &= \mu + \theta_1 \varepsilon_t + \theta_2 \varepsilon_{t-1}\end{aligned}$$

$$\varepsilon_{t+1} = \varepsilon_t$$

$$\text{Var}[\varepsilon_{t+1}] = \sigma^2_\varepsilon$$

$$\begin{aligned}\hat{x}_{t+2} &= E(\mu + \varepsilon_{t+2} + \theta_1 \varepsilon_{t+1} + \theta_2 \varepsilon_t | I_t) \\ &= \mu + \theta_2 \varepsilon_t\end{aligned}$$

$$\varepsilon_{t+2} = \varepsilon_{t+1} + \theta_1 \varepsilon_t$$

$$\text{Var}[\varepsilon_{t+2}] = \sigma^2_\varepsilon (1 + \theta_1^2)$$

$$\begin{aligned}\hat{x}_{t+3} &= E(\mu + \varepsilon_{t+3} + \theta_1 \varepsilon_{t+2} + \theta_2 \varepsilon_{t+1} | I_t) \\ &= \mu\end{aligned}$$

$$\varepsilon_{t+3} = \varepsilon_{t+2} + \theta_1 \varepsilon_{t+1} + \theta_2 \varepsilon_t$$

$$\text{Var}[\varepsilon_{t+3}] = \sigma^2_\varepsilon (1 + \theta_1^2 + \theta_2^2)$$

**Example 5.1.** Consider monthly returns of the CRSP equal-weighted index from January 1926 to December 2008.

```
> ewrtn <- ts(ewrtn, start = c(1926, 1), freq = 12)
> ewrtn1 <- window(ewrtn, end = c(2008, 2))
> reg <- arima(ewrtn1, order = c(0, 0, 9), fixed = c(NA, 0, NA, 0, 0, 0, 0, 0,
   NA, NA), method = "ML")
> x.ahead <- predict(reg, 10)
> x.ahead$pred[10]
[1] 0.01279257
> mean(ewrtn1)
[1] 0.0127984
```

- As expected, the 10-step ahead forecast is equal to the sample mean.

```
> ewrtn2 <- window(ewrtn, start = c(2007, 2))
> plot(ewrtn2, lwd = 2, xlab = "", ylab = "", ylim = c(-0.3, 0.2))
> pred <- x.ahead$pred
> lines(ts(c(ewrtn2[13], pred), start = c(2008, 2), freq = 12), lty = 4, lwd = 2)
> upper <- x.ahead$pred + 1.96*x.ahead$se
> lines(ts(c(ewrtn2[13], upper), start = c(2008, 2), freq = 12), lty = 3)
> lower <- x.ahead$pred - 1.96*x.ahead$se
> lines(ts(c(ewrtn2[13], lower), start = c(2008, 2), freq = 12), lty = 3)
> legend("bottomleft", c("Observations", "Forecasts", "95% confidence interval"),
  lty = c(1, 4, 3), lwd = c(2, 2, 1), inset = 0.01)
```

