Project3

[PART I] NPCS Implementation

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1.The screenshot result (with the given format) of the two task sets. (Time tick 0-100)

The NPCS of Output Result:

Task Set $1 = \{ \text{task1} (2,5,30), \text{task2} (3,3,60), \text{task3} (0,7,90) \}$

```
🔳 D:\學校\台科\10901\EE5036701 嵌入式作業系統實作 Embedded OS Implementat
                          created, Thread ID 161<u>5</u>6
   OSTick
   NPCS 第二題    Task Set 2 = {task1 (2,6,30), task2 (0,7,60)}
   Tick
                     Event
                     Event
Task2
Task2 get R2
Task2 release R2
Task2 get R1
Task2 release R1
Task1
   0
4466799112323555780144666777799999999121
1232355780144666777799955780121
                     Taskl get R1
Taskl release R1
                     Task1 get R2
Task1 get R2
Task1 release R2
Task2
Task63
                     Taskl
Taskl get R1
Taskl release R1
Taskl get R2
Taskl release R2
Task63
Task2
                     Task2 get R2
Task2 release R2
Task2 get R1
Task2 release R1
Task1
Task1
Task1 get R1
Task1 release R1
                     Taski get R2
Taski release R2
                     Task2
Task63
                     Task1
                     Taskl get R1
Taskl get R1
Taskl release R1
Taskl get R2
Taskl release R2
                     Task63
                     Task2
Task2 release R2
```

2.A report that describes your implementation, including scheduling results of two task sets, modified functions, data structure, etc. (please ATTACH the screenshot of the code and MARK the modified part).

```
os_time.c ucos_ii.h + × os_core.c*

Solution

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                                                                                                                                                     **********
       2001
       2002
                         typedef struct {
                                     int arrivaTime;//到達時間
                                     int executionTime;//執行時間
       2004
       2005
                                      int periodTime;//週期時間
       2006
                                     int LR1_Time;//Lock R1 與到達時間的時間差
       2007
                                     int UR1_Time;//UnLock R1 與到達時間的時間差
                                     int LR2_Time;//Lock R2 與到達時間的時間差
       2008
                                     int UR2_Time;//UnLock R2 與到達時間的時間差
       2009
                          }TaskData;
       2010
       2011
       2012
       2013
                                                                                                                                     PA03
                             2014
       2015
                                                                                                                              #define TASK_STACKSIZE
                                                                                                                                                                                                              2048
static TaskData Task1= {
        .arrivaTime=2.
         .executionTime=5,
         .periodTime=30,
                                                                                                                              #define TASK1_PRIORITY
                                                                                                                                                                                                              2
         .LR1 Time=1.
                                                                                                                              #define TASK2_PRIORITY
                                                                                                                                                                                                              4
         .UR1_Time=4,
                                                                                                                              #define TASK3_PRIORITY
                                                                                                                                                                                                              5
         .LR2_Time=0,
        .UR2_Time=0
                                                                                                                              #define TASK1_ID
                                                                                                                                                                                                              1
                                                                                                                              #define TASK2_ID
                                                                                                                                                                                                              2
static TaskData Task2 = {
                                                                                                                              #define TASK3_ID
        .arrivaTime = 3,
         .executionTime = 3,
                                                                                                                              static void task1(void* p_arg);
        .periodTime = 60,
                                                                                                                              static void task2(void* p_arg);
         .LR1\_Time = 0,
                                                                                                                              static void task3(void* p_arg);
         .UR1\_Time = 0,
        .LR2\_Time = 0,
         .UR2\_Time = 0
                                                                                                                              static OS_STK TASK1_STK[TASK_STACKSIZE];
                                                                                                                              static OS_STK TASK2_STK[TASK_STACKSIZE];
                                                                                                                              static OS_STK TASK3_STK[TASK_STACKSIZE];
static TaskData Task3 = {
        .arrivaTime = 0,
         .executionTime = 7,
        .periodTime = 90,
          .LR1\_Time = 0,
        .UR1 Time = 0,
         .LR2\_Time = 1,
         .UR2\_Time = 6
```

```
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      58
59
      */
     rivoid mywait(int tick)
60
61
     ##if OS_CRITICAL_METHOD==3
62
       OS_CPU_SR cpu_sr = 0;
63
      #endif
64
65
         int now, exit;
         OS_ENTER_CRITICAL();
66
67
         now = OSTimeGet();
68
         exit = now + tick;
         OS_EXIT_CRITICAL();
69
70
         while (1) {
          if (exit <= OSTimeGet())
71
               break;
72
         j
73
74
    □void OSTimeDly_arr(INT32U ticks, OS_TCB* task_123) //把arrival time tick 與 taskName 送進來
75
76
77
     ⊞#if OS_CRITICAL_METHOD == 3u
                                                                                       */
                                            /* Allocate storage for CPV status register
78
79
      #endif
         OS_CPU_SR cpu_sr = Ou;
80
         if (OSIntNesting > Ou) {
                                            /* See if trying to call from an ISR
                                                                                        */
81
82
             return;
83
84
          if (OSLockNesting > Ou) {
                                            /* See if called with scheduler locked
85
            return;
86
                                            /* O means no delay!
                                                                                       */
87
          if (ticks > 0u) {
88
            OS_ENTER_CRITICAL();
             y = task_123->OSTCBY;
89
                                  /* Delay current task
            OSRdyTb1[y] &= (OS_PRIO)~task_123->OSTCBBitX;
OS_TRACE_TASK_SUSPENDED(task_123);
90
91
92
             if (OSRdyTbl[y] == Ou) {
               OSRdyGrp &= (OS_PRIO)~task_123->OSTCBBitY;
93
94
             task_123->OSTCBDly = ticks;
                                                                                        */
95
                                            /* Load ticks in TCB
96
             OS_TRACE_TASK_DLY(ticks);
97
             OS_EXIT_CRITICAL();
98
             //OS_Sched();
                                              /* Find next task to run!
                                                                                         */
gg
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101
102
      **********************
103
                                           PAO3
      104
105
      */
```

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                          * PAGS-NPCS
                       */|
int t1 = 0; t2 = 0; t3 = 0;
#define RI_PRIO
OS_EVENT* RI;
OS_EVENT* RI;
                         #include <windows.h>
static void OS_SchedNew (void)
                      {

=#if OS_LOWEST_PRIO <= 63u

INTRU y;

- OSITOMA
                                                                                                                                             /* See if we support up to 64 tasks
                                 y = OSUnMapTbl[OSRdyGrp];

OSPrioHighRdy = (INT8U)((y << 3u) + OSUnMapTbl[OSRdyTbl[y]]);
                                  INTSU err;
R1 = OSMutexCreate(R1_PRIO, &err);
R2 = OSMutexCreate(R2_PRIO, &err);
                                  if (OSPrioCur!=OSPrioHighRdv) {
                                           ptcb = OSTCBPrioTb1[OSPrioHighRdy];
TaskData* point_t = ptcb->OSTCBExtPtr;
                                            if (ptcb->OSTCBId == 65535) {
                                                    \yww-vositinu == 02000) {
printf("%d\t %s\n", OSTimeGet(), "Task63");//print 題目要求
t1 = 0; t2 = 0; t3 = 0;
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                                           if (ptcb->OSTCBId == 1 && t1==0) {
                                                   (ptd>-OSICRId == 1 && t1==y);

t1 = 1;
print("Makt Mehn", OSTimeGet(), "Task1");
print("Makt Mehn", OSTimeGet(), "Task1");
if (point_t->LRI_Time opoint_t->LRZ_Time) {//如果這個Task是RI先做
if (point_t->LRI_Time to && point_t->RI_Time t= 0) {
    OSTimeBly_arr(point_t->LRI_Time t= 0 & point_t->RI_Time t= 0) {
    OSItimeBly_arr(point_t->LRI_Time t= point_t->LRI_Time t= point_t->RI_Time t= p
                                                                        OSTimeDly_arr(point_t->arrivaTime + point_t->executionTime - point_t->UR1_Time, OSTCBPrioTb1[2]);//讓Task等待Task結束的時間
                                                                }
if (point_t-\LE2_Time != 0 && point_t-\UE2_Time != 0) {
GSTimeBly_arr(point_t-\LE1_Time, GSTGMPrioTbl[2]);//續Task等待get R2的時間
printf("Not Noh", OSTimeGet(), "Task! get R2");//print 題目要求
OSMtotePrend(R2, 0, &err);
                                                              if (point_t->LE2_lime != 0 & point_t->UR2_lime != 0) {
        OSTimeBly_arr(point_t->LE1_lime, USTCBPrioTbl[2]);//讀Task等待get R2的時間
        printf("Mat Nowin, OSTimeGet(), "Taskl get E2");//print 更目要求
        OSMinterBed(22, 0, berr);
        OSTimeBly_arr(point_t->UR1_lime - point_t->LE1_lime, OSTCBPrioTbl[2]);//讀Task等待release R2的時間
        printf("Mat Nowin, OSTimeGet(), "Taskl release E2");//print 更目要求
        OSMinterBed(22);
        OSMinterBed(22);
        OSMinterBed(22);
        OSTimeBly_arr(point_t->arrivalime + point_t->axecutionTime - point_t->UR2_Time, OSTCBPrioTbl[2]);//讀Task等待Task結束的時間
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                                                                        ommtexros(ar),
OSTimeDly_arr(point_t->arrivaTime + point_t->executionTime - point_t->UR1_Time, OSTCBPrioTbl[2]);//讓Task等待Task結束的時間
```

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                                   usamitezrend(KZ, U, &brr);
OSTimeBUyarr(point_t->BEl_Time - point_t->LEl_Time, OSTCEPrioTbl[2]);//擅Task等待release 配的時間
printf("all vin,", OSTimeGet(), "Task2 release K2");//print 題目要求
OSMutexPost(K2);
OSTimeDly_arr(point_t->arrivaTime + point_t->executionTime - point_t->UR2_Time, OSTCBPrioTbl[2]);//讓Task等待Task結束的時間
                        else {//犯果這個Tack是22先微
if (point_t-31E2_Time != 0 && point_t-3E2_Time != 0) {
    OSTimeDUy_arr(point_t-31E2_Time, OSTOEPrioTb1[2]);//讓Tack等待get R229時間
    printf("WA'u Kawin", OSTimeGet(), "Tack2 get R2");//print 題目要求
    OSMtexPron(R2, 0, &err);
    OSTimeDUy_arr(point_t-vull_Time - point_t-31E1_Time, OSTOEPrioTb1[2]);//溶析ak等待release R229時間
    printf("WA'u Kawin", OSTimeGet(), "Tack2 release R2");//print 题目要求
    OSMtexPost(R2);
    OSMtexPost(R2);
    OSMtexPost(R2);
    OSTimeDUy_arr(point_t-varrivaTime + point_t->executionTime - point_t->TUR2_Time, OSTOEPrioTb1[2]);//讓Tack等待Tack結束的時間
                              | Stimenty_stitputs_-
| if (point_t->IRI_Ime |= 0) & point_t->IRI_Ime |= 0) {
| (STimelly_arr(point_t->IRI_Ime, GSTGPrioTbl[2]);//濮Task等待get Rifmsfill
| printf("Mit Wath", GSTimeSet(), "Task2 get Ri");//print 題目要求
| (SMitterBodRI, 0, Aerr);
| (SSTimeDly_arr(point_t->IRI_Ime, 0= point_t->IRI_Ime, OSTGPrioTbl[2]);//濮Task等待release Rifmsfill
| printf("Mit Wath", OSTimeSet(), "Task2 release Rif);//print 題目要求
| (SMitterSock[XI);
| (SSTimeDly_arr(point_t->arrivaTime + point_t->executionTime - point_t->IRI_Time, OSTGPPrioTbl[2]);//
                                   OSTimeBly_arr(point_t->arrivaTime + point_t->executionTime - point_t->URl_Time, OSTCBPrioTbl[2]);//讓Task等待Task結束的時間
                        }
                     }
                    if (ptcb->OSTCBId == 3 && t3 == 0) {
    t3 = 1;
    printf("%A't %s\n", OSTimeGet(), "Task3");//print 题目要求
                         if (point_t->LR1_Time < point_t->LR2_Time) {//如果這個Task是R1先敞
    if (point_t->LR1_Time l= 0 & point_t->UR1_Time l= 0) {
        OSTimeDUy_art(point_t->LR1_Time, DSTGPFrioTb1[2]);//读Task等待get R1的時間
        printf("私4 " & bun", OSTimeDet(), "Task3 get R1");//print 題目要求
        OSMutexPend(R1, 0, derr);
        OSTimeDUy_art(point_t->UR1_Time - point_t->LR1_Time, OSTCSPFrioTb1[2]);//读Task等待release R1的時間
        printf("AM4 * & bun", OSTimeDet(), "Task3 release R1");//print 题目要求
        OSMutexPost(R1);
        OSTimeDuy_art(point_t->LR1_Time, OSTCSPFrioTb1[2]);//读Task等待release R1的時間
        OSMutexPost(R1);
                                   OSTimeDly_arr(point_t->arrivaTime + point_t->executionTime - point_t->UR1_Time, OSTCBPrioTbl[2]);//讓Task等待Task結束的時間
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1891
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                                   OSMutexPost(R1);
OSTimeDly_err(point_t->arrivaTime + point_t->executionTime - point_t->UR1_Time, OSTCBPrioTb1[2]);//讓Task等待Task結束的時間
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                         OSTimeDly_arr(point_t->arrivaTime + point_t->executionTime - point_t->UR2_Time, OSTCBPrioTbl[2]);//讓Task等待Task結束的時間
                               1915
1916
1917
1918
                                   OSMINEDLY ART(0, 0211), 0211/1, 0251meHly ART(0) 121);//讓Task等待release Rith時間 printf("MAN We'n", USTimeGet(), "Tasks release RI");//print 题目要求
                                    OSMutexPost(R1);
 1919
1920
                                   OSTimeBly_arr(point_t->arrivaTime + point_t->executionTime - point_t->UR1_Time, OSTCBPrioTbl[2]);//讓Task等待Task結束的時間
                              j
 1921
1922
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1931
                     ptcb = ptcb->OSTCBNext;
                 _______
                 3
                                         T1 : 3->L(R1) 5->L(R2) 6->U(R2 R1)
T2 : 1->L(R2) 4->L(R1) 6->U(R1R2)
```

[PART II | CPP Implementation

 The screenshot result (with the given format) of the two task sets. (Time tick 0-100)

Task Set $1 = \{ \text{task1} (2,5,30), \text{task2} (3,3,60), \text{task3} (0,7,90) \}$

```
■ D:\學校\台科\10901\EE5036701 嵌入式作業系統實作 Embedded OS Implementation\-OS-_code\μOSⅡ
OSTick created, Thread ID 9192
CPP 第一題 Task Set 2 = {task1 (2,5,30), task2 (3,3,60), task3 (0,7,90)}
pro T1=2 T2=3 T3=5 R1=1 R2=4
Tick
             Event
                                          Prio_Inheritance
             Task3
                                               5->4
             Task3 get R2
            Task3 get R2
Task1
Task1 get R1
Task1 release R1
Task2
Task3 release R2
Task63
Task1
Task1 get R1
Task1 get R1
Task63
Task1
236711523367236670012361102
                                               2->1
1->2
                                               4->5
                                               2->1
2->1
             Task1
             Taskl get R1
Taskl get R1
             Task2
             Task63
             Task3
             Task3 get R2
                                               5->4
             Task1 get R1
Task1 release R1
Task3 release R2
                                               2->1
1->2
4->5
             Task63
```

```
■ 選取 D:\學校\台科\10901\EE5036701 嵌入式作業系統實作 Embedded OS Impler
                  created, Thread ID 11788
  OSTick –
  CPP 第二題 Task Set 2 = {task1 (2,6,30), task2 (0,7,60)}
  pro T1=3 T2=4 R1=1 R2=2
  Tick
               Event
                                          Prio_Inheritance
               Task2
               Task2 get R2
                                               4->2
              Task2 get R2
Task2 release R2
Task2 get R1
Task2 release R1
Task3
Task1 get R1
Task1 release R1
2->1
                                               1 -> 1
                                               1 - > 1
                                               3->1
                                               1 -> 1
               Taskl get R2
Taskl release R2
                                               1->2
2->3
               Task2
               Task63
              Taskl
Taskl get R1
Taskl release R1
                                               3->1
                                               1 - > 1
                                               1->2
2->3
               Task1 get R2
               Taski release R2
              Task63
Task2
Task2 get R2
Task2 release R2
Task2 get R1
Task2 release R1
                                               4->2
2->1
1->1
                                                1 - > 1
               Task1
              Taski get Ri
Taski release Ri
Taski get R2
Taski release R2
Task2
                                               3 - > 1
                                               1->1
                                               1->2
2->3
               Task63
               Task1
               Taski get Ri
Taski release Ri
                                               3->1
                                               1 -> 1
               Taskl get R2
Taskl release R2
                                               1->2
2->3
               Task63
               Task2
               Task2 get R2
                                               4->2
```

2.A report that describes your implementation, including scheduling results of two task sets, modified functions, data structure, etc. (please ATTACH the screenshot of the code and MARK the modified part).

```
main.c*
       os_time.c
               ucos_ii.h + × os_core.c*
IOS2
                                                   (全域範圍)
                                     PA03
  1999
  2001
        */
  2002
       ⊨typedef struct {
  2003
          int arrivaTime;//到達時間
  2004
          int executionTime;//執行時間
          int periodTime;//週期時間
  2005
          int LR1_Time;//Lock R1 與到達時間的時間差
  2006
          int UR1_Time;//UnLock R1 與到達時間的時間差
  2007
  2008
          int LR2_Time;//Lock R2 與到達時間的時間差
  2009
          int UR2_Time;//UnLock R2 與到達時間的時間差
  2010
        }TaskData;
  2011
        2012
  2013
                                    PA03
        2014
  2015
```

```
static TaskData Task1= {
                                     #define TASK_STACKSIZE
                                                               2048
    .arrivaTime=2.
    .executionTime=5,
                                     #define TASK1_PRIORITY
    .periodTime=30,
                                     #define TASK2_PRIORITY
                                                               3
    .LR1_Time=1,
                                     #define TASK3_PRIORITY
                                                               5
    .UR1_Time=4,
    .LR2_Time=0,
                                     #define TASK1_ID
                                     #define TASK2_ID
                                                               2
    .UR2_Time=0
                                     #define TASK3_ID
}:
                                     static void task1(void* p_arg);
                                     static void task2(void* p_arg);
static TaskData Task2 = {
                                     static void task3(void* p_arg);
    .arrivaTime = 3,
    .executionTime = 3,
                                     static OS_STK TASK1_STK[TASK_STACKSIZE];
    .periodTime = 60,
                                     static OS_STK TASK2_STK[TASK_STACKSIZE];
                                     static OS_STK TASK3_STK[TASK_STACKSIZE];
    .LR1_Time = 0,
    .UR1\_Time = 0,
    .LR2 Time = 0,
    .UR2 Time = 0
}:
static TaskData Task3 = {
    .arrivaTime = 0,
    .executionTime = 7,
    .periodTime = 90,
    .LR1\_Time = 0,
    .UR1\_Time = 0,
    .LR2 Time = 1,
    .UR2 Time = 6
};
```

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® OS2
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                                                         ### SakData* point_t = ptdb-SOTEDEXPPT;

if (c == 1) (printf("%dit TaskZn", OSTimeGet()); )//print 題目要求

if (c == 1) (printf("%dit TaskZn", OSTimeGet()); )//print 題目要求

if (c == point_t->Rel_Time + 1) { printf("%dit TaskZ release Rl

if (c == point_t->Rel_Time + 1) { printf("%dit TaskZ release Rl

if (c == point_t->Rel_Time + 1) { printf("%dit TaskZ release Rl

if (c == point_t->Rel_Time + 1) { printf("%dit TaskZ release Rl

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if (c == point_t->Rel_Time + 1) { printf("%dit TaskZ release Rl

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if (c == point_t->Rel_Time + 1) { printf("%dit TaskZ release Rl

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if (c == point_t->Rel_Time + 1) { printf("%dit TaskZ release Rl

if (c == point_t->Rel_Time + 1) { printf("%dit TaskZ rel
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                 1791
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1798
                                                                                  ptcb = OSTEPFroTb1[OSFrioRpiRdy];
TaskBata* point_t = ptcb - OSTEDExtPtr;
if (c == 1) { printf("Md\t Task3\n", OSTimeGet()); }//print 題目要求
if (c == point_t->URL]Time + 1) { printf("Md\t Task3 get Rl
if (c == point_t->URL]Time + 1) { printf("Md\t Task3 get Rl
if (c == point_t->URL]Time + 1) { printf("Md\t Task3 get Rl
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if (c == point_t->URL]Time + 1) { printf("Md\t
™ OS2
                                                                                                                                                                                                                                                                                                                                                                                                                                          - (全域範圍)
                                                          #define R1_PRIO
#define R2_PRIO
OS_EVENT* R1;
OS_EVENT* R2;
               1802
1803
               1804
               1805
                                                      Estatic void OS_SchedNew (void)
               1806
1807
                                                       |\text{\text{\text{\text{\text{\text{\text{\text{\text{\text{\text{\text{\text{\text{\text{\text{\text{\text{\text{\text{\text{\text{\text{\text{\text{\text{\text{\text{\text{\text{\text{\text{\text{\text{\text{\text{\text{\text{\text{\text{\text{\text{\text{\text{\text{\text{\text{\text{\text{\text{\text{\text{\text{\text{\text{\text{\text{\text{\text{\text{\text{\text{\text{\text{\text{\text{\text{\text{\text{\text{\text{\text{\text{\text{\text{\text{\text{\text{\text{\text{\text{\text{\text{\text{\text{\text{\text{\text{\text{\text{\text{\text{\text{\text{\text{\text{\text{\text{\text{\text{\text{\text{\text{\text{\text{\text{\text{\text{\text{\text{\text{\text{\text{\text{\text{\text{\text{\text{\text{\text{\text{\text{\text{\text{\text{\text{\text{\text{\text{\text{\text{\text{\text{\text{\text{\text{\text{\text{\text{\text{\text{\text{\text{\text{\text{\text{\text{\text{\text{\text{\text{\text{\text{\text{\text{\text{\text{\text{\text{\text{\text{\text{\text{\text{\text{\text{\text{\text{\text{\text{\text{\text{\text{\text{\text{\text{\text{\text{\text{\text{\text{\text{\text{\text{\text{\text{\text{\text{\text{\text{\text{\tint{\text{\text{\text{\text{\text{\text{\text{\text{\text{\text{\text{\text{\text{\text{\text{\text{\text{\text{\text{\text{\text{\text{\text{\text{\text{\text{\text{\text{\text{\text{\text{\tin}\text{\text{\text{\text{\text{\text{\text{\text{\text{\text{\text{\text{\text{\text{\text{\text{\text{\text{\text{\text{\text{\text{\text{\text{\text{\text{\text{\text{\text{\text{\text{\ti}\text{\text{\text{\text{\text{\text{\text{\text{\text{\text{\tin}\text{\text{\text{\text{\text{\text{\text{\text{\text{\text{\text{\text{\text{\text{\text{\text{\text{\text{\text{\text{\text{\text{\text{\text{\text{\text{\text{\text{\text{\text{\text{\tert{\text{\text{\text{\text{\text{\text{\text{\text{\text{\text{\ti}\tint{\text{\text{\text{\text{\text{\text{\text{\text{\texi}\tint{\text{\texi}\text{\text{\texi}\til\text{\text{\text{\texi}\text{\text{\text{\text{\text{\texi}\text{\text{\texi}\text{\text{
                                                                                                                                                                                                                                                                                                  /* See if we support up to 64 tasks
                                                                               OS_DIRECTION (
DITUBLE y;
y = OSUMMapTb[[OSRdyGrp];
y = OSUMMapTb[[OSRdyGrp];
OSPrioHighRdy = ( IMTBU)((y << 3u) + OSUMMapTb[[OSRdyTb1[y]]);
                 1812
                 1814
                                                                                 INT&U err;
Rl = OSMutexCreate(Rl_PRIO, &err);
                 1815
                                                                               RI = OSMatexCreate(R_PRIO, &err);

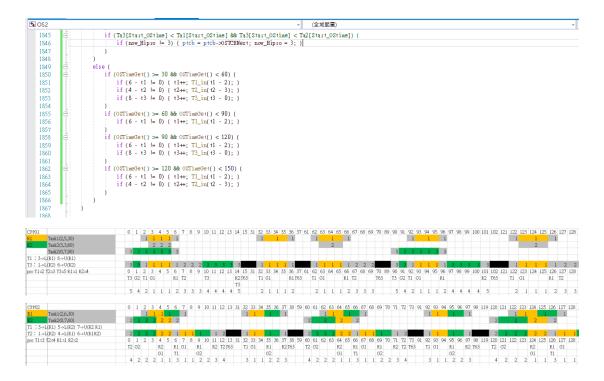
PC = OSMatexCreate(R_PRIO, &err);

if (OSPrioCur = OSPrioHighRely);

TaskData* point_t = ptcb-OSTCBExtPtr;

if (ptcb-OSTCBId == 65535) (
    print("Main %ein", OSTimeGet(), "Task63");//print 題目要求

t1 = 0; t2 = 0; t3 = 0;
                 1816
1817
               1818
1819
1820
1821
                 1822
                 1823
                                                                                                    }
if (ptcb->OSTCBId == 1) {
    if (OSTimeGet() < 30) { tl++; Tl_in(tl); }
    else (tl++; Tl_in(tl-2); }</pre>
                 1824
                 1825
                 1826
1827
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1829
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                                                                                                    1832
1833
                                                                                                     if (ptcb->OSTCBId == 3) {
                                                                                                                    if (OSTimeGet() < 30) { t3++; T3_in(t3); } else { t3++; T3_in(t3 - 2); }
                 1834
               1836
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1839
1840
1841
                                                                                                       )
Start_OStime = OSTimeGet() % 30;
                                                                                                     Stal_Costine = 0.05 index() % 30, if (Start_OStime) < 6 | if (Tal[Start_OStime] < Ta2[Start_OStime] & Ta1[Start_OStime] < Ta3[Start_OStime]) ( if (now_Hipro == 1) ( ptcb = ptcb-SOSTCENEXt; now_Hipro == 1; )
                                                                                                                       if (Ta2[Start_OStime] < Ta1[Start_OStime] && Ta2[Start_OStime] < Ta3[Start_OStime]) {
                 1842
                 1843
                                                                                                                                           if (now_Hipro != 2) { ptcb = ptcb->OSTCBNext; now_Hipro = 2; }
                 1844
                                                                                                                       ;
if (Ta3[Start_OStime] < Ta1[Start_OStime] && Ta3[Start_OStime] < Ta2[Start_OStime]) {
  if (now_Hipro != 3) { ptcb = ptcb-DOSTCENext; now_Hipro = 3; }
```



[PART III] Performance Analysis

1.Compare the scheduling behaviors between NPCS and CPP with the results of PART I and PART II. (5%)

NPCS:

If a job is using a resource, it won't be preempted by any other jobs

- Even if there are no resource conflicts
- Effectively the job runs at the highest priority

CPP:

If R is in use, T is blocked.

If R is free, R is allocated to T. T's execution priority is raised to the priority ceiling of R if that is higher. At any given time, T's execution priority equals the highest priority ceiling of all its held resources.

2.Explain how NPCS and CPP avoid the deadlock problem. (5%) NPCS:

Deadlocks never occur because any job holding resources can not be preempted **CPP**:

T's priority is assigned the next-highest priority ceiling of another resource when the resource with the highest priority ceiling is released. The task returns to its assigned priority after it has released all resources.