11. Linear algebra II: Power iteration and the QR factorisation

Last time

lacksquare Solving systems of linear equations A lacksquare lacksquare

- Iterative methods: Jacobi & Gauss–Seidel
 - Do not always converge

- Direct method: Gaussian elimination
 - Reinterpreted as LU factorisation, A = LU

Goals for today

- Iterating matrix-vector multiplication: Power iteration
- Symmetric matrices
- Gram–Schmidt algorithm
- QR factorisation

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- What happens?
- For simplicity we restrict to real, symmetric matrices A

Collaboration I

Iterating matrix multiplication

Take the matrix

$$A = \begin{bmatrix} 2 & 1 \\ 1 & 1 \end{bmatrix}$$

Take any non-zero vector **x** and carry out the iteration

$$\mathbf{x}_{n+1} = \mathsf{A}\,\mathbf{x}_n$$

- What happens?
- 3 How can we avoid that?
- 4 What equation does the resulting iteration solve?

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■ So **normalise** \mathbf{x}_{n+1} at each iteration:

$$\begin{split} \mathbf{y}_{n+1} &= \mathsf{A}\,\mathbf{x}_n \\ \mathbf{x}_{n+1} &= \frac{\mathbf{y}_{n+1}}{\|\mathbf{y}_{n+1}\|} \end{split}$$

■ Then \mathbf{x}_{n+1} converges to an \mathbf{x}^* as $n \to \infty$

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- \blacksquare Note that we are calculating A^n **x**
- Hence the name **power method** or **power iteration**

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- **x*** is an **eigenvector** of A
- With eigenvalue ||A x*||/||x*||

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- $\hat{\mathbf{v}}$ is a **unit vector** (norm 1), the **direction** of \mathbf{v}

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Problem set!

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- We may even be able to calculate A x without storing A!
- Krylov subspace methods take advantage of this
- Operate on the subspace spanned by $\{\mathbf{x}, A \mathbf{x}, A^2 \mathbf{x}, ...\}$

Real, symmetric matrices

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- Such matrices occur naturally in many situations:
 - Hessian matrix of 2nd partial derivatives is symmetric
 - Covariance matrix in statistics

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Recall: v and w are orthogonal if

$$\mathbf{v} \cdot \mathbf{w} = \mathbf{v}^\mathsf{T} \mathbf{w} = 0$$

Collaboration II

Simultaneous power iteration using QR

- What happens if we perform power iteration with two distinct (non-zero) initial vectors (but the same matrix A)
- What would we like to happen?
- 3 How can we achieve this?

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- To avoid this we need to "push them apart"
- Make them orthogonal
- How can we do so?

Collaboration III

Orthogonalisation

- Given a pair of two vectors u and v. How could we find a new pair of vectors q₁ and q₂ that are orthogonal, but span the same plane?
- 2 How could we extend this to n vectors?

- Suppose $\mathbf{v}_1, \dots, \mathbf{v}_n$ are all mutually orthogonal
- Suppose we want to solve the linear equations

$$x_1\mathbf{v}_1+\cdots+x_n\mathbf{v}_n=\mathbf{b}$$

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- Orthogonal decomposition:

$$\mathbf{b} = (\mathbf{b} \cdot \mathbf{v}_1) \mathbf{v}_1 + \dots + (\mathbf{b} \cdot \mathbf{v}_n) \mathbf{v}_n$$

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- For two vectors **u** and **v**, take **u** as the first vector
- Make an orthogonal decomposition of v as
 - $\mathbf{v} = (\text{part of } \mathbf{v} \text{ in the direction of } \mathbf{u}) + (\text{the rest})$

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- We can write $\mathbf{q}_1 = (\frac{1}{\|\mathbf{u}\|^2}\mathbf{u}\mathbf{u}^\mathsf{T})\mathbf{v}$
- In terms of a projector

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- This is the (classical) **Gram–Schmidt** algorithm
- lacktriangle It produces a set of n mutually **orthogonal** vectors \mathbf{q}_i

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- However, classical Gram-Schmidt is numerically

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- Closely related to QR algorithm for eigen-decomposition
- Trefethen & Bau, Numerical Linear Algebra

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- Factorize A = QR
- Solve Q y = b
- Solution: $\mathbf{y} = \mathbf{Q}^\mathsf{T} \mathbf{b}$
- $\qquad \qquad \mathbf{Or} \quad y_i = (\mathbf{b} \cdot \mathbf{q}_i) \mathbf{q}_i$
- lacktriangle Then solve R lacktriangle lacktriangle by backward substitution

Summary

- $\blacksquare \text{ Power iteration } \mathbf{x}_{n+1} = \mathsf{A} \, \mathbf{x}_n$
- Converges to an eigenvector of A

- Orthogonality arises as a key concept
- We can orthogonalise a set of vectors using the Gram–Schmidt algorithm

■ This corresponds to a QR factorisation of a matrix