

电路理论

——二阶电路的暂态分析

主讲人: 刘旭

电气与电子工程学院

本章学习内容

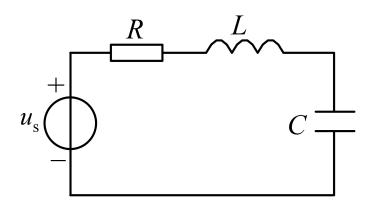
- 9.1 概述
- 9.2 零输入响应(自然响应)
- 9.3 直流电源激励下的响应

本章学习目标与难点

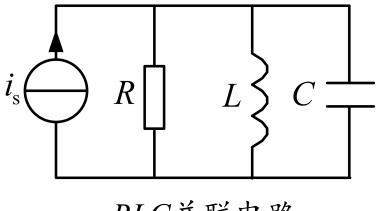
- 1. 掌握二阶电路零输入响应的变化规律; 2. 掌握直流电源激励的二阶电路响应计算
- 日标 方法; 3. 掌握自由分量与强制分量、暂态分量与 稳态分量、阶跃响应与冲激响应等概念。

理解自然响应的变化规律, 列写一般二阶 电路的微分方程。

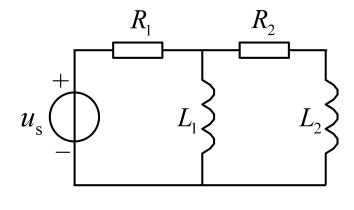
9.1 概述



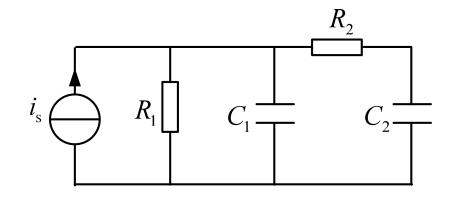
RLC串联电路



RLC并联电路



一般二阶RLL电路



一般二阶RCC电路

$$C = 0 \\ C = 0 \\ U_{C} \\ U_{C$$

$$\begin{cases} LC \frac{d^{2}u_{C}}{dt^{2}} + RC \frac{du_{C}}{dt} + u_{C} = 0 \\ u_{C}(0_{+}) = u_{C}(0_{-}) = U_{0} \\ \frac{du_{C}}{dt} \bigg|_{0_{+}} = \frac{i_{C}(0_{+})}{C} = \frac{i_{L}(0_{+})}{C} = 0 \end{cases}$$

特征方程: $LCs^2 + RCs + 1 = 0$

特征根:
$$s_{1,2} = \frac{-RC \pm \sqrt{(RC)^2 - 4LC}}{2LC} = -\frac{R}{2L} \pm \sqrt{(\frac{R}{2L})^2 - \frac{1}{LC}}$$

令
$$\alpha = \frac{R}{2L}$$
 (衰减系数), $\omega_0 = \sqrt{\frac{1}{LC}}$ (谐振角频率) $= -\alpha \pm \sqrt{\alpha^2 - \omega_0^2}$

特征根:

$$s_{1,2} = \frac{-RC \pm \sqrt{(RC)^2 - 4LC}}{2LC} = -\frac{R}{2L} \pm \sqrt{(\frac{R}{2L})^2 - \frac{1}{LC}} = -\alpha \pm \sqrt{\alpha^2 - \omega_0^2}$$

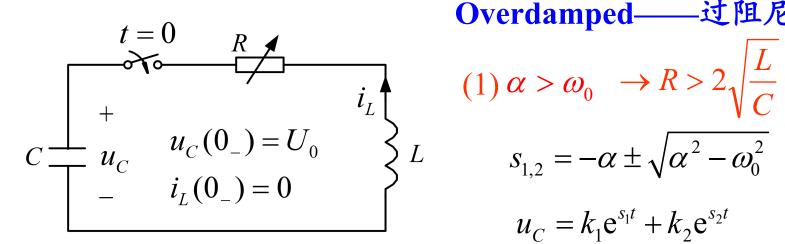
零状态响应的三种情况

(1)
$$\alpha > \omega_0 \rightarrow R > 2\sqrt{\frac{L}{C}}$$
 两个不相等负实根 过阻尼

(2)
$$\alpha < \omega_0 \rightarrow R < 2\sqrt{\frac{L}{C}}$$
 两个共轭复根 欠阻尼

(3)
$$\alpha = \omega_0 \rightarrow R = 2\sqrt{\frac{L}{C}}$$
 两个相等负实根

临界阻尼



$$u_{C}(0_{+}) = U_{0} \rightarrow k_{1} + k_{2} = U_{0}$$

$$\begin{vmatrix} du_{C} \\ dt \end{vmatrix}_{(0_{+})} \rightarrow s_{1}k_{1} + s_{2}k_{2} = 0$$

$$\begin{vmatrix} k_{1} = \frac{s_{2}}{s_{2} - s_{1}}U_{0} \\ k_{2} = \frac{-s_{1}}{s_{2} - s_{1}}U_{0} \end{vmatrix}$$

$$u_C = \frac{U_0}{s_2 - s_1} (s_2 e^{s_1 t} - s_1 e^{s_2 t})$$

Overdamped——过阻尼

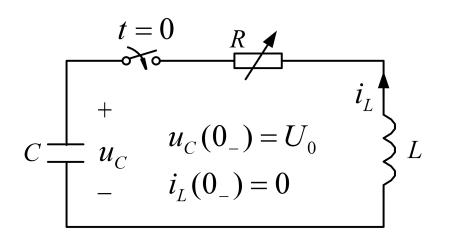
(1)
$$\alpha > \omega_0 \rightarrow R > 2\sqrt{\frac{L}{C}}$$

$$s_{1,2} = -\alpha \pm \sqrt{\alpha^2 - \omega_0^2}$$

$$u_C = k_1 e^{s_1 t} + k_2 e^{s_2 t}$$

$$\begin{cases} k_1 = \frac{s_2}{s_2 - s_1} U_0 \\ k_2 = \frac{-s_1}{s_2 - s_1} U_0 \end{cases}$$

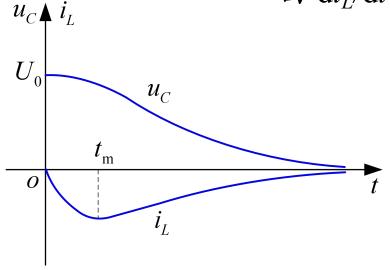
$$i_{\rm L} = C \frac{\mathrm{d}u_c}{\mathrm{d}t} = \frac{U_0}{L(s_2 - s_1)} (e^{s_1 t} - e^{s_2 t})$$



$$u_C = \frac{U_0}{s_2 - s_1} (s_2 e^{s_1 t} - s_1 e^{s_2 t})$$

$$i_{L} = C \frac{\mathrm{d}u_{c}}{\mathrm{d}t} = \frac{U_{0}}{L(s_{2} - s_{1})} (e^{s_{1}t} - e^{s_{2}t})$$

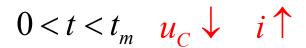
由 di_I/dt 可确定 i_I 为极小时的 t_m :

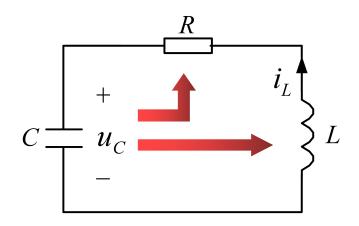


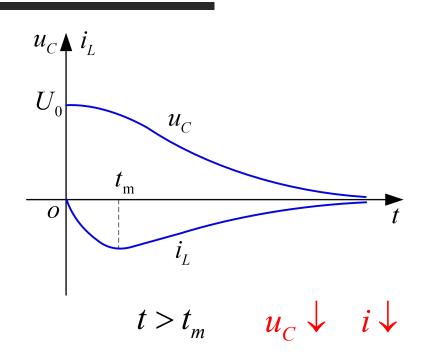
$$s_1 e^{s_1 t_m} - s_2 e^{s_2 t_m} = 0$$

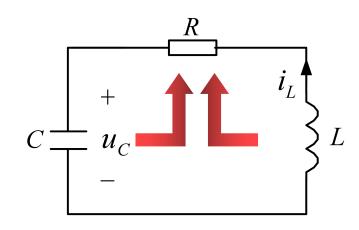
$$t_m = \frac{\ell n \frac{S_2}{S_1}}{S_1 - S_2}$$

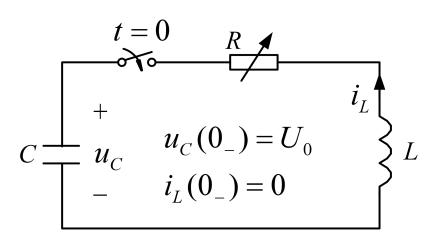
能量转换关系











underdamped——欠阻尼

(2)
$$\alpha < \omega_0 \rightarrow R < 2\sqrt{\frac{L}{C}}$$

$$i_L$$

$$\begin{cases} L & \omega_d = \sqrt{\omega_0^2 - \alpha^2} \quad \mathbf{B} \mathbf{f} \mathbf{k} \mathbf{5} \mathbf{5} \mathbf{5} \mathbf{5} \\ S & -\alpha + i\sqrt{\omega_0^2 - \alpha^2} = -\alpha + i\omega \end{cases}$$

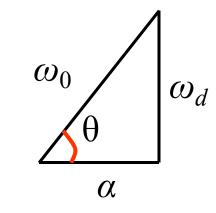
$$s_{1,2} = -\alpha \pm j\sqrt{\omega_0^2 - \alpha^2} = -\alpha \pm j\omega_d$$

$$u_C = k_1 e^{s_1 t} + k_2 e^{s_2 t} = k e^{-\alpha t} \sin(\omega_d t + \theta)$$

初始条件:

$$\begin{cases} u_C(0^+) = U_0 \to k \sin \theta = U_0 \\ \frac{du_C}{dt}(0^+) = 0 \to k(-\alpha) \sin \theta + k\omega_d \cos \theta = 0 \end{cases}$$

$$k = \frac{U_0}{\sin \theta}$$
, $\theta = arctg \frac{\omega_d}{\alpha}$ $\sin \theta = \frac{\omega_d}{\omega_0}$ $k = \frac{\omega_0}{\omega_d} U_0$



$$u_{C} = \frac{\omega_{0}}{\omega_{d}} U_{0} e^{-\alpha t} \sin(\omega_{d} t + \theta)$$

$$u_{C} \stackrel{\downarrow}{\downarrow} i_{L}$$

$$\pi - \theta < \omega_{d} t < \pi$$

$$\pi - \theta < \omega_{d} t < \pi$$

$$\pi - \theta < \omega_{d} t < \pi$$

$$\psi_{C} \stackrel{\downarrow}{\downarrow} i_{L}$$

$$\psi_{C} \stackrel{\downarrow} i_{L}$$

$$\psi_{C} \stackrel{\downarrow}{\downarrow} i_{L}$$

$$\psi_{C} \stackrel{\downarrow}{\downarrow} i_{L}$$

$$\psi_{C} \stackrel{\downarrow}$$

特例:
$$R=0$$
 时 $\alpha=0$, $\omega_d=\omega_0=\frac{1}{\sqrt{LC}}$, $\theta=\frac{\pi}{2}$

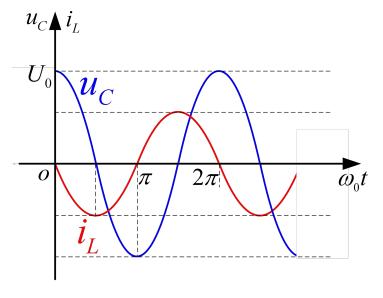
$$u_C = U_0 \sin(\omega_0 t + 90^\circ) = u_L$$

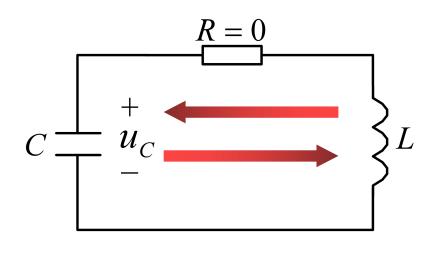
$$U_0$$

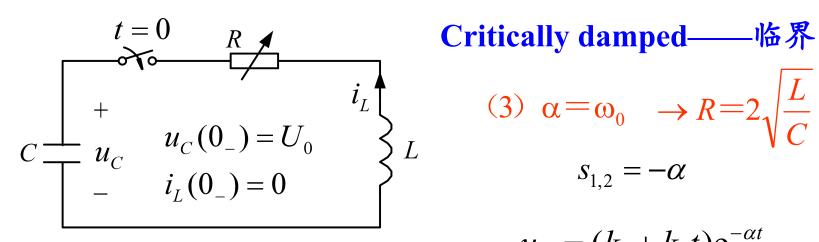
$$i = -\frac{U_0}{\omega_0 L} \sin \omega_0 t$$



等幅振荡







Critically damped——临界阻尼

(3)
$$\alpha = \omega_0 \rightarrow R = 2\sqrt{\frac{L}{C}}$$

$$s_{1,2} = -\alpha$$

$$u_C = (k_1 + k_2 t) e^{-\alpha t}$$

$$\begin{cases} k_1 = U_0 \\ k_2 = U_0 \alpha \end{cases}$$

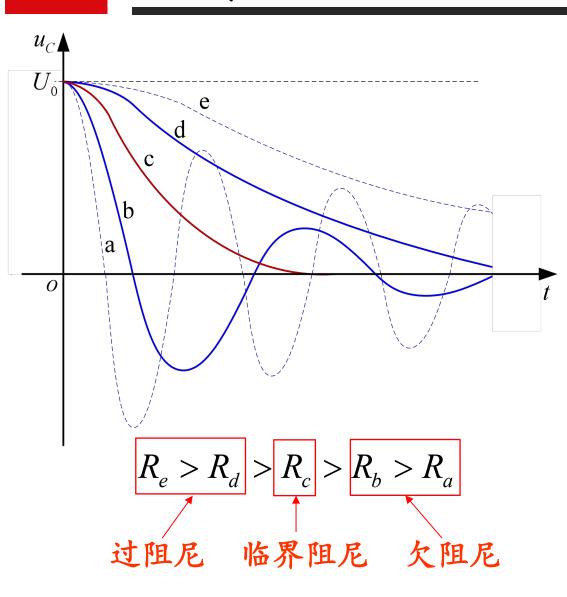
初始条件:

$$\begin{cases} u_c(0^+) = U_0 \to k_1 = U_0 \\ \frac{du_c}{dt}(0^+) = 0 \to k_1(-\alpha) + k_2 = 0 \end{cases}$$

$$u_C = U_0 e^{-\alpha t} (1 + \alpha t)$$

$$i_C = C \frac{du_C}{dt} = -\frac{U_0}{L} t e^{-\alpha t}$$

非振荡电路



$$R > 2\sqrt{\frac{L}{C}}$$
 过阻尼,
非振荡放电

$$u_C = k_1 e^{s_1 t} + k_2 e^{s_2 t}$$

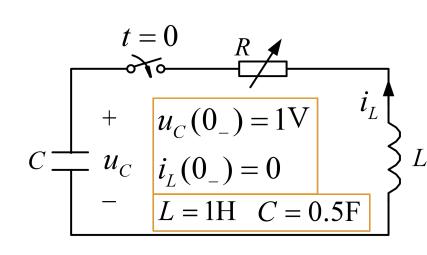
$$ightharpoonup R = 2\sqrt{\frac{L}{C}}$$
 临界阻尼,
非振荡放电

$$u_C = k_1 e^{-\alpha t} + k_2 t e^{-\alpha t}$$

$$R < 2\sqrt{\frac{L}{C}}$$
 欠阻尼,
振荡放电

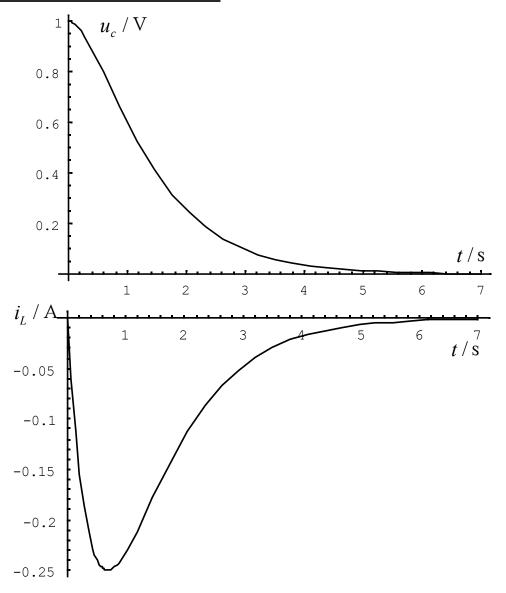
$$u_C = ke^{-\alpha t}\sin(\omega_d t + \theta)$$

Multisim仿真

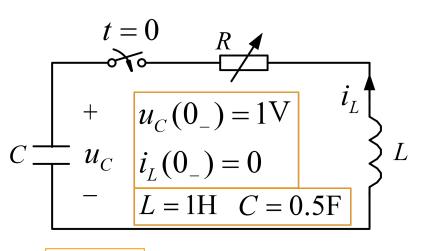


$R=3\Omega$ 过阻尼

$$\begin{bmatrix} u_c \\ i_L \end{bmatrix} = \begin{bmatrix} (2e^{-t} - e^{-2t})V \\ (-e^{-t} + e^{-2t})A \end{bmatrix}$$

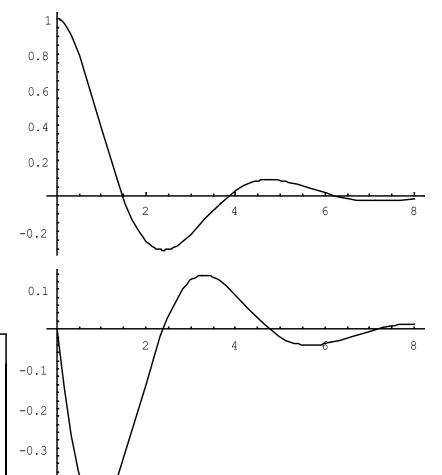


Multisim仿真

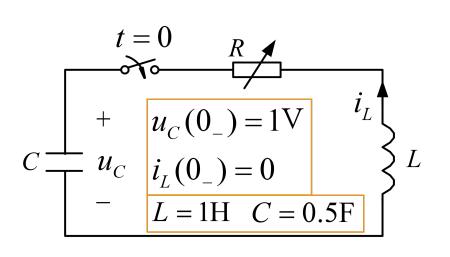


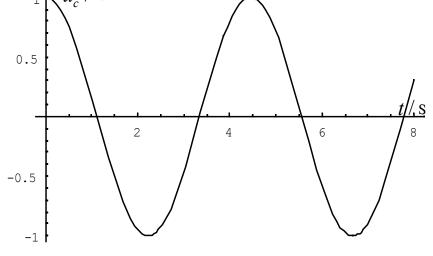
$R=1\Omega$ 欠阻尼

$$\begin{bmatrix} u_C \\ i_L \end{bmatrix} = \begin{bmatrix} e^{-0.5t} (\cos \frac{\sqrt{7}}{2}t + \frac{1}{\sqrt{7}} \sin \frac{\sqrt{7}}{2}t) V \\ (-\frac{2}{\sqrt{7}} e^{-0.5t} \sin \frac{\sqrt{7}}{2}t) A \end{bmatrix}_{-0.4}^{-0.1}$$



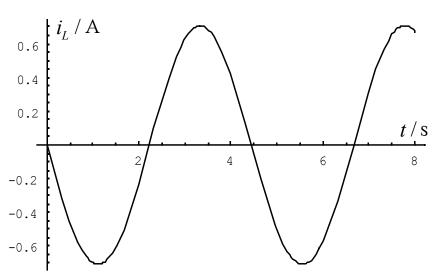
Multisim仿真



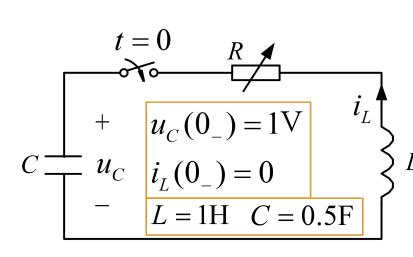


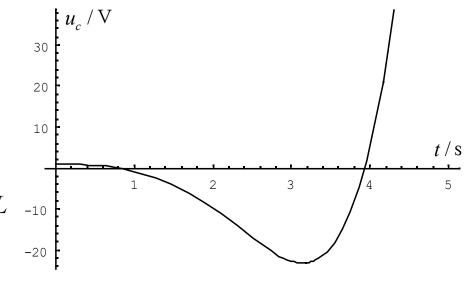
R=0 无阻尼

$$\begin{bmatrix} u_C \\ i_L \end{bmatrix} = \begin{bmatrix} (\cos\sqrt{2}t)V \\ (-\frac{1}{\sqrt{2}}\sin\sqrt{2}t)A \end{bmatrix}$$



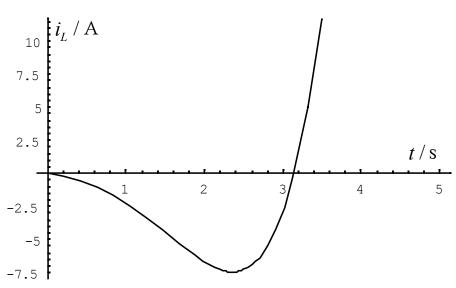
Multisim仿真





$R = -2\Omega$ 负阻尼

$$\begin{bmatrix} u_C \\ i_L \end{bmatrix} = \begin{bmatrix} e^t (\cos t - \sin t) V \\ (-e^t \sin t) A \end{bmatrix}$$



以阶跃响应为例来分析二阶RLC电路的零状态响应。

1. RLC串联电路的阶跃响应

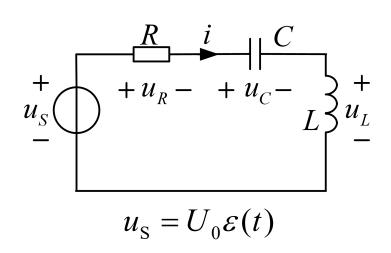
根据KVL和支路电压-电流关系,可得

$$LC\frac{d^2u_C}{dt^2} + RC\frac{du_C}{dt} + u_C = U_0$$

二阶常系数线性非齐次微分方程

初始条件为: $u_C(0_+)=u_C(0_-)=0$

$$i_L(0_+)=i_L(0_-)=0$$



特征根(固有频率)
$$\begin{cases} s_1 = -\alpha + \sqrt{\alpha^2 - \omega_0} \\ s_2 = -\alpha - \sqrt{\alpha^2 - \omega_0} \end{cases}$$

与RLC串联电路零输入响应一样,RLC串联电路的固有频率 S_1 和 S_2 也可以是两个不相等的负实数,两个相等的负实数,一对共轭复数和一对共轭虚数。

阶跃激励下的稳态分量 $u_{Cp}=U_0$

$$u_C = u_{Ch} + u_{Cp} = K_1 e^{s_1 t} + K_2 e^{s_2 t} + U_0$$

根据初始条件,有 $\begin{cases} u_C(0_+) = K_1 + K_2 + U_0 = 0 \\ \frac{du_C}{dt} \Big|_{t=0_+} = K_1 s_1 + K_2 s_2 = 0 \end{cases}$

$$K_1 = \frac{S_2}{S_1 - S_2} U_0, \quad K_2 = \frac{S_1}{S_2 - S_1} U_0$$

电容电压为

$$u_{C} = \left[\frac{1}{s_{1} - s_{2}} (s_{2}e^{s_{1}t} - s_{1}e^{s_{2}t}) + 1 \right] U_{0}\varepsilon(t)$$

RLC串联充电电路也可以区分为:

1.过阻尼
$$\alpha > \omega_0$$
 电路参数满足 $R > 2\sqrt{L/C}$

$$2.$$
临界阻尼 $\alpha = \omega_0$

$$R = 2\sqrt{L/C}$$

$$3.$$
欠阻尼 $\alpha < \omega_0$

$$R < 2\sqrt{L/C}$$

4. 无阻尼
$$\alpha=0$$
 (即 $R=0$)

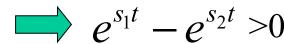
下面仅讨论过阻尼和欠阻尼两种不同情况的阶跃响应。

1.过阻尼

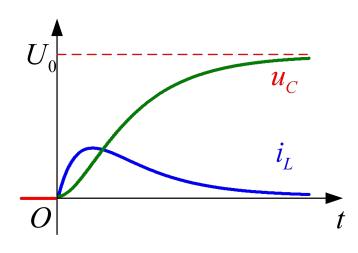
$$u_{C} = \left[\frac{1}{s_{1} - s_{2}} (s_{2}e^{s_{1}t} - s_{1}e^{s_{2}t}) + 1 \right] U_{0}\varepsilon(t)$$

$$i_L = i = C \frac{du_C}{dt} = \frac{s_1 s_2}{L(s_1 - s_2)} (e^{s_1 t} - e^{s_2 t}) U_0 \varepsilon(t)$$

由于
$$s_1 < 0$$
、 $s_2 < 0$ 及 $|s_2| > |s_1|$ $e^{s_1 t} - e^{s_2 t} > 0$



使电容电压 u_C 和电感电流 i_L 永 U_0 远不改变方向。电容元件在全 部时间内一直在充电。



2.欠阻尼

$$\begin{cases} s_1 = -\alpha + \sqrt{-(\omega_0^2 - \alpha^2)} = -\alpha + j\omega_d \\ s_2 = -\alpha - \sqrt{-(\omega_0^2 - \alpha^2)} = -\alpha - j\omega_d \end{cases}$$

或表示成极坐标形式
$$\begin{cases} s_1 = \omega_0 e^{j(90^\circ + \theta)} \\ s_1 = \omega_0 e^{-j(90^\circ + \theta)} \end{cases}$$

其中 θ = arctan($\alpha/\omega d$)

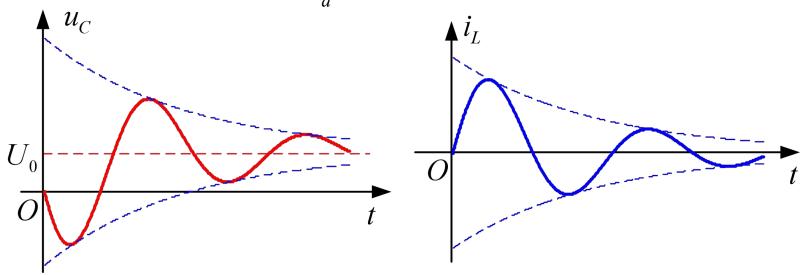
电容电压
$$u_C = \left\{1 + \frac{1}{2j\omega_d}\omega_0 e^{-\alpha t} \left[e^{j(j\omega_d t - 90^\circ - \theta)} - e^{-j(j\omega_d t - 90^\circ - \theta)}\right]\right\} U_0 \varepsilon(t)$$

$$= \left[1 + \frac{\omega_0}{\omega_d} e^{-\alpha t} \sin(\omega_d t - 90^\circ - \theta)\right] U_0 \varepsilon(t)$$

$$= \left[1 - \frac{\omega_0}{\omega_d} e^{-\alpha t} \cos(\omega_d t - \theta)\right] U_0 \varepsilon(t)$$

根据电容的电压-电流关系 $i = Cdu_C/dt$

$$i_{L} = i = \left(\frac{1}{\omega_{d}L}e^{-\alpha t}\sin\omega_{d}t\right)U_{0}\varepsilon(t)$$



2023-4-17

电路理论(64学时)

例9-1 求 $i_{L}(t>0)$

初始条件:

$$u_C(0_+) = u_C(0_-) = 15V$$

 $i_L(0_+) = i_L(0_-) = 0$

$$\frac{du_C}{dt}\Big|_{0} = \frac{i_C(0_+)}{C} = \frac{i_L(0_+)}{C} = 0$$

$$\left. \frac{\mathrm{d}u_C}{\mathrm{d}t} \right|_{0_+} = \frac{\iota_C(0_+)}{C} = \frac{\iota_L(0_+)}{C} = 0$$

微分方程:
$$0.5 \frac{d}{dt} \left(\frac{2}{19} \frac{du_C}{dt} \right) + 10 \left(\frac{2}{19} \frac{du_C}{dt} - 1 \right) + u_C = 0$$

$$\Rightarrow \frac{\mathrm{d}^2 u_C}{\mathrm{d}t^2} + 20 \frac{\mathrm{d}u_C}{\mathrm{d}t} + 19 u_C = 190$$

 10Ω

 $u_{\rm C}(0_{-}) = 15 \,\mathrm{V}, \ i_{\rm L}(0_{-}) = 0$

0.5H

$$\frac{d^{2}u_{C}}{dt^{2}} + 20\frac{du_{C}}{dt} + 19u_{C} = 190$$

$$u_{C}(0_{+}) = u_{C}(0_{-}) = 15V$$

$$i_L(0_+) = i_L(0_-) = 0$$

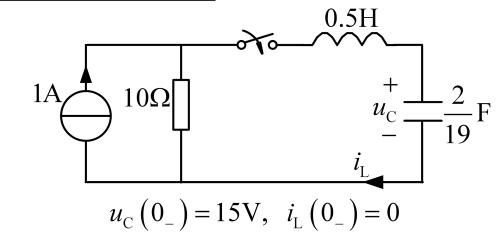
$$\frac{du_C}{dt}\Big|_{0_+} = \frac{i_C(0_+)}{C} = \frac{i_L(0_+)}{C} = 0$$

$$p_{1,2} = -10 \pm \sqrt{100 - 19} = \begin{cases} -1 \\ -19 \end{cases}$$

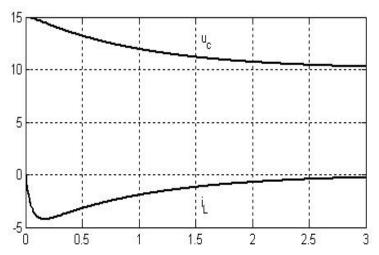
$$u_C = k_1 e^{-t} + k_1 e^{-19t} + 10$$

$$k_1 = \frac{95}{18} \quad k_2 = -\frac{5}{18}$$

2023-4-17



$$i_L = C \frac{\mathrm{d}u_C}{\mathrm{d}t} = -\frac{95}{18}e^{-t} + \frac{95}{18}e^{-19t}$$



课后作业

●9.2节: 9-5, 9-7, 9-9

●9.3节: 9-13, 9-15

谢谢聆听!!

刘旭 2023-4-17