Temporal Biased Streaming Submodular Optimization

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Data Streams

- Big data:
 - online social networks
 - Internet of things
 - mobile devices
 - ...
- Data streams: "3V" challenges
 - Volume: in TBs even PBs
 - Velocity: K/s (≈9500 tweets/sec)
 - Variety: texts, images, video, numerical data, etc.













information overload

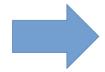
Data Stream Summarization

 Goal: use a carefully chosen subset of items to represent the stream at any time point

Challenges:

- data items arrives at a very fast speed
- each data item can only be visited once
- random access to the entire data is not allowed
- only a small fraction of the data can be loaded into memory





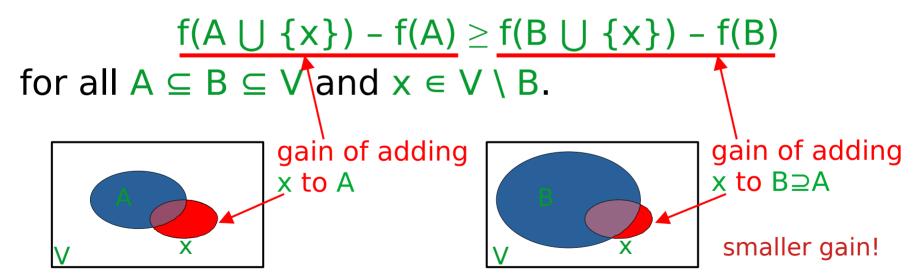


surveillance camera

summary

Submodularity

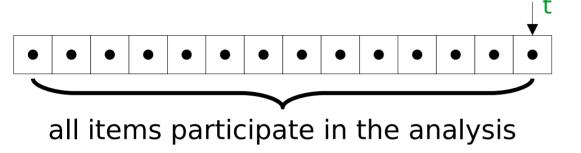
- Submodularity is a natural model for
 - representativeness, informativeness, diversity, coverage
- A set function $f: 2^{\vee} \mapsto \mathbb{R}_{>0}$ is submodular if



Captures the diminishing returns property

Streaming Submodular Optimization (SSO)

SSO for insertion-only streams [KDD'14]



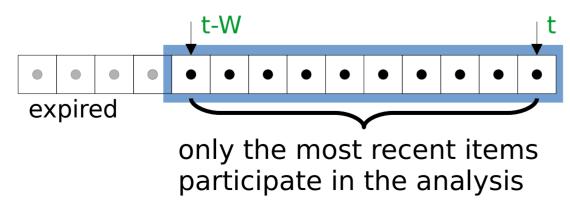
cons:

 all items are treated equally regardless of how outdated they are

two

extremes

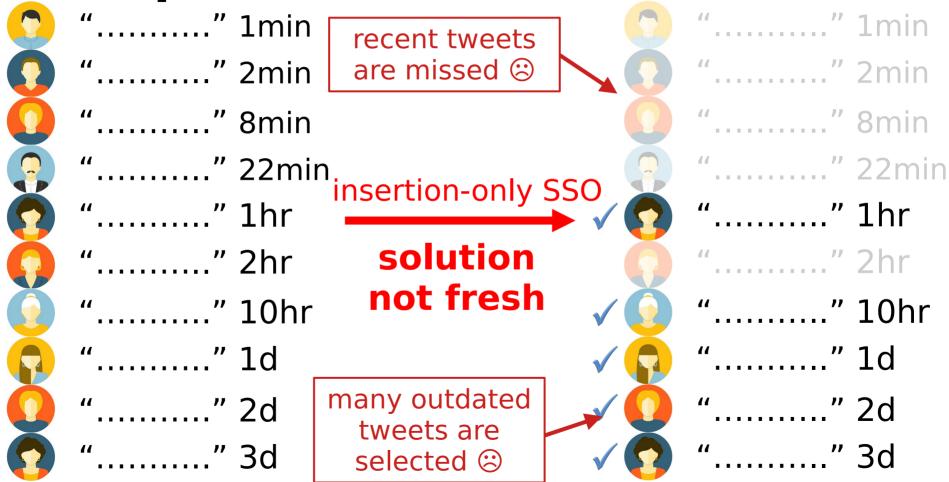
SSO for sliding-window streams [WWW'17]



cons:

 abruptly forgets all past data which may be still important

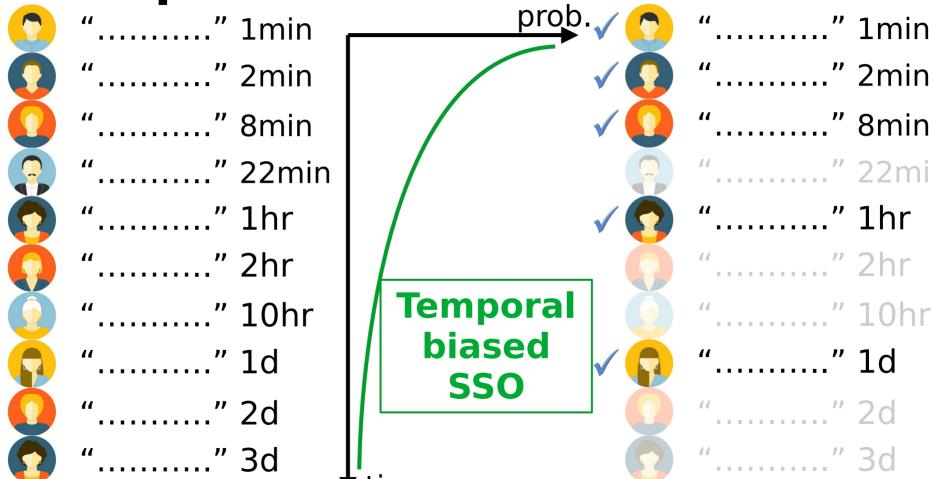
Example: Tweets Recommendation



Example: Tweets Recommendation



Example: Tweets Recommendation



Outline

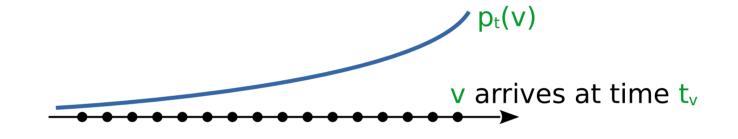
Background & Motivation



- **□** TBSSO Problem Formulation
 - Algorithms
 - Experiments
 - Conclusion

Temporal Biased Stream Model

 Each item v participates in the analysis with a probability p_t(v) decreasing over time.



- and p_t(v) ≜ h(t t_v) where h: Z → [0,1] assigns an item of age x a participation probability h(x), called the decay function, e.g.,
 - $-h(x) = p_0 e^{-\lambda x}$, i.e., an exponential decay function

Temporal Biased SSO Problem

TBSSO Problem formulation:

- Given a stream of items $S_t = \{v \in V: t_v \le t\}$ with decay function h(x),
- Want to find k items $S\subseteq V$ that maximize $\mathbb{E}_h[f(S|S_t)]$ at any query time t.

- The TBSSO problem generalizes previous settings:
 - If h(x) = 1, $\forall x$, then becomes insertion-only SSO.
 - If h(x) = 1 for $x \le W$, and h(x) = 0 otherwise, then becomes sliding-window SSO.

Outline

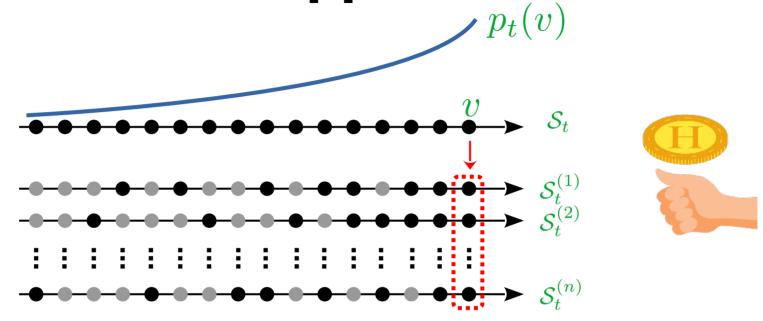
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How to Calculate $\mathbb{E}_h[f(S|S_t)]$?

Example:

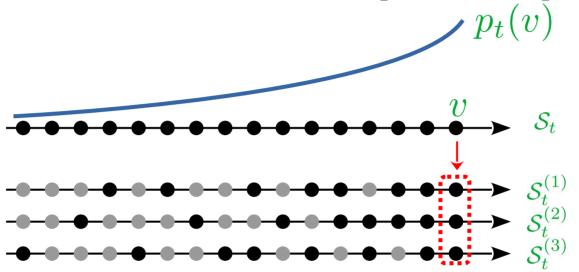
- Exactly calculating $\mathbb{E}_h[f(S|S_t)]$ needs $O(2^{|S|})$ oracle calls,
 - one oracle call refers to one evaluation of f.
- Too expensive!

Monte-Carlo Approximation



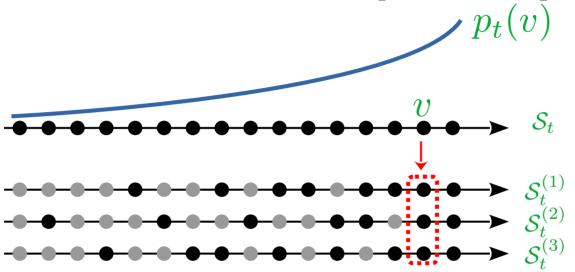
$$F(S) \triangleq \frac{1}{n} \sum_{i=1}^{n} f(S \cap \mathcal{S}_{t}^{(i)}) \xrightarrow{a.s.} \mathbb{E}_{h}[f(S|\mathcal{S}_{t})] \text{ as } n \to \infty$$

require n oracle calls, $n \ll 2^{|S|}$



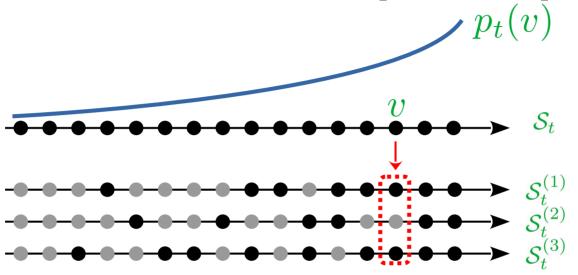
$$I_l(v) \triangleq \{i : v \in \mathcal{S}_t^{(i)} \land t_v + l = t\}$$

$$I_0(v) = \{1, 2, 3\}$$



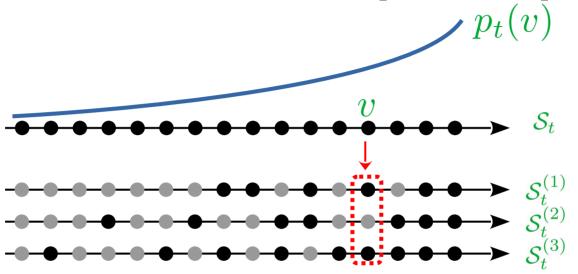
$$I_l(v) \triangleq \{i : v \in \mathcal{S}_t^{(i)} \land t_v + l = t\}$$

$$I_1(v) = \{1, 2, 3\}$$



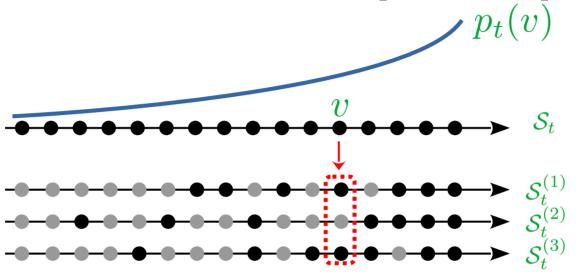
$$I_l(v) \triangleq \{i : v \in \mathcal{S}_t^{(i)} \land t_v + l = t\}$$

$$I_2(v) = \{1, 3\}$$



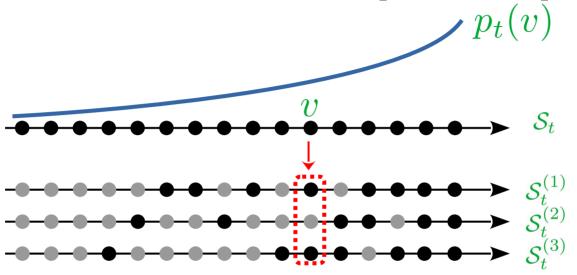
$$I_l(v) \triangleq \{i : v \in \mathcal{S}_t^{(i)} \land t_v + l = t\}$$

$$I_3(v) = \{1, 3\}$$



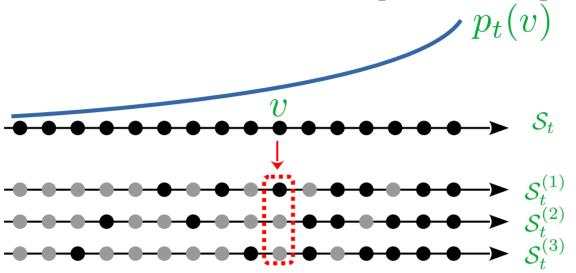
$$I_l(v) \triangleq \{i : v \in \mathcal{S}_t^{(i)} \land t_v + l = t\}$$

$$I_4(v) = \{1, 3\}$$



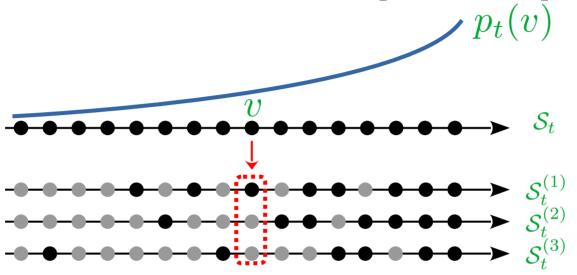
$$I_l(v) \triangleq \{i : v \in \mathcal{S}_t^{(i)} \land t_v + l = t\}$$

$$I_5(v) = \{1, 3\}$$



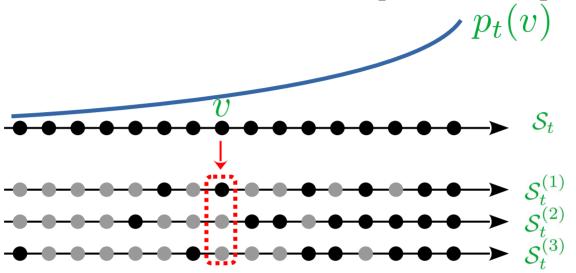
$$I_l(v) \triangleq \{i : v \in \mathcal{S}_t^{(i)} \land t_v + l = t\}$$

$$I_6(v) = \{1\}$$



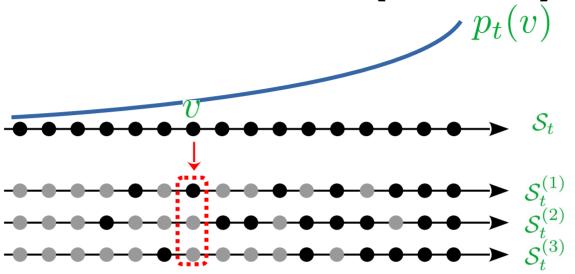
$$I_l(v) \triangleq \{i : v \in \mathcal{S}_t^{(i)} \land t_v + l = t\}$$

$$I_7(v) = \{1\}$$



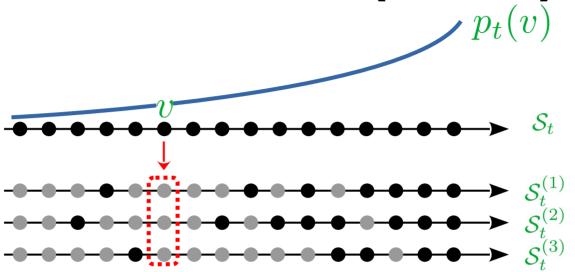
$$I_l(v) \triangleq \{i : v \in \mathcal{S}_t^{(i)} \land t_v + l = t\}$$

$$I_8(v) = \{1\}$$



$$I_l(v) \triangleq \{i : v \in \mathcal{S}_t^{(i)} \land t_v + l = t\}$$

$$I_9(v) = \{1\}$$



• B-set of an item v at time $t_v + l$:

$$I_l(v) \triangleq \{i : v \in \mathcal{S}_t^{(i)} \land t_v + l = t\}$$

 $I_{10}(v) = \emptyset$

- Eventually, a B-set will shrink to an empty set.
- · B-set is another way to represent probabilistic decays.

The Non-Decaying Case

$$p_t(v) = p_0 \in [0, 1]$$

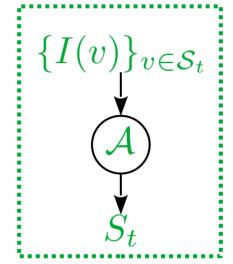
$$S_t$$

$$S_t$$

$$S_t^{(1)}$$

$$S_t^{(2)}$$

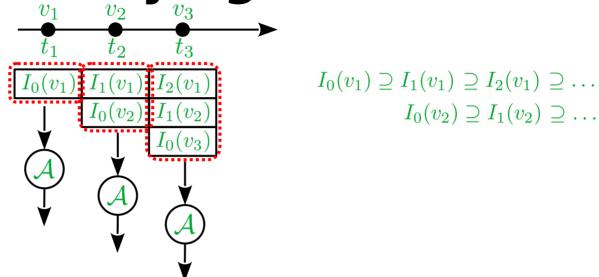
$$S_t^{(3)}$$



Atom

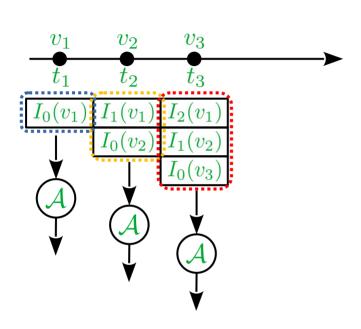
- Each item's B-set is a constant set.
- The stream becomes an insertion-only stream, where each item in the stream is a B-set, i.e., $\{I(v): v \in \mathcal{S}_t\}$
- Many insertion-only SSO algorithms can be applied.
 - denote one implementation by Atom.

The Decaying Case

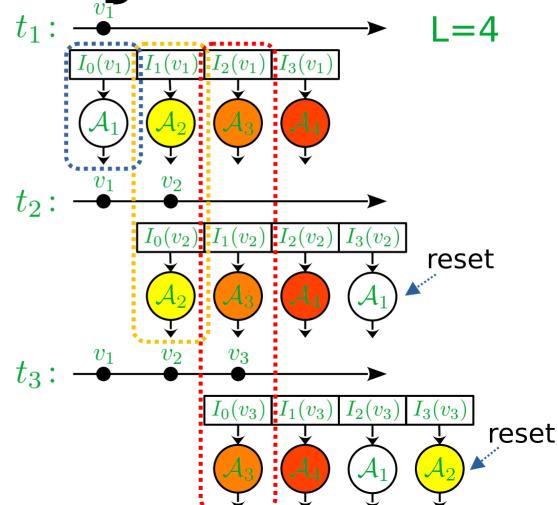


- Idea: If we can feed the B-sets at each time point to an Atom instance, then the instance's output will be the solution of the TBSSO problem at the time point.
- Challenge: Each B-set is shrinking, how to process these evolving B-sets in a streaming fashion?

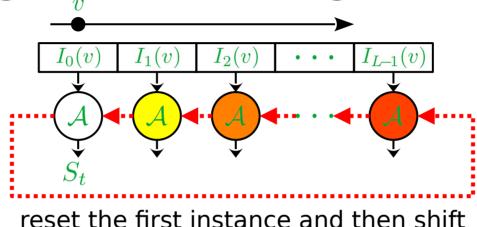
A Basic Algorithm



 Assume each item has at most L nonempty B-sets.



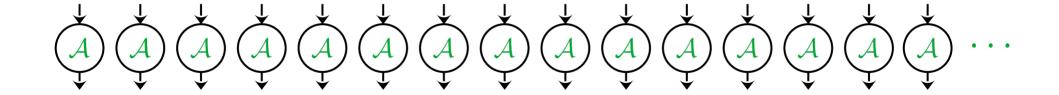
Basic Alg: Processing and Shifting



- For each item v, obtain its B-sets $\{I_l(v): 0 \le l < L\}$;
- Feed these B-sets to L Atom instances, respectively;
- Reset the first instance and circularly shift these instances before processing the next item;
- The first Atom instance's out is always the solution.

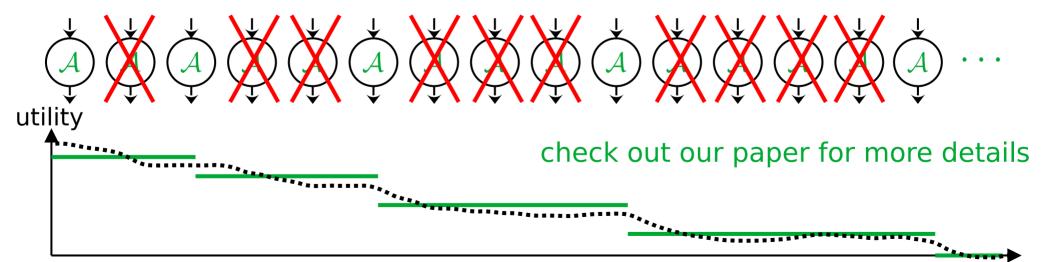
Limitations of the Basic Algorithm

- What if L is very large, e.g., L = ∞?
- Weakness: Maintaining a large number of Atom instances will incur too much RAM and CPU overloads.



A Faster Algorithm

- Idea: remove redundant Atom instances
 - trick 1: group same B-sets into one segment, each segment needs only one Atom instance;
 - trick 2: remove Atom instances that have close outputs
- Similar to use a histogram to approximate a curve.



Summary

Algorithm	Approx. Ratio	Update Time	Space
Atom	α	β	X
Basic Alg.	α	O(Lβ)	O(L _y)
Fast Alg.	α(1-ε)/2	O(βε ⁻¹ log k)	O(γε ⁻¹ log k)

- For example, if Atom is implemented by adapting SieveStreaming [KDD'14], then
 - $-\alpha=1/2-\epsilon$
 - $-\beta = O(n\epsilon^{-1}\log k)$
 - $\gamma = O(nk\epsilon^{-1}log k)$

Outline

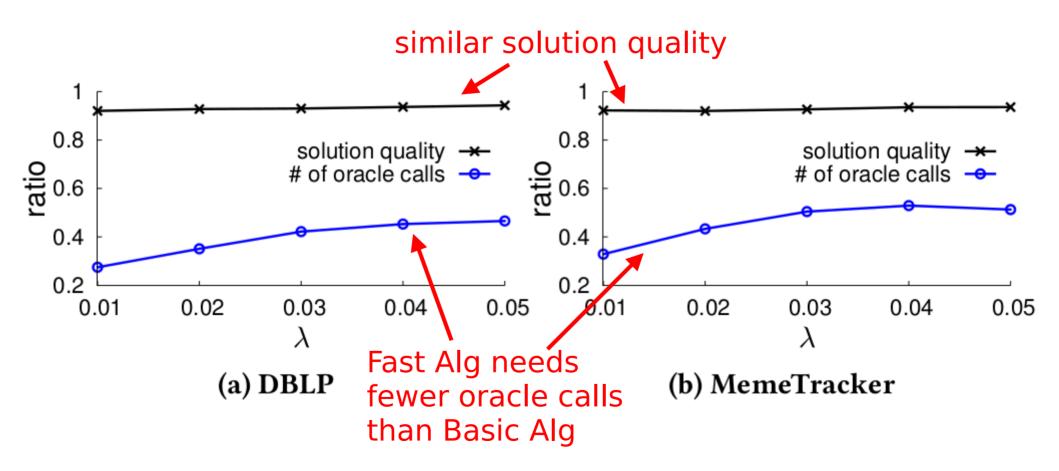
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Dataset

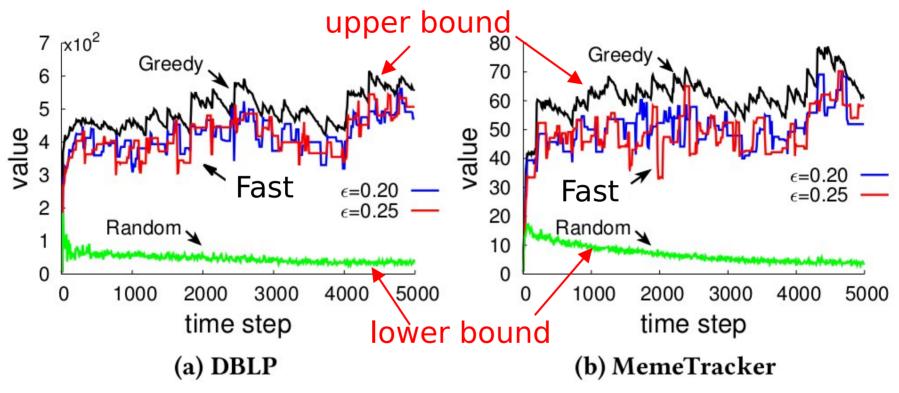
data stream	element	length	time period
DBLP [9]	author	372K	1936 - 2018
MemeTracker [21]	article	714K	1/1/2009 - 31/1/2009
StackOverflow [26]	question	2.9M	1/1/2015 - 1/3/2016
US2020-Tweets [11]	tweet	1.7M	15/10/2020 - 8/11/2020

- Goal: maintain k items that have the maximum coverage, i.e., $f(S) = |U_{v \in S} v|$ where each item is a set.
- Decay function: $h(x) = e^{-\lambda x}$, $\lambda \ge 0$.
- Baselines:
 - Greedy: uses the lazy evaluation trick, non-streaming;
 - Random: randomly select k items.

Basic Alg. vs Fast Alg.

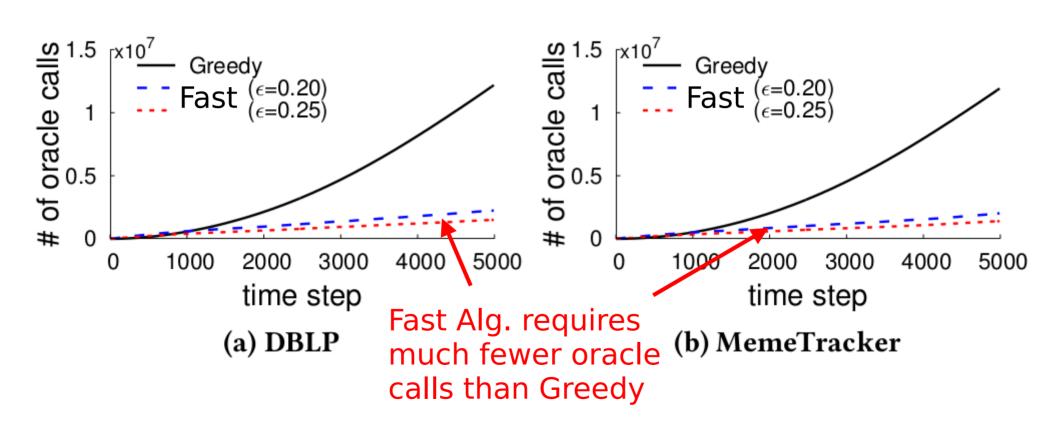


Solution Quality



• The fast algorithm is close to the solution quality of Greedy, and is much better than the Random.

Computational Efficiency



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- Experiments



Conclusion

- A novel Temporal Biased Streaming Submodular Optimization problem.
- Can be reduced to SSO over insertion-only streams.
- The proposed algorithm can find near-optimal solutions with much fewer costs than baselines.

Algorithm	Approx. Ratio	Update Time	Space
Atom	α	β	X
Basic Alg.	α	Ο(Lβ)	O(L _X)
Fast Alg.	α(1-ε)/2	O(βε ⁻¹ log k)	O(γε ⁻¹ log k)

Thanks for Listening!