

Reševanje linearnih elastostatičnih problemov z brez mrežnimi metodami

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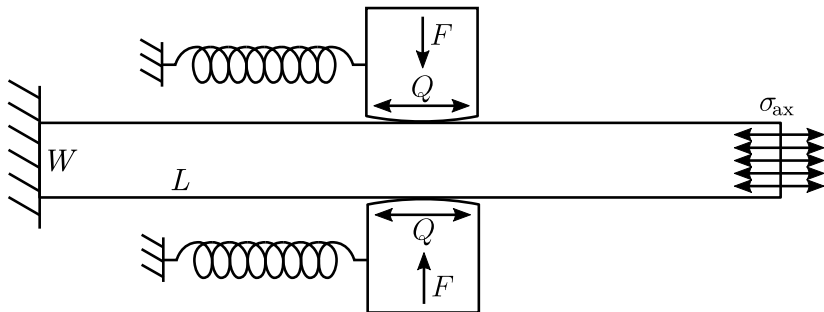
mentor: doc. dr. George Mejak
somentor: dr. Gregor Kosec, IJS

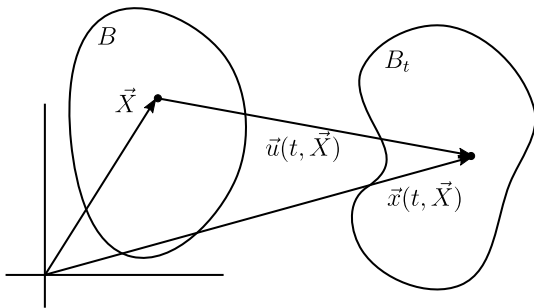


Ljubljana, 5. 9. 2017

Ciljni primer

- Želimo poznati napetosti in pomike v okolici stika





Aksioma o gibalni in vrtilni količini

$$\frac{d}{dt} \int_B \dot{\vec{x}} dm = \int_B \vec{f} dV + \int_{\partial B} \vec{t} dS$$

$$\frac{d}{dt} \int_B \dot{\vec{x}} \times \vec{x} dm = \int_B \vec{f} \times \vec{x} dV + \int_{\partial B} \vec{t} \times \vec{x} dS$$

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⇒ sledi

Navierova enačba

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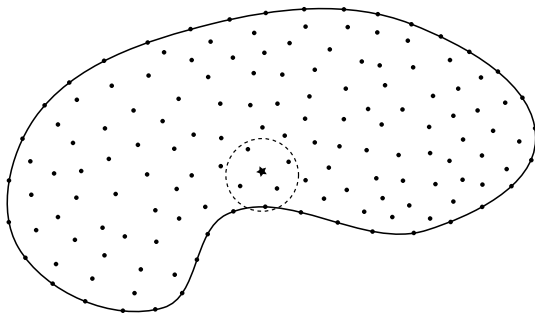
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stacionarna enačba, robni pogoji?

- ▶ Rešujemo enačbo

$$\begin{aligned}\mathcal{L}u &= f & \text{na } \Omega, \\ \mathcal{R}u &= g & \text{na } \partial\Omega.\end{aligned}$$

- ▶ Brezmrežna metoda, v močni obliki.



Aproksimacija linearnega parcialnega diferencialnega operatorja

- ▶ Ideja: $(\mathcal{L}u)(x) \approx (\mathcal{L}\hat{u})(x), \quad \hat{u}(x) = \sum_{i=1}^m \alpha_i b_i(x)$
- ▶ Zahtevamo interpolacijo v sosednjih točkah

$$\hat{u}(x_i) = u(x_i), \quad \forall x_i \text{ sosed } x$$

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$$\begin{bmatrix} b_1(x_1) & \dots & b_m(x_1) \\ \vdots & \ddots & \vdots \\ b_1(x_n) & \dots & b_m(x_n) \end{bmatrix} \begin{bmatrix} \alpha_1 \\ \vdots \\ \alpha_m \end{bmatrix} = \begin{bmatrix} u_1 \\ \vdots \\ u_n \end{bmatrix}$$

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- ▶ Sistem $B\alpha = u$
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⇒ sledi

$$\hat{u}(x) = b(x)^T \alpha = b(x)^T (WB)^+ Wu$$

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► Rešitev $\alpha = (WB)^+ Wu$

⇒ sledi

$$\hat{u}(x) = b(x)^\top \alpha = b(x)^\top (WB)^+ Wu$$

⇒ sledi

$$(\mathcal{L}u)(x) \approx (\mathcal{L}\hat{u})(x) = \underbrace{(\mathcal{L}b)(x)^\top (WB)^+ Wu}_{\varphi(x)}$$

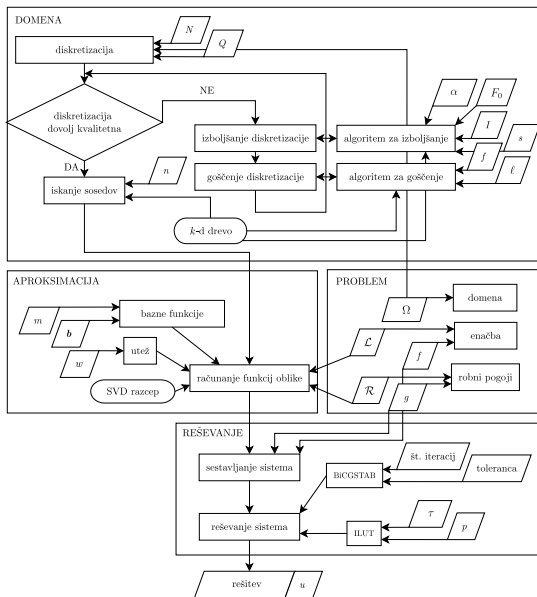
1. Izračunamo $\varphi(x)$ za vsak x in nastavimo enačbe

$$\varphi(x)u = f$$

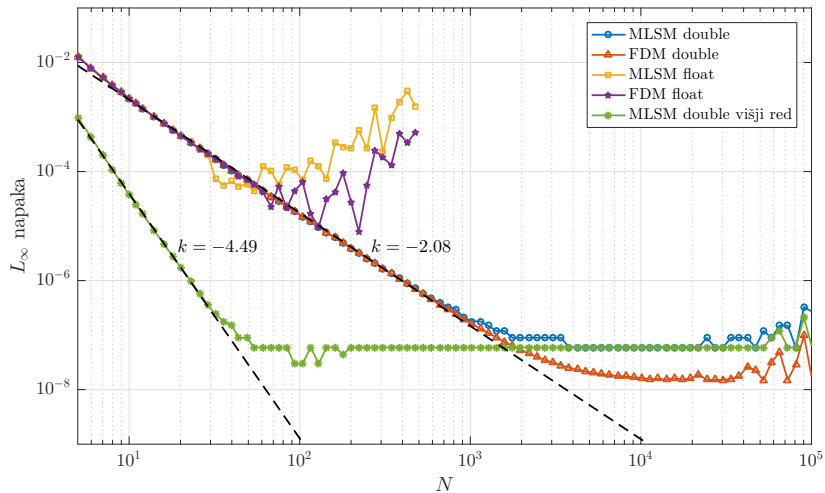
2. Zložimo v matriko A in nastavimo robne pogoje

3. Rešimo razpršen sistem $Au = f$

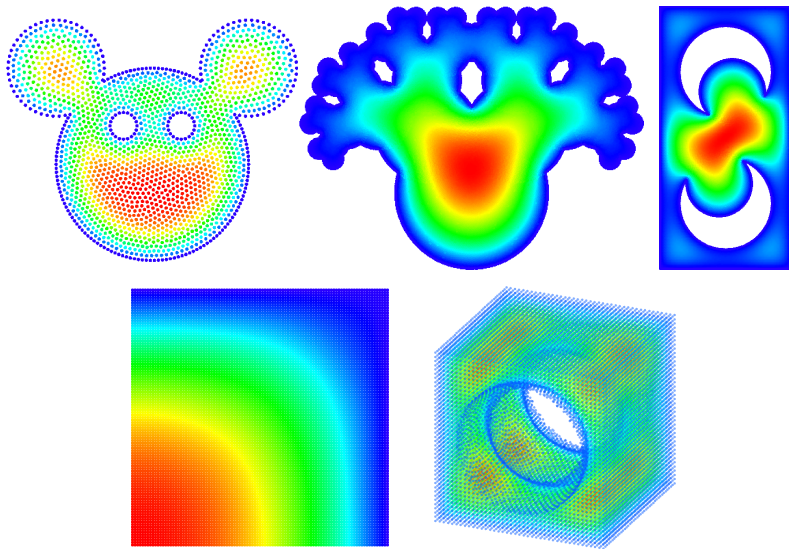
Implementacija



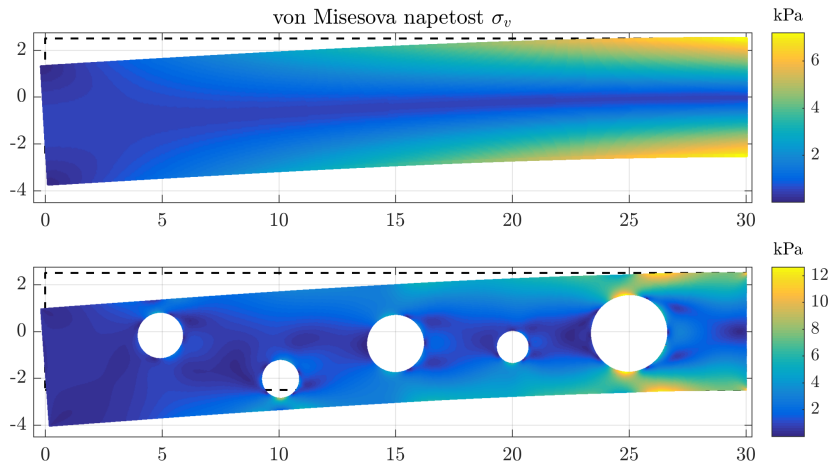
Primerjava s FDM



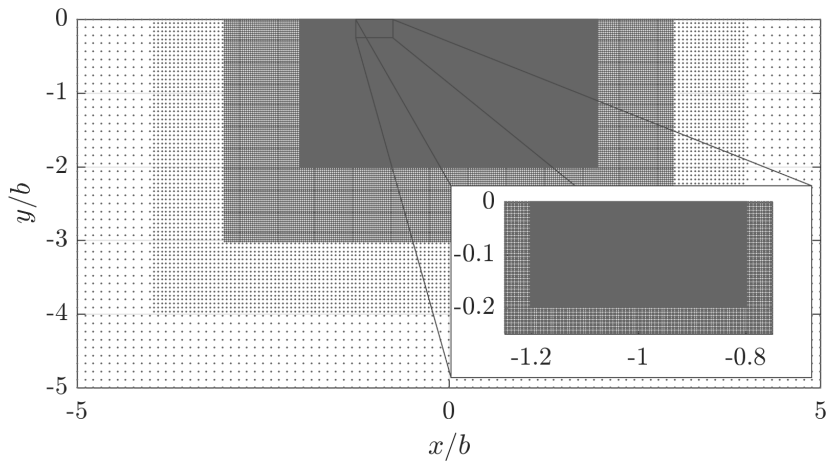
Difuzijska enačba



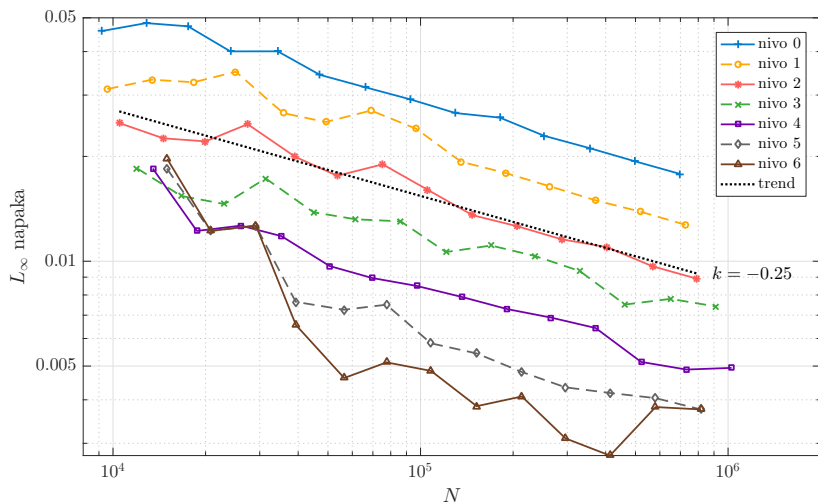
Vpet nosilec – rešitev



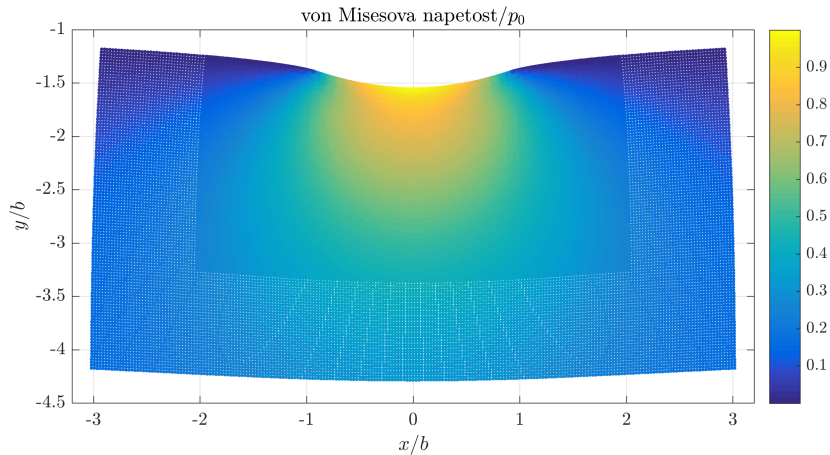
Hertzev kontakt – domena



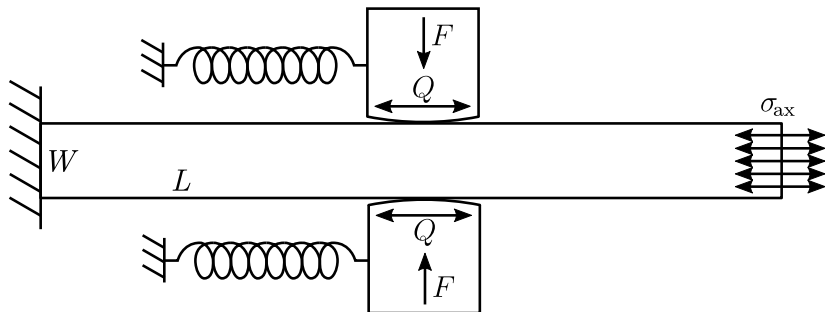
Hertzev kontakt – konvergenca



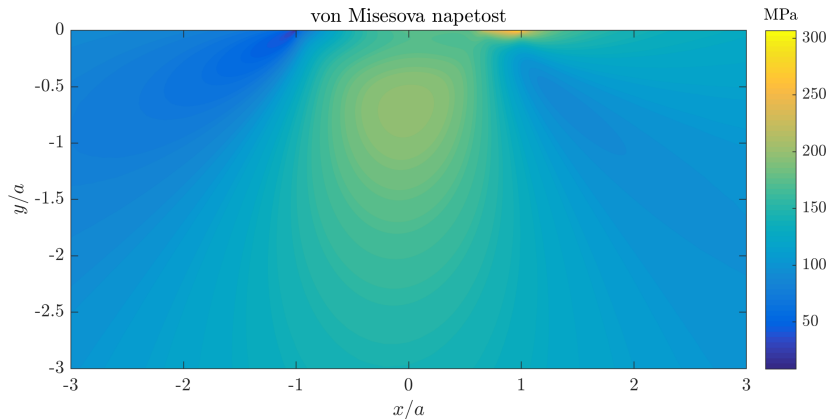
Hertzev kontakt – rešitev



Ciljni primer



Ciljni primer – rešitev



Nauk

Z brezmrežnimi metodami je mogoče uspešno in učinkovito reševati probleme iz linearne elastomehanike.

Hvala za pozornost!