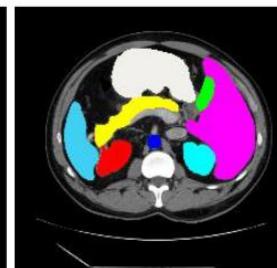
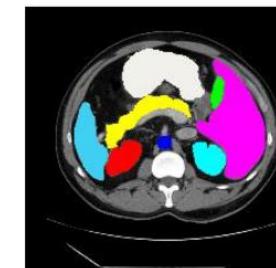
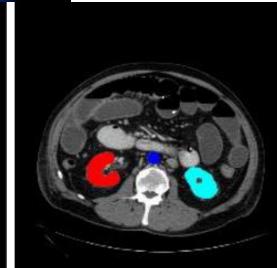
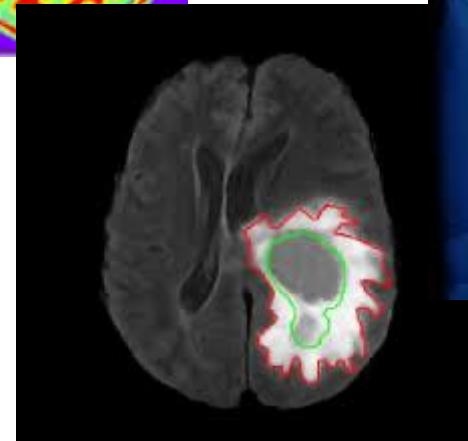
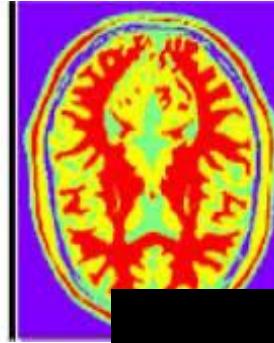
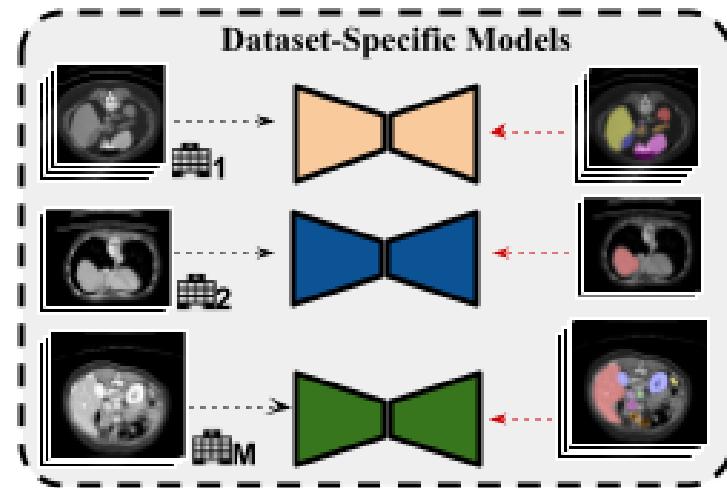


Foundation models for medical image segmentation

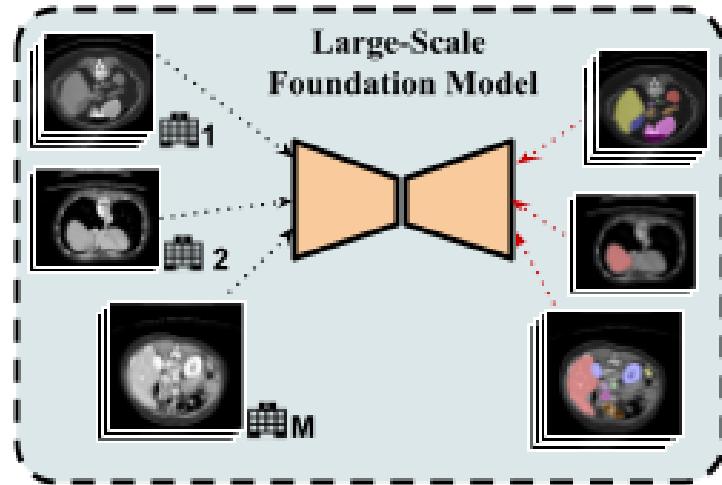


Foundation models for medical image segmentation

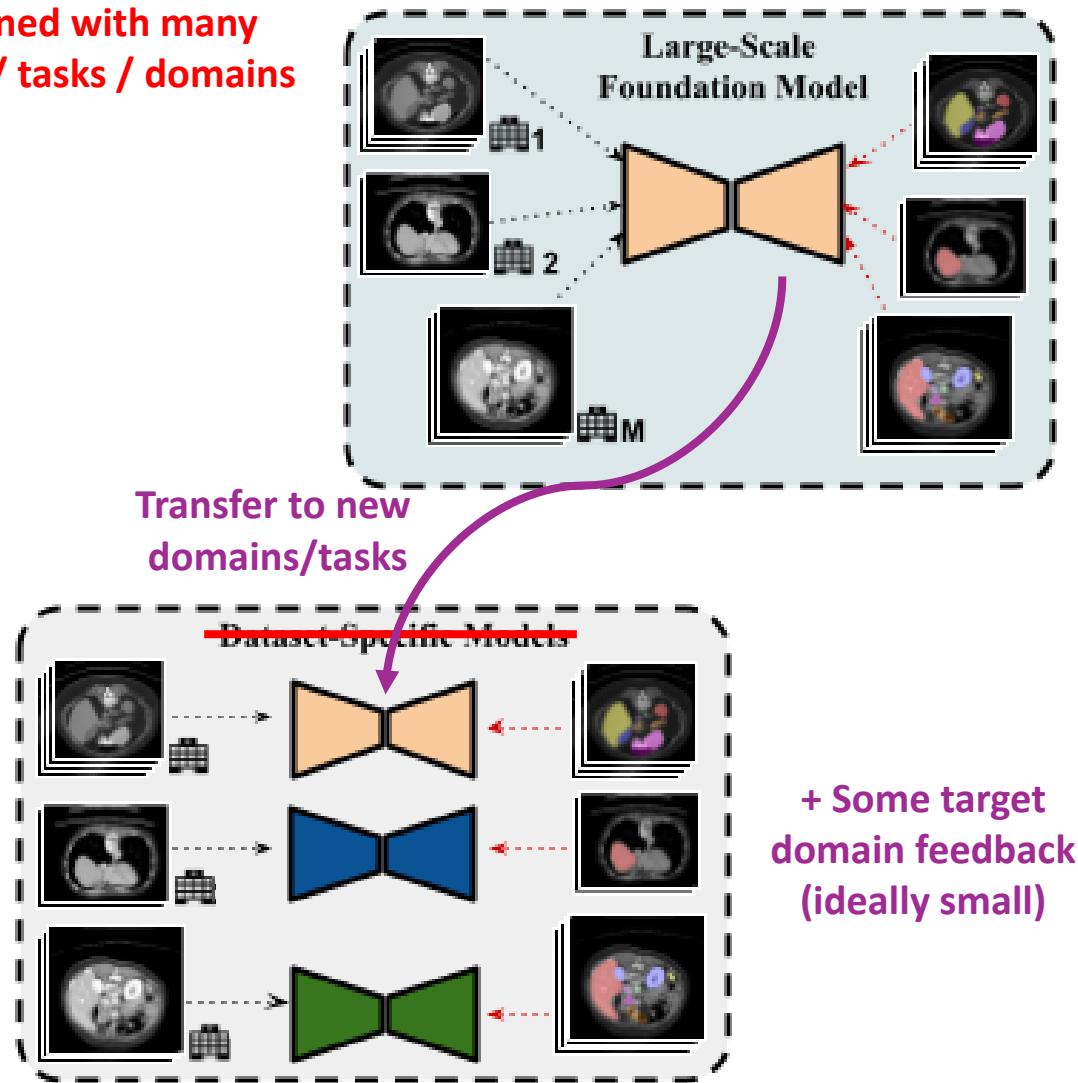


Foundation models for medical image segmentation

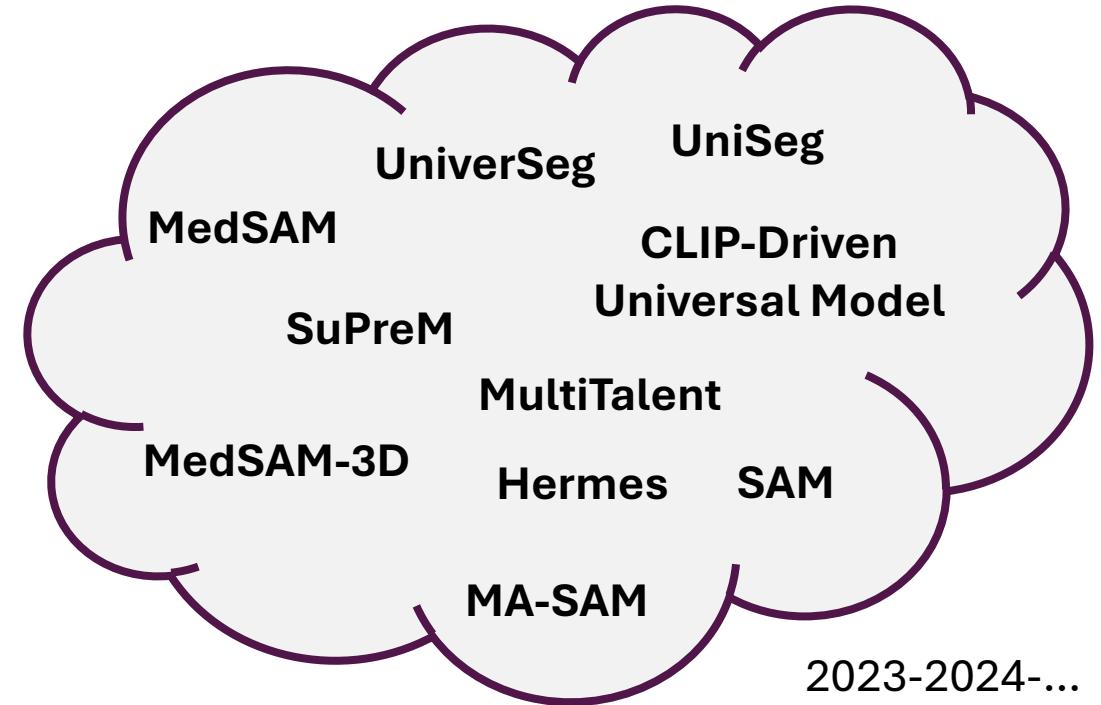
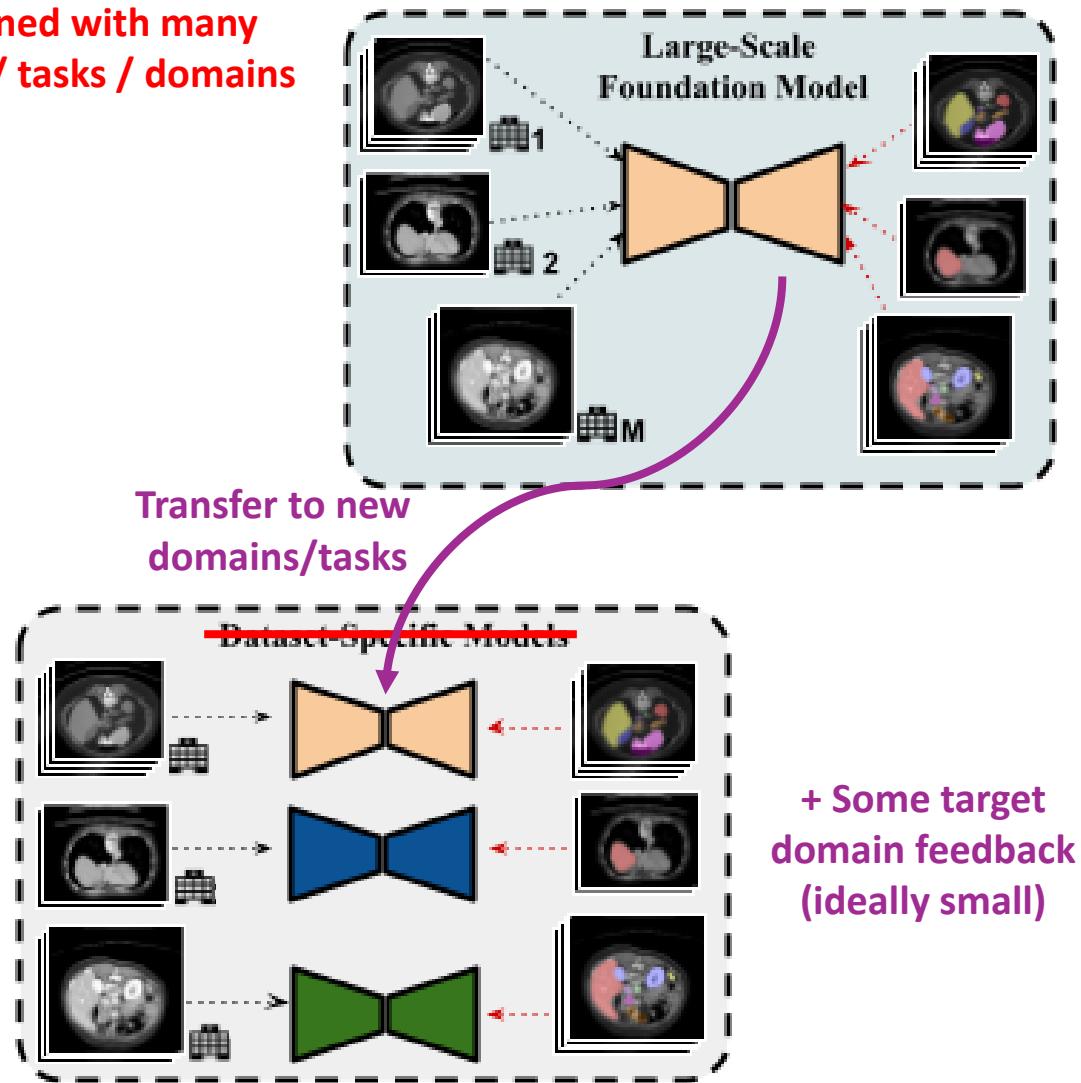
Trained with many
data / tasks / domains



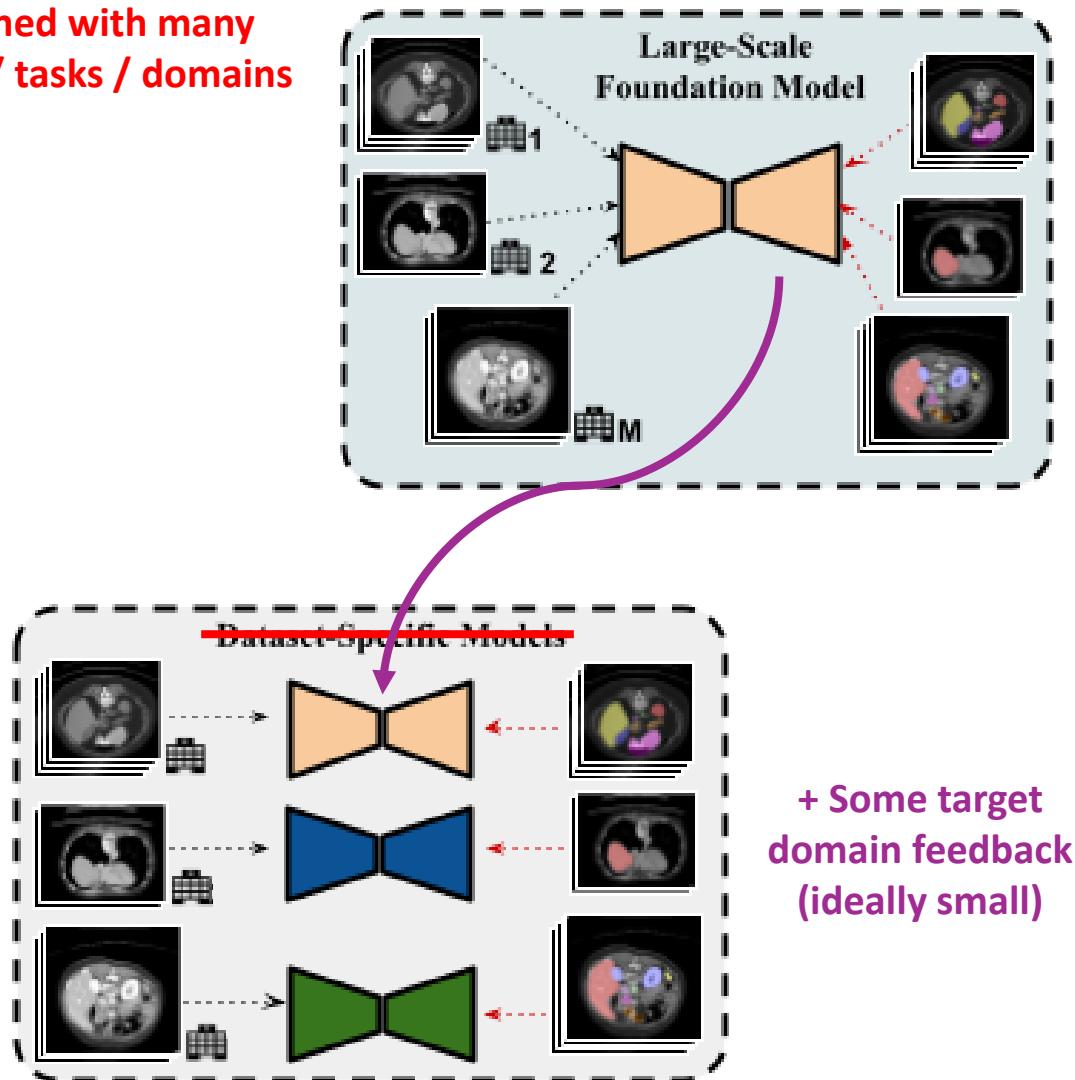
Foundation models for medical image segmentation



Foundation models for medical image segmentation



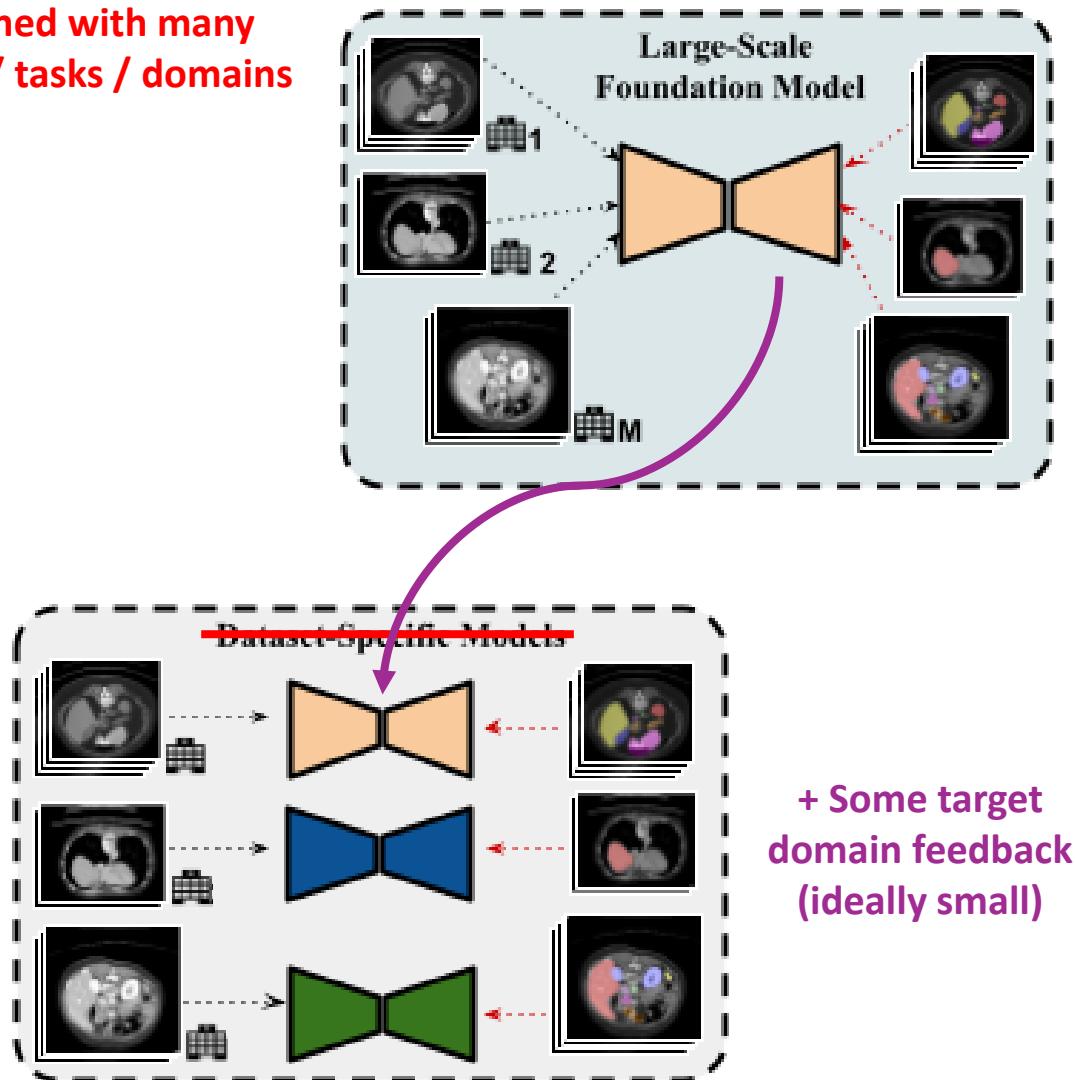
Foundation models for medical image segmentation



Organizing the mess!

1. Types of foundation models: a data perspective.
 - A. Generalist vs. Specialized
 - B. 2D vs. 3D
 - C. Multimodal vs. Unimodal
2. Learning/Usage Objectives
 - A. Zero-shot / Transfer Learning
 - B. In-Context Learning
 - C. Interactive Models (“SAM”)
3. Zero-shot / Adaptation-oriented (3D data)
 - A. How to pre-train?
 - B. How useful are foundation models? Limitations on the adaptation stage
 - C. Few-shot Parameter-Efficient Fine-tuning

Foundation models for medical image segmentation

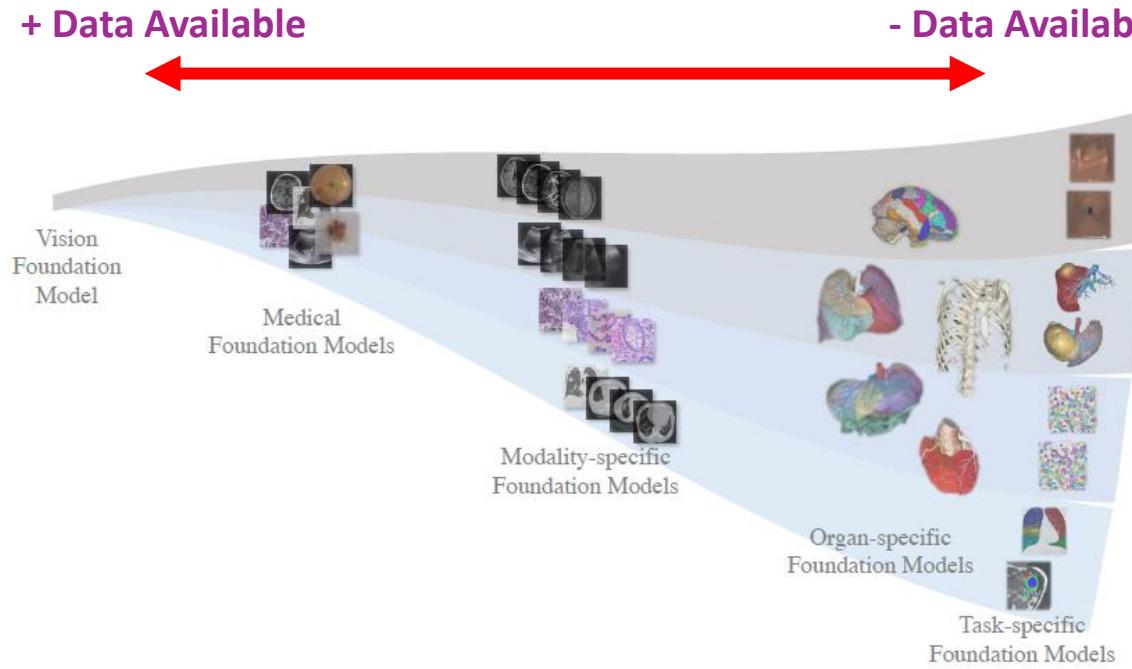


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Types of foundation models: a data perspective.

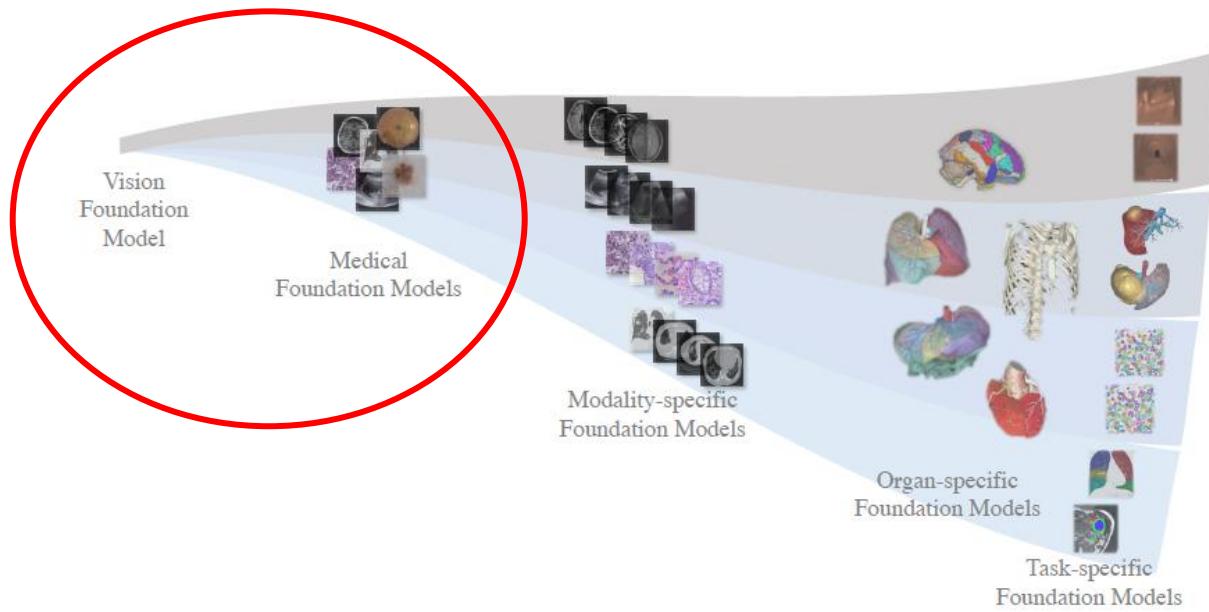
Generalist vs. Specialized (pre-training)



Huang et al. On The Challenges And Perspectives of Foundation Models For Medical Image Analysis. MEDIA'24.

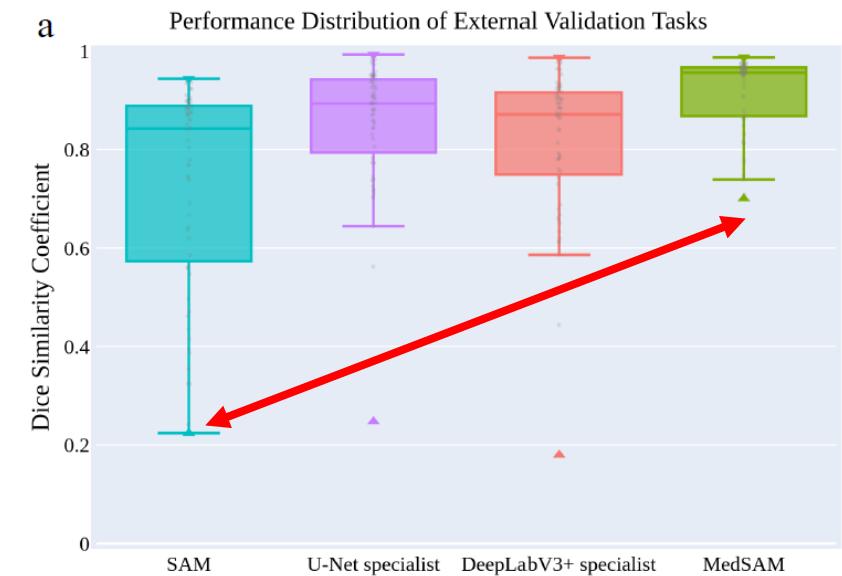
Types of foundation models: a data perspective.

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Huang et al. On The Challenges And Perspectives of Foundation Models For Medical Image Analysis. MEDIA'24.

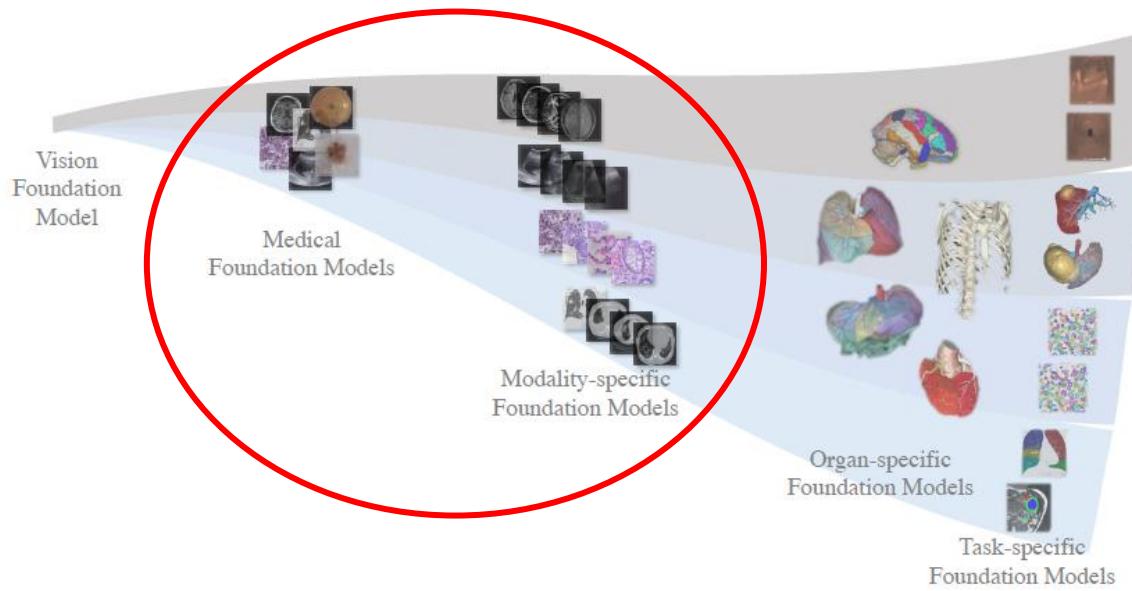
→ Medical better than General (natural image)



Ma et al. Segment Anything in Medical Images. Nat.Com.'24

Types of foundation models: a data perspective.

Generalist vs. Specialized (pre-training)

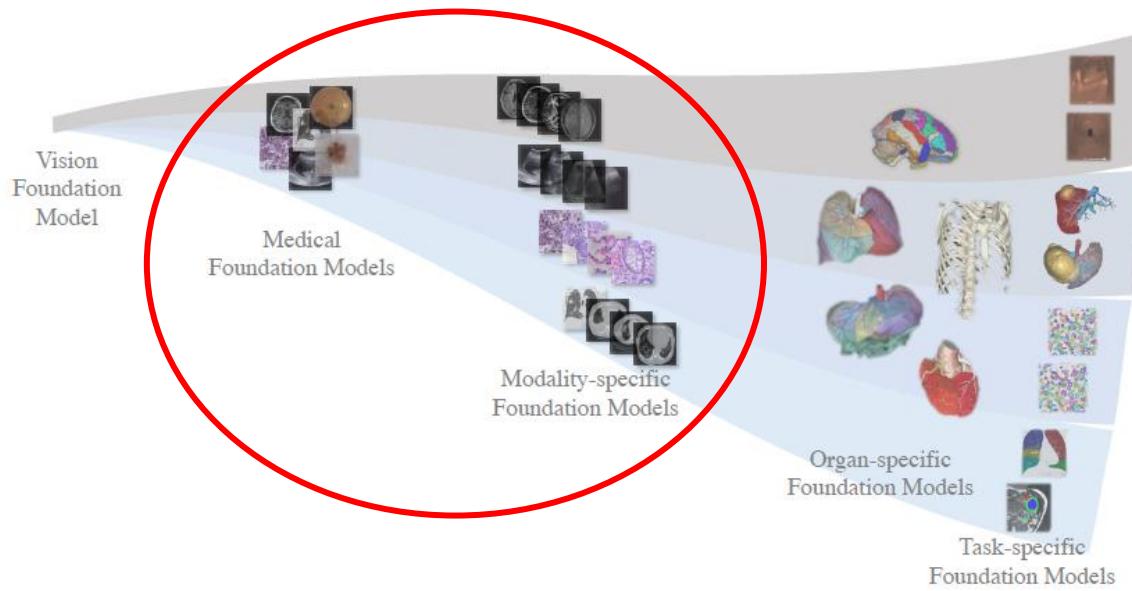


→ Modality better than Medical ?
(scarce empirical studies for segmentation)

Huang et al. On The Challenges And Perspectives of Foundation Models For Medical Image Analysis. MEDIA'24.

Types of foundation models: a data perspective.

Generalist vs. Specialized (pre-training)



Huang et al. On The Challenges And Perspectives of Foundation Models For Medical Image Analysis. MEDIA'24.

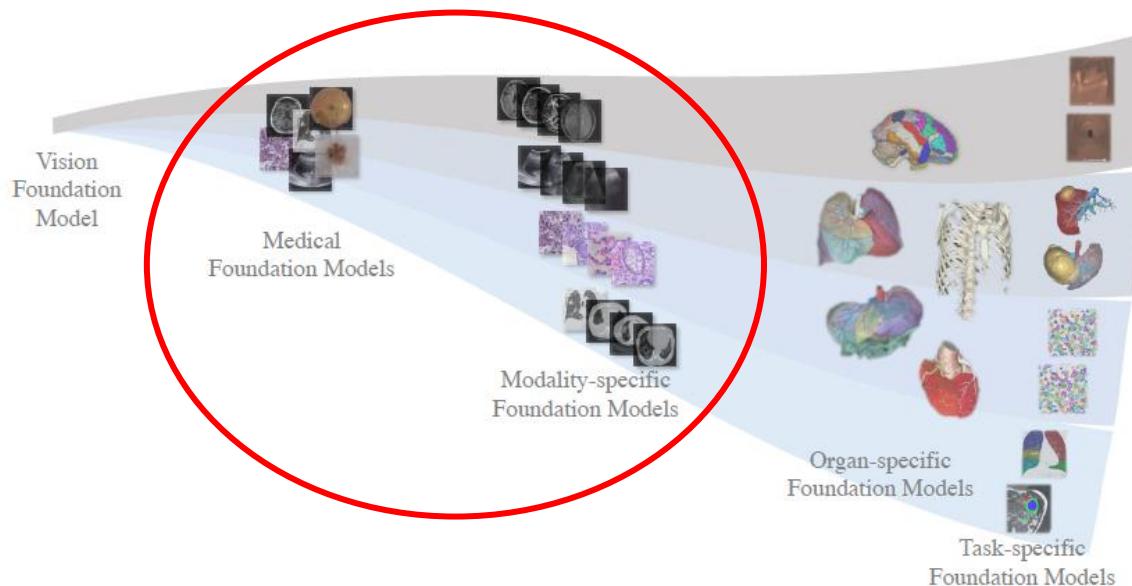
→ Modality better than Medical ?
(scarce empirical studies for segmentation)
BUT... On VLMs for classification it is the case.

		MESSIDOR	FIVES	REFUGE	20x3	ODIR _{200x3}	MMAC	Avg.
CLIP	ViT-B/32	0.200	0.256	0.433	0.333	0.480	0.183	0.314
BiomedCLIP	ViT-B/16	0.207	0.415	0.624	0.617	0.583	0.274	0.453
FLAIR	RN50	0.604	0.735	0.883	0.983	0.667	0.400	0.712
	(b) Linear Probing							
ImageNet	RN50	0.424	0.741	0.733	0.983	0.887	0.631	0.733
CLIP	ViT-B/32	0.491	0.800	0.720	0.950	0.917	0.642	0.753
BiomedCLIP	ViT-B/16	0.433	0.654	0.776	0.866	0.883	0.678	0.715
RETFound	ViT-B/16	0.457	0.765	0.747	0.950	0.887	0.547	0.725
FLAIR	RN50	0.719	0.879	0.843	1.000	0.935	0.740	0.852

Silva-Rodríguez et al. A Foundation Language-Image Model of the Retina: Encoding Expert Knowledge in Text Supervision. MEDIA'24.

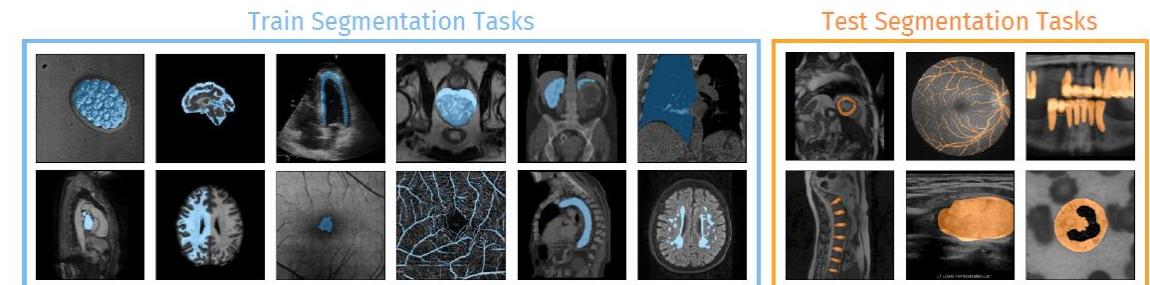
Types of foundation models: a data perspective.

Generalist vs. Specialized (pre-training)

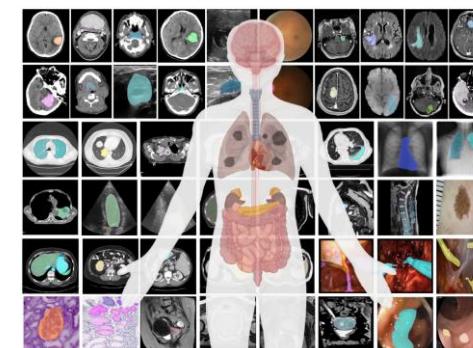


Huang et al. On The Challenges And Perspectives of Foundation Models For Medical Image Analysis. MEDIA'24.

→ Modality better than Medical ?
(scarce empirical studies for segmentation)
BUT... Large domain GAP between modalities.



Butoi et al. Universeg: Universal medical image segmentation. ICCV'23.

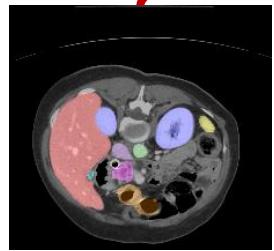


Ma et al. Segment Anything in Medical Images. Nat.Com.'24

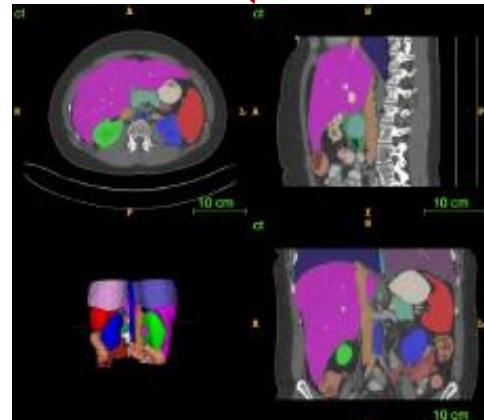
Types of foundation models: a data perspective.

2D vs. 3D (pre-training)

Actually...



2D Images*
256 x 256 pixels
512 x 512 pixels

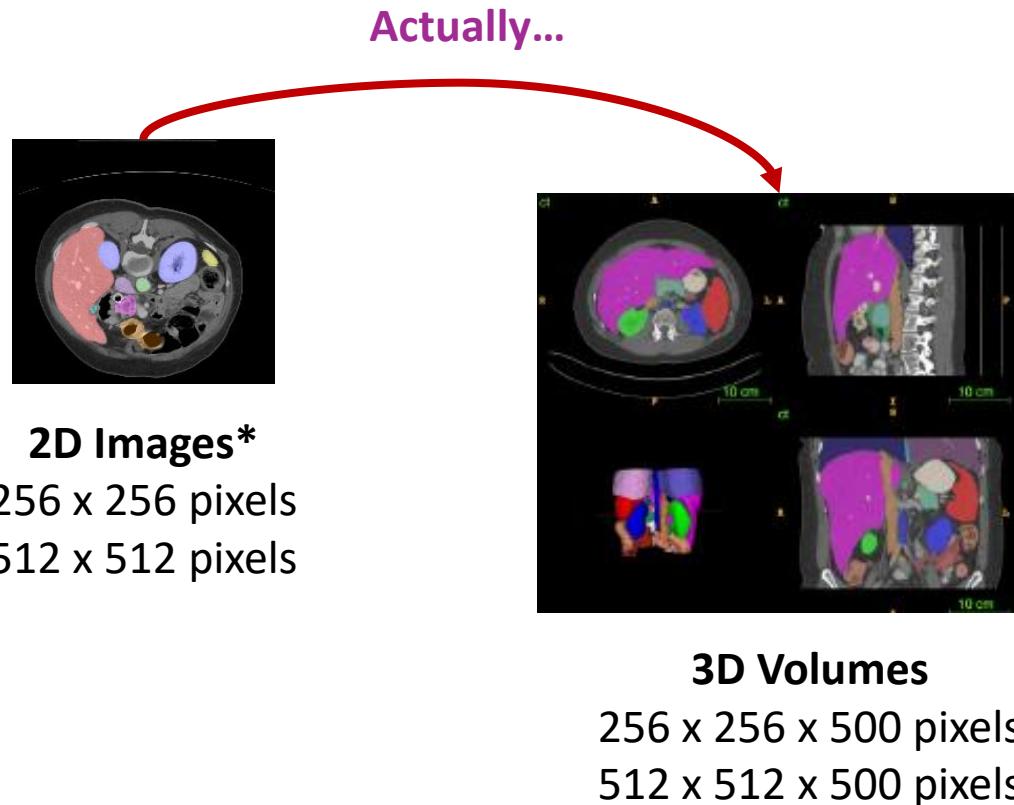


3D Volumes
256 x 256 x 500 pixels
512 x 512 x 500 pixels

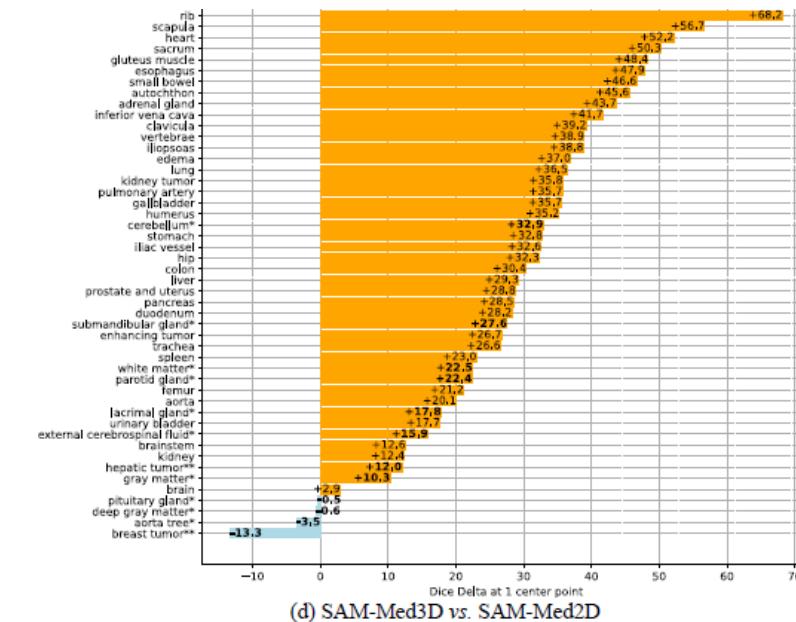
* These scales not apply to other categories such as histology WSIs

Types of foundation models: a data perspective.

2D vs. 3D (pre-training)



→ Pre-training on 3D better than on 2D
(also, a limitation of natural image pre-training)

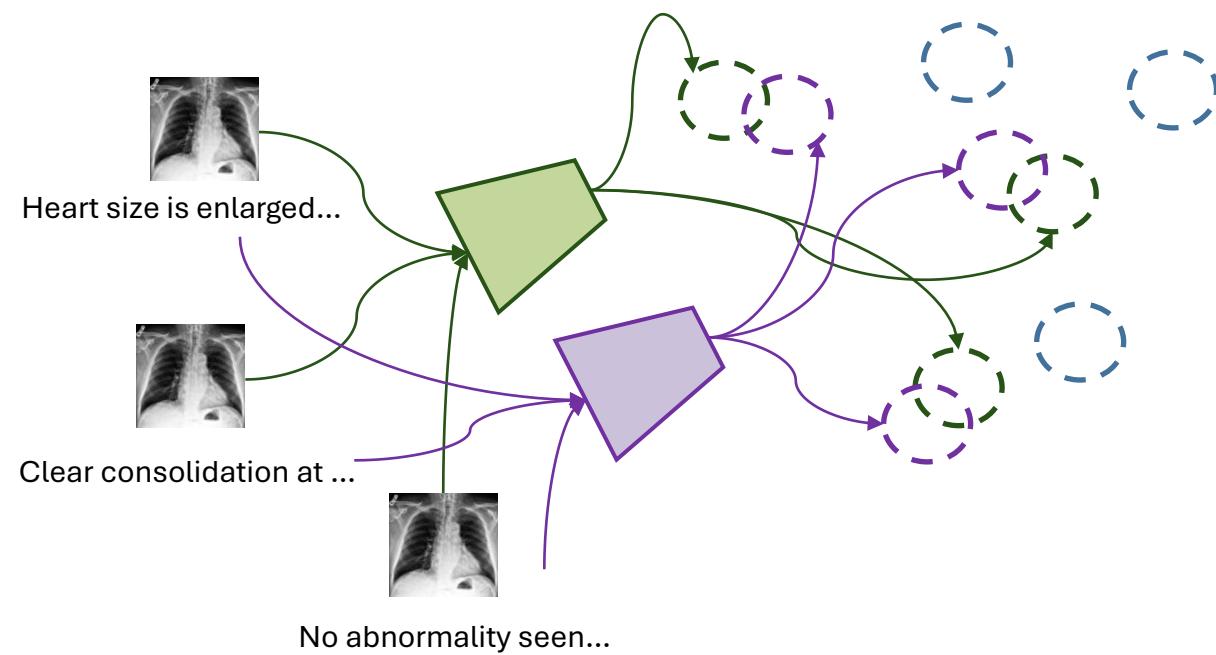


Wang et al. SAM-Med3D: Towards General-Purpose Segmentation Models for Volumetric Medical Images. ArXiv'24.

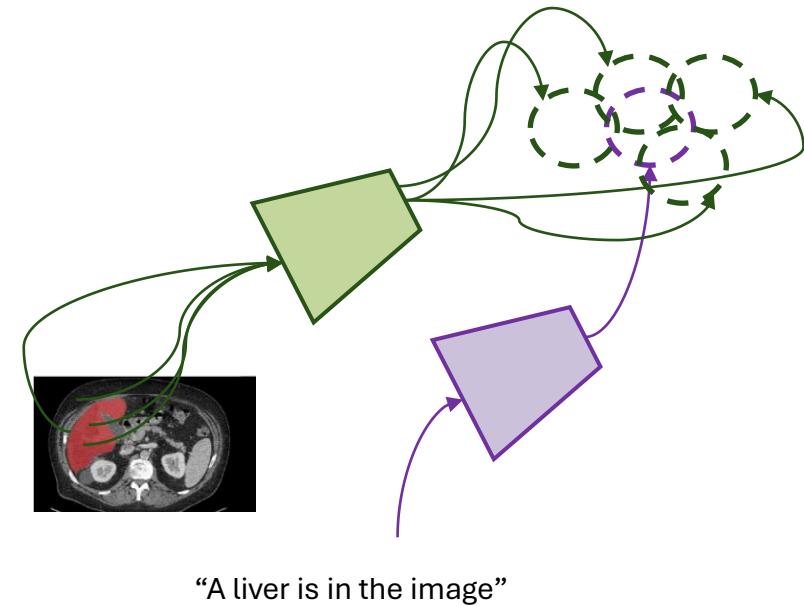
Types of foundation models: a data perspective.

Multimodal vs. Unimodal

Image-Level image-language pre-training



Segmentation image-language pre-training

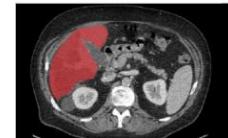


Types of foundation models: a data perspective.

Multimodal vs. Unimodal

→ Medical Image Segmentation Foundation Models are (so far) Unimodal
(FMs are not necessary multi-modal)

1. Scarcity of grounding language annotations with masks.
2. Already-existing large datasets with pixel/voxel annotations only.
3. Unclear contribution of text modality in absence of open-vocabulary concepts.

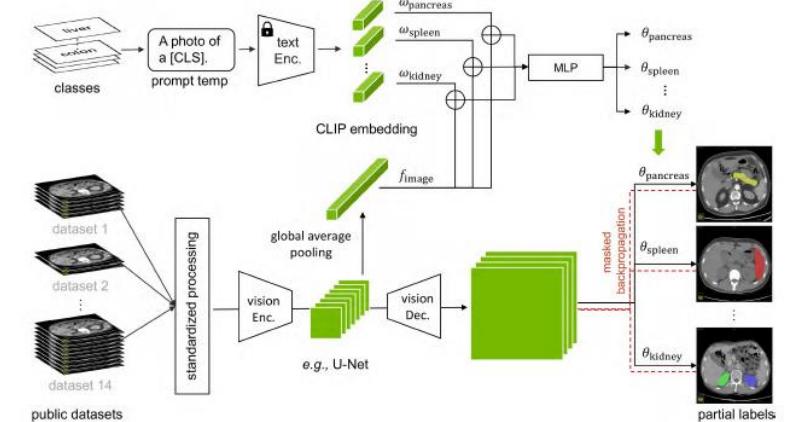


"A liver is in the image"

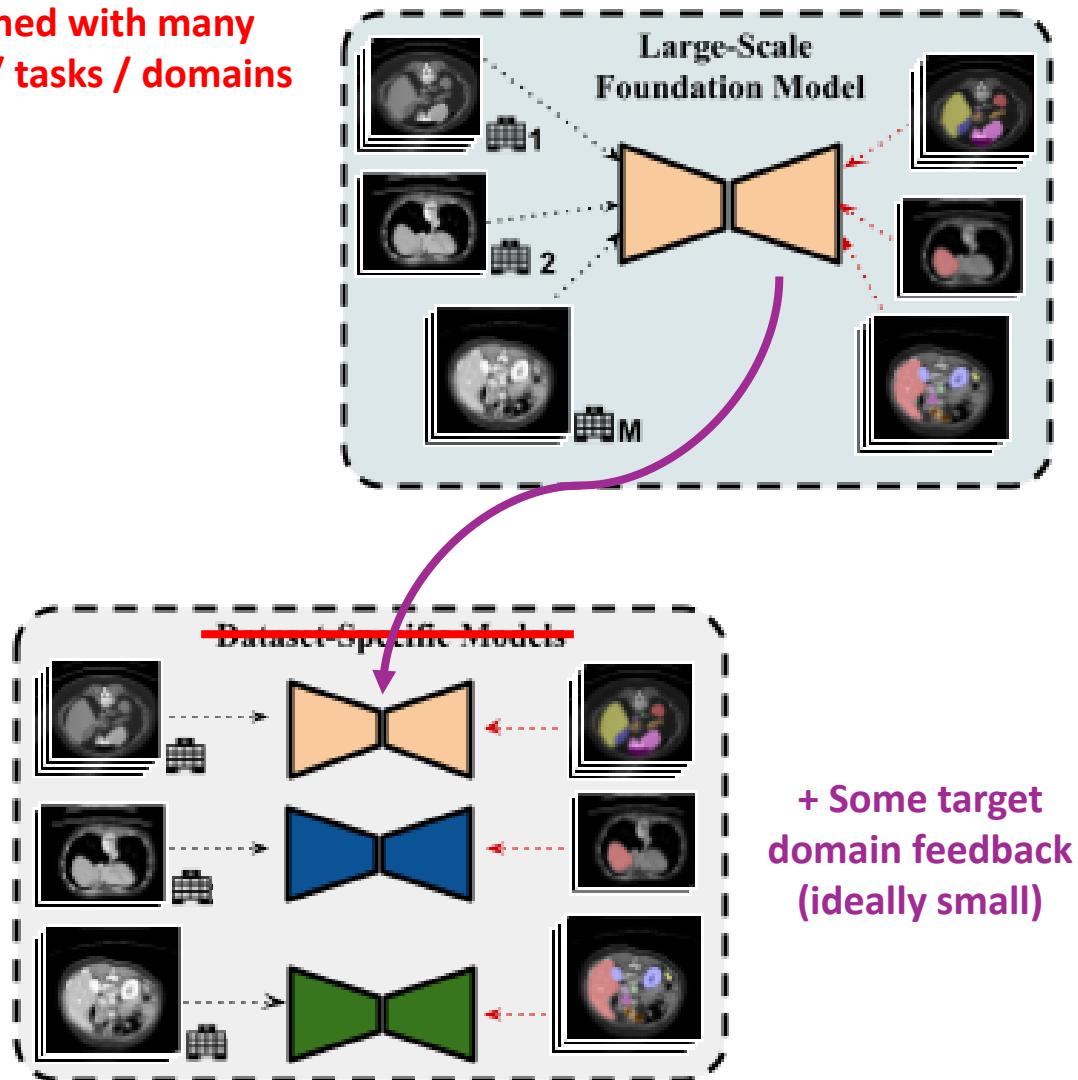
4. Some works include a CLIP-driven component, but its contribution is doubtful. **(We will see this latter)**

5. To explore in lesion segmentation?

Liu et al. CLIP-Driven Universal Model for Organ Segmentation and Tumor Detection. ICCV'23.



Foundation models for medical image segmentation



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Learning / usage objectives.

Med3D('19)

Zero-shot / Transfer Learning

CLIP-Driven

ImageNet Philosophy

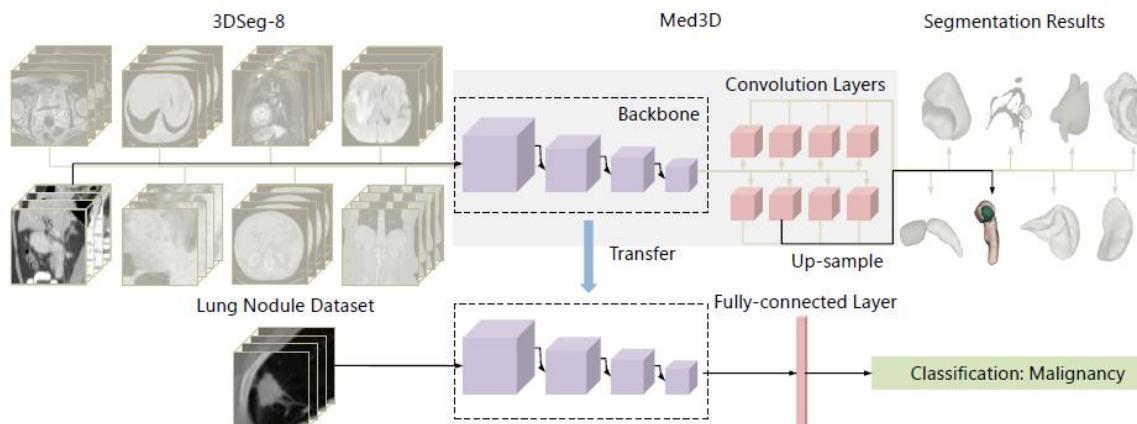


Figure 2: Framework of the proposed method.

Chen et al. Med3D: Transfer Learning for 3D Medical Image Analysis. ArXiv'19.

HERMES

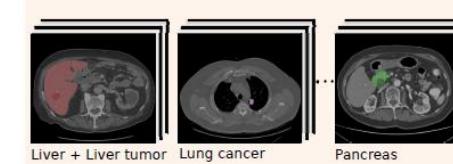
FSEFT

MultiTalent

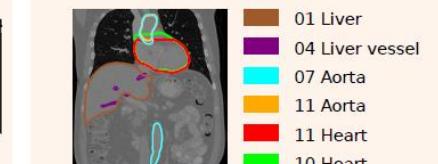
UniSeg

SuPreM

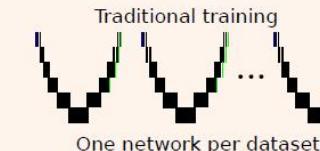
a) Collection of partially labeled datasets



b) Contradicting and overlapping classes

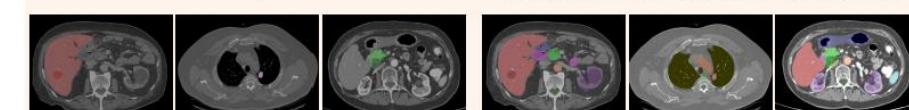


c) Training strategies



Multi-dataset training

vs.
MultiTalent: One network for all datasets



Ulrich et al. MultiTalent: A Multi-Dataset Approach to Medical Image Segmentation. MICCAI'23.

Learning / usage objectives.

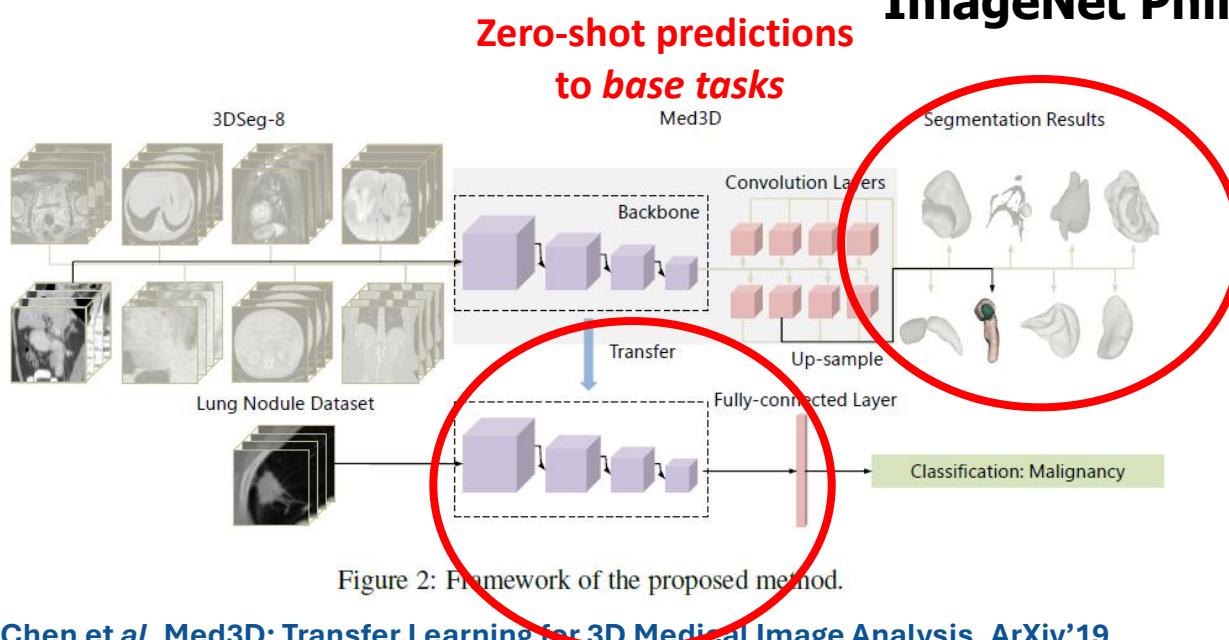
Med3D('19)

CLIP-Driven

MultiTalent

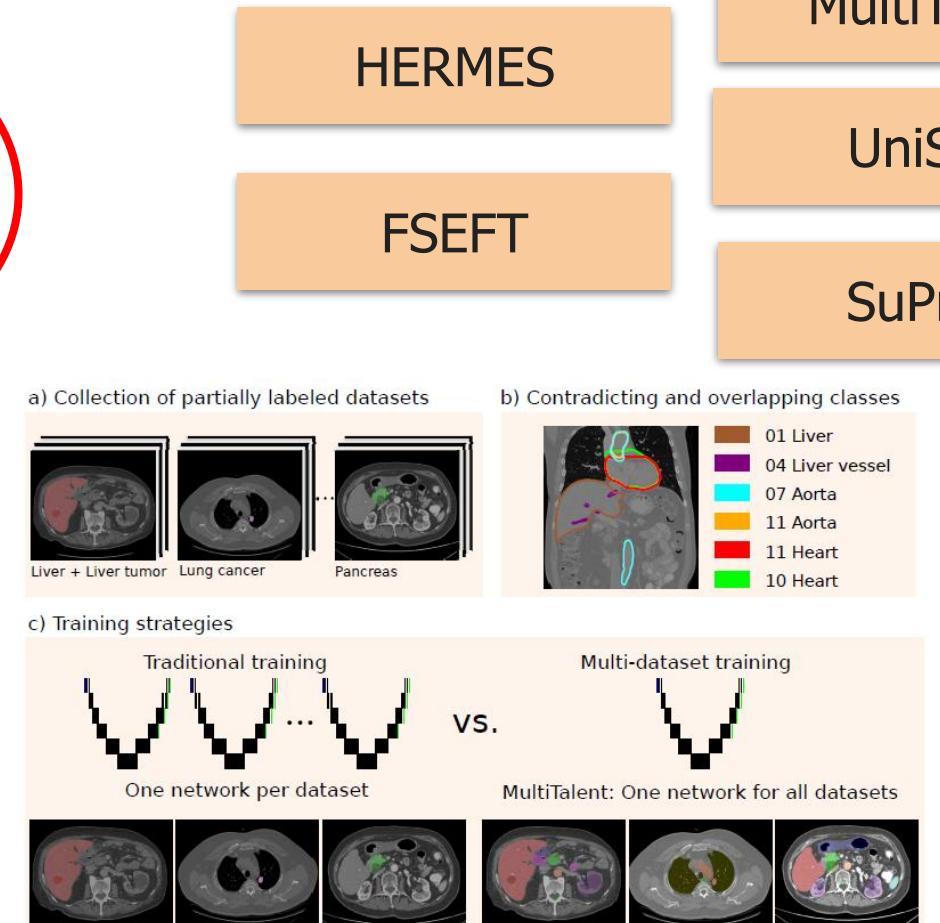
UniSeg

SuPreM



Chen et al. Med3D: Transfer Learning for 3D Medical Image Analysis. ArXiv'19.

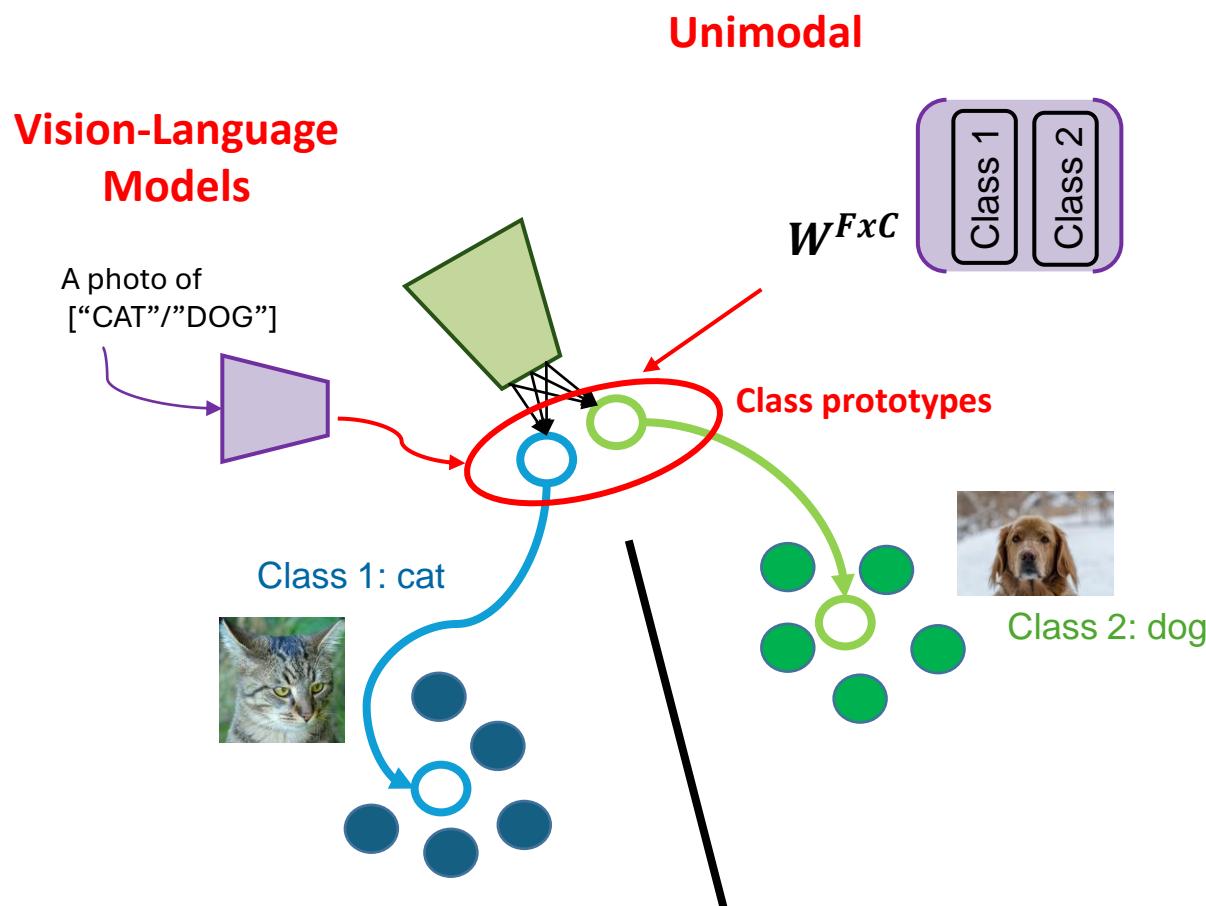
Fine-tuning to novel domains/tasks



Ulrich et al. MultiTalent: A Multi-Dataset Approach to Medical Image Segmentation. MICCAI'23.

Learning / usage objectives.

(Zero-shot: VLMs vs. Unimodal)



Zero-shot: not receiving any supervision from the target domain/task

Is zero-shot predictions to novel categories a realistic objective?

Undandara et al. No Zero-Shot without Exponential Data: Pretraining Concept frequency Determines Multimodal Model Performance. ICLRW-FM'24.

Learning / usage objectives.

UniverSeg

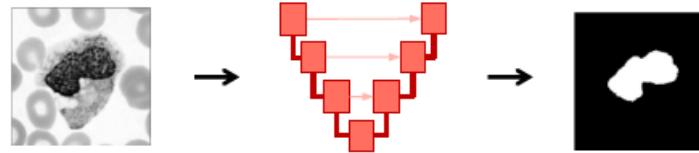
In Context Learning

Tyche

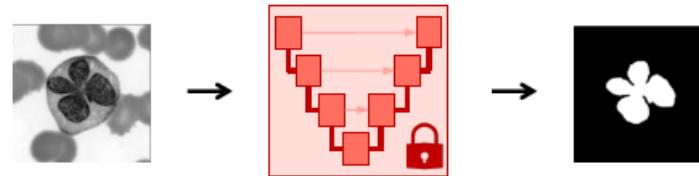
"At the end of the day, practitioners won't fine-tune"

Traditional Approach

1. Design and train a task-specific model.

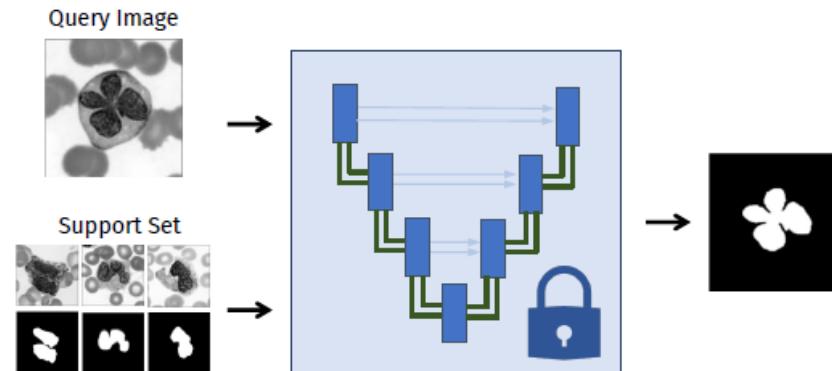


2. Predict new images with the trained model.

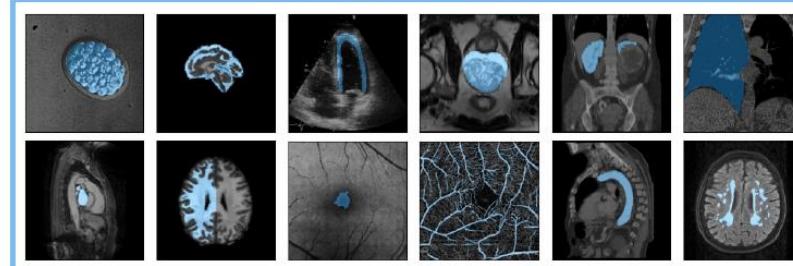


UniverSeg Approach

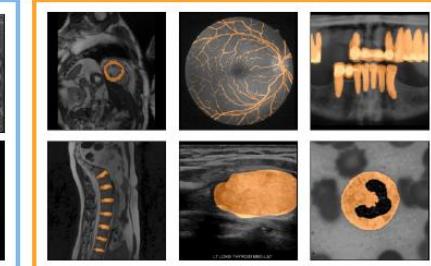
With a trained UniverSeg model, predict new images for the new task from a few labeled pairs without retraining.



Train Segmentation Tasks



Test Segmentation Tasks

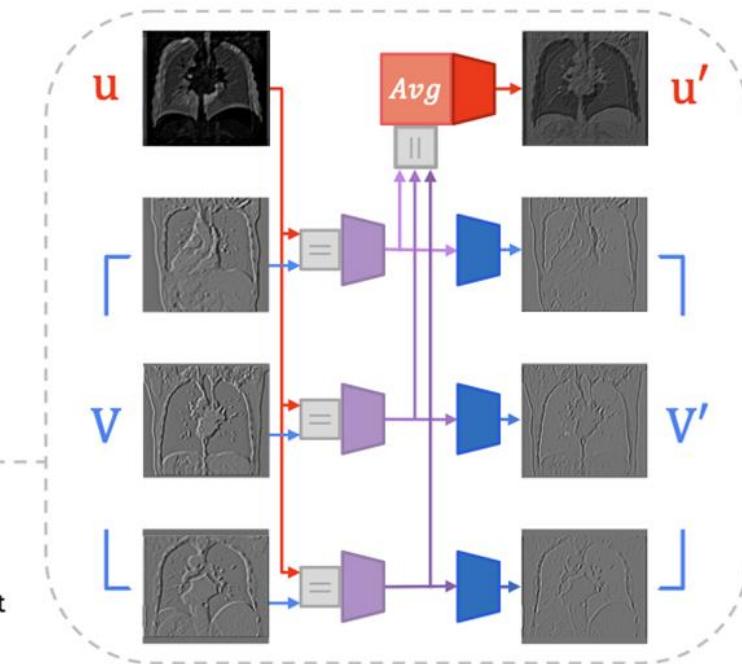
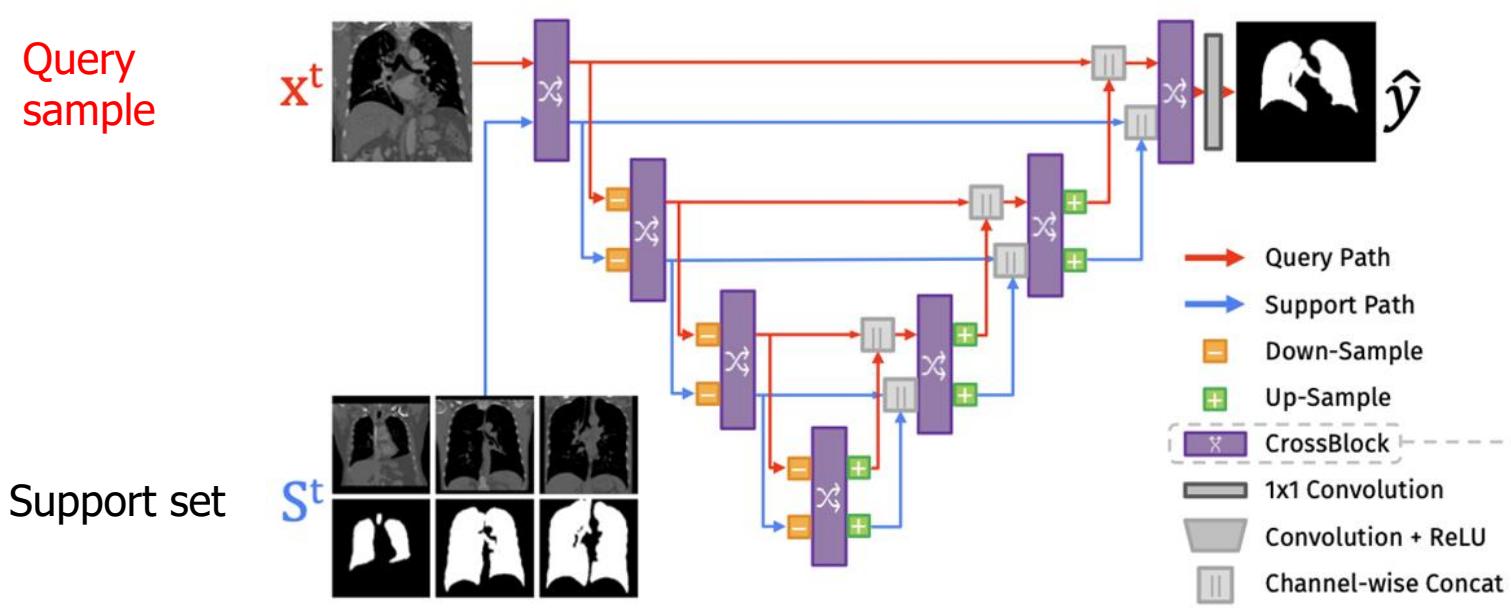


Learning / usage objectives.

UniverSeg

In Context Learning

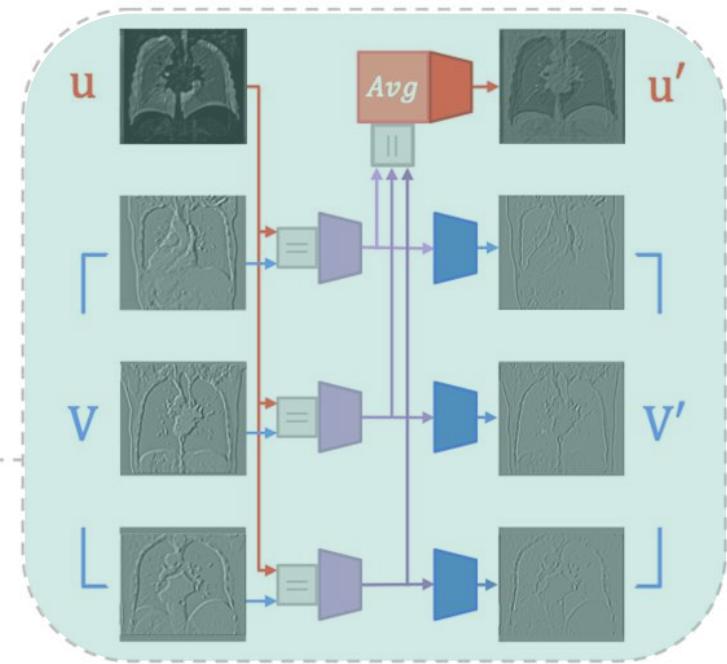
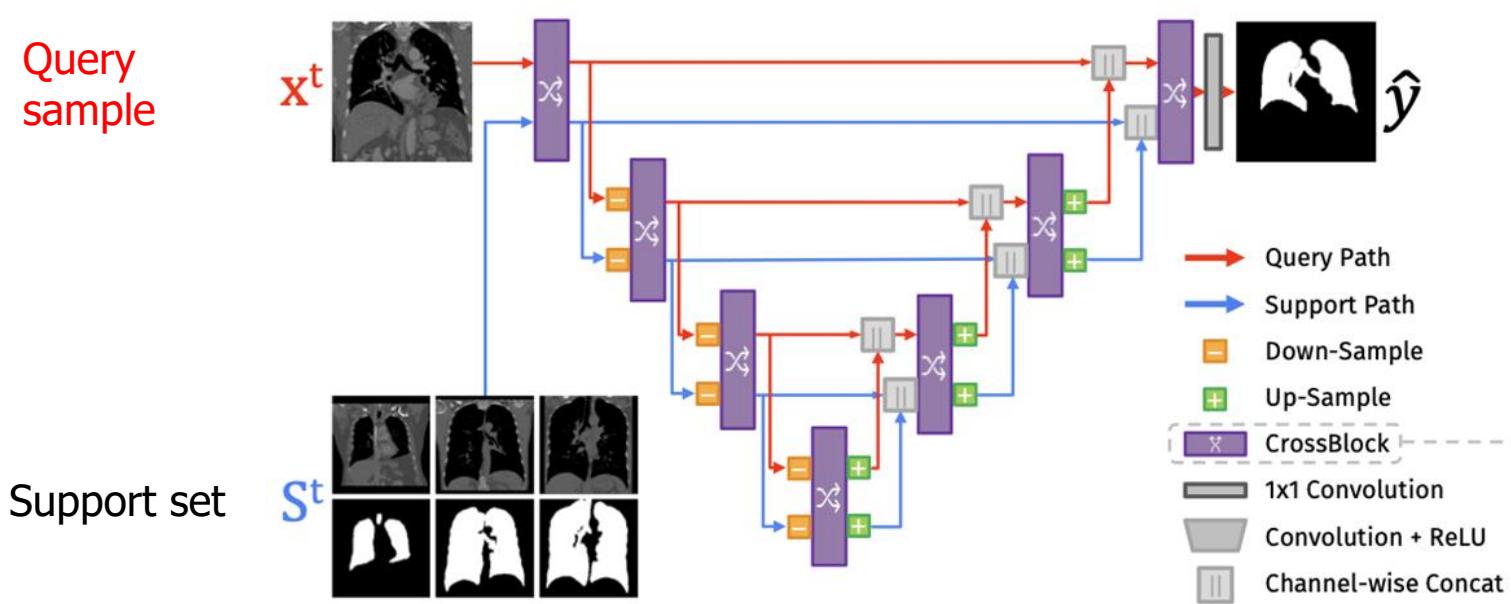
Main Idea



Learning / usage objectives.

In Context Learning

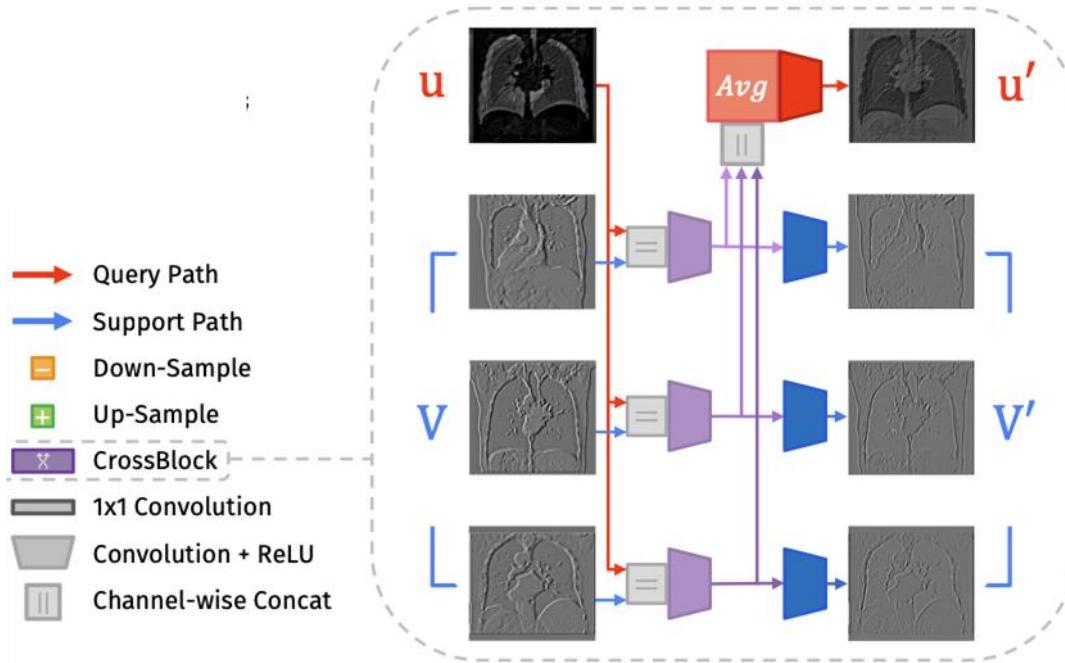
Main Idea



The representations from the query and support samples can interact at multiple scales

Learning / usage objectives.

In Context Learning



$\text{CrossBlock}(u, V; \theta_z, \theta_v) = (u', V')$, where: (2)

$$z_i = A(\text{CrossConv}(u, v_i; \theta_z)) \quad \text{for } i = 1, 2, \dots, n$$

$u' = 1/n \sum_{i=1}^n z_i$ Query output: average across support

$$v'_i = A(\text{Conv}(z_i; \theta_v)) \quad \text{for } i = 1, 2, \dots, n,$$

Support samples activation maps

$\text{CrossConv}(u, V; \theta_z) = \{z_i\}_{i=1}^n$,
for $z_i = \text{Conv}(u || v_i; \theta_z)$,

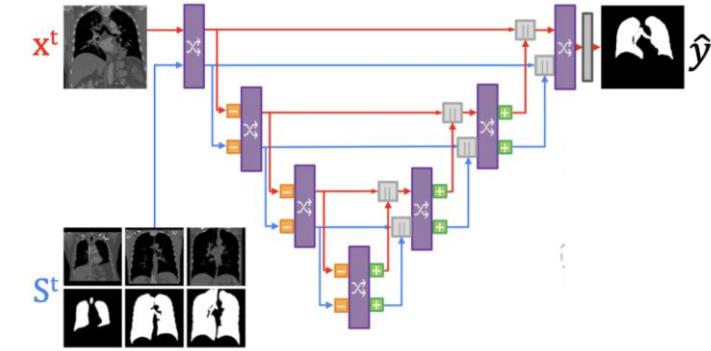
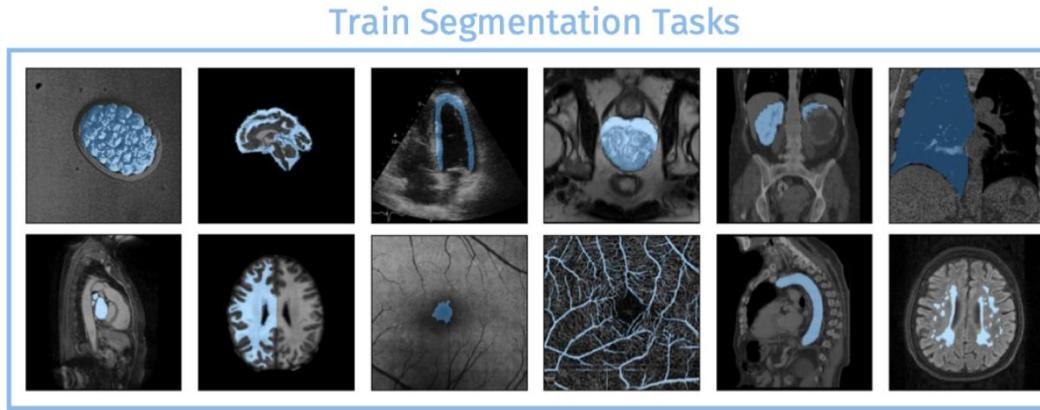
Concatenate query and support activation maps

Learning / usage objectives.

UniverSeg

In Context Learning

How this is trained? (Hint: based on meta-learning or *learning-to-learn*)

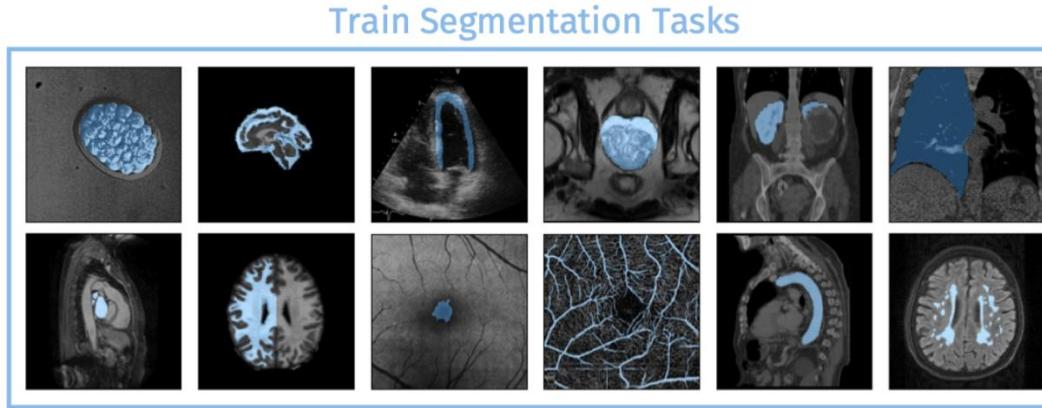


Learning / usage objectives.

UniverSeg

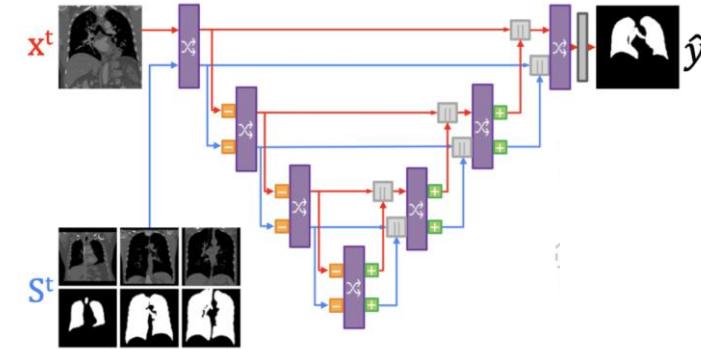
In Context Learning

How this is trained? (Hint: based on meta-learning or *learning-to-learn*)



```
for k = 1, ..., NumTrainSteps do
    t ~  $\mathcal{T}$ 
     $(x_i^t, y_i^t) \sim t$ 
     $S^t \leftarrow \{(x_j^t, y_j^t)\}_{j \neq i}^n$ 
     $x_i^t, y_i^t \leftarrow \text{Aug}_t(x_i^t, y_i^t)$ 
     $S^t \leftarrow \{\text{Aug}_t(x_j^t, y_j^t)\}_j^n$ 
     $x_i^t, y_i^t, S^t \leftarrow \text{Aug}_T(x_i^t, y_i^t, S^t)$ 
     $\hat{y}_i \leftarrow f_\theta(x_i^t, S^t)$ 
     $\ell \leftarrow \mathcal{L}_{\text{seg}}(\hat{y}_i, y_i^t)$ 
     $\theta \leftarrow \theta - \eta \nabla_\theta \ell$ 
end for
```

- ▷ Sample Task
- ▷ Sample Query
- ▷ Sample Support
- ▷ Augment Query
- ▷ Augment Support
- ▷ Task Aug
- ▷ Predict label map
- ▷ Compute loss
- ▷ Gradient step

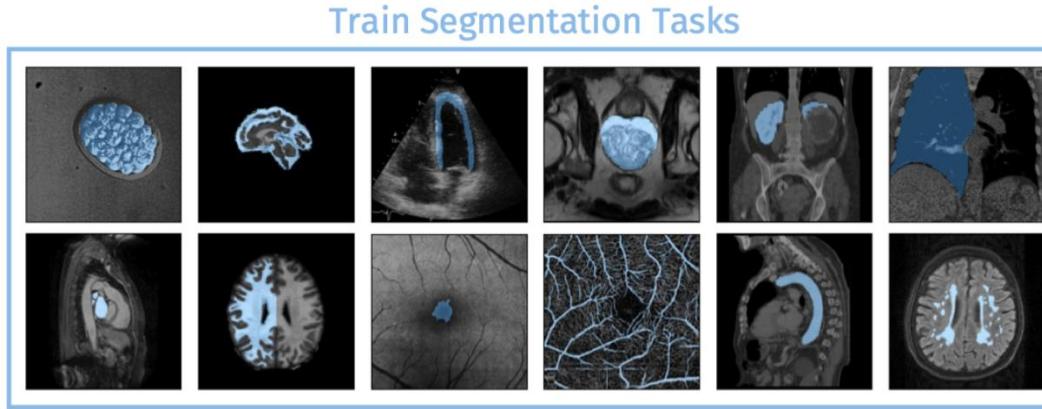


Learning / usage objectives.

UniverSeg

In Context Learning

How this is trained? (Hint: based on meta-learning or *learning-to-learn*)



for $k = 1, \dots, \text{NumTrainSteps}$ **do**

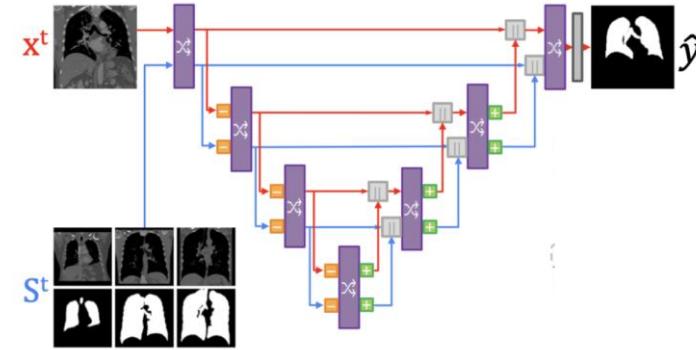
$t \sim \mathcal{T}$
 $(x_i^t, y_i^t) \sim t$
 $S^t \leftarrow \{(x_j^t, y_j^t)\}_{j \neq i}^n$
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end for

- ▷ Sample Task
- ▷ Sample Query
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- ▷ Gradient step



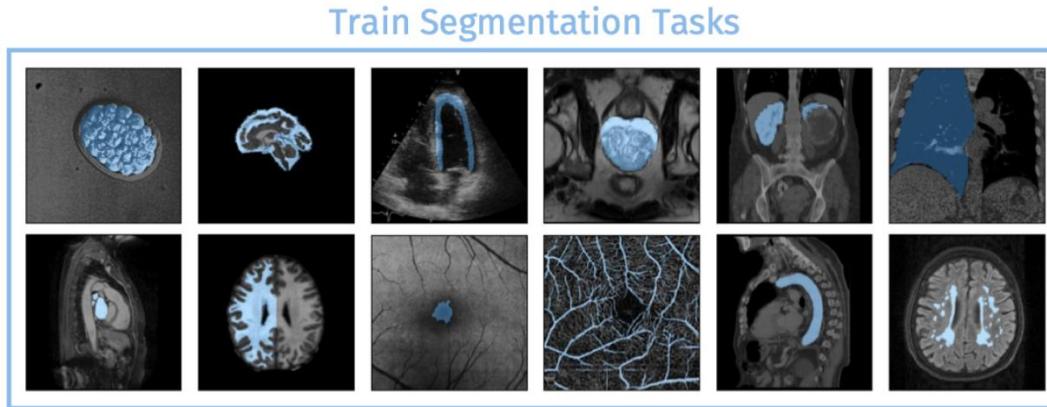
Among all training tasks



Learning / usage objectives.

In Context Learning

How this is trained? (Hint: based on meta-learning or *learning-to-learn*)



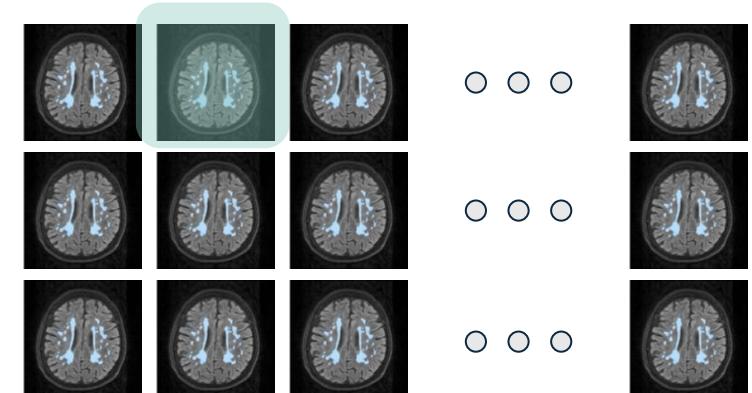
```

for  $k = 1, \dots, \text{NumTrainSteps}$  do
     $t \sim \mathcal{T}$ 
     $(x_i^t, y_i^t) \sim t$ 
     $S^t \leftarrow \{(x_j^t, y_j^t)\}_{j \neq i}^n$ 
     $x_i^t, y_i^t \leftarrow \text{Aug}_t(x_i^t, y_i^t)$ 
     $S^t \leftarrow \{\text{Aug}_t(x_j^t, y_j^t)\}_j^n$ 
     $x_i^t, y_i^t, S^t \leftarrow \text{Aug}_T(x_i^t, y_i^t, S^t)$ 
     $\hat{y}_i \leftarrow f_\theta(x_i^t, S^t)$ 
     $\ell \leftarrow \mathcal{L}_{\text{seg}}(\hat{y}_i, y_i^t)$ 
     $\theta \leftarrow \theta - \eta \nabla_\theta \ell$ 
end for

```

- ▷ Sample Task
- ▷ Sample Query
- ▷ Sample Support
- ▷ Augment Query
- ▷ Augment Support
- ▷ Task Aug
- ▷ Predict label map
- ▷ Compute loss
- ▷ Gradient step

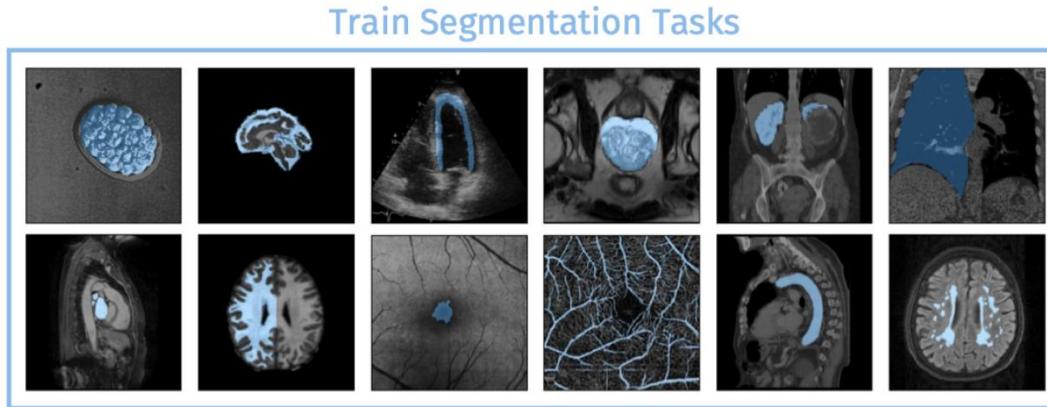
Among all training samples
from that task



Learning / usage objectives.

In Context Learning

How this is trained? (Hint: based on meta-learning or *learning-to-learn*)



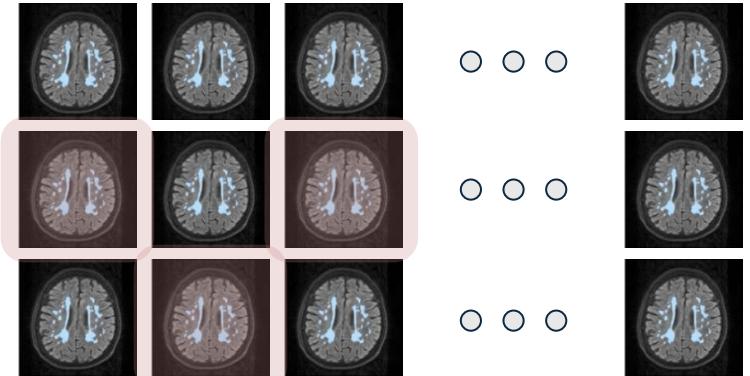
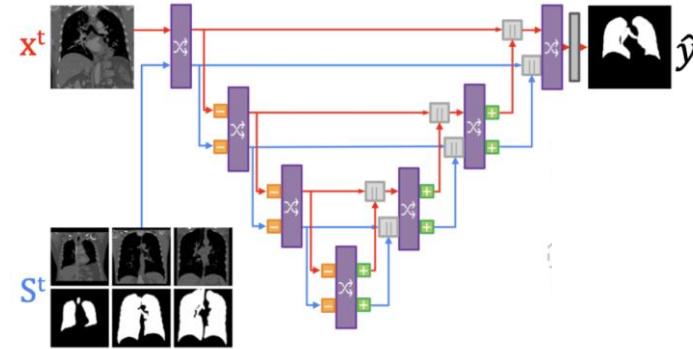
```

for  $k = 1, \dots, \text{NumTrainSteps}$  do
     $t \sim \mathcal{T}$ 
     $(x_i^t, y_i^t) \sim t$ 
     $S^t \leftarrow \{(x_j^t, y_j^t)\}_{j \neq i}^n$ 
     $x_i^t, y_i^t \leftarrow \text{Aug}_t(x_i^t, y_i^t)$ 
     $S^t \leftarrow \{\text{Aug}_t(x_j^t, y_j^t)\}_j^n$ 
     $x_i^t, y_i^t, S^t \leftarrow \text{Aug}_T(x_i^t, y_i^t, S^t)$ 
     $\hat{y}_i \leftarrow f_\theta(x_i^t, S^t)$ 
     $\ell \leftarrow \mathcal{L}_{\text{seg}}(\hat{y}_i, y_i^t)$ 
     $\theta \leftarrow \theta - \eta \nabla_\theta \ell$ 
end for

```

- ▷ Sample Task
- ▷ Sample Query
- ▷ Sample Support
- ▷ Augment Query
- ▷ Augment Support
- ▷ Task Aug
- ▷ Predict label map
- ▷ Compute loss
- ▷ Gradient step

Among all training samples
from that task

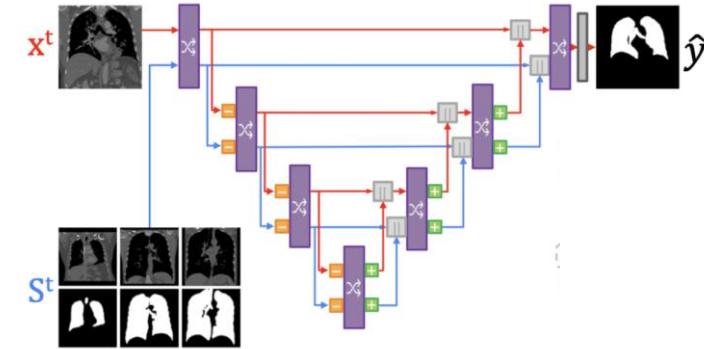


Learning / usage objectives.

In Context Learning

How this is trained? (Hint: based on meta-learning or *learning-to-learn*)

Train Segmentation Tasks



```

for  $k = 1, \dots, \text{NumTrainSteps}$  do
     $t \sim \mathcal{T}$ 
     $(x_i^t, y_i^t) \sim t$ 
     $S^t \leftarrow \{(x_j^t, y_j^t)\}_{j \neq i}^n$ 
     $x_i^t, y_i^t \leftarrow \text{Aug}_t(x_i^t, y_i^t)$ 
     $S^t \leftarrow \{\text{Aug}_t(x_j^t, y_j^t)\}_j^n$ 
     $x_i^t, y_i^t, S^t \leftarrow \text{Aug}_T(x_i^t, y_i^t, S^t)$ 
     $\hat{y}_i \leftarrow f_\theta(x_i^t, S^t)$ 
     $\ell \leftarrow \mathcal{L}_{\text{seg}}(\hat{y}_i, y_i^t)$ 
     $\theta \leftarrow \theta - \eta \nabla_\theta \ell$ 
end for

```

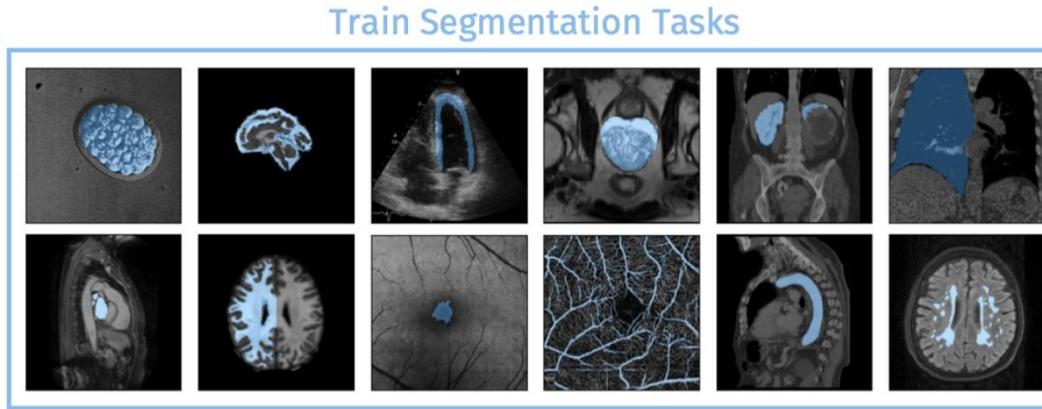
- ▷ Sample Task
- ▷ Sample Query
- ▷ Sample Support
- ▷ Augment Query
- ▷ Augment Support
 - ▷ Task Aug
- ▷ Predict label map
 - ▷ Compute loss
 - ▷ Gradient step

Learning / usage objectives.

UniverSeg

In Context Learning

How this is trained? (Hint: based on meta-learning or *learning-to-learn*)

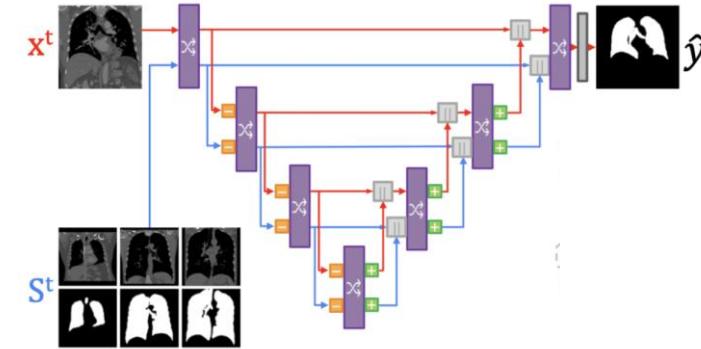


```
for k = 1, ..., NumTrainSteps do
    t ~  $\mathcal{T}$ 
     $(x_i^t, y_i^t) \sim t$ 
     $S^t \leftarrow \{(x_j^t, y_j^t)\}_{j \neq i}^n$ 
     $x_i^t, y_i^t \leftarrow \text{Aug}_t(x_i^t, y_i^t)$ 
     $S^t \leftarrow \{\text{Aug}_t(x_j^t, y_j^t)\}_j^n$ 
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     $\hat{y}_i \leftarrow f_\theta(x_i^t, S^t)$ 
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end for
```

- ▷ Sample Task
- ▷ Sample Query
- ▷ Sample Support
- ▷ Augment Query
- ▷ Augment Support
- ▷ Task Aug
- ▷ Predict label map
- ▷ Compute loss
- ▷ Gradient step



Standard (training)
forward-backward steps

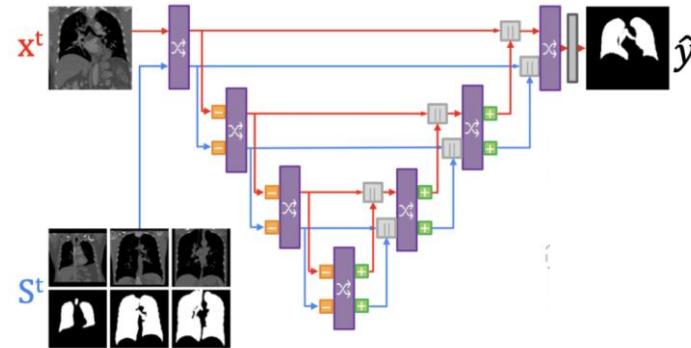
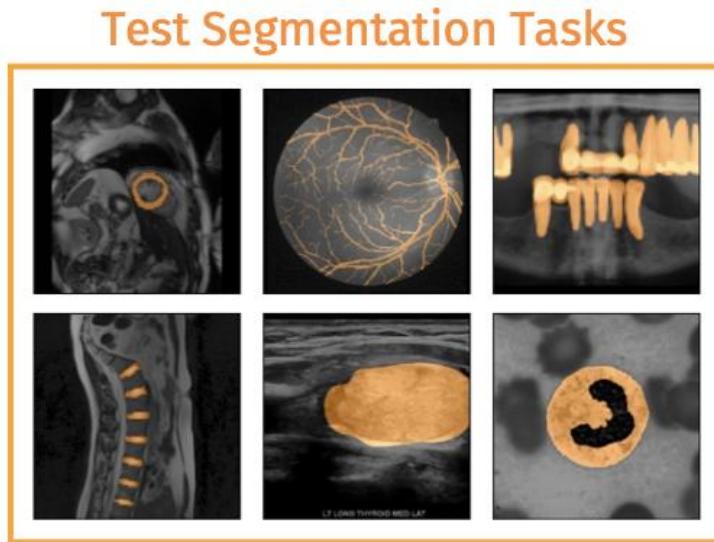


Learning / usage objectives.

UniverSeg

In Context Learning

And what about inference?



For a given image x^t $\hat{y} = f_\theta(x^t, S^t)$

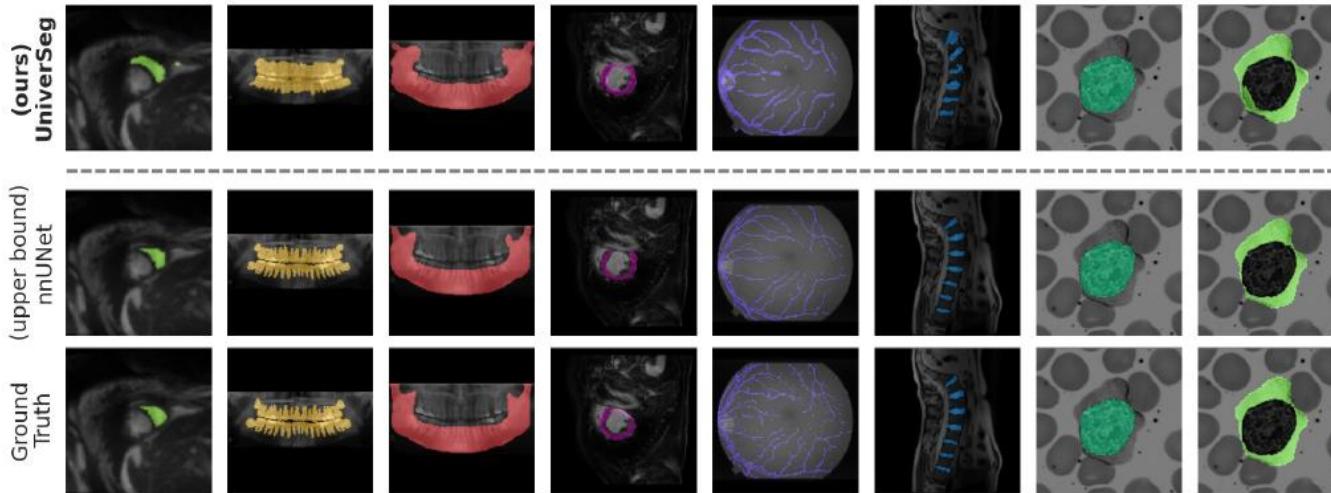
To make it more robust, multiple support sets are employed



$$\hat{y} = \frac{1}{M} \sum_{m=1}^M f_\theta(x^t, S_m^t)$$

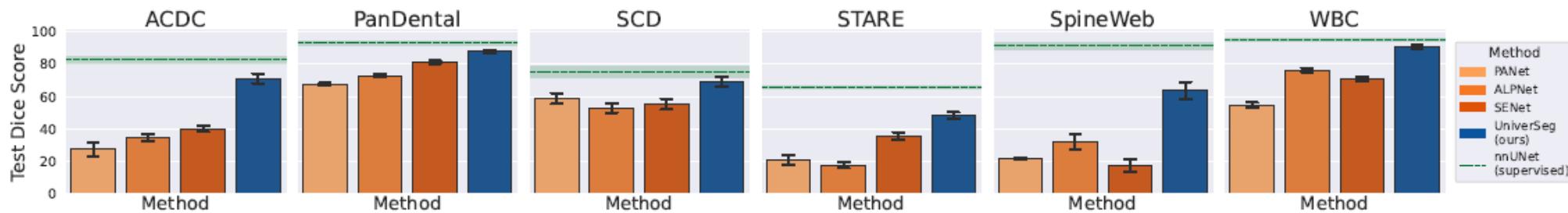
Learning / usage objectives.

In Context Learning



- Can tackle new tasks.
- Does not require fine-tuning.
- Promising performance.

- So far binary scenario.
- Performance below dataset-specific models.
- Unclear implementation on large 3D data.
- Requires continuously employing the support set.



Learning / usage objectives.

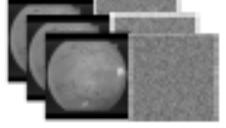
Tyche

In Context Learning

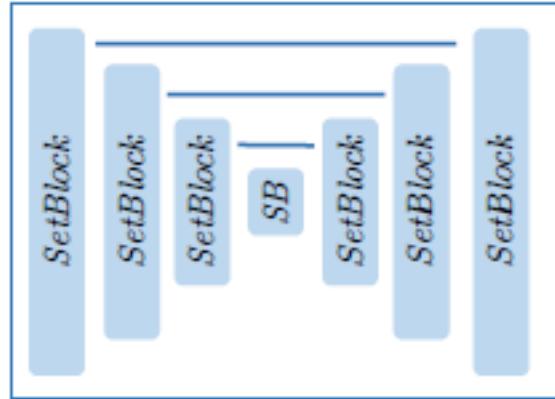
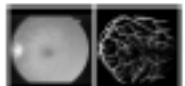
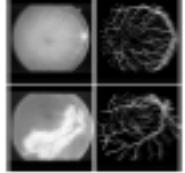
Test-Time
Augmentations

Stochastic Target

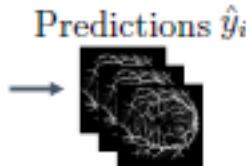
$$\{x_j^t, z_k\}_{k=1}^K$$



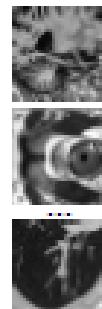
$$\text{Context } \{x_j^t, y_j^t\}_{j=1}^S$$



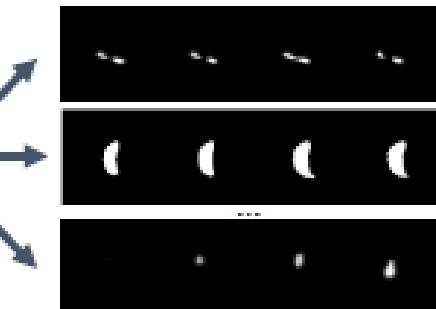
In-Context Learning
CrossBlocks



Ours: In-Context
Stochastic Model



Tyche



Measure Uncertainty

Learning / usage objectives.

SAM

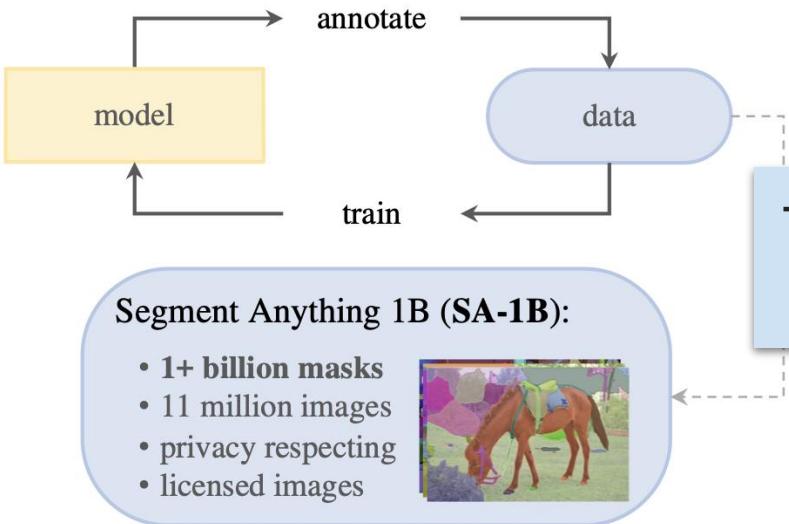
MedSAM

3DSAM-Adapter

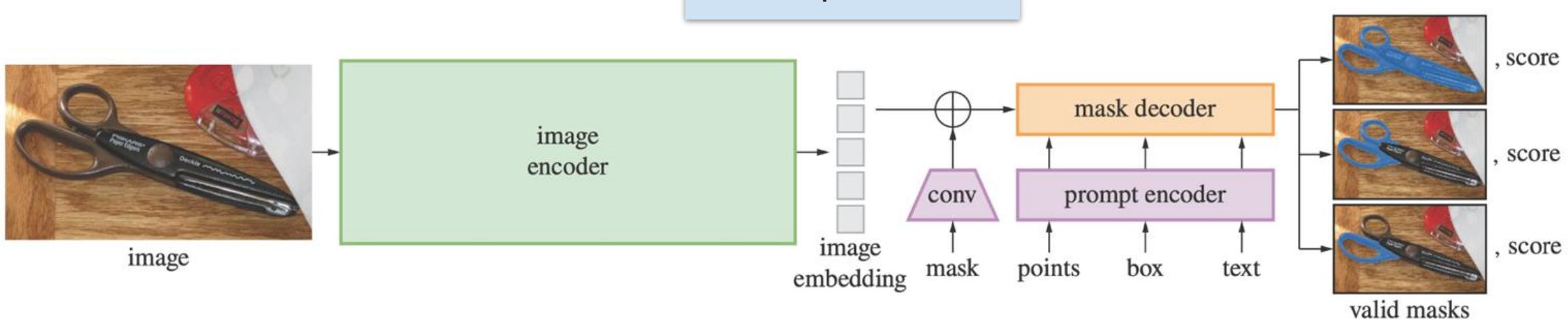
MA-SAM

Med-SAM3D

Interactive models (“SAM”)



Pipeline

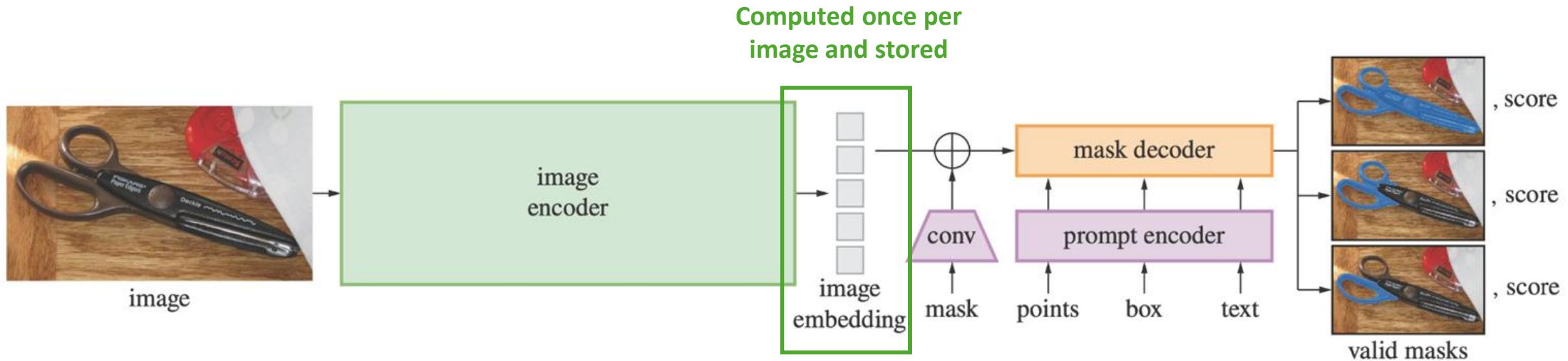


Learning / usage objectives.

SAM

Interactive models (“SAM”)

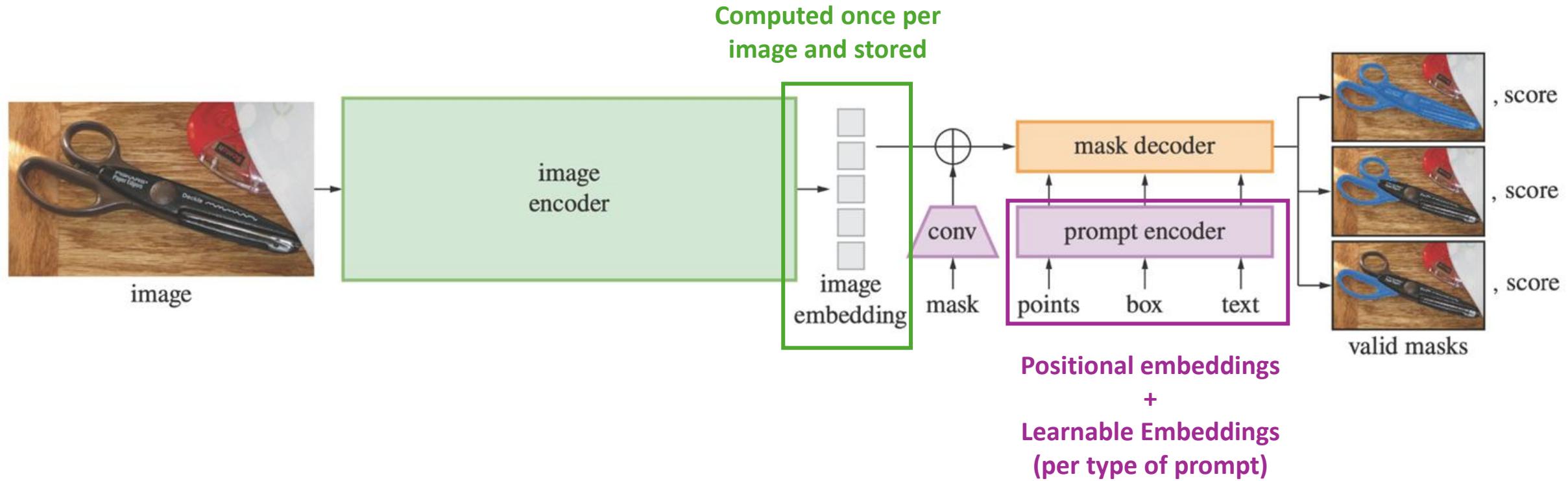
How this is trained?



Learning / usage objectives.

Interactive models (“SAM”)

How this is trained?

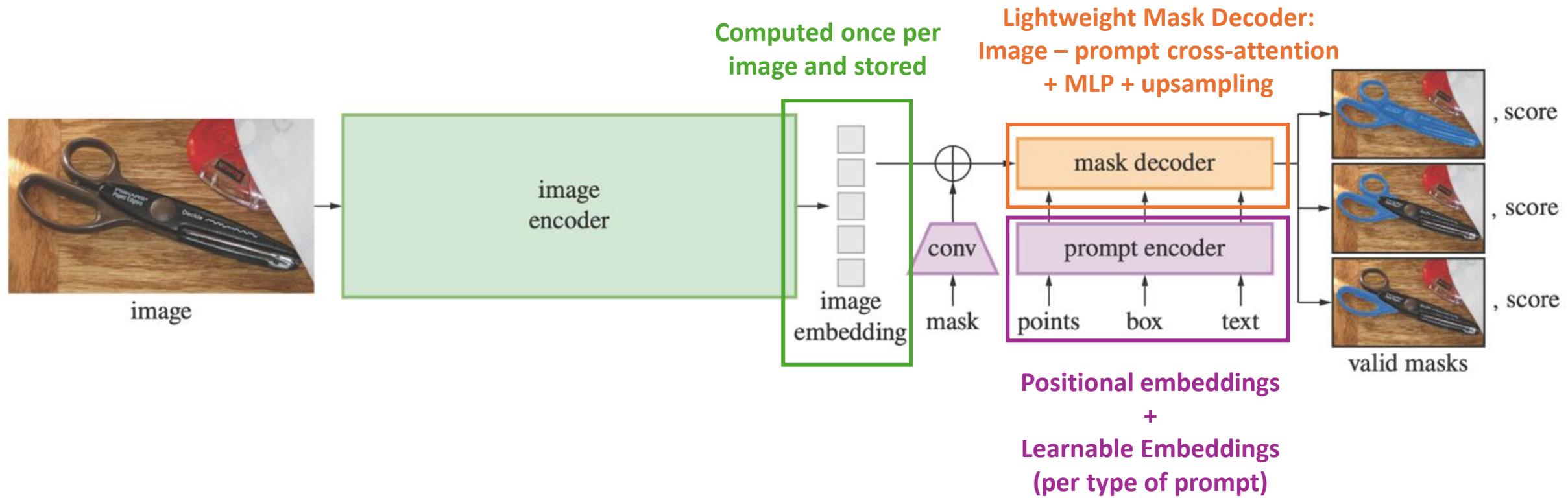


Learning / usage objectives.

SAM

Interactive models (“SAM”)

How this is trained?

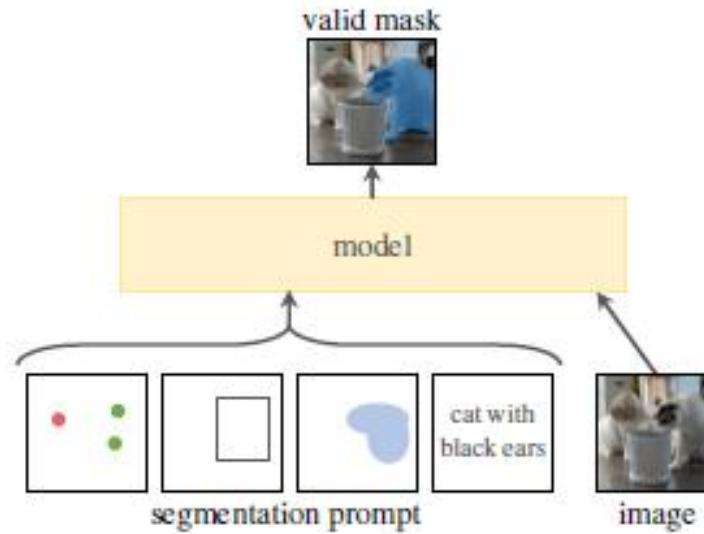


Learning / usage objectives.

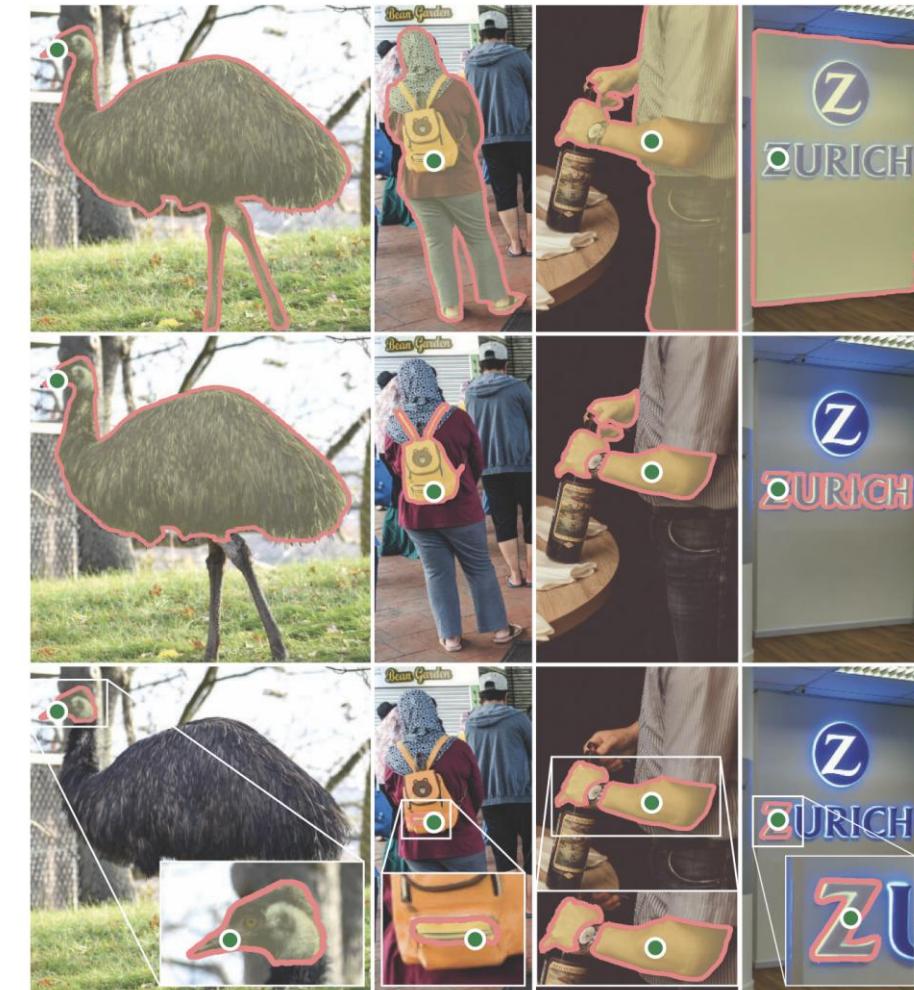
SAM

Interactive models (“SAM”)

And what about inference?



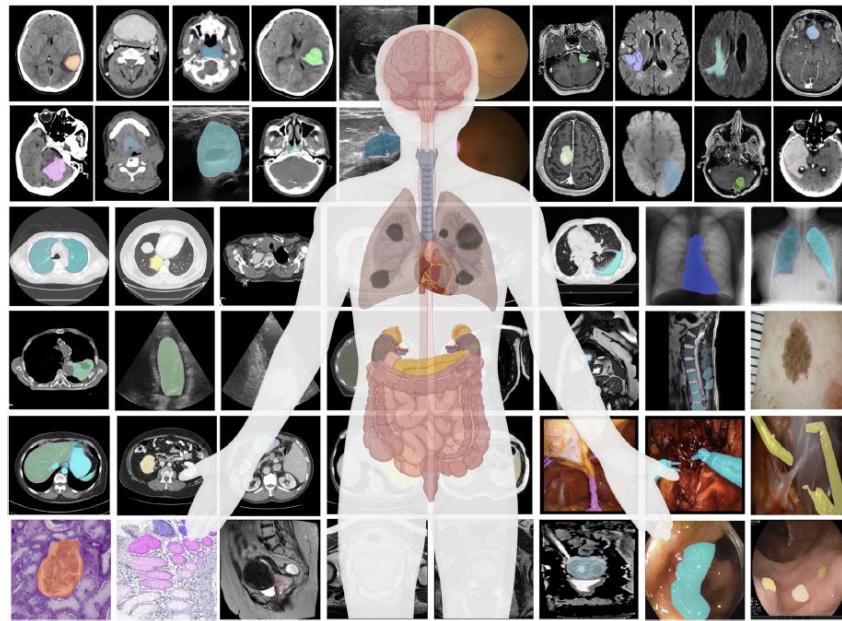
Remember: prompts on test data



Learning / usage objectives.

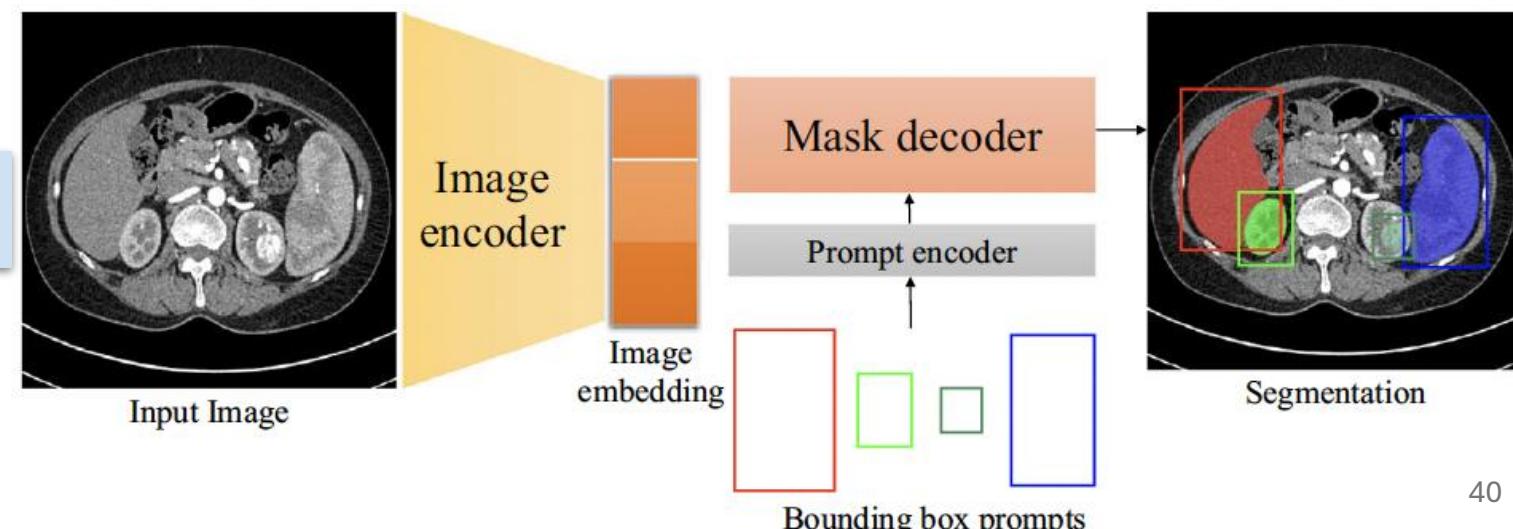
MedSAM

Interactive models (“SAM”)



Fine-tuning SAM on
an huge amount of
medical data

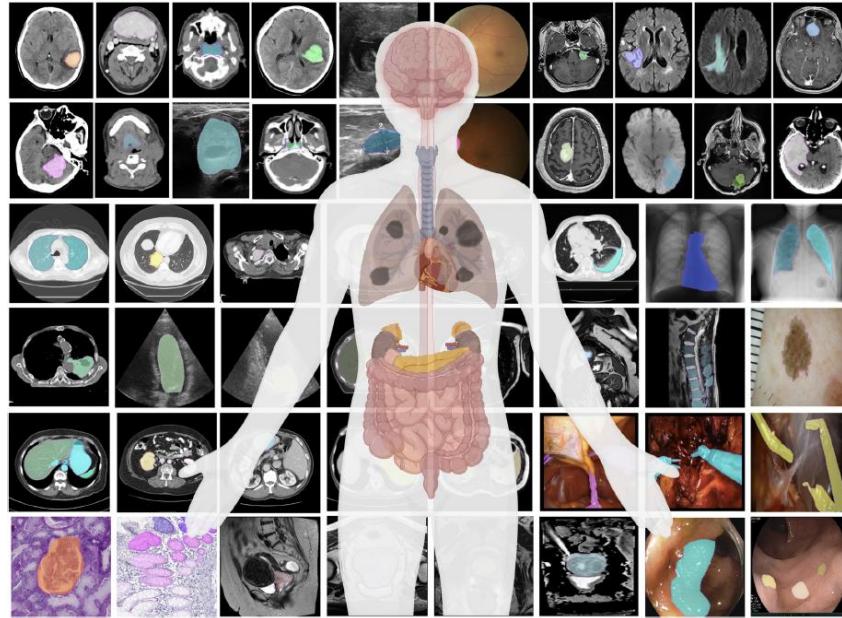
Pipeline



Learning / usage objectives.

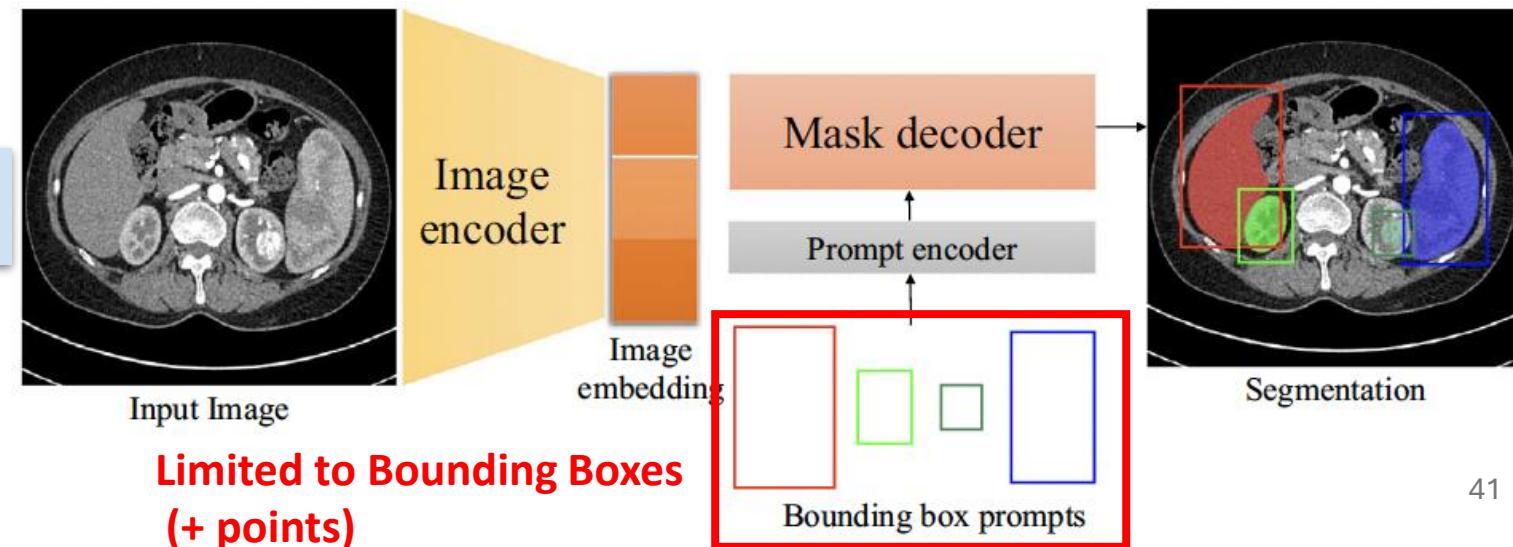
MedSAM

Interactive models (“SAM”)



Trained on an huge amount of data

Pipeline

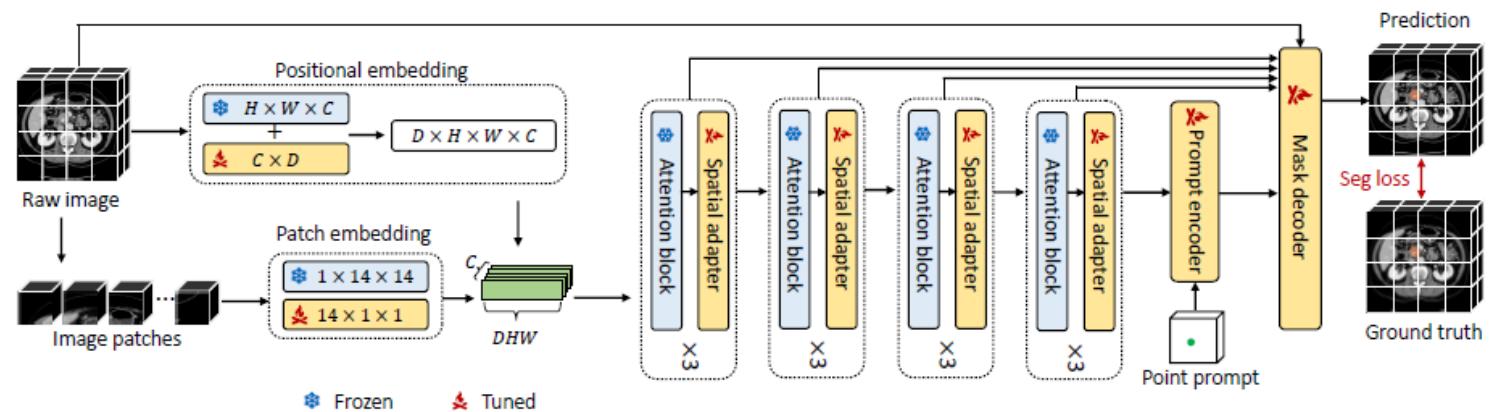
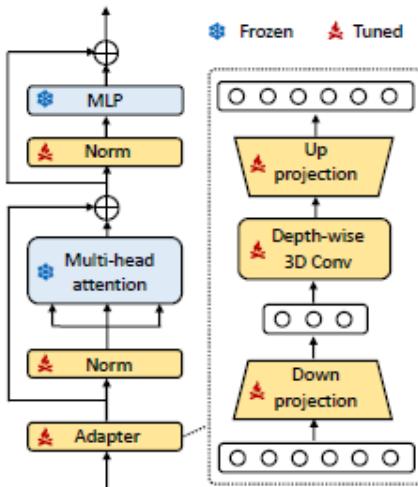


Learning / usage objectives.

3DSAM-Adapter

Interactive models (“SAM”)

Fine-tuning SAM via
Parameter-Efficient
Fine-Tuning



Gong et al. 3DSAM-adapter: Holistic Adaptation of SAM from 2D to 3D for Promptable Medical Image Segmentation. Media'24.

Learning / usage objectives.

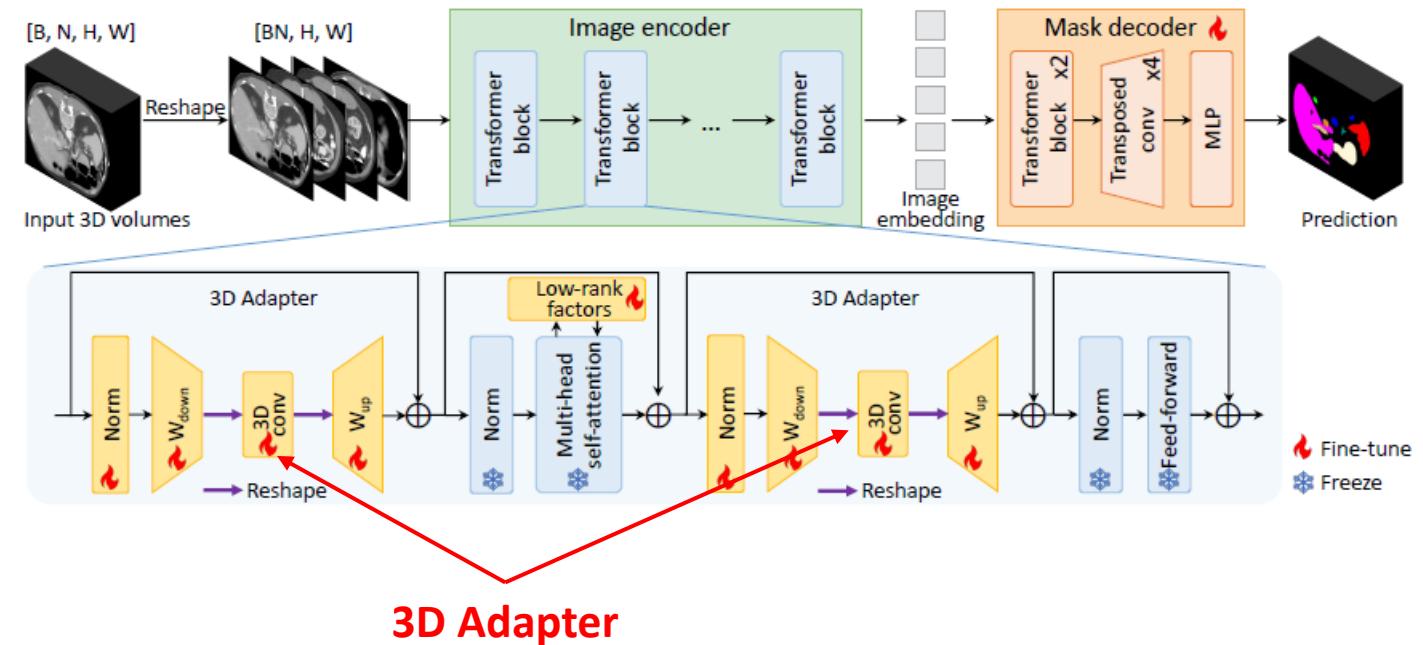
MA-SAM (3D)

Interactive models (“SAM”)

Fine-tuning SAM 2D
via Parameter-Efficient
Fine-Tuning to 3D

→ Adapt for promptable version.

Methods	Dice ↑	NSD ↑
nnU-Net (Isensee et al., 2021)	41.6	62.5
3D UX-Net (Lee et al., 2023)	34.8	52.6
SwinUNETR (Tang et al., 2022b)	40.6	60.0
nnFormer (Zhou et al., 2023a)	36.5	54.0
3DSAM-adapter (automatic) (Gong et al., 2023)	30.2	45.4
3DSAM-adapter (10 pts/scan) (Gong et al., 2023)	57.5	79.6
MA-SAM (automatic)	40.2	59.1
MA-SAM (1 tight 3D bbx/scan)	80.3	97.9
MA-SAM (1 relaxed 3D bbx/scan)	74.7	97.1

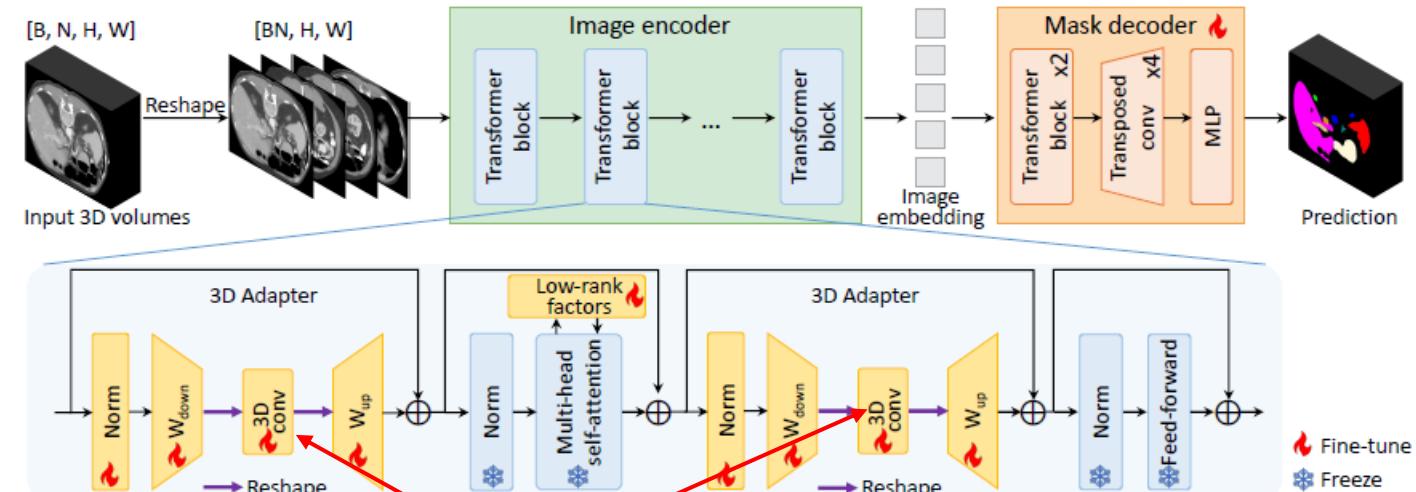


Learning / usage objectives.

MA-SAM (3D)

Interactive models (“SAM”)

Fine-tuning SAM 2D
via Parameter-Efficient
Fine-Tuning to 3D



→ Adapt for zero-shot version (SAM as pre-trained representations).

Methods	Spleen	R.Kd	L.Kd	GB	Eso.	Liver	Stomach	Aorta	IVC	Veins	Pancreas	AG	Average
Dice [%] ↑													
nnU-Net (Isensee et al., 2021)	97.0	95.3	95.3	63.5	77.5	97.4	89.1	90.1	88.5	79.0	87.1	75.2	86.3
3D UX-Net (Lee et al., 2023)	94.6	94.2	94.3	59.3	72.2	96.4	73.4	87.2	84.9	72.2	80.9	67.1	81.4
SwinUNETR (Tang et al., 2022b)	95.6	94.2	94.3	63.6	75.5	96.6	79.2	89.9	83.7	75.0	82.2	67.3	83.1
nnFormer (Zhou et al., 2023a)	93.5	94.9	95.0	64.1	79.5	96.8	90.1	89.7	85.9	77.8	85.6	73.9	85.6
SAMed_h (Zhang and Liu, 2023)	95.3	92.1	92.9	62.1	75.3	96.4	90.2	87.6	79.8	74.2	77.9	61.0	82.1
MA-SAM (Ours)	96.7	95.1	95.4	68.2	82.1	96.9	92.8	91.1	87.5	79.8	86.6	73.9	87.2

3D Adapter

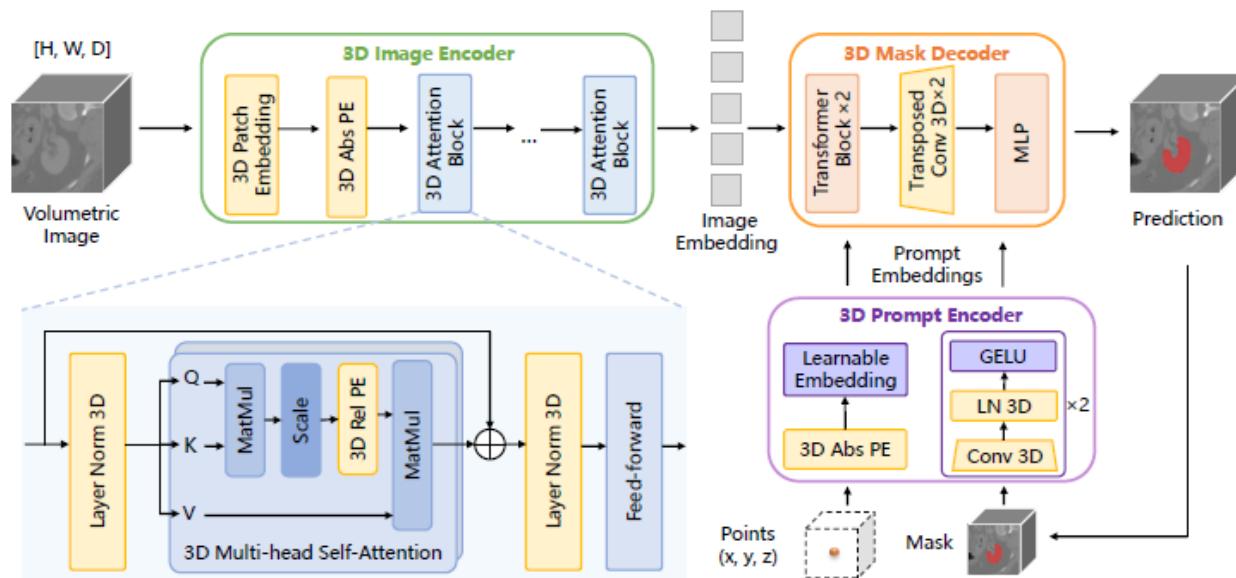
+0.9%

Learning / usage objectives.

Med-SAM3D

Training a 3D SAM
with Medical data
from Scratch

Interactive models (“SAM”)

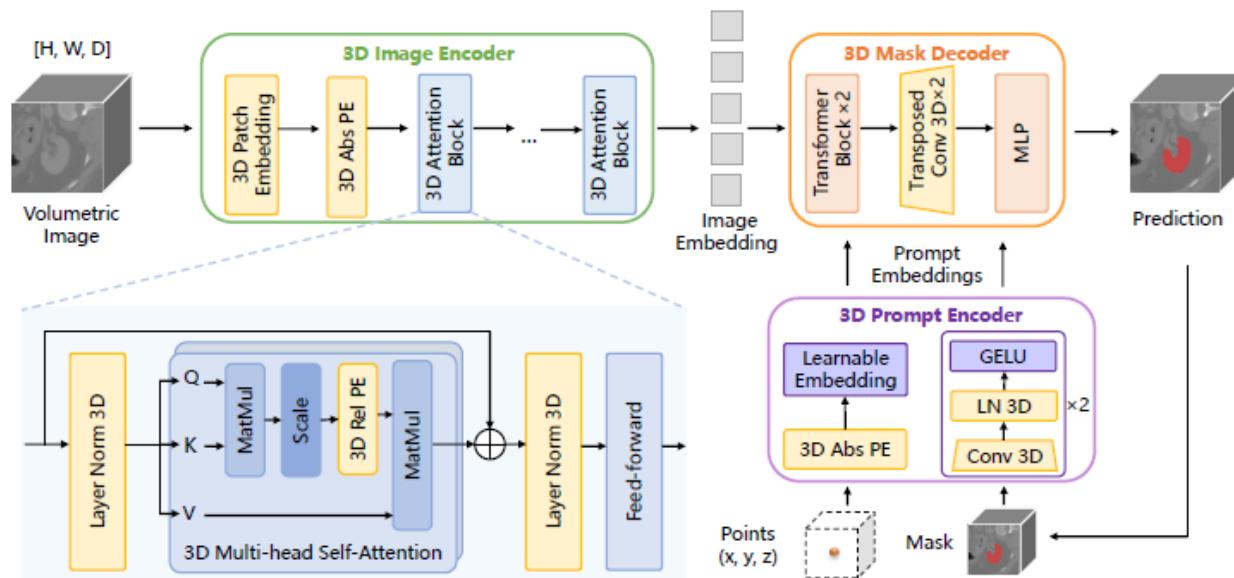


Model	Prompt	Inference Time (s)	Dice (%)		
			Seen	Unseen	Overall
SAM	N pts	$N(\tau + 0.13)$	16.79	11.73	16.15
SAM-Med2D	N pts	$N(\tau + 0.04)$	38.91	22.55	36.83
SAM-Med3D	1 pt	$\tau + 2$	81.98	37.02	76.27
SAM	$3N$ pts	$3N(\tau + 0.19)$	34.61	15.94	32.24
SAM-Med2D	$3N$ pts	$3N(\tau + 0.07)$	51.46	29.70	48.70
SAM-Med3D	3 pts	$3\tau + 3$	84.14	43.80	79.02
SAM	$5N$ pts	$5N(\tau + 0.25)$	49.39	21.86	45.89
SAM-Med2D	$5N$ pts	$5N(\tau + 0.10)$	51.89	30.41	49.17
SAM-Med3D	5 pts	$5\tau + 4$	84.62	46.26	79.75
SAM-Med3D	10 pts	$10\tau + 6$	85.19	49.92	80.71

Learning / usage objectives.

Training a 3D SAM
with Medical data
from Scratch

Interactive models (“SAM”)



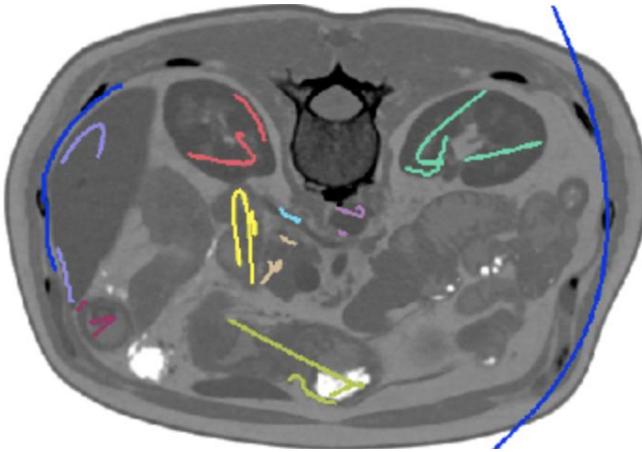
1 point for each N slices

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			Seen	Unseen	Overall
SAM	N pts	$N(\tau + 0.13)$	16.79	11.73	16.15
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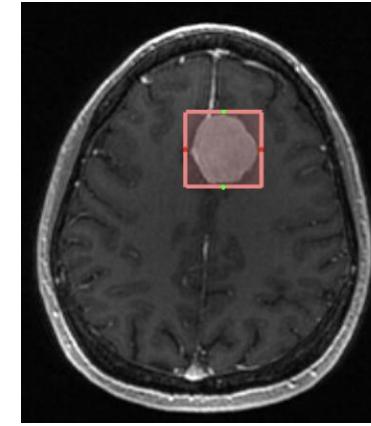
Improved over 2D version

Learning / usage objectives.

Interactive models (“SAM”)



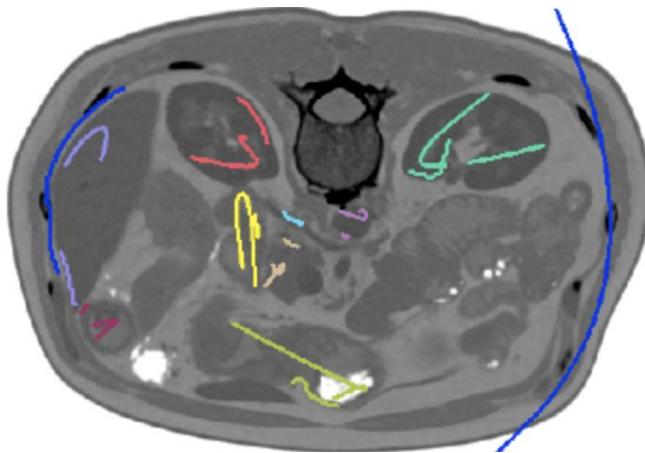
SAM is promptable
(i.e., requires user interaction
per EACH test image)



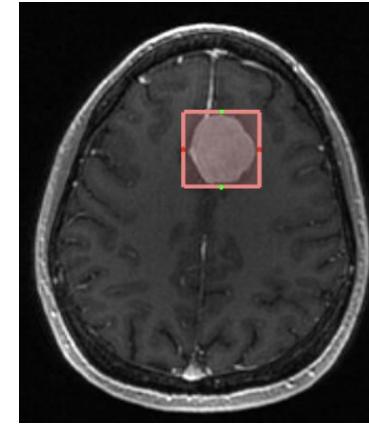
SAM only handles
binary segmentation
(one class at a time)

Learning / usage objectives.

Interactive models (“SAM”)



SAM is promptable
(i.e., requires user interaction per EACH test image)



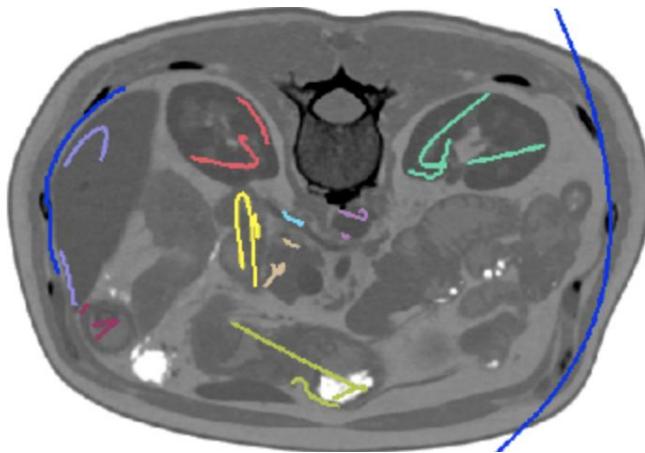
SAM only handles binary segmentation (one class at a time)

Dataset	Modality	Task-specific		General-purpose			
		UNETR [11]	nnU-Net [16]	SAM-Med2D [6] (N pts)	SegVol [8] (pt+text)	Ours (1 pt)	Ours (10 pts)
TotalSegmentator [36]	CT	75.05	85.22	38.26	-	84.68	87.59
KiTS21 [12]	CT	70.75	75.32	68.74	-	72.06	75.37
AMOS-CT [17]	CT	78.33	88.87	49.61	-	79.94	83.99
AMOS-MR [17]	MR	76.29	86.92	45.53	-	75.41	81.13
BTCV* [19]	CT	78.99	81.92	50.05	73.81	79.17	83.01
TDSC-ABUS23* [33]	US*	-	45.08	49.39	-	36.08	54.35

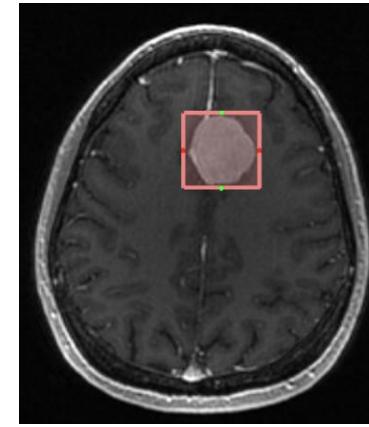
SAM yields sometimes lower results to task-specific models

Learning / usage objectives.

Interactive models (“SAM”)



SAM is promptable
(i.e., requires user interaction per EACH test image)



SAM only handles binary segmentation
(one class at a time)

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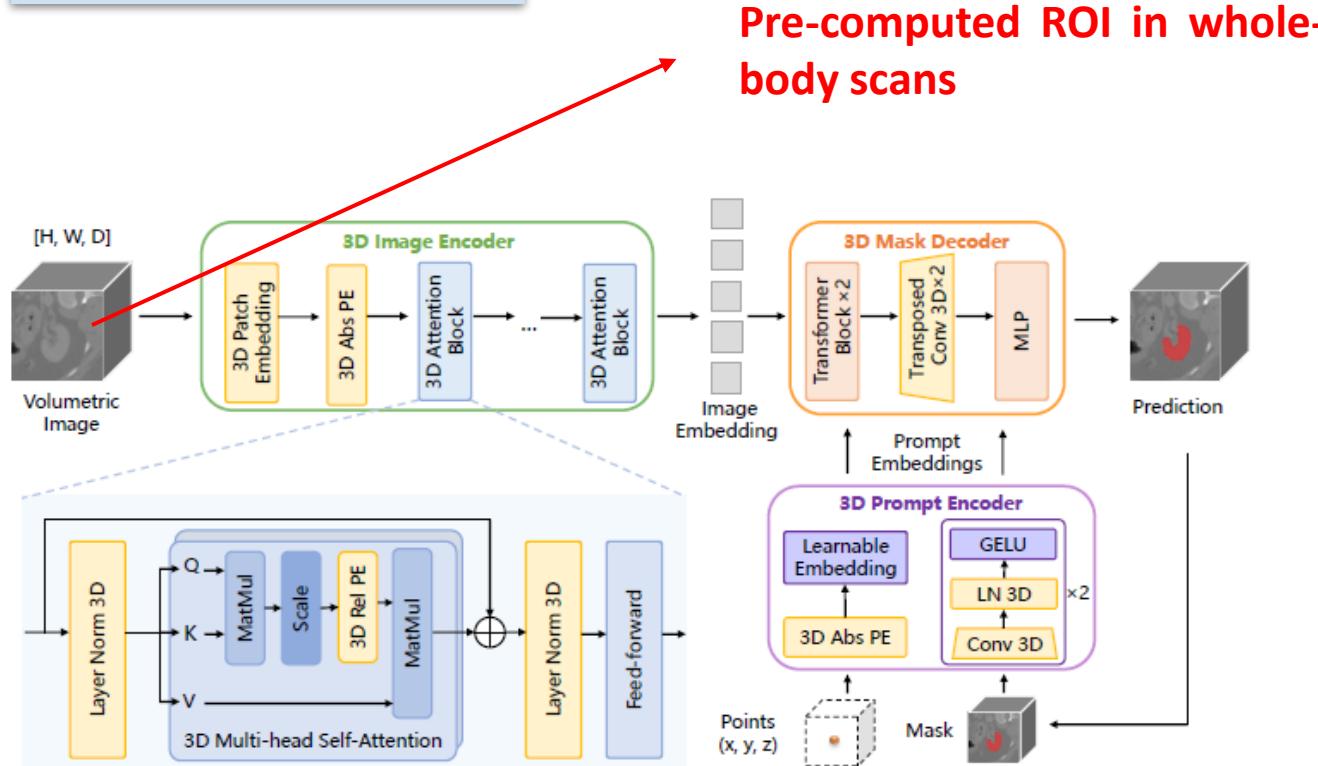
SAM yields sometimes lower results to task-specific models

Learning / usage objectives.

Med-SAM3D

Other
Details

Interactive models (“SAM”)



Pre-computed ROI in whole-body scans

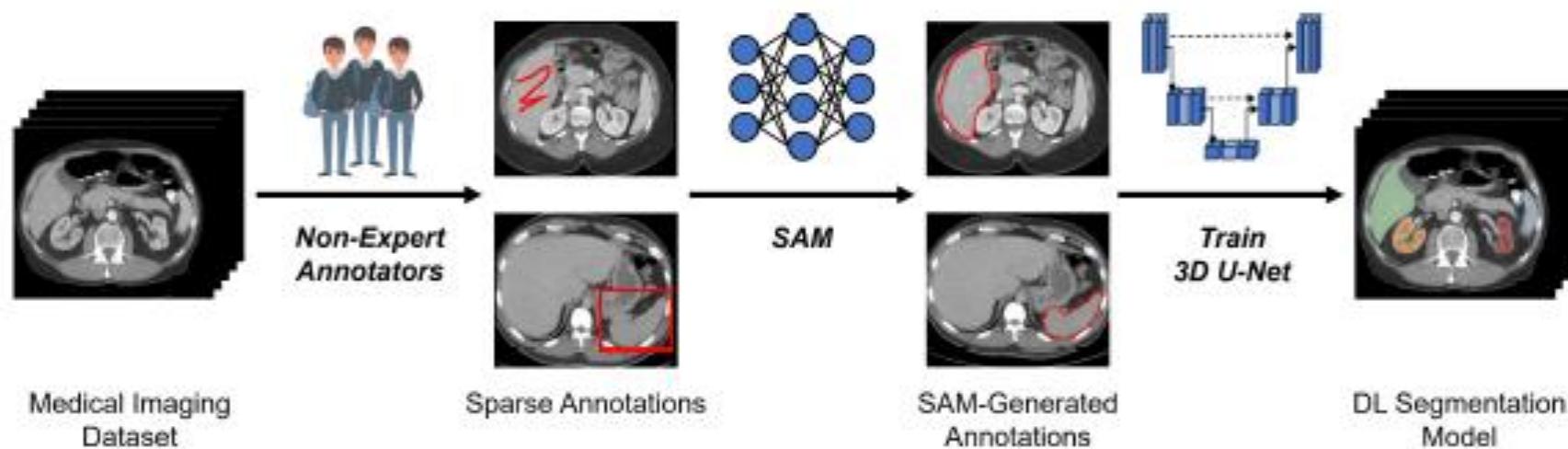
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SAM-Med3D	10 pts	$10\tau + 6$	85.19	49.92	80.71

Iterative random points over the error region
(explicit access to GT)

Learning / usage objectives.

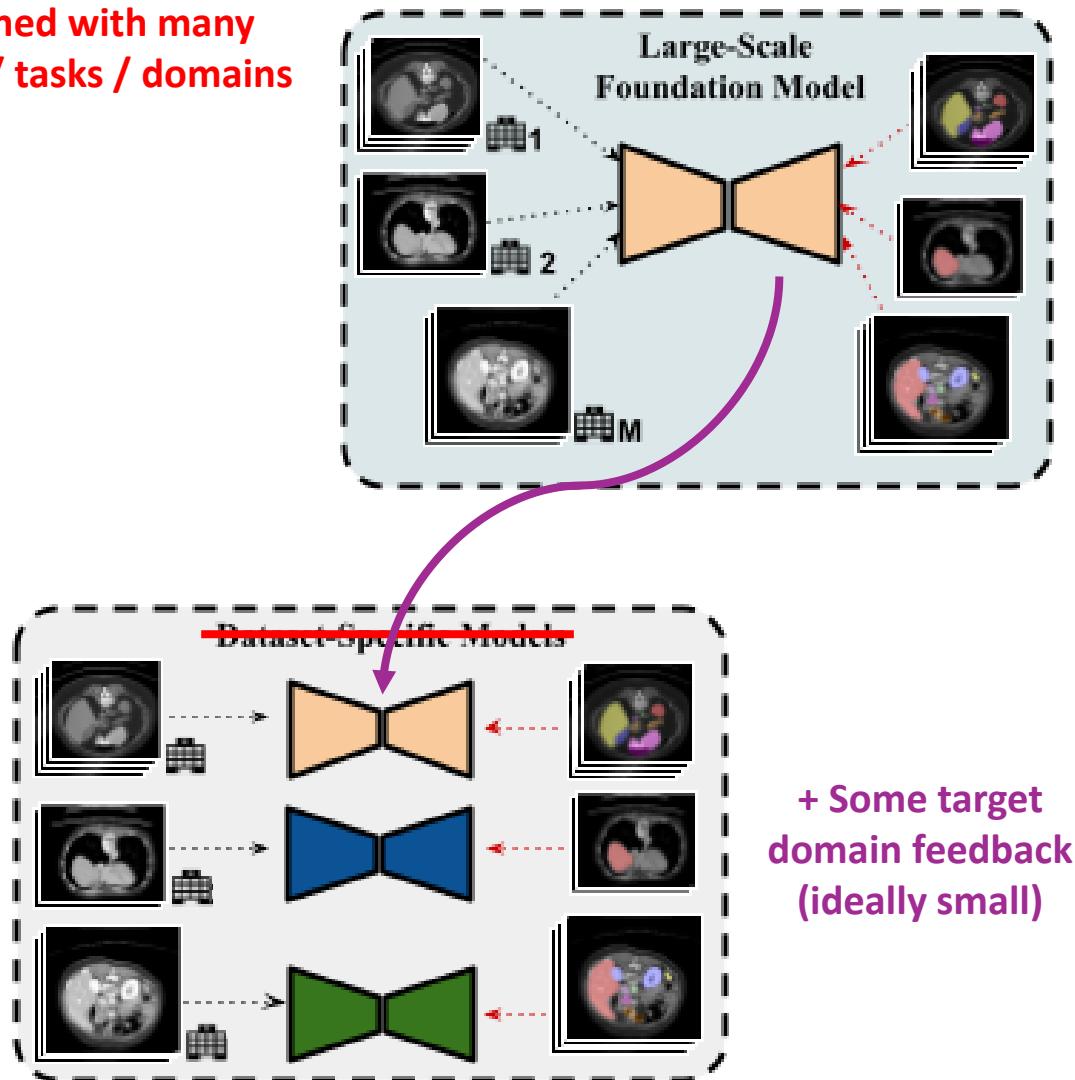
Interactive models (“SAM”)

Applications in Active Learning / Annotations



Kulkarni et al. Anytime, Anywhere, Anyone: Investigating the Feasibility of SAM for Crowd-Sourcing Medical Image Annotations. MIDL'24.

Foundation models for medical image segmentation



Organizing the mess!

1. Types of foundation models: a data perspective.
 - A. Generalist vs. Specialized
 - B. 2D vs. 3D
 - C. Multimodal vs. Unimodal
2. Learning/Usage Objectives
 - A. Zero-shot / Transfer Learning
 - B. In-Context Learning
 - C. Interactive Models (“SAM”)
3. Zero-shot / Adaptation-oriented (3D data)
 - A. How to pre-train?
 - B. How useful are foundation models? Limitations on the adaptation stage
 - C. Few-shot Parameter-Efficient Fine-tuning

Learning / usage objectives.

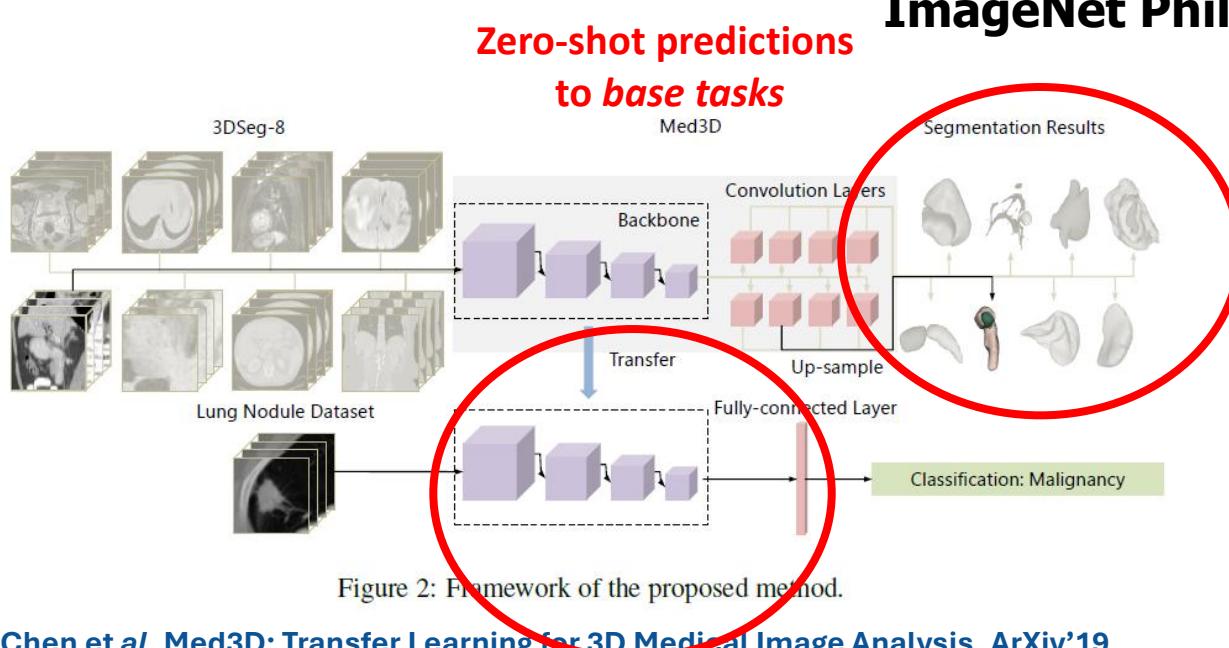
Med3D('19)

CLIP-Driven

MultiTalent

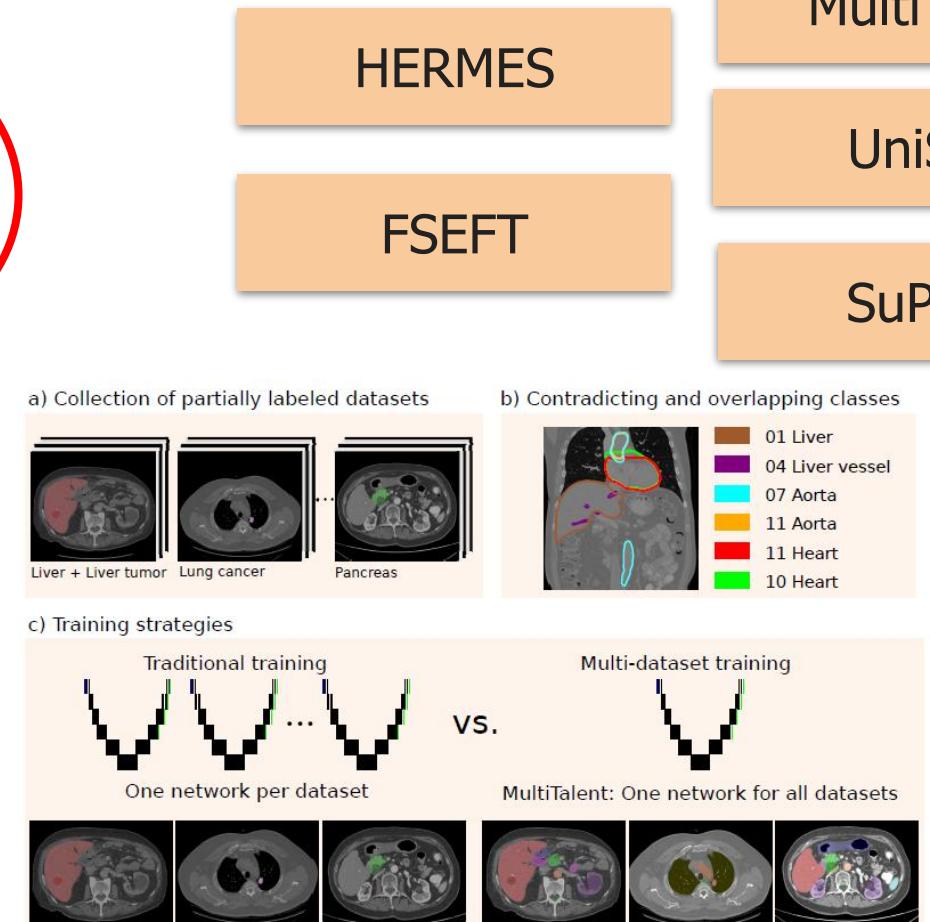
UniSeg

SuPreM



Chen et al. Med3D: Transfer Learning for 3D Medical Image Analysis. ArXiv'19.

Fine-tuning to novel domains/tasks



Ulrich et al. MultiTalent: A Multi-Dataset Approach to Medical Image Segmentation. MICCAI'23.

Zero-shot / Adaptation Oriented (3D Data)

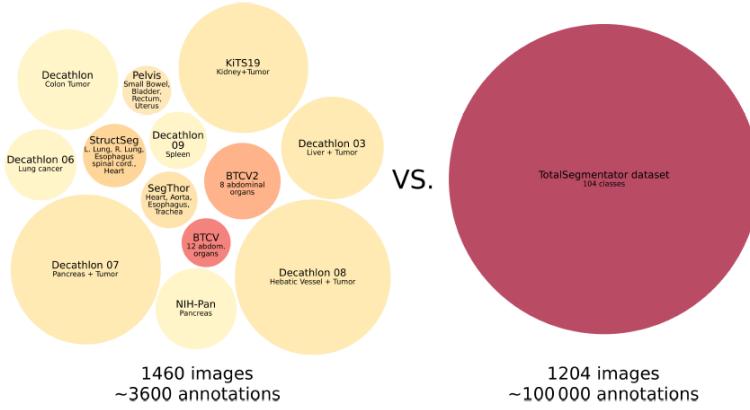
Med3D('19)

CLIP-Driven

MultiTalent

UniSeg

SuPreM



Ulrich et al. MultiTalent: A Multi-Dataset Approach to Medical Image Segmentation. MICCAI'23.

Datasets	# Targets	# Scans	Annotated Organs or Tumors
1. Pancreas-CT [62]	1	82	Pancreas
2. LiTS [3]	2	201	Liver, Liver Tumor*
3. Kits [25]	2	300	Kidney, Kidney Tumor*
4. AbdomenCT-1K [45]	4	1,000	Spleen, Kidney, Liver, Pancreas
5. CT-ORG [60]	4	140	Lung, Liver, Kidneys and Bladder
6. CHAOS [73]	4	40	Liver, Left Kidney, Right Kidney, Spl
7-11. MSD CT Tasks [1]	9	947	Spl, Liver and Tumor*, Lung Tumor*, Colon Tumor*, Pan and Tumor*, Hepatic Vessel and Tumor*
12. BTCV [37]	13	50	Spl, RKid, LKid, Gall, Eso, Liv, Sto, Aor, IVC, R&SVeins, Pan, RAG, LAG
13. AMOS22 [32]	15	500	Spl, RKid, LKid, Gall, Eso, Liv, Sto, Aor, IVC, Pan, RAG, LAG, Duo, Bla, Pro/UTE
14. WORD [44]	16	150	Spl, RKid, LKid, Gall, Eso, Liv, Sto, Pan, RAG, Duo, Col, Int, Rec, Bla, LFH, RFH
15. 3D-IRCADb [67]	13	20	Liv, Liv Cyst, RLung, LLung, Venous, PVein, Aor, Spl, RKid, LKid, Gall, IVC
16. TotalSegmentator [79]	104	1,024	Clavicula, Humerus, Scapula, Rib 1-12, Vertebrae C1-7, Vertebrae T1-9, Vertebrae L1-5, Hip, Sacrum, Femur, Aorta, Pulmonary Artery, Right Ventricle, Right Atrium, Left Atrium, Left Ventricle, Myocardium, PVein, SVein, IVC, Iliac Artery, Iliac Vena, Brain, Trachea, Lung Upper Lobe, Lung Middle Lobe, Lung Lower Lobe, AG, Spl, Liv, Gall, Pan, Kid, Eso, Sto, Duo, Small Bowel, Colon, Bla, Autochthon, Iliopsoas, Gluteus Minimus, Gluteus Medius, Gluteus Maximus
17. JHH (<i>private</i>)	21	5,038	Aor, AG, CBD, Celiac AA, Colon, duo, Gall, IVC, Lkid, RKid, Liv, Pan, Pan Duct, SMA, Small bowel, Spl, Sto, Veins, Kid LtRV, Kid RtRV, CBD Stent, PDAC*, PanNET*, Pancreatic Cyst*

Liu et al. CLIP-Driven Universal Model for Organ Segmentation and Tumor Detection. ICCV'23.

Zero-shot /Adaptation Oriented (3D Data)

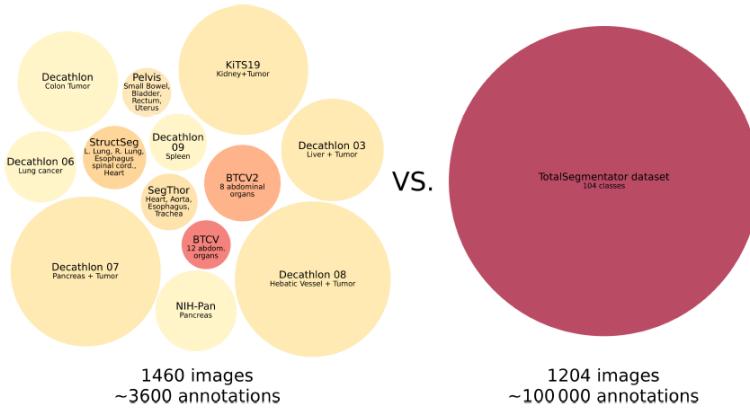
Med3D('19)

CLIP-Driven

MultiTalent

UniSeg

SuPreM



Ulrich et al. MultiTalent: A Multi-Dataset Approach to Medical Image Segmentation. MICCAI'23.

- A good number of annotated scans publicly available.
(current models are pre-trained with 2K CTs)
 - Anatomical morphology is natural 3D.
 - Labeling at voxel level is tremendously costly for practitioners.
(10 min per structure according to TotalSegmentator).
 - Enormous potential of FMs to address inter-center, inter-scan and demographics variabilities.

Datasets	# Targets	# Scans	Annotated Organs or Tumors
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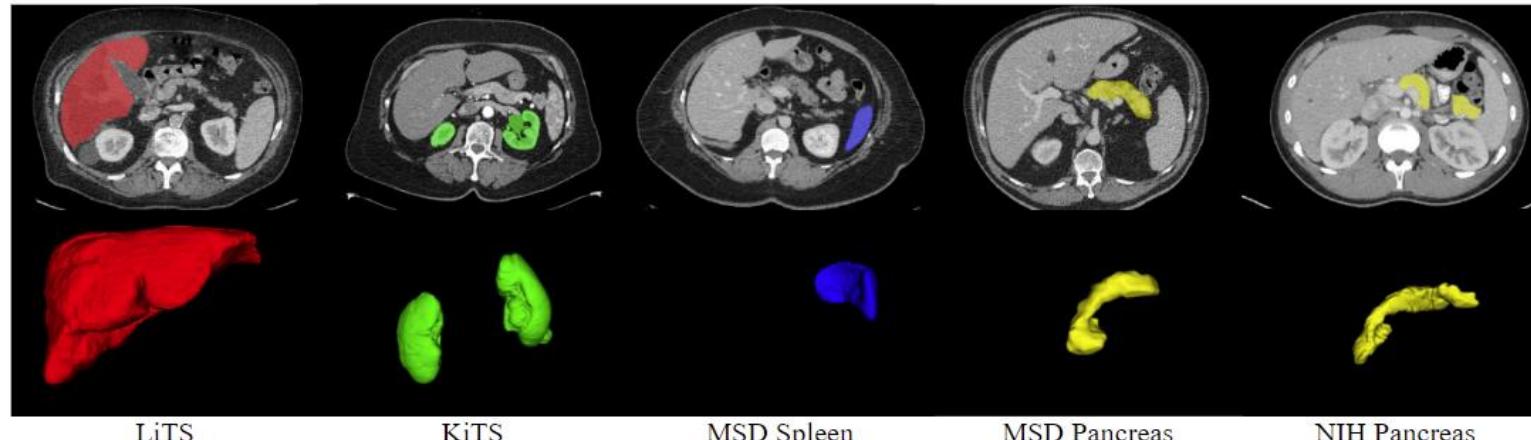
Liu et al. CLIP-Driven Universal Model for Organ Segmentation and Tumor Detection. ICCV'23.

Zero-shot / Adaptation Oriented (3D Data)

Med3D('19)

Challenges of Dataset Assembling

Partially-labeled datasets



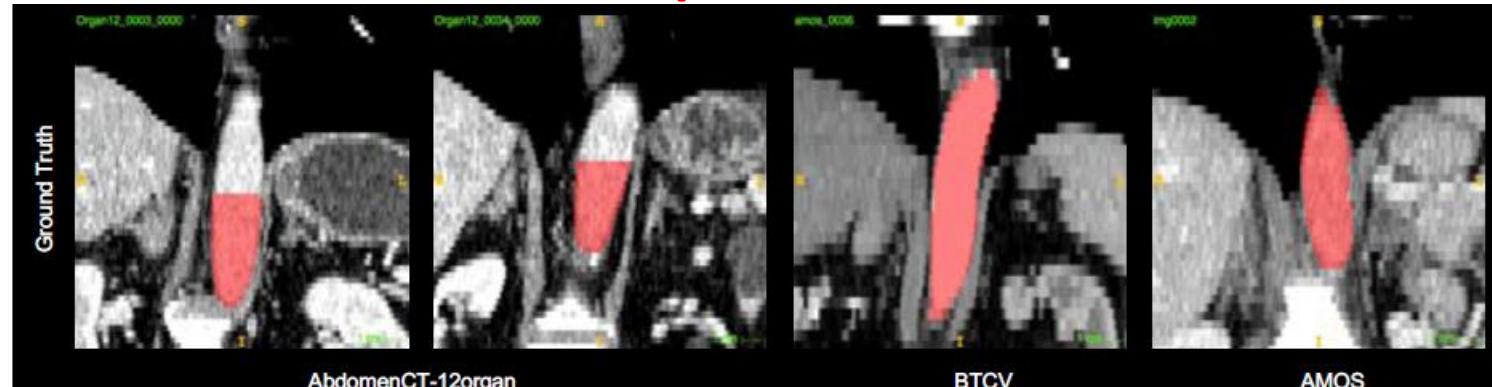
CLIP-Driven

MultiTalent

UniSeg

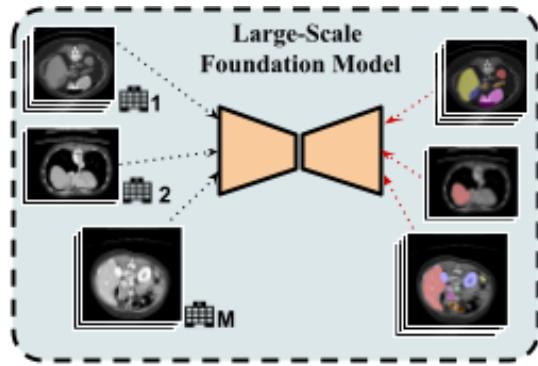
SuPreM

Inconsistent annotation protocols



Zero-shot / Adaptation Oriented (3D Data)

MultiTalent

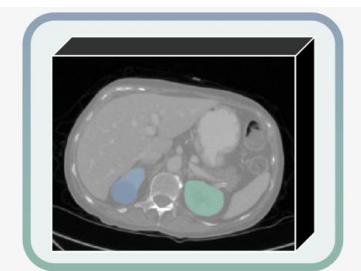


How to pre-train? Standard

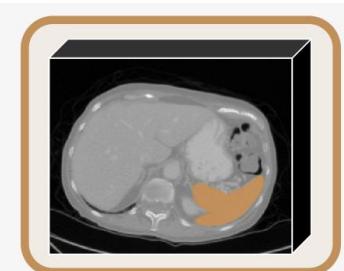
FSEFT

Assembly Dataset with
Partial Labels

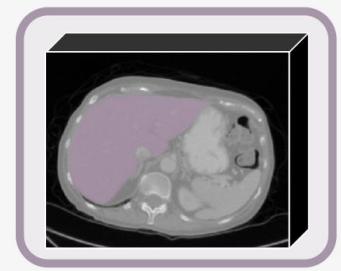
$$\mathcal{D}_T = \{(\mathbf{X}_n, \mathbf{Y}_n, \mathbf{w}_n)\}_{n=1}^N$$



Dataset A: kidney



Dataset B: spleen

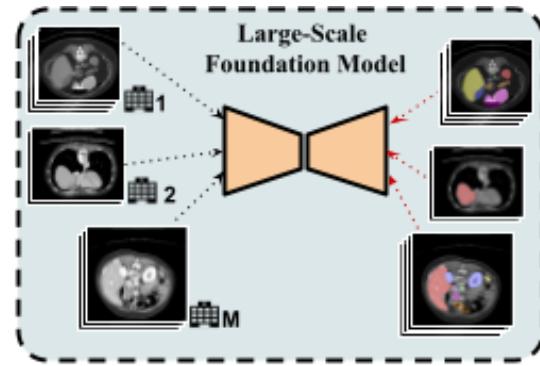


Dataset D: liver

Zero-shot / Adaptation Oriented (3D Data)

MultiTalent

FSEFT



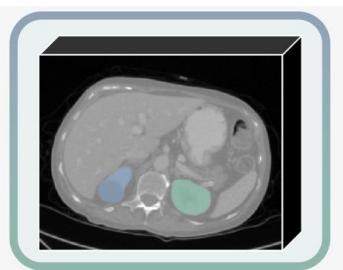
How to pre-train? Standard

Total Number of Categories

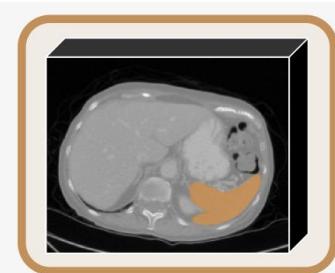
Assembly Dataset with Partial Labels

$$w^c = [0, 1, 1, 0, 0, 0, 1, 0, 0]$$

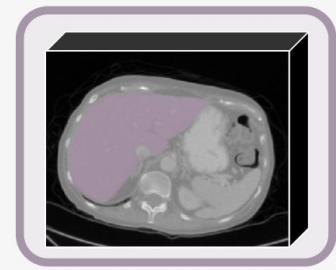
$$\mathcal{D}_T = \{(\mathbf{X}_n, \mathbf{Y}_n, \mathbf{w}_n)\}_{n=1}^N$$



Dataset A: kidney



Dataset B: spleen

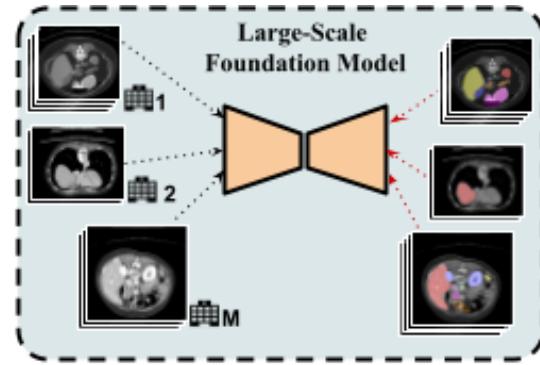


Dataset D: liver

Zero-shot / Adaptation Oriented (3D Data)

MultiTalent

FSEFT



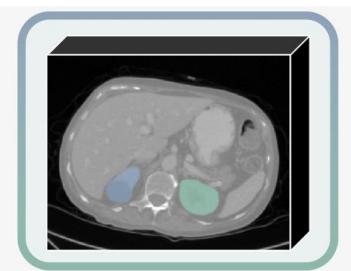
How to pre-train? Standard

Assembly Dataset with
Partial Labels

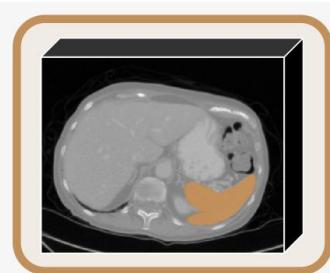
Annotated on its dataset

$$w^c = [0, 1, 1, 0, 0, 0, 1, 0, 0]$$

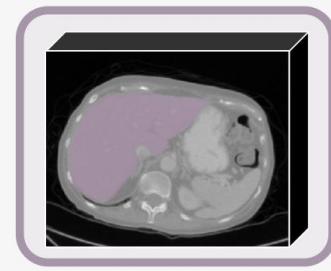
$$\mathcal{D}_T = \{(\mathbf{X}_n, \mathbf{Y}_n, \mathbf{w}_n)\}_{n=1}^N$$



Dataset A: kidney



Dataset B: spleen

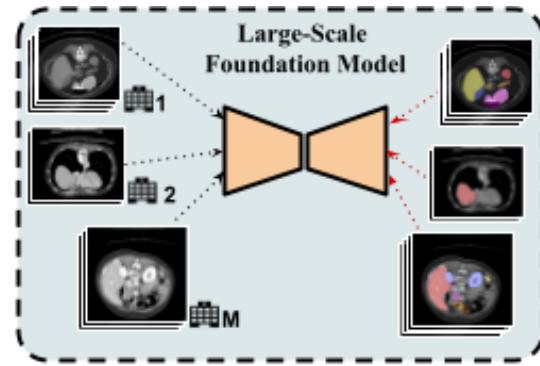


Dataset D: liver

Zero-shot / Adaptation Oriented (3D Data)

MultiTalent

FSEFT



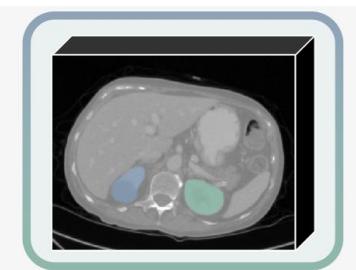
How to pre-train? Standard

NOT annotated on its
dataset

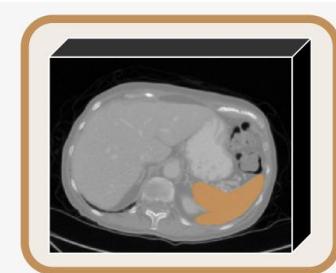
Assembly Dataset with
Partial Labels

$$w^c = [0, 1, 1, 0, 0, 0, 1, 0, 0]$$

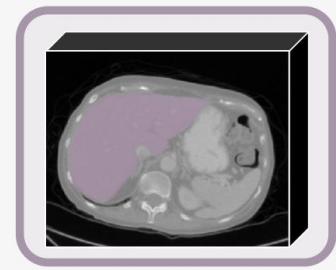
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Dataset A: kidney



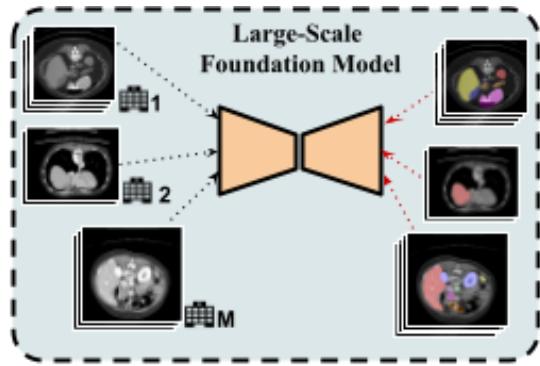
Dataset B: spleen



Dataset D: liver

Zero-shot / Adaptation Oriented (3D Data)

MultiTalent



How to pre-train? Standard

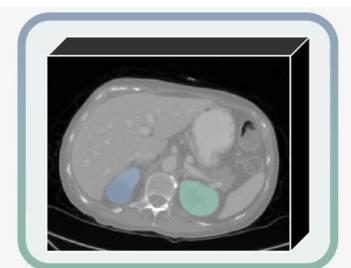
FSEFT

1. Forward Encoder-Decoder

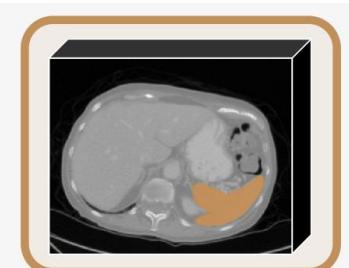
$$\mathbf{Z}_n = \theta_f(\mathbf{X}_n)$$

Assembly Dataset with
Partial Labels

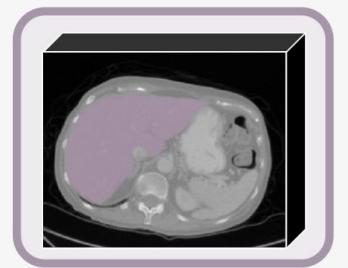
$$\mathcal{D}_T = \{(\mathbf{X}_n, \mathbf{Y}_n, \mathbf{w}_n)\}_{n=1}^N$$



Dataset A: kidney



Dataset B: spleen

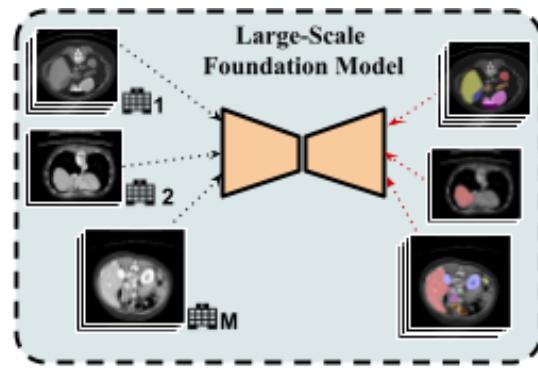


Dataset D: liver

Zero-shot / Adaptation Oriented (3D Data)

MultiTalent

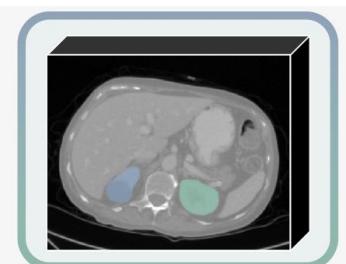
FSEFT



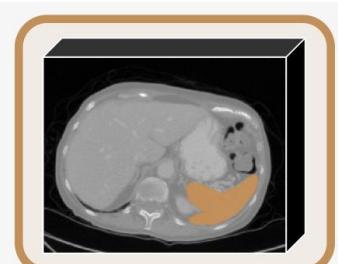
How to pre-train? Standard

Assembly Dataset with
Partial Labels

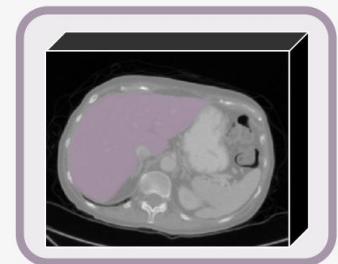
$$\mathcal{D}_T = \{(\mathbf{X}_n, \mathbf{Y}_n, \mathbf{w}_n)\}_{n=1}^N$$



Dataset A: kidney



Dataset B: spleen



Dataset D: liver

1. Forward Encoder-Decoder

$$\mathbf{Z}_n = \theta_f(\mathbf{X}_n)$$

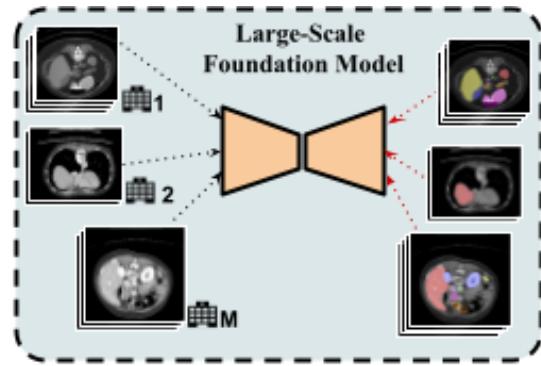
2. Forward Classifier + Sigmoid activation

$$\hat{\mathbf{Y}}_n = \sigma(\theta_c(\mathbf{Z}_n))$$

Disentangle prediction
for each task
(softmax might affect not-
annotated categories)

Zero-shot / Adaptation Oriented (3D Data)

MultiTalent

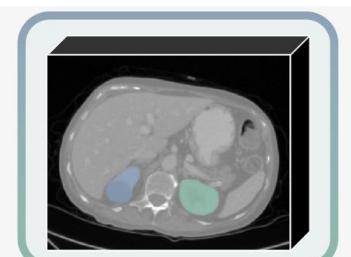


How to pre-train? Standard

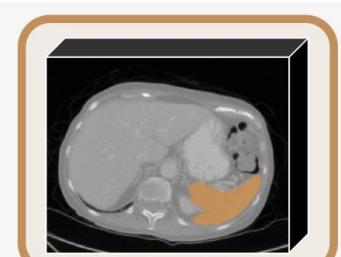
FSEFT

Assembly Dataset with
Partial Labels

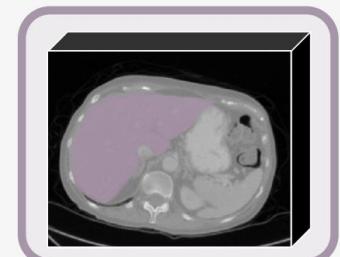
$$\mathcal{D}_T = \{(\mathbf{X}_n, \mathbf{Y}_n, \mathbf{w}_n)\}_{n=1}^N$$



Dataset A: kidney



Dataset B: spleen



Dataset D: liver

1. Forward Encoder-Decoder

$$\mathbf{Z}_n = \theta_f(\mathbf{X}_n)$$

2. Forward Classifier + Sigmoid activation

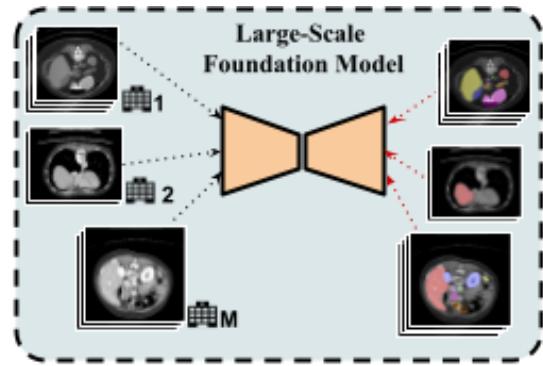
$$\hat{\mathbf{Y}}_n = \sigma(\theta_c(\mathbf{Z}_n))$$

3. Compute any **masked** segmentation loss, and update

$$\min_{\theta_f, \theta_c} \quad \frac{1}{\sum_k \mathbf{w}_{n,k}} \sum_k \mathbf{w}_{n,k} \mathcal{L}_{SEG}(\mathbf{Y}_{n,k}, \hat{\mathbf{Y}}_{n,k}), \quad n = 1, \dots, N$$

Zero-shot / Adaptation Oriented (3D Data)

MultiTalent

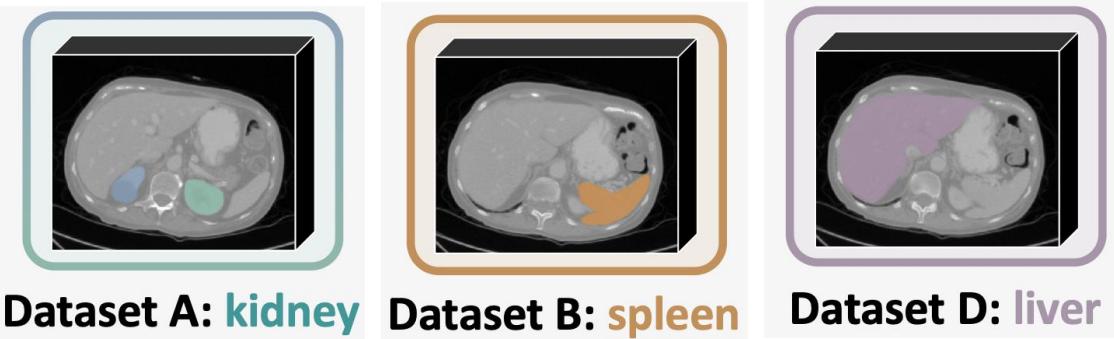


How to pre-train? Standard

FSEFT

Assembly Dataset with
Partial Labels

$$\mathcal{D}_T = \{(\mathbf{X}_n, \mathbf{Y}_n, \mathbf{w}_n)\}_{n=1}^N$$



1. Forward Encoder-Decoder

$$\mathbf{Z}_n = \theta_f(\mathbf{X}_n)$$

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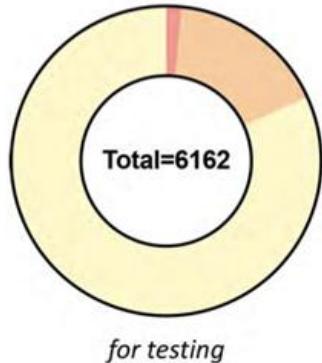
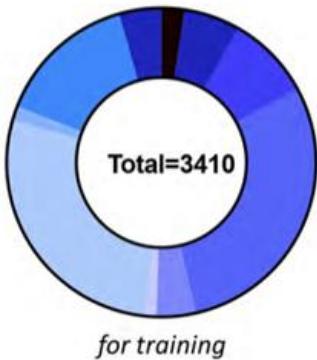
$$L = \sum_c \left(\mathbb{1}_c^{(k)} \frac{1}{I} \sum_z BCE(\hat{y}_{z,c}^{(k)}, y_{z,c}^{(k)}) - \frac{2 \sum_z \mathbb{1}_c^{(k)} \hat{y}_{z,c}^{(k)} y_{z,c}^{(k)}}{\sum_z \mathbb{1}_c^{(k)} \hat{y}_{z,c}^{(k)} + \sum_z \mathbb{1}_c^{(k)} y_{z,c}^{(k)}} \right)$$

Zero-shot / Adaptation Oriented (3D Data)

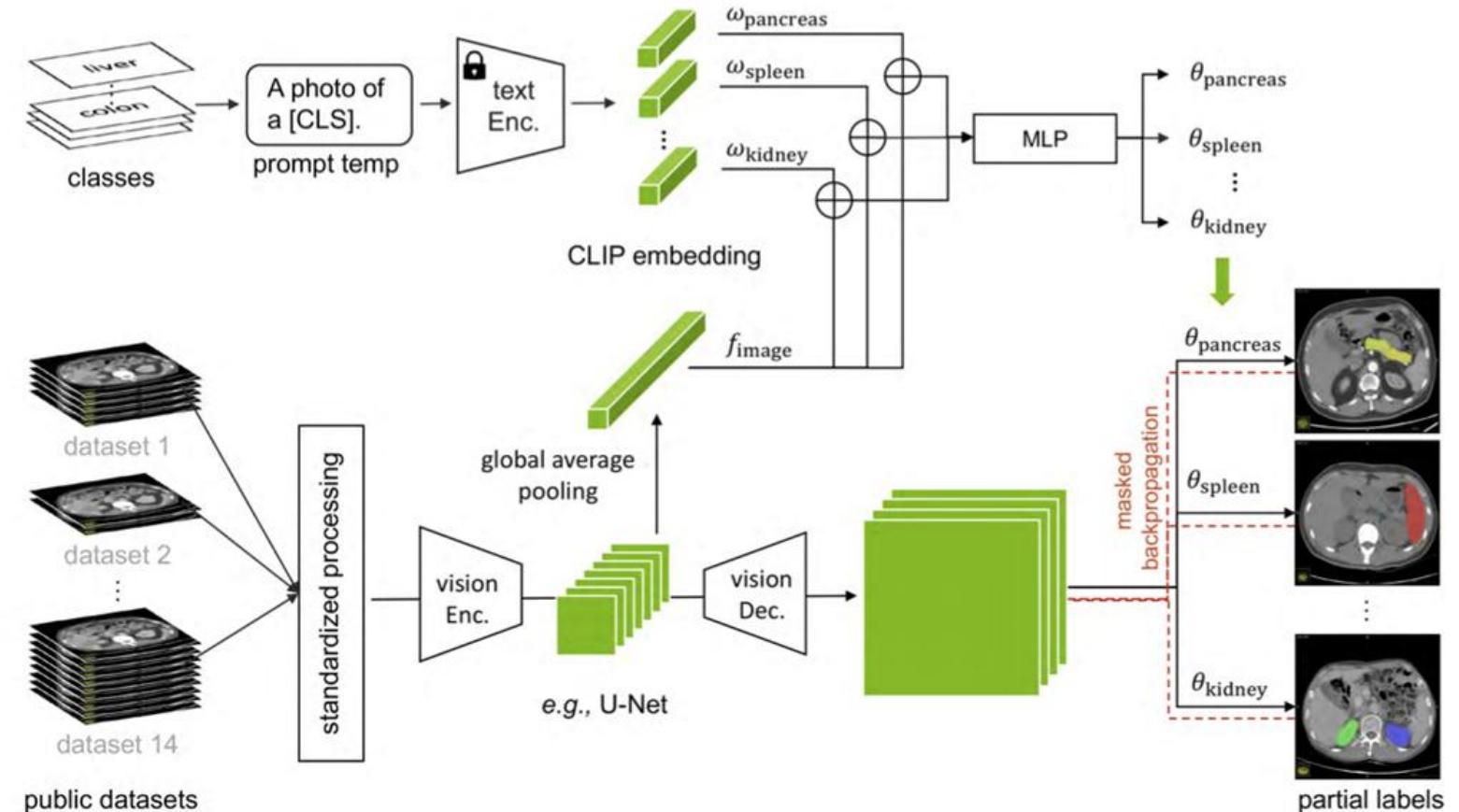
CLIP-Driven

SuPreM

Main idea



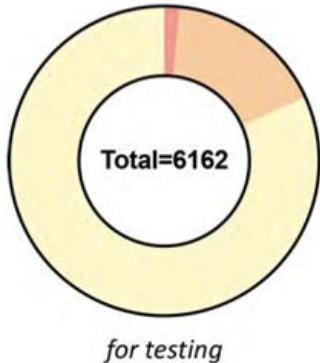
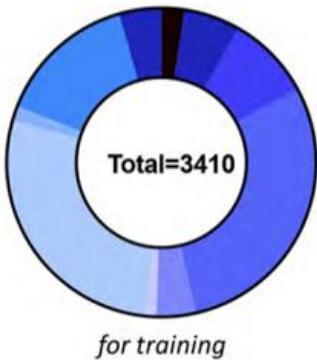
How to pre-train? CLIP-Driven



Zero-shot / Adaptation Oriented (3D Data)

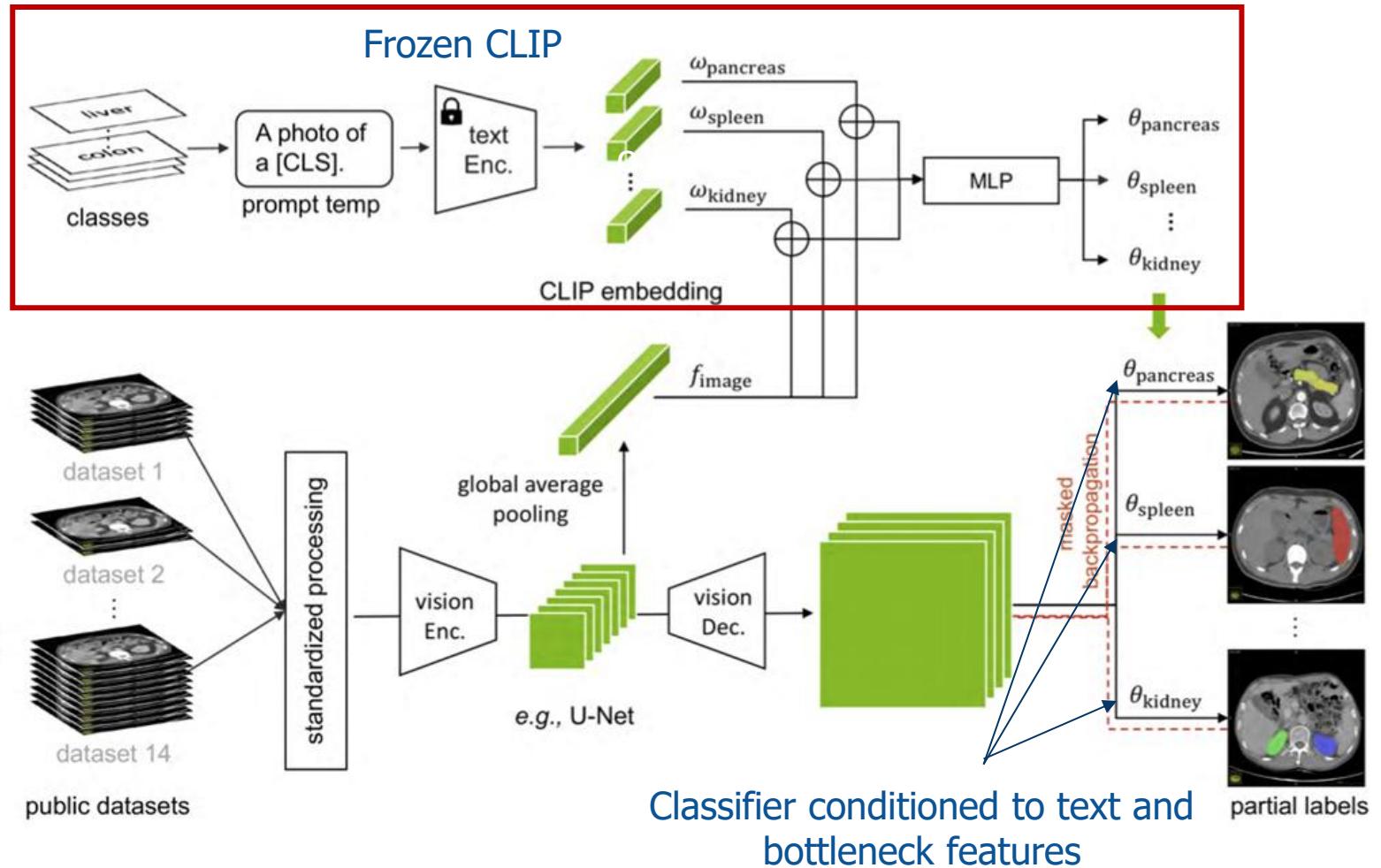
CLIP-Driven

Main idea



How to pre-train? CLIP-Driven

SuPreM

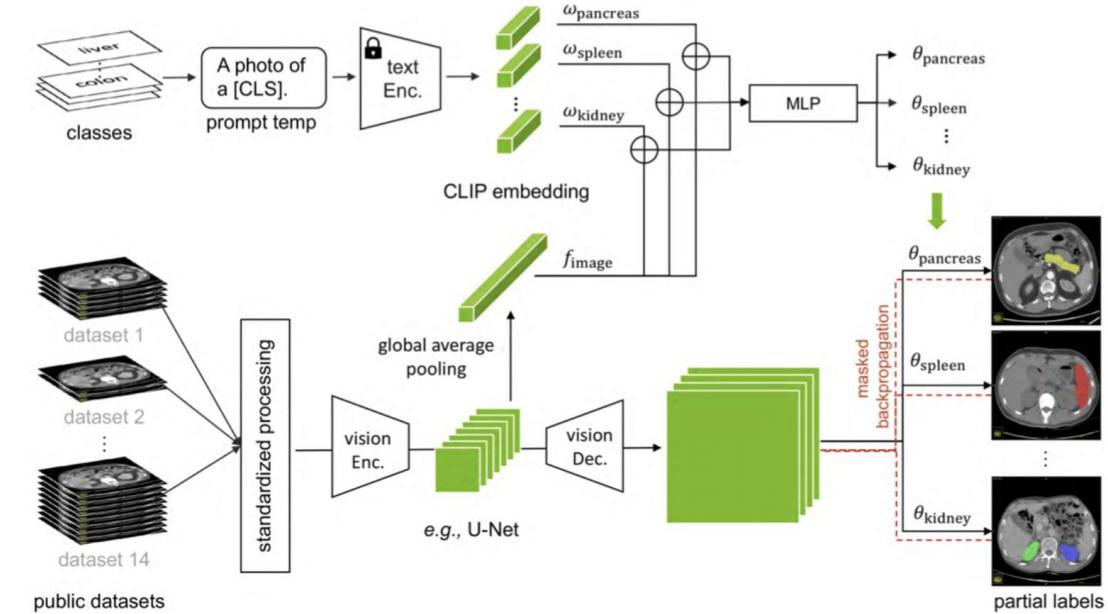


Zero-shot / Adaptation Oriented (3D Data)

CLIP-Driven

How to pre-train? CLIP-Driven

SuPreM



Zero-shot / Adaptation Oriented (3D Data)

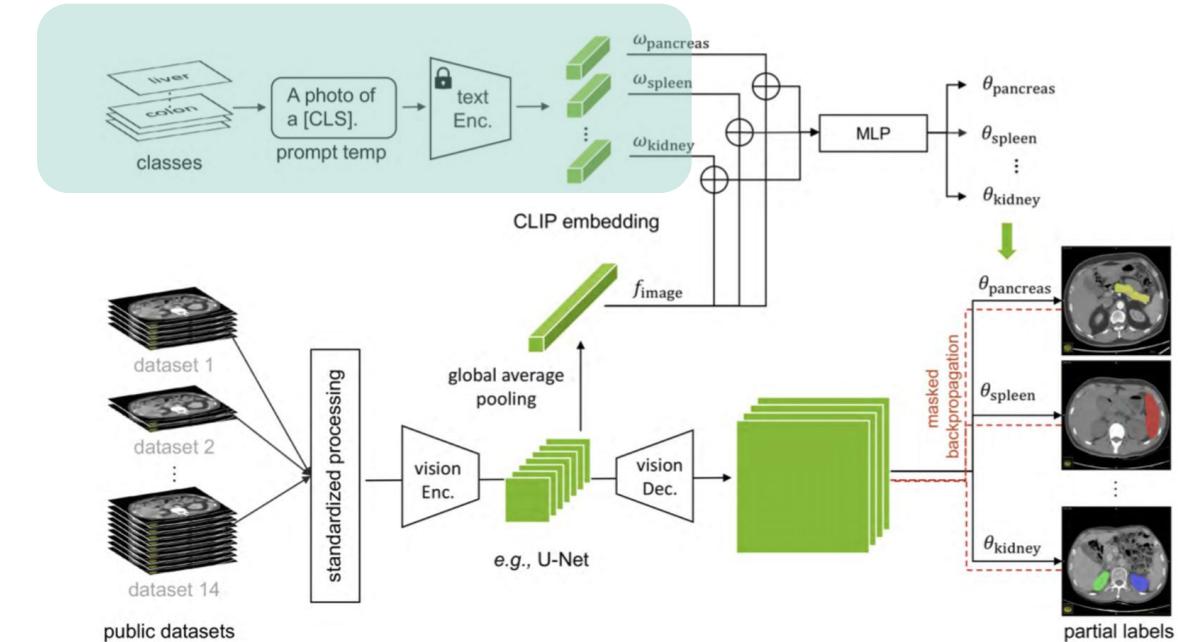
CLIP-Driven

Text branch
(generates text embedding for class k)

\mathbf{w}_k

How to pre-train? CLIP-Driven

SuPreM



Zero-shot / Adaptation Oriented (3D Data)

CLIP-Driven

Text branch
(generates text embedding for class k)

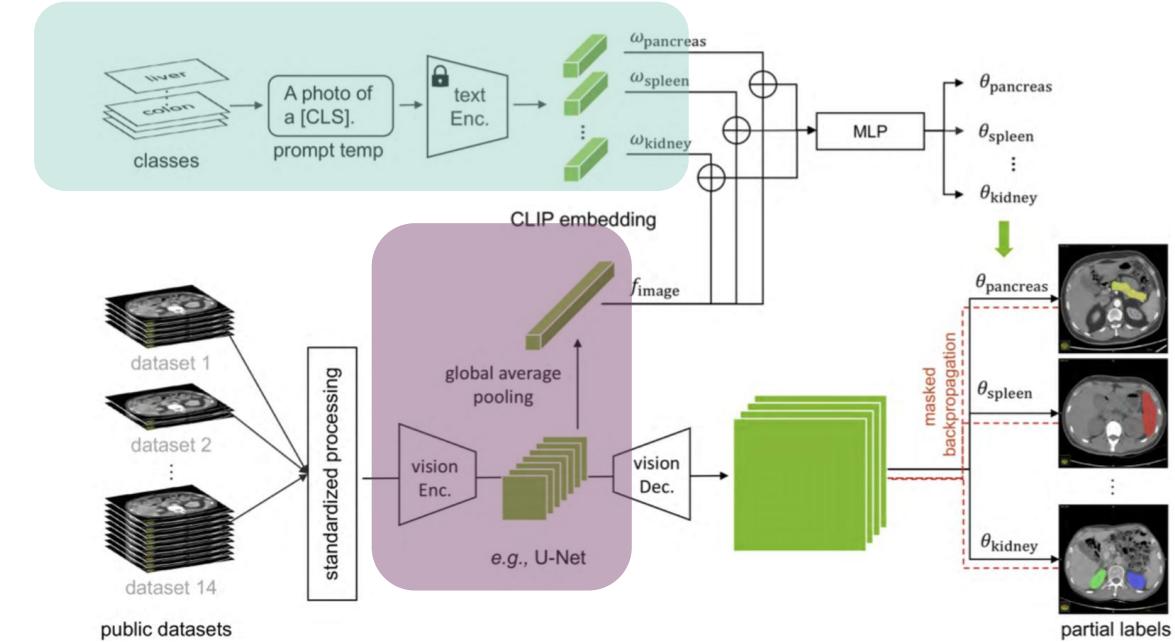
\mathbf{w}_k

Visual branch-encoder
(generates visual embedding for volume x)

\mathbf{f}

How to pre-train? CLIP-Driven

SuPreM



Zero-shot / Adaptation Oriented (3D Data)

CLIP-Driven

Text branch
(generates text embedding for class k)

\mathbf{w}_k

Visual branch-encoder
(generates visual embedding for volume x)

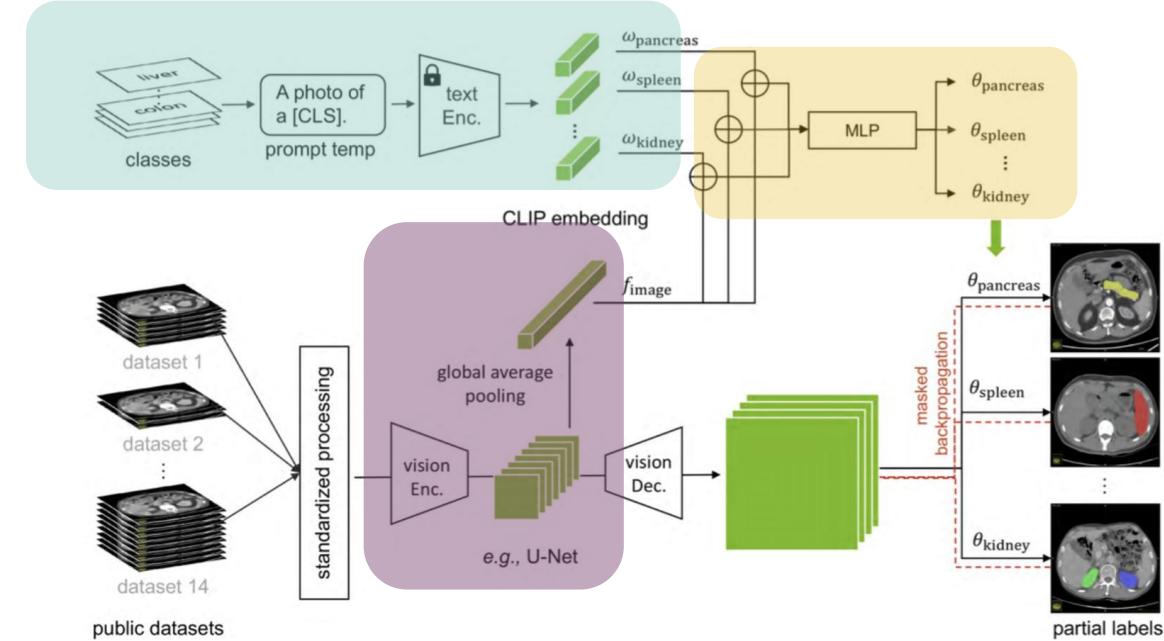
\mathbf{f}

Text-based controller MLP
(generates class parameters)

$$\theta_k = \text{MLP}(\mathbf{w}_k \oplus \mathbf{f})$$
$$\theta_k = \{\theta_{k_1}, \theta_{k_2}, \theta_{k_3}\}$$

How to pre-train? CLIP-Driven

SuPreM



Zero-shot / Adaptation Oriented (3D Data)

CLIP-Driven

Text branch
(generates text embedding for class k)

\mathbf{w}_k

Visual branch-encoder
(generates visual embedding for volume x)

\mathbf{f}

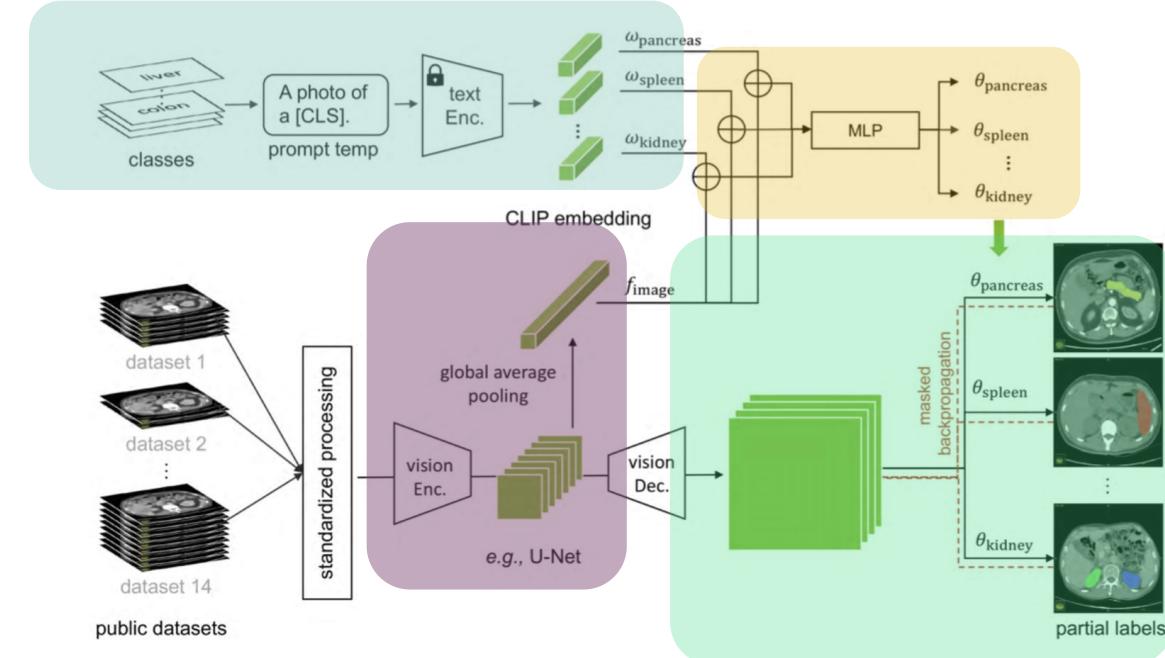
Text-based controller MLP
(generates class parameters)

$$\theta_k = \text{MLP}(\mathbf{w}_k \oplus \mathbf{f})$$
$$\theta_k = \{\theta_{k_1}, \theta_{k_2}, \theta_{k_3}\}$$

Visual branch-decoder
(generates visual embedding for image x)

$$\mathbf{P}_k = \text{sigmoid}(((\mathbf{F} * \theta_{k_1}) * \theta_{k_2}) * \theta_{k_3})$$

SuPreM



Zero-shot / Adaptation Oriented (3D Data)

CLIP-Driven

Text branch
(generates text embedding for class k)

$$\mathbf{w}_k$$

Visual branch-encoder
(generates visual embedding for volume x)

$$\mathbf{f}$$

Text-based controller MLP
(generates class parameters)

$$\begin{aligned}\theta_k &= \text{MLP}(\mathbf{w}_k \oplus \mathbf{f}) \\ \theta_k &= \{\theta_{k_1}, \theta_{k_2}, \theta_{k_3}\}\end{aligned}$$

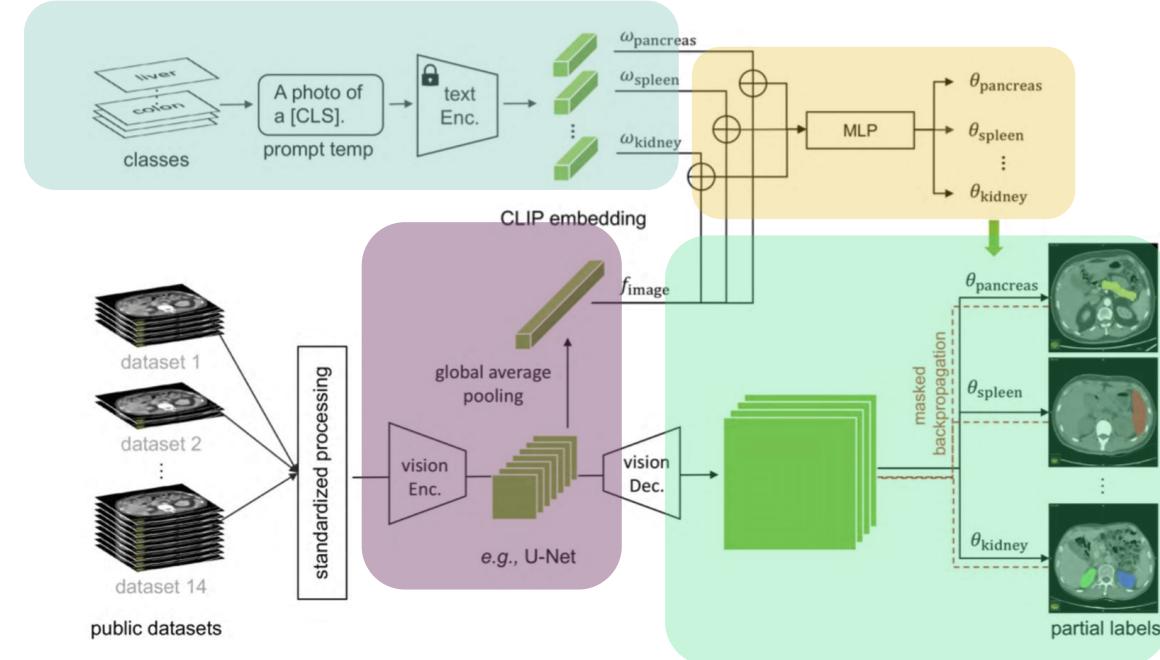
Visual branch-decoder
(generates visual embedding for image x)

$$\mathbf{P}_k = \text{sigmoid}(((\mathbf{F} * \theta_{k_1}) * \theta_{k_2}) * \theta_{k_3})$$

Training loss

$$\mathcal{L} = \sum_{k=1}^K \mathbf{1}_{\{k \in y\}} \cdot \text{BCE}_k$$

SuPreM



Zero-shot / Adaptation Oriented (3D Data)

CLIP-Driven

Text branch
(generates text embedding for class k)

\mathbf{w}_k

Visual branch-encoder
(generates visual embedding for volume x)

\mathbf{f}

Text-based controller MLP
(generates class parameters)

$$\theta_k = \text{MLP}(\mathbf{w}_k \oplus \mathbf{f})$$
$$\theta_k = \{\theta_{k_1}, \theta_{k_2}, \theta_{k_3}\}$$

Visual branch-decoder
(generates visual embedding for image x)

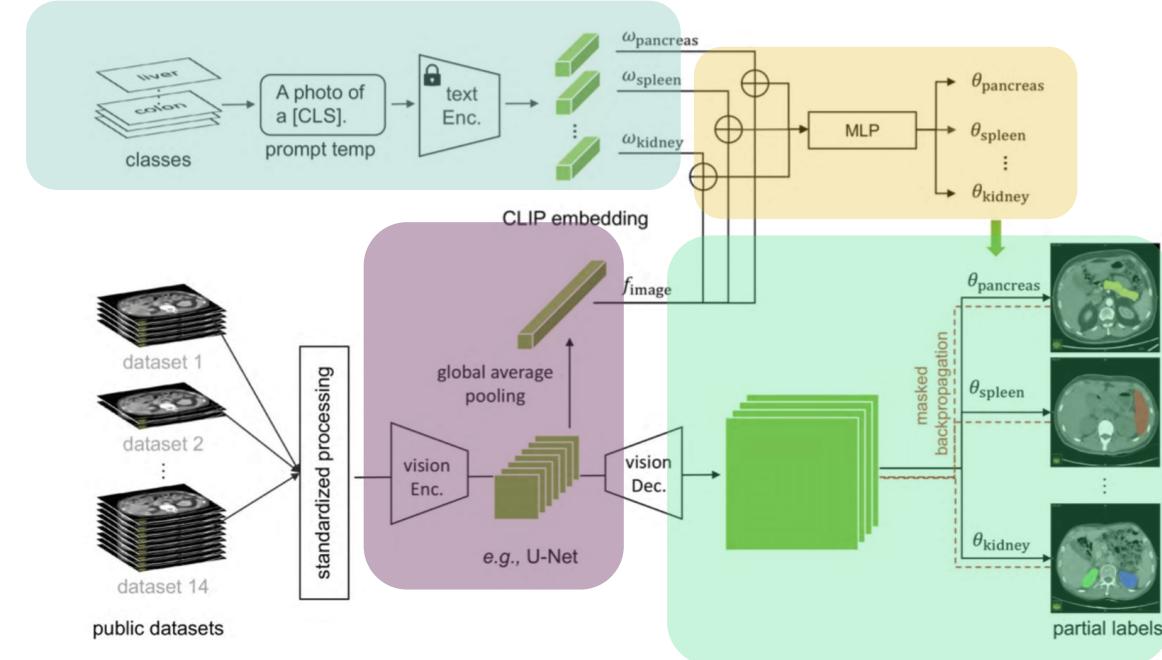
$$\mathbf{P}_k = \text{sigmoid}(((\mathbf{F} * \theta_{k_1}) * \theta_{k_2}) * \theta_{k_3})$$

Training loss

$$\mathcal{L} = \sum_{k=1}^K \mathbf{1}_{\{k \in y\}} \cdot \text{BCE}_k$$

How to pre-train? CLIP-Driven

SuPreM



→ How can the text part contribute if using a generalist model?

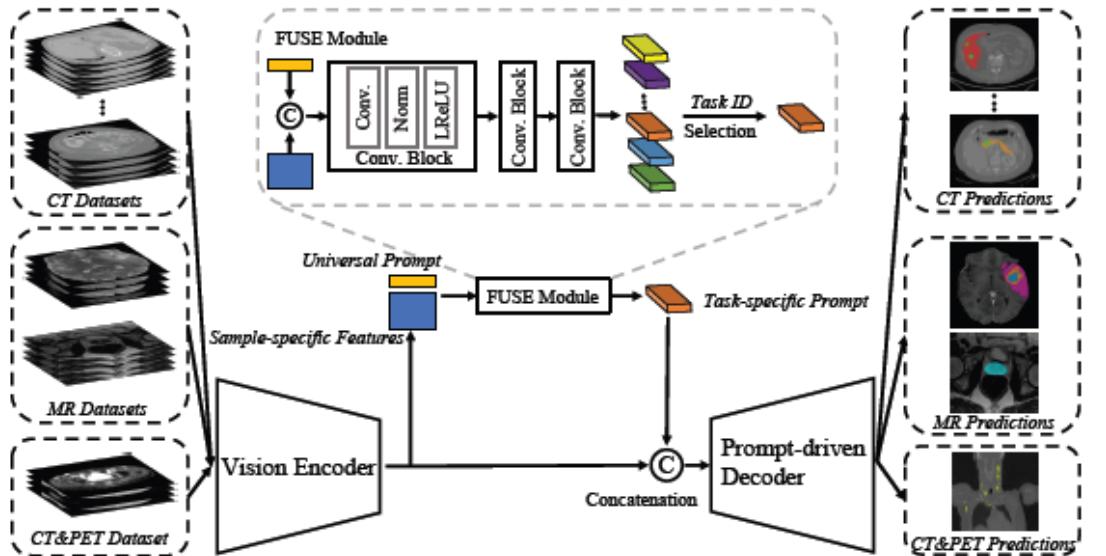
Zero-shot / Adaptation Oriented (3D Data)

UniSeg

How to pre-train? Prompt-Driven

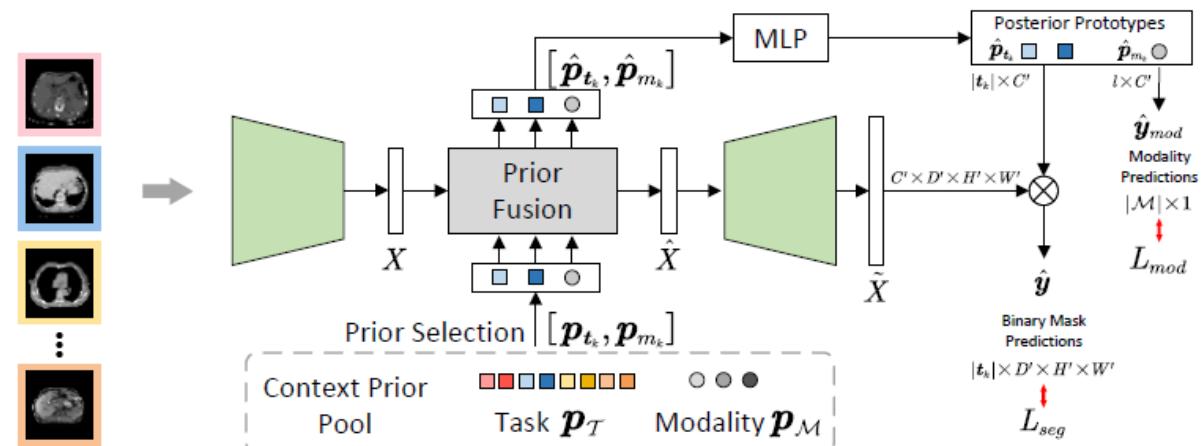
Hermes

Main idea



Ye et al. UniSeg: A Prompt-driven Universal Segmentation Model as well as a Strong Representation Learner. MICCAI'23.

- **Objective:** condition the segmentation to high level features related to **tasks/domains**.
 - **Prompt selection** is a learnable operations to operate during **inference**.



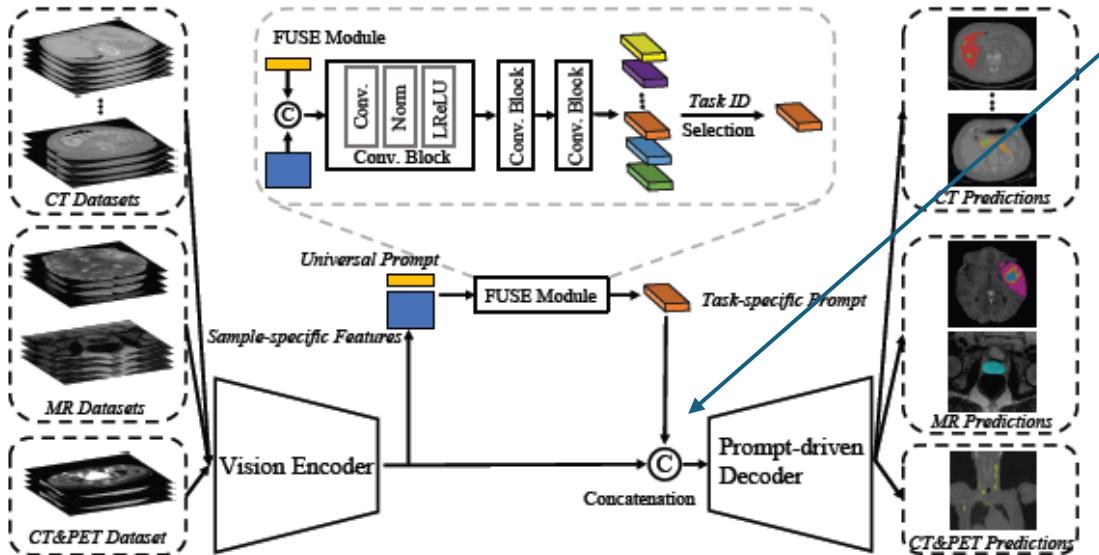
Gao et al. Training Like a Medical Resident: Context-Prior Learning Toward Universal Medical Image Segmentation. CVPR'24.

Zero-shot / Adaptation Oriented (3D Data)

UniSeg

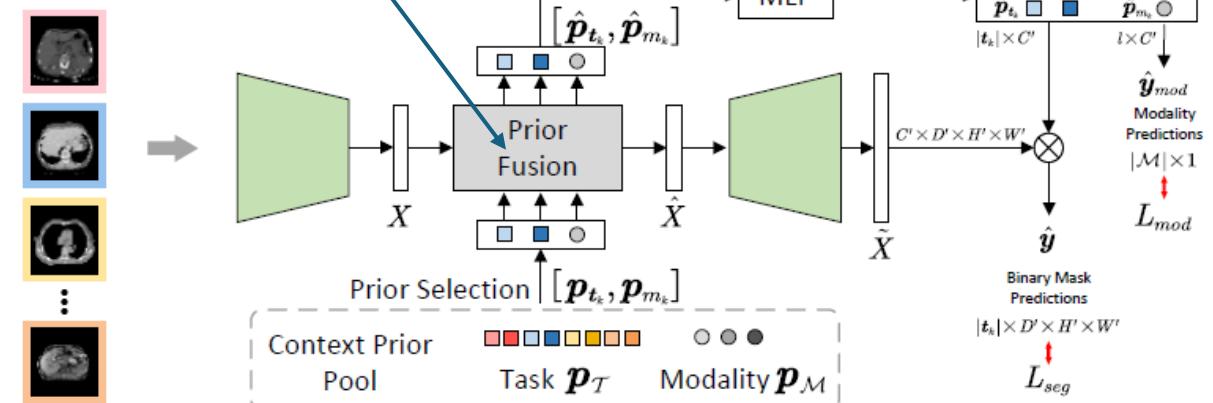
Hermes

Main idea



Ye et al. UniSeg: A Prompt-driven Universal Segmentation Model as well as A Strong Representation Learner. MICCAI'23.

Conditioning on
decoder path



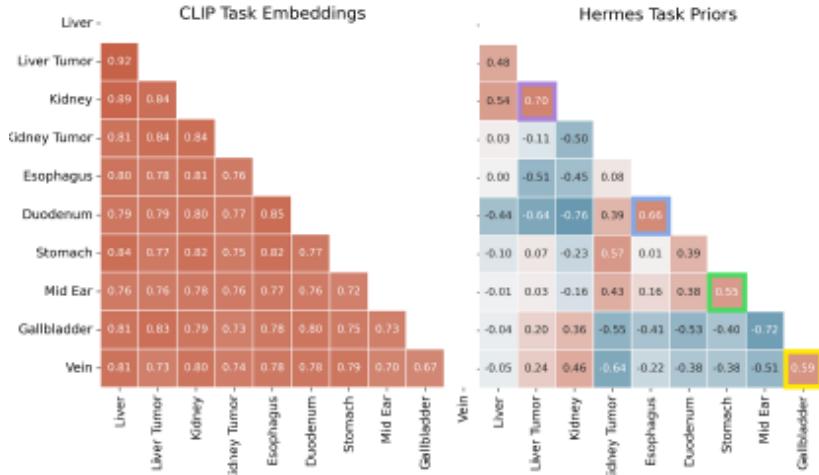
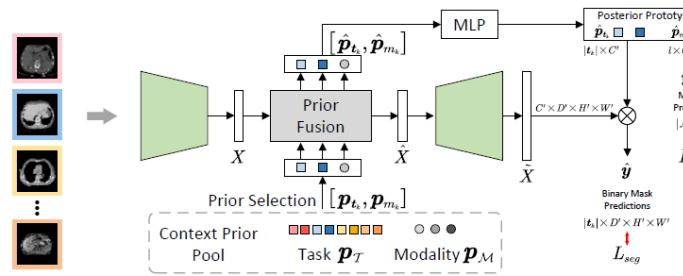
Gao et al. Training Like a Medical Resident: Context-Prior Learning Toward Universal Medical Image Segmentation. CVPR'24.

Zero-shot / Adaptation Oriented (3D Data)

UniSeg

Hermes

How to pre-train? Prompt-Driven



Prompt Similarity
among tasks

Setting	Model	1%		10%		50%		100%	
		Pan	Tumor	Pan	Tumor	Pan	Tumor	Pan	Tumor
Scratch	ResUNet	44.60	7.67	74.47	23.90	78.89	44.52	80.45	51.06
	ResUNet (AMOS CT)	56.08	8.31	77.15	25.53	80.53	46.16	81.23	52.21
	ResUNet (KiTS)	52.68	9.28	75.11	27.33	79.07	45.72	79.23	50.64
	DeSD [60] (10,594 CT)	67.82	13.89	78.11	35.82	80.95	50.23	81.97	59.11
Transfer	DoDNet [63]	66.62	11.97	76.83	31.92	80.82	47.79	81.41	53.62
	CLIP-Driven [44]	67.95	12.12	77.49	32.37	80.92	48.92	81.45	54.71
	UniSeg [61]	69.05	12.35	77.33	33.87	80.93	49.63	81.96	55.58
	Hermes-R	72.71	16.73	79.12	44.31	81.14	55.31	82.73	61.41

Zero-shot / Adaptation Oriented (3D Data)

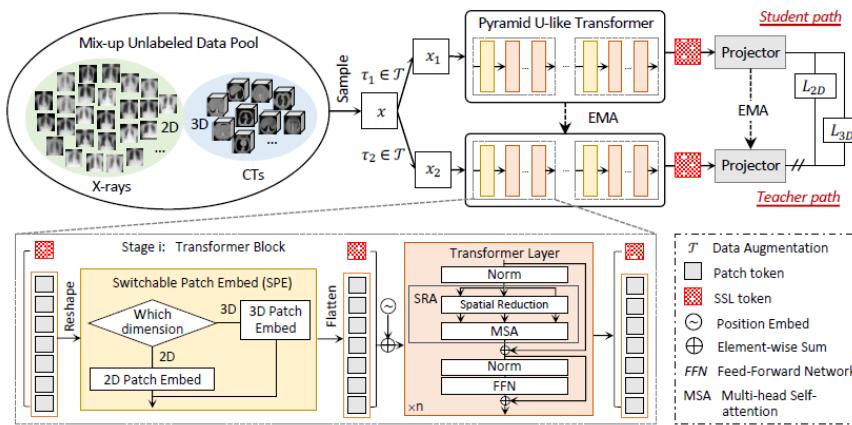
How to pretrain? Self-supervised pre-training

→ Producing quality annotations in volumetric scans is expensive and laborious.

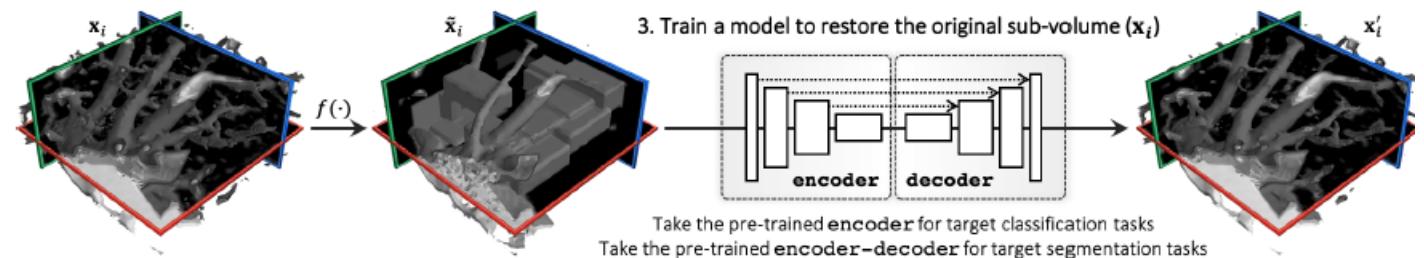
→ Large amounts of unlabeled data are available.

(current self-supervised models are pre-trained with more than 5000 CT scans)

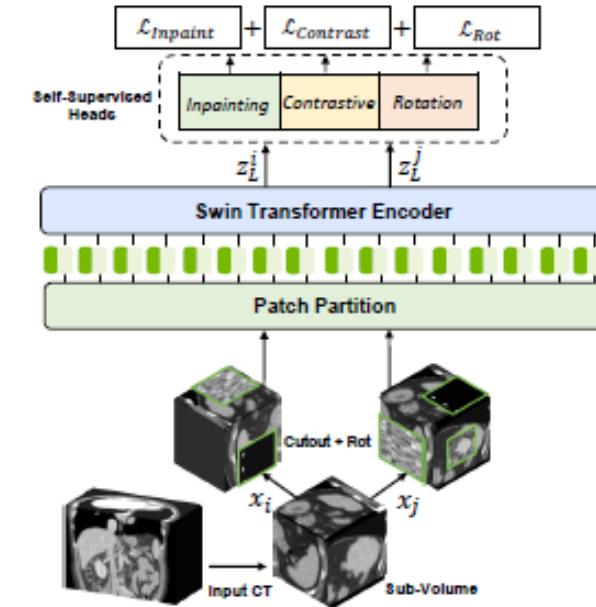
→ Different pretext tasks.



Xie et al. UniMiSS: Universal Medical Self-Supervised Learning via Breaking Dimensionality Barrier. ECCV'22.



Zhou et al. Model Genesis. Media'21.



Tang et al. Self-Supervised Pre-Training of Swin Transformers for 3D Medical Image Analysis. CVPR'22.

Zero-shot / Adaptation Oriented (3D Data)

SuPreM

Benefits of foundation models?

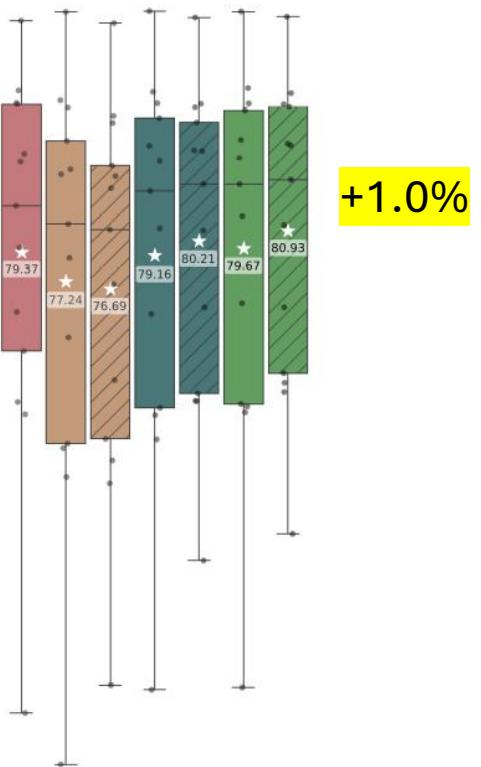
MultiTalent

- Transferability via **full fine-tuning** of the pre-trained model.
- Access to **hundreds of labeled volumes** for adaptation.

	name	backbone	params	pre-trained data	performance [†]
self-supervised	Models Genesis (Zhou et al., 2019)	U-Net	19.08M	623 CT volumes	90.1
	UniMiSS (Xie et al., 2022)	nnUNet	61.79M	5,022 CT&MRI volumes	92.9
	NV*	SwinUNETR	62.19M	1,000 CT volumes	93.2
	NV*	SwinUNETR	62.19M	3,000 CT volumes	93.4
	NV (Tang et al., 2022)	SwinUNETR	62.19M	5,050 CT volumes	93.8
supervised	NV*	SwinUNETR	62.19M	5,050 CT volumes	94.2
	NV*	SwinUNETR	62.19M	9,262 CT volumes	94.3
	Med3D (Chen et al., 2019b)	Residual U-Net	85.75M	1,638 CT volumes	91.4
	DoDNet (Zhang et al., 2021)	U-Net	17.29M	920 CT volumes	93.8
	DoDNet*	U-Net	17.29M	920 CT volumes	94.4
supervised	Universal Model (Liu et al., 2023b)	U-Net	19.08M	2,100 CT volumes	-
	Universal Model (Liu et al., 2023b)	SwinUNETR	62.19M	2,100 CT volumes	94.1
	SuPreM*	U-Net	19.08M	2,100 CT volumes	95.4
supervised	SuPreM*	SwinUNETR	62.19M	2,100 CT volumes	94.6
	SuPreM*	SegResNet	470.13M	2,100 CT volumes	94.0

+0.8%

Ulrich et al. MultiTalent: A Multi-Dataset Approach to Medical Image Segmentation. MICCAI'23.



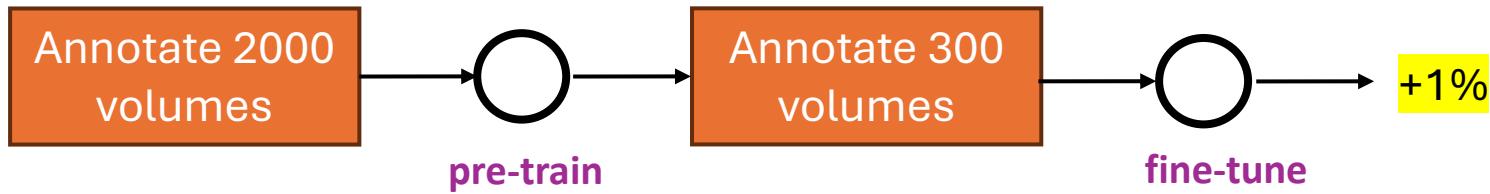
Zero-shot / Adaptation Oriented (3D Data)

SuPreM

Benefits of foundation models?

MultiTalent

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	SuPreM*	U-Net	19.08M	2,100 CT volumes	95.4
adaptation	SuPreM*	Swin UNETR	62.19M	2,100 CT volumes	94.6
	SuPreM*	SegResNet	470.13M	2,100 CT volumes	94.0

Zero-shot / Adaptation Oriented (3D Data)

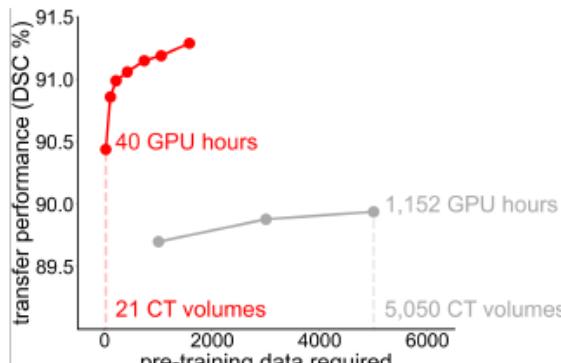
SuPreM

Benefits of foundation models

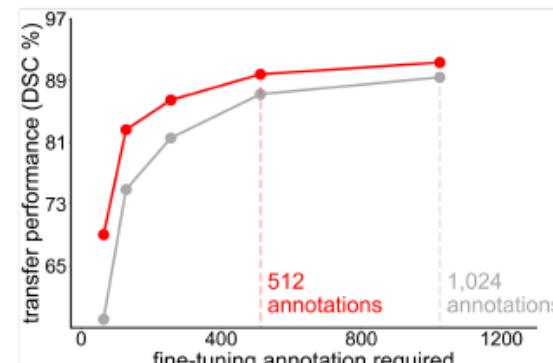
- SuPreM models are pre-trained on a curated dataset with 25 fully-annotated structures.

[Li et al. AdbomenAtlas: A Large Scale Detailed Annotated and Multi Center Dataset for Efficient Transfer Learning and Open Algorithmic Benchmarking. Media'24.](#)

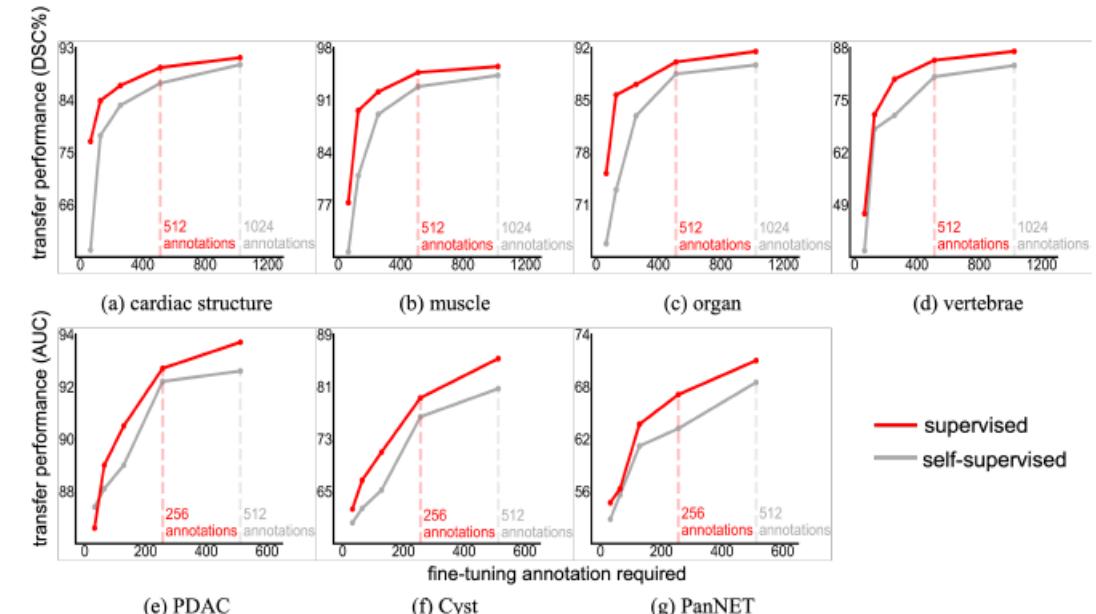
- Supervised pre-training is orders of magnitude more data-efficient than self-supervision.
- This holds even when transferring to unseen structures.



(a) data & computational efficiency
in *pre-training*



(b) annotation & learning efficiency
in *fine-tuning*

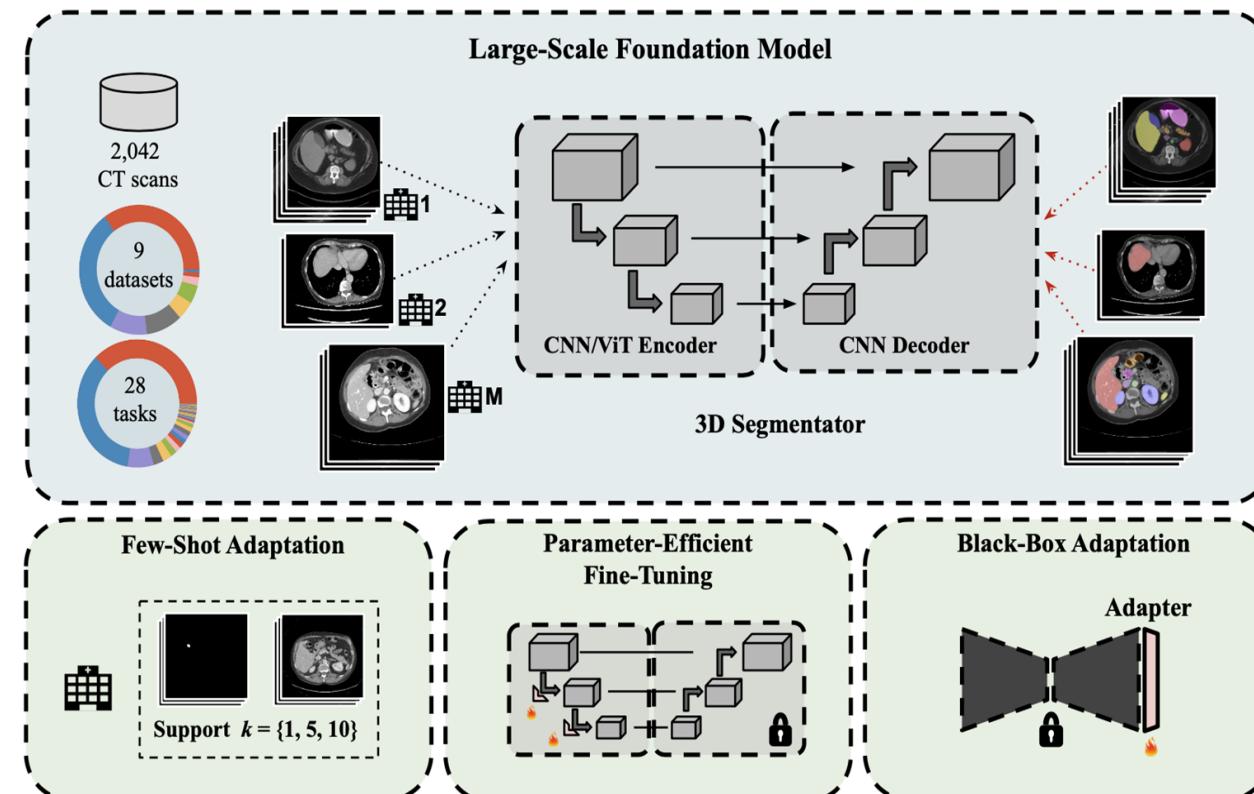


Zero-shot / Adaptation Oriented (3D Data)

FSEFT

Few-Shot Efficient Fine-Tuning

Main idea (how to adapt a pre-trained large-scale model efficiently)

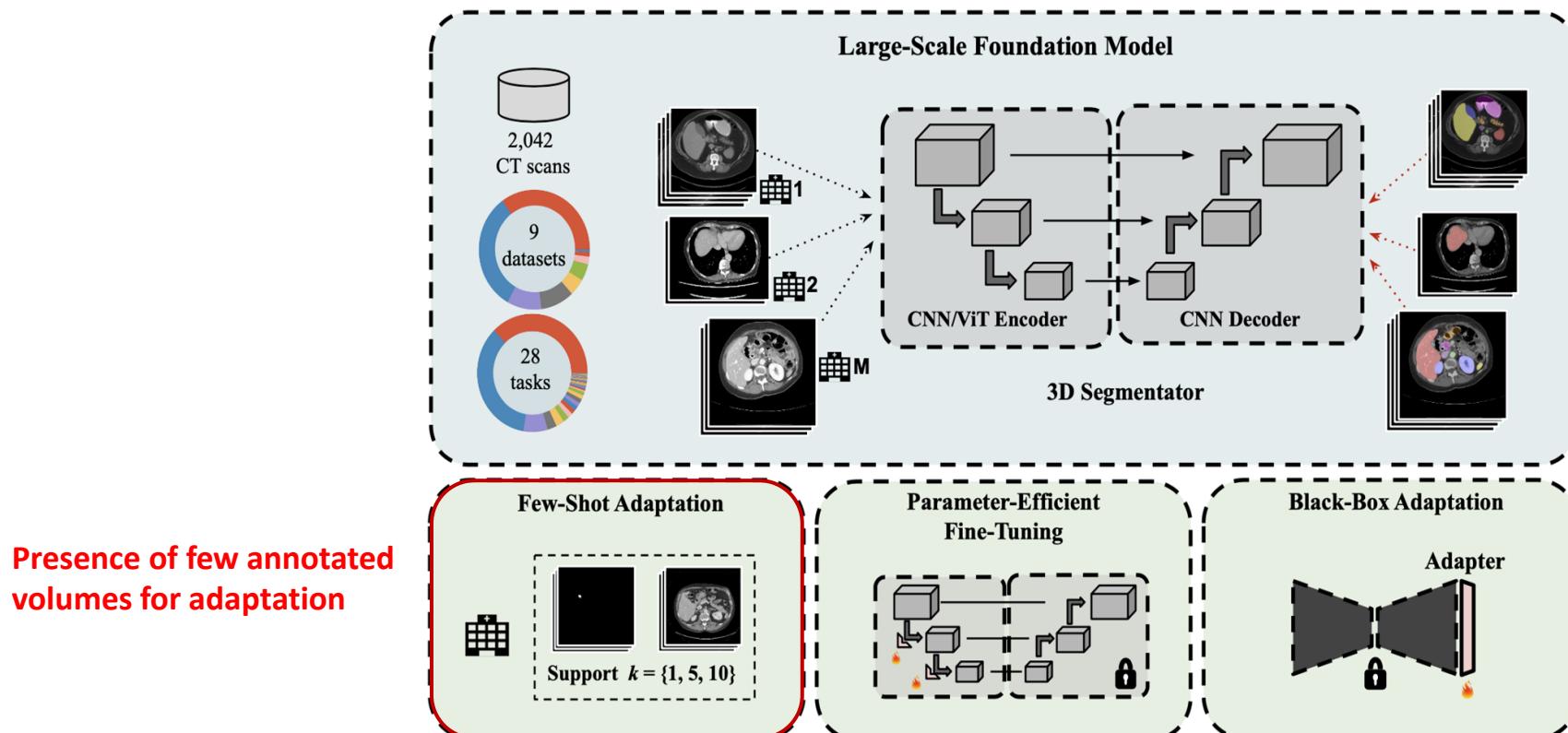


Zero-shot / Adaptation Oriented (3D Data)

FSEFT

Few-Shot Efficient Fine-Tuning

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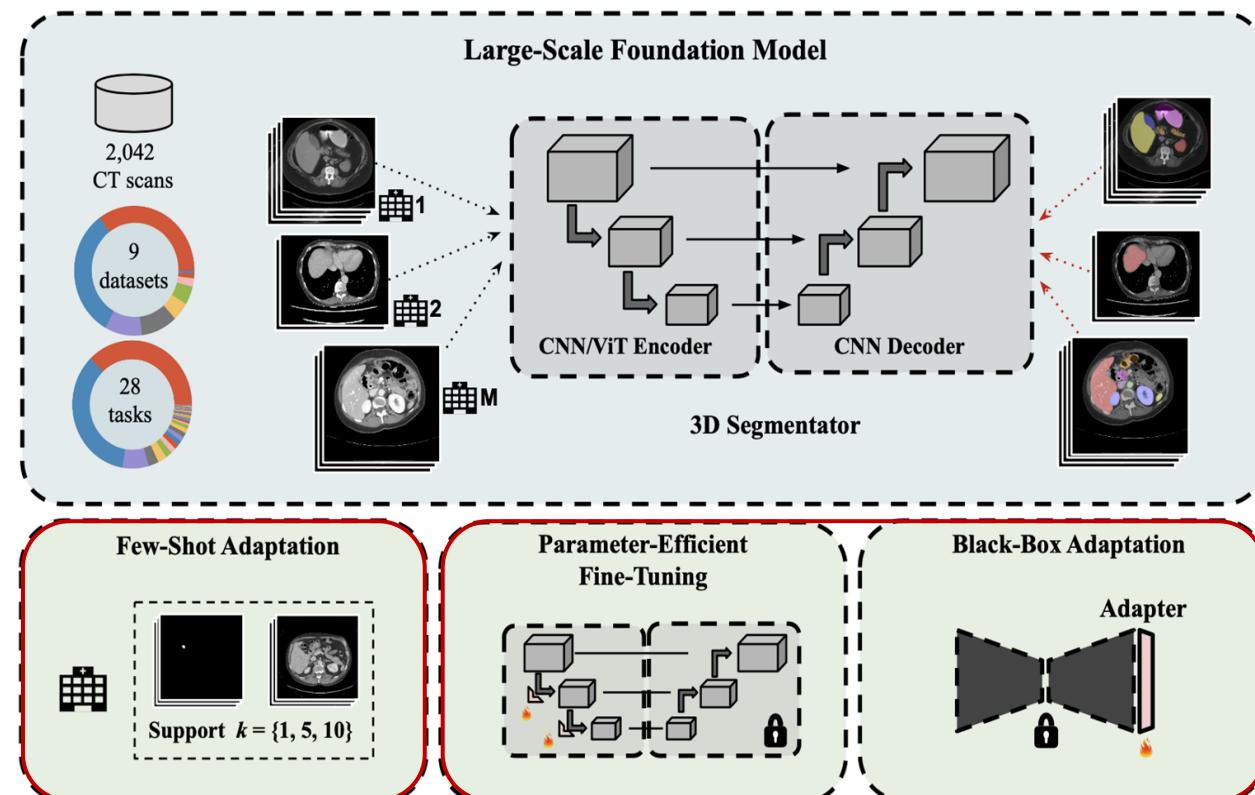


Zero-shot / Adaptation Oriented (3D Data)

FSEFT

Few-Shot Efficient Fine-Tuning

Main idea (how to adapt a pre-trained large-scale model efficiently)



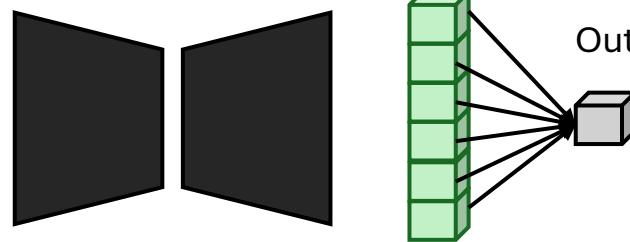
Zero-shot / Adaptation Oriented (3D Data)

FSEFT

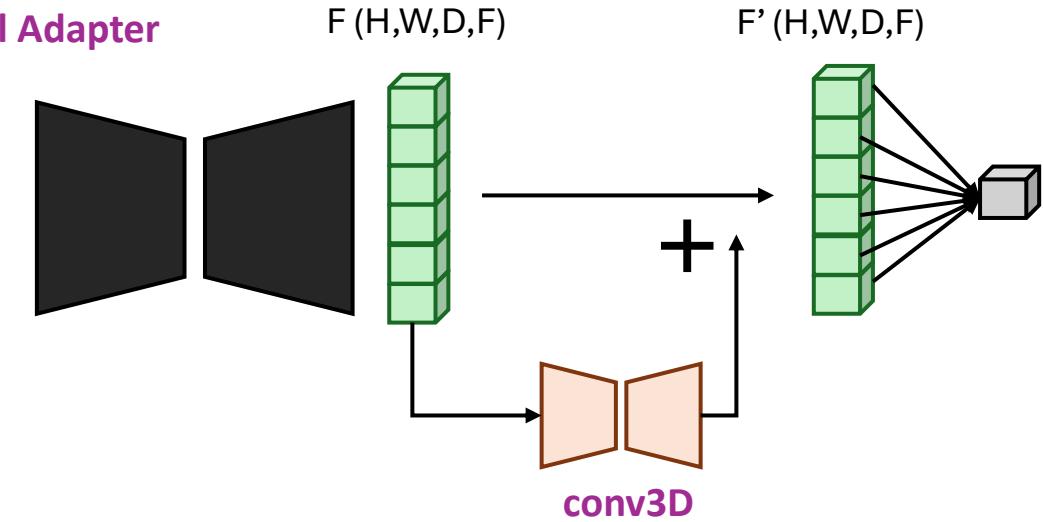
Few-Shot Efficient Fine-Tuning

Black-box Adapters

Linear Probing



Spatial Adapter



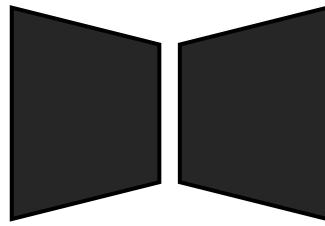
Zero-shot / Adaptation Oriented (3D Data)

FSEFT

Few-Shot Efficient Fine-Tuning

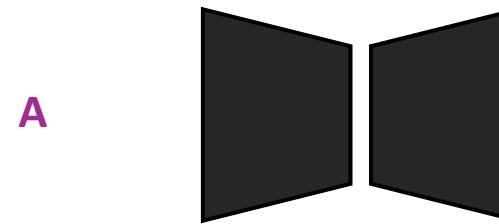
Black-box Adapters

Linear Probing



$F(H,W,D,F)$

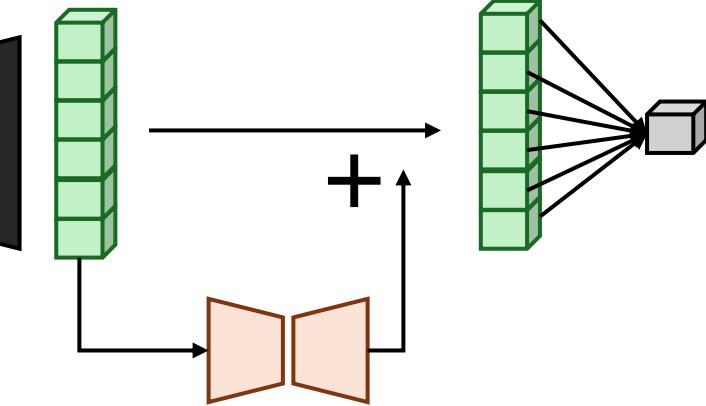
Spatial Adapter



A

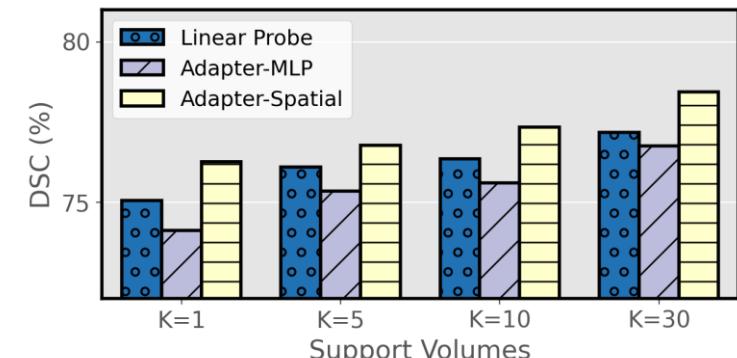
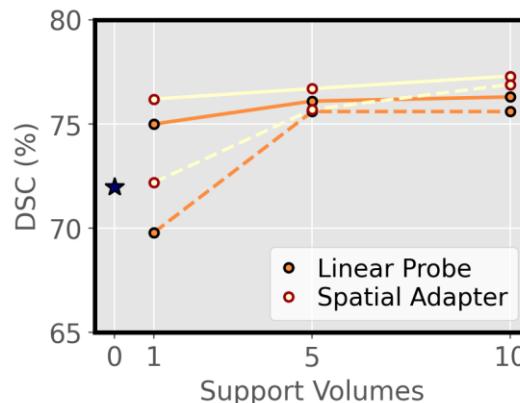
$F(H,W,D,F)$

$F'(H,W,D,F)$



conv3D

MLP vs. Spatial

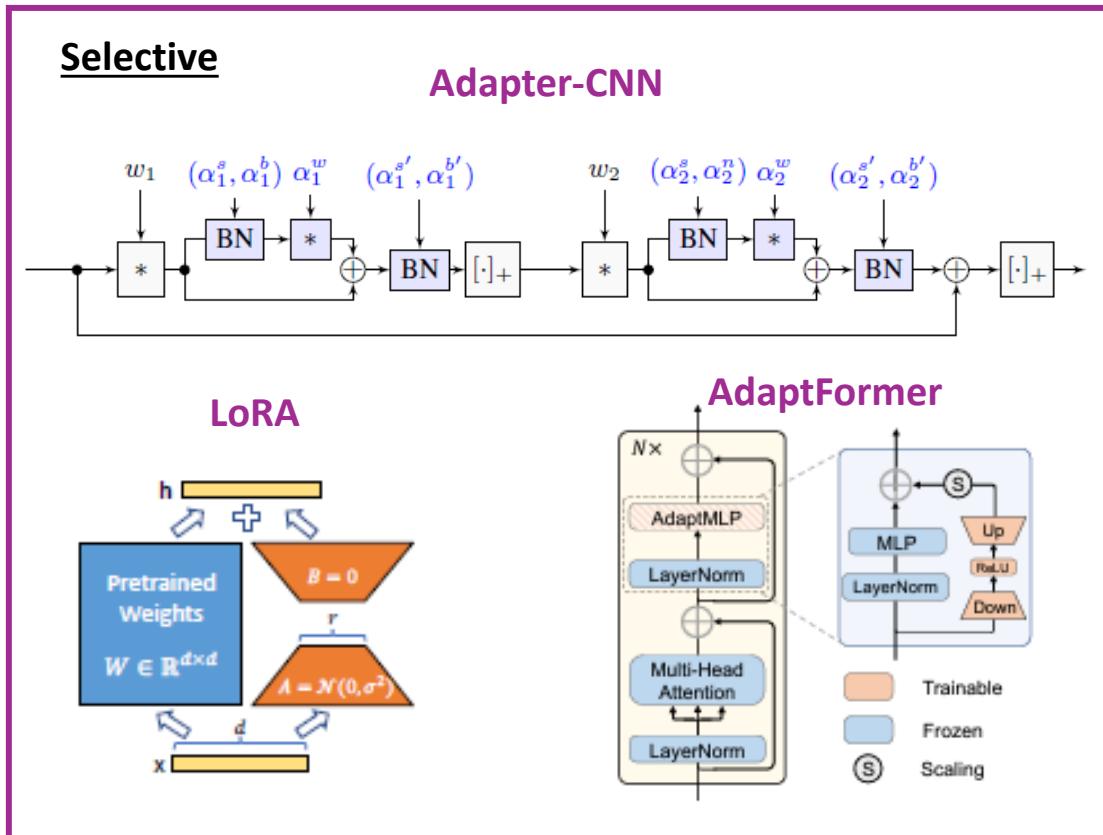


Zero-shot / Adaptation Oriented (3D Data)

FSEFT

Few-Shot Efficient Fine-Tuning

Parameter-Efficient Fine-Tuning

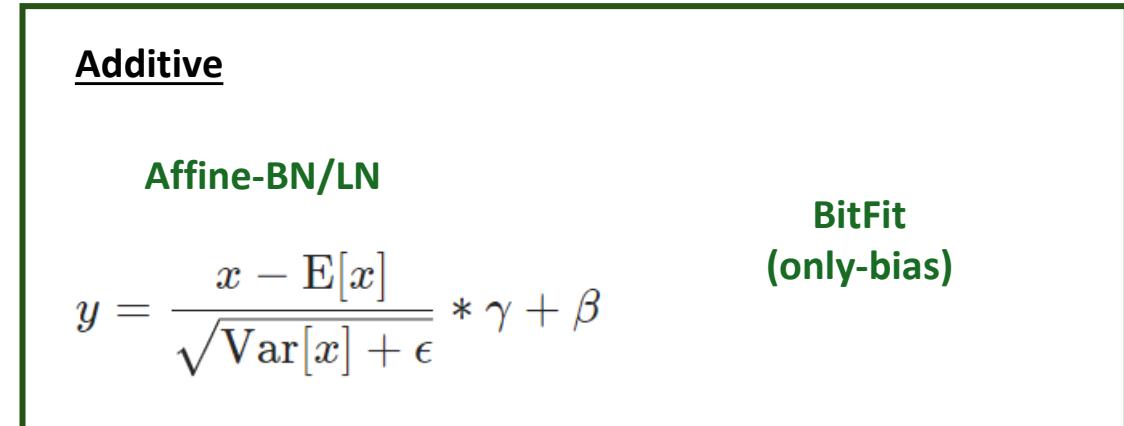
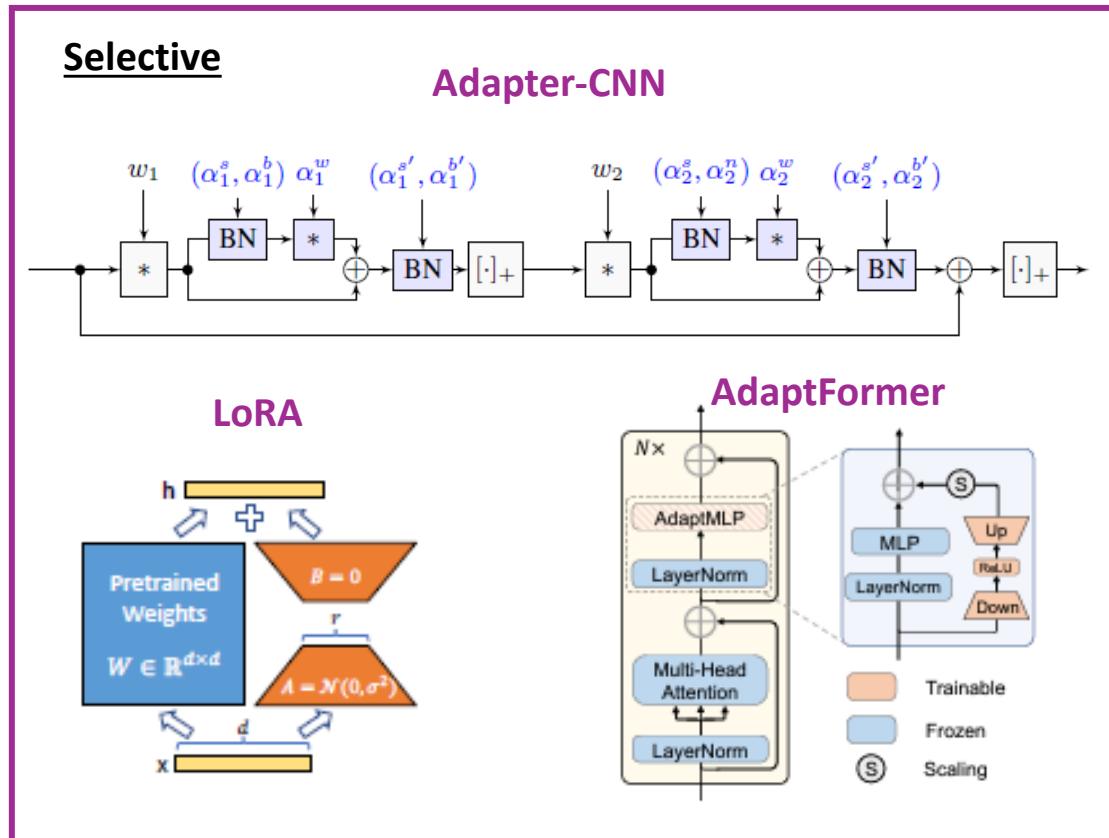


Zero-shot / Adaptation Oriented (3D Data)

FSEFT

Few-Shot Efficient Fine-Tuning

Parameter-Efficient Fine-Tuning

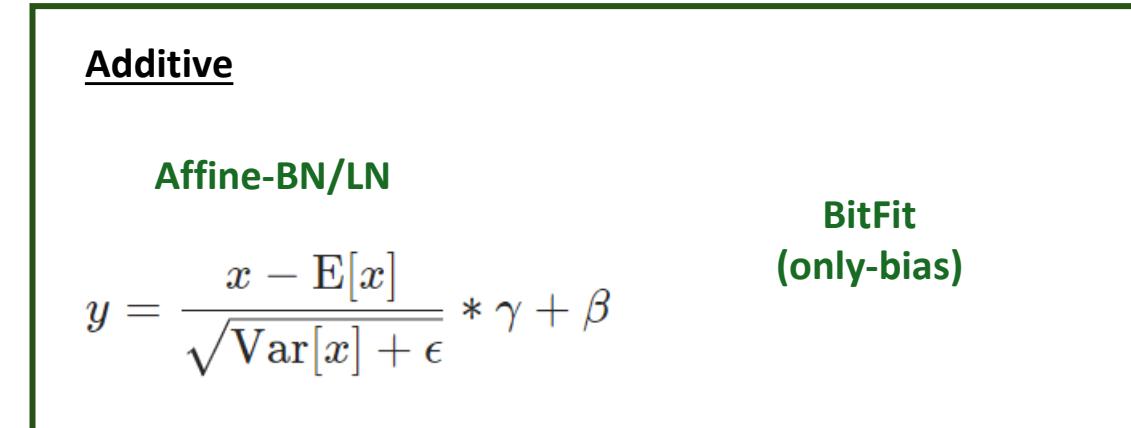
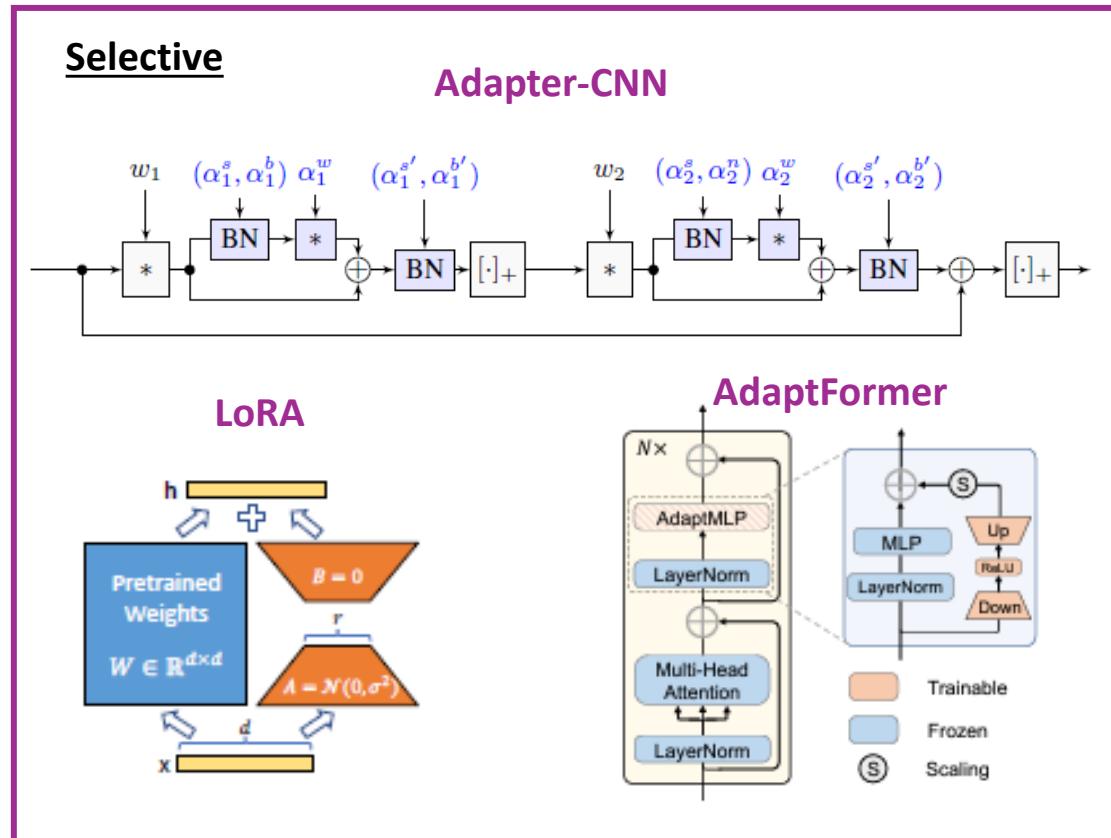


Zero-shot / Adaptation Oriented (3D Data)

FSEFT

Few-Shot Efficient Fine-Tuning

Parameter-Efficient Fine-Tuning



**What to do with the Decoder?
(millions of parameters)**

→ **Base** categories: **frozen**.

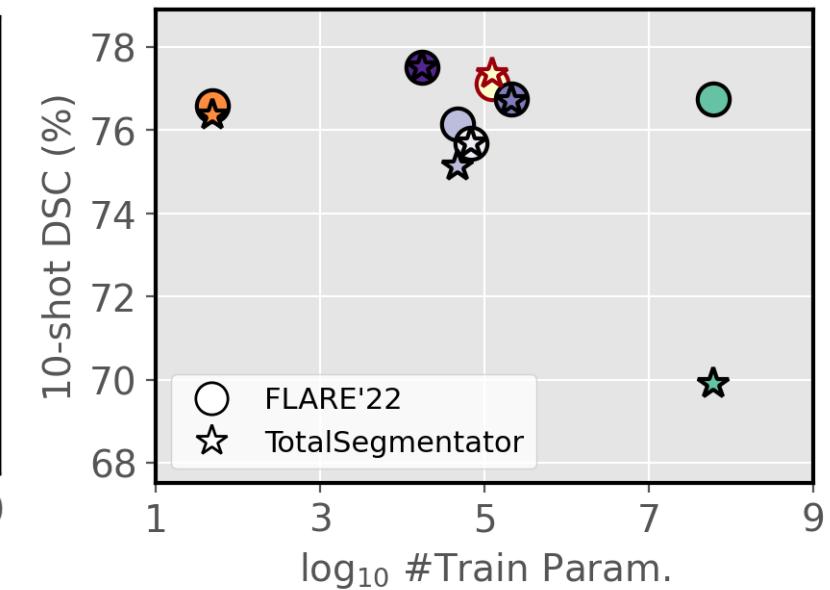
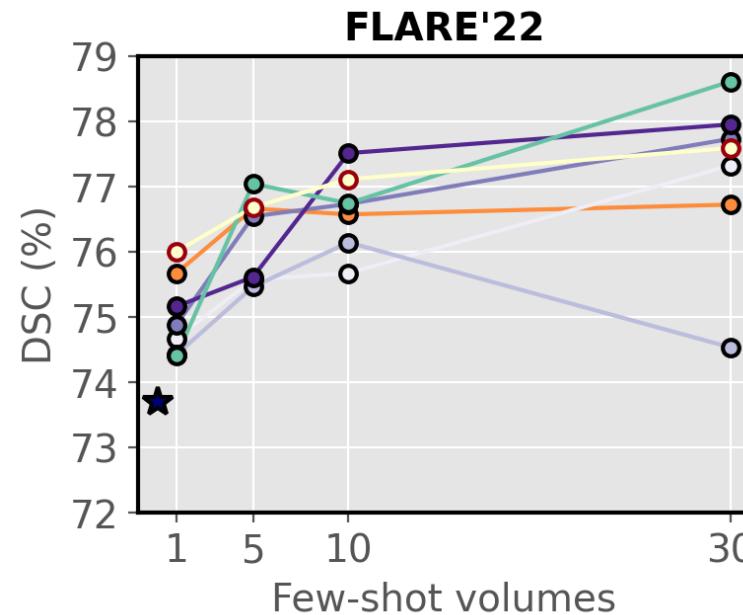
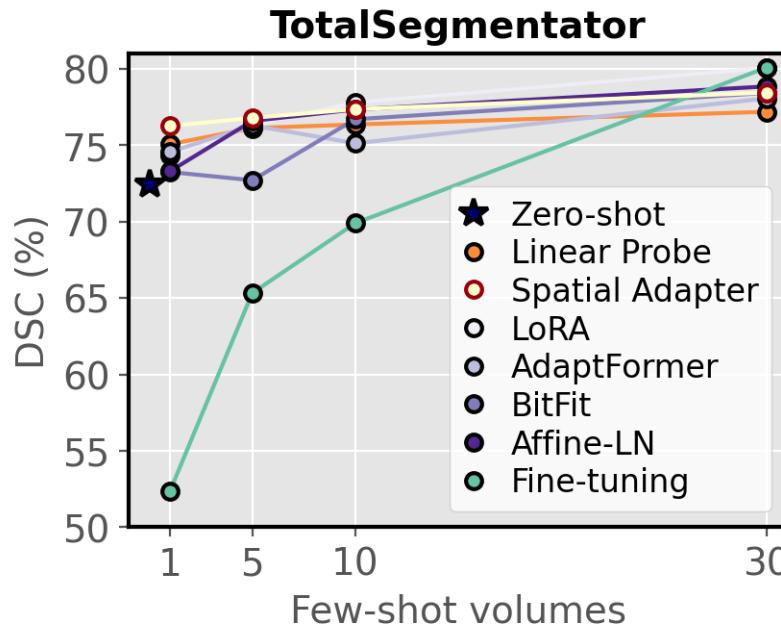
→ **New** categories: **fine-tuned**.

Zero-shot / Adaptation Oriented (3D Data)

FSEFT

Few-Shot Efficient Fine-Tuning

Transferability to known tasks (domain shift)

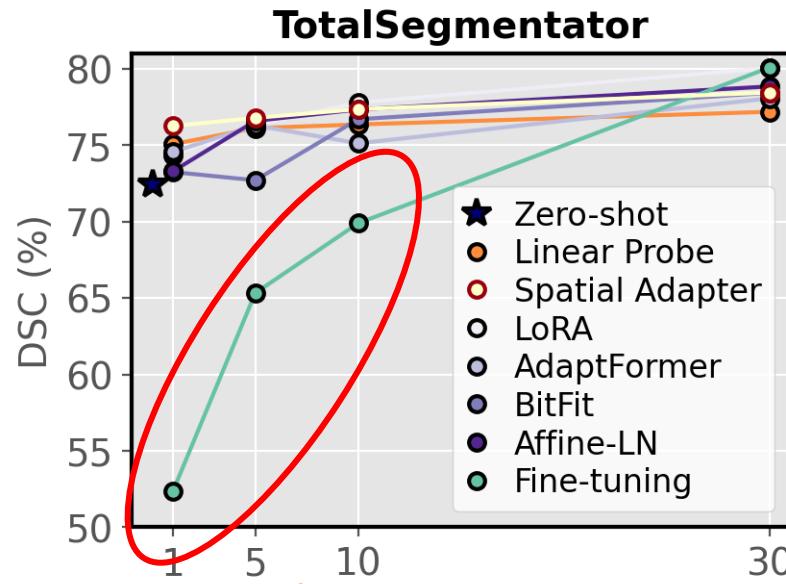


Zero-shot / Adaptation Oriented (3D Data)

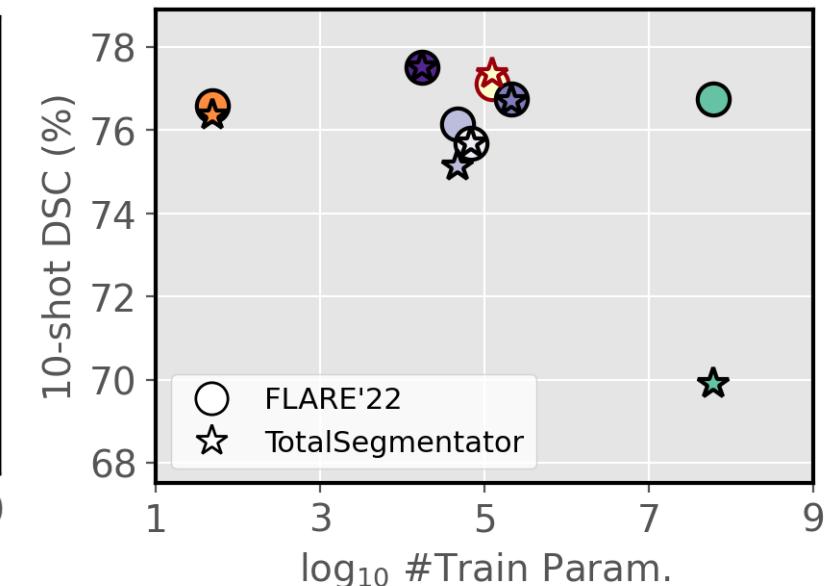
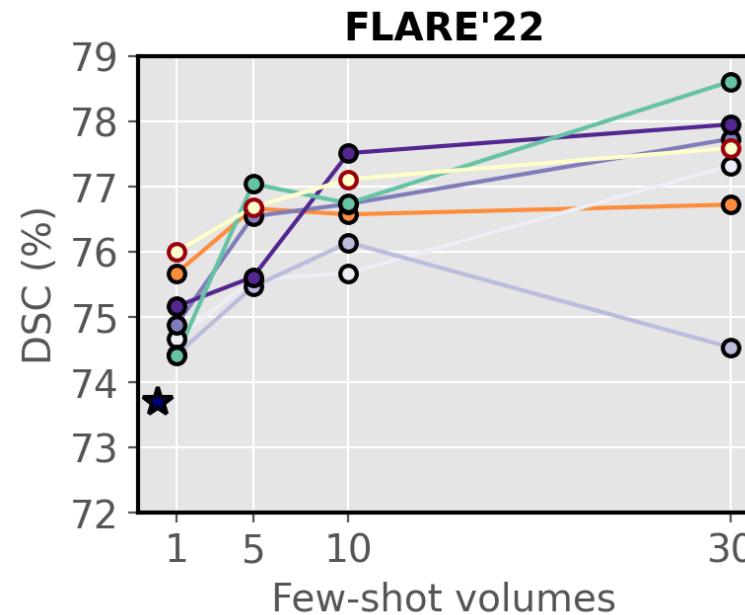
FSEFT

Few-Shot Efficient Fine-Tuning

Transferability to known tasks (domain shift)



Fine-tuning might distort the model

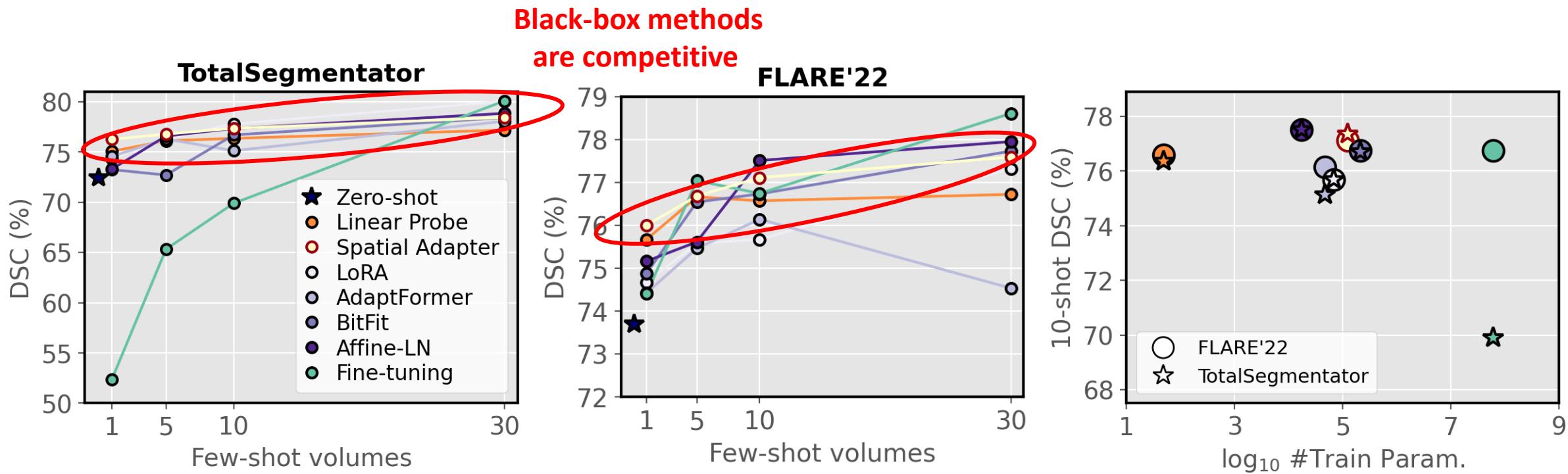


Zero-shot / Adaptation Oriented (3D Data)

FSEFT

Few-Shot Efficient Fine-Tuning

Transferability to known tasks (domain shift)

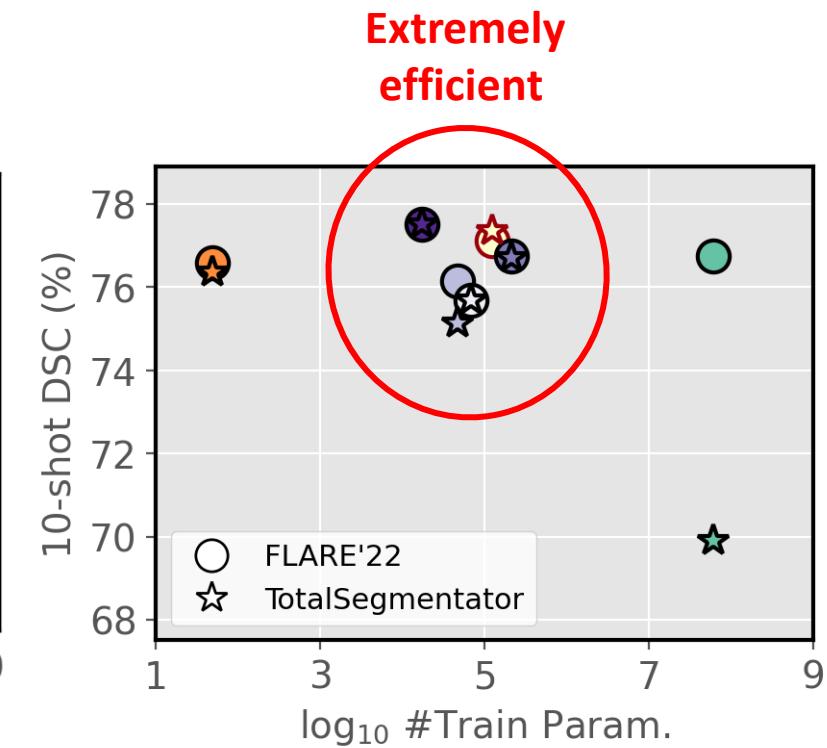
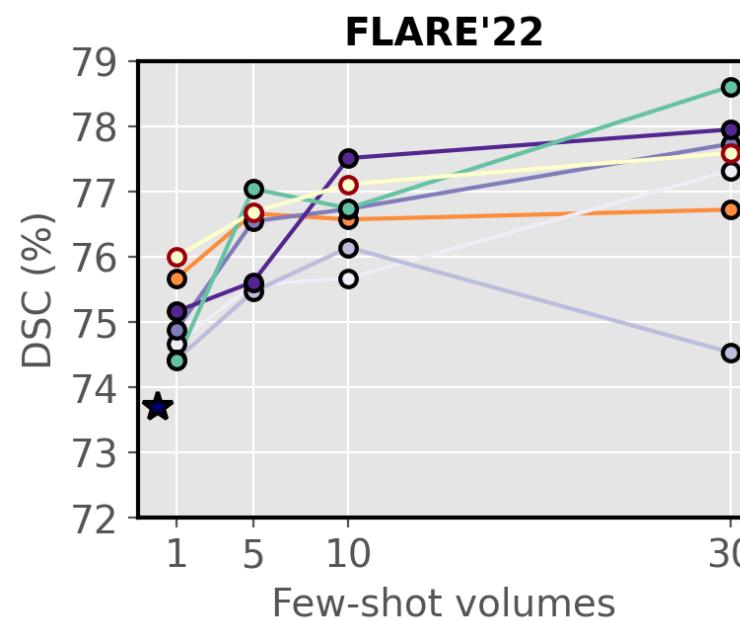
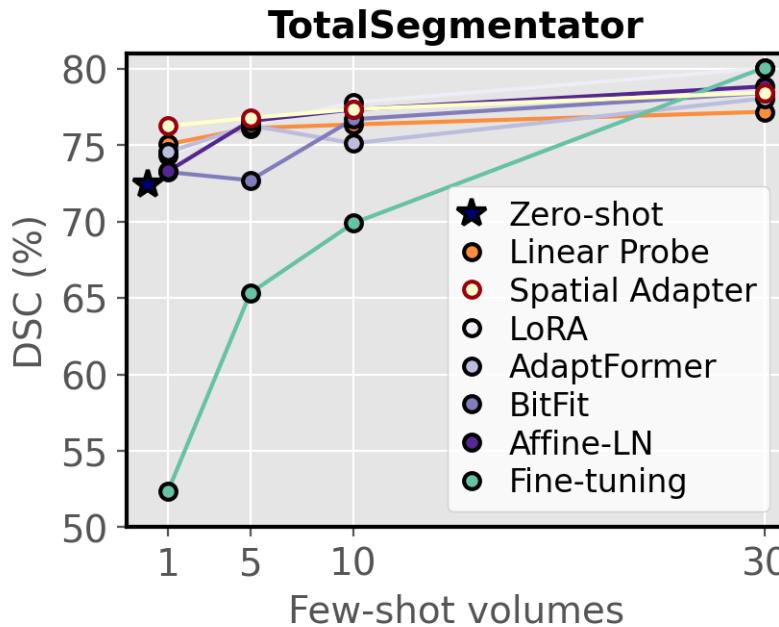


Zero-shot / Adaptation Oriented (3D Data)

FSEFT

Few-Shot Efficient Fine-Tuning

Transferability to known tasks (domain shift)



Zero-shot / Adaptation Oriented (3D Data)

FSEFT

Few-Shot Efficient Fine-Tuning

Transferability to known tasks (domain shift)

Setting	Method	Spl	IKid	Gall	Eso	Liv	Pan	Sto	Duo	Aor	Avg.
5-shot	PEFT CNN-Adapter (Rebuffi et al., 2018)	47.69	39.58	40.52	53.05	55.08	43.17	28.47	35.73	84.62	47.55
	Bias (Cai et al., 2020)	71.16	69.54	70.16	55.86	71.03	79.60	51.25	69.04	88.92	69.62
	Affine-BN (Frankle et al., 2021)	69.22	72.33	65.66	52.68	67.61	75.50	45.08	66.52	86.94	66.84
	BB Linear Probe	93.97	75.59	75.94	50.50	80.29	68.19	57.18	77.18	88.48	74.14
10-shot	PEFT CNN-Adapter (Rebuffi et al., 2018)	57.32	61.79	42.96	55.61	52.21	52.77	39.96	34.97	89.26	54.09
	Bias (Cai et al., 2020)	72.79	76.14	83.37	59.65	73.97	79.68	60.65	73.46	92.80	74.72
	Affine-BN (Frankle et al., 2021)	72.15	74.06	77.15	58.65	72.31	77.08	61.74	63.94	92.43	72.17
	BB Spatial Adapter	91.22	75.63	77.48	50.02	80.87	69.17	56.28	77.63	85.29	73.73

(a) 3D-UNet

Setting	Method	Spl	IKid	Gall	Eso	Liv	Pan	Sto	Duo	Aor	Avg.
5-shot	PEFT BitFit (Ben-Zaken et al., 2021)	88.76	85.91	79.42	50.22	92.17	73.64	62.81	69.30	90.82	77.01
	LoRA (Hu et al., 2022)	61.31	46.52	52.50	46.43	80.50	66.86	38.66	54.15	73.33	57.81
	AdaptFormer (Chen et al., 2022a)	87.57	86.05	60.17	51.79	90.11	76.73	68.29	74.49	93.12	76.48
	BB Affine-LN (Basu et al., 2024)	88.14	83.81	76.10	50.04	91.89	75.46	64.41	71.91	90.91	76.96
10-shot	PEFT Linear Probe	94.62	91.86	82.98	49.29	93.54	78.86	72.43	77.30	88.77	81.07
	Spatial Adapter	95.34	88.13	85.08	55.56	94.27	78.84	75.33	78.17	87.40	82.01
	PEFT BitFit (Ben-Zaken et al., 2021)	95.16	86.54	84.86	56.93	93.58	72.03	69.26	75.47	90.44	80.47
	LoRA (Hu et al., 2022)	63.97	54.53	59.25	55.33	84.03	77.72	58.72	73.89	80.59	67.56

(b) Swin-UNETR

Black-box methods hold their performance when directly applied to SuPreM models

Zero-shot / Adaptation Oriented (3D Data)

FSEFT

Few-Shot Efficient Fine-Tuning

Transferability to novel tasks (new organs)

Setting	Method	Lung*	Heart†	Gluteus‡	Avg.
FULL	Fine-tuning (Tang et al., 2022)	19.59	53.14	55.37	42.70
	Fine-tuning (<i>Ours</i>)	31.01	60.79	65.35	52.38
	BitFit (Ben-Zaken et al., 2021)	14.79	48.90	39.43	34.28
PEFT	LoRA (Hu et al., 2022)	13.80	50.55	46.36	38.49
	AdaptFormer (Chen et al., 2022a)	18.82	53.35	48.61	40.26
	Affine-LN (Basu et al., 2024)	16.92	58.38	46.07	40.46
	Decoder fine-tuning	25.98	65.69	64.23	51.97
	+BitFit (Ben-Zaken et al., 2021)	<u>26.17</u>	65.78	64.34	52.10
	+LoRA (Hu et al., 2022)	26.16	76.12	69.89	57.39
	+AdaptFormer (Chen et al., 2022a)	23.84	72.32	69.79	55.32
BB	+Affine-LN (Basu et al., 2024)	<u>26.09</u>	65.91	<u>64.53</u>	<u>52.18</u>
	Linear Probe	9.35	9.19	7.52	8.68
	Spatial Adapter	10.08	14.66	12.75	12.50

* Avg. of five: upper/lower lobe left, upper/lower lobe right, middle lobe.

† Avg. of five: myocardium, atrium/ventricle left, atrium/ventricle right.

‡ Avg. of six: maximus left/right, medius left/right, minimus left/right.

Black-box methods are
NOT competitive
(Decoder Specialization)

Zero-shot / Adaptation Oriented (3D Data)

FSEFT

Few-Shot Efficient Fine-Tuning

Transferability to novel tasks (new organs)

Setting	Method	Lung*	Heart†	Gluteus‡	Avg.
FULL	Fine-tuning (Tang et al., 2022)	19.59	53.14	55.37	42.70
	Fine-tuning (<i>Ours</i>)	31.01	60.79	65.35	52.38
	BitFit (Ben-Zaken et al., 2021)	14.79	48.90	39.43	34.28
PEFT	LoRA (Hu et al., 2022)	13.80	50.55	46.36	38.49
	AdaptFormer (Chen et al., 2022a)	18.82	53.35	48.61	40.26
	Affine-LN (Basu et al., 2024)	16.92	58.38	46.07	40.46
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Additive PEFT
outperform Selective
methods

Zero-shot / Adaptation Oriented (3D Data)

FSEFT

Few-Shot Efficient Fine-Tuning

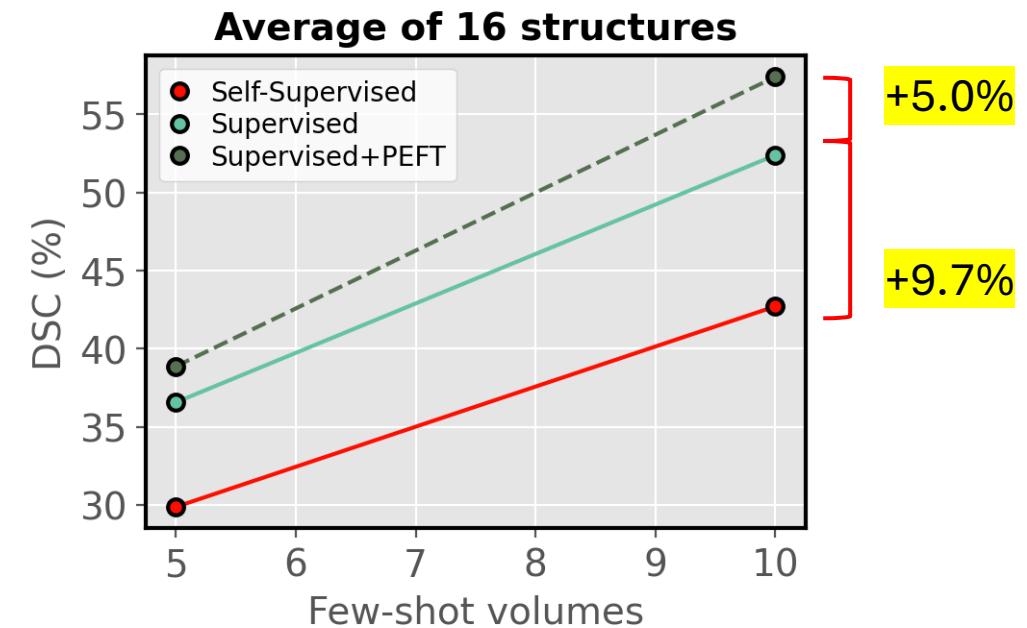
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Zero-shot / Adaptation Oriented (3D Data)

FSEFT

Few-Shot Efficient Fine-Tuning

Transferability to novel tasks (new organs)

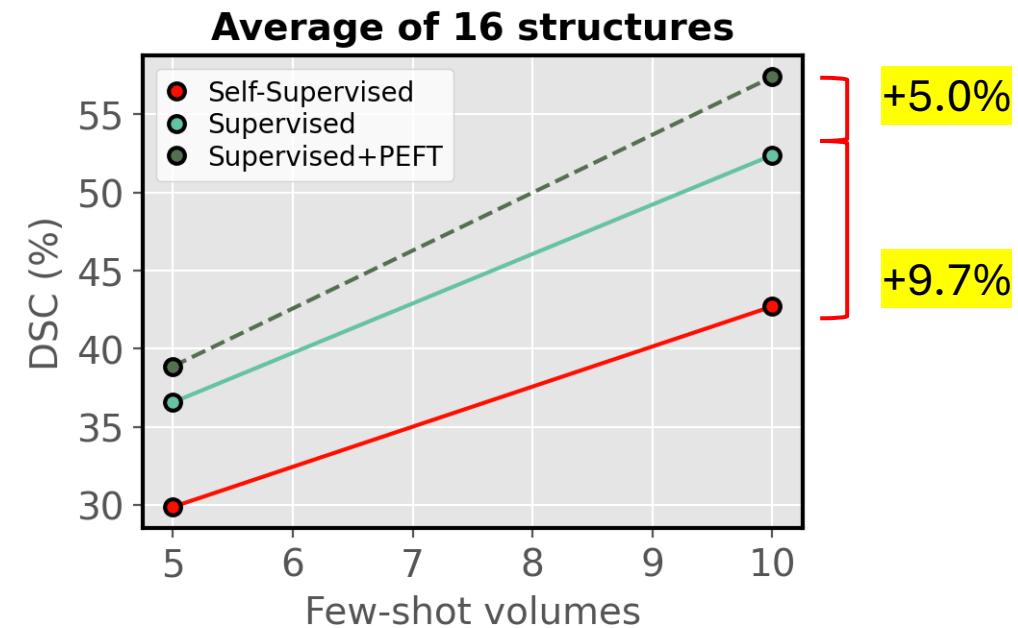
*not for all structures

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Zero-shot / Adaptation Oriented (3D Data)

Challenges and future

Transferability between modalities, e.g. CT to MRI.

Model selection: we need to facilitate the adaptation/fine-tuning stage to practitioners.

How to know a priori if using black-box Adapters, or PEFT.
Which PEFT method to use?

Improving PEFT for convolutional architectures.

Better benchmarks in generalist vs. specialized pre-training for 3D.

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