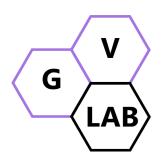
## Convolution

## Multi-channels input and multi-filters layer

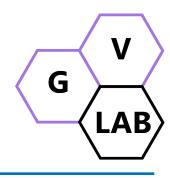
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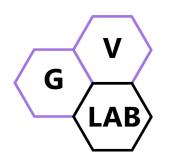
## **Contents**



- Multi-channels input
- Multi-filters layer

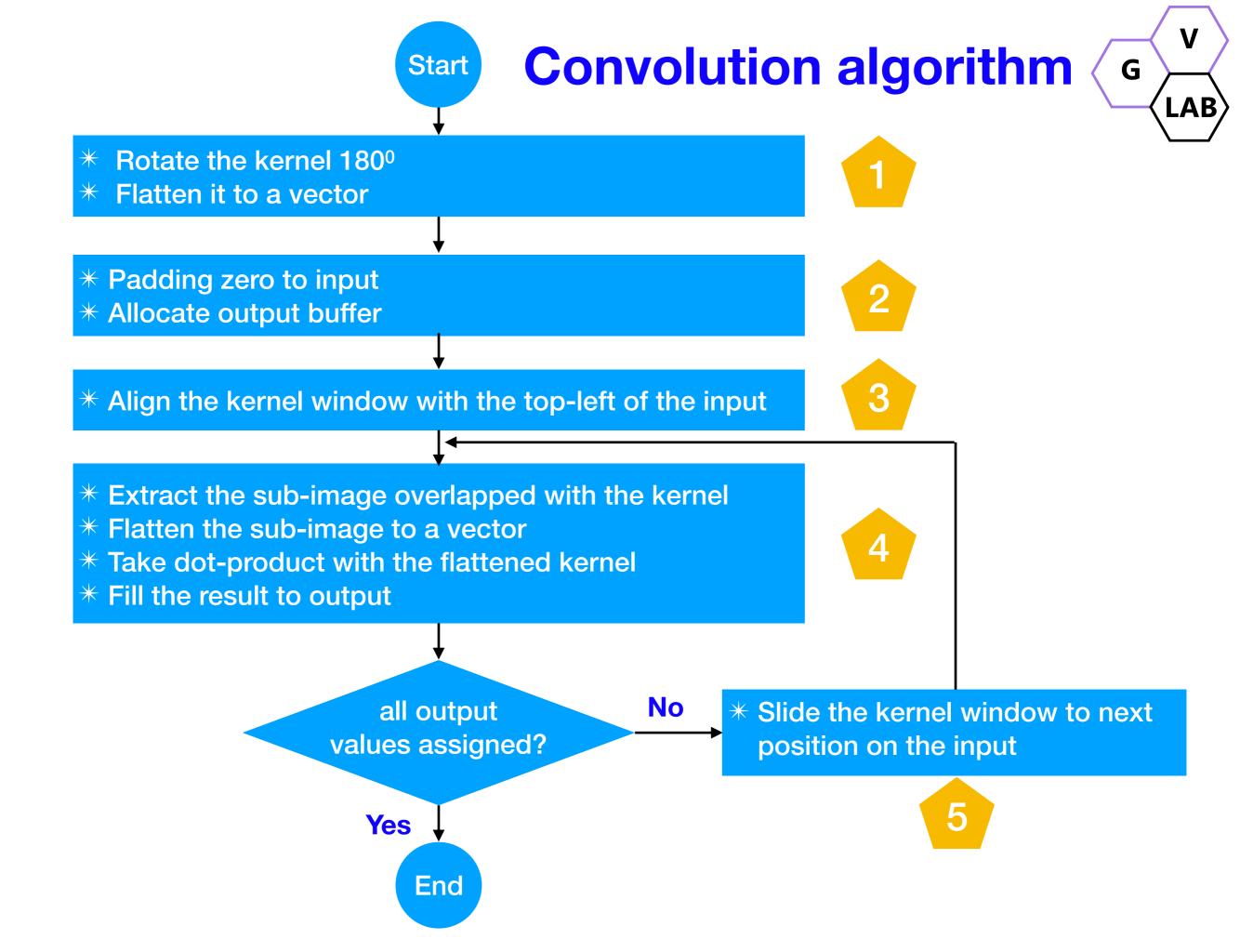
# **Convolution**Multi-channels input

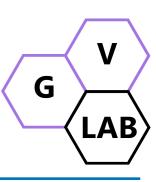
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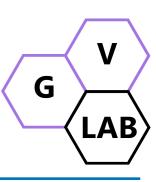




Input image or feature map: multiple channels

		1	3	1	0
	2	2	0	1	0
3	1	0	1	0	0
1	1	2	0	1	1
1	2	2	1	1	
0	1	0	2		•

Input: 3 channels



#### Input image or feature map: multiple channels

		1	3	1	0
	2	2	0	1	0
3	1	0	1	0	0
1	1	2	0	1	1
1	2	2	1	1	
0	1	0	2		'

3	1	0	1
1	1	2	0
1	2	2	1
0	1	0	2

Channel 1 (RED)

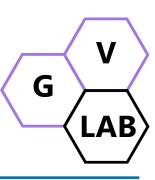
2	2	0	1
1	1	1	0
1	0	0	1
1	1	0	1

Channel 2 (GREEN)

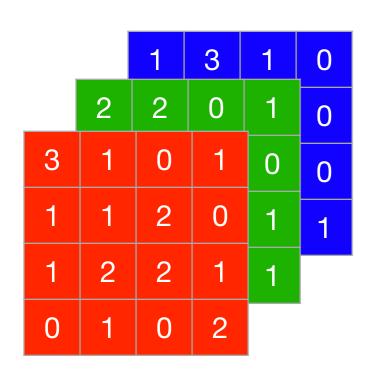
1	3	1	0
1	1	2	0
2	1	0	0
2	0	0	1

Channel 3 (BLUE)

Input: 3 channels



#### Input image or feature map: multiple channels

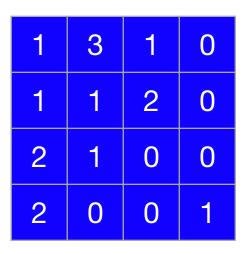


3	1	0	1
1	1	2	0
1	2	2	1
0	1	0	2

Channel 1 (RED)

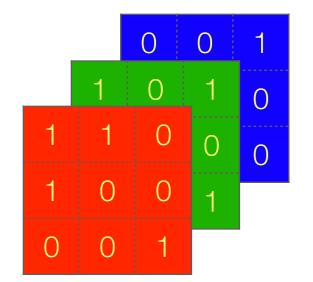
2	2	0	1
1	1	1	0
1	0	0	1
1	1	0	1

Channel 2 (GREEN)

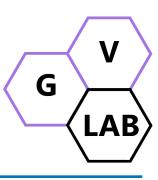


Channel 3 (BLUE)

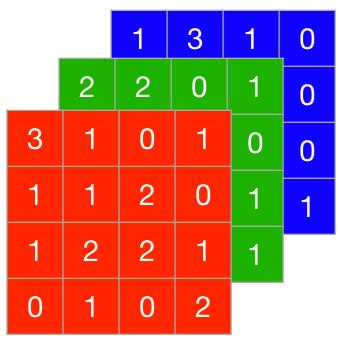
Input: 3 channels



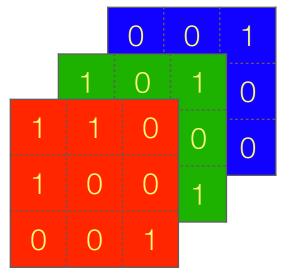
Kernel: 3 channels



#### Input image or feature map: multiple channels

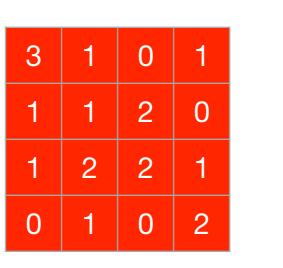


(RED)

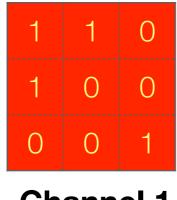


Input: 3 channels

Kernel: 3 channels



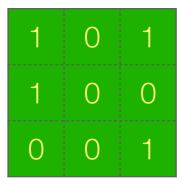
**Channel 1** 



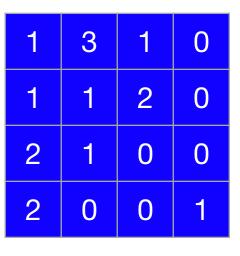
**Channel 1** (RED)

2	2	0	1
1	1	1	0
1	0	0	1
1	1	0	1

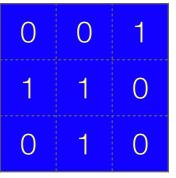
**Channel 2** (GREEN)



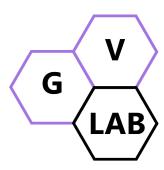
**Channel 2** (GREEN)



**Channel 3** (BLUE)

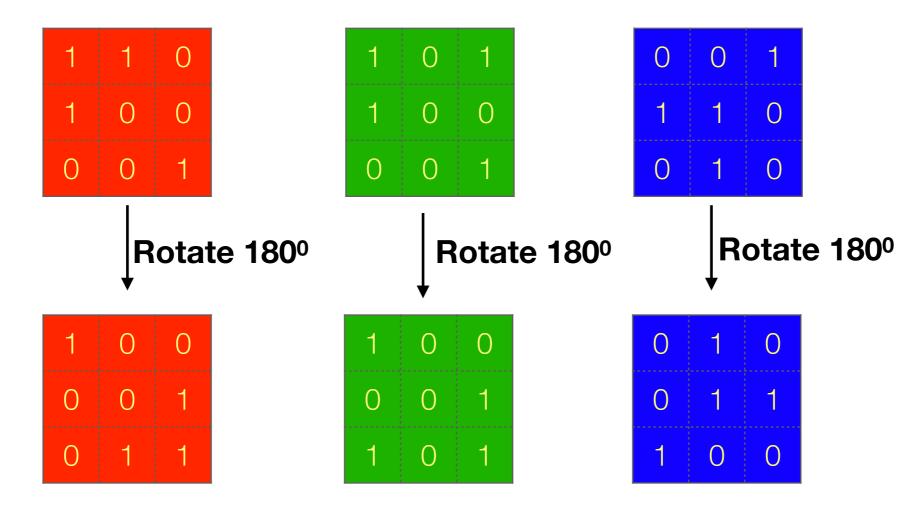


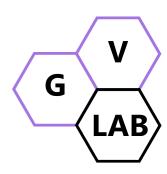
**Channel 3** (BLUE)



1

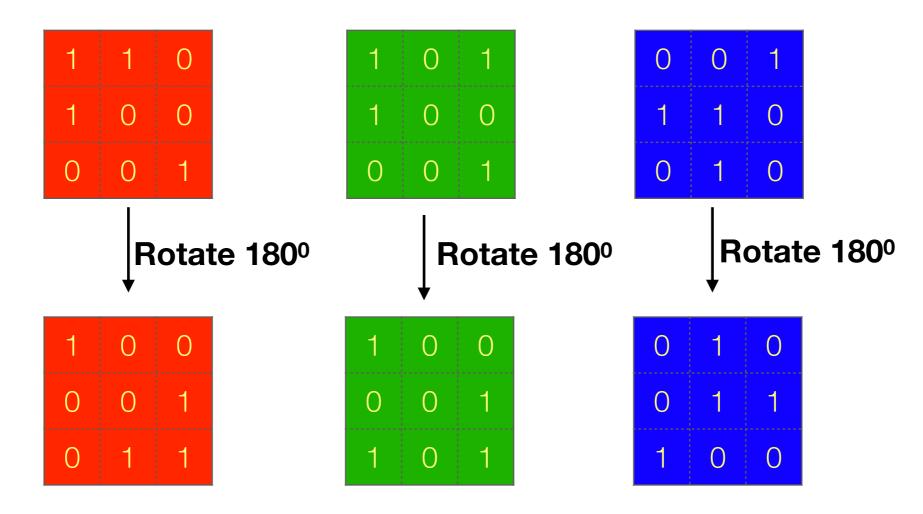
#### Rotate kernel 180°





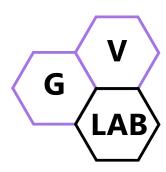
1

#### Flatten the rotated kernel to a vector



#### **After flattening:**





2

### **Padding the input**

3	1	0	1
1	1	2	0
1	2	2	1
0	1	0	2

Channel 1 (RED)

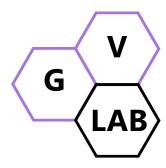
2	2	0	1
1	1	1	0
1	0	0	1
1	1	0	1

Channel 2 (GREEN)

1	3	1	0
1	1	2	0
2	1	0	0
2	0	0	1

Channel 3 (BLUE)

(No padding)



2

#### Allocate the output buffer

3	1	0	1
1	1	2	0
1	2	2	1
0	1	0	2

Channel 1 (RED)

2	2	0	1
1	1	1	0
1	0	0	1
1	1	0	1

Channel 2 (GREEN)

Channel 3 (BLUE)

input: 
$$i_1 = i_2 = 4$$

**kernel:**  $k_1 = k_2 = 3$ 

**padding:**  $p_1 = p_2 = 0$ 

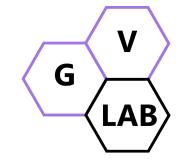
**strides:**  $s_1 = s_2 = 1$ 

$$i_1 - k_1 + 1 = 2$$
 $i_2 - k_2 + 1 = 2$ 
Output

3	1	0	1
1	1	2	0
1	2	2	1
0	1	0	2

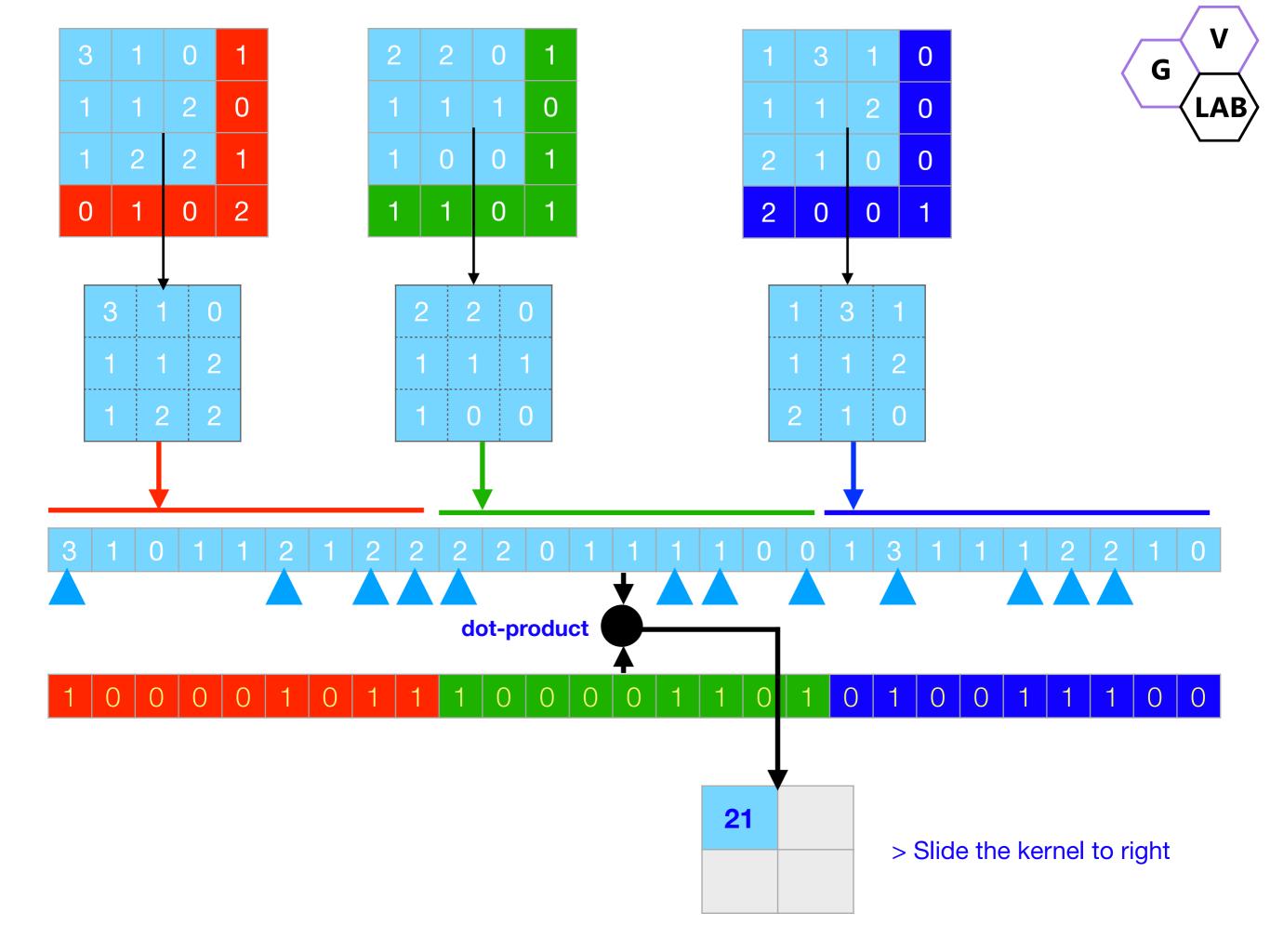
2	2	0	1
1	1	1	0
1	0	0	1
1	1	0	1

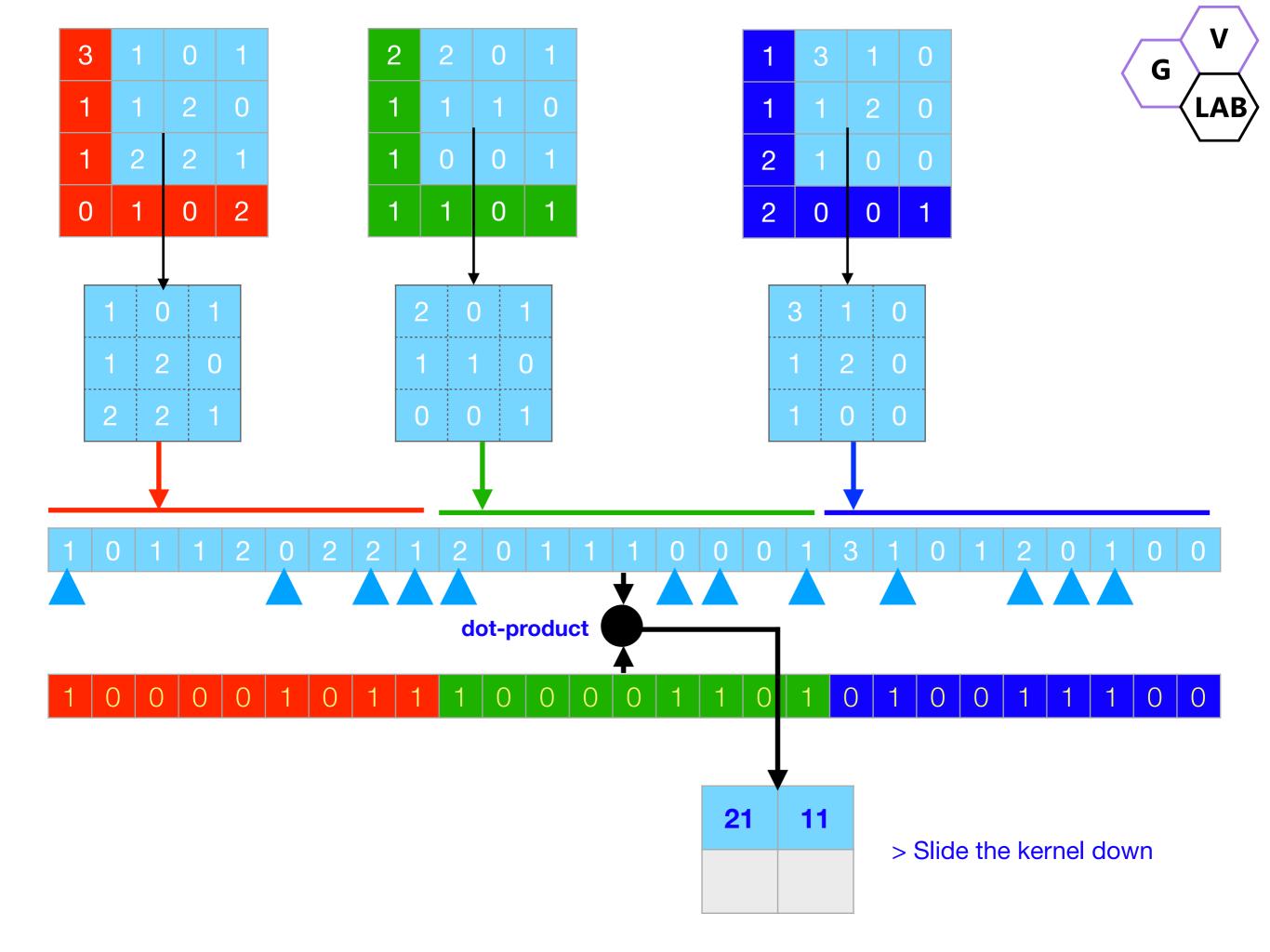
1	3	1	0
1	1	2	0
2	1	0	0
2	0	0	1

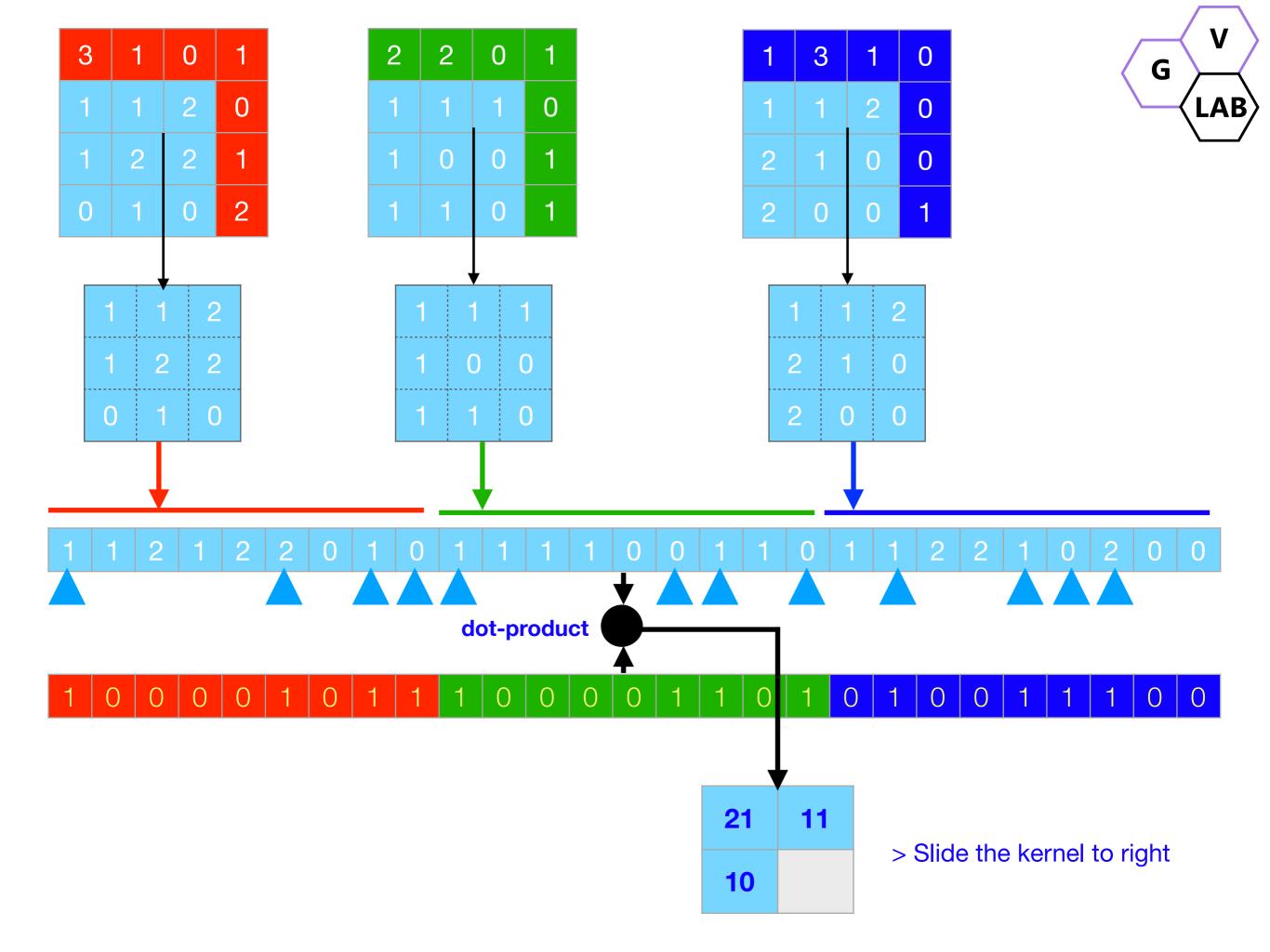


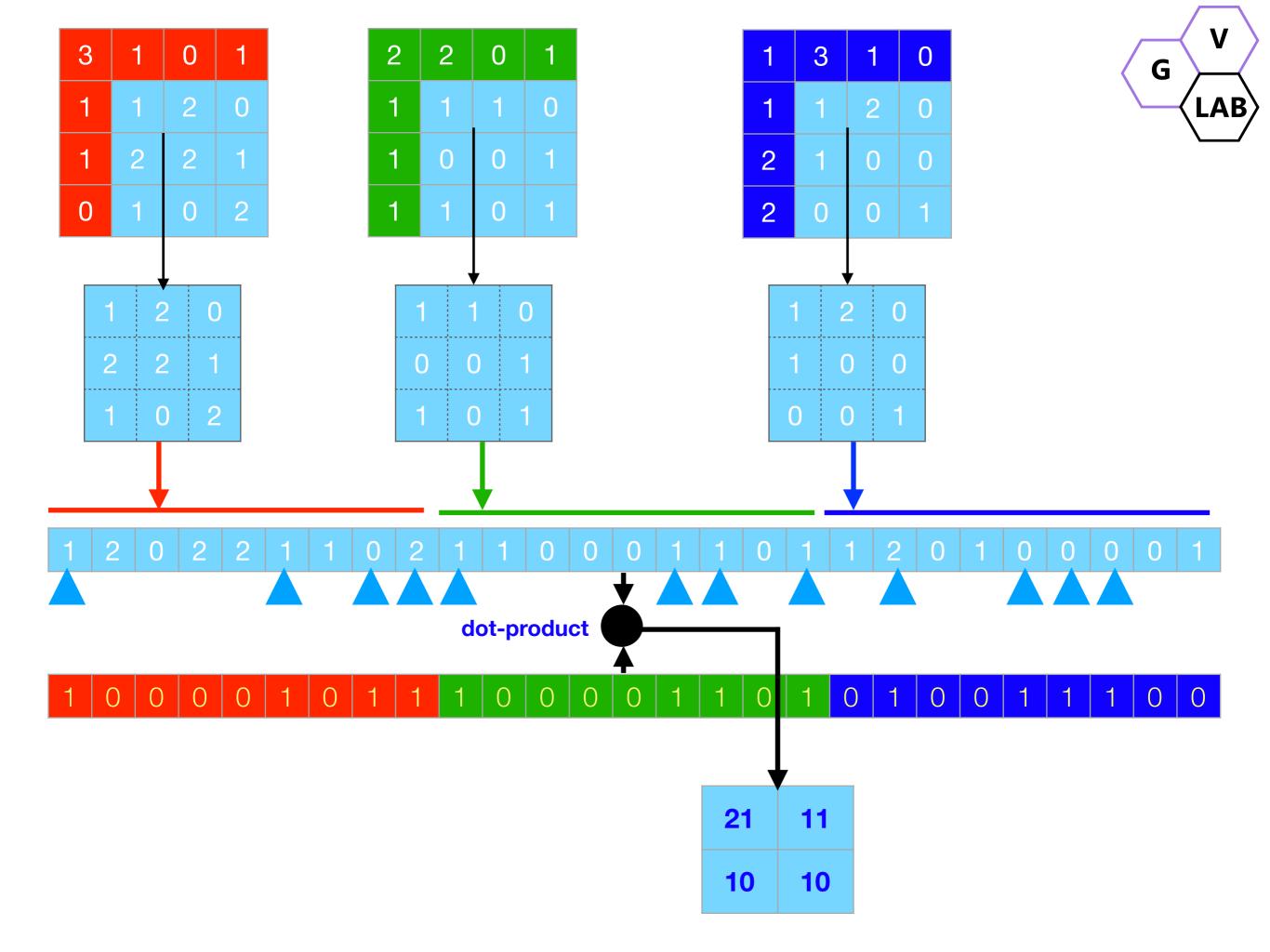


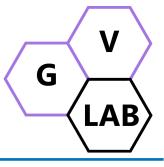
## **Starting the cross-correlation process**



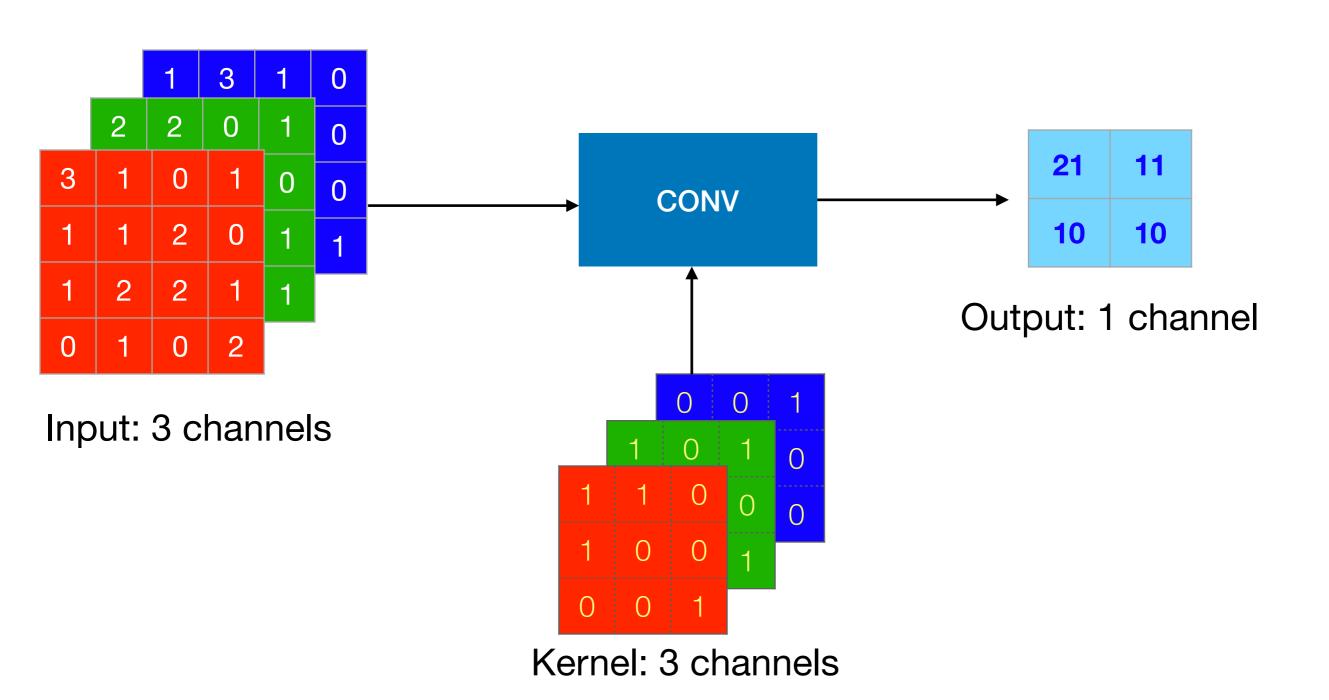






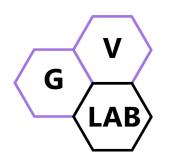


### **Final result**



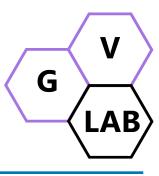
# **Convolution Multi-filters layer**

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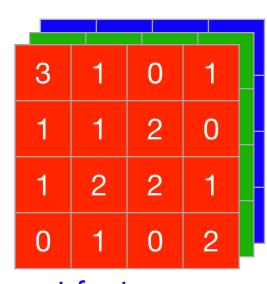


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- A Input: a feature map of D channels
- Convolution layer in Deep learning frameworks:
  - Consists of multiple filters:
    - \* Each the filters' kernel has D channels (#channels of the input)
    - \*All the filters' kernel are the same size, e.g., 3x3
- How the convolution layer computed?



Input feature map (D = 3 channels)

