

Heterogeneity in Firms: A Proxy Variable Approach for Quantile Production Functions

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January 18, 2021

Abstract

We propose a new approach to estimate firm-level production functions in which output elasticities are heterogeneous across the firm-size distribution. This paper extends the proxy variable approach for estimating production functions to the conditional quantiles of firm production. Production function parameters are identified by conditional quantile restrictions and estimated using the implied unconditional sample moment restrictions. We show that this method allows us to capture heterogeneity in output elasticities along the firm-size distribution that would not be estimated in conditional mean models. We provide small-sample evidence in a Monte Carlo study to show that this approach is robust compared to other production function estimators. The method is applied to firm and plant-level manufacturing data from the US, Chile, and Colombia.

Keywords: Production functions, Heterogeneous elasticity, Nonlinear quantile regression

JEL Classification: C14, C36, D24

1 Introduction

Production function estimation is an ongoing and historical empirical research topic that links firm's input to output decisions. Identification of the output elasticities and consequently the distribution of firm-level productivity is constrained by endogeneity issues. This is because productivity is unobserved by the econometrician, but observed by the firm when making input decisions.

A popular approach to address this issue is to introduce a proxy variable such as investment, made popular by Olley and Pakes (1996) or an intermediate material input using Levinsohn and Petrin (2003) or Ackerberg *et al.* (2015). These proxies are a function of a state variable such as capital and the unobserved productivity components. Under certain assumptions, this demand function is strictly increasing in its scalar unobserved productivity component. Inverting this

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demand function controls for unobserved productivity and the production function parameters can be estimated with a simple two-stage estimator.

While these methods have been useful in identifying the production function parameters and recovering consistent estimates of total factor productivity (TFP) resulting estimates may be biased if there is additional heterogeneity in production technology across firms. Thus, allowing for heterogeneous coefficients is one possible way to capture these differences. The literature on heterogeneous production functions is small relative to the empirical research using the homogeneous coefficient model, even though many empirical studies have found firm's heterogeneous behavior and decision.¹ This is because estimating the homogeneous coefficient model by itself is very difficult due to the issue of unobserved productivity.

In our approach we allow firm heterogeneity in production technology beyond Hick's neutral productivity shock to be driven by the rank of the unobserved production shock, η_{it} . We simultaneously extend the proxy variable approach to this framework in order to control for the part of production unobservables that are correlated with inputs. Since applying the quantile regression requires non-smooth criterion function, it is not straightforward to estimate the production functions by allowing for endogenous inputs and their heterogeneous coefficients. We are not aware of any published paper which takes into account for the endogeneity issue of production functions in the conventional quantile regression framework. We fill the gap in this paper by proposing an easy-to-implement estimator.

We show through simulation, that our proposed two-step estimator performs relatively well to the most current control function approaches of Levinsohn and Petrin (2003) and Ackerberg *et al.* (2015) and is successful in capturing heterogeneous output elasticities along the conditional distribution of firm's output. In our empirical application, we consider several popular firm and plant-level manufacturing datasets and compare our estimator to control function approaches. We show that heterogeneity in these estimates implies differences in capital intensity and TFP growth over time.

The rest of the paper is organized as follows. Section 2 reviews prior approaches for production function estimation and the literature on panel data quantile regression. Section 3 introduces the econometric model and the proposed estimator. Section 4 presents finite-sample behaviors of the estimator via Monte Carlo experiments and Section 5 applies this estimator to US, Chilean, and Colombian manufacturing datasets. Section 6 concludes with directions for future research.

¹Some notable examples are Kasahara, Schrimpf and Suzuki (2017), Balat, Brambilla and Sasaki (2018), Li and Sasaki (2017) and Dermirer (2020) to name of few. Also Gandhi *et al.* (2020) who estimate a nonparametric production function and obtain heterogeneous estimates by construction.

2 Literature Review

2.1 Production Function Estimation

We briefly review the LP (2003) procedure for estimating a *value-added* production function (in logs)^{2,3}.

$$y_{it} = \beta_k k_{it} + \beta_l l_{it} + \omega_{it} + \eta_{it}. \quad (1)$$

where y_{it} denotes value-added output, l_{it} denotes labor input for firm i at time t , k_{it} denotes capital input, ω_{it} is unobserved productivity and η_{it} denotes an iid shock to production.

To control for the correlation between ω_{it} and inputs k_{it} and l_{it} . LP introduce an intermediate input demand defined as⁴

$$m_{it} = m_t(k_{it}, \omega_{it}) \quad (2)$$

where the function f is strictly increasing in ω_{it} for all k_{it} . Productivity can then be expressed as

$$\omega_{it} = m_t^{-1}(k_{it}, m_{it}). \quad (3)$$

Substituting into the production function

$$y_{it} = \beta_k k_{it} + \beta_l l_{it} + m_t^{-1}(k_{it}, m_{it}) + \eta_{it} = \beta_l l_{it} + \Phi(k_{it}, m_{it}) + \eta_{it} \quad (4)$$

An estimate for β_l and $\Phi_t(k_{it}, m_{it})$ can be obtained by the following first stage moment restriction

$$\mathbb{E}[y_{it} - \beta_l l_{it} - \Phi_t(k_{it}, m_{it}) | \mathcal{I}_{it}] = 0 \quad (5)$$

where \mathcal{I}_{it} denotes the firm's information at time t . A linear approximation can be used, in which case estimates can be obtained from a simple linear regression.

A second stage moment restriction identifies the coefficient on capital. Assume that productivity follows an auto-regressive process

$$\omega_{it} = \mathbb{E}[\omega_{it} | \omega_{it-1}] + \xi_{it} = g(\omega_{it-1}) + \xi_{it} \quad (6)$$

where ξ_{it} denotes an innovation to productivity and satisfies $\mathbb{E}[\xi_{it} | \mathcal{I}_{it-1}] = 0$.

²We consider a value-added production function here to be consistent with the model we introduce in Section 3 for reasons which we will discuss in the corresponding section

³We drop the constant β_0 since it is not separately identified from ω_{it} without a location normalization

⁴In the original paper of Levinsohn and Petrin (2003) they consider multiple intermediate inputs such as energy, fuels, and materials as potential proxies. We focus on material inputs as the proxy.

Then, the production function parameters can be estimated from the moment restrictions

$$\begin{aligned} \mathbb{E}[\xi_{it} + \eta_{it} | \mathcal{I}_{it-1}] = \\ \mathbb{E}[\tilde{y}_{it} - \beta_k k_{it} \\ - g(\hat{\Phi}_{t-1}(k_{it-1}, m_{it-1}) - \beta_k k_{it-1}) | \mathcal{I}_{it-1}] = 0, \end{aligned} \tag{7}$$

where $\tilde{y}_{it} = y_{it} - \hat{\beta}_l l_{it}$ and $\hat{\Phi}$ denotes estimates from the first stage. LP proceed by using instruments from \mathcal{I}_{it-1} and minimize a Generalized Method of Moments (GMM) criterion function. Standard errors are obtained using a bootstrap procedure since the two-step nature of this estimators complicates asymptotic inference.

2.2 Production Functions and Quantile Regression

Connecting variation in the random error, η_{it} , to differences in a firm's final output decisions is not straightforward in the standard production function model. We briefly review a subfield of production function estimation that facilitates a more natural interpretation; production frontier models. We discuss limitations of these applications and return to our interpretation in Section 3.

A (stochastic) frontier (SFA) model of production proposed by Aigner *et al.* (1977) introduces statistical error into a frontier model. Frontier models assume firms firms deviate from an optimal frontier of production. The SFA model is typically written as

$$y_i = f(x_i, \beta) + \varepsilon_i, \tag{8}$$

where $\varepsilon_i = \eta_i - u_i$, x_i are inputs to production and β are the parameters. The error term η_i denotes the statistical noise in the model such as measurement error and u_{it} represents one-sided deviations from the production frontier. Estimates of β are typically obtained using maximum likelihood which requires strong distributional assumptions on the error terms. Estimation of the efficient frontier is then a conditional mean estimator rather than a maximal value estimator as noted by Bernini *et al.* (2004). They suggest quantile regression could then be used to estimate the highest percentiles of the conditional output distribution as it relates to the stochastic frontier, however, a theoretical difficulty is then choosing which quantile corresponds to the frontier. A more detailed derivation of a quantile representation of the frontier was introduced by Aragon *et al.* (2005) in a nonparametric model which requires inversion of a conditional empirical CDF. Since the purpose of this paper is not to compare the advantages and disadvantages of production frontier models and ours we leave this discussion for future studies and acknowledge the theoretical challenges of quantile frontier models.

There are two main challenges of implementing a quantile regression framework to the standard production function model. Firstly, as we alluded to earlier in this section, if we maintain a structural interpretation of firm production, reduced-form linear quantile regression models are

likely not sufficient in linking a firm's output choice as a function of the error term η_{it} as we elaborate in the next section. Secondly, addressing the endogeneity of ω_{it} using traditional panel data methods have challenges specific towards the production function literature and quantile models.

Regarding the second point, quantile panel data models allow for flexible interactions between unobserved heterogeneity and the quantiles of the conditional response function. Some well known approaches assume a time-invariant fixed effect such as Koenker (2004), Lamarche (2010), Canay (2011) which acts as a pure location shifter of the conditional quantile function. This approach may have two main disadvantages. First, assuming the unobservable is time-invariant is restrictive and Griliches and Hausman (1986) has shown to leads to low estimates of β_k . Secondly, the fixed effects of these models are incidental parameters so as the sample size grows, so does the number of parameters that need to be estimated which makes it computationally costly. An alternative to fixed effect estimation is to model the unobserved heterogeneity as a projection onto the observables plus a disturbance in the spirit of Chamberlain (1984). Abrevaya and Dahl (2008) adopt this approach with a linear data generating process for birth outcomes and linking it to its quantile function to estimate the effect of birth inputs over the birth-weight distribution. This approach is further developed by Bache *et al.* (2012). One downside of this approach is that it is difficult to describe the behavior of the conditional quantile function as it depends on the joint distribution of unobservables in the response function and the random effect.

Another alternative is to make use of valid instruments if they are available. The conventional argument for using input prices p_{it}^k and p_{it}^l as instruments is that they must be uncorrelated with the error term $\omega_{it} + \eta_{it}$ and correlated with input choices for capital and labor. Then one could use two-stage least squares to obtain consistent estimates of β_k and β_l . This idea can be extended to quantile-IV models such as Chernozhukov and Hansen (2005). In their identification arguments, one would need to strengthen assumptions to conditional independence as well as monotonicity of a quantile structural function (QSF) in $U_{it} = \omega_{it} + \eta_{it}$. Then if one writes the QSF for the production function as $y_{it} = Q(k_{it}, l_{it}, U_{it})$ where $\tau \in (0, 1]$ denotes the quantile index, the model is identified from a quantile type moment restriction

$$P[y_{it} \leq Q(k_{it}, l_{it}, \tau) | k_{it}, l_{it}, p_{it}^k, p_{it}^l] = \tau \quad (9)$$

while this identification argument is used in our model, we do not use the estimation procedure for reasons explained in the next section. One of these reasons are that input prices may not have enough variation across firms and exogeneity can be violated if they capture input quality differences as argued by Griliches and Hausman (1986).

3 A Random Coefficient Production Function

We specify a *value-added* production function as a random coefficient model:⁵

$$y_{it} = \beta_k(\eta_{it})k_{it} + \beta_l(\eta_{it})l_{it} + \omega_{it} \quad (10)$$

The variables in equation (10) have the same interpretation as the ones we introduced in the LP model. The only difference here is that we allow the output elasticities to be functionally dependent on the production shock η_{it} while productivity still maintains its additive separability.⁶

A special case of (10) is the location scale model,

$$y_{it} = \beta_k k_{it} + \beta_l l_{it} + \omega_{it} + (\mu_k k_{it} + \mu_l l_{it})\eta_{it} \quad (11)$$

Which implies that the τ th conditional quantile of y_{it} is given by

$$Q_{y_{it}}(\tau | \mathcal{I}_{it}) = \beta_k k_{it} + \beta_l l_{it} + \omega_{it} + (\mu_k k_{it} + \mu_l l_{it})F^{-1}(\tau) \quad (12)$$

where $F^{-1}(\tau)$ is the quantile function of production shocks η_{it} .

The formulation of (11) is not new to the production function literature. The assumption that input choices can impact firm's production beyond the conditional mean has important consequences for firm's attitude towards production risk. A volume of literature that originated in the late 1970's challenged the standard stochastic specifications of production functions (Just and Pope, 1978, 1979) by considering a specification that allowed firm's inputs to both increase or decrease the marginal variability of final output. The most common application of those models are in the agricultural industry where the variance on the yield of harvested crops could be increased by adverse weather or decreased by pesticide usage. Since manufacturing businesses tend to operate in a more controlled environment, risk is less prevalent in these industries so the conditional variance of η_{it} may be smaller. A general quantile model such as the one specified in (10) can be seen as an extension of the higher-order moment estimation of risk initiated by Antle (1983). However, it can also be seen purely as an econometric specification issue as we are unaware of any tests that could distinguish between higher order moment production risk and misspecification. We choose the latter interpretation for our model.

We note that under quantile preferences a firm who maximizes the τ level of utility of profits could explain heterogeneity in the output distribution. Unlike risk-neutral firms, firms could have a utility function that is represented by preferences of the firm manager(s) who decides the opti-

⁵A value-added specification is not without loss of generality. Only specific value-added production functions such as the Leontief value-added model can be mapped to its gross-output counterpart while also avoiding the non-identification results of Gandhi *et al.* (2020). This becomes more difficult with this specification.

⁶More specifically, productivity is only a location shifter of the conditional output distribution. We cannot allow $\omega_{it} = \omega_{it}(\eta_{it})$ since this would violate the scalar unobservability assumption of our proxy variable

mal expenditure on inputs. Different managers may have different preferences for risk. Quantile utility maximization is not a new concept. A short list of papers have considered quantile utility maximization such as Manski (1988), Rostek (2009), Chambers (2007), and Bhattacharya (2009). Dynamic input choices such as investment are much more difficult to solve using the quantile utility framework and the reader can refer to de Castro and Galvao (2017) for a treatment of dynamic quantile utility models. As far as we know, the quantile utility framework has not been applied to firm decision problems and a more thorough treatment of such is outside the scope of this paper.

3.1 Identification

3.1.1 Production Function in Levinsohn and Petrin (2003)

Returning to our misspecification interpretation in Equation (10), we follow LP in the usual set of assumptions on timing of input choices and scalar unobservability.

Assumption 3.1

- (a) *The production function $y_{it} = f_t(k_{it}, l_{it}, \omega_{it}, \eta_{it})$ is strictly increasing in η_{it}*
- (b) *The firm's information set at time t includes current and past productivity shocks $\{\omega_{it}\}_{t=0}^t$, but does not include past productivity shocks $\{\omega_{it}\}_{t=t+1}^\infty$. η_{it} is independent of \mathcal{I}_{it}*
- (c) *Firm's productivity shocks evolve according to a first-order Markov process*

$$\omega_{it} = g(\omega_{it-1}) + \xi_{it} \quad (13)$$

where the iid productivity innovations ξ_{it} satisfy $\mathbb{E}[\xi_{it} | \mathcal{I}_{it-1}] = 0$

- (d) *Firms accumulate capital according to*

$$K_{it} = \kappa_t(I_{it-1}, K_{it-1}). \quad (14)$$

where K_{it-1} and I_{it-1} denote previous period capital and investment

- (e) *Firm's intermediate input demand function is given by $m_{it} = m_t(k_{it}, \omega_{it})$*
- (f) *The intermediate input demand function $m_t(k_{it}, \omega_{it})$ is strictly increasing in ω_{it}*

Given these Assumption (3.1)(e, f), we invert intermediate input demand $\omega_{it} = m^{-1}(k_{it}, m_{it})$ and substitute into the production function. We treat m_t^{-1} as a nonparametric function (k_{it}, m_{it}) . We then have:

$$y_{it} = \beta_k(\eta_{it})k_{it} + \beta_l(\eta_{it})l_{it} + m_t^{-1}(k_{it}, m_{it}) = \beta_l(\eta_{it})l_{it} + \Phi(k_{it}, m_{it}, \eta_{it}) \quad (15)$$

Using Assumption (3.1)(a, b) we have the following identification condition for the first stage:

$$P(y_{it} \leq \beta_l(\tau)l_{it} + \Phi(k_{it}, m_{it}; \tau) | \mathcal{I}_{it}) = \tau \quad (16)$$

The equation in (15) is a semiparametric partially linear quantile regression model which can be consistently estimated using approaches proposed by Lee (2003), Koekner *et al.* (1994), or Chen and Pouzo (2009). We can then plug these estimates back into the production function and apply Assumption (3.1)(c) to obtain:

$$y_{it} = \beta_k(\eta_{it})k_{it} + \hat{\beta}_l(\tau)l_{it} + g(\hat{\Phi}(k_{it-1}, m_{it-1}; \tau) - \beta_k(\eta_{it})k_{it-1}) + \xi_{it} \quad (17)$$

The main challenge of the identification result in the second stage is that it is not true in general that

$$P(y_{it} \leq \beta_k(\tau)k_{it} + \hat{\beta}_l(\tau)l_{it} + g(\hat{\Phi}(k_{it-1}, m_{it-1}; \tau) - \beta_k(\tau)k_{it-1}) + \xi_{it} | \mathcal{I}_{it-1}) = \tau \quad (18)$$

The lack of identification in using the above equation is related to the identification issues of quantile panel data models using correlated random effects. For example, Canay (2011) notes that the conditional behavior of (18) depends on the joint distribution of η_{it} and ξ_{it} which makes identification of $(g, \beta_k(\tau))$ in the second stage problematic. Identification issues related to quantile panel data models using conditional quantile restrictions are studied by Rosen (2012) who develops conditions for both set and point identification. Cai *et al.* (2018) note that an equation like (17) can be interpreted as measurement error in the dependent variable of a quantile regression model where ξ_{it} is the measurement error in y_{it} . This type of model is studied by Hausman *et al.* (2019) who use a sieve MLE approach for estimating the density of the measurement error. Both aforementioned papers require varying degrees of distributional assumptions on the error term which we would like to avoid in our model. An alternative would be to use the entropic integration method of Schennach (2014) and integrate out ξ_{it} via simulation. However, this approach would introduce additional nuisance parameters that would need to be estimated.

We can avoid distributional assumptions and nuisance parameters by framing the identification condition in the ξ_{it} component, similar to Ackerberg *et al.* (2015) by concentrating out the constant $\beta_0(\tau)$ and g . For a hypothetical guess of $\beta_k(\tau)$, say $\tilde{\beta}_k(\tau)$ we can write for a fixed $\tau \in (0, 1]$

$$\beta_0(\tau) + \omega_{it} = y_{it} - \hat{\beta}_l(\tau)l_{it} - \tilde{\beta}_k(\tau)k_{it} = \hat{\Phi}(k_{it}, m_{it}; \tau) - \tilde{\beta}_k(\tau)k_{it} \quad (19)$$

We can rewrite the AR(1) productivity process as

$$\hat{\Phi}(k_{it}, m_{it}; \tau) - \tilde{\beta}_k(\tau)k_{it} = \beta_0(\tau) + g(\hat{\Phi}(k_{it-1}, m_{it-1}; \tau) - \tilde{\beta}_k(\tau)k_{it-1}) + \xi_{it} \quad (20)$$

and note that the implied residuals satisfy

$$\mathbb{E}[\xi_{it}(\tilde{\beta}_k(\tau))|\mathcal{I}_{it-1}] = 0 \quad (21)$$

which can be estimated by standard GMM procedures for a fixed $\tau \in (0, 1]$

This estimator is then a simple extension of the control function approach where the first stage parameters are estimated using quantile regression techniques. The location-shift assumption on the productivity process allows us to identify and estimate the parameters in the second stage while concentrating out additional parameters. Some interesting extensions could include additional heterogeneity in the productivity process such as a location-scale model for productivity which could be estimated using He (1997) or a random-coefficient model where second stage identification would rely on a conditional quantile restriction and estimated using Kaplan and Sun (2016).

3.1.2 Production Function in Ackerberg *et al.* (2015)

In the Ackerberg *et al.* (2015) setting, the intermediate input demand $m_{it} = m_t(k_{it}, l_{it}, \omega_{it})$ is conditional on the labor input. This allows a more flexible timing assumption on when labor is chosen by the firm relative to the other inputs. Labor can have dynamic implications and be partially or fully realized before productivity ω_{it} . In this setting, the labor elasticity β_l cannot be identified in the first stage as in the LP approach. The first stage equation is then:

$$y_{it} = \beta_k(\eta_{it})k_{it} + \beta_l(\eta_{it})l_{it} + m_t^{-1}(k_{it}, l_{it}, m_{it}) = \Phi(k_{it}, l_{it}, m_{it}, \eta_{it}), \quad (22)$$

where we have used monotonicity of the intermediate input demand function in ω_{it} to control for unobserved productivity. The nonparametric function $\Phi(\cdot; \tau)$ can be identified using Assumption (3.1) (a) and (b)

$$P(y_{it} \leq \Phi(k_{it}, l_{it}, m_{it}; \tau) | \mathcal{I}_{it}) = \tau \quad (23)$$

which suggests that the functional $\Phi(\cdot, \tau)$ can be estimated by nonparametric quantile methods such local linear or polynomial regression (Chaudhuri, 1991a,b), smoothing splines (Koekner *et al.*, 1994), or more general sieve based estimation (Chen and Pouzo, 2012).

As before, we concentrate out the constant $\beta_0(\tau)$ and g . For a hypothetical guess of $(\beta_l(\tau), \beta_k(\tau))$ we can write

$$\beta_0(\tau) + \omega_{it} = y_{it} - \tilde{\beta}_l(\tau)l_{it} - \tilde{\beta}_k(\tau)k_{it} = \hat{\Phi}(k_{it}, l_{it}, m_{it}; \tau) - \tilde{\beta}_k(\tau)k_{it} - \tilde{\beta}_l(\tau)l_{it} \quad (24)$$

We can rewrite the AR(1) productivity process as

$$\begin{aligned}\hat{\Phi}(k_{it}, l_{it}, m_{it}; \tau) - \tilde{\beta}_k(\tau)k_{it} - \tilde{\beta}_l(\tau)l_{it} \\ = \beta_0(\tau) + g(\hat{\Phi}(k_{it-1}, l_{it-1}, m_{it-1}; \tau) - \tilde{\beta}_k(\tau)k_{it-1} - \tilde{\beta}_l(\tau)l_{it-1}) + \xi_{it}\end{aligned}\tag{25}$$

and note that the implied residuals satisfy

$$\mathbb{E}[\xi_{it}(\tilde{\beta}_k(\tau), \tilde{\beta}_l(\tau)) | \mathcal{I}_{it-1}] = 0\tag{26}$$

which can be estimated by standard GMM procedures for a fixed $\tau \in (0, 1]$

3.2 Estimation

We discuss how to estimate the LP production function in two stages.

First Stage

Recall, in the first stage we have the identification condition

$$P(y_{it} \leq \beta_l(\tau)l_{it} + \Phi(k_{it}, m_{it}; \tau) | \mathcal{I}_{it}) = \tau\tag{27}$$

which yields

$$\mathbb{E}[1\{y_{it} \leq \beta_l(\tau)l_{it} + \Phi(k_{it}, m_{it}; \tau)\} - \tau | \mathcal{I}_{it}] = 0\tag{28}$$

Similar to Olley and Pakes (1996), $\Phi(\cdot; \tau)$ can be approximated by a flexible polynomial so that estimates $\hat{\beta}_l(\tau)$ and $\hat{\Phi}(\cdot; \tau)$ can be obtained from a polynomial quantile regression. A more complete model of $\Phi(\cdot; \tau)$ can be obtained using a finite-dimensional sieve and estimated using a minimum distance criterion function. We briefly introduce this approach.

To fix notation, let $x_{it} = (k_{it}, m_{it})$ denote the variables in the nonparametric function, Φ . Let $\Lambda_1(y_{it}, l_{it}; \beta_l, \Phi(x_{it})) = 1\{y_{it} - \beta_l(\tau)l_{it} - \Phi(x_{it}) \leq 0\} - \tau$. Rephrasing our first stage identification condition as

$$\mathbb{E}[\Lambda_1(y_{it}, l_{it}; \beta_l, \Phi(x_{it})) | \mathcal{I}_{it}] = 0\tag{29}$$

we can see that this resembles the semiparametric moment conditions studied by Chen and Pouzo (2009) and Ai and Chen (2012) where the residual function is non-differentiable in (β_l, Φ) due to the indicator function. However, one difference between our model and theirs is that there is no endogeneity in the first stage which simplifies estimation. Let $\alpha = (\beta_l, \Phi)$. The first stage estimates

can be found from the following minimization problem

$$(\hat{\beta}_l, \hat{\Phi}) = \underset{\alpha \in (\Theta \times \mathcal{H}_{k(n)})}{\operatorname{argmin}} \sum_{i=1}^N \sum_{t=1}^T \hat{\mathbb{E}}[\Lambda_1(y_{it}, l_{it}; \beta_l, \Phi) | \mathcal{I}_{it}]' \hat{\Sigma}_1^{-1} \hat{\mathbb{E}}[\Lambda_1(y_{it}, l_{it}; \beta_l, \Phi) | \mathcal{I}_{it}] \quad (30)$$

where $\Theta \subset \mathbb{R}$ with $\beta_l \in \Theta$ and $\{\mathcal{H}_{k(n)} : k(n) = 1, 2, \dots\}$ is a sequence of approximating finite dimensional linear sieve spaces which becomes dense as $k(n) \rightarrow \infty$. In practice one could use a tensor-product linear sieve basis function such as B-splines or polynomials. $\hat{\mathbb{E}}[\Lambda_1(y_{it}, l_{it}; \beta_l, \Phi) | \mathcal{I}_{it}]$ and $\hat{\Sigma}_1$ are nonparametric estimators of $\mathbb{E}[\Lambda_1(y_{it}, l_{it}; \beta_l, \Phi) | \mathcal{I}_{it}]$ and Σ_1 which can be obtained using series LS estimator and $\hat{\Sigma}_1 = \tau(1 - \tau)$. In our simulation study and empirical application we use a 3rd order polynomial with interactions and estimate the first stage parameters using simple weighted linear quantile regression, which we justify in the next section.

Second Stage

Once estimates of $\beta_l(\tau)$ and $\Phi(k_{it}, m_{it}; \tau)$ are obtained, we can estimate the residuals of the productivity innovation shocks for a given $\tilde{\beta}_k(\tau)$

$$\hat{\xi}_{it}(\tilde{\beta}_k(\tau)) = \hat{\Phi}(k_{it}, m_{it}; \tau) - \tilde{\beta}_k(\tau)k_{it} - g(\hat{\Phi}(k_{it-1}, m_{it-1}; \tau) - \tilde{\beta}_k(\tau)k_{it-1}, \rho) \quad (31)$$

where we parameterize the process for productivity g by a finite dimensional parameter vector ρ .⁷ To simplify notation in the later section we let $\beta = (\beta_0, \beta_k, \rho)$ and $\hat{\xi}_{it}(\tilde{\beta}_k(\tau)) = \Lambda_2(y_{it}, l_{it}, \beta_l, \beta, \Phi(x_{it}))$, so we can rewrite the moment condition in equation (21) as

$$\mathbb{E}[\Lambda_2(y_{it}, l_{it}, \beta_l, \beta, \Phi(x_{it})) | \mathcal{I}_{it-1}] = 0 \quad (32)$$

The capital coefficient is identified using the fact that current capital does not respond to innovation shocks in productivity. In practice we include additional instruments $(k_{it-1}, l_{it-1}, m_{it-1})$ so that our model is over-identified and $\beta_k(\tau)$ can be estimated using a GMM criterion function so that $\hat{\beta}$ solves

$$\hat{\beta} = \underset{\beta}{\operatorname{argmin}} \hat{\mathbb{E}}[\Lambda_2(y_{it}, l_{it}, \beta_l, \beta, \Phi(x_{it}))]' \hat{\Sigma}_2 \hat{\mathbb{E}}[\Lambda_2(y_{it}, l_{it}, \beta_l, \beta, \Phi(x_{it}))] \quad (33)$$

where $\hat{\mathbb{E}}[\cdot]$ are the sample unconditional moments corresponding to (32) and $\hat{\Sigma}_2$ may be an arbitrary weighting matrix. We discuss how to efficiently choose the weighting matrix in this two-step approach using Ackerberg *et al.* (2014) in the next section.

⁷We use a third degree polynomial in ω_{it-1} to estimate g in the empirical application. In practice, one could estimate g nonparametrically, however this complicates the asymptotic results

3.3 Asymptotics

We divide the discussion of asymptotics in two parts. In the first part, we show how the coefficients for the variable inputs identified in the first stage can be efficiently estimated using Ai and Chen (2012). In the second part, we show how the capital coefficient can be efficiently estimated using the appropriate weighting matrix as shown in Ackerberg *et al.* (2014).

First Stage

The main difficulty in establishing asymptotic normality for the labor estimate in the first stage is the non-smoothness of the residual function in equation (29). Chen and Pouzo (2009) extend the results of Ai and Chen (2003) to show that the estimate of the parametric part of their model is not only asymptotically normal, but also establish its semiparametric efficiency bound. In the model without endogeneity, they show that their estimator reaches the same efficiency bound as Lee (2003). Readers can refer to Section 5 of Chen and Pouzo (2009), in particular, Remark 5.1 illustrates how to weaken their assumptions in the case of exogeneity. Let $u_{it} = y_{it} - \beta_l l_{it} - \Phi(x_{it})$. Using Condition 5.6 and 5.7 in Chen and Pouzo (2009)

$$\sqrt{n}(\hat{\beta}_l - \beta_l) \rightarrow N(0, V_1^{-1}) \quad (34)$$

where

$$V_1 = \tau(1-\tau) \left\{ \mathbb{E}[f_{U|L,X}^2(0)l_{it}^2] - \mathbb{E}\left[\frac{\mathbb{E}[f_{U|L,X}^2(0)l_{it}|X]^2}{\mathbb{E}[f_{U|L,X}^2(0)|X]}\right] \right\}^{-1} \quad (35)$$

A simple consistent estimator for the asymptotic variance can be given by

$$\hat{V}_1 = \tau(1-\tau) \left\{ \frac{1}{NT} \sum_{i=1}^N \sum_{t=1}^T \left[\hat{f}_{U|L,X}^2(0)l_{it}^2 - \frac{\hat{\mathbb{E}}[f_{U|L,X}^2(0)l_{it}|X]^2}{\hat{\mathbb{E}}[f_{U|L,X}^2(0)|X]} \right] \right\}^{-1} \quad (36)$$

where $\hat{f}_{U|L,X}(0)$ and $\hat{\mathbb{E}}[\cdot|X]$ are consistent nonparametric estimators of $f_{U|L,X}(0)$ and $\mathbb{E}[\cdot|X]$. An alternative to plugging in these into the estimate of the asymptotic variance, is to use a weighted bootstrap procedure. Chen and Pouzo (2009) show that this algorithm produces consistent estimates the asymptotic distribution of β_l as long as one chooses an i.i.d sample of positive weights denoted by w_{it} which satisfy $\mathbb{E}[w_{it}] = 1$ and $Var[w_{it}] < \infty$ and is independent from the data. In practice we draw weights from a standard exponential distribution for each iteration of the bootstrap procedure and use these to compute a weighted quantile regression estimator of β_l and Φ .

Second Stage

Asymptotic normality of two-stage GMM estimators is well-established in the literature. The second stage estimates satisfy

$$\sqrt{n}(\hat{\beta} - \beta) \xrightarrow{d} N(0, V_2) \quad (37)$$

where

$$V_2 = (G_2' \Sigma_2 G_2)^{-1} (G_2' \Sigma_2 V_{\Lambda 2} \Sigma_2 G_2) (G_2' \Sigma_2 G_2)^{-1} \quad (38)$$

Here, $G_2 = \frac{\partial \mathbb{E}(\Lambda_2(y_{it}, l_{it}, \beta_l, \beta, \Phi(x_{it})))}{\partial \beta}$, $V_{\Lambda 2} = \text{Var}(\Lambda_2(y_{it}, l_{it}, \beta_l, \beta, \Phi(x_{it})))$ and Σ_2 is the weighting matrix. The two-step GMM estimator of β is not efficient since the information sets used in the first stage and the second stage are not simultaneously considered. In order to adjust for the variance in estimating the first stage parameters β_l and Φ , we show how Ackerberg *et al.* (2014) can be applied to choosing an optimal weighting matrix that reflects the noise from the first stage estimates and provide the semi-parametric efficiency bound.

The intuition of the Ackerberg *et al.* (2014) approach is that under certain conditions, the original unconditional moments $\mathbb{E}[\Lambda_2(y_{it}, l_{it}, \beta_l, \beta, \Phi(x_{it}))]$ can be orthogonalized with respect to the moment condition in equation (29). When the first step is exactly identified from a semiparametric partially linear quantile restriction, this new moment condition is written as:⁸

$$\begin{aligned} \tilde{\Lambda}_2(y_{it}, l_{it}, \beta_l, \beta, \Phi) &= \Lambda_2(y_{it}, l_{it}, \beta_l, \beta, \Phi) + \sum_{t=1}^T \left[\left(\frac{\partial \mathbb{E}[\Lambda_2(y_{it}, l_{it}, \beta_l, \beta, \Phi) | \mathcal{I}_{it-1}]}{\partial l_{it}} \right. \right. \\ &\quad \left. \left. + \frac{\partial \mathbb{E}[\Lambda_2(y_{it}, l_{it}, \beta_l, \beta, \Phi) | \mathcal{I}_{t-1}]}{\partial \Phi_j'} \right) \times \frac{\tau - \mathbb{1}\{y_{it} \leq \beta_l l_{it} - \Phi_t(x_{it})\}}{f_{U|L,X}(0)} \right] \end{aligned} \quad (39)$$

Ackerberg *et al.* (2014) show that the semiparametric efficiency bound for β can be written as the inverse of

$$\tilde{V}_2 = \left(\frac{\partial \mathbb{E}[\Lambda_2(y_{it}, l_{it}, \beta_l, \beta, \Phi)]}{\partial \beta} \right)' \text{Var}(\tilde{\Lambda}_2(y_{it}, l_{it}, \beta_l, \beta, \Phi))^{-1} \left(\frac{\partial \mathbb{E}[\Lambda_2(y_{it}, l_{it}, \beta_l, \beta, \Phi)]}{\partial \beta} \right) \quad (40)$$

so that this bound can be achieved by choosing a weighting matrix $\Sigma_2 = \text{Var}(\tilde{\Lambda}_2(y_{it}, l_{it}, \beta_l, \beta, \Phi))^{-1}$ which can be consistently estimated by plugging in estimates $\hat{\beta}_l$, $\hat{\Phi}$, and $\hat{f}_{U|L,X}(0)$ from the first stage.

In practice, it is much easier to compute a numerically equivalent estimate of $\text{Var}(\tilde{\Lambda}_2(y_{it}, l_{it}, \beta_l, \beta, \Phi))^{-1}$ as shown by Ackerberg *et al.* (2012) which is outlined by Ackerberg *et al.* (2014) in Section 3.3 of their paper.

⁸Although the results of Chen and Pouzo (2009) and Ai and Chen (2012) do not require the first step to be exactly identified, we require it in order to derive the semiparametric efficiency bound for the second step estimates

4 Monte Carlo Experiments

We use a location-scale version of Levinsohn and Petrin (2003) and replicate Ackerberg *et al.* (2015) simulations sampling 1000 datasets consisting of 1000 firms. We simulate optimal input choices for 100 time periods, using the last 10 periods for estimation.

$$y_{it} = \beta_0 + \beta_k k_{it} + \beta_l l_{it} + \omega_{it} + (\gamma_0 + \gamma_k k_{it} + \gamma_l l_{it})\eta_{it} \quad (41)$$

with $\beta_0 = 0$, $\beta_k = 0.4$ and $\beta_l = 0.6$. The location scale parameters are set as $\gamma_0 = 0$, $\gamma_k = 0.7$ and $\gamma_l = -0.6$. For each simulation we simulate two DGPs with $\eta_{it} \sim N(0, 0.1)$ and $\eta_{it} \sim Laplace(0, 0.1)$.

To produce consistent estimates of the labor coefficient in the first stage, we do not allow for any wage variation across firms and labor is chosen at time t with perfect information about ω_{it} . However, we add optimization error in labor. An AR(1) process is specified for productivity $\omega_{it} = \rho\omega_{it-1} + \xi_{it}$ where $\rho = 0.7$. The variance of ξ_{it} and initial value ω_{i0} is set so that the standard deviation of ω_{it} is constant over time and equal to 0.3

We compare the LP estimation procedure with our “QLP” two-step procedure under the two different sets of experiments specified earlier. We estimate the model for $\tau \in \{0.1, 0.15, \dots, 0.85, 0.9\}$ and use current period capital, k_{it} as our instrument so that our model is exactly identified. For the weighting matrix, we use an estimate of the variance covariance matrix of the sample moments. We use a continuously updated GMM procedure such that estimates of $\beta_k(\tau)$ in the second stage are estimated simultaneously with the weighting matrix. We initialize the algorithm at the true value of $\beta_k(\tau)$ however we find that the estimation is robust to reasonable initial values.

We focus on whether our estimate can capture heterogeneity in the output distribution reasonably well compared to the mean estimates from the LP approach. Previous papers such as Olley and Pakes (1996) and Levinsohn and Petrin (2003) already show that the control function approach controls for endogeneity bias from unobserved productivity and perform specification tests for the set of possible control functions such as investment, material inputs, fuels, and energy.

Figure 1 graphs the estimated coefficients for QLP and LP. The black line denotes the QLP estimator and its corresponding 90% confidence interval is the gray shaded area. The solid red line denotes the LP estimator and the dotted red lines are its corresponding 90% confidence interval. Capital coefficients are the first column of the graph and labor coefficients are the second column. The first row corresponds to DGP 1 with $\eta_{it} \sim N(0, 0.1)$ and the second row corresponds to DGP 2 with $\eta_{it} \sim Laplace(0, 0.1)$. The estimator does reasonably well at capturing heterogeneity outside of the conditional mean estimate for both capital and labor. Not surprisingly, the confidence intervals for capital are wider than the interval for labor due to nature of the multi-step procedure. Figure 2 shows that these estimators perform well in finite sample. The MSE for both estimators is plotted over $\tau \in \{0.1, 0.15, \dots, 0.85, 0.9\}$ with the black line denoting the QLP estimates and the dotted red line denoting the LP estimates.

Figure 1: QLP estimated coefficients of $\beta_k(\tau)$ and $\beta_l(\tau)$. Dotted line is LP estimator

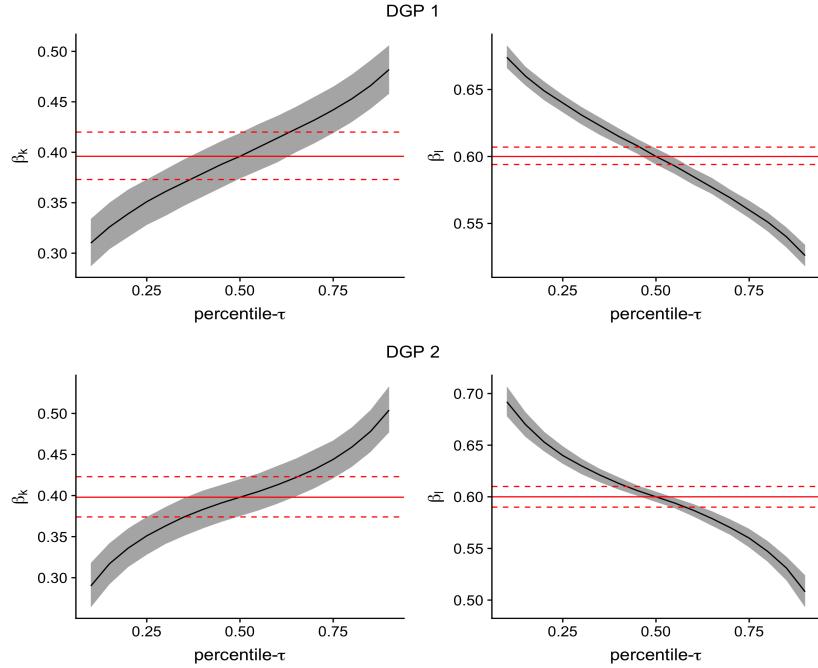
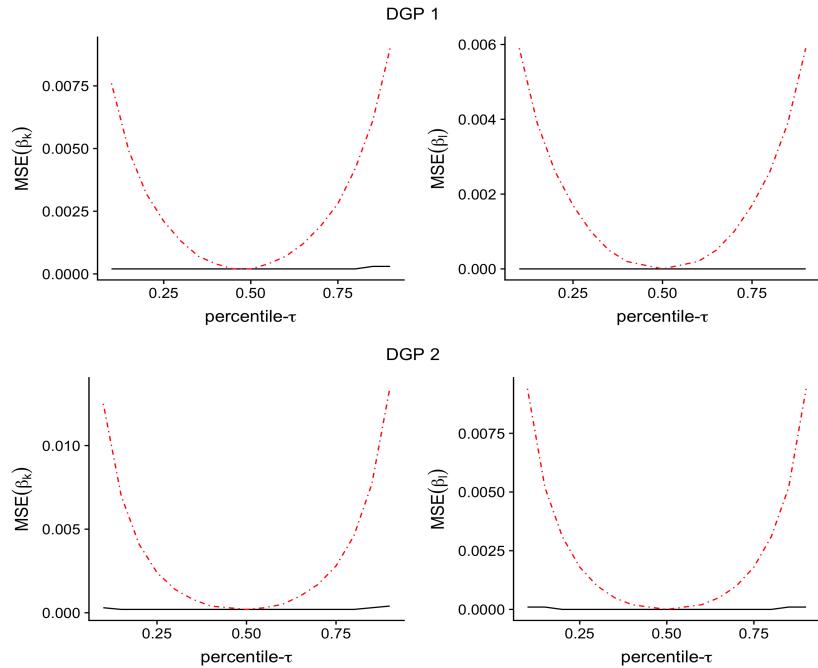


Figure 2: Simulated precision of QLP estimators of $\beta_k(\tau)$ and $\beta_l(\tau)$ s. Dotted line is LP estimator.



5 Application

We apply our estimator to popular firm and plant level manufacturing datasets from the US, Chile, and Colombia to examine heterogeneity in the output distribution⁹. For each country we examine estimates across different manufacturing industries as well as how these estimates have changed over time and the implications for heterogeneity in productivity across small and large firms/plants. We use the QLP estimator presented in this paper and compare it to the LP estimates. We estimate the labor coefficient using a partially regression with a 3rd degree polynomial with interactions in capital and materials. To estimate capital, we use the CUE GMM criterion function mentioned earlier with instruments $k_{it}, k_{it-1}, l_{it-1}$ and m_{it-1} . We initialize the starting values for the non-linear search using quantile regression estimates of $\beta_k(\tau)$. We use bootstrap to estimate standard errors with the number of iterations set to 500. In the first stage we use a weighted bootstrap with weights drawn from a standard exponential distribution re-sampled at each iteration. In the second stage we use a nonparametric bootstrap and recenter sample moments in each iteration.

5.1 US Compustat

The source for the US manufacturing data is from Compustat which covers publicly traded firms and contains data from their financial statements. We collect a sample between 1961 and 2010 on sales, capital expenditures, number of workers, and other expenses to construct measures of output, capital, labor, and material inputs using 3-digit deflators from Bartelsman and Gray (1996). Data preparation follows Keller and Yeaple (2009) and Demirer (2020). Summary statistics for these deflated values are provided in Table 1. We present a series of output elasticity estimates in Table 2 which are illustrated graphically in Figures 3, 4, 5, and 6.

For each industry in the US sample, we see that the estimates of the capital elasticity is increasing in the firm size distribution and decreasing in the labor elasticity corresponding to industries 31 and 32. For industry 33 and the combined industries, the labor elasticity is an inverse U-shape; it increases quickly for low τ , but then flattens out after $\tau = 0.5$.

⁹We thank Mert Demirer for providing the datasets from Chile and Colombia

Table 1: Summary Statistics (in logs) for the US Manufacturing Data

Industry (NAICS code)		1st Qu.	Median	3rd Qu.	Mean	sd
31 (Total=3271)	Output	19.05	20.24	21.57	20.3	1.77
	Capital	18.66	20.37	21.76	20.19	2.12
	Labor	17.42	19.08	20.61	19.02	2.21
	Materials	17.96	19.59	21.15	19.54	2.21
32 (Total=7207)	Output	15.67	17.04	18.51	17.01	2.05
	Capital	15.65	17.51	19.13	17.31	2.41
	Labor	14.44	16.01	17.57	16.01	2.29
	Materials	14.89	16.53	18.25	16.52	2.37
33 (Total=13978)	Output	7.38	8.58	9.8	8.5	1.67
	Capital	6.67	8.29	9.74	8.15	1.95
	Labor	6.01	7.42	8.91	7.48	1.93
	Materials	6.33	7.82	9.29	7.82	1.95
All (Total=24456)	Output	18.58	19.78	21.23	19.85	1.79
	Capital	18.14	19.86	21.26	19.67	2.16
	Labor	16.98	18.59	20.13	18.56	2.17
	Materials	17.49	19.12	20.66	19.06	2.2

Table 2: Coefficient Estimates and Standard Errors for US Manufacturing Firms

Industry (NAICS code)	τ	Capital		Labor		Returns to Scale		Capital Intensity	
		Coef.	s.e.	Coef.	s.e.	Coef.	s.e.	Coef.	s.e.
31	0.10	0.110	0.0226	0.607	0.0311	0.717	0.0320	0.182	0.0419
	0.25	0.151	0.0218	0.543	0.0372	0.694	0.0341	0.277	0.0508
	0.50	0.188	0.0228	0.464	0.0354	0.652	0.0369	0.406	0.0633
	0.90	0.244	0.0366	0.456	0.0452	0.700	0.0489	0.535	0.1185
32	0.10	0.125	0.0184	0.654	0.0497	0.779	0.0453	0.191	0.0326
	0.25	0.122	0.0135	0.605	0.0332	0.727	0.0293	0.201	0.0277
	0.50	0.143	0.0138	0.561	0.0264	0.705	0.0269	0.255	0.0287
	0.90	0.181	0.0239	0.526	0.0307	0.707	0.0357	0.344	0.0545
33	0.10	0.009	0.0307	0.210	0.0598	0.218	0.0592	0.042	0.2655
	0.25	0.063	0.0203	0.354	0.0432	0.417	0.0429	0.177	0.0760
	0.50	0.093	0.0140	0.439	0.0304	0.531	0.0289	0.211	0.0419
	0.90	0.154	0.0178	0.446	0.0287	0.600	0.0260	0.347	0.0536
All	0.10	0.086	0.0208	0.363	0.0420	0.449	0.0505	0.236	0.0630
	0.25	0.119	0.0124	0.411	0.0257	0.531	0.0258	0.291	0.0401
	0.50	0.127	0.0100	0.470	0.0201	0.598	0.0198	0.271	0.0278
	0.90	0.165	0.0135	0.474	0.0179	0.639	0.0183	0.348	0.0361

NAICS 31

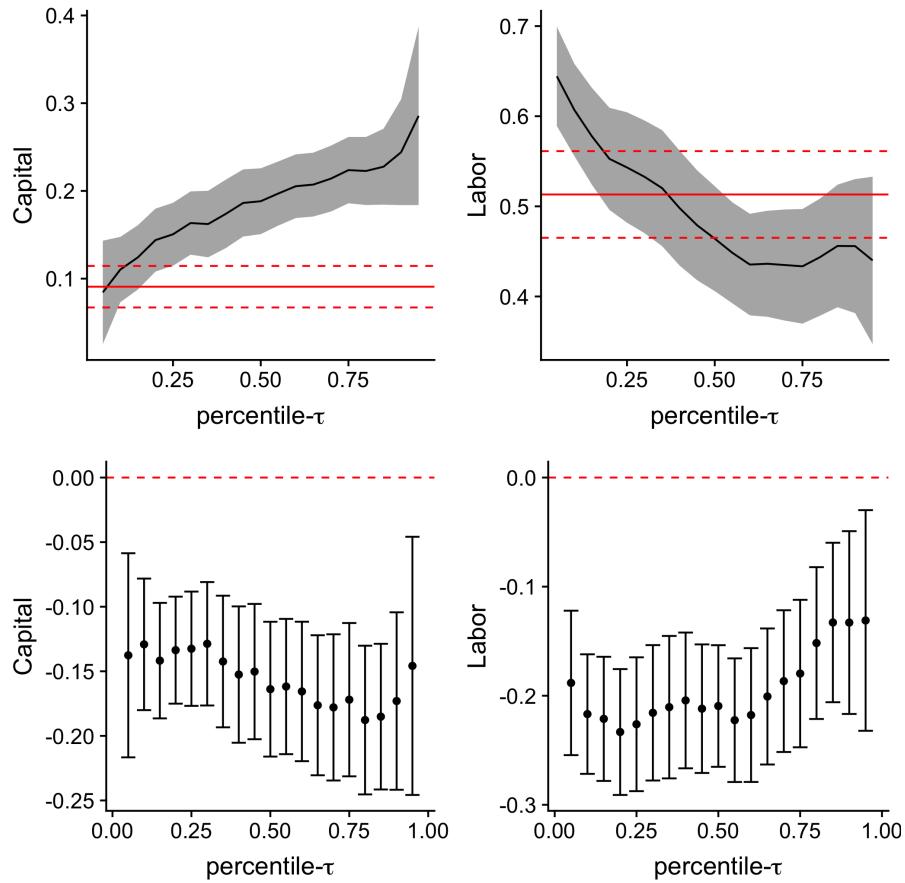


Figure 3: Top row: Estimated values of production function coefficients and their point-wise 90% confidence interval. Bottom row: Difference between QLP and quantile regression estimates and their 95% confidence intervals.

NAICS 32

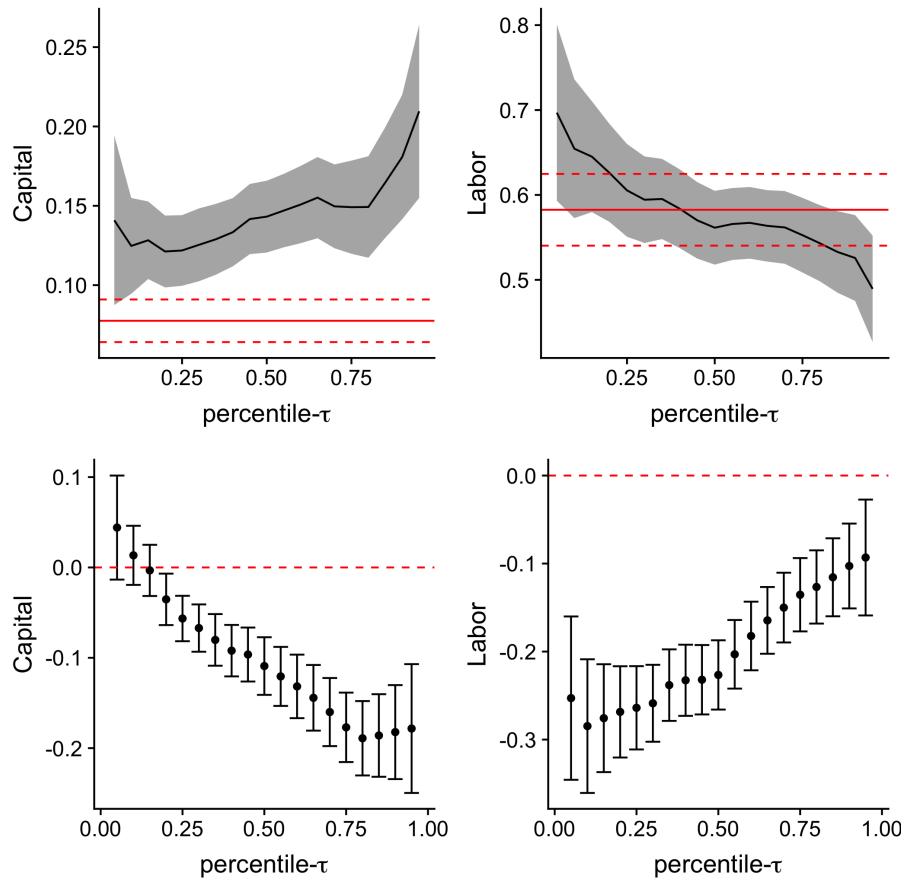


Figure 4: Top row: Estimated values of production function coefficients and their point-wise 90% confidence interval. Bottom row: Difference between QLP and quantile regression estimates and their 95% confidence intervals.

NAICS 33

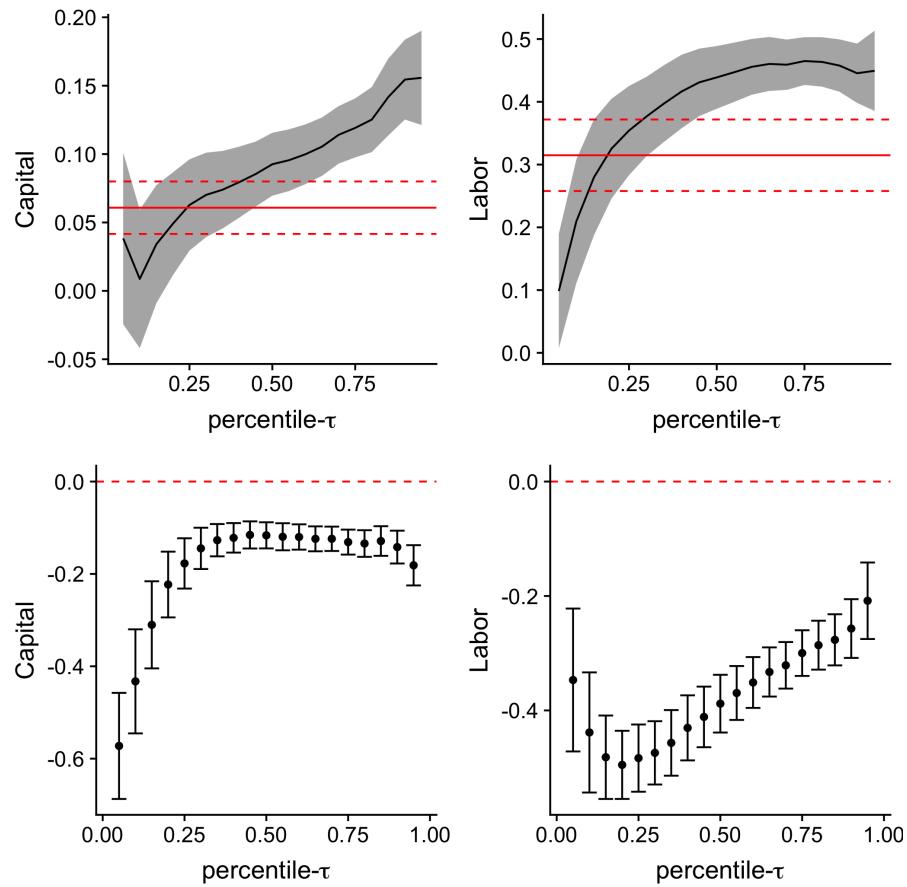


Figure 5: Top row: Estimated values of production function coefficients and their point-wise 90% confidence interval. Bottom row: Difference between QLP and quantile regression estimates and their 95% confidence intervals.

NAICS All

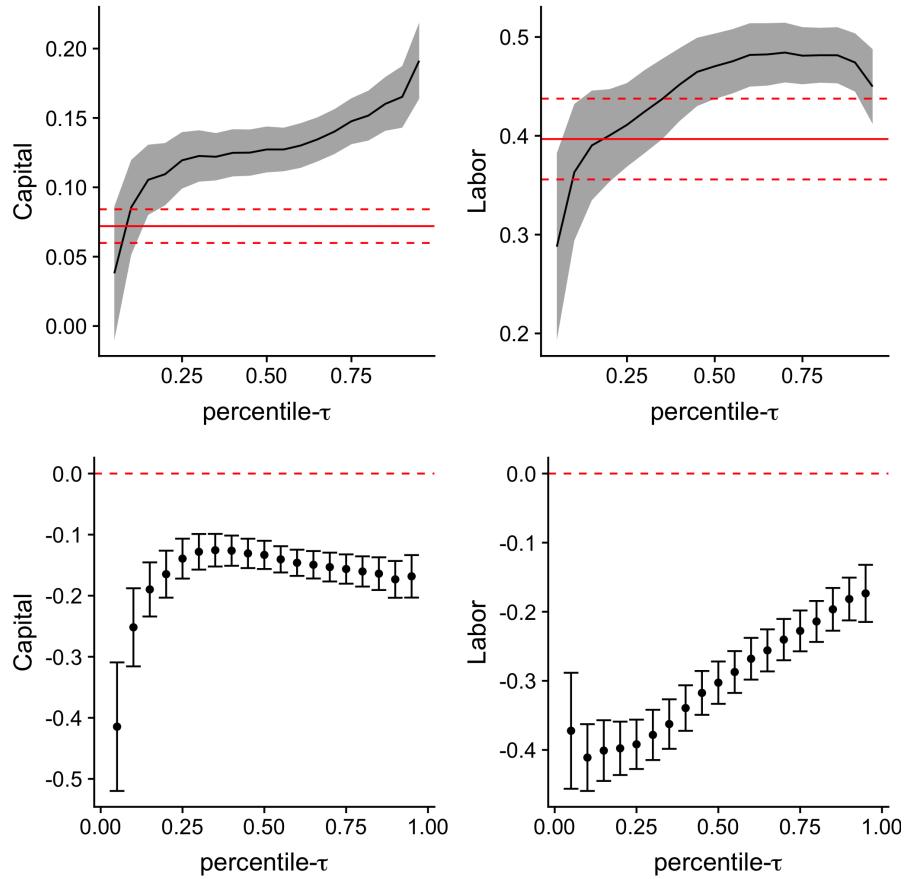


Figure 6: Top row: Estimated values of production function coefficients and their point-wise 90% confidence interval. Bottom row: Difference between QLP and quantile regression estimates and their 95% confidence intervals.

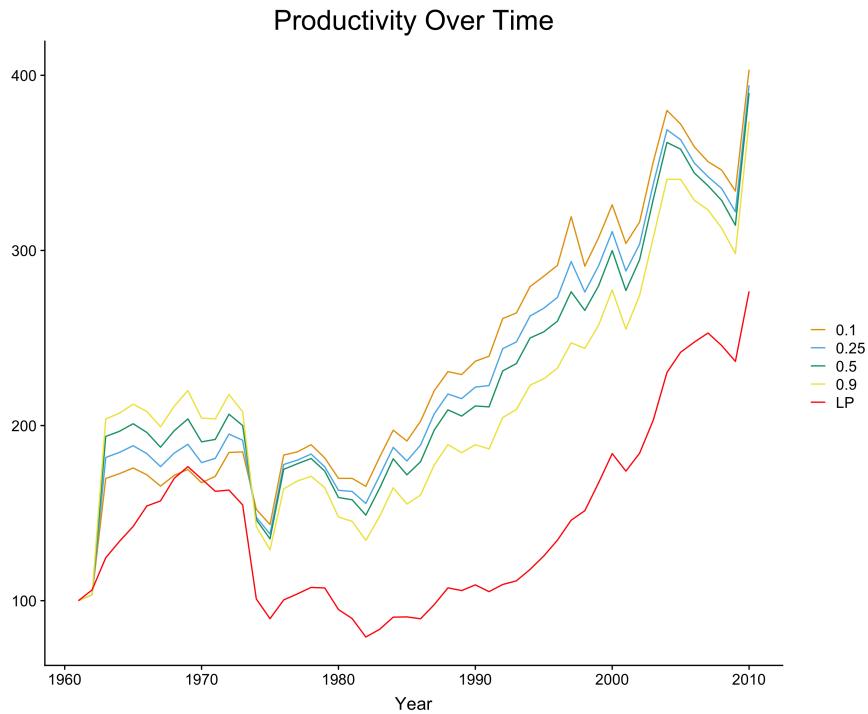


Figure 7: Estimated average TFP over time for the US. Base productivity in 1961 is set to 100.

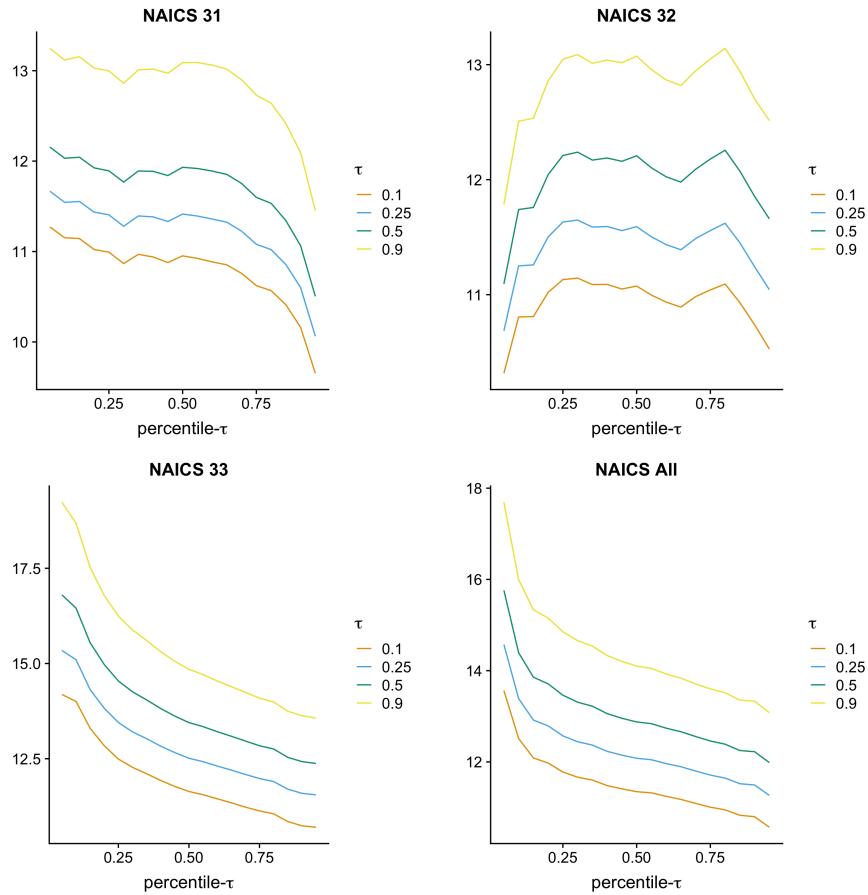


Figure 8: Estimated TFP at different quantiles over the firm-size distribution

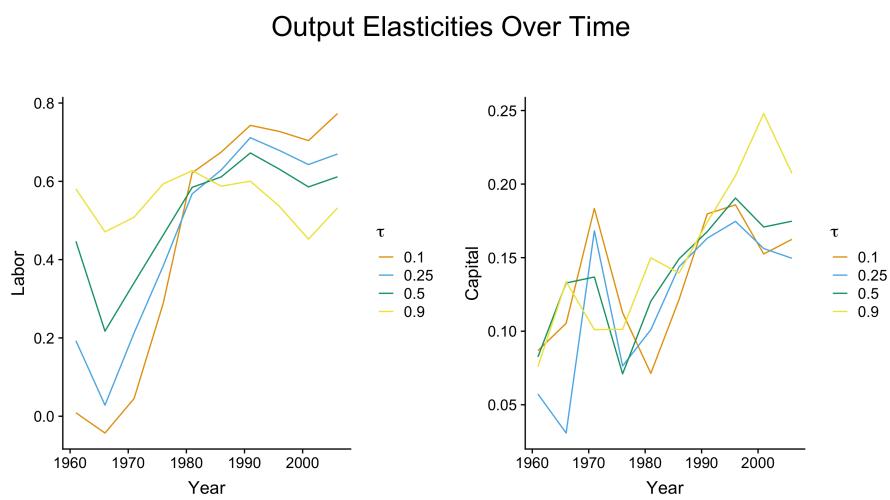


Figure 9: Estimated values of production function coefficients over time estimated at 5 year intervals

5.2 Chilean Manufacturing

Table 3: Summary Statistics (in logs) for Chile Manufacturing Data

Industry (ISIC code)		1st Qu.	Median	3rd Qu.	Mean	sd
311 (Total=13838)	Output	10.21	10.84	12.22	11.36	1.58
	Capital	10.56	11.4	12.4	11.52	1.37
	Labor	10.49	11.4	12.54	11.53	1.43
	Materials	10.38	11.28	12.53	11.56	1.6
381 (Total=4311)	Output	6.69	7.66	9.06	8.02	1.98
	Capital	7.52	8.51	9.7	8.65	1.68
	Labor	7.21	8.34	9.56	8.4	1.72
	Materials	7.22	8.35	9.72	8.54	1.92
321 (Total=4302)	Output	2.77	3.22	3.91	3.49	0.99
	Capital	2.89	3.47	4.22	3.71	1.08
	Labor	2.94	3.48	4.37	3.69	0.95
	Materials	2.89	3.43	4.28	3.67	1.02
All (Total=51567)	Output	9.84	10.46	11.81	10.94	1.56
	Capital	9.91	10.75	11.79	10.86	1.41
	Labor	9.68	10.62	11.75	10.73	1.48
	Materials	9.81	10.68	11.89	10.93	1.62

Table 4: Coefficient Estimates and Standard Errors for Chilean Manufacturing Firms

Industry (ISIC code)	τ	Capital		Labor		Returns to Scale		Capital Intensity	
		Coef.	s.e.	Coef.	s.e.	Coef.	s.e.	Coef.	s.e.
311	0.10	0.442	0.0291	0.380	0.0523	0.823	0.0443	1.163	0.2123
	0.25	0.384	0.0251	0.380	0.0351	0.764	0.0307	1.010	0.1243
	0.50	0.331	0.0211	0.423	0.0263	0.754	0.0267	0.783	0.0845
	0.90	0.300	0.0211	0.444	0.0364	0.744	0.0339	0.674	0.0877
381	0.10	0.367	0.0426	0.774	0.0800	1.141	0.0594	0.474	0.1089
	0.25	0.365	0.0269	0.649	0.0533	1.014	0.0463	0.563	0.0816
	0.50	0.302	0.0260	0.606	0.0431	0.908	0.0384	0.499	0.0813
	0.90	0.272	0.0344	0.503	0.0523	0.775	0.0448	0.541	0.1273
321	0.10	0.352	0.0469	0.677	0.0847	1.029	0.0588	0.520	0.1253
	0.25	0.377	0.0357	0.564	0.0614	0.940	0.0461	0.668	0.1114
	0.50	0.340	0.0289	0.553	0.0484	0.893	0.0369	0.615	0.0961
	0.90	0.323	0.0321	0.538	0.0502	0.861	0.0412	0.601	0.1121
All	0.10	0.437	0.0147	0.522	0.0267	0.959	0.0197	0.837	0.0684
	0.25	0.433	0.0115	0.487	0.0197	0.920	0.0159	0.888	0.0547
	0.50	0.429	0.0099	0.457	0.0158	0.886	0.0134	0.939	0.0484
	0.90	0.433	0.0116	0.391	0.0211	0.824	0.0184	1.105	0.0790

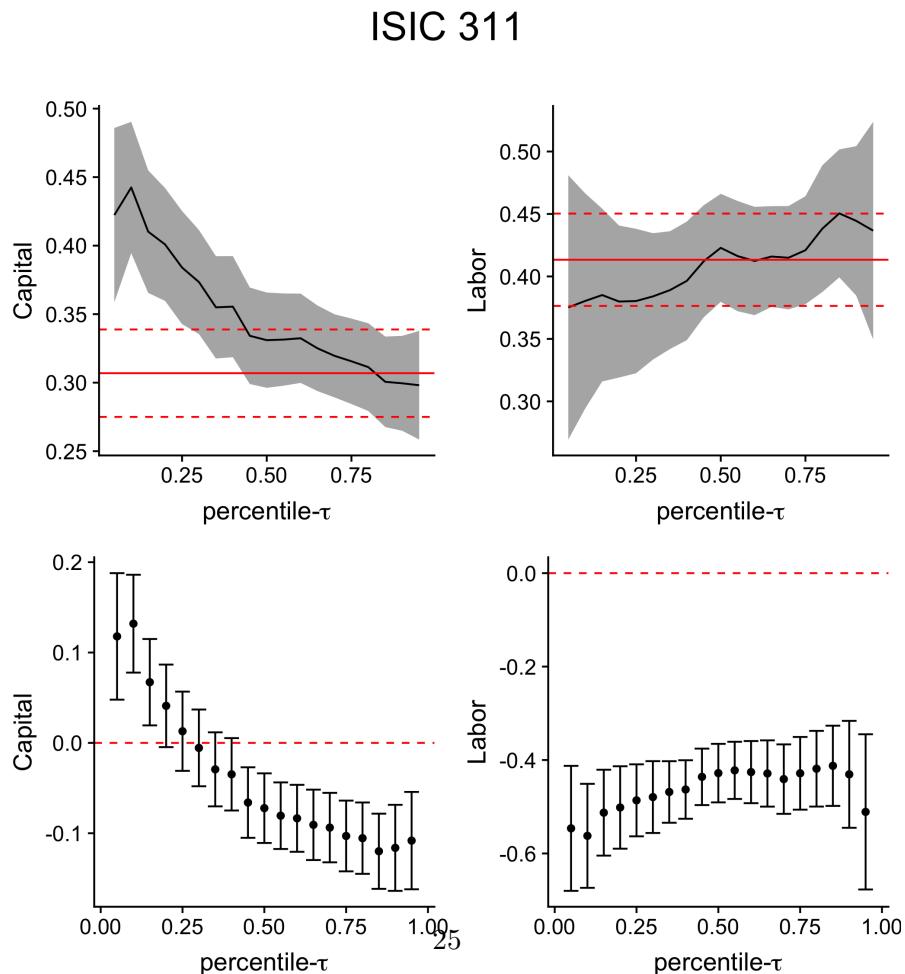


Figure 10: Top row: Estimated values of production function coefficients and their point-wise 90% confidence interval. Bottom row: Difference between QLP and quantile regression estimates and

ISIC 321

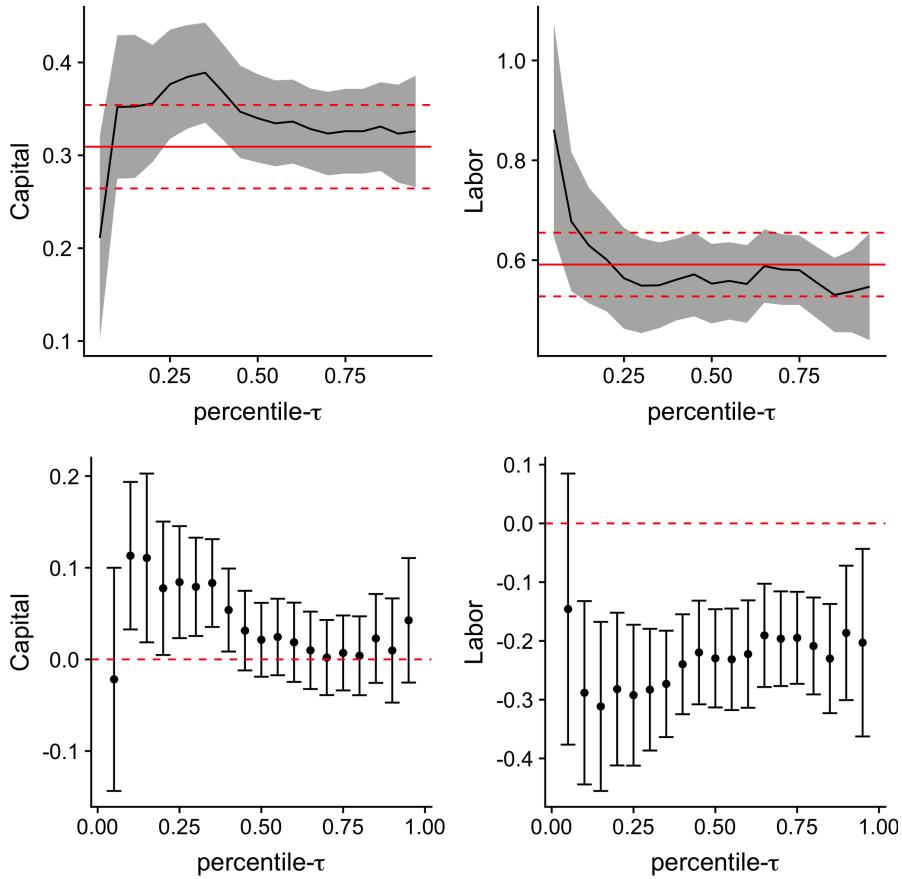


Figure 11: Top row: Estimated values of production function coefficients and their point-wise 90% confidence interval. Bottom row: Difference between QLP and quantile regression estimates and their 95% confidence intervals.

ISIC 381

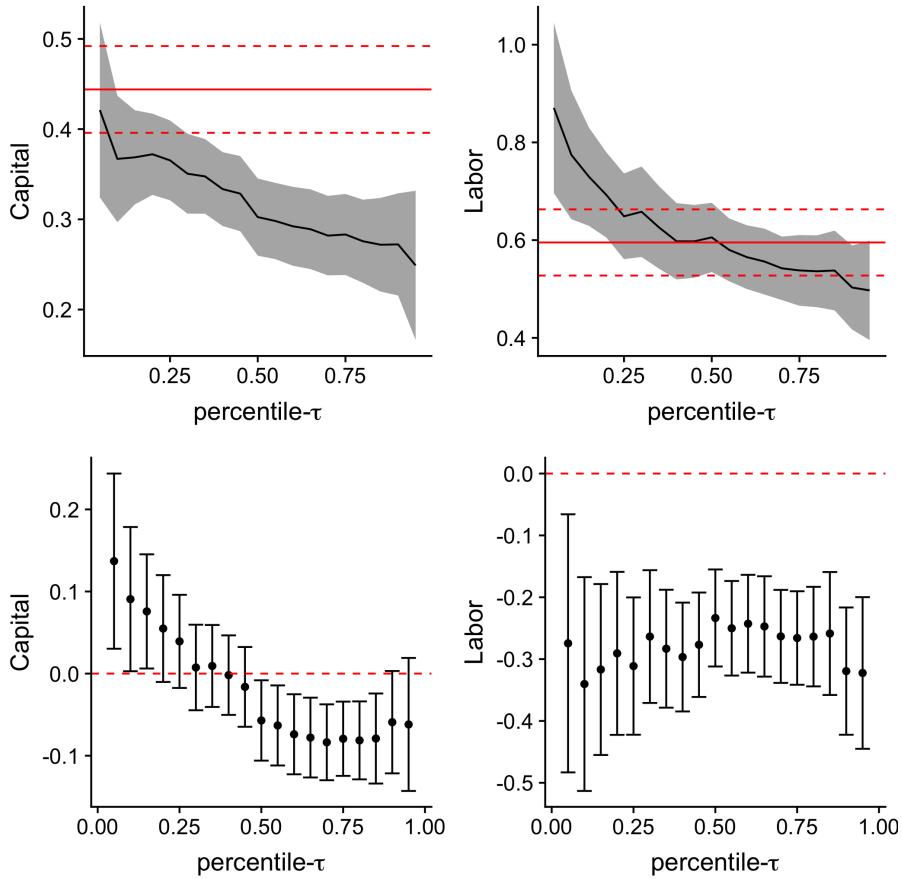


Figure 12: Top row: Estimated values of production function coefficients and their point-wise 90% confidence interval. Bottom row: Difference between QLP and quantile regression estimates and their 95% confidence intervals.

ISIC All

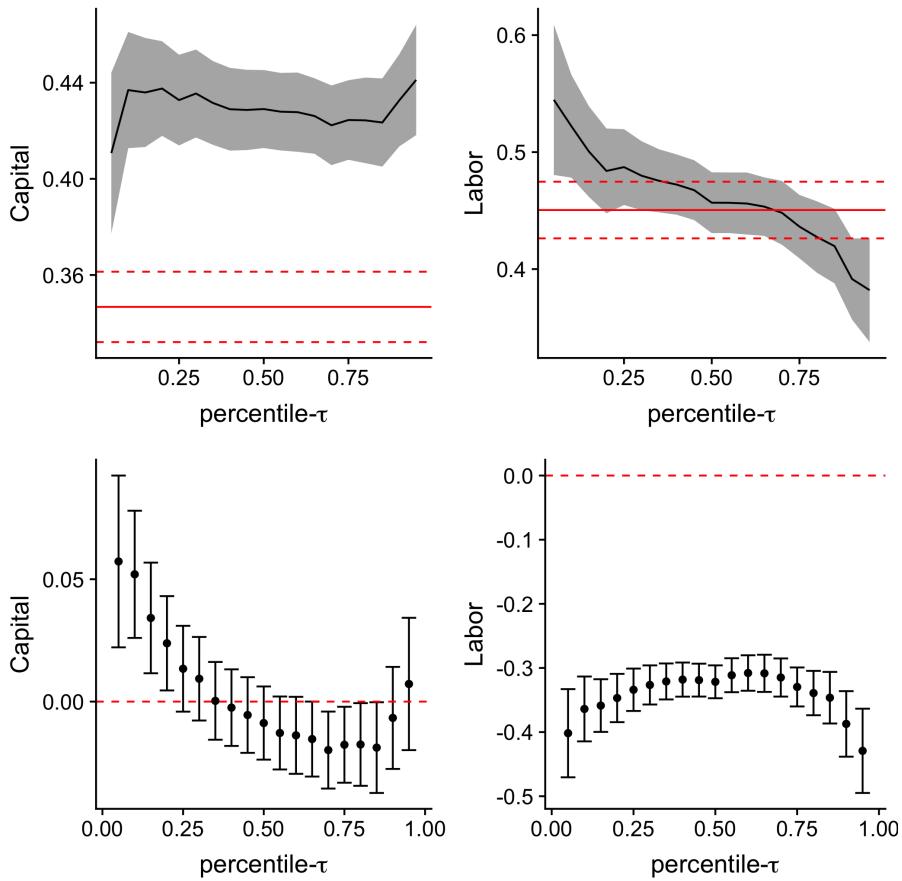


Figure 13: Top row: Estimated values of production function coefficients and their point-wise 90% confidence interval. Bottom row: Difference between QLP and quantile regression estimates and their 95% confidence intervals.

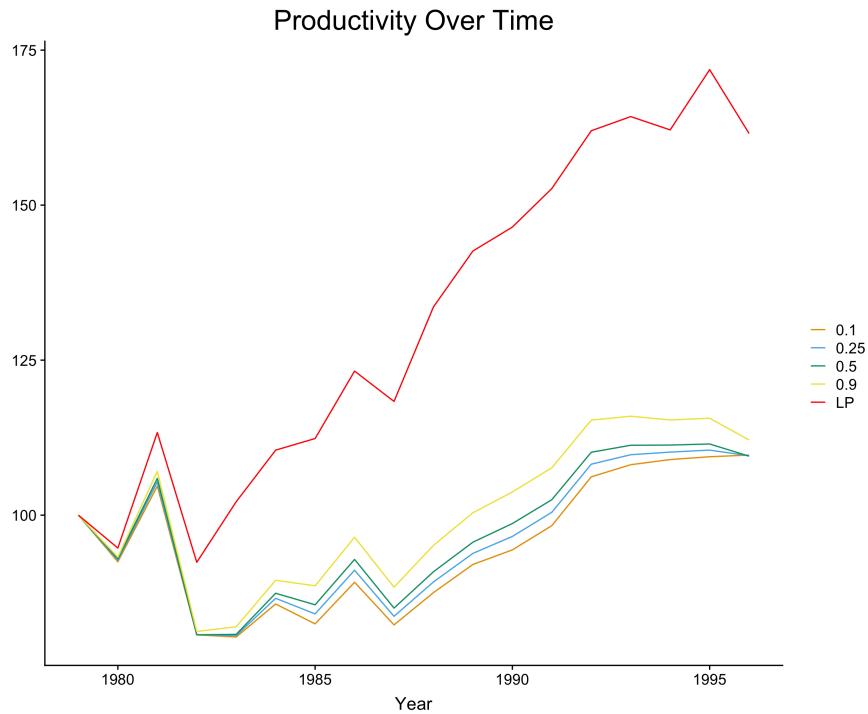


Figure 14: Estimated average TFP over time for Chile. Base productivity in 1979 is set to 100.

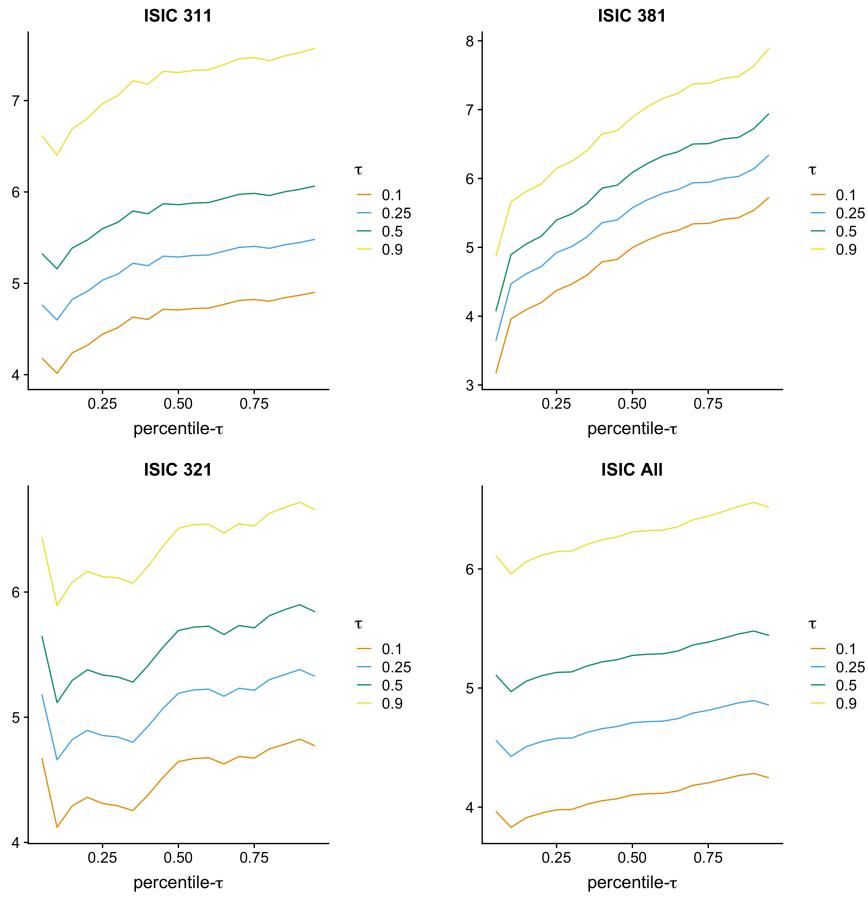


Figure 15: Estimated TFP at different quantiles over the firm-size distribution

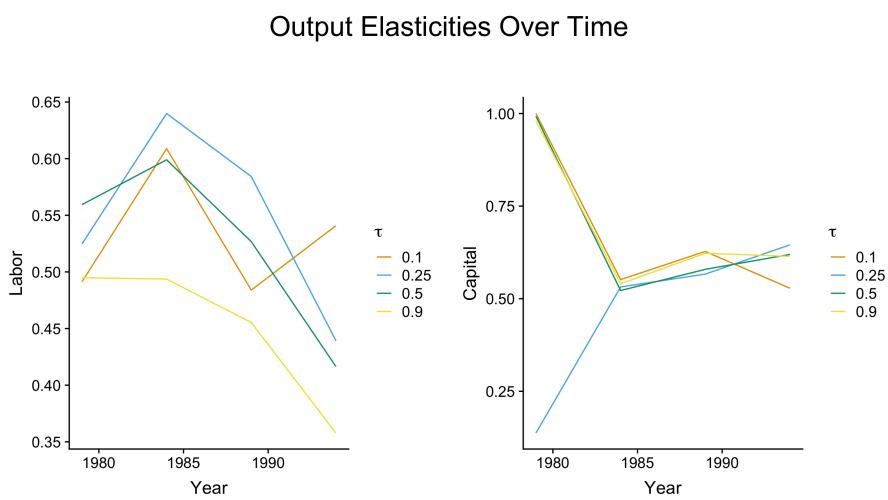


Figure 16: Estimated values of production function coefficients over time estimated at 2 year intervals

5.3 Colombia Manufacturing

Table 5: Summary Statistics (in logs) for Colombia Manufacturing Data

Industry (ISIC code)		1st Qu.	Median	3rd Qu.	Mean	sd
311 (Total=13215)	Output	9.03	10.21	11.59	10.42	1.8
	Capital	8.69	9.37	10.22	9.49	1.18
	Labor	8.52	9.3	10.33	9.54	1.43
	Materials	8.7	9.62	10.88	9.92	1.67
322 (Total=12182)	Output	6.02	7.07	8.35	7.24	1.78
	Capital	5.47	6.14	6.93	6.23	1.21
	Labor	5.89	6.75	7.81	6.93	1.55
	Materials	5.9	6.89	8.16	7.12	1.77
381 (Total=7411)	Output	2.56	3.09	3.97	3.36	1.1
	Capital	2.77	3.3	3.95	3.42	0.92
	Labor	2.64	3.18	3.91	3.37	0.98
	Materials	2.71	3.3	4.11	3.5	1.09
All (Total=87783)	Output	8.39	9.73	11.26	9.87	2
	Capital	7.62	8.53	9.46	8.48	1.51
	Labor	7.77	8.65	9.72	8.8	1.58
	Materials	7.89	8.93	10.26	9.15	1.88

Table 6: Coefficient Estimates and Standard Errors for Colombian Manufacturing Firms

Industry (ISIC code)	τ	Capital		Labor		Returns to Scale		Capital Intensity	
		Coef.	s.e.	Coef.	s.e.	Coef.	s.e.	Coef.	s.e.
311	0.10	0.225	0.0229	0.784	0.0318	1.009	0.0274	0.287	0.0384
	0.25	0.254	0.0209	0.626	0.0214	0.880	0.0222	0.405	0.0422
	0.50	0.281	0.0208	0.529	0.0205	0.811	0.0223	0.531	0.0546
	0.90	0.309	0.0317	0.372	0.0333	0.681	0.0348	0.832	0.1648
322	0.10	0.144	0.0233	0.833	0.0329	0.977	0.0248	0.173	0.0338
	0.25	0.136	0.0191	0.745	0.0292	0.881	0.0225	0.183	0.0319
	0.50	0.174	0.0209	0.639	0.0309	0.813	0.0215	0.272	0.0460
	0.90	0.309	0.0354	0.381	0.0413	0.690	0.0311	0.812	0.1728
381	0.10	0.184	0.0486	1.159	0.0703	1.344	0.0400	0.159	0.0507
	0.25	0.296	0.0295	0.951	0.0379	1.247	0.0268	0.311	0.0428
	0.50	0.343	0.0298	0.743	0.0369	1.086	0.0356	0.462	0.0541
	0.90	0.348	0.0372	0.560	0.0383	0.908	0.0403	0.621	0.1010
All	0.10	0.236	0.0114	0.850	0.0179	1.085	0.0154	0.277	0.0165
	0.25	0.268	0.0083	0.741	0.0118	1.009	0.0095	0.362	0.0157
	0.50	0.299	0.0077	0.641	0.0095	0.940	0.0089	0.466	0.0169
	0.90	0.320	0.0117	0.498	0.0145	0.818	0.0136	0.644	0.0402

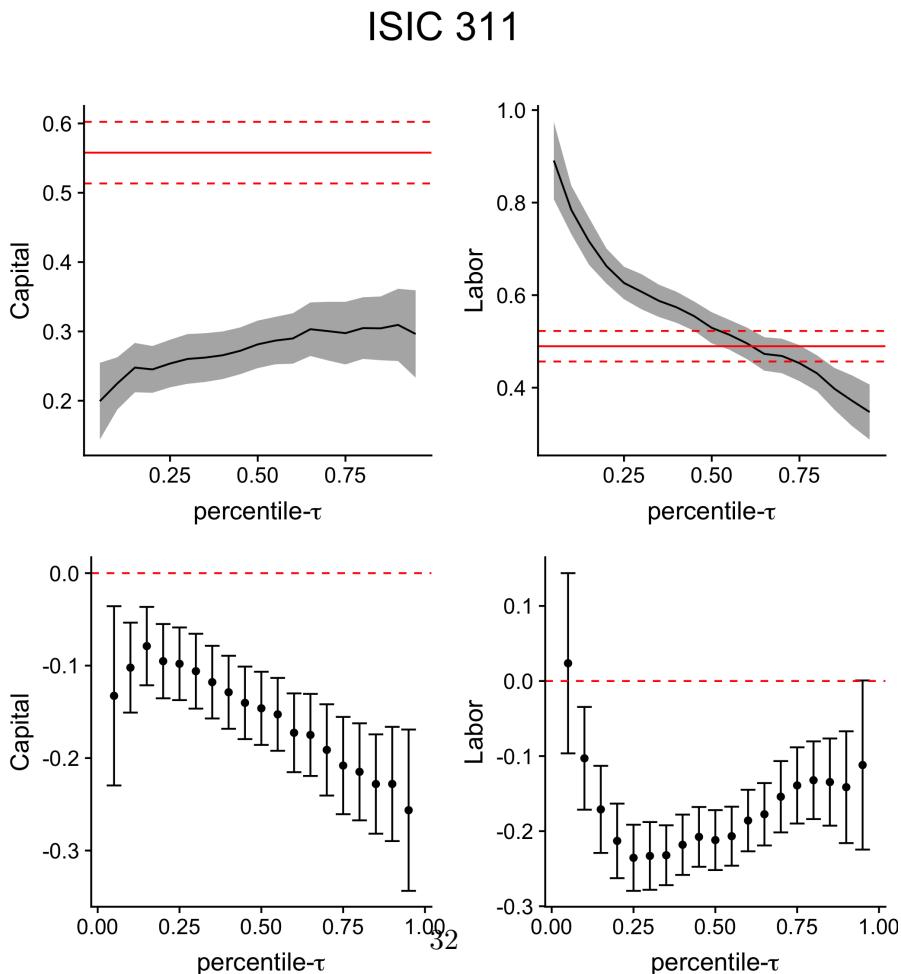


Figure 17: Top row: Estimated values of production function coefficients and their point-wise 90% confidence interval. Bottom row: Difference between QLP and quantile regression estimates and

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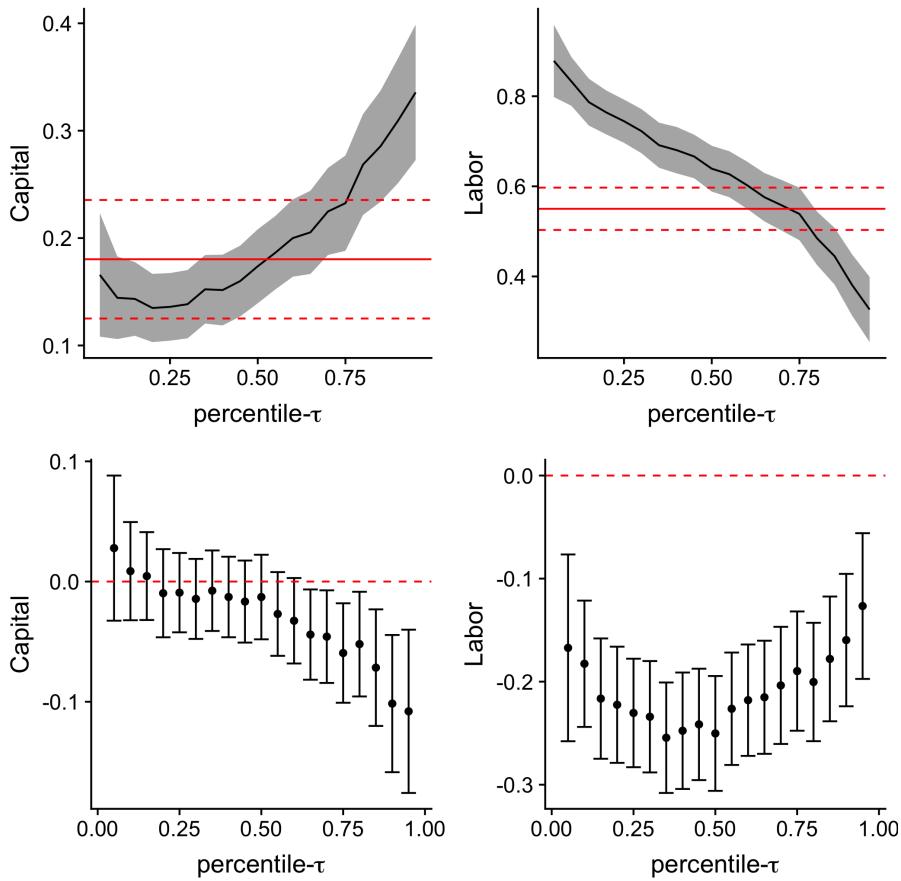


Figure 18: Top row: Estimated values of production function coefficients and their point-wise 90% confidence interval. Bottom row: Difference between QLP and quantile regression estimates and their 95% confidence intervals.

ISIC 381

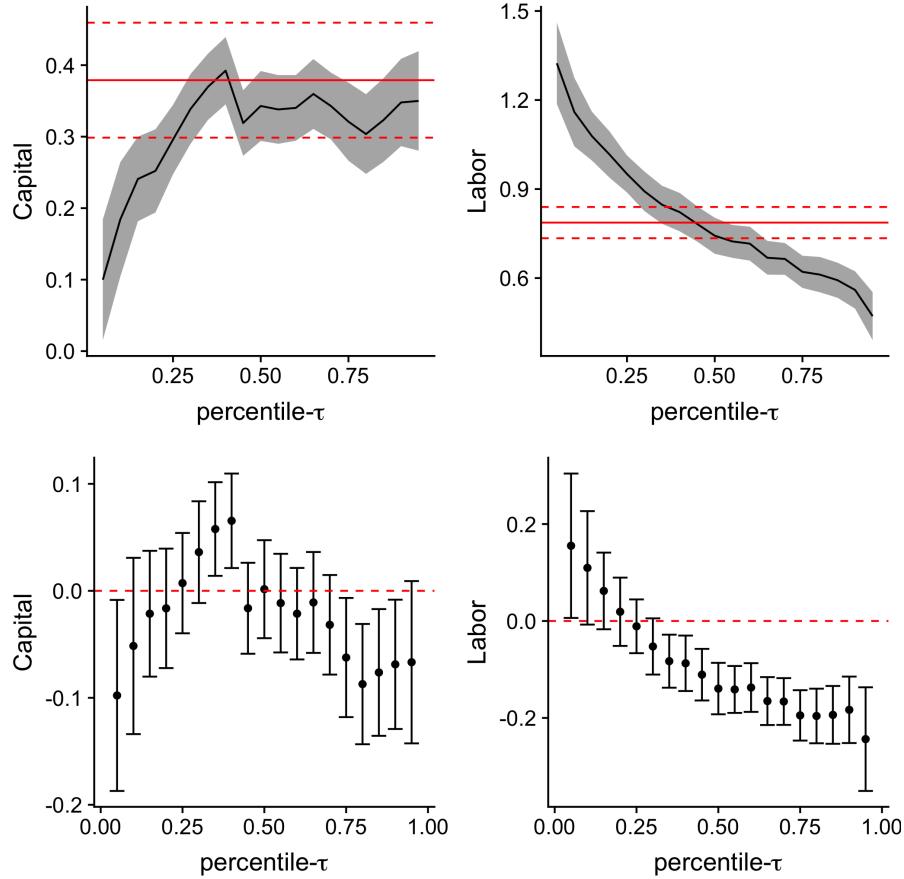


Figure 19: Top row: Estimated values of production function coefficients and their point-wise 90% confidence interval. Bottom row: Difference between QLP and quantile regression estimates and their 95% confidence intervals.

ISIC All

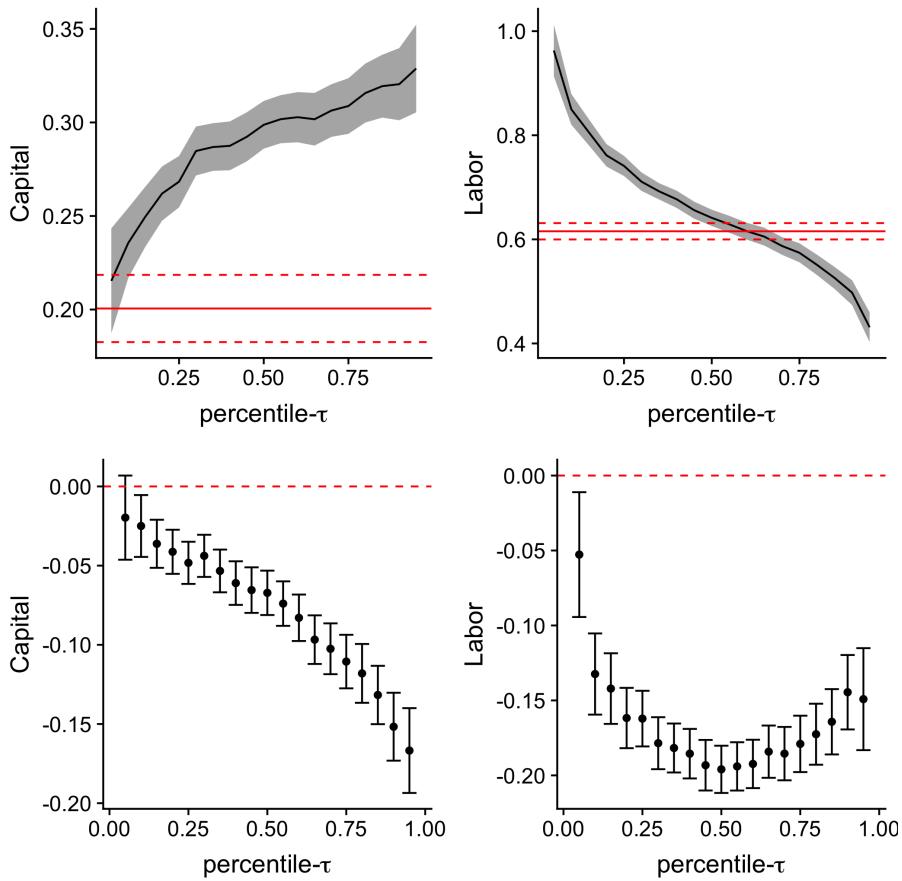


Figure 20: Top row: Estimated values of production function coefficients and their point-wise 90% confidence interval. Bottom row: Difference between QLP and quantile regression estimates and their 95% confidence intervals.

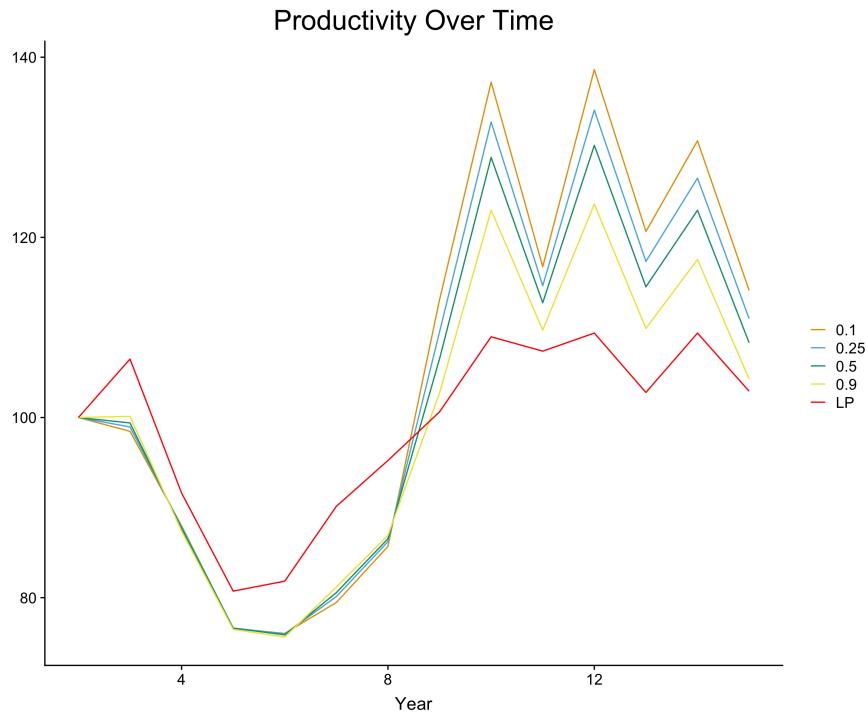


Figure 21: Estimated average TFP over time for Colombia. Base productivity in 1978 is set to 100.

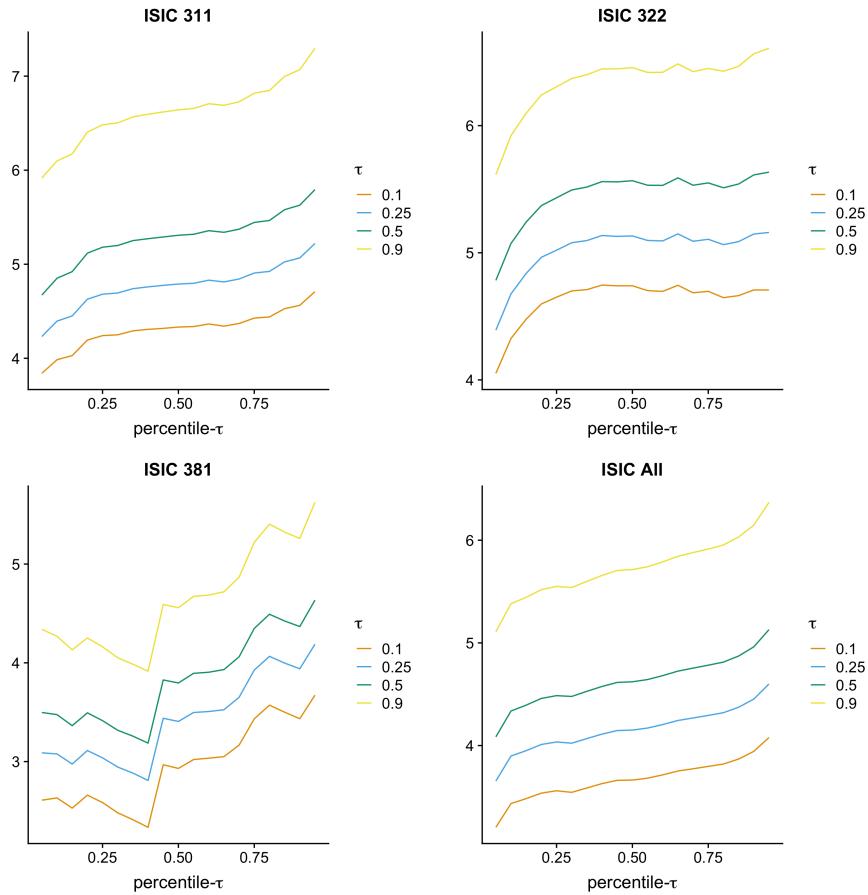


Figure 22: Estimated TFP at different quantiles over the firm-size distribution

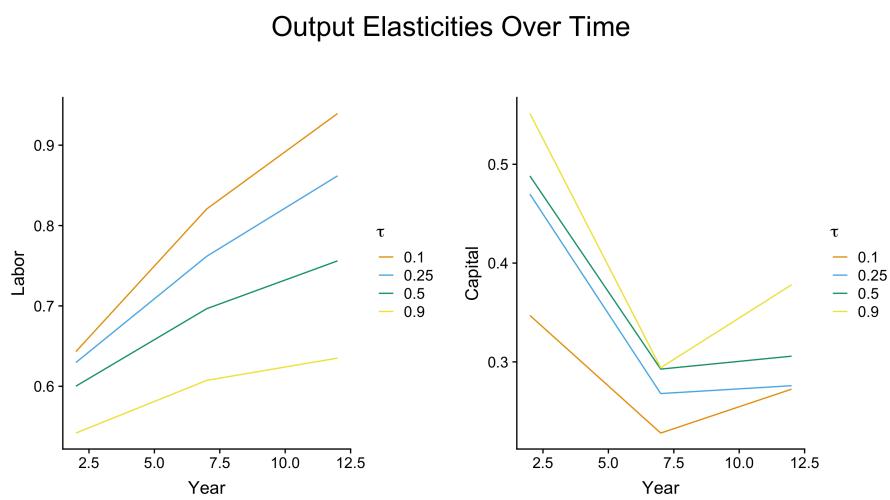


Figure 23: Estimated values of production function coefficients over time estimated at 2 year intervals

6 Conclusions

We proposed a method that extends the intermediate input proxy variable approach to estimating quantiles of the conditional quantiles of firm production. The method is computationally attractive as it resembles the two-stage estimator introduced in the control function literature with conditional quantile restrictions at each stage. As a result, practitioners are able to easily apply the proposed estimator to production function models where the data reveal significant heterogeneous output elasticities along the conditional distribution of firm's output. We showed that this estimator works well in finite samples by replicating the experiment of ACF (2015) and showing that it captures heterogeneity in firm-size under different data generating processes.

Econometric issues with this estimator are currently being explored. A method to consistently estimate the long-run variance of the sample moment conditions to achieve the semi-parametric efficiency bound under general conditions is desired and extending the asymptotic results of de Castro, Galvao, Kaplan and Liu (2018) might not be straightforward. We also seek to estimate and interpret the resulting estimates of total factor productivity. Once these are addressed, an application using data such as the Chilean firm-level data may reveal heterogeneity in production technology along the distribution of firm output. We leave them as future research agenda.

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