

# Lec. 11: Approximation Algorithms

# Outline

- Approximation Algorithms
  - Load Balancing
  - Bin Packing
  - Center Selection
- Maximum Weighted Cut
- Maximum Coverage
- Weighted Vertex Cover
- Metric Travelling Salesman Problem
- Knapsack Problem

## NP-hard optimization problems

Q. Suppose I need to solve an NP-hard problem. What should I do?

A. Theory says you're unlikely to find a poly-time algorithm.

Must sacrifice **one** of three desired features.

- **Solve problem to optimality.**
- Solve problem in poly-time.
- Solve arbitrary instances of the problem.

# Approximation algorithms

Key: **provably** close to optimal.

*OPT*: the value of an optimal solution,  
*SOL*: the value of the solution that our algorithm returned.

## Additive approximation algorithms:

- $SOL \leq OPT + c$  for a minimization problem
- $SOL \geq OPT - c$  for a maximization problem

## Multiplicative approximation algorithms:

- $SOL \leq c \cdot OPT$  for a minimization problem
- $SOL \geq OPT/c$  for a maximization problem

**Challenge.** Need to prove a solution's value is close to optimum, without even knowing what optimum value is!

## Time-accuracy tradeoff

**Def.** An algorithm  $A$  is a **PTAS** (Polynomial-Time Approximation Scheme) if for every  $\epsilon > 0$ ,  $A$  runs in polynomial time (which may depend on  $\epsilon$ ) and return a  $(1 + \epsilon)$ -approximate solution

- For example,  $A$  may run in time  $n^{100/\epsilon}$ .

**Def.** An algorithm  $A$  is a **FPTAS** (fully PTAS) if for every  $\epsilon > 0$ ,  $A$  runs in time  $\text{poly}(n, 1/\epsilon)$  and return a  $(1 + \epsilon)$ -approximate solution

# 1. Load Balancing

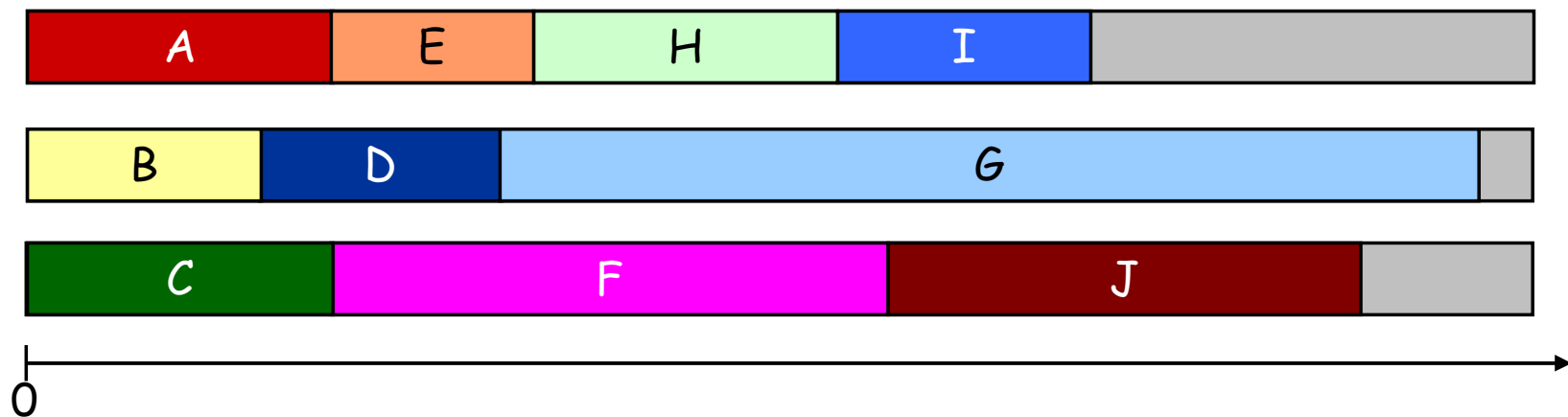
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# Load Balancing

**Input.**  $m$  identical machines;  $n > m$  jobs, job  $j$  has processing time  $t_j$ .

Job scheduling:

- Each job must run **contiguously** on one machine.
- A machine can process at most one job at a time.



**load** of machine  $i$  is  $L_i = \text{sum process times of jobs assigned to machine } i$

**makespan**  $L = \max_i L_i$ .

**Load balancing.** Assign each job to a machine to minimize makespan.

## List scheduling algorithm

Consider  $n$  jobs in some fixed order (i.e. list).  
Assign job  $j$  to machine whose load is **smallest** so far.

**Thm.** [Graham 1966] LS algorithm is a 2-approximation.

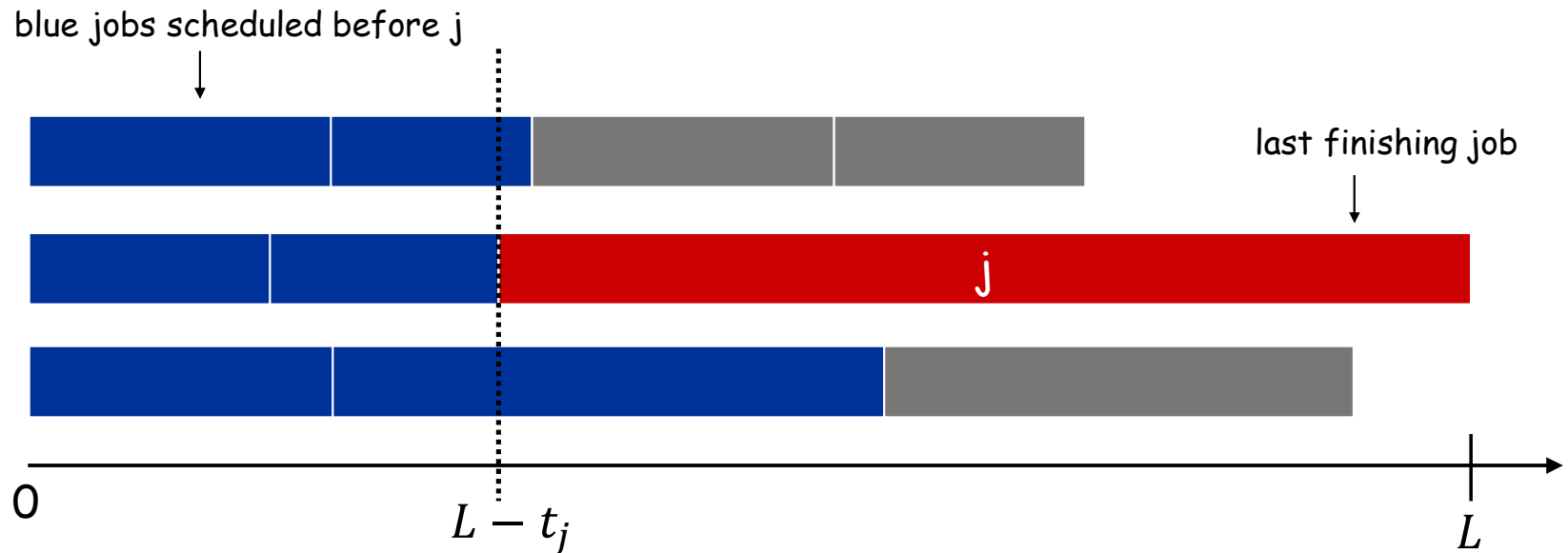
- ❖ **First** worst-case analysis of an approximation algorithm.
- ❖ Need to compare resulting solution with optimal makespan  $L^*$ .

**Lem.**  $L^* \geq \max\{\max_{1 \leq j \leq n} t_j, \frac{1}{m} \sum_{j=1}^n t_j\}$ .



# List scheduling analysis

**Thm.** LS algorithm is a 2-approximation.



**Pf.**  $j$ 's starting time  $L - t_j$  = **least load** of machines at this time  
 $\leq \frac{1}{m} \sum_{i=1}^{j-1} t_i \leq L^* - \frac{1}{m} t_j$

Thus,

$$L \leq L^* + \left(1 - \frac{1}{m}\right) t_j \leq L^* + \left(1 - \frac{1}{m}\right) L^* = \left(2 - \frac{1}{m}\right) L^*$$

## Tight instance

Q. Is our analysis tight?

A. Essentially yes.

Ex:  $m$  machines,  $m(m-1)$  jobs length 1 jobs, one job of length  $m$

$m = 10$

										machine 2 idle
										machine 3 idle
										machine 4 idle
										machine 5 idle
										machine 6 idle
										machine 7 idle
										machine 8 idle
										machine 9 idle
										machine 10 idle

list scheduling makespan = 19

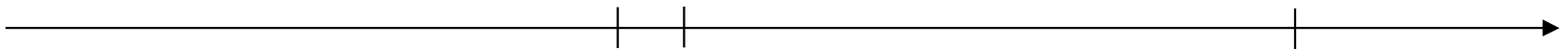
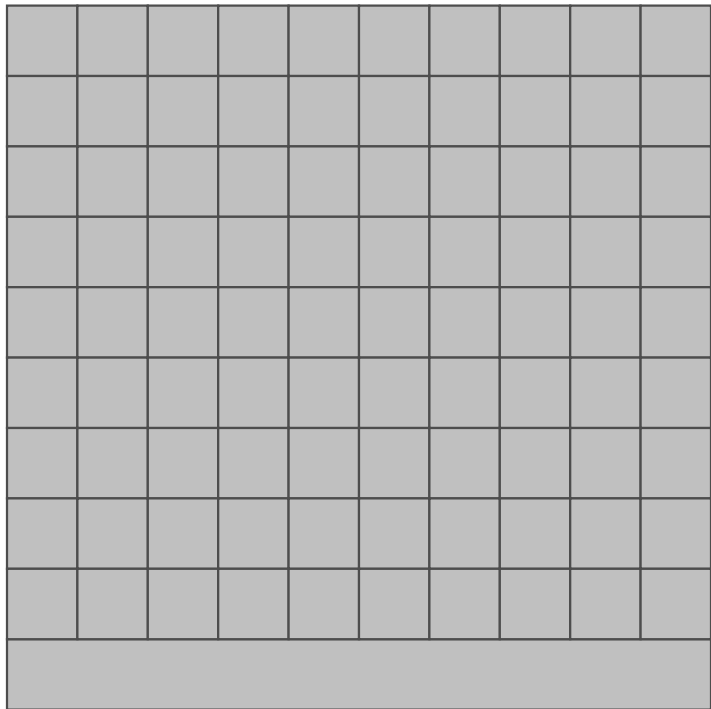
## Tight instance

Q. Is our analysis tight?

A. Essentially yes.

Ex:  $m$  machines,  $m(m-1)$  jobs length 1 jobs, one job of length  $m$

$m = 10$



optimal makespan = 10

## LPT Rule

**Rationale:**  $L \leq L^* + \left(1 - \frac{1}{m}\right) t_j$

- place the shorter jobs more towards the end of the schedule, where they can be used for **finer** load balancing.

**Longest processing time (LPT).** Sort  $n$  jobs in **descending** order of processing time, and then run list scheduling algorithm.

**Observation.** The first  $m$  jobs are put on  $m$  different machines

## LPT Rule: simple analysis

**Lem.**  $L^* \geq 2t_{m+1}$ .

**Pf.** Among the first  $m + 1$  jobs, at least two are in the same machine ▀

**Thm.** LPT rule is a  $3/2$  approximation algorithm.

**Pf.** If the last-finishing job  $j \leq m$ , then  $L = L^*$ .

Otherwise

$$L \leq L^* + \left(1 - \frac{1}{m}\right)t_j \leq L^* + \frac{1}{2}\left(1 - \frac{1}{m}\right)L^* = \left(\frac{3}{2} - \frac{1}{m}\right)L^*$$

## LPT Rule: tighter analysis

Q. Is our  $3/2$  analysis tight?

A. No.

Thm. [Graham 1969] LPT rule is a  $4/3$ -approximation.

Pf. exercise.

Q. Is Graham's  $4/3$  analysis tight?

A. Essentially yes.

Tight instance: exercise

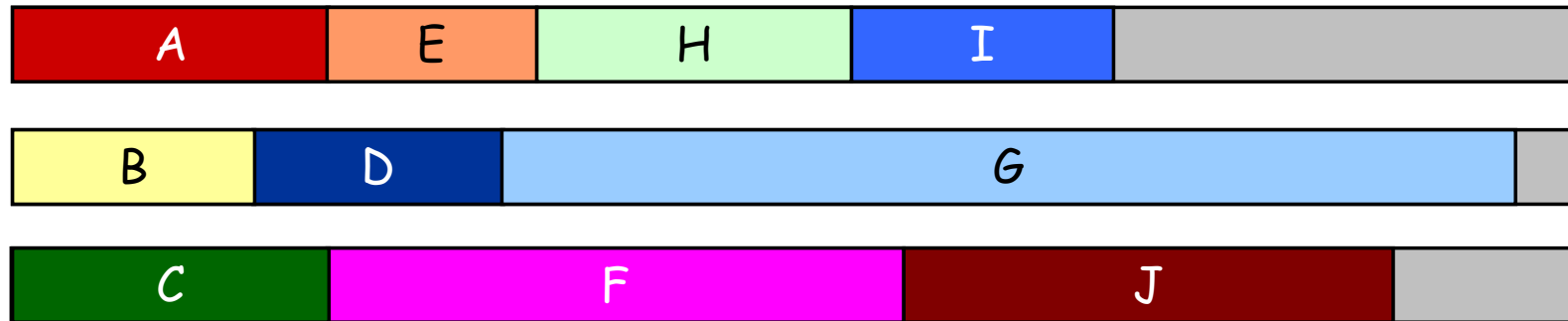
## 2. Bin Packing

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# Bin Packing

**Input:**  $n$  jobs, job  $j$  has processing time  $t_j \leq 1$ .

**Packing:** A partition of the jobs into groups of total load  $\leq 1$ . Each group corresponds to a **bin** (machine)



**Bin packing:** Find a partition with fewest groups (bins).

NP-complete to **approximate** within a factor less than  $3/2$ !



## Lower bound on optimum

$B^*$ : minimum number of bins

$L$ : the set of “long” jobs with processing time  $> 1/2$

**Observation.**  $B^* \geq \max\{\lceil \sum_j t_j \rceil, |L|\}$ .

## First-Fit (FF) algorithm

Put items in some fixed list (order), and for each job in the list:

- If the job fits into one of the currently open bins, then put it in the **first** of these bins.
- Otherwise, open a new bin and put the new job in it.

**Key property.** Among all open bins, all but one are more than **half**-full.

**Thm.** FF algorithm is a 2-approximation.

**Pf.** If  $B > 2B^*$ , then total load  $> (2B^*)/2 = B^* \geq \lceil \sum_j t_j \rceil$ .

## First-Fit Decreasing (FFD) algorithm

**FFD:** Sort jobs in **decreasing order** of  $t_j$ , and then run FF algorithm.

**Thm.** FFD algorithm is a  $3/2$ -approximation.

**Pf.**  $k := \left\lceil \frac{2}{3}B \right\rceil$  and it is sufficient to show  $k \leq \max\{|L|, \lceil \sum_j t_j \rceil\}$ .

Assume  $k > |L|$ , and  $S :=$  jobs in the bins  $k, k+1, \dots, B$ .

- Each job in  $S$  is short and doesn't fit any of the first  $k-1$  bins.
- $|S| \geq 2(B-k) + 1 \geq k-1$

Pair up  $k-1$  jobs in  $S$  with the first  $k-1$  bins.

Each pair has total load  $> 1$ , and the total load of all pairs  $> k-1$ .

$$k-1 < \sum_j t_j \Rightarrow k \leq \lceil \sum_j t_j \rceil$$

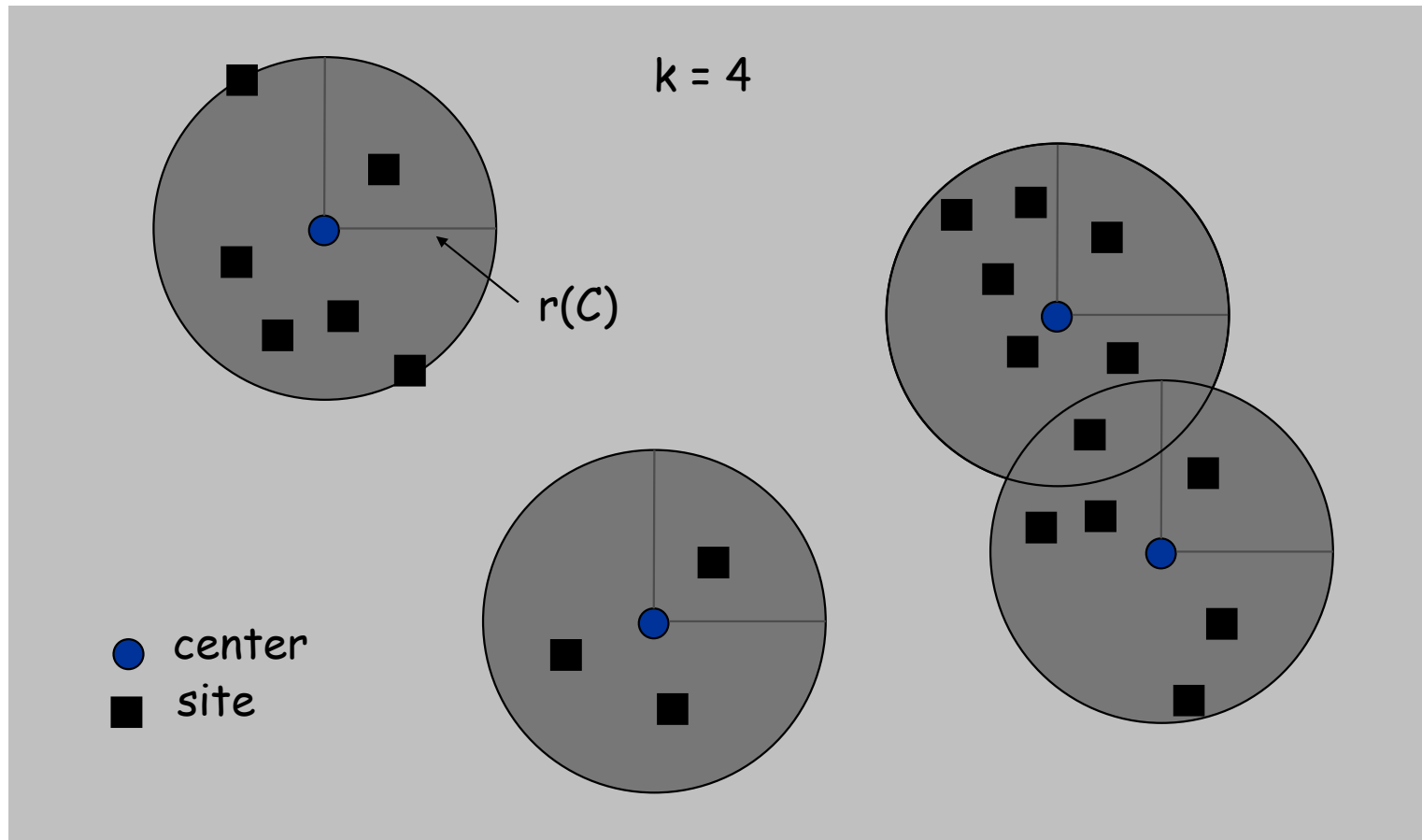
### 3. Center Selection

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# Center Selection Problem

**Input.**  $n$  sites  $s_1, \dots, s_n$ .

**Center selection problem.** Select  $k$  centers  $C$  so that maximum distance from a site to nearest center is minimized.



# Center Selection Problem: metric distances

## Notation.

- $\text{dist}(x, y)$  = distance between  $x$  and  $y$ .
- $\text{dist}(s_i, C) = \min_{c \in C} \text{dist}(s_i, c)$  = distance from  $s_i$  to **closest** center.
- $r(C) = \max_i \text{dist}(s_i, C)$  = smallest covering radius.

**Goal.** Find set of centers  $C$  that minimizes  $r(C)$ , subject to  $|C| = k$ .

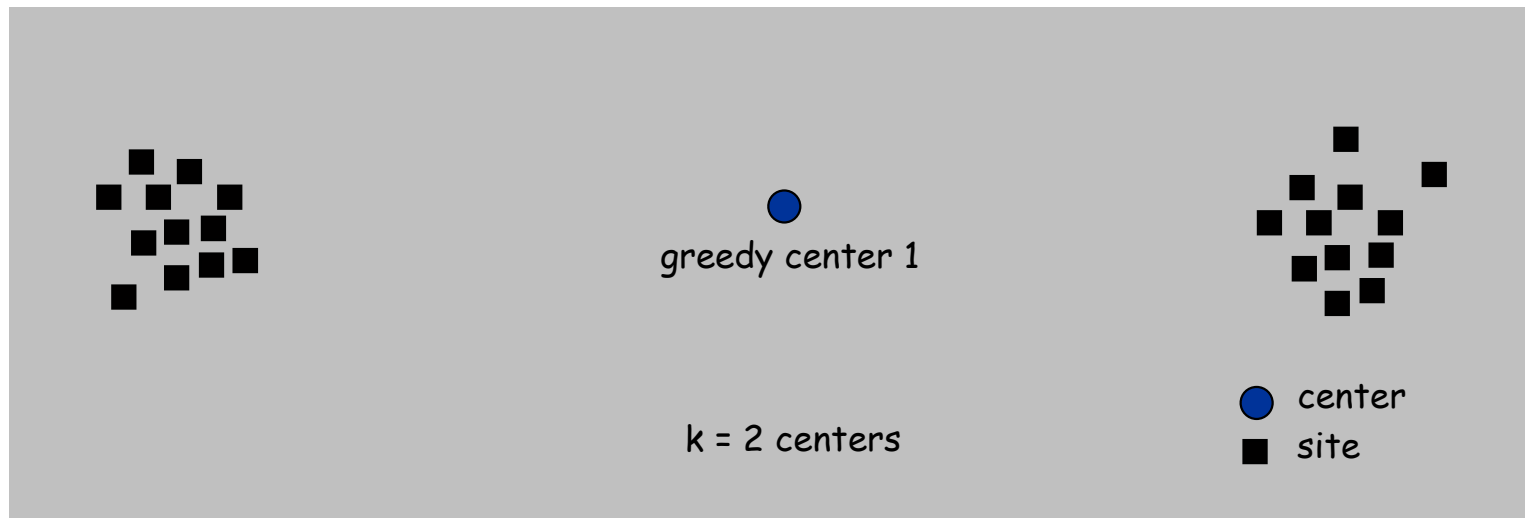
## Metric Distance:

- $\text{dist}(x, x) = 0$  (identity)
- $\text{dist}(x, y) = \text{dist}(y, x)$  (symmetry)
- $\text{dist}(x, y) \leq \text{dist}(x, z) + \text{dist}(z, y)$  (triangle inequality)

## Greedy algorithm: a false start

- Put the first center at the **best** possible location for a single center
- Keep adding centers so as to reduce the covering radius each time by as much as possible.

Remark: arbitrarily bad!



## Greedy algorithm

- Place the first center at an arbitrary given site, and
- repeatedly place the next center at the (the most dissatisfied) site farthest from any existing center.

```
C = {s1}  
repeat k-1 times  
    Select a site si with maximum dist(si, C)  
    Add si to C  
return C
```

↑  
site farthest from any center

**Observation.** All centers in  $C$  are pairwise at least  $r(C)$  apart.

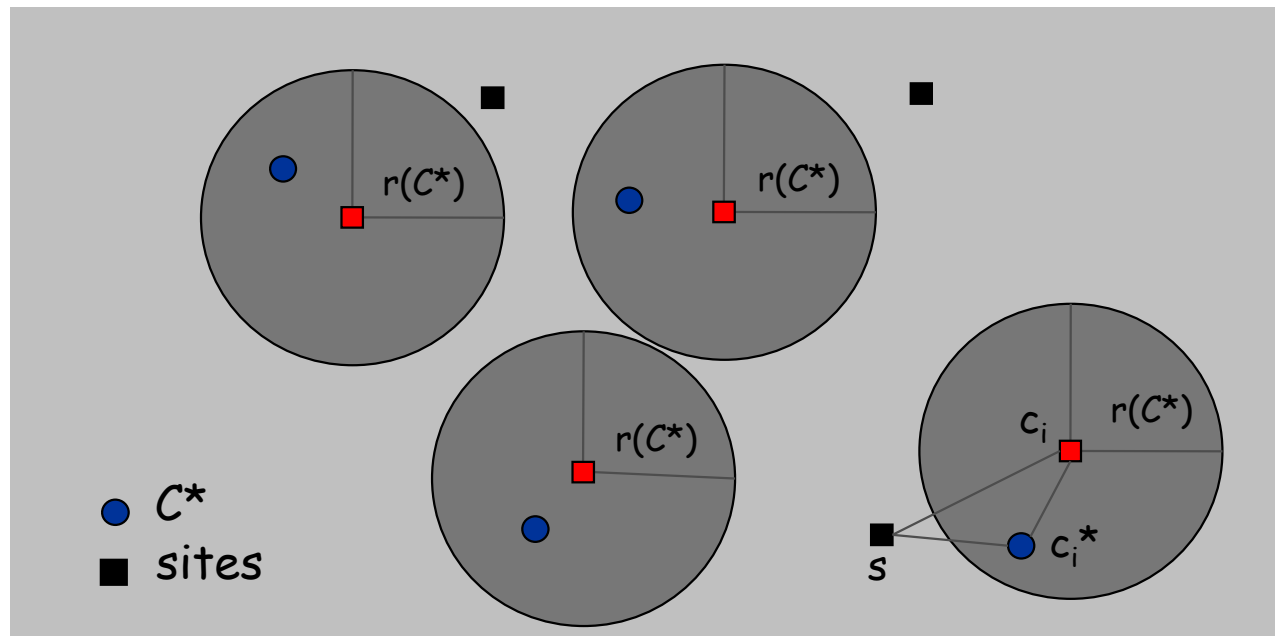


## Analysis of greedy algorithm

**Thm.** Let  $C^*$  be an optimal set of  $k$  centers. Then  $r(C) \leq 2r(C^*)$ .

**Pf.** (by contradiction) Assume  $r(C^*) < \frac{1}{2} r(C)$ .

- The  $k$  disks centered at  $C$  of radius  $r(C^*)$  are **disjoint**.
- **Exactly one** optimal center  $c_i^*$  in each disk;
- Let  $c_i$  be the center of the disk containing  $c_i^*$ .
- For any site  $s$  and its closest center  $c_i^*$  in  $C^*$ ,  
$$\text{dist}(s, C) \leq \text{dist}(s, c_i) \leq \text{dist}(s, c_i^*) + \text{dist}(c_i^*, c_i) \leq 2r(C^*).$$
- Thus  $r(C) \leq 2r(C^*)$ . ▀



## Approximation hardness

**Thm.** Greedy algorithm is a 2-approximation for center selection problem.

**Q.** Is there hope of a  $3/2$ -approximation?  $4/3$ ?

**Thm.** Unless  $P = NP$ , there is **no**  $\rho$ -approximation for center-selection problem for any  $\rho < 2$ .

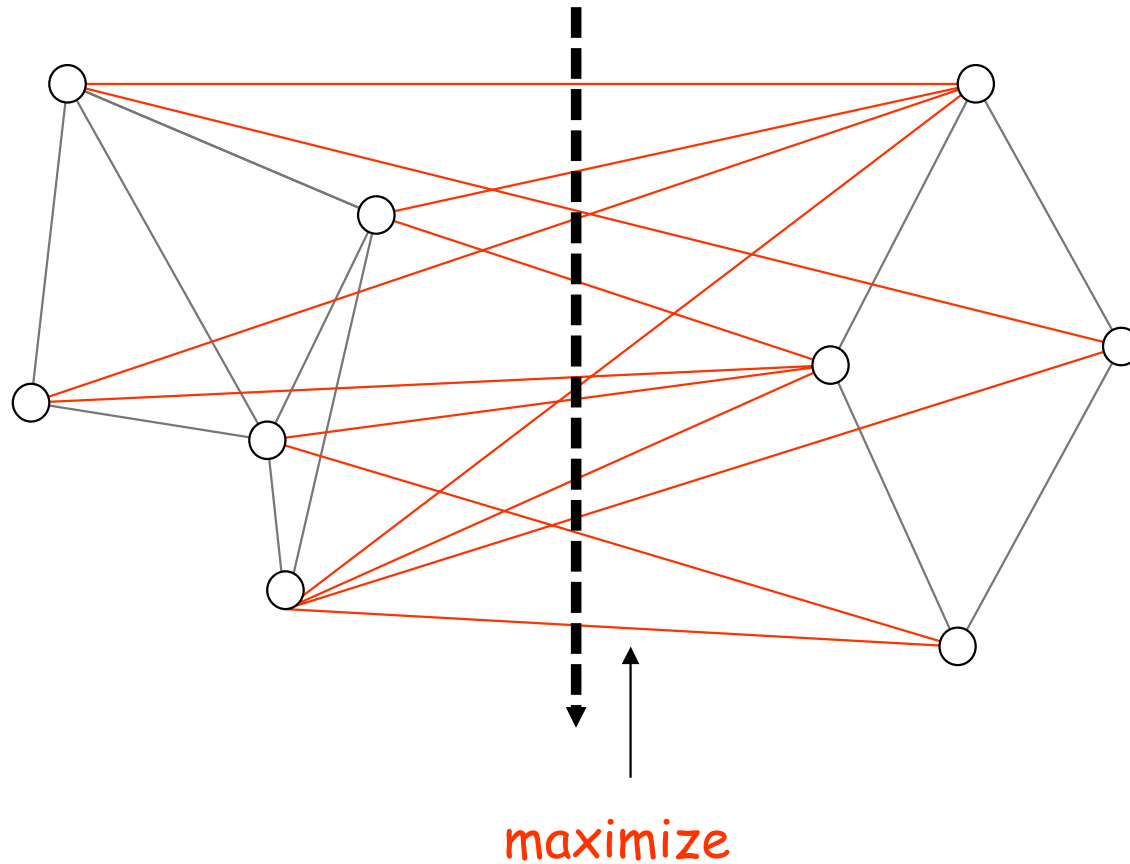
## 4. Maximum Weighted Cut

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# Maximum Weighted Cut

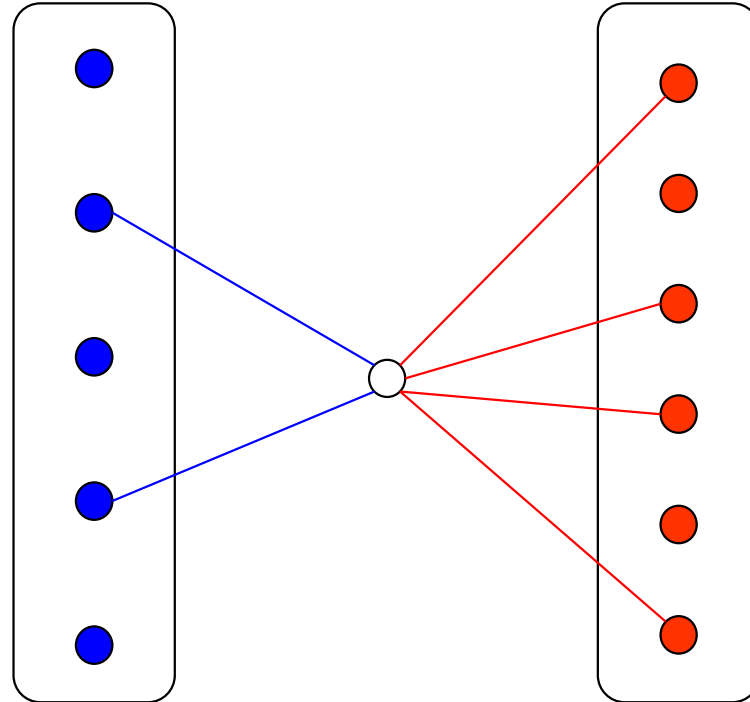
**Input:** a non-negative edge-weighted graph  $G = (V, E; w)$

**Max-weighted cut problem:** find a cut of maximum total weight



## Greedy algorithm

- Pick an arbitrary ordering  $1, 2, \dots, n$  of nodes
- Place node 1 at the left side, **and** repeatedly place the next node at the **better** side.



## Analysis of greedy algorithm

**Thm.** The weight of the greedy cut is at least  $w(E)/2$ . Hence the greedy algorithm is 2-approximate.

**Pf.**

- Partition  $E$  into  $E_2, E_3, \dots, E_n$ , where  
 $E_i$  = the set of edges between  $i$  and  $\{1, \dots, i-1\}$ .
- Node  $i$  contributes at least  $w(E_i)/2$  towards the cut.
- The total weight of the cut is at least  $w(E)/2$ .

## Better approximation

- $(1/0.878)$ -approximation: [Goemans-Williamson 1995] using semidefinite programming
  - best possible if the Unique Games Conjecture is true
- NP-hard to approximate better than  $17/16$  [Håstad 2001]

## 5. Maximum Coverage

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## Maximum Coverage

**Input:** a bipartite graph  $G = (U, W; E)$ , and a positive integer  $k \leq |U|$

**Goal:** Find a  $k$ -subset  $S$  of  $U$  maximizing  $|N(S)|$

```
S := ∅;  
repeat k times  
    u := a node in U with maximum degree in G;  
    add u to S and remove u and its neighbors from G;  
return S
```

**Thm.** Let  $S^*$  be an optimal solution and  $opt := |N(S^*)|$ . Then  
$$|N(S)| \geq [1 - (1 - 1/k)^k]opt \geq (1 - 1/e)opt.$$

## Geometric decreasing of the optimality gap

$S: u_1, u_2, \dots, u_k$

$n_0 := 0$  ; and  $n_i := |N(\{u_1, \dots, u_i\})|$  for  $1 \leq i \leq k$

**Claim.**  $(opt - n_i) \leq (1 - 1/k)(opt - n_{i-1})$ .

**Pf.** At the beginning of the iteration  $i$ ,

- # of nodes in  $N(S^*)$  remaining in  $G \geq opt - n_{i-1}$
- $n_i - n_{i-1} = \text{max degree of } G \geq (opt - n_{i-1})/k$

Thus,

$$(opt - n_{i-1}) - (opt - n_i) = n_i - n_{i-1} \geq (opt - n_{i-1})/k$$

## Approximation bound

$$(opt - n_k) \leq (1 - 1/k)^k opt$$
$$|N(S)| = n_k \geq [1 - (1 - 1/k)^k] opt$$

Q: Can we do better?

**Thm.** [Feige 1998] Unless  $P \neq NP$ , no poly-time algorithm can do better than  $1 - 1/e$ .

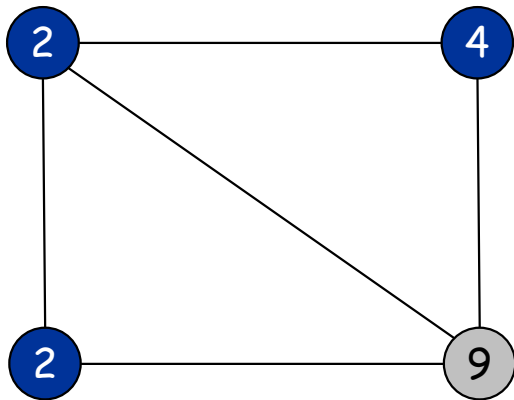
**Remark:** Extended to submodular coverage

## 6. Weighted Vertex Cover

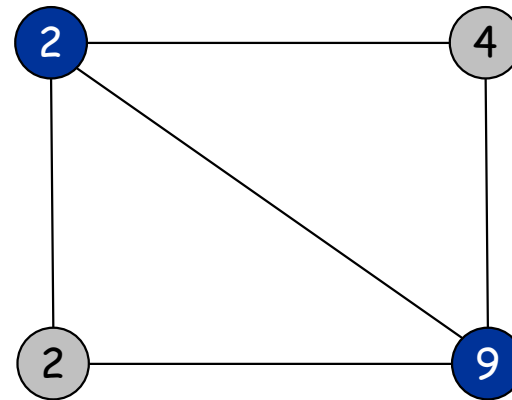
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## Weighted Vertex Cover

**Weighted vertex cover.** Given a graph  $G = (V, E; c)$  with vertex costs, find a vertex cover of minimum cost.



cost = 8



cost = 11

## Frugal bidding

**Bidding:** Each edge  $e$  offers a bid (payment)  $p(e) \geq 0$  for coverage

**Frugality.**  $p(\delta(v)) \leq c(v)$  for each vertex  $v$ .

**Claim.** For any vertex cover  $S$  and any frugal bidding  $p$ ,  $c(S) \geq p(E)$ .

**Pf.**  $p(E) \leq \sum_{v \in S} p(\delta(v)) \leq \sum_{v \in S} c(v) = c(S)$

**Tight** vertices:  $p(\delta(v)) = c(v)$  (cost is covered by the collectable bids)

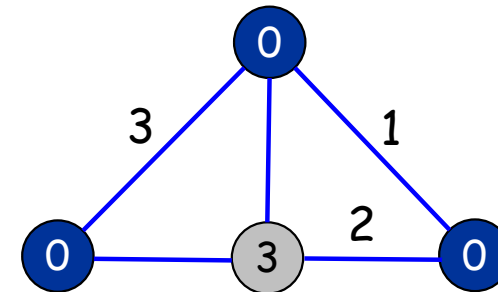
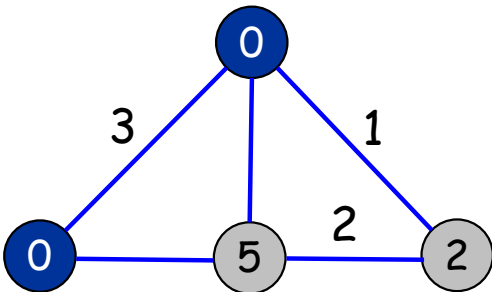
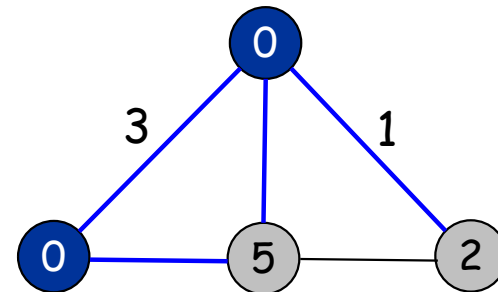
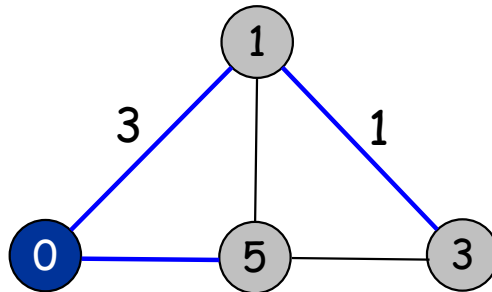
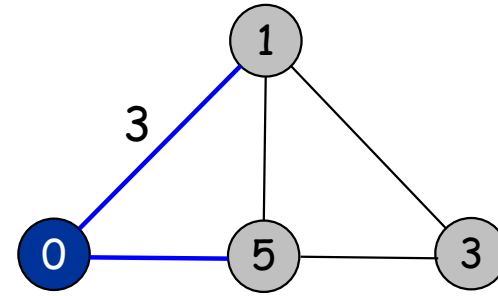
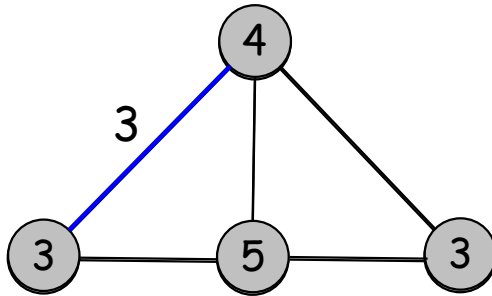
. Only tight vertices are **willing** to join the VC

## Frugal bidding method

Set bids and find vertex cover simultaneously.

```
foreach e in E,  $p(e) \leftarrow 0$   
 $S \leftarrow \emptyset$   
  
while ( $\exists$  edge without tight endpoints)  
    select such an edge  $e$   
    increase  $p(e)$  maximally without violating frugality  
    add tight endpoints of  $e$  to  $S$   
  
return  $S$ 
```

## Frugal bidding method: example





## Frugal bidding method: analysis

Thm. Frugal bidding method is a 2-approximation.

Intuition: each edge's bid is competed by its 2 endpoints.

Pf. Let  $S^*$  be optimal vertex cover. We show  $c(S) \leq 2c(S^*)$ .

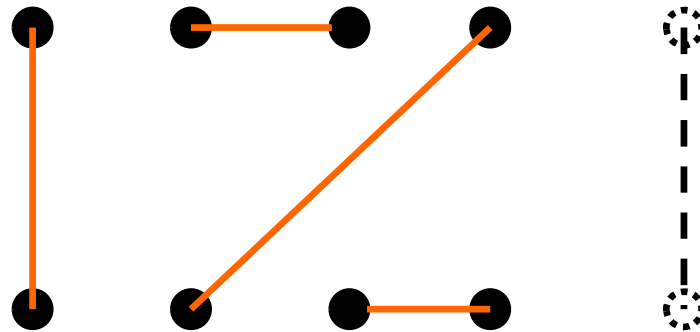
$$c(S) = \sum_{v \in S} c(v) = \sum_{v \in S} p(\delta(v)) \quad \leftarrow \text{all nodes in } S \text{ are tight}$$

$$\leq \sum_{v \in V} p(\delta(v))$$

$$= 2p(E) \quad \text{each edge counted twice}$$

$$\leq 2c(S^*) \quad \text{frugality lemma}$$

## (Unweighted) Vertex Cover: restriction



Compute a maximal matching  $M$ .

Return all matched vertices as a vertex cover.

$$opt \geq |M|$$

So,  $2|M| \leq 2opt$ , and we have a 2-approximation algorithm!

## Approximation hardness of Minimum Vertex Cover

- NP-complete to approximate within a factor of 1.36
- No  $(2 - \varepsilon)$ -approximation if the Unique Game Conjecture is true.
- **Maximal IS**: hard to approximate within  $n^{1-\varepsilon}$ .

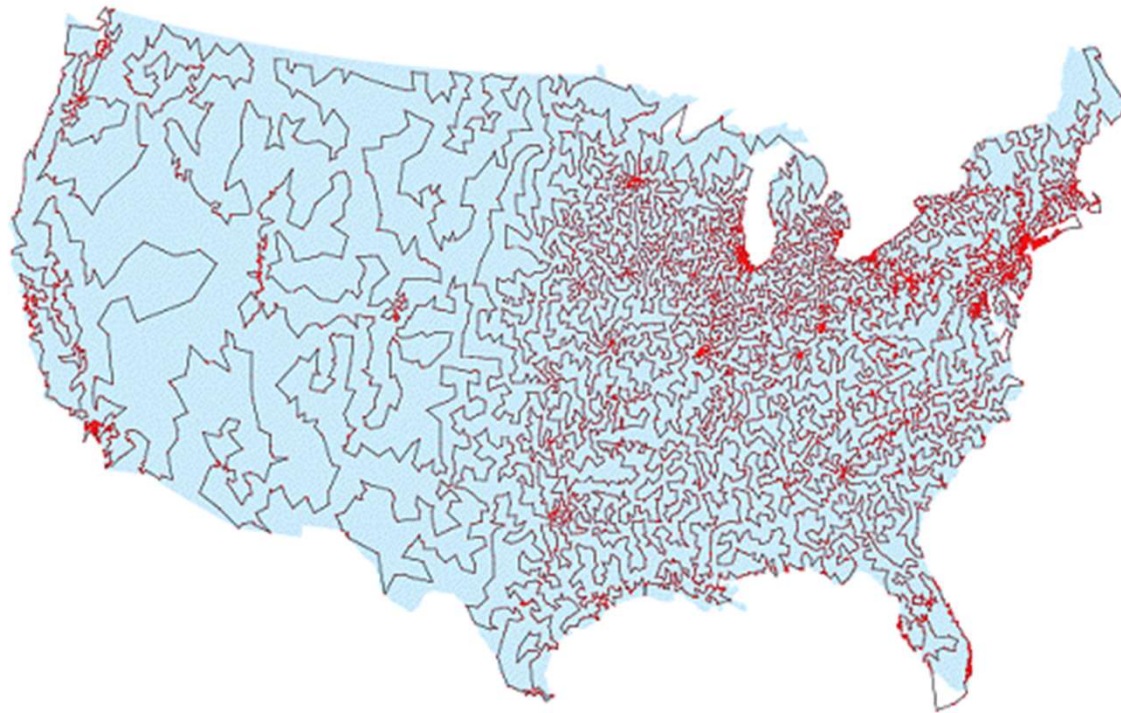
## 7. Metric TSP

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# Metric Traveling Salesman Problem (TSP)

**Input:**  $n$  cities  $c_1, \dots, c_n$  with metric mutual distances

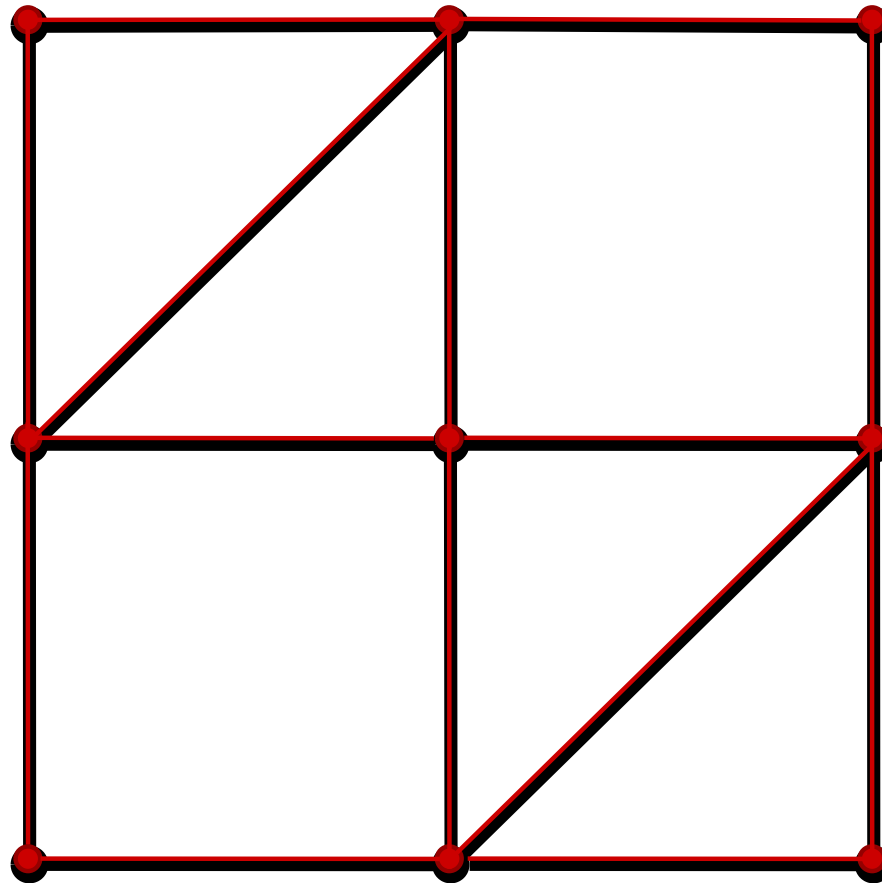
**TSP:** Find a Hamiltonian tour of shortest total length on the  $n$  cities



$n = 13,509$

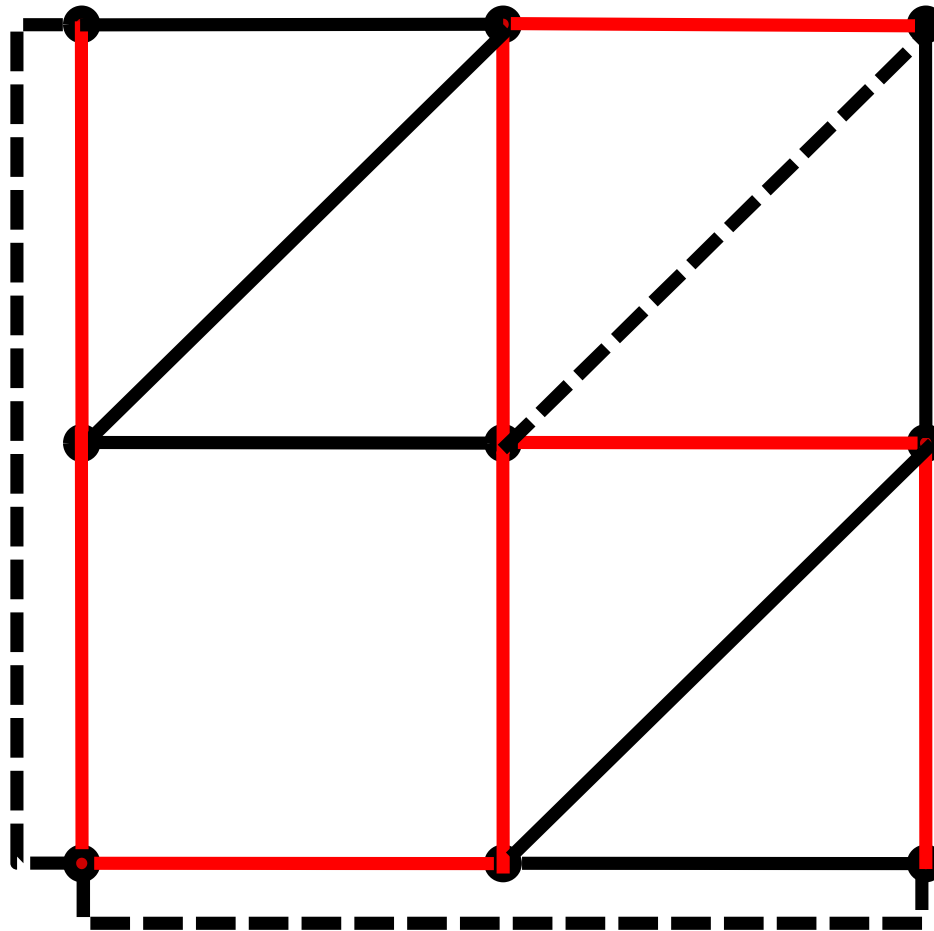
## Relaxing Hamiltonian tour to spanning cycle

Relaxation: allow vertex repetitions in the tour



## Extracting Hamiltonian tour from spanning cycle

Traversing a spanning cycle but skipping previously-visited vertices yields a Hamiltonian tour of **no greater** length



## Constructing a short spanning cycle

Christofides-Serdyukov algorithm [Christofides, 1976]:

an MST + a shortest perfect matching on its odd-degree vertices

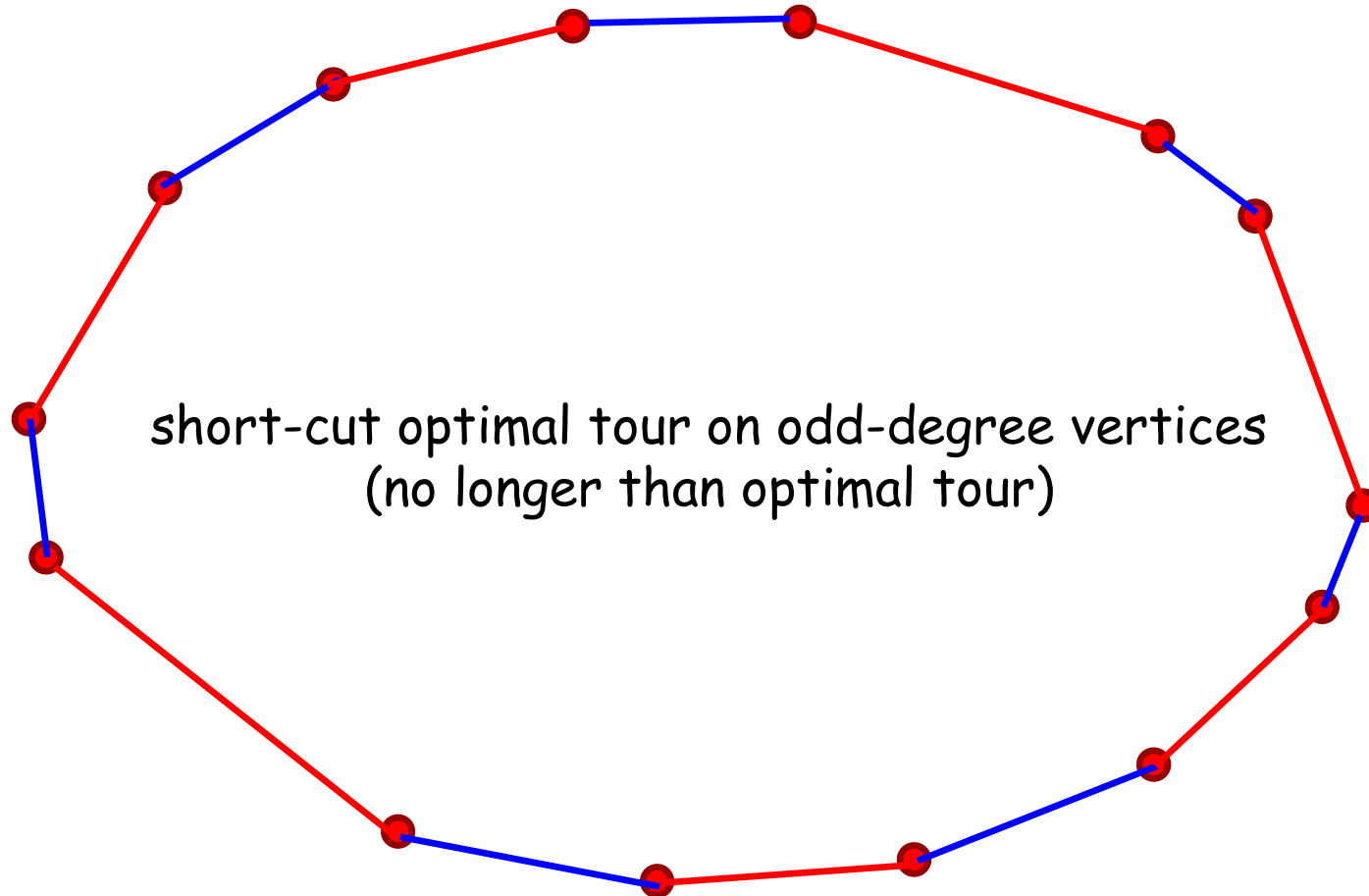
= a spanning cycle

**Lemma.**  $\text{mst} \leq \text{opt}$ ,  $\text{matching} \leq \text{opt}/2$

**Theorem :** Christofides -Serdyukov algorithm is a  $3/2$ -approximation.



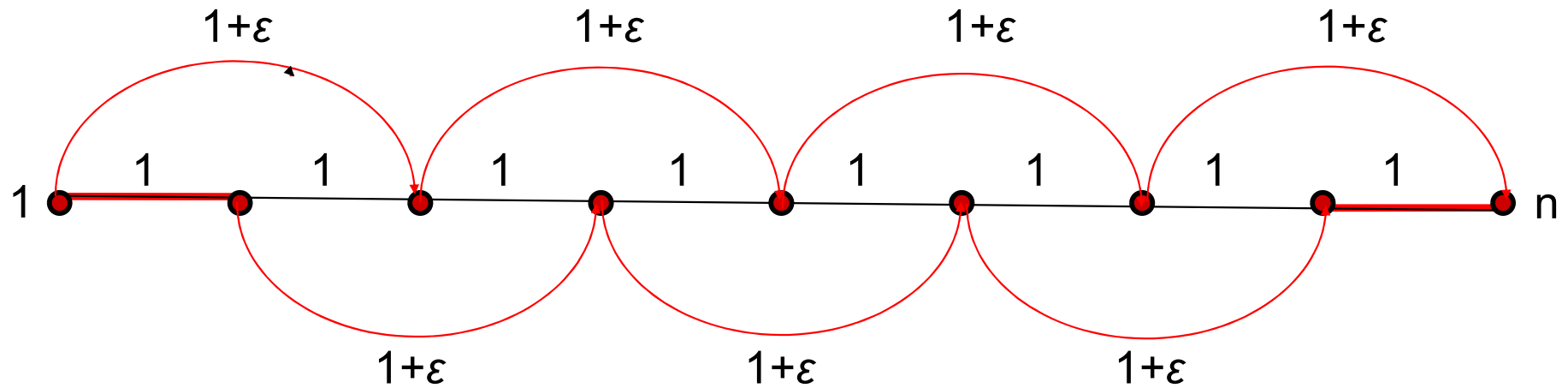
## Bound on optimal matching



matching  $M_1$  + matching  $M_2$  = short-cut optimal tour

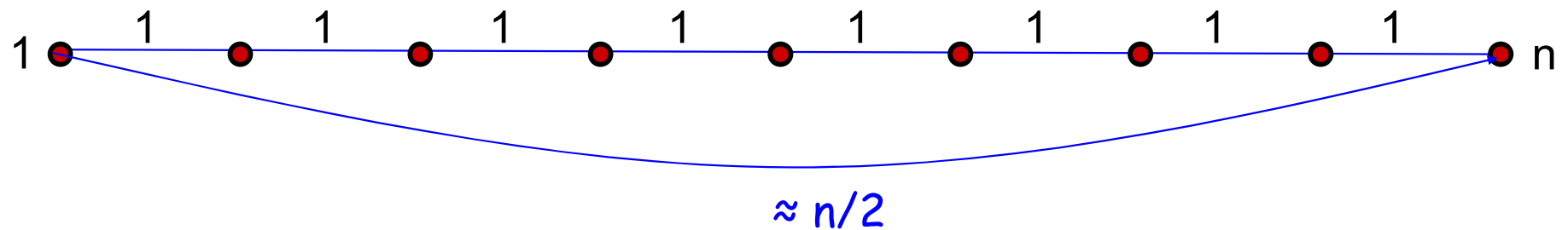
$$\text{optimal matching} \leq \min(M_1, M_2) \leq \text{opt}/2$$

## A tight instance



all other edges have distances given by the shortest paths

red tour  $\approx n$



output tour  $\approx 1.5n$

## Can we do better?

- No better approx. algorithm is known.
- Assuming  $P \neq NP$ , no polynomial-time algorithm can do better than  $220/219 = 1.004566\dots$  [Papadimitriou & Vempala, 2006].
- For Euclidean and related metrics, there exists a PTAS [Arora, 1998][Mitchell, 1999].

## 8. Knapsack

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# Knapsack Problem

**Input.**  $n$  items with specified sizes and profits  $s_i$  and  $p_i$ ; and a knapsack capacity  $B$  with  $\max_i s_i \leq B < \sum_i s_i$

**Def.** The size and profit of a subset  $I$  of items:

$$s(I) = \sum_{i \in I} s_i, \quad p(I) = \sum_{i \in I} p_i$$

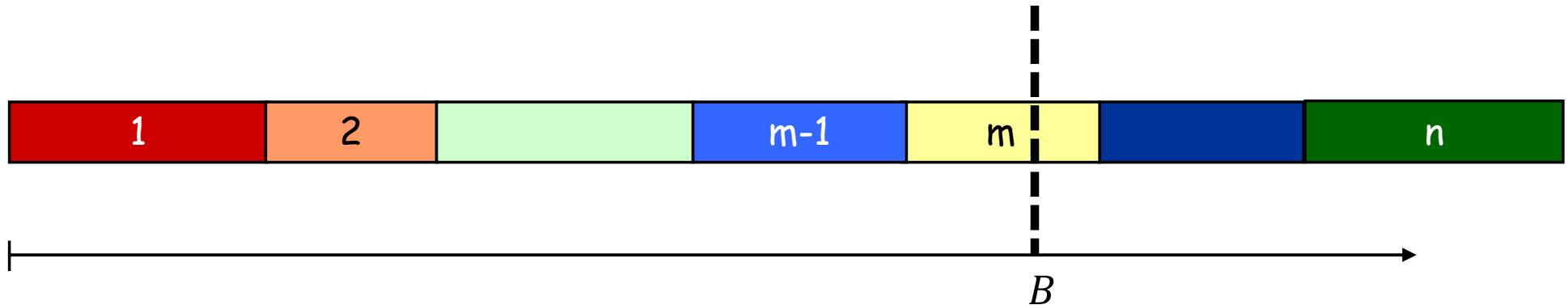
**Def.** For a subset  $I$  of items is feasible if  $s(I) \leq B$

**Knapsack problem:** find a feasible subset with maximum profit.

**Def.** The **return** of an item  $i$  is  $r_i = p_i/s_i$

# Fractional Knapsack Problem

Fractional relaxation: allow a fraction of an item



Fractional greedy algorithm [Dantzig 1957]:

Sort the items by return in decreasing order: 1, 2, ..., n.

Compute the first  $m$  s.t.  $[1:m]$  is not feasible.

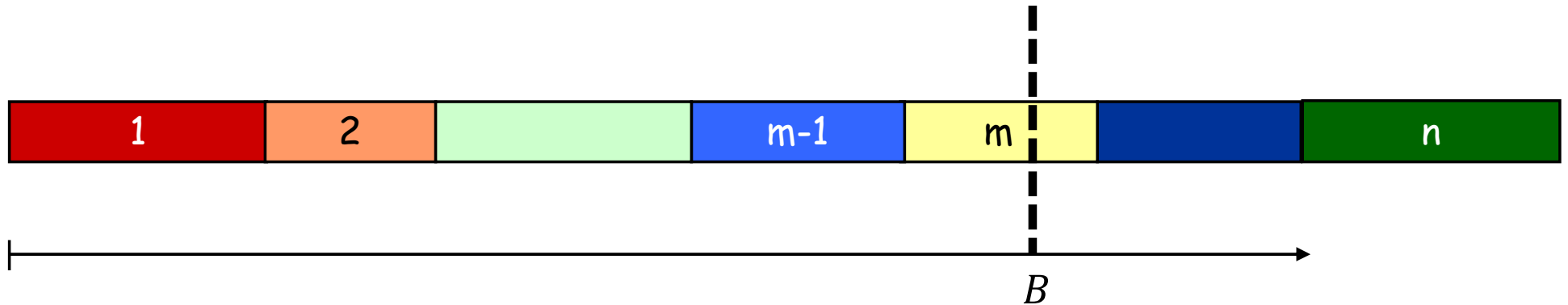
Add  $[1:m-1]$  and a fraction  $\{B - s([1:m-1])\}/s_m$  of item  $m$

Fractional optimum:

$$opt^* = p([1:m-1]) + \frac{B - s([1:m-1])}{s_m} p_m < p([1:m-1]) + p_m$$

## Rounding the fractional greedy solution

Rounding: pick the more profitable  $I$  between  $[1:m-1]$  and  $m$



Thm.  $p(I) \geq \text{opt}/2$ .

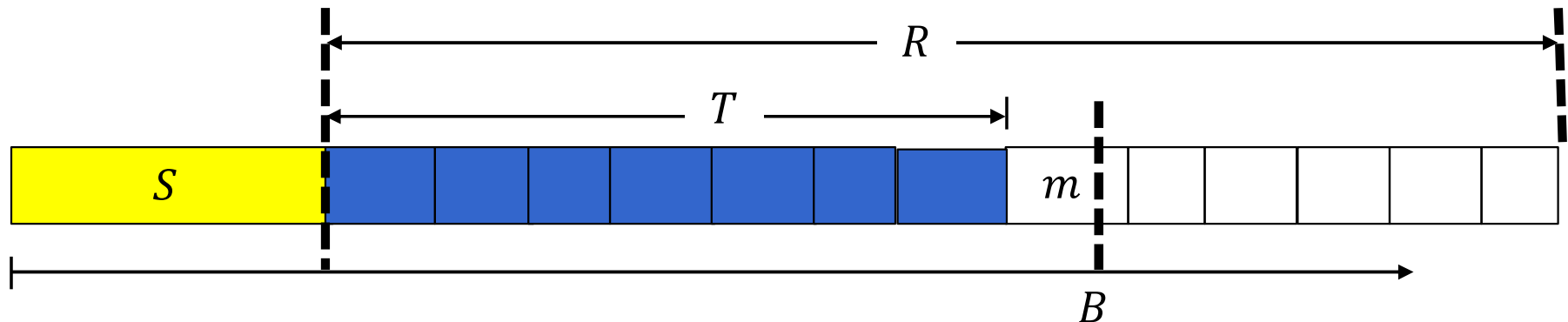
Pf.  $\text{opt} \leq \text{opt}^* < p([1:m-1]) + p_m \leq 2p(I)$

## A PTAS with partial enumeration

[Sahni 1975]

$k$ : a fixed positive integer constant

$I \leftarrow$  the best feasible subset of **less than**  $k$  items; //enumeration  
for each feasible subset  $S$  of  $k$  items //enumeration  
     $R \leftarrow \{j \notin S: p_j \leq \min_{i \in S} p_i\}$  //pruning  
    compute the **greedy** extension  $T \subseteq R$  of  $S$  //greedy extension  
    if  $p(S \cup T) > p(I)$  then  $I \leftarrow S \cup T$   
return  $I$ .



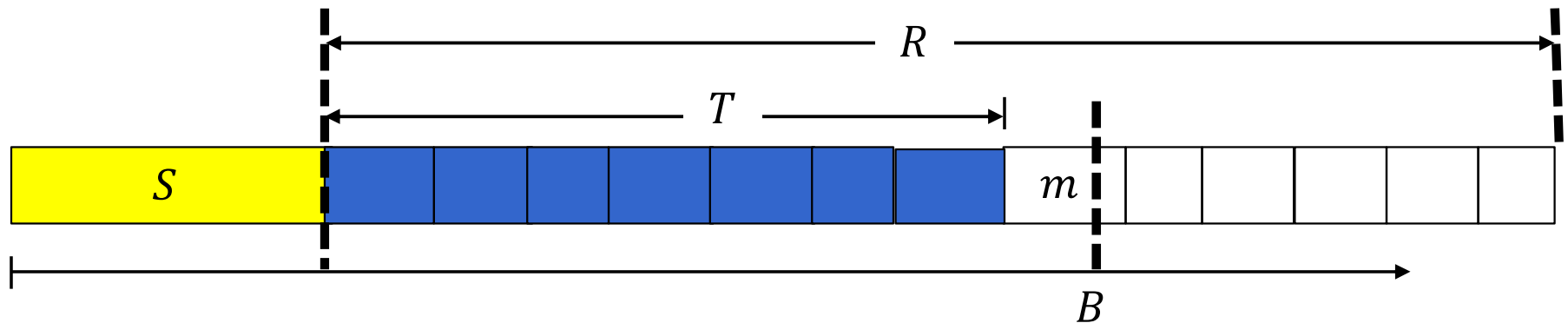


# Analysis of the PTAS

**Thm.** The running time is  $O(n^{k+1})$ , and  $p(I) \geq \text{opt}/(1 + 1/k)$ .

**Pf.** Assume  $I$  is not optimal. Let  $O$  be an optimal solution. Then  $|O| > k$ .

$S$ : the set of  $k$  most profitable items in  $O$



$$p(O \setminus S) < p(T) + p_m \leq p(T) + p(S)/k$$

$$\text{opt} = p(O) \leq p(T) + (1 + 1/k)p(S) \leq (1 + 1/k)p(S \cup T) \leq (1 + 1/k)p(I)$$

## Recap: Dynamic programming for Knapsack

**Assumption:** the profits of all items are integers

**Recap:** solvable **exactly** by a 2-dim. DP in  $O(n^2P)$  time & space, where  $P := \max_i p_i$

- States: min. size required to attain a profit  $q$  by the first  $k$  items.
- DP table indexed by  $(k, q)$ :  $n$  rows and at most  $nP$  columns
- Each entry can be computed in constant time (look up **two** entries).

**Pseudo-polynomial** time & space

Optimal solution is preserved by scaling of the profits.

## Rounding & Scaling

**Idea:** Round (up or down) and then scale down the profits.  
Compute the optimal solution in this modified instance

- Suppose  $P \geq 1000n$ . Then  $opt \geq P \geq 1000n$ .
- **Round up** each profit to nearest multiple of 100 :  $100\lceil p_i/100 \rceil$ .
  - ❖ individual rounding error  $< 100$ .
  - ❖ total rounding error  $< 100n < (1/10)opt$ .
- Compute the optimal solution w.r.t the up-rounded profits:
  - ❖ **scale down** the up-rounded profits by 100 times:  $p_i^* := \lceil p_i/100 \rceil$
  - ❖ apply DP using this down-scaled profits
  - ❖ the running time is **100** times faster.

# FPTAS for KNAPSACK

[Ibarra-Kim 1975]

$\varepsilon > 0$ : a time-accuracy trade-off parameter

Let  $K := \varepsilon P / n$ ; and define  $p^*$  by  $p_i^* := \lfloor p_i / K \rfloor$  for  $1 \leq i \leq n$ .  
Apply DP with  $p^*$  and to find the most profitable set  $I$ .  
Return  $I$ .

**Thm.**  $p(I) \geq (1 - \varepsilon)opt$  and the running time is  $O(n^3/\varepsilon)$ .

## Analysis of the FPTAS

Let  $O$  be an optimal set.

For each  $i$ ,  $p_i \leq Kp_i^* = K\lceil p_i/K \rceil < p_i + K$ .

$$opt = p(O) \leq Kp^*(O) \leq Kp^*(I) \leq p(I) + nK = p(I) + \varepsilon P \leq p(I) + \varepsilon opt$$

So,  $p(I) \geq (1 - \varepsilon)opt$ .

The DP with  $p^*$  has  $n$  rows and at most  $n\lceil P/K \rceil = O(n^2/\varepsilon)$  columns.

So, the total time (and space) complexity is  $O(n^3/\varepsilon)$ .

## Further speedup with reduced DP columns

The number of DP columns  $n^P$  can be replaced any  $C \geq \text{opt}$  and the DP runs  $O(nC)$  time.

Choice of smaller  $C$ : Run the fractional greedy & rounding to output  $I_1$ , and let

$$C := \min\{p([1:n]), 2p(I_1)\}$$

If  $C \leq 2n/\varepsilon$ , then DP returns an optimal solution in  $O(n^2/\varepsilon)$  time.

So, assume  $C > 2n/\varepsilon$ .

## Further speedup with reduced DP columns

$$K := \varepsilon p(I_1)/n$$

Define  $p^*$  by  $p_i^* := \lfloor p_i/K \rfloor$  for  $1 \leq i \leq n$  and  $C^* = \lfloor C/K \rfloor$

Apply DP with  $p^*$  and  $C^*$  to find the most profitable set  $I_2$ .

Output the **more profitable one**  $I$  between  $I_1$  and  $I_2$ .

$$C^* = \lfloor C/K \rfloor \leq 2p(I_1)/K \leq 2n/\varepsilon$$

So, the total time (and space) complexity is  $O(n^2/\varepsilon)$ .

**Thm.**  $p(I) \geq \text{opt}/(1 + \varepsilon)$

**Pf.** For each  $i$ ,  $p_i - K < Kp_i^* = K\lfloor p_i/K \rfloor \leq p_i$ .

$$p(O) < Kp^*(O) + |O|K \leq Kp^*(I_2) + nK \leq p(I_2) + \varepsilon p(I_1) \leq (1 + \varepsilon)p(I)$$

## Quick Summary on FPTAS

1. Modify the instance by rounding/scaling the numbers.
2. Use DP to compute an optimal solution  $S$  in the modified instance.
3. Output  $S$  as the approximate solution.

Other examples:

- Load balancing with fixed number of machines,
- Other variants of Knapsack
- Delay constrained shortest path