Exact decoding for phrase-based SMT

Wilker Aziz¹, Marc Dymetman², Lucia Specia¹

¹University of Sheffield ²Xerox Research Centre Europe

October 27, 2014

Outline

Introduction

Approach

Results

Conclusions

Viterbi decoding

$$\mathbf{d}^* = \underset{\mathbf{d} \in \mathcal{D}(\mathbf{x})}{\operatorname{argmax}} \ f(\mathbf{d})$$
$$= \underset{\mathbf{d} \in \mathcal{D}(\mathbf{x})}{\operatorname{argmax}} \ \boldsymbol{\theta}^\top \mathbf{H}(\mathbf{d})$$

Viterbi decoding

$$\mathbf{d}^* = \underset{\mathbf{d} \in \mathcal{D}(\mathbf{x})}{\operatorname{argmax}} f(\mathbf{d})$$
$$= \underset{\mathbf{d} \in \mathcal{D}(\mathbf{x})}{\operatorname{argmax}} \boldsymbol{\theta}^\top \mathbf{H}(\mathbf{d})$$

space of translation derivations compatible with the input x

Viterbi decoding

$$\mathbf{d}^* = \underset{\mathbf{d} \in \mathcal{D}(\mathbf{x})}{\operatorname{argmax}} f(\mathbf{d})$$
$$= \underset{\mathbf{d} \in \mathcal{D}(\mathbf{x})}{\operatorname{argmax}} \theta^\top \mathbf{H}(\mathbf{d})$$

we are looking for the best derivation under a linear parameterisation $(\boldsymbol{\theta} \in \mathbb{R}^m)$

Viterbi decoding

$$\begin{aligned} \mathbf{d}^* &= \underset{\mathbf{d} \in \mathcal{D}(\mathbf{x})}{\operatorname{argmax}} \ f(\mathbf{d}) \\ &= \underset{\mathbf{d} \in \mathcal{D}(\mathbf{x})}{\operatorname{argmax}} \ \boldsymbol{\theta}_1^\top \mathbf{H}_1(\mathbf{d}) + \boldsymbol{\theta}_2^\top \mathbf{H}_2(\mathbf{d}) \end{aligned}$$

"local" features assess steps in a derivation independently

$$\mathbf{H}_1(\mathbf{d}) = \sum_{e \in \mathbf{d}} \mathbf{h}_1(e)$$

Viterbi decoding

$$\mathbf{d}^* = \underset{\mathbf{d} \in \mathcal{D}(\mathbf{x})}{\operatorname{argmax}} f(\mathbf{d})$$
$$= \underset{\mathbf{d} \in \mathcal{D}(\mathbf{x})}{\operatorname{argmax}} \boldsymbol{\theta}_1^{\top} \mathbf{H}_1(\mathbf{d}) + \boldsymbol{\theta}_2^{\top} \mathbf{H}_2(\mathbf{d})$$

"local" features assess steps in a derivation independently

$$\mathbf{H}_1(\mathbf{d}) = \sum_{e \in \mathbf{d}} \mathbf{h}_1(e)$$

"nonlocal" features make weaker independence assumptions

e.g.
$$H_{LM}(\mathbf{d}) = \log p_{LM}(yield(\mathbf{d}))$$

 $\langle \mathcal{D}(\mathbf{x}), f(\mathbf{d}) \rangle$ can be seen as the intersection between

 $\langle \mathcal{D}(\mathbf{x}), f(\mathbf{d}) \rangle$ can be seen as the intersection between

lacktriangle a translation hypergraph $\mathcal{G}(\mathbf{x})$

locally parameterised

 $\langle \mathcal{D}(\mathbf{x}), f(\mathbf{d}) \rangle$ can be seen as the intersection between

ightharpoonup a translation hypergraph $\mathcal{G}(\mathbf{x})$

locally parameterised

lacktriangle and a target language model ${\cal A}$

as a wFSA

 $\langle \mathcal{D}(\mathbf{x}), f(\mathbf{d}) \rangle$ can be seen as the intersection between

ightharpoonup a translation hypergraph $\mathcal{G}(\mathbf{x})$

locally parameterised

lacktriangle and a target language model ${\cal A}$

as a wFSA

Phrase-based SMT with a distortion limit (d) and an n-gram LM

$$|\mathcal{G}(\mathbf{x})| \propto I^2 2^d$$

 $|\mathcal{A}| \propto |\Delta|^{n-1}$

 $\langle \mathcal{D}(\mathbf{x}), f(\mathbf{d}) \rangle$ can be seen as the intersection between

ightharpoonup a translation hypergraph $\mathcal{G}(\mathbf{x})$

locally parameterised

lacktriangle and a target language model ${\cal A}$

as a wFSA

Phrase-based SMT with a distortion limit (d) and an n-gram LM

$$|\mathcal{G}(\mathbf{x})| \propto I^2 2^d$$

 $|\mathcal{A}| \propto |\Delta|^{n-1}$

Problem

The intersection is too large for standard dynamic programming

Contribution

Previous work on exact decoding

- compact models
- ▶ simpler parameterisation using 3-gram LMs

Contribution

Previous work on exact decoding

- compact models
- ▶ simpler parameterisation using 3-gram LMs

This work

- large models
- ► realistic 5-gram LMs

Full intersection is wasteful

$$\mathcal{G}(\mathbf{x})\cap\mathcal{A}$$

Full intersection is wasteful

$$\mathcal{G}(\mathbf{x}) \cap \mathcal{A}$$

► complete *n*-gram LM

Full intersection is wasteful

$$\mathcal{G}(\mathbf{x}) \cap \mathcal{A} = \mathcal{G}(\mathbf{x}) \cap \left(\bigcap_{i=1}^{M} \mathcal{A}^{(i)}\right)$$

complete n-gram LM

► encodes one *n*-gram

Full intersection is wasteful

$$\mathcal{G}(\mathbf{x}) \cap \mathcal{A} = \mathcal{G}(\mathbf{x}) \cap \left(\bigcap_{i=1}^{M} \mathcal{A}^{(i)}\right)$$

complete n-gram LM

encodes one n-gram

Assumption

not every n-gram participates in high-scoring derivations

Full intersection is wasteful

$$\mathcal{G}(\mathbf{x}) \cap \mathcal{A} = \mathcal{G}(\mathbf{x}) \cap \left(\bigcap_{i=1}^{M} \mathcal{A}^{(i)}\right)$$

complete n-gram LM

► encodes one *n*-gram

Assumption

not every n-gram participates in high-scoring derivations

Problem

which n-grams are really necessary? and at which level of refinement?

Full intersection is wasteful

$$\mathcal{G}(\mathbf{x}) \cap \mathcal{A} = \mathcal{G}(\mathbf{x}) \cap \left(\bigcap_{i=1}^{M} \mathcal{A}^{(i)}\right)$$

complete n-gram LM

encodes one n-gram

Assumption

not every n-gram participates in high-scoring derivations

Problem

which n-grams are really necessary? and at which level of refinement?

Strategy

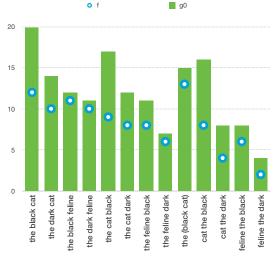
start with strong independence assumptions revisit those assumptions as necessary



o f 20 15 10 0 0

> cat the black cat the dark feline the black feline the dark

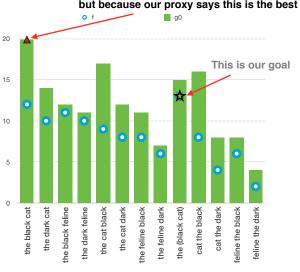
the black cat the black cat the black cat the dark feline the cat black feline the cat black the feline black the feline black the feline black cat) the feline dark feline cat black cat) the feline dark feline cat black cat) the feline cat black cat) the feline cat black cat



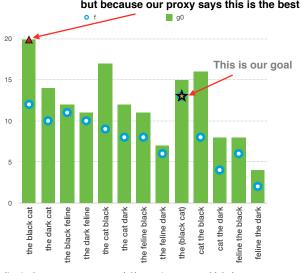
 \blacktriangleright upperbound the complex target $f(\mathbf{d})$ by a simpler proposal $g(\mathbf{d})$



▶ we are interested in finding f's argmax however we cannot search through f



 \blacktriangleright we find $\mathbf{d}^* = \operatorname{argmax}_{\mathbf{d}} g(\mathbf{d})$



 \blacktriangleright we find $\mathbf{d}^* = \operatorname{argmax}_{\mathbf{d}} g(\mathbf{d})$ and assess $f(\mathbf{d}^*)$



but because our proxy says this is the best

- $lackbox{ we find } \mathbf{d}^* = \operatorname{argmax}_{\mathbf{d}} g(\mathbf{d}) \text{ and assess } f(\mathbf{d}^*)$
- ightharpoonup finding our best solution thus far (according to f)

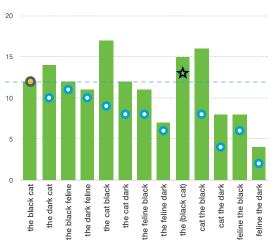


lacktriangle we find $\mathbf{d}^* = \operatorname{argmax}_{\mathbf{d}} g(\mathbf{d})$ and assess $f(\mathbf{d}^*)$

o f

- ightharpoonup finding our best solution thus far (according to f)
- however we cannot guarantee exactness yet

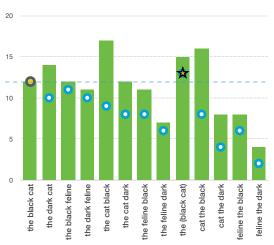




g1

▶ so we refine g as to bring it closer to f e.g. by making $g(\mathbf{d}^*) = f(\mathbf{d}^*)$

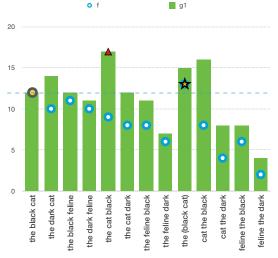
o f



▶ so we refine g as to bring it closer to f e.g. by making $g(\mathbf{d}^*) = f(\mathbf{d}^*)$

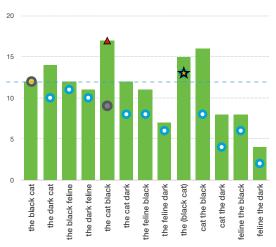
o f

at the cost of some little complexity increase (extra nodes and edges)



as a consequence, g's argmax has changed we solve $\mathbf{d}^* = \operatorname{argmax}_{\mathbf{d}} g(\mathbf{d})$

o f



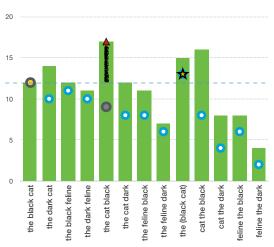
▶ as a consequence, g's argmax has changed we solve $\mathbf{d}^* = \operatorname{argmax}_{\mathbf{d}} g(\mathbf{d})$

o f

▶ and assess $f(\mathbf{d}^*)$ again our best solution thus far might remain unchanged



we cannot yet guarantee exactness

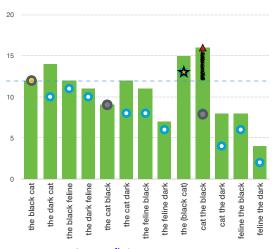


g1

- we cannot yet guarantee exactness
- even though our maximum error is smaller

o f

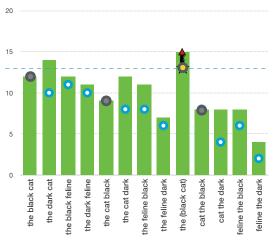




g2

o f

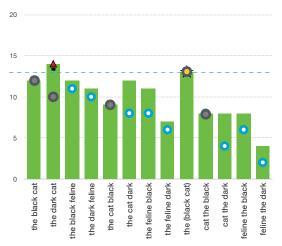
lacktriangle but we can continue refining g



g3

o f

- ightharpoonup but we can continue refining g
- ightharpoonup for as long as g and f disagree on the maximum



o f

- ightharpoonup but we can continue refining g
- ightharpoonup for as long as g and f disagree on the maximum

OS*



- ightharpoonup but we can continue refining g
- ightharpoonup for as long as g and f disagree on the maximum
- until we have a certificate of optimality

o f

1: function Optimise (g, ϵ)

- 1: function Optimise (g, ϵ)
- 2: $\mathbf{d}^* \leftarrow \operatorname{argmax}_{\mathbf{d}} g(\mathbf{d})$

 $\triangleright \mathsf{proxy's} \ \mathrm{argmax}$

- 1: function Optimise (g, ϵ)
- 2: $\mathbf{d}^* \leftarrow \operatorname{argmax}_{\mathbf{d}} g(\mathbf{d})$
- 3: $g^* \leftarrow g(\mathbf{d}^*)$
- 4: $f^* \leftarrow f(\mathbf{d}^*)$

▷ proxy's argmax

 \triangleright observe a point in f

- 1: function Optimise (g, ϵ)
- 2: $\mathbf{d}^* \leftarrow \operatorname{argmax}_{\mathbf{d}} g(\mathbf{d})$
- 3: $g^* \leftarrow g(\mathbf{d}^*)$
- 4: $f^* \leftarrow f(\mathbf{d}^*)$
- 5: while $(q^* f^* \ge \epsilon)$ do

- $\triangleright \mathsf{proxy's} \ \mathrm{argmax}$
- \triangleright observe a point in f
- $hd \epsilon$ is the maximum error

```
1: function OPTIMISE(g, \epsilon)

2: \mathbf{d}^* \leftarrow \operatorname{argmax}_{\mathbf{d}} g(\mathbf{d}) \triangleright proxy's \operatorname{argmax}

3: g^* \leftarrow g(\mathbf{d}^*)

4: f^* \leftarrow f(\mathbf{d}^*) \triangleright observe a point in f

5: while (q^* - f^* \ge \epsilon) do \triangleright \epsilon is the maximum error

6: A \leftarrow \operatorname{actions}(g, \mathbf{d}^*) \triangleright collect refinement actions
```

```
1: function Optimise(g, \epsilon)
         \mathbf{d}^* \leftarrow \operatorname{argmax}_{\mathbf{d}} q(\mathbf{d})
                                                                            ▷ proxy's argmax
     g^* \leftarrow g(\mathbf{d}^*)
3:
    f^* \leftarrow f(\mathbf{d}^*)
                                                                     \triangleright observe a point in f
5:
      while (q^* - f^* > \epsilon) do
                                                                \triangleright \epsilon is the maximum error
               A \leftarrow \operatorname{actions}(q, \mathbf{d}^*)
                                                           6:
               q \leftarrow \text{refine}(q, A)
7:

    □ update proposal
```

```
1: function Optimise(q, \epsilon)
          \mathbf{d}^* \leftarrow \operatorname{argmax}_{\mathbf{d}} q(\mathbf{d})
                                                                                 ▷ proxy's argmax
3:
     q^* \leftarrow q(\mathbf{d}^*)
     f^* \leftarrow f(\mathbf{d}^*)
                                                                          \triangleright observe a point in f
        while (q^* - f^* \ge \epsilon) do
                                                                    \triangleright \epsilon is the maximum error
5:
                A \leftarrow \operatorname{actions}(q, \mathbf{d}^*)
                                                               6:
                q \leftarrow \text{refine}(q, A)

    □ update proposal

7:
                \mathbf{d}^* \leftarrow \operatorname{argmax}_{\mathbf{d}} q(\mathbf{d})
                                                                                 ▶ update argmax
8:
```

```
1: function Optimise(q, \epsilon)
           \mathbf{d}^* \leftarrow \operatorname{argmax}_{\mathbf{d}} q(\mathbf{d})
                                                                                 ▷ proxy's argmax
 3:
       q^* \leftarrow q(\mathbf{d}^*)
      f^* \leftarrow f(\mathbf{d}^*)
                                                                          \triangleright observe a point in f
         while (q^* - f^* > \epsilon) do
                                                                    \triangleright \epsilon is the maximum error
 5:
                 A \leftarrow \operatorname{actions}(g, \mathbf{d}^*)
                                                               6:
                 q \leftarrow \text{refine}(q, A)
 7:

    □ update proposal

 8:
                 \mathbf{d}^* \leftarrow \operatorname{argmax}_{\mathbf{d}} q(\mathbf{d})
                                                                                 ▶ update argmax
                 q^* \leftarrow q(\mathbf{d}^*)
 9:
                 f^* \leftarrow \max(f^*, f(\mathbf{d}^*))
10:
                                                                       ▷ update "best so far"
           end while
11:
```

```
1: function Optimise(q, \epsilon)
           \mathbf{d}^* \leftarrow \operatorname{argmax}_{\mathbf{d}} q(\mathbf{d})
                                                                              ▷ proxy's argmax
 3:
       q^* \leftarrow q(\mathbf{d}^*)
      f^* \leftarrow f(\mathbf{d}^*)
 4:
                                                                       \triangleright observe a point in f
       while (q^* - f^* > \epsilon) do
                                                                  \triangleright \epsilon is the maximum error
 5:
                 A \leftarrow \operatorname{actions}(g, \mathbf{d}^*)
                                                             6:
                 q \leftarrow \text{refine}(q, A)
 7:

    □ update proposal

 8:
                 \mathbf{d}^* \leftarrow \operatorname{argmax}_{\mathbf{d}} q(\mathbf{d})
                                                                              ▶ update argmax
                 q^* \leftarrow q(\mathbf{d}^*)
 9:
                 f^* \leftarrow \max(f^*, f(\mathbf{d}^*))
10:
                                                                     ▷ update "best so far"
           end while
11.
           return g, d*
12:
13: end function
```

In g , the true LM $p_{\rm LM}$ is replaced by an upperbound $q_{\rm LM}$ with stronger independence assumptions

In g, the true LM $p_{\rm LM}$ is replaced by an upperbound $q_{\rm LM}$ with stronger independence assumptions

▶ Suppose $\alpha=y_I^J$ is a substring of $\mathbf{y}=y_1^M$ e.g. $\alpha=\mathsf{black}_2$ cat $_3$ in $\mathbf{y}=\mathsf{BOS}_0$ the $_1$ black $_2$ cat $_3$ EOS $_4$

In g, the true LM $p_{\rm LM}$ is replaced by an upperbound $q_{\rm LM}$ with stronger independence assumptions

- ▶ Suppose $\alpha=y_I^J$ is a substring of $\mathbf{y}=y_1^M$ e.g. $\alpha=\operatorname{black}_2\operatorname{cat}_3$ in $\mathbf{y}=\operatorname{BOS}_0$ the 1 black 2 cat 3 EOS 4
 - lacksquare contribution of lpha to the true LM score of ${f y}$

$$p_{\rm LM}(\alpha) \equiv \prod_{k=I}^J p(y_k|y_1^{k-1})$$

e.g. $p(\mathsf{black}_2|\mathsf{BOS}_0 \mathsf{the}_1)p(\mathsf{cat}_3|\mathsf{BOS}_0 \mathsf{the}_1 \mathsf{black}_2)$

In g, the true LM $p_{\rm LM}$ is replaced by an upperbound $q_{\rm LM}$ with stronger independence assumptions

- ▶ Suppose $\alpha=y_I^J$ is a substring of $\mathbf{y}=y_1^M$ e.g. $\alpha=\mathsf{black}_2$ cat $_3$ in $\mathbf{y}=\mathsf{BOS}_0$ the $_1$ black $_2$ cat $_3$ EOS $_4$
 - lacksquare contribution of lpha to the true LM score of ${f y}$

$$p_{\rm LM}(\alpha) \equiv \prod_{k=I}^J p(y_k|y_1^{k-1})$$

e.g. $p(\mathsf{black}_2|\mathsf{BOS}_0 \mathsf{the}_1)p(\mathsf{cat}_3|\mathsf{BOS}_0 \mathsf{the}_1 \mathsf{black}_2)$

• upperbound to $p_{\text{LM}}(\alpha)$

$$q_{\rm LM}(\alpha) \equiv q(y_I|\epsilon) \prod_{k=I+1}^J q(y_k|y_I^{k-1})$$

e.g. $q(\mathsf{black}_2|\epsilon)q(\mathsf{cat}_3|\mathsf{black}_2)$

where
$$q(\mathbf{z}|P) \equiv \max_{\mathbf{H} \in \Delta^*} p(\mathbf{z}|\mathbf{H}P)$$

An n-gram is scored in its most optimistic context H

$$q(\mathbf{z}|\mathbf{P}) \equiv \max_{\mathbf{H} \in \Delta^*} p(\mathbf{z}|\mathbf{HP})$$

An n-gram is scored in its most optimistic context H

$$q(\mathbf{z}|\mathbf{P}) \equiv \max_{\mathbf{H} \in \Delta^*} p(\mathbf{z}|\mathbf{HP})$$

Efficiently computed using a Max-ARPA table M

An n-gram is scored in its most optimistic context H

$$q(\mathbf{z}|\mathbf{P}) \equiv \max_{\mathbf{H} \in \Delta^*} p(\mathbf{z}|\mathbf{HP})$$

Efficiently computed using a Max-ARPA table M

start with an ARPA table

$$n$$
-gram Pz — conditional $\log p(\mathbf{z}|\mathbf{P})$ — backoff $b(\mathbf{Pz})$

An n-gram is scored in its most optimistic context H

$$q(\mathbf{z}|\mathbf{P}) \equiv \max_{\mathbf{H} \in \Delta^*} p(\mathbf{z}|\mathbf{HP})$$

Efficiently computed using a Max-ARPA table M

- start with an ARPA table
 n-gram Pz conditional log p(z|P) backoff b(Pz)
- ▶ compute an upperbound view of the last 2 columns n-gram Pz max-conditional $\log q(\mathbf{z}|\mathbf{P})$ max-backoff $m(\mathbf{Pz})$

An n-gram is scored in its most optimistic context H

$$q(\mathbf{z}|\mathbf{P}) \equiv \max_{\mathbf{H} \in \Delta^*} p(\mathbf{z}|\mathbf{HP})$$

Efficiently computed using a Max-ARPA table M

- ▶ start with an ARPA table
 n-gram Pz conditional log p(z|P) backoff b(Pz)
- ▶ compute an upperbound view of the last 2 columns n-gram Pz max-conditional $\log q(\mathbf{z}|\mathbf{P})$ max-backoff $m(\mathbf{Pz})$

Then for an arbitrary *n*-gram Pz,

$$q(\mathbf{z}|\mathbf{P}) = \left\{ \begin{array}{ll} p(\mathbf{z}|\mathbf{P}) & \quad & \mathsf{Pz} \not\in M \text{ and } \mathsf{P} \not\in M \\ p(\mathbf{z}|\mathbf{P}) \times m(\mathsf{P}) & \quad & \mathsf{Pz} \not\in M \text{ and } \mathsf{P} \in M \\ q(\mathbf{z}|\mathsf{P}) & \quad & \mathsf{Pz} \in M \end{array} \right.$$

The proposal $g(\mathbf{d})$ can be efficiently represented by a hypergraph

The proposal $g(\mathbf{d})$ can be efficiently represented by a hypergraph Remark!

Nodes do not store LM state

The proposal $g(\mathbf{d})$ can be efficiently represented by a hypergraph Remark!

Nodes do not store LM state

$$|\langle \mathcal{D}(\mathbf{x}), f(\mathbf{d}) \rangle| = |\mathcal{G}(\mathbf{d}) \cap \mathcal{A}| \propto I^2 2^d |\Delta|^{n-1}$$

The proposal $g(\mathbf{d})$ can be efficiently represented by a hypergraph

Remark!

Nodes do not store LM state

$$|\left\langle \mathcal{D}(\mathbf{x}), g(\mathbf{d}) \right\rangle| = |\mathcal{G}(\mathbf{d}) \cap \mathcal{A}| \propto I^2 2^d \Delta^{n-1}$$

Goal: break independence assumptions

- 1. making larger n-grams
- 2. bringing g closer to f

Goal: break independence assumptions

- 1. making larger n-grams
- 2. bringing g closer to f

Examples

Goal: break independence assumptions

- 1. making larger n-grams
- 2. bringing g closer to f

Examples

$$g'(\mathbf{d}) = \begin{cases} g(\mathbf{d}) & \text{if } \mathbf{d} \neq \operatorname{argmax} g(\mathbf{d}) \\ f(\mathbf{d}) & \text{otherwise.} \end{cases}$$

Goal: break independence assumptions

- 1. making larger *n*-grams
- 2. bringing g closer to f

Examples

$$g'(\mathbf{d}) = \begin{cases} g(\mathbf{d}) & \text{if } \mathbf{d} \neq \operatorname{argmax} g(\mathbf{d}) \\ f(\mathbf{d}) & \text{otherwise.} \end{cases}$$

Too local: one derivation at a time

Goal: break independence assumptions

- 1. making larger n-grams
- 2. bringing g closer to f

Examples

$$g'(\mathbf{d}) = g(\mathbf{d}) \frac{q(\mathbf{z}|\mathbf{hP})^k}{q(\mathbf{z}|\mathbf{P})}$$

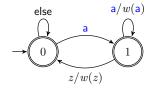
where k counts occurrences of hPz in yield(d)

Goal: break independence assumptions

- 1. making larger n-grams
- 2. bringing g closer to f

Examples

$$g'(\mathbf{d}) = g(\mathbf{d}) \frac{q(\mathbf{z}|\mathbf{hP})}{q(\mathbf{z}|\mathbf{P})}^k$$



where k counts occurrences of hPz in $yield(\mathbf{d})$

Too global: refines derivations which already score poorly

Break independence assumptions (making larger *n*-grams) **but not in every derivation**

Break independence assumptions (making larger n-grams) but not in every derivation

Example:

• suppose the argmax is $(X_1(X_2(X_3 \text{the}) \text{black}) \text{cat})$

Break independence assumptions (making larger n-grams) but not in every derivation

Example:

- suppose the argmax is $(X_1(X_2(X_3\mathsf{the})\mathsf{black})\mathsf{cat})$
- \triangleright and node X_3 currently stores an empty LM states

¹[Li and Khudanpur, 2008, Heafield et al., 2013] ←□→←②→←②→←②→←②→

Break independence assumptions (making larger n-grams) but not in every derivation

Example:

- ▶ suppose the argmax is $(X_1(X_2(X_3\mathsf{the})\mathsf{black})\mathsf{cat})$
- ightharpoonup and node X_3 currently stores an empty LM states
- \blacktriangleright this motivates a refined node $X_{3'}$ whose LM state is

the · LMSTATE(X_3)

Break independence assumptions (making larger n-grams) but not in every derivation

Example:

- ▶ suppose the argmax is $(X_1(X_2(X_3\mathsf{the})\mathsf{black})\mathsf{cat})$
- ightharpoonup and node X_3 currently stores an empty LM states
- ▶ this motivates a refined node $X_{3'}$ whose LM state is

the · LMSTATE(
$$X_3$$
)

▶ incoming edges to X₃ are split

¹[Li and Khudanpur, 2008, Heafield et al., 2013] $\leftarrow \square \rightarrow \leftarrow \square \rightarrow \leftarrow \square \rightarrow \leftarrow \square \rightarrow \square \square \square$

Break independence assumptions (making larger n-grams) but not in every derivation

Example:

- ▶ suppose the argmax is $(X_1(X_2(X_3\mathsf{the})\mathsf{black})\mathsf{cat})$
- ightharpoonup and node X_3 currently stores an empty LM states
- ▶ this motivates a refined node $X_{3'}$ whose LM state is

the · LMSTATE(
$$X_3$$
)

- ▶ incoming edges to X₃ are split
- lacktriangle outgoing edges from $X_{3'}$ are reweighted copies of those leaving X_3

 $^{^1}$ [Li and Khudanpur, 2008, Heafield et al., 2013] $\leftarrow \square \rightarrow \leftarrow \square \rightarrow \leftarrow \square \rightarrow \leftarrow \square \rightarrow \square \rightarrow \square \rightarrow \square$

Break independence assumptions (making larger n-grams) but not in every derivation

Example:

- ▶ suppose the argmax is $(X_1(X_2(X_3\mathsf{the})\mathsf{black})\mathsf{cat})$
- ightharpoonup and node X_3 currently stores an empty LM states
- ▶ this motivates a refined node $X_{3'}$ whose LM state is

the · LMSTATE(
$$X_3$$
)

- ightharpoonup incoming edges to X_3 are split
- lacktriangle outgoing edges from $X_{3'}$ are reweighted copies of those leaving X_3

This is connected to an intersection local to X_3

$$*(X_3*{\sf the})z*$$
 with weight update $rac{q(z|{\sf the})}{q(z)}$

¹[Li and Khudanpur, 2008, Heafield et al., 2013] ←□→←♂→←≧→←≧→←≧→

Refinement actions

Goal: lower g's maximum as much as possible

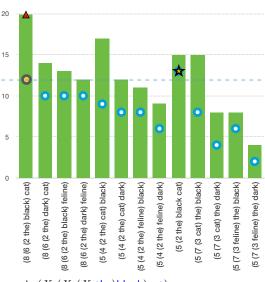
Refinement actions

Goal: lower g's maximum as much as possible

Heuristic

Refine all nodes participating in the current argmax

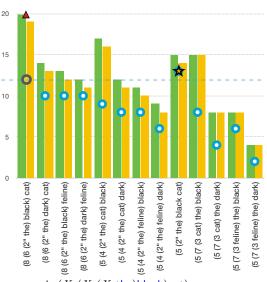
▶ by extending a node's LM (right) state by exactly one word from yield(argmax g(d))



g

o f

▶ argmax is (X₈(X₆(X₂the)black)cat)



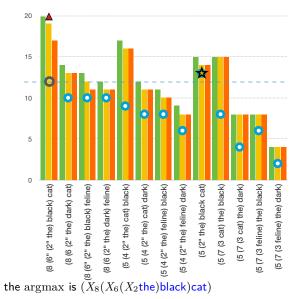
g

the

▶ the argmax is $(X_8(X_6(X_2 \text{the}) \text{black}) \text{cat})$

o f

ightharpoonup refine spans continuing from X_2 by conditioning on the

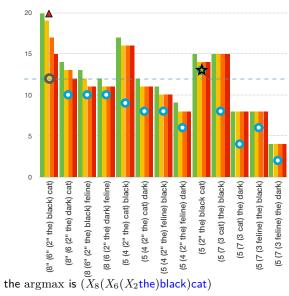


the

black

O f

refine spans continuing from X_6 by conditioning on black



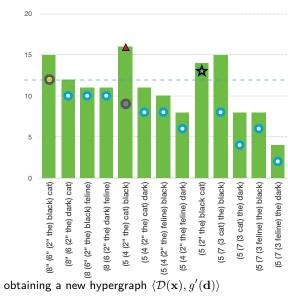
the

black

cat

o f

refine spans continuing from X_8 by conditioning on cat



g"

o f

Experiments

German-English (WMT14 data)

- phrase extraction: 2.2M sentences
- ▶ maximum phrase length 5
- maximum translation options 40
- unpruned LMs: 25M sentences
- ▶ dev set: NEWSTEST2010 (LM interpolation and tuning)
- ▶ batch-mira tuning (cube pruning beam 5000)
- ▶ test set: NEWSTEST2012 (3,003 sentences)
- ightharpoonup distortion limit d=4

Exact decoding

n	build (s)	total (s)	Ν	V	E
3	1.5	21	190	2.5	159
4	1.5	50	350	4	288
5	1.5	106	555	6.1	450

- time to build initial proposal
- decoding time
- number of iterations
- size of the hypergraph (in thousands of nodes and edges)

Cube pruning

Search errors by beam size (k)

k	n-gram LM					
N	3	4	5			
10	2168	2347	2377			
10^2	613	999	1126			
10^{3}	29	102	167			
10^4	0	4	7			

Translation quality with BLEU

Cube pruning and exact decoding with OS*

k	3-gram LM	4-gram LM	5-gram LM
10	20.47	20.71	20.69
10^2	21.14	21.73	21.76
10^3	21.27	21.89	21.91
10^4	21.29	21.92	21.93
OS*	21.29	21.92	21.93

Exact decoding

Exact decoding

► manageable time

Exact decoding

- manageable time
- fraction of the search space

Exact decoding

- manageable time
- fraction of the search space

Search error curves for beam search and cube pruning

Exact decoding

- manageable time
- fraction of the search space

Search error curves for beam search and cube pruning

- large phrase tables
- ▶ large 5-gram LMs

Exact decoding

- manageable time
- fraction of the search space

Search error curves for beam search and cube pruning

- large phrase tables
- ► large 5-gram LMs

Exactness at the cost of worst-case complexity, however

Exact decoding

- manageable time
- fraction of the search space

Search error curves for beam search and cube pruning

- large phrase tables
- ▶ large 5-gram LMs

Exactness at the cost of worst-case complexity, however

we demonstrate empirically that the algorithm is practicable

Recent developments

- 1. exact k-best
- 2. exact sampling

Future work

Optimisation

- early stop the search
- error safe pruning

Future work

Optimisation

- early stop the search
- error safe pruning

Speedups

- be more selective with refinements
- ▶ LR to deal with powerset constraints (allowing for higher d)
- more grouping (partial edges)

Future work

Optimisation

- early stop the search
- error safe pruning

Speedups

- be more selective with refinements
- ▶ LR to deal with powerset constraints (allowing for higher d)
- more grouping (partial edges)

Hiero models

Thanks!

Questions?

Variable-order LM

n	Nodes at level $\it m$				LM states at level m				
	0	1	2	3	4	1	2	3	4
3	0.4	1.2	0.5	-	-	113	263	-	-
4	0.4	1.6	1.4	0.3	-	113 132	544	212	-
5	0.4	2.1	2.4	0.7	0.1	142	790	479	103

Table : Average number of nodes (in thousands) whose LM state encode an m-gram, and average number of unique LM states of order m in the final hypergraph for different n-gram LMs (d=4 everywhere).

References I

Kenneth Heafield, Philipp Koehn, and Alon Lavie. Grouping language model boundary words to speed k-best extraction from hypergraphs. In *Proceedings of the 2013 Conference of the North American Chapter of the Association for Computational Linguistics: Human Language Technologies*, pages 958–968, Atlanta, Georgia, USA, June 2013.

Zhifei Li and Sanjeev Khudanpur. A scalable decoder for parsing-based machine translation with equivalent language model state maintenance. In *Proceedings of the Second Workshop on Syntax and Structure in Statistical Translation*, SSST '08, pages 10–18, Stroudsburg, PA, USA, 2008. Association for Computational Linguistics.