

AAE 364L – Experiment #2 Grading Sheet
The Control of a Gantry

Name _____

Possible Points

Cover Page - 1

| | | |
|------------------------------------|----------|--|
| Title, Name, Course, Date, TA etc. | 1 | |
| Subtotal | 1 | |

Introduction - 4

| | | |
|---------------------------|----------|--|
| Objectives/Goals/Purposes | 2 | |
| Intended Methods | 2 | |
| Subtotal | 4 | |

Procedure - 10

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|---|-----------|--|
| Definition of Variables including State Variables | 2 | |
| Schematic and Description of Apparatus | 3 | |
| Procedure of Experiments | 5 | |
| Subtotal | 10 | |

Results - 20

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|---|-----------|--|
| Part (i) ω_p from both linear approximation and experiment | 2 | |
| Part (ii) ω_n and ζ from eigenvalues of A | 2 | |
| Part (ii) ω_n from computed from Bode plot | 1 | |
| Part (ii) $ G_a(i\omega) $ from Bode plot and experiment | 3 | |
| Part (iii) Values of K from Simulink/Prelab and poles location, t_s when $d\alpha/dt(0) = \pi/2$ | 3 | |
| Part (iii) Values of K from experiment and poles location, estimated t_s when $d\alpha/dt(0) = \pi/2$ | 3 | |
| Part (iv) Values of K from Simulink/Prelab and poles location, t_s | 3 | |
| Part (iv) Values of K from experiment and poles location, t_s | 3 | |
| Subtotal | 20 | |

Analysis and Discussion – 30

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|--|-----------|--|
| Nonlinear EOMs | 1 | |
| Linearized EOMs and equilibrium points | 1 | |
| State variables, state vector, system matrices A,B,C,D | 3 | |
| Part (i) | 5 | |
| Part (ii) | 5 | |
| Part (iii) | 5 | |
| Part (iv) | 5 | |
| Discussion of state feedback and pole placement | 5 | |
| Subtotal | 30 | |

Conclusion and Recommendation – 10

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|--|-----------|--|
| Main Points | 5 | |
| Theoretical/Experimental Limitations | 3 | |
| Personal Lessons Learned and Suggestions for Improvement | 2 | |
| Subtotal | 10 | |

Style, Participation, and Prelab – 25

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|-----------------|-----------|--|
| Organization | 4 | |
| Grammar | 3 | |
| Neatness | 3 | |
| Participation | 5 | |
| Prelab | 10 | |
| Subtotal | 25 | |

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|--------------|------------|--|
| Total | 100 | |
|--------------|------------|--|