CAMBRIDGE INTERNATIONAL EXAMINATIONS

GCE Advanced Subsidiary Level and GCE Advanced Level

MARK SCHEME for the October/November 2012 series

9702 PHYSICS

9702/51

Paper 5 (Planning, Analysis and Evaluation), maximum raw mark 30

This mark scheme is published as an aid to teachers and candidates, to indicate the requirements of the examination. It shows the basis on which Examiners were instructed to award marks. It does not indicate the details of the discussions that took place at an Examiners' meeting before marking began, which would have considered the acceptability of alternative answers.

Mark schemes should be read in conjunction with the question paper and the Principal Examiner Report for Teachers.

Cambridge will not enter into discussions about these mark schemes.

Cambridge is publishing the mark schemes for the October/November 2012 series for most IGCSE, GCE Advanced Level and Advanced Subsidiary Level components and some Ordinary Level components.



Page 2		Mark Scheme	Syllabus	Paper		
		GCE AS/A LEVEL – October/November 2012	9702	51		
ı	Planning (15 marks)					
ı	Defining the	problem (3 marks)				
ı	P v is the i	ndependent variable or vary v.				
I	P E is the	dependent variable or measure <i>E.</i>				
I	P Keep the	e number of turns on the coil <u>constant</u> .				
ı	Methods of data collection (5 marks)					
ı	M1 Labelled	diagram showing magnet falling vertically through coil.				
I	M2 Voltmete	er or c.r.o. connected to the coil. Allow voltage sensor c	onnected to da	talogger.		
M3 Method to change speed e.g. change height.						
ı	bottom of the mag	4 Measurements to determine <i>v</i> . Use metre rule to measure distance magnet falls to the bottom of the coil or metre rule/ruler to measure length of coil or ruler to measure length of the magnet. [Allow timing instrument to measure the time of the fall from the start to the bottom of the coil.]				
ı	height m	of determining v corresponding to appropriate distance nethod) or $v = L/t$ for length of magnet or coil and by steed to datalogger. [Allow $v = gt$ for timing fall to bottom of	opwatch, timer			
		nalysis (2 marks) ph of <i>E</i> against <i>v</i> . [Allow lg <i>E</i> against lg <i>v</i>]				
,		hip valid if <u>straight</u> line <u>through origin</u> . en straight line with gradient = (+)1 (ignore reference to	<i>y</i> -intercept)]			
	•	iderations (1 mark) by from falling magnet/use sand tray/cushion to catch ma	agnet.			
1	D1/2/3/4 Re Use coil with 1 Detailed	letail (4 marks) elevant points might include large number of turns/drop magnet from large heights/s use of datalogger/storage oscilloscope to determine maincluding slow motion play back		v video		

- 2 Use same magnet or magnet of same strength.
- 3 Use of short magnet so that v is (nearly) constant
- 4 Use short/thin coil so that *v* is (nearly) constant
- 5 Use a non-metallic <u>vertical</u> guide/tube
- 6 Method to support <u>vertical</u> coil or guide/tube
- 7 Repeat experiment for each *v* and average

Do not allow vague computer methods.

[Total: 15]

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2 Analysis, conclusions and evaluation (15 marks)

Part	Mark	Expected Answer	Additional Guidance
(a)	A1	Gradient = hc/e y-intercept = - B/e	Note y-intercept must be negative
(b)	T1	1/ λ / 10 ⁶ m ⁻¹	Appropriate column heading
	T2	1.05 or 1.053 1.14 or 1.143 1.53 or 1.527 1.79 or 1.786 1.98 or 1.980 2.33 or 2.326	Must be values in table. A mixture of 3 s.f. and 4 s.f. is allowed.
(c) (i)	G1	Six points plotted correctly	Must be within half a small square. Penalise 'blobs'. Ecf allowed from table.
	U1	All error bars in V/V plotted correctly.	Do not allow near misses
(c) (ii)	G2	Line of best fit	If points are plotted correctly then lower end of line should pass between (1.12, 0.7) and (1.16,0.7) and upper end of line should pass between (2.32, 2.25) and (2.34, 2.25). Allow ecf from points plotted incorrectly – examiner judgement.
	G3	Steepest or shallowest possible line	Line should be clearly labelled or dashed. Should pass from top of top error bar to bottom of bottom error bar or bottom of top error bar to top of bottom error bar. Mark scored only if error bars are plotted.
(c) (iii)	C1	Gradient of best fit line	The triangle used should be at least half the length of the drawn line. Check the read offs. Work to half a small square. Do not penalise POT. Should be about 1.3 × 10 ⁻⁶ .
	U2	Uncertainty in gradient	Method of determining absolute uncertainty Difference in worst gradient and gradient. [± 0.08]
(c) (iv)	C2	y-intercept	Must be negative Expect to see point substituted into $y = mx + c$ FOX does not score. Do not penalise POT. Should be between -0.72 and -0.86
	U3	Method of determining uncertainty in y-intercept	Difference in worst y-intercept and y-intercept. [Should be about \pm 0.14]. FOX does not score. Allow ecf from (c)(iv) .

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(d) (i)	C3	<i>h</i> in the range 6.77×10^{-34} to 7.14×10^{-34} and given to 2 or 3 significant figures	Gradient must be used. Penalise 1 s.f. or >3 s.f. $h = \text{gradient} \times e/c = \text{gradient} \times 5.33 \times 10^{-28}$ Allow 6.8×10^{-34} to 7.1×10^{-34} to 2 s.f.
(d) (ii)	U4	Percentage uncertainty in h	$\frac{\Delta m}{m} \times 100 \text{ or } \frac{\Delta h}{h} \times 100$ [should be about 6%]
(e)	C4	B = -e × y-intercept and J or CV or VC	Ignore '–' signs. <i>y</i> -intercept must be used but allow ecf from FOX. Should be between 1.16×10^{-19} J and 1.37×10^{-19} J. If FOX 8.3 $\times 10^{-20}$ J
	U5	Absolute uncertainty in B	Uncertainty = best B – worst B = Δy -intercept × e

[Total: 15]

Uncertainties in Question 2

(c) (iii) Gradient [U2]

Uncertainty = gradient of line of best fit – gradient of worst acceptable line

Uncertainty = ½ (steepest worst line gradient – shallowest worst line gradient)

(iv) [U3]

Uncertainty = y-intercept of line of best fit – y-intercept of worst acceptable line Uncertainty = $\frac{1}{2}$ (steepest worst line y-intercept – shallowest worst line y-intercept)

(d) (ii) [U4]

Percentage uncertainty =
$$\frac{\Delta m}{m} \times 100$$

Percentage uncertainty = $\frac{\Delta h}{h} \times 100 = \frac{1}{2} \frac{(\max h - \min h)}{h} \times 100$

(e) [U5]

Absolute uncertainty = best B – worst B

Absolute uncertainty =
$$\Delta y$$
-intercept $\times e$
Absolute uncertainty = $\frac{\Delta c}{c} \times B$