

Validation of CFD Software Packages in Modeling Pollutant Dispersion

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HKUST

8 August 2016

Outline

① Introduction

② Setting Up the Model

③ Results

④ Analysis

⑤ Conclusions

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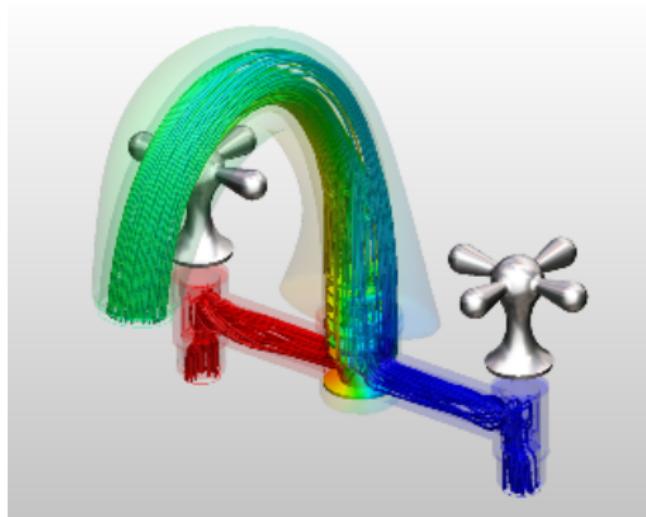
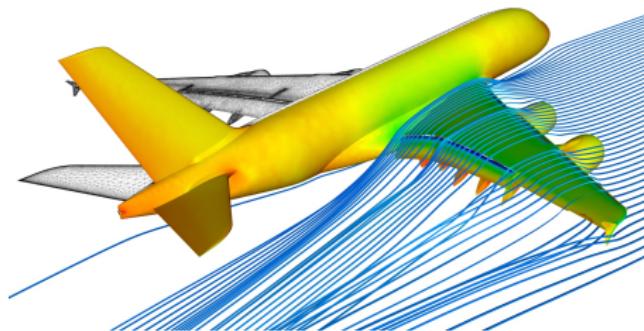
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Air Pollution



[3]

Computational Fluid Dynamics (CFD)



[1] [4]

The Navier-Stokes Equations (Incompressible)

- Equation of continuity:

$$\frac{\partial u_i}{\partial x_i} = 0$$

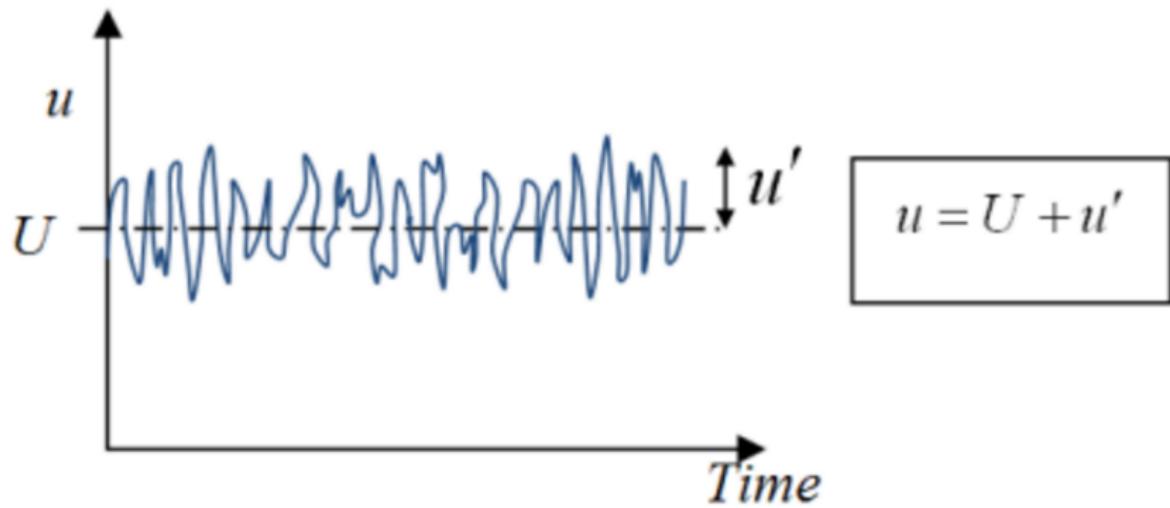
- Equation of momentum:

$$\frac{\partial(\rho u_i)}{\partial t} + \frac{\partial}{\partial x_j} (\rho u_i u_j) = -\frac{\partial p}{\partial x_i} + \frac{\partial}{\partial x_j} (2\mu s_{ji}) + pg_i,$$

where $s_{ji} = \frac{1}{2} \left(\frac{\partial u_i}{\partial x_j} + \frac{\partial u_j}{\partial x_i} \right)$.

Reynolds Averaging

Mean component + Fluctuating component



[5]

Reynolds Averaging Cont.

For a generic variable $u(\mathbf{x}, t)$, we have

$$u(\mathbf{x}, t) = U(\mathbf{x}) + u'(\mathbf{x}, t),$$

where Reynolds time-averaging is defined as

$$U(\mathbf{x}) =: \bar{u}(\mathbf{x}, t) = \lim_{\tau \rightarrow \infty} \frac{1}{\tau} \int_t^{t+\tau} u(\mathbf{x}, t) dt.$$

[2]

The Reynolds-Averaged Navier-Stokes (RANS) Equations

- Equation of continuity:

$$\frac{\partial U_i}{\partial x_i} = \frac{\partial u'_i}{\partial x_i} = 0$$

- Equation of momentum:

$$\frac{\partial}{\partial t}(\rho U_i) + U_j \frac{\partial}{\partial x_j}(\rho U_i) = -\frac{\partial p}{\partial x_i} + \frac{\partial}{\partial x_j}(2\rho\nu \bar{S}_{ji}) - \frac{\partial}{\partial x_j}(\rho \bar{u}'_i \bar{u}'_j),$$

where $S_{ji} = \frac{1}{2}(\frac{\partial U_i}{\partial x_j} + \frac{\partial U_j}{\partial x_i})$ is the mean strain rate tensor.

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Note: the nonlinear term $\rho \bar{u}'_i \bar{u}'_j$ is called the Reynolds stress.

[2]

The Boussinesq Eddy Viscosity Assumption

For an incompressible flow, the Reynolds stress is modeled as

$$\rho \overline{u'_i u'_j} = \mu_t \left(\frac{\partial U_i}{\partial x_j} + \frac{\partial U_j}{\partial x_i} \right) - \frac{2}{3} k \rho \delta_{ij}.$$

The Boussinesq Eddy Viscosity Assumption

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The scalar property μ_t is called the eddy viscosity.

[2]

Generic Scalar Transport Equation

For a generic scalar variable ϕ , we have

$$\frac{\partial(\rho\phi)}{\partial t} + \frac{\partial}{\partial x_i}(\rho u_i \phi) = \frac{\partial}{\partial x_i} \left[\Gamma \frac{\partial \phi}{\partial x_i} \right] + S,$$

where S is the source term, and Γ is the diffusion coefficient.

Turbulence Model

The Realizable $k - \epsilon$ (RKE) Model:

$$\left\{ \begin{array}{l} \frac{\partial(\rho k)}{\partial t} + \frac{\partial(\rho U_j k)}{\partial x_j} = \frac{\partial}{\partial x_j} \left(\left(\mu + \frac{\mu_t}{\sigma_k} \right) \frac{\partial k}{\partial x_j} \right) + \tau_{ij} \frac{\partial U_i}{\partial x_j} - \rho \epsilon \\ \\ \frac{\partial(\rho \epsilon)}{\partial t} + \frac{\partial(\rho \epsilon U_j)}{\partial x_j} = \left(\mu + \frac{\mu_t}{\sigma_\epsilon} \right) \nabla^2 \epsilon + C_1 S \rho \epsilon - C_2 \frac{\rho \epsilon^2}{k + \sqrt{\nu \epsilon}} \end{array} \right.$$

[6]

Mass Transport

$$\frac{\partial T}{\partial t} + \nabla \cdot (\vec{u}T) - \nabla^2 \left(\left(D_T + \frac{\mu_t}{Sc_t} \right) T \right) = R,$$

where R is the source term, D_T is the mass diffusivity, and Sc_t is the turbulent Schmidt number.

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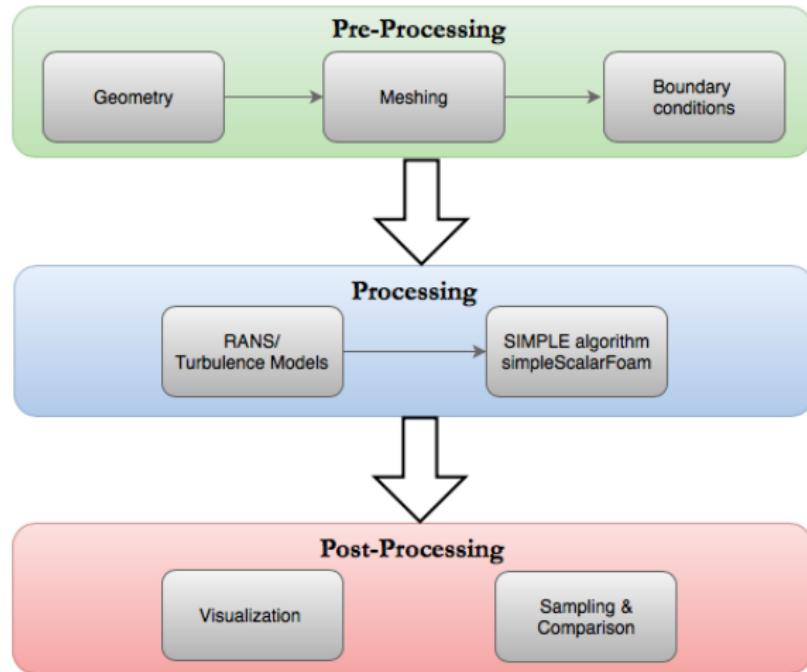
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Setting Up the Model



Tokyo Polytechnic University (TPU) Wind Tunnel Experiment

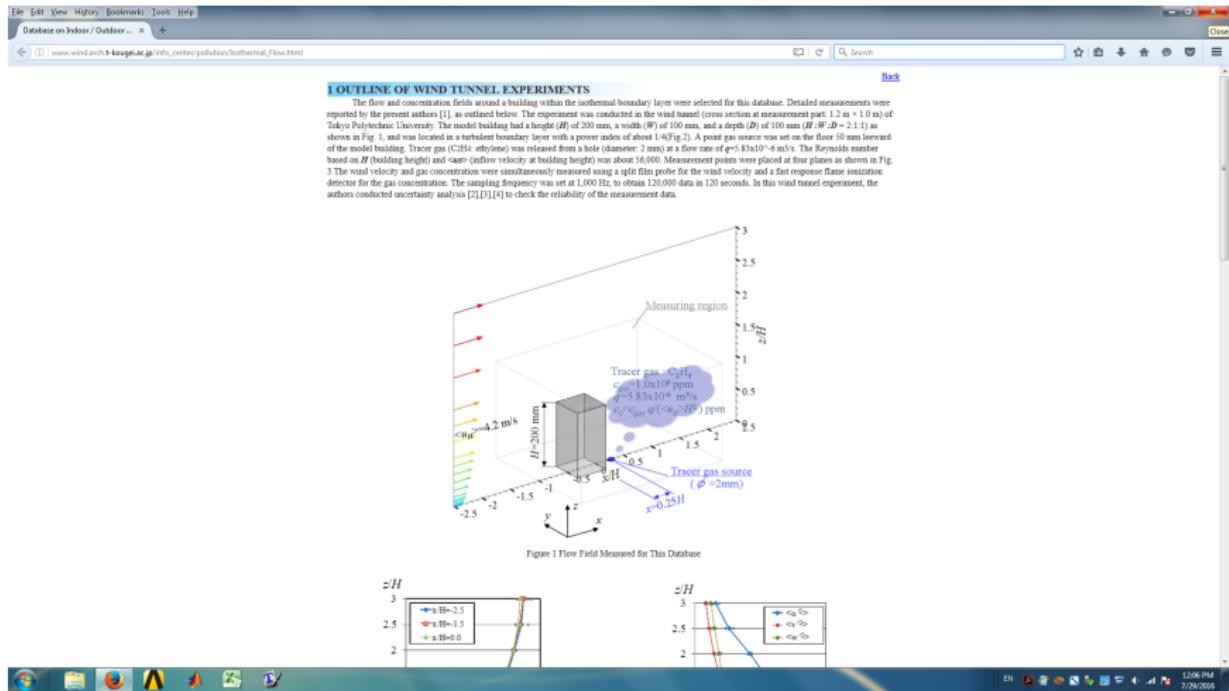


Figure 1 Flow Field Measured for This Database

Geometry

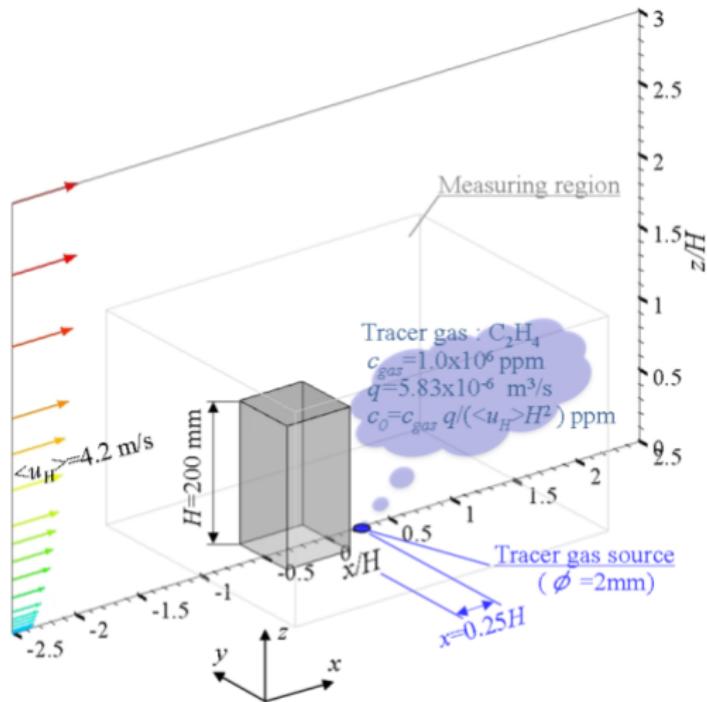
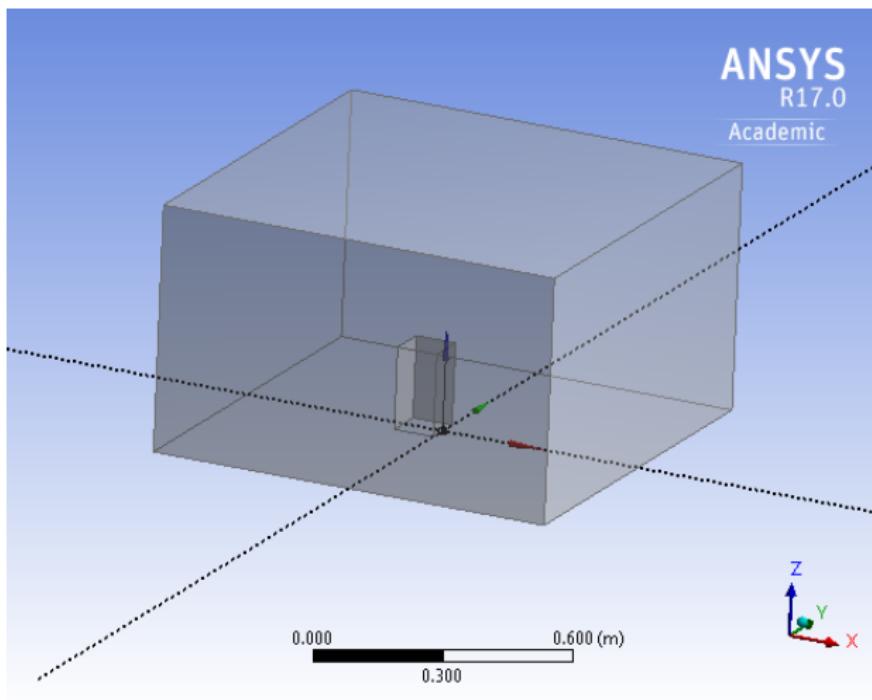
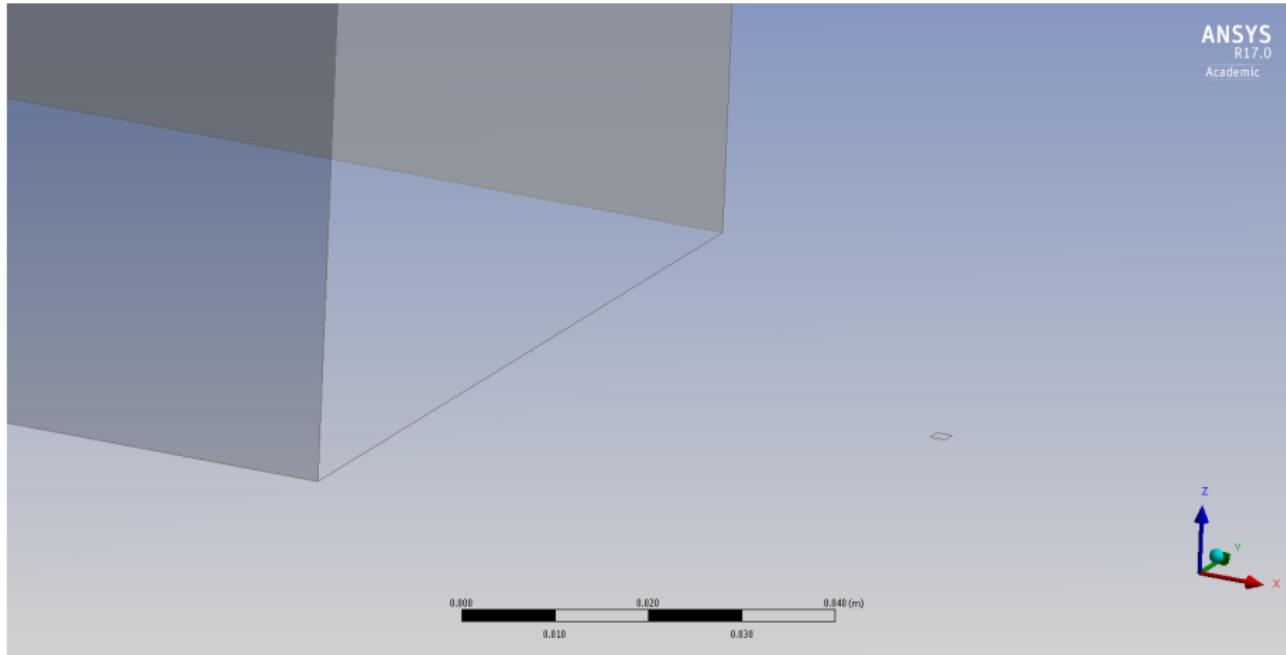


Figure 1 Flow Field Measured for This Database

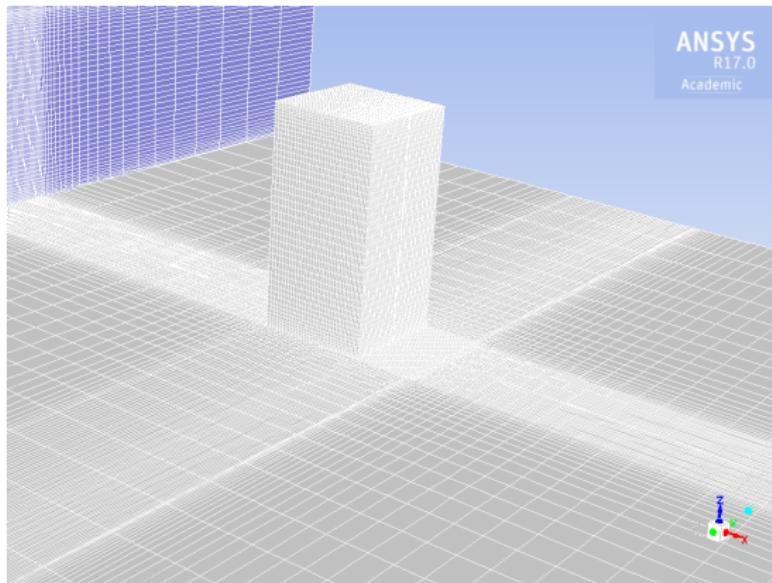
Geometry Cont.



Geometry Cont.

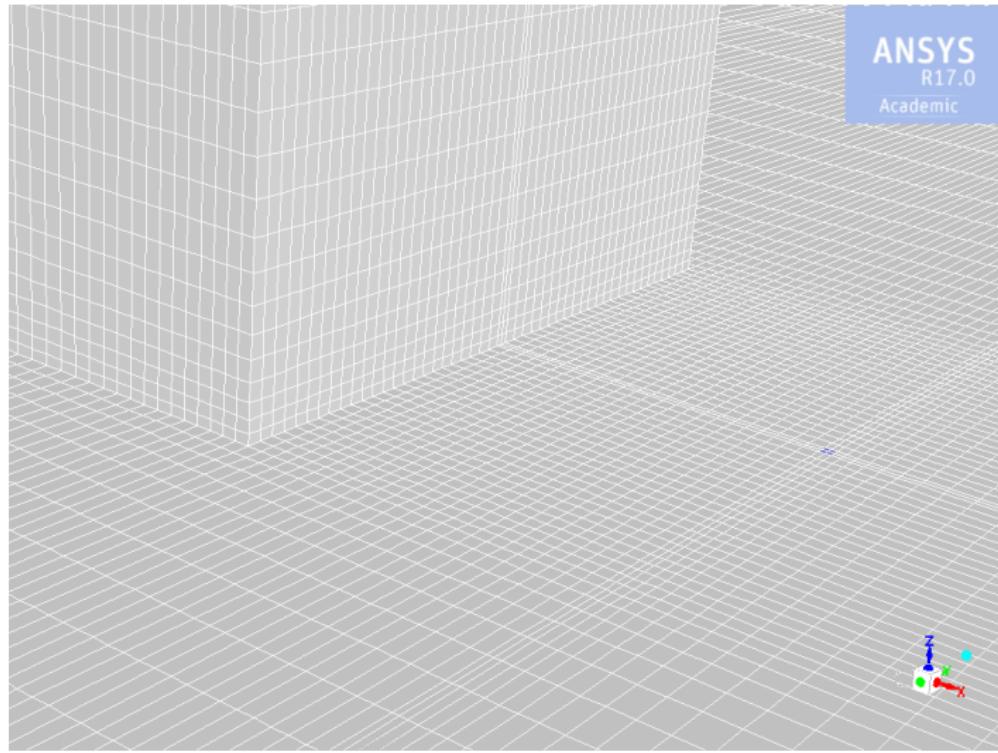


Meshing

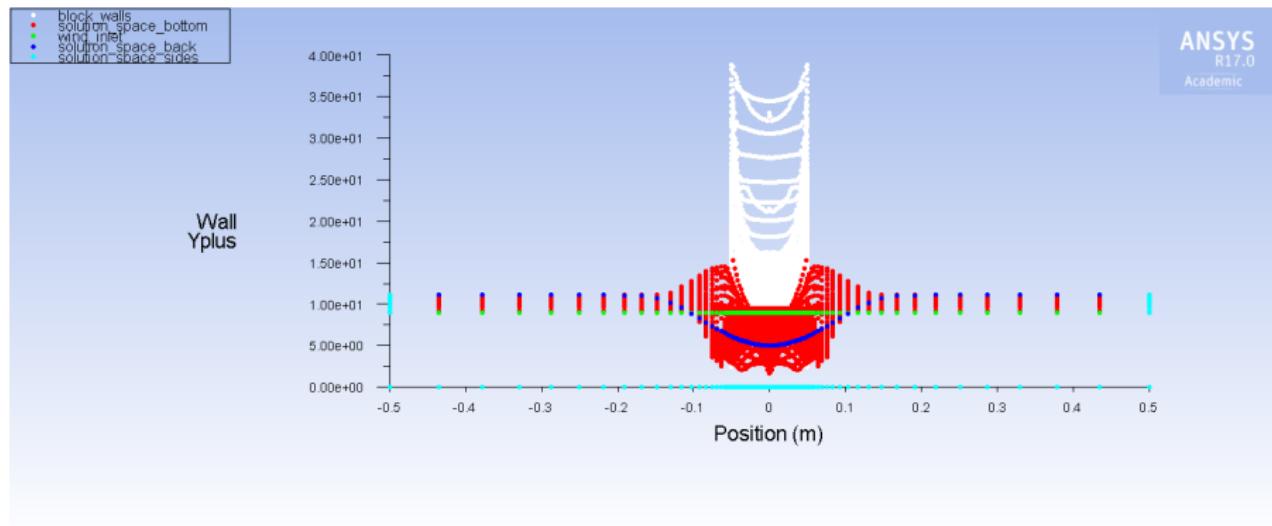


$$\frac{U}{u_*} = \frac{1}{\kappa} \ln(y^+) + B$$

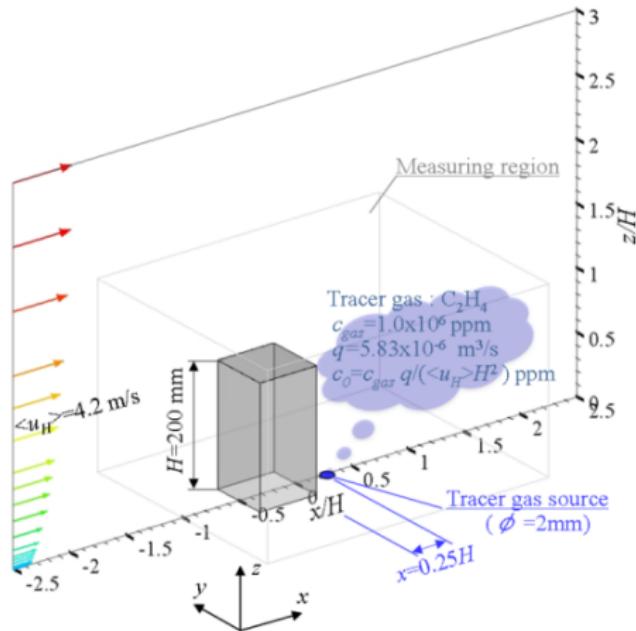
Meshing Cont.



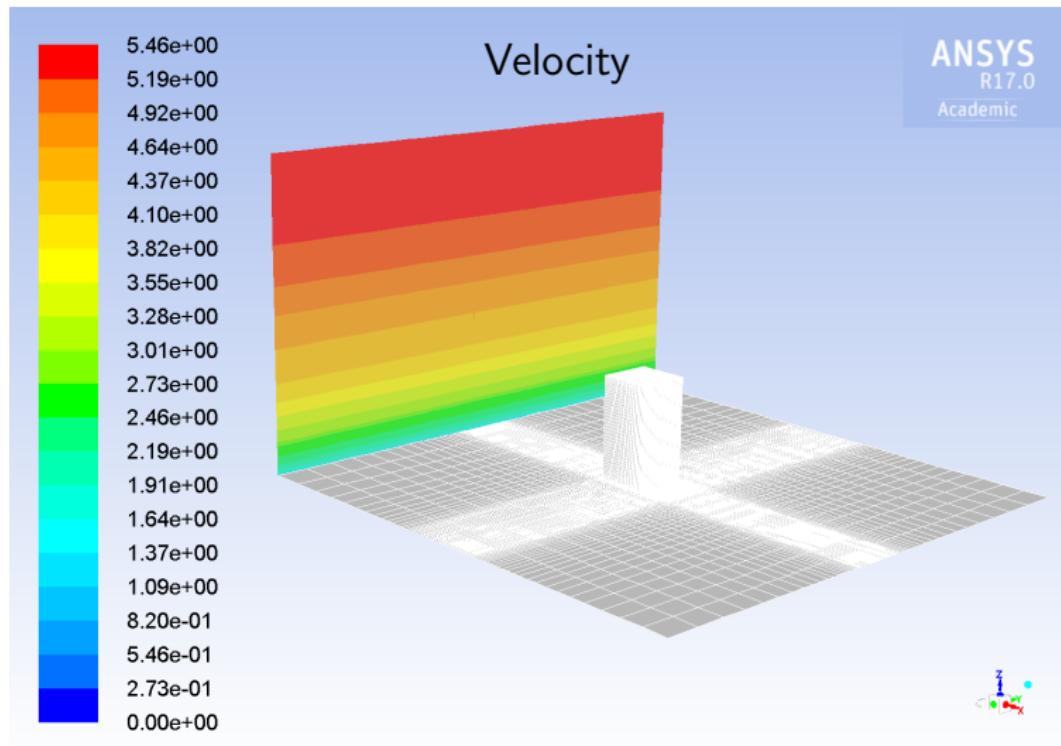
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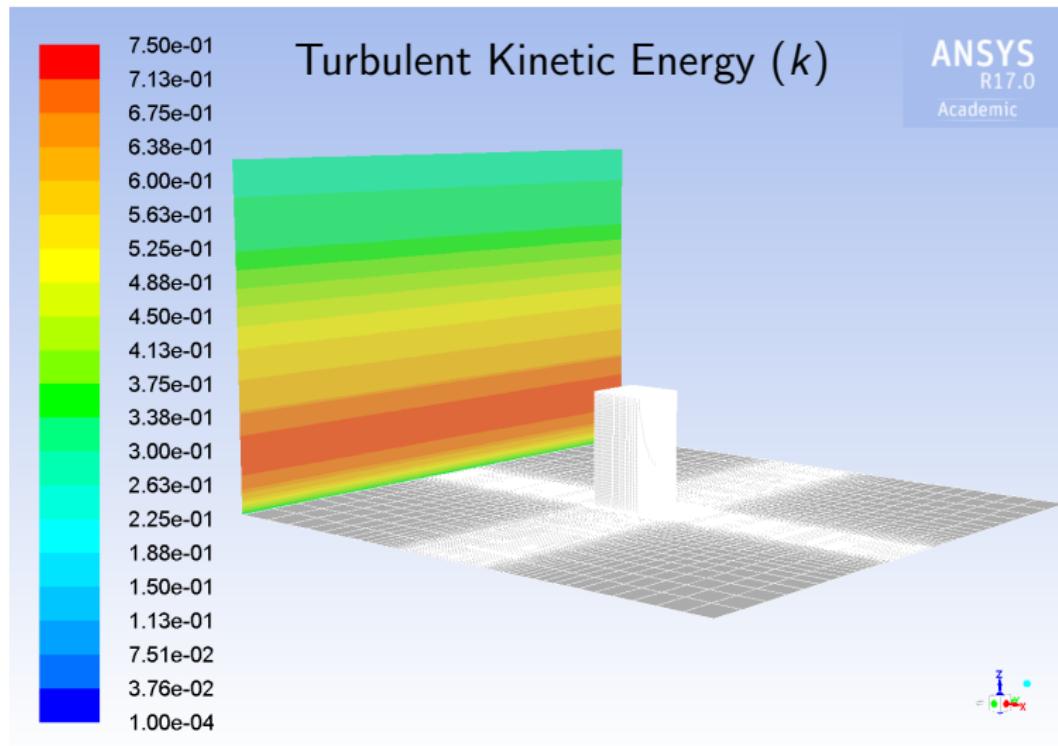
Boundary Conditions and Parameters



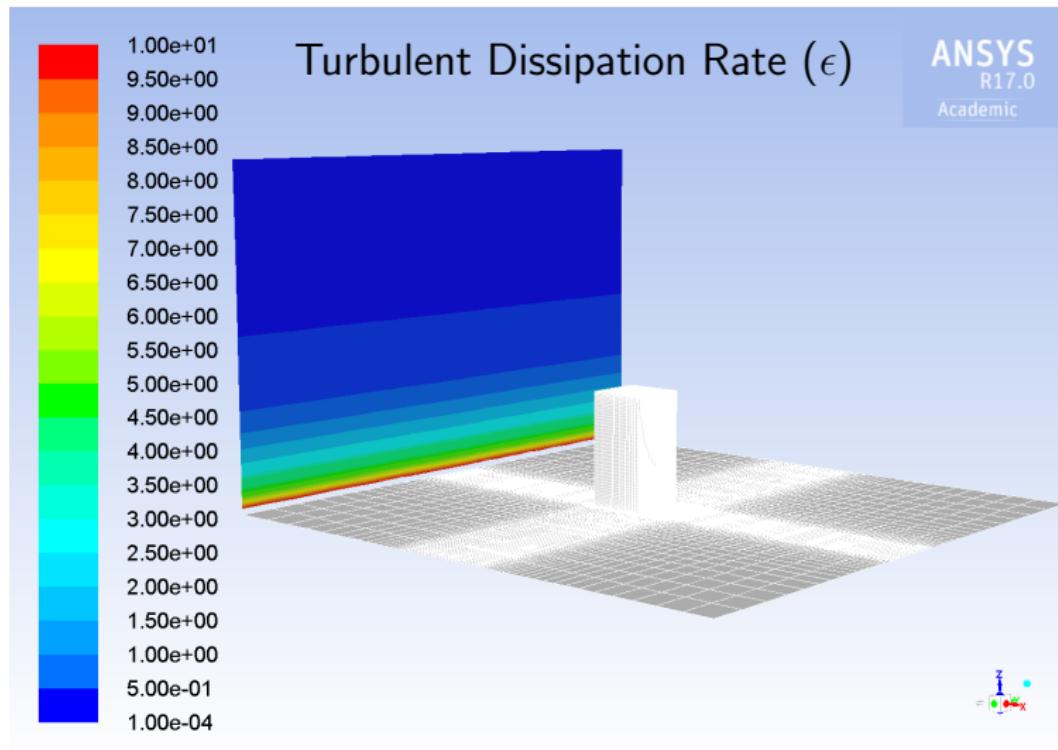
Boundary Conditions and Parameters Cont.



Boundary Conditions and Parameters Cont.



Boundary Conditions and Parameters Cont.



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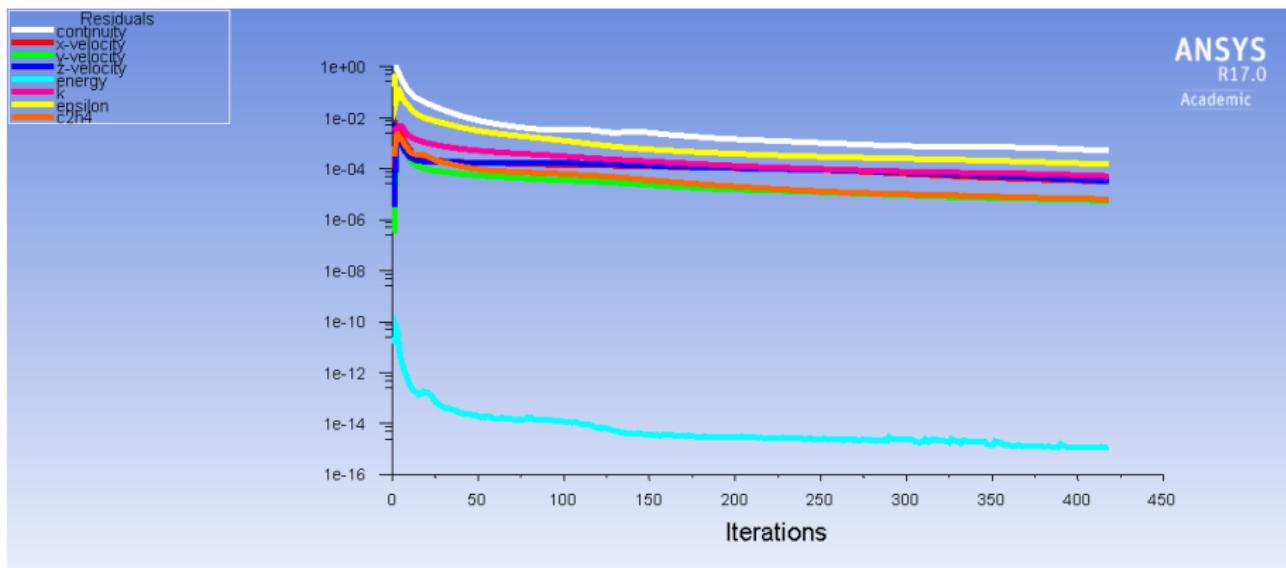
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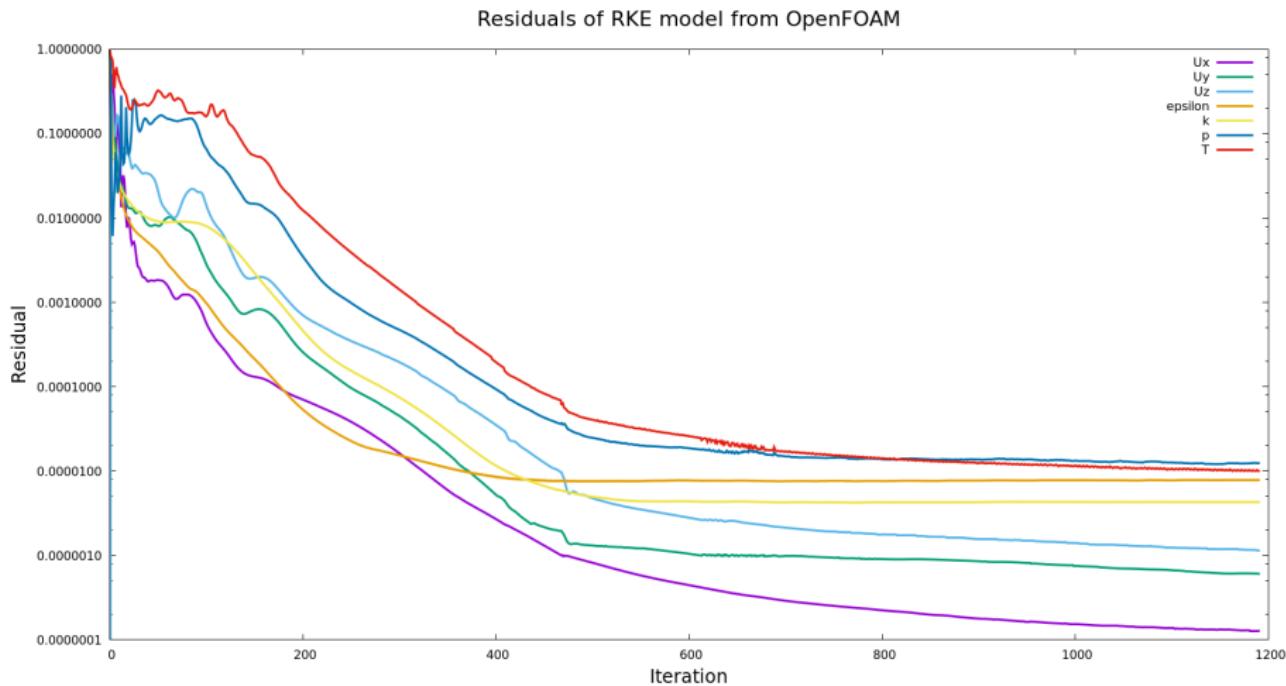
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Results



Results Cont.



Results Cont.

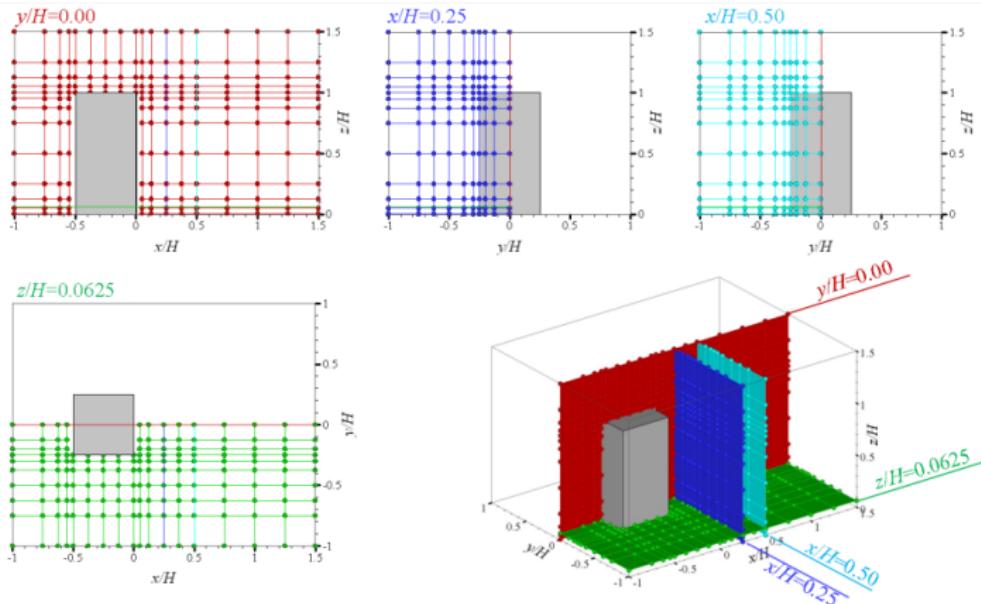
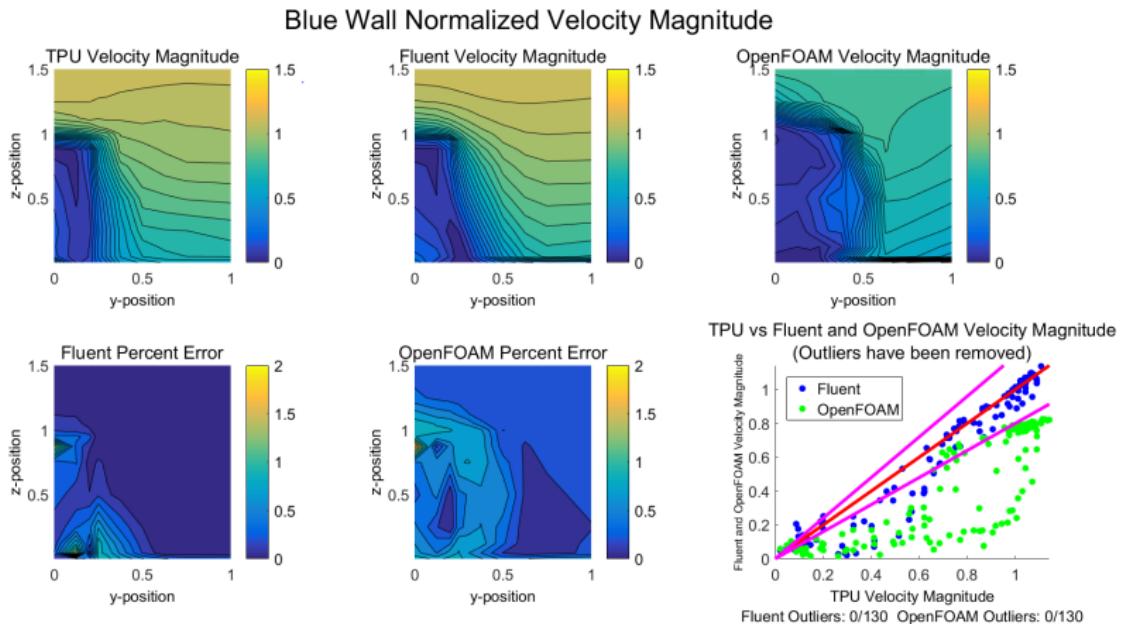


Figure 3 Measurement Point Locations

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Results Cont.



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Analysis: Velocity Magnitude

	Blue		Cyan		Green		Red	
	Fluent	FOAM	Fluent	FOAM	Fluent	FOAM	Fluent	FOAM
Percent Mean Absolute Error	0.18	0.62	0.26	0.52	0.43	0.64	0.44	1.17
Percent Median Absolute Error	0.05	0.16	0.09	0.18	0.38	0.38	0.20	0.36
Fraction of Error Less Than 50%	0.89	0.82	0.86	0.77	0.57	0.65	0.76	0.62

Analysis: Concentration

	Blue		Cyan		Green		Red	
	Fluent	FOAM	Fluent	FOAM	Fluent	FOAM	Fluent	FOAM
Percent Mean Absolute Error	0.82	6.91	0.62	1.00	0.75	2.16	0.53	9.67
Percent Median Absolute Error	0.85	1.01	0.65	1.00	0.56	1.01	0.53	1.12
Fraction of Error Less Than 50%	0.24	0.06	0.36	0.00	0.45	0.12	0.47	0.10

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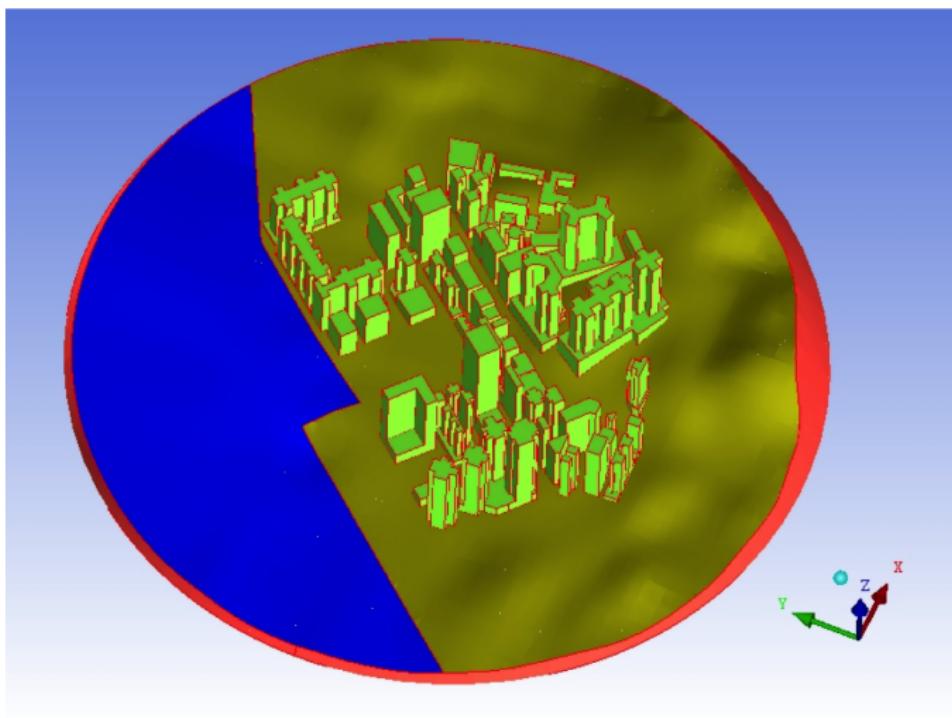
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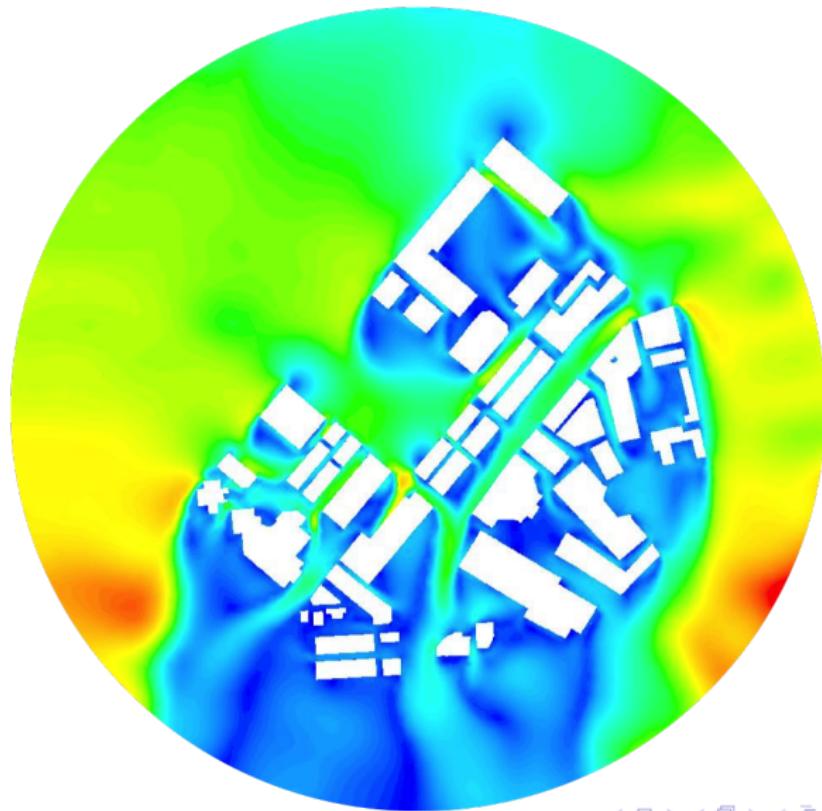
Conclusions

- Testing with Fluent justifies our choice for using the realizable $k - \epsilon$ turbulence model for this one-block case
- Comparisons between Fluent and OpenFoam show that OpenFoam does not perform as well as Fluent for the one-block case
- Future work includes refining the mesh, tuning parameters, using different solvers, and simulating other geometric models

Future Work



Future Work



Acknowledgements



Bibliography I

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Thank you for listening.

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Any Questions?