### MATH544 Notes

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# Chapter 1

# **Pre-Class**

#### 1.1 Number Fields

**Definition 1.1.1.** A field is any set  $\mathbb{K}$  which follow the Field Axioms:

- 1.  $\alpha + \beta = \beta + \alpha$  (addition is commutative).
- 2.  $(\alpha + \beta) + \gamma = \alpha + (\beta + \gamma)$  (addition is associative).
- 3. There exists an element 0 such that  $\alpha + 0 = \alpha$ .
- 4. For every  $\alpha \in \mathbb{K}$ , there exists  $\beta$  such that  $\alpha + \beta = 0$ .
- 5.  $\alpha\beta = \beta\alpha$  (multiplication is commutative).
- 6.  $(\alpha\beta)\gamma = \alpha(\beta\gamma)$  (multiplication is associative).
- 7. There exists an element 1 such that  $1 \cdot \alpha = \alpha$ .
- 8. For every  $\alpha$  there exists a  $\gamma$  such that  $\alpha \gamma = 1$ .
- 9.  $\alpha(\beta + \gamma) = \alpha\beta + \alpha\gamma$ , multiplication is distributive over addition.

**Definition 1.1.2.** Two fields,  $\mathbb{K}$  and  $\mathbb{K}'$  are said to be **isomorphic** if we can setup a one to one correspondence between  $\mathbb{K}$  and  $\mathbb{K}'$ .

The most common fields are,  $\mathbb{Q}$ ,  $\mathbb{R}$ ,  $\mathbb{C}$ .

### 1.2 Theory of Linear Algebra

Involving space, and the most general case, a series of linear equations.

#### 1.3 Determinant

The determinant is the scalar that a 1 area, volume, hypervolume etc. gets scaled by. Even a one length can be scaled or reduced to 0. When a determinant is 0, it means that all space, gets squished to a lower dimension and thus has 0 volume, or 0 area, and so on.

$$D = \begin{vmatrix} a_{11} & a_{12} & \dots & a_{1n} \\ a_{21} & a_{22} & \dots & a_{2n} \\ \vdots & \vdots & \ddots & \vdots \\ a_{n1} & a_{2n} & \dots & a_{nn} \end{vmatrix} = \det ||a||$$

### 1.4 Acknowledgements

Almost none of this work is of my own. This work is from *Linear Algebra* by George Shilov. And lecture notes from Dr. Matt Miller's MATH544H class taught at the University of South Carolina in the Spring of 2019.

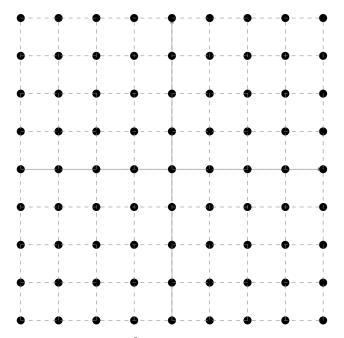


Figure 1.1: Vector Space  $\mathbb{R}^2$  for  $\forall (x,y); -4 \leq x \leq 4$  and  $-4 \leq y \leq 4$ .

# Chapter 2

## Lectures

### 2.1 14 January 2019

**Definition 2.1.1.** Linear Algebra is the study of vector spaces and the maps between them.

**Definition 2.1.2.** A function  $T: V \to W$ , from vector space V, the domain, to vector space W, the codomain, is called a linear transformation if

$$T(c\vec{u}+\vec{v})=cT(\vec{u})+T(\vec{v});\ \forall \vec{u},\vec{v}\in V \land c\in \mathbb{R}$$

Example 2.1.1.

$$T: \mathbb{R} \to \mathbb{R}; \ T(x) = 2x$$
 
$$T(cu+v) = 2cu+v = cT(u) + T(v)$$

So this is a linear transformation.

#### Example 2.1.2.

$$C^0[0,2\pi] = \{f: [0,2\pi] \to \mathbb{R} \mid f \text{ is continuous}\}$$
 
$$S: C^0[0,2\pi] \to \mathbb{R}$$

$$S(f) = f(\pi)$$

Check linearity.

$$S(cf + g) = (cf + g)(\pi) = cf(\pi) + g(\pi) = cS(f) + S(g)$$

Example 2.1.3.

Let 
$$T: C^0[0, 2\pi] \to \mathbb{R}$$

$$T(f) = \bar{f}$$

$$T(f) = \frac{1}{2\pi} \int_0^{2\pi} f(x) \ dx$$

Check linearity.

$$T(cf+g) = \frac{1}{2\pi} \int_0^{2\pi} (cf+g)(x) dx$$

$$T(cf+g) = \frac{1}{2\pi} (c \int_0^{2\pi} f(x) dx + \int_0^{2\pi} g(x) dx)$$

$$T(cf+g) = cT(f) + T(g)$$

 $\mathbb{R}^2$  and  $\mathbb{R}^3$  are vector spaces, (x,y) is mapped to the vector  $\begin{bmatrix} x \\ y \end{bmatrix}$  and (x,y,z) is mapped to the vector  $\begin{bmatrix} x \\ y \\ z \end{bmatrix}$ .

**Example 2.1.4.** Let  $T: \mathbb{R}^2 \to \mathbb{R}^3$  be defined by

$$T(\begin{bmatrix} x \\ y \end{bmatrix}) = \begin{bmatrix} x+3y \\ -x+y \\ 2x+y \end{bmatrix}$$

Verify linearity.

$$T(c \begin{bmatrix} x \\ y \end{bmatrix} + \begin{bmatrix} z \\ w \end{bmatrix}) = T(\begin{bmatrix} cx+z \\ cy+w \end{bmatrix} = \begin{bmatrix} cx+z+3cu+3w \\ -cx-z+cy+w \\ 2cx+2z+cy+w \end{bmatrix}$$

$$T(c \begin{bmatrix} x \\ y \end{bmatrix} + \begin{bmatrix} z \\ w \end{bmatrix}) = \begin{bmatrix} cx + 3cu \\ -cx + cy \\ 2cx + cy \end{bmatrix} + \begin{bmatrix} z + 3w \\ -z + w \\ 2z + w \end{bmatrix}$$

$$T(c \begin{bmatrix} x \\ y \end{bmatrix} + \begin{bmatrix} z \\ w \end{bmatrix}) = c \begin{bmatrix} x + 3u \\ -x + y \\ 2x + y \end{bmatrix} + \begin{bmatrix} z + 3w \\ -z + w \\ 2z + w \end{bmatrix}$$

$$T(c \begin{bmatrix} x \\ y \end{bmatrix} + \begin{bmatrix} z \\ w \end{bmatrix}) = cT(\begin{bmatrix} x \\ y \end{bmatrix}) + T(\begin{bmatrix} z \\ w \end{bmatrix})$$

This transformation is the same as the matrix transformation,  $\begin{bmatrix} 1 & 3 \end{bmatrix}$ 

$$\begin{bmatrix} 1 & 3 \\ -1 & 1 \\ -2 & 1 \end{bmatrix}.$$

**Definition 2.1.3.** Let  $T:V\to W$  be a linear transformation. The range or image of T is the set range (T).

