studynotes

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November 12, 2016

1 Notes

1.1 Calculus

1.1.1 W8

- 1. Integration of Rational Functions, Section 9.5 for shit in the form of $f(x) = \frac{g(x)}{h(x)}$
 - (a) If the numerator is a higher degree function than the denominator, must use long division
 - \bullet \square Add example to cheat sheet
 - (b) Use partial fractions to separate function
 - Factorise denominator first, to split
 - do the other stuff you need to do (shouldn't need an example for this)
 - (c) Integrate as normal
- 2. Improper Integrals, Section 9.6 An integral is **improper** if it is unbounded at an end point, or if an endpoint is infinite.
 - \square Add example to cheat sheet (be sure to include the limits)
- 3. Taylor Polynomials, Sections 10.1-10.2 **Lagrange's Remainder Theorem** $En(x) = \frac{f^{(n+1)}(x_0)}{(n+1)!}(x-a)^{n+1}$ Used for determining the error in the approximation

Taylor Polynomials
$$\sum_{i=0}^n \frac{f^{(i)}(a)}{i!} (x-a)^i$$

 \bullet \square Defs example for this one

1.1.2 W9

1. Taylor Series, Sections 10.3-10.5 The **Taylor Series** of f about a is the infinite sum: $\sum_{i=0}^{\infty} \frac{f^{(i)}(a)}{i!} (x-a)^i$

I don't have a fucking clue how to do these, so do make sure to

 \bullet \square include an example

1.1.3 W10

1. Differential Equations, Section 11.1-11.5 **Ordinary**: single variable An **ODE** is <u>separable</u> if it can be written in the form: $f(y)\frac{dy}{dx} = g(x)$ Solve by "multiplying by dx" and integrating: $\int f(y)dy = \int g(x)dx$

First Order Linear DEs y' + p(x)y = q(x) if q(x) = 0, this is separable, and solvable using: $y = e^{-P(x)} \int e^{P(x)} q(x) dx$, where p'(x) = p(x)

- \bullet \square example of something similar the salt water one, or practise several of them
- 2. Functions of Several Variables, Section 12.1 just graphs of shit, hopefully not important LUL

1.1.4 W11

- 1. Domains and Subsets of Rⁿ, Section 12.2 IDEK FUCK ME DADDY
- 2. Limits and Continuity, Section 13.1
- 3. Partial Derivatives, Section 13.1 $\frac{\delta f}{\delta x} = f_1 = D_1 f$ for $\frac{\delta f}{\delta x}$, differentiate for x, treat y as a constant, opposite for y for the more complicated shit, $\frac{\delta^2 f}{\delta x \delta y} = \frac{\delta f}{\delta y} (\frac{\delta f}{\delta x})$ and such like Theorem of $\frac{\delta^2 f}{\delta x \delta y} (a, b) = \frac{\delta^2 f}{\delta y \delta x} (a, b)$. If this isn't working, check continuity of function
- 4. Linear Approximation, Section 13.2 $f(x + \Delta x, y + \Delta y) \approx f(x, y) + \frac{\delta f}{\delta x}(x, y)\Delta x + \frac{\delta f}{\delta y}(x, y)\Delta y$ the differential of f(x,y) at (a,b) is $df(a, b) = \frac{\delta f}{\delta x}(a, b)dx + \frac{\delta f}{\delta y}(a, b)dy$
 - $\bullet \square$ example?
- 5. Differentiability, Section 13.3 hand write this formula, fuck putting that in \LaTeX f differentiable at (a,b) => f continuous at (a,b)

6. The Chain Rule, Section 13.4 hand write this as well, it's gay to write but doesn't seem too hard to use, maybe an example but probs not as long as I've practiced some of them

1.1.5 W12

- 1. Gradients and Directional Derivatives, Section 13.5 $\frac{\delta f}{\delta x}$ measures RoC in x-direction $\frac{\delta f}{\delta y}$ measures RoC in y-direction The gradient of f is: $\nabla f = \frac{\delta f}{\delta x}\vec{i} + \frac{\delta f}{\delta y}\vec{j}(+\frac{\delta f}{\delta z}\vec{k})$ looooot of shit for this one, make sure to practise
- 2. Extrema and Optimisation, Section 13.6 Critical points:

Stationary point where $\nabla f(a, b) = 0$

Singular point where $\nabla f(a,b)$ does not exist

Boundary point where (a,b) is on the boundary of the domain of f

Local min/max can only occur at critical points there is a lot more than this, make sure to get the important parts

3. Multivariable Integration, Sections 14.1-14.2

1.1.6 W13

1. More Multivariable Integration, Sections 14.3-14.5

1.2 Algebra

1.2.1 W8

- 1. Complex Numbers, Lay App. B, Adams App. 1
- 2. Invertibale Matrices, Lay 2.2-2.3

1.2.2 W9

1. Determinants, Lay 3.1-3.2

1.2.3 W10

1. More Determinants, Lay 3.2-3.3

1.2.4 W11

- 1. Eigenvectors and Eigenvalues, Lay 5.1-5.2
- 2. Diagonalisation, Lay 5.3
- 3. Eigenvectors and Linear Transformations, Lay 5.4 (unfinished)

1.2.5 W12

- 1. Eigenvectors and Linear Transformations, rest of Lay 5.4
- 2. Applications to Differential Equations, Lay 5.7 (unfinished)
- 3. Complex Eigenvalues, Lay 5.5 (unfinished)

1.2.6 W13

- 1. More Complex Eigenvalues, Factoring as A=PCP⁻¹, rest of Lay 5.5
- 2. Discrete and Continuous Dynamical System, Lay 5.6-5.7

2 TODOstuff

- 2.1 TODO Include examples noted in ^
- 2.2 TODO Be sure of how to compute the various spaces and their bases of a matrix