MATH 3940 Problem Set 1 Solutions - Matlab

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Question 2: (a) >> A=[-1\ 2\ 2\ 5\ 1; 0\ 3\ 1\ 2\ 1; 1\ -4\ 1\ 0\ -2; 0\ 5\ 3\ 1\ 1; 3\ -6\ 0\ 4\ 3];
>> det(A)
ans = 282.0000
\gg inv(A)
ans = -0.4929 1.2234 0.3475 -0.1950 0.0532
      0.1738 -0.7766 0.0142 0.4716 0.0532
      0.1241 -0.8404 -0.4184 0.3369 0.1809
(b) >> B=[ 7 5 9 2 -1]';
>> x = A \setminus B
x = 5.3511
     1.9787
    -1.6489
     3.6596
    -6.6064
Question 3: (b) Using the Matlab command lu, we find that
>> A=[0 1 2 -1; 1 1 -1 0; -1 -1 1 3; 1 2 0 1];
>> [L U P]=lu(A)
L = 1 0 0 0
    0 1 0 0
    1 1 1 0
   -1 0 0 1
U = 1 \quad 1 \quad -1 \quad 0
   0 1 2 -1
      0 -1 2
     0 0 3
   0
P = 0 \quad 1 \quad 0 \quad 0
  1 0 0 0
  0 0 0 1
  0 0 1 0
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>> B=[-1 5 1 9]';
We write this forward substitution program in M file
function X=forsub(A,B)
% A is an n x n lower triangular nonsingular matrix and B is an n x 1 matrix. Find the dimension of B and initialize X
n=length(B);
X=zeros(n,1);
X(1)=B(1)/A(1,1);
for k=2:n
X(k)=(B(k)-A(k,1:k-1)*X(1:k-1))/A(k,k);
End
We recall in Matlab as follows:
>> Y=forsub(L,P*B)
Y = 5
     -1
      5
      6
Then we use the backward substitution program in M file
function X=backsub(A,B)
% A is an n x n upper triangular nonsingular matrix and B is n x 1 matrix. Find the dimension of B and initialize X
n=length(B);
X=zeros(n,1);
X(n)=B(n)/A(n,n);
for k=n-1:-1:1
X(k)=(B(k)-A(k,k+1:n)*X(k+1:n))/A(k,k);
end
>> X=backsub(U,Y)
X = 1
     3
    -1
     2
Question 4:
(b) >> A=[1 2 -1; 2 8 -4; -1 -4 3];
>> U=chol(A)
U = 1 2 -1
     0 2 -1
     0 0 1
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>> B=[ -1 -10 7]';
Using forward substitutions and backward substitution program from previous question,
>> Y=forsub(U',B)
Y = -1
      -4
      2
>> X=backsub(U,Y)
X = 3
     -1
      2
Question 5: (b) M file for Jacobi method is function [X,k]=jacobi2(A,B,P,tol,maxite)
%A is an N X N nonsingular matrix, B is an N X 1 nonsingular matrix,
% P is an N X 1 nonsingular matrix initial guess, tol is tolerance for P
N=length(B);
for k=1:maxite
  for j=1:N
    X(j)=(B(j)-A(j,[1:j-1,j+1:N])*P([1:j-1,j+1:N]))/A(j,j);
  end
  error=abs(norm(X'-P));
  relerr=error/norm(X);
  P=X';
   if (error<tol) | (relerr<tol)</pre>
   break
end
end
X=X';
>> A=[1 2 -1; 2 8 -4; -1 -4 3];
>> B=[0 6 -2]';
>>[X,k]=jacobi2(A,B,[0 0 0]',10^(-6),35)
X = 1.0e + 04 *
 6.5540
  2.5961
 -4.0179
k = 35
                   The iterations diverge.
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(d) M file for Gauss-Siedel method is
function [X,k]=gauseid(A,B,P,tol,maxite)
%A is an N X N nonsingular matrix, B is an N X 1 nonsingular matrix,
% P is an N X 1 nonsingular matrix initial guess, tol is tolerance for P
Digits=8;
N=length(B);
for k=1:maxite
  for j=1:N
    if j==1
      X(1)=(B(1)-A(1,2:N)*P(2:N))/A(1,1);
    elseif j==N
      X(N)=(B(N)-A(N,1:N-1)*(X(1:N-1))')/A(N,N);
    else
      %X contains the kth approximations and P the (k-1)st
    X(j)=(B(j)-A(j,1:j-1)*(X(1:j-1))'-A(j,j+1:N)*P(j+1:N))/A(j,j);
  end
end
  error=norm(X'-P);
  relerr=error/norm(X);
  P=X';
  if (error<tol) | (relerr<tol)</pre>
  break
end
end
X=X';
>> A=[1 2 -1; 2 8 -4; -1 -4 3];
>> B=[0 6 -2]';
>> [X, k]=gauseid(A,B,[0 0 0]',10^(-6),35)
X = -3.0000
     2.0000
     1.0000
k = 33
```

The iterations converge in 33 iterations.