

## Triangular Factorization (Matrix Factorization)

If  $A$  is a non-singular matrix, then the linear system  $Ax=B$  can be solved by using Gaussian elimination. Another method is that we factor the matrix  $A$  in terms of a lower triangular matrix and an upper triangular matrix. Then we can use forward and backward substitution to solve the system.

**Case 1: The Gaussian elimination** is performed without any row interchanges. That is, no pivoting and  $a_{kk} \neq 0$  for all  $k=0, 1, 2, \dots, N$ .

In this case the matrix  $A$  can be factored as  $A=LU$  where

$$\underbrace{\begin{bmatrix} a_{11} & a_{12} & a_{13} & \cdots & a_{1N} \\ a_{21} & a_{22} & a_{23} & \cdots & a_{2N} \\ a_{31} & a_{32} & a_{33} & \cdots & a_{3N} \\ \vdots & \vdots & \vdots & & \vdots \\ a_{N1} & a_{N2} & a_{N3} & \cdots & a_{NN} \end{bmatrix}}_{\mathbf{A}} = \underbrace{\begin{bmatrix} 1 & 0 & 0 & \cdots & 0 \\ m_{21} & 1 & 0 & \cdots & 0 \\ m_{31} & m_{32} & 1 & \cdots & 0 \\ \vdots & \vdots & \vdots & & \vdots \\ m_{N1} & m_{N2} & m_{N3} & \cdots & 1 \end{bmatrix}}_{\mathbf{L}} \underbrace{\begin{bmatrix} u_{11} & u_{12} & u_{13} & \cdots & u_{1N} \\ 0 & u_{22} & u_{23} & \cdots & u_{2N} \\ 0 & 0 & u_{33} & \cdots & u_{3N} \\ \vdots & \vdots & \vdots & & \vdots \\ 0 & 0 & 0 & \cdots & u_{NN} \end{bmatrix}}_{\mathbf{U}}$$

$$U_{kk} \neq 0 \text{ for } k = 1, 2, \dots, N$$

All diagonal entries of  $L$  are 1, ( $l_{kk} = 1$  for  $k = 1, 2, \dots, N$ ).

$m$ 's are multipliers calculated during the process of Gaussian elimination.

To solve the system  $Ax=B$

( $x$  is a solution)

$$\underbrace{LU}_{\mathbf{y}} x = B \quad (*)$$

$$\text{Let } UX = y \stackrel{(*)}{\Rightarrow} Ly = B$$

First, we solve  $Ly = B$  by using forward substitution (b/c lower triangular matrix)  
and then solve  $Ux = y$  by using back substitution.

**Example 1:** Consider the system

$$\begin{aligned}x_1 + 4x_2 + 3x_3 &= 1 \\2x_1 + 5x_2 + 4x_3 &= 4 \\x_1 - 3x_2 - 2x_3 &= 5\end{aligned}$$

**Find LU decomposition** of the coefficient matrix A with no pivoting.  
Then **solve** the resulting system using forward and back substitution.

**Solution:**

$$A = \begin{bmatrix} 1 & 4 & 3 \\ 2 & 5 & 4 \\ 1 & -3 & -2 \end{bmatrix}$$

$$\begin{aligned}m_{21} &= \frac{2}{1} = 2 & R_2 - 2R_1 \rightarrow R_2 \\m_{31} &= \frac{1}{1} = 1 & R_3 - R_1 \rightarrow R_3\end{aligned} \quad \begin{bmatrix} 1 & 4 & 3 \\ 0 & -3 & -2 \\ 0 & -7 & -5 \end{bmatrix}$$

$$m_{32} = -\frac{7}{-3} = \frac{7}{3} \quad R_3 - \frac{7}{3}R_2 \rightarrow R_3 \quad \begin{bmatrix} 1 & 4 & 3 \\ 0 & -3 & -2 \\ 0 & 0 & -\frac{1}{3} \end{bmatrix}$$

↓  
U

$R_3$	0	-7	-5
$\frac{7}{3}R_2$	0	-7	$-\frac{14}{3}$
	-	+	+
	0	0	$-\frac{1}{3}$

We have  $A = LU$  where  $L = \begin{bmatrix} 1 & 0 & 0 \\ m_{21} & 1 & 0 \\ m_{31} & m_{32} & 1 \end{bmatrix} = \begin{bmatrix} 1 & 0 & 0 \\ 2 & 1 & 0 \\ 1 & \frac{7}{3} & 1 \end{bmatrix}$  and  $U = \begin{bmatrix} 1 & 4 & 3 \\ 0 & -3 & -2 \\ 0 & 0 & -\frac{1}{3} \end{bmatrix}$

First, we solve  $Ly = B \Rightarrow \begin{bmatrix} 1 & 0 & 0 \\ 2 & 1 & 0 \\ 1 & \frac{7}{3} & 1 \end{bmatrix} \begin{bmatrix} y_1 \\ y_2 \\ y_3 \end{bmatrix} = \begin{bmatrix} 1 \\ 4 \\ 5 \end{bmatrix}$

$$\begin{aligned}y_1 &= 1 & \Rightarrow & y_1 = 1 \\2y_1 + y_2 &= 4 & \Rightarrow & 2(1) + y_2 = 4 & \Rightarrow & y_2 = 2 \\y_1 + \frac{7}{3}y_2 + y_3 &= 5 & \Rightarrow & 1 + \frac{7}{3}(2) + y_3 = 5 & \Rightarrow & y_3 = 5 - 1 - \frac{14}{3} = -\frac{2}{3}\end{aligned}$$

$$\Rightarrow y = \begin{bmatrix} y_1 \\ y_2 \\ y_3 \end{bmatrix} = \begin{bmatrix} 1 \\ 2 \\ -\frac{2}{3} \end{bmatrix}$$

Now we solve  $UX = y \Rightarrow \begin{bmatrix} 1 & 4 & 3 \\ 0 & -3 & -2 \\ 0 & 0 & -\frac{1}{3} \end{bmatrix} \begin{bmatrix} x_1 \\ x_2 \\ x_3 \end{bmatrix} = \begin{bmatrix} 1 \\ 2 \\ -\frac{2}{3} \end{bmatrix}$

$$x_1 + 4x_2 + 3x_3 = 1$$

$$-3x_2 - 2x_3 = 2$$

$$-\frac{1}{3}x_3 = -\frac{2}{3} \Rightarrow x_3 = 2$$

$$(2) \Rightarrow -3x_2 - 2(2) = 2 \Rightarrow -3x_2 = 6 \Rightarrow x_2 = -2$$

$$(1) \Rightarrow x_1 + 4(-2) + 3(2) = 1 \Rightarrow x_1 = 1 + 8 - 6 = 3$$

The solution is  $(x_1, x_2, x_3) = (3, -2, 2)$  or  $x = \begin{bmatrix} 3 \\ -2 \\ 2 \end{bmatrix}$  Ans

Computational complexity of backward substitution is of  $O(N^2)$ .  
Computational complexity of forward substitution is of  $O(N^2)$ .  
Computational complexity of Gaussian elimination is  $O(N^3)$ .  
Computational complexity of  $LU$  decomposition is  $O(N^3)$ .

50 x 50 system

$N=50$

$(50)^2 = 2500$  operations

$(50)^3 = 125000$  operations using  
more storage and time and more  
roundoff errors.

**In Gaussian elimination**, we start with  $[A|B]$

→ If  $B$  changes then we need to do all  
calculations again.

**In Lu decomposition**, we do not use  $B$ . The  $B$  is only used in forward substitution.

If a linear system is to be solved many times with same coefficient matrix  $A$  but with different  $B$ ,  
then LU decomposition is more efficient in terms of computational complexity.

However, if a system is to be solved only one time, then Gaussian elimination is used.

**Case 2:** When the **Gaussian elimination** is performed **with row interchanged**, that is, partial pivoting or any of  $a_{kk} = 0$


A permutation matrix  $P$  is an  $N \times N$  matrix obtained by row interchanges of the identity matrix  $I_N$ .

$P$  has only one nonzero entry in each row and column and that entry is 1.

In the case of row interchanges, we can factor  $PA$  in terms of lower triangular matrix and upper triangular matrix.

$$I = \begin{bmatrix} 1 & 0 & 0 & 0 \\ 0 & 1 & 0 & 0 \\ 0 & 0 & 1 & 0 \\ 0 & 0 & 0 & 1 \end{bmatrix}$$


$$R_2 \leftrightarrow R_4 \quad \begin{bmatrix} 1 & 0 & 0 & 0 \\ 0 & 0 & 0 & 1 \\ 0 & 0 & 1 & 0 \\ 0 & 1 & 0 & 0 \end{bmatrix}$$


  
 $P$

$$PA = LU \text{ where } L = \begin{bmatrix} 1 & 0 & \cdots & 0 \\ m_{21} & 1 & \cdots & 0 \\ \vdots & \vdots & \ddots & \vdots \\ m_{N1} & m_{N2} & \cdots & 1 \end{bmatrix} \text{ and } U = \begin{bmatrix} u_{11} & u_{12} & \cdots & u_{1N} \\ 0 & u_{22} & \cdots & u_{2N} \\ 0 & 0 & \cdots & u_{NN} \end{bmatrix}$$

In this case we need to switch rows of  $L$ , but we can only interchange the elements in the row which are permissible, i.e., they do not change the patterns of  $L$ .

To solve  $Ax=B$ , we multiply by  $P \Rightarrow PAX = PB$


  
 $LUX = PB$

Let  $UX = Y \Rightarrow LY = PB$

**First**, we solve  $LY = PB$  by forward substitution  
**and then** we solve  $UX = Y$  by backward substitution.

**Example 2:** Consider the system

$$\begin{aligned}x_1 + 4x_2 + 3x_3 &= 1 \\2x_1 + 5x_2 + 4x_3 &= 4 \\x_1 - 3x_2 - 2x_3 &= 5\end{aligned}$$

Find LU decomposition of the coefficient matrix A using partial pivoting, then solve the system using forward and backward substitution.

**Solution:**

$$A = \begin{bmatrix} 1 & 4 & 3 \\ 2 & 5 & 4 \\ 1 & -3 & -2 \end{bmatrix}$$

P

$$\begin{bmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 1 \end{bmatrix}$$

$$R_1 \leftrightarrow R_2 \begin{bmatrix} 2 & 5 & 4 \\ 1 & 4 & 3 \\ 1 & -3 & -2 \end{bmatrix}$$

$$R_1 \leftrightarrow R_2 \begin{bmatrix} 0 & 1 & 0 \\ 1 & 0 & 0 \\ 0 & 0 & 1 \end{bmatrix}$$

$$\begin{aligned}m_{21} &= \frac{1}{2} & R_2 - \frac{1}{2}R_1 \rightarrow R_2 \\m_{31} &= \frac{1}{2} & R_3 - \frac{1}{2}R_1 \rightarrow R_3\end{aligned} \quad \begin{bmatrix} 2 & 5 & 4 \\ 0 & \frac{3}{2} & 1 \\ 0 & -\frac{11}{2} & -4 \end{bmatrix}$$

$$\left| -\frac{11}{2} \right| > \left| \frac{3}{2} \right| \quad R_2 \leftrightarrow R_3 \quad \begin{bmatrix} 2 & 5 & 4 \\ 0 & -\frac{11}{2} & -4 \\ 0 & \frac{3}{2} & 1 \end{bmatrix} \quad \begin{bmatrix} 0 & 1 & 0 \\ 0 & 0 & 1 \\ 1 & 0 & 0 \end{bmatrix}$$

P

$$m_{32} = \frac{\frac{3}{2}}{-\frac{11}{2}} = -\frac{3}{11}$$

$$\begin{aligned}R_3 - \left(-\frac{3}{11}\right)R_2 &\rightarrow R_3 \\ \text{or } R_3 + \frac{3}{11}R_2 &\rightarrow R_3\end{aligned}$$

$$\begin{bmatrix} 2 & 5 & 4 \\ 0 & -\frac{11}{2} & -4 \\ 0 & 0 & -\frac{1}{11} \end{bmatrix}$$

U

$$L = \begin{bmatrix} 1 & 0 & 0 \\ m_{21} & 1 & 0 \\ m_{31} & m_{32} & 1 \end{bmatrix}$$

$R_1 \leftrightarrow R_2$  will not change anything.  
 $R_2 \leftrightarrow R_3$  will change  $m_{21}$  and  $m_{31}$

$$1 - \left(\frac{12}{11}\right) = \frac{11 - 12}{11}$$

$$\text{So here } L = \begin{bmatrix} 1 & 0 & 0 \\ m_{31} & 1 & 0 \\ m_{21} & m_{32} & 1 \end{bmatrix} = \begin{bmatrix} 1 & 0 & 0 \\ \frac{1}{2} & 1 & 0 \\ \frac{1}{2} & -\frac{3}{11} & 1 \end{bmatrix}$$

**To solve**, we first solve  $LY = PB$

$$PB = \begin{bmatrix} 0 & 1 & 0 \\ 0 & 0 & 1 \\ 1 & 0 & 0 \end{bmatrix} \begin{bmatrix} 1 \\ 4 \\ 5 \end{bmatrix} \xrightarrow{\downarrow} = \begin{bmatrix} 4 \\ 5 \\ 1 \end{bmatrix}$$

$$\begin{bmatrix} 1 & 0 & 0 \\ \frac{1}{2} & 1 & 0 \\ \frac{1}{2} & -\frac{3}{11} & 1 \end{bmatrix} \begin{bmatrix} y_1 \\ y_2 \\ y_3 \end{bmatrix} = \begin{bmatrix} 4 \\ 5 \\ 1 \end{bmatrix}$$

$$y_1 = 4$$

$$\frac{1}{2}y_1 + y_2 = 5 \quad \Rightarrow \quad \frac{1}{2}(4) + y_2 = 5 \quad \Rightarrow \quad y_2 = 3$$

$$\frac{1}{2}y_1 - \frac{3}{11}y_2 + y_3 = 1 \quad \Rightarrow \quad \frac{1}{2}(4) - \frac{3}{11}(3) + y_3 \quad \Rightarrow \quad y_3 = 1 - 2 + \frac{9}{11} = -\frac{2}{11}$$

$$\Rightarrow y = \begin{bmatrix} 4 \\ 3 \\ -\frac{2}{11} \end{bmatrix}$$

$$\text{Now we solve } Ux = Y \Rightarrow \begin{bmatrix} 2 & 5 & 4 \\ 0 & -\frac{11}{2} & -4 \\ 0 & 0 & -\frac{1}{11} \end{bmatrix} \begin{bmatrix} x_1 \\ x_2 \\ x_3 \end{bmatrix} = \begin{bmatrix} 4 \\ 3 \\ -\frac{2}{11} \end{bmatrix}$$

$$2x_1 + 5x_2 + 4x_3 = 4 \quad (1)$$

$$-\frac{11}{2}x_2 - 4x_3 = 3 \quad (2)$$

$$-\frac{1}{11}x_3 = -\frac{2}{11} \quad \Rightarrow \quad x_3 = 2$$

$$(2) \Rightarrow -\frac{11}{2}x_2 - 4(2) = 3 \quad \Rightarrow \quad -\frac{11}{2}x_2 = 11 \quad \Rightarrow \quad x_2 = -2$$

$$(1) \Rightarrow 2x_1 + 5(-2) + 4(2) = 4 \quad \Rightarrow \quad 2x_1 = 4 + 10 - 8 = 6 \quad \Rightarrow \quad x_1 = 3$$

The solution is  $(x_1, x_2, x_3) = (3, -2, 2)$  **Ans**

By default, MATLAB do partial pivoting for LU decomposition. MATLAB has a built-in command  $[L \ U \ P] = \text{lu}(A)$

```
>> A = [1 4 3; 2 5 4; 1 -3 -2];
```

```
>> [L U P] = lu(A)
```

output

$$L = \begin{bmatrix} 1 & 0 & 0 \\ 0.5 & 1 & 0 \\ 0.5 & -0.2727 & 1 \end{bmatrix}$$
$$U = \begin{bmatrix} 2 & 5 & 4 \\ 0 & -5.5 & -4 \\ 0 & 0 & -0.0909 \end{bmatrix}$$
$$P = \begin{bmatrix} 0 & 1 & 0 \\ 0 & 0 & 1 \\ 1 & 0 & 0 \end{bmatrix}$$

Do not write  $[L \ U] = \text{lu}(A)$  it will not give correct L and U

Also, if you only write

```
>> lu(A)
```

then it will return correct U but not L (not lower triangular)

Textbook has program for back substitution on page 123.

**You have to modify that program for forward substitution.**

using the x, you will solve the system