

# Visualizing Real-Time Flight Traffic with dump1090 and Elasticsearch

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#### What if you could track flights... yourself?





#### The Hardware: Realtek Software Defined Radio





# The Data Source: dump1090

Hex	Mode	Sqwk	Flight	Alt	Spd	Hdg	Lat	Long	RSSI	Msgs	Ti\ 🗏
A5A37D	S			1600	101	041			-12.6	3	1
A9FCD9	S	1200	N74237	2150	123	165	47.565	-122.544	-4.1	100	0
A533BD	S		UAL2741	3375	223	061	47.648	-122.433	-7.6	82	0
06A12F	S		QTR52X	39000	468	172	47.650	-122.733	-2.8	46	2



#### What I Wanted to Build

- Real-time flight dashboard
- Searchable, historical flight data
- Map of planes in Kibana using the Geospatial type





#### The Stack





# Connecting to dump1090

```
import socket

HOST = "localhost"
PORT = 30003 # SBS1 TCP output

sock = socket.socket(socket.AF_INET, socket.SOCK_STREAM)
sock.connect((HOST, PORT))
data = sock.recv(1024).decode("utf-8")
```



#### Parsing Flight Messages



#### Why is the data partial?

- Planes release small amounts of information instead of large payloads to reduce overall radio noise
- Each message is sent out 1 5 seconds based on what it is



### Defining the Mapping

```
mapping = {
       "mappings": {
            "properties": {
                "icao": {"type": "keyword"},
                "flight": {"type": "keyword"},
6
                "altitude": {"type": "integer"},
                "heading": {"type": "integer"},
8
                "location": {"type": "geo_point"},
9
                "timestamp": {"type": "date"},
                "speed": {"type": "integer"},
13 }
```



# Building a bigger picture

```
"_op_type": "update",
          "_index": "adsb-traffic,
          "_id": doc["icao"],
          "doc": update_doc,
          "doc_as_upsert": True,
6
           "upsert": {
               "icao": doc["icao"],
8
               "location": {"lat": doc["lat"], "lon": doc["lon"]},
               "altitude": doc["altitude"],
               "heading": doc["heading"],
               "speed": doc["speed"],
               "flight": doc["flight"],
               "timestamp": doc["timestamp"],
               "message_type": doc["message_type"],
           },
```

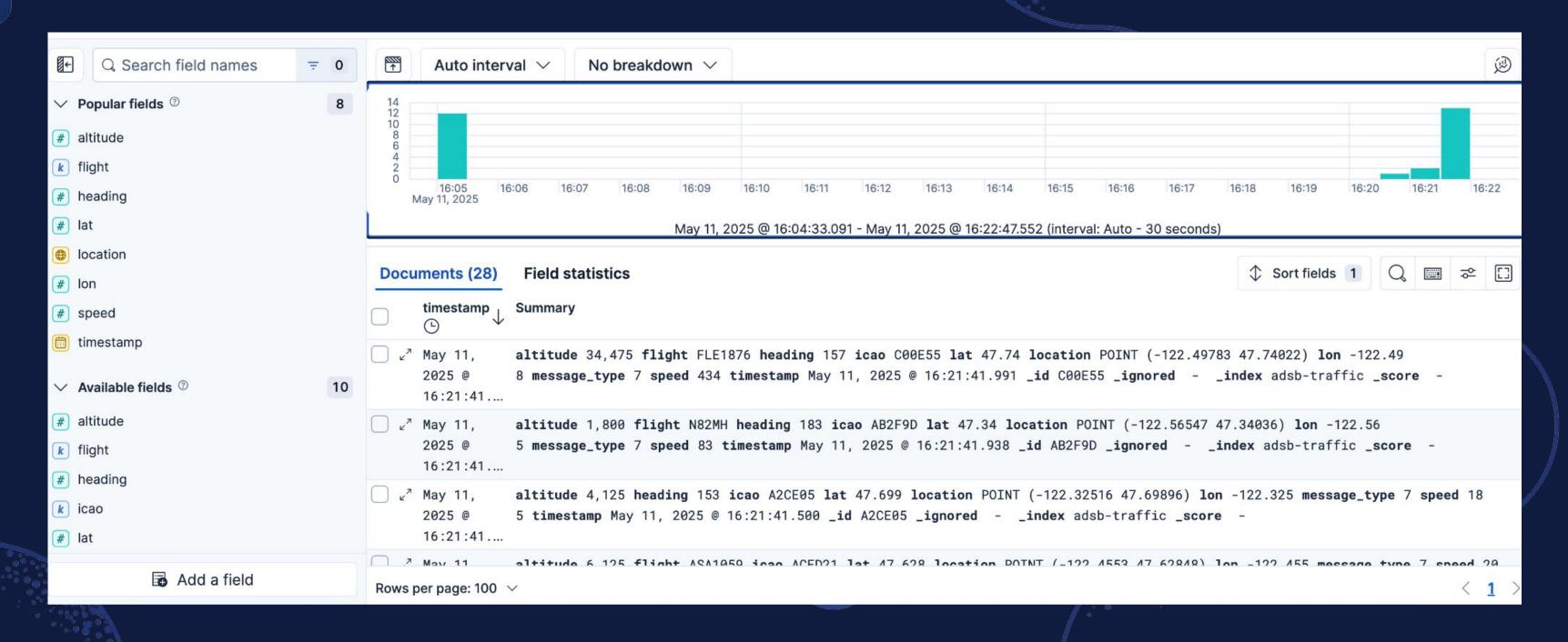


#### Connecting it all

- Read from dump1090
- Format lines into dictionaries
- Set up bulk action upsert
- Send bulk request
- Repeat

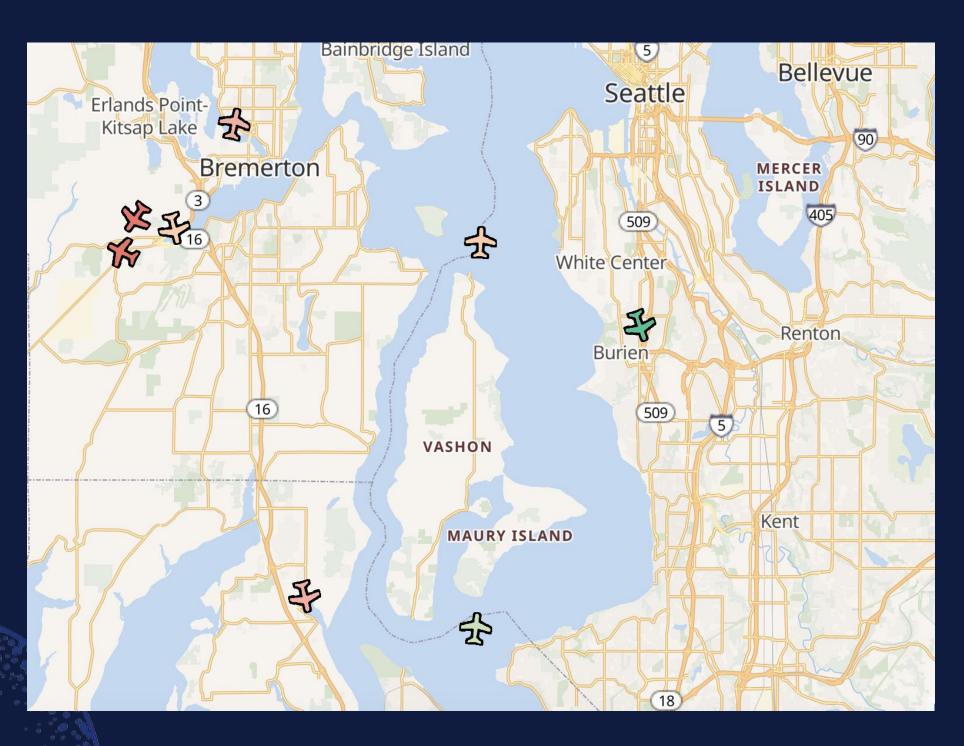


### Creating the Kibana Map





#### Creating the Kibana Map



#### So many tasty fields!

- Geopoint place on map
- Elevation color gradient
- Heading icon direction
- 20 minutes from NOW



## What I learned from this project (planes):

- Cessna Skyhawk 172 is THE most common plane
- Flight patterns are consistent
- Busy times
- Military doesn't always transpond
- Flight APIs are overpriced





### What I learned from this project (Elastic):

- doc\_as\_upsert is key to building documents over time from partial fragments
- Personal opinion: bulk actions client should be native or built out more, at least for Python



#### Dashboard enrichment

#### Future work to be done:

- Notifications for new or flagged aircraft
- Squawk notifications (7500 is bad)
- Visual flight path based on previous geopoint
- Bigger antenna



#### Challenges

- Elasticsearch document TTL (time-to-live)
  - Used to have native TTL support, but it was deprecated in version 5.0 and removed in 6.0.
  - Index Lifecycle Management, but that's brutish and coarse
  - Call a function to trim old timestamped documents?



#### Further Applications

- Marine Traffic is very similar
- Send and receive data packets and store in Elastic
- Organize CB communications
- Literally point at an object in the sky





### Thank you!

- Repository is available with BOM and links!
- We can share our data live!
- Planes are cool!

