# Learned Data Augmentation and Non-autoregressive Translation

Justin Chiu Cornell Tech jtc257@cornell.edu

October 28, 2021

5 Abstract

6 Abstract

2

3

## 7 1 Introduction

- 8 Learned models of data are often misspecified. When the goal of modeling is not density estimation,
- 9 but some alternative objective, this misspecification may lead to undesirable behaviour under the
- maximum likelihood objective. In this note, we consider learned data augmentation techniques to
- edit each data point so that the data as a whole is more amenable to learning for a particular model.

## 12 Problem Setup

Given data consisting of (x,y) pairs, our goal is to learn a model  $q(y \mid x)$  such that it maximizes some objective  $\mathbb{E}_{p(x,y)}$  [[]  $\operatorname{argmax}_{\hat{y}} D(q(\hat{y} \mid x),y)$ ], where D is some discrepancy measure between our prediction  $\hat{y}$  and the true output y. A concrete example of this is translation, where x is a source sentence (for example, German), y is a target sentence (for example, English), and D is the BLEU score between our generated translation and the true reference target sentence. Our goal is to, given a family of student models  $q_{\theta}(y \mid x)$  indexed by  $\theta$ , learn an edit model  $q_{\phi}(\hat{y} \mid y, x)$  whose conditional distribution over  $\hat{y}$  is easier for the student model  $q_{\theta}$  to learn.

#### 3 Method

### 21 References