Learned Data Augmentation and Non-autoregressive Translation

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5 Abstract

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7 1 Introduction

- 8 Learned models of data are often misspecified. When the goal of modeling is not density estimation,
- 9 but some alternative objective, this misspecification may lead to undesirable behaviour under the
- maximum likelihood objective. In this note, we consider learned data augmentation techniques to
- edit each data point so that the data as a whole is more amenable to learning for a particular model.

12 Problem Setup

Given data consisting of (x,y) pairs, our goal is to learn a model $q(y \mid x)$ such that it maximizes some objective $\mathbb{E}_{p(x,y)}\left[\operatorname{argmax}_{\hat{y}}D(q(\hat{y}\mid x),y)\right]$, where D is some discrepancy measure between our prediction \hat{y} and the true output y. A concrete example of this is translation, where x is a source sentence (for example, German), y is a target sentence (for example, English), and D is the BLEU score between our generated translation and the true reference target sentence. Our goal is to, given a family of student models $q_{\theta}(y \mid x)$ indexed by θ , learn an edit model $q_{\phi}(\hat{y} \mid y, x)$ whose conditional distribution over \hat{y} is easier for the student model q_{θ} to learn.

3 Method

21 References