# Word Games

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# Dialogue

- Communication is rarely unambiguous
  - Ambiguity resolution through dialogue
  - Clarification questions
- Interactive, symmetric reference games
  - Isolates ambiguity resolution
  - Both give and request information

### Games

#### Friends of agent A:

Name	School	Major	Company
Jessica Josh	Columbia Columbia	Computer Science Linguistics	Google Google

A: Hi! Most of my friends work for Google

B: do you have anyone who went to columbia?

A. Hello?

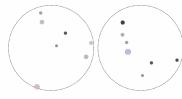
A: I have Jessica a friend of mine

A: and Josh, both went to columbia

B: or anyone working at apple?

B: SELECT (Jessica, Columbia, Computer Science, Google)

A: SELECT (Jessica, Columbia, Computer Science, Google)



#### Human A's view Human B's view

Human B: three light grey dots in a diagonal line

Human A: i dont have that but i have a black dot neer the top to the right, the only

black dot in the circle

Human B: i have two black dots, find something else

Human A: ok i have a light grey dot by itself

at the bottom to the left, right on the line

Human B: how big is it

Human A: its one of the bigger ones Human B: okay just pick it then

Human A: ok

Human B: SELECT blue Human A: SELECT red

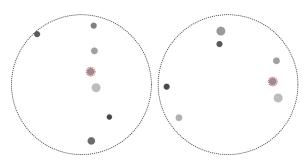
Mutual Friends and OneCommon

# Issue: Poor neural reasoning

#### From Mutual Friends: Neural + Human

- ► A: Know anyone who likes chess?
- B: None of my friends like chess.
- (conversation continues)
- A: Crocheting?
- B: None like crocheting.
- ► A: Chess?
- B: None like chess either, haha.

# Issue: Poor neural reasoning



#### Agent 0: human || 1: human

	0	1
0	1	I see a large grey dot with a smaller black dot right below it
1	0	is the smaller black dot to the right and below
2	1	No, it is slightly to the left and below
3	0	Might not be the same one. Do you have a lot of dots in a fairly vertical conformation
4	1	I have three dots in a kinda vertical line with different shade of gray but close in size
5	0	Is the middle dot curved to the left or right a little bit?
6	1	the middle dot is slighty to the left of the other two and is also a little bit darker than the rest
7	0	Yes pick that middle dot

# Issue: Poor neural reasoning



Agent 0: pragmatic\_confidence || 1: human

	0	1
0	0	i have one large black dot by itself . do you have it?
1	1	Yes, I do have that.
2	0	let 's pick that one
3	1	ok
4	0	ok

## Issue: Scaling rule-based

- Rule-based text generation and understanding is somewhat viable for Mutual Friends
  - Very optimistic selection, but can be tuned
- Continuous and spatial nature of OneCommon makes writing rules difficult
  - ► Size, color, and positions all continuous
  - Descriptions are relative

## Current approaches: Two extremes

- Neural encoder-decoder
  - Encode past interactions with a neural net
  - ► Generate what to say with a neural net
  - ▶ Brittle strategy, less brittle language
- Rule-based
  - Encode past interactions in a table
  - Use rules for what to say next
  - ► Nonparametric lookup of utterances
  - ► Brittle language, less brittle strategy
- ▶ Meet in middle with interpretable planning + neural language

# A dialogue turn

- Engaging in dialogue requires
  - ▶ Inference: What do I know? How do I represent it?
  - Planning: What should I do and say?
- Formulate as model-based planning
  - Plan what to say through a simple model of our partner
  - Model of partner conditions on past information

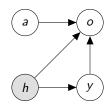
# Model-based planning

- Goal: Use a supervised static model in an interactive setting
- Belief state (What do I know)
  - Interpretable summary of past information that is relevant to task
  - Model latent partner information
  - Able to enforce constraints
- Model-based planning (What should I say)
  - Pick best action by imagining how partner would respond
  - ► Can train partner response models on static data
  - Allows policies to perform better than the data they trained on
  - Need a measure of utility to determine which action to take (heuristic: reduce uncertainty)

## Belief model

- Latent quantity y
- Actions  $a_t$ , observations  $o_t$  (e.g. yes/no questions)
- ▶ Interaction history  $h_t = (a_0, o_0, ..., a_t, o_t)$  contains all previous actions and observations
- ▶ Given an initial belief  $p(y | h_t)$  + next action/observation, obtain next belief via

$$p(y \mid h_{t+1}) = p(y \mid h_t, a_{t+1}, o_{t+1}) \propto \underbrace{p(o_{t+1} \mid h_t, a_{t+1}, y)}_{\text{observation model}} p(y \mid h_t)$$



## Belief state

- ▶ Use belief state  $p(y \mid h)$  to capture information relevant to planning
- Most of the burden is on the observation model p(o | h, a, y)
   Must be able to predict partner
- Prior work assumes conditional independence  $p(o \mid h, a, y) = p(o \mid a, y)$
- Why is this bad?

# Conditional independence in partner modeling

- Prior work assumes conditional independence  $p(o \mid h, a, y) = p(o \mid a, y)$
- If you ask the same question twice, your belief changes both times!
  - $ightharpoonup p(\text{yes} \mid h = \emptyset, y)$  can vary depending on the latent y
  - ▶ p(yes | h = (red dot?, yes), a = red dot?, y) = 1, since we just asked!
- 'Questions with correlated answers' and deficient observation model lead to uncalibrated beliefs, and therefore poor strategy
- Contribution: relax independence assumption
  - Use copy attention from past answers to current answer
  - Probably solved by using Transformer (is there enough data)

## Belief calibration: Other issues

# Planning: Use prior work

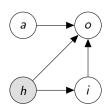
- ► Goal: Mutually select the same item *y* as partner
  - ► Row in knowledge base, dot
  - Coordinate through dialogue
- Given history h, we need to chose an action a by optimizing utility

$$\max_{a} U(h, a)$$

- ▶ Utility U = information gain + utterance + pragmatic cost
  - ▶ IG: Entropy reduction of item selection probability
  - Utterance cost: Can't send a full paragraph
  - Pragmatic cost: Want utterance to be accurate
- ▶ Ideally estimate and optimize future reward directly
  - Heuristic approximation of future reward U
  - Limited-horizon planning to minimize impact of model error

### Information Gain

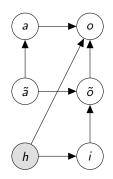
- A good action should decrease uncertainty
- Requires
  - ▶ Belief distribution over selection item given history p(i | h)
  - Partner response model p(o | h, a, i)
- Represent a turn as



Language and planning coupled

# Decoupling language and planning

- Compress actions a and observations o into language and abstract representations  $\tilde{a}, \tilde{o}$ 
  - Language is high dimensional, redundant, and inefficient for planning
- Represent a turn as



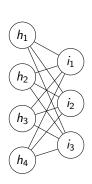
▶ Abstract observation  $\tilde{o} \perp \!\!\!\perp h \mid \tilde{a}, i$ 

# State and belief: Representation

- ► History: whether attributes have been confirmed  $h \in \{0,1\}^N$
- ▶ Items:  $i \in [M], M << N$
- Logistic regression with attributes as features

$$p(i \mid h) = \frac{\exp(\sum_{n} \psi(h_{n}, i))}{\sum_{i'} \exp(\sum_{n} \psi(h_{n}, i'))}$$
$$\psi(h_{n}, i) = W_{ni}1(h_{n}(i))$$

- Generate per-game W = f(context) from neural network
  - Many correlated features
  - ► How to (conditionally) sparsify?
- ► Dialogue = online feature selection



## **Attributes**

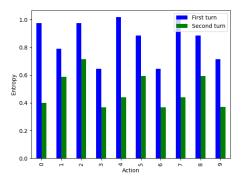
- Mutual Friends
  - Combinations of columns of knowledge base
  - Name, major, company
- OneCommon
  - Which dots are mentioned
  - Need to learn lower-level attributes
- ► Numerical reasoning?

## **Experiments**

- Mutual Friends
  - Augment rule-based (prior work) to optimize info gain
  - After OneCommon: Add neural on top
- OneCommon
  - ► Use attributes = raw mention configurations
    - ▶ Need belief / info gain / LR weights
    - ▶ How to deal with redundancy? (i.e. correlation between features)
  - Learn latent refinement on top of mention configurations

## Information gain issues

- Best info gain could be to ask the same question twice
- Usual fix: Limit to asking once only
- Would be nice to have a principled way to deal with correlated features though



Second turn after taking action with lowest entropy

# Related work: 20 questions

- ► Padmakumar and Mooney (2020)
  - Attribute-based classification (string heuristic to map to description) + activate learning about attributes
  - ► Info gain (on top of binary unweighted logistic regression) as feature for RL policy
- Yu et al. (2019)
  - Question-based classification (attributes)
  - Learn weights of features
  - Do not consider feature correlations
- More interesting language, symmetric setting
- Learn weights, account for correlation
- Symmetry, deal with unexpected features

# End

### Concerns

- Would a large LM solve all of this?
  - Fine tune on small onecommon dataset, are there still repeats?
  - Unlikely to solve strategy / over optimistism

# End

## Value: Information Gain

- drop slide
- Picture would be much better here...
- ► Value = expected information gain

$$IG(h, a) = H(i \mid h) - \mathbb{E}_{p(o|h, a)} [H(i \mid h, a, o)]$$

$$\mathbb{E}_{p(o|h, a)} [H(i \mid h, a)] = \sum_{o} \sum_{i'} p(o \mid h, a, i) p(i \mid h) H(i \mid h, a, o)$$

- Equivalent to minimizing expected uncertainty after receiving a response
- Cite Yu et al, White et al

## Citations I

Padmakumar, A. and Mooney, R. J. (2020). Dialog policy learning for joint clarification and active learning queries. *CoRR*, abs/2006.05456.

Yu, L., Chen, H., Wang, S. I., Artzi, Y., and Lei, T. (2019). Interactive classification by asking informative questions. *CoRR*, abs/1911.03598.