```
import pandas as pd
from bs4 import BeautifulSoup
import requests
```

#### Grabbing all the websites that have to do with my rocket data acquisition.

```
response = requests.get("https://nextspaceflight.com/rockets/")
response1 = requests.get("https://nextspaceflight.com/rockets/?page=1&search=")
response2 = requests.get("https://nextspaceflight.com/rockets/?page=2&search=")
response3 = requests.get("https://nextspaceflight.com/rockets/?page=3&search=")
response4 = requests.get("https://nextspaceflight.com/rockets/?page=4&search=")
response5 = requests.get("https://nextspaceflight.com/rockets/?page=5&search=")
response6 = requests.get("https://nextspaceflight.com/rockets/?page=6&search=")
response7 = requests.get("https://nextspaceflight.com/rockets/?page=8search=")
```

#### Parsing the html using BeautifulSoup

```
soup = BeautifulSoup(response.content, "html.parser")
soup1 = BeautifulSoup(response1.content, "html.parser")
soup2 = BeautifulSoup(response2.content, "html.parser")
soup3 = BeautifulSoup(response3.content, "html.parser")
soup4 = BeautifulSoup(response4.content, "html.parser")
soup5 = BeautifulSoup(response5.content, "html.parser")
soup6 = BeautifulSoup(response6.content, "html.parser")
soup7 = BeautifulSoup(response7.content, "html.parser")
```

#### Function for parsing my 8 soups.

```
def getRocketData(soup):
  rocket_sections = soup.find_all('section', class_='card section--center mdl-grid mdl-grid--no-spacing mdl-shadow--6dp')
  rocket_data = []
  for section in rocket_sections:
      # Extract rocket name
      rocket_name = section.find('h5').text
      info_elements = section.find_all('div', class_='mdl-cell mdl-cell--12-col-desktop mdl-cell--12-col-tablet')
#rocket_info = {element.text.split(': ')[0]: element.text.split(': ')[1] for element in info_elements}
      rocket_info = {}
      for element in info_elements:
        key, value = element.text.split(': ')
        rocket_info[key] = value
      # Append data to the list, this unpacks the dictionary I built
      rocket_data.append({'Rocket Name': rocket_name, **rocket_info})
  return (rocket_data)
a = getRocketData(soup)
b = getRocketData(soup1)
c = getRocketData(soup2)
d = getRocketData(soup3)
e = getRocketData(soup4)
f = getRocketData(soup5)
g = getRocketData(soup6)
h = getRocketData(soup7)
dfp1 = pd.DataFrame(a)
dfp2 = pd.DataFrame(b)
dfp3 = pd.DataFrame(c)
dfp4 = pd.DataFrame(d)
dfp5 = pd.DataFrame(e)
dfp6 = pd.DataFrame(f)
dfp7 = pd.DataFrame(g)
```

I accidently made dfp1 the same as dfp2 so I just took it off.

```
df_rockets = pd.concat([dfp2, dfp3, dfp4, dfp5, dfp6, dfp7], ignore_index = True)
```

Final dataframe for now thank god

Gonna do some cleaning. I am going to take out all of the NaN's and I do not understand the given success rate. Successes is 1 and failure is 1 and partial failure is 1. I am going to treat each one as a failure entirely.

```
df_rockets.fillna(0, inplace=True)
```

df rockets.head()

<del>_</del>		Rocket Name	Missions	Successes	Partial Failures	Failures	Succe Stre		Success Rate	
	0	Alpha	4	1	2	1		0	50.0%	11.
	1	Amur	0	0	0	0		0	0	
	2	Angara 1	3	3	0	0		3	100%	
	3	Angara A5	4	3	0	1		1	75.0%	
	4	Antares	18	17	0	1		13	94.4%	
Next	ste	ps: Gene	rate code wi	th df_rockets	● Vie	w recommend	ed plots			

Some more cleaning. The Successes and failures were casted in as objects so now I am casting them as integers to do some analysis on them further.

```
df_rockets.Successes = df_rockets.Successes.astype(int)
df_rockets.Failures = df_rockets.Failures.astype(int)
df_rockets["Partial Failures"] = df_rockets["Partial Failures"].astype(int)
df_rockets.Missions = df_rockets.Missions.astype(int)
df_rockets["Success Streak"] = df_rockets["Success Streak"].astype(int)

df_rockets["Accurate Success Rate"] = ((df_rockets["Successes"] / (df_rockets["Missions"])) * 100)
df_rockets["Failure Rate"] = (df_rockets["Failures"] + df_rockets["Partial Failures"]) / df_rockets.Missions
df_rockets["Total Failures"] = df_rockets.Failures + df_rockets["Partial Failures"]
```

Check the most reliable rockets, upon research apparently plotly plots stuff by how they appear in the dataframe, I wanted success rate to be in order by descending so I did so.

From early inspection it seems that these 100% range for 1 for 1, I should check for higher count of missions. I decided that rockets with high TRL (technological readiness level) should have at least 100 flights. I realize that this results in a small dataset, but I just want to see what rockets are successful and put them into a visualization.

```
df_sorted = df_rockets.sort_values(by='Accurate Success Rate', ascending = False)
df_TRL = df_rockets[df_rockets.Missions > 100]
df_TRLsorted = df_TRL.sort_values(by=['Accurate Success Rate', 'Missions', 'Success Streak'], ascending = False)
df_TRL_success = df_TRL.sort_values(by = "Success Streak", ascending = False)
df_TRL
```

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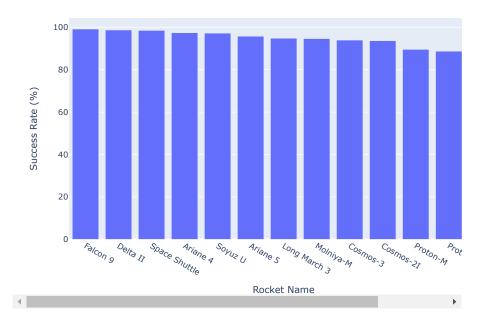
		Rocket Name	Missions	Successes	Partial Failures	Failures	Success Streak	Success Rate	Accurate Success Rate	Fai:
	8	<b>B</b> Ariane 4 116 113		0	3	74	97.4%	97.413793	0.02	
	9	Ariane 5	117	112	3	2	20	97.0%	95.726496	0.042
	15	Atlas- Agena	109	89	5	15	7	83.9%	81.651376	0.18
	37	Cosmos- 2I	126	118	0	8	14	93.7%	93.650794	0.06
	38	Cosmos-	479	450	8	21	22	94.8%	93.945720	0.06
	52	Delta II	155	153	1	1 2	100 323	99.0% 99.3%	98.709677	0.012
	68	Falcon 9	352	349	1				99.147727	0.008
	101	Long March 3	154	146	6	2	30	96.8%	94.805195	0.05
	121	Molniya- M	280	265	12	3	4	96.8%	94.642857	0.05
4										•

Next steps: Generate code with df\_TRL View recommended plots

Using plotly to create a bar chart of the success rate of rockets with a minumum of 100 launches.

<del>\_</del>

## Success Rate of Rockets with a Minimum of 100 launches

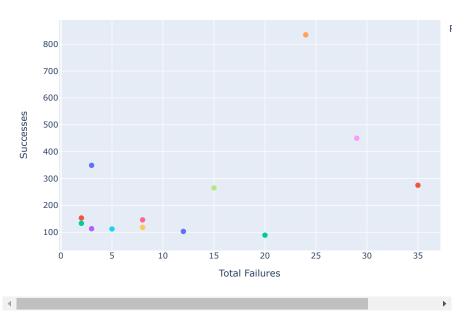


Note: This format came from plotly I used it as a reference to make my points larger.

fig = px.scatter(df\_TRLsorted, x="Total Failures", y = "Successes", color = "Rocket Name", title="Success vs Total Failures for Rockets wit
fig.update\_traces(marker=dict(size=8))
fig.update\_layout(hovermode='closest')
fig.show()



## Success vs Total Failures for Rockets with over 100 Launches

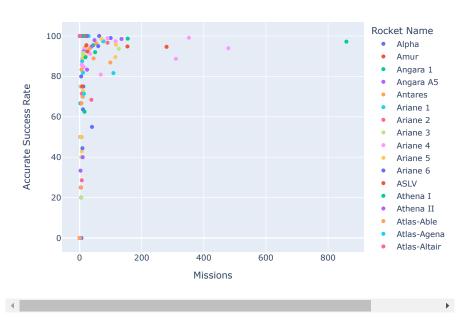


From the plot below we see that most launch vehicles do not go over 200 launches. The success rate of the launches are clustered up in between 100 launches or so.

px.scatter(df\_rockets, x="Missions", y= "Accurate Success Rate", color="Rocket Name", title="Overall Success Rate (%) for all Rockets")



## Overall Success Rate (%) for all Rockets

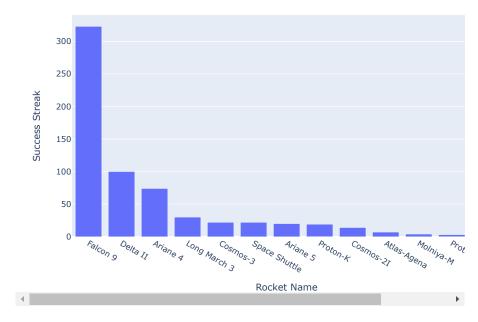


#### **Success Streak of Rockets**

px.bar(df\_TRL\_success, x="Rocket Name", y = "Success Streak", title="Success Streak per Rocket Name")



## Success Streak per Rocket Name



## Total number of missions per rocket

 ${\tt px.bar(df\_rockets,\ x="Rocket\ Name",\ y="Missions",\ title="Number\ of\ Missions\ per\ Rocket")}$ 

 $\overline{\Rightarrow}$ 

## Number of Missions per Rocket

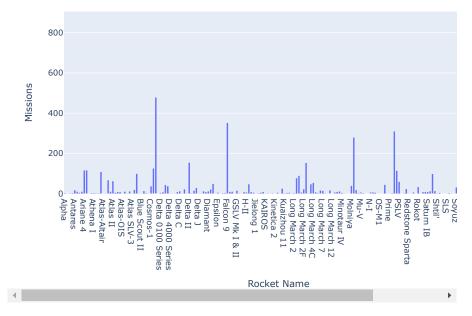
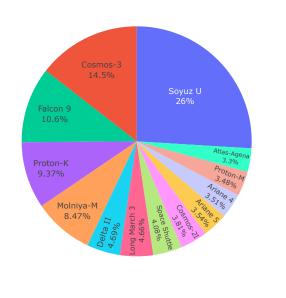


fig = px.pie(df\_TRL\_success, values ="Missions", names="Rocket Name", title="Proportion of Launches per Rocket Relative to Other Rockets wifig.update\_traces(textposition="inside", textinfo = 'percent+label')



## Proportion of Launches per Rocket Relative to Other Rockets with High TR



New Section: Using Kaggle Dataset for mission launches.

# Double-click (or enter) to edit

```
space = pd.read_csv("Space_Corrected.csv")
space.head()
```

→		Unnamed: 0.1	Unnamed:	Company Name	Location	Datum	Detail	Status Rocket	Rocket
	0	0	0	SpaceX	LC-39A, Kennedy Space Center, Florida, USA	Fri Aug 07, 2020 05:12 UTC	Falcon 9 Block 5   Starlink V1 L9 & BlackSky	StatusActive	50.0
	4								

View recommended plots

\*checks to see if my code works

Next steps:

Generate code with space

LC-39A, Kennedy Space Center, Florida, USA

```
f = space.loc[0]
#string = f.Location.split(',')
val = f.Location.strip()
pp = val.split(',')

location_list = ['LC-39A', 'Kennedy Space Center', 'Florida', 'USA']

if 'USA' in val:
    print("USA is in the list.")
else:
    print("USA is not in the list.")

print(location_list)
print(val)

USA is in the list.
    ['LC-39A', 'Kennedy Space Center', 'Florida', 'USA']
```

Mapping values like how we did in the titanic notebooks. I wanted to see if a given mission was USA sponsored or not, and I wanted to change Status from StatusActive to just Active. Just felt like it was smoother, cleaner, easier to read that way.

```
def values(c):
    val = c.strip()
    if 'USA' in c:
        return "USA"
    else:
        return "World"

def Status(c):
    if c == "StatusActive":
        return "Active"
    else:
        return "Inactive"

space["Status"] = space["Status Rocket"].map(Status)
space["US_or_Not"] = space["Location"].map(values)
```

We have the same thing going on here like we did prior section. I am going to consider partial and prelaunch failure as failure as a whole.

```
space["Status Mission"].value_counts()

Status Mission
Success 3879
Failure 339
Partial Failure 102
Prelaunch Failure 4
Name: count, dtype: int64
```

Kind of like how we did it for the classes for malignant and benign. I wanted to turn the successes into something binary in terms of 0 & 1. I also wanted to do it for failure count because why not.

```
def successCount(c):
 if "Success" in c:
   return 1
  else:
    return 0
space["binary_success"] = space["Status Mission"].map(successCount)
def failureCount(c):
 if "Failure" in c:
   return 1
  else:
    return 0
space["failureCount"] = space["Status Mission"].map(failureCount)
space.binary_success.value_counts()
₹
    binary_success
     1 3879
          445
     Name: count, dtype: int64
space.failureCount.value_counts()
   failureCount
     0 3879
          445
     1
     Name: count, dtype: int64
```

Wanted to see how the USA fairs on a global scale vs the world in terms of rocket success and failure

Next steps:

```
joint_success = pd.crosstab(
    space["US_or_Not"], space["binary_success"], normalize = True
)

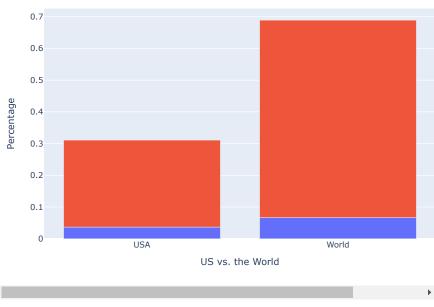
# abels = {"Rocket Name": "Rocket Name", "Accurate Success Rate": "Success Rate (%)"}

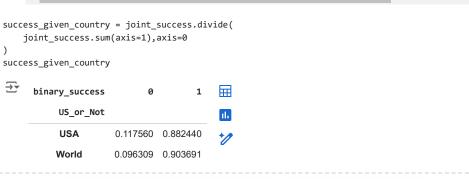
px.bar(joint_success, title="US vs. the World Joint Proportion",
    labels = {"US_or_Not": "US vs. the World", "value": "Percentage"})

$\incress{c}$

\[
\text{The Morld Joint Proportion Morld Morld
```

## US vs. the World Joint Proportion





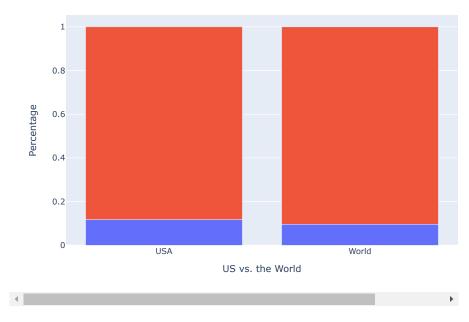
Generate code with success\_given\_country

In more USA vs the world graphs, we see that the USA has a slightly lower percentage of success versus the world, and a higher percentage of failure. This is probably due to the rockets shown prior in my first stage of data collection. The soyuz/cosmos are reliable rockets used multiple times with high success rate, so that can overpower the USA's success especially with our early struggle in apollo missions and our commercial rocket endeavors.

View recommended plots



## Conditional Distributions for Success of a Rocket Launch given USA or not



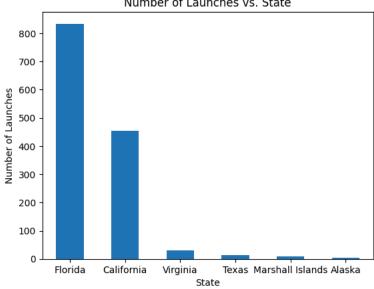
More cleaning for some reason it was red in w/ question marks just replacing.

# Discussion on further parts of the project

After attempts at machine learning using the provided dataset from kaggle and feedback from Dr. Ross, I realized that I may not have enough features to apply machine learning to this project. With that being said, embedded within ceratin columns were various other parameters that I could map values to. Namely launch pad, launch center, country, and state (given that it is a USA country). Additionally, I was able to attain the launch vehicle that was used, and the number of satellites aboard each mission (although this may have been a guess in the website each one had a major satellite on board, but from prior aerospace classes we know that most launch vehicles take up mini satellites like the ones we have at Cal Poly such as Cubesats. But I am sure that they did not include those in the launch detail). I was also able to get the day of the launch (numerical), the actual day of the wekk, and the month. From the company names, i did some additional research to find out whether or not these companies were commercial or government.

```
def launchPad(c):
 val = c.strip()
 p = val.split(',')
 return p[0]
space["Launch Pad"] = space["Location"].map(launchPad)
def launchCenter(c):
 val = c.strip()
 p = val.split(',')
 return p[1]
space["Launch Center"] = space["Location"].map(launchCenter)
def country(c):
 val = c.strip()
 p = val.split(',')
 if p[-1] == " New Mexico":
   return "USA"
 return p[-1]
space["Country"] = space["Location"].map(country)
def stateUS(c):
 val = c.strip()
 if "USA" in c:
   p = val.split(",")
   return p[2].strip()
 else:
space["State"] = space["Location"].map(stateUS)
def vehicle(c):
 val = c.split("|")
 return val[0]
space["Vehicle"] = space["Detail"].map(vehicle)
def DayofWeek(c):
 val = c.split()
 return val[0]
space["Day of the Week"] = space["Datum"].map(DayofWeek)
def month(c):
 val = c.split()
 return val[1]
space["Month"] = space["Datum"].map(month)
def day(c):
 val = c.split()
 new_string = val[2].replace(",", "")
 return new_string
space["Day"] = space["Datum"].map(day)
def type_agency(c):
 gov = ["CASIC", "Khrunichev", "CASC", "Roscosmos","JAXA", "VKS RF", "ISRO", "KARI","RVSN USSR","AMBA", "ESA", "NASA", "AEB", "US Air Force
  if c in gov:
   return "Government"
 else:
    return "Commercial"
space["Agency Type"] = space["Company Name"].map(type_agency)
def numSatellites(c):
   count = 1
   val = c.split("|")
    for item in val[1]:
     if item == "&":
       count += 1
space["Satellite Count"] = space["Detail"].map(numSatellites)
```

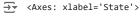
```
def failCount(c):
   if c != 1:
     return 1
  else:
     return 0
space["failCount"] = space["binary_success"].map(failCount)
space.Detail.unique()
 → array(['Falcon 9 Block 5 | Starlink V1 L9 & BlackSky',
                  Long March 2D | Gaofen-9 04 & Q-SAT',
                  'Starship Prototype | 150 Meter Hop', .
                  'Vanguard | Vanguard TV3', 'Sputnik 8K71PS | Sputnik-2',
                  'Sputnik 8K71PS | Sputnik-1'], dtype=object)
space["Company Name"].unique()
'IAI', 'Rocket Lab', 'Virgin Orbit', 'VKS RF', 'MHI', 'IRGC',
'Arianespace', 'ISA', 'Blue Origin', 'ISRO', 'Exos', 'ILS',
'i-Space', 'OneSpace', 'Landspace', 'Eurockot', 'Land Launch',
'CASIC', 'KCST', 'Sandia', 'Kosmotras', 'Khrunichev', 'Sea Launch',
'KARI', 'ESA', 'NASA', 'Boeing', 'ISAS', 'SRC', 'MITT', 'Lockheed',
'AEB', 'Starsem', 'RVSN USSR', 'EER', 'General Dynamics',
'Martin Marietta', 'Yuzhmash', 'Douglas', 'ASI', 'US Air Force',
'CNES', 'CECLES', 'RAE', 'UT', 'OKB-586', 'AMBA', "Armée de l'Air",
'ISS Navy'l dtyne=chiect')
                  'US Navy'], dtype=object)
df_US = space[space.US_or_Not == "USA"]
a = df_US.State.value_counts()
a.plot.bar(rot=0, xlabel="State", ylabel="Number of Launches", title="Number of Launches vs. State")
Axes: title={'center': 'Number of Launches vs. State'}, xlabel='State',
       ylabel='Number of Launches'>
                                          Number of Launches vs. State
```

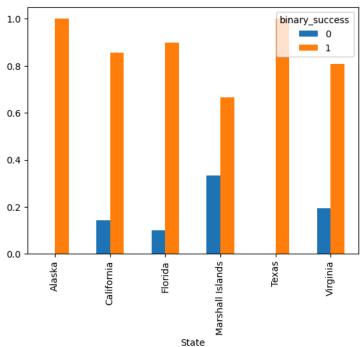


space.Country.unique()

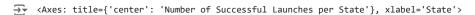
Some analysis on the further data. I got some feedback from my friend and he said the plot (two below) is not an accurate representation of success. Yes, Florida has had the most successful launches but we also have to take into account that Florida also had the most launches. So, I decided to go with the crosstab format because it shows the actual percentage of success and failure per launch.

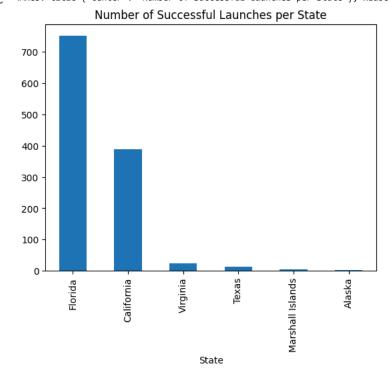
```
a = pd.crosstab(df_US.State, df_US.binary_success, normalize=True)
success_given_state = a.divide(
    a.sum(axis=1),axis=0
)
success_given_state.plot.bar()
```



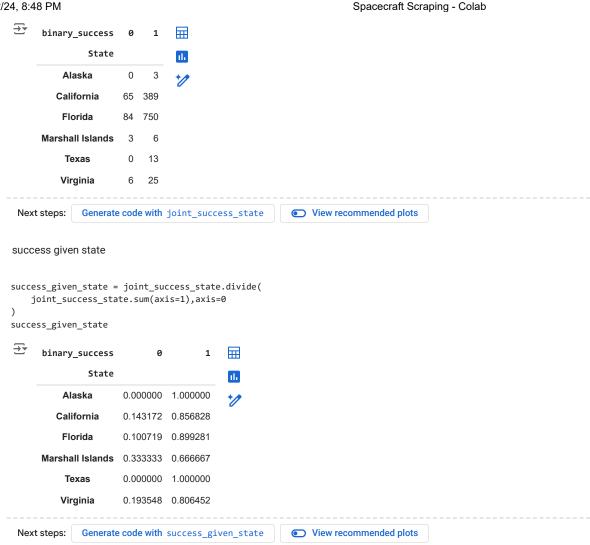


df\_US.groupby("State")["binary\_success"].sum().sort\_values(ascending=False).plot.bar(title = "Number of Successful Launches per State")



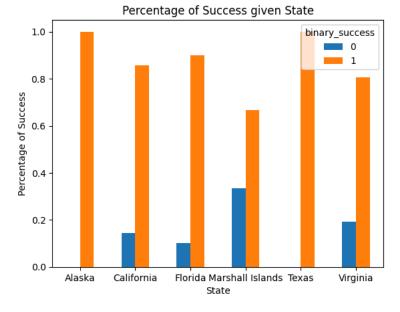


```
joint_success_state = pd.crosstab(
    df_US["State"], df_US["binary_success"]
)
joint_success_state
```



success\_given\_state.plot.bar(rot=0, ylabel="Percentage of Success", title="Percentage of Success given State")

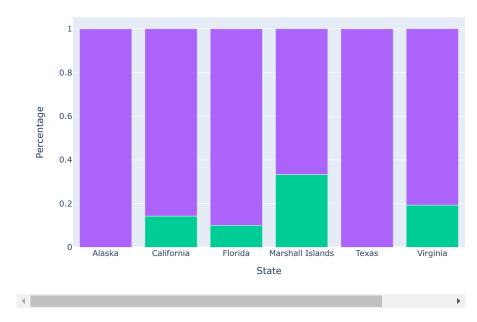
<Axes: title={'center': 'Percentage of Success given State'}, xlabel='State',</pre> ylabel='Percentage of Success'>



```
px.bar(success_given_state, labels = {"State": "State", "value": "Percentage"},
       title = "Conditional Distributions for Success of a Rocket Launch given USA or not",
       category_orders={"binary_success": ["Success", "Failure"]})
```



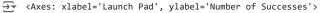
Conditional Distributions for Success of a Rocket Launch given USA or not

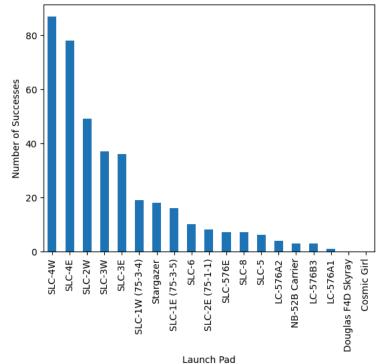


df\_US.State.unique()

df\_California = df\_US[df\_US.State == "California"]

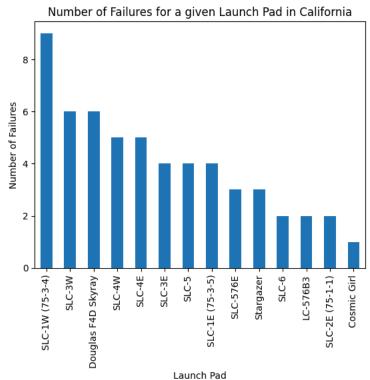
df\_California.groupby("Launch Pad")["binary\_success"].sum().sort\_values(ascending=False).plot.bar(xlabel="Launch Pad", ylabel="Number of Su





df\_California\_failures = df\_California[df\_California["Status Mission"] == "Failure"]
df\_California\_failures["Launch Pad"].value\_counts().plot.bar(xlabel = "Launch Pad", ylabel="Number of Failures", title="Number of Failures")

<axes: title={'center': 'Number of Failures for a given Launch Pad in California'},
xlabel='Launch Pad', ylabel='Number of Failures'>



space.head()

	•	
	7	

,	Unnamed: 0.1	. ,		Location	Datum	Detail	Status Rocket	Rocket
(	0	0	SpaceX	LC-39A, Kennedy Space Center, Florida, USA	Fri Aug 07, 2020 05:12 UTC	Falcon 9 Block 5   Starlink V1 L9 & BlackSky	StatusActive	50.0
1	I 1	1	CASC	Site 9401 (SLS-2), Jiuquan Satellite Launch Ce	Thu Aug 06, 2020 04:01 UTC	Long March 2D   Gaofen- 9 04 & Q-SAT	StatusActive	29.75
2	<b>2</b> 2	2	SpaceX	Pad A, Boca Chica, Texas, USA	Tue Aug 04, 2020 23:57	Starship Prototype   150 Meter Hop	StatusActive	NaN
4								<b>&gt;</b>

space["Status Mission"].value\_counts()

→ Status Mission

Success 3879
Failure 339
Partial Failure 102
Prelaunch Failure 4
Name: count, dtype: int64

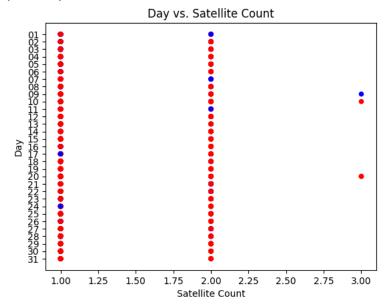
space["Day"].astype(int)

9 7 1 6 2 4 3 30 4 30

```
4319
              5
     4320
              1
     4321
     4322
              3
     4323
     Name: Day, Length: 4324, dtype: int64
import plotly.express as px
ds = space["Status Mission"].value_counts().reset_index()
ds
₹
         Status Mission count
                                  ☶
      0
                Success
                          3879
      1
                  Failure
                           339
      2
            Partial Failure
                           102
      3 Prelaunch Failure
 Next steps:
              Generate code with ds
                                       View recommended plots
space["binary_success_label"] = space["binary_success"].map({0: "Failure", 1: "Success"})
p = space["binary_success_label"].value_counts().reset_index()
px.pie(p, values = "binary_success_label", names="count", title="Success vs. Failure")
<del>_</del>
          Success vs. Failure
```

```
space_byDay = space.sort_values(by="Day", ascending=False)
colors = space["binary_success"].map({
    0: "blue",
    1: "red"
})
space_byDay.plot.scatter(
    x = "Satellite Count", y = "Day", c=colors, title = "Day vs. Satellite Count"
)
```

```
<axes: title={'center': 'Day vs. Satellite Count'}, xlabel='Satellite Count',
    ylabel='Day'>
```



```
def successOrnot(c):
    fail = ["Failure"]
    if c in fail:
        return "Failure"
    else:
        return "Success"

space["successornot"] = space["Status Mission"].map(successOrnot)
```

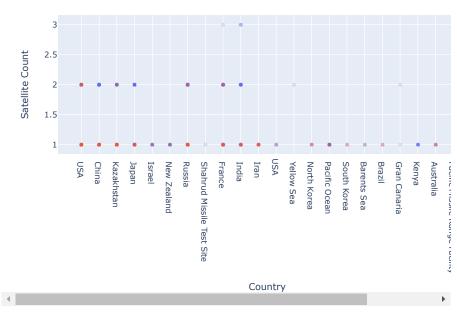
Focusing on three features: Agency Type, Satellite Count for sake of the graph

```
colors = space["successornot"].map({
    "Success": "blue",
    "Failure": "red"
})

px.scatter(space, x="Country", y="Satellite Count", color = colors, opacity=.2, title="Satellite Count vs. Country")

>>>
```

## Satellite Count vs. Country

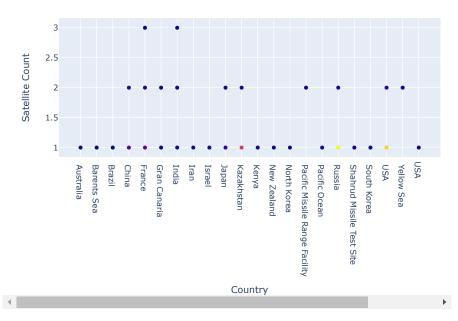


Start coding or generate with AI.

# df\_California.groupby("Launch Pad")["binary\_success"].sum().sort\_values(ascending=False).plot.bar(xlabel="Launch Pad", ylabel="Number of !
df\_success = space.groupby(['Country', "Satellite Count"])["binary\_success"].sum().reset\_index()
px.scatter(df\_success, x = "Country", y="Satellite Count", color = "binary\_success", title="Satellite Count and Country vs. Binary Success"



## Satellite Count and Country vs. Binary Success



```
space["binary_success"].value_counts()

binary_success
1 3879
```

0 445 Name: count, dtype: int64

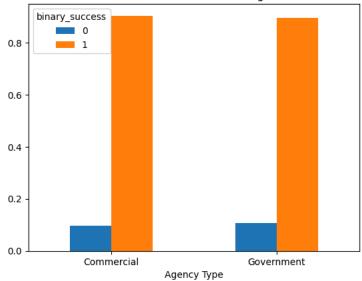
Making a dataframe of failed launches. I did this so I can see what attributes can lead to a failure, used for machine learning later.

Percentage of success per agency type, better represented as a percentage than a count, as there are significantly more government launches.

```
a = pd.crosstab(space["Agency Type"], space["binary_success"], normalize=True)
success_given_agency = a.divide(
    a.sum(axis=1),axis=0
)
success_given_agency.plot.bar(rot=0, title="Commercial & Government Percentage of Success")
success_given_agency
```



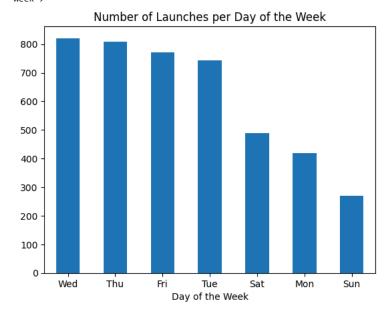
## Commercial & Government Percentage of Success





Total number of launches per day of the week for both success and failures, wanted to see if there was a trend.

space["Day of the Week"].value\_counts().plot.bar(rot=0, title=("Number of Launches per Day of the Week"))

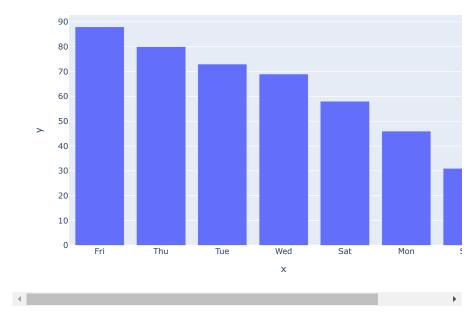


## Now this is unsuccessful launches per day of the week.

dayData = failCount["Day of the Week"].value\_counts()
px.bar(failCount, x=dayData.index, y = dayData.values, title= "Number of Failed Launches per Day of the Week")



Number of Failed Launches per Day of the Week

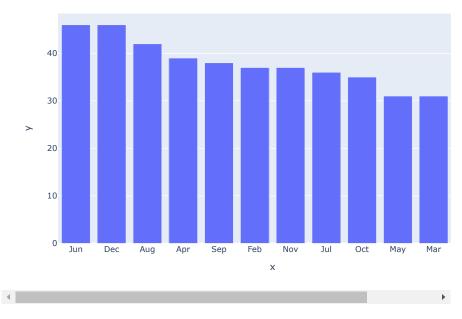


## Number of failed launches per month

monthData = failCount["Month"].value\_counts()
px.bar(failCount, x=monthData.index, y = monthData.values, title="Number of Failed Launches per month")



## Number of Failed Launches per month

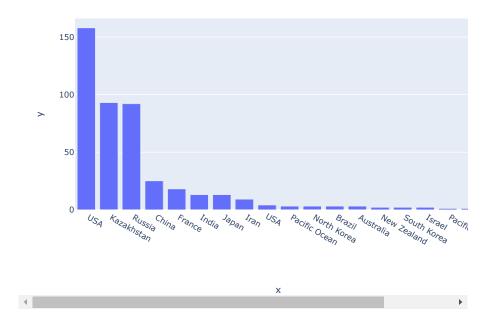


## **Number of failed Launches per Country**

countryData = failCount["Country"].value\_counts()
px.bar(failCount, x=countryData.index, y = countryData.values, title="Number of Failed Launches per Country")



## Number of Failed Launches per Country



# Actual Start of my machine learning

```
space['Country'] = space['Country'].str.strip()
```

#### Predicting mission status by using the features, month, country, and agency type.

```
import pandas as pd
from sklearn.preprocessing import StandardScaler, OneHotEncoder
from \ sklearn.neighbors \ import \ KNeighborsClassifier
from sklearn.pipeline import make_pipeline
from sklearn.compose import make_column_transformer
ct = make_column_transformer(
    (OneHotEncoder(handle_unknown='ignore'), ["Month", "Country", "Agency Type"]), remainder = "passthrough"
# this is my training data
xTT = space[["Month", "Country", "Agency Type", "Satellite Count"]]
yTT = space["binary_success"]
# define a pipeline
pipeline20 = make_pipeline(
    KNeighborsClassifier(n_neighbors=2)
pipeline20.fit(xTT, yTT)
a = pipeline20.predict(xTT)
pd.Series(a).value_counts()
          3815
           509
     Name: count, dtype: int64
```

## Getting the cv\_scores for my model

```
from sklearn.model_selection import cross_val_score
cv_scores = cross_val_score(pipeline20, xTT, yTT,
                           cv=10, scoring="accuracy")
cv_scores
cv_scores.mean()
```

#### Precision, recall, f1 score fir success and failure

→ 0.8115147335557268

7/2/24. 8:48 PM

```
success = (yTT == 1)
cv_scores = cross_val_score(pipeline20, xTT, success,
               cv=10, scoring="precision")
precision_success = cv_scores.mean()
precision_success
recall_success = cross_val_score(pipeline20, xTT, success,
                cv=10, scoring="recall").mean()
recall_success
f1score_success = cross_val_score(pipeline20, xTT, success,
               cv=10, scoring="f1").mean()
precision_success, recall_success, f1score_success
(0.8964957418599067, 0.893014598151256, 0.8946016140067016)
from sklearn.metrics import make_scorer, precision_score, recall_score, f1_score
failure = (yTT == 0)
precision_scorer = make_scorer(precision_score, zero_division=1)
recall_scorer = make_scorer(recall_score, zero_division=1)
f1_scorer = make_scorer(f1_score, zero_division=1)
cv_scores = cross_val_score(pipeline20, xTT, failure,
               cv=10, scoring=precision_scorer)
precision_failure = cv_scores.mean()
precision_failure
recall_failure = cross_val_score(pipeline20, xTT, failure,
                cv=10, scoring=recall_scorer).mean()
recall failure
f1score_failure = cross_val_score(pipeline20, xTT, failure,
                cv=10, scoring="f1").mean()
precision_failure, recall_failure, f1score_failure
\rightarrow (0.8, 0.0, 0.0)
from sklearn.model_selection import GridSearchCV
grid search = GridSearchCV(
   pipeline20,
    param_grid={"kneighborsclassifier__n_neighbors": range(1, 50)},
    scoring="f1_macro",
    cv=10
)
grid_search.fit(xTT, yTT)
grid_search.best_params_
{'kneighborsclassifier__n_neighbors': 2}
```

## Best valu for k is the one that was passed in

```
pd.DataFrame(grid_search.cv_results_).sort_values("rank_test_score").head(10)
```

	mean_fit_time	std_fit_time	mean_score_time	std_score_time	param_kneighborsclass
1	0.016780	0.002025	0.166443	0.040720	
0	0.012066	0.003586	0.079144	0.019506	
9	0.011021	0.000927	0.071931	0.003935	
2	0.014667	0.002946	0.152613	0.099016	
3	0.010793	0.000496	0.071553	0.002862	
28	0.015660	0.003161	0.157076	0.088427	
29	0.011699	0.002166	0.073090	0.002112	
30	0.010860	0.000410	0.074566	0.005240	
31	0.011365	0.001260	0.075810	0.005735	
32	0.010913	0.000878	0.072350	0.001519	

## Trying with new model, i could not get the cv.errors() loop to work.

```
ct = make_column_transformer(
    (OneHotEncoder(), ["Month", "Day of the Week", "Agency Type"]), remainder = "passthrough"
# this is my training data
xT1 = space[["Month", "Day of the Week", "Agency Type", "Satellite Count"]]
yT1 = space["binary_success"]
pipeline0 = make_pipeline(
    ct,
    KNeighborsClassifier(n_neighbors=2)
pipeline0.fit(xT1, yT1)
\overline{\pm}
                       Pipeline
       ▶ columntransformer: ColumnTransformer
           ▶ onehotencoder ▶ remainder
            ▶ KNeighborsClassifier
a = pipeline0.predict(xT1)
pd.Series(a).value_counts()
<del>_____</del> 1
         3648
     Name: count, dtype: int64
from sklearn.model_selection import cross_val_score
cv_scores = cross_val_score(pipeline0, xT1, yT1,
                           cv=10, scoring="accuracy")
cv_scores
array([0.84295612, 0.76674365, 0.78290993, 0.78060046, 0.74768519,
            0.77314815, 0.75231481, 0.7337963 , 0.77314815, 0.75925926])
cv_scores.mean()
```

```
0.771256201351467

Start coding or generate with AI.
```

#### Precision, recall, and f1 scores for my model: looking at successes

```
success = (yT1 == 1)

cv_scores = cross_val_score(pipeline0, xT1, success, cv=10, scoring="precision")

precision_success = cv_scores.mean()

precision_success

→ 0.893022100699319

recall_success = cross_val_score(pipeline0, xT1, success, cv=10, scoring="recall").mean()

recall_success

→ 0.8463471323157249

flscore_success = cross_val_score(pipeline0, xT1, success, cv=10, scoring="f1").mean()

flscore_success

→ 0.868811052927353
```

#### Precision, recall, and f1 scores for my model: looking at failures

```
from sklearn.metrics import make_scorer, precision_score
failure = (yT1 == 0)
precision_scorer = make_scorer(precision_score, zero_division=1)
cv_scores = cross_val_score(pipeline0, xT1, failure,
               cv=10, scoring=precision scorer)
precision_failure = cv_scores.mean()
precision_failure
recall_scorer = make_scorer(recall_score, zero_division=1)
recall_failure = cross_val_score(pipeline0, xT1, failure,
               cv=10, scoring=recall_scorer).mean()
recall_failure

→ 0.006717171717171717
f1score_failure = cross_val_score(pipeline0, xT1, failure,
               cv=10, scoring="f1").mean()
f1score_failure
→ 0.0126111111111111111
```

## Finding best k, using gridsearch

```
from sklearn.model_selection import GridSearchCV

grid_search = GridSearchCV(
    pipeline0,
    param_grid={"kneighborsclassifier__n_neighbors": range(1, 50)},
    scoring="f1_macro",
    cv=10
)

grid_search.fit(xT1, yT1)
grid_search.best_params_
```

{'kneighborsclassifier\_n\_neighbors': 4}

pd.DataFrame(grid\_search.cv\_results\_).sort\_values("rank\_test\_score").head(10)

<del>_</del>		mean_fit_time	std_fit_time	mean_score_time	std_score_time	param_kneighborsclass
	3	0.011371	0.001593	0.072126	0.006082	
	0	0.010570	0.000274	0.074288	0.005656	
	1	0.010769	0.000305	0.073792	0.005978	
	2	0.011476	0.001034	0.072645	0.005084	
	7	0.011751	0.002223	0.073388	0.004610	
	5	0.010976	0.000933	0.072155	0.004185	
	6	0.011161	0.001855	0.072667	0.004523	
	4	0.010577	0.000171	0.070575	0.001870	
	9	0.024728	0.007201	0.212580	0.067221	
	35	0.014072	0.003309	0.142996	0.075932	

### New precision and new recall for both success and failure

```
new_precision = cross_val_score(
   grid_search.best_estimator_,
   xT1, success,
   scoring="precision",
   cv=10).mean()
new_recall = cross_val_score(
   grid_search.best_estimator_,
   xT1, success,
   scoring="recall",
   cv=10).mean()
new_precision, new_recall
(0.8973334946288993, 0.9847911505367752)
precision_success, recall_success
→ (0.893022100699319, 0.8463471323157249)
new_precision_failure = cross_val_score(
   grid_search.best_estimator_,
   xT1, failure,
   scoring=precision_scorer,
   cv=10).mean()
new_recall_failure = cross_val_score(
   grid_search.best_estimator_,
    xT1, failure,
   scoring=recall_scorer,
   cv=10).mean()
new_precision_failure, new_recall_failure
→ (0.91999999999999999999, 0.00222222222222222)
```

#### This is the original precision and failure for model 2

```
Spacecraft Scraping - Colab
precision_failure, recall_failure
(0.453333333333333, 0.0067171717171717)
space.columns
'US_or_Not', 'binary_success', 'failureCount', 'Launch Pad',
'Launch Center', 'Country', 'State', 'Vehicle', 'Day of the Week',
'Month', 'Day', 'Agency Type', 'Satellite Count', 'failCount',
'binary_success_label', 'successornot'],
             dtype='object')
**Start of new model, checking how day of the week and month are related.
colors = space["binary_success"].map({
    0: "blue",
    1: "red"
})
px.scatter(space, x="Month", y="Day of the Week", color = colors, opacity = 0.2, title="Success/Failure of Day in the Week vs. Month")
\overline{\mathcal{T}}
            Success/Failure of Day in the Week vs. Month
             Wed
```



```
ct_new = make_column_transformer(
    (OneHotEncoder(), ["Month", "Day of the Week"]), remainder = "passthrough"
# this is my training data
xT_new = space[["Month", "Day of the Week"]]
yT_new = space["binary_success_label"]
# define a pipeline
pipeline_new = make_pipeline(
    ct_new,
    KNeighborsClassifier(n_neighbors=2)
pipeline_new.fit(xT_new, yT_new)
```

```
Pipeline

columntransformer: ColumnTransformer

onehotencoder remainder

OneHotEncoder passthrough

KNeighborsClassifier

a = pipeline_new.predict(xT_new)

ond Series(a) value counts()
```

```
a = pipeline_new.predict(xT_new)
pd.Series(a).value counts()
     Success
               3749
               575
     Failure
     Name: count, dtype: int64
from sklearn.model_selection import cross_val_score
cv_scores = cross_val_score(pipeline_new, xT_new, yT_new,
                           cv=10, scoring="accuracy")
cv_scores.mean()
   0.7960006629030877
success = (yT new == 1)
failure = (yT_new == 0)
cv_scores = cross_val_score(pipeline_new, xT_new, success,
               cv=10, scoring=precision_scorer)
precision_success = cv_scores.mean()
precision_success
recall_success = cross_val_score(pipeline_new, xT_new, success,
               cv=10, scoring=recall_scorer).mean()
recall_success
f1score_success = cross_val_score(pipeline_new, xT_new, success,
               cv=10, scoring=f1_scorer).mean()
precision_success, recall_success, f1score_success

→ (1.0, 1.0, 1.0)

cv_scores = cross_val_score(pipeline_new, xT_new, failure,
               cv=10, scoring=precision_scorer)
precision_success = cv_scores.mean()
precision_success
recall_success = cross_val_score(pipeline_new, xT_new, failure,
               cv=10, scoring=recall_scorer).mean()
recall_success
f1score_success = cross_val_score(pipeline_new, xT_new, failure,
               cv=10, scoring=f1_scorer).mean()
precision_success, recall_success, f1score_success
\rightarrow (1.0, 1.0, 1.0)
from sklearn.model_selection import GridSearchCV
grid_search = GridSearchCV(
   pipeline_new,
    param_grid={"kneighborsclassifier__n_neighbors": range(1, 50)},
    scoring="f1_macro",
    cv=10
)
grid_search.fit(xT_new, yT_new)
grid_search.best_params_
```

The number of k nearest neighbors is the same as my original model.

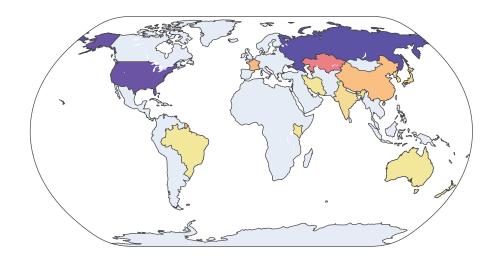
# Making chloropeth plots for fun

```
Start coding or generate with AI.
import geopandas as gpd
import geopandas as gpd
countryLst = ["Russia", "USA", "Kazakhstan", "France", "China", "Japan", "India", "Pacific Ocean", "New Zealand", "Iran", "Israel", "Kenya",
freq = [1395, 1344, 701, 303, 268, 126, 76, 36,13,13,11,9,6,5,3]
data = {'Country' : ["Russia", "United States of America", "Kazakhstan", "France", "China", "Japan", "India", "Pacific Ocean", "New Zealand",
        'freq': [1395, 1344, 701, 303, 268, 126, 76, 36, 13, 13, 11, 9, 6, 5, 3, 3]}
df1 = pd.DataFrame(data)
world_filepath = gpd.datasets.get_path('naturalearth_lowres')
world = gpd.read_file(world_filepath)
world.head()
→ <ipython-input-175-794e9e622c9b>:1: FutureWarning:
     The geopandas.dataset module is deprecated and will be removed in GeoPandas 1.0. You can get the original 'naturalearth_lowres' data fr
                                                                                                                                \blacksquare
            pop_est
                        continent
                                                    name iso_a3 gdp_md_est
                                                                                                                     geometry
            889953.0
                                                      Fiji
                                                             FJI
                                                                        5496 MULTIPOLYGON (((180.00000 -16.06713, 180.00000...
                          Oceania
         58005463.0
                                                                                POLYGON ((33.90371 -0.95000, 34.07262 -1.05982...
                             Africa
                                                 Tanzania
                                                            TZA
                                                                       63177
            603253.0
                            Africa
                                               W. Sahara
                                                            ESH
                                                                         907
                                                                                POLYGON ((-8.66559 27.65643, -8.66512 27.58948...
         37589262.0 North America
                                                  Canada
                                                            CAN
                                                                     1736425
                                                                              MULTIPOLYGON (((-122.84000 49.00000, -122.9742...
        328239523.0 North America United States of America
                                                                    21433226 MULTIPOLYGON (((-122.84000 49.00000, -120.0000...
 Next steps:
              Generate code with world
                                         View recommended plots
world = gpd.read_file(gpd.datasets.get_path('naturalearth_lowres'))
# Merge the GeoDataFrame with your DataFrame
geo_df = world.merge(df1, how='left', left_on='name', right_on='Country') #match the country w iso3 in new df
# Create the choropleth map using Plotly Express
fig = px.choropleth(
    geo_df,
    locations='iso_a3', # for natrualearth_lowres there are iso_a3 which are the code names and name which is the actual name
    color='freq',
    color_continuous_scale='sunset',
    projection='natural earth',
    title='Choropleth Map of Number of Launches'
# Show the map
fig.show()
```

<ipython-input-176-222bbeb83844>:1: FutureWarning:

The geopandas.dataset module is deprecated and will be removed in GeoPandas 1.0. You can get the original 'naturalearth\_lowres' data fr

## Choropleth Map of Number of Launches



df\_rockets.head()

<b>∓</b> *		Rocket Name	Missions	Successes	Partial Failures	Failures	Success Streak	Success Rate	Accurate Success Rate	Failure Rate	Total Failures	
	0	Alpha	4	1	2	1	0	50.0%	25.000000	0.750000	3	Ш
	1	Amur	0	0	0	0	0	0	0.000000	0.000000	0	
	2	Angara 1	3	3	0	0	3	100%	100.000000	0.000000	0	
	3	Angara A5	4	3	0	1	1	75.0%	75.000000	0.250000	1	
	4	Antares	18	17	0	1	13	94.4%	94.444444	0.055556	1	

View recommended plots

space.head()

Next steps:

Generate code with df\_rockets

<del></del>	ı	Unnamed: 0.1	Unnamed:	Company Name	Location	Datum	Detail	Status Rocket	Rocket	Status Mission	Status	 State	Vehicle	Day of the Week	Mon <sup>.</sup>
	0	0	0	SpaceX	LC-39A, Kennedy Space Center, Florida, USA	Fri Aug 07, 2020 05:12 UTC	Falcon 9 Block 5   Starlink V1 L9 & BlackSky	StatusActive	50.0	Success	Active	 Florida	Falcon 9 Block 5	Fri	Αı
	1	1	1	CASC	Site 9401 (SLS-2), Jiuquan Satellite Launch Ce	Thu Aug 06, 2020 04:01 UTC	Long March 2D   Gaofen- 9 04 & Q-SAT	StatusActive	29.75	Success	Active	 None	Long March 2D	Thu	Αı
	2	2	2	SpaceX	Pad A, Boca Chica, Texas, USA	Tue Aug 04, 2020 23:57	Starship Prototype   150 Meter Hop	StatusActive	NaN	Success	Active	 Texas	Starship Prototype	Tue	Αı
	4 ■														•

a = space.groupby("Country")["failCount"].sum()