

**Problem 1** Rudin Chapt. 9 Problem 6

If  $f(0, 0) = 0$  and

$$f(x, y) = \frac{xy}{x^2 + y^2} \quad \text{if } (x, y) \neq (0, 0)$$

prove that  $(D_1f)(x, y)$  and  $(D_2f)(x, y)$  exist at every point of  $\mathbb{R}^2$ , although  $f$  is not continuous at  $(0, 0)$ .

**Solution:** When  $(x, y) \neq (0, 0)$  then

$$(D_1f)(x, y) = \frac{y(y^2 - x^2)}{(x^2 + y^2)^2} \quad \text{and} \quad (D_2f)(x, y) = \frac{x(x^2 - y^2)}{(x^2 + y^2)^2}$$

Now at  $(0, 0)$

$$\begin{aligned} (D_1f)(0, 0) &= \lim_{h \rightarrow 0} \frac{f(h, 0) - f(0, 0)}{|h|} \\ &= \lim_{h \rightarrow 0} \frac{\frac{h \times 0}{h^2 + 0} - 0}{|h|} \\ &= \lim_{h \rightarrow 0} \frac{0}{|h|} \\ &= 0 \end{aligned}$$

$$\begin{aligned} (D_2f)(0, 0) &= \lim_{k \rightarrow 0} \frac{f(0, k) - f(0, 0)}{|k|} \\ &= \lim_{k \rightarrow 0} \frac{\frac{0 \times k}{0 + k^2} - 0}{|k|} \\ &= \lim_{k \rightarrow 0} \frac{0}{|k|} \\ &= 0 \end{aligned}$$

Hence  $(D_1f)(x, y)$  and  $(D_2f)(x, y)$  exists at every point of  $\mathbb{R}^2$ .

Now if we approach  $(0, 0)$  along the line then it approaches to 0. But if we approach  $(0, 0)$  along the line  $y = x$  then

$$\lim_{h \rightarrow 0} f(h, h) = \lim_{h \rightarrow 0} \frac{h^2}{2h^2} = \frac{1}{2}$$

Hence  $f$  is not continuous at  $(0, 0)$

□

**Problem 2** Rudin Chapt. 9 Problem 7

Suppose that  $f$  is a real-valued function defined in an open set  $E \subset \mathbb{R}^n$ , and that the partial derivatives  $D_1f, \dots, D_nf$  are bounded in  $E$ . Prove that  $f$  is continuous in  $E$ .

Hint: Proceed as in the proof of Theorem 9.21.

**Solution:** Let  $a$  is any arbitrary point in  $E$ . We have to show that  $\forall \epsilon > 0 \exists \delta > 0 |f(a + h) - f(a)| < \epsilon$  wherever  $\|h\| < \delta$ . Now. Let  $h = \sum_{i=1}^n h_i e_i$  where  $e_i$  is the  $i$ -th vector of the standard basis of  $\mathbb{R}^n$ .

$$\begin{aligned} f(a + h) - f(a) &= f\left(a + \sum_{i=1}^n h_i e_i\right) - f(a) \\ &= \left[f\left(a + \sum_{i=1}^n h_i e_i\right) - f\left(a + \sum_{i=1}^{n-1} h_i e_i\right)\right] + \left[f\left(a + \sum_{i=1}^{n-1} h_i e_i\right) - f\left(a + \sum_{i=1}^{n-2} h_i e_i\right)\right] \\ &\quad + \dots + [f(a + h_1 e_1) - f(a)] \\ &= \sum_{k=1}^n \left[f\left(a + \sum_{i=1}^k h_i e_i\right) - f\left(a + \sum_{i=1}^{k-1} h_i e_i\right)\right] \end{aligned}$$

Now each  $f\left(a + \sum_{i=1}^k h_i e_i\right) - f\left(a + \sum_{i=1}^{k-1} h_i e_i\right)$  is a one-variable function from  $\mathbb{R}$  to  $\mathbb{R}$ . By Mean Value Theorem  $\exists \theta_k \in (0, 1)$  such that

$$f\left(a + \sum_{i=1}^k h_i e_i\right) - f\left(a + \sum_{i=1}^{k-1} h_i e_i\right) = \frac{\partial f}{\partial x_k} \Big|_{v_k} h_k$$

where  $v_k = a + \sum_{i=1}^{k-1} h_i e_i + \theta_k h_k e_k$ . Hence

$$f(a + h) - f(a) = \sum_{i=1}^n \frac{\partial f}{\partial x_i} \Big|_{v_i} h_i = \sum_{i=1}^n D_i f(v_i) h_i$$

Since all  $D_i f$  are bounded in, Let  $D_i f$  is bounded by  $M_i$  where  $M_i > 0$ . Then take  $M = \max\{M_i \mid 1 \leq i \leq n\}$ . Hence  $|D_1(v_i) h_i| < M |h_i|$ . Hence

$$|f(a + h) - f(a)| = \left| \sum_{i=1}^n D_i f(v_i) h_i \right| \leq \sum_{i=1}^n M |h_i| = M \|h\|_1$$

Now as  $h \rightarrow 0$  we can say  $\|h\| \rightarrow 0$ . Hence  $M \|h\|_1 \rightarrow 0$ . Therefore  $|f(a + h) - f(a)| \rightarrow 0$ . Hence  $\forall \epsilon > 0 \exists \delta > 0$  such that  $\|h\| < \delta$  whenever  $|f(a + h) - f(a)| < \epsilon$ . Therefore  $f$  is continuous in  $E$

□

### Problem 3 Rudin Chapt. 9 Problem 8

Suppose that  $f$  is a differentiable real function in an open set  $E \subset \mathbb{R}^n$ , and that  $f$  has a local maximum at a point  $x \in E$ . Prove that  $f'(x) = 0$ .

**Solution:** Let  $u \in \mathbb{R}^n$  and  $u$  is nonzero. Then consider the function  $g(t) = x + tu$  which is a function from  $\mathbb{R}$  to  $\mathbb{R}^n$ . Now  $h = f \circ g$  is a  $\mathbb{R} \rightarrow \mathbb{R}$  function and  $h(t) = (f \circ g)(t) = f(x + ut)$ . Hence  $h$  has a maximum at  $t = 0$ . Therefore  $h'(0) = 0$ . Now by Chain Rule  $h'(t) = f'(g(t))g'(t) = f'(g(t))u$ . Hence  $h'(0) = f'(g(0))u = f'(x)u$ . Hence  $f'(x)u = 0$  since  $u$  is nonzero  $f'(x) = 0$

□

### Problem 4 Rudin Chapt. 9 Problem 10

If  $f$  is a real function defined in a convex open set  $E \subset \mathbb{R}^n$ , such that  $(D_1 f)(x) = 0$  for every  $x \in E$ , prove that  $f(x)$  depends only on  $x_2, \dots, x_n$ .

Show that the convexity of  $E$  can be replaced by a weaker condition, but that some condition is required. For example, if  $n = 2$  and  $E$  is shaped like a horseshoe, the statement may be false.

**Solution:** To prove  $f(x)$  depends only on  $x_2, x_3, \dots, x_n$  it is enough to show that  $f(x, x_2, \dots, x_n) = f(y, x_2, \dots, x_n)$  where  $(x, x_2, \dots, x_n), (y, x_2, \dots, x_n) \in E$ . Hence for any  $u \in (x, y)$   $(u, x_2, \dots, x_n) \in E$  as  $E$  is convex. Now by Mean Value Theorem  $f(x, x_2, \dots, x_n) - f(y, x_2, \dots, x_n) = (x - y) D_1 f(z, x_2, \dots, x_n)$  for some  $z \in (x, y)$ . Given that  $D_1 f(x) = 0$  Hence  $f(x, x_2, \dots, x_n) - f(y, x_2, \dots, x_n) = 0$ . Therefore  $f(x)$  depends only on  $x_2, \dots, x_n$ .

We need the property where for fixed  $x_2, \dots, x_n$  if  $(x, x_2, \dots, x_n)$  and  $(y, x_2, \dots, x_n)$  are in  $E$  then  $E$  must contain the line segment joining  $(x, x_2, \dots, x_n)$  and  $(y, x_2, \dots, x_n)$ . Hence we can say that if  $E$  intersects any line parallel to  $X$ -axis then it should be an interval on that line.

□

**Problem 5** Rudin Chapt. 9 Problem 13

Suppose  $f$  is a differentiable mapping of  $\mathbb{R}^1$  into  $\mathbb{R}^3$  such that  $|f(t)| = 1$  for every  $t$ . Prove that  $f'(t) \cdot f(t) = 0$ .

Interpret this result geometrically.

**Solution:** Let  $f = \begin{bmatrix} f_1 \\ f_2 \\ f_3 \end{bmatrix}$ . Given that  $|f(t)| = 1 \implies f_1^2(t) + f_2^2(t) + f_3^2(t) = 1$  for all  $t \in \mathbb{R}$ . Now

$$0 = \frac{d}{dt}|f(t)|^2 = \frac{d}{dt}(f_1^2(t) + f_2^2(t) + f_3^2(t)) = 2(f_1'(t)f_1(t) + f_2'(t)f_2(t) + f_3'(t)f_3(t)) = 2f'(t) \cdot f(t)$$

Hence  $f'(t) \cdot f(t) = 0$  for all  $t \in \mathbb{R}$ .

$f'(t) \cdot f(t)$  means the vector  $f'(t)$  is perpendicular to  $f(t)$ . If  $f(t)$  is the radius vector of a point on a unit sphere then  $f'(t)$  is tangent vector on that point to the sphere

□