

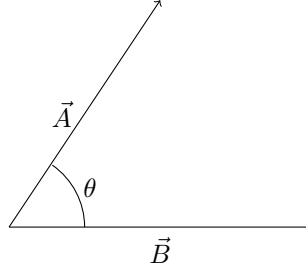
Classical Mechanics 1, Autumn 2021 CMI
Problem set 1
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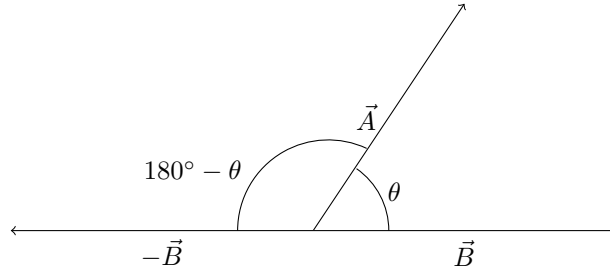
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1. Geometric Interpretation of Non-collinear Vector Subtraction:-

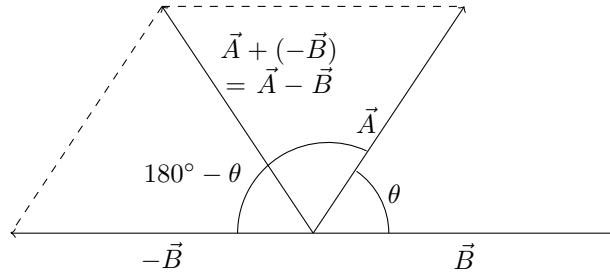
Let \vec{A} and \vec{B} are two non-collinear vectors emanating from origin in $2d$ plane which makes an angle θ with each other.



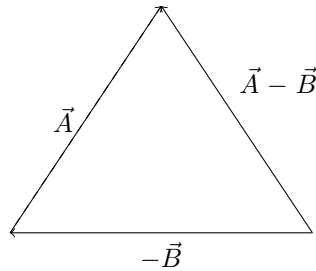
Now for $\vec{A} - \vec{B}$ we can write this as $\vec{A} + (-\vec{B})$ where $-\vec{B}$ represents the vector which has same magnitude as \vec{B} but the direction is opposite. Hence this $-\vec{B}$ vector makes an angle $180^\circ - \theta$ with \vec{A}



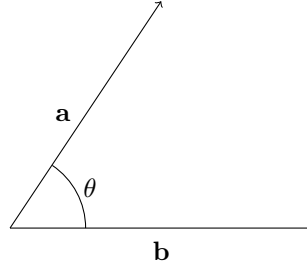
Now addition of this two vectors will be the diagonal of the parallelogram whose two adjacent sides are \vec{A} and $-\vec{B}$.



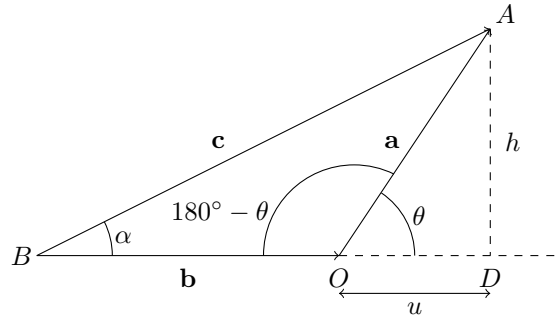
Hence we can say geometrically that $\vec{A} - \vec{B}$ is the third side of the triangle made by \vec{A} and $-\vec{B}$.



2. Let \mathbf{a} and \mathbf{b} are two vectors in \mathbb{R}^3 which makes an angle θ with each other.



Hence the the vector $\mathbf{c} = \mathbf{a} + \mathbf{b}$ is the resultant vector



Now by Pythagorean's theorem

$$OD^2 + AD^2 = OA^2 \implies u^2 + h^2 = a^2$$

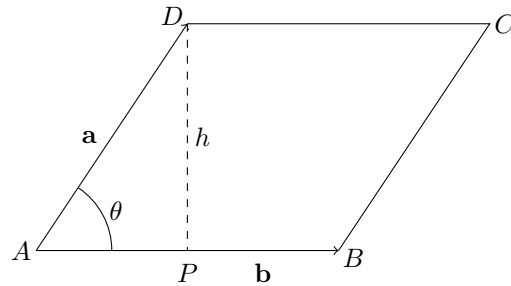
and

$$\begin{aligned} BD^2 + AD^2 &= AB^2 \implies (b + u)^2 + h^2 = c^2 \\ &\implies b^2 + 2ub + u^2 + h^2 = c^2 \\ &\implies b^2 + 2ub + a^2 = c^2 \\ &\implies b^2 + 2(a \cos \theta)b + a^2 = c^2 \\ &\implies b^2 + 2ab \cos \theta + a^2 = c^2 \text{ [Proved]} \end{aligned}$$

and

$$\alpha = \tan^{-1} \left(\frac{h}{b + u} \right) = \tan^{-1} \left(\frac{a \sin \theta}{b + a \cos \theta} \right)$$

3. Let $ABCD$ be a parallelogram where $\angle DAB = \theta$



Here the height of the parallelogram is the length of the perpendicular drawn from D on the line AB , $DP = h$. Now take the sides AD and AB as two vectors \mathbf{a} and \mathbf{b} respectively. Then the base of the parallelogram is b . Hence the area of the parallelogram is

$$\begin{aligned} h \times b &= (a \sin \theta) \times b \\ &= |\mathbf{a} \times \mathbf{b}| \text{ [Proved]} \end{aligned}$$

Now if we take any other two adjacent sides instead of AD and AB we can shift the vectors \mathbf{a} and \mathbf{b} to those sides and the area will be same.

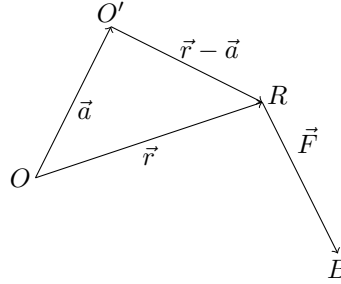
- (a) If we choose AD and DC then $AD = \mathbf{a}$ and $DC = \mathbf{b}$. Hence the area of the parallelogram will be still same.
- (b) If we choose DC and BC then $BC = \mathbf{a}$ and $DC = \mathbf{b}$. Hence the area of the parallelogram will be still same.
- (c) If we choose BC and AB then $BC = \mathbf{a}$ and $AB = \mathbf{b}$. Hence the area of the parallelogram will be still same.

Therefore no matter which two adjacent sides we choose as the vectors the area of the parallelogram remains same, $|\mathbf{a} \times \mathbf{b}|$

4. Let the initial position vector of a particle on which the force \vec{F} is acted upon is \vec{r} . Hence the initial torque (τ_i) on the particle is

$$\tau_i = \vec{r} \times \vec{F}$$

Now the origin is shifted by a vector \vec{a} the new position vector of the particle is $\vec{r} - \vec{a}$



Hence after shifting the origin the new torque (τ_f) will be

$$\tau_f = (\vec{r} - \vec{a}) \times \vec{F}$$

Hence the difference between final and initial torque is

$$\tau_f - \tau_i = (\vec{r} - \vec{a}) \times \vec{F} - \vec{r} \times \vec{F} = -\vec{a} \times \vec{F} = \vec{F} \times \vec{a}$$

Therefore if the origin is shifted by \vec{a} then the change in torques is $\vec{F} \times \vec{a}$.

5. Let

$$\vec{a} = a_1\hat{i} + a_2\hat{j} + a_3\hat{k}$$

and

$$\vec{b} = b_1\hat{i} + b_2\hat{j} + b_3\hat{k}$$

Therefore

$$\begin{aligned}\vec{a} \times \vec{b} &= \begin{vmatrix} \hat{i} & \hat{j} & \hat{k} \\ a_1 & a_2 & a_3 \\ b_1 & b_2 & b_3 \end{vmatrix} \\ &= (a_2b_3 - a_3b_2)\hat{i} + (a_3b_1 - a_1b_3)\hat{j} + (a_1b_2 - a_2b_1)\hat{k}\end{aligned}$$

Hence the cartesian components of $\vec{a} \times \vec{b}$ is $(a_2b_3 - a_3b_2)\hat{i} + (a_3b_1 - a_1b_3)\hat{j} + (a_1b_2 - a_2b_1)\hat{k}$

6. Let

$$\begin{aligned}\vec{a} &= a_1\hat{i} + a_2\hat{j} + a_3\hat{k} \\ \vec{b} &= b_1\hat{i} + b_2\hat{j} + b_3\hat{k} \\ \vec{c} &= c_1\hat{i} + c_2\hat{j} + c_3\hat{k}\end{aligned}$$

Therefore

$$\begin{aligned}\vec{a} \times \vec{b} &= \begin{vmatrix} \hat{i} & \hat{j} & \hat{k} \\ a_1 & a_2 & a_3 \\ b_1 & b_2 & b_3 \end{vmatrix} \\ &= (a_2b_3 - a_3b_2)\hat{i} + (a_3b_1 - a_1b_3)\hat{j} + (a_1b_2 - a_2b_1)\hat{k}\end{aligned}$$

and

$$\begin{aligned}\vec{b} \times \vec{c} &= \begin{vmatrix} \hat{i} & \hat{j} & \hat{k} \\ b_1 & b_2 & b_3 \\ c_1 & c_2 & c_3 \end{vmatrix} \\ &= (b_2c_3 - b_3c_2)\hat{i} + (b_3c_1 - b_1c_3)\hat{j} + (b_1c_2 - b_2c_1)\hat{k}\end{aligned}$$

Now

$$\begin{aligned}LHS = \vec{a} \cdot (\vec{b} \times \vec{c}) &= (a_1\hat{i} + a_2\hat{j} + a_3\hat{k}) \cdot \left((b_2c_3 - b_3c_2)\hat{i} + (b_3c_1 - b_1c_3)\hat{j} + (b_1c_2 - b_2c_1)\hat{k} \right) \\ &= a_1(b_2c_3 - b_3c_2) + a_2(b_3c_1 - b_1c_3) + a_3(b_1c_2 - b_2c_1) \\ &= c_1(a_2b_3 - a_3b_2) + c_2(a_3b_1 - a_1b_3) + c_3(a_1b_2 - a_2b_1)\end{aligned}$$

and

$$\begin{aligned}RHS = \vec{c} \cdot (\vec{a} \times \vec{b}) &= (c_1\hat{i} + c_2\hat{j} + c_3\hat{k}) \cdot \left((a_2b_3 - a_3b_2)\hat{i} + (a_3b_1 - a_1b_3)\hat{j} + (a_1b_2 - a_2b_1)\hat{k} \right) \\ &= c_1(a_2b_3 - a_3b_2) + c_2(a_3b_1 - a_1b_3) + c_3(a_1b_2 - a_2b_1)\end{aligned}$$

Therefore $LHS = RHS$. Hence

$$\vec{a} \cdot (\vec{b} \times \vec{c}) = \vec{c} \cdot (\vec{a} \times \vec{b}) \text{ [Proved]}$$

7. Let

$$\begin{aligned}\vec{a} &= \hat{i} + 2\hat{j} + 3\hat{k} \\ \vec{b} &= 2\hat{i} + 3\hat{j} + 4\hat{k} \\ \vec{c} &= 3\hat{i} + 4\hat{j} + 5\hat{k}\end{aligned}$$

Then

$$\begin{aligned}\vec{a} \times \vec{b} &= (\hat{i} + 2\hat{j} + 3\hat{k}) \times (2\hat{i} + 3\hat{j} + 4\hat{k}) \\ &= (2 \times 4 - 3 \times 3)\hat{i} + (3 \times 2 - 1 \times 4)\hat{j} + (1 \times 3 - 2 \times 2)\hat{k} \\ &= -\hat{i} + 2\hat{j} - \hat{k}\end{aligned}$$

hence

$$\begin{aligned}(\vec{a} \times \vec{b}) \times \vec{c} &= (-\hat{i} + 2\hat{j} - \hat{k}) \times (3\hat{i} + 4\hat{j} + 5\hat{k}) \\&= (2 \times 5 - (-1) \times 4)\hat{i} + ((-1) \times 3 - (-1) \times 5)\hat{j} + ((-1) \times 4 - 2 \times 3)\hat{k} \\&= 14\hat{i} + 8\hat{j} - 10\hat{k}\end{aligned}$$

and

$$\begin{aligned}\vec{b} \times \vec{c} &= (2\hat{i} + 3\hat{j} + 4\hat{k}) \times (3\hat{i} + 4\hat{j} + 5\hat{k}) \\&= (3 \times 5 - 4 \times 4)\hat{i} + (4 \times 3 - 2 \times 5)\hat{j} + (2 \times 4 - 3 \times 3)\hat{k} \\&= -\hat{i} + 2\hat{j} - \hat{k}\end{aligned}$$

hence

$$\begin{aligned}\vec{a} \times (\vec{b} \times \vec{c}) &= (\hat{i} + 2\hat{j} + 3\hat{k}) \times (-\hat{i} + 2\hat{j} - \hat{k}) \\&= (2 \times (-1) - 3 \times 2)\hat{i} + (3 \times (-1) - 1 \times (-1))\hat{j} + (1 \times 2 - 2 \times (-1))\hat{k} \\&= -8\hat{i} - 2\hat{j} + 4\hat{k}\end{aligned}$$

Therefore

$$(\vec{a} \times \vec{b}) \times \vec{c} \neq \vec{a} \times (\vec{b} \times \vec{c})$$

Hence the cross product is not associative. [Proved]