

**Question 1.**

- a. State and prove the Schwarz inequality.

For any non-zero vectors  $u$  and  $v$  with innerproduct  $\langle, \rangle$

$$|\langle x, y \rangle| \leq \|u\| \|v\|$$

*Proof.* Let  $u$  and  $v$  be non-zero vectors with inner product,  $\langle, \rangle$ , and let  $x$  be a scalar. Consider now,

$$\langle u + xv, u + xv \rangle = \langle u, u \rangle + x\langle u, v \rangle + x\langle u, v \rangle + x^2\langle v, v \rangle = \langle u, u \rangle + 2x\langle u, v \rangle + x^2\langle v, v \rangle$$

By definition of the inner product, we know that it is greater than zero, so we have,

$$\langle u, u \rangle + 2x\langle u, v \rangle + x^2\langle v, v \rangle \geq 0$$

We shall expand this into the familiar quadratic form,

$$\underbrace{\|v\|^2}_{a} x^2 + \underbrace{2\langle u, v \rangle}_{b} x + \underbrace{\|u\|^2}_{c} \geq 0$$

For a quadratic function to be greater than or equal to zero, we need the  $D \leq 0$ , where  $D$  is the discriminant of the quadratic formula. Because this condition is satisfied, we see that,

$$\begin{aligned} 4\langle u, v \rangle^2 - 4\|u\|^2\|v\|^2 &\leq 0 \\ \Leftrightarrow \langle u, v \rangle^2 &\leq \|u\|^2\|v\|^2 \end{aligned}$$

Taking the principle root of both sides, we arrive at the equation,

$$|\langle u, v \rangle| \leq \|u\| \|v\|$$

Thus, we have proven the Schwarz inequality □

- b. Prove for any
- $p$
- and
- $q$
- in
- $\mathbb{R}^n$
- ,

$$\|p - q\| \geq \|p\| - \|q\|$$

where  $\| \cdot \|$  is the magnitude of a vector in  $\mathbb{R}^n$  defined by  $\|x\| = \left( \sum_i x_i^2 \right)^{1/2}$  and the dot product of two vectors  $x, y$  is defined as  $x \cdot y = \sum_i x_i y_i$ , which is the inner product in  $\mathbb{R}^n$ .

*Proof.* We consider,

$$(\|p\| - \|q\|)^2$$

Expanding, we arrive at,

$$\|p\|^2 - 2\|p\| \|q\| + \|q\|^2$$

Note, from the Schwarz inequality,

$$|\langle x, y \rangle| \leq \|u\| \|v\| \Leftrightarrow -2\langle x, y \rangle \geq -2\|u\| \|v\|$$

Thus,

$$\|p\|^2 - 2\|p\| \|q\| + \|q\|^2 \leq \|p\|^2 - 2\langle p, q \rangle + \|q\|^2$$

But,

$$\|p - q\|^2 = \|p\|^2 - 2p \cdot q + \|q\|^2 = \|p\|^2 - 2\langle p, q \rangle + \|q\|^2$$

So, we have

$$\|p - q\|^2 \geq (\|p\| - \|q\|)^2$$

Taking the principle root, we arrive at,

$$\|p - q\| \geq |\|p\| - \|q\||$$

Finally, we note that  $x \leq |x| \forall x \in \mathbb{R}$ . So,

$$\|p - q\| \geq |\|p\| - \|q\|| \geq \|p\| - \|q\|$$

As desired. □

c. Now, let  $\theta$  be the angle between vector  $p$  and  $q$ . We define,

$$\cos(\theta) = \frac{p \cdot q}{\|p\| \|q\|}$$

Consider now, the Schwarz inequality as applied to  $\mathbb{R}^n$ . Our inner product becomes the dot product, and we have,

$$\begin{aligned} p \cdot q &\leq \|p\| \|q\| \\ -\|p\| \|q\| &\leq p \cdot q \leq \|p\| \|q\| \\ -1 &\leq \frac{p \cdot q}{\|p\| \|q\|} \leq 1 \end{aligned}$$

So, we see that the range of  $\cos(\theta)$  is  $[-1, 1]$

### Question 2.

- a. A subset  $U$  of a vector space  $V$  is a subspace of  $V$  if  $U$  is a vector space with the same operations as  $V$ .  
 b. Prove that the intersection between two subspaces of a vector space is also a subspace.

*Proof.* Let  $A$  and  $B$  be distinct subspaces of the vector space  $V$ , and let  $W = A \cap B$ .

First, we note that by the definition of a subspace,  $\vec{0} \in A, B$ . Thus,  $\vec{0} \in W$ . So, we have the zero vector.

Second, consider arbitrary elements  $x, y \in W$ . By construction of  $W$ , we know that  $x, y \in A$  and  $x, y \in B$ . Because  $A$  and  $B$  are subspaces of  $V$ , we know that  $x + y \in A$  and  $x + y \in B$ . Thus, we see that  $x + y \in W$ . So,  $W$  is closed under addition.

Finally, we consider  $c$ , a scalar value. Then,  $\forall x \in W$ , we know that both  $x$  and  $cx$  are in  $A$  and  $B$  because they are subspaces. Thus,  $cx \in W \forall x \in W$ , and we see that  $W$  is closed under scalar multiplication.

So, we may conclude that  $W$  is also a subspace of  $V$ .  $\square$

- c. Prove that the union between two subspaces of a vector space is also a subspace.

*Proof.* We consider an example. Let  $A = \{(x, 0) | x \in \mathbb{R}\}$ , and  $B = \{(0, y) | y \in \mathbb{R}\}$ , i.e. the  $x$  and  $y$  axes. We know that these sets are subspaces of the vector space  $\mathbb{R}^2$ . Let us now construct,

$$W = \{(x, 0), (0, y) | x, y \in \mathbb{R}\} = A \cup B$$

and consider,

$$x^* = (1, 0), y^* = (0, 1)$$

By definition,  $x^*$  and  $y^*$  are in  $W$ , but,

$$x^* + y^* = (1, 1) \notin W$$

So,  $W$  is not closed under addition, a violation of the definition of a vector subspace. Thus, we have reached a contradiction. Hence, in general, a set formed from the union of two vector subspaces will not also be a subspace.  $\square$

### Question 3. Let,

$$A = \begin{bmatrix} 2 & 1 \\ 3 & -1 \end{bmatrix}$$

- a. Compute  $A^T A^{-1}$ . First, we compute  $A^{-1}$  by finding  $\det(A)$ .

$$\begin{vmatrix} 2 & 1 \\ 3 & -1 \end{vmatrix} = (2)(-1) - (1)(3) = -5$$

Then,

$$A^{-1} = \frac{1}{-5} \begin{bmatrix} -1 & -1 \\ -3 & 2 \end{bmatrix}$$

So, we may compute,

$$A^T A^{-1} = \frac{1}{-5} \begin{bmatrix} 2 & 3 \\ 1 & -1 \end{bmatrix} \begin{bmatrix} -1 & -1 \\ -3 & 2 \end{bmatrix} = \frac{1}{-5} \begin{bmatrix} -2-9 & -2+6 \\ -1+3 & -1-2 \end{bmatrix} = \begin{bmatrix} \frac{11}{5} & \frac{-4}{5} \\ \frac{-2}{5} & \frac{-3}{5} \end{bmatrix}$$

b. A matrix  $A$  is called symmetric if

$$A = A^T$$

Here,

$$A = \begin{bmatrix} 2 & 1 \\ 3 & -1 \end{bmatrix} \neq \begin{bmatrix} 2 & 3 \\ 1 & -1 \end{bmatrix} = A^T$$

So  $A$  is not symmetric.

c. Let  $f(x) = 2x^2 - 2$ . What is the trace of  $f(A)$ ?

We begin by computing

$$f(A) = 2A^2 - 2I$$

$$A^2 = \begin{bmatrix} 2 & 1 \\ 3 & -1 \end{bmatrix} \begin{bmatrix} 2 & 1 \\ 3 & -1 \end{bmatrix} = \begin{bmatrix} 4+3 & 2-1 \\ 6-3 & 3+1 \end{bmatrix} = \begin{bmatrix} 7 & 1 \\ 3 & 4 \end{bmatrix}$$

Then,

$$f(A) = 2A^2 - 2I = 2 \begin{bmatrix} 7 & 1 \\ 3 & 4 \end{bmatrix} - 2 \begin{bmatrix} 1 & 0 \\ 0 & 1 \end{bmatrix} = \begin{bmatrix} 14 & 2 \\ 6 & 8 \end{bmatrix} - \begin{bmatrix} 2 & 0 \\ 0 & 2 \end{bmatrix} = \begin{bmatrix} 12 & 2 \\ 6 & 6 \end{bmatrix}$$

Then,

$$\text{tr}(f(A)) = \sum_i A_{ii} = 12 + 6 = 18$$

**Question 4.** Let  $A$  be any  $2 \times 2$  matrix. Then,

$$\frac{1}{2}(\text{tr}(A))^2 - \frac{1}{2}(\text{tr}(A^2)) - \det(A) = 0$$

*Proof.* Let  $A$  be an arbitrary matrix of dimension  $2 \times 2$ . With elements  $a, b, c, d$  constructed as,

$$A = \begin{bmatrix} a & b \\ c & d \end{bmatrix}$$

Consider first,

$$\text{tr}(A) = a + d$$

Then

$$\frac{1}{2}(\text{tr}(A))^2 = \frac{1}{2}(a + d)^2 = \frac{a^2}{2} + ad + \frac{d^2}{2}$$

Next,

$$A^2 = AA = \begin{bmatrix} a & b \\ c & d \end{bmatrix} \begin{bmatrix} a & b \\ c & d \end{bmatrix} = \begin{bmatrix} a^2 + bc & ab + bd \\ ac + cd & bc + d^2 \end{bmatrix}$$

So,

$$\text{tr}(A^2) = a^2 + 2bc + d^2 \Leftrightarrow \frac{1}{2}(\text{tr}(A^2)) = \frac{a^2}{2} + bc + \frac{d^2}{2}$$

Finally,

$$\begin{vmatrix} a & b \\ c & d \end{vmatrix} = ad - bc$$

So,

$$\begin{aligned} \frac{1}{2}(\text{tr}(A))^2 - \frac{1}{2}(\text{tr}(A^2)) - \det(A) &= \left(\frac{a^2}{2} + ad + \frac{d^2}{2}\right) - \left(\frac{a^2}{2} + bc + \frac{d^2}{2}\right) - (ad - bc) \\ &= (ad - bc) - (ad - bc) \\ &= 0 \end{aligned}$$

As desired. □

**Question 5.** Let  $L$  be the linear transformation from  $\mathbb{R}^3 \rightarrow \mathbb{R}^3$  given by,

$$L(x, y, z) = (-2x - y + z, -x - 2y + z, x + y - 2z)$$

We consider the construction of  $L$  in matrix form, i.e.

$$L = \begin{bmatrix} L_{11} & L_{12} & L_{13} \\ L_{21} & L_{22} & L_{23} \\ L_{31} & L_{32} & L_{33} \end{bmatrix}$$

Such that,

$$\begin{bmatrix} L_{11} & L_{12} & L_{13} \\ L_{21} & L_{22} & L_{23} \\ L_{31} & L_{32} & L_{33} \end{bmatrix} \begin{pmatrix} x \\ y \\ z \end{pmatrix} = \begin{pmatrix} -2x - y + z \\ -x - 2y + z \\ x + y - 2z \end{pmatrix}$$

From this definition, it is clear that the rows of  $L$  are constructed as the coefficients for each row of the output vector, thus,

$$L = \begin{bmatrix} -2 & -1 & 1 \\ -1 & -2 & 1 \\ 1 & 1 & -2 \end{bmatrix}$$

Consider now, the computations of the eigenvalues of this matrix as  $\det(L - \lambda I) = 0$  So,

$$\begin{aligned} \det(L - \lambda I) &= \begin{vmatrix} -2 - \lambda & -1 & 1 \\ -1 & -2 - \lambda & 1 \\ 1 & 1 & -2 - \lambda \end{vmatrix} \\ &= (-2 - \lambda)((-2 - \lambda)^2 - 1) - (-1)(2 + \lambda - 1) + (1)(-1 + 2 + \lambda) \\ &= -\lambda^3 - 6\lambda^2 - 9\lambda - 4 \end{aligned}$$

Plotting this characteristic polynomial, we see that  $\lambda = -4$  is a root, as well as  $\lambda = -1$  being a multiple root. Thus, we have our three roots of this polynomial,  $\lambda_1 = -4$ ,  $\lambda_2 = \lambda_3 = -1$ . We begin construction of the eigenvectors as follows,

$$(L - \lambda_1 I)\vec{e}_1 = \vec{0}, (L - \lambda_2 I)\vec{e}_2 = \vec{0}, (L - \lambda_3 I)\vec{e}_3 = \vec{0}$$

$$\begin{aligned} (L - \lambda_1 I)\vec{e}_1 &= \begin{bmatrix} 2 & -1 & 1 \\ -1 & 2 & 1 \\ 1 & 1 & 2 \end{bmatrix} \begin{bmatrix} \varepsilon_1 \\ \varepsilon_2 \\ \varepsilon_3 \end{bmatrix} \\ &= \begin{bmatrix} 2 & -1 & 1 \\ 0 & \frac{3}{2} & \frac{3}{2} \\ 0 & \frac{3}{2} & \frac{3}{2} \end{bmatrix} \begin{bmatrix} \varepsilon_1 \\ \varepsilon_2 \\ \varepsilon_3 \end{bmatrix} & R_2+ = \frac{1}{2}R_1, R_3- = \frac{1}{2}R_1 \\ &= \begin{bmatrix} 2 & -1 & 1 \\ 0 & 1 & 1 \\ 0 & 0 & 0 \end{bmatrix} \begin{bmatrix} \varepsilon_1 \\ \varepsilon_2 \\ \varepsilon_3 \end{bmatrix} & R_2 = \frac{2}{3}R_2, R_3- = R_2 \\ &= \begin{bmatrix} 1 & 0 & 1 \\ 0 & 1 & 1 \\ 0 & 0 & 0 \end{bmatrix} \begin{bmatrix} \varepsilon_1 \\ \varepsilon_2 \\ \varepsilon_3 \end{bmatrix} & R_1+ = R_2, R_1 = \frac{1}{2}R_1 \end{aligned}$$

Setting equal to  $\vec{0}$  we find,

$$\begin{bmatrix} 1 & 0 & 1 \\ 0 & 1 & 1 \\ 0 & 0 & 0 \end{bmatrix} \begin{bmatrix} \varepsilon_1 \\ \varepsilon_2 \\ \varepsilon_3 \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \\ 0 \end{bmatrix}$$

$$\varepsilon_1 = -\varepsilon_3, \quad \varepsilon_2 = -\varepsilon_3$$

So, taking  $\varepsilon_3 = 1$  for simplicity,

$$\lambda_1 \Rightarrow \vec{e}_1 = \begin{bmatrix} -1 \\ -1 \\ 1 \end{bmatrix}$$

Similarly,

$$\begin{aligned} (L - \lambda_{2,3}I)\vec{e}_{2,3} &= \begin{bmatrix} -1 & -1 & 1 \\ -1 & -1 & 1 \\ 1 & 1 & -1 \end{bmatrix} \begin{bmatrix} \varepsilon_1 \\ \varepsilon_2 \\ \varepsilon_3 \end{bmatrix} \\ &= \begin{bmatrix} 1 & 1 & -1 \\ 0 & 0 & 0 \\ 0 & 0 & 0 \end{bmatrix} \begin{bmatrix} \varepsilon_1 \\ \varepsilon_2 \\ \varepsilon_3 \end{bmatrix} \end{aligned} \quad R_2- = R_1, \quad R_3+ = R_1, \quad R_1 = -R_1$$

Setting equal to  $\vec{0}$  we find,

$$\begin{bmatrix} 1 & 1 & -1 \\ 0 & 0 & 0 \\ 0 & 0 & 0 \end{bmatrix} \begin{bmatrix} \varepsilon_1 \\ \varepsilon_2 \\ \varepsilon_3 \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \\ 0 \end{bmatrix}$$

$$\varepsilon_1 + \varepsilon_2 = \varepsilon_3$$

Here, we must fix two variables to arrive at a vector, thus we have multiple eigenvectors:

$$\lambda_2, \varepsilon_1 = 0, \varepsilon_2 = 1 \Rightarrow \vec{e}_2 = \begin{bmatrix} 0 \\ 1 \\ 1 \end{bmatrix}$$

$$\lambda_3, \varepsilon_1 = 1, \varepsilon_2 = 0 \Rightarrow \vec{e}_3 = \begin{bmatrix} 1 \\ 0 \\ 1 \end{bmatrix}$$

Finally, as a check, we apply the linear transformation  $L$  onto each of these vectors to see if they are true eigenvectors.

$$L\vec{e}_1 = \begin{bmatrix} -2 & -1 & 1 \\ -1 & -2 & 1 \\ 1 & 1 & -2 \end{bmatrix} \begin{bmatrix} -1 \\ -1 \\ 1 \end{bmatrix} = \begin{bmatrix} 2+1+1 \\ 1+2+1 \\ -1-1-2 \end{bmatrix} = \begin{bmatrix} 4 \\ 4 \\ -4 \end{bmatrix} = -4 \begin{bmatrix} -1 \\ -1 \\ 1 \end{bmatrix} = \lambda_1 \vec{e}_1$$

$$L\vec{e}_2 = \begin{bmatrix} -2 & -1 & 1 \\ -1 & -2 & 1 \\ 1 & 1 & -2 \end{bmatrix} \begin{bmatrix} 0 \\ 1 \\ 1 \end{bmatrix} = \begin{bmatrix} 0-1+1 \\ 0-2+1 \\ 0+1-2 \end{bmatrix} = \begin{bmatrix} 0 \\ -1 \\ -1 \end{bmatrix} = -1 \begin{bmatrix} 0 \\ 1 \\ 1 \end{bmatrix} = \lambda_2 \vec{e}_2$$

$$L\vec{e}_3 = \begin{bmatrix} -2 & -1 & 1 \\ -1 & -2 & 1 \\ 1 & 1 & -2 \end{bmatrix} \begin{bmatrix} 1 \\ 0 \\ 1 \end{bmatrix} = \begin{bmatrix} -2+0+1 \\ -1+0+1 \\ 1+0-2 \end{bmatrix} = \begin{bmatrix} -1 \\ 0 \\ -1 \end{bmatrix} = -1 \begin{bmatrix} 1 \\ 0 \\ 1 \end{bmatrix} = \lambda_3 \vec{e}_3$$

Hence, we have found the eigenvalues and the eigenvectors associated with them. To test whether these vectors are linearly independent, we need,

$$\det([\vec{e}_1, \vec{e}_2, \vec{e}_3]) \neq 0$$

Checking,

$$\begin{vmatrix} -1 & 0 & 1 \\ -1 & 1 & 0 \\ 1 & 1 & 1 \end{vmatrix} = -1(1-0) + 0 + 1(-1-1) = -1-2 = -3 \neq 0$$

Thus, our eigenvectors are independent.