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EduMIP





Things used in this project

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Story



Custom parts and enclosures



StrawsonDesign (https://github.com/StrawsonDesign) - EduMiP (https://github.com/StrawsonDesign/EduMiP/forks)
(https://github.com/StrawsonDesign/EduMiP)

No description — Read More (https://github.com/StrawsonDesign/EduMiP#readme)

Latest commit to the **master** branch on Dec 20, 2017 **Download as zip (https://github.com/StrawsonDesign/EduMiP/archive/master.zip)**

Schematics



99beaglebone (https://github.com/beaglebone) / beaglebone-blue

BeagleBoard.org BeagleBone Blue - BeagleBone optimized for mobile robotics — Read More
(<https://github.com/beagleboard/beaglebone-blue#readme>)
<https://beagleboard.org/blue> (<https://beagleboard.org/blue>)

Download as zip (<https://github.com/beagleboard/beaglebone-blue/archive/master.zip>)

Code



102 **StrawsonDesign** (<https://github.com/StrawsonDesign>) / **librobotcontrol**
 “What if I want to build a robot that can follow a line?”

Robotics Focused library for embedded Linux computers. — Read More
(<https://github.com/StrawsonDesign/librobotcontrol#readme>)
<http://strawsondesign.com/docs/librobotcontrol/> (<http://strawsondesign.com/docs/librobotcontrol/>)

Download as zip (<https://github.com/StrawsonDesign/librobotcontrol/archive/master.zip>)

Credits



Comments



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