

# JUSTIN LUO

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Highly motivated Computer Science major at Caltech with a strong foundation in mathematics and engineering. Actively seeking opportunities to contribute to technology development with real-world applications.

## EDUCATION

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**California Institute of Technology (Caltech)**, Pasadena, CA  
Major in Computer Science w/ Minor in Robotics

September 2023 — Present  
GPA 4.04 out of 4.0

## SKILLS

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- **Platforms:** Python, C++, C, Java, Rust, React, OCaml, CUDA, GLSL, OpenGL, Matlab, Git, PyTorch, TensorFlow, MuJoCo, Blender, ROS, Kubernetes, Docker, Linux & Windows Sysadmin
- **Concepts:** Large Language Models, Software Design, Algorithms, Computer Systems, Robotics, Reinforcement Learning, Computer Vision, Graphics, Parallel Computing, Real Time Simulation

## WORK EXPERIENCE

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**Hudson River Trading**  
*Algorithm Developer*

New York City  
*Summer 2026*

**Teaching Assistant**  
*ME/CS/EE 129 - Experimental Robotics*

California Institute of Technology  
*Spring 2025*

Guided small groups in creating an automated exploration robot, integrating sensors & multi-threading in the grad level course.  
*CS 12 - Introduction to Prototyping* *Winter 2025*

Assisted 50+ students in designing and creating an open-ended project, providing a foundational experience in prototyping.  
*ME 8 - Introduction to Robotics* *Fall 2024*

Led 40+ students in designing a fully autonomous camera & arm system, requiring teaching proficiency in Python and CAD.

## AWARDS & ACCOLADES

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- Putnam Top 300
- IMC Prosperity 12th Place
- USA Computing Olympiad Gold, Cyberpatriot Cybersecurity National Finalist
- USA Physics Olympiad Semifinalist
- Eagle Scout

## RESEARCH AND PUBLICATIONS

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**Su Robotics Lab @ UCSD**  
*Research Intern*

San Diego, CA  
*Summer 2025*

- Engineered pipelines for grasp-aware mesh decomposition for **Reinforcement Learning (RL)**, mitigating the computational bottleneck imposed by simulation speed.
- Contributed to **Maniskill**, a comprehensive RL manipulation training library developed by the Su Lab.
- Achieved up to **100% speedup** in training time with grasp-optimized agents.

**Perona Vision Lab @ Caltech**  
*Undergraduate Researcher*

Pasadena, CA  
*Summer 2024*

- Investigated the novel use of **Reinforcement Learning (RL)** to generate synthetic datasets for tracking on animals.
- Generated a dataset of **2000+ synthetic videos**, and significantly improved in-domain performance for CoTracker3.
- Workshop paper presented at **CV4Animals @ CVPR 2025**

**Research Project w/ Dr. Makoto Miyakoshi @ UCSD SCCN**  
*Research Assistant*

San Diego, CA  
*September 2021 — April 2023*

- Researched the reliability, durability, and performance of **ICA**, an advanced algorithm used for **EEG signal processing**.
- Published into **Frontiers in Computational Neuroscience**: <https://doi.org/10.3389/frsip.2023.1064138>.