

JUSTIN VARGHESE JOHN

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SUMMARY

Master's student **researching robot planning**, with a strong foundation in **autonomous navigation, multi-robot systems, embedded systems, real-time control, and intelligent perception**. I thrive at the intersection of research and practical deployment, having built systems that move from simulation and **digital twins** into real-world testing. My projects span from collaborative exploration and maze-solving manipulators to real-time evasive robots optimized for edge hardware. Driven by curiosity and long-term vision, I am particularly interested in advancing robotics through **AI-driven solutions**.

EDUCATION

Master of Science in Robotics and Autonomous Systems (AI)

Ira A. Fulton Schools of Engineering
Arizona State University, Tempe

GPA: 3.94/4.0

Bachelor of Technology (Honors) in Robotics and Automation

Minor in Computer Science and Engineering (AI)
APJ Abdul Kalam Technological University

CGPA: 3.721/4.0

August 2024 - Expected May 2026
AZ, USA

August 2019 - August 2023
Kerala, India

KEY SKILLS

Technical Skills

- **Programming Languages:** Python, C++, C, MATLAB, SQL
- **Machine Learning & AI:** Deep Learning, Machine Learning, Computer Vision, Neural Networks, TensorFlow, PyTorch, AI for Perception, Model Fine-tuning & Optimization, Large-scale Data Processing, AI Deployment/Real-time Systems, Embedded AI
- **GPU & Inference Systems:** CUDA, cuDNN, TensorRT, LLM,
- **Robotics & Simulation:** ROS, SLAM, Gazebo, Simulink, OpenCV, Autonomous Systems, PLC, SCADA, PID Control, Robotic Hardware
- **Software & Tools:** Linux, SolidWorks, Arduino IDE, Edge Computing

Soft Skills

- Communication skills, Critical Thinking, Leadership skills, Teamwork, Problem-solving, Project Management, Adaptability, Creativity, Decision-making, Resilience, Time management.

Leadership & Volunteerism:

- Robotics Department Representative, SESA | May 2020 – Apr 2021.
- National Service Scheme (NSS): Active volunteer (2017-2019).

Certifications

- Fundamentals of Engineering Project Management from Arizona State University
- Inter-Personal Skills in Engineering Project Management from Arizona State University

EXPERIENCE

Graduate Researcher - Autonomous Agents and Intelligent Robots (AAIR) Lab

Arizona State University

July 2025 - Present
Tempe, AZ

- Conducting master's thesis research in **robot planning** under **Prof. Siddharth Srivastava**, focusing on decision-making and planning frameworks for autonomous robotic systems.
- Developing and testing **planning algorithms** for integration with perception and control in real-world autonomous platforms.

Robotics Engineering Intern – EPICS Program

Cartken

May 2025 - Aug 2025
Tempe, AZ

- Collaborated with **Cartken** through ASU's EPICS program to analyze the **lifecycle and environmental impact** of autonomous delivery robots, focusing on sustainable reuse and recycling of components.
- Supported robot prototyping, electrical troubleshooting, and programming, contributing to the development of circular design practices for future robotic systems.

Process Automation and Robotics Intern

ABB India Ltd

October 2022
Bangalore, India

- Collaborated with engineers on **industrial automation workflows**, acquiring proficiency in PLC and SCADA systems.
- Garnered hands-on experience with professional engineers in robotics and automation.

PROJECTS

ReflexDodgeBot: Real-Time Evasion Using Monocular Vision on Embedded Hardware

January 2025 - May 2025

- Developed **ReflexDodgeBot**, a real-time object evasion system using monocular depth estimation and Kalman-based motion tracking, enabling sensor-free, reflex-like responses to approaching obstacles on NVIDIA Jetson Nano.

- Achieved efficient edge deployment by optimizing perception and control pipelines for real-time performance under hardware constraints, with potential scalability to more advanced AI models.

Autonomous Drone Landing System & Custom MATLAB Simulator

January 2025 - May 2025

- Designed and deployed an autonomous drone landing system using MATLAB Simulink, enabling real-time tracking and precision landing on a moving platform with vision-based control.
- Built a custom MATLAB-based drone simulator capable of modeling and simulating various drone types and flight scenarios, supporting control algorithm testing and mission planning.

Autonomous Maze-Solving Robot System

August 2024 - December 2024

- Designed and implemented a digital twin simulation for MyCobot Pro 600 in MATLAB-Simulink, validating forward and inverse kinematics to optimize robotic motion planning for autonomous maze solving.
- Developed a vision-based robotic system integrating BFS pathfinding, inverse kinematics, and real-world execution, enabling the MyCobot Pro 600's end effector to autonomously navigate and solve a maze.

Multi-Robot Exploration and Mapping

August 2024 - December 2024

- Developed a multi-robot exploration system integrating modified Lévy walk strategy with potential field navigation, ensuring efficient coverage, collision avoidance, and seamless map merging.
- Validated over 90% map coverage efficiency and system stability through MATLAB-based simulations, optimizing multi-robot coordination for autonomous exploration.

Real-Time Incident Detection for Intelligent Transportation

July 2022 - June 2023

- Trained a Deep Learning model using TensorFlow on a high-performance server, enabling high-accuracy road incident detection with 95% precision.
- Optimized the model for edge deployment using Edge Impulse, reducing its size by 75% while maintaining accuracy, and deployed it on Arduino Nano 33 BLE, enhancing real-time emergency response efficiency and scalability.

Road Marking System Simulation

January 2023 - June 2023

- Developed a MATLAB-based road marking system utilizing semantic segmentation to identify and highlight lane boundaries on unmarked rural roads, enhancing autonomous driving capabilities and improving navigation safety.
- Designed and implemented a lane departure warning mechanism, leveraging image processing techniques to detect vehicle position relative to generated lane markings, significantly reducing the risk of unintended lane deviations and improving road safety in unstructured environments.

Autonomous Surveillance Vehicle

January 2022 - June 2022

- Developed an autonomous vehicle using Nvidia Jetson Nano, implementing ML-based scene understanding with a camera for road-following, collision avoidance, and environmental monitoring.
- Designed and integrated an embedded system for real-time motor control, utilizing Python and deep learning models to process visual inputs and enable adaptive navigation.