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# ThePointClass.py
from math import sqrt, sin, cos, pi
from random import uniform as
randu
class Point:
    Attributes:
        x: float, the x-coordinate
of a point
       y: float, the y-coordinate of a point
    def
_{\rm init}_{\rm (self,x,y)}:
        """ Creates a point.
        PreC: x and y are
floats
        self.x = x
        self.y = y
    def
__str__(self):
        """ Pretty prints a point object.
        То
apply this function to a point P, write
              print P
 return '(%6.3f,%6.3f)' %(self.x,self.y)
    def Dist(self,other):
""" Returns a float that is the distance from self to other.
        PreC:
self and other are points
        d =
sqrt((self.x-other.x)**2+(self.y-other.y)**2)
        return d
    def Rotate(self,theta):
     """ Returns a point that is obtained by rotating self about the
origin theta degrees in the counterclockwise direction.
        PreC: self is a point
and theta is a number.
        x = self.x
        y = self.y
c = cos(pi*(theta/180.0))
        s = sin(pi*(theta/180.0))
        return
Point(x*c-y*s,x*s+y*c)
    def Reflect(self):
        """ Returns a point that
is obtained by reflecting self about the
        the 45-degree line y = x
PreC: self is a point.
        x = self.x
        y = self.y
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P = Point(y,x) return P