# My Tiny BASIC Extended

# (mytb)

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Ever since reading the first year of Dr. Dobb's Journal of Computer Calisthenics and Orthodontia (yes, that was the original name of the magazine), I wanted to write a tiny BASIC interpreter using the intermediate language (IL) method. The first couple years of DDJ printed source code to several BASICs but none of them used IL.

Well, the idea was always in the back of my mind, so one day I re-read the articles, found some good web pages about the topic, and started writing my own in 6502 assembly language. While it can easily be argued that this was not a good use of my time, it was fun and very satisfying, reminding me of the days when I dreamed of having a high level language on my KIM-1 computer.

Now supports both upper and lower case characters for commands and variables.

So here it is, Bob's Tiny BASIC. It's not as tiny as it could be, but it does have some support for program storage/retrieval. It has support for the base KIM-1 computer, the xKIM monitor by Corsham Technologies, and the CTMON65 monitor by Corsham Technologies. The source is on github:

https://github.com/CorshamTech/6502-Tiny-BASIC

For the Extended version supporting IRQ and Task extensions: https://github/JustLostInTime/em6502

This version of not so tiny basic is useful to learn about multi threaded and multi tasking system and the basic functionality they provide. Besides it lets you run multi task programs on your Corsham CT6502 SS-50 system and Kim system with at least 32K.

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# **Numbers and Variables**

There are 26 integer variables named A to Z. And An exit code Variable ^

Variables may be subscripted var[<expr>]. Any Variable may be subscripted up to end of the variable SET. For example A may have 1 to 26 subscripts representing A-Z in the variable set. B may have subscripts 1 to 25 representing b to z and so forth up to Z which may only have a single subscript 1 . Subscripts start at 1. Tasks may access other tasks Variables with the following notation <PID-Expression>!<Variable-Name>[Subscript] . Subscript is optional. A tasks exit code is available using PID!^

```
1. Access Tasks Variable A: a = task(1000): ? a!a
```

2. Access Tasks EXIT code:  $a = task(1000) : taskw(a) : ? a!^$ 

Each Task has its own Variable set A-Z. This version is not so small.

Numbers are signed 16 bit integers, with a range of -32768 to 32767. Special Variables:

PID - Represents the Process ID of the current task.

Currently some multiple of 25.

TRUE Represents the value -1 or hex \$FFFF

FALSE Represents the value 0

Parameters Passed to a GOSUB or TASK may be accessed using the # variable Example:

```
1. Access parameter 0: ? #[0]
2. " 1: ? #[1]
```

See Task Section for details

# **Expressions/Functions**

# ABS(<number>)

Returns the absolute value of the number.

### FREE()

Returns the number of free bytes for user programs.

### **CALL(<Address expression>,<Value Expression>)**

Call a system function with optionally passing a value in Accumulator.

The Call returns what ever is in the Accumulator when the system function returns.

### **GETCH()**

Returns the next character from the tty keyboard.

# RND(<upper limit>)

Returns a random number from 1 to limit. If limit is not specified, it is set to 32767

# PEEK(<address expression>)

Returns the value at the specified location. Treats address value as unsigned.

# **Commands**

#### **CLS**

Clear the screen by sending the ANSI ESC[3] sequence

DEC <Variable-Name>

Decrement variable by 1. Considerably faster than a=a-1

#### DIR

Lists the content of the disk.

#### **END**

Stops the currently running program, returning the user to the prompt.

#### **ERASE <File Name>**

Delete file from the disk.

#### **EXIT**

Returns back to the underlying OS/Monitor.

### **GOTO <Line Number-expression>**

Computes the value of the expression and then jumps to that line number, or the next line after it, if that specific line does not exist.

# GOSUB <Line Number-expression>[( Parameter 1, ...)]

Compute the value of the expression and then calls a subroutine at that line, or the next line after it. Return back to the calling point with the RETURN keyword. Parameters are passed on the Stack. So are limited by the size of the stack which is also used for math. Currently 20 entries deep.

### IF <expression> [THEN] <statement>[:<statement>]

If the expression evaluates to a non-zero value (TRUE) then the statements following THEN will be executed. THEN Keyword is optional.

#### INC <Variable-name>

Increments the variable by 1. Considerably faster than a=a+1

# INPUT [prompt string ; ] <variable> [,<variable> ...]

Prints a question mark, gets the user's input, converts to a number, then saves the value to the specified variable. If a string follows the keyword then it is printed as a prompt. If the variable ends with a \$ then a single character is read from the input. Example:

input "Enter a letter",a\$

This will read a letter from the keyboard and stores the value in a

### [LET] <variable> = <expression>

Assigns a value to a variable. Let is not required when assigning values to a variable.

#### LOAD <filename>

Loads the specified file into memory. The file is just a text file, so you can edit programs using another editor, then load them with this command. Note that this like typing in lines at the prompt, so if there is an existing program in memory and another is loaded, they are "merged" together. Filename must match the case on the directory listing. NOTE: Quotes are not used to enclose file names.

#### **NFW**

This clears the program currently in memory. There is no mercy, no second chances, and no confirmation. The existing program is gone, instantly.

# POKE <address-expression>, <byte Value expression>

Sets the memory address to the specified byte value

# [PRINT | PR | ?] < values > [; |, ]

Print can have quoted strings, commas, semicolons, numbers and variables.

Commas move to the next tab stop, while semicolons don't advance the cursor.

Using the? Reduces the size of the program and speeds execution.

Print by its self prints a CR LF

A comma or semi colon at the end will not output the CRLF.

If an expression starts with a \$ then the value is output as hex.

If an expression starts with a % then the value is displayed as an unsigned 16 bit value.

If \$ trails an expression the value is written as a character.

# Examples:

```
? free(), %free(), $free() ---- outputs: -22344 43192 A8B8
```

# **PUTCH <expression>**

Put a character to the output device. Range is 0-255

# **REM** [<comments>]

The rest of the line is ignored. It is a comment. It is not mandatory to have any text after the REM keyword. Comments made code easier to read, but they also take time to execute, so too many comments can slow down the code.

# [RETURN | RET][(Return Value expression)

Will return to the next statement following the GOSUB which brought the program to this subroutine. Also used by tasks see Task Section.

#### **RUN**

Begins execution of the program currently in memory starting at the lowest line number.

### SAVE <filename>

Save the current program to the specified filename. Note that the filename is used exactly as specified; nothing (like ".BAS") is automatically added. Note: quotes are not used to enclose the file name.

# Trace <Switch value>

- $_{1}$  %10000000 IPPC trace the core VM
- 2 %01000000 Basic program trace
- 3. %01000001 Interactive Basic program trace

# **TASKS and TASK MANAGEMENT**

Time Sliced Circular scheduling multitasking is supported by Tiny Basic. There are 10 available task entries, The Main Task always uses the first entry leaving 9 available entries for user tasks. The following TASK management commands and functions are available.

Time slices are set by default to 512 IL instructions.. See SLICE

### KILL <Task PID - expression>

Kills the task specified by the expression should be the value returned by TASK() when a task is started.

# STAT(<Task PID - expression>)

Returns the 0 if the task has stopped, 1 otherwise.

# **SLICE < Time-Slice-Count Expression>**

Defines the number of ticks for each time slice used by the task manager. This defaults to 512.

# TASK(<Line Number expression>[,Parameter-expression]...)

As a command This creates a new task starting at the specified line number. As a function it returns the PID of the new task.

# TASKE[(<Exit value-Expression>)]

This may be used within an executing task to end task. If used within the MAIN Line It acts the same as and END statement. The exit value is optional and is stored in the tasks context after the task exits. This is synonymous with the use of return(exit code-expression). The exit code is accessed using the special ^ variable.

1. Pid-expression!^

#### **TASKN**

This Release the rest of the tasks time slice to the system. Execution of the task continues at the next statement when the task receives another time slice.

# TASKW(<Task PID Expression>[,<Task PID Expression>]...

Wait for a task or group of tasks to complete.

# TASKT(MessageValue-Expression, Task PID-Expression)

Transmit a message to a running task. Adds the message to the Message Queue and the Receiving task must issue a TASKR to receive the message.

# **TASKR**([Variable Name])

Variable name is optional and will contain the senders PID on exit. Receives an inter-task message and returns the value or 0 if no wait and nothing received. So don't send a message value of zero! The message may be any other integer value.

# **Task Specific variables**

#### PID

Is the PID of the current task.

### #[Parameter index-expression]

This is the parameter from the parameter list passed when the task was started. Basically the parameters are pushed onto the math stack when the task is started. So the stack size and the need to do math limit the number of parameters that can be passed. No checking is done...So be careful. Parameter index start at zero.

Example: a = #[0] : b = #[1]

These values are read/write and may be used as local variables.

# **Task Implementation Description.**

Tasks are implemented in the IL interpreter and are really a crude form of tasking. Allowing each task a number of IL instructions before the Task is suspended and the next task is started. Task me to some degree be cooperative and issue a task next command to release the remainder of their time slice.

#### Task Control Block Definition

```
27 private variables A-Z,^
                                                       54 Bytes
     Math stack of up to 20 entries
                                                       40 Bytes
     Gosub/For-next Stack 16 entries
                                                       64 Bytes
4. IL Interpreter stack 20 entries
                                                       40 Bytes
    Pointers for each stack 3 Bytes
                                                       03 Bytes
   Basic Application Instruction Pointer
                                                       02 Bytes

    Basic Application Index Register
    Math Work Registers R0,R1,MQ,R1

                                                       01 Bytes
                                                       07 Bytes
9. Indirect Pointers 3
                                                       06 Bytes
                                                      216 Bytes
```

#### **Context Control Block Definition**

```
VARIABLES
                                       2 bytes
                                                    pointer to, 26 A-Z
                                       2 byte
2 byte
                                                   IL program counter
IL call stack
      ILSTACK
      ILSTACKPTR
                                       1 byte
                                                    Pointer ti current entry
      MATHSTACK
                                       2 bytes
1 byte
                                                   MATH Stack pointer
6.
7.
8.
9.
10.
11.
12.
      MATHSTACKPTR
                                                    Pointer to current stack position
      GOSUBSTACK
                                       2 bytes
                                                   pointer to gosub stack
current offset in the stack, moved to task table
      GOSUBSTACK
                                       1 byte
2 bytes
                                                    Pointer to active message, from bottom of il stack
      CURPTR
                                       2 bytes
                                                   Pointer to current Basic line
      CUROFF
                                       1 byte Current offset in Basic Line
                                       2 bytes
                                                   arithmetic register 0
      R1
MQ
                                       2 bytes
                                                    ;arithmetic register 1
                                       2 bytes
                                                    used for some math
                                       1 byte
                                                    General purpose work register(tasking)
                                      25 bytes
```

There are ten Task slots Allocated by default in the provided Source Code. This can be altered by the user. Therefore a total of 2140 bytes are required to support multitasking out of the box. A lot of area for some machines.

The interpreter occupies 6K of memory so for a useful Multi tasking system a minimum of 16K is required, Prefer 32 to 48K. Corsham's 6502 ss-50 system comes with 64K. They also sell memory upgraded for the KIM systems and the Rockwell systems.

This system is a good educational tool. And practical for small projects requiring multiple tasks. It is useful to explore Tasking using the em6502 emulator.

# **Inter-process communication**

Inter process communications is supported by the system.

# ipcs(<message-expression>,<task PID-expression>)

Send a msg to another task

Write messages to the ipc message queue of another task On Return - True-good or False-failed

The message may not be sent if queue is full.

Currently 10 entries are available but this is shared by the Gosub stack.

### Example:

```
On Main task: b = task(1000): a = ipcs(100,b): ? a On Task B: a = ipcr(b): ? "Msg From "a;" Mgs is ";b
```

# ipcr(<variable name>)

Read messages from the IPS message queue

Returns

message value from message queue a message -1 is reserved meaning no entry found The provided variable contains the pid of the sending task. This is optional. This always waits for a message

before returning.

# Ipcc()

Check the message Queue for messages and return the count Returns

Number of messages waiting

# **IRQ and IRQ MANAGEMENT**

# IRQ e number -expression>

Enables the interrupts and Sets the line number to go to when an IRQ is received.

IRQ's are disabled until the IRQ subroutine completes with a ireturn statement. Setting a line number of zero stops the IRQ requests and disables interrupts.

# [IRETURN | IRET]

Returning from an interrupt service routine. Enables the IRQ interrupt.

# **Error Codes**

- 1 = Expression
- 2 = Stack underflow (expression error)
- 3 = Stack overflow (expression is too complex)
- 4 = Unexpected stuff at end of line
- 5 = Syntax error (possibly unknown command)
- 6 = Divide by zero
- 7 = Read fail loading a file
- 8 = Write fail saving a file
- 9 = No filename provided
- 10= File Not Found
- 11=Gosub Stack underflow, too many returns
- 12=Gosub stack overflow, to many nested gosub statements
- 13=Bad Line Number specified, not found
- 14=Unable to create new task, no more slots
- 15=Array Subscript out of range
- 16=Invalid Task PID provided
- 17=Out of space on queue to send new message
- 18=The expect Stack frame was not found.

# **Multi Statement lines**

A colon may be used to place more than one statement on a line. Any line starting with an if statement will only execute the remainder of the line if the expression is true. Even when containing a : and more statements.

<statement>[:<statement].. as many statement than can fit in 132 characters per line

# **Improving Speed**

Tiny BASIC on a 6502 using IL is slower than a machine language program, by a huge margin, but there are steps to slightly improve performance.

- Don't use a lot of REM statements, at least not near the beginning of the code. Every REM must be skipped at run time.
- Put heavily used code closer to the front of the program so those line numbers can be found quicker. An old trick was to have a GOTO at the start of the program which jumps to a very high line number which does the initialization.
- Use variables instead of constants. Constants have to be converted from ASCII characters into an integer, while variables are quick to look up the binary values.

# **Example programs**

3040 print "End of task 3000 ";PID

# **Example Task program** 10 print "Simple task test, to activate all tasks",r 15 a = 2000 : b = 10 : c = 120 x = task(1000): ? "PID = ";x 30 y = task(2000): ? "PID = ";y 40 z = task(3000): ? "PID = ";z 50 k = task(4000): ? "PID = ";k 60 l = task(5000): ? "PID = ";1 70 m = task(6000): ? "PID = ";m 80 n = task(7000): ? "PID = ";n 90 o = task(8000): ? "PID = "; o 100 p = task(9000): ? "PID = ";p 110 taskw(x,y,z,k,l,m,n,o,p): Rem wait for all the tasks to finish 191 print "End of loop ",r 195 r = r + c : if r < a goto b200 print "Test complete" 210 end 1000 print "Begin new task 1000 PID=";PID 1005 a = 0 : b = 20 : c = 1040 : d = 1010 : e = 11010 a = a + e1020 if a > b then goto c1030 goto d 1040 print "End of task 1000";PID 1050 taske 2000 print "Begin new task 2000 PID=";PID 2005 b = 0 : s = 20 : c = 2010 : d = 1 : a = 32010 b = b + d2020 if b < s then goto c 2040 print "End of task 2000 ";PID 2050 taske 3000 print "Begin new task 3000 PID=";PID 3005 c = 0 : a=20 : b=3040 : d = 3010 : h=13010 c = c + h3020 if c > a then goto b3030 goto d

```
3050 taske
```

```
4000 print "Begin new task 4000 PID=";PID
4005 d = 0 : e = 20 : f = 4040 : g = 4010 : h = 1
4010 d = d + h
4020 \text{ if } d > e \text{ then goto } f
4030 goto g
4040 print "End of task 4000 ";PID
4050 taske
5000 print "Begin new task 5000 PID=";PID
5005 \text{ e} = 0 \text{ :} f = 20 \text{ :} g = 5010 \text{ :} h = 1
5010 e = e + h
5020 if e < f then goto g
5040 print "End of task 5000";PID
5050 taske
6000 print "Begin new task 6000 PID=";PID
6005 f = 0 : a=1 :b=10000 :c=20:d=6010
6010 f = f + a
6015 gosub b
6020 \text{ if } f < c \text{ then go to } d
6040 print "End of task 6000";PID, q
6050 taske
7000 print "Begin new task 7000 PID=";PID
7005 g = 0 : a=1 :b=10000:c=7010:d=20
7010 g = g + a
7015 gosub b
7020 \text{ if } g < d \text{ then goto } c
7040 print "End of task 7000";PID, q
7050 taske
8000 print "Begin new task 8000 PID=";PID
8005 \text{ h} = 0 : \text{a} = 1 : \text{b} = 8010 : \text{c} = 20 : \text{d} = 10000
8010 h = h + a
8015 gosub d
8020 \text{ if } h < c \text{ then goto } b
8040 print "End of task 8000";PID, q
8050 taske
9000 print "Begin new task 9000 PID=";PID
9005 i = 0 : j = 1 : k = 9010 : a = 20 : b = 10000
9010 i = i + j
9015 gosub b
9020 if i < a then goto k
```

```
9040 print "End of task 9000";PID, q
9050 taske
10000 Rem gosub test
10010 q = q + 1
10020 return
Sample IPC program
10 REM test ipc is working
15 cls
20 a = Task(2000) : b = task(3000,a)
30 taskw(a,b)
40?:?: print "Test completed a's exitcode = ";a!^; " B's exit code = ";b!^
50 end
2000 Rem this task will wait for a message
2005 print "PID: ";PID, "Waiting for message":?
2010 a = ipcr(b)
2020 print "I am PID: ";PID, "Recieved msg: ";a, "From PID: ",b:?
2030 return(a)
3000 Rem Send a message to another task
3010 \text{ a} = \#[0]: Rem should be the pid start for first task
3020 Print "PID: ";PID, " Sending message to PID: ";a
3030 print "Result of sending msg = ";:if ipcs(300, a)? "Sent" : return(84)
```

3040 print "Failed": return(84)