

### Problem 3

$x_{k+1} = x_k - \frac{\nabla f(x_k)}{\|\nabla f(x_k)\|} \Rightarrow$  newton step

so: multivariable functions

$x_{k+1} = x_k - J_{f(x_k)}^{-1} \cdot f(x_k)$

$J_{f(x)} = \begin{bmatrix} \frac{\partial f(x)}{\partial x_1} \\ \frac{\partial f(x)}{\partial x_2} \end{bmatrix} \rightarrow \begin{bmatrix} \frac{\partial f(x)}{\partial x_1} \\ \frac{\partial f(x)}{\partial x_2} \end{bmatrix} \rightarrow \text{Jacobian matrix}$

$\nabla f = \begin{bmatrix} \frac{\partial f(x)}{\partial x_1} \\ \frac{\partial f(x)}{\partial x_2} \end{bmatrix}$

$P_d = -J_{f(x_k)}^{-1} F(x_k)$

$P_d: J_{f(x_k)}^{-1} = -F(x_k)$

$\begin{bmatrix} -6 & 9 \\ 1 & 1 \end{bmatrix} \begin{bmatrix} p_1 \\ p_2 \end{bmatrix} = \begin{bmatrix} 18 \\ 0 \end{bmatrix}$

$\begin{bmatrix} -6 & 9 \\ 1 & 1 \end{bmatrix} \times \begin{bmatrix} p_1 \\ p_2 \end{bmatrix} = \begin{bmatrix} 18 \\ 0 \end{bmatrix}$

$-6p_1 + 9p_2 = 18$

$p_1 = -p_2$

$P_d = \begin{bmatrix} -\frac{9}{5} \\ \frac{6}{5} \end{bmatrix}$

solution  $p$   
 $J_{f(x)} = \begin{bmatrix} x_1^2 - 3 & 3x_1(x_1 + 2) \\ x_1 e^{x_1} \cos(x_2 e^{x_1 - 1}) & e^{x_1} \cos(x_2 e^{x_1 - 1}) \end{bmatrix}$

$J_{f(x_0)} = \begin{bmatrix} -6 & 9 \\ 1 & 1 \end{bmatrix}$

$x_{k+1} = x_k - J_{f(x_k)}^{-1} \cdot f(x_k)$

$x_{k+1} = x_k + P$

$x_{k+1} = \begin{bmatrix} -\frac{6}{5} \\ \frac{6}{5} \end{bmatrix}$

### Problem 9

$f(x_1, x_2) = e^{x_1} x_2^2$

sought to be minimized  $x_0 = (0, 1)$  over  $\mathbb{R}^2$

1) Steepest descent direction  $\rightarrow P^T$

$P_d = -\nabla f(x)$

$s = \begin{bmatrix} x_2^2 \cdot e^{x_1} \\ 2x_2 \cdot e^{x_1} \end{bmatrix} = \begin{bmatrix} 1 \\ 2 \end{bmatrix}$

$P_d = \begin{bmatrix} -1 \\ -2 \end{bmatrix} \Rightarrow \nabla f(x) \cdot P_d = \nabla f$

$\begin{bmatrix} 1 & 2 \\ 2 & 2 \end{bmatrix} \begin{bmatrix} p_1 \\ p_2 \end{bmatrix} = \begin{bmatrix} -1 \\ -2 \end{bmatrix}$

$p_1 + 2p_2 = -1$

$p_1 + p_2 = -1$

$p_1 = -1$

$p_2 = 0$

$\nabla f \cdot P_d = \begin{bmatrix} 1 & 2 \end{bmatrix} \begin{bmatrix} -1 \\ 0 \end{bmatrix} = -1 < 0$

Yes, dir in the direction of descent

4)  $m(p) = f(x) + \nabla f(x)^T p + \frac{1}{2} p^T \nabla^2 f(x) p$

quadratic model by newton's method

$f(x) = \frac{1}{2} x^T A x + b^T x + c$

$\nabla f = \frac{1}{2} (A + A^T) x + b$

if  $A$  is symmetrical matrix

$A = A^T$ , so

$\nabla f = A x + b$

$f(x) = \frac{1}{2} x^T A x + b^T x + c$

$A_{n \times n}$  matrix

$f(x) = \frac{1}{2} \sum_{i=1}^n \sum_{j=1}^n a_{ij} x_i x_j + b^T x + c$

$f = \frac{1}{2} (A + A^T) x + b$

radial