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PYTHON PROGRAM TO PERFORM OBJECT DETECTION WITH YOLOv3

Aim:

To perform object detection with YOLOv3 in python.

Procedure:

1. Parse command-line arguments to choose between webcam, video, or image detection.
2. Load the pre-trained YOLO model, configuration file, and COCO class names.
3. Load and resize the input image or video frame.
4. Convert the input image/frame to a blob for YOLO processing.
5. Perform forward pass through the YOLO network to detect objects.
6. Extract bounding boxes, class IDs, and confidence scores from the YOLO output.
7. Apply non-maximum suppression to filter overlapping boxes.
8. Draw bounding boxes and labels on the detected objects in the image/frame.
9. Display the processed image/frame with detected objects.
10. Release video capture and close all OpenCV windows on exit.

Code:

```
import cv2 import
numpy as np import
argparse import time

parser = argparse.ArgumentParser()
```

```
parser.add_argument('--webcam', help="True/False", default=False)
parser.add_argument('--play_video', help="Tue/False", default=False)
parser.add_argument('--image', help="Tue/False", default=False)
parser.add_argument('--video_path', help="Path of video file",
default="videos/car_on_road.mp4")
parser.add_argument('--image_path', help="Path of image to detect objects",
default="Images/bicycle.jpg")
parser.add_argument('--verbose', help="To print statements", default=True) args =
parser.parse_args()

#Load yolo def load_yolo(): net =
cv2.dnn.readNet("yolov3.weights", "yolov3.cfg") classes =
[] with open("coco.names", "r") as f:
      classes = [line.strip() for line in f.readlines()]


  output_layers = [layer_name for layer_name in
net.getUnconnectedOutLayersNames()]
  colors = np.random.uniform(0, 255, size=(len(classes), 3)) return
  net, classes, colors, output_layers

def load_image(img_path): # image loading
  img = cv2.imread(img_path) img =
  cv2.resize(img, None, fx=0.4, fy=0.4)
  height, width, channels = img.shape return
  img, height, width, channels

def start_webcam():
  cap = cv2.VideoCapture(0)
  return cap
```

```
def display_blob(blob):
    '''
        Three images each for RED, GREEN, BLUE channel
    '''
    for b in blob:
        for n, imgb in enumerate(b):
            cv2.imshow(str(n), imgb)

def detect_objects(img, net, outputLayers):
    blob = cv2.dnn.blobFromImage(img, scalefactor=0.00392, size=(320, 320),
mean=(0, 0, 0), swapRB=True, crop=False)
    net.setInput(blob)
    outputs = net.forward(outputLayers) return
    blob, outputs

def get_box_dimensions(outputs, height, width):
    boxes = [] confs = []
    class_ids = [] for
    output in outputs:
        for detect in output: scores =
            detect[5:] class_id =
            np.argmax(scores) conf =
            scores[class_id] if conf > 0.3:
                center_x = int(detect[0] * width)
                center_y = int(detect[1] * height) w
                = int(detect[2] * width) h =
                int(detect[3] * height)
                x = int(center_x - w/2) y =
                int(center_y - h / 2)
                boxes.append([x, y, w, h])
```

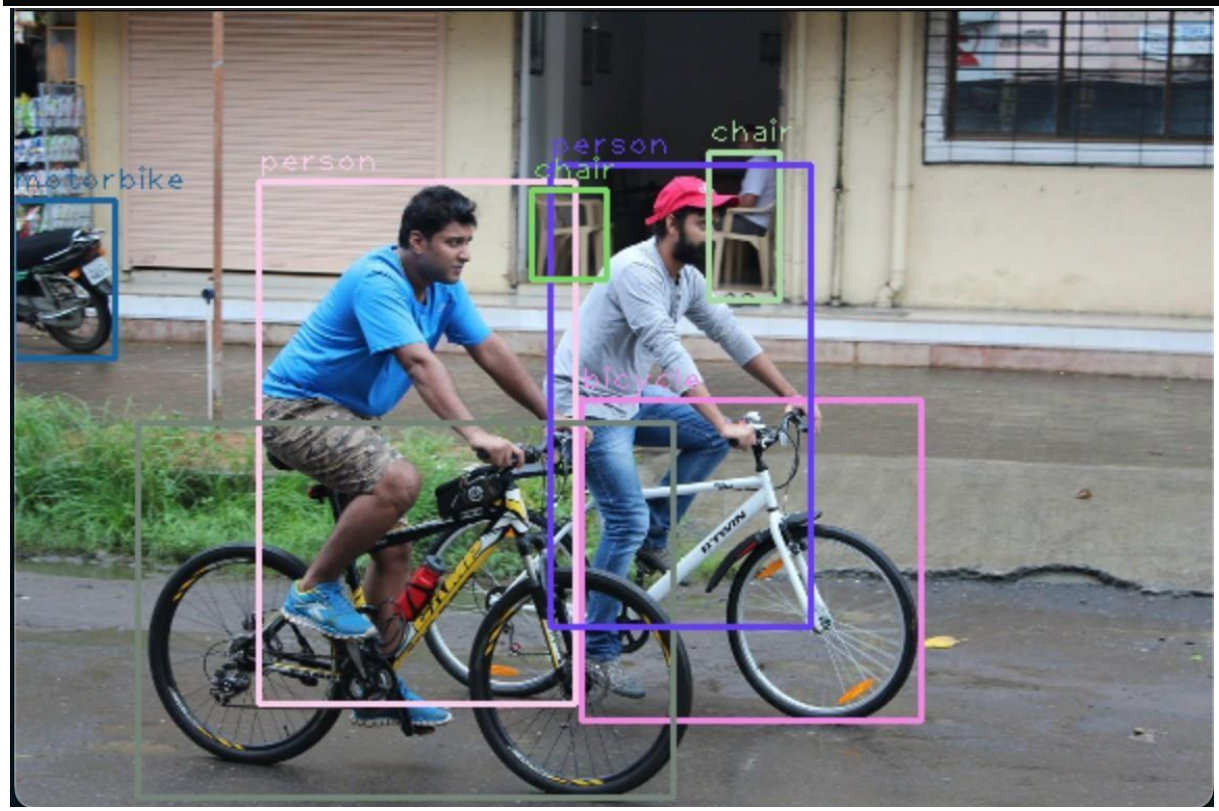
```
            confs.append(float(conf))
            class_ids.append(class_id)
    return boxes, confs, class_ids


def draw_labels(boxes, confs, colors, class_ids, classes, img):
    indexes = cv2.dnn.NMSBoxes(boxes, confs, 0.5, 0.4)
    font = cv2.FONT_HERSHEY_PLAIN for i in
    range(len(boxes)): if i in indexes:
        x, y, w, h = boxes[i] label =
        str(classes[class_ids[i]]) color =
        colors[i]
        cv2.rectangle(img, (x,y), (x+w, y+h), color, 2) cv2.putText(img,
        label, (x, y - 5), font, 1, color, 1)
    cv2.imshow("Image", img)


def image_detect(img_path):
    model, classes, colors, output_layers = load_yolo() image, height, width,
    channels = load_image(img_path) blob, outputs = detect_objects(image,
    model, output_layers) boxes, confs, class_ids =
    get_box_dimensions(outputs, height, width) draw_labels(boxes, confs,
    colors, class_ids, classes, image) while True: key = cv2.waitKey(1) if key
    == 27:
        break


def webcam_detect():
    model, classes, colors, output_layers = load_yolo()
    cap = start_webcam() while True:
      _, frame = cap.read()
      height, width, channels = frame.shape
```

```
        blob, outputs = detect_objects(frame, model, output_layers) boxes, confs,
        class_ids = get_box_dimensions(outputs, height, width)
        draw_labels(boxes, confs, colors, class_ids, classes, frame) key =
        cv2.waitKey(1) if key == 27:
            break
    cap.release()

def start_video(video_path):
    model, classes, colors, output_layers = load_yolo()
    cap = cv2.VideoCapture(video_path) while True:
        _, frame = cap.read()
        height, width, channels = frame.shape
        blob, outputs = detect_objects(frame, model, output_layers) boxes, confs,
        class_ids = get_box_dimensions(outputs, height, width)
        draw_labels(boxes, confs, colors, class_ids, classes, frame) key =
        cv2.waitKey(1) if key == 27:
            break
    cap.release()


if ___name ___ == '_____main_':
    webcam = args.webcam video_play
    = args.play_video image =
    args.image if webcam:
        if args.verbose:
            print('---- Starting Web Cam object detection -----')
        webcam_detect()
    if  video_play:  video_path  =
        args.video_path  if
        args.verbose:
            print('Opening '+video_path+" ..... ")
```

```
    start_video(video_path)
if image:
    image_path = args.image_path if
    args.verbose:
        print("Opening "+image_path+" ..... ")
    image_detect(image_path)

cv2.destroyAllWindows()
```

Output:

```
Opening images/bicycle.jpg ....
2024-09-16 17:13:01.811 Python[6037:1698341] +[IMKClient subclass]: chose IMKClient_Legacy
2024-09-16 17:13:01.811 Python[6037:1698341] +[IMKInputSession subclass]: chose IMKInputSession_Legacy
```



Result:

Thus, to perform object detection using YOLOv3 in python has been completed successfully.