

Numerical Computing :: Project Eight

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In [1]: %matplotlib notebook
from matplotlib import pyplot
import matplotlib.pyplot as plt
import numpy as np
import math
```

1. Method of Normal Equations (uses the Cholesky factorization)

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In [2]: #3.Solve with Cholesky factorization
def choleskySolve(A, b):
    new_A = np.matmul(A.T, A)
    new_b = np.matmul(A.T, b)
    L = np.linalg.cholesky(new_A)
    y = np.linalg.solve(L, new_b)
    return np.linalg.solve(L.T, y)

def NormEqChol(A, b):
    if np.linalg.matrix_rank(A) == A.shape[1]:
        return choleskySolve(A,b)
    else:
        print("Rank ({{}}) must be equal to number of columns ({{}})".format(1,2))
        return None
```

2. Method based on the Thin QR factorization

```
In [3]: #Thin QR
def ThinQR(A, b):
    Q, R = np.linalg.qr(A)
    return np.linalg.solve(R, Q.T.dot(b))
```

- Next, load the given matrix (download from Canvas) into memory. Call the matrix A,

$$A = [a_1 \cdots a_n] \quad (1)$$

where $a_i \in \mathbb{R}^m$ is the i th column of A. Define the matrices A_1, \dots, A_n as:

$$A_k = [a_1 \cdots a_k], \quad k = 1, \dots, n. \quad (2)$$

That is, A_k contains the first k columns of the matrix A (that you loaded into memory).

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In [4]: #Load matrix
mat8= np.loadtxt('Project 8 Matrix.txt',dtype=float, encoding=None, delimiter=",")
```

1. Report the size, rank, and condition number of A_k .

```
In [5]: def MatrixEvaluation(mat):
#1. What are the matrix dimensions?
size=mat.shape

# What is the rank?
rank= np.linalg.matrix_rank(mat)

# What is the condition number?
cond= np.linalg.cond(mat)

return print("Size: {}, Rank: {}, Condition Number: {}".format(size,rank,cond))
```

2. Analyze Error Data

- Now, generate the error data that you'll analyze. For k from $k_{min} = 40$ to $k_{max} = 65$:
- Generate 100 random vectors $b_i \in \mathbb{R}_m$.
- For each b_i :
 - (a) Use the built-in equation solver (numpy.linalg.lstsq) to compute the least-squares minimizers given A_k and b_i . Call this vector x_{true} , because we're just gonna trust the software on this one.
 - (b) Use your Normal Equation solver to compute the least-squares minimizer, x_{NE} . Compute the relative error with x_{true} .
 - (c) Use your QR solver to compute the least-squares minimizer, x_{QR} . Compute the relative error with x_{true} .

```
In [6]: #adapted from proj5
def generate_random_bs(mat, num_bs):
    ret = []
    for i in range(num_bs):
        ret.append(np.random.rand(mat.shape[0],1))
    return ret

#from proj5
def relative_error(sol, truth):
    return np.linalg.norm(sol - truth) / np.linalg.norm(sol)
```

```
In [7]: low = 40
high = 65
avg_NE_errors = []
avg_QR_errors = []

for k in range(low, high + 1):
    # 1: Report size, rank, and condition number for each matrix  $A_k$ 
    A_k = np.delete(mat8, [x for x in range(k, mat8.shape[0])], 1)
    MatrixEvaluation(A_k)
    #Call this vector  $x_{true}$ 
```

```

# 2 Generate 100 random vectors b_i. For each b_i:
b_is = generate_random_bs(A_k, 100)

# vector xtrue, because we're just gonna trust the software on this one.
xtrue = []

#hold each bs error for each method
xNE = []
xQR = []

i = 0

for b_i in b_is:
    # Use the built-in equation solver (numpy.linalg.lstsq) to compute the least-sq
    xtrue.append(np.linalg.lstsq(A_k, b_i, rcond=None)[0])

    # use Normal Equation method that uses Cholesky Solving
    #and compute relative error
    xNE.append(relative_error(NormEqChol(A_k, b_i), xtrue[i]))

    # use Thin QR factorization
    #and compute relative error
    xQR.append(relative_error(ThinQR(A_k, b_i), xtrue[i]))

    i+=1

avg_NE_errors.append(np.mean(xNE))
avg_QR_errors.append(np.mean(xQR))

```

```

Size: (101, 40), Rank: 40, Condition Number: 74.87666090810829
Size: (101, 41), Rank: 41, Condition Number: 103.80036453828598
Size: (101, 42), Rank: 42, Condition Number: 152.28560787895992
Size: (101, 43), Rank: 43, Condition Number: 217.5603797633556
Size: (101, 44), Rank: 44, Condition Number: 328.8920284188398
Size: (101, 45), Rank: 45, Condition Number: 483.7805289853143
Size: (101, 46), Rank: 46, Condition Number: 753.0464969101489
Size: (101, 47), Rank: 47, Condition Number: 1140.0742240740228
Size: (101, 48), Rank: 48, Condition Number: 1826.7931127930933
Size: (101, 49), Rank: 49, Condition Number: 2846.4222743668856
Size: (101, 50), Rank: 50, Condition Number: 4695.087418605814
Size: (101, 51), Rank: 51, Condition Number: 7530.548252626719
Size: (101, 52), Rank: 52, Condition Number: 12789.3765489398
Size: (101, 53), Rank: 53, Condition Number: 21122.71687383797
Size: (101, 54), Rank: 54, Condition Number: 36949.48320886926
Size: (101, 55), Rank: 55, Condition Number: 62868.333661241464
Size: (101, 56), Rank: 56, Condition Number: 113329.35745270173
Size: (101, 57), Rank: 57, Condition Number: 198770.68211674056
Size: (101, 58), Rank: 58, Condition Number: 369475.91867289506
Size: (101, 59), Rank: 59, Condition Number: 668493.2863225089
Size: (101, 60), Rank: 60, Condition Number: 1282274.0199211722
Size: (101, 61), Rank: 61, Condition Number: 2395303.239322347
Size: (101, 62), Rank: 62, Condition Number: 4745459.92767099
Size: (101, 63), Rank: 63, Condition Number: 9161533.469392981
Size: (101, 64), Rank: 64, Condition Number: 18765737.99510158
Size: (101, 65), Rank: 65, Condition Number: 37486287.33249055

```

Make two plots on a semilogy scale:

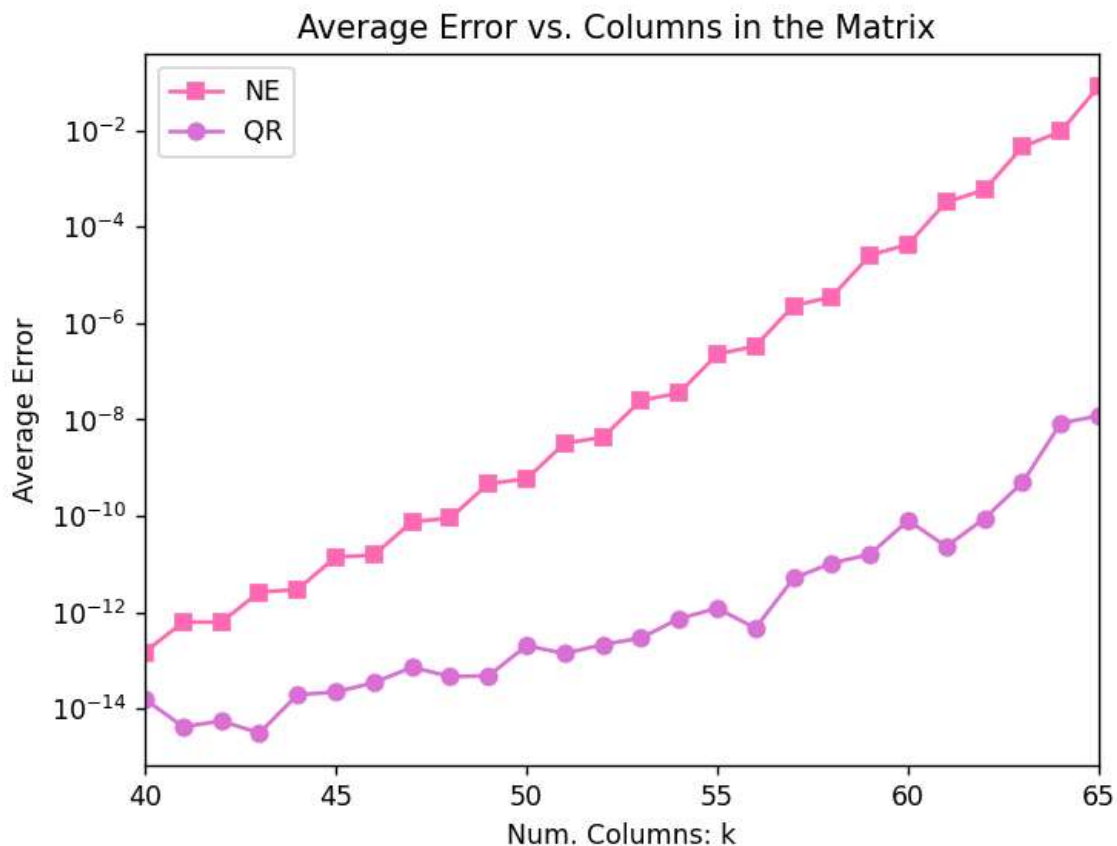
- 1) the average error versus k (how many columns in the matrix) for both QR and the Normal Equations

In [8]:

```
#for columns
k = [n for n in range(low, high + 1)]

#semilog plot with matlab
plt.semilogy(k, avg_NE_errors, '-s', label='NE', color='hotpink')
plt.semilogy(k, avg_QR_errors, '-o', label='QR', color='orchid')
plt.xlim([low, high])

#Label
plt.title("Average Error vs. Columns in the Matrix ")
plt.xlabel("Num. Columns: k")
plt.ylabel("Average Error")
plt.legend()
plt.show()
```



Now tell me what's going on. More specifically:

1. What is the relationship between the error using QR versus the Normal Equations?

-QR error is lower on average than the method of Normal Equations. This is because in NE method when we are forming the product, we square the condition number of the problem matrix which causes instability.

2. What is the relationship between the errors and the condition number of A_k ?

- As condition number increases, the error also increases

3. Suppose your matrix A is ill-conditioned. Which method is more favorable?

- If the matrix is ill-conditioned it can reduce the accuracy of a least squares solution.

- The the method of using normal equations using Cholesky (NormEqChol) is likely to be unstable, especially for large problems. In general it is not recommended in general.

- QR factorization is more stable than the Cholesky approach so it is the standard method for least squares problems.

References

- Paul's famous lectures, as always
- used many helper functions from my Project 4 and 5
- http://www.math.iit.edu/~fass/477577_Chapter_5.pdf
- <https://pythontic.com/visualization/charts/semilog>
- <https://johnwlambert.github.io/least-squares/>
- <http://www.ece.northwestern.edu/local-apps/matlabhelp/techdoc/ref/qr.html>
- <https://www.quantstart.com/articles/QR-Decomposition-with-Python-and-NumPy/>
- <https://boostedml.com/2020/04/solving-full-rank-linear-least-squares-without-matrix-inversion-in-python-and-numpy.html>

In []: