

CS 370: Computer Imaging

Pushpak Karnick

Motivation to study Image Processing

Why Image Processing?

- Images are ubiquitous
- Casual and targeted output
 - Social Media ...
 - Photoshop, Inkscape, ...
 - Maya, ZBrush, Houdini ...
- Output of the 3D Visualization Pipeline

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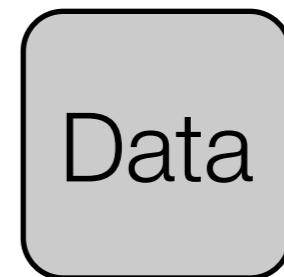
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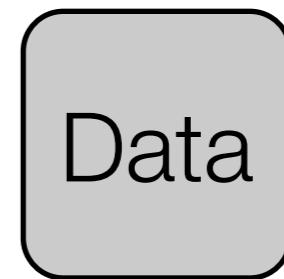
Data
Processing



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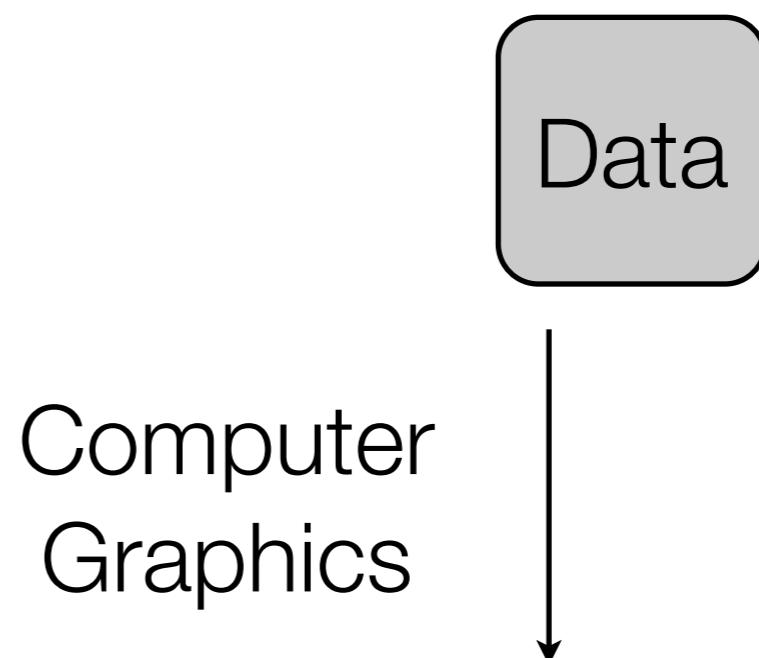
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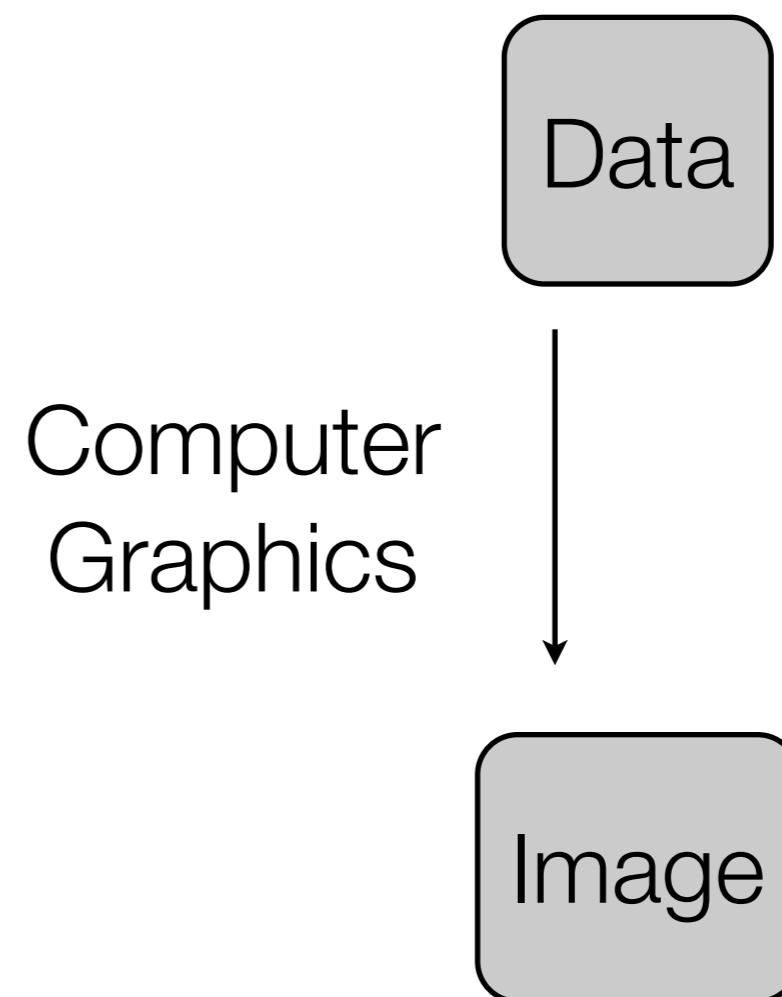
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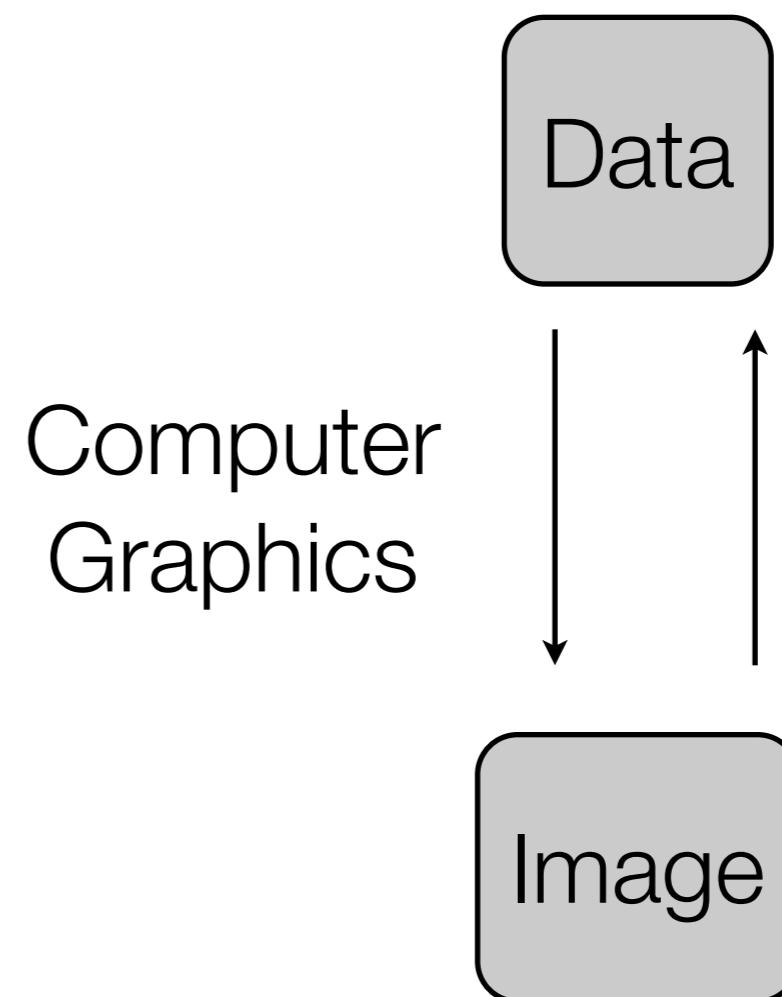
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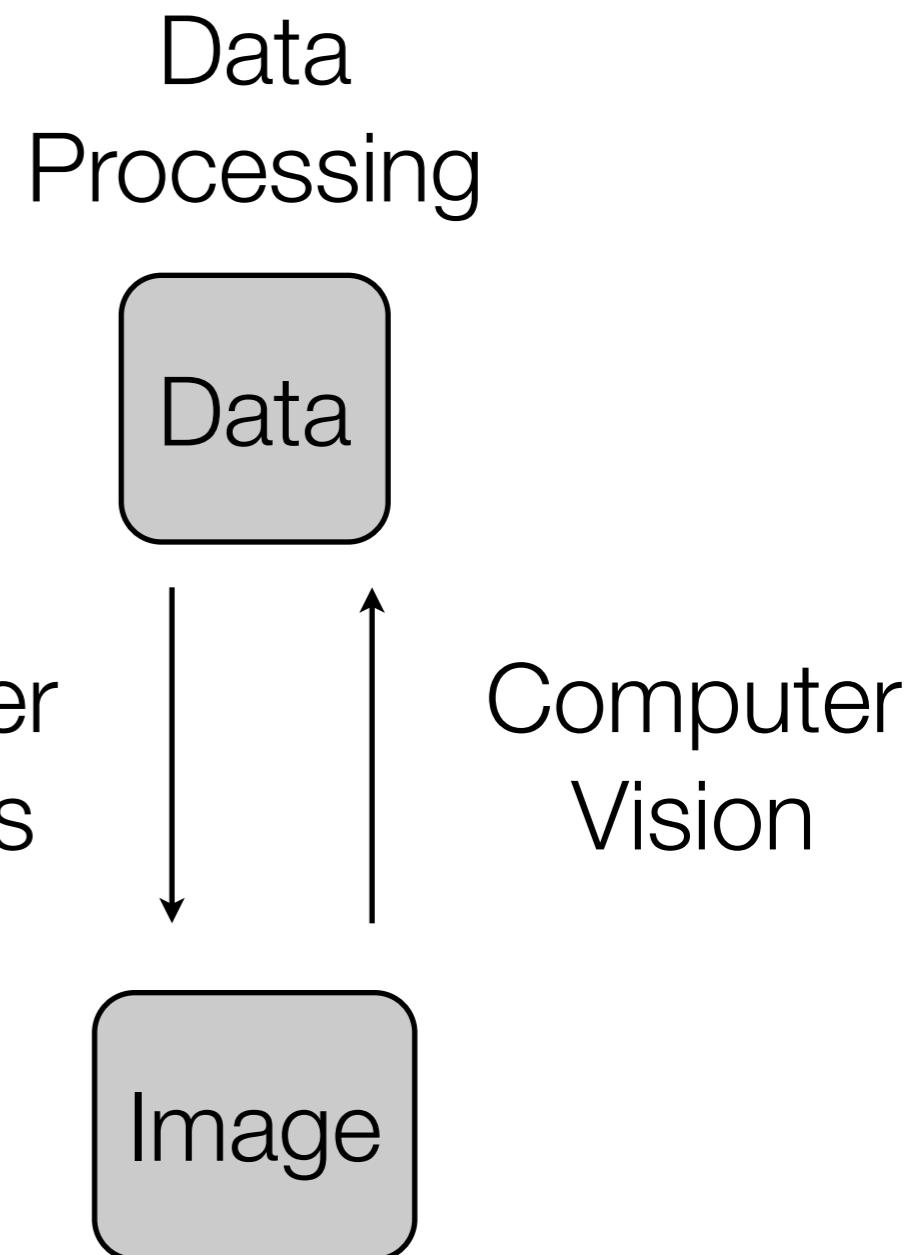
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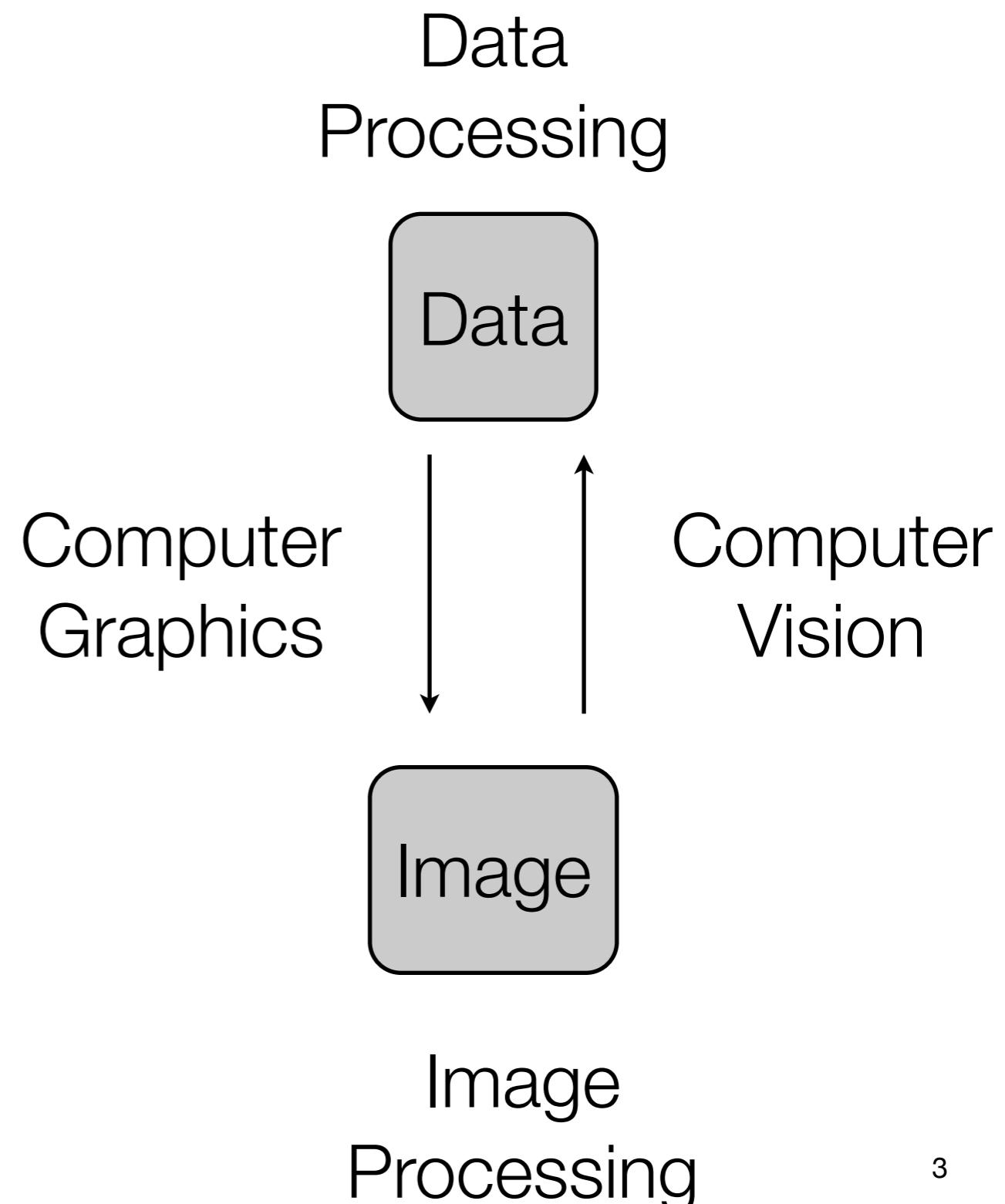
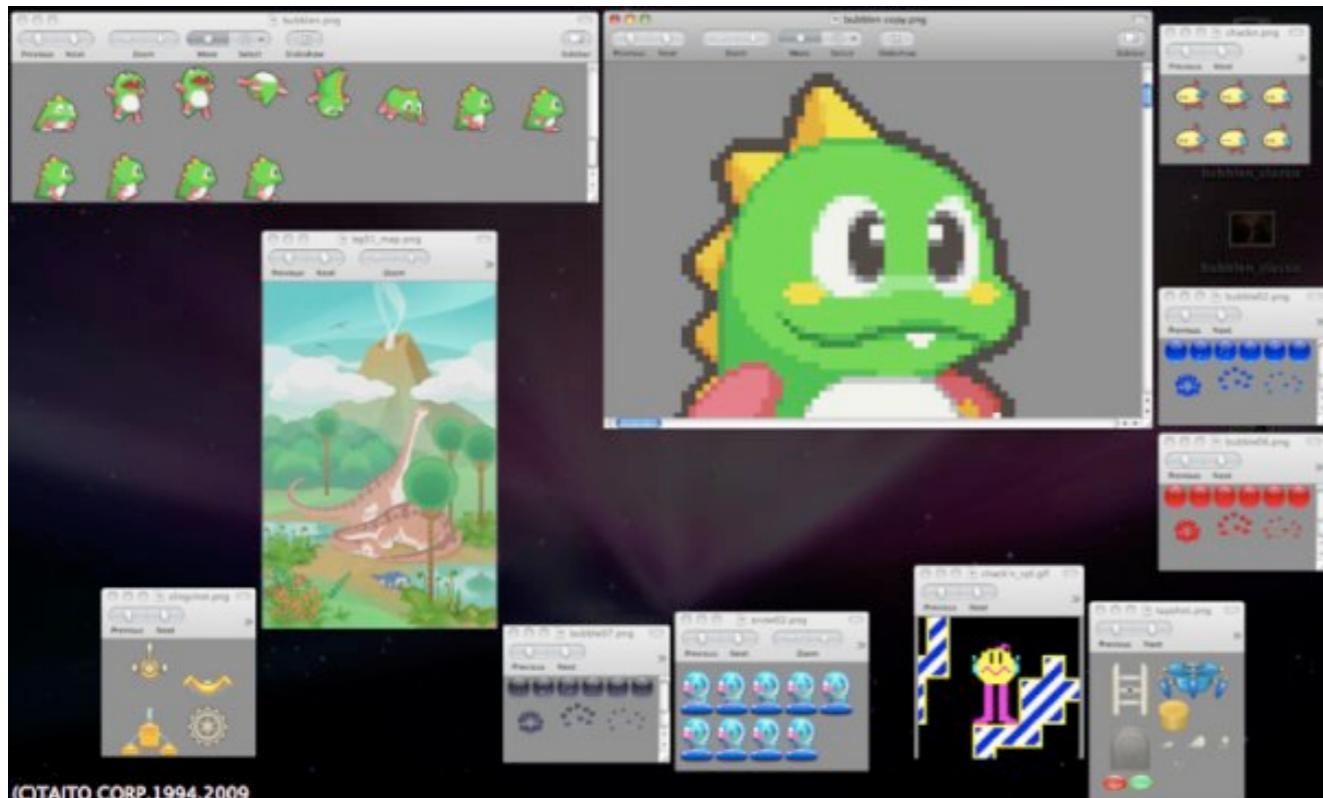


Image-based Methods in Games

- Sprites, billboards, HUDs
- Particle Systems
- Post-processing operations
 - Tone mapping - High Dynamic Range (HDR) Imaging
 - Real-time glow
 - Depth-of-field
 - Motion Blur

Sprites, Billboards



(c) Taito Corp, 2009

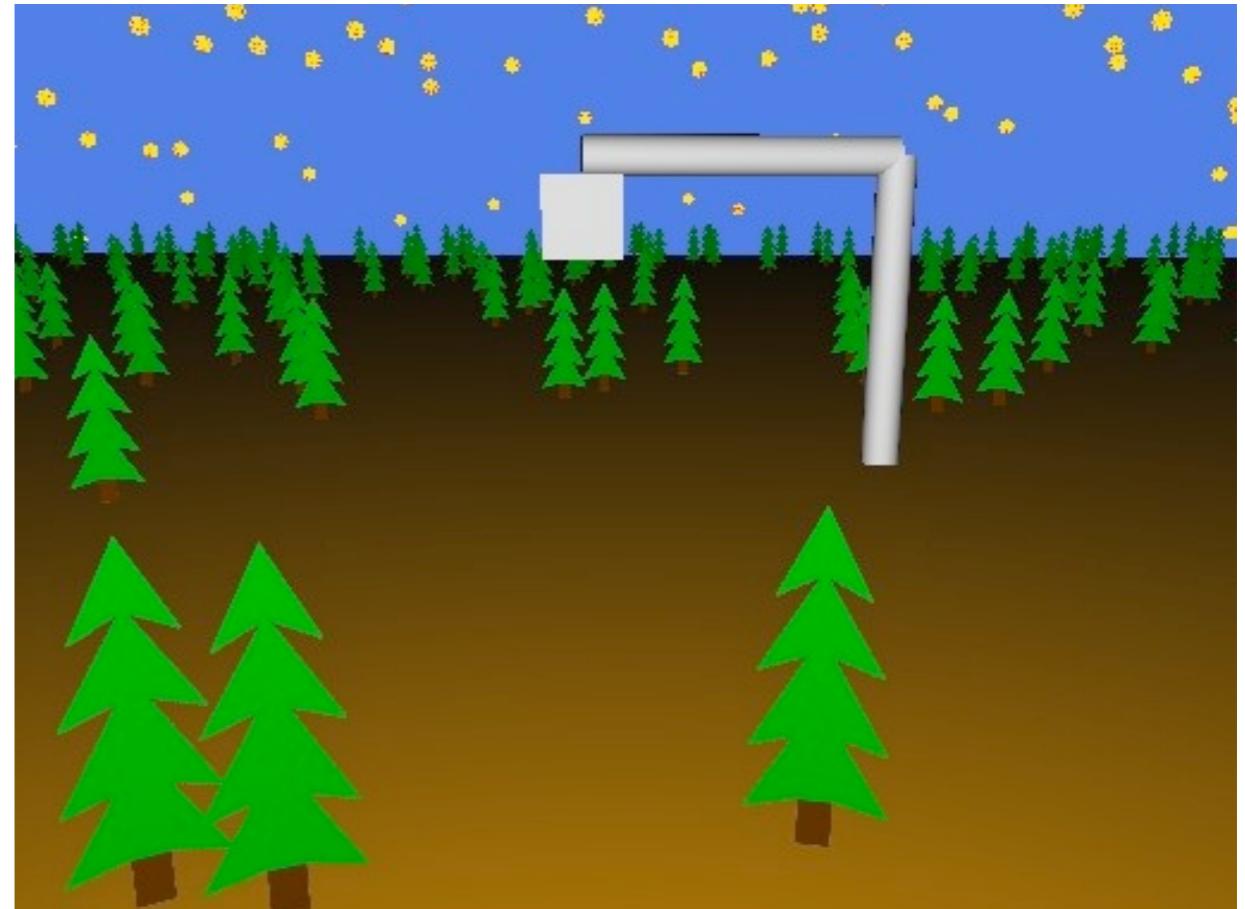


Figure courtesy www.gametrailers.com

Heads-up Displays (HUDs)



Metroid Prime



Mass Effect, BioWare

High Dynamic Range (HDR)



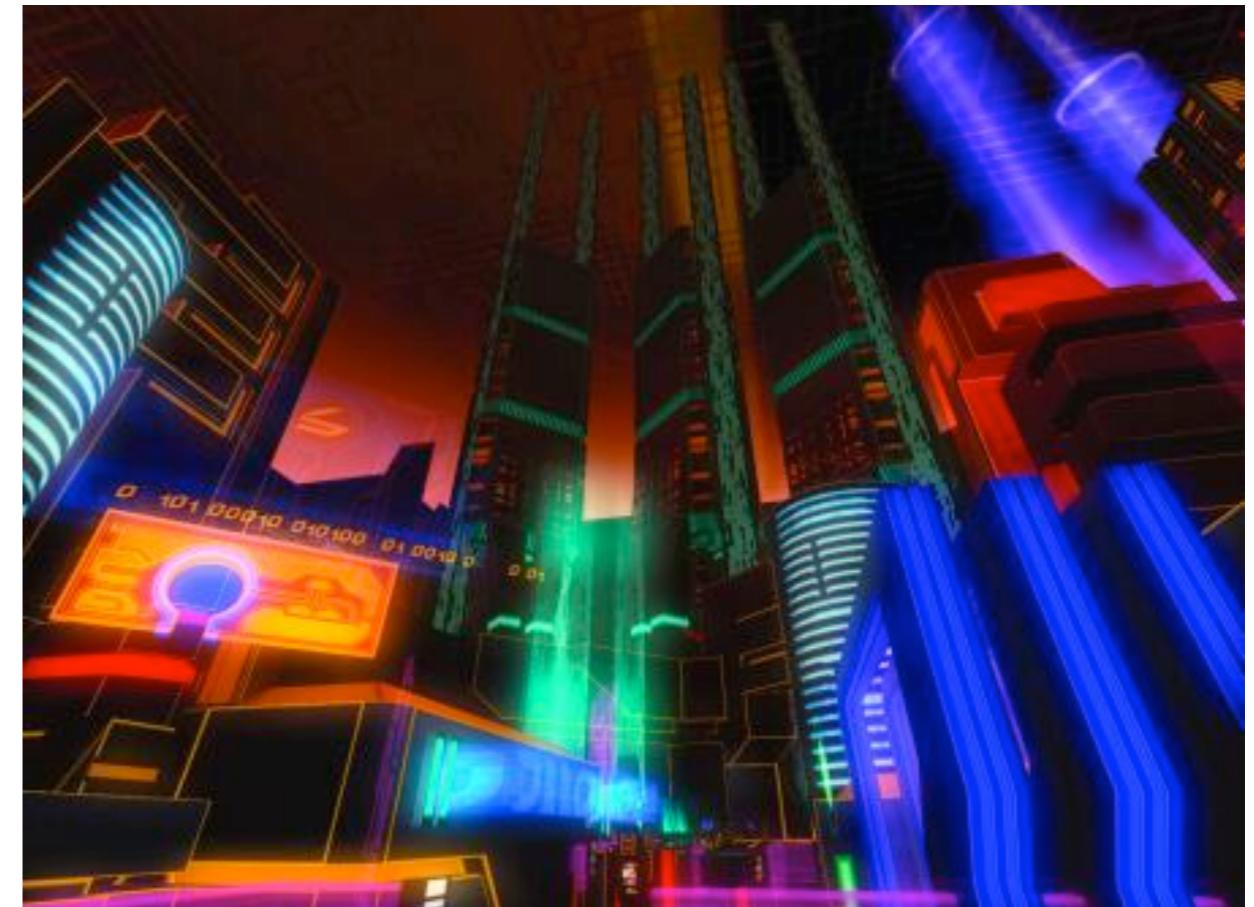
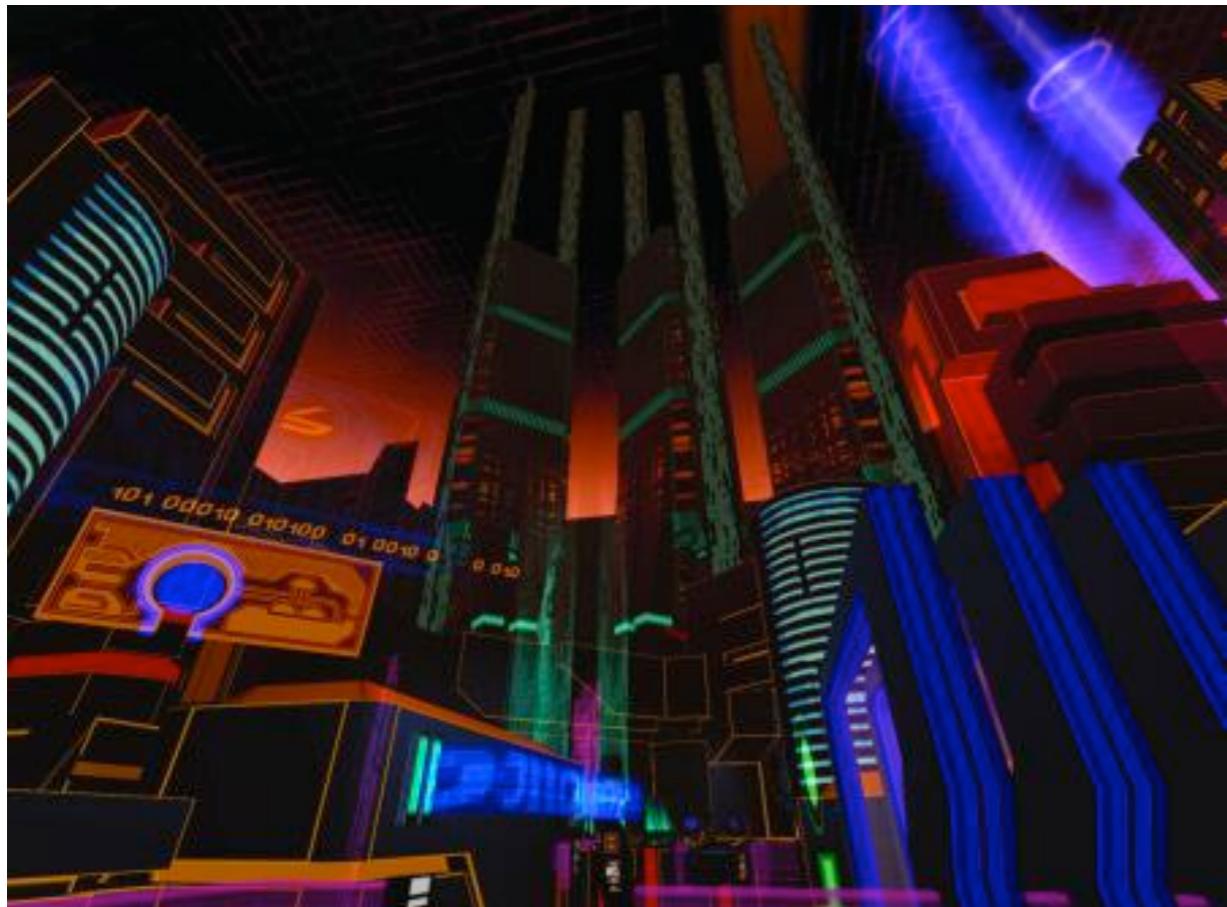
Images courtesy
[wikipedia.org](https://en.wikipedia.org)

High Dynamic Range (HDR)



Images courtesy
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Real-time Glow (Bloom)



Depth of Field Effects



But... what's trending in “Image Processing and Computer Vision” **today**?

Edge AI, Vision Transformers (ViT), Generative AI
Multimodal, 3D Vision / Depth Estimation
Self-supervised Learning
Synthetic Data, Explainable AI (XAI)
Real-time Processing, Video Analysis
Federated Learning, Hyperspectral Imaging
Low-light Enhancement, Deepfake Detection
Event Cameras, Robotics, AR/VR
Ethical AI
Quantum Image, Energy-efficient/Efficient AI
Biomedical Imaging

Generative
Multimodal
time efficient
Analysis
Video Processing
Imaging
Transformers

light Biomedical
AR Data Quantum
Detection Image Real
Estimation
XAI Hyperspectral
Ethical ViT Robotics
Low Event
Synthetic Edge Depth

3D
Self Energy Explainable
Federated Enhancement

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Supervised Deepfake
Cameras VR

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- **Event Cameras, Quantum Image Processing, Biomedical Imaging, Energy-efficient AI:** Cutting-edge techniques gaining traction in specialized research.

This is a LOT

- Yup!
- Most 4-year degrees would not be able to cover all of the topics mentioned in the previous slide, **to the depth and understanding required from a CS graduate**
- Our approach: First, get the fundamentals, then build on top
- Another view: ***First depth, then breadth***

How did we get **here**?

A look through the history of Image Processing



FIGURE 1.1 A digital picture produced in 1921 from a coded tape by a telegraph printer with special typefaces. (McFarlane.) [References in the bibliography at the end of the book are listed in alphabetical order by authors' last names.]



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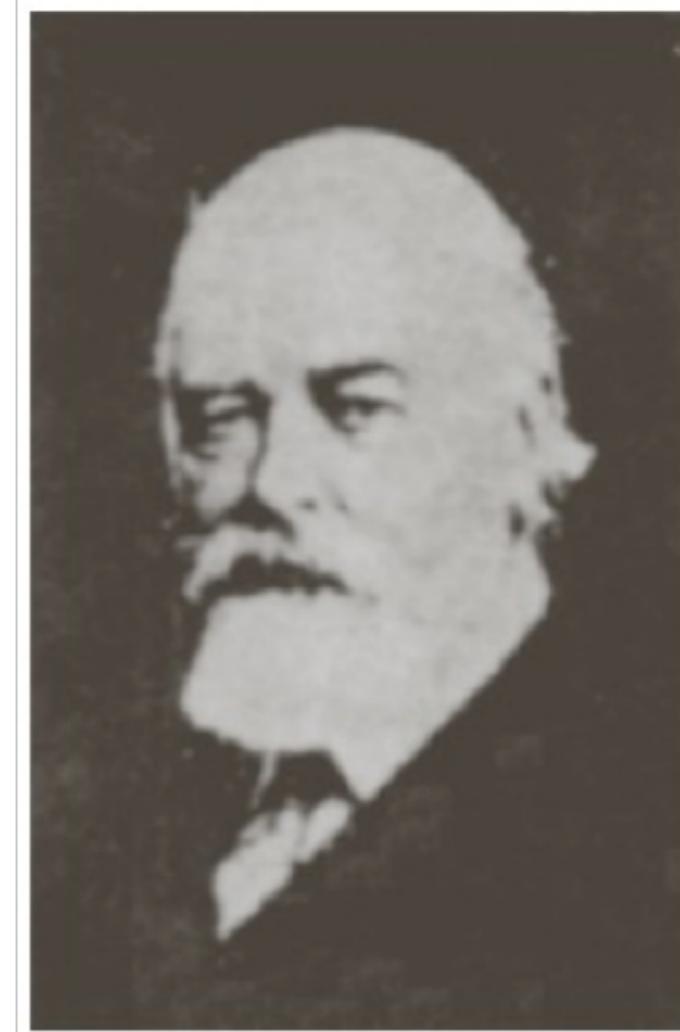


FIGURE 1.2
A digital picture
made in 1922
from a tape
punched after
the signals had
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15 levels
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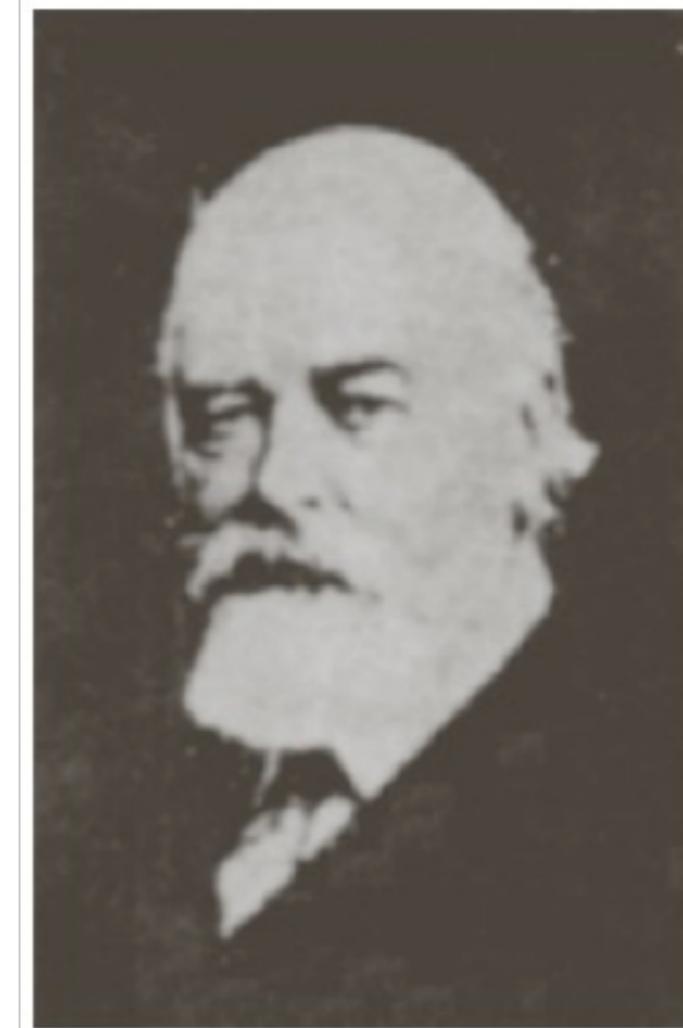


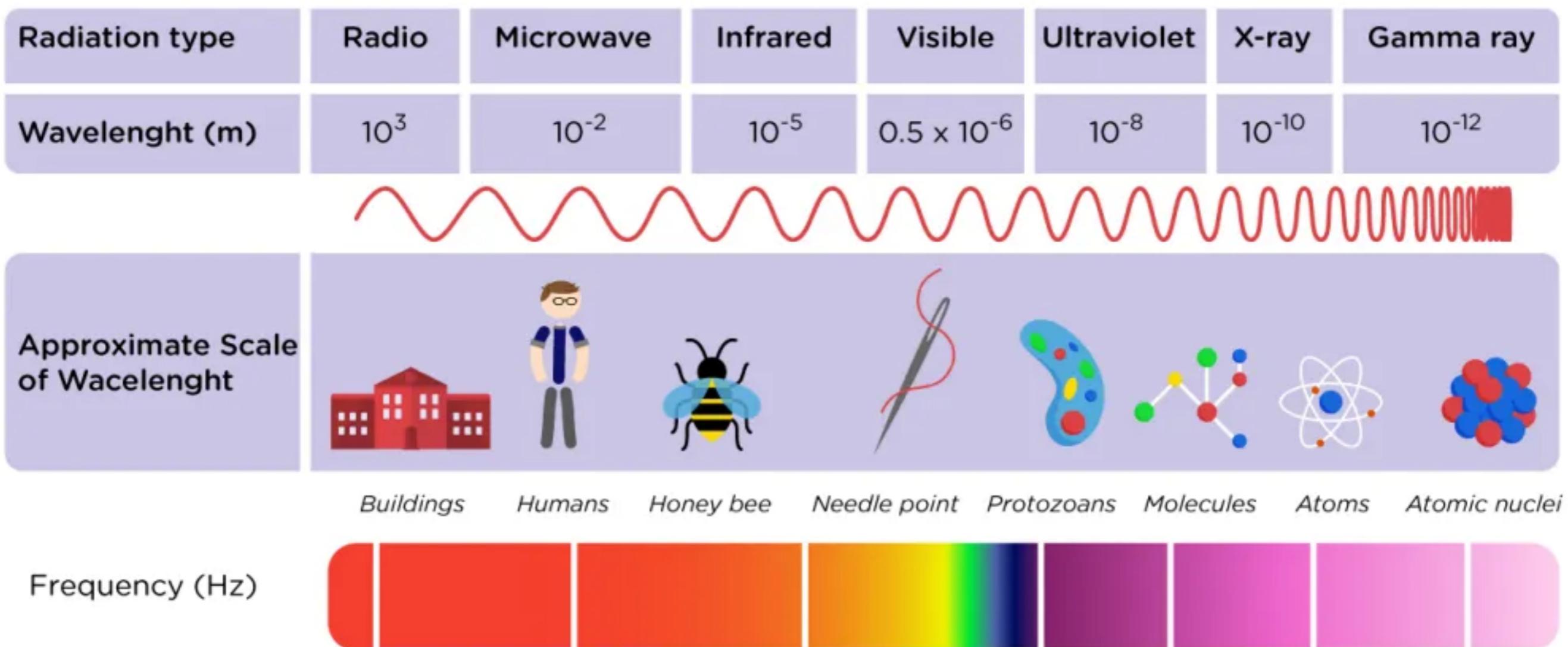
FIGURE 1.4

The first picture of the moon by a U.S. spacecraft. *Ranger 7* took this image on July 31, 1964 at 9:09 A.M. EDT, about 17 minutes before impacting the lunar surface. (Courtesy of NASA.)



Truly “digital” images

Electromagnetic Spectrum



Jack Westin

a
d
c
b
e

FIGURE 1.7
Examples of X-ray imaging.
(a) Chest X-ray.
(b) Aortic angiogram.
(c) Head CT.
(d) Circuit boards.
(e) Cygnus Loop.
(Images courtesy of (a) and (c) Dr. David R. Pickens, Dept. of Radiology & Radiological Sciences, Vanderbilt University Medical Center; (b) Dr. Thomas R. Gest, Division of Anatomical Sciences, Univ. of Michigan Medical School; (d) Mr. Joseph E. Pascente, Lixi, Inc.; and (e) NASA.)

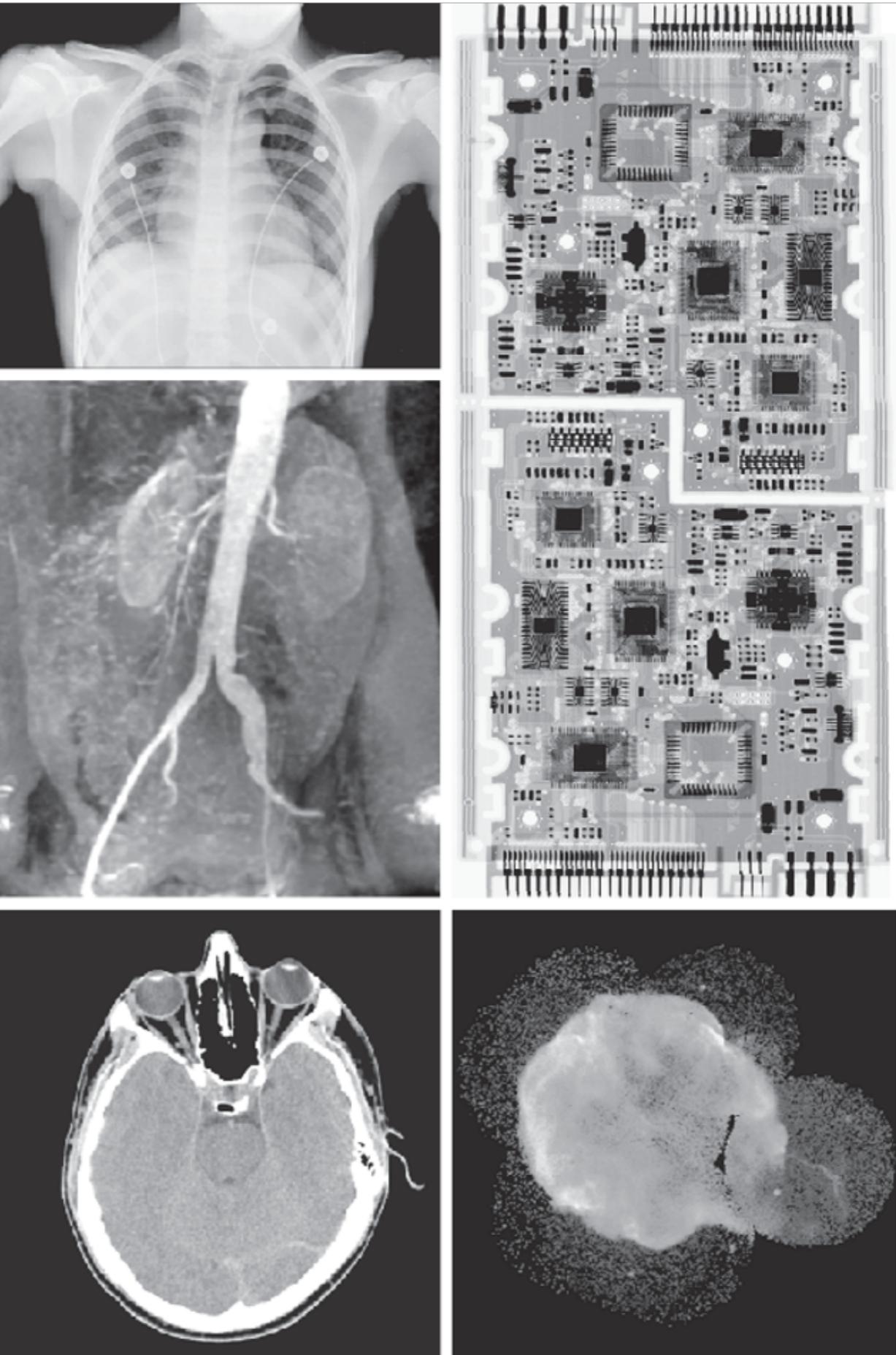


TABLE 1.1

Thematic bands
of NASA's
LANDSAT
satellite.

Band No.	Name	Wavelength (μm)	Characteristics and Uses
1	Visible blue	0.45–0.52	Maximum water penetration
2	Visible green	0.53–0.61	Measures plant vigor
3	Visible red	0.63–0.69	Vegetation discrimination
4	Near infrared	0.78–0.90	Biomass and shoreline mapping
5	Middle infrared	1.55–1.75	Moisture content: soil/vegetation
6	Thermal infrared	10.4–12.5	Soil moisture; thermal mapping
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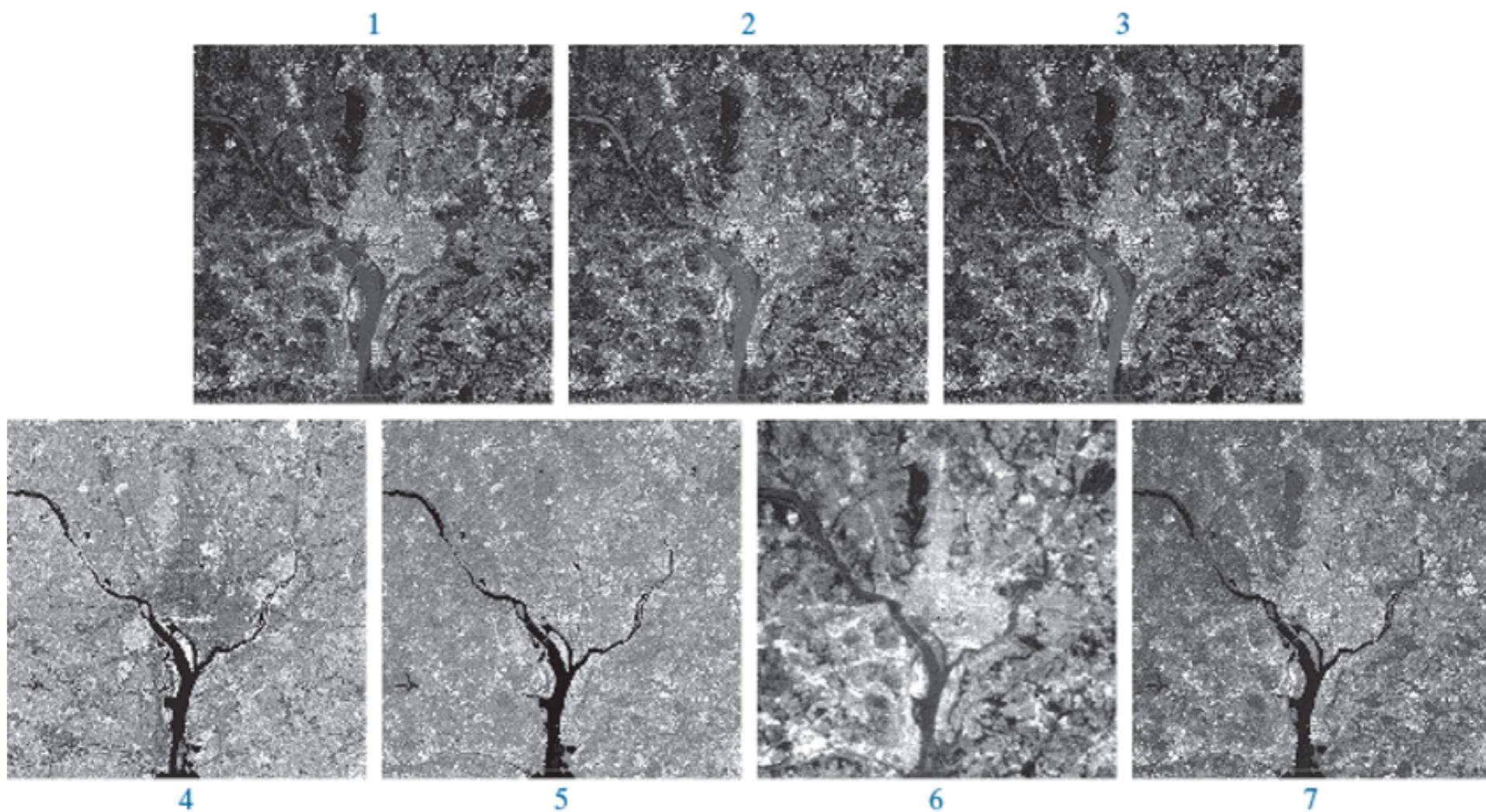


FIGURE 1.10 LANDSAT satellite images of the Washington, D.C. area. The numbers refer to the thematic bands in Table 1.1. (Images courtesy of NASA.)

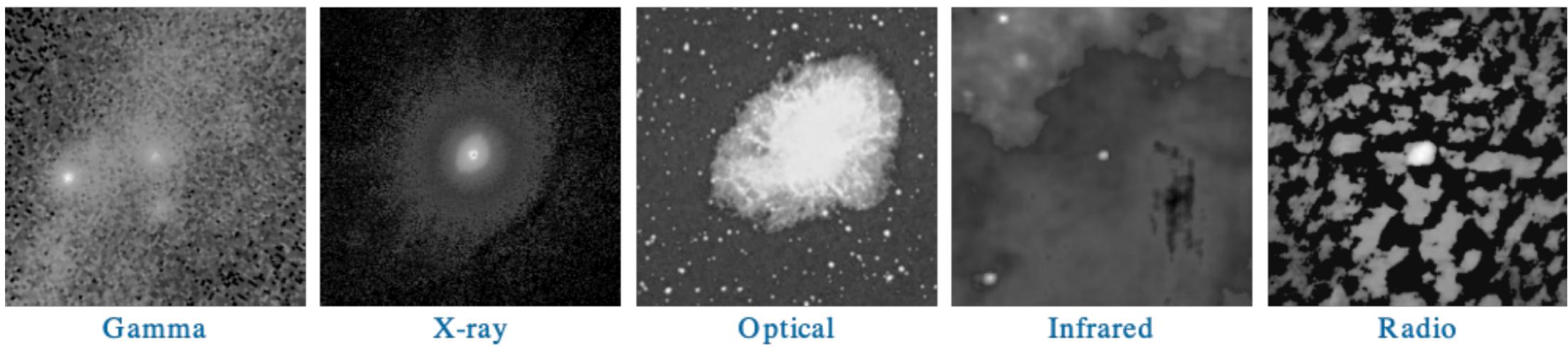


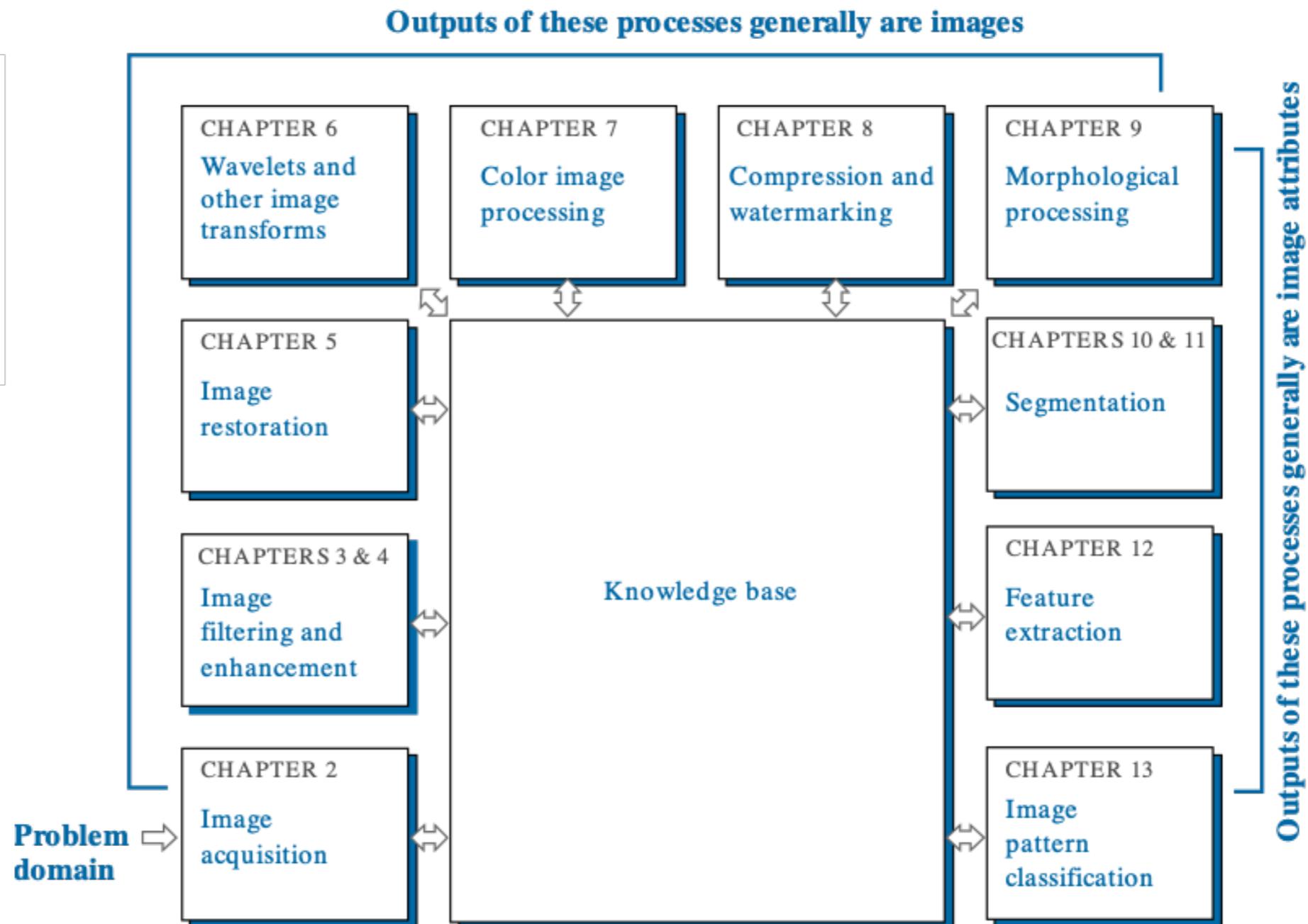
FIGURE 1.18 Images of the Crab Pulsar (in the center of each image) covering the electromagnetic spectrum. (Courtesy of NASA.)

Key Steps in Digital Image Processing

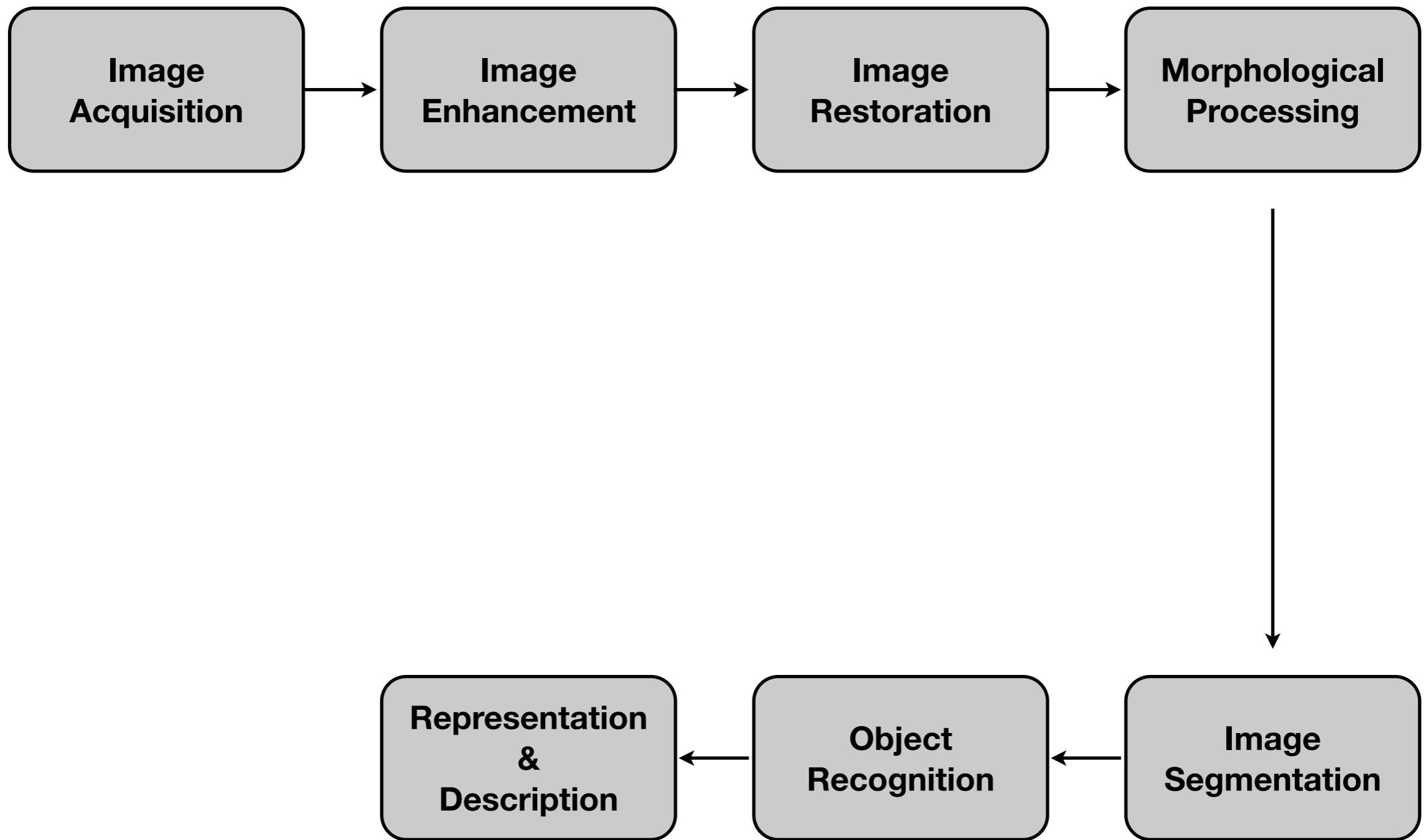
or

“What can I do with this image?”

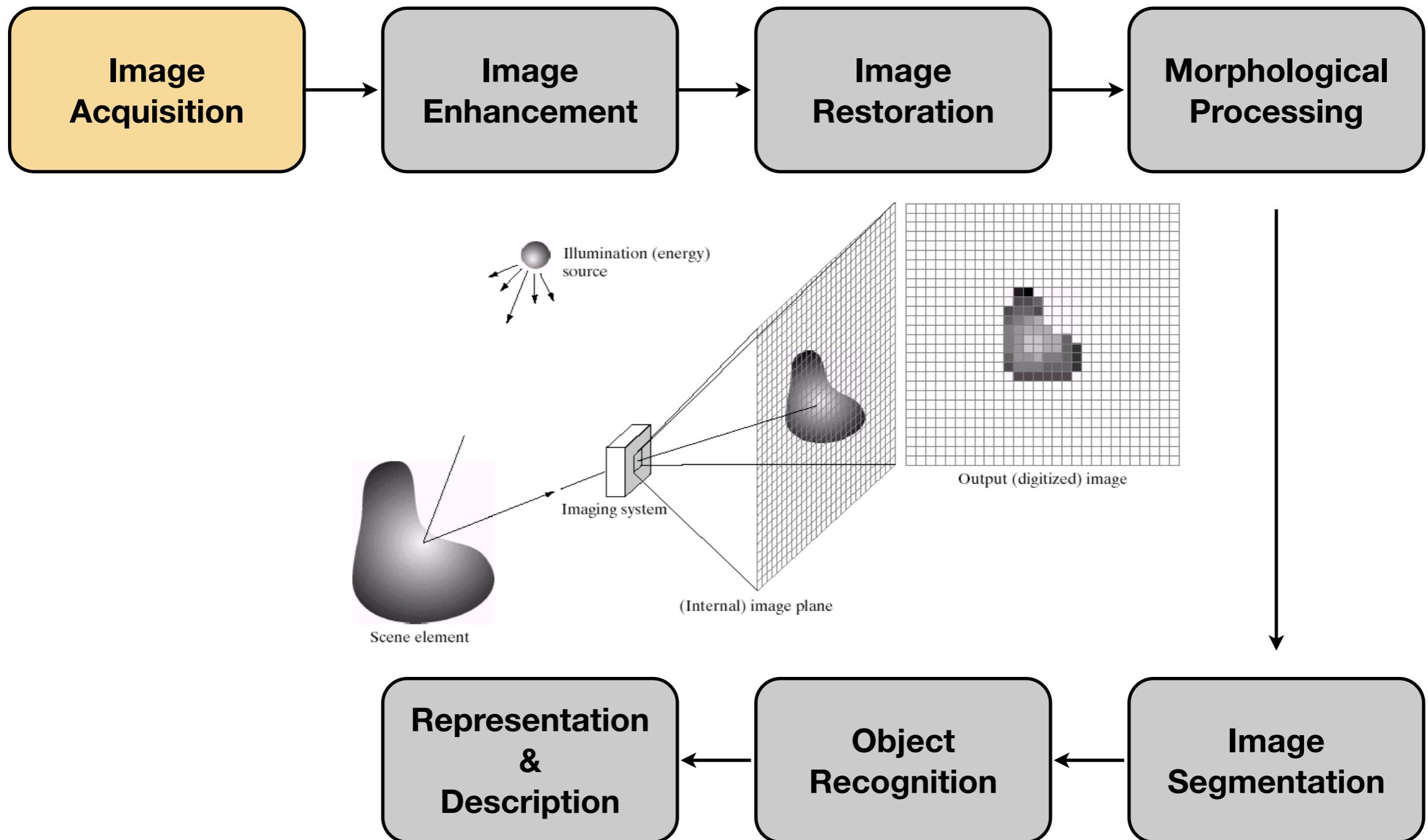
FIGURE 1.23
Fundamental steps in digital image processing. The chapter(s) indicated in the boxes is where the material described in the box is discussed.



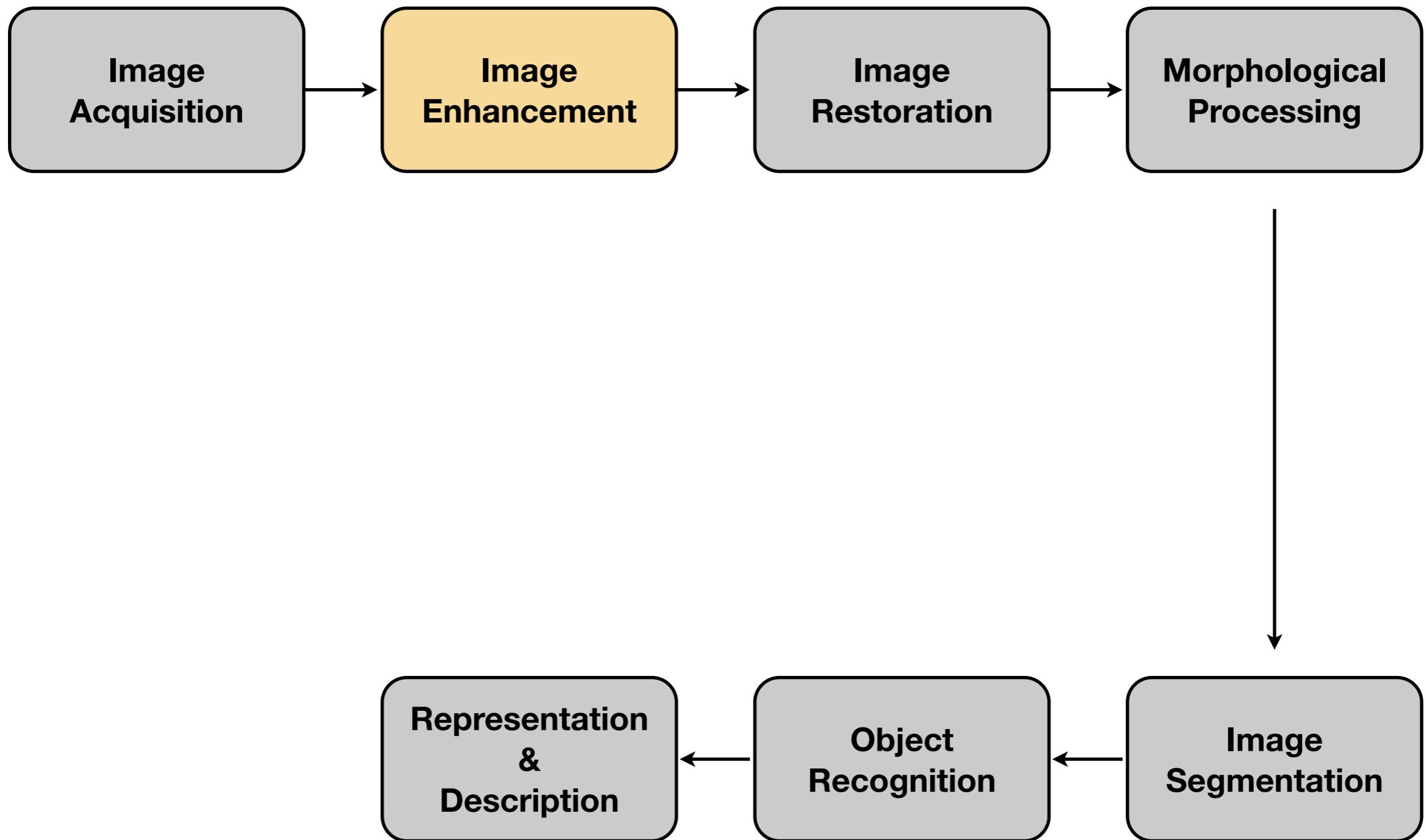
Digital Image Processing Pipeline



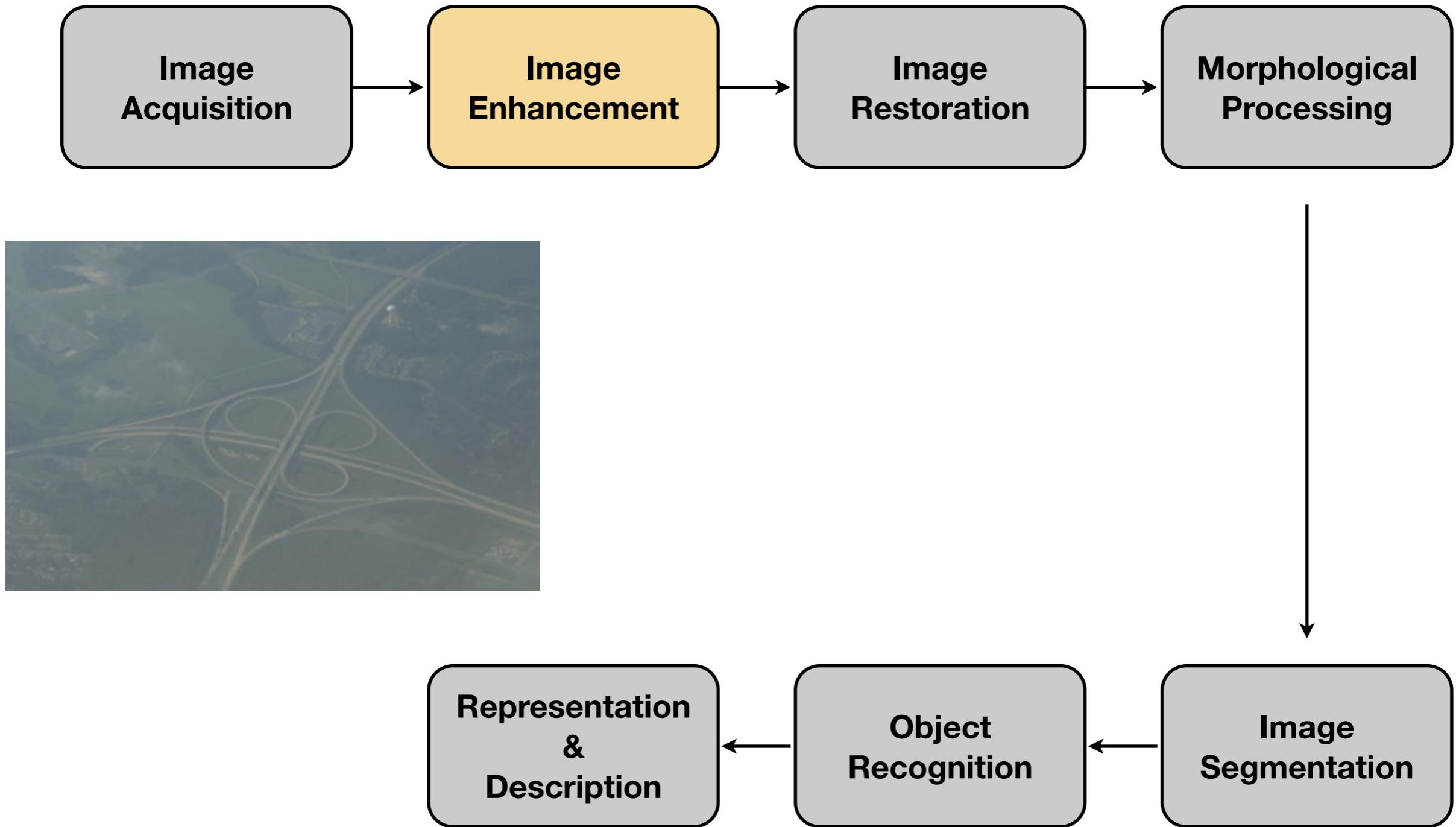
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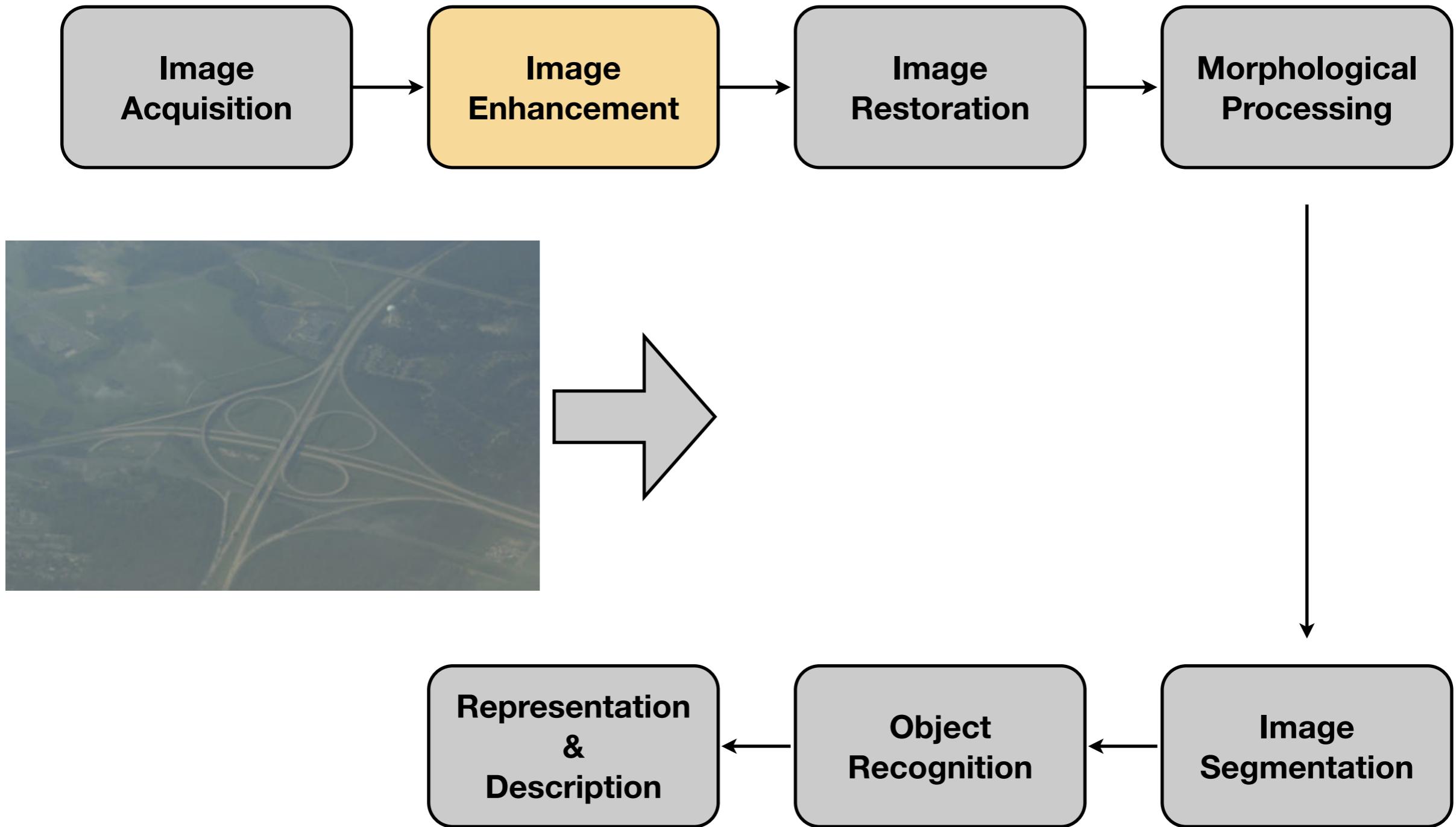
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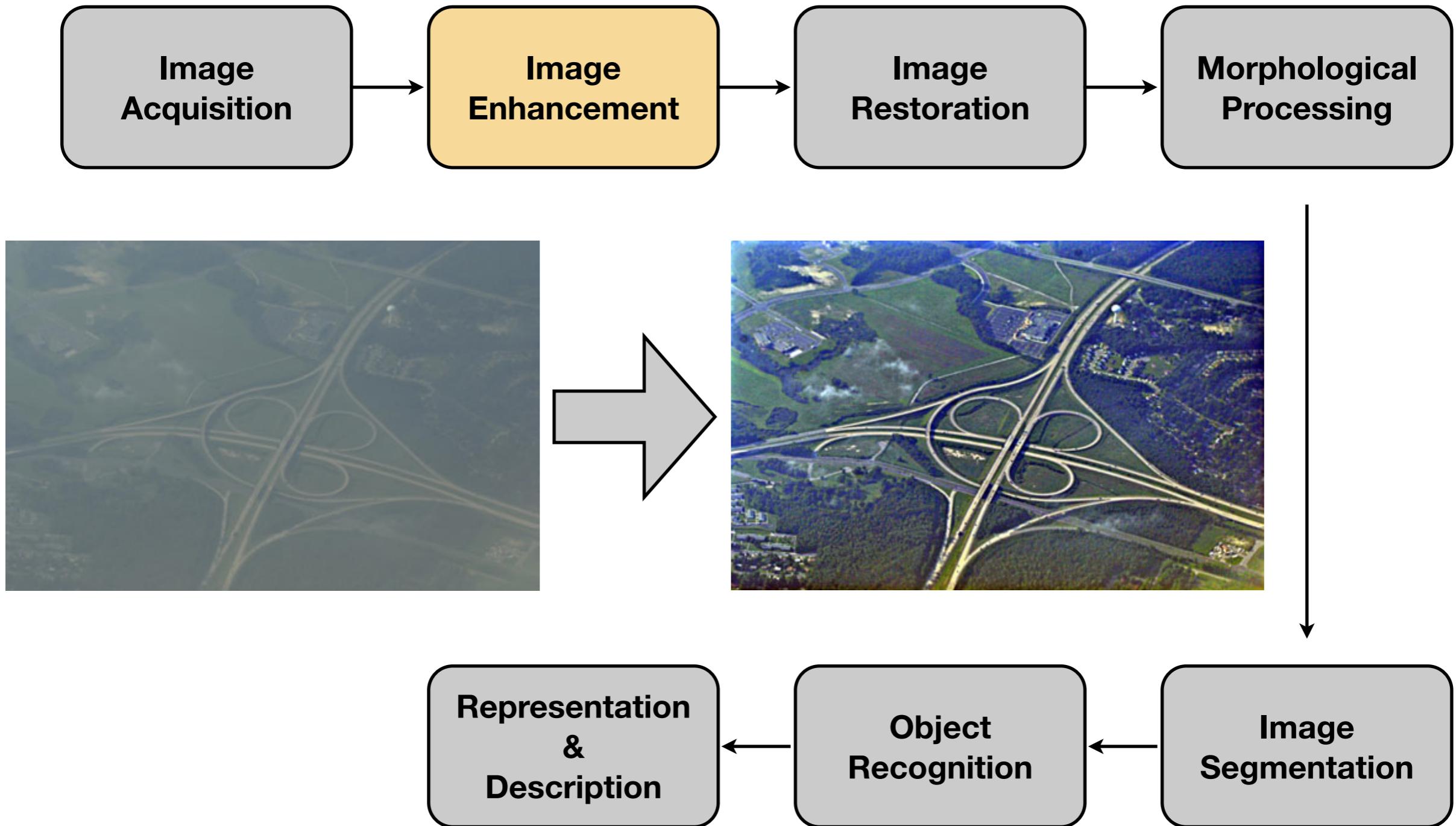
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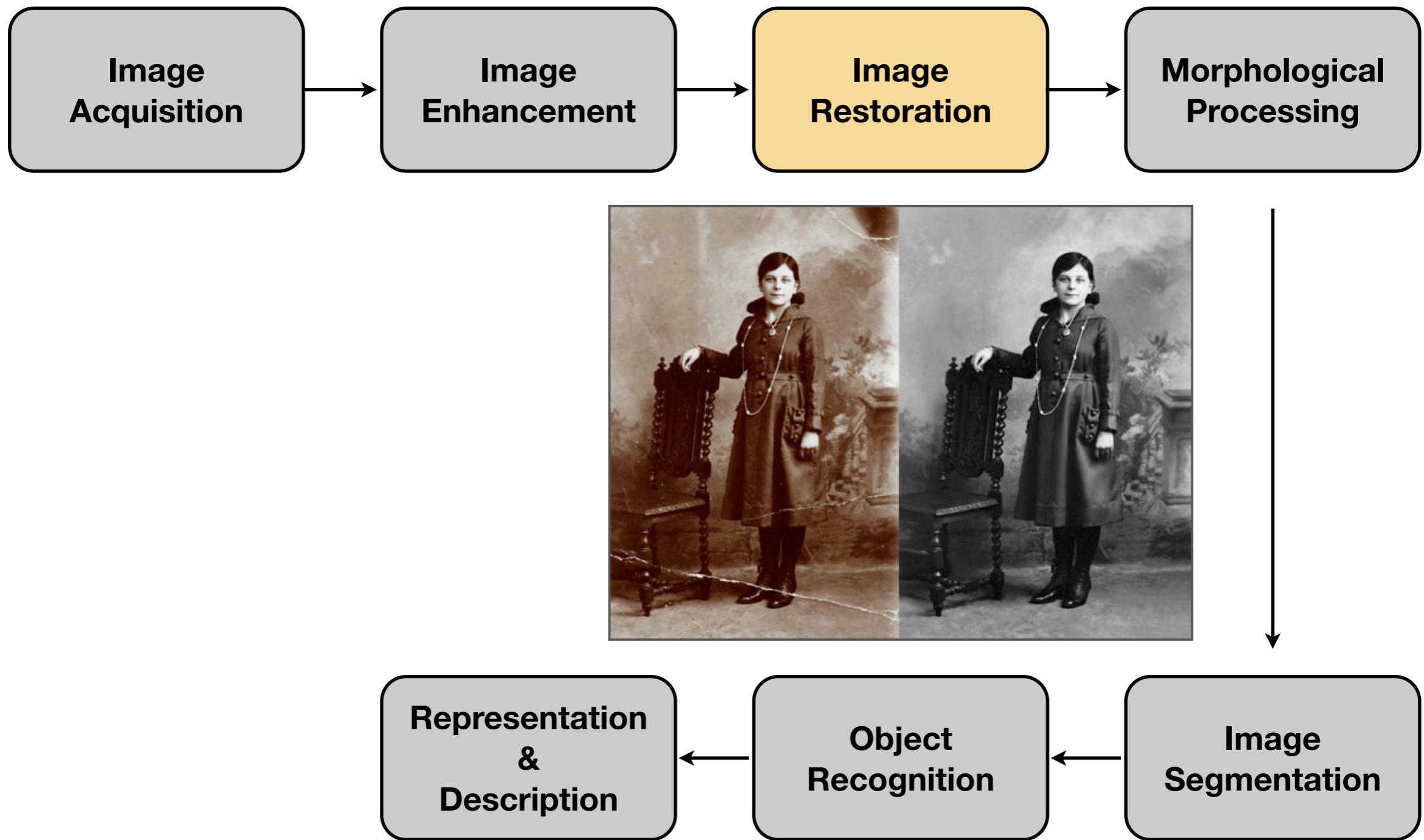
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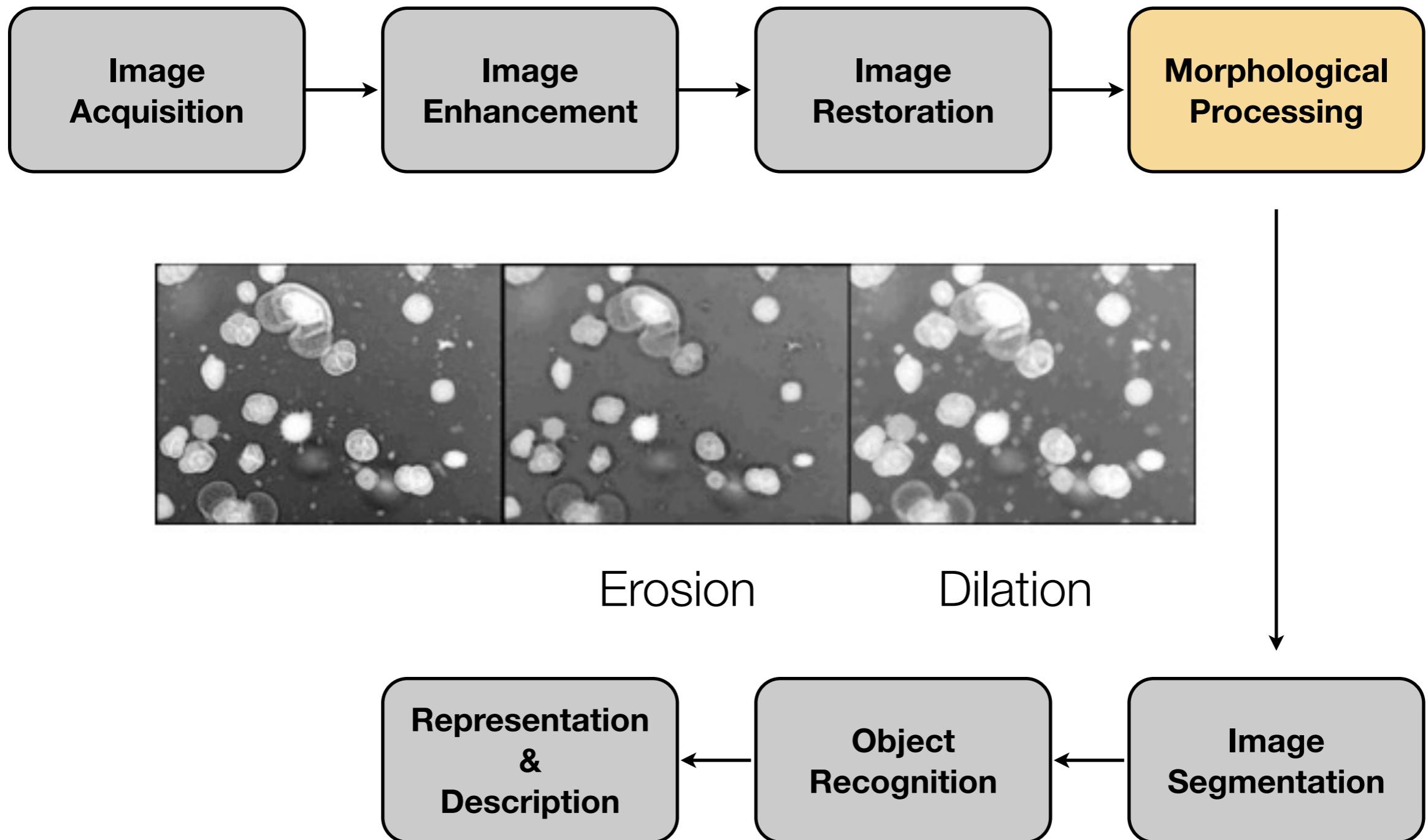
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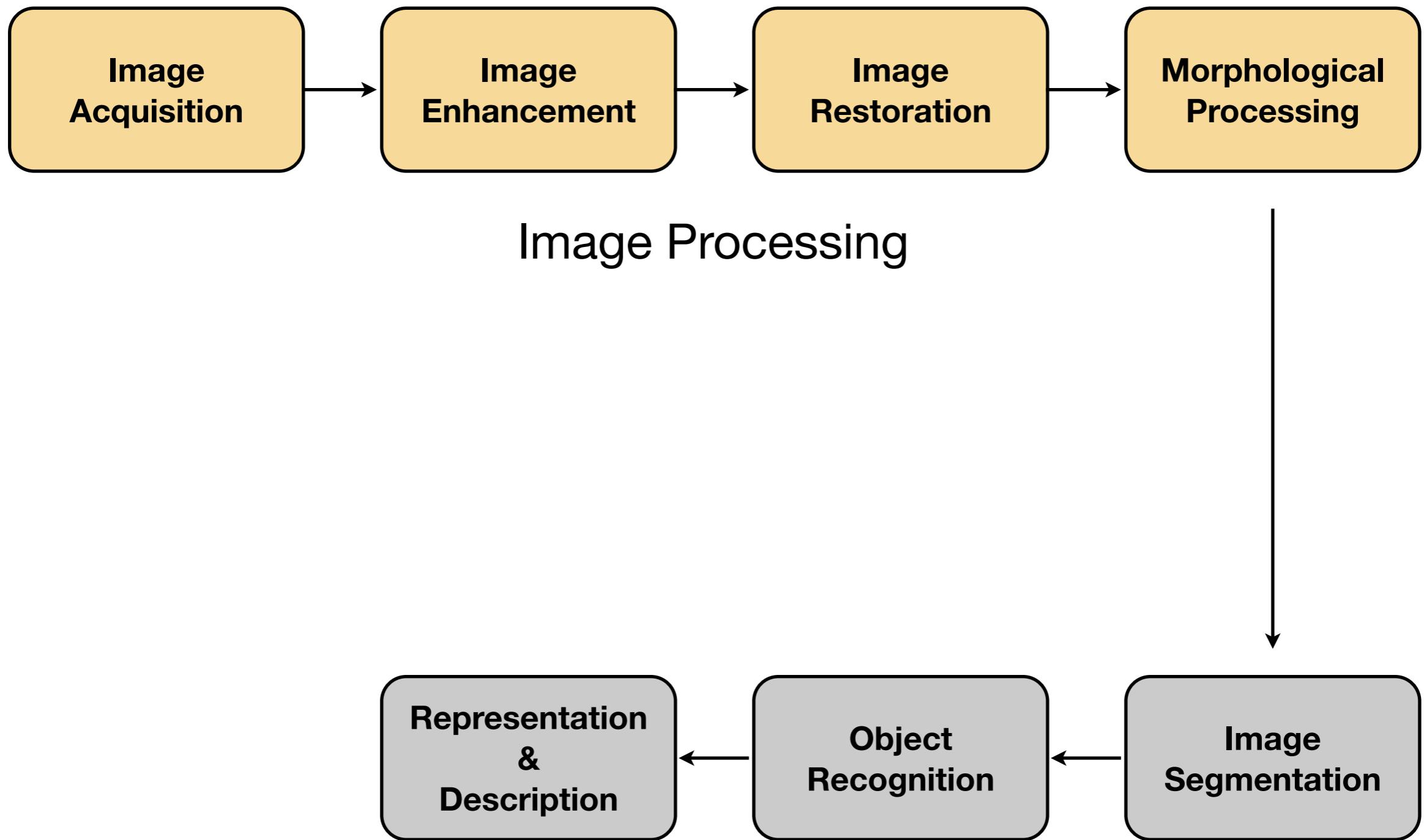
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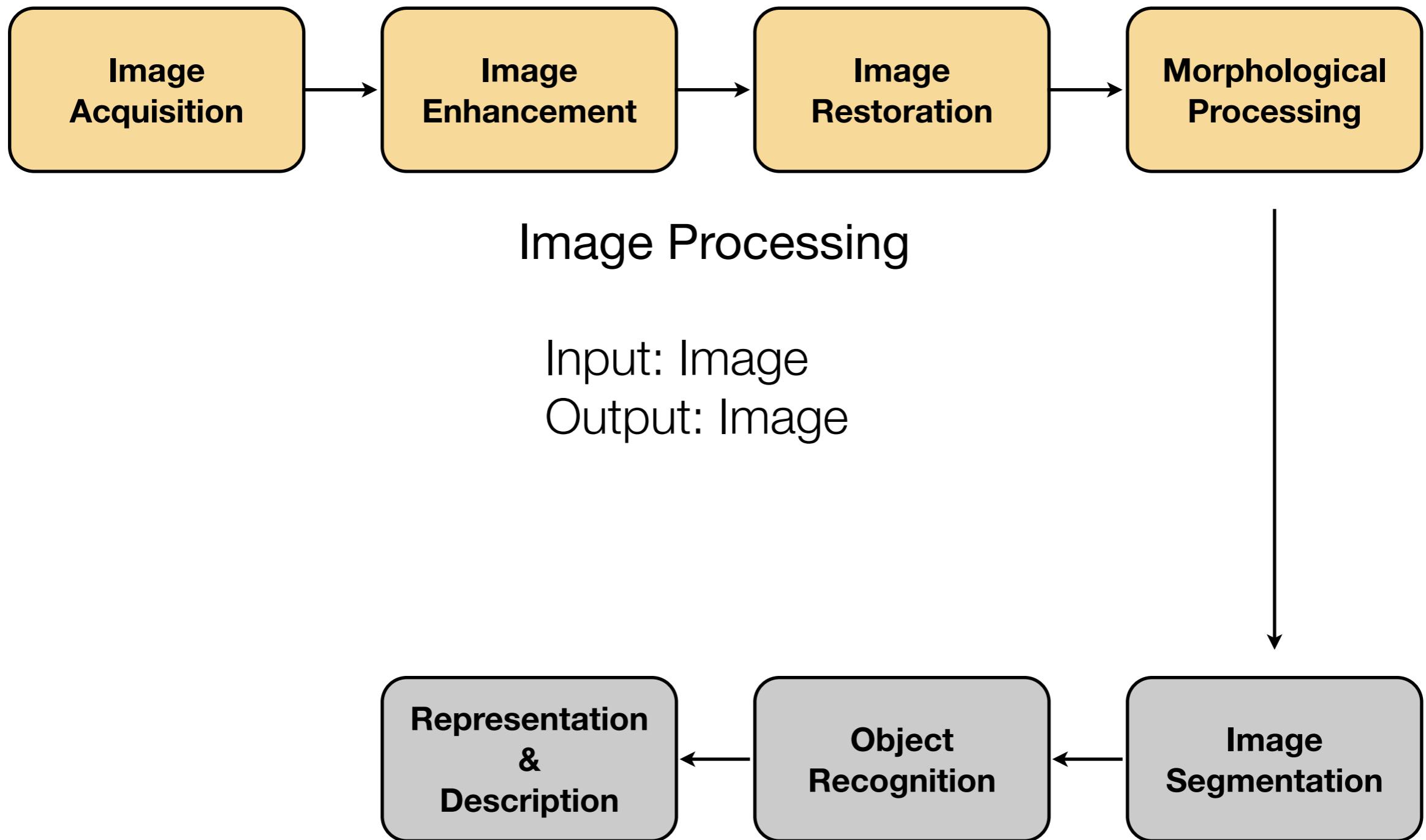
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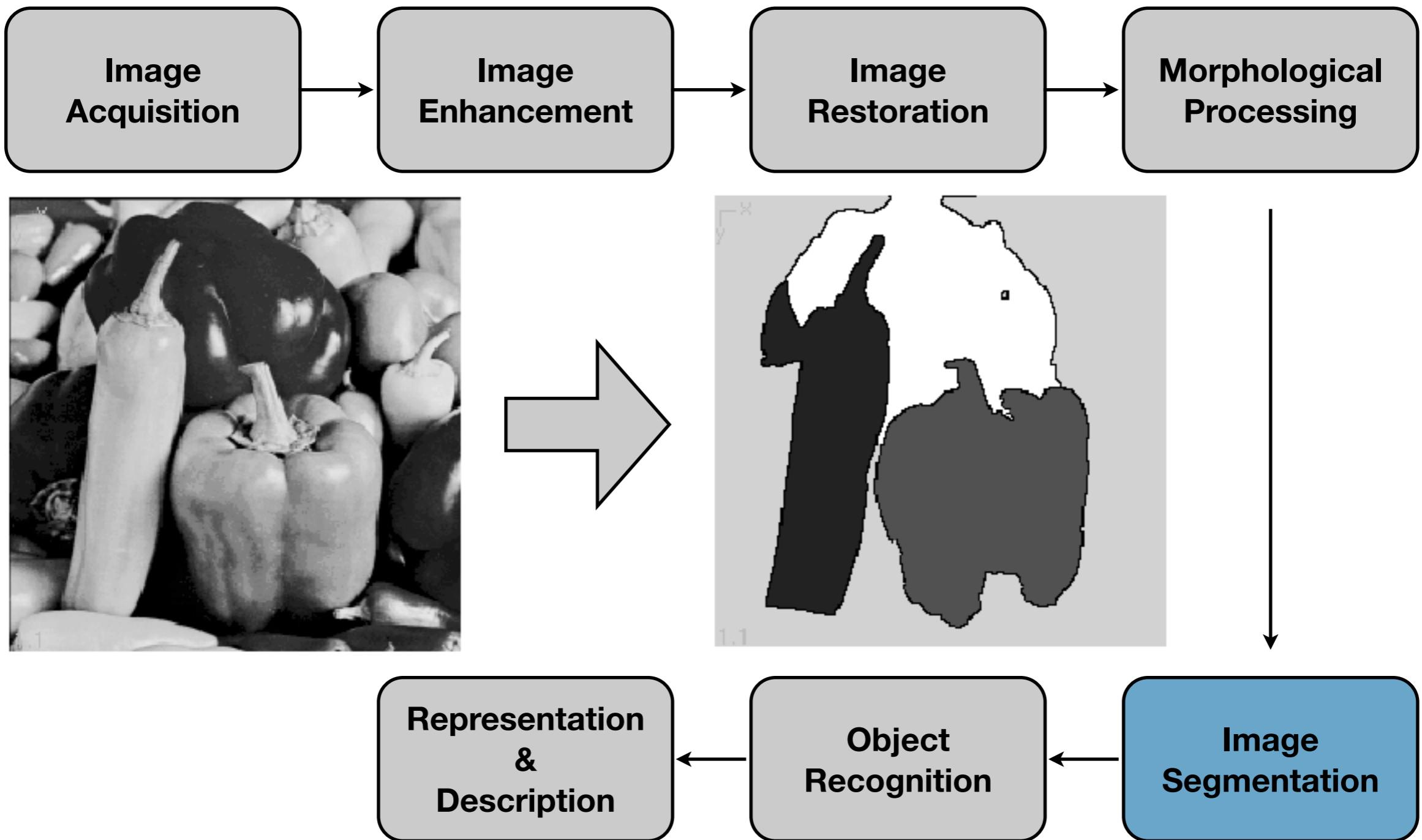
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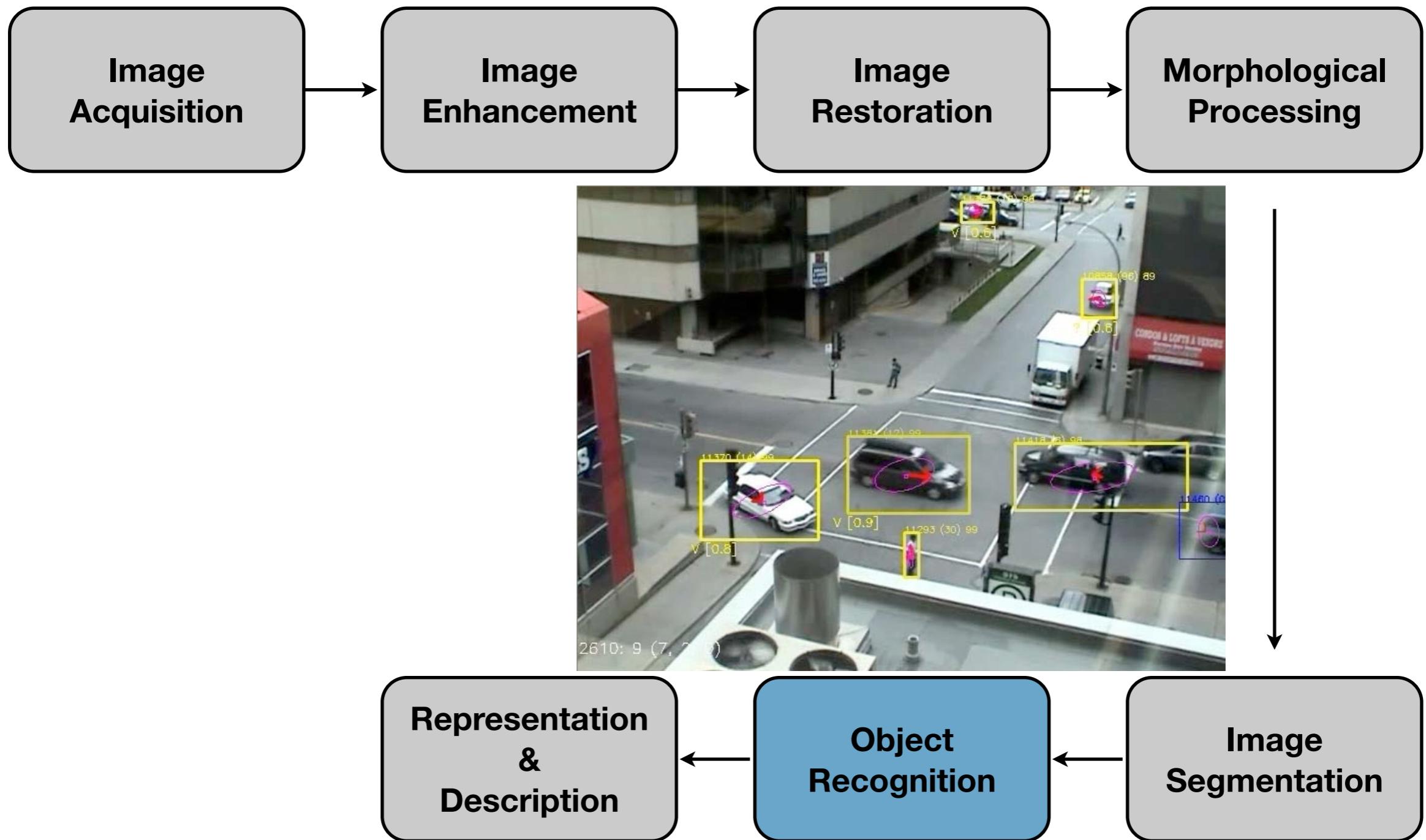
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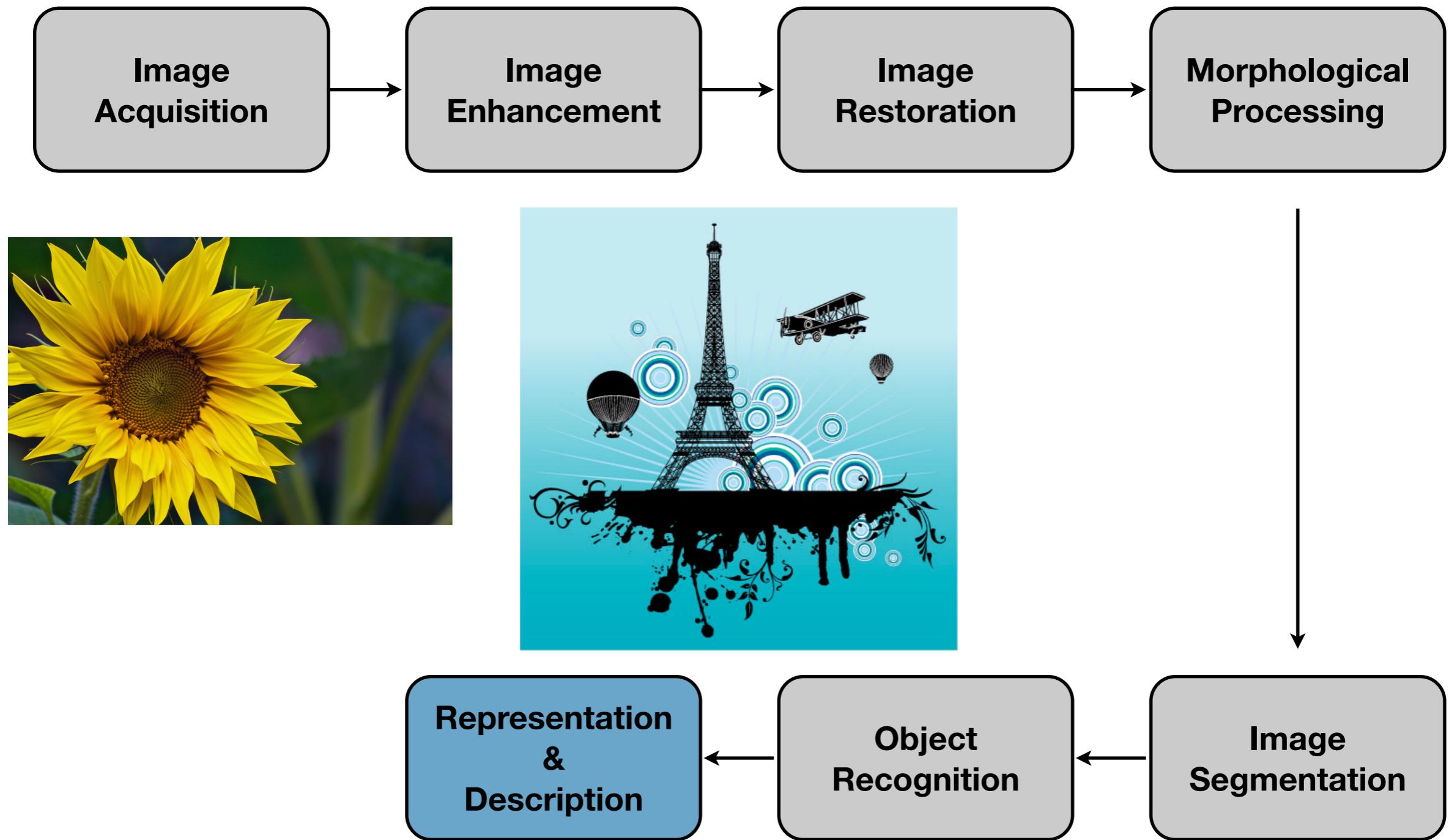
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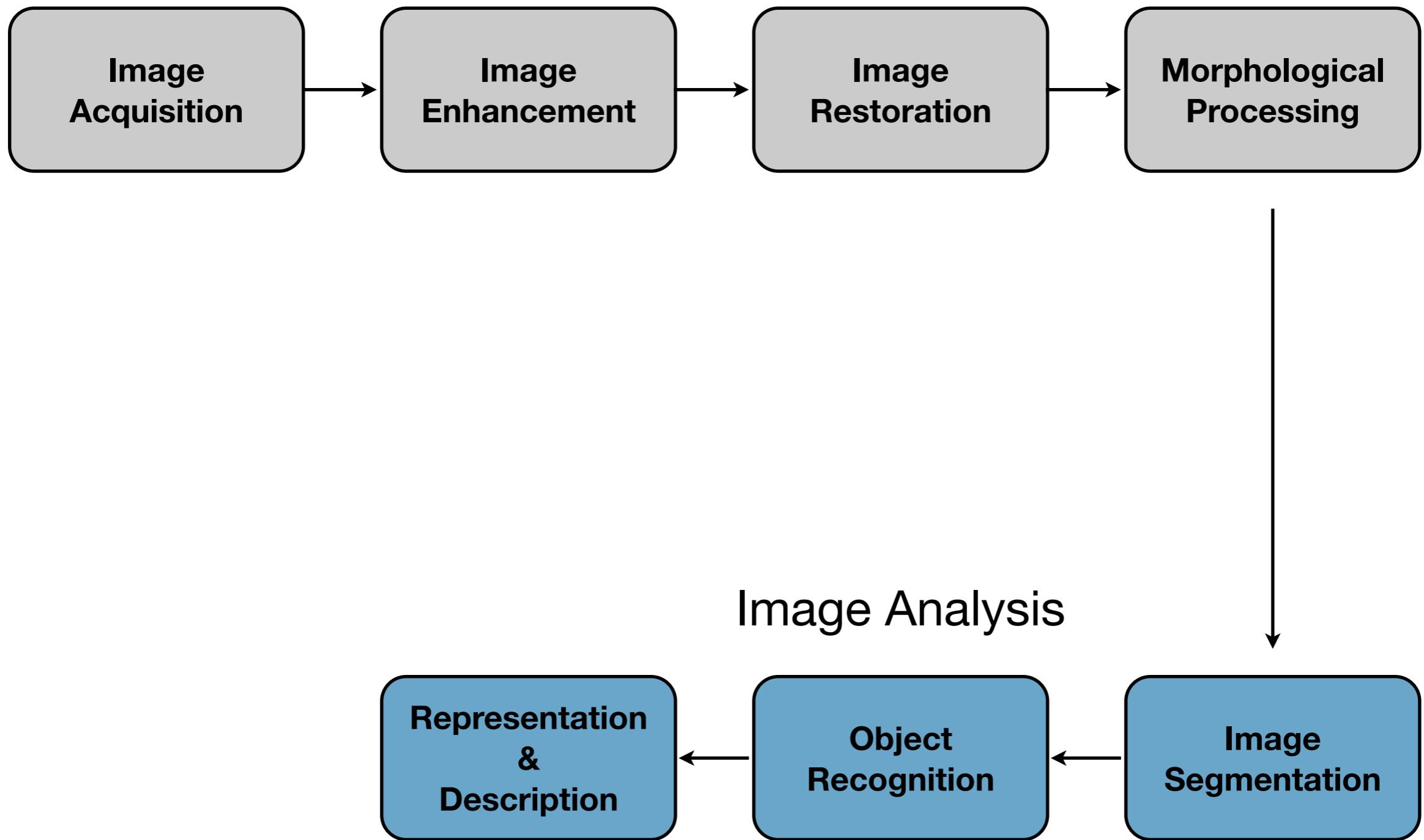
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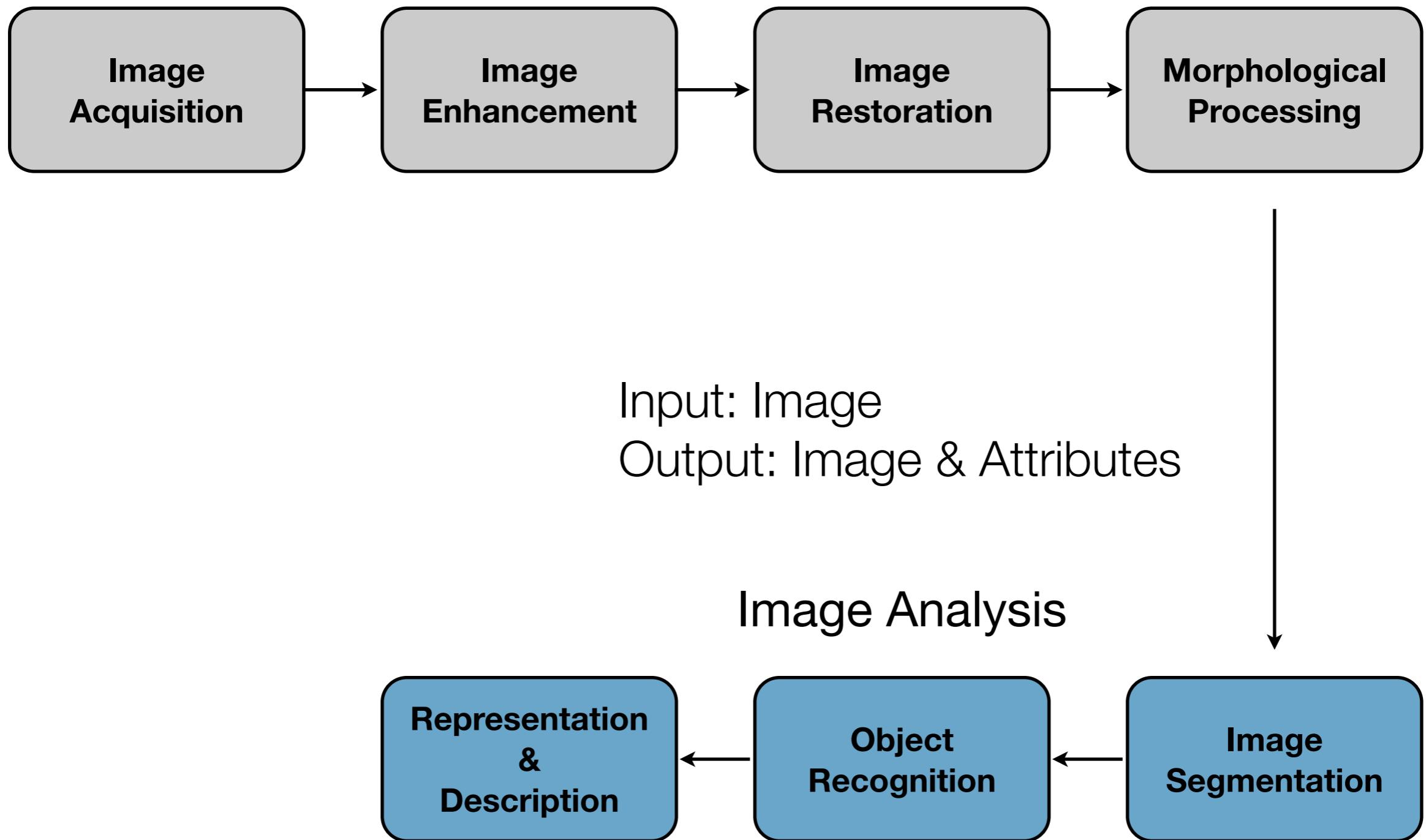
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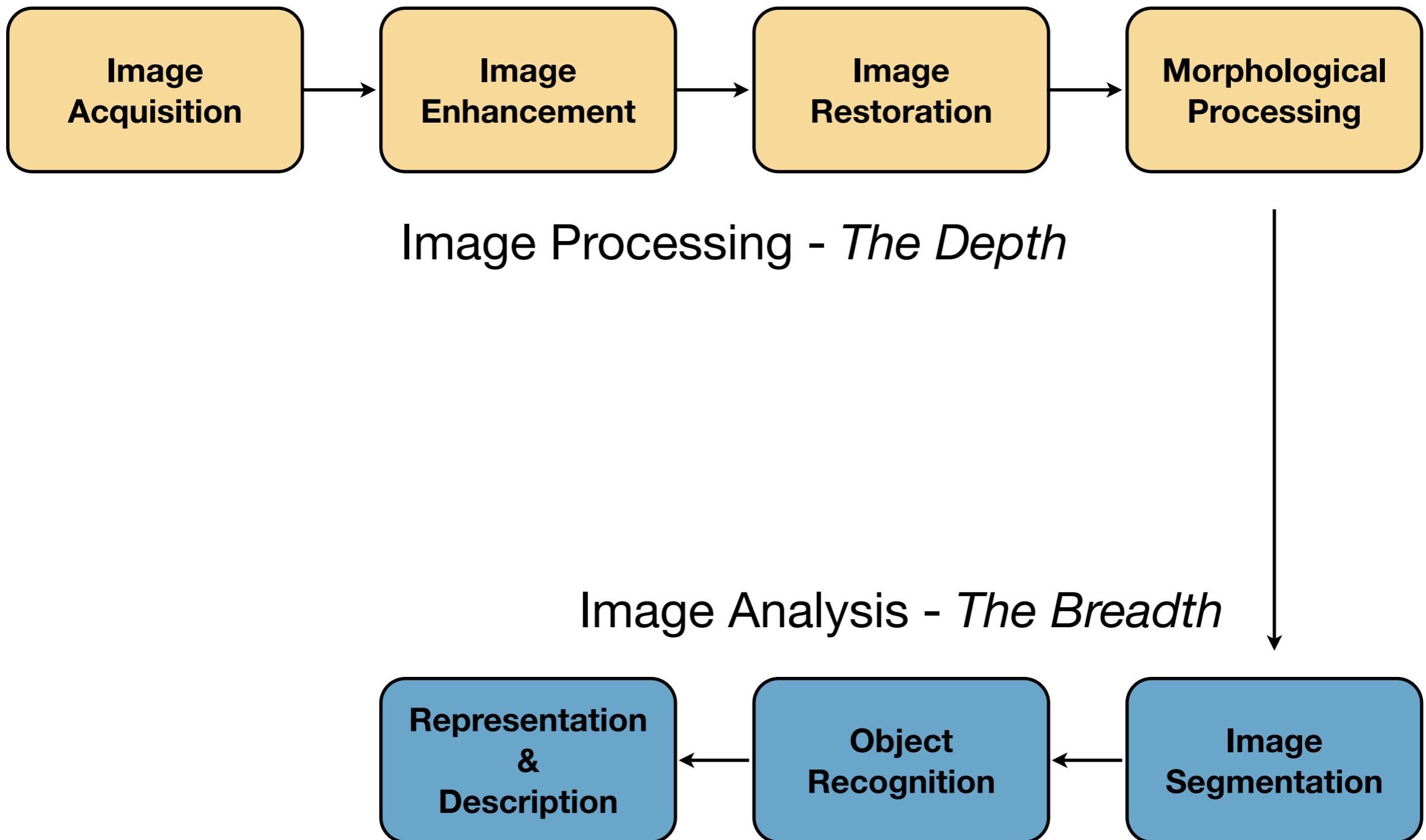
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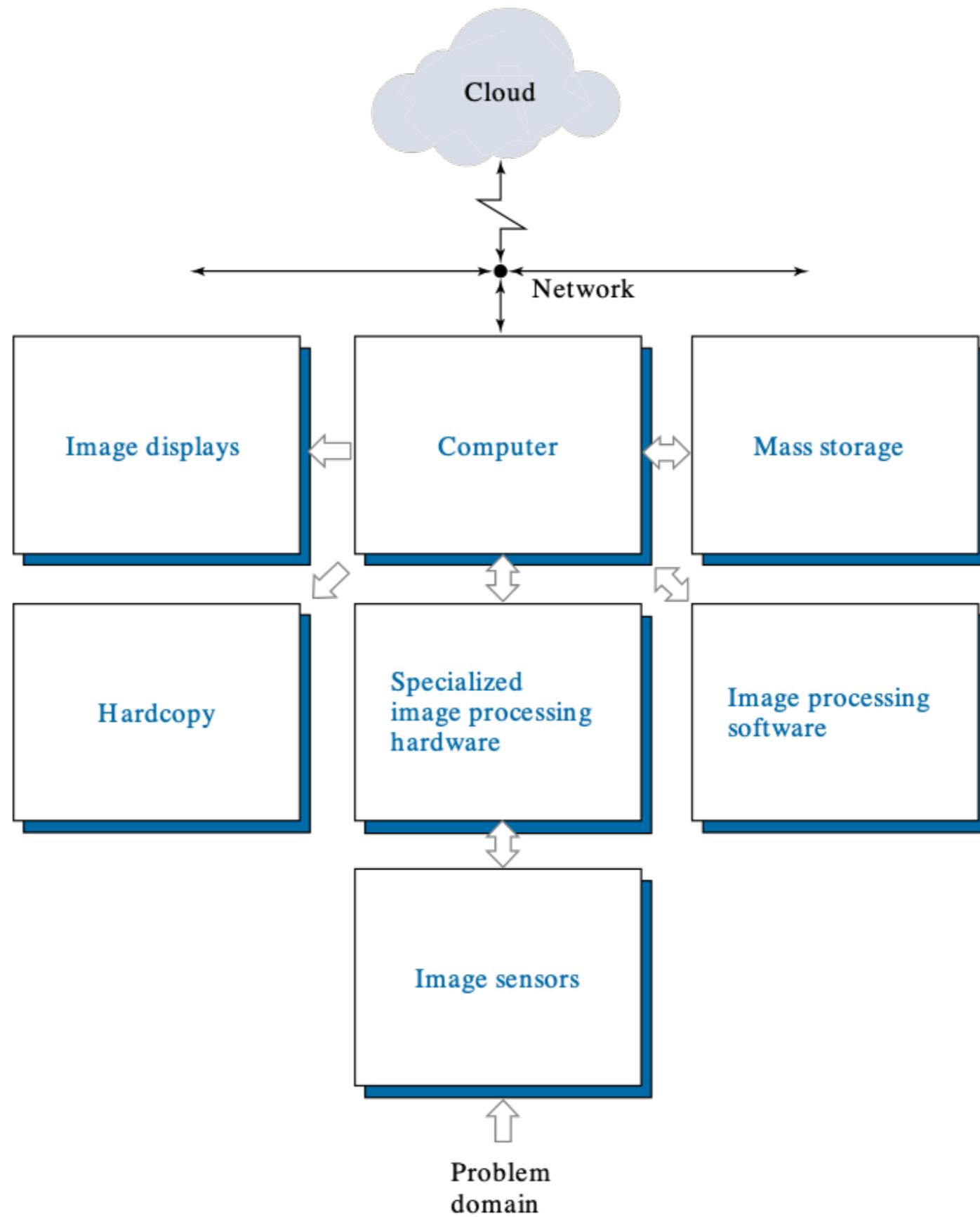


Digital Image Processing Pipeline



Key Components in Digital Image Processing
or
“How is this stuff implemented?”

FIGURE 1.24
Components of a
general-purpose
image processing
system.



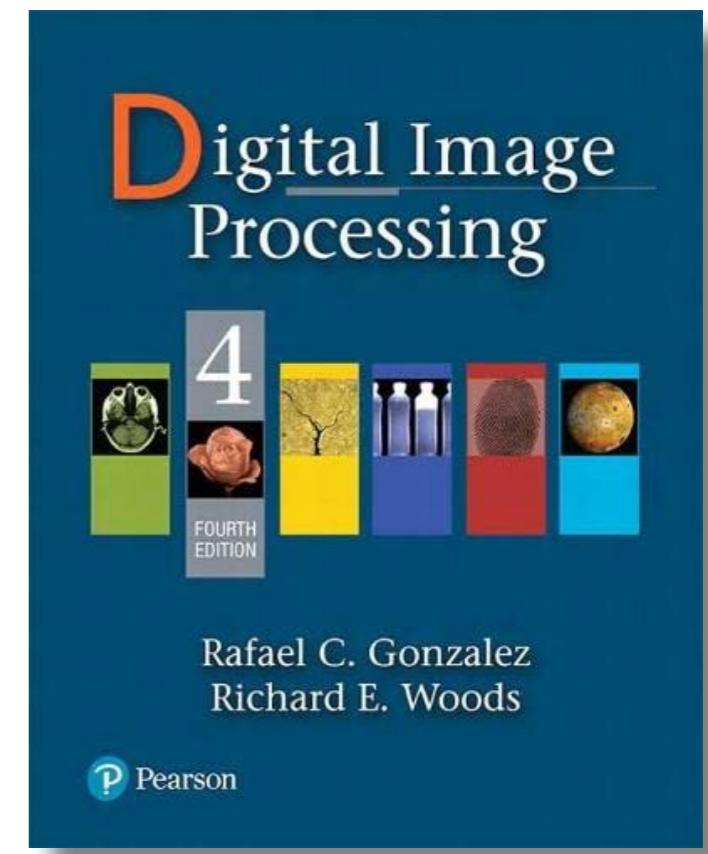
What to Expect from This Course?

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- Fundamentals of Image Processing
- Applications to real-world datasets
- Image processing implementation
 - Implement using Python / C++ / Compute Shaders
- Course material presented in **Python**
- Student-based outcome
 - A configurable, extensible Image Processing toolset that YOU can showcase in your portfolio

Course Details

- Textbook (**NOT REQUIRED**)
- Reference Book (will be used in slides/examples)
 - Digital Image Processing, Gonzalez & Woods, 4th edition
- Online materials, as needed
 - Course Slides
 - Research and White papers
- Programming Assignments
 - **The Depth** - 3 Programming Assignments (2 weeks)
 - **The Breadth** - Group Project (due end of semester - monthly deliverables due)
- Mid-term Exam
- Final Exam



Programming Platform

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- Census assignment coming up
 - Write a small application that allows you to load and display images

Do's and Don'ts for 3rd-party libraries

- Use third-party libraries for the following -
 - Load and save images
 - Display image data on screen
- DO NOT use them for -
 - image processing operations that are the outcomes of the assignment
 - e.g. addition, masking, histogram processing, edge detection etc.
- **When in doubt - consult the instructor**

Grade Distribution

Topic	Undergraduate	Graduate
Programming Assignments + Quizzes (2)	30%	15%
Midterm Exam	20%	15%
Group Project	30%	30%
Final Exam (Comprehensive)	20%	20%
Paper Implementation & Presentation	20%	20%
Total	100%	100%

Grade Levels

Points	Letter Grade
[93, 100]	A
[90, 93)	A-
[87, 90)	B+
[83, 87)	B
[80, 83)	B-
[77, 80)	C+
[73, 77)	C
[70, 73)	C-
[60, 73)	D
< 60	F

Pre-requisites

- Good implementation skills

- Linear Algebra

- Matrices

- 2D Transforms

- Enthusiasm to learn !

Lecture 01

Image Processing - The Fundamentals

Is this a “good” image?



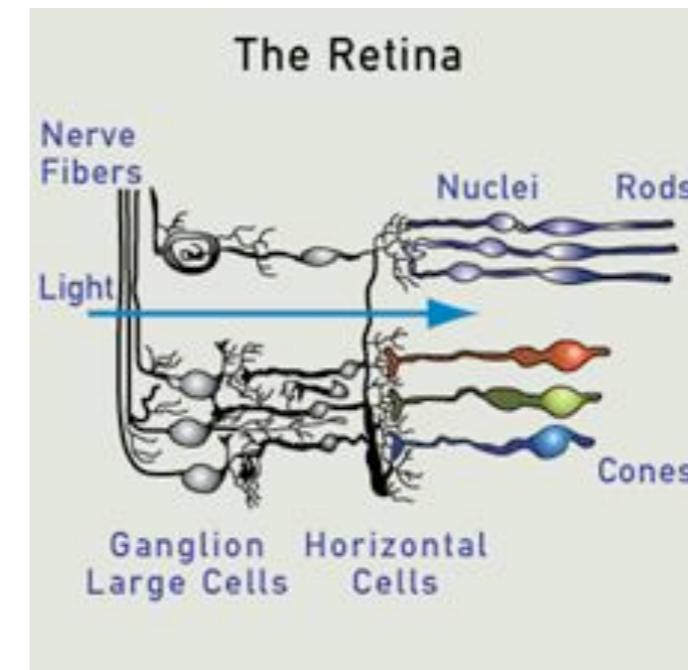
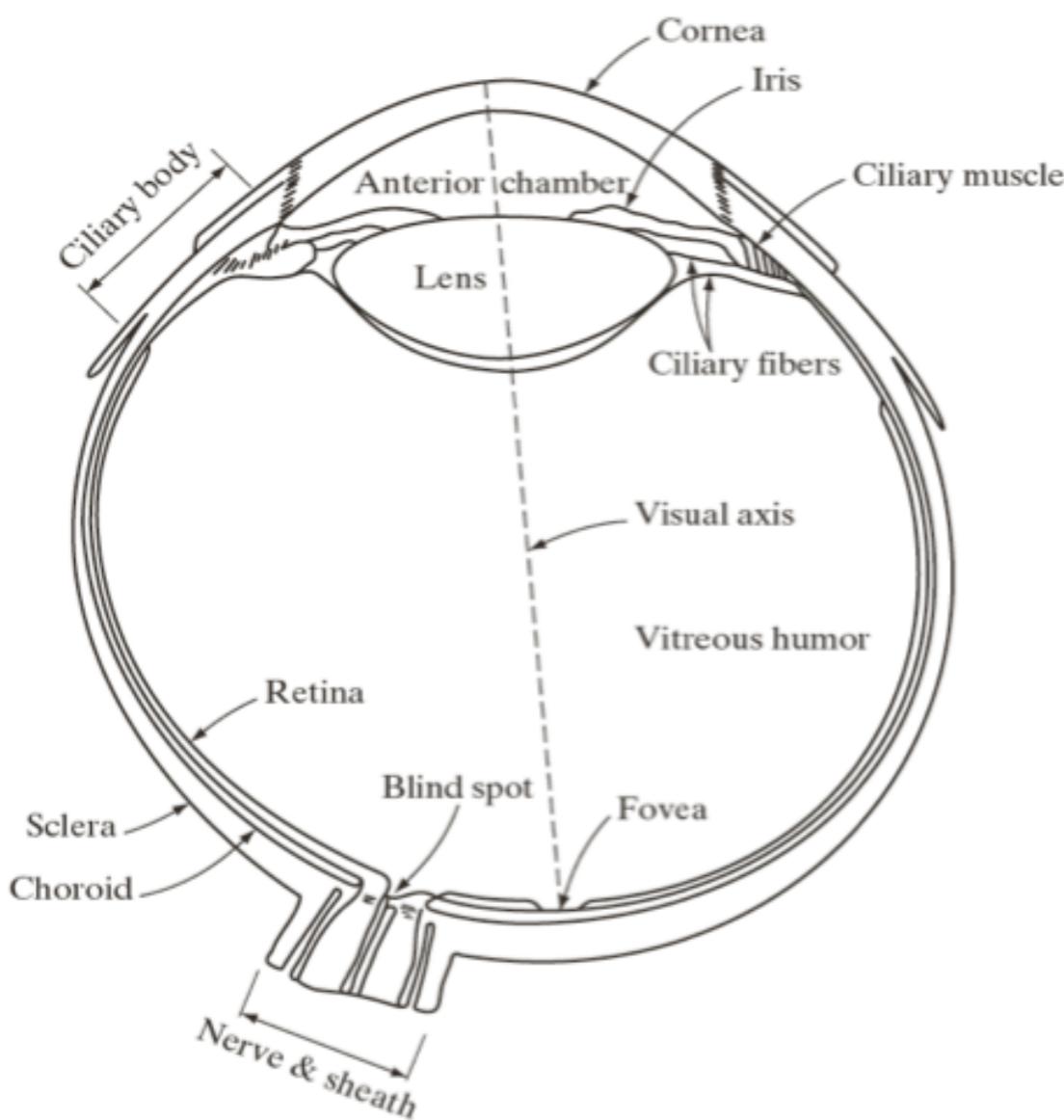
<http://mynorthkorea.blogspot.com/2013/08/north-korea-and-satellite-resolution.html>

“Goal” of Image Processing

- Create images that “look good”
- What does the phrase “look good” imply?
 - One person’s good image may be another’s trash!
- VERY IMPORTANT TO REMEMBER
 - Image Processing quality assessment is largely subjective process
 - Typical mechanism : come up with a mathematical model/algorithm/ process that makes the image **appear desirable to the human observer for the specific operation or process in mind**

How do humans perceive images?

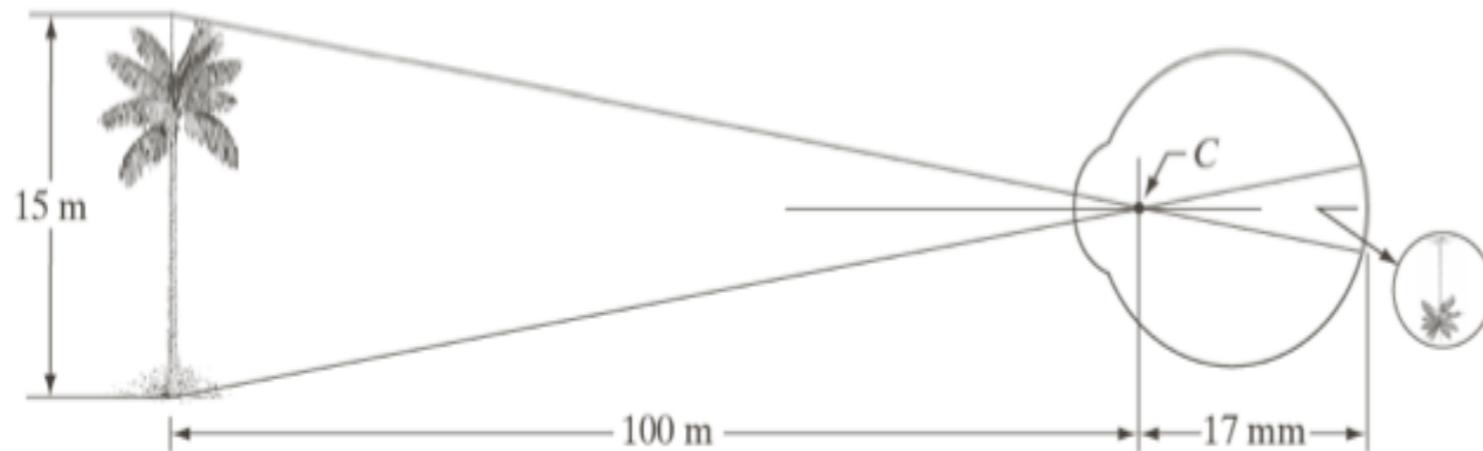
● Human Visual System



Images courtesy "Digital Image Processing," by Gonzalez & Woods, 3rd ed.

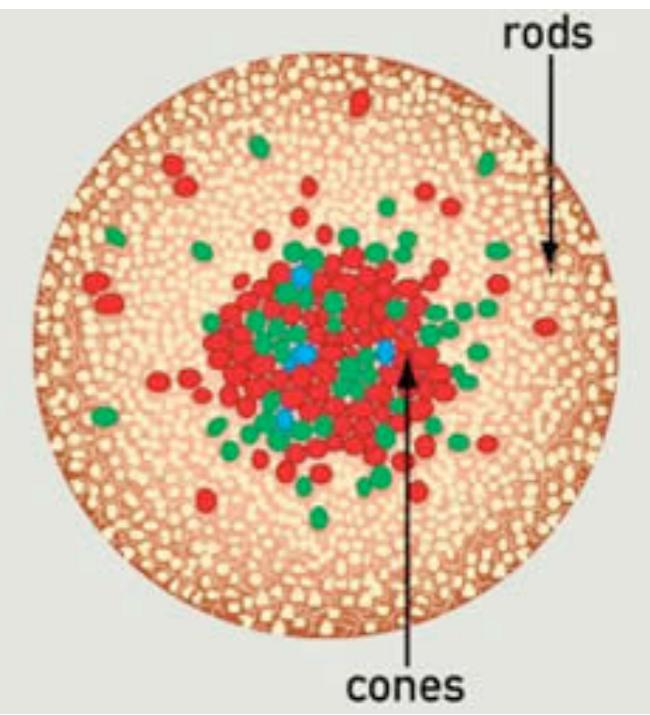
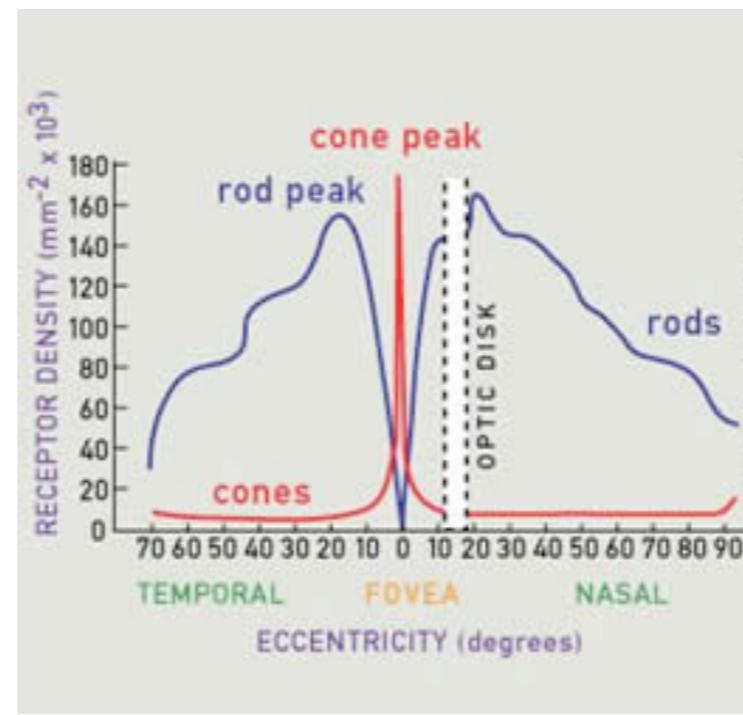
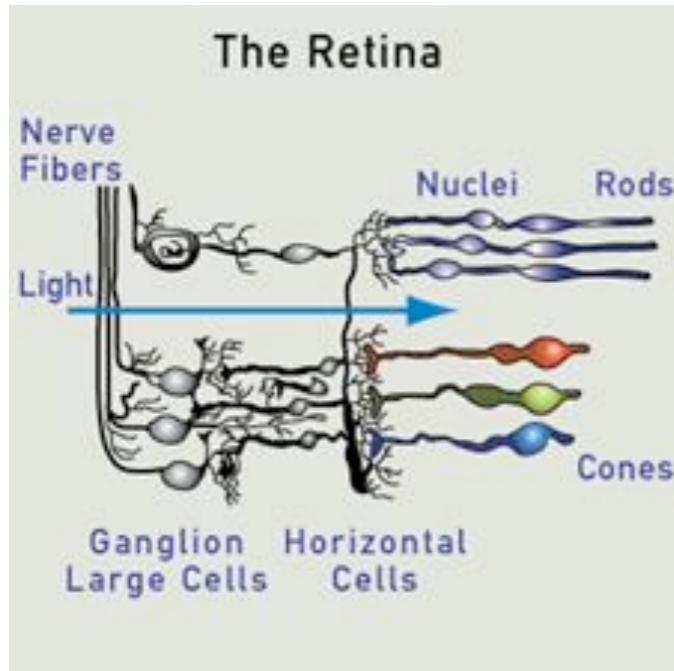
www.webexhibits.org

Image Formation - Lens based Model



- Flexible lens - to allow focusing on variable distances
- Focal distance varies between 17 mm to 14 mm

Visual Perception



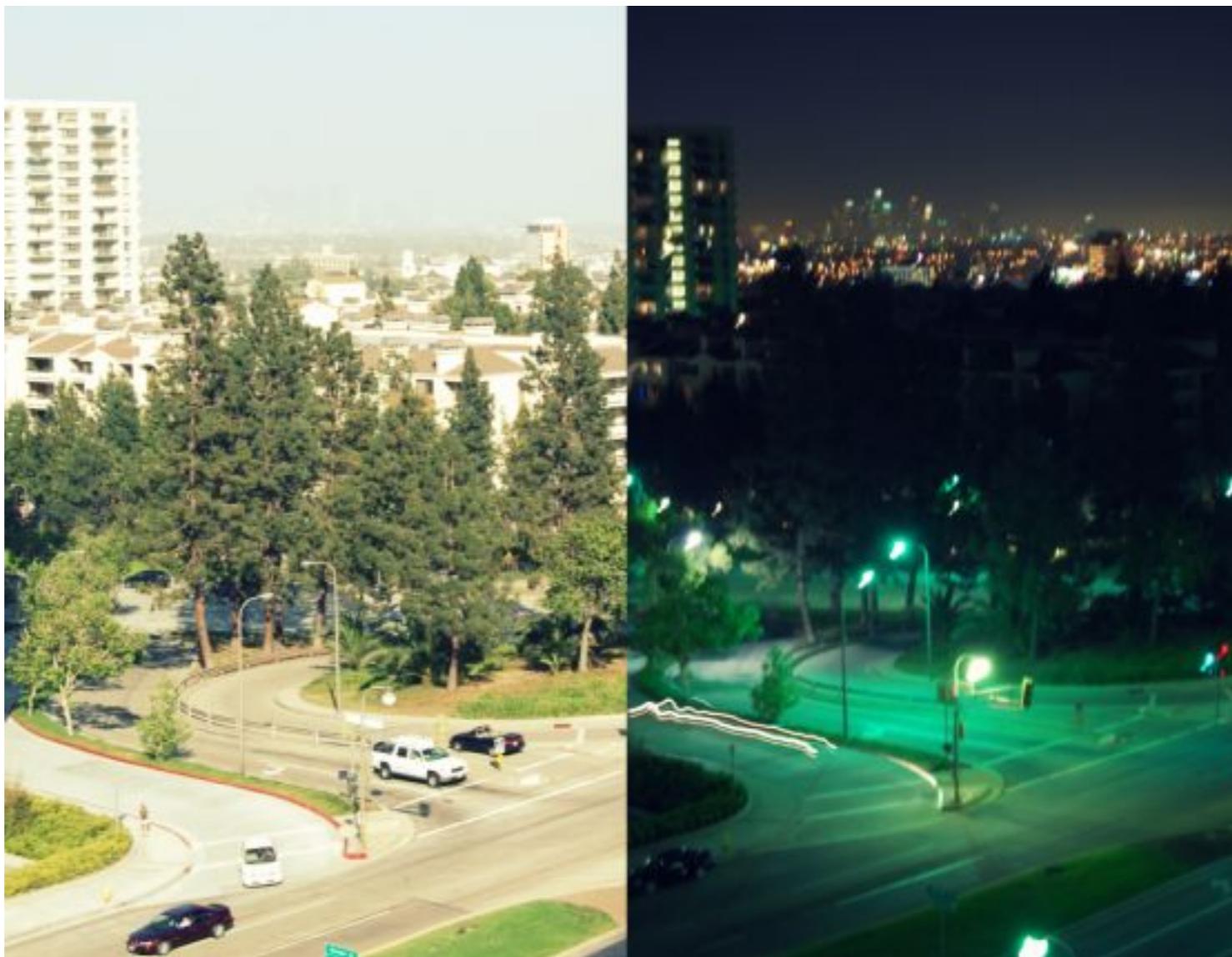
- More rods than cones (75-150 million Vs 6-7 million)
- Rods account for low-light, peripheral vision
 - Scotopic vision
- Cones help in frontal, color vision
 - Photopic vision

Day vs Night Vision



Day vs Night Vision

Objects
identified by
color



Day vs Night Vision

Objects
identified by
color

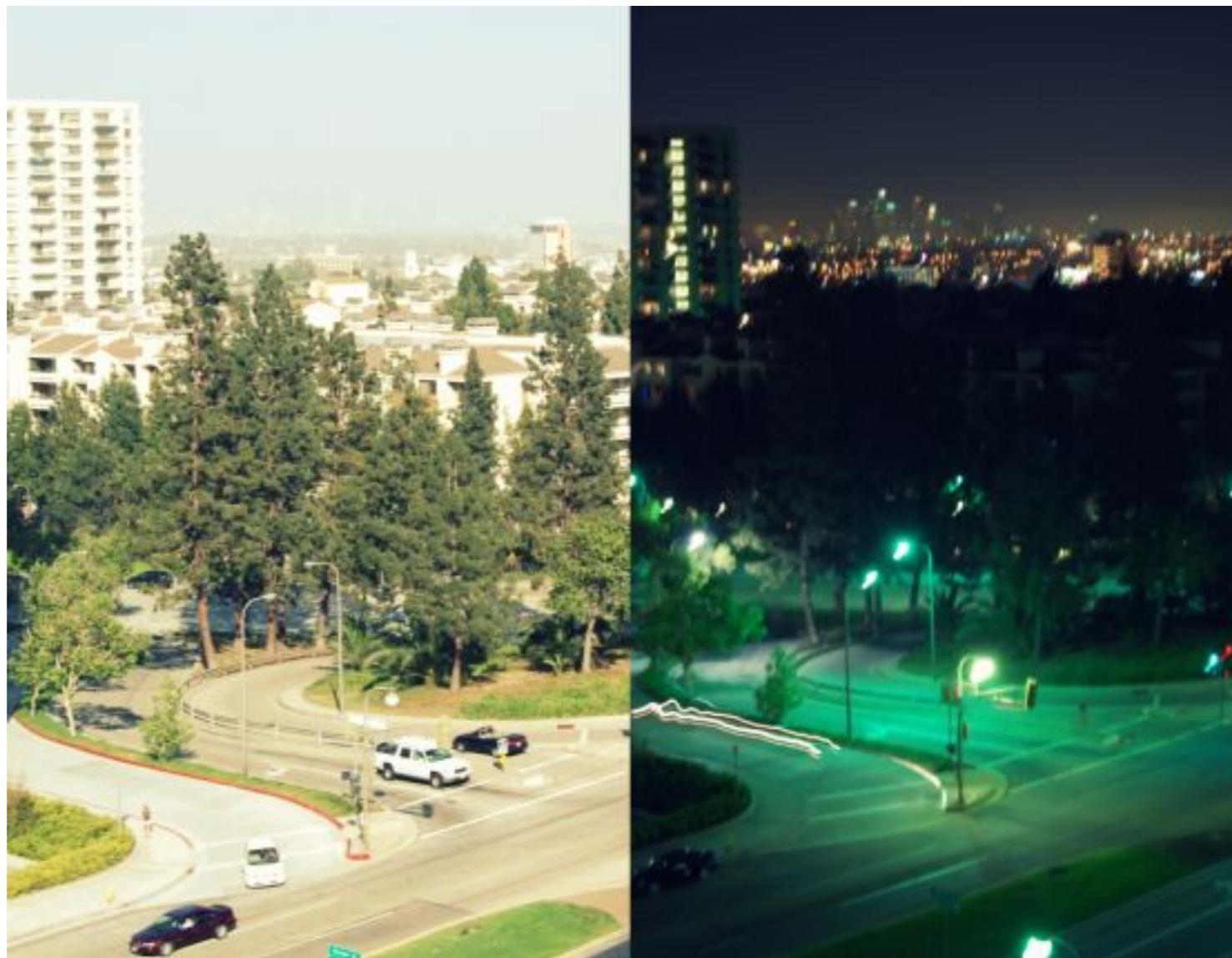


Objects
identified by
shape

Day vs Night Vision

Objects
identified by
color

Cones are
activated



Objects
identified by
shape

Day vs Night Vision

Objects
identified by
color

Cones are
activated



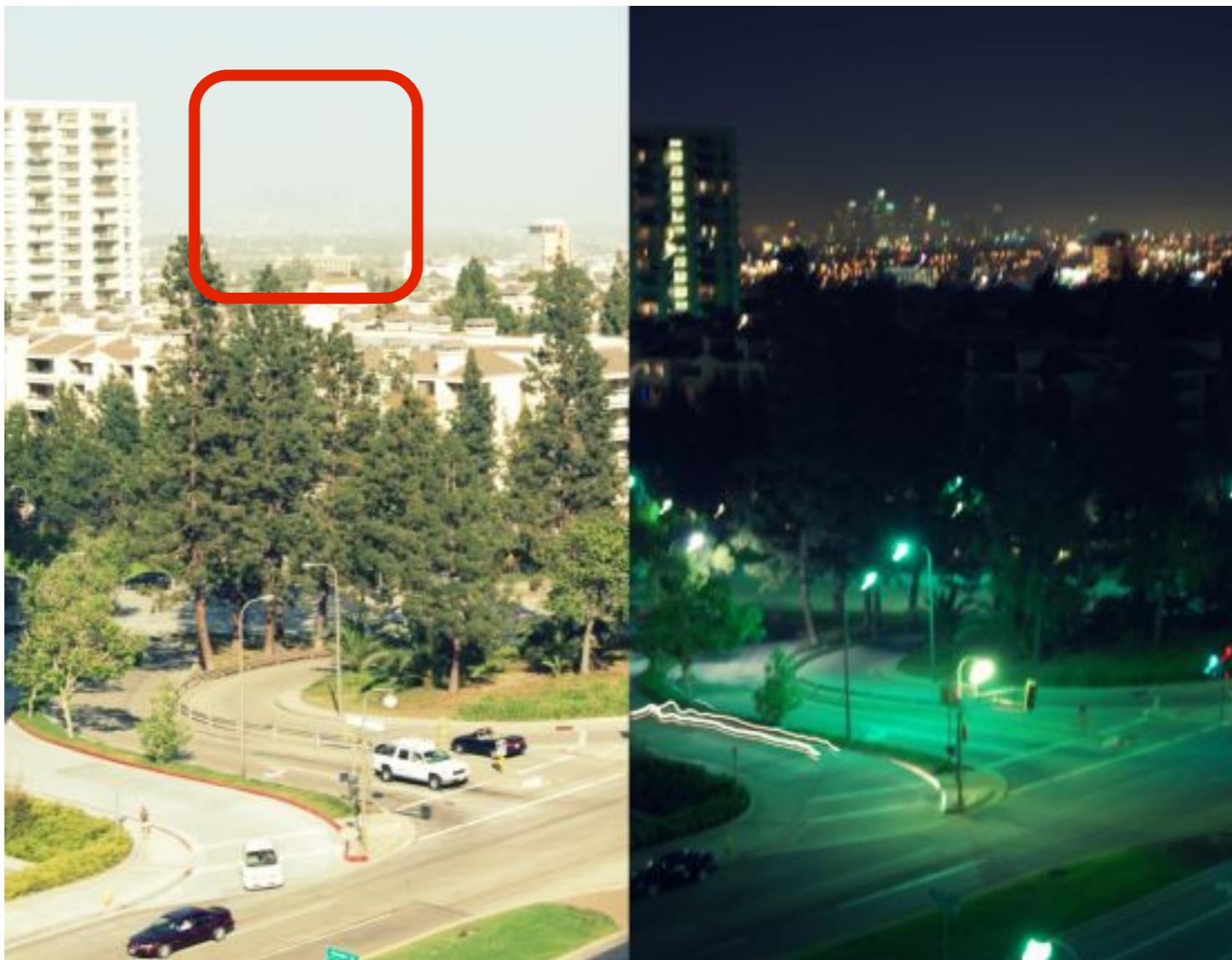
Objects
identified by
shape

Rods are
activated

Day vs Night Vision

Objects identified by color

Cones are activated



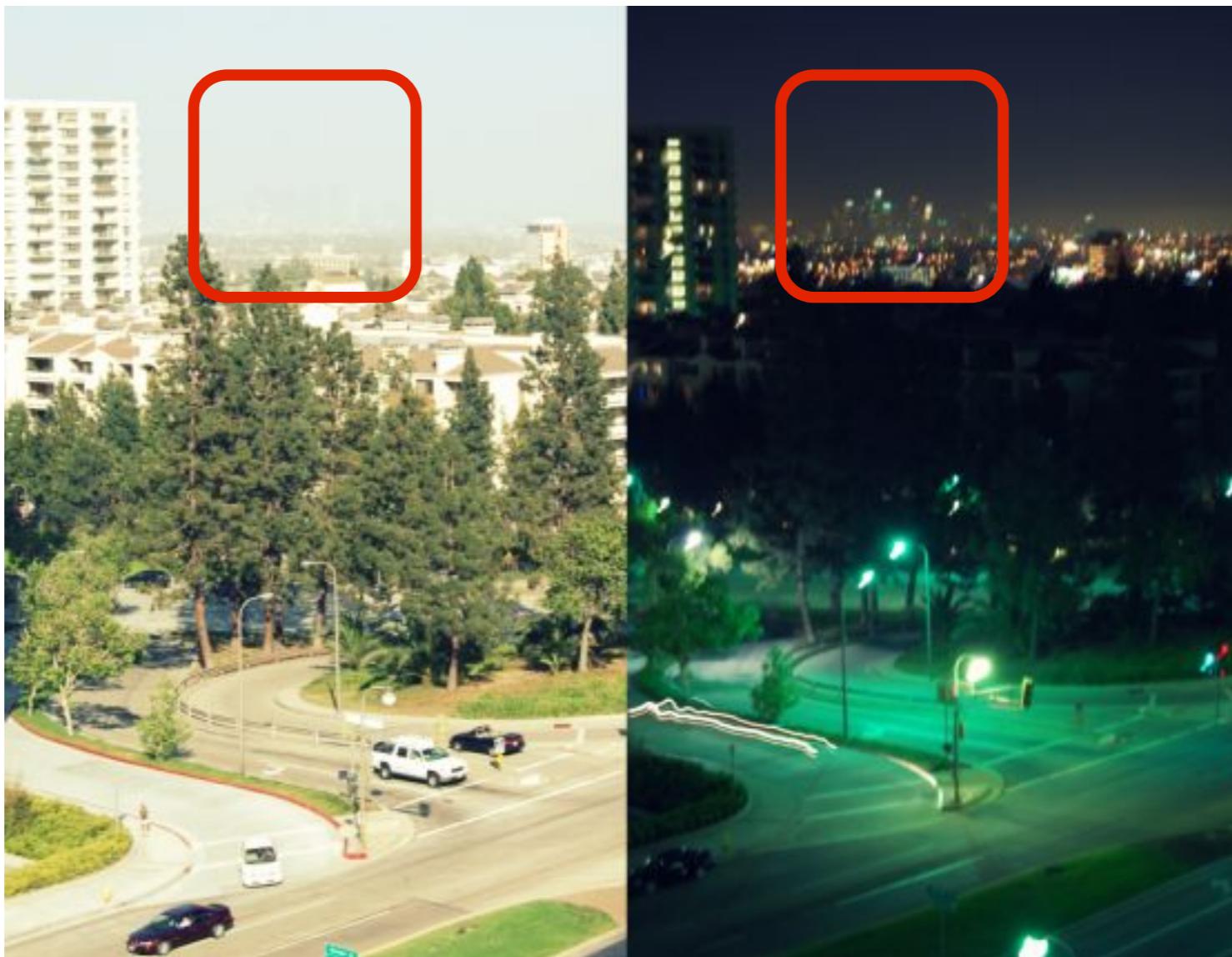
Objects identified by shape

Rods are activated

Day vs Night Vision

Objects identified by color

Cones are activated



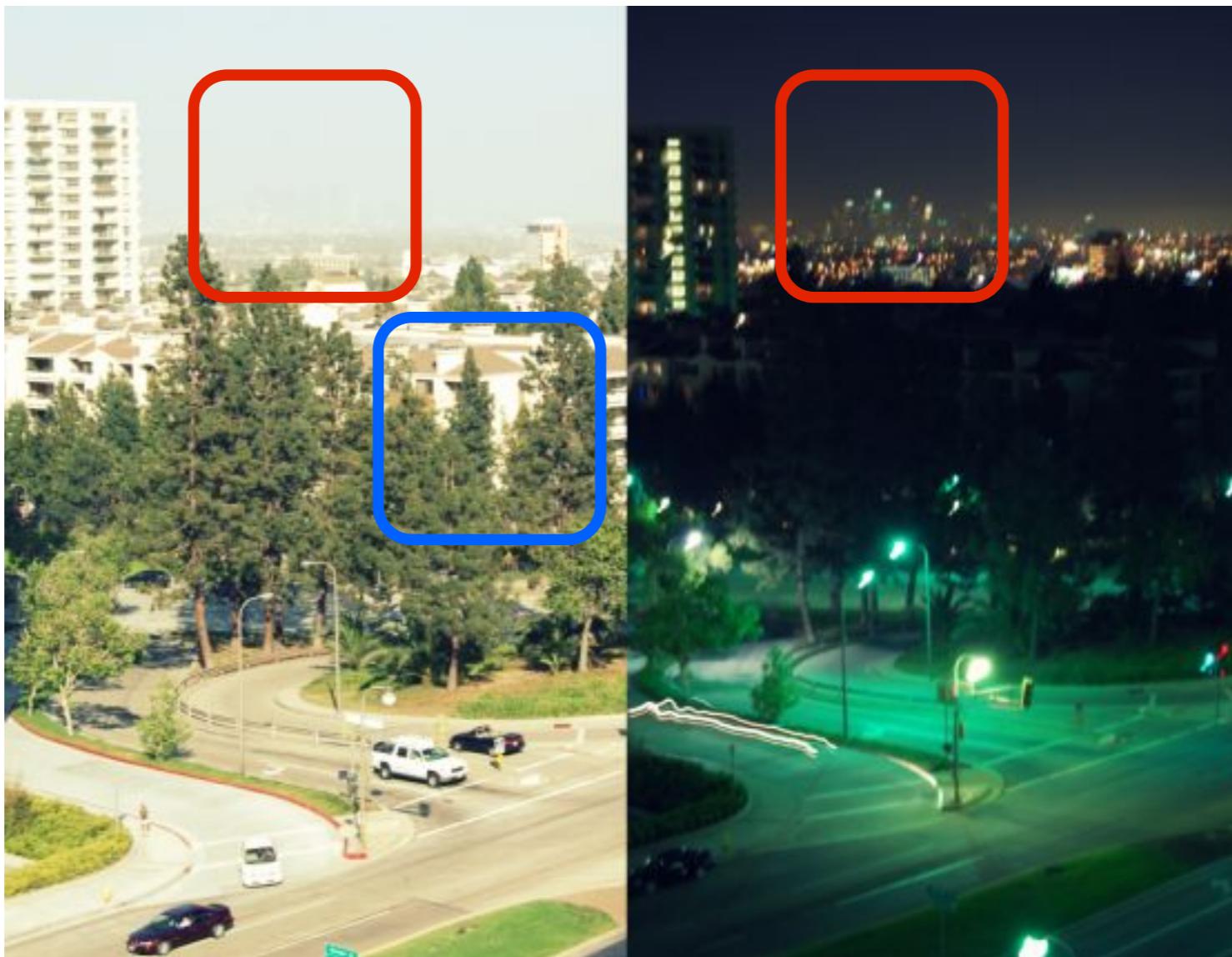
Objects identified by shape

Rods are activated

Day vs Night Vision

Objects identified by color

Cones are activated



Objects identified by shape

Rods are activated

Day vs Night Vision

Objects identified by color

Cones are activated

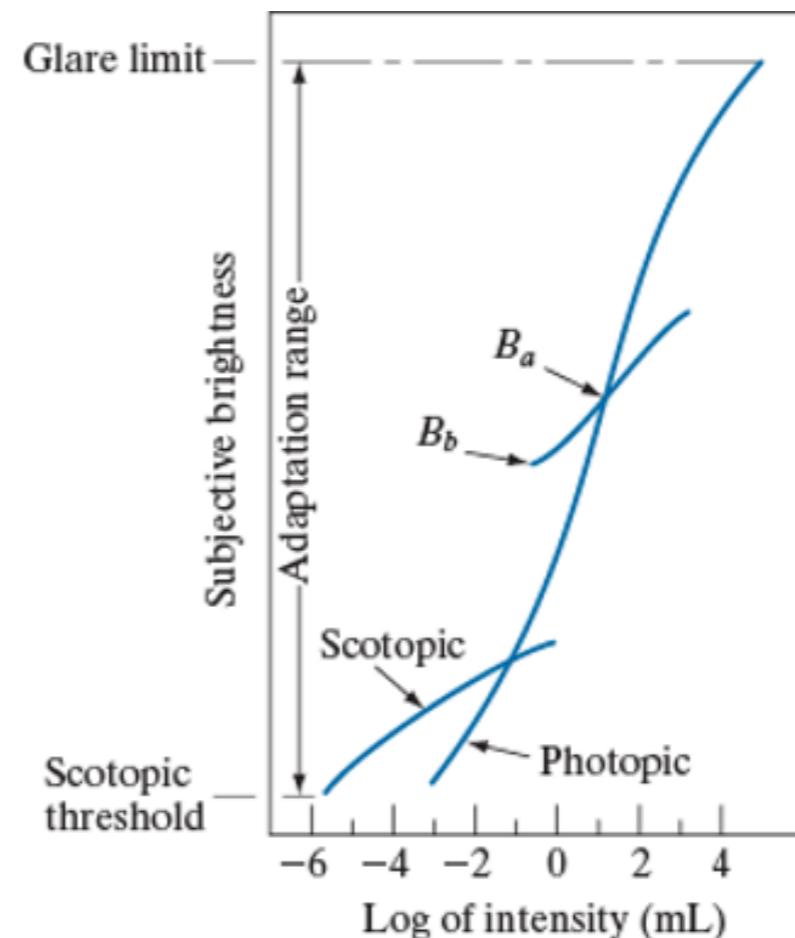


Objects identified by shape

Rods are activated

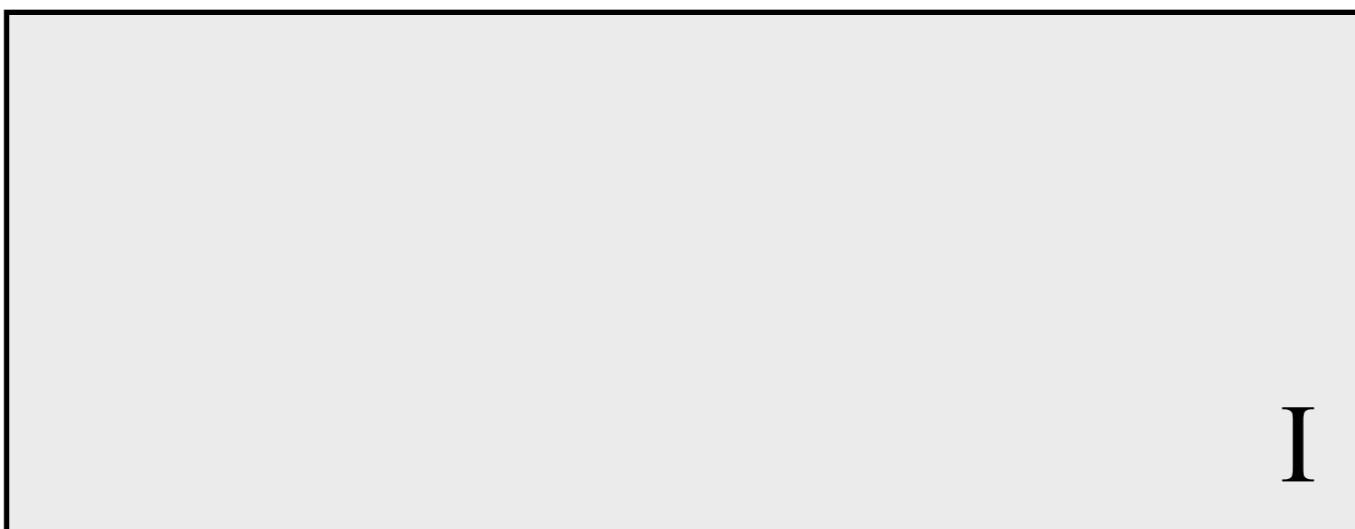
Visual Response - Brightness Adaptation

- Brightness discrimination is crucial to image understanding
- Actual dynamic range of the human eye - order of 10^{10}
- Essential point: The human visual system cannot operate on the entire dynamic range *at once*
- Changes to overall sensitivity, known as “brightness adaptation”



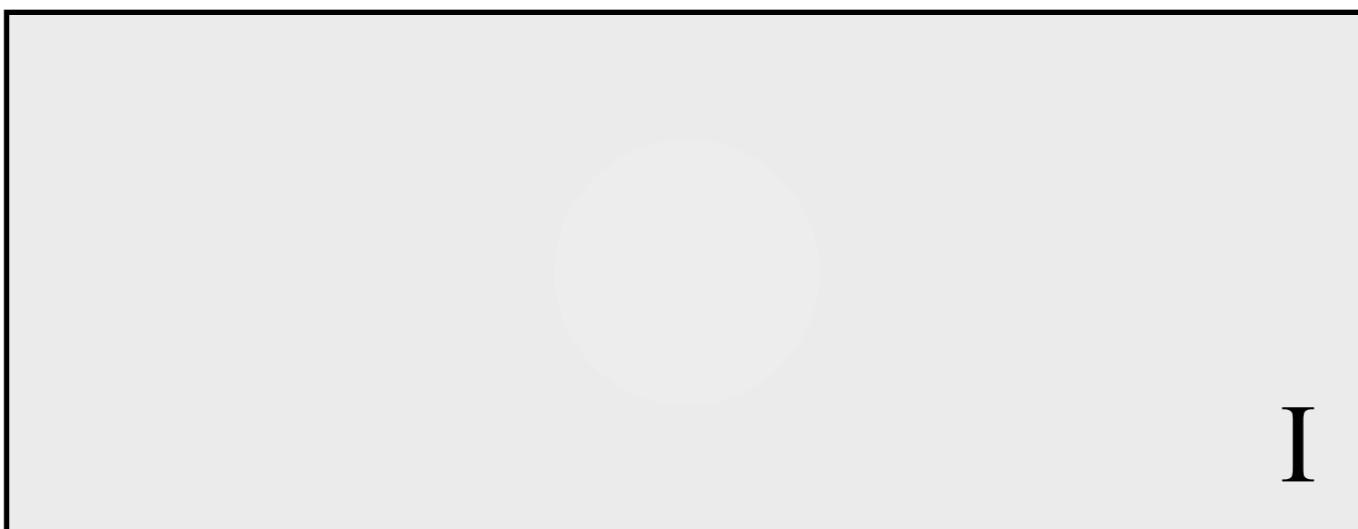
B_a : Brightness adaptation level
 B_b : Bottom threshold for discernible intensities

Brightness Discrimination Test



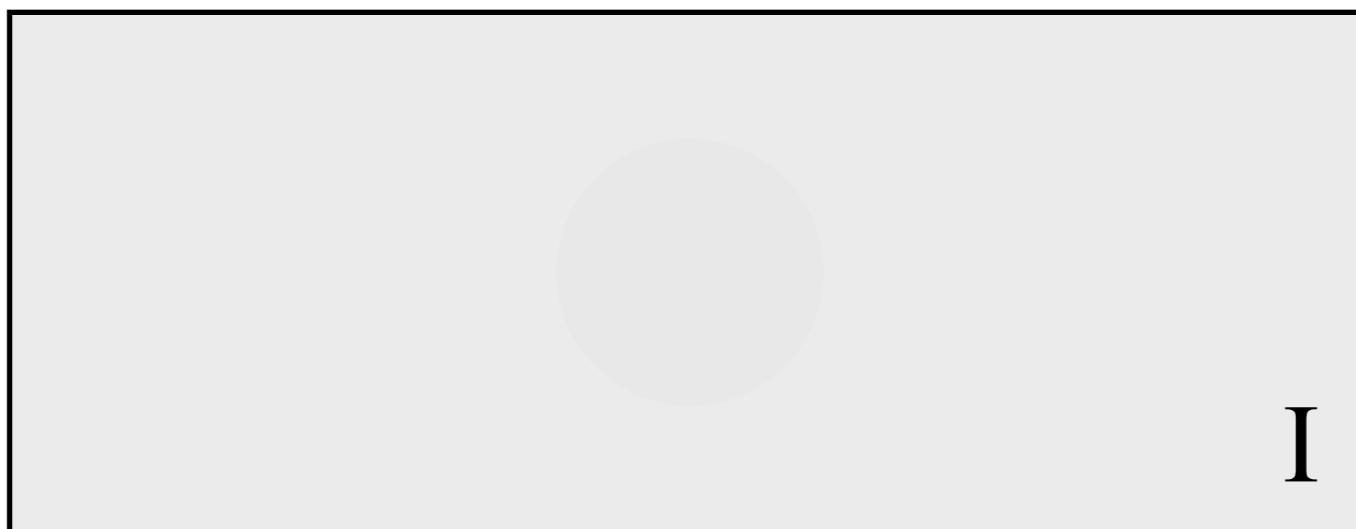
Brightness discrimination is poor in low-light conditions

Brightness Discrimination Test



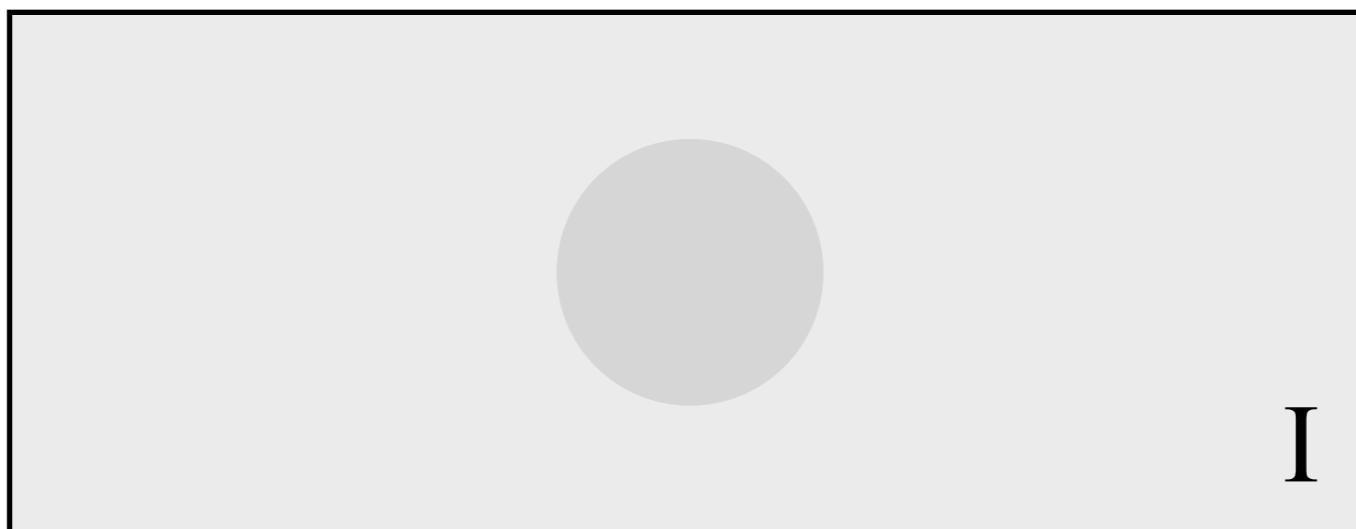
Brightness discrimination is poor in low-light conditions

Brightness Discrimination Test



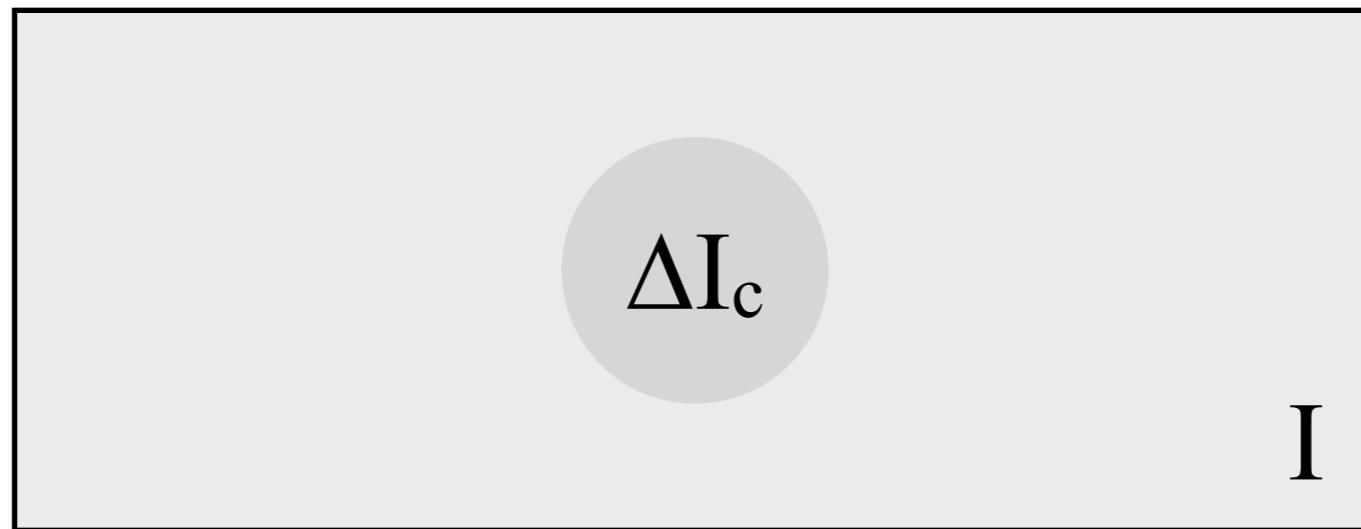
Brightness discrimination is poor in low-light conditions

Brightness Discrimination Test



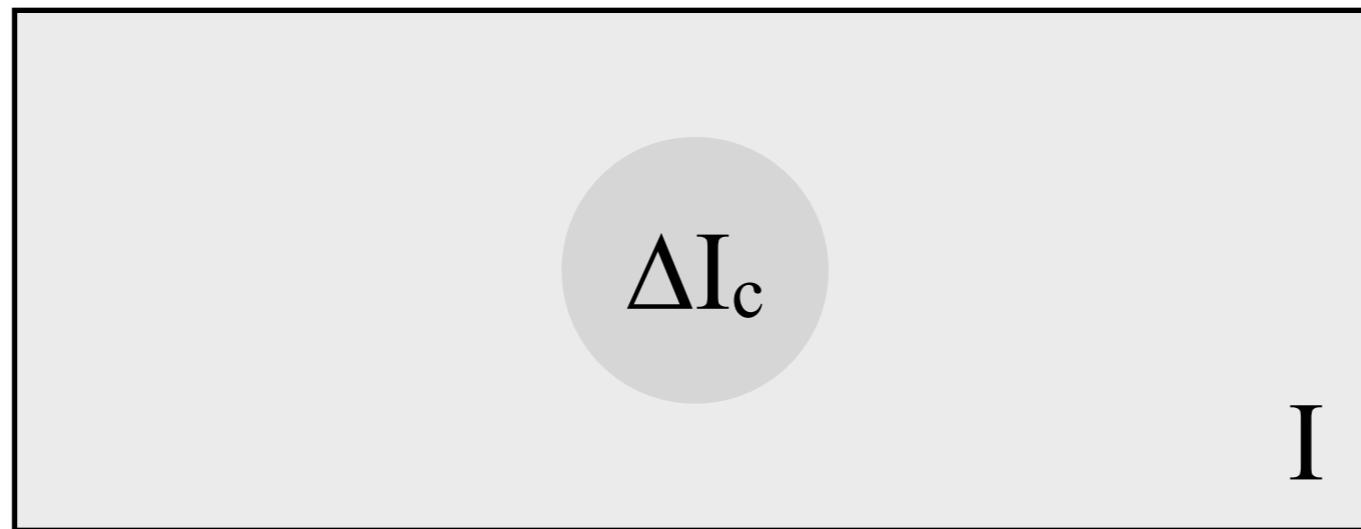
Brightness discrimination is poor in low-light conditions

Brightness Discrimination Test



Brightness discrimination is poor in low-light conditions

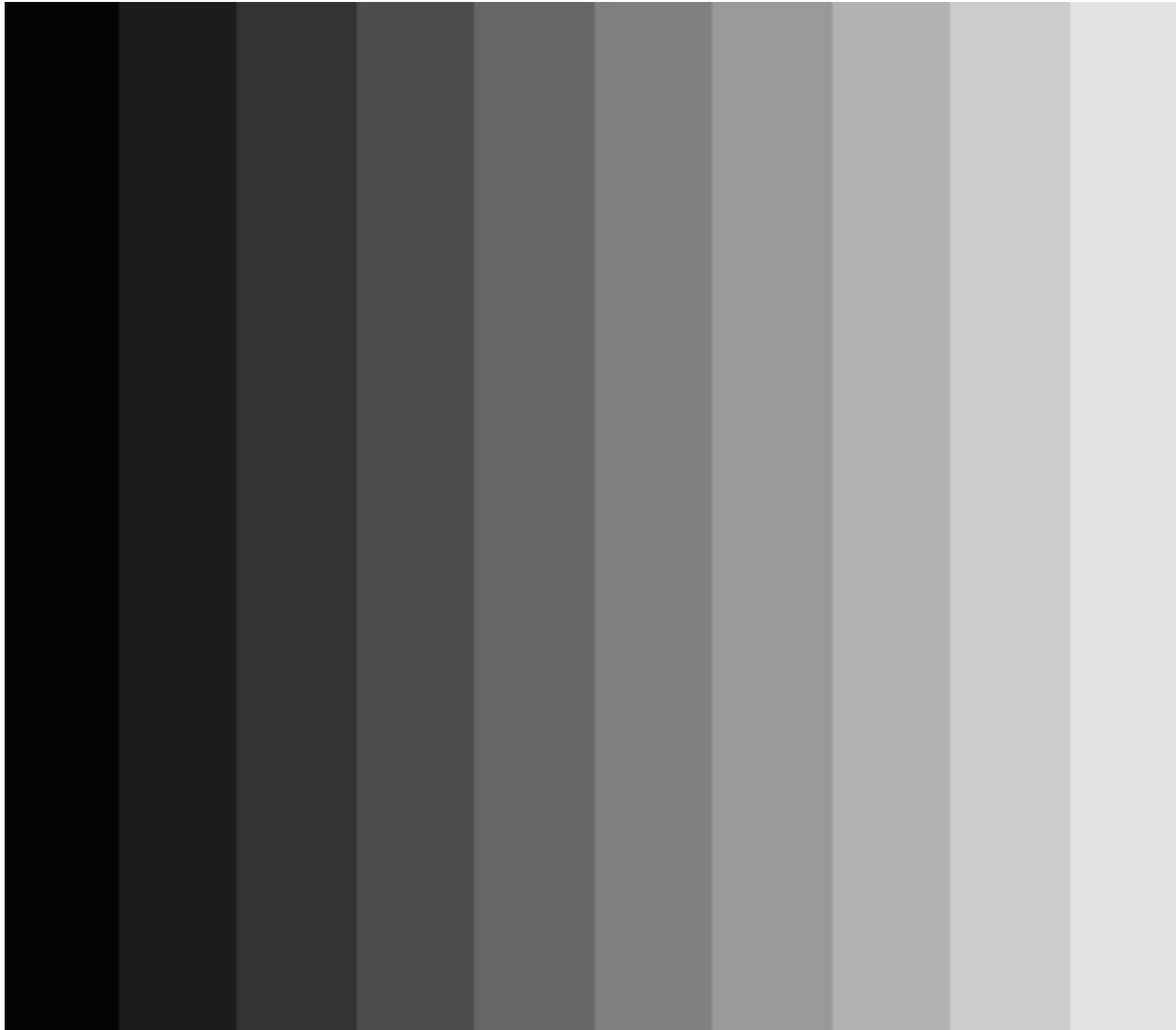
Brightness Discrimination Test



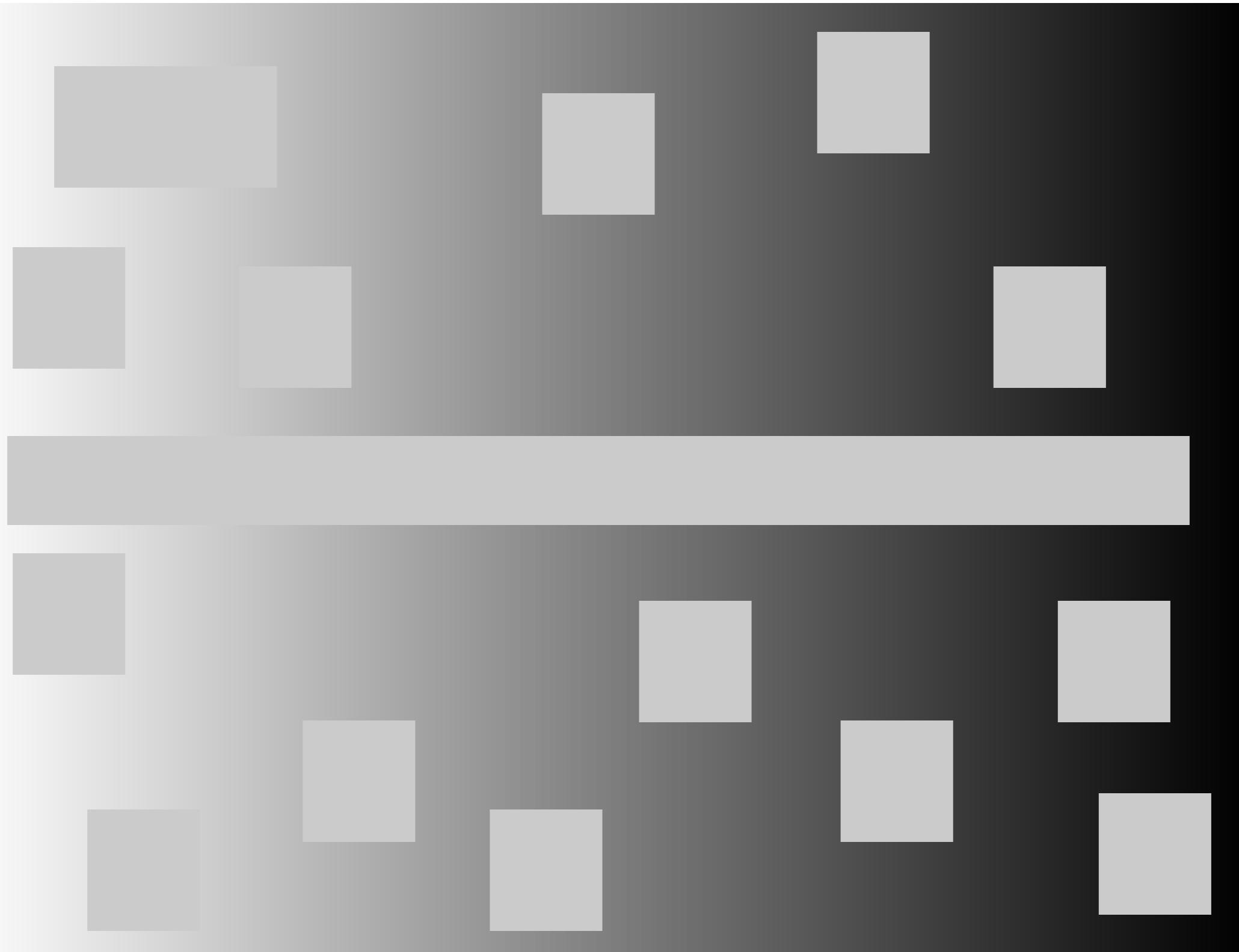
$\Delta I_c / I$: Weber Ratio

Brightness discrimination is poor in low-light conditions

Perception



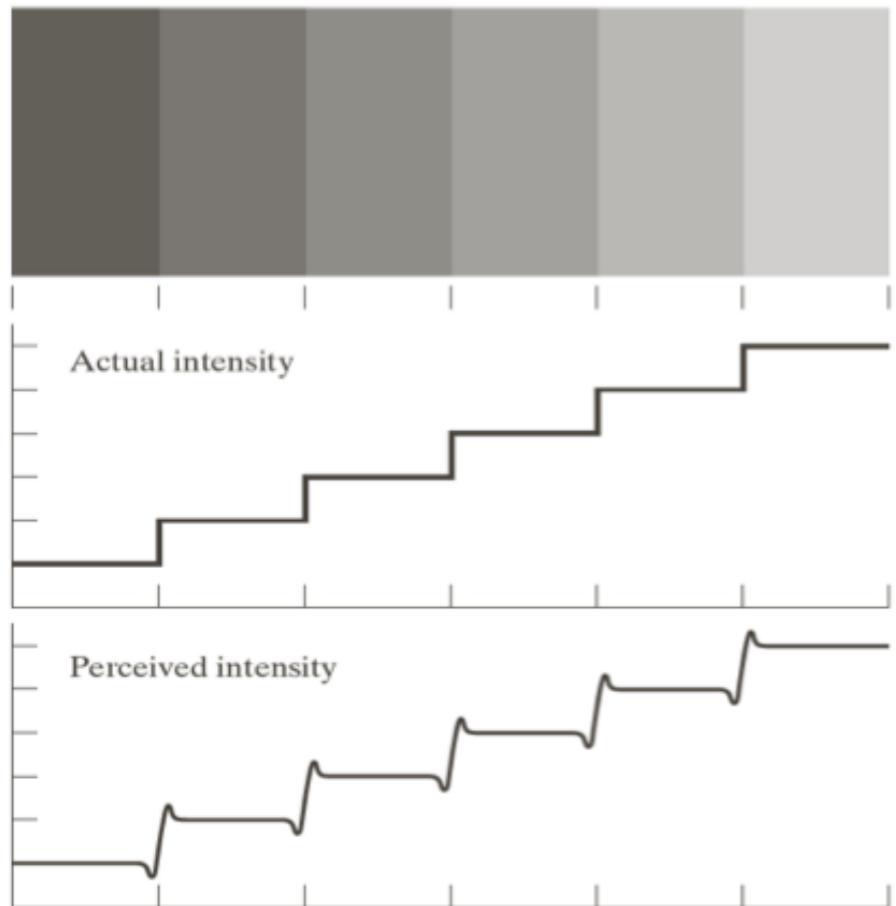
Contrast Perception



Contrast Perception

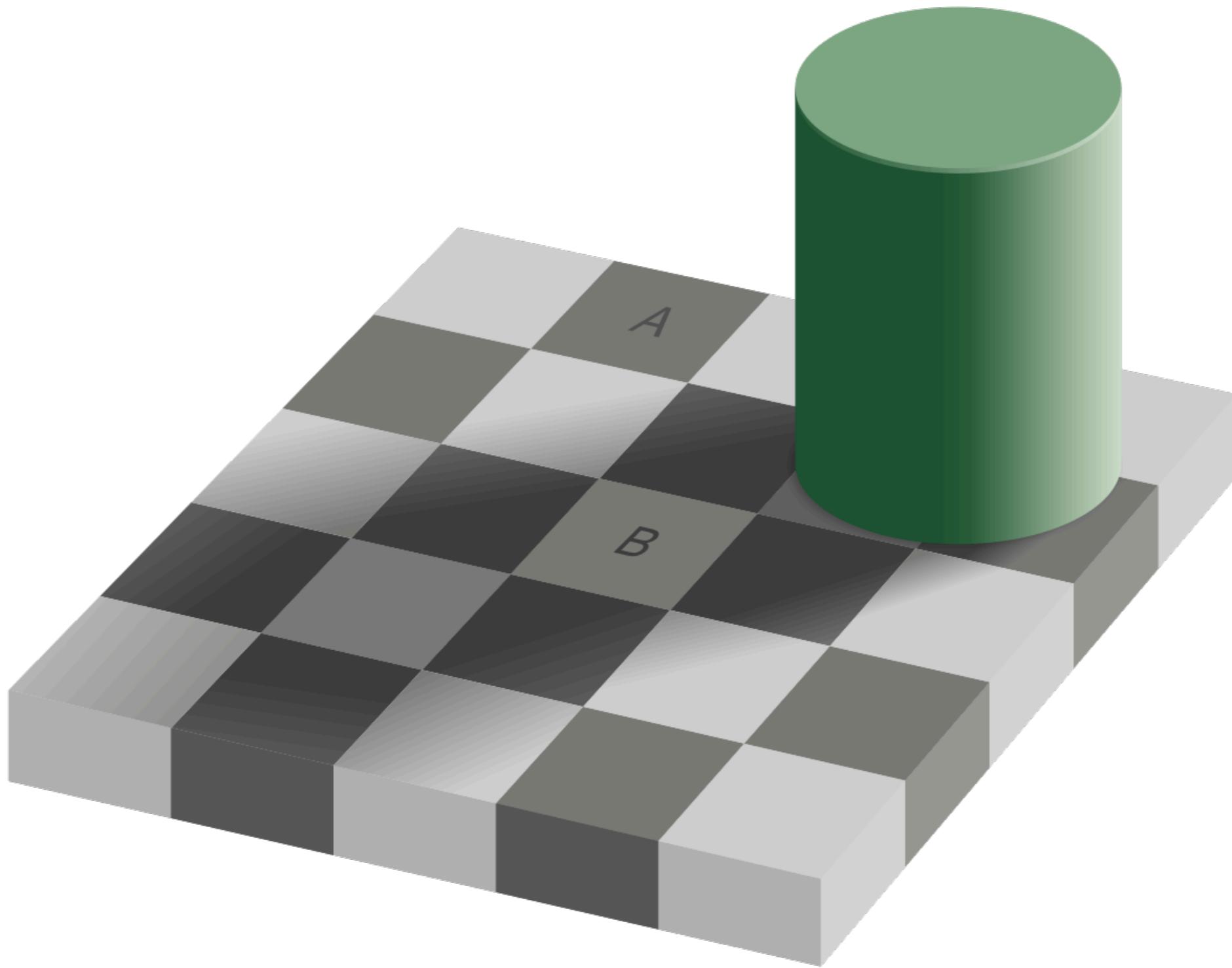


Perception



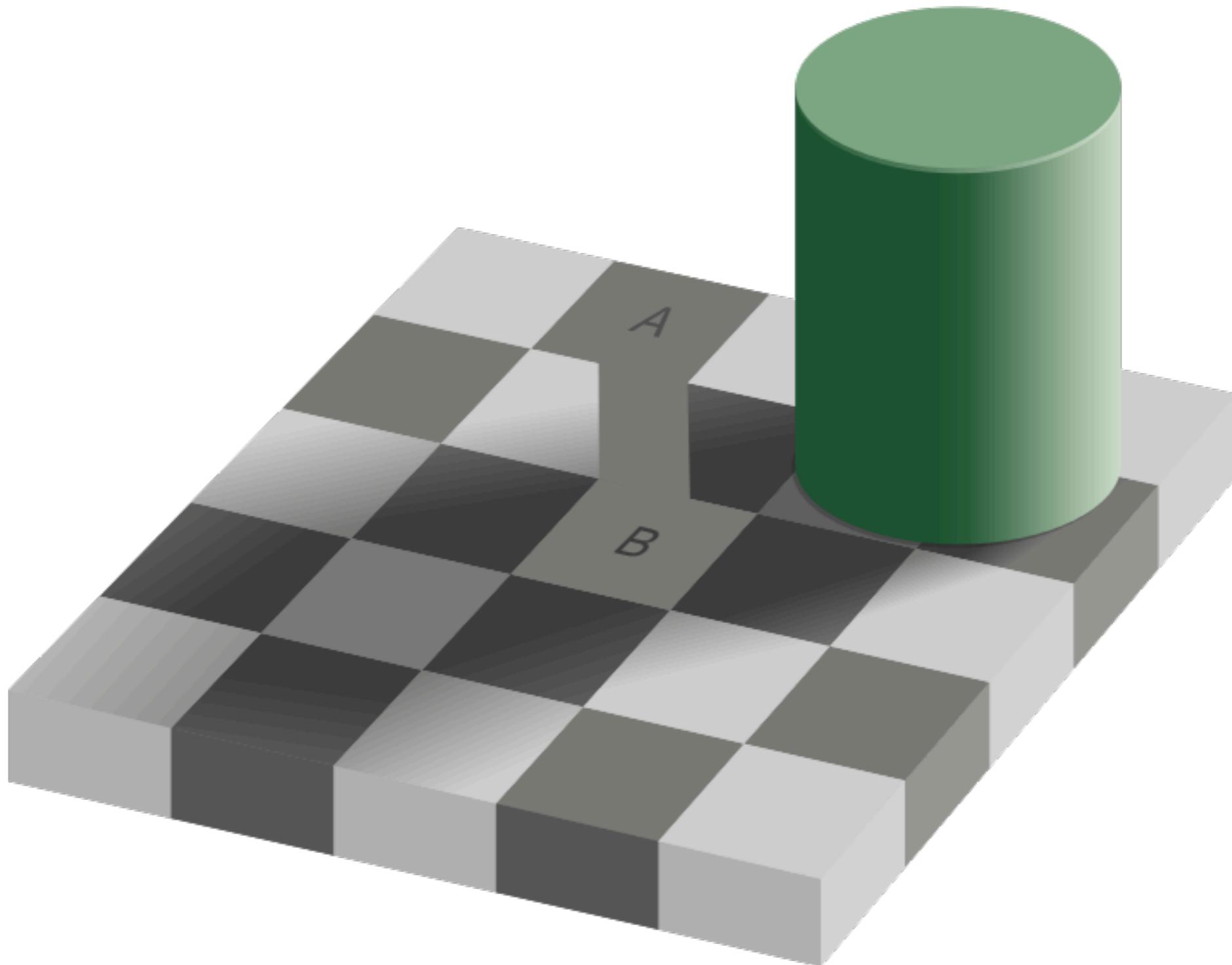
Perceived brightness is a function of intensity
Mach Bands (Ernst Mach, 1865)

??

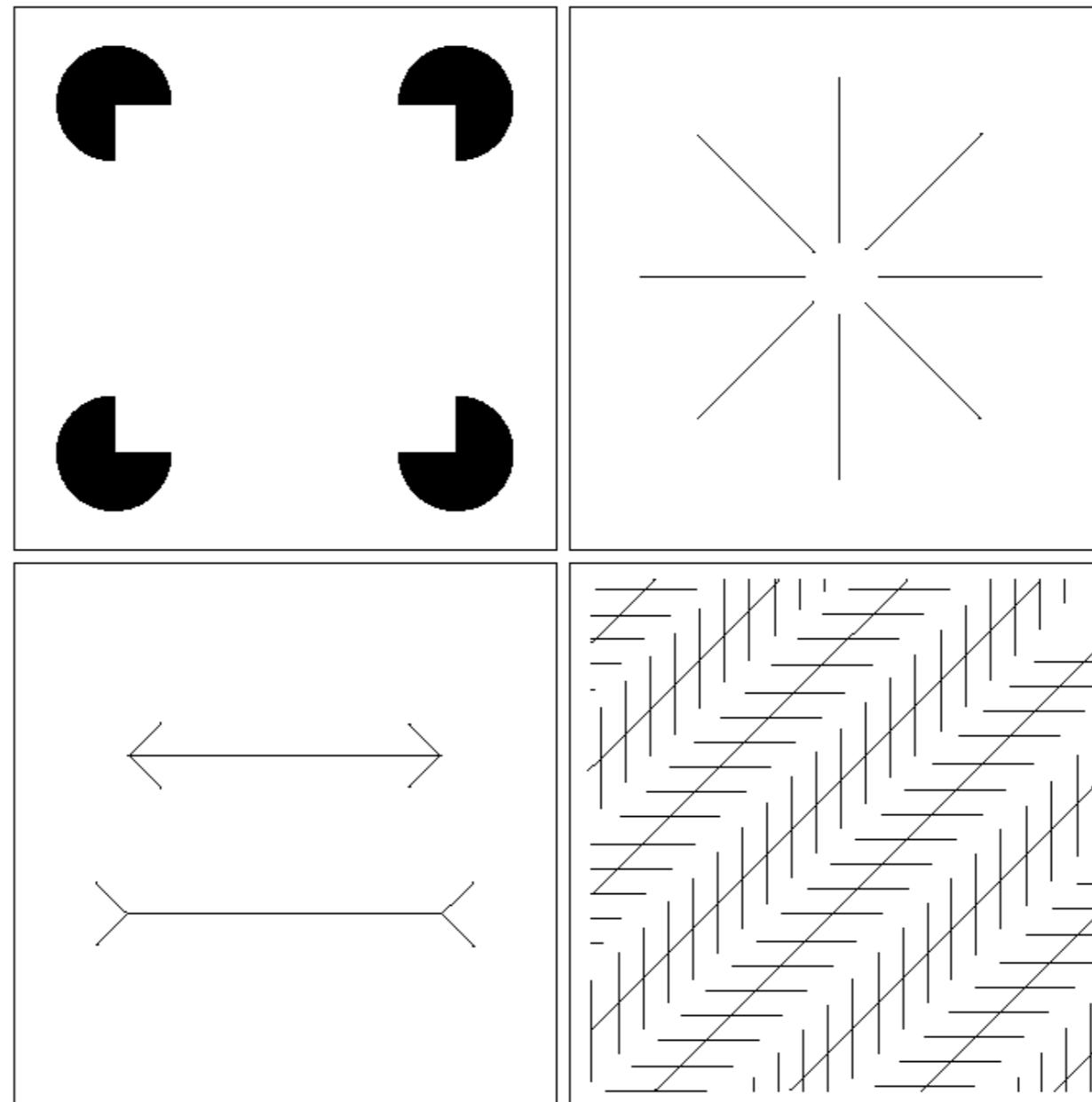


Shadow Illusion

By Original by Edward H. Adelson - File created by Adrian Pingstone, based on the original created by Edward H. Adelson, Copyrighted free use, <https://commons.wikimedia.org/w/index.php?curid=45737683>



Optical Illusions





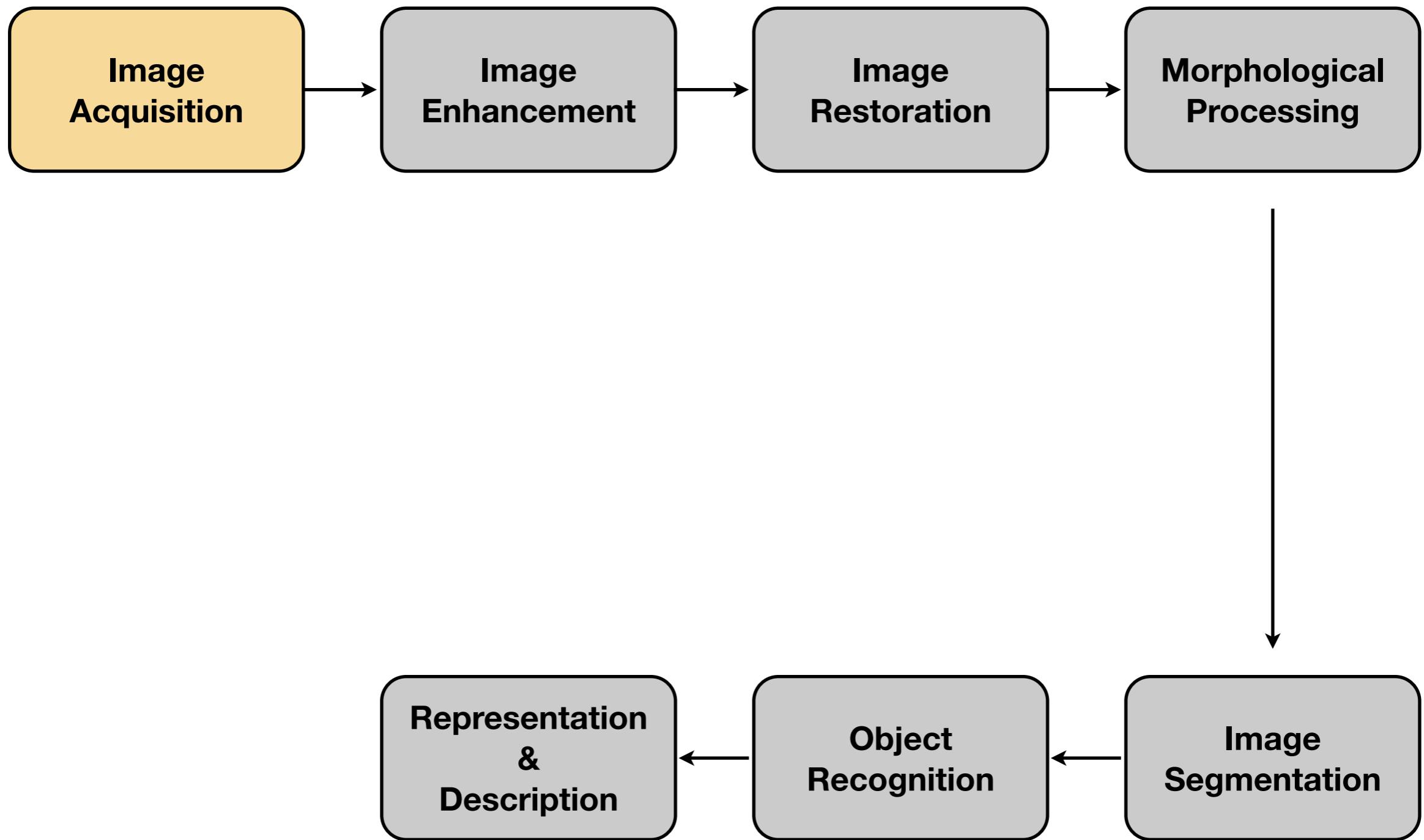
Key Idea

Pixel colors by themselves, **do not** correspond to “visual information.”

Images have to be **processed**, to be made **understandable** to humans.

The Image Processing Pipeline

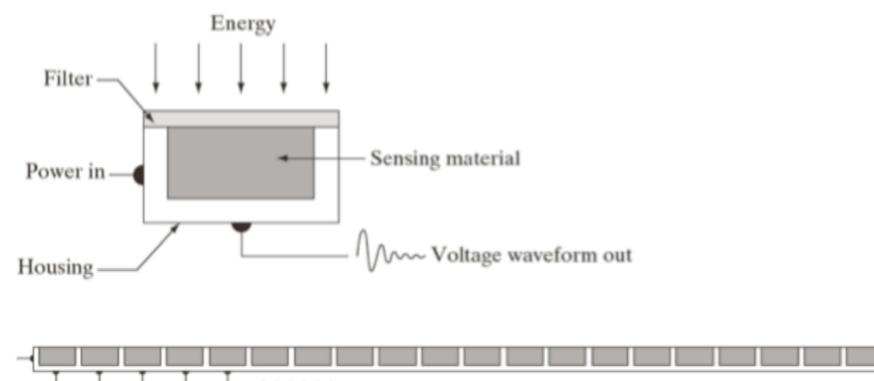
Digital Image Processing Pipeline



Capturing Digital Images

- Imaging sensors

- Individual



- Line-sensors

- Array sensors

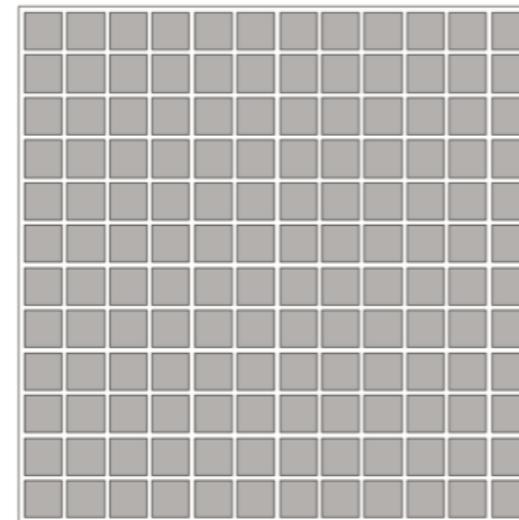
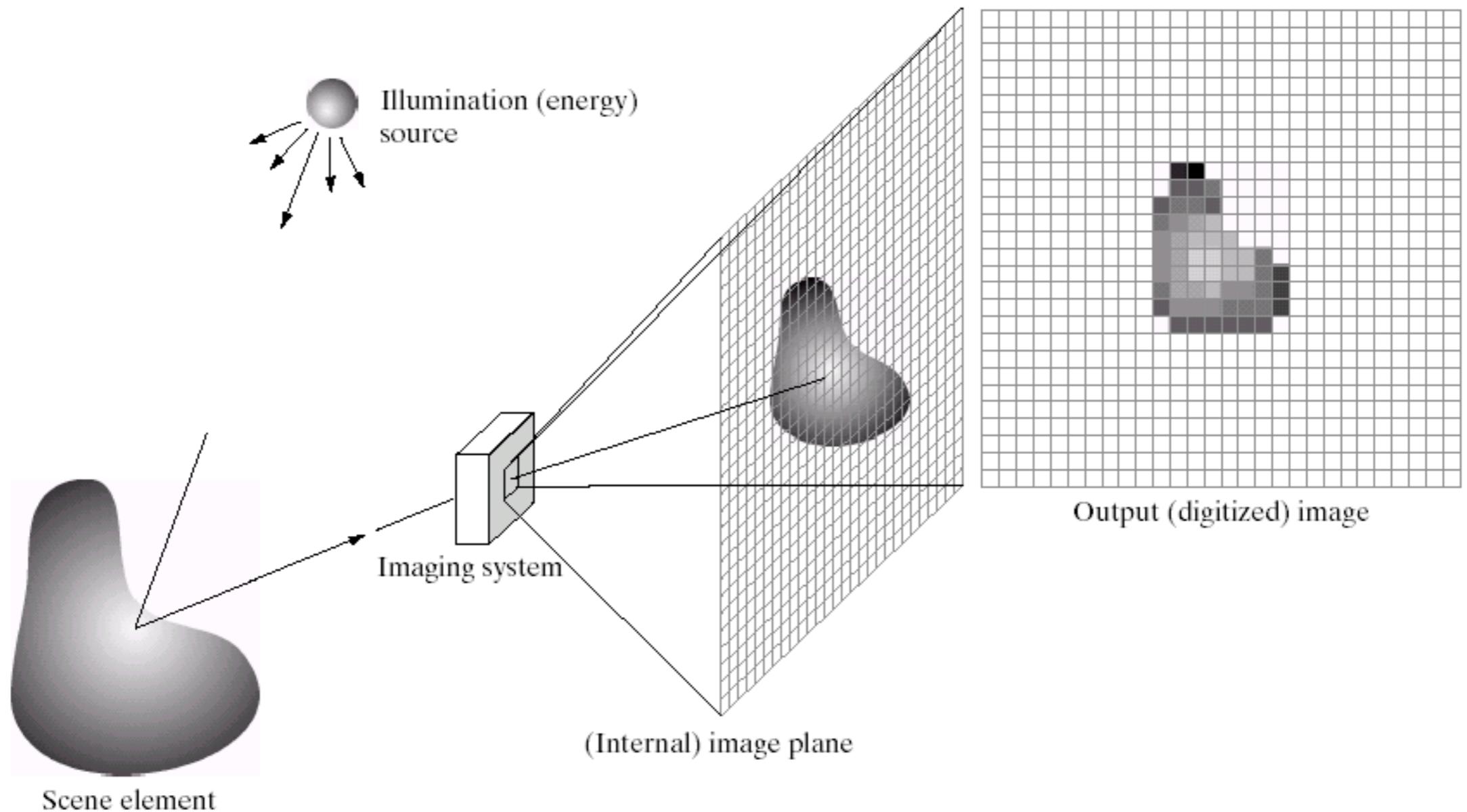


Image Acquisition

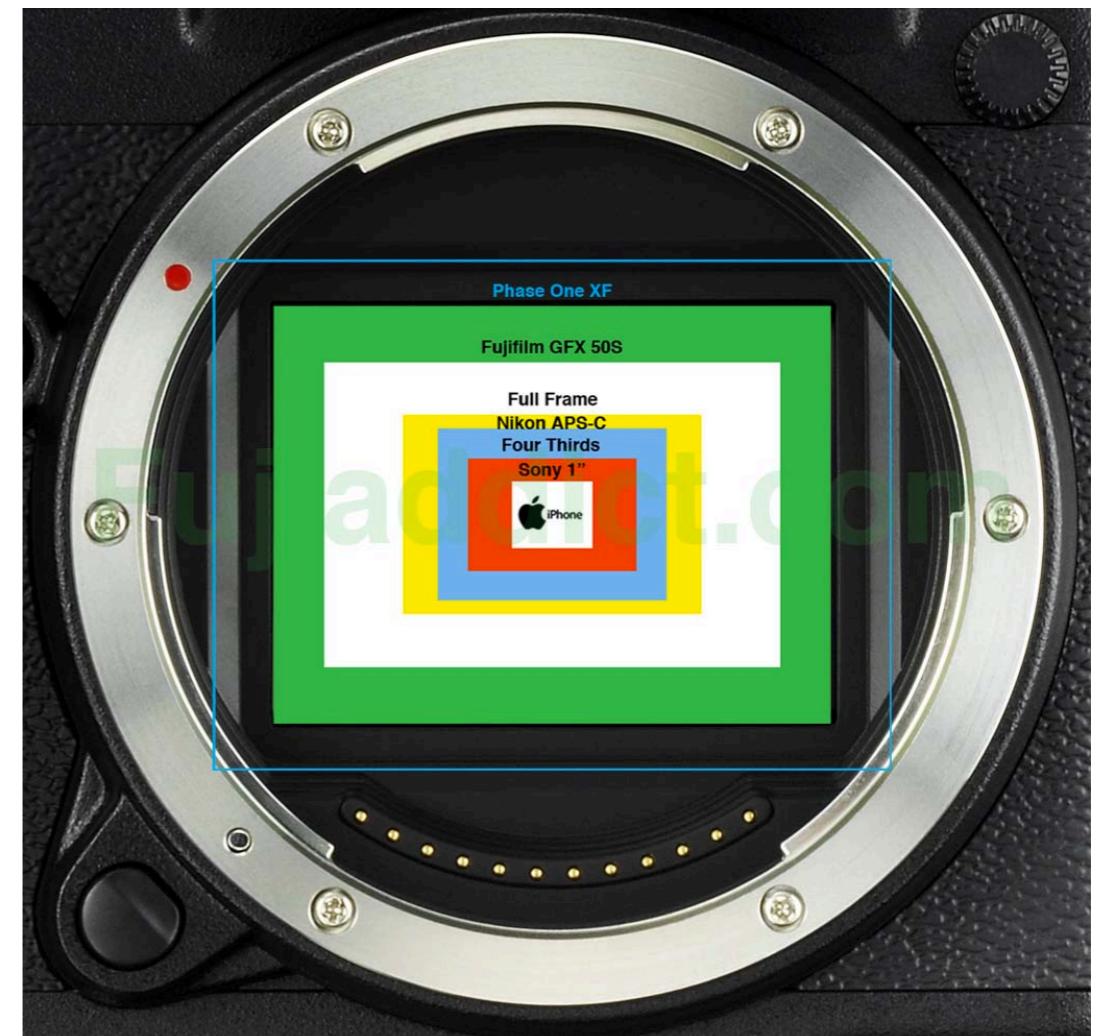
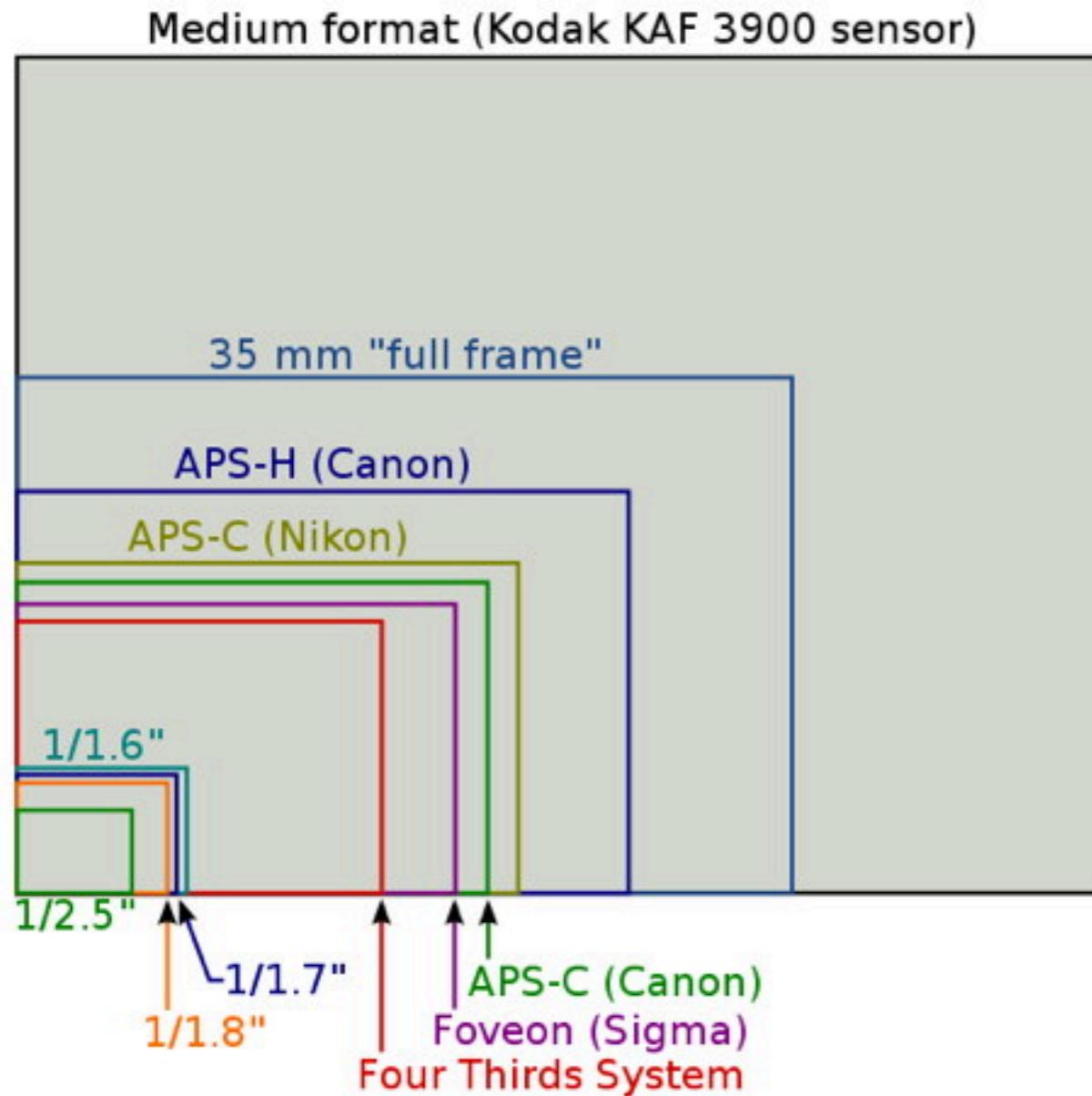


Imaging Plane

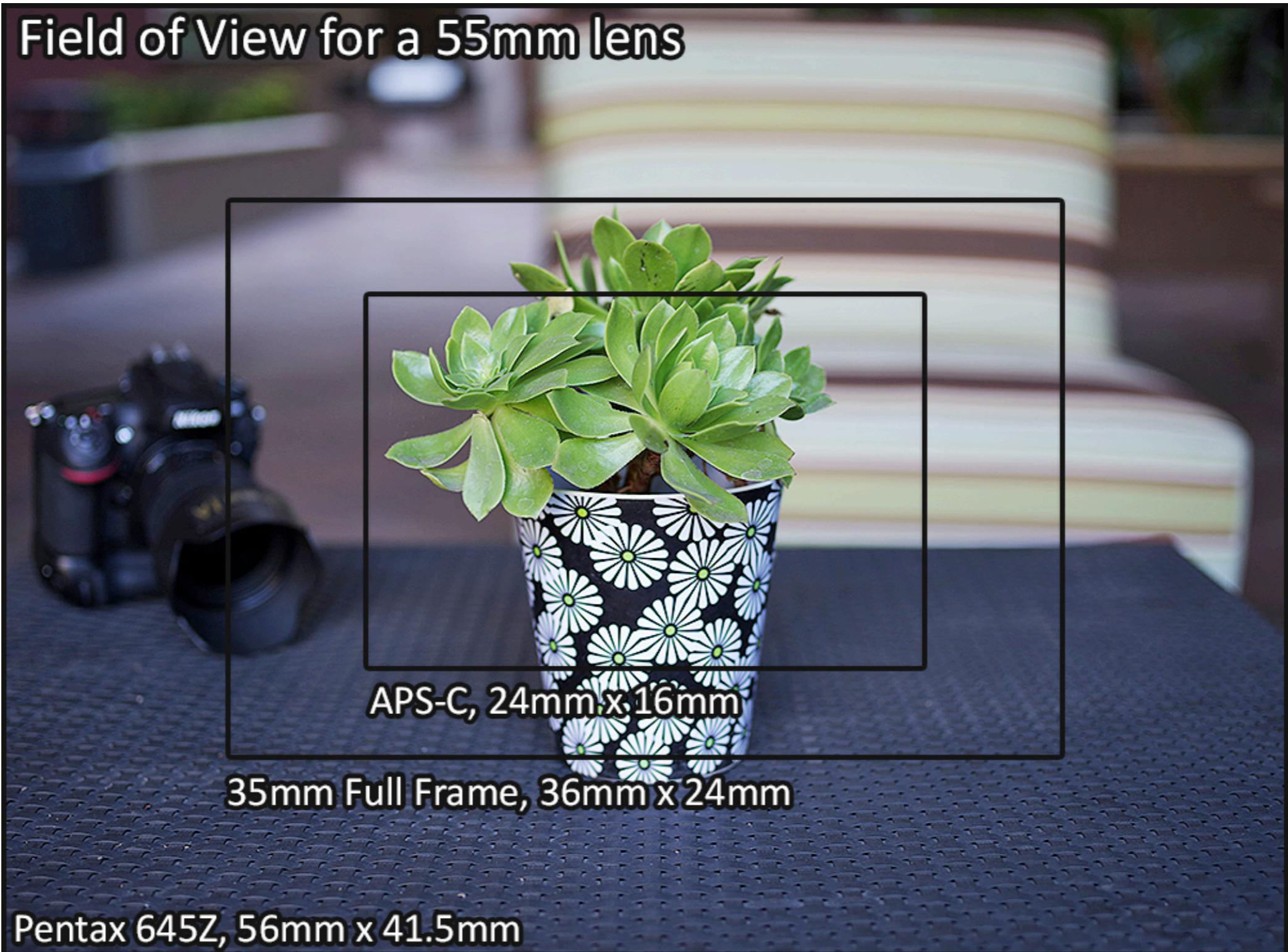
- Usually, the 2D planar receiver of the projected photons
- Film or glass plate
- This is the 2D plane where the image is “formed” by accumulation of photons



The Digital Imaging Plane == Image Sensor



FoV Comparison



Mathematical Model of the Image Plane

Illumination and Reflectance

- Image intensity is function of two phenomena
 - Incident light - Source illumination
 - Reflected light - Scene elements
- Resulting light energy can be modeled as follows:

$$f(x, y) = i(x, y)r(x, y)$$

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$$0 < i(x, y) < \infty \quad \text{incident energy}$$

Illumination and Reflectance

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- Incident light - Source illumination

- Reflected light - Scene elements

- Resulting light energy can be modeled as follows:

$$f(x, y) = i(x, y)r(x, y)$$

$$0 < i(x, y) < \infty \quad \text{incident energy}$$

$$0 < r(x, y) < 1 \quad \text{reflectance property}$$

Practical Considerations

- Preceding bounds are theoretical
- In practice

Ambient Conditions	Incident energy
Bright daylight	9000 ft-cd
Cloudy day	≈ 1000 ft-cd
Lighted Office	100 ft-cd
Full moon	0.01 ft-cd

feet-candela

Material	Reflectance
Black velvet	0.01
Stainless Steel	0.65
Flat white wall paint	0.8
Silver plated metal	0.9

Gray Level Range

- Intensity of a monochrome image at location (x,y) -> Gray level, L
- For practical (indoor) situations

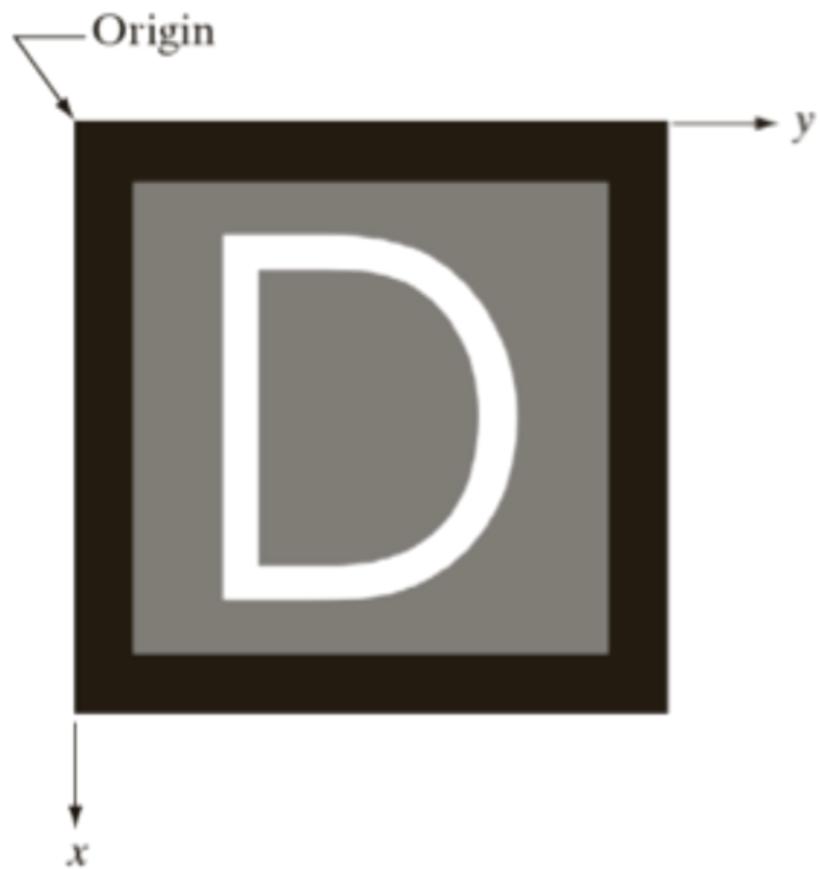
$$L_{min} \approx 0.05$$

$$L_{max} \approx 100$$

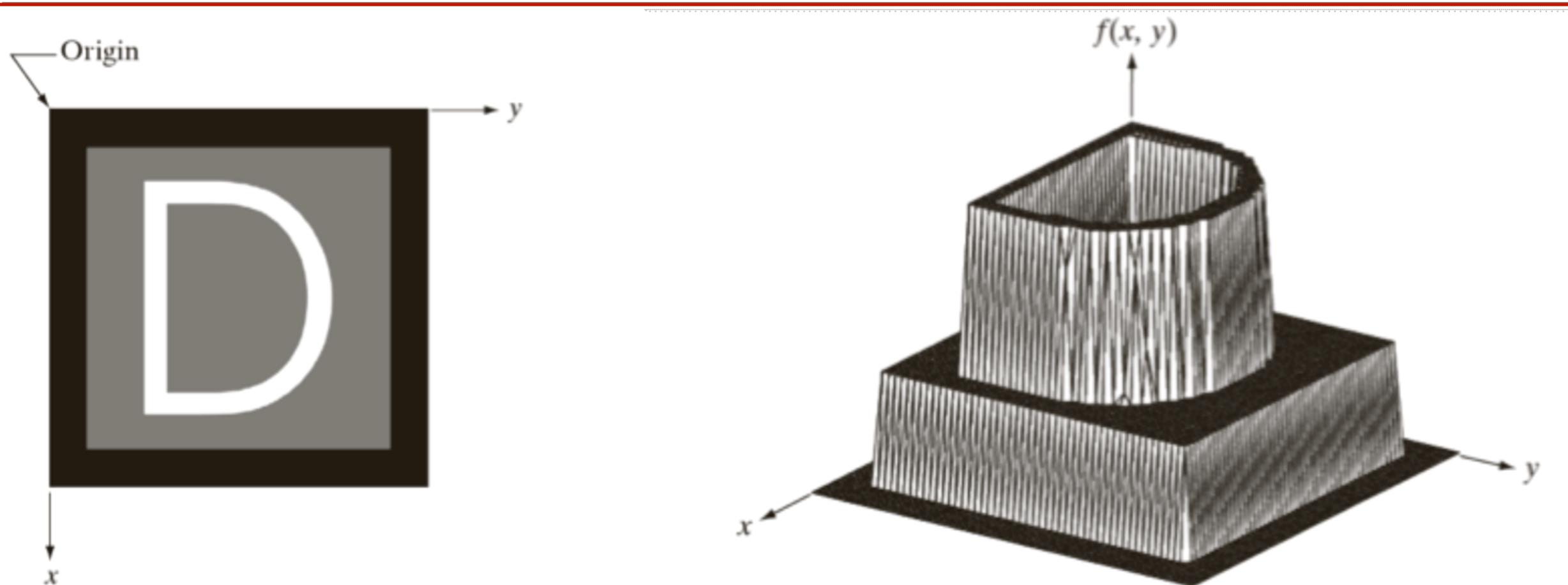
- The range $[L_{min}, L_{max}]$ is called *Gray Scale* range
- In practice, the interval starts from “0” to a maximum value “L”
 - $I = 0$ is “black” / total absorption
 - $I = L$ is “white” / total reflectance

Continuous Representation of Images

Continuous Representation of Images



Continuous Representation of Images



Continuous Representation of Images

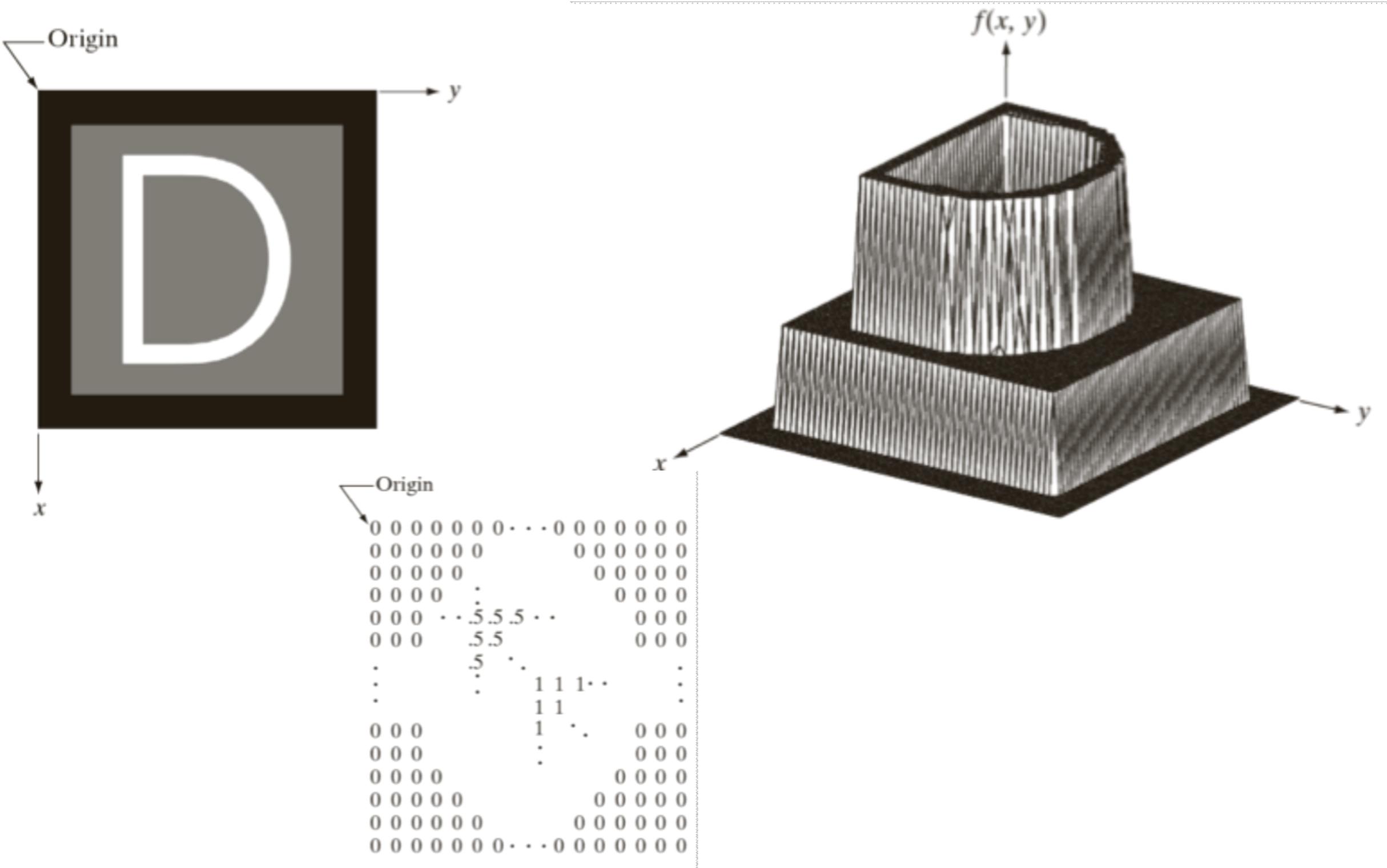


Image courtesy “Digital Image Processing,” by Gonzalez & Woods, 3rd ed.

Sampling & Quantization

“Welcome to the Digital World”

- Representing the image intensities in a computing device
- Digitizing in spatial and energy domains
 - Spatial digitization : Image Sampling
 - Energy digitization : Gray Level Quantization

Digital Image Representation

- Sample at regular intervals in the X and Y axes
- N = row samples, and M = column samples
- I = N x M array of intensity values

$$f(x, y) = \begin{bmatrix} f(0, 0) & f(0, 1) & \dots & f(0, M - 1) \\ f(1, 0) & f(1, 1) & \dots & f(1, M - 1) \\ \dots & \dots & \dots & \dots \\ f(N - 1, 0) & f(N - 1, 1) & \dots & f(N - 1, M - 1) \end{bmatrix}$$

Mathematical Model of a Digital Image

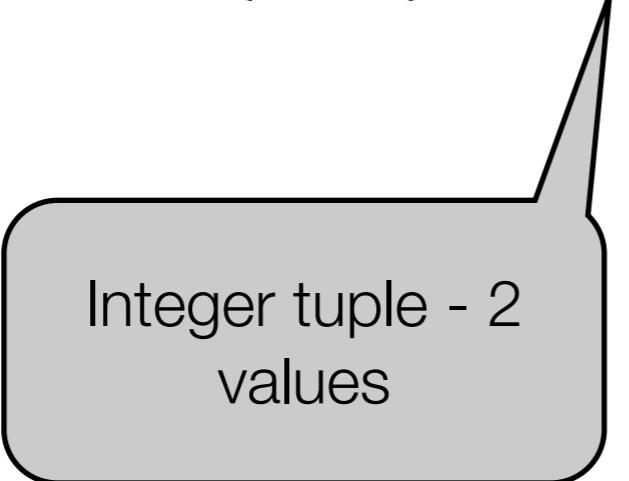
- 2D light intensity function

$$f(x, y) : \mathbb{Z} * \mathbb{Z} \rightarrow \mathbb{R}$$

Mathematical Model of a Digital Image

- 2D light intensity function

$$f(x, y) : \mathbb{Z} * \mathbb{Z} \rightarrow \mathbb{R}$$



Integer tuple - 2 values

Mathematical Model of a Digital Image

- 2D light intensity function

$$f(x, y) : \mathbb{Z} * \mathbb{Z} \rightarrow \mathbb{R}$$

A diagram illustrating a 2D light intensity function. At the top, the function is defined as $f(x, y) : \mathbb{Z} * \mathbb{Z} \rightarrow \mathbb{R}$. Below the function, two rounded rectangular boxes represent the domain and codomain. The left box, labeled "Integer tuple - 2 values", has a curved arrow pointing upwards towards the function. The right box, labeled "Real values", has a curved arrow pointing downwards from the function.

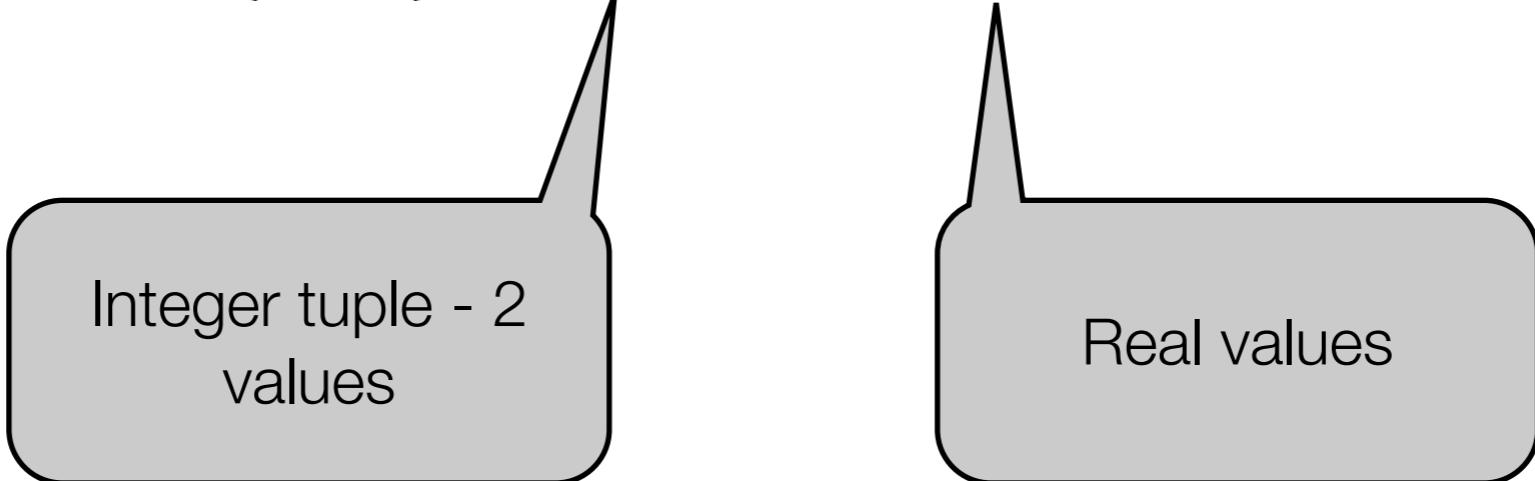
Integer tuple - 2 values

Real values

Mathematical Model of a Digital Image

- 2D light intensity function

$$f(x, y) : \mathbb{Z} * \mathbb{Z} \rightarrow \mathbb{R}$$



Integer tuple - 2
values

Real values

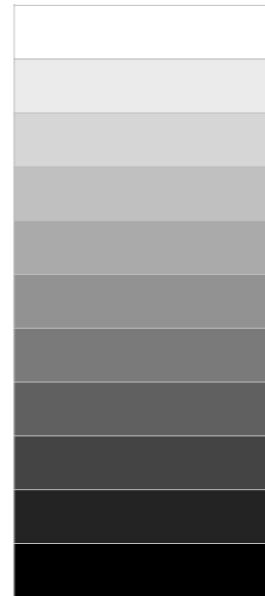
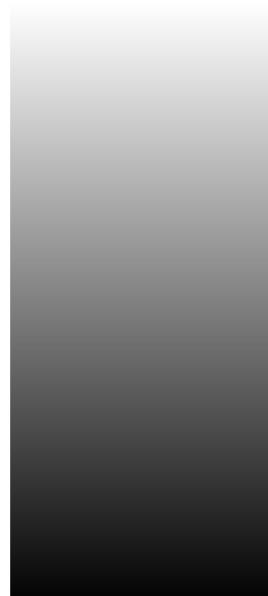
$$f(3, 6) = 3.56$$

Quantization

- Quantum => discrete packets
- Represent the continuous grayscale image with the help of discrete values
- Lossy !!

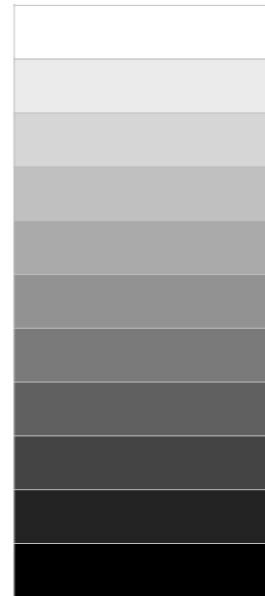
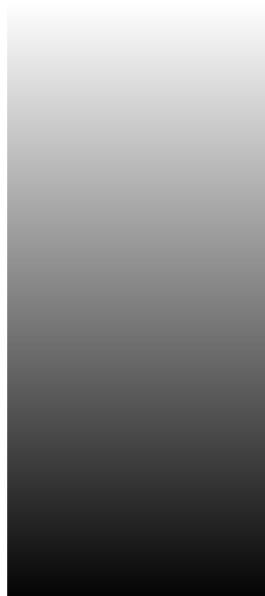
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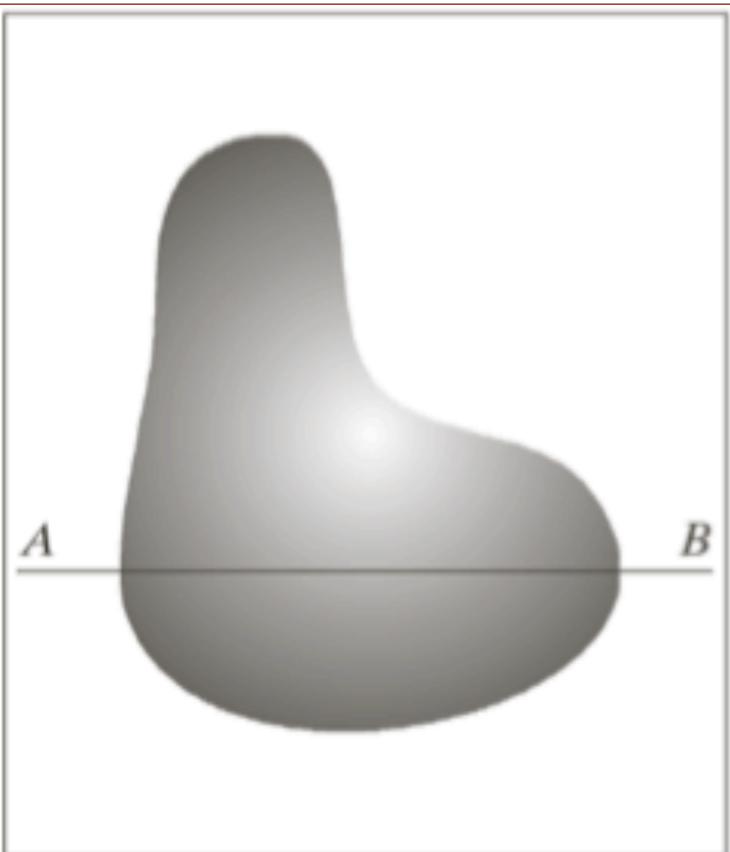
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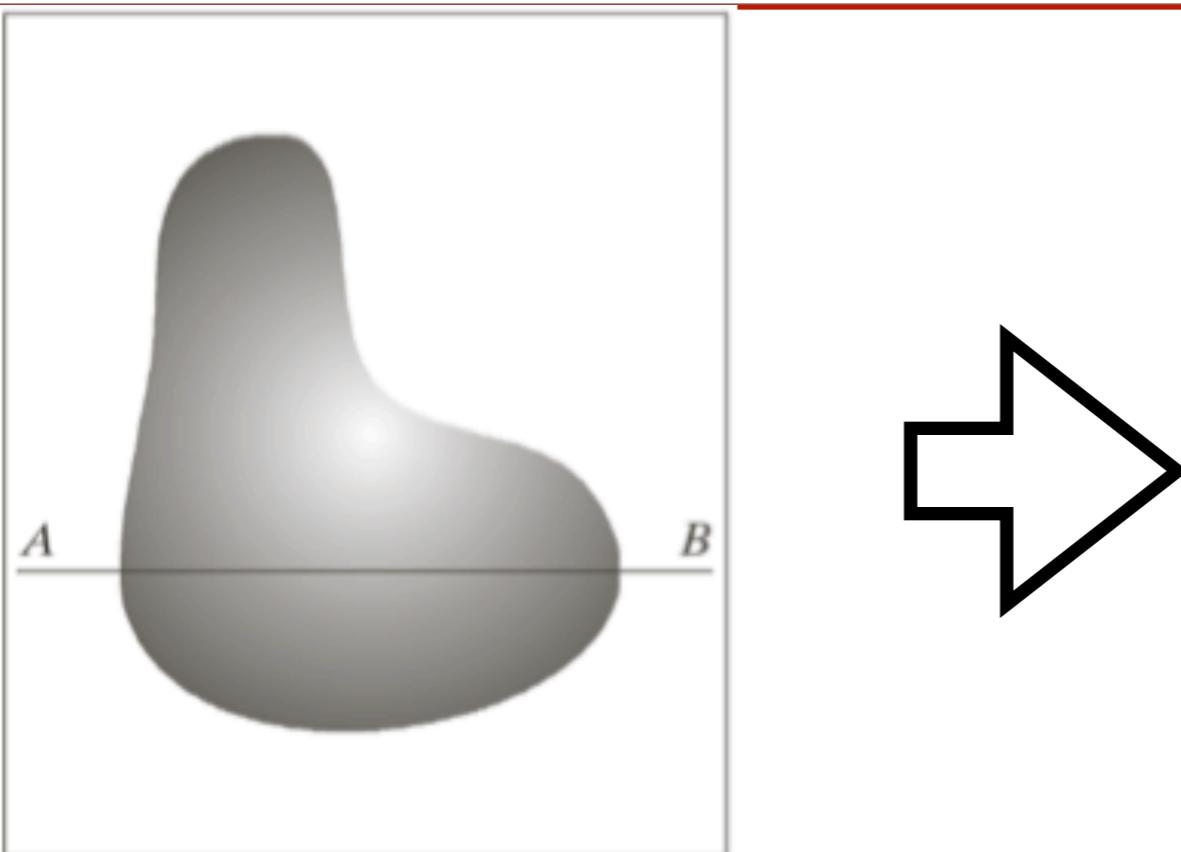


G, number of gray levels

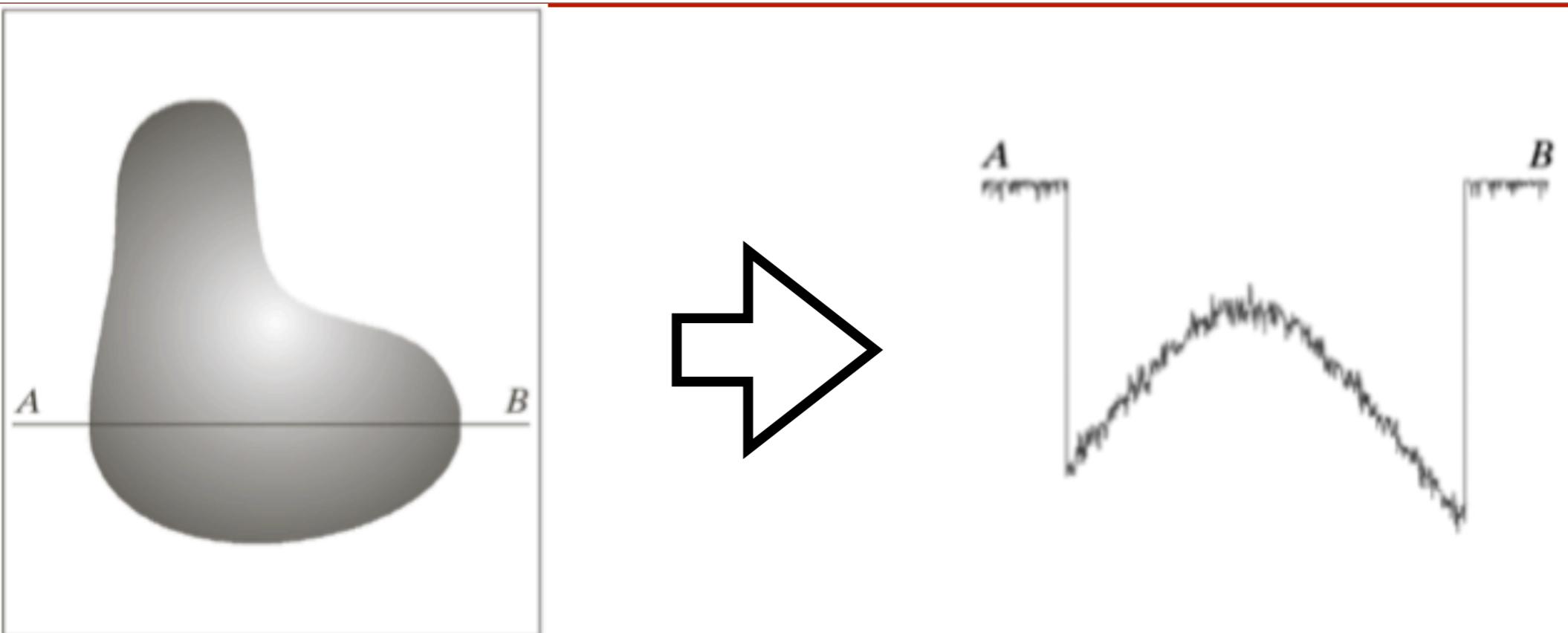
From Analog to Digital



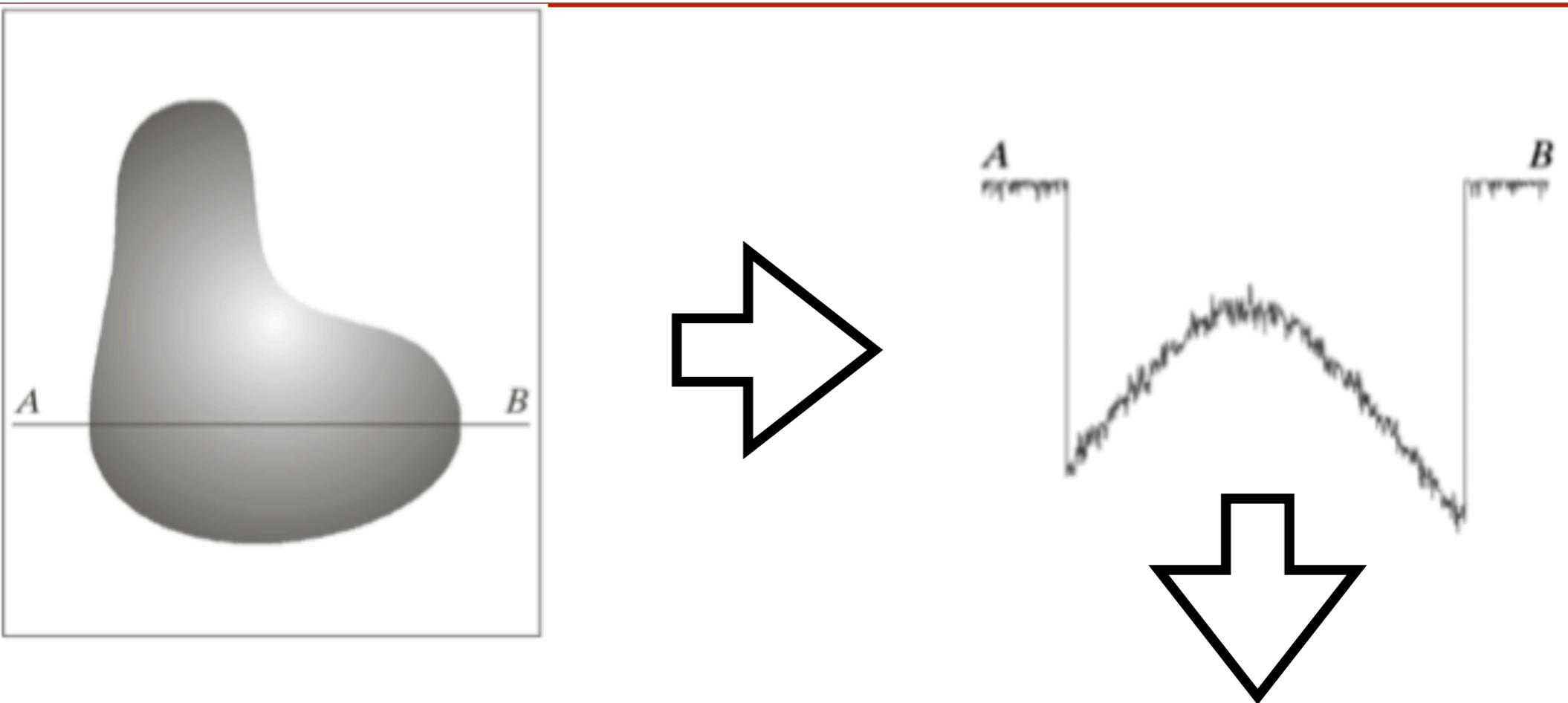
From Analog to Digital



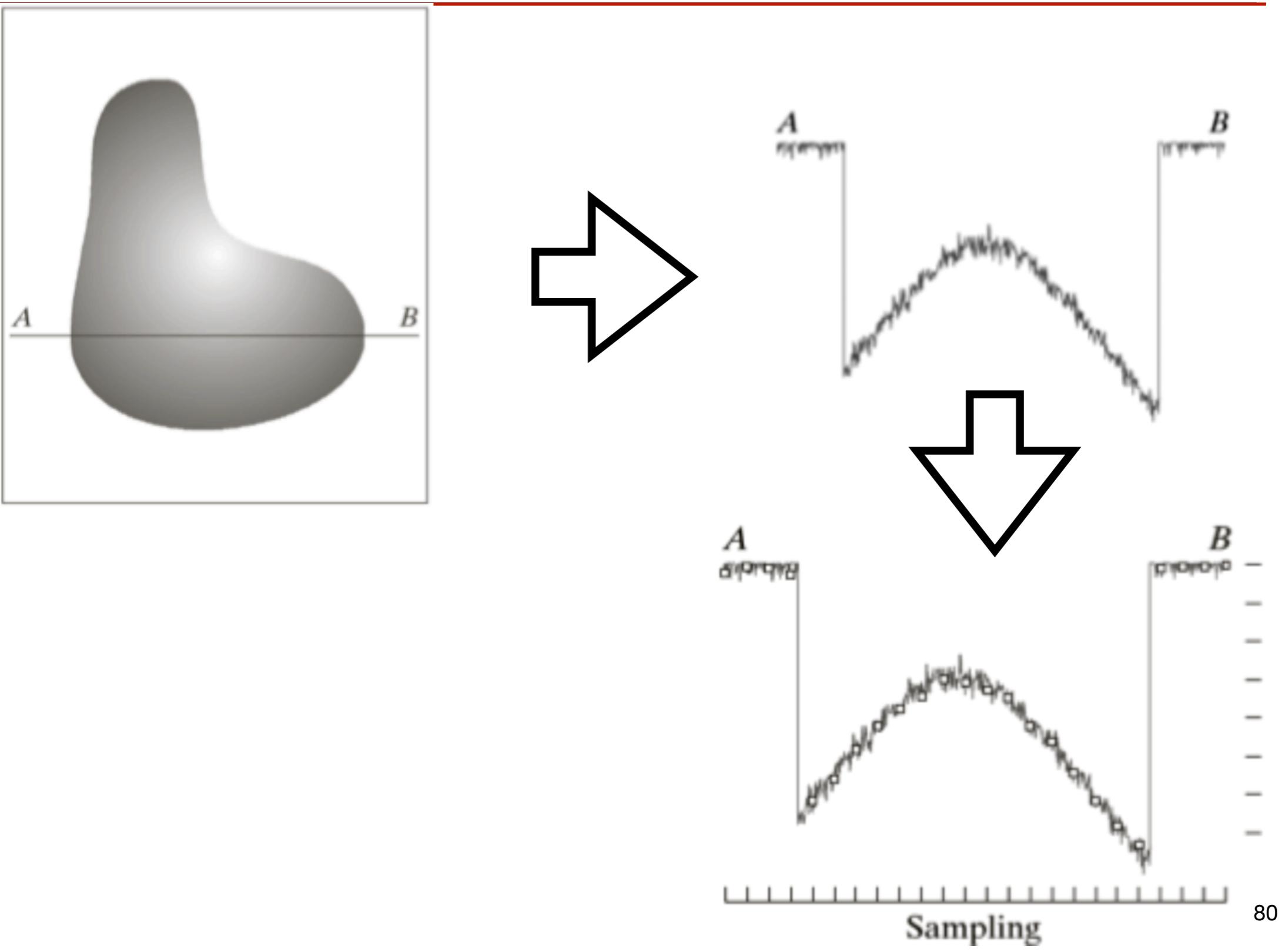
From Analog to Digital



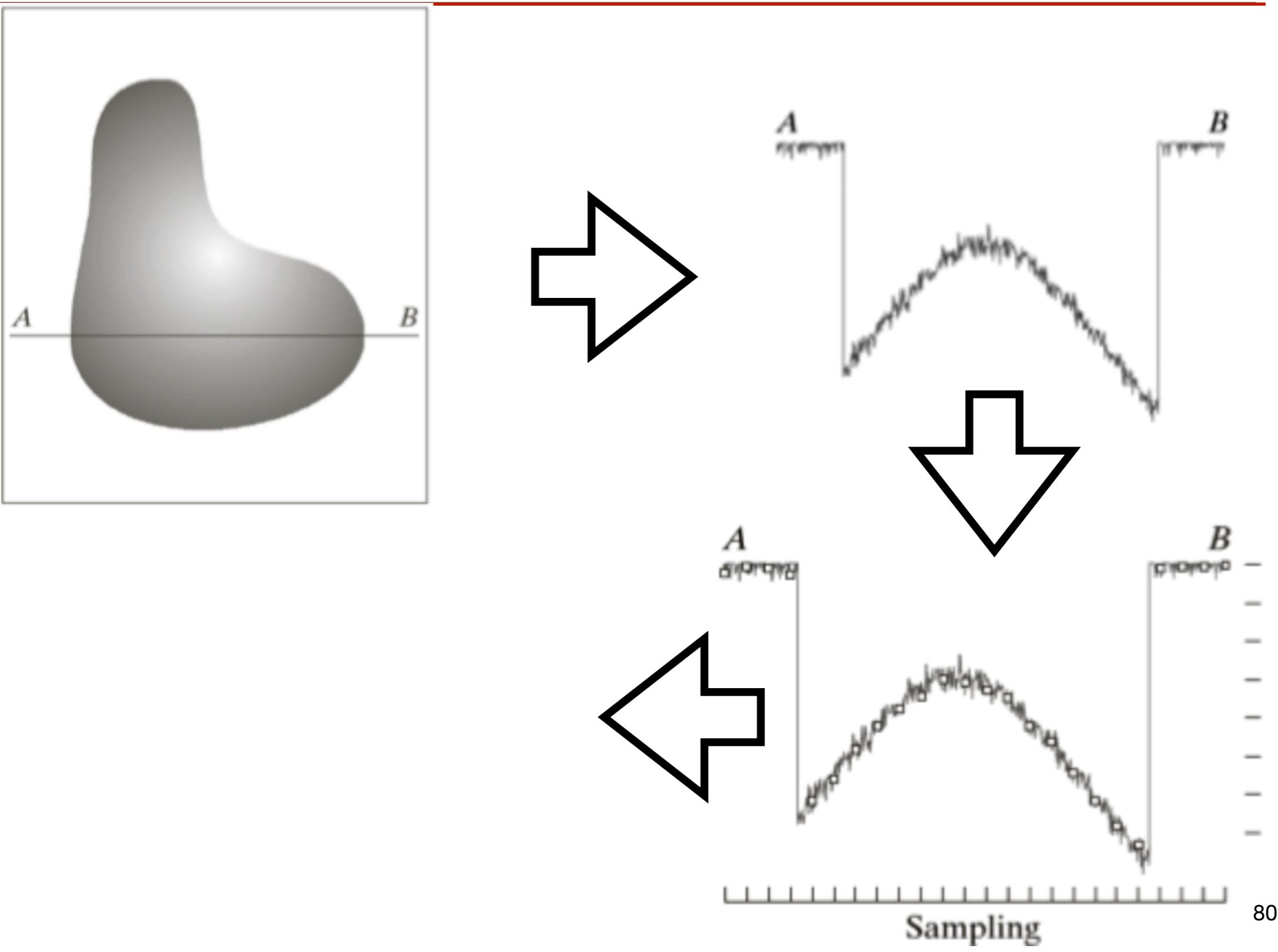
From Analog to Digital



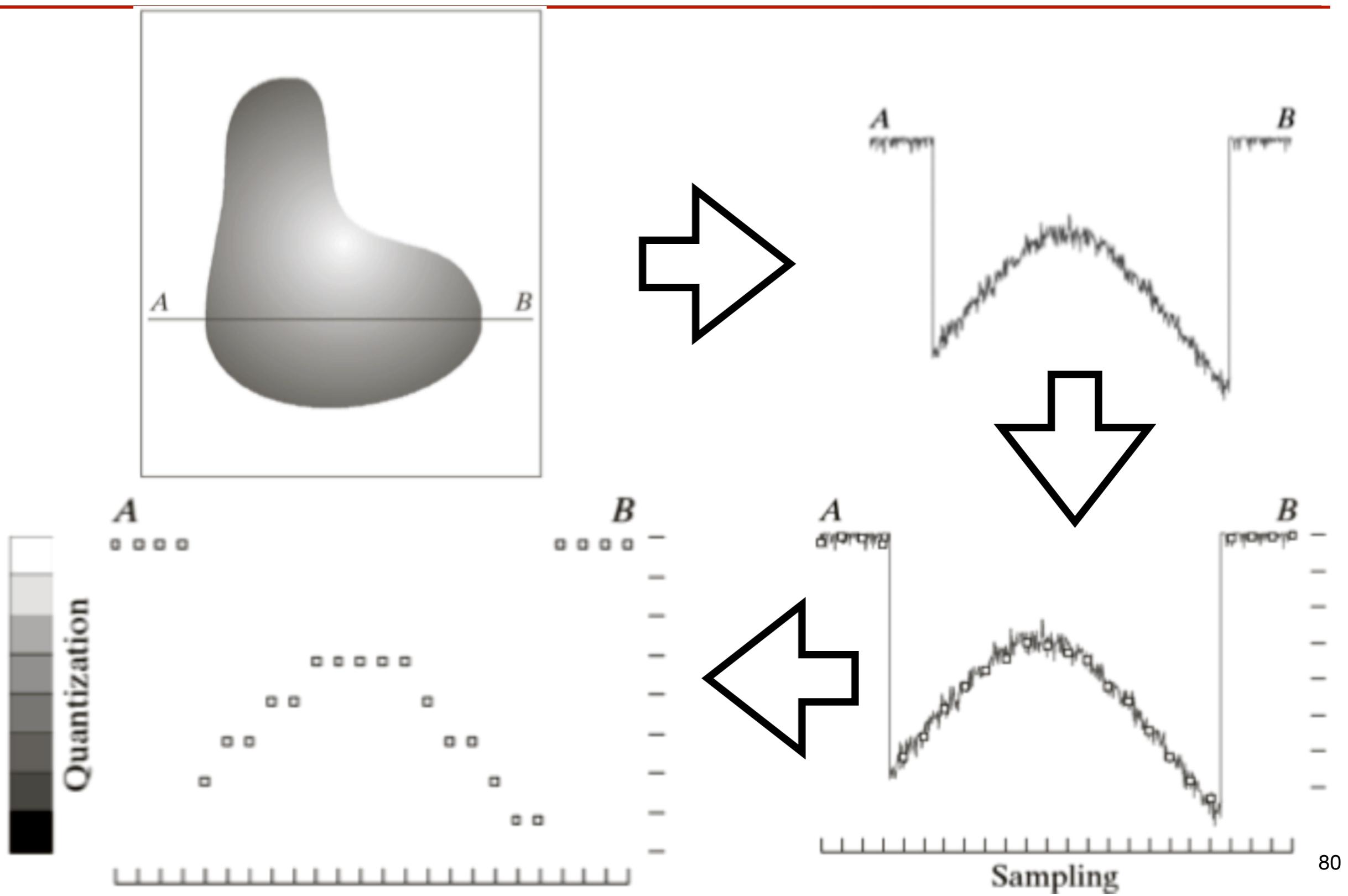
From Analog to Digital



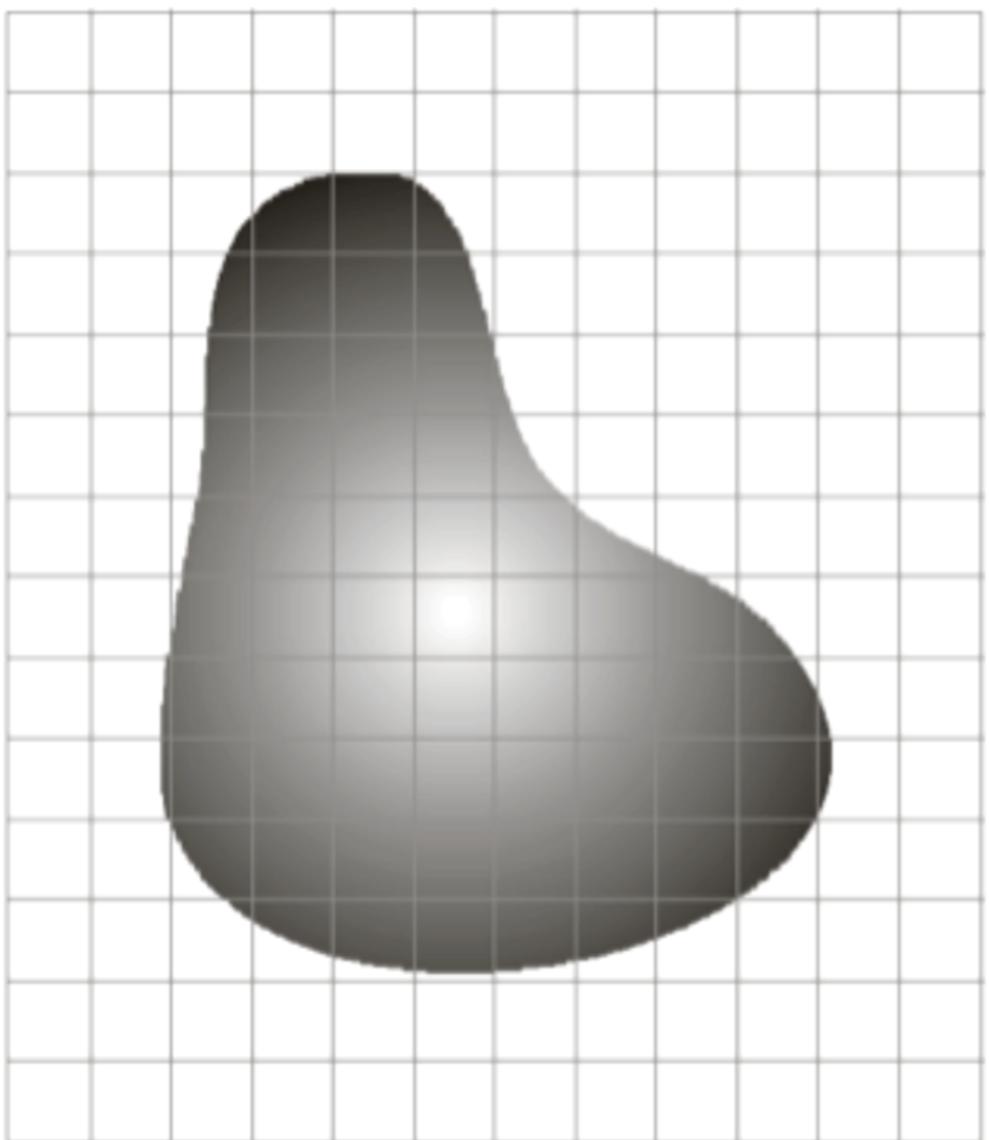
From Analog to Digital



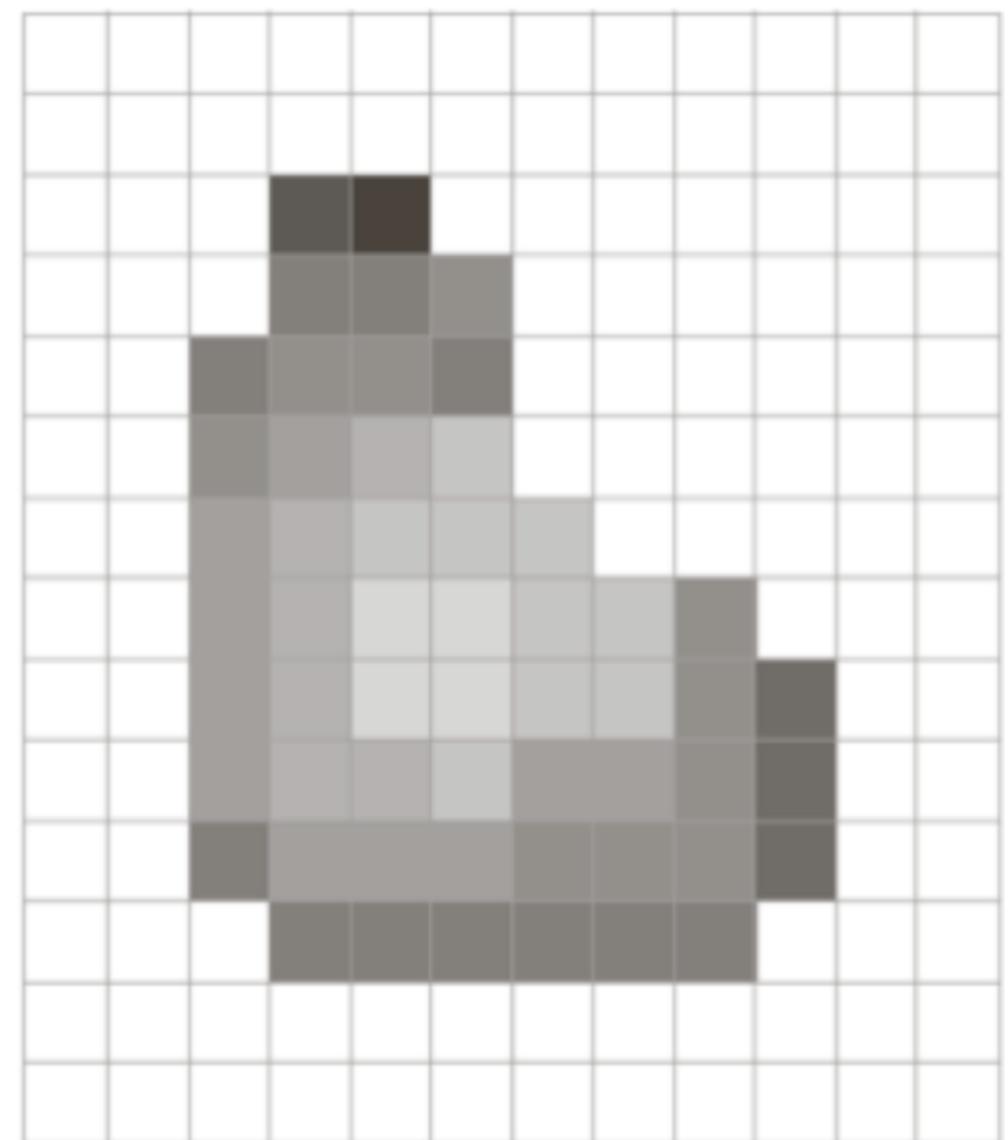
From Analog to Digital



From Analog to Digital (2)



Continuous input on the sensor



Result of Image Sampling and Quantization

Image Resolution

$$G = 2^k$$

$$N = \text{rows}$$

$$M = \text{columns}$$

Number of bits to store the image

$$b = N * M * k$$

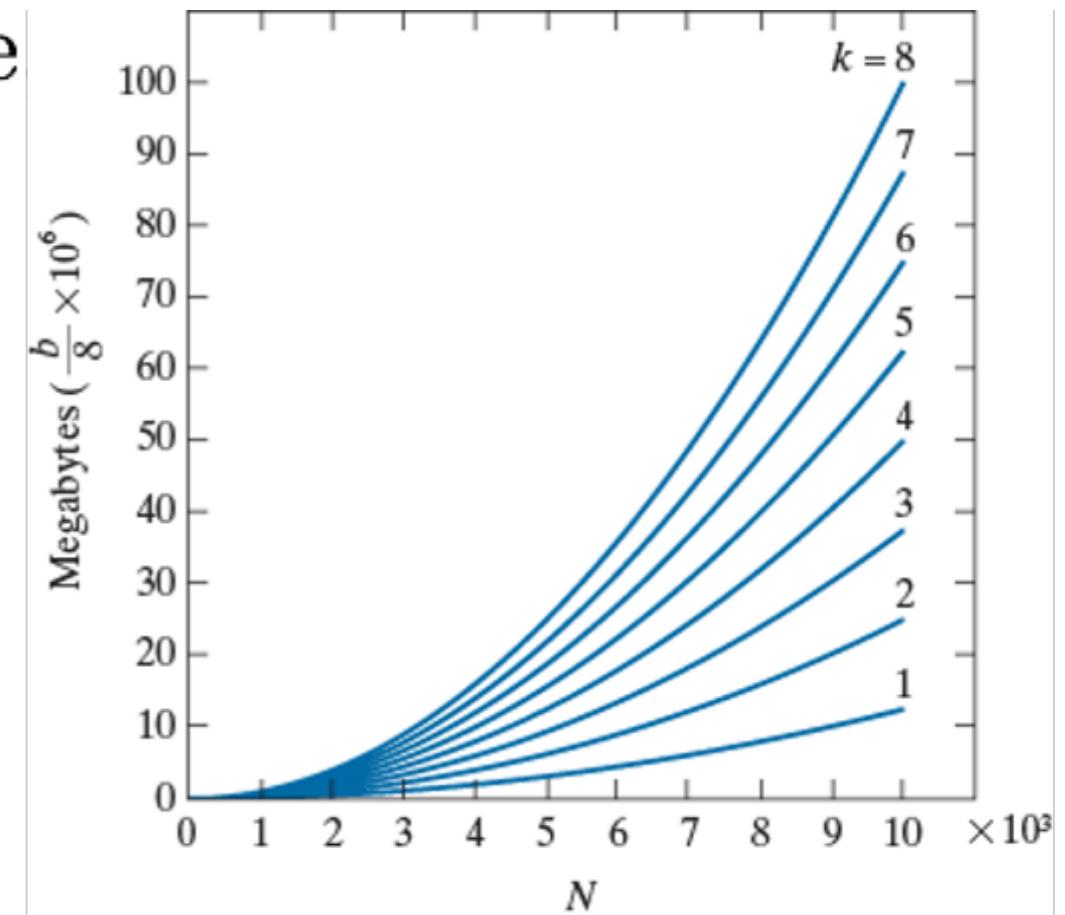


Image Resolution

$$G = 2^k$$

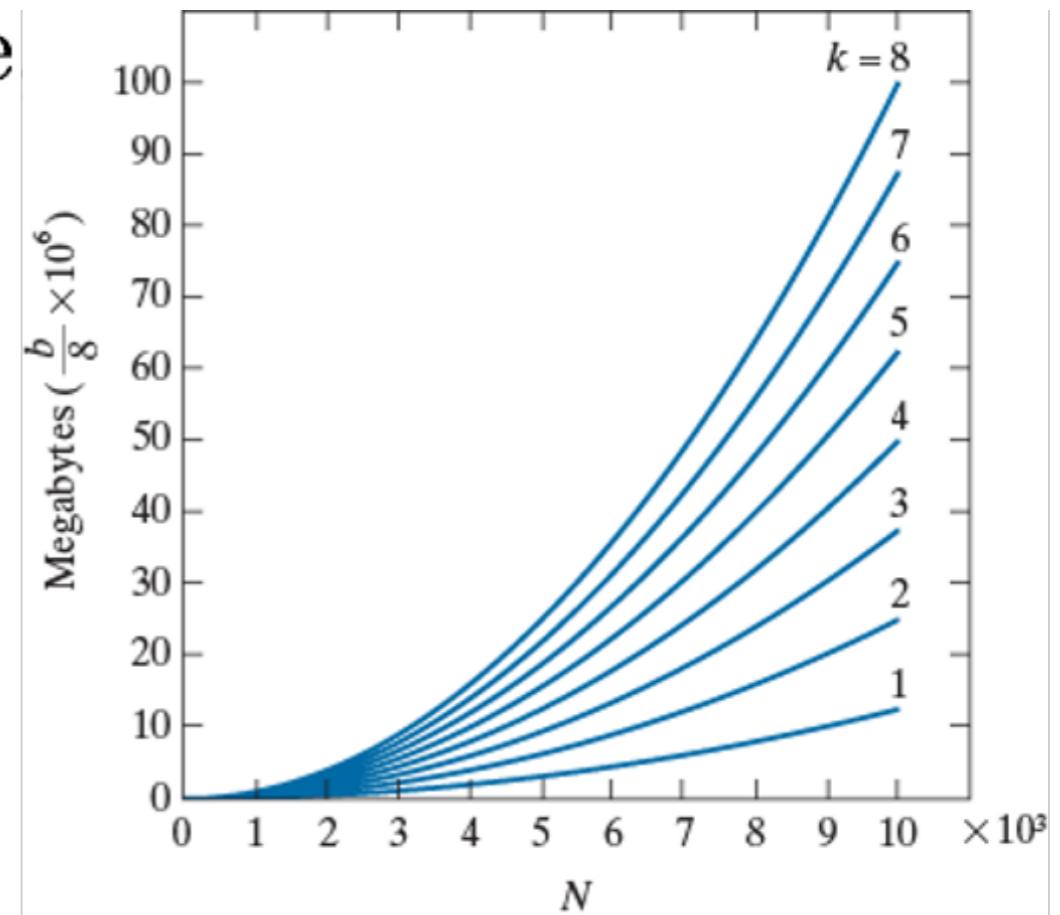
$N = \text{rows}$

$M = \text{columns}$

Number of bits to store the image

$$b = N * M * k$$

- How many megapixels on an analog media?



Acquisition Artifacts - Noise & Saturation



One digital value represents a range of continuous values

How many levels of Quantization are enough?

How many levels of Quantization are enough?



256

How many levels of Quantization are enough?



256



128

How many levels of Quantization are enough?



256

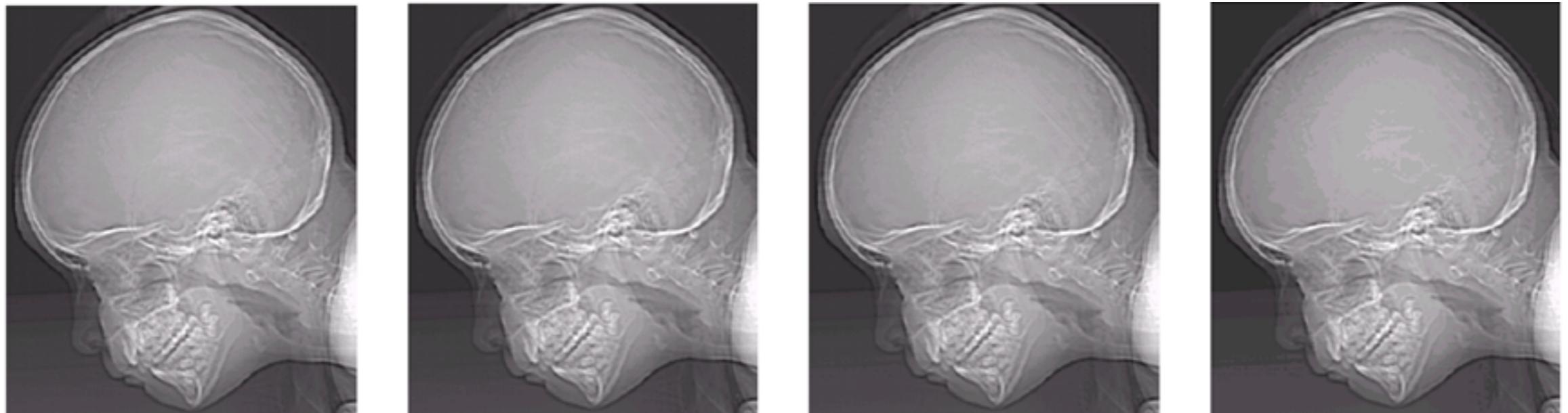


128



64

How many levels of Quantization are enough?



256

128

64

32

How many levels of Quantization are enough?



256



128



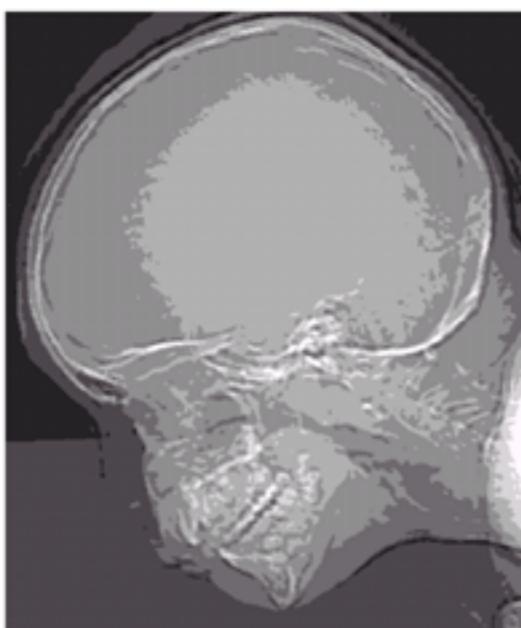
64



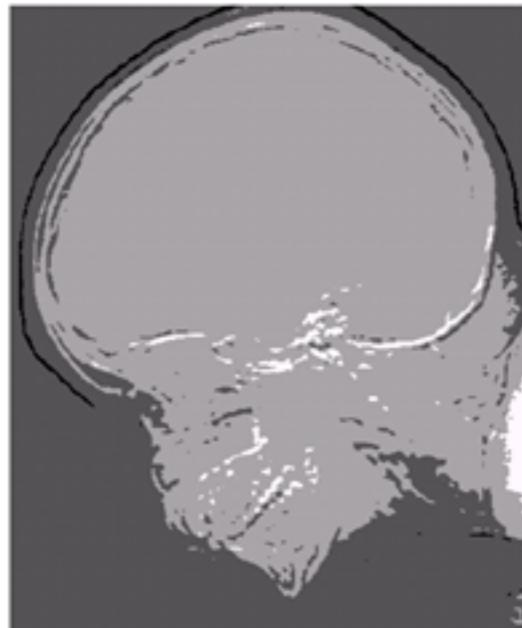
32



16



8



4



2

How many Pixels are enough?



100%

How many Pixels are enough?



100%

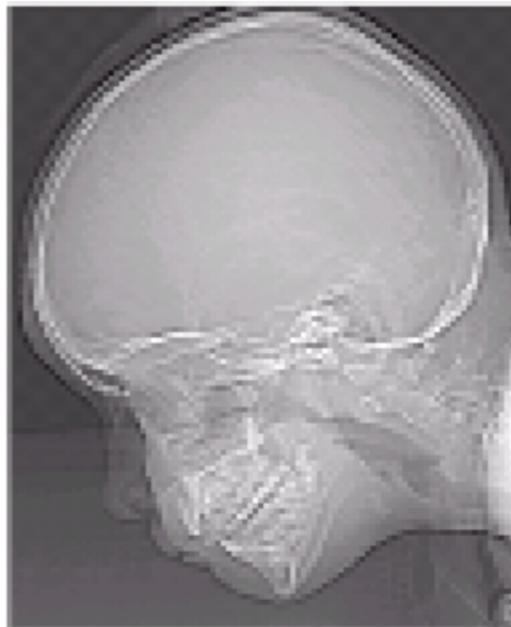


50%

How many Pixels are enough?



100%



50%



25%

How many Pixels are enough?



100%



50%



25%



10%

Non-uniform Sampling & Quantization

- Sample more points in regions of details

- Change of intensity level

- Edges



Low-detail



Mid-detail



High-detail

Non-uniform sampling - low detail image

Non-uniform sampling - low detail image



Input Image

Non-uniform sampling - low detail image



Input Image



Non uniform
Sampling

Non-uniform sampling - low detail image



Input Image



Non uniform
Sampling



Output Image

Non-uniform sampling - low detail image



Input Image



Non uniform
Sampling



Output Image

Difference
image



Sampling with Details

- Not feasible for **dense** images - **crowd** example
 - Too much detail/edge information to encode
- Requires extra storage
- Non-uniform quantization
 - Use more bits for frequently occurring values
 - Huffman encoding

Summary

- Digital Image Processing - Steps & Components
 - Image Operations (Image Processing)
 - Image Analysis (Computer Vision)
- Real-world images are 2D continuous signals
- Digitization Process
 - Sampling - choosing discrete points in the Spatial Domain
 - Quantization - ‘snapping’ to specific energy values in Image Intensity Range

Thank You.