view_frames Result Recorded at time: 1613888845.792 SimpleFlight Broadcaster: /airsim_node Average rate: 10000.000 Hz Average rate: 2.390 Hz Average rate: 100.204 Hz Average rate: 4.768 Hz Average rate: 4.768 Hz Average rate: 2.390 Hz Average rate: 2.415 Hz Most recent transform: 0.000 (1613888845.792 sec old) \ Most recent Buffer length: 4.920 sec Buffer length: 0.000 sec Buffer length: 4.614 sec Buffer length: 4.602 sec Buffer length: 4.614 sec Buffer length: 4.602 sec Buffer length: 4.140 sec SimpleFlight/odom_local_ned front_left_custom_body front_left_custom_optical front_center_custom_optical front_right_custom_body front_right_custom_optical front_center_custom_body Broadcaster: /airsim_node Broadcaster: /tf1 Average rate: 10000.000 Hz Average rate: 10.199 Hz Most recent transform: 1613888845.859 (-0.066 sec old) Most recent transform: 0.000 (1613888845.792 sec old) Most recent transform: 0.000 (1613888845.792 sec old) Most recent transform: 0.000 (1613888845.792 sec old) Most 1 recent transform: 0.000 (1613888845.792 sec old) Most recent transform: 0.000 (1613888845.792 sec old) | Most recent transform: 0.000 (1613888845.792 sec old) | Most recent transform: 0.000 (1613888845.792 sec old) | Buffer length: 0.000 sec Buffer length: 4.805 sec front_right_custom_body/static SimpleFlight/LidarCustom base_link front_left_custom_optical/static front_right_custom_optical/static front_center_custom_optical/static front_left_custom_body/static Broadcaster: /robot_state_publisher Broadcaster: /robot_state_publisher Average rate: 10000.000 Hz Average rate: 10000.000 Hz Buffer length: 0.000 sec Buffer length: 0.000 sec camera_link sonar_link Broadcaster: /robot state publisher Broadcaster: /robot_state_publisher Average rate: 10000.000 Hz Average rate: 10000.000 Hz Buffer length: 0.000 sec Buffer length: 0.000 sec camera_depth_frame camera_rgb_frame Broadcaster: /robot_state_publisher Broadcaster: /robot_state_publisher Average rate: 10000.000 Hz Average rate: 10000.000 Hz Most recent transform: 0.000 (1613888845.792 sec old) Most recent transform: 0.000 (1613888845.792 sec old) Buffer length: 0.000 sec Buffer length: 0.000 sec camera_rgb_optical_frame camera_depth_optical_frame

world_ned

front_center_custom_body/static

Broadcaster: /tf4

Average rate: 10.198 Hz

Buffer length: 4.805 sec

Broadcaster: /ned_to_enu_pub

Average rate: 10.198 Hz

Most recent transform: 1613888845.832 (-0.039 sec old)

Broadcaster: /tf0

Most recent transform: 1613888845.859 (-0.067 sec old)

Average rate: 10.198 Hz

Buffer length: 4.805 sec

openni_rgb_optical_frame

Buffer length: 4.805 sec

world_enu

world

Broadcaster: /tf2

Average rate: 20.184 Hz

Buffer length: 4.905 sec

Broadcaster: /tf3

Average rate: 10.195 Hz

Most recent transform: 1613888845.880 (-0.088 sec old)

Buffer length: 4.905 sec

base_footprint

base_stabilized

Broadcaster: /airsim_node

transform: 1613888845.393 (0.400 sec old)

Average rate: 2.415 Hz

Buffer length: 4.140 sec