

Shortest Paths 1



Paths in graphs

Consider a digraph $G = (V, E)$ with edge-weight function $w : E \rightarrow \mathbb{R}$. The **weight** of path $p = v_1 \rightarrow v_2 \rightarrow \cdots \rightarrow v_k$ is defined to be

$$w(p) = \sum_{i=1}^{k-1} w(v_i, v_{i+1}).$$

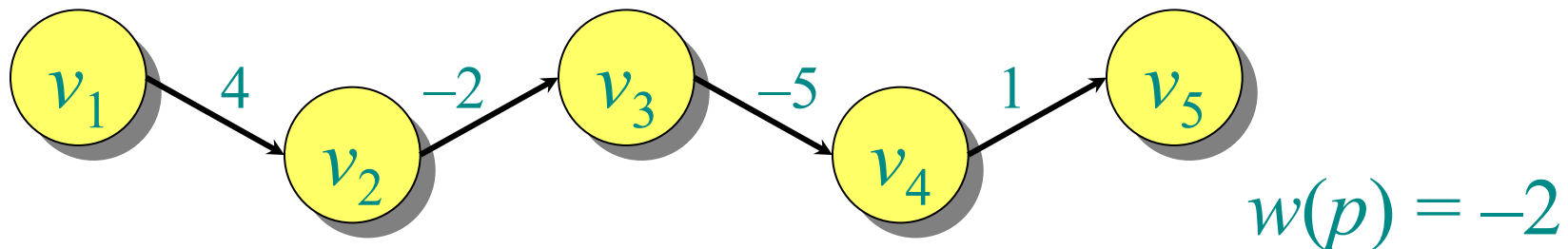


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Example:





Shortest paths

A *shortest path* from u to v is a path of minimum weight from u to v . The *shortest-path weight* from u to v is defined as

$$\delta(u, v) = \min\{w(p) : p \text{ is a path from } u \text{ to } v\}.$$

Note: $\delta(u, v) = \infty$ if no path from u to v exists.



Optimal substructure

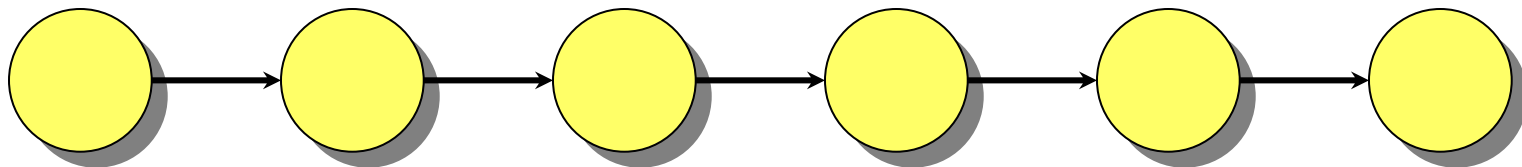
Theorem. A subpath of a shortest path is a shortest path.

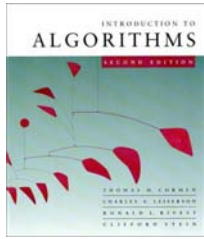


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Proof. Cut and paste:

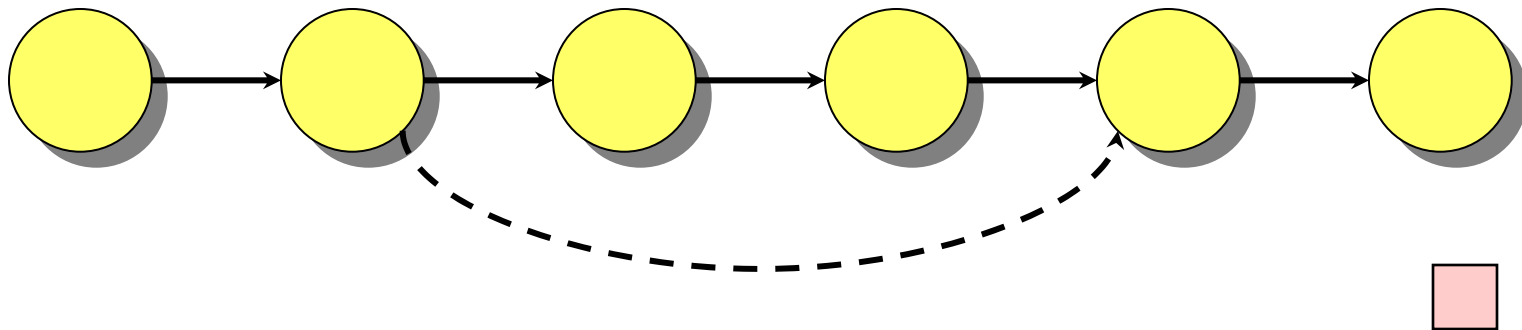


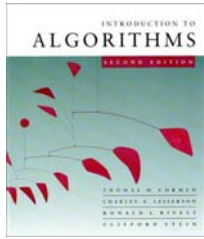


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Triangle inequality

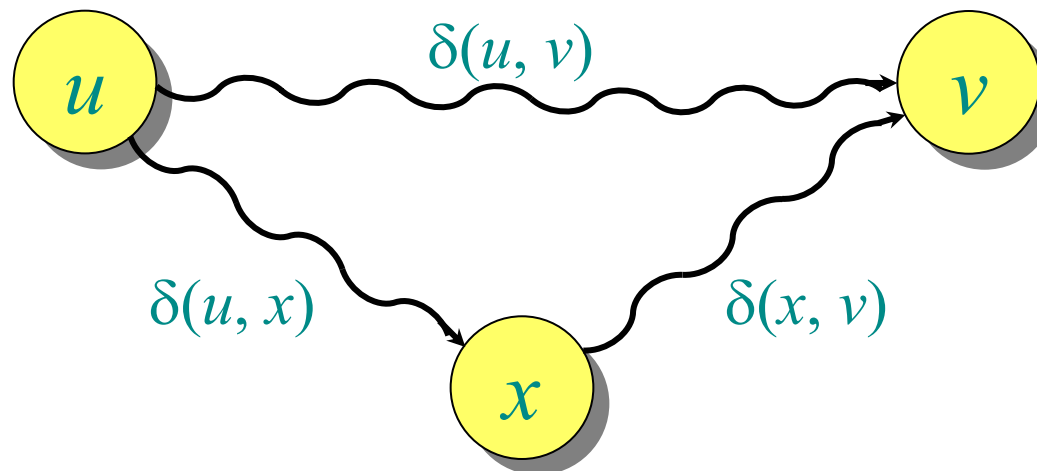
Theorem. For all $u, v, x \in V$, we have
$$\delta(u, v) \leq \delta(u, x) + \delta(x, v).$$



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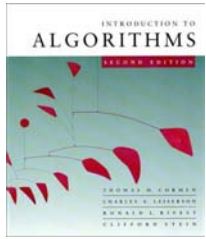
Proof.





Well-definedness of shortest paths

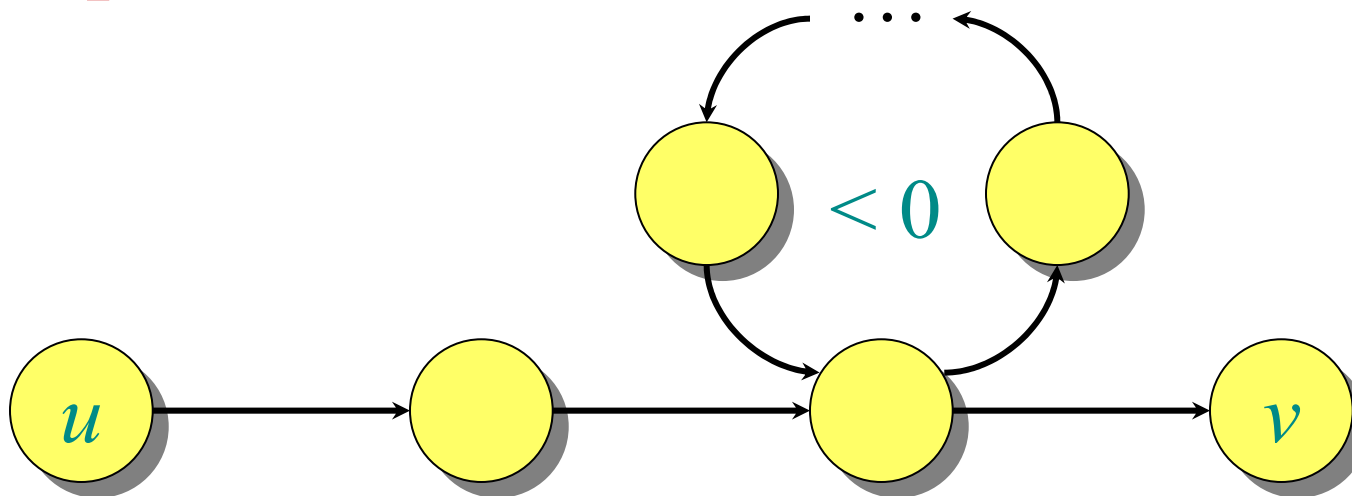
If a graph G contains a negative-weight cycle, then some shortest paths may not exist.



Well-definedness of shortest paths

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Example:





Single-source shortest paths

Problem. From a given source vertex $s \in V$, find the shortest-path weights $\delta(s, v)$ for all $v \in V$.

If all edge weights $w(u, v)$ are *nonnegative*, all shortest-path weights must exist.

IDEA: Greedy.

1. Maintain a set S of vertices whose shortest-path distances from s are known.
2. At each step add to S the vertex $v \in V - S$ whose distance estimate from s is minimal.
3. Update the distance estimates of vertices adjacent to v .



Dijkstra's algorithm

$d[s] \leftarrow 0$

for each $v \in V - \{s\}$

do $d[v] \leftarrow \infty$

$S \leftarrow \emptyset$

$Q \leftarrow V$ $\blacktriangleleft Q$ is a priority queue maintaining $V - S$



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while $Q \neq \emptyset$

do $u \leftarrow \text{EXTRACT-MIN}(Q)$

$S \leftarrow S \cup \{u\}$

for each $v \in \text{Adj}[u]$

do if $d[v] > d[u] + w(u, v)$

then $d[v] \leftarrow d[u] + w(u, v)$



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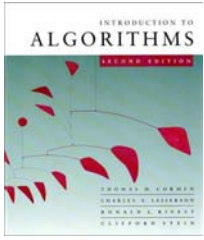
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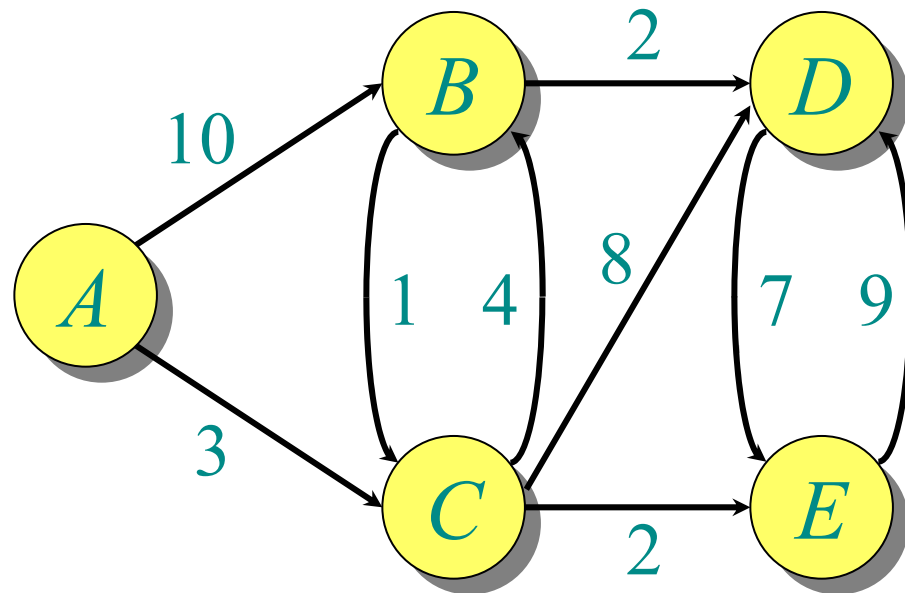
do if $d[v] > d[u] + w(u, v)$ *relaxation*
then $d[v] \leftarrow d[u] + w(u, v)$ *step*

Implicit DECREASE-KEY



Example of Dijkstra's algorithm

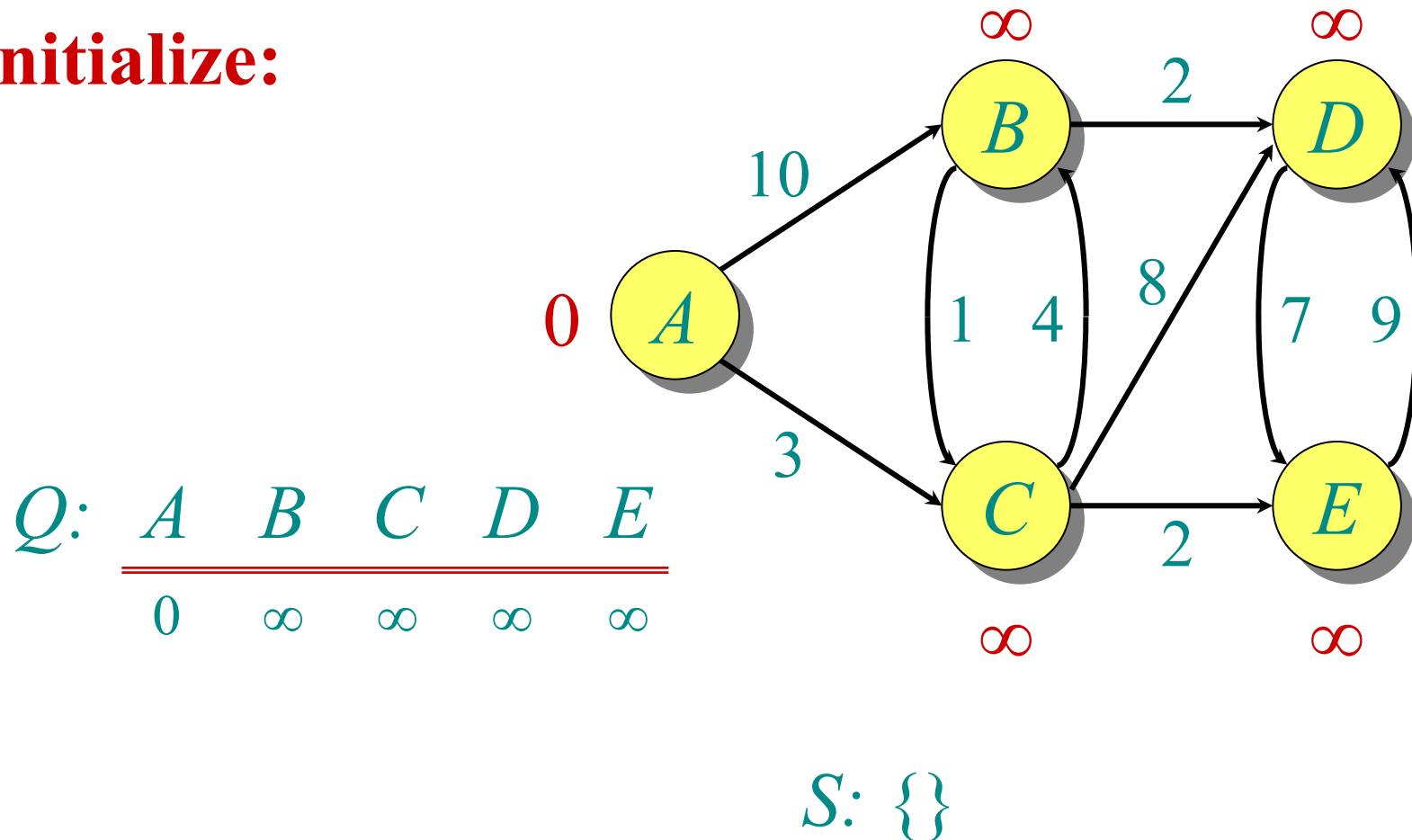
**Graph with
nonnegative
edge weights:**





Example of Dijkstra's algorithm

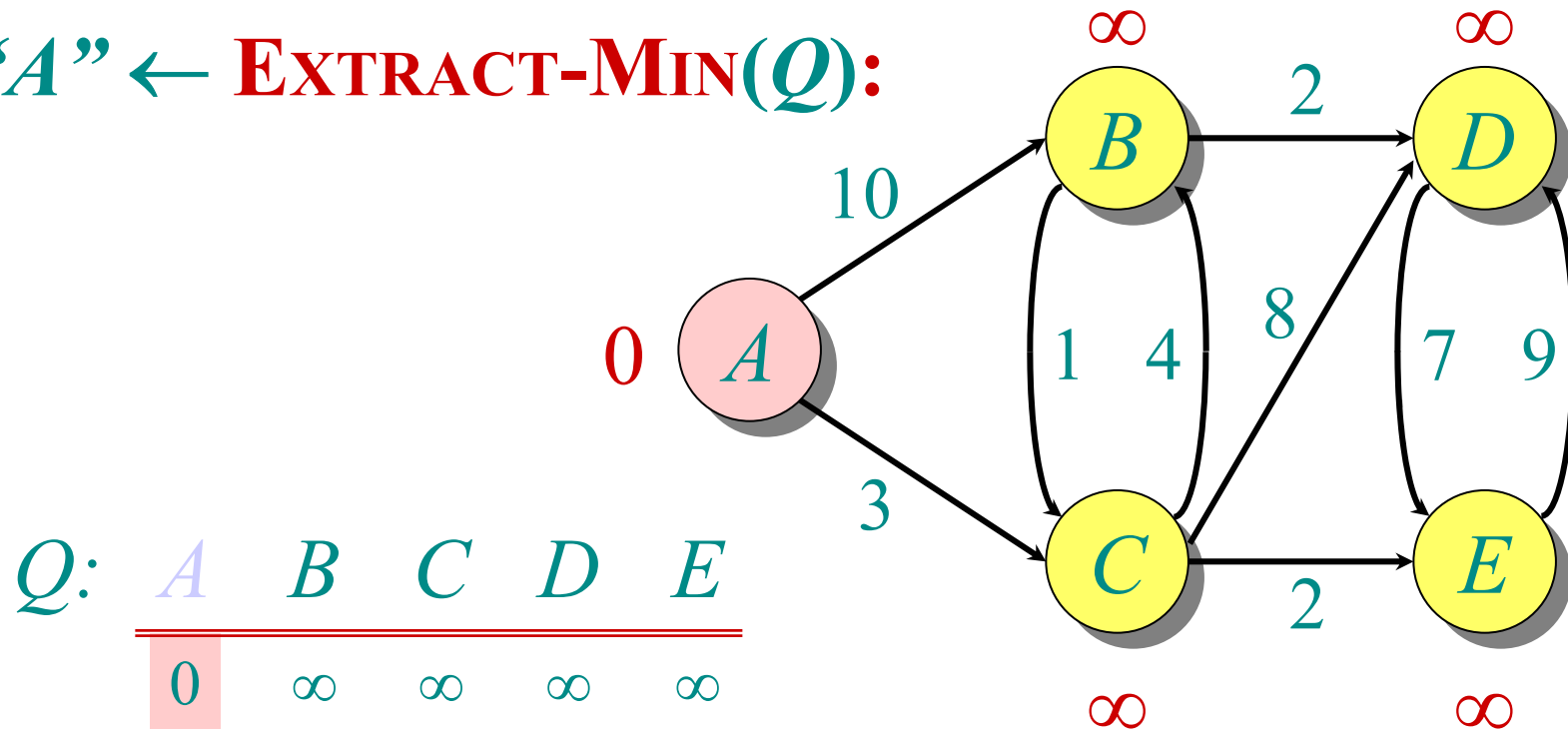
Initialize:





Example of Dijkstra's algorithm

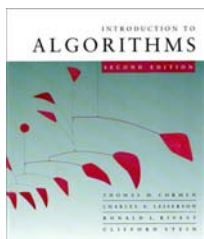
“A” \leftarrow **EXTRACT-MIN**(Q):



Q :

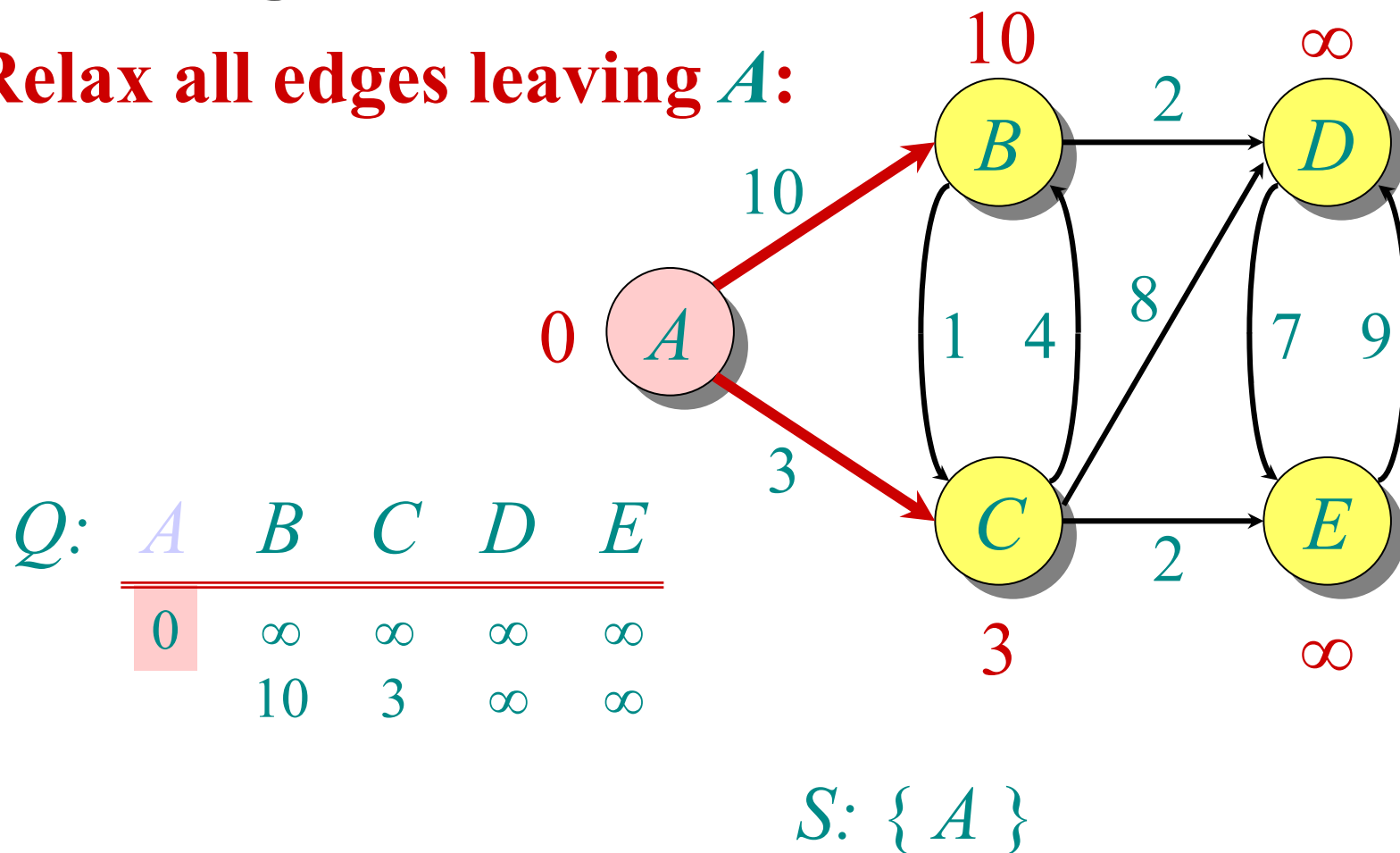
A	B	C	D	E
0	∞	∞	∞	∞

S : { A }



Example of Dijkstra's algorithm

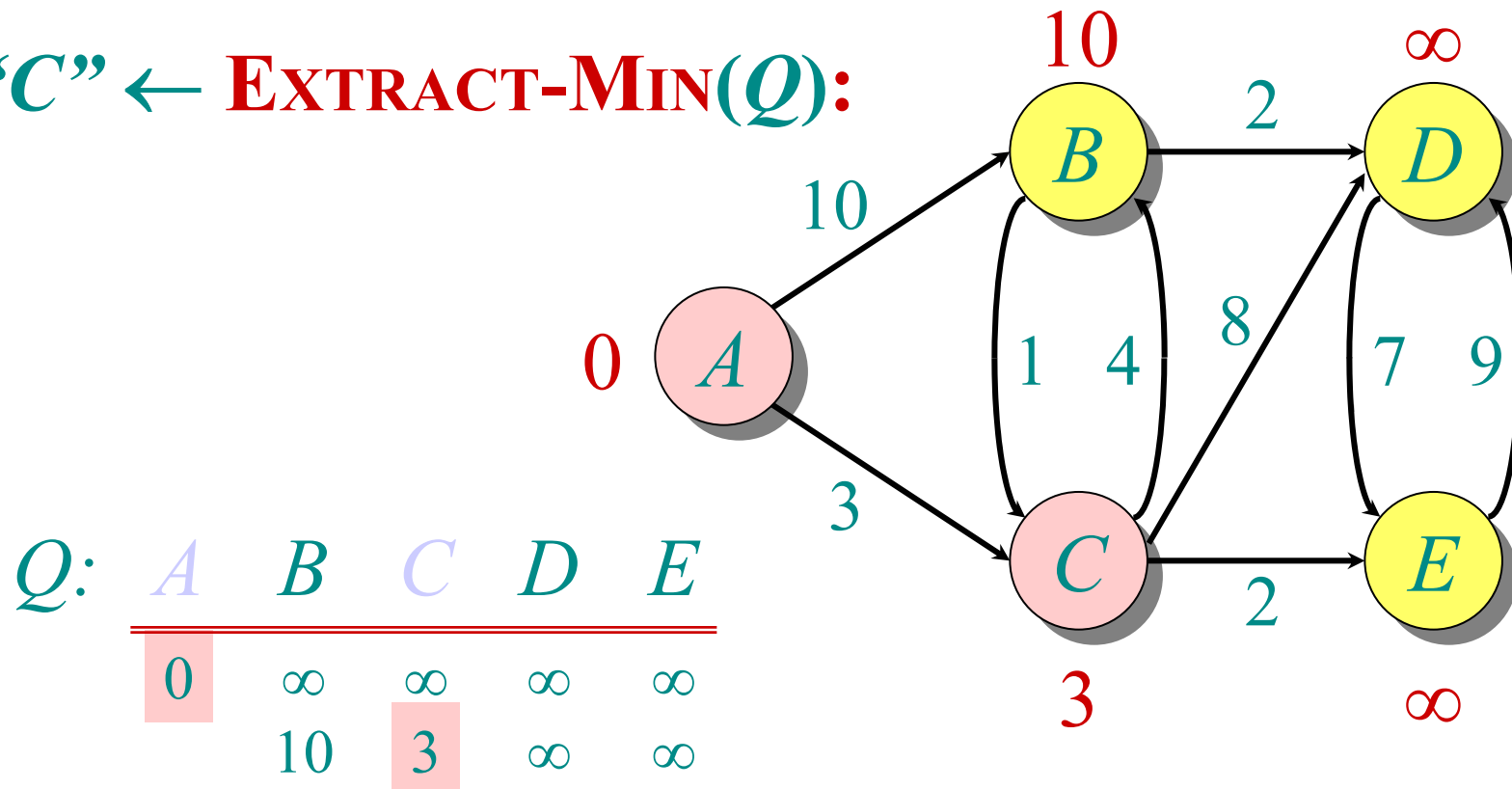
Relax all edges leaving A :





Example of Dijkstra's algorithm

“C” ← **EXTRACT-MIN**(Q):

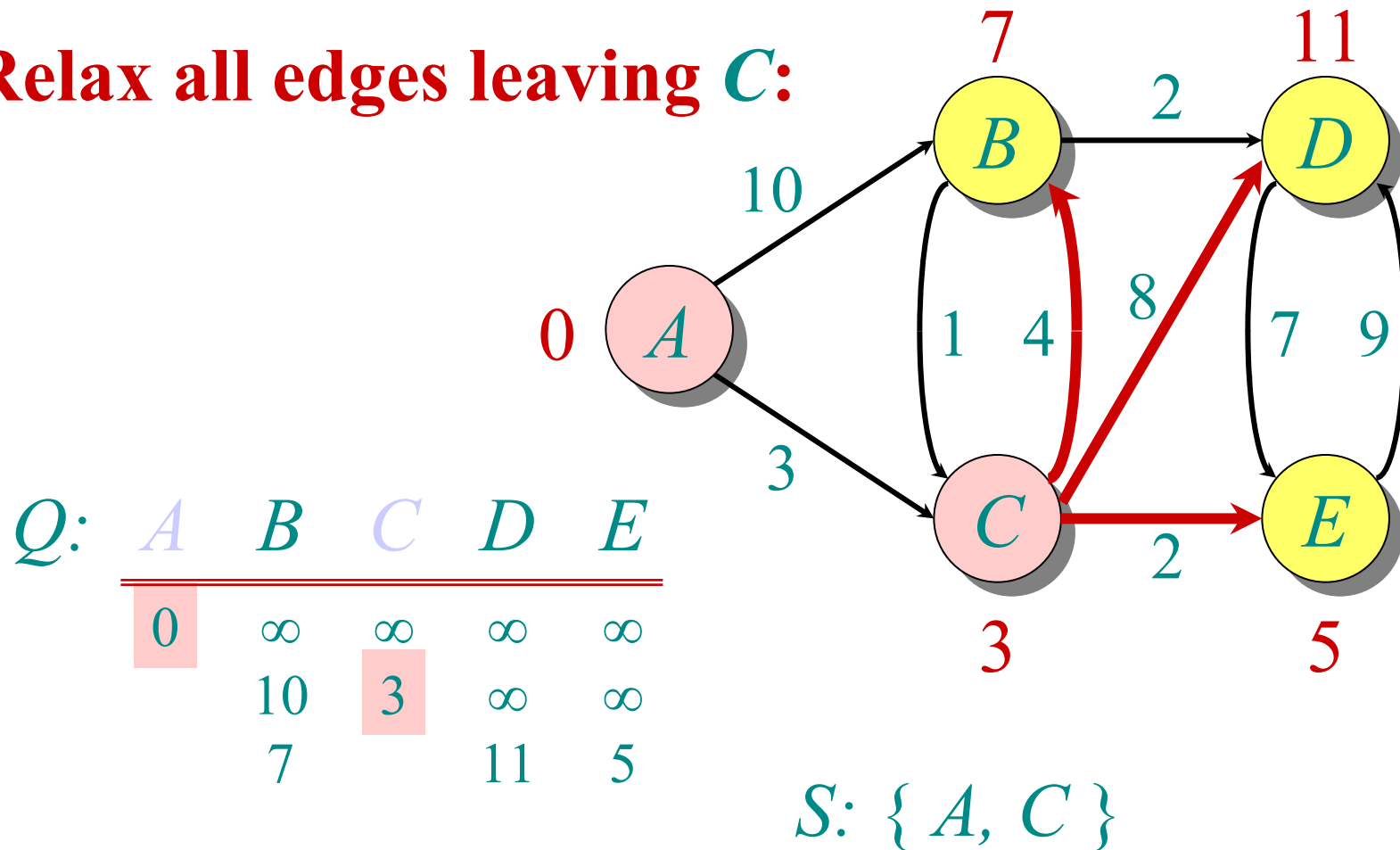


S: { A, C }



Example of Dijkstra's algorithm

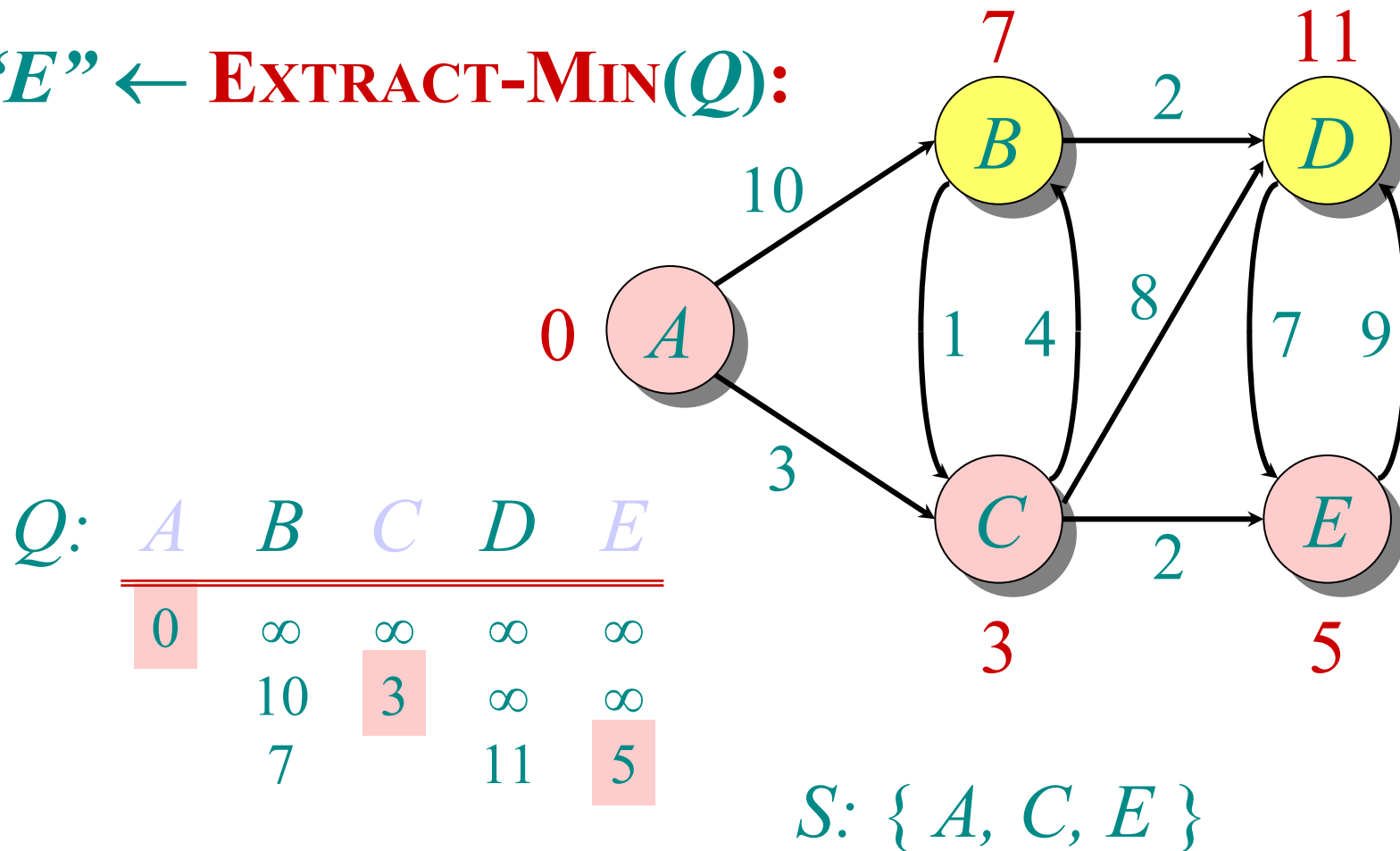
Relax all edges leaving **C**:





Example of Dijkstra's algorithm

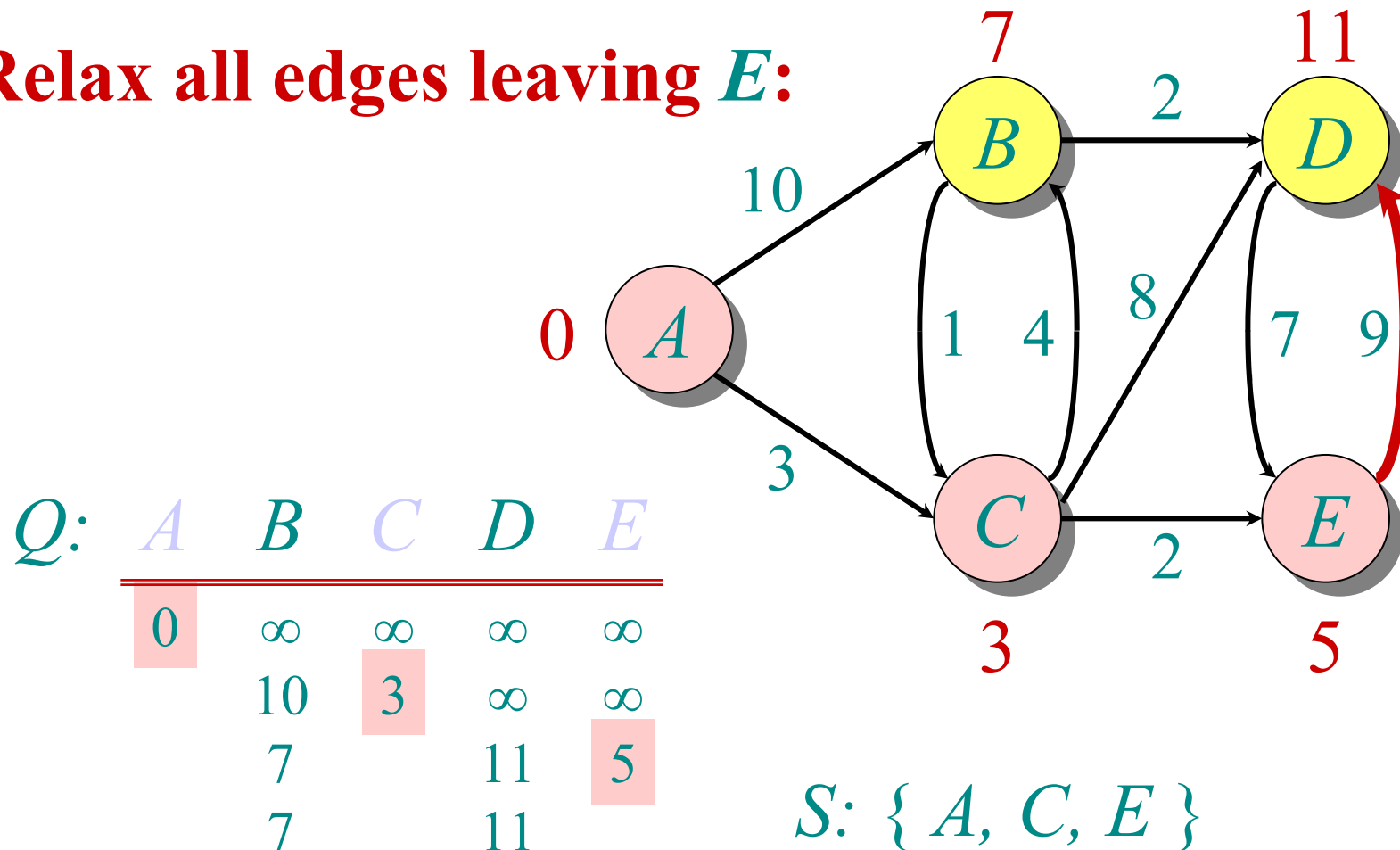
“E” \leftarrow **EXTRACT-MIN**(*Q*):





Example of Dijkstra's algorithm

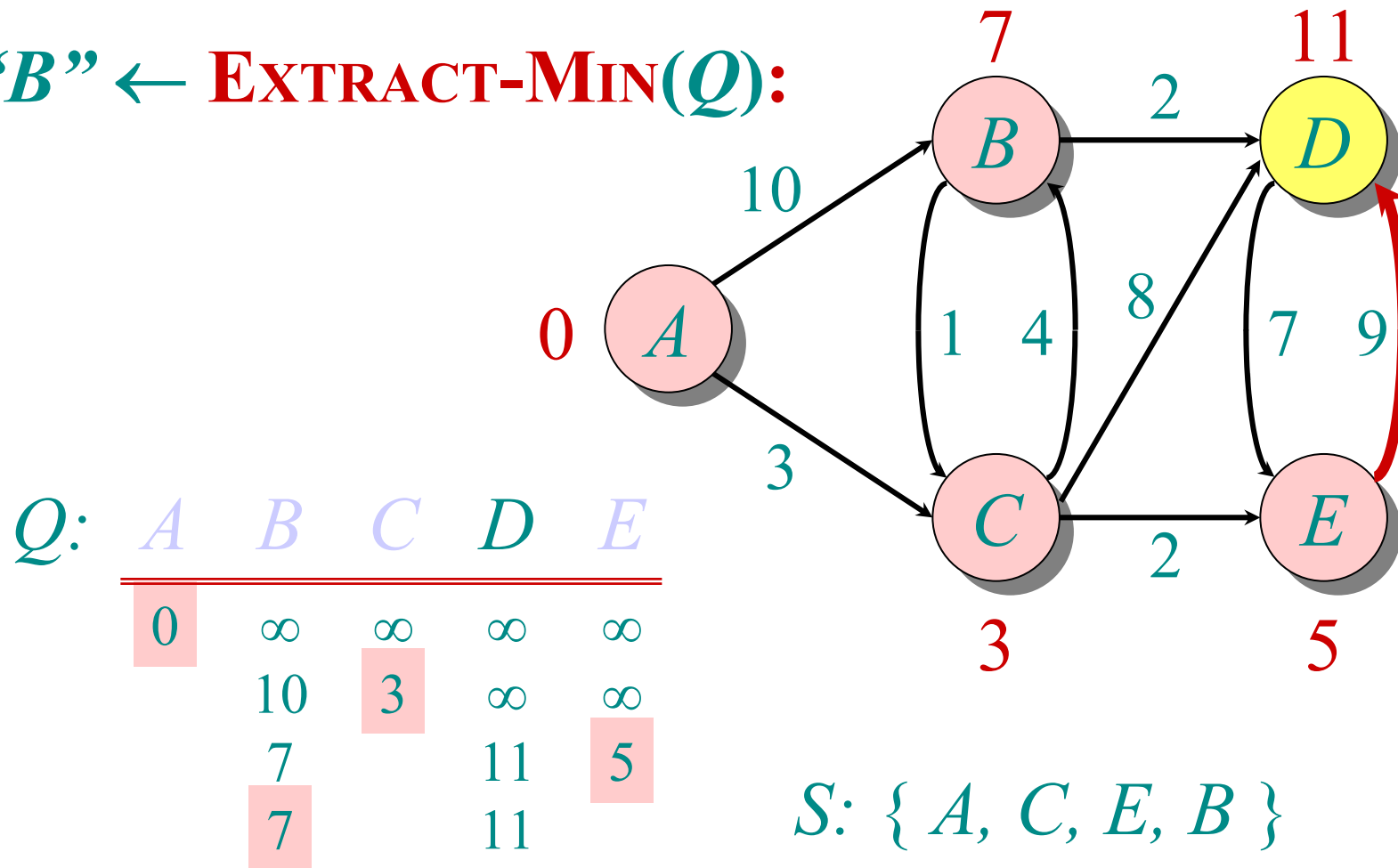
Relax all edges leaving E :





Example of Dijkstra's algorithm

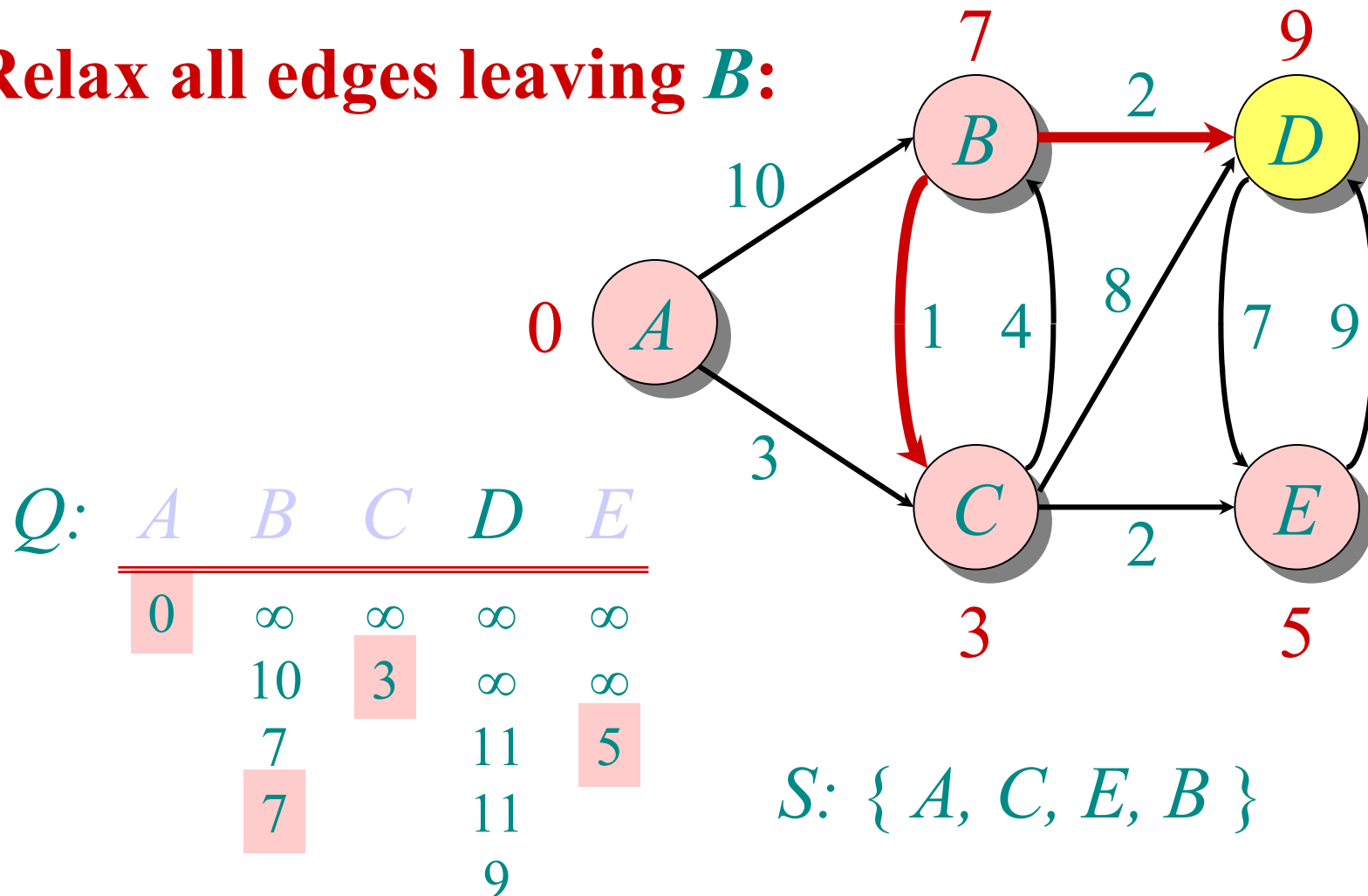
“*B*” \leftarrow **EXTRACT-MIN**(*Q*):





Example of Dijkstra's algorithm

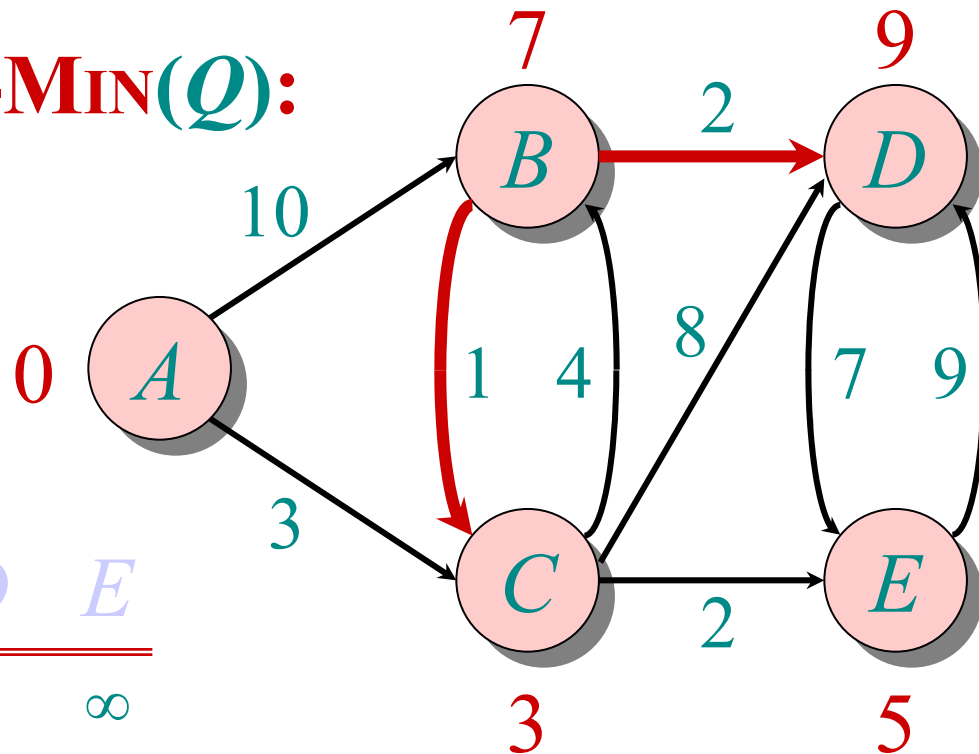
Relax all edges leaving *B*:





Example of Dijkstra's algorithm

“D” ← **EXTRACT-MIN**(Q):



Q:

A	B	C	D	E
0	∞	∞	∞	∞
	10	3	∞	∞
	7		11	5
	7		11	
			9	

S: { A, C, E, B, D }

Correctness

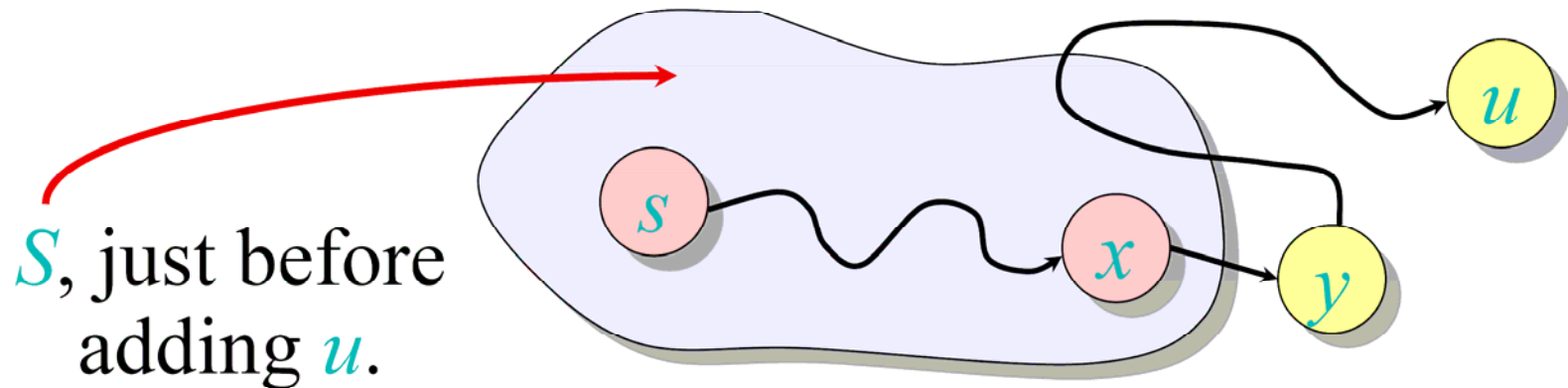
Lemma. Let u be v 's predecessor on a shortest path from s to v . Then, if $d[u] = \delta(s, u)$ and edge (u, v) is relaxed, we have $d[v] = \delta(s, v)$ after the relaxation.

Proof. Observe that $\delta(s, v) = \delta(s, u) + w(u, v)$. Suppose that $d[v] > \delta(s, v)$ before the relaxation. (Otherwise, we're done.) Then, the test $d[v] > d[u] + w(u, v)$ succeeds, because $d[v] > \delta(s, v) = \delta(s, u) + w(u, v) = d[u] + w(u, v)$, and the algorithm sets $d[v] = d[u] + w(u, v) = \delta(s, v)$. □

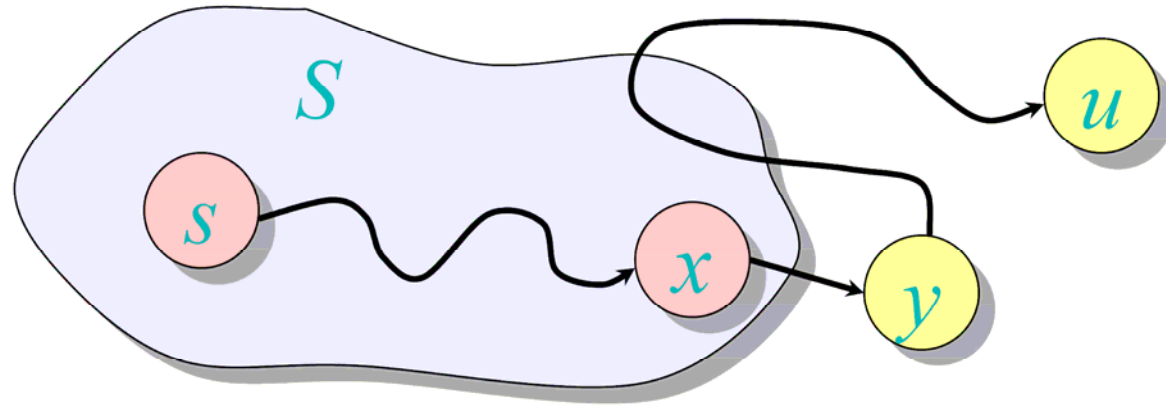
Correctness

Theorem. Dijkstra's algorithm terminates with $d[v] = \delta(s, v)$ for all $v \in V$.

Proof. It suffices to show that $d[v] = \delta(s, v)$ for every $v \in V$ when v is added to S . Suppose u is the first vertex added to S for which $d[u] > \delta(s, u)$. Let y be the first vertex in $V - S$ along a shortest path from s to u , and let x be its predecessor:



Correctness

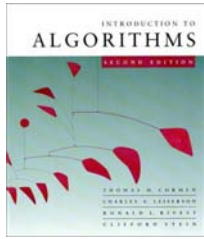


Since u is the first vertex violating the claimed invariant, we have $d[x] = \delta(s, x)$. When x was added to S , the edge (x, y) was relaxed, which implies that $d[y] = \delta(s, y) \leq \delta(s, u) < d[u]$. But, $d[u] \leq d[y]$ by our choice of u . Contradiction. \square



Analysis of Dijkstra

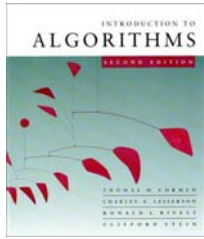
```
while  $Q \neq \emptyset$ 
do  $u \leftarrow \text{EXTRACT-MIN}(Q)$ 
   $S \leftarrow S \cup \{u\}$ 
  for each  $v \in \text{Adj}[u]$ 
    do if  $d[v] > d[u] + w(u, v)$ 
       then  $d[v] \leftarrow d[u] + w(u, v)$ 
```



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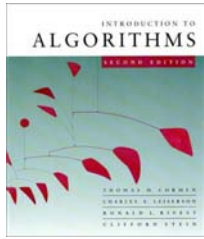
$|V|$
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Handshaking Lemma $\Rightarrow \Theta(E)$ implicit DECREASE-KEY's.



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Handshaking Lemma $\Rightarrow \Theta(E)$ implicit DECREASE-KEY's.

$$\text{Time} = \Theta(V \cdot T_{\text{EXTRACT-MIN}} + E \cdot T_{\text{DECREASE-KEY}})$$

Note: Same formula as in the analysis of Prim's minimum spanning tree algorithm.



Analysis of Dijkstra (continued)

$$\text{Time} = \Theta(V) \cdot T_{\text{EXTRACT-MIN}} + \Theta(E) \cdot T_{\text{DECREASE-KEY}}$$

Q	$T_{\text{EXTRACT-MIN}}$	$T_{\text{DECREASE-KEY}}$	Total
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Analysis of Dijkstra (continued)

$$\text{Time} = \Theta(V) \cdot T_{\text{EXTRACT-MIN}} + \Theta(E) \cdot T_{\text{DECREASE-KEY}}$$

Q	$T_{\text{EXTRACT-MIN}}$	$T_{\text{DECREASE-KEY}}$	Total
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array	$O(V)$	$O(1)$	$O(V^2)$
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Analysis of Dijkstra (continued)

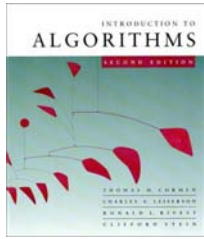
$$\text{Time} = \Theta(V) \cdot T_{\text{EXTRACT-MIN}} + \Theta(E) \cdot T_{\text{DECREASE-KEY}}$$

Q	$T_{\text{EXTRACT-MIN}}$	$T_{\text{DECREASE-KEY}}$	Total
array	$O(V)$	$O(1)$	$O(V^2)$
binary heap	$O(\lg V)$	$O(\lg V)$	$O(E \lg V)$



Unweighted graphs

Suppose that $w(u, v) = 1$ for all $(u, v) \in E$.
Can Dijkstra's algorithm be improved?



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        ENQUEUE( $Q, v$ )
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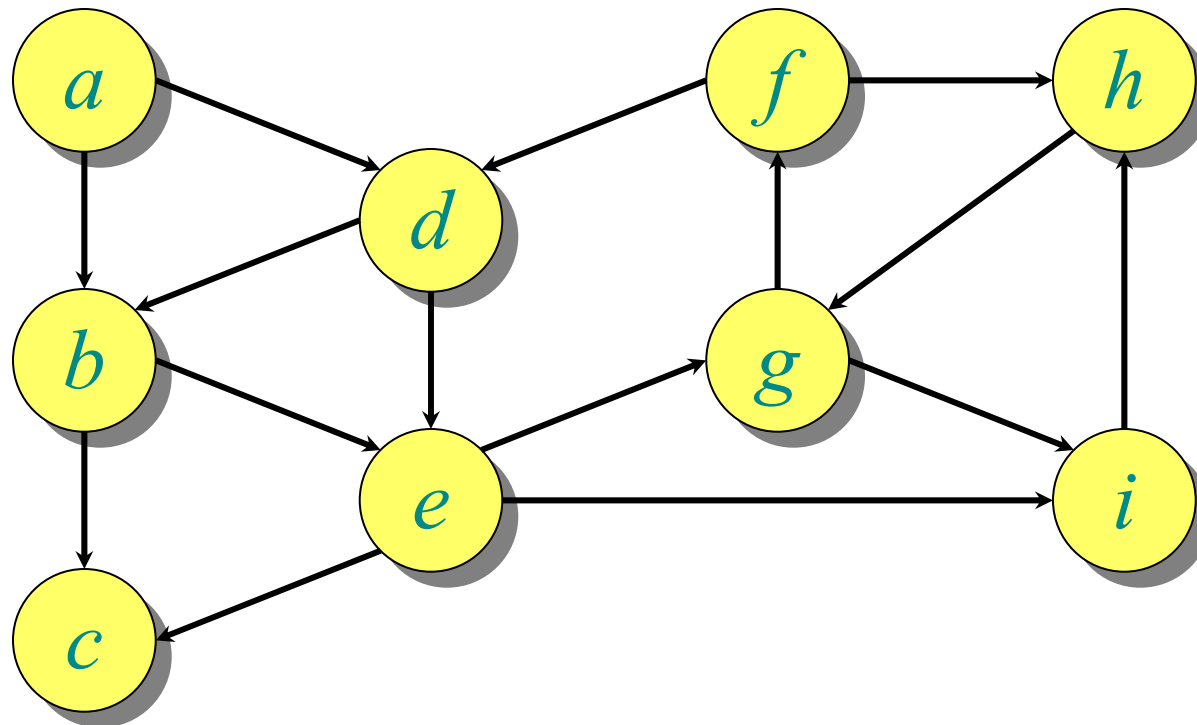
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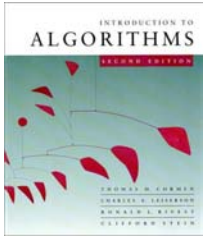
Analysis: Time = $O(V + E)$.



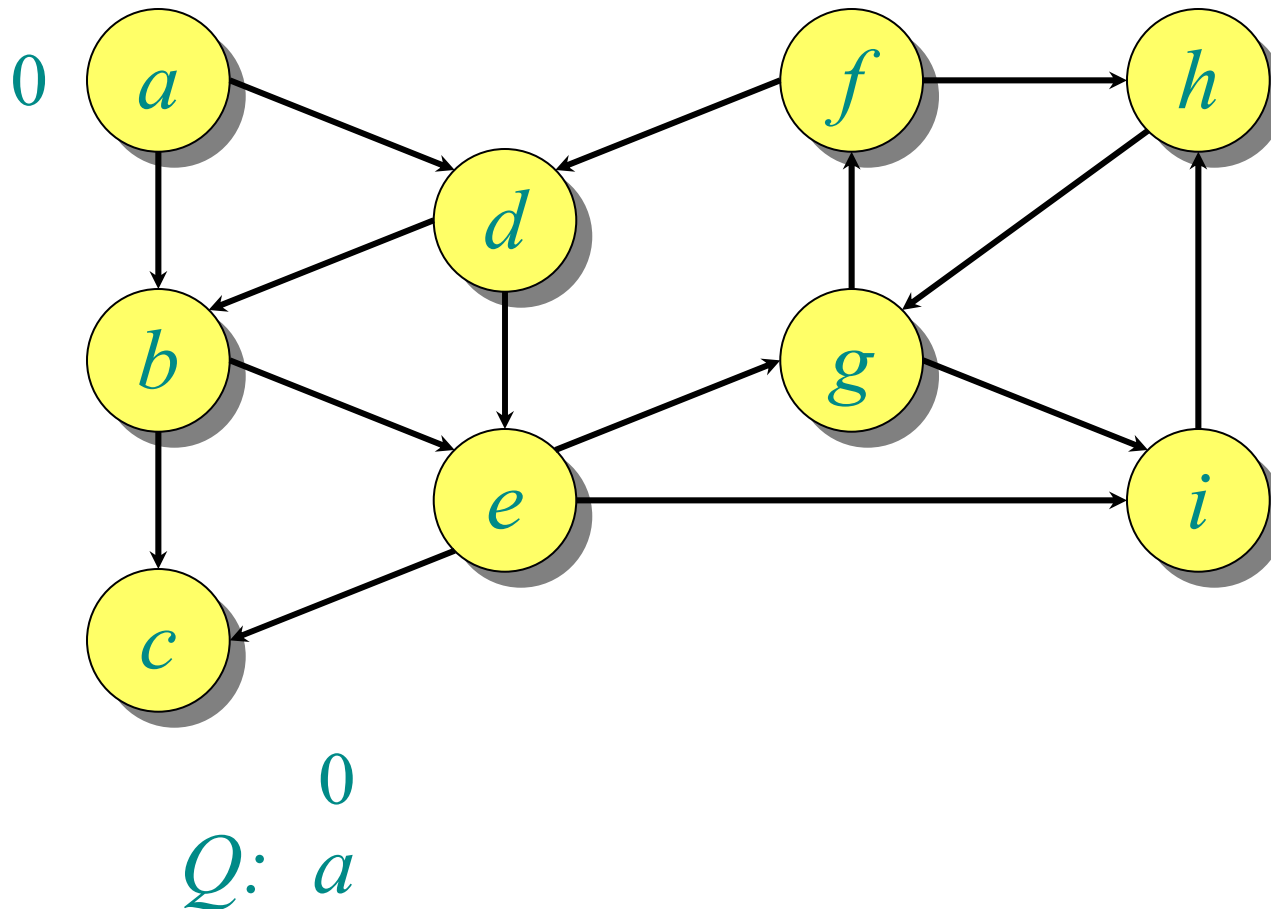
Example of breadth-first search

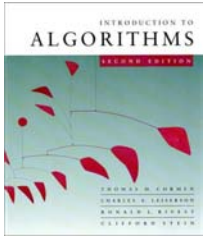


Q :

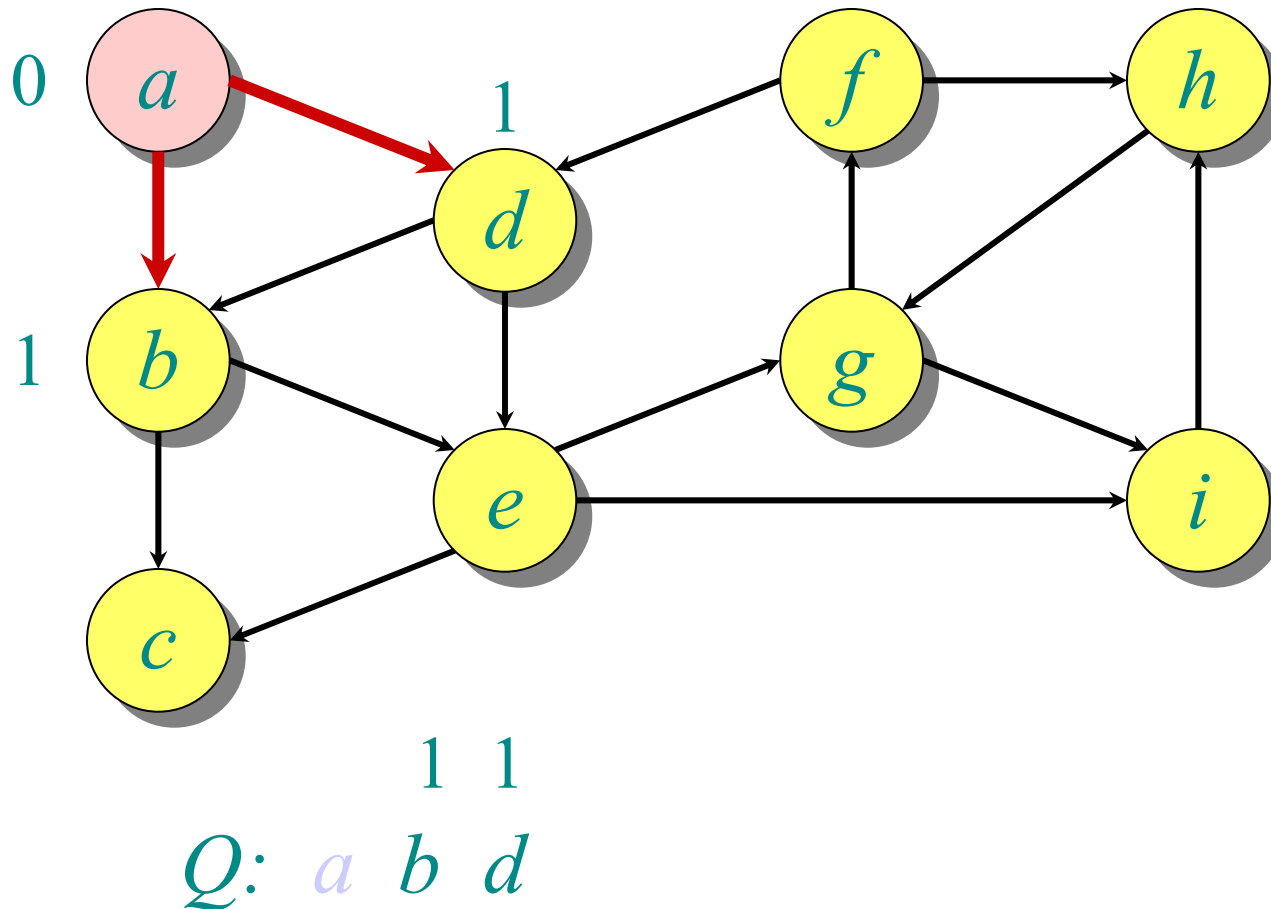


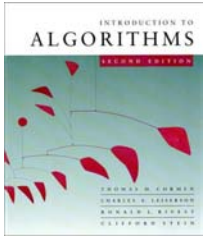
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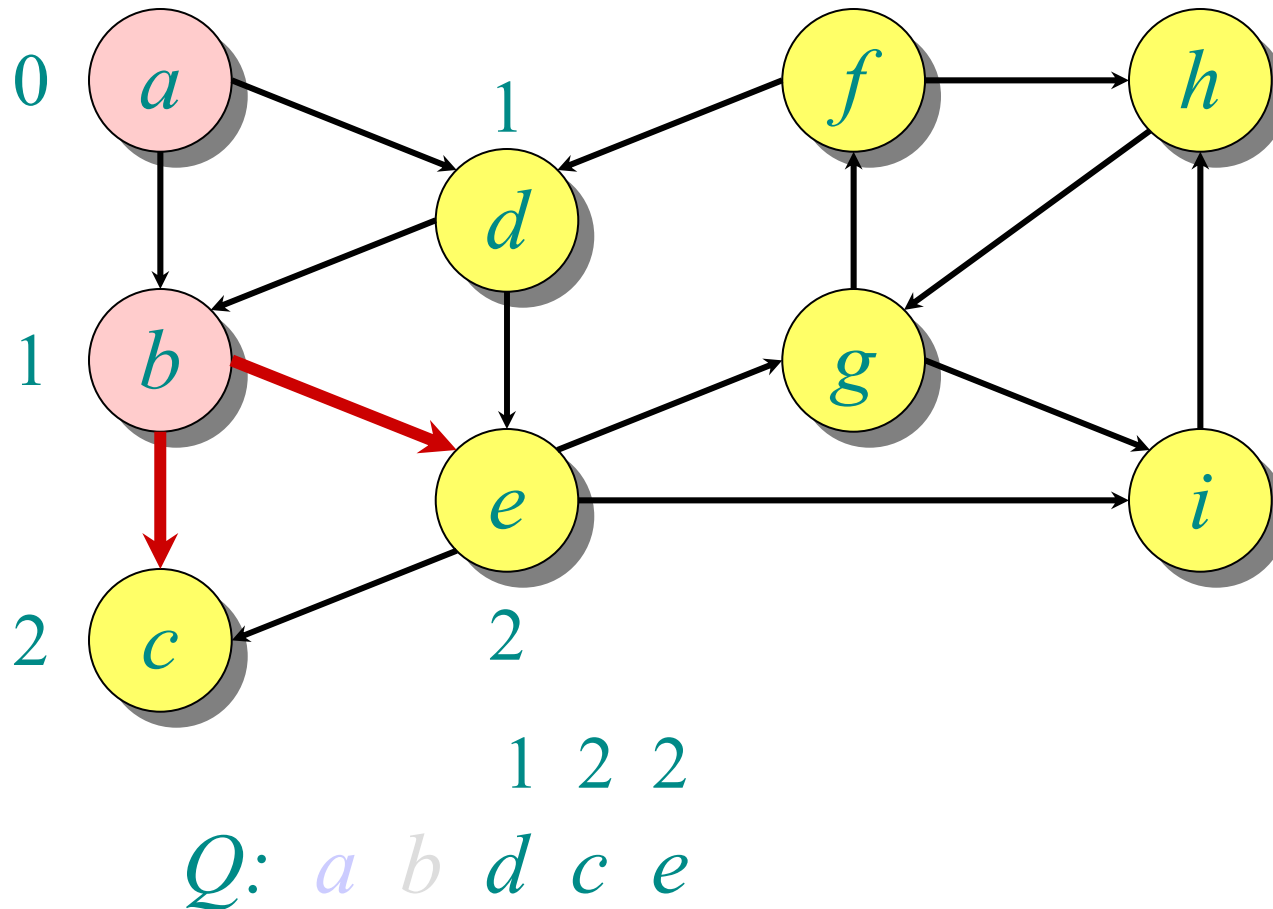


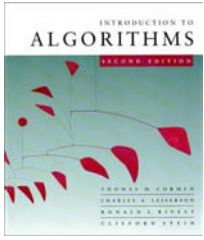
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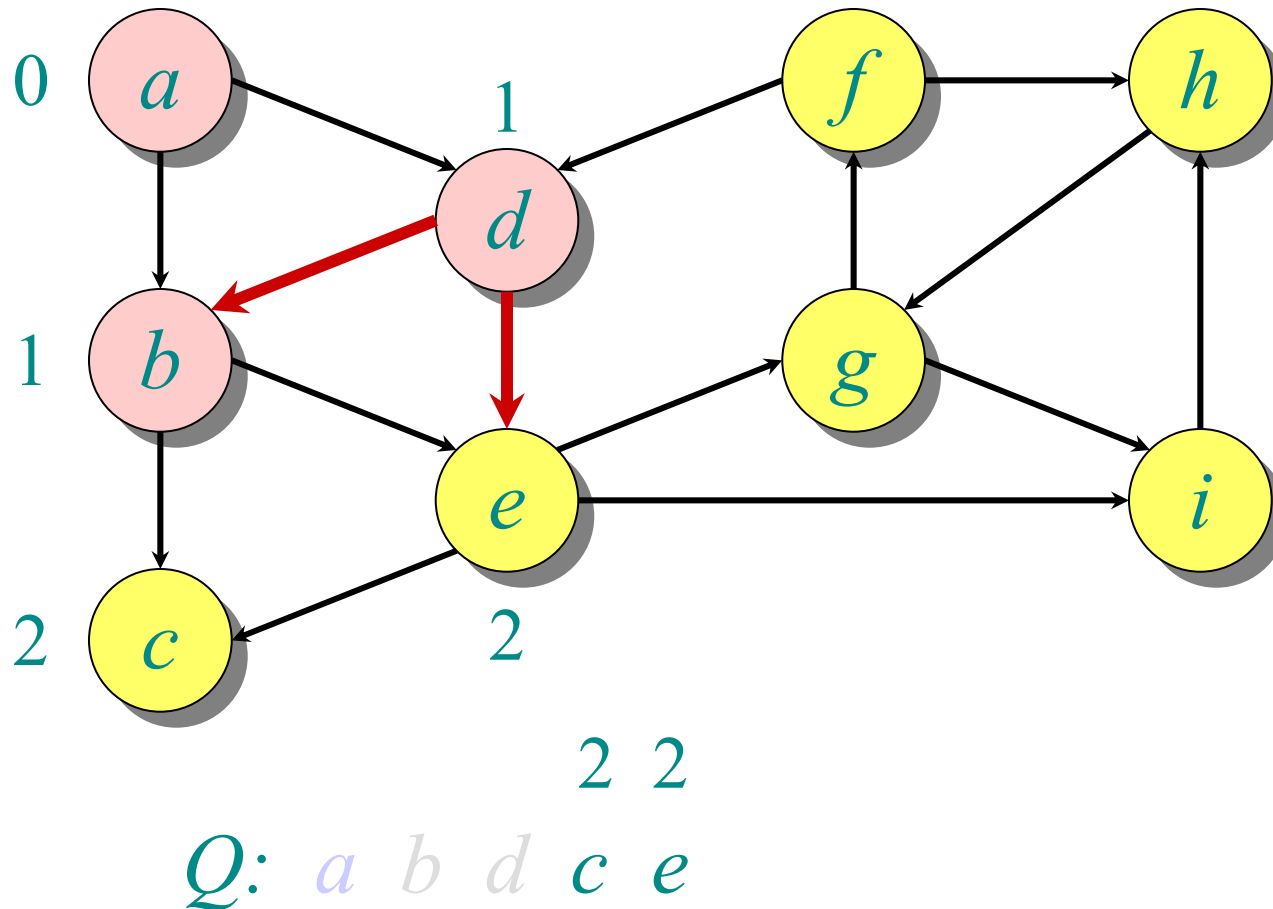


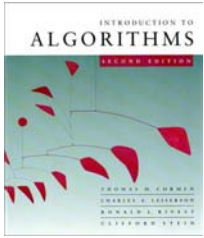
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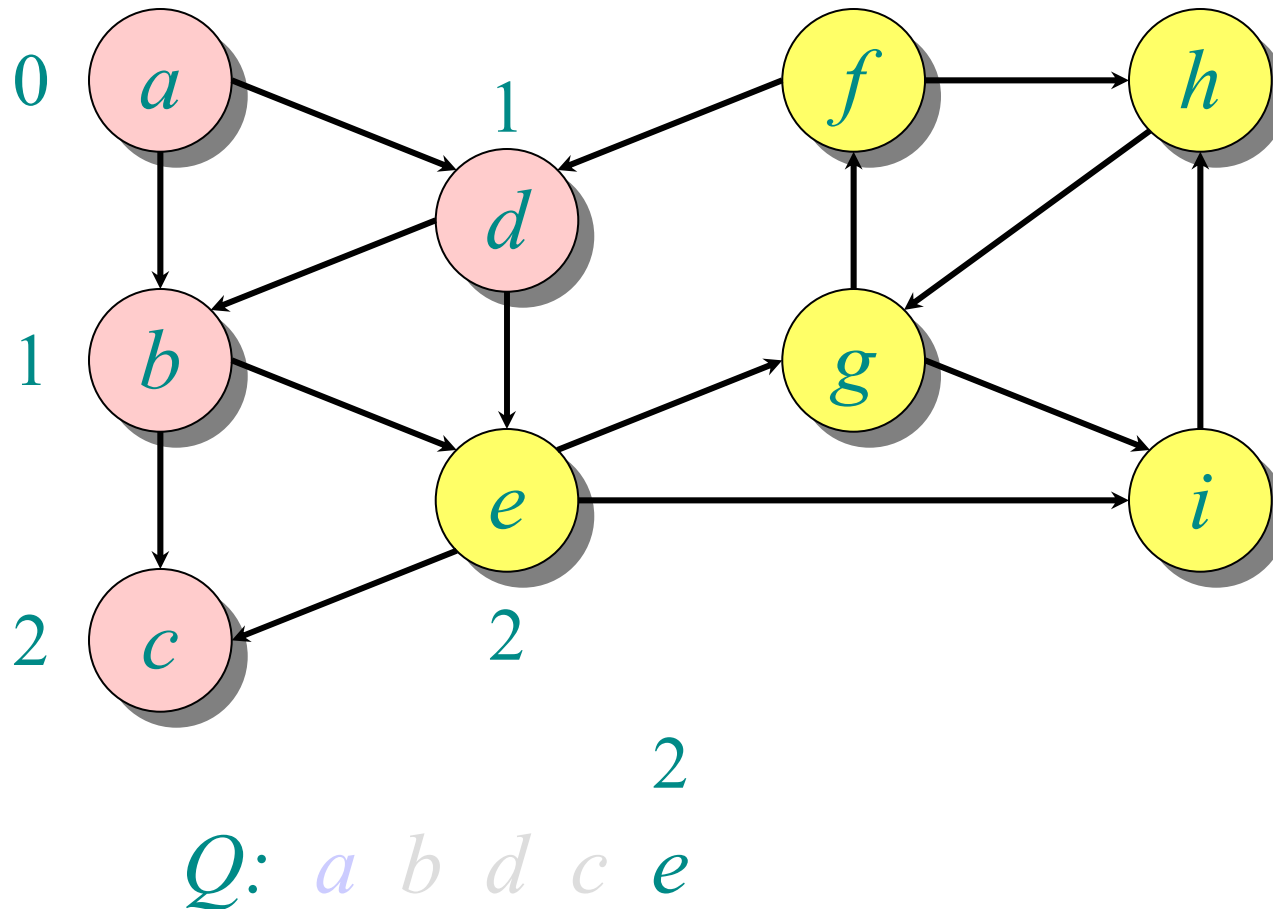


Example of breadth-first search



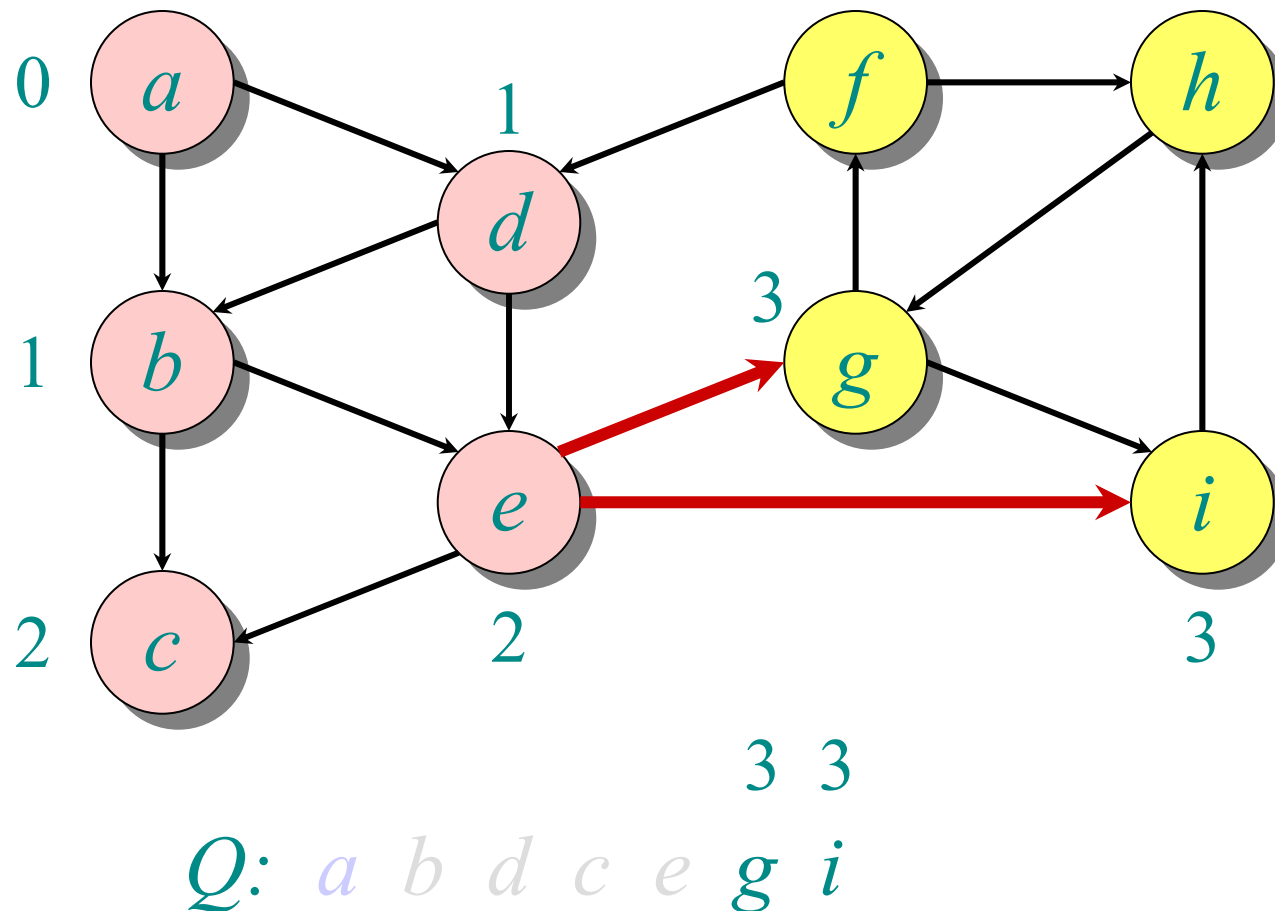


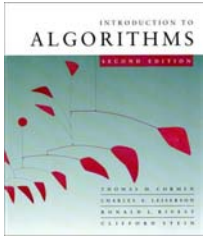
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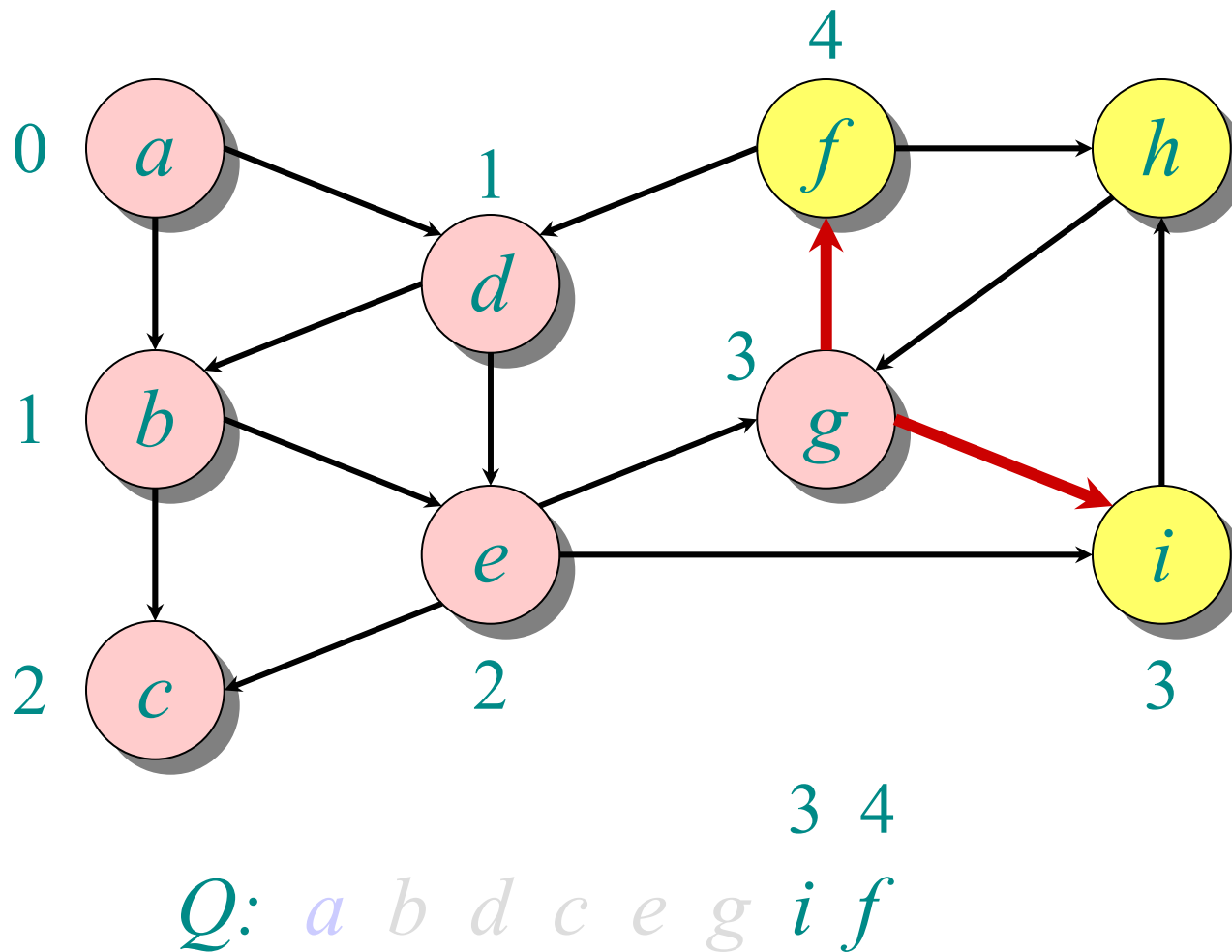


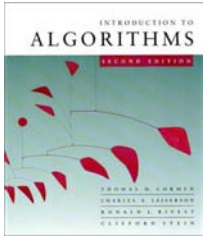
Example of breadth-first search



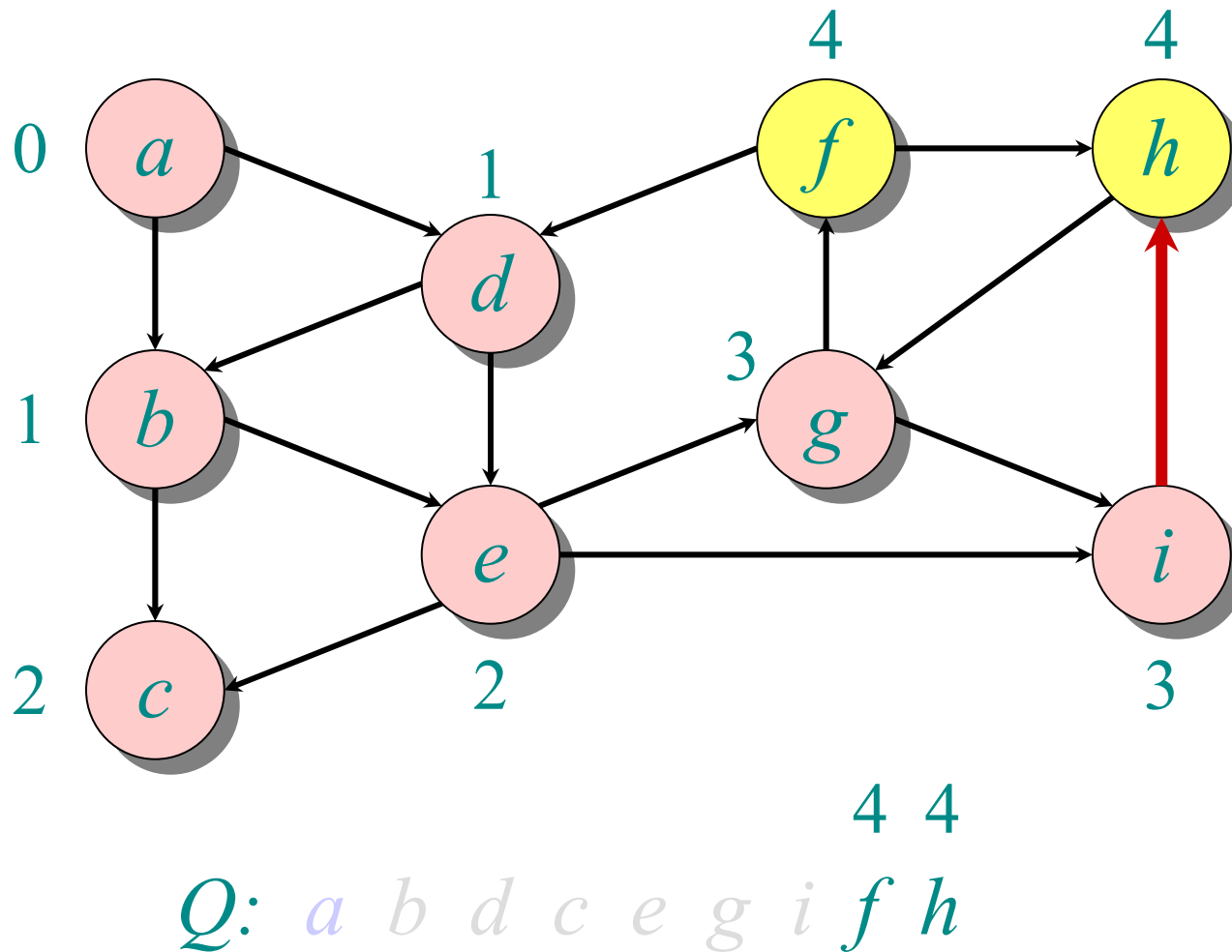


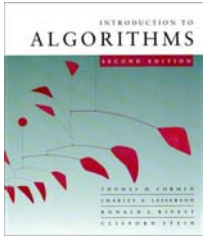
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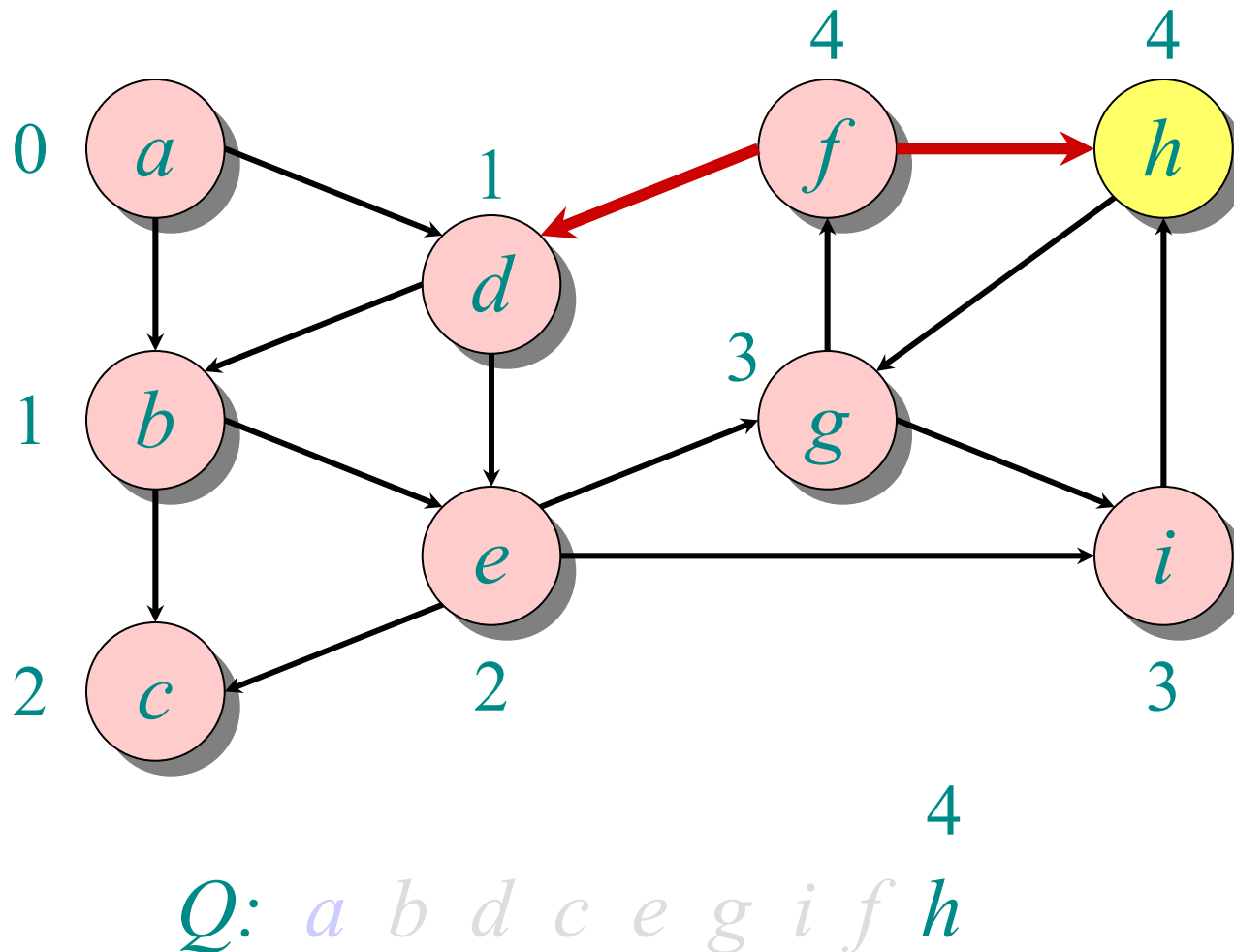


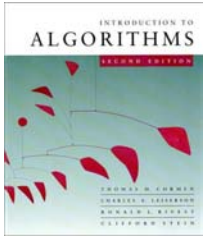
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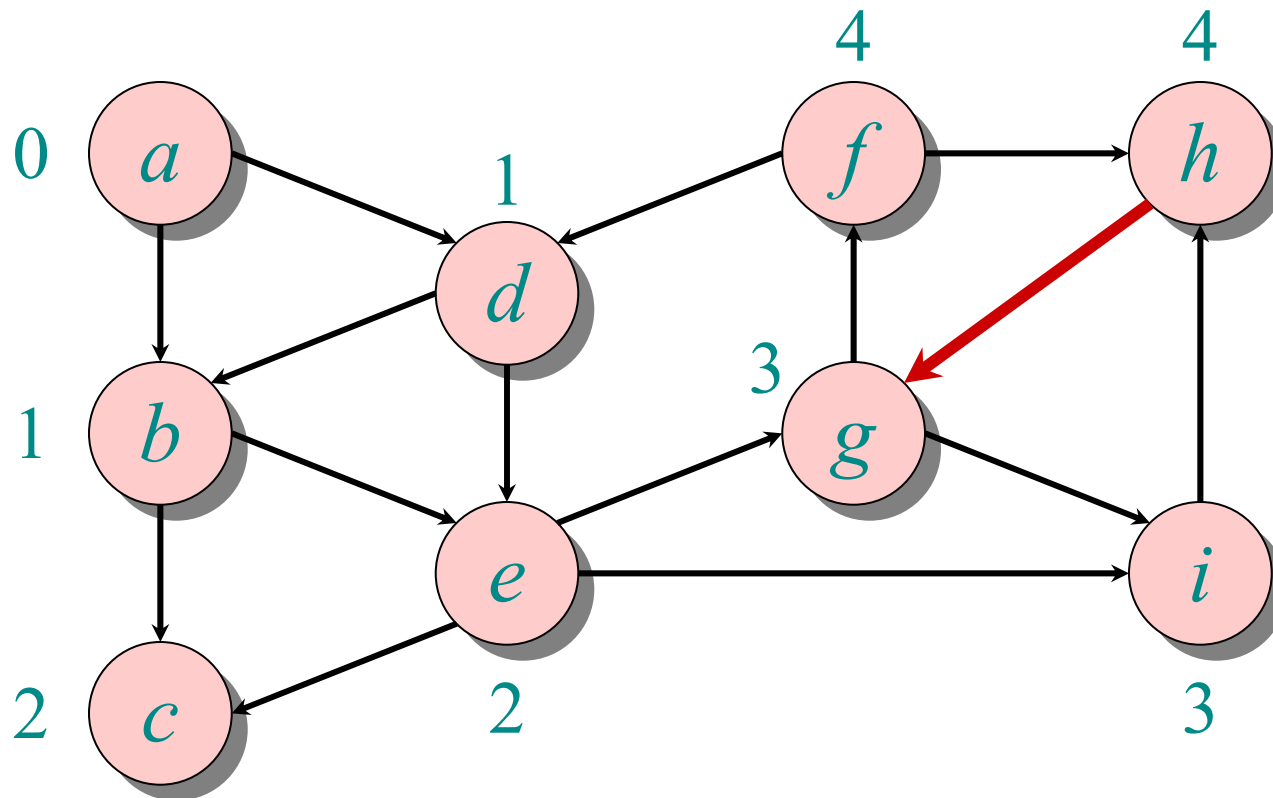


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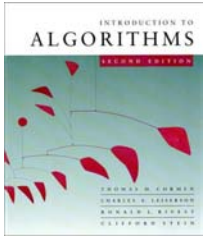




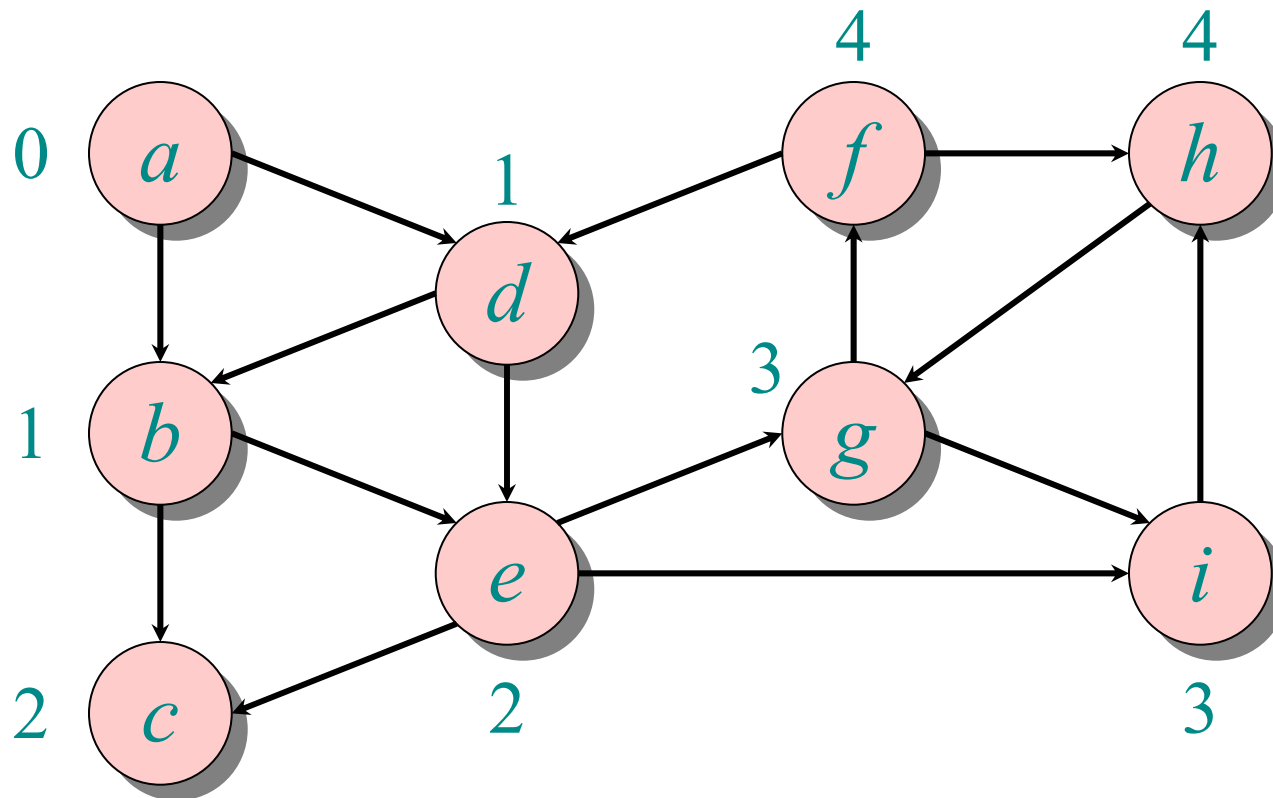
Example of breadth-first search



Q: *a* *b* *d* *c* *e* *g* *i* *f* *h*



Example of breadth-first search



Q: *a* *b* *d* *c* *e* *g* *i* *f* *h*



Correctness of BFS

```
while  $Q \neq \emptyset$ 
do  $u \leftarrow \text{DEQUEUE}(Q)$ 
  for each  $v \in \text{Adj}[u]$ 
  do if  $d[v] = \infty$ 
    then  $d[v] \leftarrow d[u] + 1$ 
         $\text{ENQUEUE}(Q, v)$ 
```

Key idea:

The FIFO Q in breadth-first search mimics the priority queue Q in Dijkstra.

- **Invariant:** v comes after u in Q implies that $d[v] = d[u]$ or $d[v] = d[u] + 1$.